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# Analysis of System Reliability as a Capital Investment

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# ANALYSIS OF SYSTEM RELIABILITY AS A CAPITAL INVESTMENT

BY

ALBERT J. WILLIAMS
B.S., East Carolina University, 1950

#### RESEARCH REPORT

Submitted in partial fulfillment of the requirements for the degree of Master of Science: Engineering Math and Computer Systems in the Graduate Studies Program of the College of Engineering of Florida Technological University at Orlando, Florida

Fall Quarter 1978 ANALYSIS OF SYSTEM RELIABILITY AS A CAPITAL INVESTMENT

BY

ALBERT J. WILLIAMS

# ABSTRACT

This report, "Analysis of System Reliability as a Capital Investment", is an analysis of radar system reliability of two similar tracking radar systems as a capital investment. It describes the two tracking radar systems and calculates the mission failure rates based upon field failure data. Additionally, an analysis of a simulation program written in FORTRAN is performed which treats system reliability as a capital investment based on 335 electronic systems that were fabricated with a reliability program versus 564 electronic systems fabricated without a reliability program. The data from the two tracking radar systems, one with a reliability program and the other without, is incorporated in the computer program to verify the conclusions of the author of the computer simulation program.

Handd Kee Director of Research Report

#### ACKNOWLEDGEMENT

I would like to acknowledge the encouragement and support of my family during the preparation of this report. This report is dedicated to my wife and daughters, Carolyn, Vicki, Donna and Denise whose unwavering love and understanding were instrumental in the completion of the research for this report.

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#### CHAPTER I

#### INTRODUCTION

Performance of electronic and mechanical equipment is a grave concern of commercial as well as military customers. Failure or unscheduled down time can be costly. Equipment bought or leased on a contract basis is expected to do the specified job any time the job is required, and "the probability that no failure will occur in a given time interval of operation of a device or equipment is termed its reliability."

Equipment reliability can evoke a comical overtone such as the case of the national television presidential candidate debate in 1977 when the voice communication system failed and the candidates stood and looked at each other and the audience for several minutes. Also, equipment reliability can denote a deadly overtone. An example is the LlOll aircraft that crashed into a Southern Florida swamp in 1972 while a member of the crew was trying to localize a failure in the landing mechanism. Another example of equipment reliability is the costly loss of an atomic

lgor Bazovsky, Reliability Theory and Practice (Englewood Cliffs, N. J.: Prentice-Hall, Inc., 1961), p. 6.

submarine and its crew which in 1963 failed to surface and sank to the bottom of the Atlantic Ocean.

Since the Korean War, quantitative reliability has become widely used and measured by applying statistical methods. Government and commercial industry has placed a strong emphasis on equipment reliability. The Department of Defense contracts for equipment specify reliability compliance with the DOD specification MIL-STD-785A. 2
MIL-STD-785A defines the specifications that a reliability program must contain for systems and equipment development and production. 3 These specifications are:

- 1. The contractor must establish and maintain an effective reliability program to permit the most economical achievement of overall program objectives.
- The mission responsive reliability requirements and objectives must be specified contractually.
- The minimum acceptable hardware reliability requirements must be demonstrated by means of tests and analyses.
- 4. The proposed program plan must describe how the reliability program is to be conducted.

System reliability treated as a capital investment is

<sup>&</sup>lt;sup>2</sup>Bertram L. Amstadter, <u>Reliability Mathematics Fundamentals</u>; <u>Practices</u>; <u>Procedures</u> (New York: McGraw-Hill Book Co., 1971), pp. 1-3.

<sup>3</sup>U. S., Department of Defense, Reliability Program for Systems and Equipment Development and Production MIL-STD-785A, (Washington, D.C.: Government Printing Office, 28 March 1969), pp. 1-9.

the subject of a report by Anthony Coppola entitled "Reliaability as a Capital Investment" in the <u>Proceedings 1974</u>

Annual Reliability and Maintainability Symposium. Capital
investment is defined as an expenditure of funds in the
expectation of a worthwhile return. The treatment in his
report demonstrates that a total reliability program is a
good investment by comparing the operational costs of 564
avionics electronic systems procured with minimum reliability with the operational costs of 335 avionics electronic
systems procured with a total reliability program.

# Objective Of The Study

The objective of this study is to demonstrate the accuracy of the Coppola report and verify his conclusions in order to apply the simulation method to a pair of radar systems.

#### Statement Of The Problem

The problem of this study is to apply the simulation technique to a pair of radar systems which have reliability histories similar to the Coppola examples to verify his conclusions that reliability is a good capital investment.

# Radar Background Criteria

The pair of radar systems employed for cost and reliability data are the Mod 3 Radio Guidance System, Mod 3 RGS, located at Cape Canaveral Air Force Station, Florida and the Mod 3 General Electric Radio Tracking System, Mod 3 GERTS, located at Vandenberg Air Force Base, California. Mod 3 RGS and Mod 3 GERTS have a tracking radar operating in conjunction with launch vehicle guidance equipment and a guidance computer. The guidance computers are different and are not included in the reliability assessment. Mod 3 RGS has a total reliability program and Mod 3 GERTS has a minimal reliability program based on data through 1976.

The tracking radar mission requirement is to supply accurate position information consisting of launch vehicle range, azimuth and elevation to the guidance computer and to transmit guidance commands to the launch vehicle during the guidance portion of the launch vehicle trajectory.

Guidance commands consist of pitch and yaw steering and discrete relay closure commands. The guidance portion of the launch vehicle trajectory consists of the first six minutes after lift-off. Failure rates of the two systems are calculated based on a mission failure. A mission failure is classified as a failure that could prevent the equipment from meeting mission requirements during an actual missile flight.

