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1 **Title:** Finite Element and deformation analyses predict pattern of bone failure in loaded zebrafish  
2 spines.

3

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11

12 **Abstract (200 words max)**

13

14 The spine is the central skeletal support structure in vertebrates consisting of repeated units of  
15 bone, the vertebrae, separated by intervertebral discs that enable the movement of the spine.  
16 Spinal pathologies such as idiopathic back pain, vertebral compression fractures and  
17 intervertebral disc failure affect millions of people world-wide. Animal models can help us to  
18 understand the disease process, and zebrafish are increasingly used as they are highly  
19 genetically tractable, their spines are axially loaded like humans, and they show similar  
20 pathologies to humans during ageing. However biomechanical models for the zebrafish are  
21 largely lacking. Here we describe the results of loading intact zebrafish spinal motion segments  
22 on a material testing stage within a micro Computed Tomography machine. We show that  
23 vertebrae and their arches show predictable patterns of deformation prior to their ultimate  
24 failure, in a pattern dependent on their position within the segment. We further show using  
25 geometric morphometrics which regions of the vertebra deform the most during loading, and  
26 that Finite Element models of the trunk subjected reflect the real patterns of deformation and  
27 strain seen during loading and can therefore be used as a predictive model for biomechanical  
28 performance.

29

30 **Keywords**

31 Finite Element, Zebrafish, Spine, Loading, Mechanics, Deformation, Geometric morphometrics.

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35

## 36 **Introduction**

37 The spine consists of a repeated pattern of motion segments (MSs) of bony vertebrae separated by  
38 intervertebral discs (IVDs) that enable movement. Back pain and IVD degeneration affect millions of  
39 people worldwide (1,2), and vertebral compression fractures are a frequent feature of osteoporosis  
40 (3). Biomechanical pathologies of the spine are underpinned by genetic, physiological and  
41 environmental pathways that together damage IVD, muscle and the bone, changing the mechanics of  
42 the system.

43 Animal models, typically rodents, are frequently used to study mechanisms of spinal  
44 pathology (4). However, quadrupeds are disadvantageous for studying the human spine as  
45 gravitational load acts perpendicular to their axial skeleton. Zebrafish are increasingly used as a model  
46 for human disease, due to their genetic tractability. Unlike quadrupeds, but similar to humans under  
47 gravity (Fig. 1a), their spine is antero-posteriorly loaded as a result of swimming through viscous water  
48 (5). Zebrafish are well established as models for skeletogenesis, pathology, and ageing (6), and  
49 develop spinal pathologies in response to altered genetics (7) and ageing (8). However, the  
50 biomechanics of the zebrafish spine are comparatively poorly characterised.

51 Finite element analysis (FEA) has proven a pivotal tool in the study of biomechanical subjects  
52 (9), and offers a method for biomechanically characterising the zebrafish spine, including intact MS.  
53 This technique digitally models an object of known material properties using a series of linked nodes  
54 of known number and geometry, that can be subjected to a wide variety of forces outputting the  
55 predicted geometry, strain and deformation. Results can be validated by comparison with the results  
56 of loading experiments in which a sample is loaded *ex vivo* (10,11). FEA has been used in zebrafish to  
57 test contributions of shape and material properties in joint morphogenesis (12,13) and to study strain  
58 patterns in a single vertebra (14).

59 Here, we describe a novel integrated experimental platform that brings together imaging,  
60 modelling and real-world validation to explore the biomechanics of intact zebrafish spinal MSs. We  
61 generated an FEA model of the spine, which we validated with a loading experiment using a high-  
62 precision material testing stage (MTS) under set loading regimes using micro Computed Tomography  
63 ( $\mu$ -CT). Three-dimensional geometric morphometrics (3D GM) was used to explore patterns of  
64 deformation seen in each vertebra during loading. Comparison of results demonstrated that our FEA  
65 model accurately predicted the relative patterns of deformation and strain experienced by real  
66 samples loaded *ex vivo*.

