車北大＂

A Term Rewriting Approach to Program Tr ansf or mat i on by Templ at es

| 著者 | Chi ba Yuki |
| :--- | :--- |
| 学位授与機関 | Tohoku Uni ver si ty |
| URL | ht t p：／／hdl ．handl e．net $/ 10097 / 34539$ |

# A Term Rewriting Approach 

to
Program Transformation by Templates
by

Yuki Chiba

Supervisor: Professor Yoshihito Toyama

Tohoku University

February 12, 2008

## Abstract

Huet and Lang (1978) presented a framework of automated program transformation based on lambda calculus in which programs are transformed according to a given program transformation template. They introduced a second-order matching algorithm of simply-typed lambda calculus to verify whether the input program matches the template. They also showed how to validate the correctness of the program transformation using the denotational semantics.

We propose in this thesis a framework of program transformation by templates based on term rewriting. In our new framework, programs are given by term rewriting systems. To automate our program transformation, we introduce a term pattern matching problem and present a sound and complete algorithm that solves this problem.

We also discuss how to validate the correctness of program transformation in our framework. We introduce a notion of correct templates and a simple method to construct such templates without explicit use of induction. We then show that in any program transformation by correct templates the correctness of the transformation can be verified automatically. In our framework the correctness of the program transformation is discussed based on the operational semantics. This is a sharp contrast to Huet and Lang's framework.

RAPT (Rewriting-based Automated Program Transformation system), which implements our framework is reported in this thesis. RAPT transforms input many-sorted TRSs according to specified correct templates and verifies its correctness automatically. We explain each phase within RAPT and report several experiments of program transformations obtained from RAPT.

To enhance the variety of program transformation, it is important to introduce new transformation templates. Up to our knowledge, however, few works discuss about the construction of transformation templates. We then propose a method that automatically constructs transformation templates from similar program transformations. The key idea of our method is a second-order generalization, which is an extension of Plotkin's first-order generalization (1969). We give a second-order generalization algorithm and prove the soundness of the algorithm. We then report about an implementation of the generalization procedure and an experiment on the construction of transformation templates.

## Acknowledgments

I would like to express my gratitude to my supervisor Professor Yoshihito Toyama for his kind discussion, guidance and encouragement during this work. He has showed me a notion of equivalent transformation of TRSs which plays an essential role in this work. I also wish to thank Associate Professor Takahito Aoto for his kind discussion, guidance and encouragement. A part of RAPT has been implemented by him. I am very grateful to Professor Atsushi Ohori and Professor Naoki Kobayashi for their useful comments and suggestions.

## Contents

Abstract ..... i
Acknowledgments ..... i
1 Introduction ..... 1
1.1 Program Transformation by Templates ..... 1
1.2 Term Rewriting System ..... 1
1.3 Overview of this Thesis ..... 2
2 Term Rewriting System ..... 4
3 Program Transformation by Templates ..... 8
3.1 Motivating Example ..... 8
3.2 Term Homomorphism ..... 10
3.3 Summary ..... 13
4 Correctness of Transformations ..... 14
4.1 Equivalent Transformation of TRS ..... 14
4.2 Correctness of Templates ..... 17
4.3 Summary ..... 21
5 Matching Algorithm ..... 22
5.1 Term Pattern Matching ..... 22
5.2 TRS Pattern matching ..... 25
5.3 Summary ..... 28
6 Program Transformation System RAPT ..... 29
6.1 Implementation ..... 29
6.1.1 Specification of input TRS and transformation template ..... 29
6.1.2 Implementation details ..... 30
6.2 Experiments ..... 33
7 Constructing Templates ..... 35
7.1 Generalization of Terms ..... 36
7.2 Generalization of TRSs ..... 42
7.3 Generalization of transformations ..... 44
7.4 Summary ..... 48
8 Conclusion ..... 51

Bibliography 53
Publications 55

## Chapter 1

## Introduction

### 1.1 Program Transformation by Templates

Automatically transforming given programs to optimize efficiency is one of the most fascinating techniques for programming languages [18, 19]. Several techniques for transforming functional programming languages have been developed [3, 12, 26]. Huet and Lang [12] presented a framework of automated program transformation in which programs are transformed according to a given program transformation template, where the template consists of program schemas for input and output programs, and a set of equations which the input (and output) programs must validate to guarantee the correctness of transformation. The programs and program schemas in their framework are given by second-order simply-typed lambda terms. They gave a second-order matching algorithm to verify whether a template could be applied to an input program. They also showed how to validate the correctness of transformations using denotational semantics.

After Huet and Lang's pioneering work, Curien et al. [6] provided an improved matching algorithm using top-down matching method. Yokoyama et al. [27] presented sufficient conditions to have at most one solution and a deterministic algorithm to find such a solution. de Moor and Sittampalam [8] presented a matching algorithm that could also be applied to third-order matching problems. The programs in all of these algorithms are represented by lambda terms and higher-order substitutions are achieved by the $\beta$-reduction of lambda calculus. However, in contrast to this successive work on matching algorithms, the formal verification component of the correctness of transformation has been neglected within the framework of program transformation using templates. Thus, the verification of the correctness of transformation in this framework still depends on Huet and Lang's original technique based on denotational semantics. In their framework, the correctness of transformations is often verified using several inductive properties of programs (e.g. associativity of addition) as hypotheses. It is known that one may need to verify different hypotheses to guarantee the correctness of each transformation. To the best of our knowledge, there exists no framework of program transformation by templates equipping automated verification of hypotheses to guarantee the correctness of transformations

### 1.2 Term Rewriting System

Term rewriting systems (TRSs, for short) are used for computational models of functional programming languages [1, 23]. TRSs consist sets of rewrite rules of terms. Let us consider an example of TRS. Formal definitions of TRSs appear in next chapter. The following TRS $\mathcal{R}_{\text {add }}$
represents a program which computes additions of two input natural numbers.

$$
\mathcal{R}_{a d d} \begin{cases}+(0, x) & \rightarrow x \\ +(\mathrm{s}(x), y) & \rightarrow \mathrm{s}(+(x, y))\end{cases}
$$

Note that, natural numbers $0,1,2, \cdots$ are expressed as $0, s(0), s(s(0)), \cdots$, respectively.
The computation by TRSs is carried out by the reduction. For example, an addition of 2 and 3 is computed by rewriting a term $+(\mathrm{s}(\mathrm{s}(0)), \mathrm{s}(\mathrm{s}(\mathrm{s}(0))))$ using the TRS $\mathcal{R}_{\text {add }}$ as follows:

$$
\begin{array}{rll}
+(\mathrm{s}(\mathrm{~s}(0)), \mathrm{s}(\mathrm{~s}(\mathrm{~s}(0)))) & \rightarrow_{\mathcal{R}_{\text {add }}} & \mathrm{s}(+(\mathrm{s}(0), \mathrm{s}(\mathrm{~s}(\mathrm{~s}(0))))) \\
& \boldsymbol{\mathcal { R }}_{\text {add }} & \mathrm{s}(\mathrm{~s}(+(0, \mathrm{~s}(\mathrm{~s}(\mathrm{~s}(0)))))) \\
& \boldsymbol{\mathcal { R }}_{\text {add }} & \mathrm{s}(\mathrm{~s}(\mathrm{~s}(\mathrm{~s}(\mathrm{~s}(0)))))
\end{array}
$$

Since there exist several automated theorem proving methods based on term rewriting for verifying inductive properties of programs[21, 25], one may expect to construct a framework of TRS transformation by templates with automated verification of the correctness of transformations by applying such automated theorem proving techniques. However, no framework of TRS transformation using pattern matching is known.

### 1.3 Overview of this Thesis

We propose a framework of program transformation by templates in this thesis based on term rewriting. Applying automated theorem proving techniques of term rewriting, the correctness of transformations are verified automatically in our framework. Chapter 2 recalls basic notions about term rewriting which are used in this thesis.

In our framework, a transformation template (template, for short) consists of two term rewriting system patterns (TRS patterns, for short) -an input part and an output part of the template. A TRS is transformed according to a template, first by performing the pattern matching between the given TRS and the input part of the template, and then applying the result of pattern matching to the output part of the template (Figure 1.1). In Chapter 3, we explain the detail of our framework through motivating examples. We also introduce the notion of term homomorphisms to describe how a TRS pattern matches a concrete TRS.


Figure 1.1: Overview of TRS transformation by templates
Chapter 4 discusses about verifying the correctness of transformations. In contrast to existing works, the correctness of transformations is discussed based on operational semantics. To guarantee the correctness of transformation, we introduce the notion of correct templates and a simple method of constructing such templates without explicit use of induction. We also give sufficient conditions to guarantee the correctness of transformations by correct templates. We
then show that the correctness of transformation can be verified automatically for some class of TRSs.

A key part of our procedure of TRS transformation using templates- the TRS pattern matching problem-is solved using the term pattern matching algorithm Match introduced in Chapter 5. We then show termination, soundness and completeness of Match. We also extend Match to solve TRS pattern matching problems.

In Chapter 6, we explain about RAPT (Rewriting-based Automated Program Transformation system), which implements our framework and reports several experiments using RAPT.

In order to apply our framework of program transformation, one have to construct transformation templates beforehand. Since transformation templates are often constructed by generalizing similar transformations, a generalization procedure can help to construct transformation templates automatically. Therefore, we propose 2nd-order generalization algorithm to construct transformation templates automatically in Chapter 7.

Chapter 8 concludes this thesis and reports differences against existing works.

## Chapter 2

## Term Rewriting System

This chapter introduces basic notions of term rewriting systems used in this thesis based on [1].
Let $\mathscr{F}$ and $\mathscr{V}$ be sets of function symbols and variables, respectively. We assume that these sets are mutually disjoint. Any function symbol $f \in \mathscr{F}$ has its arity (denoted by arity $(f)$ ). We define the set $\mathrm{T}(\mathscr{F}, \mathscr{V})$ of terms inductively by:

1. $\mathscr{V} \subseteq \mathrm{T}(\mathscr{F}, \mathscr{V})$; and
2. $f\left(t_{1}, \ldots, t_{n}\right) \in \mathrm{T}(\mathscr{F}, \mathscr{V})$ for any $f \in \mathscr{F}$ such that $\operatorname{arity}(f)=n$ and $t_{1}, \ldots, t_{n} \in \mathrm{~T}(\mathscr{F}, \mathscr{V})$.

A term without variables is a ground term. The set of ground terms is denoted by $\mathrm{T}(\mathscr{F})$. For a term $s=f\left(s_{1}, \ldots, s_{n}\right)$, the root symbol of $s$ is $f($ denoted $\operatorname{by} \operatorname{root}(s)=f)$.

A substitution $\theta$ is a mapping from $\mathscr{V}$ to $\mathrm{T}(\mathscr{F}, \mathscr{V})$. A substitution $\theta$ is extended to a mapping $\hat{\theta}$ over terms $\mathrm{T}(\mathscr{F}, \mathscr{V})$ like this:

1. $\hat{\theta}(x)=\theta(x)$ if $x \in \mathscr{V}$,
2. $\hat{\theta}\left(f\left(s_{1}, \ldots, s_{n}\right)\right)=f\left(\hat{\theta}\left(s_{1}\right), \ldots, \hat{\theta}\left(s_{n}\right)\right)$.

We usually identify $\hat{\theta}$ and $\theta$. We denote $s \theta$ instead of $\theta(s)$. The domain of a substitution $\theta$ (denoted by $\operatorname{dom}(\theta)$ ) is defined by $\operatorname{dom}(\theta)=\{x \in \mathscr{V} \mid x \neq \theta(x)\}$.

Consider special (indexed) constants $\square_{i}(i \geq 1)$ called holes such that $\square_{i} \notin \mathscr{F}$. An (indexed) context $C$ is an element of $\mathrm{T}\left(\mathscr{F} \cup\left\{\square_{i} \mid i \geq 1\right\}, \mathscr{V}\right) . C\left[s_{1}, \ldots, s_{n}\right]$ is the result of $C$ replacing $\square_{i}$ by $s_{1}, \ldots, s_{n}$ from left to right. $C\left\langle s_{1}, \ldots, s_{n}\right\rangle$ is the term obtained by replacing each $\square_{i}$ in $C$ with $s_{i}$ (indexed replacement). A context $C$ with precisely one hole is denoted by $C[]$. The set of contexts is denoted by $\mathrm{T}^{\square}(\mathscr{F}, \mathscr{V})$; its subset $\mathrm{T}\left(\mathscr{F} \cup\left\{\square_{i} \mid 1 \leq i \leq n\right\}, \mathscr{V}\right)$ is denoted by $\mathrm{T}_{n}^{\square}(\mathscr{F}, \mathscr{V}) . \mathrm{T}^{\square}(\mathscr{F})$ and $\mathrm{T}_{n}^{\square}(\mathscr{F})$ are defined in the same way as $\mathrm{T}(\mathscr{F})$.

Example 2.1 (Context). Let $C_{1}=\mathrm{f}\left(\square_{1}\right), C_{2}=\mathrm{g}\left(\square_{2}, \square_{1}\right)$, and $C_{3}=\mathrm{g}\left(\square_{2}, \mathrm{~g}\left(\square_{1}, \square_{1}\right)\right)$ be contexts. Here, we get

$$
\begin{array}{ll}
C_{1}[\mathrm{a}] & =\mathrm{f}(\mathrm{a}) \\
C_{1}\langle\mathrm{a}, \mathrm{~b}\rangle & =\mathrm{f}(\mathrm{a}) \\
C_{2}[\mathrm{a}, \mathrm{~b}] & =\mathrm{g}(\mathrm{a}, \mathrm{~b}) \\
C_{2}\langle\mathrm{a}, \mathrm{~b}\rangle & =\mathrm{g}(\mathrm{~b}, \mathrm{a}) \\
C_{3}[\mathrm{a}, \mathrm{~b}, \mathrm{c}] & =\mathrm{g}(\mathrm{a}, \mathrm{~g}(\mathrm{~b}, \mathrm{c})) \\
C_{3}\langle\mathrm{a}, \mathrm{~b}\rangle & =\mathrm{g}(\mathrm{~b}, \mathrm{~g}(\mathrm{a}, \mathrm{a}))
\end{array}
$$

A pair $\langle l, r\rangle$ of terms is a rewrite rule if $l \notin \mathscr{V}$ and $\mathscr{V}(l) \supseteq \mathscr{V}(r)$. We usually write the rewrite rule $\langle l, r\rangle$ as $l \rightarrow r$. A term rewriting system (TRS for short) is a set of rewrite rules. As usual, we always assume that variables in each rewrite rule are disjoint, although the same variable name may be used. A term $s$ reduces to a term $t$ by $\mathcal{R}$ (denoted by $s \rightarrow_{\mathcal{R}} t$ ) if there exists a context $C[]$, a substitution $\theta$ and a rewrite rule $l \rightarrow r \in \mathcal{R}$ such that $s=C[l \theta]$ and $t=C[r \theta]$.

Example 2.2 (Summation). The following TRS $\mathcal{R}_{\text {sum }}$ represents a program which computes summations of input lists of natural numbers.

$$
\mathcal{R}_{\text {sum }}\left\{\begin{array}{lll}
\operatorname{sum}([]) & \rightarrow & 0 \\
\operatorname{sum}\left(x_{1}: y_{1}\right) & \rightarrow & +\left(x_{1}, \operatorname{sum}\left(y_{1}\right)\right) \\
+\left(0, x_{2}\right) & \rightarrow & x_{2} \\
+\left(\mathrm{s}\left(x_{3}\right), y_{3}\right) & \rightarrow & \mathrm{s}\left(+\left(x_{3}, y_{3}\right)\right)
\end{array}\right.
$$

Note that, natural numbers $0,1,2, \cdots$ are expressed as $0, \mathrm{~s}(0), \mathrm{s}(\mathrm{s}(0)), \cdots$, respectively.
The reflexive transitive closure of $\rightarrow_{\mathcal{R}}$ is denoted by ${ }_{\rightarrow}^{*} \mathcal{R}$, the transitive closure by ${ }^{+} \underset{\mathcal{R}}{ }$, and the equivalence closure by $\stackrel{*}{\leftrightarrow} \mathcal{R}$. A term $s$ is in normal form of a $\operatorname{TRS} \mathcal{R}$ when $s \rightarrow_{\mathcal{R}} t$ for no term $t$. $\operatorname{NF}(\mathcal{R})$ denotes the set of terms in normal form of a TRS $\mathcal{R}$.

A TRS $\mathcal{R}$ is terminating, or strongly normalizing ( $\mathrm{SN}(\mathcal{R})$ ) if there exists no infinite reduction $s_{1} \rightarrow_{\mathcal{R}} s_{2} \rightarrow_{\mathcal{R}} s_{3} \rightarrow_{\mathcal{R}} \cdots$. A binary relation $>$ is well-founded if there exists no infinite sequence such that $a_{1}>a_{2}>\cdots$. A binary relation $>$ of terms is closed under contexts if $s>t$ implies $C[s]>C[t]$, for any terms $s$ and $t$ and contexts $C[]$. A binary relation $>$ of terms is closed under substitutions if $s>t$ implies $s \theta>t \theta$, for any terms $s$ and $t$ and substitutions $\theta$. A strict order is a transitive and irreflexive relation. A reduction order is a well-founded strict order which is closed under contexts and substitutions. The following theorem shows the motivation for introducing reduction orders:

Theorem 2.3. A TRS $\mathcal{R}$ is terminating iff there exists a reduction order $>$ such that $l>r$ for all $l \rightarrow r \in \mathcal{R}$.

Proof. 1. Assume $\mathcal{R}$ is terminating. It is obvious that ${ }_{\rightarrow}^{+} \underset{\mathcal{R}}{ }$ is a reduction order and $l{ }^{+}{ }_{\mathcal{R}} r$ for all $l \rightarrow r \in \mathcal{R}$.
2. Since $>$ is a reduction order, for any $l \rightarrow r \in \mathcal{R}, l>r$ implies $C[l \theta]>C[r \theta]$, for any contexts $C[]$ and substitutions $\theta$. Thus, $s_{1} \rightarrow \mathcal{R} s_{2}$ implies $s_{1}>s_{2}$. Since $>$ is wellfounded, there exists no infinite reduction $s_{1} \rightarrow_{\mathcal{R}} s_{2} \rightarrow_{\mathcal{R}} s_{3} \rightarrow_{\mathcal{R}} \cdots$.

Definition 2.4 (lexicographic path order). Let $\mathscr{F}$ be a finite set of function symbols and $>$ be a strict order on $\mathscr{F}$. The lexicographic path order $>_{\text {lpo }}$ on $\mathrm{T}(\mathscr{F}, \mathscr{V})$ induced by $>$ is defined as follows:
$s>_{\text {lpo }} t$ iff

1. $t \in \mathscr{V}(s)$ and $s \neq t$, or
2. $s=f\left(s_{1}, \cdots, s_{m}\right), t=g\left(t_{1}, \cdots, t_{n}\right)$, and
(a) there exists $i, 1 \leq i \leq m$, with $s_{i}>_{\text {lpo }} t$, or
(b) $f>g$ and $s>_{\text {lpo }} t_{j}$ for all $j, 1 \leq j \leq n$, or
(c) $f=g, s>_{l p o} t_{j}$ for all $j, 1 \leq j \leq n$, and there exists $i, 1 \leq i \leq m$, such that $s_{1}=t_{1}, \cdots, s_{i-1}=t_{i-1}$ and $s_{i}>_{l p o} t_{i}$.

Theorem 2.5. For any strict order on $\mathscr{F}$, the induced lexicographic path order $>_{l p o}$ is a reduction order on $\mathrm{T}(\mathscr{F}, \mathscr{V})$.

A TRS $\mathcal{R}$ is confluent, or has the Church-Rosser property, (denoted by $\operatorname{CR}(\mathcal{R})$ ) if, for any $\operatorname{term}_{*}, s_{1}, s_{2}, s \xrightarrow{*} \mathcal{R} s_{1}$ and $s{ }^{*} \mathcal{R} s_{2}$ imply that there exists a term $t$ such that $s_{1}{ }^{*} \mathcal{R} t$ and $s_{2} \xrightarrow{*} \mathcal{R} t$. Note that $\mathrm{CR}(\mathcal{R}), s, t \in \mathrm{NF}(\mathcal{R})$ and $s \stackrel{*}{\leftrightarrow} \mathcal{R} t$ imply $s=t$. A TRS $\mathcal{R}$ is locally confluent, or has the weakly Church-Rosser property, (denoted by $\operatorname{WCR}(\mathcal{R})$ ) if, for any term $s, s_{1}, s_{2}, s \rightarrow_{\mathcal{R}} s_{1}$ and $s \rightarrow_{\mathcal{R}} s_{2}$ imply that there exists a term $t$ such that $s_{1} \xrightarrow{*} \mathcal{R} t$ and $s_{2} \xrightarrow{*} \mathcal{R} t$. The following lemma is a variant of Newman's Lemma [16].

Lemma 2.6. A terminating TRS is confluent if it is locally confluent.
For substitutions $\sigma$ and $\theta$, we say $\sigma$ is more general than $\theta$ if there exists a substitution $\sigma^{\prime}$ such that $\theta=\sigma^{\prime} \circ \sigma$. In this case, we write $\sigma \lesssim \theta$. Terms $s$ and $t$ are unifiable if there exists substitution $\sigma$ such that $s \sigma=t \sigma$. In this case $\sigma$ is a unifier of $s$ and $t$. A unifier $\sigma$ of terms $s$ and $t$ is most general unifier if $\sigma$ is more general than any unifier of $s$ and $t$. A most general unifier of $s$ and $t$ is denoted as $\operatorname{mgu}(s, t)$.

Definition 2.7. Let $l_{1} \rightarrow r_{1}$ and $l_{2} \rightarrow r_{2}$ be rewrite rules whose variables are disjoint (i.e. $\left.\mathscr{V}\left(l_{1}\right) \cap \mathscr{V}\left(l_{2}\right)=\emptyset\right)$. If there exists a context $C[]$ such that $l_{1}=C\left[l_{1}^{\prime}\right]$ where $l_{1}^{\prime}$ is not a variable and $l_{1}^{\prime}$ and $l_{2}$ are unifiable, we say $l_{1}$ overlaps $l_{2}$ and a pair of terms $\left\langle r_{1} \sigma, C\left[r_{2}\right] \sigma\right\rangle$ is called a critical pair where $\sigma$ is a most general unifier of $l_{1}^{\prime}$ and $l_{2}$.

The critical pairs of a TRS $\mathcal{R}$ are the critical pairs between any two rules whose variables are renamed. The set of critical pairs of a $\operatorname{TRS} \mathcal{R}$ is denoted by $\operatorname{CP}(\mathcal{R})$. We say that a TRS $\mathcal{R}_{1}$ overlaps a TRS $\mathcal{R}_{2}$ if there exist rewrite rules $l_{1} \rightarrow r_{1} \in \mathcal{R}_{1}$ and $l_{2} \rightarrow r_{2} \in \mathcal{R}_{2}$ such that $l_{1}$ overlaps $l_{2}$. A critical pair $\langle s, t\rangle$ of a $\operatorname{TRS} \mathcal{R}$ is joinable if there exists a term $u$ such that $s \xrightarrow{*} \mathcal{R} u$ and $t \xrightarrow{*} \mathcal{R} u$.

The following is called Critical Pair Theorem, which is brought by Knuth and Bendix[14].
Theorem 2.8. A TRS is locally confluent iff all its critical pairs are joinable.
We obtain the following theorem from Critical Pair Theorem and Lemma 2.6.
Corollary 2.9. A terminating $T R S$ is confluent iff all its critical pairs are joinable
Critical Pair Theorem can apply only terminating TRSs to show their confluence and confluence is undecidable in general. It is known that there are sufficient conditions to guarantee confluence of TRSs. Orthogonality is one of such sufficient conditions. A linear term is a term in which any variable appears at most once. For any term $s$, the set of function symbols and variables in $s$ are denoted by $\mathscr{F}(s)$ and $\mathscr{V}(s)$, respectively. A rewrite rule $l \rightarrow r$ is left-linear when $l$ is linear; a TRS $\mathcal{R}$ is left-linear if every rewrite rule in $\mathcal{R}$ is left-linear. A TRS is orthogonal if it is left-linear and has no critical pairs. The following theorem shows that orthogonality is a sufficient condition to show confluence.