#### CHAPTER II

### RELIABILITY CONCEPTS

The concept of reliability is centuries old. Sailors and fishermen have been concerned about the design and seaworthiness of their sea craft for thousands of years. Kings and knights of the Middle Ages were apprehensive about the design, performance, and effectiveness of their armor and weapons. However, the science of reliability engineering is a relative new field that grew out of the failure problems associated with complex military service equipment during World War II and the Korean War. Reliability measures equipment or device performance based on mathematical probability theory and statistical methods. 5 The widely accepted definition of reliability is "the probability that a device will operate adequately for a given period of time in its intended application."6 Reliability can be predicted and measured based on the failure rate history of a device. Failure rate of a device usually falls into three categories which are early failures, random failures, and end-of-life failures. Each of these has a particular identity. Early failures are those which occur when a

<sup>&</sup>lt;sup>5</sup>Bazovsky, <u>Reliability Theory and Practice</u>, pp. 274-286. <sup>6</sup>Amstadter, <u>Reliability Mathematics</u>, p. 1.

device is new and undergoing debugging. Random failures are those which occur during the useful life of a device. dom failures of a device that has completed a thorough debugging phase usually exhibit a constant failure rate or relatively constant failure rate during the useful life of the device. End-of-life failures are failures which occur due to the wear out or ageing of a device. If a failure distribution or histogram of failures versus time were plotted on a new piece of electronic equipment that was repaired as it failed, early failures would indicate a high failure frequency that decreases approximately exponentially to a relatively constant failure frequency over a period of time, then the failure frequency would begin increasing approximately exponentially indicating that the end-of-life or wear out of the equipment is being reached. The contour of the histogram would be shaped like a standard bathtub which is commonly referred to as the "bathtub curve" in engineering reliability.7

One of the forerunners of engineering reliability is the work performed in the early years of the rail transportation industry concerning ball and roller bearings. Extensive records on failure rate histories were maintained in order to improve the reliability of ball and roller bear-

<sup>7</sup>A. K. S. Jardine, Maintenance, Replacement, and Reliability (New York: John Wiley and Sons, 1973), pp. 1-9.

ings. Another forerunner of engineering reliability is the probability calculations performed on multiengine aircraft between World War I and World War II. Considerable effort was expended in calculating and predicting the probability of flight survival of aircraft with two engines if one engine failed and three or four engine aircraft if one or more engines failed. Information was gained that was valuable concerning "the relative amount of engine overhaul maintenance for aircraft of different types of configurations."

In 1952, the exponential failure distribution became the most popular distribution used in reliability work. Its popular use is based on the fact that it uses simple addition of failure rates for reliability calculations. Design data can be compiled using a simple format. 10

The system failure rate of n units operating in series so the system fails if any unit fails is equal to the sum of the individual unit failure rates.

$$\sum_{ss} = \sum_{i=1}^{n} 
 \sum_{i}$$

<sup>8</sup> Bazovsky, Reliability Theory and Practice, p. 2.

<sup>9&</sup>lt;sub>Ibid., p. 274.</sub>

Richard E. Barlow and Frank Proschan, <u>Mathematical</u> Theory of Reliability (New York: John Wiley and Sons, 1965), pp. 1-5.

The system mean time between failure (MTBF) is equal to the inverse of system failure rate.

$$MTBF = \frac{1}{\sum_{SS}}$$

System reliability for repairable systems which are operating in the useful life portion of the bath-tub curve is defined with the following formula.

$$R_{SS}(t) = e^{-} \sum_{SS} t$$

The Department of Defense reliability document MIL-HDBK-217B specifies that Air Force electronic systems will be assessed by using the exponential failure distribution for calculation of failure rates and reliability computing.

<sup>11</sup> Amstadter, Reliability Mathematics, pp. 32-35.

#### CHAPTER III

#### SYSTEM DESCRIPTION

The Mod III Radio Guidance System is composed of a Mod III Track Radar, Guidance Computer, and Airborne Beacon Set. Launch vehicle position information consisting of range, azimuth, and elevation is supplied to the Guidance Computer by the Mod III Track Radar at a 2 pps rate. A flag line is also supplied to the computer to indicate that the radar is tracking in the monopulse mode. For acquiring a target, Mod III Track uses a conical scan mode of tracking and a monopulse mode for normal tracking of a target. radar operates in the X band frequency range at a nominal pulse recurrence frequency of 300 with a message train of 14 pulses in conjuction with an Airborne Beacon Set which is aboard a launch vehicle. Contained within the 14 pulse message train is pitch and yaw steering and discrete relay closure commands which are determined by the Guidance Computer, decoded by the Airborne Beacon Set and supplied to the vehicle auto pilot system. For range information, the Airborne Beacon Set transmits an RF pulse to the Mod III Track Radar. The beacon transmitted RF pulse is triggered by the fourteenth pulse in the message train. Mod III Track also utilizes the beacon return pulse for pointing the antenna and azimuth and elevation information is derived based on antenna position. Baldwin encoders, mounted on the antenna in the azimuth and elevation plane, derive the azimuth and elevation angle information.

For Go-No Go checks prior to entering a test with a launch vehicle, Mod III Track utilizes a boresight tower test transmitter antenna which is triggered by the Track transmitted fourteenth pulse. To check out Mod III Track, an automatic test sequence is utilized which checks the angle encoders, angle tracking, range tracking, acquisition, message data validity, and track mode sequence switching.

A Flight Data Recording System is used to monitor Mod III Radio Guidance operation. The equipment provides facilities for recording data obtained from the position tracking radar during checkout operations or tests and during the flight of a launch vehicle. The data is used for the following purposes:

- 1. Preflight monitoring of the guidance system during checkout or test as an aid in the determination of guidance system status.
- Inflight monitoring of the guidance system to check its performance and observe any radical or abnormal departure of the launch vehicle from its programmed trajectory.
- 3. Postflight evaluation of the guidance system to

determine such factors as: programming errors; operating errors; equipment failures; inaccuracies and/or inadequacies; and ease of operation.

Documentation and classification of all repairs and failures on units comprising the Mod III Track Radar are provided for through use of an Inspection and Consumption Report (I & CR) form. Provision for vendor or internal laboratory analysis is made as required.

Mod III RGS Tracking Radar is comprised of 18,753 components in 33 units. A discription of the system functional operation is enclosed in Appendix A. System failure rate is 0.0011057 and the calculations are included in Appendix A. The cost of the system is \$21,417,000.

The Mod III GERTS Tracking Radar is comprised of 16,953 components in 31 units. It does not have an extended range tracker or a redundant transmitter. The system failure rate is 0.0018416 based on limited available data. The cost of the system is \$12,620,000.

The MTBF of the RGS Tracking Radar is 904 hours between failures compared to 543 for the GERTS Tracking Radar.

#### CHAPTER IV

#### RELIABILITY PROGRAM AS CAPITAL INVESTMENT

A reliability program is a capital investment with the return on the investment based on benefits due to reduced maintenance costs. A capital investment is an investment of funds with the expectation of incurring a greater return. Five commonly used methods of evaluating a capital investment are:

- 1. Computation of return on investment: Percent of investment returned each year of investment.
- 2. Payback period: Time required to recoup investment at zero discounting.
- 3. Ratio of benefit to cost: Total return divided by amount of investment.
- 4. Net return: Total return less cost of investment.
- 5. Discounted benefit/cost ratio and discounted net return: Return reduced by a preset amount usually compounded yearly.