67

## 68 **Methods**

69 **Zebrafish samples**

70 1-year old, wild-type (WT) zebrafish were fixed in 4% paraformaldehyde and dehydrated to 70% EtOH.  
71 MSs were acquired by making two cuts in the trunk, between the morphologically homogeneous  
72 vertebra 18 and 24 of a total of 33 vertebrae<sup>5</sup> (Fig. 1a-c).

73

74 ***In vitro* vertebral loading experiment**

75 Loading experiments were conducted using a custom-built Material Testing Stage (MTS2) in the Bruker  
76 SKYSCAN 1272  $\mu$ CT system. Radiographic visualisation of each MS (n=3) was performed and if  
77 required, vertebrae were trimmed to retain three complete vertebrae and associated IVDs (Fig. 1b-d).  
78 Samples were stabilized (anterior-up) in the MTS2 using cyanoacrylate glue. The MTS2 was  
79 programmed to perform a sequential series of seven scans at a series of increasing loads (Table 1),  
80 using 60 KeV X-ray energy, 50 W current, 5  $\mu$ m isotropic voxel size and a 0.25 mm Aluminium filter.  
81 1501 projections were collected during a 180<sup>o</sup> rotation, with 400 ms exposure time. Reconstructions  
82 were performed using NRecon (Version 1.7.1.0). Surfaces of vertebrae, muscle and IVDs in each  
83 dataset were generated using Avizo (Avizo version 8; Visualization Sciences Group) (Fig. 1c-e, Table 1)  
84 and linear measurements of IVDs and MS lengths made using the “3D Measurement” tool. Vertebrae  
85 surfaces were further processed in Meshlab (Table 2).

86

87 **Finite Element Analysis (FEA)**

88 An MS surface mesh was created based on a 1-year-old WT specimen  $\mu$ CT scanned using a Nikon XTH  
89 225ST  $\mu$ CT system as described under two conditions; (a) native state and (b) contrast-enhanced  
90 following 14 day incubation in 2.5% phosphomolybdemic acid (15). Scan (a) was used to segment  
91 vertebrae (V18-V24), and scan (b) to segment IVDs. The resulting binary labels from scans (a) and (b)  
92 were saved as 8-bit tiff stacks, manually registered in 3D space in Avizo (‘Trackball’ tool) and  
93 algorithmically combined (‘Algebra’ tool), creating a single volume of separate materials representing  
94 three vertebrae and four IVDs (Fig. 1d-e, Table 2). A 500  $\mu$ m thick cylinder was created contacting the  
95 anterior-most IVD perpendicular to the model axis, to mimic the stainless-steel compressive plate and  
96 distribution of forces applied during loading (Fig. 1f).

97 The complete vertebral surface mesh was imported into Simpleware ScanIP (version 2018.12,  
98 Synopsys Inc.) to create an FE model. The model consisted of 1,054,187 linear tetrahedral elements  
99 joined at 257,392 nodes comprising four material types: vertebral bone, annulus-fibrosus, nucleus-  
100 pulposus and stainless-steel (Fig. 1d-f, Table 2). The model was analysed in Abaqus (2018 version). A  
101 custom datum coordinate system was created centred on the antero-posterior axis of the model, and  
102 a concentrated force applied to the central node of the anterior face of the compressive plate. This

103 loading case was repeated in each of 7 steps of a multi-step analysis, with load values matching the  
104 increments applied in the MTS (Table 1). The model was constrained in two locations using boundary  
105 conditions, at the base of the posterior-most IVD (constrained in 3 axes), and at the top of the  
106 compressive plate (constrained in 2 axes, allowing movement along the model's antero-posterior axis  
107 (Fig. 1f). Deformed meshes from each step were exported as surface files and analysed using 3D-GM  
108 for quantitative comparison between relative and absolute patterns of deformation predicted by FEA  
109 and observed in MTS data.

