

Whitney Multiapproximation

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Abstract

In this article we prove that Whitney theorem for the value of the best multiapproximation of a function $f \in L_p([a, b]^d)$, $0 < p < \infty$ by algebraic multipolynomial p_{m-1} of degree $\leq m - 1$.

1. Introduction, definitions and main result

Whitney theorem has applications in many areas and has been further generalized to various classes of function and other approximating spaces .

Whitney theorem was proved by Burkill [1] when $(k = 2, p = \infty)$ and Storozhenko [2] when $(0 < p < 1)$.

In [3], [4] Whitney proved that if $f \in C([a, b])$ then $E_{k-1}(f)_{[a,b]} \leq W_k \omega_k \left(f, \frac{b-a}{k}, [a, b] \right)$ where $W_k = \text{const}$ depends only on k .

In 2003 E.S. Bhaya [5] proved the following theorem by using Whitney theorem of interpolatory type for k -monotone functions for K. A. Kopotun.

Theorem A: Let $m, k \in \mathbb{N}$, $m < k$ and $f \in \Delta^k \cap W_p^m(I)$. Then for any, $n \geq k - 1$, there exists a polynomial $p_n \in \Pi_n$ such that for any $p < 1$

$$\| f^{(j)} - p_n^{(j)} \|_p \leq c(p, k) \omega_{k-j}^\varphi(f^{(j)}, n^{-1}, I)_p \text{ for } j = 1, \dots, m.$$

In 2004 S.Dekel and D.Leviatan [6] proved the following Whitney estimate.

Theorem B: Given $0 < p \leq \infty, r \in \mathbb{N}$, and $d \geq 1$, there exists a constant $C(d, r, p)$, depending only on the three parameters, such that for every bounded convex domain $\Omega \subset \mathbb{R}^d$, and each function $f \in L_p(\Omega)$,

$$E_{r-1}(f, \Omega)_p \leq C(d, r, p) \omega_r(f, \text{diam}(\Omega), \Omega)_p,$$

where $E_{r-1}(f, \Omega)_p$ is the degree of approximation by polynomials of total degree $r - 1$, and $\omega_r(f, \cdot)_p$ is the modulus of smoothness of order r .

In 2011 Dinh Dung and Tino Ullrich [7] proved the following Whitney type inequalities

Theorem C: Let $1 \leq p \leq \infty, r \in \mathbb{N}^d$. then there is a constant C depending only on r, d such that for every $f \in L_p(Q)$

$$\left(\sum_{e \subset [d]} \prod_{i \in e} 2^{r_i} \right)^{-1} \Omega(f, \delta, Q)_{p,Q} \leq E_r(f)_{p,Q} \leq C \Omega(f, \delta, Q)_{p,Q},$$

Where $Q := [a_1, b_1] \times \dots \times [a_d, b_d]$ and $\delta = \delta(Q) := (b_1 - a_1, \dots, b_d - a_d)$ is the size of Q .

For the proof our main result we need the following definitions :

Let us introduce a new version of Lagrange polynomial on \mathbb{R}^d , and call it a Lagrange multipolynomial.

Definition 1.1.

A Lagrange multipolynomial $L(x, f) = L((x_1, x_2, \dots, x_d); f)$

$$L((x_1, x_2, \dots, x_d); f) = L((x_1, \dots, x_d); f; (x_{01}, \dots, x_{0d}), (x_{11}, \dots, x_{1d}), \dots, (x_{m1}, \dots, x_{md})) \tag{1}$$

that interpolates a function f at points $x_0 = (x_{01}, \dots, x_{0d}), x_1 = (x_{11}, \dots, x_{1d}), \dots, x_m = (x_{m1}, \dots, x_{md})$ (interpolation nodes) is defined as an algebraic multipolynomial of at most m th order that takes the same values at these points as the function f , that is

$$L(x_i; f) = L((x_{i1}, \dots, x_{id}); f) = f((x_{i1}, \dots, x_{id})) \tag{2}$$

where $i = 0, \dots, m$.

Example, for $m = 1$ we have

$$\begin{aligned}
 L(x; f; x_0, x_1) &= L((x_1, \dots, x_d); f; (x_{01}, \dots, x_{0d}), (x_{11}, \dots, x_{1d})) \\
 &= \frac{(x_1 - x_{11}) \dots (x_d - x_{1d})}{(x_{01} - x_{11}) \dots (x_{0d} - x_{1d})} f((x_{01}, \dots, x_{0d})) + \frac{(x_1 - x_{01}) \dots (x_d - x_{0d})}{(x_{11} - x_{01}) \dots (x_{1d} - x_{0d})} f((x_{11}, \dots, x_{1d})) \\
 &= f(x_{01}, \dots, x_{0d}) + \frac{f((x_{11}, \dots, x_{1d})) - f((x_{01}, \dots, x_{0d}))}{(x_{11} - x_{01}) \dots (x_{1d} - x_{0d})} ((x_1 - x_{01}) \dots (x_d - x_{0d})) \tag{3}
 \end{aligned}$$

where $x_{0j} \neq x_{1j}$, $j = 1, \dots, d$

Definition 1.2.

$$\begin{aligned}
 \text{Let } I_k(x) &= I_k((x_1, \dots, x_d)) = I_k((x_1, \dots, x_d); (x_{01}, \dots, x_{0d}), \dots, (x_{m1}, \dots, x_{md})) \\
 &= \prod_{\substack{i=0 \\ k \neq i}}^m \frac{(x_1 - x_{i1}) \dots (x_d - x_{id})}{(x_{k1} - x_{i1}) \dots (x_{kd} - x_{id})} , \quad k = 0, \dots, m , \tag{4}
 \end{aligned}$$

a new version of fundamental Lagrange multi polynomials.