Theorem 2.10. If a $T R S$ is orthogonal then it is confluent.
We note that Theorem 2.10 can apply nonterminating TRSs.
Modularity is one of effective methods to show several properties. Toyama showed that confluence has modularity[24, 25].

Theorem 2.11. Let $\mathcal{R}_{1}$ and $\mathcal{R}_{2}$ be left-linear TRSs such that each TRS does not overlap another. $\mathrm{CR}\left(\mathcal{R}_{1}\right) \wedge \mathrm{CR}\left(\mathcal{R}_{2}\right)$ implies $\mathrm{CR}\left(\mathcal{R}_{1} \cup \mathcal{R}_{2}\right)$.

We assume that the set $\mathscr{F}$ of function symbols is divided into two disjoint sets-the set $\mathscr{F}_{\mathrm{d}}$ of defined function symbols and the set $\mathscr{F}_{\mathrm{c}}$ of constructor symbols. Elements of $\mathrm{T}\left(\mathscr{F}_{\mathrm{c}}, \mathscr{V}\right)$ are called constructor terms. A rewrite rule $l \rightarrow r$ is a constructor rule if $l=f\left(l_{1}, \ldots, l_{n}\right)$ for some $f \in \mathscr{F}_{\mathrm{d}}$ and $l_{1}, \ldots, l_{n} \in \mathrm{~T}\left(\mathscr{F}_{\mathrm{c}}, \mathscr{V}\right)$. A TRS $\mathcal{R}$ is a constructor system (CS for short) if every rewrite rule is a constructor rule.

Definition 2.12. Suppose $\mathscr{F}_{\mathrm{c}} \subseteq \mathscr{G} \subseteq \mathscr{F} . A T R S \mathcal{R}$ is sufficiently complete for $\mathscr{G}(\mathrm{SC}(\mathcal{R}, \mathscr{G})$ ) when for any ground term $s \in \mathrm{~T}(\mathscr{G})$ there exists $t \in \mathrm{~T}\left(\mathscr{F}_{\mathrm{c}}\right)$ such that $s{ }^{*}{ }_{\mathcal{R}} t$.

A $\operatorname{TRS} \mathscr{R}$ is quasi-reducible if for any $f \in \mathscr{D}(\operatorname{arity}(f)=n)$ and $s_{1}, \ldots, s_{n} \in T(\mathscr{C})$ $f\left(s_{1}, \ldots, s_{n}\right)$ is not a normal form of $\mathcal{R}$. Note that if a TRS $\mathcal{R}$ is sufficient complete then $\mathcal{R}$ is quasi-reducible.

Proposition 2.13. $\mathrm{SN}(\mathcal{R})$ and $\mathrm{QR}(\mathcal{R}, \mathscr{G})$ imply $\mathrm{SC}(\mathcal{R}, \mathscr{G})$.
Let $\mathcal{S}$ be a set of sorts. $\mathscr{V}^{\beta}$ denote a set of variables whose sorts are $\beta$. $\mathscr{F}^{\alpha_{1} \times \cdots \times \alpha_{n} \rightarrow \beta}$ denotes the set of function symbols which take arguments of sorts $\alpha_{1}, \cdots, \alpha_{n}$ to values of sorts $\beta$. We note that for any function symbol $f$, arity $(f)=n$ implies $f \in \mathscr{F}^{\alpha_{1} \times \cdots \times \alpha_{n} \rightarrow \beta}$ for some $\alpha_{1}, \cdots, \alpha_{n}, \beta \in \mathcal{S}$. We now define the set $\mathrm{T}^{\beta}(\mathscr{F}, \mathscr{V})$ of many-sorted terms whose sorts are $\beta$ inductively by:

1. $\mathscr{V}^{\beta} \subseteq \mathrm{T}^{\beta}(\mathscr{F}, \mathscr{V})$
2. $f\left(t_{1}, \cdots, t_{n}\right) \in \mathrm{T}^{\beta}(\mathscr{F}, \mathscr{V})$ for any $f \in \mathscr{F}^{\alpha_{1} \times \cdots \times \alpha_{n} \rightarrow \beta}$ and $t_{i} \in \mathrm{~T}^{\alpha_{i}}(\mathscr{F}, \mathscr{V})$ for all $i(1 \leq$ $i \leq n)$.
A TRS $\mathcal{R}$ is called a many-sorted $T R S$ if for any $l \rightarrow r \in \mathcal{R}, l \in \mathrm{~T}^{\beta}(\mathscr{F}, \mathscr{V})$ iff $r \in \mathrm{~T}^{\beta}(\mathscr{F}, \mathscr{V})$ for some $\beta \in \mathcal{S}$. We define $\operatorname{SN}(\mathcal{R}), \operatorname{CR}(\mathcal{R}), \operatorname{SC}(\mathcal{R}, \mathscr{G})$ and $\mathcal{Q R}(\mathrm{R}, \mathscr{G})$

An equation is a pair of terms; we usually write an equation $l \approx r$. For a set $\mathcal{E}$ of equations, we write $s \leftrightarrow \mathcal{E} t$ if there exists a context $C[]$, a substitution $\theta$, and an equation $l \approx r \in \mathcal{E}$ such that $s=C[l \theta]$ and $t=C[r \theta]$ or $s=C[r \theta]$ and $t=C[l \theta]$. The reflexive transitive closure of $\leftrightarrow \mathcal{E}$ is denoted by $\stackrel{*}{\leftrightarrow} \mathcal{E}$. A substitution $\theta$ is ground on $\mathscr{G}$ if $\theta(x) \in \mathrm{T}(\mathscr{G})$ for any $x \in \operatorname{dom}(\theta)$. An equation $s \approx t$ is an inductive consequence of $\mathcal{R}$ for $\mathscr{G}\left(\mathcal{R}, \mathscr{G} \vdash_{\text {ind }} s \approx t\right)$ when for any ground substitution $\theta_{g}$ on $\mathscr{G}$ such that $\mathscr{V}(s) \cup \mathscr{V}(t) \subseteq \operatorname{dom}\left(\theta_{g}\right), s \theta_{g} \stackrel{*}{\leftrightarrow} \mathcal{R} t \theta_{g}$ holds. For a set $\mathcal{E}$ of equations, we write $\mathcal{R}, \mathscr{G} \vdash_{\text {ind }} \mathcal{E}$ when $\mathcal{R}, \mathscr{G} \vdash_{\text {ind }} s \approx t$ for any $s \approx t \in \mathcal{E}$.

The equivalence of two TRSs are defined as follows:
Definition 2.14. Let $\mathscr{G}$ be a set of function symbols such that $\mathscr{F}_{\mathrm{c}} \subseteq \mathscr{G} \subseteq \mathscr{F}$. Two TRSs, $\mathcal{R}$ and $\mathcal{R}^{\prime}$, are said to be equivalent for $\mathscr{G}$ (notation, $\mathcal{R} \simeq_{\mathscr{G}} \mathcal{R}^{\prime}$ ), if for any ground term $s \in \mathrm{~T}(\mathscr{G})$ and ground constructor term $t \in \mathrm{~T}\left(\mathscr{F}_{\mathrm{c}}\right), s \xrightarrow{*} \mathcal{R} t$ iff $s \xrightarrow{*} \mathcal{R}^{\prime} t$ holds.

At this juncture, we need to make a short remark about the definition of the equivalence of TRSs. In a program transformation from $\mathcal{R}$ to $\mathcal{R}^{\prime}$, one cannot generally expect $s \stackrel{*}{\leftrightarrow} \mathcal{R} t$ iff $s \stackrel{*}{\longleftrightarrow} \mathcal{R}^{\prime} t$ for all ground terms $s \in \mathrm{~T}(\mathscr{F})$ and ground constructor term $t \in \mathrm{~T}\left(\mathscr{F}_{\mathrm{c}}\right)$. This is because one TRS may use some subfunctions that the other may not have. This is why the equivalence of TRSs is defined with respect to a set $\mathscr{G}$ of function symbols. Intuitively, the functions in $\mathscr{G}$ are those originally required to compute by the TRSs in comparison.

Although whether two TRSs are equivalent cannot generally be decided, it is known that two TRSs are equivalent when there exists an equivalent transformation from one to the other [25] for some restricted class of TRSs. We simplify and improve this technique for our framework in Chapter 4.

## Chapter 3

## Program Transformation by Templates

In this chapter, we formalize the framework of program transformation by templates based on term rewriting. We give a notion of transformation templates within our framework. We then introduce a notion of term homomorphism to specify how to apply transformation templates to TRSs. We also show that term homomorphisms preserve reductions.

### 3.1 Motivating Example

This section introduces our framework of program transformation in which programs are formalized by TRSs. Let us start with some motivating examples.

Example 3.1. A program that computes the summation of a list is specified by the following TRS $\mathcal{R}_{\text {sum }}$, in which the natural numbers $0,1,2, \ldots$ are expressed as $0, \mathrm{~s}(0), \mathrm{s}(\mathrm{s}(0)), \ldots$.

$$
\mathcal{R}_{\text {sum }}\left\{\begin{array}{lll}
\operatorname{sum}([]) & \rightarrow & 0 \\
\operatorname{sum}\left(x_{1}: y_{1}\right) & \rightarrow & +\left(x_{1}, \operatorname{sum}\left(y_{1}\right)\right) \\
+\left(0, x_{2}\right) & \rightarrow & x_{2} \\
+\left(\mathbf{s}\left(x_{3}\right), y_{3}\right) & \rightarrow & \mathrm{s}\left(+\left(x_{3}, y_{3}\right)\right)
\end{array}\right.
$$

This $\mathcal{R}_{\text {sum }}$ computes the summation of a list using a recursive call. For instance, sum(1:(2:(3:(4:(5:[]))) $\xrightarrow{*}_{\mathcal{R}_{\text {sum }}}+\left(1,+\left(2,+(3,+(4,+(5, \operatorname{sum}([])))) \xrightarrow{*}_{\mathcal{R}_{\text {sum }}} 15\right.\right.$.

Using the well-known transformation from the recursive form to the iterative (tail-recursive) form, the following different $\operatorname{TRS} \mathcal{R}_{\text {sum }}^{\prime}$ for the list summation program is obtained:

$$
\mathcal{R}_{\text {sum }}^{\prime} \begin{cases}\operatorname{sum}\left(x_{4}\right) & \rightarrow \operatorname{sum} 1\left(x_{4}, 0\right) \\ \operatorname{sum} 1\left([], x_{5}\right) & \rightarrow x_{5} \\ \operatorname{sum} 1\left(x_{6}: y_{6}, z_{6}\right) & \rightarrow \operatorname{sum} 1\left(y_{6},+\left(z_{6}, x_{6}\right)\right) \\ +\left(0, x_{7}\right) & \rightarrow x_{7} \\ +\left(\mathrm{s}\left(x_{8}\right), y_{8}\right) & \rightarrow \mathrm{s}\left(+\left(x_{8}, y_{8}\right)\right)\end{cases}
$$

$\mathcal{R}_{\text {sum }}^{\prime}$ computes the summation of a list more efficiently without the recursion. The equality of the two programs is found using the associativity of the function + and the property $+(0, n)=$ $+(n, 0)$.

Example 3.2. Let us consider another example of program transformation. A program that computes the concatenation of a list of lists is specified by the following TRS $\mathcal{R}_{\text {cat }}$.

$$
\mathcal{R}_{c a t}\left\{\begin{array}{lll}
\operatorname{cat}([]) & \rightarrow & {[]} \\
\operatorname{cat}\left(x_{1}: y_{1}\right) & \rightarrow & \operatorname{app}\left(x_{1}, \operatorname{cat}\left(y_{1}\right)\right) \\
\operatorname{app}\left([], x_{2}\right) & \rightarrow & x_{2} \\
\operatorname{app}\left(x_{3}: y_{3}, z_{3}\right) & \rightarrow & x_{3}: \operatorname{app}\left(y_{3}, z_{3}\right)
\end{array}\right.
$$

For example, we have $\operatorname{cat}([[1,2],[3],[4,5]]) \xrightarrow{*}_{\mathcal{R}_{c a t}}[1,2,3,4,5]$. Similarly to Example 3.1, the transformation from the recursive form to the iterative form gives a more efficient $\operatorname{TRS} \mathcal{R}_{c a t}^{\prime}$ as follows.

$$
\mathcal{R}_{c a t}^{\prime} \begin{cases}\operatorname{cat}\left(x_{4}\right) & \rightarrow \operatorname{cat1}\left(x_{4},[]\right) \\ \operatorname{cat1}\left([], x_{5}\right) & \rightarrow x_{5} \\ \operatorname{cat1}\left(x_{6}: y_{6}, z_{6}\right) & \rightarrow \operatorname{cat1}\left(y_{6}, \operatorname{app}\left(z_{6}, x_{6}\right)\right) \\ \operatorname{app}\left([], x_{7}\right) & \rightarrow x_{7} \\ \operatorname{app}\left(x_{8}: y_{8}, z_{8}\right) & \rightarrow x_{8}: \operatorname{app}\left(y_{8}, z_{8}\right)\end{cases}
$$

Note that the associativity of the function app and the property app([ ],as) $=\operatorname{app}(a s,[])$ hold. Thus, the equality of the two programs is shown similarly.

Example 3.3. One can easily observe that these two transformations in the previous examples can be generalized to a more abstract "transformation template": the TRS pattern $\mathcal{P}$

$$
\mathcal{P} \begin{cases}\mathrm{f}(\mathrm{a}) & \rightarrow \mathrm{b} \\ \mathrm{f}\left(\mathrm{c}\left(u_{1}, v_{1}\right)\right) & \rightarrow \\ \mathrm{g}\left(\mathrm{~b}, u_{2}\right) & \rightarrow \\ \mathrm{g}\left(\mathrm{~d}\left(u_{3}, v_{3}\right), w_{3}\right) & \left.\rightarrow \mathrm{f}\left(v_{1}\right)\right) \\ \mathrm{d}\left(u_{3}, \mathrm{~g}\left(v_{3}, w_{3}\right)\right)\end{cases}
$$

is transformed to the TRS pattern $\mathcal{P}^{\prime}$

$$
\mathcal{P}^{\prime} \begin{cases}\mathrm{f}\left(u_{4}\right) & \rightarrow \mathrm{f}_{1}\left(u_{4}, \mathrm{~b}\right) \\ \mathrm{f}_{1}\left(\mathrm{a}, u_{5}\right) & \rightarrow u_{5} \\ \mathrm{f}_{1}\left(\mathrm{c}\left(u_{6}, v_{6}\right), w_{6}\right) & \rightarrow \mathrm{f}_{1}\left(v_{6}, \mathrm{~g}\left(w_{6}, u_{6}\right)\right) \\ \mathrm{g}\left(\mathrm{~b}, u_{7}\right) & \rightarrow u_{7} \\ \mathrm{~g}\left(\mathrm{~d}\left(u_{8}, v_{8}\right), w_{8}\right) & \rightarrow \mathrm{d}\left(u_{8}, \mathrm{~g}\left(v_{8}, w_{8}\right)\right)\end{cases}
$$

All the function symbols $\mathrm{f}, \mathrm{a}, \mathrm{b}, \mathrm{g}, \cdots$ occurring in the TRS patterns $\mathcal{P}$ and $\mathcal{P}^{\prime}$ are pattern variables. If we match the TRS pattern $\mathcal{P}$ to a concrete TRS $\mathcal{R}$ with an instantiation for these pattern variables, we obtain a more efficient $\operatorname{TRS} \mathcal{R}^{\prime}$ by applying this instantiation to the pattern $\mathcal{P}^{\prime}$. The equality of $\mathcal{R}_{\text {sum }}$ and $\mathcal{R}_{\text {sum }}^{\prime}\left(\mathcal{R}_{\text {cat }}\right.$ and $\left.\mathcal{R}_{\text {cat }}^{\prime}\right)$ is guaranteed when the instantiation satisfies the following equations, called a hypothesis:

$$
\mathcal{H} \begin{cases}\mathrm{g}\left(\mathrm{~b}, u_{1}\right) & \approx \mathrm{g}\left(u_{1}, \mathrm{~b}\right) \\ \mathrm{g}\left(\mathrm{~g}\left(u_{2}, v_{2}\right), w_{2}\right) & \approx \mathrm{g}\left(u_{2}, \mathrm{~g}\left(v_{2}, w_{2}\right)\right)\end{cases}
$$

We are now going to introduce a formal definition of a "transformation template".
Definition 3.4. Let $\mathscr{X}$ be a set of pattern variables (disjoint from $\mathscr{F}$ and $\mathscr{V}$ ) where each pattern variable $p \in \mathscr{X}$ has its arity (denoted by $\operatorname{arity}(p)$ ). A term pattern (or just pattern) is a term in $\mathrm{T}(\mathscr{F} \cup \mathscr{X}, \mathscr{V})$. A TRS pattern $\mathcal{P}$ is a set of rewriting rules over patterns. A hypothesis $\mathcal{H}$ is a set of equations over patterns. A transformation template (or just template) is a triple $\left\langle\mathcal{P}, \mathcal{P}^{\prime}, \mathcal{H}\right\rangle$ of two TRS patterns $\mathcal{P}, \mathcal{P}^{\prime}$ and a hypothesis $\mathcal{H}$. For patterns $s$, $t$, we define $s \rightarrow_{\mathcal{P}} t, s \leftrightarrow_{\mathcal{H}} t$, etc. similarly for terms.

### 3.2 Term Homomorphism

To achieve program transformation using templates, we need a mechanism to specify how a template is applied to a concrete TRS. For this, we use a variant of the notion of tree homomorphism [5]-we call this a term homomorphism.

Definition 3.5. Let $\varphi$ be a mapping from $\mathscr{X} \cup \mathscr{V}$ to $T^{\square}(\mathscr{X} \cup \mathscr{F}, \mathscr{V})$. We say $\varphi$ is a term homomorphism if the following conditions are satisfied:

1. $\varphi(p) \in T_{\operatorname{arity}(p)}^{\square}(\mathscr{F})$ for any $p \in \operatorname{dom}_{\mathscr{X}}(\varphi)$,
2. $\varphi(x) \in \mathscr{V}$ for any $x \in \operatorname{dom}_{\mathscr{V}}(\varphi)$,
3. $\varphi$ is injective on $\operatorname{dom}_{\mathscr{V}}(\varphi)$, i.e., for any $x, y \in \operatorname{dom}_{\mathscr{V}}(\varphi)$, if $x \neq y$ then $\varphi(x) \neq \varphi(y)$,
where $\operatorname{dom}_{\mathscr{X}}(\varphi)=\left\{p \in \mathscr{X} \mid \varphi(p) \neq p\left(\square_{1}, \ldots, \square_{\text {arity }(p)}\right)\right\}$ and $\operatorname{dom}_{\mathscr{V}}(\varphi)=\{x \in \mathscr{V} \mid \varphi(x) \neq$ $x\}$. A term homomorphism $\varphi$ is extended to a mapping over $\mathrm{T}(\mathscr{F} \cup \mathscr{X}, \mathscr{V})$ as follows:

$$
\varphi(s)=\left\{\begin{array}{l}
\varphi(x) \quad \text { if } s=x \in \mathscr{V} \\
f\left(\varphi\left(s_{1}\right), \ldots, \varphi\left(s_{n}\right)\right) \\
\text { if } s=f\left(s_{1}, \ldots, s_{n}\right), f \in \mathscr{F} \\
\varphi(p)\left\langle\varphi\left(s_{1}\right), \ldots, \varphi\left(s_{n}\right)\right\rangle \\
\quad \text { if } s=p\left(s_{1}, \ldots, s_{n}\right), p \in \mathscr{X}
\end{array}\right.
$$

Note that $\varphi(s)$ is a pattern for any pattern $s$ and term homomorphism $\varphi$. For a term homomorphism $\varphi$ and a rewrite rule $l \rightarrow r$ (an equation $s \approx t$ ) over patterns, $\varphi(l \rightarrow r$ ) $(\varphi(s \approx t))$ is defined by $\varphi(l) \rightarrow \varphi(r)($ resp. $\varphi(s) \approx \varphi(t))$. For a TRS pattern $\mathcal{P}$ and a hypothesis $\mathcal{H}, \varphi(\mathcal{P})$ and $\varphi(\mathcal{H})$ are defined by $\varphi(\mathcal{P})=\{\varphi(l \rightarrow r) \mid l \rightarrow r \in \mathcal{P}\}$ and $\varphi(\mathcal{H})=\{\varphi(s \approx t) \mid s \approx$ $t \in \mathcal{H}\}$, respectively.

If $\varphi(\mathcal{P})=\mathcal{R}$ for some term homomorphism $\varphi$, we assume $\mathscr{V}(\mathcal{P}) \cap \mathscr{V}(\mathcal{R})=\emptyset$ without loss of generality.

We are now going to demonstrate that any term homomorphism preserves reduction. This property of term homomorphisms is proved in a straightforward manner using the injectivity of term homomorphisms. To show this, we extend term homomorphisms $\varphi$ for substitution $\theta$ like this: $\varphi(\theta)(x)=\varphi\left(\theta\left(\varphi^{-1}(x)\right)\right)$, where $\varphi^{-1}(x)=y$ if $y \in \operatorname{dom}_{\mathscr{V}}(\varphi)$, and $\varphi(y)=x ; \varphi^{-1}(x)=x$ otherwise. Note that since term homomorphism $\varphi$ is injective on $\operatorname{dom}_{\mathscr{V}}(\varphi)$, one can uniquely define the mapping $\varphi^{-1}$.

Lemma 3.6. Let $t$ be a pattern, $\theta$ a substitution, and $\varphi$ a term homomorphism such that $\mathscr{V}(t) \subseteq \operatorname{dom}_{\mathscr{V}}(\varphi)$. Then, $\varphi(t \theta)=\varphi(t) \varphi(\theta)$.
(Proof) The proof proceeds by induction on $t$.

1. $t=x \in \mathscr{V}$.

Let $\varphi(x)=y$. Then,

$$
\begin{aligned}
\varphi(x \theta) & =\varphi\left(\theta\left(\varphi^{-1}(y)\right)\right) \\
& =\varphi(\theta)(y) \\
& =\varphi(x) \varphi(\theta)
\end{aligned}
$$

2. $t=f\left(t_{1}, \ldots, t_{n}\right)$ with $f \in \mathscr{F}$.

Then,

$$
\begin{aligned}
\varphi(t \theta) & =\varphi\left(f\left(t_{1} \theta, \ldots, t_{n} \theta\right)\right) \\
& =f\left(\varphi\left(t_{1} \theta\right), \ldots, \varphi\left(t_{n} \theta\right)\right) \\
& =f\left(\varphi\left(t_{1}\right) \varphi(\theta), \ldots, \varphi\left(t_{n}\right) \varphi(\theta)\right) \\
& =f\left(\varphi\left(t_{1}\right), \ldots, \varphi\left(t_{n}\right)\right) \varphi(\theta) \\
& =\varphi\left(f\left(t_{1}, \ldots, t_{n}\right)\right) \varphi(\theta) \\
& =\varphi(t) \varphi(\theta)
\end{aligned}
$$

3. $t=p\left(t_{1}, \ldots, t_{n}\right)$ with $p \in \mathscr{X}$.

Then,

$$
\begin{aligned}
& \varphi(t \theta) \\
= & \varphi\left(p\left(t_{1}, \ldots, t_{n}\right) \theta\right) \\
= & \varphi\left(p\left(t_{1} \theta, \ldots, t_{n} \theta\right)\right) \\
= & \varphi(p)\left\langle\varphi\left(t_{1} \theta\right), \ldots, \varphi\left(t_{n} \theta\right)\right\rangle \\
= & \varphi(p)\left\langle\varphi\left(t_{1}\right) \varphi(\theta), \ldots, \varphi\left(t_{n}\right) \varphi(\theta)\right\rangle \\
= & \left(\varphi(p)\left\langle\varphi\left(t_{1}\right), \ldots, \varphi\left(t_{n}\right)\right\rangle\right) \varphi(\theta) \\
= & \left(\varphi\left(p\left(t_{1}, \ldots, t_{n}\right)\right) \varphi(\theta)\right. \\
= & \varphi(t) \varphi(\theta) .
\end{aligned}
$$

(Note that $\mathscr{V}(\varphi(p))=\emptyset$.
Lemma 3.7. Let $t$ be a pattern, $C[]$ a context, and $\varphi$ a term homomorphism. Then, $\varphi(C[t])=$ $\varphi(C)[\varphi(t), \ldots, \varphi(t)]$.
(Proof) The proof proceeds by induction on the size of $C[]$.