In his study, Coppola used number 3 above and computed the return on investment for each reliability case and used actual field failure data from three comparable avionic systems as inputs to a computer simulation model. The model uses standard economic analysis procedures to compute the

return in reduced maintenance costs of a system procurred with a complete reliability program as a basis for comparing with another system which was procured without any or little reliability activity. Included in the program is a model to compute the cost of a complete reliability program. Costs of the reliability program were based on a thorough and complete reliability effort including the following program elements.

- Screening of all microcircuits to MIL-STD-883,
   Class B.
- Screening of all semiconductors to JAN "TX" specifications.
- A burn-in of 100 hours of all critical assemblies (e.g., power supplies, etc.).
- 4. Performance of reliability allocations, predictions and design review activity.
- 5. A 5000 hour reliability evaluation test.
- 6. A formal reliability demonstration to test plan III of MIL-STD-781B, Test Level F.
- 7. A 50 hour burn-in of each system produced.
- 8. A failure analysis of each failure encountered during the above tests.

In developing the computer program, the definition for return on investment (ROI) was designated as annual return divided by the investment cost, and annual return was defined to be the savings in maintenance costs due to the

application of a reliability program. The investment cost includes the cost of performing each reliability program element, the labor overhead charges and the increase in G and A(general and administrative overhead) and profit that is caused by the use of a reliability program.

ROI = 
$$\frac{NC_1}{C_2 (1 + k_1)(1 + k_2)}$$

Where N = number of failures avoided each year because of the reliability program

C1 = cost to repair a failure

C<sub>2</sub> = cost of the reliability program including labor overhead.

k, = G & A overhead.

k2 = fee or profit.

The factors of the above equations were expanded into 34 variables and a computer program computes ROI from these variables. In a sensitivity analysis, return on investment was iterated with each one of the 34 variables doubled one at a time and the results compared to the original ROI.

Case 1 in Coppola's simulation consisted of 564 systems with 13,553 parts per system and Case 3 consisted of 335 systems with 11,545 parts per system. Case 1 had little or no reliability effort compared with Case 3 which had a thorough reliability program.

#### CHAPTER V

#### REVIEW OF LITERATURE

Reliability program costs for current military and commercial electronic equipment range from 7 to 30 percent of the contract price for high reliability equipment. In the early 1950's, before a reliability program for military equipment was mandatory, the yearly cost of maintaining and repairing some equipment exceeded the contract price of the equipment. Consequently many studies have been performed to show that a reliability program is a good investment of capital for electronic equipment. The most common method of measuring the worth of a capital investment is to compute the return on investment of the capital outlay. This is the method used in a study by Coppola (1974).

Black and Proschan (1959) used models to minimize shortages subject to cost restraint with demand probability density for spares assumed a priori. In another model, they maximized system reliability with optimal allocation of spares subject to a linear restraint with the demand for spares depending on actual field failures with known probability failure distributions. The models used were non-linear functions and were solved by a nonlinear programming method for maximizing a nonlinear function subject to

linear restraints.

Everett (1963) showed that the LaGrange multiplier method of solving constrained maximum problems can be applied to any type of problem if the constraints can be represented as bounds. The method does not guarantee a solution but if one is found, it is an optimum solution. He states that "the method has good potential for solving problems of optimal allocation of a number of resources to a number of independent ventures where the total payoff is the sum of the payoffs that accrue from each venture."

Federowicz and Mazumda (1968) developed a geometric programming model to determine the cost of achieving a predicted reliability level assuming the allocation of redundant elements is optimal. The model design can be used with linear and nonlinear constraints and random failures.

In a study of the SST aircraft system concept edited by English, Howard (1968) measures the return on investment by using the discounted cash flow method which is based on the time value of money or compound rates of return. The Civil Aeronautics Board calculates return on investment as a straight line depreciation method using a

<sup>12</sup>J. Morely English, <u>Cost-Effectiveness The Economic</u>
<u>Evaluation of Engineered Systems</u> (New York: John Wiley and Sons, 1968), p. 177.

10 or 15 year life period. The time value of money is not considered. It does not assume that a dollar now is worth more than in the future. 13

Thorne and Carlson (1970) treat profit on an investment as income generated minus expenses and show that return on investment has many variations. 14 Payout time is the time required to recoup the initial investment. Payout time with interest applies an interest charge on the fixed investment remaining or applies an interest charge on the working capital and fixed capital. It is more common to use payout time without interest than payout time with interest. The return on original investment is the ratio of average annual cash flow to the original investment. A variation of this is the return on average investment in which the divisor is the average outstanding investment and it depends on the depreciation schedule used. The discounted cash flow. interest rate of return method, profitability index, internal rate of return or investor's method adjust cash flows over the life of a project to a fixed point in time using compound interest. The fixed point in

<sup>13</sup> Ibid., p. 202.

<sup>14</sup> F. C. Jelen, Cost and Optimization Engineering (New York: McGraw-Hill Book Co., 1970), pp. 85-88.

time used is the original investment time. The venture worth or incremental present worth method uses discounting at a fixed rate and depends on life of the project.

Thuesen, Fabrycky and Thuesen (1977) show that an investment is described by cash receipts and disbursements anticipated if the investment is undertaken. Present worth is an amount at the present that is equal to investment cash flow at a given interest rate. The payback or payout period is the length of time to recover the initial cost of an investment. Prospective value is a recently developed basis that measures investment desirability considering that the rate representing a minimum desirable return is greater than the rate money can be invested.

<sup>15</sup>H. G. Thuesen, W. J. Fabrycky, and G. J. Thuesen, Engineering Economy (Englewood Cliffs, N. J.: Prentice-Hall, Inc., 1977), pp. 135-156.

#### CHAPTER VI

#### SIMULATION PROGRAM AND RELIABILITY ANALYSIS

When Coppola's simulation program was transcribed to program coding sheets for card punching, three errors were identified in the typing format.

- 1. Entry 0940 reads CABI=G+H
  Correct reading is CABI=G\*H
- Entry 1210 reads PRINT: 75, CM,CL,CT,SS
   Correct reading is PRINT 75,CM,CL,CT,SS
- 3. Entry 1310 reads 50 FORMAT(3X,2F(12,0,F8.3,F8.3))
  Correct reading is 50 FORMAT(3X,2F(12.0,F8.3,F8.3))

After the above corrections were made, the program was then run on FTU computer link. The job failed because the FTU computer link would not accept the PRINT statements as written in entries 0760, 0820, 1200, 1230, 1260, 1290, and 1320. Further investigation revealed that these print statements would be accepted on a Honeywell 635 computer system. In order to run the program on the FTU computer link, the PRINT statements were changed to a PRINT and FORMAT statement. The corrected simulation program was successfully run using Coppola data and the data print out verifies his results. The simulation run is included in this report as Appendix B.