We set

$$\begin{aligned}
 p(x) &= p((x_1, \dots, x_d)), x \in R^d \\
 &= ((x_1 - x_{01}) \dots (x_d - x_{0d}))((x_1 - x_{11}) \dots (x_d - x_{1d})) \dots ((x_1 - x_{m1}) \dots (x_d - x_{md})).
 \end{aligned}$$

And note that

$$\begin{aligned}
 p((x_{k1}, \dots, x_{kd})) &= \lim_{\substack{j \rightarrow x_{kj} \\ j=1, \dots, d}} \frac{p((x_1, \dots, x_d))}{((x_1 - x_{k1}) \dots (x_d - x_{kd}))} \\
 &= \lim_{\substack{j \rightarrow x_{kj} \\ j=1, \dots, d}} \prod_{i=0}^m ((x_1 - x_{i1}) \dots (x_d - x_{id})) \\
 &= \prod_{i=0}^m ((x_{k1} - x_{i1}) \dots (x_{kd} - x_{id})) .
 \end{aligned}$$

Therefore , for any $k = 0, \dots, m$, the new version of the fundamental Lagrange multipolynomials are represented in the form

$$I_k((x_1, \dots, x_d)) = I_k((x_1, \dots, x_d); (x_{01}, \dots, x_{0d}), (x_{11}, \dots, x_{1d}), \dots, (x_{m1}, \dots, x_{md}))$$

$$= \frac{p((x_1, \dots, x_d))}{((x_1 - x_{k1}) \dots (x_d - x_{kd})) \dot{p}((x_{k1}, \dots, x_{kd}))} ,$$

where $x_j \neq x_{kj}$, $j = 1, \dots, d$, $k = 0, \dots, m$.

Let $\delta_{i,k}$ denote the Kronecker symbol , which is equal to 1 for $i = k$ and to 0 otherwise .

It follows from the obvious equality $I_k(x_{i1}, \dots, x_{id}) = \delta_{i,k}$, $i, k = 0, \dots, m$, that the Lagrange multipolynomial exists and is represented by the relation

$$L((x_1, \dots, x_d); f; (x_{01}, \dots, x_{0d}), \dots, (x_{m1}, \dots, x_{md}))$$

$$= \sum_{k=0}^m f((x_{k1}, \dots, x_{kd})) I_k((x_1, \dots, x_d); (x_{01}, \dots, x_{0d}), \dots, (x_{m1}, \dots, x_{md})) \quad (5)$$

Definition 1.3.

The expression $[(x_{01}, \dots, x_{0d}), (x_{11}, \dots, x_{1d}), \dots, (x_{m1}, \dots, x_{md}); f]$

is called the divided difference of order m for the function f at the points $x_0 = (x_{01}, \dots, x_{0d}), x_1 = (x_{11}, \dots, x_{1d}), \dots, x_m = (x_{m1}, \dots, x_{md})$

For example

$$[x_0, x_1; f] = \frac{f((x_{01}, \dots, x_{0d}))}{(x_{01} - x_{11}) \dots (x_{0d} - x_{1d})} + \frac{f((x_{11}, \dots, x_{1d}))}{(x_{11} - x_{01}) \dots (x_{1d} - x_{0d})}$$

$$= \frac{f((x_{01}, \dots, x_{0d})) - f((x_{11}, \dots, x_{1d}))}{(x_{01} - x_{11}) \dots (x_{0d} - x_{1d})} \quad (6)$$

Let $[x_0; f] = [(x_{01}, \dots, x_{0d}); f] = f((x_{01}, \dots, x_{0d}))$. (7)

Definition 1.4.

The expression

$$\Delta_h^m(f; (x_{01}, \dots, x_{0d})) := \sum_{k=0}^m \left((-1)^{m-k} \binom{m}{k} \right)^d f((x_{01} + kh_1, \dots, x_{0d} + kh_d)) \quad (8)$$

where $d \in \mathbb{N}$ chosen so that $(-1)^{m-k} = (-1)^d$

is called the multi m th difference of the function $f \in L_p([a, b]^d), 0 < p < \infty$ at the point $x_0 = (x_{01}, \dots, x_{0d})$ with step $h = (h_1, \dots, h_d)$.

Denote $\Delta_h^0(f; (x_{01}, \dots, x_{0d})) = f((x_{01}, \dots, x_{0d}))$ and $\Delta_0^m(f; (x_{01}, \dots, x_{0d})) = 0$.

Our main result is:

Theorem 1.1.

If $f \in L_p([a, b]^d), 0 < p < \infty$, then

$$E_{m-1}(f)_{L_p[a,b]^d} \leq C(p, m, d) \omega_m(f; h; [a, b]^d)_p$$

where $h = (h_1, \dots, h_d)$.

Now to prove our theorem we need the lemmas and theorems which will be stated and proved in the following sections :

2. Divided differences

Let us define the difference

$$f((x_1, \dots, x_d)) - L((x_1, \dots, x_d); f; (x_{01}, \dots, x_{0d}), \dots, (x_{m1-1}, \dots, x_{md-1})),$$

by the product $((x_1 - x_{01}) \dots (x_d - x_{0d})) \dots ((x_1 - x_{m1-1}) \dots (x_d - x_{md-1}))$

Using (4) and (5), we represent the quotient at the points $x_1 = x_{m1}, \dots, x_d = x_{md}$ as follows :

$$\frac{f((x_{m_1}, \dots, x_{m_d})) - L((x_{m_1}, \dots, x_{m_d}); f; (x_{0_1}, \dots, x_{0_d}), \dots, (x_{m_1-1}, \dots, x_{m_d-1}))}{\prod_{k=0}^{m-1} ((x_{m_1} - x_{k_1}) \dots (x_{m_d} - x_{k_d}))}$$

$$= \sum_{k=0}^m \frac{f((x_{k_1}, \dots, x_{k_d}))}{\prod_{\substack{i=0 \\ i \neq k}}^m ((x_{k_1} - x_{i_1}) \dots (x_{k_d} - x_{i_d}))}$$

$$= [(x_{0_1}, \dots, x_{0_d}), (x_{1_1}, \dots, x_{1_d}), \dots, (x_{m_1}, \dots, x_{m_d}); f] \tag{9}$$

Theorem 2.1.