1. $C[]=\square$.

Trivial.
2. $C[]=f\left(s_{1}, \ldots, C^{\prime}[], \ldots, s_{n}\right)$ with $f \in \mathscr{F}$. Then,

$$
\begin{aligned}
& \varphi\left(f\left(s_{1}, \ldots, C^{\prime}[t], \ldots, s_{n}\right)\right) \\
&=\left.f\left(\varphi\left(s_{1}\right), \ldots, \varphi\left(C^{\prime}[t]\right), \ldots, \varphi\left(s_{n}\right)\right)\right) \\
&= f\left(\varphi\left(s_{1}\right), \ldots, \varphi\left(C^{\prime}\right)[\varphi(t), \ldots, \varphi(t)],\right. \\
&\left.\left.\ldots, \varphi\left(s_{n}\right)\right)\right) \\
&= f\left(\varphi\left(s_{1}\right), \ldots, \varphi\left(C^{\prime}\right), \ldots, \varphi\left(s_{n}\right)\right) \\
&= \varphi(C)[\varphi(t), \ldots, \varphi(t)]
\end{aligned}
$$

3. $C[]=p\left(s_{1}, \ldots, s_{n}\right)$ with $s_{i}=C^{\prime}[]$ and $p \in \mathscr{X}$.

Then,

$$
\begin{aligned}
& \varphi\left(p\left(s_{1}, \ldots, C^{\prime}[t], \ldots, s_{n}\right)\right) \\
= & \varphi(p)\left\langle\varphi\left(s_{1}\right), \ldots, \varphi\left(C^{\prime}[t]\right), \ldots, \varphi\left(s_{n}\right)\right\rangle \\
= & \varphi(p)\left\langle\varphi\left(s_{1}\right), \ldots,\right. \\
= & \left.\varphi\left(C^{\prime}\right)[\varphi(t), \ldots, \varphi(t)], \ldots, \varphi\left(s_{n}\right)\right\rangle \\
= & \left(\varphi(p)\left\langle\varphi\left(s_{1}\right), \ldots, \varphi\left(C^{\prime}\right), \ldots, \varphi\left(s_{n}\right)\right\rangle\right) \\
= & \varphi\left(p\left(s_{1}, \ldots, C^{\prime}, \ldots, s_{n}\right)\right) \\
= & \varphi(C)[\varphi(t), \ldots, \varphi(t)] \\
= & {[\varphi(t), \ldots, \varphi(t)] } \\
&
\end{aligned}
$$

Proposition 3.8. Let $\mathcal{P}$ be a TRS pattern, $\mathcal{R}$ a TRS, $\mathcal{H}$ a hypothesis, $\mathcal{E}$ a set of equations, and $\varphi$ a term homomorphism such that $\varphi(\mathcal{P})=\mathcal{R}(\varphi(\mathcal{H})=\mathcal{E})$. If $s \rightarrow_{\mathcal{P}} t\left(s \leftrightarrow_{\mathcal{H}} t\right)$, then we have $\varphi(s) \rightarrow_{\mathcal{R}} \varphi(t)\left(\right.$ resp. $\left.\varphi(s) \leftrightarrow_{\mathcal{E}} \varphi(t)\right)$.
(Proof) Suppose $s \rightarrow_{\mathcal{P}} t$. Then, there exists a context $C[]$, a substitution $\theta$, and a rewrite rule pattern $l \rightarrow r \in \mathcal{P}$ such that $s=C[l \theta]$ and $r=C[r \theta]$. Also, $\mathscr{V}(l), \mathscr{V}(r) \subseteq \operatorname{dom}(\varphi)$ by $\mathscr{V}(\mathcal{P}) \cap \mathscr{V}(\mathcal{R})$. Then,

$$
\begin{aligned}
\varphi(s) & =\varphi(C[l \theta]) \\
& =\varphi(C)[\varphi(l \theta), \ldots, \varphi(l \theta)] \\
& \quad(\text { by Lemma 3.7) } \\
& =\varphi(C)[\varphi(l) \varphi(\theta), \ldots, \varphi(l) \varphi(\theta)] \\
& \quad(\text { by Lemma 3.6) } \\
& \xrightarrow{*} \mathcal{R} \quad \varphi(C)[\varphi(r) \varphi(\theta), \ldots, \varphi(r) \varphi(\theta)] \\
& =\varphi(C)[\varphi(r \theta), \ldots, \varphi(r \theta)] \\
& \quad(\text { by Lemma 3.6) } \\
& =\varphi(C[r \theta])(\text { by Lemma 3.7) } \\
& =\varphi(t) .
\end{aligned}
$$

It can be shown that $s \leftrightarrow_{\mathcal{H}} t$ implies $\varphi(s) \leftrightarrow_{\mathcal{E}} \varphi(t)$ in a similar way.
The TRS transformation by a template is defined as follows.
Definition 3.9. Let $\left\langle\mathcal{P}, \mathcal{P}^{\prime}, \mathcal{H}\right\rangle$ be a template. $A T R S \mathcal{R}$ is transformed into $\mathcal{R}^{\prime}$ by $\left\langle\mathcal{P}, \mathcal{P}^{\prime}, \mathcal{H}\right\rangle$ if there exists a term homomorphism $\varphi$ such that $\mathcal{R}=\varphi(\mathcal{P}) \cup \mathcal{R}_{\text {com }}$ and $\mathcal{R}^{\prime}=\varphi\left(\mathcal{P}^{\prime}\right) \cup \mathcal{R}_{\text {com }}$ for some $T R S \mathcal{R}_{\text {com }}$.

Note that the hypothesis $\mathcal{H}$ is not used in the definition of the transformation, but it will be needed later when we discuss the correctness of the transformation.

Example 3.10. Let $\mathcal{R}_{\text {sum }}, \mathcal{R}_{\text {sum }}^{\prime}$ be the TRSs in Example 3.1, and $\left\langle\mathcal{P}, \mathcal{P}^{\prime}, \mathcal{H}\right\rangle$ the template given in Example 3.3. Then, the following term homomorphism $\varphi$ satisfies $\mathcal{R}_{\text {sum }}=\varphi(\mathcal{P})$ and $\mathcal{R}_{\text {sum }}^{\prime}=\varphi\left(\mathcal{P}^{\prime}\right)$.

$$
\varphi=\left\{\begin{array}{ll}
\mathrm{f} \mapsto \operatorname{sum}\left(\square_{1}\right), & u_{1} \mapsto x_{1}, u_{6} \mapsto x_{6}, \\
\mathrm{~g} \mapsto+\left(\square_{1}, \square_{2}\right), & v_{1} \mapsto y_{1}, v_{6} \mapsto y_{6}, \\
\mathrm{f}_{1} \mapsto \operatorname{sum}\left(\square_{1}, \square_{2}\right), & u_{2} \mapsto x_{2}, w_{6} \mapsto z_{6}, \\
\mathrm{a} \mapsto[], & v_{3} \mapsto x_{3}, u_{7} \mapsto x_{7}, \\
\mathrm{~b} \mapsto 0, & w_{3} \mapsto y_{3}, v_{8} \mapsto y_{8}, \\
\mathrm{c} \mapsto \square_{1}: \square_{2}, & u_{4} \mapsto x_{4}, w_{8} \mapsto z_{8} \\
\mathrm{~d} \mapsto \mathrm{~s}\left(\square_{2}\right), & u_{5} \mapsto x_{5},
\end{array}\right\}
$$

Thus, the TRS $\mathcal{R}_{\text {sum }}$ is transformed into $\mathcal{R}_{\text {sum }}^{\prime}$ by $\left\langle\mathcal{P}, \mathcal{P}^{\prime}, \mathcal{H}\right\rangle$ where $\mathcal{R}_{\text {com }}=\emptyset$.
Example 3.11. Let $\mathcal{R}_{c a t}, \mathcal{R}_{c a t}^{\prime}$ be the TRSs in Example 3.2, and $\left\langle\mathcal{P}, \mathcal{P}^{\prime}, \mathcal{H}\right\rangle$ the template given in Example 3.3. Then, the following term homomorphism $\varphi$ satisfies $\mathcal{R}_{\text {cat }}=\varphi(\mathcal{P})$ and $\mathcal{R}_{c a t}^{\prime}=\varphi\left(\mathcal{P}^{\prime}\right)$.

$$
\varphi=\left\{\begin{array}{ll}
\mathrm{f} \mapsto \operatorname{cat}\left(\square_{1}\right), & u_{1} \mapsto x_{1}, u_{6} \mapsto x_{6}, \\
\mathrm{~g} \mapsto \mathrm{app}\left(\square_{1}, \square_{2}\right), & v_{1} \mapsto y_{1}, v_{6} \mapsto y_{6}, \\
\mathrm{f}_{1} \mapsto \operatorname{cat}\left(\square_{1}, \square_{2}\right), u_{2} \mapsto x_{2}, w_{6} \mapsto z_{6}, \\
\mathrm{a} \mapsto[], & v_{3} \mapsto y_{3}, u_{7} \mapsto x_{7}, \\
\mathrm{~b} \mapsto[], & u_{3} \mapsto x_{3}, u_{8} \mapsto x_{8}, \\
\mathrm{c} \mapsto \square_{1}: \square_{2}, & w_{3} \mapsto z_{3}, v_{8} \mapsto y_{8}, \\
\mathrm{~d} \mapsto \square_{1}: \square_{2}, & u_{4} \mapsto x_{4}, w_{8} \mapsto z_{8} \\
& u_{5} \mapsto x_{5},
\end{array}\right\}
$$

Thus, the TRS $\mathcal{R}_{c a t}$ is transformed into $\mathcal{R}_{c a t}^{\prime}$ by $\left\langle\mathcal{P}, \mathcal{P}^{\prime}, \mathcal{H}\right\rangle$ where $\mathcal{R}_{c o m}=\emptyset$.
Readers can easily observe from these examples that $\mathcal{R}_{\text {sum }}$ and $\mathcal{R}_{\text {cat }}$ are respectively transformed into $\mathcal{R}_{\text {sum }}^{\prime}$ and $\mathcal{R}_{\text {cat }}^{\prime}$ in the same way. A question naturally arises from this observation: does the template guarantee the correctness of all the transformations done by that template? In the next chapter, we will discuss the criteria for the templates for the correct transformation and try to give a definite answer to this question.

### 3.3 Summary

We proposed a framework of program transformation by templates in this chapter. Programs are represented by TRSs. A transformation templates is defined as a triple $\left\langle\mathcal{P}, \mathcal{P}^{\prime}, \mathcal{H}\right\rangle$ of two TRS patterns $\mathcal{P}$ and $\mathcal{P}^{\prime}$ which are TRSs including pattern variables and hypothesis $\mathcal{H}$. In order to specify how a template is applied to a concrete TRS, we introduced a notion of term homomorphisms. We then show that term homomorphisms preserve reductions (Proposition 3.8). The definition of TRS transformations by templates was given in Definition 3.9.

## Chapter 4

## Correctness of Transformations

Verifying the correctness is one of important problems for program transformations. The correctness of transformations is formalized as the equality of input and output TRSs in our framework. Equivalent transformation of TRSs proposed by Toyama[25] is one of techniques to verify the equality of two TRSs. In this chapter, we simplify and improve this technique to specialize in our framework. We then propose a notion of correct templates which guarantee the correctness of transformation of restricted TRSs. The method of constructing correct templates is given by lifting up the notion of equivalent transformation of TRSs to the template level.

### 4.1 Equivalent Transformation of TRS

This section discusses how the correctness of program transformation using templates is validated, i.e., when the equivalence of the input and output programs of program transformations are guaranteed. Intuitively, a program transformation from one program to another is correct if these programs compute the same answer for any input data.

Although whether two TRSs are equivalent cannot generally be decided, it is known that two TRSs are equivalent when there exists an equivalent transformation from one to the other [25] for some restricted class of TRSs. Let us simplify and improve this technique for our framework.

For a set $\mathscr{G}$ of function symbols, we speak of a $\operatorname{TRS} \mathcal{R}$ (or a set $\mathcal{E}$ of equations) over $\mathscr{G}$ when all rewrite rules (resp. equations) consist of terms in $\mathrm{T}(\mathscr{G}, \mathscr{V})$.

Definition 4.1. Let $\mathcal{R}_{0}$ be a left-linear $C S$ over $\mathscr{F}_{0}$ and $\mathcal{E}$ be a set of equations over $\mathscr{F}_{0}$. An equivalent transformation sequence under $\mathcal{E}$ is a sequence $\mathcal{R}_{0}, \ldots, \mathcal{R}_{n}$ of $T R S$ s (over $\mathscr{F}_{0}, \ldots, \mathscr{F}_{n}$, respectively) such that $\mathcal{R}_{k+1}$ is obtained from $\mathcal{R}_{k}$ by applying one of the following inference rules:
(I) Introduction

$$
\mathcal{R}_{k+1}=\mathcal{R}_{k} \cup\left\{f\left(x_{1}, \ldots, x_{n}\right) \rightarrow r\right\}
$$

provided that $f\left(x_{1}, \ldots, x_{n}\right) \rightarrow r$ is a left-linear constructor rewrite rule such that $f \notin \mathscr{F}_{k}$ and $r \in \mathrm{~T}\left(\mathscr{F}_{k}, \mathscr{V}\right)$. We put $\mathscr{F}_{k+1}=\mathscr{F}_{k} \cup\{f\}$.
(A) Addition

$$
\mathcal{R}_{k+1}=\mathcal{R}_{k} \cup\{l \rightarrow r\}
$$

provided $l \stackrel{*}{\longleftrightarrow} \mathcal{R}_{k} \cup \mathcal{E} r$ holds.

$$
\mathcal{R}_{k+1}=\mathcal{R}_{k} \backslash\{l \rightarrow r\}
$$

When this is the case, we write $\mathcal{R}_{k} \Rightarrow \mathcal{R}_{k+1}$. (In the Addition and Elimination rules, $\mathscr{F}_{k+1}$ can be any set of function symbols such that $\mathscr{F}_{k+1} \subseteq \mathscr{F}_{k}$ provided that $\mathcal{R}_{k+1}$ is a TRS over $\mathscr{F}_{k+1}$.) The reflexive transitive closure of $\Rightarrow$ is denoted $b y \stackrel{*}{\Rightarrow}$. We indicate the rule of $\Rightarrow b y$ $\underset{I}{\Rightarrow}, \underset{A}{\Rightarrow}$, or $\underset{E}{\Rightarrow}$. Finally, we say there exists an equivalent transformation from $\mathcal{R}$ to $\mathcal{R}^{\prime}$ under $\mathcal{E}$ when there exits an equivalent transformation sequence $\mathcal{R} \underset{I}{\Rightarrow} \cdot \underset{A}{\Rightarrow} \cdot \underset{E}{\Rightarrow} \mathcal{R}^{\prime}$ under $\mathcal{E}$.

Differences against [25] are listed as follows:

1. Orders of applying inference rules are fixed (Introduction $\rightarrow$ Addition $\rightarrow$ Elimination).
2. Some equations can be used in the Addition rule.

Theorem 4.2. Let $\mathscr{G}$ and $\mathscr{G}^{\prime}$ be sets of function symbols such that $\mathscr{F}_{c} \subseteq \mathscr{G}_{\mathcal{G}} \mathscr{G}^{\prime} \subseteq \mathscr{F}$. Let $\mathcal{R}$ be a left-linear CS over $\mathscr{G}, \mathcal{E}$ a set of equations over $\mathscr{G}$, and $\mathcal{R}^{\prime}$ a TRS over $\mathscr{G}^{\prime}$. Suppose that $\mathcal{R}, \mathscr{G} \vdash_{\text {ind }} \mathcal{E}$ and there exists an equivalent transformation from $\mathcal{R}$ to $\mathcal{R}^{\prime}$ under $\mathcal{E}$. Then, $\operatorname{CR}(\mathcal{R})$ $\wedge \mathrm{SC}(\mathcal{R}, \mathscr{G}) \wedge \mathrm{SC}\left(\mathcal{R}^{\prime}, \mathscr{G}^{\prime}\right)$ imply $\mathcal{R} \simeq \mathscr{G}_{\boldsymbol{G} \mathscr{G}^{\prime}} \mathcal{R}^{\prime}$.
(Proof) Suppose $\mathcal{R} \underset{I}{\stackrel{*}{\Rightarrow}} \mathcal{R}_{I} \xrightarrow[A]{\Rightarrow} \mathcal{R}_{A} \underset{E}{\stackrel{*}{\Rightarrow}} \mathcal{R}^{\prime}$. We first show some properties of $\mathcal{R}_{I}$. Let $\mathcal{R}_{0}=\mathcal{R}$ and $\mathcal{R}_{i} \underset{I}{\Rightarrow} \mathcal{R}_{i} \cup\left\{f\left(x_{1}, \ldots, x_{n}\right) \rightarrow r\right\}=\mathcal{R}_{i+1}$. Then, $\operatorname{SC}\left(\mathcal{R}_{i}, \mathscr{F}_{i}\right)$ implies $\operatorname{SC}\left(\mathcal{R}_{i+1}, \mathscr{F}_{i} \cup\{f\}\right)$ by the definition of the Introduction rule. Thus, by our assumption $\operatorname{SC}(\mathcal{R}, \mathscr{G})$, it easily follows by induction on the length of $\mathcal{R} \underset{I}{\stackrel{*}{\Rightarrow}} \mathcal{R}_{i}$ that $\operatorname{SC}\left(\mathcal{R}_{i}, \mathscr{F}_{i}\right)$ for all $i$ such that $\mathcal{R} \underset{I}{\underset{I}{*}} \mathcal{R}_{i}$. Thus, we may assume w.l.o.g. $\operatorname{SC}\left(\mathcal{R}_{I}, \mathscr{F}\right)$, because we may ignore any function symbols not appearing even in $\mathcal{R}_{I}$. It is clear that $\mathcal{R} \subseteq \mathcal{R}_{I}$ by the definition of the Introduction rule. Also, from $\operatorname{CR}\left(\mathcal{R}_{0}\right)$ and the fact that each introduced rewrite rule $f\left(x_{1}, \ldots, x_{n}\right) \rightarrow r$ at $i+1$ is left-linear and non-overlapping with left-linear $\operatorname{TRS} \mathcal{R}_{i}$, it follows that $\operatorname{CR}\left(\mathcal{R}_{I}\right)$ using the commutativity of TRSs. Thus, for $\mathcal{R}_{I}$, we have (1) $\operatorname{SC}\left(\mathcal{R}_{I}, \mathscr{F}\right)$, (2) $\mathcal{R} \subseteq \mathcal{R}_{I}$, and (3) $\operatorname{CR}\left(\mathcal{R}_{I}\right)$. We next show that $\stackrel{*}{\longleftrightarrow}_{\mathcal{R}}=\stackrel{*}{\longleftrightarrow}_{\mathcal{R}^{\prime}}$ on $\mathrm{T}\left(\mathscr{G} \cap \mathscr{G}^{\prime}\right)$.

1. $\stackrel{*}{\longleftrightarrow} \mathcal{R}=\stackrel{*}{\longleftrightarrow} \mathcal{R}_{I}$ on $\mathrm{T}(\mathscr{G})$. (i.e., for any $s, t \in \mathrm{~T}(\mathscr{G}), s \stackrel{*}{\longleftrightarrow} \mathcal{R} t$ iff $s \stackrel{*}{\longleftrightarrow} \mathcal{R}_{I} t$.)
( $\subseteq$ ) Trivial. (〕) Suppose that $s \stackrel{*}{\hookrightarrow} \mathcal{R}_{I} t$ where $s, t \in \mathrm{~T}(\mathscr{G})$. By $\operatorname{SC}(\mathcal{R}, \mathscr{G})$, there exist ground constructor terms $s^{\prime}, t^{\prime} \in \mathrm{T}\left(\mathscr{F}_{\mathrm{c}}\right)$ such that $s \xrightarrow{*}_{\mathcal{R}} s^{\prime}$ and $t{ }^{*} \mathcal{R} t^{\prime}$. From $\mathcal{R} \subseteq \mathcal{R}_{I}$, we have $s \xrightarrow{*}_{\mathcal{R}_{I}} s^{\prime}$ and $t \xrightarrow{*} \mathcal{R}_{I} t^{\prime}$. Thus, by $\mathrm{CR}\left(\mathcal{R}_{I}\right)$ and $\mathrm{T}\left(\mathscr{F}_{\mathrm{c}}\right) \subseteq \mathrm{NF}\left(\mathcal{R}_{I}\right), s^{\prime}=t^{\prime}$ holds. This means $s \xrightarrow{*} \mathcal{R} s^{\prime}=t^{\prime} \stackrel{*}{\leftarrow} \mathcal{R} t$.
2. $\stackrel{*}{\leftrightarrow} \mathcal{R}_{I}=\stackrel{*}{\leftrightarrow} \mathcal{R}_{A}$ on $\mathrm{T}(\mathscr{F})$. (i.e., for any $s, t \in \mathrm{~T}(\mathscr{F}), s \stackrel{*}{\leftrightarrow} \mathcal{R}_{I} t$ iff $s \stackrel{*}{\leftrightarrow} \mathcal{R}_{A} t$.)
$(\subseteq)$ Trivial. ( $\supseteq$ ) Suppose that $s \leftrightarrow_{\mathcal{E}} t$ where $s, t \in \mathrm{~T}(\mathscr{F})$. By the definition of $\leftrightarrow \mathcal{E}$, there exist a context $C[]$, a ground substitution $\theta_{g}$, and an equation $l \approx r \in \mathcal{E}$ or $r \approx l \in \mathcal{E}$ such that $s=C\left[l \theta_{g}\right]$ and $t=C\left[r \theta_{g}\right] . \operatorname{By~} \operatorname{SC}\left(\mathcal{R}_{I}, \mathscr{F}\right)$, there exists a ground substitution $\theta_{g}^{\mathrm{c}}$ such that $\theta_{g}(x) \xrightarrow{*} \mathcal{R}_{I} \theta_{g}^{\mathrm{c}}(x) \in \mathrm{T}\left(\mathscr{F}_{\mathrm{c}}\right)$ for any $x \in \operatorname{dom}\left(\theta_{g}\right)$. Then, $C\left[l \theta_{g}\right] \xrightarrow{*} \mathcal{R}_{I} C\left[l \theta_{g}^{\mathrm{c}}\right]$ and $C\left[r \theta_{g}\right] \stackrel{*}{\mathcal{R}_{I}} C\left[r \theta_{g}^{\mathrm{c}}\right]$ hold. Now, since $l \theta_{g}^{\mathrm{c}}, r \theta_{g}^{\mathrm{c}} \in \mathrm{T}(\mathscr{G})$, we have $l \theta_{g}^{\mathrm{c}} \stackrel{*}{\leftrightarrow} \mathcal{R} r \theta_{g}^{\mathrm{c}}$ by our assumption $\mathcal{R}, \mathscr{G} \vdash_{\text {ind }} \mathcal{E}$. Thus, by $\mathcal{R} \subseteq \mathcal{R}_{I}, C\left[l \theta_{g}^{\mathrm{c}}\right] \stackrel{*}{\leftrightarrow} \mathcal{R}_{I} C\left[r \theta_{g}^{\mathrm{c}}\right]$ holds. Hence, $\stackrel{*}{\leftrightarrow} \mathcal{R}_{I} \supseteq$ $\leftrightarrow \mathcal{E}$ on $\mathscr{F}$. It is easy to see by the definition of the Addition rule that $\stackrel{*}{\leftrightarrow} \mathcal{R}_{A}=\stackrel{*}{\leftrightarrow} \mathcal{E} \cup \mathcal{R}_{I}$ on $\mathrm{T}(\mathscr{F}, \mathscr{V})$. Hence, $\stackrel{*}{\leftrightarrow} \mathcal{R}_{A} \subseteq \stackrel{*}{\leftrightarrow}_{\mathscr{E} \cup \mathcal{R}_{I}} \subseteq \stackrel{*}{\leftrightarrow} \mathcal{R}_{I}$ on $\mathrm{T}(\mathscr{F})$.
3. $\stackrel{*}{\longleftrightarrow} \mathcal{R}_{I}=\stackrel{*}{\longleftrightarrow} \mathcal{R}^{\prime}$ on $\mathrm{T}\left(\mathscr{G}^{\prime}\right)$ (i.e., for any $s, t \in \mathrm{~T}\left(\mathscr{G}^{\prime}\right), s \stackrel{*}{\leftrightarrow} \mathcal{R}_{I} t$ iff $s \stackrel{*}{\longleftrightarrow} \mathcal{R}^{\prime} t$.)
$(\supseteq)$ It easily follows from item 2 and the definition of the Elimination rule. ( $\subseteq$ ) Suppose
that $s \stackrel{*}{\mapsto} \mathcal{R}_{I} t$ where $s, t \in \mathrm{~T}\left(\mathscr{G}^{\prime}\right)$. From $\mathrm{SC}\left(\mathcal{R}^{\prime}, \mathscr{G}^{\prime}\right)$, there exist ground constructor terms $s^{\prime}, t^{\prime} \in \mathrm{T}\left(\mathscr{F}_{\mathrm{c}}\right)$ such that $s \xrightarrow{*} \mathcal{R}^{\prime} s^{\prime}$ and $t \xrightarrow{*} \mathcal{R}^{\prime} t^{\prime}$. As we have already shown $\stackrel{*}{\leftrightarrow} \mathcal{R}_{I} \supseteq \stackrel{*}{\leftrightarrow} \mathcal{R}^{\prime}$ on $\mathrm{T}\left(\mathscr{G}^{\prime}\right)$, it follows that $s^{\prime} \stackrel{*}{\leftrightarrow} \mathcal{R}_{I} s \stackrel{*}{\leftrightarrow} \mathcal{R}_{I} t \stackrel{*}{\longleftrightarrow} \mathcal{R}_{I} t^{\prime}$. From $\mathrm{CR}\left(\mathcal{R}_{I}\right)$ and $\mathrm{T}\left(\mathscr{F}_{\mathrm{c}}\right) \subseteq \mathrm{NF}\left(\mathcal{R}_{I}\right)$, $s^{\prime}=t^{\prime}$ holds. This means $s \stackrel{*}{\mathcal{R}^{\prime}} s^{\prime}=t^{\prime} \stackrel{*}{\leftarrow} \mathcal{R}^{\prime} t$.