110

### 111 **Three-dimensional geometric morphometrics (3D-GM)**

112 3D-GM analysis of vertebral deformation was performed using the "Geomorph" package for the "r"  
113 statistics software (16). For each loading experiment, we used the first scan (1N load) to create a  
114 template of 3D coordinates for 22 fixed three-dimensional landmarks (Fig. 2a-c) linked by 300 surface  
115 sliding semi-landmarks (using the "buildtemplate" function). By assigning the same landmarks in each  
116 scan (using the "digitalsurface" function), we compared the first scan with subsequent scans of the same  
117 vertebra using generalised Procrustes analysis (allowing semi-landmarks to 'slide' in order to remove  
118 arbitrary spacing). Resulting shape variables were subjected to principal component analysis (PCA) to  
119 identify the principal patterns of variation between scans of the same vertebra, and isolate trends in  
120 deformation with increasing compressive load.

121

## 122 **3. Results and discussion**

### 123 **Vertebral motion segments fail under loading of 12-16N at positions of maximum von Mises strain.**

124 To test the range of compressive loads that the MS could resist until failure, we subjected an MS to  
125 exponentially increasing compressive forces from 1-100N. This specimen failed at 16N whereupon the  
126 central vertebra fractured mid-centrum. A primary loading regime between 1-16N was thus  
127 established (Table 1) for the three primary specimens; occupying the elastic, plastic and failure regions  
128 of the compressive loading profile of a typical MS. Failure was considered when at least one vertebral  
129 centrum fractured across the axis (e.g. Fig. 1j,l). All samples failed between 12-16N upon shallow angle  
130 fracture in the central vertebra, with the smallest specimen (specimen 3) failing at the lowest force  
131 (Fig. 1g,h). This is higher than maximum aquatic forces experienced during swim training by Fiaz et  
132 al.<sup>5</sup>, which reached ~9.5N. Minor differences in mounting orientation created differences in linear  
133 deformation between right and left sides, but specimens follow similar patterns. Prior to failure, linear  
134 measurements show an increase in IVD antero-posterior thickness (Table 1, bracketed dash line in Fig.  
135 1g) suggesting the IVD acts like a coiled spring that may further contribute to the ultimate strain and  
136 failure of the segment when released via small scale bone fracture (Fig. 1h). The surrounding epaxial

137 musculature showed no obvious deformation or damage until the entire MS failed, at which point  
138 muscle fibre organisation was lost (Fig 1i-l). Comparison between MTS data and FEA results  
139 demonstrated strong spatial correlation between maximum predicted strain and ultimate point of  
140 failure in the central vertebra (Fig 1.m-o).

141

#### 142 **Morphometric characterization of vertebral compression is predicted by FEA**

143 We found characteristic patterns of deformation and strain in response to compressive loading of  
144 zebrafish vertebrae. 3D-GM results from MTS data follow distinct trends for each vertebrae between  
145 the three specimens (Fig.2d,i,n), showing consistent dorso-ventral compression, and lateral  
146 compression that is reversed at higher loads potentially due to elastic rebound of the IVD and  
147 fracturing along the zygapophyses that occurs at these loads (Fig. 2). This relative pattern is shared  
148 between each specimen, although specimen 3 experiences this at lower loads than specimens 1-2,  
149 before failing at 12N. Fractures are observed where the arches and zygapophyses contact the  
150 centrum, at loads that precede the failure of the segment (Fig 2f, h, k, m, p & r). Comparison  
151 with FEA data (blue points in graphs d,i,n) suggest that the FE model accurately predicts these  
152 patterns (Fig. 2d,i & n), and that patterns of deformation could explain the first signs of damage prior  
153 to failure. In both datasets the anterior vertebra undergoes most deformation, particularly  
154 posterior deformation of the arches (Fig. 2 e-h). The central vertebrae and arches show strong  
155 torsion (Fig. j-m), increasing through the loading regime leading to the failure of the segment  
156 (Fig. 1l,o). The posterior vertebra shows the least deformation and is most isotropic in pattern  
157 (Fig. 2o-r), potentially due to protection offered by the anterior IVDs.