The Lagrange multipolynomial $L(x; f; x_0, \dots, x_m)$ is represented by the following Newton formula:

$$L(x; f; x_0, \dots, x_m) = L((x_1, \dots, x_d); f; (x_{0_1}, \dots, x_{0_d}), \dots, (x_{m_1}, \dots, x_{m_d}))$$

$$= [(x_{0_1}, \dots, x_{0_d}); f] + [(x_{0_1}, \dots, x_{0_d}), (x_{1_1}, \dots, x_{1_d}); f]((x_1 - x_{0_1}) \dots (x_d - x_{0_d})) + \dots +$$

$$[(x_{0_1}, \dots, x_{0_d}), (x_{1_1}, \dots, x_{1_d}), \dots, (x_{m_1}, \dots, x_{m_d}); f]((x_1 - x_{0_1}) \dots (x_d - x_{0_d})) ((x_1 - x_{1_1}) \dots (x_d - x_{1_d})) \dots ((x_1 - x_{m_1-1}) \dots (x_d - x_{m_d-1})) \tag{10}$$

Proof:

For $m = 1$, formula (10) follows from (3), (6) and (7) .

Assume that (10) is true for a number $m - 1$.

By induction , let us prove that this formula is true for the number m , that is

$$L((x_1, \dots, x_d); f; (x_{0_1}, \dots, x_{0_d}), \dots, (x_{m_1}, \dots, x_{m_d}))$$

$$= L((x_1, \dots, x_d); f; (x_{0_1}, \dots, x_{0_d}), \dots, (x_{m_1-1}, \dots, x_{m_d-1})) + [(x_{0_1}, \dots, x_{0_d}), \dots, (x_{m_1}, \dots, x_{m_d}); f]$$

$$((x_1 - x_{0_1}) \dots (x_d - x_{0_d})) \dots ((x_1 - x_{m_1-1}) \dots (x_d - x_{m_d-1})) .$$

Since both parts of this equality are multipolynomials of degree $\leq m$, it suffices to prove that this equality holds at all points $x_i, i = 0, \dots, m$.

By the definition of Lagrange multipolynomial (Definition1.1) , for all $i = 0, \dots, m - 1$, we have

$$L((x_{i_1}, \dots, x_{i_d}); f; (x_{0_1}, \dots, x_{0_d}), \dots, (x_{m_1-1}, \dots, x_{m_d-1}))$$

$$+[(x_{01}, \dots, x_{0d}), \dots, (x_{m1}, \dots, x_{md}); f] ((x_{i1} - x_{01}) \dots (x_{id} - x_{0d})) \dots ((x_{i1} - x_{m1-1}) \dots (x_{id} - x_{md-1})) = f((x_{i1}, \dots, x_{id})) + \mathbf{0}$$

$$= L((x_{i1}, \dots, x_{id}); f; (x_{01}, \dots, x_{0d}), \dots, (x_{m1}, \dots, x_{md})),$$

for $i = m$ according to (9) we obtain

$$L((x_{m1}, \dots, x_{md}); f; (x_{01}, \dots, x_{0d}), \dots, (x_{m1-1}, \dots, x_{md-1})) +$$

$$[(x_{01}, \dots, x_{0d}), \dots, (x_{m1}, \dots, x_{md}); f] ((x_{m1} - x_{01}) \dots (x_{md} - x_{0d})) \dots ((x_{m1} - x_{m1-1}) \dots (x_{md} - x_{md-1}))$$

$$= f((x_{m1}, \dots, x_{md})) = L((x_{m1}, \dots, x_{md}); f; (x_{01}, \dots, x_{0d}), \dots, (x_{m1}, \dots, x_{md})) \quad \square$$

Lemma 2.1.

$$L_{x_j}^{(m)}(f) = m! \psi \quad [(x_{01}, \dots, x_{0d}), (x_{11}, \dots, x_{1d}), \dots, (x_{m1}, \dots, x_{md}); f] \tag{11}$$

where ψ is a constant and $j = 1, \dots, d$.

proof:

We have

$$\left(((x_1 - x_{01})(x_1 - x_{11}) \dots (x_1 - x_{m1-1}))((x_2 - x_{02})(x_2 - x_{12}) \dots (x_2 - x_{m2-1})) \dots ((x_3 - x_{03})(x_3 - x_{13}) \dots (x_3 - x_{m3-1})) \dots ((x_d - x_{0d})(x_d - x_{1d}) \dots (x_d - x_{md-1})) \right)^{(m)}$$

$$= \left(x_j^m \prod_{i=0}^{m-1} \prod_{\substack{\ell=1 \\ \ell \neq j}}^d (x_\ell - x_{i\ell}) \right)^{(m)} + \left(c_1 x_j^{m-1} \prod_{i=0}^{m-1} \prod_{\substack{\ell=1 \\ \ell \neq j}}^d (x_\ell - x_{i\ell}) \right)^{(m)}$$

$$+ \dots + \left(c_m \prod_{i=0}^{m-1} \prod_{\substack{\ell=1 \\ \ell \neq j}}^d (x_\ell - x_{i\ell}) \right)^{(m)},$$

where c_1, c_2, \dots, c_m are constant and $j = 1, \dots, d$

$$= m! \left(\prod_{i=0}^{m-1} \prod_{\substack{\ell=1 \\ \ell \neq j}}^d (x_\ell - x_{i\ell}) \right), \text{ so}$$

$$L_{x_j}^{(m)}(f) = m! \left(\prod_{i=0}^{m-1} \prod_{\substack{\ell=1 \\ \ell \neq j}}^d (x_\ell - x_{i\ell}) \right) [(x_{01}, \dots, x_{0d}), (x_{11}, \dots, x_{1d}), \dots, (x_{m1}, \dots, x_{md}); f]$$

$$= m! \psi [(x_{01}, \dots, x_{0d}), (x_{11}, \dots, x_{1d}), \dots, (x_{m1}, \dots, x_{md}); f],$$

where $\psi = \prod_{i=0}^{m-1} \prod_{\substack{\ell=1 \\ \ell \neq j}}^d (x_\ell - x_{i\ell})$ is a constant \square

Lemma 2.2.

The following identity is true

$$(x_{0j} - x_{mj})[(x_{01}, \dots, x_{0d}), \dots, (x_{m1}, \dots, x_{md}); f] = [(x_{01}, \dots, x_{0d}), \dots, (x_{m1-1}, \dots, x_{md-1}); f] - [(x_{11}, \dots, x_{1d}), \dots, (x_{m1}, \dots, x_{md}); f] \tag{12}$$

where $j = 1, \dots, d$.

Proof :

Let $L((x_1, \dots, x_d)) = L((x_1, \dots, x_d); f; (x_{01}, \dots, x_{0d}), \dots, (x_{m1}, \dots, x_{md}))$.