From 1, 3, and $\mathrm{T}\left(\mathscr{G} \cap \mathscr{G}^{\prime}\right) \subseteq \mathrm{T}(\mathscr{G}), \mathrm{T}(\mathscr{F}), \mathrm{T}\left(\mathscr{G}^{\prime}\right)$, it follows that $\stackrel{*}{\leftrightarrow} \mathcal{R}=\stackrel{*}{\leftrightarrow} \mathcal{R}^{\prime}$ on $\mathrm{T}\left(\mathscr{G} \cap \mathscr{G}^{\prime}\right)$. Finally, we show $\mathcal{R} \simeq_{\mathscr{G} \cap \mathscr{G}^{\prime}} \mathcal{R}^{\prime}$. Suppose $s \in \mathrm{~T}\left(\mathscr{G} \cap \mathscr{G}^{\prime}\right), t \in \mathrm{~T}\left(\mathscr{F}_{\mathrm{c}}\right)$, and $s \xrightarrow{*} \mathcal{R} t$. From $\mathrm{SC}\left(\mathcal{R}^{\prime}, \mathscr{G}^{\prime}\right)$, there exists a constructor term $t^{\prime} \in \mathrm{T}\left(\mathscr{F}_{\mathrm{c}}\right)$ such that $s \stackrel{*}{\rightarrow}_{\mathcal{R}^{\prime}} t^{\prime}$. By $\stackrel{*}{\leftrightarrow} \mathcal{R}=\stackrel{*}{\leftrightarrow} \mathcal{R}^{\prime}$ on $\mathrm{T}\left(\mathscr{G} \cap \mathscr{G}^{\prime}\right)$ and $\mathscr{F}_{\mathrm{c}} \subseteq \mathscr{G} \cap \mathscr{G}^{\prime}$, we have $t \stackrel{*}{\leftrightarrow} \mathcal{R} t^{\prime}$. Then, by $\mathrm{CR}(\mathcal{R})$ and $\mathrm{T}\left(\mathscr{F}_{\mathrm{c}}\right) \subseteq \mathrm{NF}(\mathcal{R})$, it follows $t=t^{\prime}$. Hence, $s \xrightarrow{*}_{\mathcal{R}^{\prime}} t^{\prime}=t$. Conversely, suppose $s \in \mathrm{~T}\left(\mathscr{G} \cap \mathscr{G}^{\prime}\right), t \in \mathrm{~T}\left(\mathscr{F}_{\mathrm{c}}\right)$, and $s \xrightarrow{*}_{\mathcal{R}^{\prime}} t$. From $\operatorname{SC}(\mathcal{R}, \mathscr{G})$, there exists a constructor term $t^{\prime} \in \mathrm{T}\left(\mathscr{F}_{\mathrm{c}}\right)$ such that $s \xrightarrow{*} \mathcal{R} t^{\prime}$. By $\stackrel{*}{\leftrightarrow} \mathcal{R}=\stackrel{*}{\leftrightarrow} \mathcal{R}^{\prime}$ on $\mathrm{T}\left(\mathscr{G} \cap \mathscr{G}^{\prime}\right)$ and $\mathscr{F}_{\mathrm{c}} \subseteq \mathscr{G} \cap \mathscr{G}^{\prime}$, we have $t \stackrel{*}{\leftrightarrow} \mathcal{R} t^{\prime}$. Then, by $\mathrm{CR}(\mathcal{R})$ and $\mathrm{T}\left(\mathscr{F}_{\mathrm{c}}\right) \subseteq \operatorname{NF}(\mathcal{R})$, it follows $t=t^{\prime}$. Hence, $s \xrightarrow{*} \mathcal{R} t^{\prime}=t$.

Example 4.3. Let $\mathcal{R}_{\text {sum }}, \mathcal{R}_{\text {sum }}^{\prime}$ be the TRSs in Example 3.1. Let $\mathcal{E}$ be the following set of equations.

$$
\mathcal{E}\left\{\begin{array}{lll}
+(0, x) & \approx+(x, 0) \\
+(+(x, y), z) & \approx & +(x,+(y, z))
\end{array}\right.
$$

Note that any equation in $\mathcal{E}$ is an inductive consequence of $\mathcal{R}_{\text {sum }}$ for $\mathscr{G}=\{$ sum,,$+:,[], \mathrm{s}, 0\}$, i.e., $\mathcal{R}, \mathscr{G} \vdash_{\text {ind }} \mathcal{E}$.

We now demonstrate an equivalent transformation from $\mathcal{R}_{\text {sum }}$ to $\mathcal{R}_{\text {sum }}^{\prime}$ under $\mathcal{E}$. Let $\mathcal{R}_{0}=$ $\mathcal{R}_{\text {sum }}$.

1. Let $\mathcal{R}_{1}=\mathcal{R}_{0} \cup\left\{\operatorname{sum}_{1}(x, y) \rightarrow+(y, \operatorname{sum}(x))\right\}$. Clearly, $\mathcal{R}_{0} \Rightarrow \mathcal{R}_{1}$ by the Introduction rule.
2. Let $\mathcal{R}_{2}=\mathcal{R}_{1} \cup\left\{\operatorname{sum}(x) \rightarrow \operatorname{sum}_{1}(x, 0)\right\}$. Here, we have

$$
\begin{array}{rll}
\operatorname{sum}(x) & \leftarrow \mathcal{R}_{1} & +(0, \operatorname{sum}(x)) \\
& \leftarrow \mathcal{R}_{1} & \operatorname{sum}_{1}(x, 0)
\end{array}
$$

Thus, $\mathcal{R}_{1} \Rightarrow \mathcal{R}_{2}$ by the Addition rule.
3. Let $\mathcal{R}_{3}=\mathcal{R}_{2} \cup\left\{\operatorname{sum}_{1}([], x) \rightarrow x\right\}$. Then, we have

$$
\begin{array}{rll}
\operatorname{sum}_{1}([], x) & \rightarrow \mathcal{R}_{2} & +(x, \operatorname{sum}([])) \\
& \rightarrow \mathcal{R}_{2} & +(x, 0) \\
& \leftrightarrow \mathcal{E} & +(0, x) \\
& \rightarrow \mathcal{R}_{2} & x
\end{array}
$$

Thus, $\mathcal{R}_{2} \Rightarrow \mathcal{R}_{3}$ by the Addition rule.
4. Let $\mathcal{R}_{4}=\mathcal{R}_{3} \cup\left\{\operatorname{sum}_{1}(x: y, z) \rightarrow \operatorname{sum}_{1}(y,+(z, x))\right\}$. Then, we have

$$
\begin{array}{rll}
\operatorname{sum}_{1}(x: y, z) & \rightarrow \mathcal{R}_{3} & +(z, \operatorname{sum}(x: y)) \\
& \rightarrow_{\mathcal{R}_{3}} & +(z,+(x, \operatorname{sum}(y))) \\
& \leftrightarrow \mathcal{E} & +(+(z, x), \operatorname{sum}(y)) \\
& \leftarrow_{\mathcal{R}_{3}} & \operatorname{sum}_{1}(y,+(z, x))
\end{array}
$$

Thus, $\mathcal{R}_{3} \Rightarrow \mathcal{R}_{4}$ by the Addition rule.
5. Finally, applying the Elimination rule three times to $\mathcal{R}_{4}$, we obtain $\mathcal{R}_{\text {sum }}^{\prime}$.

Thus, there exists an equivalent transformation from $\mathcal{R}_{\text {sum }}$ to $\mathcal{R}_{\text {sum }}^{\prime}$ under $\mathcal{E}$. It is easily shown that $\mathcal{R}_{\text {sum }}$ is confluent and sufficiently complete for $\mathscr{G}$ and that $\mathcal{R}_{\text {sum }}^{\prime}$ is sufficiently complete for $\mathscr{G} \cup\{$ sum 1$\}$. Therefore, from Theorem 4.2, it follows that $\mathcal{R}_{\text {sum }} \simeq_{\mathscr{G}} \mathcal{R}_{\text {sum }}^{\prime}$.

### 4.2 Correctness of Templates

For the TRS transformation in Example 3.2, it is easily observed that the correctness of the transformation can be proved exactly in the same way. Thus, one may naturally expect that such manual transformations can be conducted at the template level. A naive method of proving the correctness of a template $\left\langle\mathcal{P}, \mathcal{P}^{\prime}, \mathcal{H}\right\rangle$ is to find an equivalent transformation from $\mathcal{P}$ to $\mathcal{P}^{\prime}$ under $\mathcal{H}$ similar to TRSs. This naive method, however, does not work because $\mathcal{P} \xlongequal{*}$ $\mathcal{P}^{\prime}$ under $\mathcal{H}$ does not imply $\varphi(\mathcal{P}) \stackrel{*}{\Rightarrow} \varphi\left(\mathcal{P}^{\prime}\right)$ under $\varphi(\mathcal{H})$ in general. For example, suppose $\mathcal{P}$ $=\{\mathrm{p}(x) \rightarrow \mathrm{a}(\mathrm{b})\}$ and $\mathcal{P}^{\prime}=\mathcal{P} \cup\{\mathrm{q}(x) \rightarrow \mathrm{b}\}$. Then, $\mathcal{P} \underset{I}{\Rightarrow} \mathcal{P}^{\prime}$. However, $\varphi(\mathcal{P}) \nRightarrow I \Rightarrow\left(\mathcal{P}^{\prime}\right)$ when $\varphi=\left\{\mathrm{p} \mapsto \mathrm{f}\left(\square_{1}\right), \mathrm{q} \mapsto \mathrm{f}\left(\square_{1}\right), \mathrm{a} \mapsto 0, \mathrm{~b} \mapsto 1\right\}$. The key idea in the proof of Theorem 4.2 is the preservation of the Church-Rosser property under the Introduction rule. In the example above, $\varphi\left(\mathcal{P}^{\prime}\right)$ does not have the Church-Rosser property even though $\mathcal{P}^{\prime}$ does. Thus, in order to preserve the correctness of each step, in particular the Introduction step in equivalence transformation, some restrictions on the term homomorphism $\varphi$ are necessary.

Correct templates are constructed by inference rules similar to equivalent transformations.
Definition 4.4. Let $\mathcal{P}_{0}$ be a TRS pattern over a set $\Sigma_{0} \subseteq \mathscr{F} \cup \mathscr{X}$ and $\mathcal{H}$ a hypothesis over $\Sigma_{0}$. A correct transformation sequence under $\mathcal{H}$ is a sequence $\mathcal{P}_{0}, \ldots, \mathcal{P}_{n}$ of TRS patterns (over $\Sigma_{0}, \ldots, \Sigma_{n}$, respectively) such that $\mathcal{P}_{k+1}$ is obtained from $\mathcal{P}_{k}$ by applying one of the following inference rules:

## (I) Introduction

$$
\mathcal{P}_{k+1}=\mathcal{P}_{k} \cup\left\{p\left(x_{1}, \ldots, x_{n}\right) \rightarrow r\right\}
$$

provided that $p\left(x_{1}, \ldots, x_{n}\right) \rightarrow r$ is a left-linear rewrite rule such that $p \notin \Sigma_{k}$ and $r \in$ $\mathrm{T}\left(\Sigma_{k}, \mathscr{V}\right)$. We put $\Sigma_{k+1}=\Sigma_{k} \cup\{p\}$.
(A) Addition

$$
\mathcal{P}_{k+1}=\mathcal{P}_{k} \cup\{l \rightarrow r\}
$$

provided $l \stackrel{*}{\leftrightarrow} \mathcal{P}_{k} \cup \mathcal{H} r$ holds.
(E) Elimination

$$
\mathcal{P}_{k+1}=\mathcal{P}_{k} \backslash\{l \rightarrow r\}
$$

When this is the case, we write $\mathcal{P}_{k} \Rightarrow \mathcal{P}_{k+1}$. (In the Addition and Elimination rules, $\Sigma_{k+1}$ can be any set such that $\Sigma_{k+1} \subseteq \Sigma_{k}$ provided that $\mathcal{P}_{k+1}$ is a TRS pattern over $\Sigma_{k+1}$.) The reflexive transitive closure of $\Rightarrow$ is denoted $b y \stackrel{*}{\Rightarrow}$. We indicate the rule of $\Rightarrow b y \underset{I}{\Rightarrow}, \underset{A}{\Rightarrow}$, or $\underset{E}{\Rightarrow}$. Finally, we say that $\left\langle\mathcal{P}, \mathcal{P}^{\prime}, \mathcal{H}\right\rangle$ is a correct template when there exits a correct transformation sequence $\mathcal{P} \underset{I}{\stackrel{*}{\Rightarrow}} \cdot \underset{A}{*} \cdot \underset{E}{\stackrel{*}{\Rightarrow}} \mathcal{P}^{\prime}$ under $\mathcal{H}$.

Since, for any term homomorphism $\varphi, \mathcal{P} \Rightarrow \mathcal{P}^{\prime}$ does not imply $\varphi(\mathcal{P}) \Rightarrow \varphi\left(\mathcal{P}^{\prime}\right)$, generally, some restrictions of term homomorphisms are necessary to use for correct transformations. Such restrictions are needed to guarantee the fact that the Introduction rule preserves the ChurchRosser property and sufficient completeness. Let $\mathcal{P}$ and $\mathcal{P}^{\prime}$ be TRS patterns over $\Sigma$ and $\Sigma^{\prime}$, respectively and $\varphi$ a term homomorphism. Suppose $\mathcal{P} \underset{I}{\Rightarrow} \mathcal{P} \cup\left\{p\left(x_{1}, \ldots, x_{n}\right) \rightarrow r\right\}=\mathcal{P}^{\prime}$ by the Introduction rule. $\operatorname{CR}(\mathcal{P})$ implies $\operatorname{CR}\left(\mathcal{P}^{\prime}\right)$ because $p$ does not appear in $\mathcal{P}$. If $p \notin \operatorname{dom} \mathscr{X}(\varphi)$ and $p$ does not appear in $\varphi(\mathcal{P})$, then $\operatorname{CR}(\varphi(\mathcal{P}))$ implies $\operatorname{CR}\left(\varphi\left(\mathcal{P}^{\prime}\right)\right)$. Further, $\mathrm{SC}(\mathcal{P}, \Sigma)$ implies $\mathrm{SC}\left(\mathcal{P}^{\prime}, \Sigma \cup\{p\}\right)$ because any ground term pattern which contains $p$ can be reduced to a ground term pattern which does not contain $p$. If $\varphi(r) \in \mathrm{T}(\mathscr{G}, \mathscr{V})$ whenever $\varphi(\mathcal{P})$ is a TRS over $\mathscr{G} \subseteq \mathscr{F}$, then $\operatorname{SC}(\varphi(\mathcal{P}), \mathscr{G})$ implies $\operatorname{SC}\left(\varphi\left(\mathcal{P}^{\prime}\right), \mathscr{G} \cup\{p\}\right)$. These conditions are summarized by the following definition.

Definition 4.5. Let $\Sigma$ and $\mathscr{G}$ be sets such that $\Sigma \subseteq \mathscr{F} \cup \mathscr{X}$ and $\mathscr{G} \subseteq \mathscr{F}$. A term homomorphism $\varphi$ carries $\Sigma$ to $\mathscr{G}$ if

1. $\operatorname{dom}_{\mathscr{X}}(\varphi)=\Sigma \backslash \mathscr{F}$, and
2. range $\mathscr{X}(\varphi) \subseteq \mathscr{G}$.
where range $_{\mathscr{X}}(\varphi)=\bigcup_{p \in \operatorname{dom}_{\mathscr{X}}(\varphi)} \mathscr{F}(\varphi(p))$.
Next lemma can be shown in a straightforward way.
Lemma 4.6. Let $\mathcal{P}$ and $\mathcal{P}^{\prime}$ be TRS patterns over $\Sigma$ and $\Sigma^{\prime}$, respectively, and $\varphi$ a term homomorphism which carries $\Sigma$ to $\mathscr{G} \subseteq \mathscr{F}$. If $\varphi(\mathcal{P})$ is a TRS over $\mathscr{G}$ and $\mathcal{P} \underset{I}{\Rightarrow} \mathcal{P}^{\prime}$ by the Introduction rule, then $\varphi(\mathcal{P}) \underset{I}{\Rightarrow} \varphi\left(\mathcal{P}^{\prime}\right)$ by the Introduction rule.

In Lemma 4.6, each pattern variable appearing in $\varphi\left(\mathcal{P}^{\prime}\right)$ is regarded as a fresh function symbol. This is also applied to the next theorem.

We then obtain the following theorem from Proposition 3.8 and Lemma 4.6.
Theorem 4.7. Let $\left\langle\mathcal{P}, \mathcal{P}^{\prime}, \mathcal{H}\right\rangle$ be a correct template where $\mathcal{P}$ and $\mathcal{P}^{\prime}$ are TRS patterns over $\Sigma$ and $\Sigma^{\prime}$, respectively, and $\varphi$ a term homomorphism which carries $\Sigma$ to $\mathscr{G}$. If $\left(\Sigma^{\prime} \backslash \Sigma\right) \cap \mathscr{G}=\emptyset$ and $\varphi(\mathcal{P})$ is a TRS over $\mathscr{G}$, then there exists an equivalent transformation $\varphi(\mathcal{P}) \stackrel{*}{\Rightarrow} \varphi\left(\mathcal{P}^{\prime}\right)$ under $\varphi(\mathcal{H})$.

This theorem leads to the next definition of TRS transformation by correct templates.
Definition 4.8. Let $\left\langle\mathcal{P}, \mathcal{P}^{\prime}, \mathcal{H}\right\rangle$ be a template where $\mathcal{P}$ and $\mathcal{P}^{\prime}$ are TRS patterns over $\Sigma$ and $\Sigma^{\prime}$, respectively. A TRS $\mathcal{R}$ over $\mathscr{G}$ is transformed to a TRS $\mathcal{R}^{\prime}$ over $\mathscr{G}^{\prime}$ if there exist a term homomorphism $\varphi$ and a $T R S \mathcal{R}_{\text {com }}$ over $\mathscr{G}$ such that:

1. $\mathcal{R}=\varphi(\mathcal{P}) \cup \mathcal{R}_{c o m}$,
2. $\varphi$ carries $\Sigma$ to $\mathscr{G}$,
3. $\mathcal{R}^{\prime}=\varphi_{\text {out }}\left(\mathcal{P}^{\prime}\right) \cup \mathcal{R}_{\text {com }}$, where
$\varphi_{\text {out }}=\varphi \cup\left\{p \mapsto f_{p}\left(\square_{1}, \ldots, \square_{\operatorname{arity}(p)}\right) \mid\right.$ $p \notin \operatorname{dom}_{\mathscr{X}}(\varphi), f_{p}$ is a fresh function symbol (i.e. $\left.\left.f_{p} \notin \mathscr{G}\right)\right\}$,
4. $\left(\Sigma^{\prime} \backslash \Sigma\right) \cap \mathscr{G}=\emptyset$, and
5. $\mathcal{R}, \mathscr{G} \vdash_{\text {ind }} \varphi(\mathcal{H})$.

Next theorem gives sufficient conditions to guarantee the correctness of TRS transformations by correct templates.

Theorem 4.9. If a left-linear $C S \mathcal{R}$ over $\mathscr{G}$ is transformed to a $T R S \mathcal{R}^{\prime}$ over $\mathscr{G}^{\prime}$ by a correct template $\left\langle\mathcal{P}, \mathcal{P}^{\prime}, \mathcal{H}\right\rangle$, then $\operatorname{CR}(\mathcal{R}) \wedge \operatorname{SC}(\mathcal{R}, \mathscr{G}) \wedge \mathrm{SC}\left(\mathcal{R}^{\prime}, \mathscr{G}\right)$ implies $\mathcal{R} \simeq \mathscr{G}^{(G G} \mathcal{G}^{\prime} \mathcal{R}^{\prime}$.

In this section, we give correct transformation templates which can be used to apply tupling transformations.

Let $\left\langle\mathcal{P}, \mathcal{P}^{\prime}, \mathcal{H}\right\rangle$ be a template where

$$
\begin{aligned}
& \mathcal{P}\left\{\begin{array} { l l l } 
{ \mathrm { p } ( \mathrm { a } ) } & { \rightarrow } & { \mathrm { c } } \\
{ \mathrm { p } ( \mathrm { b } ( \mathrm { a } ) ) } & { \rightarrow } & { \mathrm { d } } \\
{ \mathrm { p } ( \mathrm { b } ( \mathrm { b } ( x ) ) ) } & { \rightarrow } & { \mathrm { q } ( \mathrm { p } ( \mathrm { b } ( x ) ) , \mathrm { p } ( x ) ) } \\
{ \pi _ { 1 } ( \langle x , y \rangle ) } & { \rightarrow } & { x } \\
{ \pi _ { 2 } ( \langle x , y \rangle ) } & { \rightarrow } & { y }
\end{array} \quad \mathcal { P } ^ { \prime } \quad \left\{\begin{array}{lll}
\mathrm{p}(\mathrm{a}) & \mathrm{c} \\
\mathrm{p}(\mathrm{~b}(\mathrm{a})) & \rightarrow & \mathrm{d} \\
\mathrm{p}(\mathrm{~b}(\mathrm{~b}(x))) & \rightarrow & \pi_{1}(\mathrm{r} 1(\mathrm{r}(x))) \\
\mathrm{r}(\mathrm{a}) & \rightarrow & \langle\mathrm{d}, \mathrm{c}\rangle \\
\mathrm{r}(\mathrm{~b}(x)) & \rightarrow & \mathrm{r} 1(\mathrm{r}(x)) \\
\mathrm{r} 1(x) & \rightarrow & \left\langle\mathrm{q}\left(\pi_{1}(x), \pi_{2}(x)\right), \pi_{1}(x)\right\rangle \\
\pi_{1}(\langle x, y\rangle) & \rightarrow & x \\
\pi_{2}(\langle x, y\rangle) & \rightarrow & y
\end{array}\right.\right. \\
& \mathcal{H}=\emptyset .
\end{aligned}
$$

Here, $\pi_{1}, \pi_{2}$, and $\langle\cdot\rangle$ are function symbols. We now show that the template $\left\langle\mathcal{P}, \mathcal{P}^{\prime}, \mathcal{H}\right\rangle$ is a correct template.