Coppola's corrected computer program was used to perform an analysis of Mod 3 reliability as a capital investment. The results of this computer run are included in Appendix C. Case I used the data from the Mod 3 GERTS and case 3 used the data from the Mod 3 RGS. Case 2 values were not changed for this computer run. The field failure rates of GERTS and RGS were divided by the number of parts in each system to put the values of V(1) and V(6) in the same units of measure as used by Coppola, failures per part hour. The following list shows which variables and values were changed to run the computer program for Mod 3 comparisons.

VARIABLE	NAME	OLD VALUE	NEW VALUE
V(1)	FR W/O REL	6.5X10 <sup>-6</sup>	10.86x10 <sup>-8</sup>
V(2)	No. Parts	13553	16953
V(3)	No. Systems	564	1
V(4)	Op Hrs/Mo	45.5	120
V(6)	FR W Rel	1.7X10-6	5.9X10 <sup>-8</sup>
V(2)	(Case 3)	11545	18753
V(3)	(Case 3)	335	1

The descriptions of the 3 cases used in this computer run are summarized in Table I.

TABLE I - DESCRIPTION OF CASE STUDIES

CASE	PARTS/SYSTEM	TOTAL SYSTEMS	COST/SYSTEM
I	16,953	1	\$12,620,000
II	3,293	325	35,000
III	18,753	1	21,417,000

Table II presents the results of ROI analysis where the cost of reliability does not consider spares savings.

TABLE II - RESULTS OF ROI WITHOUT SPARES SAVINGS

CASE	CR	ROI(1)
I	\$2,323,314	0.00013
II	5,114,711	0.004
III	2,420,308	0.00014

The above results do not reflect the same results that Coppola obtained with his systems. Case I does not show a higher ROI than Case III. Moreover, the Case II results are considerably different from what he obtained in his computer simulation.

Table III presents the results of ROI analysis where the cost of reliability is reduced by spares savings.

TABLE III - RESULTS OF ROI WITH SPARES SAVINGS

CASE	CR	ROI(2)
- I	\$2,323,037	0.00013
II	5,101079	0.00400
III	2,419,756	0.00014

In Table III above the CR entries are slightly different from those in Table II; however, the percentages for ROI(2) are the same as those for ROI(1). This is not the type of results that Coppola obtained with his simulation using hundreds of systems. Again, Case II does not reflect the results that Coppola obtained.

Table IV indicates the analysis of reliability as a capital investment where spares savings are not considered. Benefit/Cost is the ROI multiplied by the expected number of years of service. The expected number of years of service was chosen as ten years, the same value Coppola used in his simulation study. The Discounted B/C(benefit/cost) ratio is obtained by multiplying ROI by a present worth factor. The present worth factor is obtained from Table IV in the Coppola report and is based on discount rate of ten percent compounded annually. The net return is computed by multiplying the Benefit/Cost by capital investment cost and then subtracting the capital investment cost. Discounted net return(Discounted NR) is then computed by multiplying the

Discounted B/C by the investment cost then subtracting the investment cost.

TABLE IV - ANALYSIS OF RELIABILITY AS A CAPITAL INVESTMENT WITHOUT SPARES SAVINGS

MEASURE	CASE I	CASE II	CASE III
ROI (%)	0.013	0.4	0.014
Payback(years)	7,675	268	7,228
Benefit/Cost	0.13	4	0.14
Discounted B/C	0.0008	0.025	0.0009
Net Return(\$X10 <sup>6</sup> )	-2.02	15.34	-2.08
Discounted NR (\$X106)	-2.32	-4.99	-2.40

The results in Table IV do not reflect the same results as Coppola obtained. Payback in years in Table IV for Case I is greater than Case III, which is opposite from Coppola's results. Also, the Net Return and Discounted NR for both Case I and III are negative values; and another interesting point is that the number of years for payback is in the thousands.

Table V shows the analysis of reliability as a capital investment with spares savings subtracted from investment cost. These results are very close to the results in Table IV above which are considerably different from the results Coppola obtained in his analysis.

TABLE V - ANALYSIS OF RELIABILITY AS A CAPITAL INVESTMENT WITH SPARES SAVINGS

MEASURE	CASE I	CASE II	CASE III
ROI(%)	0.013	0.4	0.014
Payback (years)	7674	267	7226
Benefit/Cost	0.13	4	0.14
Discounted B/C	0.0008	0.025	0.0009
Net Return(\$X10 <sup>6</sup> )	-2.02	15.30	-2.08
Discounted NR (\$X10°)	-2.32	-4.97	-2.42

Coppola's results show that the Net Return and Discounted NR are greater when spares savings are subtracted from investment cost. In Table IV and V above there is no change in these values.

The sensitivity analysis results in Appendix C compare favorably with those in Appendix B which uses Coppola data in the simulation.

#### CHAPTER VII

#### ANALYSIS OF SYSTEM SIMULATION

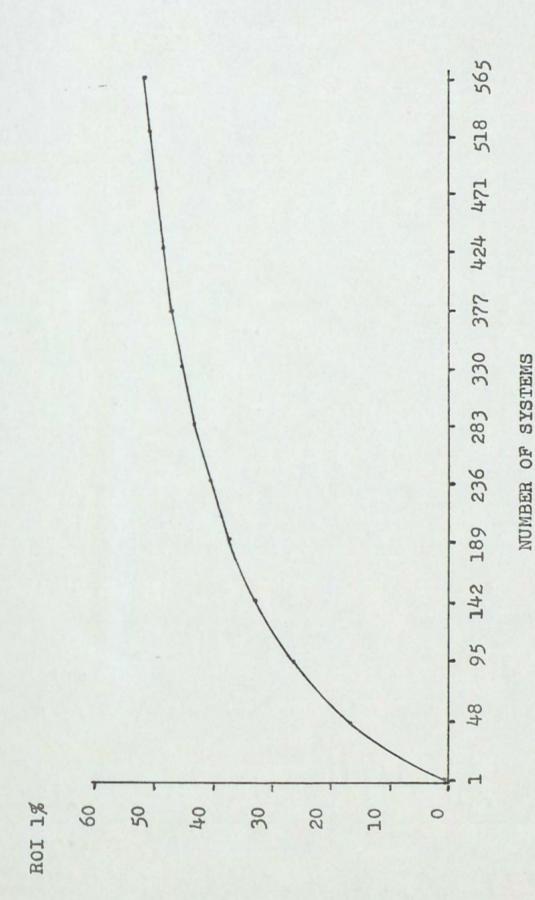
In the computer simulation run using the Mod 3 Track data as inputs, the return on investment(ROI) for Case I and Case 3 is opposite to the results Coppola obtained in his simulation. In order to investigate the effect the number of systems has on the return on investment, a computer simulation run was made using Coppola data and varying the number of systems from 1 to 565 in steps of 47.