It follows from (10) and (11) that

$$L_{x_j}^{(m-1)}(f) = [(x_{01}, \dots, x_{0d}), \dots, (x_{m1-1}, \dots, x_{md-1}); f](m-1)! \psi + [(x_{01}, \dots, x_{0d}), \dots, (x_{m1}, \dots, x_{md}); f] \psi \left(m! x_j - (m-1)! (x_{0j} + \dots + x_{mj-1}) \right).$$

Interchanging the points $x_0 = (x_{01}, \dots, x_{0d})$ and $x_m = (x_{m1}, \dots, x_{md})$ in (10) we get

$$L_{x_j}^{(m-1)}(f) = [(x_{m1}, \dots, x_{md}), (x_{11}, \dots, x_{1d}), \dots, (x_{m1-1}, \dots, x_{md-1}); f](m-1)! \psi$$

$$+ [(x_{m1}, \dots, x_{md}), (x_{11}, \dots, x_{1d}), \dots, (x_{m1-1}, \dots, x_{md-1}), (x_{01}, \dots, x_{0d}); f]$$

$$\psi \left(m! x_j - (m-1)! (x_{mj} + x_{1j} + \dots + x_{mj-1}) \right)$$

$$= [(x_{11}, \dots, x_{1d}), \dots, (x_{m1}, \dots, x_{md}); f](m-1)! \psi$$

$$+[(x_{01}, \dots, x_{0d}), \dots, (x_{m1}, \dots, x_{md}); f] \psi \left(m! x_j - (m - 1)! (x_{1j} + \dots + x_{mj}) \right) .$$

Subtracting equalities

$$[(x_{01}, \dots, x_{0d}), \dots, (x_{m1-1}, \dots, x_{md-1}); f](m - 1)! \psi + [(x_{01}, \dots, x_{0d}), \dots, (x_{m1}, \dots, x_{md}); f] \psi \left(m! x_j - (m - 1)! (x_{0j} + \dots + x_{mj-1}) \right) , \text{ and}$$

$$[(x_{11}, \dots, x_{1d}), \dots, (x_{m1}, \dots, x_{md}); f](m - 1)! \psi + [(x_{01}, \dots, x_{0d}), \dots, (x_{m1}, \dots, x_{md}); f] \psi \left(m! x_j - (m - 1)! (x_{1j} + \dots + x_{mj}) \right) , \text{ we get}$$

$$([(x_{01}, \dots, x_{0d}), \dots, (x_{m1-1}, \dots, x_{md-1}); f] - [(x_{11}, \dots, x_{1d}), \dots, (x_{m1}, \dots, x_{md}); f])(m - 1)! \psi$$

$$- \left((m - 1)! \psi [(x_{01}, \dots, x_{0d}), \dots, (x_{m1}, \dots, x_{md}); f] (x_{0j} - x_{mj}) \right) = 0 .$$

By dividing on $(m - 1)! \psi$, we get

$$(x_{0j} - x_{mj}) [(x_{01}, \dots, x_{0d}), \dots, (x_{m1}, \dots, x_{md}); f]$$

$$= [(x_{01}, \dots, x_{0d}), \dots, (x_{m1-1}, \dots, x_{md-1}); f] - [(x_{11}, \dots, x_{1d}), \dots, (x_{m1}, \dots, x_{md}); f] \quad \square$$

Now let $x_0, x_1 \in [a, b]^d$ and let a function f be absolutely continuous on $[a, b]^d$. Then according to the Lebesgue theorem we have

$$f((x_{11}, \dots, x_{1d})) - f((x_{01}, \dots, x_{0d}))$$

$$= \int_{x_{01}}^{x_{11}} \dots \int_{x_{0d}}^{x_{1d}} f_{t_1, t_2, \dots, t_d}((t_1, \dots, t_d)) dt_1 \dots dt_d .$$

Performing the change of variables $t_1 = x_{01} + (x_{11} - x_{01})\tilde{t}_1 , \dots , t_d = x_{0d} + (x_{1d} - x_{0d})\tilde{t}_1$ we obtain

$$[(x_{01}, \dots, x_{0d}), (x_{11}, \dots, x_{1d}); f]$$

$$= \frac{1}{(x_{11} - x_{01}) \dots (x_{1d} - x_{0d})} \int_{x_{01}}^{x_{11}} \dots \int_{x_{0d}}^{x_{1d}} f_{t_1, \dots, t_d}((t_1, \dots, t_d)) dt_1 \dots dt_d$$

$$= \int_0^1 \dots \int_0^1 f'((x_{01} + (x_{11} - x_{01})\tilde{t}_1 , \dots, x_{0d} + (x_{1d} - x_{0d})\tilde{t}_1)) d\tilde{t}_1^d , \tag{13}$$

where $dt_1 = (x_{11} - x_{01}) d\tilde{t}_1 , \dots , dt_d = (x_{1d} - x_{0d}) d\tilde{t}_1 , f' = f_{t_1, \dots, t_d}$ and $d\tilde{t}_1^d = d\tilde{t}_1 d\tilde{t}_1 \dots d\tilde{t}_1 , d$ times .

A similar representation is true for any m by virtue of the following theorem:

Theorem 2.2.

Let $x_i \in [a, b]^d$ where $x_i = (x_{i1}, \dots, x_{id})$ for $i = 0, \dots, m$.