1. Let $\mathcal{P}_{0}=\mathcal{P}$.
2. Let $\mathcal{P}_{1}=\mathcal{P}_{0} \cup\{\mathrm{r}(x) \rightarrow\langle\mathrm{p}(\mathrm{b}(x)), \mathrm{p}(x)\rangle\}$. Here, r is a fresh pattern variable. Thus, $\mathcal{P}_{0} \Rightarrow \mathcal{P}_{1}$ by the Introduction rule.
3. Let $\mathcal{P}_{2}=\mathcal{P}_{1} \cup\left\{\mathrm{r} 1(x) \rightarrow\left\langle\mathbf{q}\left(\pi_{1}(x), \pi_{2}(x)\right), \pi_{1}(x)\right\rangle\right\}$. Here, r 1 is a fresh pattern variable. Thus, $\mathcal{P}_{1} \Rightarrow \mathcal{P}_{2}$ by the Introduction rule.
4. Let $\mathcal{P}_{3}=\mathcal{P}_{2} \cup\{r(a) \rightarrow\langle d, c\rangle\}$. Here, we have $r(a) \rightarrow_{\mathcal{P}_{2}}\langle\mathrm{p}(\mathrm{b}(\mathrm{a})), \mathrm{p}(\mathrm{a})\rangle \xrightarrow{*} \mathcal{P}_{2}\langle\mathrm{~d}, \mathrm{c}\rangle$. Thus, $\mathcal{P}_{2} \Rightarrow \mathcal{P}_{3}$ by the Addition rule.
5. Let $\mathcal{P}_{4}=\mathcal{P}_{3} \cup\{\mathrm{r}(\mathrm{b}(x)) \rightarrow \mathrm{r} 1(\mathrm{r}(x))\}$. Here, we have $\mathrm{r}(\mathrm{b}(x)) \rightarrow \mathcal{P}_{3}\langle\mathrm{p}(\mathrm{b}(\mathrm{b}(x))), \mathrm{p}(\mathrm{b}(x))\rangle$ $\rightarrow \mathcal{P}_{3}\langle\mathrm{q}(\mathrm{p}(\mathrm{b}(x)), \mathrm{p}(x)), \mathrm{p}(\mathrm{b}(x))\rangle \stackrel{*}{\leftarrow} \mathcal{P}_{3}\left\langle\mathrm{q}\left(\pi_{1}(\mathrm{r}(x)), \pi_{2}(\mathrm{r}(x))\right), \pi_{1}(\mathrm{r}(x))\right\rangle \mathcal{P}_{3} \mathrm{r} 1(\mathrm{r}(x))$. Thus, $\mathcal{P}_{3} \Rightarrow \mathcal{P}_{4}$ by the Addition rule.
6. Let $\mathcal{P}_{5}=\mathcal{P}_{4} \cup\left\{\mathrm{p}(\mathrm{b}(\mathrm{b}(x))) \rightarrow \pi_{1}(\mathrm{r} 1(\mathrm{r}(x)))\right\}$. Here, we have $\mathrm{p}(\mathrm{b}(\mathrm{b}(x))) \leftarrow \mathcal{P}_{4} \pi_{1}(\langle\mathrm{p}(\mathrm{b}(\mathrm{b}(x))), \mathrm{p}(\mathrm{b}(x))\rangle) \leftarrow \mathcal{P}_{4}$ $\pi_{1}(\mathrm{r}(\mathrm{b}(x))) \rightarrow_{\mathcal{P}_{4}} \pi_{1}(\mathrm{r} 1(\mathrm{r}(x)))$. Thus, $\mathcal{P}_{4} \Rightarrow \mathcal{P}_{5}$ by the Addition rule.
7. Finally, applying the Elimination rule twice to $\mathcal{P}_{5}$, we obtain $\mathcal{P}^{\prime}$.

Thus, $\left\langle\mathcal{P}, \mathcal{P}^{\prime}, \mathcal{H}\right\rangle$ is a correct template.
Example 4.10. The following TRS $\mathcal{R}_{\text {fib }}$ computes Fibonacci number of input natural numbers. $\mathcal{R}_{\text {fib }}$ is transformed to the TRS $\mathcal{R}_{\text {fib }}^{\prime}$ by the template $\left\langle\mathcal{P}, \mathcal{P}^{\prime}, \mathcal{H}\right\rangle$.

$$
\mathcal{R}_{\mathrm{fib}}\left\{\begin{array}{lllll}
\mathrm{fib}(0) & \rightarrow \mathrm{s}(0) & +(0, x) & \rightarrow x \\
\mathrm{fib}(\mathrm{~s}(0)) & \rightarrow & \mathrm{s}(0) & +(\mathrm{s}(x), y) & \rightarrow \\
\mathrm{fib}(\mathrm{~s}(\mathrm{~s}(x))) & \rightarrow & +(\mathrm{fib}(\mathrm{~s}(x)), \mathrm{fib}(x)) & \pi_{1}(\langle x, y\rangle) & \rightarrow \\
& & \pi_{2}(\langle x, y\rangle) & \rightarrow y
\end{array}\right.
$$

$$
\mathcal{R}_{\mathrm{fib}}^{\prime}\left\{\begin{array}{lllll}
\mathrm{fib}(0) & \rightarrow \mathrm{s}(0) & +(0, x) & \rightarrow & x \\
\mathrm{fib}(\mathrm{~s}(0)) & \rightarrow \mathrm{s}(0) & +(\mathrm{s}(x), y) & \rightarrow & \mathrm{s}(+(x, y)) \\
\mathrm{fib}(\mathrm{~s}(\mathrm{~s}(x))) & \rightarrow & \pi_{1}\left(\mathrm{f}_{\mathrm{r} 1}\left(\mathrm{f}_{\mathrm{r}}(x)\right)\right) & \pi_{1}(\langle x, y\rangle) & \rightarrow \\
\mathrm{f}_{\mathrm{r}}(0) & \rightarrow & \langle\mathrm{s}(0), \mathrm{s}(0)\rangle & \pi_{2}(\langle x, y\rangle) & \rightarrow \\
\mathrm{f}_{\mathrm{r}}(\mathrm{~s}(x)) & \rightarrow & \mathrm{f}_{\mathrm{r} 1}\left(\mathrm{f}_{\mathrm{r}}(x)\right) & & \\
\mathrm{f}_{\mathrm{r} 1}(x) & \rightarrow & \left\langle+\left(\pi_{1}(x), \pi_{2}(x)\right), \pi_{1}(x)\right\rangle & &
\end{array}\right.
$$

Let us consider another template. The following template $\left\langle\tilde{\mathcal{P}}, \tilde{\mathcal{P}}^{\prime}, \tilde{\mathcal{H}}\right\rangle$ deals with slightly more complicated tupling transformations.

$$
\begin{aligned}
& \tilde{\mathcal{P}} \begin{cases}\mathrm{p}(\mathrm{a}) & \rightarrow \mathrm{b} \\
\mathrm{p}(\mathrm{c}(x, y)) & \rightarrow \mathrm{h}(x, y, \mathrm{q}(y), \mathrm{p}(y)) \\
\mathrm{q}(\mathrm{a}) & \rightarrow \\
\mathrm{q}(\mathrm{c}(x, y)) & \rightarrow \mathrm{e}(x, y, \mathrm{q}(y)) \\
\pi_{1}(\langle x, y\rangle) & \rightarrow x \\
\pi_{2}(\langle x, y\rangle) & \rightarrow y\end{cases} \\
& \tilde{\mathcal{P}}^{\prime} \quad \begin{cases}\mathrm{p}(\mathrm{a}) & \rightarrow \mathrm{b} \\
\mathrm{p}(\mathrm{c}(x, y)) & \rightarrow \pi_{1}\left(\mathrm{r}_{1}(x, y, \mathrm{r}(y))\right) \\
\mathrm{r}(\mathrm{a}) & \rightarrow\langle\mathrm{b}, \mathrm{~d}\rangle \\
\mathrm{r}(\mathrm{c}(x, y)) & \rightarrow \mathrm{r} 1(x, y, \mathrm{r}(y)) \\
\mathrm{r}(x, y, z) & \rightarrow \\
\left.\quad \mathrm{h}\left(x, y, \pi_{2}(z), \pi_{1}(z)\right), \mathrm{e}\left(x, y, \pi_{2}(z)\right)\right\rangle \\
\mathrm{q}(\mathrm{a}) & \rightarrow \mathrm{d} \\
\mathrm{q}(\mathrm{c}(x, y)) & \rightarrow \mathrm{e}(x, y, \mathrm{q}(y)) \\
\pi_{1}(\langle x, y\rangle) & \rightarrow x \\
\pi_{2}(\langle x, y\rangle) & \rightarrow y\end{cases} \\
& \tilde{\mathcal{H}}=\emptyset
\end{aligned}
$$

Here, $\pi_{1}, \pi_{2}$, and $\langle\cdot\rangle$ are function symbols.
We now show that there exists a correct transformation sequence from $\tilde{\mathcal{P}}$ to $\tilde{\mathcal{P}}^{\prime}$ under $\tilde{\mathcal{H}}$, i.e. $\left\langle\tilde{\mathcal{P}}, \tilde{\mathcal{P}}^{\prime}, \tilde{\mathcal{H}}\right\rangle$ is a correct template.

1. Let $\mathcal{P}_{0}=\tilde{\mathcal{P}}$.
2. Let $\mathcal{P}_{1}=\mathcal{P}_{0} \cup\{\mathrm{r}(x) \rightarrow\langle\mathrm{p}(x), \mathrm{q}(x)\rangle\}$. Here, r is a fresh pattern variable. Thus $\mathcal{P}_{0} \Rightarrow \mathcal{P}_{1}$ by the Introduction rule.
3. Let $\mathcal{P}_{2}=\mathcal{P}_{1} \cup\left\{\mathrm{r} 1(x, y, z) \rightarrow\left\langle\mathrm{h}\left(x, y, \pi_{2}(z), \pi_{1}(z)\right), \mathrm{e}\left(x, y, \pi_{2}(z)\right)\right\rangle\right\}$. Here, r 1 is a fresh pattern variable. Thus $\mathcal{P}_{1} \Rightarrow \mathcal{P}_{2}$ by the Introduction rule.
4. Let $\mathcal{P}_{3}=\mathcal{P}_{2} \cup\{\mathrm{r}(\mathrm{a}) \rightarrow\langle\mathrm{b}, \mathrm{d}\rangle\}$. Here, we have $\mathrm{r}(\mathrm{a}) \rightarrow_{\mathcal{P}_{2}}\langle\mathrm{p}(\mathrm{a}), \mathrm{q}(\mathrm{a})\rangle{ }^{*} \mathcal{P}_{2}\langle\mathrm{~b}, \mathrm{~d}\rangle$. Thus, $\mathcal{P}_{2} \Rightarrow \mathcal{P}_{3}$ by the Addition rule.
5. Let $\mathcal{P}_{4}=\mathcal{P}_{3} \cup\{\mathrm{r}(\mathrm{c}(x, y)) \rightarrow \mathrm{r} 1(x, y, \mathrm{r}(y))\}$. We have $\mathrm{r}(\mathrm{c}(x, y)) \rightarrow_{\mathcal{P}_{3}}\langle\mathrm{p}(\mathrm{c}(x, y)), \mathrm{q}(\mathrm{c}(x, y))\rangle$ $\xrightarrow{*} \mathcal{P}_{3}\langle\mathrm{~h}(x, y, \mathrm{q}(y), \mathrm{p}(y)), \mathrm{e}(x, y, \mathrm{q}(y))\rangle \stackrel{*}{\leftarrow} \mathcal{P}_{3}\left\langle\mathrm{~h}\left(x, y, \pi_{2}(\mathrm{r}(y)), \pi_{1}(\mathrm{r}(y))\right), \mathrm{e}\left(x, y, \pi_{2}(\mathrm{r}(y))\right)\right\rangle \leftarrow \mathcal{P}_{3}$ $\mathrm{r} 1(x, y, \mathrm{r}(y))$. Thus, $\mathcal{P}_{3} \Rightarrow \mathcal{P}_{4}$ by the Addition rule.
6. Let $\mathcal{P}_{5}=\mathcal{P}_{4} \cup\left\{\mathrm{p}(\mathrm{c}(x, y)) \rightarrow \pi_{1}(\mathrm{r} 1(x, y, \mathrm{r}(y)))\right\}$. Here, we have $\mathrm{p}(\mathrm{c}(x, y)) \leftarrow \mathcal{P}_{4} \pi_{1}(\mathrm{r}(\mathrm{c}(x, y))) \rightarrow_{\mathcal{P}_{4}}$ $\pi_{1}(\mathrm{r} 1(x, y, \mathrm{r}(y)))$. Thus, $\mathcal{P}_{4} \Rightarrow \mathcal{P}_{5}$ by the Addition rule.
7. Finally, applying the Elimination rule twice to $\mathcal{P}_{5}$, we obtain $\tilde{\mathcal{P}}^{\prime}$.

Thus, $\left\langle\tilde{\mathcal{P}}, \tilde{\mathcal{P}}^{\prime}, \tilde{\mathcal{H}}\right\rangle$ is a correct template.
Example 4.11. A list of numbers is said to be steep if each element is greater than the sum of the elements that follow it [7]. The following TRS $\mathcal{R}_{\text {steep }}$ specifies a program which checks
whether input lists are steep. $\mathcal{R}_{\text {steep }}$ is transformed to TRS $\mathcal{R}_{\text {steep }}^{\prime}$ by the template $\left\langle\tilde{\mathcal{P}}, \tilde{\mathcal{P}}^{\prime}, \tilde{\mathcal{H}}\right\rangle$.

$$
\begin{aligned}
& (\text { steep }(\text { nil }) \rightarrow \text { true and(true, true) } \rightarrow \text { true } \\
& \operatorname{steep}(x: x s) \quad \rightarrow \quad \text { and(true, false) } \rightarrow \text { false } \\
& \operatorname{and}(\operatorname{gt}(x, \operatorname{sum}(x s)), \text { steep }(x s)) \text { and(false, true) } \rightarrow \text { false } \\
& \mathcal{R}_{\text {steep }}\left\{\begin{array}{lllll}
\operatorname{sum}(\text { nil }) & \rightarrow 0 & \text { and(false, false }) & \rightarrow \text { false } \\
\operatorname{sum}(x: y s) & \rightarrow & +(x, \operatorname{sum}(y s)) & +(0, x) & \rightarrow \\
\operatorname{gt}(0,0) & \rightarrow \text { false } & +(\mathrm{s}(x), y) & \rightarrow \mathrm{s}(+(x, y))
\end{array}\right. \\
& \mathcal{R}_{\text {steep }}\left\{\begin{array}{lllll}
\operatorname{sum}(\text { nil }) & \rightarrow 0 & \text { and(false, false } & \rightarrow \text { false } \\
\operatorname{sum}(x: y s) & \rightarrow+(x, \operatorname{sum}(y s)) & +(0, x) & \rightarrow x \\
\operatorname{gt}(0,0) & \rightarrow \text { false } & +(\mathrm{s}(x), y) & \rightarrow \mathrm{s}(+(x, y))
\end{array}\right. \\
& \begin{array}{llll}
\mathrm{gt}(0,0) \\
\mathrm{gt}(0, \mathrm{~s}(y)) & \rightarrow & \text { false } & \pi_{1}(\langle x, y\rangle)
\end{array} \quad \rightarrow \mathrm{s} \\
& \operatorname{gt}(\mathrm{~s}(x), 0) \quad \rightarrow \quad \text { true } \\
& \pi_{2}(\langle x, y\rangle) \quad \rightarrow \quad y \\
& \mathcal{R}_{\text {steep }}^{\prime}\left\{\begin{array}{lll}
\operatorname{steep}([]) & \rightarrow & \text { true } \\
\operatorname{steep}(x: y) & \rightarrow & \pi_{1}\left(\mathrm{f}_{\mathrm{r} 1}\left(x, y, \mathrm{f}_{\mathrm{r}}(y)\right)\right) \\
\mathrm{f}_{\mathrm{r}}([]) & \rightarrow & \text { true }, 0\rangle \\
\mathrm{f}_{\mathrm{r}}(x: y) & \rightarrow & \mathrm{f}_{\mathrm{r} 1}\left(x, y, \mathrm{f}_{\mathrm{r}}(y)\right) \\
\mathrm{f}_{\mathrm{r} 1}(x, y, z) & \rightarrow & \\
\left\langle\operatorname{and}\left(\operatorname{gt}\left(x, \pi_{2}(z)\right), \pi_{1}(z)\right),+\left(x, \pi_{2}(z)\right)\right\rangle \\
\operatorname{sum}([]) & \rightarrow & 0 \\
\operatorname{sum}(x: y) & \rightarrow & +(x, \operatorname{sum}(y)) \\
\operatorname{gt}(0,0) & \rightarrow & \text { false } \\
\operatorname{gt}(0, \mathrm{~s}(y)) & \rightarrow & \text { false }
\end{array}\right. \\
& \operatorname{gt}(\mathrm{s}(x), 0) \quad \rightarrow \text { true } \\
& \operatorname{gt}(\mathrm{s}(x), \mathrm{s}(y)) \quad \rightarrow \quad \operatorname{gt}(x, y) \\
& \text { and(false, false) } \rightarrow \text { false } \\
& \text { and(false, true) } \rightarrow \text { false } \\
& \text { and(true, false) } \rightarrow \text { false } \\
& \text { and(true, true) } \rightarrow \text { true } \\
& +(0, x) \quad \rightarrow \quad x \\
& +(\mathrm{s}(x), y) \quad \rightarrow \mathrm{s}(+(x, y)) \\
& \pi_{1}(\langle x, y\rangle) \quad \rightarrow \quad x \\
& \pi_{2}(\langle x, y\rangle) \quad \rightarrow \quad y
\end{aligned}
$$

Example 4.12. The following TRS $\mathcal{R}_{\text {factlist }}$ computes lists whose elements are factorial numbers.

$$
\mathcal{R}_{\text {factlist }}\left\{\begin{array}{lll}
\text { factlist }(0) & \rightarrow & {[]} \\
\text { factlist }(\mathbf{s}(x)) & \rightarrow \\
\times(\mathbf{s}(x), & \text { fact }(x)): \text { factlist }(x) \\
\operatorname{fact}(0) & \rightarrow & \mathbf{s}(0) \\
\operatorname{fact}(\mathbf{s}(x)) & \rightarrow & \times(\mathbf{s}(x), \text { fact }(x))
\end{array}\right.
$$

$$
\begin{array}{lll}
\times(0, y) & \rightarrow & 0 \\
\times(\mathbf{s}(x), y) & \rightarrow & +(y, \times(x, y)) \\
+(0, x) & \rightarrow & x \\
+(\mathbf{s}(x), y) & \rightarrow & \mathbf{s}(+(x, y)) \\
\pi_{1}(\langle x, y\rangle) & \rightarrow & x \\
\pi_{2}(\langle x, y\rangle) & \rightarrow & y
\end{array}
$$

Since $\tilde{\mathcal{P}}$ can match to $\mathcal{R}_{\text {factlist }}$, one might expect that $\mathcal{R}_{\text {factlist }}$ is transformed by the template $\left\langle\tilde{\mathcal{P}}, \tilde{\mathcal{P}}^{\prime}, \tilde{\mathcal{H}}\right\rangle$. But this transformation fails. For, factlist $(\mathrm{s}(y)) \rightarrow \pi_{1}\left(\mathrm{f}_{\mathrm{r} 1}\left(x, y, \mathrm{f}_{\mathrm{r}}(y)\right)\right)$ appears in $\varphi_{\text {out }}\left(\tilde{\mathcal{P}}^{\prime}\right)$, but this rule is not a rewrite rule ( $x$ appears in the rhs but the lhs). Indeed, $\varphi$ cannot instantiate $r 1$ because $\varphi$ has to carry the signature of $\tilde{\mathcal{P}}$ to $\mathcal{R}_{\text {factlist }}$, that is, $\mathrm{r} 1 \notin \operatorname{dom} \mathscr{X}(\varphi)$ must hold.

### 4.3 Summary

In this chapter, we gave a notion of equivalent transformation of TRSs which improved and simplified the technique proposed by Toyama[25]. We then proved that the equality of restricted TRSs is guaranteed by the equivalent transformation of TRSs (Theorem 4.2). The method to construct correct templates is given by lifting up the technique of equivalent transformation of TRSs to template level. We also introduced the notion of carrying signatures for term homomorphisms which preserve inferences of equivalent transformations. The definition of transformations by templates (Definition 4.5) takes account of carrying signatures for term homomorphisms. Theorem 4.9 showed that correct templates guarantee the correctness of transformations for restricted TRSs. We gave examples of correct templates and TRS transformations by them.

## Chapter 5

## Matching Algorithm

In this chapter, we mainly focus on the TRS pattern matching problem, which is a key part of our procedure of TRS transformation by templates. We introduce a term pattern matching problem and present a sound and complete algorithm that solves this problem. Then the algorithm that solves TRS pattern matching problem is obtained using the term pattern matching algorithm.

### 5.1 Term Pattern Matching

Definition 5.1. (1) A pair $\langle s, t\rangle$ of a pattern $s$ and a term $t$ is called a (term pattern) matching pair. A matching pair $\langle s, t\rangle$ is written as $s \unlhd t$. A (term pattern) matching problem is a finite set of matching pairs. (2) For a matching pair $s \unlhd t$, we say $s$ matches $t$ when there exists a term homomorphism $\varphi$ such that $\varphi(s)=t$; the term homomorphism $\varphi$ is called a matcher (or solution) of $s \unlhd t$. (3) A matching problem $S$ is trivial when $s=t$ for all $s \unlhd t \in S$. For $a$ term homomorphism $\varphi$ and a matching problem $S$, let $\varphi(S)=\{\varphi(s) \unlhd t \mid s \unlhd t \in S\}$. When $\varphi(S)$ is trivial, $\varphi$ is said to be a matcher (or solution) of the matching problem $S$.

Example 5.2. Suppose $\mathrm{f}, \mathrm{c} \in \mathscr{X}$ and sum, $: \in \mathscr{F}$. Then $\mathrm{f}(\mathrm{c}(u, v)) \unlhd \operatorname{sum}(x: y)$ is a matching pair. Let $S=\{\mathrm{f}(\mathrm{c}(u, v)) \unlhd \operatorname{sum}(x: y)\}$ be a matching problem and $\varphi=\left\{\mathrm{f} \mapsto \operatorname{sum}\left(\square_{1}\right)\right.$, $\left.\mathrm{c} \mapsto \square_{1}: \square_{2}, u \mapsto x, v \mapsto y\right\}$ a term homomorphism. Then $\varphi(S)=\{\operatorname{sum}(x: y) \unlhd \operatorname{sum}(x: y)\}$ is a trivial matching problem and thus $\varphi$ is a matcher of $S$. We also write $\varphi(S)$ as $\{\mathrm{f} \mapsto$ $\left.\operatorname{sum}\left(\square_{1}\right), \mathrm{c} \mapsto \square_{1}: \square_{2}, u \mapsto x, v \mapsto y\right\} S$.

We next give a procedure Match that computes a matcher of $S$ non-deterministically for a given matching problem $S$ when it succeeds.