The print out of the results of this computer run is shown in Appendix D. Graph 1 illustrates the change in ROI 1 as the number of systems is varied and shows the number of systems versus ROI 1 is a hyperbolic type relationship.

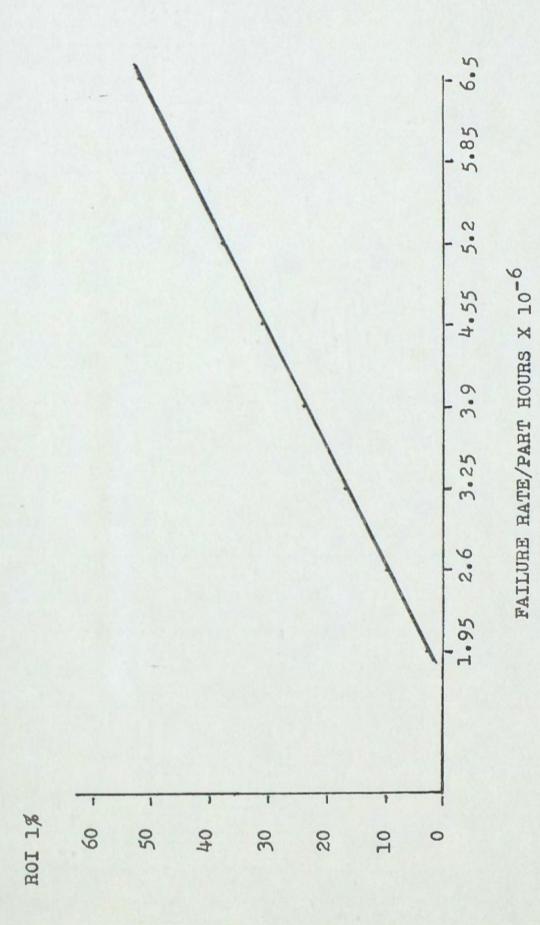
The relationship between failure rate and ROI 1 was investigated by making a computer run with Coppola data and varying the failure rate from 0.325X10<sup>-6</sup> to 6.825X10<sup>-6</sup> in steps of 0.325X10<sup>-6</sup>. The print out of the results of this computer run is included in Appendix E. Graph 2 shows system failure rate versus ROI 1 as the Coppola data system failure rate without reliability approaches the system failure rate with reliability. The graph illustrates that this relationship is linear.

Cost of Reliability(CR) for Case 2 in the Mod 3 simu-

lation run is considerably different from CR in the Coppola simulation run. The reason for the difference is that the failure rate for Case 3 is used to calculate CR in each computer simulation and V(6), failure rate with reliability, is  $5.9 \times 10^{-6}$  in Coppola data inputs and  $1.7 \times 10^{-8}$  for Mod 3 data inputs in the simulation runs.



GRAPH 1 - SYSTEMS VERSUS ROI 1



GRAPH 2 - FAILURE RATE VERSUS ROI 1

#### CHAPTER VIII

## CONCLUSIONS AND RECOMMENDATIONS

#### Conclusions

The objective of this study was to demonstrate the accuracy of the Coppola report and verify his conclusions in order to apply the simulation method to a pair of radar systems.

The problem of this study was to apply the simulation technique to a pair of radar systems which have reliability histories similar to the Coppola examples to verify his conclusions that reliability is a good capital investment.

The results of this study show that the Coppola simulation program was verified by running the program on the FTU computer link. The computer print out data verified the accuracy of the Coppola report data, and based on his data and simulation technique, his conclusions were also verified.

When the simulation technique was applied to a pair of radar systems, the Coppola conclusions were not verified.

Two reasons for this are documented in Appendix D and E as follows:

1. The simulation program is sensitive to the number

- of systems used as input data which is illustrated with Graph 1 in Chapter VII.
- 2. The simulation is sensitive to the difference between the failure rates which is illustrated in Graph 2 in Chapter VII.

#### Recommendations

Based on the findings, observations, and analyses of this study the following recommendations are submitted for the reader's consideration:

- 1. No further sensitivity analysis is required.
- 2. Capital should be invested in a reliability program as a contract item when electronic equipment is procured.

#### APPENDIX A

#### SYSTEM FUNCTIONAL CONFIGURATION

For reliability purposes, Mod III Track is subdivided into specific cabinets or cabinet groupings which have relatively independent operational and failure effect characteristics. The following listings show the units and a discription of the operational characteristics of the equipment. Failure rate calculations are included.

# UNITS 1 and 2, TRACK TRANSMITTER

These two units are identical; either unit may be selected as the prime unit at the option of the Track Console Operator. The transmitter accepts coded 14-pulse message groups from the Encoder, Unit 6. The pulses are transformed into 60kw, X-band, RF pulses by a tunable magnetron power oscillator in the main transmitter. Two levels of radiated power are used during normal operation of the transmitter. Radiation is at lower power until the missile has traveled 12 miles when power changeover is controlled by two micro switches on the range servo gear train.

Transmitter Junction Box, Unit 3 (consisting of terminal boards, ledex switch, toggle switches and cabling) provides interconnections between the two Transmitters, Track

Console and Recorder. A failure in this unit shall be assessed to the unit affected, Unit 1 or 2.

### UNIT 4, TRACK CONSOLE

The Track Console is primarily used to monitor the condition of the position tracking radar equipment. It is also used as a maintenance device to isolate troubles in a unit, equipment or assembly.

The operation of the Track Console consists of those procedures which must be performed to turn on and adjust the subsystem units and to verify operational status. The latter includes: the monitoring of the controls and indicators for proper position and display; the automatic equipment checkout; and the manual checkout and calibration required to bring the equipment to the standby condition.

### UNIT 5, RANGE DATA

The timing pulse generator panels contained in Unit 5 generate the basic timing pulse sequence for the position tracking radar equipment. This unit also contains the range tracking servo which provides the pulse transmitted to return pulse time from which range is derived.