If the function f has the absolute continuous $(m - 1)$ th derivative on $[a, b]^d$, then

$$\begin{aligned}
 & [(x_{01}, \dots, x_{0d}), (x_{11}, \dots, x_{1d}), \dots, (x_{m1}, \dots, x_{md}); f] \\
 &= \int_0^1 \dots \int_0^1 \int_0^{\tilde{t}_1} \dots \int_0^{\tilde{t}_1} \dots \int_0^{\tilde{t}_{m-1}} \dots \int_0^{\tilde{t}_{m-1}} f^{(m)}((x_{01}, \dots, x_{0d}) \\
 &\quad + ((x_{11} - x_{01})\tilde{t}_1, \dots, (x_{1d} - x_{0d})\tilde{t}_1) + \dots \\
 &\quad + ((x_{m1} - x_{m1-1})\tilde{t}_m, \dots, (x_{md} - x_{md-1})\tilde{t}_m)) d\tilde{t}_m^d \dots d\tilde{t}_1^d \tag{14}
 \end{aligned}$$

Proof:

Assume that representation (14) is true for a number $m - 1$. By induction, let us prove that (14) is also true for the number m . Denote $\tilde{t}_0 := 1$. According to relation (12) and the induction hypothesis, we have

$$\begin{aligned}
 & (x_{mj} - x_{mj-1}) [(x_{01}, \dots, x_{0d}), \dots, (x_{m1}, \dots, x_{md}); f] \\
 &= [(x_{01}, \dots, x_{0d}), \dots, (x_{m1-2}, \dots, x_{md-2}), (x_{m1}, \dots, x_{md}); f] \\
 &\quad - [(x_{01}, \dots, x_{0d}), \dots, (x_{m1-1}, \dots, x_{md-1}); f] \\
 &= \int_0^{\tilde{t}_0} \dots \int_0^{\tilde{t}_0} \dots \int_0^{\tilde{t}_{m-2}} \dots \int_0^{\tilde{t}_{m-2}} \left(\int_{u_1}^{v_1} \dots \int_{u_d}^{v_d} f^{(m)}(t_1, \dots, t_d) dt_1 \dots dt_d \right) d\tilde{t}_{m-1}^d \dots d\tilde{t}_1^d,
 \end{aligned}$$

where

$$f^{(m)} = f_{\substack{t_1 \dots t_1 \\ m \text{ times}}, t_2 \dots t_2, \dots, t_d \dots t_d}_{\substack{m \text{ times} \quad m \text{ times}}},$$

$$v_1 = x_{01} + \dots + (x_{m1-2} - x_{m1-3})\tilde{t}_{m-2} + (x_{m1} - x_{m1-2})\tilde{t}_{m-1},$$

⋮

$$v_d = x_{0d} + \dots + (x_{md-2} - x_{md-3})\tilde{t}_{m-2} + (x_{md} - x_{md-2})\tilde{t}_{m-1},$$

$$u_1 = x_{01} + \dots + (x_{m1-1} - x_{m1-2})\tilde{t}_{m-1} \quad ,$$

⋮

$$u_d = x_{0d} + \dots + (x_{md-1} - x_{md-2})\tilde{t}_{m-1} \quad .$$

It remains to introduce a new integration variable \tilde{t}_m instead of $t = (t_1, \dots, t_d)$ in the last integral by using the change of variables

$$t_1 = x_{01} + (x_{11} - x_{01})\tilde{t}_1 + \dots + (x_{m1-1} - x_{m1-2})\tilde{t}_{m-1} + (x_{m1} - x_{m1-1})\tilde{t}_m \quad ,$$

⋮

$$t_d = x_{0d} + (x_{1d} - x_{0d})\tilde{t}_1 + \dots + (x_{md-1} - x_{md-2})\tilde{t}_{m-1} + (x_{md} - x_{md-1})\tilde{t}_m \quad .$$

And then note that this change of variables transforms the segment $[0, \tilde{t}_m]^d$ into the segment that connects the points $u = (u_1, \dots, u_d)$ and $v = (v_1, \dots, v_d)$ \square

Lemma 2.3.

Let $i \in N$, $i \leq m$ and let $x_i \in [a, b]^d$ then

$$[(x_{01}, \dots, x_{0d}), \dots, (x_{m1}, \dots, x_{md}); f] = [(x_{i1}, \dots, x_{id}), \dots, (x_{m1}, \dots, x_{md}); f_i] \quad (15)$$

where $f_i((x_1, \dots, x_d)) = [(x_{01}, \dots, x_{0d}), \dots, (x_{i1-1}, \dots, x_{id-1}); (x_1, \dots, x_d); f]$

proof:

Can easily be proved by induction with the use of (12)

Lemma 2.4.

Let $k \in N$, $k \leq m$, and let $x_i \in [a, b]^d$ for all $i = 0, \dots, m$. If a function f is k times continuously differentiable on $[a, b]^d$ or f has the $(k - 1)$ th absolutely continuous derivative on $[a, b]^d$, then

$$[(x_{01}, \dots, x_{0d}), \dots, (x_{m1}, \dots, x_{md}); f] = \int_0^1 \dots \int_0^1 [(x_{11}, \dots, x_{1d}), \dots, (x_{m1}, \dots, x_{md}); f_{\tilde{t}_1^d}] d\tilde{t}_1^d \quad (16)$$

Proof:

From (13), (14) and (15) we get

$$[(x_{01}, \dots, x_{0d}), \dots, (x_{m1}, \dots, x_{md}); f]$$

$$= \int_0^1 \dots \int_0^1 \dots \int_0^{\tilde{t}_{k-1}} \dots \int_0^{\tilde{t}_{k-1}} [(x_{k1}, \dots, x_{kd}), \dots, (x_{m1}, \dots, x_{md}); f_{\tilde{t}_1^d, \dots, \tilde{t}_k^d}] d\tilde{t}_k^d \dots d\tilde{t}_1^d,$$

where

$$f_{\tilde{t}_1^d, \dots, \tilde{t}_k^d}((x_1, \dots, x_d))$$

$$= f^{(k)} \left((x_{01}, \dots, x_{0d}) + ((x_{11}, \dots, x_{1d}) - (x_{01}, \dots, x_{0d}))\tilde{t}_1 + \dots \right.$$

$$\quad \left. + ((x_{k1-1}, \dots, x_{kd-1}) - (x_{k1-2}, \dots, x_{kd-2}))\tilde{t}_{k-1} \right.$$

$$\quad \left. + ((x_{k1}, \dots, x_{kd}) - (x_{k1-1}, \dots, x_{kd-1}))\tilde{t}_k \right).$$

In particular, if $k = 1$, then

$$[(x_{01}, \dots, x_{0d}), \dots, (x_{m1}, \dots, x_{md}); f]$$

$$= \int_0^1 \dots \int_0^1 [(x_{11}, \dots, x_{1d}), \dots, (x_{m1}, \dots, x_{md}); f_{\tilde{t}_1^d}] d\tilde{t}_1^d \quad \square$$

3. Finite differences

In this section, we assume that the points $x_i = (x_{i1}, \dots, x_{id})$ are equidistant, that is, for all $i = 0, \dots, m$ we have

$$x_{i1} = x_{01} + ih_1, \dots, x_{id} = x_{0d} + ih_d, h \in R^d, h_j \neq 0, j = 1, \dots, d.$$

For the Lagrange interpolation multipolynomial

$$L((x_1, \dots, x_d)) = L((x_1, \dots, x_d); f; (x_{01}, \dots, x_{0d}), \dots, (x_{m1-1}, \dots, x_{md-1}))$$

$$= \sum_{k=0}^{m-1} f((x_{k1}, \dots, x_{kd})) I_k((x_1, \dots, x_d), (x_{01}, \dots, x_{0d}), \dots, (x_{m1-1}, \dots, x_{md-1})).$$

We determine the values of the new version of the fundamental Lagrange multipolynomials I_k at the point $x_1 = x_{m1}, \dots, x_d = x_{md}$.