Definition 5.3. (1) Let $\Longrightarrow$ be a relation between pairs of a matching problem and a term homomorphism defined by: $\langle S, \varphi\rangle \Longrightarrow\left\langle S^{\prime}, \varphi^{\prime}\right\rangle$ when $\langle S, \varphi\rangle$ is rewritten to $\left\langle S^{\prime}, \varphi^{\prime}\right\rangle$ by an application of the rules Bound, Split or Extract in Table 5.1. Let $\xlongequal{*}$ be the reflexive transitive closure of $\Longrightarrow$. (2) The procedure Match is given as follows:

Match
Input: a matching problem $S$
Output: a term homomorphism $\varphi$

1. Repeatedly apply inference rules Bound, Split or Extract starting from $\langle S, \emptyset\rangle$.
2. Output $\varphi$ if $\langle S, \emptyset\rangle \stackrel{*}{\Longrightarrow}\langle\emptyset, \varphi\rangle$.

Table 5.1: Inference rules of Match

1. Bound

$$
\frac{\langle S \cup\{x \unlhd y\}, \varphi\rangle}{\langle S, \varphi \cup\{x \mapsto y\}\rangle} \quad x, y \in \mathscr{V}, \varphi(x)=y \vee\left(x \notin \operatorname{dom}_{\mathscr{V}}(\varphi) \wedge y \notin \operatorname{range}(\varphi)\right)
$$

2. Split

$$
\frac{\left\langle S \cup\left\{f\left(s_{1}, \ldots, s_{n}\right) \unlhd f\left(t_{1}, \ldots, t_{n}\right)\right\}, \varphi\right\rangle}{\left\langle S \cup\left\{s_{1} \unlhd t_{1}, \ldots, s_{n} \unlhd, t_{n}\right\}, \varphi\right\rangle} \quad f \in \mathscr{F}
$$

3. Extract

$$
\begin{array}{cl}
\left\langle S \cup\left\{p\left(s_{1}, \ldots, s_{n}\right) \unlhd C\left\langle t_{1}, \ldots, t_{n}\right\rangle\right\}, \varphi\right\rangle & p \in \mathscr{X}, C \in C_{n}(\mathscr{F}) \\
\left\langle\{p \mapsto C\}\left(S \cup\left\{s_{i} \unlhd t_{i} \mid \square_{i} \in C\right\}\right), \varphi \cup\{p \mapsto C\}\right\rangle & \forall i \leq n . \forall x \mapsto y \in \varphi \\
& \left(\square_{i} \in C \wedge y \in \mathscr{V}\left(t_{i}\right) \Rightarrow x \in \mathscr{V}\left(s_{i}\right)\right)
\end{array}
$$

Example 5.4. We demonstrate a sequence $\langle S, \emptyset\rangle \stackrel{*}{\Longrightarrow}\langle\emptyset, \varphi\rangle$ in the procedure Match for an input $S=\{\mathrm{f}(\mathrm{c}(u, v)) \unlhd \operatorname{sum}(x: y), \mathrm{g}(u, \mathrm{f}(v)) \unlhd+(x, \operatorname{sum}(y))\}$ in Figure 5.1.

|  | $\langle\{\mathrm{f}(\mathrm{c}(u, v)) \unlhd \operatorname{sum}(x: y), \mathrm{g}(u, \mathrm{f}(v)) \unlhd+(x, \operatorname{sum}(y))\}, \emptyset\rangle$ | $=\left\langle S_{0}, \varphi_{0}\right\rangle$ |
| :--- | :--- | :--- |
| $\underset{\text { Extract }}{\Longrightarrow}$ | $\left\langle\{\mathrm{c}(u, v) \unlhd x: y, \mathrm{~g}(u, \operatorname{sum}(v)) \unlhd+(x, \operatorname{sum}(y))\}, \varphi_{0} \cup\left\{\mathrm{f} \mapsto \operatorname{sum}\left(\square_{1}\right)\right\}\right\rangle$ | $=\left\langle S_{1}, \varphi_{1}\right\rangle$ |
| $\underset{\text { Extract }}{\Longrightarrow}$ | $\left\langle\{u \unlhd x, v \unlhd y, \mathrm{~g}(u, \operatorname{sum}(v)) \unlhd+(x, \operatorname{sum}(y))\}, \varphi_{1} \cup\left\{\mathrm{c} \mapsto \square_{1}: \square_{2}\right\}\right\rangle$ | $=\left\langle S_{2}, \varphi_{2}\right\rangle$ |
| $\overrightarrow{\text { Bound }}$ | $\left\langle\{v \unlhd y, \mathrm{~g}(u, \operatorname{sum}(v)) \unlhd+(x, \operatorname{sum}(y))\}, \varphi_{2} \cup\{u \mapsto x\}\right\rangle$ | $=\left\langle S_{3}, \varphi_{3}\right\rangle$ |
| $\underset{\text { Bound }}{\Longrightarrow}$ | $\left\langle\{\mathrm{g}(u, \operatorname{sum}(v)) \unlhd+(x, \operatorname{sum}(y))\}, \varphi_{3} \cup\{v \mapsto y\}\right\rangle$ | $=\left\langle S_{4}, \varphi_{4}\right\rangle$ |
| $\underset{\text { Extract }}{\Longrightarrow}$ | $\left\langle\{u \unlhd x, \operatorname{sum}(v) \unlhd \operatorname{sum}(y)\}, \varphi_{4} \cup\left\{\mathrm{~g} \mapsto+\left(\square_{1}, \square_{2}\right)\right\}\right\rangle$ | $=\left\langle S_{5}, \varphi_{5}\right\rangle$ |
| $\underset{\text { Bound }}{\Longrightarrow}$ | $\left\langle\{\operatorname{sum}(v) \unlhd \operatorname{sum}(y)\}, \varphi_{5} \cup\{u \mapsto x\}\right\rangle$ | $=\left\langle S_{6}, \varphi_{6}\right\rangle$ |
| $\underset{\text { Split }}{\Longrightarrow}$ | $\left\langle\{v \unlhd y\}, \varphi_{6}\right\rangle$ | $=\left\langle S_{7}, \varphi_{7}\right\rangle$ |
| $\overline{\text { Bound }}$ | $\left\langle\emptyset, \varphi_{7} \cup\{v \mapsto y\}\right\rangle$ | $=\left\langle S_{8}, \varphi_{8}\right\rangle$ |

Figure 5.1: A sequence $\langle S, \emptyset\rangle \stackrel{*}{\Longrightarrow}\langle\emptyset, \varphi\rangle$ in the procedure Match
The next lemma is readily checked.
Lemma 5.5 (Match is well-defined). By applying inference rules Bound, Split or Extract any pair of a matching problem and a term homomorphism is rewritten to a pair of a matching problem and a term homomorphism, that is, the procedure Match is well-defined.

Our next aim in this section is to prove the correctness of the procedure Match. First, we show that for a given input the procedure Match terminates and that the set of all possible outputs of the algorithm is finite. These facts are necessary to show the soundness and completeness of the procedure Match.

Theorem 5.6 (termination of Match). The procedure Match terminates for any input.
Proof. Clearly, it suffices to show that $\Longrightarrow$ is noetherian. Let $>$ be the usual order on the set of positive natural numbers, $>\times>$ the lexicographic extension of $>$ from left to right, and $>_{m}$ the multiset extension of $>\times>$. Moreover, let $\gg$ be a partial order on the set of pairs of a matching problem and a term homomorphism given by: $\langle S, \varphi\rangle \gg\left\langle S^{\prime}, \varphi^{\prime}\right\rangle$ iff $[\langle | \mathscr{X}(s)|,|s|\rangle \mid s \unlhd t \in S]>_{m}$ $\left[\langle | \mathscr{X}(s)|,|s|\rangle \mid s \unlhd t \in S^{\prime}\right]$ where $|\mathscr{X}(s)|$ denotes the cardinality of the set of pattern variables appear in $s$ and $|s|$ denotes the term size of $s$. Since the order $>_{m}$ is well-founded, so is the order $\gg$. Then for each of the inference rules, it is easy to show $\langle S, \varphi\rangle \Longrightarrow\left\langle S^{\prime}, \varphi^{\prime}\right\rangle$ implies $\langle S, \varphi\rangle \gg\left\langle S^{\prime}, \varphi^{\prime}\right\rangle$. Hence $\Longrightarrow$ is noetherian.

We now know the procedure Match terminates and therefore use the term algorithm instead of the procedure.

Theorem 5.7 (number of outputs). For any given input, the number of outputs of the algorithm Match is finite.

Proof. Clearly, the number of non-deterministic choices of the procedure Match is finite. Thus, because the procedure Match is terminating, the number of possible outputs of the algorithm Match is finite.

We next give proofs of the soundness and the completeness of the algorithm Match. These are proved by induction on the length of the sequence $\langle S, \emptyset\rangle \stackrel{*}{\Longrightarrow}\langle\emptyset, \varphi\rangle$. For this, it is convenient to have a notion of a solution for a pair $\langle S, \varphi\rangle$ of a matching problem $S$ and a term homomorphism $\varphi$.

Definition 5.8. Let $S$ be a matching problem and $\varphi$ a term homomorphism. A term homomorphism $\tilde{\varphi}$ is said to be a solution of the pair $\langle S, \varphi\rangle$ if (1) $\tilde{\varphi}(S)$ is trivial and (2) $\varphi \subseteq \tilde{\varphi}$.

Lemma 5.9. Let $S, S^{\prime}$ be matching problems and $\varphi, \varphi^{\prime}, \tilde{\varphi}$ term homomorphisms. Suppose $\langle S, \varphi\rangle \Longrightarrow\left\langle S^{\prime}, \varphi^{\prime}\right\rangle$ and $\tilde{\varphi}$ is a solution of $\left\langle S^{\prime}, \varphi^{\prime}\right\rangle$. Then $\tilde{\varphi}$ is a solution of $\langle S, \varphi\rangle$.

Proof. Distinguish cases by the inference rule applied in the step $\langle S, \varphi\rangle \Longrightarrow\left\langle S^{\prime}, \varphi^{\prime}\right\rangle$.
Theorem 5.10 (soundness of Match). Let $S$ be a matching problem and $\varphi$ an output of the algorithm Match for the input $S$. Then $\varphi$ is a matcher of $S$.

Proof. Using Lemma 5.9, it is easy to show by induction on the length of $\left\langle S^{\prime}, \varphi^{\prime}\right\rangle \stackrel{*}{\Longrightarrow}\left\langle S^{\prime \prime}, \varphi^{\prime \prime}\right\rangle$ that if $\tilde{\varphi}$ is a solution of $\left\langle S^{\prime \prime}, \varphi^{\prime \prime}\right\rangle$ then it is also a solution of $\left\langle S^{\prime}, \varphi^{\prime}\right\rangle$. The claim follows immediately from this.

We next show the completeness of the algorithm Match. To state the completeness in a precise way, we introduce the notion of a complete set of matchers.

Definition 5.11. Let $S$ be a matching problem and $\Phi$ a set of term homomorphisms. The set $\Phi$ is said to be a complete set of matchers of $S$ when the following conditions are satisfied: (1) any term homomorphism $\varphi \in \Phi$ is a matcher of $S$; (2) for any matcher $\varphi^{\prime}$ of $S$, there exists $\varphi \in \Phi$ such that $\varphi \subseteq \varphi^{\prime}$.

Lemma 5.12. Let $\langle S, \varphi\rangle$ be a pair of a non-empty matching problem $S$ and a term homomorphism $\varphi$, and $\tilde{\varphi}$ its solution. Then there exists a pair $\left\langle S^{\prime}, \varphi^{\prime}\right\rangle$ of a matching problem $S^{\prime}$ and a term homomorphism $\varphi^{\prime}$ such that $\tilde{\varphi}$ is a solution of $\left\langle S^{\prime}, \varphi^{\prime}\right\rangle$ and $\langle S, \varphi\rangle \Longrightarrow\left\langle S^{\prime}, \varphi^{\prime}\right\rangle$.

Proof. Let $S=S^{\prime \prime} \cup\{s \unlhd t\}$. By our assumption that $\tilde{\varphi}$ is a solution of $\langle S, \varphi\rangle$, it follows that (1) $\tilde{\varphi}\left(S^{\prime \prime}\right)$ is trivial, and (2) $\varphi \subseteq \tilde{\varphi}$. The proof proceeds by induction on the structure of $s$.

1. $s=x \in \mathscr{V}$.

Then $t=\tilde{\varphi}(x)$, so let $y=\tilde{\varphi}(x)$. Then by $\varphi \subseteq \tilde{\varphi}$ and $\tilde{\varphi}(x)=y$, we have either $\varphi(x)=y$ or $x \notin \operatorname{dom}_{\mathscr{V}}(\varphi)$ and $y \notin \operatorname{range}(\varphi)$ as $\tilde{\varphi}$ is injective on $\operatorname{dom}_{\mathscr{V}}(\tilde{\varphi})$. Thus, one can apply inference rule Bound, and we have $\langle S, \varphi\rangle \Longrightarrow\left\langle S^{\prime \prime}, \varphi \cup\{x \mapsto y\}\right\rangle$. Then, clearly, we have $\varphi^{\prime}=\varphi \cup\{x \mapsto y\} \subseteq \tilde{\varphi}$. Together with $S^{\prime \prime} \subseteq S$, we know $\tilde{\varphi}$ is a solution of $\left\langle S^{\prime \prime}, \varphi^{\prime}\right\rangle$.
2. $s=f\left(s_{1}, \ldots, s_{n}\right)$ with $f \in \mathscr{F}$.

Then $t=\tilde{\varphi}\left(f\left(s_{1}, \ldots, s_{n}\right)\right)=f\left(\tilde{\varphi}\left(s_{1}\right), \ldots, \tilde{\varphi}\left(s_{n}\right)\right)$, so let $t=f\left(t_{1}, \ldots, t_{n}\right)$ where $t_{i}=\tilde{\varphi}\left(s_{i}\right)$ for $i=1, \ldots, n$. Then, one can apply the inference rule $\mathbf{S p l i t}$, and we have $\langle S, \varphi\rangle \Longrightarrow$ $\left\langle S^{\prime \prime} \cup\left\{s_{1} \unlhd t_{1}, \ldots, s_{n} \unlhd t_{n}\right\}, \varphi\right\rangle$. It is easy to check $\tilde{\varphi}$ is a solution of $\left\langle S^{\prime \prime} \cup\left\{s_{1} \unlhd t_{1}, \ldots, s_{n} \unlhd\right.\right.$ $\left.\left.t_{n}\right\}, \varphi\right\rangle$.
3. $s=p\left(s_{1}, \ldots, s_{n}\right)$ with $p \in \mathscr{X}$.

Since $\tilde{\varphi}\left(p\left(s_{1}, \ldots, s_{n}\right)\right)=t$ and $t \in \mathrm{~T}(\mathscr{F}, \mathscr{V}), p \in \operatorname{dom}_{\mathscr{X}}(\tilde{\varphi})$. By the definition of term homomorphism, we have $\tilde{\varphi}(p) \in C_{n}(\mathscr{F})$. Then $t=\tilde{\varphi}\left(p\left(s_{1}, \ldots, s_{n}\right)\right)=\tilde{\varphi}(p)\left\langle\tilde{\varphi}\left(s_{1}\right), \ldots, \tilde{\varphi}\left(s_{n}\right)\right\rangle$. Let $C=\tilde{\varphi}(p)$ and $t_{i}=\tilde{\varphi}\left(s_{i}\right)$ (for $\left.i=1, \ldots, n\right)$. Then $C \in C_{n}(\mathscr{F})$. Suppose $x \mapsto y \in \varphi$, $\square_{i} \in C$, and $y \in \mathscr{V}\left(t_{i}\right)$. Then $x \mapsto y \in \tilde{\varphi}$ and $y \in \mathscr{V}\left(\tilde{\varphi}\left(s_{i}\right)\right)$. Thus, since $\tilde{\varphi}$ is injective on $\operatorname{dom}_{\mathscr{V}}(\tilde{\varphi})$, it follows $x \in \mathscr{V}\left(s_{i}\right)$. Thus, one can apply inference rule Extract, and we have $\langle S, \varphi\rangle \Longrightarrow\left\langle\{p \mapsto C\}\left(S^{\prime \prime} \cup\left\{s_{i} \unlhd t_{i} \mid \square_{i} \in C\right\}\right), \varphi \cup\{p \mapsto C\}\right\rangle$. Since $\{p \mapsto C\} \in \tilde{\varphi}$, we have $\tilde{\varphi}\left(\{p \mapsto C\}\left(S^{\prime \prime} \cup\left\{s_{i} \unlhd t_{i} \mid \square_{i} \in C\right\}\right)\right)=\tilde{\varphi}\left(S^{\prime \prime} \cup\left\{s_{i} \unlhd t_{i} \mid \square_{i} \in C\right\}\right)$. Thus, it is easy to check $\tilde{\varphi}$ is a solution of $\left\langle\{p \mapsto C\}\left(S^{\prime \prime} \cup\left\{s_{i} \unlhd t_{i} \mid \square_{i} \in C\right\}\right), \varphi \cup\{p \mapsto C\}\right\rangle$.

Theorem 5.13 (completeness of Match). Let $\Phi$ be the collection of all outputs of the algorithm Match for the input $S$. Then $\Phi$ is a complete set of matchers of $S$.
Proof. By Theorem 5.10, any $\varphi \in \Phi$ is a matcher of $S$. Let $\tilde{\varphi}$ be a matcher of $S$. From Lemma 5.12, there exists a sequence $\langle S, \emptyset\rangle=\left\langle S_{0}, \varphi_{0}\right\rangle \Longrightarrow\left\langle S_{1}, \varphi_{1}\right\rangle \Longrightarrow \cdots$ of pairs of a matching problem and a term homomorphism such that $\tilde{\varphi}$ is a solution of $\left\langle S_{i}, \varphi_{i}\right\rangle$ (for $i \geq 0$ ). By Theorem 5.6, this sequence is finite. So there exists $\varphi^{\prime}$ such that $\langle S, \emptyset\rangle \stackrel{*}{\Longrightarrow}\left\langle\emptyset, \varphi^{\prime}\right\rangle$ and $\varphi^{\prime} \subseteq \tilde{\varphi}$. Since $\langle S, \emptyset\rangle \stackrel{*}{\Longrightarrow}\left\langle\emptyset, \varphi^{\prime}\right\rangle$ means $\varphi^{\prime} \in \Phi$, the claim follows.

### 5.2 TRS Pattern matching

We now introduce the TRS pattern matching problem in a way similar to the term matching problem. From here on, we assume that for any TRS $\mathcal{R}$ and any defined symbol $f \in \mathscr{F}_{\mathrm{d}}$, there exists a rewrite rule $l \rightarrow r \in \mathcal{R}$ such that $\operatorname{root}(l)=f$.

Definition 5.14. A pair $\langle\mathcal{P}, \mathcal{R}\rangle$ of a TRS pattern $\mathcal{P}$ and TRS $\mathcal{R}$ is called a TRS pattern matching problem. A TRS pattern matching problem $\langle\mathcal{P}, \mathcal{R}\rangle$ is written as $\mathcal{P} \unlhd \mathcal{R}$. (2) For a TRS pattern matching problem $\mathcal{P} \unlhd \mathcal{R}$ we say $\mathcal{P}$ matches $\mathcal{R}$ when there exists a CS homomorphism $\varphi$ such that $\varphi(\mathcal{P})=\mathcal{R}$; the CS homomorphism $\varphi$ is called a matcher (or solution) of $\mathcal{P} \unlhd \mathcal{R}$.

By encoding $\mathcal{P}$ and $\mathcal{R}$ by sequences of patterns and terms and then running the term pattern matching algorithm, one can find a solution of the TRS pattern matching problem. Let us first demonstrate this by an example.
Example 5.15. Let $\mathcal{P} \unlhd \mathcal{R}$ be a TRS pattern matching problem where

$$
\mathcal{P}\left\{\begin{array}{lll}
\mathrm{f}(\mathrm{a}) & \rightarrow & \mathrm{b} \\
\mathrm{f}\left(\mathrm{c}\left(u_{1}, v_{1}\right)\right) & \rightarrow & \mathrm{g}\left(u_{1}, \mathrm{f}\left(v_{1}\right)\right)
\end{array}\right.
$$

$$
\mathcal{R}\left\{\begin{array}{lll}
\operatorname{sum}([]) & \rightarrow & 0 \\
\operatorname{sum}\left(x_{1}: y_{1}\right) & \rightarrow & +\left(x_{1}, \operatorname{sum}\left(y_{1}\right)\right)
\end{array}\right.
$$

This TRS pattern matching problem is encoded as a term pattern matching problem

$$
\begin{gathered}
S=\left\{\mathrm{f}(\mathrm{a}) \unlhd \operatorname{sum}([]), \mathrm{b} \unlhd 0, \mathrm{f}\left(\mathrm{c}\left(u_{1}, v_{1}\right)\right) \unlhd \operatorname{sum}\left(x_{1}: y_{1}\right),\right. \\
\left.\mathrm{g}\left(u_{1}, \mathrm{f}\left(v_{1}\right)\right) \unlhd+\left(x_{1}, \operatorname{sum}\left(y_{1}\right)\right)\right\} .
\end{gathered}
$$

(There are choices on which correspondence of the rules in $\mathcal{P}$ and $\mathcal{R}$ is to be chosen, but we assume that suitable such a choice has been selected in an adequate way.)

By applying the algorithm Match to the term pattern matching problem $S$, we obtain the following three solutions:

$$
\begin{aligned}
& \left\{\begin{array}{ll}
\mathrm{f} \mapsto \operatorname{sum}\left(\square_{1}\right), & \mathrm{g} \mapsto+\left(\square_{1}, \square_{2}\right), \\
\mathrm{a} \mapsto[], & \mathrm{b} \mapsto 0, \quad \mathrm{c} \mapsto \square_{1}: \square_{2}, \\
u_{1} \mapsto x_{1}, & v_{1} \mapsto y_{1}
\end{array}\right\}, \\
& \left\{\begin{array}{ll}
\mathrm{f} \mapsto \square_{1}, & \mathrm{~g} \mapsto+\left(\square_{2}, \operatorname{sum}\left(\square_{1}\right)\right), \\
\mathrm{a} \mapsto \operatorname{sum}([]), & \mathrm{b} \mapsto 0, \quad \mathrm{c} \mapsto \operatorname{sum}\left(\square_{2}: \square_{1}\right), \\
u_{1} \mapsto y_{1}, & v_{1} \mapsto x_{1}
\end{array}\right\}, \\
& \left\{\begin{array}{ll}
\mathrm{f} \mapsto \square_{1}, & \mathrm{~g} \mapsto+\left(\square_{1}, \operatorname{sum}\left(\square_{2}\right)\right), \\
\mathrm{a} \mapsto \operatorname{sum}([]), & \mathrm{b} \mapsto 0, \quad \mathrm{c} \mapsto \operatorname{sum}\left(\square_{1}: \square_{2}\right), \\
u_{1} \mapsto x_{1}, & v_{1} \mapsto y_{1}
\end{array}\right\} .
\end{aligned}
$$

Among these solutions, one can select a CS homomorphism $\varphi$, for which $\varphi(\mathcal{P})=\mathcal{R}$ holds. Indeed, the first term homomorphism is a CS homomorphisms.

More formally, the TRS pattern matching procedure is introduced as follows.
Definition 5.16. (1) Let $\mathcal{P}$ be a TRS pattern and $\mathcal{R}$ a TRS. A sequentialization of a TRS pattern matching problem $\mathcal{P} \unlhd \mathcal{R}$ is a term pattern matching problem

$$
\bigcup_{\substack{s \rightarrow t \in \mathcal{P} \\ \sigma(s \rightarrow t)=l \rightarrow r \in \mathcal{R}}}\{s \unlhd l, t \unlhd r\}
$$

where $\sigma$ maps each $s \rightarrow t \in \mathcal{P}$ to some $l \rightarrow r \in \mathcal{R}$. Note that variables of each rewriting rule are w.l.o.g. assumed to be disjoint. (2) The procedure TRSMatch is given like this:

## TRSMatch

Input: a TRS pattern matching problem $\mathcal{P} \unlhd \mathcal{R}$
Output: a CS homomorphism $\varphi$

1. Take any sequentialization of $\mathcal{P} \unlhd \mathcal{R}$, and computes term homomorphism $\varphi$ using Match.
2. output $\varphi$ if $\varphi$ is a CS homomorphism.