## UNIT X5, EXTENDED RANGE DATA

Unit X5 is part of the Extended Range Tracker group which includes Cabinet X6 and X62. The group is an electronic range gate system that provides space launch guidance capabilities beyond the 800-mile-plus limitations of the mechanical data unit in Cabinet 5.

## UNIT 6, ENCODER

Timing pulses generated in Unit 5 are used to generate the sequence of pulses designated the ABC pulse repetition frequency. These pulses occur at a rate of approximately 300 Hertz and each pulse initiates transmission of a specific message to the missile.

## UNIT X6, EXTENDED RANGE ENCOCER

Unit X6, part of the Extended Range Tracker group, provides the timing for Unit X5.

#### UNIT 7, ANGLE DATA

Unit 7 contains the angle data handling equipment and part of the range data handling equipment. The latter computes the range of the missile in flight and generates fine and coarse tracking gates which switch on the receiver for reception of the video returns. The angle data handling equipment extracts azimuth and elevation data from angle encoders on the antenna. These encoders derive this data from the physical position of the antenna.

### UNIT 8, POWER DISTRIBUTION

Unit 8 controls the distribution of power to all the units of the position tracking equipment. A failure occurring in this unit is assessed with respect to the cabinet or function of the position tracking equipment effected by the malfunction. For example, a failure to circuit breaker number 1 which controls the load to the radome air conditioner would not be assessed as a failure against

primary mission objectives since the absence of air conditioning in the radome for the short period that the missile is controlled in flight is considered noncritical. Circuit breaker number 8, however, which controls power flow to the receiver, would be assessed in-line criticality in case of failure.

#### UNIT 9, CHECKOUT TRANSMITTER

The Checkout Transmitter, Unit 9, is used to simulate beacon response during manual or automatic checkout of the position tracking radar equipment. The maximum power output of the Checkout Transmitter is 1 watt. The power output may be adjusted by a motor driven attenuator controlled by a switch on the Track Console, Unit 4. A coaxial switch couples the output to the boresight tower or to a test horn located between the two monopulse reflectors in the radome.

This transmitter is used to perform system calibration, verification and operation tests. It is not essential to fulfillment of primary mission objectives and, therefore, its failures cannot be included in the assessment of Mod III Track reliability.

## UNIT 10, TRANSLATOR

The Translator houses automatic checkout control equipment circuits which simulate the missile decoder and pulse beacon and test message comparator circuits. The purpose of the equipment is to perform an automatic or manual checkout of the position tracking radar equipment on a

Go/No Go basis during countdown or standby. Automatic checkout is accomplished by a series of 13 discrete tests. Although the Translator is a piece of checkout equipment, it does not contribute any in-line functions.

#### UNIT 11, ANTENNA MOUNT

The Antenna Mount consists primarily of: a conical acquisition antenna; two monopulse reflectors; antenna ele-vation drive motor; antenna azimuth drive motor; two angle data encoders; mount junction boxes; a camera and the antenna mount proper.

#### UNIT 12, RF EQUIPMENT

Unit 12 is one part of the receiver group which is a three-channel radar receiver system incorporating the receiver principles of conical scan acquisition and monopulse tracking. The conical scan acquisition mode is used to acquire the missile whereas the monopulse tracking mode provides tracking data after the missile has been acquired.

During monopulse tracking, the nominal 300 pps beacon replies received by the two horns of the monopulse antenna are coupled through waveguides to a magic T comparator. The signals are added, subtracted, phase shifted and finally converted to a 30 mega Hertz IF signal in waveguide mixers and passed through separate monopulse preamplifiers to Receiver Unit 13.

#### UNIT 13, RECEIVER

The 30 MHz IF signals from the monopulse preamplifiers in Unit 12 are routed through coaxial cables to the monopulse main IF amplifier unit in Unit 13. The separately preamplified signals are routed through separate IF amplifier stages for further amplification before detection.

#### UNIT 14, RADOME

Unit 14, Radome, is positioned by the Radome servo which is slaved to the antenna azimuth servo in normal operation.

#### UNIT 15, AZIMUTH MOTOR GENERATOR

Unit 15 provides further amplification of the dc drive signal from the main servo amplifier and in turn supplies power for the motor that drives the antenna in azimuth. The failure of the antenna to be driven in azimuth would cause loss of azimuth data. Therefor, Unit 15 is an In-line item.

### UNIT 16, ELEVATION MOTOR GENERATOR

This unit functions in the same manner as Unit 15, except it supplies power for the antenna elevation motors.

It also is an In-line item.

## UNIT 17, RADOME MOTOR GENERATOR

This unit functions in the same manner as Unit 15, except it supplies power for the motor moving the radome in the azimuth plane. If the radome does not move in the direction of the missile, then the antenna radiation will be

obstructed. Consequently, this is an In-line unit.

## UNIT 18, GYRO MOTOR GENERATOR

The Gyro Motor Generator provides the excitation for the azimuth and elevation gyros. The gyros and the associated precession amplifiers provide velocity feedback signals. Therefore, it is an In-line unit.

#### UNIT 19, RADOME AIR CONDITIONER

The entire radome is air conditioned to protect the equipment against dust and changes in temperature. However, lack of air conditioning in the Radome for the short period of a launch vehicle flight is not considered to be critical. Therefore, the unit is regarded as not In-line.

#### UNIT 20, SERVO CABINET

Unit 20 processes Azimuth, Elevation and Radome error signals and applies error correction signals to the Azimuth, Elevation, and Radome motor-generators (Units 15, 16, and 17) which provide the driving signals for the antenna and radome.

## UNIT 21, MOTOR FIELD SUPPLY

The azimuth motor field supply provides 100 volts do for the field windings of the azimuth drive motor. Loss of this supply would be critical; therefore, Unit 21 is an Inline unit.

# UNIT 34, ANTENNA AND BORESIGHT ASSEMBLY

This is checkout equipment used during countdown and other checkout procedures, but not used during the liftoff

and flight phases of a mission. Therefore, this equipment is classified as not In-line.

#### UNIT 29, OPTICAL TRACKER

The Optical Tracker is pointed toward the missile durflight by the Optical Tracker Operator (via visual contact).

It generates electrical signals corresponding to the azimuth and elevation of the missile. The signals can be manually selected by the Track Console Operator to drive the antenna servo system for acquisition, or reacquisition in case of a failure in the designate mode of operation. For failure assessment purposes, it is classified as not In-line.

#### UNIT 30, WAVEGUIDE AND CABLE ASSEMBLY

The majority of the waveguide and cables are In-line; however, each is assessed according to the classification of the function it performs.