According to (4), we have

$$\begin{aligned}
 & I_k((x_{m1}, \dots, x_{md}), (x_{01}, \dots, x_{0d}), \dots, (x_{m1-1}, \dots, x_{md-1})) \\
 &= \prod_{\substack{i=0 \\ k \neq i}}^{m-1} \frac{(x_{m1} - x_{i1}) \dots (x_{md} - x_{id})}{(x_{k1} - x_{i1}) \dots (x_{kd} - x_{id})} \\
 &= \prod_{\substack{i=0 \\ i \neq k}}^{m-1} \frac{(x_{01} + mh_1 - x_{01} - ih_1) \dots (x_{0d} + mh_d - x_{0d} - ih_d)}{(x_{01} + kh_1 - x_{01} - ih_1) \dots (x_{0d} + kh_d - x_{0d} - ih_d)} \\
 &= \prod_{\substack{i=0 \\ i \neq k}}^{m-1} \frac{(m-i)h_1 \dots (m-i)h_d}{(k-i)h_1 \dots (k-i)h_d} \\
 &= \prod_{\substack{i=0 \\ i \neq k}}^{m-1} \frac{(m-i) \dots (m-i)}{(k-i) \dots (k-i)} \\
 &= \left(-(-1)^{m-k} \binom{m}{k} \right) \dots \left(-(-1)^{m-k} \binom{m}{k} \right) \\
 &= \left(-(-1)^{m-k} \binom{m}{k} \right)^d.
 \end{aligned}$$

We represent the difference $f((x_{m1}, \dots, x_{md})) - L((x_{m1}, \dots, x_{md}))$ in the form

$$\begin{aligned}
 & f((x_{m1}, \dots, x_{md})) - L((x_{m1}, \dots, x_{md})) \\
 &= \sum_{k=0}^m \left((-1)^{m-k} \binom{m}{k} \right)^d f((x_{01} + kh_1, \dots, x_{0d} + kh_d)). \tag{17}
 \end{aligned}$$

Lemma 3.1.

$$\begin{aligned}
 & \Delta_h^m(f; (x_{01}, \dots, x_{0d})) \\
 &= (m!)^d (h_1 \dots h_d)^m [(x_{01}, \dots, x_{0d}), (x_{01} + h_1, \dots, x_{0d} + h_d), \dots, (x_{01} + mh_1, \dots, x_{0d} + mh_d); f], \tag{18}
 \end{aligned}$$

Proof:

Since $f((x_{m1}, \dots, x_{md})) - L((x_{m1}, \dots, x_{md}))$

$$= \sum_{k=0}^m \left((-1)^{m-k} \binom{m}{k} \right)^d f((x_{01} + kh_1, \dots, x_{0d} + kh_d))$$

and

$$f((x_{m1}, \dots, x_{md})) - L((x_{m1}, \dots, x_{md}); f; (x_{01}, \dots, x_{0d}), \dots, (x_{m1-1}, \dots, x_{md-1}))$$

$$= \prod_{k=0}^{m-1} ((x_{m1} - x_{k1}) \dots (x_{md} - x_{kd})) [(x_{01}, \dots, x_{0d}), (x_{11}, \dots, x_{1d}), \dots, (x_{m1}, \dots, x_{md}); f],$$

then

$$\Delta_h^m(f; (x_{01}, \dots, x_{0d}))$$

$$= \prod_{k=0}^{m-1} ((x_{01} + mh_1 - x_{01} - kh_1) \dots (x_{0d} + mh_d - x_{0d} - kh_d)) [(x_{01}, \dots, x_{0d}), (x_{01} + h_1, \dots, x_{0d} + h_d), \dots, (x_{01} + mh_1, \dots, x_{0d} + mh_d); f]$$

$$= \prod_{k=0}^{m-1} (((m-k)h_1) \dots ((m-k)h_d)) [(x_{01}, \dots, x_{0d}), (x_{01} + h_1, \dots, x_{0d} + h_d), \dots, (x_{01} + mh_1, \dots, x_{0d} + mh_d); f]$$

$$= ((mh_1)((m-1)h_1)((m-2)h_1) \dots ((m-m+1)h_1)) \dots ((mh_d)((m-1)h_d)((m-2)h_d) \dots ((m-m+1)h_d)) [(x_{01}, \dots, x_{0d}), (x_{01} + h_1, \dots, x_{0d} + h_d), \dots, (x_{01} + mh_1, \dots, x_{0d} + mh_d); f]$$

$$= (m! h_1^m) \dots (m! h_d^m) [(x_{01}, \dots, x_{0d}), (x_{01} + h_1, \dots, x_{0d} + h_d), \dots, (x_{01} + mh_1, \dots, x_{0d} + mh_d); f]$$

$$= (m!)^d (h_1 \dots h_d)^m [(x_{01}, \dots, x_{0d}), (x_{01} + h_1, \dots, x_{0d} + h_d), \dots, (x_{01} + mh_1, \dots, x_{0d} + mh_d); f] \square$$

Lemma 3.2.