The following results follow immediately from those for the Match.
Theorem 5.17 (properties of TRSMatch). For any input, the procedure TRSMatch terminates and the number of outputs of the algorithm TRSMatch is finite.

The following theorem guarantees that any TRS pattern matching problem is solved by our TRS pattern matching algorithm.

Theorem 5.18 (solution of TRS pattern matching). Let $\Phi$ be the collection of all outputs of the algorithm TRSMatch for the input $\mathcal{P} \unlhd \mathcal{R}$. Then (1) any $\varphi \in \Phi$ is a CS homomorphism such that $\varphi(\mathcal{P})=\mathcal{R}$; (2) if a CS homomorphism $\varphi$ is a solution of the TRS pattern matching problem $\mathcal{P} \unlhd \mathcal{R}$, then there exists $\tilde{\varphi} \in \Phi$ such that $\tilde{\varphi} \subseteq \varphi$.

Proof. (1) It follows easily from the definition of TRSMatch and Theorem 5.10. (2) Suppose that a CS homomorphism $\varphi$ is a solution of the TRS pattern matching problem $\mathcal{P} \unlhd \mathcal{R}$. Then clearly $\varphi$ is a solution of some sequentialization $S$ of $\mathcal{P} \unlhd \mathcal{R}$. Let $\Phi^{\prime}$ be the set of solutions of the term pattern matching problem $S$. Then by Theorem 5.13 , there exists a term homomorphism $\tilde{\varphi} \in \Phi^{\prime}$ such that $\tilde{\varphi} \subseteq \varphi$ and $\tilde{\varphi}(S)$ is trivial. Thus for any $p, q \in \mathscr{X}_{\mathrm{d}}, \operatorname{root}(\tilde{\varphi}(p))=\operatorname{root}(\tilde{\varphi}(q))$ implies $p=q$; for otherwise, $\varphi$ is not a CS homomorphism by $\tilde{\varphi} \subseteq \varphi$. Since any defined pattern variable $p \in \mathscr{X}_{\mathrm{d}}$ appears at the root of some rewrite rule in $\mathcal{P}, p \in \operatorname{dom}_{\mathscr{X}}(\tilde{\varphi})$ holds. Thus for any $p \in \mathscr{X}_{\mathrm{d}}, \tilde{\varphi}(p)=\varphi(p)=f\left(\square_{i_{1}}, \ldots, \square_{i_{n}}\right)$ for some $f \in \mathscr{F}_{\mathrm{d}}$. Therefore $\tilde{\varphi}$ is a CS homomorphism and hence $\tilde{\varphi} \in \Phi$.

Finally, the procedure for TRS transformation by templates is completed like this:

## TRS transformation procedure

Input: TRS $\mathcal{R}$, transformation template $\left\langle\mathcal{P}, \mathcal{P}^{\prime}, \mathcal{H}\right\rangle$
Output: TRS $\mathcal{R}^{\prime}$

1. Using TRSMatch, find a CS homomorphism $\varphi$ such that $\varphi(\mathcal{P})=\mathcal{R}$.
2. If $p \in \mathscr{X} \backslash \operatorname{dom}_{\mathscr{X}}(\varphi)$ appears in $\mathcal{P}^{\prime}$, then set $\varphi(p)=f\left(\square_{1}, \ldots, \square_{\operatorname{arity}(p)}\right)$ for a fresh function symbol $f$.
3. Let $\mathcal{R}^{\prime}=\varphi\left(\mathcal{P}^{\prime}\right)$.

Example 5.19. Let $\mathcal{R}$ be a TRS in Example 3.1 and $\left\langle\mathcal{P}, \mathcal{P}^{\prime}, \mathcal{H}\right\rangle$ be a template in Example 3.3. Below we demonstrate our TRS transformation procedure for the inputs $\mathcal{R}$ and $\left\langle\mathcal{P}, \mathcal{P}^{\prime}, \mathcal{H}\right\rangle$.

1. First, running the TRSMatch for inputs $\mathcal{P} \unlhd \mathcal{R}$, the following CS homomorphism $\varphi$ is found.

$$
\varphi=\left\{\begin{array}{ll}
\mathrm{f} \mapsto \operatorname{sum}\left(\square_{1}\right), & u_{1} \mapsto x_{1}, \\
\mathrm{~g} \mapsto+\left(\square_{1}, \square_{2}\right), & v_{1} \mapsto y_{1}, \\
\mathrm{a} \mapsto[], & u_{2} \mapsto x_{2}, \\
\mathrm{~b} \mapsto 0, & v_{3} \mapsto x_{3}, \\
\mathrm{c} \mapsto \square_{1}: \square_{2}, & w_{3} \mapsto y_{3}, \\
\mathrm{~d} \mapsto \mathrm{~s}\left(\square_{2}\right) &
\end{array}\right\}
$$

2. Since a pattern variable $f_{1}$ appearing in $\mathcal{P}^{\prime}$ does not appear in $\operatorname{dom}(\varphi)$, we set $\varphi\left(f_{1}\right)=$ $\operatorname{sum} 1\left(\square_{1}, \square_{2}\right)$. where sum1 is a fresh function symbol.
3. Apply $\varphi$ to $\mathcal{P}^{\prime}$ and obtain

$$
\mathcal{R}^{\prime} \begin{cases}\operatorname{sum}\left(u_{4}\right) & \rightarrow \operatorname{sum} 1\left(u_{4}, 0\right) \\ \operatorname{sum} 1\left([], u_{5}\right) & \rightarrow u_{5} \\ \operatorname{sum} 1\left(u_{6}: v_{6}, w_{6}\right) & \rightarrow \operatorname{sum} 1\left(v_{6},+\left(w_{6}, u_{6}\right)\right) \\ +\left(0, u_{7}\right) & \rightarrow u_{7} \\ +\left(\mathrm{s}\left(u_{8}\right), v_{8}\right) & \rightarrow \operatorname{s}\left(+\left(u_{8}, v_{8}\right)\right)\end{cases}
$$

Thus, the output TRS is $\mathcal{R}^{\prime}$.

Our TRS matching algorithm, in particular, term pattern matching algorithm and the second-order matching algorithm in lambda calculus by Huet and Lang [6, 11, 12] seem to have an obvious resemblance although they are incomparable. In the rest of this section, we explain this briefly.

In the framework based on the lambda calculus, each program is given by a recursive program schema [23] like this:

$$
\left\{\begin{aligned}
\operatorname{rev}(x) \rightarrow & \operatorname{if}(\operatorname{null}(x),[], \\
& \operatorname{app}(\operatorname{rev}(\operatorname{cdr}(x)), \operatorname{car}(x):[])) .
\end{aligned}\right.
$$

Such a recursive program schema is represented by a lambda term using a fixpoint operator Y :

$$
\mathrm{Y}(\lambda \operatorname{rev} \cdot \lambda x \cdot \operatorname{if}(\operatorname{null}(x),[], \operatorname{app}(\operatorname{rev}(\operatorname{cdr}(x)), \operatorname{car}(x):[]))),
$$

or more precisely,

$$
\mathrm{Y}(\lambda \operatorname{rev} \cdot \lambda x . \operatorname{if}(\operatorname{null} x)[]((\operatorname{app}(\operatorname{rev}(\operatorname{cdr} x)))(:(\operatorname{car} x)[]))) .
$$

Note that the function symbol rev in the recursive program schema is changed into a (bound) variable rev in the corresponding lambda term.

On the other hand, programs represented by TRSs are not necessarily recursive program schemas. For example the similar reverse program is represented by the following TRS.

$$
\left\{\begin{array}{lll}
\operatorname{rev}([]) & \rightarrow & {[]} \\
\operatorname{rev}(x: y) & \rightarrow & \operatorname{app}(\operatorname{rev}(y), x:[]) .
\end{array}\right.
$$

Like this, TRS may not be a recursive program schema in general. Because of this, the secondorder matching algorithms in lambda calculus can not be directly applied to the TRS pattern matching problem.

### 5.3 Summary

In this chapter, we gave a term pattern matching algorithm Match and show its soundness and completeness (Theorem 5.10 and 5.13 ). We then proposed a TRS pattern matching algorithm TRSMatch by extending Match. We also compared the framework of program transformation by templates based on term rewriting and lambda calculus in the view of pattern matching.

## Chapter 6

## Program Transformation System RAPT

RAPT (Rewriting-based Automated Program Transformation system) is an implementation of our framework. This chapter describes about RAPT and reports experiments of transformations brought by RAPT. RAPT transforms input many-sorted TRSs according to specified correct templates and verifies its correctness automatically.

### 6.1 Implementation

A key property of our framework is sufficient completeness, which has to be satisfied by input and output TRSs. Sufficient completeness is checked in RAPT by the decidable necessary and sufficient condition for terminating TRSs [13, 17], and thus currently the target of program transformation by RAPT is limited to terminating TRSs. A simple procedure to check confluence is also available for terminating TRSs [1].

RAPT uses rewriting induction [21], in which termination plays an essential role, to verify that the instantiated hypotheses of transformation template are inductive consequences of the input TRS. Since RAPT handles only terminating TRSs, rewriting induction is integrated keeping the whole system simple. Other inductive proving methods [2, 4] also can be possibly incorporated.

For the termination checking, RAPT detects a possible compatible precedence for the lexicographic path ordering (LPO) [1]. The obtained reduction ordering is used as a basis of rewriting induction. Other methods to verify termination of TRSs [1] may well be incorporated.

### 6.1.1 Specification of input TRS and transformation template

Inputs of RAPT are a many-sorted TRS and a transformation template. The input TRS is specified by the following sections.

1. FUNCTIONS: function symbols with sort declaration.
2. RULES: rewrite rules over many-sorted terms.

The transformation template $\left\langle\mathcal{P}, \mathcal{P}^{\prime}, \mathcal{H}\right\rangle$ is specified by the following sections.

1. INPUT: rewrite rules of $\mathcal{P}$ over patterns,

| FUNCTIONS | INPUT |
| :---: | :---: |
| sum: List -> Nat; | ?f(?a()) -> ?b(); |
| cons: Nat * List -> List; | ?f(?c(u,v)) -> ?g(?e(u), ?f(v)) ; |
| nil: List; | ?g(?b(), u) -> u; |
| +: Nat * Nat -> Nat; | ? $\mathrm{g}(\mathrm{?d}(\mathrm{u}, \mathrm{v}), \mathrm{w})->$ ?d(u, ?g(v,w)) |
| s: Nat -> Nat; |  |
| 0: Nat | OUTPUT |
|  | ?f(u) -> ?f1(u, ?b()) ; |
| RULES | ?f1(?a(), u) -> u; |
| sum(nil()) -> O(); | ?f1(?c(u,v),w) -> ?f1(v, ?g(w,?e(u)) ) |
| sum(cons(x,ys)) $\rightarrow$ + $(\mathrm{x}, \mathrm{sum}(\mathrm{ys}))$; | ? $\mathrm{g}(\mathrm{?b}(), \mathrm{u})->\mathrm{u}$; |
| +(0(), x) -> x ; | ?g(?d(u,v),w) -> ?d(u, ?g(v,w)) |
| +(s(x) , y) $\rightarrow$ s $(+(x, y))$ |  |
|  | HYPOTHESIS |
|  | ? $\mathrm{g}(\mathrm{?b}(), \mathrm{u})=$ ? $\mathrm{g}(\mathrm{u}, \mathrm{?b}())$; |
|  | ? $\mathrm{g}(\mathrm{?g}(\mathrm{u}, \mathrm{v}), \mathrm{w})=? \mathrm{~g}(\mathrm{u}, \mathrm{?g}(\mathrm{v}, \mathrm{w})$ ) |

Figure 6.1: Specification of input TRS and transformation template
2. OUTPUT: rewrite rules of $\mathcal{P}^{\prime}$ over patterns,
3. HYPOTHESIS: equations of $\mathcal{H}$ over patterns.

Figure 6.1 shows the many-sorted $\operatorname{TRS} \mathcal{R}_{\text {sum }}$ and the template $\left\langle\mathcal{P}, \mathcal{P}^{\prime}, \mathcal{H}\right\rangle$ which appear in Section 2 prepared as an input to RAPT: rules, equations and sort declarations are separated by ";"; pattern variables are preceded by "?"; and to distinguish variables from constants, the latter are followed by "()".

### 6.1.2 Implementation details

RAPT is implemented using SML/NJ. The source code of RAPT consists of about 5,000 lines.
The TRS transformation and the verification of its correctness are conducted in RAPT in 6 phases. In Figure 6.2, we describe these phases and dependencies among each phase. Solid arrows represent data flow and dotted arrows explain how information obtained in each phase is used.

If these 6 phases are successfully passed then RAPT produces output TRSs. The correctness of the transformation is guaranteed, provided the transformation template is developed. RAPT can also report summaries of program transformation in a readable format (Figure 6.3).

We now explain operations of each phases briefly.

1. Validation of input TRS In this phase, RAPT checks whether the input TRS is leftlinear and well-typed, and from rewrite rules divides function symbols into defined function symbols and constructor symbols and checks whether the input TRS is a constructor system. The information of function symbols will be used in Phases 3 and 4.
2. Precedence detection In this phase, RAPT checks the input TRS is terminating by LPO and (if it is the case) detects a precedence. The suitable precedence (if there exists one) for LPO is computed based on the LPO constraint solving algorithm described in [10].


Figure 6.2: Overview of RAPT
3. Proving confluence and sufficient completeness In this phase, RAPT proves whether the input TRS is confluent and sufficiently complete. This makes use of the information of constructor symbols detected at Phase 1 and the fact that the input TRS is left-linear and terminating verified at Phases 1 and 2, respectively. For confluence, it is checked whether all critical pairs are joinable. For sufficient completeness, quasi-reducibility of the TRS is checked; this part is based on the (many-sorted extension of) complement algorithm introduced in [15] that computes the complement of a substitution.
4. TRS pattern matching In this phase, RAPT finds a combination of rewrite rules to apply the transformation and the term homomorphism which instantiates the input pattern TRS to these rewrite rules; the matching algorithm TRSMatch is used in this part. Using information of function symbols detected in Phase 1, it is also checked whether this term homomorphism is a CS-homomorphism. Pattern matching of rewrite rules are carried out in order, and use the information of matching solutions to limit next rewrite rules to perform the pattern match. Since solving the patten matching of main function usually gives information which subfunctions are used in sequel, this heuristics performs the TRS matching relatively well. Visually, consider the case when $\mathcal{P}=\left\{\mathrm{p}_{i}(x) \rightarrow \mathrm{p}_{i-1}(x) \mid 1 \leq i \leq 9\right\} \cup\left\{\mathrm{p}_{0}(x) \rightarrow \mathrm{a}\right\}$ and $\mathcal{R}=\left\{\mathrm{f}_{i}(x) \rightarrow \mathrm{f}_{i-1}(x) \mid 1 \leq i \leq 9\right\} \cup\left\{\mathrm{f}_{0}(x) \rightarrow 0\right\}$ where the number of all possible combinations of rewrite rules becomes $10!=3,628,800$ while the number of matching performed becomes $\sum_{i=0}^{10} i=55$.
5. Verification of hypothesis In this phase, RAPT checks whether the input TRS satisfies the hypothesis part of the template. This is done by (1) instantiating the hypotheses through the term homomorphism found at Phase 4 and (2) proving they are inductive consequences of the input TRS, using rewriting induction. The latter uses LPO with the precedence detected at Phase 2.
6. Validation of output TRS In this phase, RAPT checks whether the output TRS is (1) terminating, (2) left-linear, (3) type consistent, and (4) sufficiently complete. In (3), because the pattern TRS $\mathcal{P}^{\prime}$ for the output may contain a pattern variable not occurring in the pattern TRS $\mathcal{P}$ for the input, types may be unknown for some of function symbols in $\mathcal{R}^{\prime}$. Therefore,

## Summary of Program Transformation

reported by RAPT
February 21, 2006
Transformation Template:

$$
\begin{aligned}
& \mathcal{P}\left\{\begin{array}{lll}
\mathrm{f}(\mathrm{a}) & \rightarrow & \mathrm{b} \\
\mathrm{f}(\mathrm{c}(u, v)) & \rightarrow & \mathrm{g}(\mathrm{e}(u, v), \mathrm{f}(v))
\end{array}\right. \\
& \mathcal{P}^{\prime}\left\{\begin{array}{lll}
\mathrm{f}(u) & \rightarrow & \mathrm{f} 1(u, \mathrm{~b}) \\
\mathrm{f} 1(\mathrm{a}, u) & \rightarrow & u \\
\mathrm{f} 1 \mathrm{c}(u, v), w) & \rightarrow & \mathrm{f} 1(v, \mathrm{~g}(w, \mathrm{e}(u, v)))
\end{array}\right. \\
& \mathcal{H}\left\{\begin{array}{lll}
\mathrm{g}(\mathrm{~b}, u) & \approx & u \\
\mathrm{~g}(u, \mathrm{~b}) & \approx & u \\
\mathrm{~g}(\mathrm{~g}(u, v), w) & \approx & \mathrm{g}(u, \mathrm{~g}(v, w))
\end{array}\right.
\end{aligned}
$$

Input TRS:

$$
\mathcal{R} \begin{cases}\operatorname{rev}(\operatorname{nil}) & \rightarrow \text { nil } \\ \operatorname{rev}(\operatorname{cons}(x, y s)) & \rightarrow \operatorname{app}(\operatorname{rev}(y s), \operatorname{cons}(x, \text { nil })) \\ \operatorname{app}(\operatorname{nil}, x) & \rightarrow x \\ \operatorname{app}(\operatorname{cons}(x, y), z) & \rightarrow \operatorname{cons}(x, \operatorname{app}(y, z))\end{cases}
$$

Termination of $\mathcal{R}$ is checked by LPO with the precedence $\{$ rev > app, rev > nil, rev > cons, app > cons $\}$. The set of critical pairs of $\mathcal{R}$ is $\}$.

A solution of matching (CS-homomorphisms):

$$
\varphi=\left\{\begin{array}{lll}
\mathrm{b} & \mapsto & \text { nil } \\
\mathrm{a} & \mapsto & \text { nil } \\
\mathrm{e} & \mapsto & \operatorname{cons}\left(\square_{1}, \text { nil }\right) \\
\mathrm{g} & \mapsto & \operatorname{app}\left(\square_{2}, \square_{1}\right) \\
\mathrm{c} & \mapsto & \operatorname{cons}\left(\square_{1}, \square_{2}\right) \\
\mathrm{f} & \mapsto & \operatorname{rev}\left(\square_{1}\right)
\end{array}\right\}
$$

The instantiation of hypothesis:

$$
\varphi(\mathcal{H}) \begin{cases}\operatorname{app}(u, \operatorname{nil}) & \approx u \\ \operatorname{app}(\operatorname{nil}, u) & \approx u \\ \operatorname{app}(w, \operatorname{app}(v, u)) & \approx \operatorname{app}(\operatorname{app}(w, v), u)\end{cases}
$$

Output TRS:

$$
\mathcal{R}^{\prime} \begin{cases}\operatorname{rev}(u) & \rightarrow \mathrm{f} 1(u, \mathrm{nil}) \\ \mathrm{f} 1(\operatorname{nil}, u) & \rightarrow \\ \mathrm{f} 1(\operatorname{cons}(u, v), w) & \rightarrow \mathrm{f} 1(v, \operatorname{cons}(u, w)) \\ \operatorname{app}(\operatorname{nil}, x) & \rightarrow \\ \operatorname{app}(\operatorname{cons}(x, y), z) & \rightarrow \\ \operatorname{cons}(x, \operatorname{app}(y, z))\end{cases}
$$

Figure 6.3: Example of a program transformation report


Figure 6.4: Snapshot of TRS pattern matching
we need to infer the type information together with the type consistency check. (4) is proved based on the fact the output TRS is terminating which is verified at (1) using LPO.

### 6.2 Experiments

We have checked operations of RAPT using several templates. Table 6.1 describes some of transformation templates and numbers of TRSs succeeded in transformation by each template. Template I is the one which appears in Section 2. This template represents a well-known transformation from recursive programs to iterative programs. A same kind of transformation is also described by Template II. The main difference between Template I and II is the righthand side of second rule of input parts. In our experiments, there exist TRSs which cannot be transformed by one of these templates but can be done by the other. Template III is the one which overcomes this difference; unchanged rewrite rules of input and output TRS patterns are removed and rewrite rules which are necessary to develop the template are pushed into the hypothesis. Template IV represents another transformation known as fusion or deforestation [26].

RAPT performs transformations of these examples in less than 100 msec .

Table 6.1: Experimental result

| Template I | TRSs | Template II | TRSs |
| :---: | :---: | :---: | :---: |
| $\left\{\begin{array}{lll}\mathrm{f}(\mathrm{a}) & \rightarrow & \mathrm{b} \\ \mathrm{f}(\mathrm{c}(u, v)) & \rightarrow & \mathrm{g}(\mathrm{e}(u), \mathrm{f}(v)) \\ \mathrm{g}(\mathrm{b}, u) & \rightarrow & u \\ \mathrm{~g}(\mathrm{~d}(u, v), w) & \rightarrow & \mathrm{d}(u, \mathrm{~g}(v, w))\end{array}\right\}$ |  | $\left\{\begin{array}{lll} \mathrm{f}(\mathrm{a}) & \rightarrow & \mathrm{b} \\ \mathrm{f}(\mathrm{c}(u, v)) & \rightarrow & \mathrm{g}(\mathrm{f}(v), \mathrm{e}(u)) \\ \mathrm{g}(\mathrm{~b}, u) & \rightarrow & u \\ \mathrm{~g}(\mathrm{~d}(u, v), w) & \rightarrow & \mathrm{d}(u, \mathrm{~g}(v, w)) \end{array}\right\},$ |  |
| $\left\{\begin{array}{lll}\mathrm{f}(u) & \rightarrow & \mathrm{f}_{1}(u, \mathrm{~b}) \\ \mathrm{f}_{1}(\mathrm{a}, u) & \rightarrow & u \\ \mathrm{f}_{1}(\mathrm{c}(u, v), w) & \rightarrow & \mathrm{f}_{1}(v, \mathrm{~g}(w, \mathrm{e}(u))) \\ \mathrm{g}(\mathrm{b}, u) & \rightarrow \\ \mathrm{g}(\mathrm{d}(u, v), w) & \rightarrow & u \\ \mathrm{~g}(\mathrm{l}, u, \mathrm{~g}(v, w))\end{array}\right\}$, | 3 | $\left\{\begin{array}{lll} \mathrm{f}(u) & \rightarrow & \mathrm{f}_{1}(u, \mathrm{~b}) \\ \mathrm{f}_{1}(\mathrm{a}, u) & \rightarrow & u \\ \mathrm{f}_{1}(\mathrm{c}(u, v), w) & \rightarrow & \mathrm{f}_{1}(v, \mathrm{~g}(\mathrm{e}(u), w)) \\ \mathrm{g}(\mathrm{~b}, u) & \rightarrow & u \\ \mathrm{~g}(\mathrm{~d}(u, v), w) & \rightarrow & \mathrm{d}(u, \mathrm{~g}(v, w)) \end{array}\right\}$ | 3 |
| $\left\{\begin{array}{lll}\mathrm{g}(\mathrm{b}, u) & \approx \\ \mathrm{g}(\mathrm{g}(u, v), w) & \approx & \mathrm{g}(u, \mathrm{~b}) \\ \mathrm{g}(u, \mathrm{~g}(v, w))\end{array}\right\}$ |  | $\left\{\begin{array}{lll} \mathrm{g}(\mathrm{~b}, u) & \approx & \mathrm{g}(u, \mathrm{~b}) \\ \mathrm{g}(\mathrm{~g}(u, v), w) & \approx & \mathrm{g}(u, \mathrm{~g}(v, w)) \end{array}\right\}$ |  |
| Template III | TRSs | Template IV | TRSs |
| $\left\{\begin{array}{llll}\mathrm{f}(\mathrm{a}) & \rightarrow & \mathrm{b} \\ \mathrm{f}(\mathrm{c}(u, v)) & \rightarrow & \mathrm{g}(\mathrm{e}(u, v), \mathrm{f}(v))\end{array}\right\}$, |  | $\left\{\begin{array}{lll}\mathrm{f}(x, y, z) & \rightarrow & \mathrm{g}(\mathrm{h}(x, y), z) \\ \mathrm{g}(\mathrm{a}, y) & \rightarrow & \mathrm{b}(u) \\ \mathrm{g}(\mathrm{c}(x, y), z) & \rightarrow & \mathrm{e}(x, \mathrm{~g}(y, z)) \\ \mathrm{h}(\mathrm{a}, y) & \rightarrow & \mathrm{r}(y) \\ \mathrm{h}(\mathrm{c}(x, y), z) & \rightarrow & \mathrm{c}(\mathrm{d}(x), \mathrm{h}(y, z))\end{array}\right\}$ |  |
| $\left\{\begin{array}{lll}\mathrm{f}(u) & \rightarrow & \mathrm{f}_{1}(u, \mathrm{~b}) \\ \mathrm{f}_{1}(\mathrm{a}, u) & \rightarrow & u \\ \mathrm{f}_{1}(\mathrm{c}(u, v), w) & \rightarrow & \mathrm{f}_{1}(v, \mathrm{~g}(w, \mathrm{e}(u, v)))\end{array}\right\}$, | 11 | $\left\{\begin{array}{lll} \mathrm{f}(\mathrm{a}, y, z) & \rightarrow & \mathrm{g}(\mathrm{r}(y), z) \\ \mathrm{f}(\mathrm{c}(x, y), z, w) & \rightarrow & \mathrm{e}(\mathrm{~d}(x), \mathrm{f}(y, z, w)) \\ \mathrm{g}(\mathrm{a}, y) & \rightarrow & \mathrm{b}(u) \end{array}\right\}$ | 8 |
| $\left\{\begin{array}{lcl}\mathrm{g}(\mathrm{b}, u) & \approx & u \\ \mathrm{~g}(u, \mathrm{~b}) & \approx & u \\ \mathrm{~g}(\mathrm{~g}(u, v), w) & \approx & \mathrm{g}(u, \mathrm{~g}(v, w))\end{array}\right\}$ |  | $\left.\begin{array}{lll} \mathrm{g}(\mathrm{c}(x, y), z) & \rightarrow & \mathrm{e}(x, \mathrm{~g}(y, z)) \\ \mathrm{h}(\mathrm{a}, y) & \rightarrow & \mathrm{r}(y) \\ \mathrm{h}(\mathrm{c}(x, y), z) & \rightarrow & \mathrm{c}(\mathrm{~d}(x), \mathrm{h}(y, z)) \end{array}\right\},$ |  |

## Chapter 7

## Constructing Templates

To apply the technique of program transformation by template, appropriate transformation patterns have to be constructed beforehand. Thus, it is important to introduce new transformation patterns in order to enhance the variety of program transformation. Up to our knowledge, however, few works discuss about the construction of transformation templates.