## UNIT 31, TRACK JUNCTION BOX

The majority of Unit 31 is In-line; however, the functions affected by failures in this unit are the basis upon which a failure is assessed.

## UNIT 37, VOLTAGE REGULATOR

Unit 37 is a commercial regulator for critical power and classified as In-line.

## UNIT 33, RECORDER NO. 1

Unit 33 serves the same as Unit 32.

## UNIT 38, FOUNDATION JUNCTION BOX

Most of Unit 38 is In-line; however, each failure in the Junction Box is assessed on the basis of the classification of the function that the cable or item in the Junction Box performs.

#### UNIT 39, RECORDER NO. 3

Unit 39 serves the same function as Unit 32.

#### UNIT 50, TEST EQUIPMENT SERIES

The Test Equipment Series is composed of a Range and Timing Simulation, Autosequence Tester, Command Simulator and Receiver Simulator Console. Since this is checkout equipment, it is not In-line.

#### UNIT 62, EXTENDED RANGE CONSOLE

Unit 62 is an operating console for Units X5 and X6.

## UNIT 32, RECORDER NO. 2

Unit 32 is an 8-channel Sanborn Recorder that provides analog data as a check on system performance. The recorder measures eight of the Track parameter for quick-look purposes during the flight phase. Since this equipment performs a monitoring function, it is classified as not Inline for the purposes of failure assessment.

#### SYSTEM FAILURE RATE CALCULATIONS

The Mod III RGS Track system failure rate is calculated by summing the failure rates of the individual unit cabinets. To calculate a cabinet failure rate, the cumulative number of failures in a cabinet is divided by the cumulative hours of operation of the cabinet.

UNIT	NAME	HOURS	FAILURES	FAILURE RATE
1	Transmitter	3010	1	.0003322
5	Range Data	26072	1	.0000384
6	Encoder	26073	4	.0001534
7	Angle Data	26066	3	.0001151
11	Antenna Mount	25639	5	.0001950
12	RF Equipment	25773	1	.0000388
13	Receiver	25773	6	.0002328
	System Total			.0011057

# APPENDIX B

COMPUTER PROGRAM WITH COPPOLA DATA

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CKET=V(20)*AX

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AA=1/(V(6)*V(17)*V(13)*V(19)*V(19)*V(2)

CKUT=AA*AB

CSAI=V(17)*V(17)*V(13)*V(19)*V(19)*V(19)*V(6)*V(2))

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#### APPENDIX C

COMPUTER PROGRAM WITH MOD III TRACK RADAR DATA

JOR 471

INI	DATE = 78141														5
SYSPR															L PRUG
DDNAME SYSPRINT											FEODT	Errok!		DIE TO DE	
PHOCSTEP	2.0 MAIN	INITIAL STATEMENTS DIMENSION V(34) V(1)=10.86/10**8	(2)=16953 0 PAKTS	(3)=1 0 SYSTEMS (4)=126	F HPS/MO (35 FH*1.3)	(6) = 5.9/10**8	1"	(3)=0.1	(9) = 10	(10)=2.2 (10)=2.2		*	(13)=2.5		
STEP FORT	G1 RELEASE 2	0 0	L>Z	0	0	U (	ر ک	ט נ	: >i	ا>لا	;>u	) (	ة>ك د	.><	
***LT005***	FORTRAN IV	0001	0003	5000	9000	2000	0000	6000	0010	0011	0012	0013	0014	0015	0016

PART /SPECIAL ASSM  AN: ASSM (REL. PARTS · FAIL ANAL)  SRET/FLD FR  MTBF  JLTS OF SPEC MTBF	MAIN DATE = 78141	FR IN MOS  & RQT"ON" TIME  /TOTAL PARTS
SPECIAL ASSM/PART V(16)=100 FURN-IN HOUPS/SPECIAL A V(17)=5 S/HR TECHNICIAN V(18)=100 PARTS/SPECIAL ASSM V(19)=24 ENG HPS/FAIL (REL.PARTS V(20)=500) RET HRS V(21)=7 FW IN ASSM BISRET/FLD F V(22)=2 SPEC MIBE/FLD MTBF V(23)=10.8 TEST HRS IN MULTS OF SP	2.0	V(24)=50 SYSTEM BI HRS/EA V(25)=3 SYSTEM BI FR/FLD FR V(26)=0.15 G&A V(27)=0.1 FEF V(29)=2 UKU NRT\$ V(29)=2 UKU NRT\$ V(29)=2 UKU NRT\$ V(30)=11000 \$/SPARE LRU V(31)=300 \$/SPARE LRU V(32)=0.05 HRS ASSN 917DAY V(34)=2 CALENDAR TIME/RET & RQT V(34)=2 CALENDAR TIME/RET & V(34)=2 CALENDAR TIME/RET & V(34)=2 V(33)=0.23
00000000	RELEASE	0000000000
0017 0018 0019 0020 0021 0022 0023 0024 ***LTOP***	FORTRAN IV G1	0025 0026 0027 0028 0029 0031 0032 0033 0034

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CABI=G*H

AX=V(17)*V(13)*V(34)+V(6)*V(21)*V(2)*V(9)*V(10)*V(19)

CRET=V(20)*AX

AA=1/(V(6)*V(2))*V(22)*V(23)

AB=V(17)*V(13)*V(24)*V(34)+V(6)*V(10)*V(10)*V(19)*V(2)

CROT=AA*B

CSBI=V(3)*V(24)*(V(17)*V(13)+V(9)*V(10)*V(19)*V(6)*V(2))

CT=CABI+CRET+CROT+CSBI

CR=(CA+CL+CT)*(1+V(20))*(1+V(27))

SO=V(1)*V(2)*V(3)*V(4)*(1-V(28))*V(29)

SO=V(1)*V(2)*V(3)*V(4)*V(28)*V(29)

SO=V(1)*V(2)*V(3)*V(4)*V(28)*V(29)
13 V(2) = 3293

14 V(2) = 3293

V(3) = 8000

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V(3) = 90.27

PRINT 22

22 FORMAT (7H CASE 2/)

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V(4-1)=V(N-1)/2
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C=YPI/YPI8
D=CI/CIB
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## APPENDIX D

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AA=1/(V(6) *V(2)) *V(22) *V(23)

AA=V(17) *V(13) *V(24) *V(34) +V(6) *V(19) *V(10) *V(19) *V(2)

CRGT=AA*AB

CSF1=V(3) *V(24) * (V(17) *V(13) +V(9) *V(10) *V(19) *V(6) *V(25) *V(2))