Let $x_0 \in [a, b]^d$, $h_j > 0, j = 1, \dots, d$, $x_k = (x_{k1}, \dots, x_{kd})$ such that

$$x_{k1} = x_{01} + kh_1, \dots, x_{kd} = x_{0d} + kh_d \text{ and } x_m \in [a, b]^d, x_m = (x_{m1}, \dots, x_{md}).$$

If $F \in L_p^1([a, b]^d)$, then for every $x \in [a, b]^d$ the following inequality is true:

$$\begin{aligned} & \|F((x_1, \dots, x_d)) - L((x_1, \dots, x_d); F; (x_{01}, \dots, x_{0d}), \dots, (x_{m1}, \dots, x_{md}))\|_{L_p[a,b]^d} \\ & \leq C(p) \frac{1}{(m!)^d (h_1 \dots h_d)^m} \|((x_1 - x_{01}) \dots (x_d - x_{0d})) \dots ((x_1 - x_{m1}) \dots (x_d - x_{md}))\|_{L_p[a,b]^d} \omega_m(F', h, [a, b]^d)_p \end{aligned} \tag{19}$$

Proof:

For every $\tilde{t}_1 \in [0, 1]$, we set

$$\begin{aligned} F_{\tilde{t}_1^d}((u_1, \dots, u_d)) &= F'((x_1, \dots, x_d) + ((u_1, \dots, u_d) - (x_1, \dots, x_d))\tilde{t}_1) \\ &= F'((x_1 + (u_1 - x_1)\tilde{t}_1, \dots, x_d + (u_d - x_d)\tilde{t}_1)), \end{aligned}$$

where $u \in [a, b]^d$.

Then relations (16) and (18) yield

$$\begin{aligned} & [(x_1, \dots, x_d), (x_{01}, \dots, x_{0d}), \dots, (x_{m1}, \dots, x_{md}); F] \\ &= \int_0^1 \dots \int_0^1 [(x_{01}, \dots, x_{0d}), \dots, (x_{m1}, \dots, x_{md}); F_{\tilde{t}_1^d}] d\tilde{t}_1^d \\ &= \frac{1}{(m!)^d (h_1 \dots h_d)^m} \int_0^1 \dots \int_0^1 \Delta_h^m (F_{\tilde{t}_1^d}; (x_{01}, \dots, x_{0d})) d\tilde{t}_1^d \end{aligned}$$

Since

$$\begin{aligned} & \left\| \Delta_h^m (F_{\tilde{t}_1^d}; (u_1, \dots, u_d)) \right\|_{L_p[a,b]^d} \\ &= \left\| \Delta_{h\tilde{t}_1}^m (F'; (x_1 + (u_1 - x_1)\tilde{t}_1, \dots, x_d + (u_d - x_d)\tilde{t}_1)) \right\|_{L_p[a,b]^d} \\ &\leq \omega_m(F', h\tilde{t}_1, [a, b]^d)_p \leq \omega_m(F', h, [a, b]^d)_p, \end{aligned}$$

then

$$\|[(x_1, \dots, x_d), (x_{01}, \dots, x_{0d}), \dots, (x_{m1}, \dots, x_{md}); F]\|_{L_p[a,b]^d}$$

$$\begin{aligned}
 &= \left\| \frac{1}{(m!)^d (h_1 \dots h_d)^m} \int_0^1 \dots \int_0^1 \Delta_h^m (F_{\tilde{t}_1^d}; (x_{01}, \dots, x_{0d})) d\tilde{t}_1^d \right\|_{L_p[a,b]^d} \\
 &\leq C(p) \frac{1}{(m!)^d (h_1 \dots h_d)^m} \left\| \Delta_h^m (F_{\tilde{t}_1^d}; (x_{01}, \dots, x_{0d})) \right\|_{L_p[a,b]^d} \\
 &= C(p) \frac{1}{(m!)^d (h_1 \dots h_d)^m} \left\| \Delta_{h\tilde{t}_1}^m (F'; (x_1 + (x_{01} - x_1)\tilde{t}_1, \dots, x_d + (x_{0d} - x_d)\tilde{t}_1)) \right\|_{L_p[a,b]^d} \\
 &\leq C(p) \frac{1}{(m!)^d (h_1 \dots h_d)^m} \omega_m(F', h, [a, b]^d)_p,
 \end{aligned}$$

relation (19) follows from (9) such that

$$\begin{aligned}
 &F((x_1, \dots, x_d)) - L((x_1, \dots, x_d); F; (x_{01}, \dots, x_{0d}), \dots, (x_{m1}, \dots, x_{md})) \\
 &= ((x_1 - x_{01}) \dots (x_d - x_{0d})) \dots ((x_1 - x_{m1}) \dots (x_d - x_{md})) [(x_1, \dots, x_d), (x_{01}, \dots, x_{0d}), \dots, (x_{m1}, \dots, x_{md}); F],
 \end{aligned}$$

since

$$\begin{aligned}
 &\|[(x_1, \dots, x_d), (x_{01}, \dots, x_{0d}), \dots, (x_{m1}, \dots, x_{md}); F]\|_{L_p[a,b]^d} \\
 &\leq C(p) \frac{1}{(m!)^d (h_1 \dots h_d)^m} \omega_m(F', h, [a, b]^d)_p,
 \end{aligned}$$

then

$$\begin{aligned}
 &\|F((x_1, \dots, x_d)) - L((x_1, \dots, x_d); F; (x_{01}, \dots, x_{0d}), \dots, (x_{m1}, \dots, x_{md}))\|_{L_p[a,b]^d} \\
 &\leq C(p) \frac{1}{(m!)^d (h_1 \dots h_d)^m} \|((x_1 - x_{01}) \dots (x_d - x_{0d})) \dots ((x_1 - x_{m1}) \dots (x_d - x_{md}))\|_{L_p[a,b]^d} \omega_m(F', h, [a, b]^d)_p \quad \square
 \end{aligned}$$

4. Proof of theorem 1.1.

Let $x_k = (x_{k1}, \dots, x_{kd})$ and $x_0 = (x_{01}, \dots, x_{0d})$ such that $x_{0j} := a$,

$$h_j := \frac{b-a}{m}, j = 1, \dots, d \text{ and } x_{k1} = x_{01} + kh_1, \dots, x_{kd} = x_{0d} + kh_d,$$

$$F((x_1, \dots, x_d)) := \int_a^{x_1} \dots \int_a^{x_d} f((u_1, \dots, u_d)) \, du_1 \dots du_d ,$$

$$G((x_1, \dots, x_d)) := F((x_1, \dots, x_d)) - L((x_1, \dots, x_d); F; (x_{01}, \dots, x_{0d}), \dots, (x_{m1}, \dots, x_{md})),$$

$$g((x_1, \dots, x_d)) = G'((x_1, \dots, x_d)) ,$$

$$\omega_m((t_1, \dots, t_d)) = \omega_m((t_1, \dots, t_d), f, [a, b]^d)_p \equiv \omega_m((t_1, \dots, t_d), g, [a, b]^d)_p .$$

We fix $x \in [a, b]^d$, choose δ for which $(x + m\delta) \in [a, b]^d$ and let $\delta' = (t_1\delta_1, \dots, t_d\delta_d)$.