158 Comparison with *ex-vivo* loading of vertebral MSs validates the accuracy of our FEA  
159 model for predicting patterns of deformation and strain across these structures. This offers a  
160 step towards a digital 'sandbox' approach to modelling the effects of genetic, physiological  
161 and morphological properties on the reaction and resistance of vertebral MSs to loading.  
162 Inputting specific properties of vertebral samples into a validated FE model will allow their  
163 effects on the biomechanics of the spine to be quantitatively tested *in silico*, allowing the  
164 relative contributions of shape and material properties to be explored and empirically tested.  
165 This will aid comparison of mechanical performance between different model systems. As an  
166 advantage of the zebrafish system is the wealth of mutants modelling human disease genetics  
167 (17), comparisons of mechanical performance between genotype and phenotype will be  
168 possible. In the longer term this approach may give insight into biomechanical aspects of

169 spinal pathology; allowing identification of 'at risk sites' in the spine. This could provide a basis  
170 for more specific or earlier interventions than those commonly employed.

171

## 172 Fig Legends

### 173 Figure 1. Ex vivo spine loading leads to motion segment failure in a region of high strain predicted 174 by Finite Element Analysis.

175 **a**, Schematic of zebrafish motion segment (MS) dissection. **b**, Material testing stage (MTS) schematic  
176 and X-radiograph. **c**, Orthogonal reconstruction slices showing vertebrae and associated soft tissue. **d**,  
177 Three-dimensional reconstruction of the finite element analysis (FEA) model with colours reflecting  
178 different materials. **e**, Details of the nucleus-pulposus (pink) and annulus fibrosis (blue) from **d**  
179 showing linear measurements of inter-vertebral disk (IVD) thickness. **f**, Predicted compressive  
180 deformation and strain map from FEA; dashed lines indicate axes in which boundary conditions  
181 were established. **g**, Changes to IVD width measurements (bracketed dashed line highlights IVD elastic  
182 rebound) and **h**, changes in MS length with increasing load for the three MTS specimens; direction of  
183 arrowhead denotes measurement type. **i**, **j** Reconstructions of MTS Specimen 1 compressed to 10N  
184 (**i**), and 16N (**j**) with central vertebra indicated by \* in each. **k** & **l** Antero-posterior cross-sections of  
185 the central vertebra at 10N (**k**) and 16N (**l**). Muscle segmented in red, and bone in grey in **i-l**. Red  
186 dashed line in **l** denotes angle of fracture at the vertebral centrum. **m**, **o** FEA strain maps at 10N (**m**)  
187 and 16N (**o**). Scale shown in **n**.

188

### 189 Figure 2. Finite Element and geometric morphometric analyses model deformation patterns prior 190 to failure

191 **a-c** Landmarks assigned for Three-dimensional geometric morphometric (3D-GM) analysis. **d**, **i** & **n**  
192 Results of principal components analyses (PCA) of landmark deformation under increasing  
193 compressive loads for each specimen, and deformation predicted by FEA (key in **s**). Black bracketed  
194 lines indicate reduced lateral compression. **e**, **j** & **o** 3D vector plots with black line vectors representing  
195 the direction of landmark deformation and colours highlighting the extent of landmark deformation  
196 for each vertebra in Specimen 1 (vector scales magnified by 10; colour scale in **t**). **g**, **i** & **q** Deformation  
197 maps predicted by FEA (scales presented in **u**). **f**, **h**, **k**, **m**, **p** & **r** Examples of fractures (outlined in red  
198 for clarity) occurring at compressive loads before failure; corresponding with deformation patterns  
199 predicted in FEA and seen *Ex vivo*.

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252

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257 **Author contributions:** EN, EK and JA performed experiments, EN, EK, JA, CF and CLH analysed data.  
258 The project was designed by CH and KRB. All authors contributed to drafting the manuscript.

259 **Data availability:** Models are available at [data.bris.ac.uk](http://data.bris.ac.uk)

260