CT=CAF1+CHET+CAFT+CSFT

CF=CAF1+CHET+CAFT+CSFT

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SN=V(6) *V(2) *V(3) *V(4) *V(4) *V(28) *V(29)

SN=V(6) *V(2) *V(2) *V(4) *V(4) *V(4) *V(28) *V(29)

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PRINT 55,K,CR,R011,YP1,CI,R012,YP2,SYS
FOAMAT (1X,12,2(F12.0,F8.3),F8.3),6X,1(F8.3))
CONTINUE
V(3) = (V(3)-1)+((N-1)*47)
CONTINUE
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YP2=1/RUI1
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SYS	565.000 SYS	518,000 SYS	471.000 SYS	424,000 SYS	377.600 SYS	330.000 SYS	283.000 SYS	236.000 SYS	189.000 SYS	142,000 SYS	95.000 SYS	48.000 SYS	1.000 SYS	-46.000
YP2	0.999 YP2	1.633 YP2	1.074 YP2	1.124 YP2	1.186 YP2	1.266	1.373 YP2	1.523 YP2	1.746 YP2	2.118 YP2	2.858 YP2	5.046 YP2	212.923 YP2	-3.992
ROIZ	1.001	0.968 R012	0.931 RUIZ	0.650 RUIZ	0.843 RUIZ	0.790 R012	0.728	0.657 HUIZ	0.573 R012	0.472	0.350 R012	0.198 HU12	0.005 R012	-0.250
CI	5011450.	4751392.	4491335. C1	4231274.	3971216. CI	3711155. CI	3451096. CI	3191039.	2930979. CI	2670918.	2410858. CI	2150799.	1890739.	1630681.
YP1	1,912	1.946 YP1	1.987 YP1	2°037	2.100 YP1	2.180 YP1	2.287 YF1	2.436 YP1	2,660 Y21	3.032 YP1	3.771 YP1	5,959 YP1	213,837 YP1	-3.079
K011	U.523	0.514 HO11	0.503 RUII	6.491 HUII	ROI1	R011	0.437 RUII	0.411 HOII	R011	0.330 RUII	0.265 ROIL	W.168	ROI1	-0.325
CR	9593785.	8952541.	8311296.	CR 7670051.	7028808.	6387562.	5746318.	5105074.	4463828.	3822584.	3181340.	2540095.	1898850.	1257607.
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# APPENDIX E

## FAILURE RATE VERSUS ROI 1

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PAUCSTEP D	2.0 MAIN	INITIAL STATEMENTS DIMENSION V(34) V(1)=6.5/10**6	FLO FR W/U REL PROG V(2)=13553	V(3)=564	V(4)=45.55	V(5)=250	V(6)=1.7/10**6	V(7)=2	CUST OF SCREENS/PART	MAT Jr.1 V(9)=10	ENG S/HR	ENG ON FACTOR	ENG MIZPART FOR REL EFFORT	0C 5/11/2	FACTORY CH FACTOR	ADDITIONAL OC MH/PT DUE	SHECTAL ASSMIPART	RUMM-IN HOURS/SPECIAL A	V(17)=S S/HH TECHNICIAN	V(18) = 1000 1 1 1 000 0	V(19)=24	ENG. HRS/FAIL (REL. PARTS, FAIL
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V(20)=5000 RET HFS V(21)=7 FR IN ASSM BISRET/FLD FR V(22)=2 SPEC WIRF/FLD MIBF V(23)=16.8 TEST M.S IN HULTS OF SPEC MIBF	EASE 2.0  V(24) = 50  SYSTEM STEMS FALLOFR V(20) = 3 IFRFLD FR  V(20) = 10.15  V(20) = 10.10  V(20) = 10.01  V(20) = 10.00  V(30) = 10.00  V(
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0021 0022 0023 0024 *LTUP***	FORTRAN IV 61 0025 0026 0027 0028 0028 0029 0032 0032 0032 0033 0034 0036 0036 0036 0036 0036 0036

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NOTERM, NOID, E. BCDIC, SOURCE, NOLIST, NODECK, LOAD, NOMAP, NOTEST NAME = MAIN , LINECNT = 50
                                                    CK-1 = AA + AB

CS-1 = V (3) *V (24) * (V (17) *V (13) *V (10) *V (19) *V (6) *V (25) *V (2))

CT = CA - (1 + CRE1 + CB - V (1 + V (2 +
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       AA=1/(v(6) &v(2)) &V(22) &V(23)
AC=V(17) &V(13) &V(34) +V(6) &V(9) &V(10) &V(19) &V(2)
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FORMAT (1X, 12, 2 (F12, 0, F8, 3, F8, 3), 6X, 1 (F12, 9))

CONTINUE

V(1) = V(1) *20/N

CONTINUE

STOP

END
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		FR	0.000000325 FH	0.000000650 FR	0.000000975 FR	0.000001300 FR	0.000001625 FR	0.000001950 FR	0.000002275 FR	0.000002600 FR	0.000002925 FR	0.000003250 FR	0.000003575
S SPECIFIED LIST, LFT S1ZE=(116736,34816) HAS BEEN ADDED TO DATA SET	DUNAME FTO6F001	YP2	-7.591 YP2	-9.658 YP2	-13.578 YP2	-23.868 YP2	-123.335 YP2	35.814 YP2	15.055 YP2	9.289 YP2	6.592 YP2	5.010 YP2	3.984 YP2
	DDN	ROIZ	-0.132 K012	-0.104 HC12	-0.074 ROIZ	-0.042 ROIZ	-0.008 ROIZ	0.028 ROIZ	0.066 R012	0.108 RCI2	0.152 R012	0.200 R012	0.251 R0[2
	CSTEP	CI	.0890464.	10580751.	10271038. CI	9961325.	9651613. CI	9341999. CI	9032186. CI	8722473. CI	8412761. CI	8103048.	7793334.
OR OPTIONS N(S) USED EXIST BUT	PAUCST	YP1	-6.67d	-8.745 YP1	-12.664 YP1	-22.954 YP1	122,422 YP1	36.727	15.96a YP1	10.202	7,495 YP1	5.924 YF1	4.897 YP1
FBS-LEVEL LINKAGE FOITOR OP DEFAULT OPTION(S) ***GO DOES NOT EXIST	EP 60	ROII	-0.150 R011	-V:114	-0.079 R011	-0.044 ROII	-0.008-1 R011	U.027	0.053 RCI1	0.098 RUI1	0.133 RUI1	0.169 RUII	HO1104
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