As a result, we get

$$\begin{aligned} & \int_0^1 \dots \int_0^1 \Delta_{\delta'}^m(g; (x_1, \dots, x_d)) \, dt_1 \dots dt_d \\ &= (-1)^{md} g((x_1, \dots, x_d)) \\ & \quad + \sum_{k=1}^m \left((-1)^{m-k} \binom{m}{k} \right)^d \int_0^1 \dots \int_0^1 g((x_1 + kt_1\delta_1, \dots, x_d + kt_d\delta_d)) \, dt_1 \dots dt_d \\ &= (-1)^{md} g((x_1, \dots, x_d)) \\ & \quad + \sum_{k=1}^m \left((-1)^{m-k} \binom{m}{k} \right)^d \int_0^1 \dots \int_0^1 G'((x_1 + kt_1\delta_1, \dots, x_d + kt_d\delta_d)) \, dt_1 \dots dt_d \\ &= (-1)^{md} g((x_1, \dots, x_d)) \\ & \quad + \sum_{k=1}^m \left((-1)^{m-k} \binom{m}{k} \right)^d \frac{1}{k^d(\delta_1 \dots \delta_d)} \left(G((x_1 + k\delta_1, \dots, x_d + k\delta_d)) \right. \\ & \quad \left. - G((x_1, \dots, x_d)) \right), \end{aligned}$$

whence

$$\begin{aligned} & |g((x_1, \dots, x_d))| \\ & \leq \int_0^1 \dots \int_0^1 |\Delta_{\delta'}^m(g; (x_1, \dots, x_d))| \, dt_1 \dots dt_d \\ & \quad + \left| \sum_{k=1}^m \left((-1)^{m-k} \binom{m}{k} \right)^d \frac{1}{k^d(\delta_1 \dots \delta_d)} \left(G((x_1 + k\delta_1, \dots, x_d + k\delta_d)) \right. \right. \\ & \quad \left. \left. - G((x_1, \dots, x_d)) \right) \right| \end{aligned}$$

Then

$$\begin{aligned} \|g\|_{L_p[a,b]^d} &\leq \left\| \int_0^1 \dots \int_0^1 |\Delta_{\delta'}^m(g; (x_1, \dots, x_d))| dt_1 \dots dt_d \right. \\ &\quad \left. + \sum_{k=1}^m \left((-1)^{m-k} \binom{m}{k} \right)^d \frac{1}{k^d (\delta_1 \dots \delta_d)} \left(G((x_1 + k\delta_1, \dots, x_d + k\delta_d)) \right. \right. \\ &\quad \left. \left. - G((x_1, \dots, x_d)) \right) \right\|_{L_p[a,b]^d} \\ &\leq C(p) \left\| \int_0^1 \dots \int_0^1 \Delta_{\delta'}^m(g; (x_1, \dots, x_d)) dt_1 \dots dt_d \right\|_{L_p[a,b]^d} \\ &\quad + C(p) \left\| \sum_{k=1}^m \left((-1)^{m-k} \binom{m}{k} \right)^d \frac{1}{k^d (\delta_1 \dots \delta_d)} \left(G((x_1 + k\delta_1, \dots, x_d + k\delta_d)) \right. \right. \\ &\quad \left. \left. - G((x_1, \dots, x_d)) \right) \right\|_{L_p[a,b]^d} \\ &\leq C(p) \omega_m(g, |\delta|, [a, b]^d)_p + C(p) \frac{2}{|\delta_1| \dots |\delta_d|} \|G\|_{L_p[a,b]^d} \sum_{k=1}^m \left(\binom{m}{k} \frac{1}{k} \right)^d. \end{aligned}$$

By virtue of Lemma(3.2) we have $\|G\|_{L_p[a,b]^d} \leq C(p)(h_1 \dots h_d) \omega_m(F', h, [a, b]^d)_p$

$$= C(p)(h_1 \dots h_d) \omega_m(f, h, [a, b]^d)_p.$$

Therefore

$$\begin{aligned} E_{m-1}(f)_{L_p[a,b]^d} &\leq \|g\|_{L_p[a,b]^d} \\ &\leq C(p) \omega_m(g, |\delta|, [a, b]^d)_p + C(p) \frac{2}{|\delta_1| \dots |\delta_d|} (h_1 \dots h_d) \sum_{k=1}^m \left(\binom{m}{k} \frac{1}{k} \right)^d \omega_m(f, h, [a, b]^d)_p, \end{aligned}$$

note that δ_j can always be chosen so that $h_j \geq |\delta_j| \geq h_j / 2$, then $E_{m-1}(f)_{L_p[a,b]^d} \leq C(p) \omega_m(f, h, [a, b]^d)_p$

$$+ C(p) \frac{2}{(h_1 \dots h_d)} (h_1 \dots h_d) \sum_{k=1}^m \left(\binom{m}{k} \frac{1}{k} \right)^d \omega_m(f, h, [a, b]^d)_p$$

$$= \left(C(p) + 2C(p) \sum_{k=1}^m \left(\binom{m}{k} \frac{1}{k} \right)^d \right) \omega_m(f, h, [a, b]^d)_p$$

$$= C(p, m, d) \omega_m(f, h, [a, b]^d)_p,$$

where $C(p, m, d)$ is Whitney constant

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الخلاصة

برهنا في هذا البحث نظرية وتني لأفضل تقريب متعدد للدالة f التي تنتمي إلى الفضاء L_p , $0 < p < \infty$ بواسطة متعددة الحدود الجبرية متعددة المتغيرات p_{m-1} من الدرجة اقل أو تساوي $m - 1$.

الكلمات المفتاحية: نظرية وتني, التقريب المتعدد, متعددة حدود لاكرانج .