Our idea is to construct transformation patterns by considering the opposite of problems of program transformation, that is, we try to construct transformation patterns by generalizing similar TRS transformations. For example, from TRS transformations $\mathcal{R}_{\text {sum }} \Rightarrow \mathcal{R}_{\text {sum }}^{\prime}$ and $\mathcal{R}_{c a t} \Rightarrow \mathcal{R}_{c a t}^{\prime}$, we try to construct the transformation pattern $\mathcal{P} \Rightarrow \mathcal{P}^{\prime}$. We expect that our method will help to extract new transformation patterns from existing program transformations.


Figure 7.1: Overview of the construction of a template
We first propose a generalization procedure of two terms, and extend it for two TRSs. We then propose the construction of transformation patterns using the generalization procedure of TRSs. The input part of the transformation pattern is constructed by generalizing inputs of program transformations. Then the output part is constructed by generalizing outputs of program transformations using the information of generalization of input part. (Fig. 7.1).

Our method is inspired by Plotkin's work[20] for the first-order generalization of terms. The key technique of our method is the 2nd-order generalization of terms; contrast to the first-order generalization, a function part of a term can be instantiated in the 2nd-order generalization. For example, a first-order generalization of $+\left(\mathbf{s}\left(x_{1}\right), y_{1}\right)$ and $+\left(x_{2}, \mathbf{s}\left(y_{2}\right)\right)$ is $+\left(x_{3}, y_{3}\right)$. On the other hand, a 2nd-order generalization of $+\left(\mathrm{s}\left(x_{1}\right), y_{1}\right)$ and $\times\left(\mathrm{s}\left(x_{2}\right), y_{2}\right)$ is $\mathrm{p}\left(\mathrm{s}\left(x_{3}\right), y_{3}\right)$ where p is a pattern variable that is instantiated by + or $\times$.

An important problem in program transformation is to guarantee its correctness. We say that a program transformation is correct when the input and output program perform the same computation. In fact, incorrect transformations may be also obtained by the transformation pattern $\mathcal{P} \Rightarrow \mathcal{P}^{\prime}$ above. We have defined a transformation template by a triple $\left\langle\mathcal{P}, \mathcal{P}^{\prime}, \mathcal{H}\right\rangle$ where $\mathcal{P}$ and $\mathcal{P}^{\prime}$ are used to form the transformation pattern $\mathcal{P} \Rightarrow \mathcal{P}^{\prime}$ and $\mathcal{H}$, called hypothesis, is a set of equations. A hypothesis $\mathcal{H}$ is used to represent lemmas which input TRSs have to satisfy to guarantee the correctness of transformation.

Currently, no automatic method to produce correct templates is known. In our framework, after constructing a transformation pattern by generalizing input similar transformations, we look for an appropriate hypothesis and prove the correctness to construct correct template (Fig. 7.1).

### 7.1 Generalization of Terms

In this section, we propose a term generalization procedure, called 2 nd-Gen, and show its soundness. 2nd-Gen will be used as a basic module of TRS generalization procedure. We first give a notion of generalization of two term patterns.

Definition 7.1. Let $s$ and $t$ be term patterns. A term pattern $u$ is a generalization of $s$ and $t$ if there exist term homomorphisms $\varphi_{1}$ and $\varphi_{2}$ such that $\varphi_{1}(u)=s$ and $\varphi_{2}(u)=t$.

Example 7.2. Let $\mathrm{f}, \mathrm{g} \in \mathscr{F}, \mathrm{p}, \mathrm{q} \in \mathscr{X}$ and $x, y, z \in \mathscr{V}$. Then

1. $\mathrm{p}(x, y)$ is a generalization of $\mathrm{f}(x, x)$ and $\mathrm{g}(y)$, since $\left.\varphi_{1}(\mathrm{p}(x, y))\right)=\mathrm{f}(x, x)$ and $\varphi_{2}(\mathrm{p}(x, y))=$ $\mathrm{g}(y)$ for $\varphi_{1}=\left\{\mathrm{p} \mapsto \mathrm{f}\left(\square_{1}, \square_{1}\right)\right\}, \varphi_{2}=\left\{\mathrm{p} \mapsto \mathrm{g}\left(\square_{2}\right)\right\}$.
2. $\mathrm{p}(z)$ is a generalization of $\mathrm{f}(x, x)$ and $\mathrm{g}(y)$, since $\left.\varphi_{1}(\mathrm{p}(z))\right)=\mathrm{f}(x, x)$ and $\varphi_{2}(\mathrm{p}(z))=\mathrm{g}(y)$ for $\varphi_{1}=\left\{\mathrm{p} \mapsto \mathrm{f}\left(\square_{1}, \square_{1}\right), z \mapsto x\right\}, \varphi_{2}=\left\{\mathrm{p} \mapsto \mathrm{g}\left(\square_{1}\right), z \mapsto y\right\}$.
3. $\mathrm{p}(\mathrm{q}(z))$ is a generalization of $\mathrm{f}(x, x)$ and $\mathrm{g}(y)$, since $\left.\varphi_{1}(\mathrm{p}(\mathrm{q}(z)))\right)=\mathrm{f}(x, x)$ and $\varphi_{2}(\mathrm{p}(\mathrm{q}(z)))=$ $\mathrm{g}(y)$ for $\varphi_{1}=\left\{\mathrm{p} \mapsto \mathrm{f}\left(\square_{1}, \square_{1}\right), \mathrm{q} \mapsto \square_{1}, z \mapsto x\right\}, \varphi_{2}=\left\{\mathrm{p} \mapsto \square_{1}, \mathrm{q} \mapsto \mathrm{g}\left(\square_{1}\right), z \mapsto y\right\}$.

Our generalization procedure 2nd-Gen given later computes a generalization of two input term patterns in a non-deterministic way. Table 7.1 explains how two input term patterns $\mathrm{f}(\mathrm{g}(x), y)$ and $\mathrm{f}(z, \mathrm{~h}(u, w))$ are generalized into $\mathrm{f}\left(\mathrm{p}\left(v_{1}\right), \mathrm{q}\left(v_{2}, u\right)\right)$ using 2nd-Gen.

Initially, two input terms $\mathrm{f}(\mathrm{g}(x), y)$ and $\mathrm{f}(z, \mathrm{~h}(u, w))$ are coupled into $\mathrm{f}(\mathrm{g}(x), y) \wedge \mathrm{f}(z, \mathrm{~h}(u, w))$, using a special binary function symbol $\wedge$ (step 1 ). Since $\wedge$ indicates the position which will be generalized, nesting of $\wedge$ is not allowed. Next, 2nd-Gen repeats the following process depending on two symbols $\alpha$ and $\beta$ immediately below some $\wedge$, until it obtains a solution.

I If $\alpha$ and $\beta$ are local variables, then the coupled local variables $\alpha \wedge \beta$ is replaced with a new local variable. The memorizing function records the association between the coupled local variables and the introduced local variable.

II If $\alpha$ and $\beta$ are the same function symbols or pattern variables, then the symbol $\wedge$ is distributed in each argument.

III Otherwise, the coupled contexts is replaced with a new pattern variable and the modified arguments. The memorizing function records the association between the coupled contexts and the introduced pattern variable.

Var
if either

$$
\begin{array}{cc}
C[x \wedge y], \Phi & \begin{array}{c}
(1) \\
C
\end{array}(x \wedge y)=z \text { or } \\
C[z] \theta, \Phi \cup\{x \wedge y \mapsto z\} & (2) x \notin \operatorname{range}\left(\Phi_{[1]}^{-1}\right), y \notin \operatorname{range}\left(\Phi_{[2]}^{-1}\right) \text {, and } z \text { is a fresh local variable } \\
\text { where } \theta=\{x:=z, y:=z\} \text { is a substitution. }
\end{array}
$$

## Div

$$
\frac{C\left[p\left(s_{1}, \ldots, s_{n}\right) \wedge p\left(t_{1}, \ldots, t_{n}\right)\right], \Phi}{C\left[p\left(s_{1} \wedge t_{1}, \ldots, s_{n} \wedge t_{n}\right)\right], \Phi} \quad \text { if } p \in \mathscr{F} \cup \mathscr{X}
$$

Gen

$$
\text { if either } \Phi\left(C_{1} \wedge C_{2}\right)=p \text { or }
$$

(1) $C_{1}, C_{2} \in T_{n}^{\square}(\mathscr{F} \cup \mathscr{X}), C_{1} \neq C_{2}$,
(2) $p$ is a fresh ( $n$-ary) pattern variable

$$
\frac{C\left[C_{1}\left\langle s_{1}, \ldots, s_{n}\right\rangle \wedge C_{2}\left\langle t_{1}, \ldots, t_{n}\right\rangle\right], \Phi}{C\left[p\left(\alpha_{1}, \ldots, \alpha_{n}\right)\right], \Phi \cup\left\{C_{1} \wedge C_{2} \mapsto p\right\}}
$$

(3) $C_{1} \wedge C_{2} \notin \operatorname{dom}(\Phi)$
(4) $\mathscr{H}\left(C_{1}\right) \cup \mathscr{H}\left(C_{2}\right)=\left\{\square_{1}, \ldots, \square_{n}\right\}$, and
(5) $\alpha_{i}=\left\{\begin{array}{l}s_{i} \wedge t_{i} \text { if } \square_{i} \in \mathscr{H}\left(C_{1}\right) \cap \mathscr{H}\left(C_{2}\right) \\ \Phi_{[1]}\left(s_{i}\right) \text { if } \square_{i} \in \mathscr{H}\left(C_{1}\right) \backslash \mathscr{H}\left(C_{2}\right) \\ \Phi_{[2]}\left(t_{i}\right) \text { if } \square_{i} \in \mathscr{H}\left(C_{2}\right) \backslash \mathscr{H}\left(C_{1}\right)\end{array}\right.$

## Figure 7.2: Inference rules of $\mathbf{2 n d}-G e n$

Let $\wedge$ be a special binary function symbol. A coupled term pattern is defined as follows.
Definition 7.3. The set $\mathrm{T} \wedge(\mathscr{F} \cup \mathscr{X}, \mathscr{V})$ of coupled term patterns is defined as follow: (i) $\mathrm{T}(\mathscr{F} \cup \mathscr{X}, \mathscr{V}) \subseteq \mathrm{T} \wedge(\mathscr{F} \cup \mathscr{X}, \mathscr{V})$; (ii) $s, t \in \mathrm{~T}(\mathscr{F} \cup \mathscr{X}, \mathscr{V})$ implies $s \wedge t \in \mathrm{~T} \wedge(\mathscr{F} \cup \mathscr{X}, \mathscr{V})$; (iii) if $s_{1}, \ldots, s_{n} \in \mathrm{~T} \wedge(\mathscr{F} \cup \mathscr{X}, \mathscr{V}), p \in \mathscr{F} \cup \mathscr{X}$ and $\operatorname{arity}(p)=n$ then $p\left(s_{1}, \ldots, s_{n}\right) \in \mathrm{T} \wedge(\mathscr{F} \cup \mathscr{X}, \mathscr{V})$.

From the definition it is clear that every coupled term patten has no nested $\wedge$ symbols. A coupled term pattern $t$ is $\wedge$-free if $t \in \mathrm{~T}(\mathscr{F} \cup \mathscr{X}, \mathscr{V})$. A coupled term pattern $t$ is $\wedge$-top if $t=t^{\prime} \wedge t^{\prime \prime}$ for some $t^{\prime}, t^{\prime \prime} \in \mathrm{T}(\mathscr{F} \cup \mathscr{X}, \mathscr{V})$.

Each term homomorphism $\varphi$ and each substitution $\theta$ are extended to coupled term patterns by $\varphi(s \wedge t)=\varphi(s) \wedge \varphi(t)$ and $\theta(s \wedge t)=s \wedge t$ respectively. Note that the symbol $\wedge$ cancels the substitution to the term patterns below it (i.e. $\theta(s \wedge t) \neq \theta(s) \wedge \theta(t)$ in general). The set $\mathrm{T} \wedge(\mathscr{F} \cup \mathscr{X} \cup \mathscr{H}, \mathscr{V})$ is defined similarly.
Definition 7.4. Let $t$ be a coupled term pattern. For $i=1,2$, the (first and second) projection $\pi_{i}(t)$ of $t$ is defined as follows:

$$
\pi_{i}(t)=\left\{\begin{array}{l}
t \quad \text { if } t \in \mathrm{~T}(\mathscr{F} \cup \mathscr{X}, \mathscr{V}) \\
p\left(\pi_{i}\left(s_{1}\right), \ldots, \pi_{i}\left(s_{n}\right)\right) \\
\quad \text { if } t=p\left(s_{1}, \ldots, s_{n}\right) \text { for } p \in \mathscr{F} \cup \mathscr{X} \\
s_{i} \quad \text { if } t=s_{1} \wedge s_{2}
\end{array}\right.
$$

Example 7.5. Let $\mathrm{f}, \mathrm{g} \in \mathscr{F}$ and $x, y \in \mathscr{V}$. Then $s_{1}=\mathrm{f}(x, x) \wedge \mathrm{g}(y)$, $s_{2}=\mathrm{f}(x \wedge y, x)$, $s_{3}=\mathrm{f}(x \wedge y, x \wedge \mathrm{~g}(y))$ are coupled term patterns but $\mathrm{f}(x \wedge(x \wedge y), x)$ is not because it has nested $\wedge$ symbols. The $\wedge$-top subterms of $s_{3}$ are $x \wedge y$ and $x \wedge \mathrm{~g}(y)$. Also, we have $\pi_{1}\left(s_{1}\right)=\pi_{1}\left(s_{2}\right)=$ $\pi_{1}\left(s_{3}\right)=\mathrm{f}(x, x), \pi_{2}\left(s_{1}\right)=\mathrm{g}(y), \pi_{2}\left(s_{2}\right)=\mathrm{f}(y, x)$, and $\pi_{2}\left(s_{3}\right)=\mathrm{f}(y, \mathrm{~g}(y))$.

From the definition the following properties of the projection are obtained easily.
Lemma 7.6. Let $i=1$ or 2 .

1. If $s$ is $\wedge$-free then $\pi_{i}(s)=s$.
2. For any term homomorphism $\varphi$ and coupled term pattern $s, \pi_{i}(\varphi(s))=\varphi\left(\pi_{i}(s)\right)$.
3. For any coupled term pattern $C\left[s_{1} \wedge s_{2}\right], \pi_{i}\left(C\left[s_{1} \wedge s_{2}\right]\right)=\pi_{i}\left(C\left[s_{i}\right]\right)$.

The memorizing function $\Phi$, which records the association between the coupled contexts (the coupled local variables) and the introduced pattern variables (the introduced local variables, respectively), is carried along with the coupled term pattern during the generalization.

Definition 7.7. A memorizing function is a partial mapping $\Phi$ from $\left\{C_{1} \wedge C_{2} \mid C_{1}, C_{2} \in\right.$ $\left.\mathrm{T}^{\square}(\mathscr{F} \cup \mathscr{X})\right\} \cup\{x \wedge y \mid x, y \in \mathscr{V}\}$ to $\mathscr{X} \cup \mathscr{V}$ such that $(1) \Phi(x \wedge y) \in \mathscr{V}$ and $\Phi\left(C_{1} \wedge C_{2}\right) \in \mathscr{X}$, (2) $\Phi(x \wedge y)$ and $\Phi\left(C_{1} \wedge C_{2}\right)$ are fresh local variables and pattern variables (i.e., different from all the variables already used), respectively, (3) $x \wedge y, x \wedge y^{\prime} \in \operatorname{dom}(\Phi)$ (or $y \wedge x, y^{\prime} \wedge x \in \operatorname{dom}(\Phi)$ ) implies $y=y^{\prime}$, (4) If $C_{1} \wedge C_{2} \mapsto p \in \Phi$ and $\operatorname{arity}(p)=n$, then $C_{1} \neq C_{2}, C_{1}, C_{2} \in T_{n}^{\square}(\mathscr{F} \cup \mathscr{X})$, and $\mathscr{H}\left(C_{1}\right) \cup \mathscr{H}\left(C_{2}\right)=\left\{\square_{1}, \ldots, \square_{n}\right\}$.

For a memorizing function $\Phi$, its inverse projection is a term homomorphism defined by $\Phi_{[i]}^{-1}=\left\{u \mapsto s_{i} \mid s_{1} \wedge s_{2} \mapsto u \in \Phi\right\}$, and its local projection is a substitution defined by $\Phi_{[i]}=\left\{x_{i}:=z \mid x_{1} \wedge x_{2} \mapsto z \in \Phi, z \in \mathscr{V}\right\}$. From the condition (3) of the memorizing function, the local projection $\Phi_{[i]}$ is well-defined.

The memorization function has the next property which follows immediately from the definition.

Lemma 7.8. Let $\Phi$ be a memorizing function. Let $s$ be $a \wedge$-free term such that $\mathscr{V}(s) \cap$ $\operatorname{range}(\Phi)=\emptyset$. Then $\Phi_{[i]}^{-1}\left(\Phi_{[i]}(s)\right)=s$.

The generalization procedure 2nd-Gen works on pairs $\langle s, \Phi\rangle$ of a coupled term pattern $s$ and a memorizing function $\Phi$. Figure 7.2 gives the inference rules of 2nd-Gen. For pairs $\langle s, \Phi\rangle$ and $\left\langle s^{\prime}, \Phi^{\prime}\right\rangle$, we write $\langle s, \Phi\rangle \rightsquigarrow\left\langle s^{\prime}, \Phi^{\prime}\right\rangle$ when $\left\langle s^{\prime}, \Phi^{\prime}\right\rangle$ is obtained from $\langle s, \Phi\rangle$ by applying one of the inference rules in Figure 7.2. The reflexive transitive closure of $\rightsquigarrow$ is denoted by $\stackrel{*}{\rightsquigarrow}$.

The generalization procedure 2nd-Gen is given as follows:

## procedure 2nd-Gen

Input: term patterns $s$ and $t$
begin

1. Rename local variables of $s$ and $t$ so that
$\mathscr{V}(s)$ and $\mathscr{V}(t)$ are disjoint.
2. Compute $\langle s \wedge t, \emptyset\rangle \stackrel{*}{\rightsquigarrow}\langle u, \Phi\rangle$ until $u$
becomes $\wedge$-free.
3. Output a term pattern $u$ end.

Since there exist several possibilities for applying the rule Gen, two input term patterns $s$ and $t$ may have more than one generalization. For example, $\mathrm{p}(u, u)$ and $\mathrm{q}(\mathrm{h}, v)$ are generalizations of $\mathrm{f}(\mathrm{a}, x)$ and $\mathrm{g}(y, y)$. We note that for a given coupled term pattern the number of possible combinations of $C_{1}$ and $C_{2}$ in the rule Gen is finite, because of the condition (4) of Gen.

Lemma 7.9. The procedure 2nd-Gen is well-defined.

Proof. It suffices to show that if $\Phi$ is a memorizing function and $\langle s, \Phi\rangle \rightsquigarrow\left\langle s^{\prime}, \Phi^{\prime}\right\rangle$ then $\Phi^{\prime}$ is again a memorizing function. We distinguish cases by the inference rule applied in the step $\langle s, \Phi\rangle \rightsquigarrow\left\langle s^{\prime}, \Phi^{\prime}\right\rangle$.
(Var) The case $x \wedge y \mapsto z \in \Phi$ is obvious. Suppose $x \wedge y \mapsto z \notin \Phi$. Then $\Phi^{\prime}=\Phi \cup\{x \wedge y \mapsto z\}$, $x \notin \operatorname{range}\left(\Phi_{[1]}^{-1}\right), y \notin \operatorname{range}\left(\Phi_{[2]}^{-1}\right)$, and $z$ is a fresh local variable. Clearly, $\Phi^{\prime}$ is a partial mapping from $\left\{C_{1} \wedge C_{2} \mid C_{1}, C_{2} \in \mathrm{~T}^{\square}(\mathscr{F} \cup \mathscr{X})\right\} \cup\{x \wedge y \mid x, y \in \mathscr{V}\}$ to $\mathscr{X} \cup \mathscr{V}$. The conditions (1),(2),(4) are clearly satisfied. The condition (3) follows since $x \notin \operatorname{range}\left(\Phi_{[1]}^{-1}\right)$ and $y \notin \operatorname{range}\left(\Phi_{[2]}^{-1}\right)$.
(Div) Since $\Phi^{\prime}=\Phi$, the claim follows immediately.
(Gen) The case $C_{1} \wedge C_{2} \mapsto p \in \Phi$ is obvious. So, suppose $C_{1} \wedge C_{2} \mapsto p \notin \Phi$. By $C_{1}, C_{2} \in$ $\mathrm{T}^{\square}(\mathscr{F} \cup \mathscr{X}), \Phi^{\prime}$ is a partial mapping $\left\{C_{1} \wedge C_{2} \mid C_{1}, C_{2} \in \mathrm{~T}^{\square}(\mathscr{F} \cup \mathscr{X})\right\} \cup\{x \wedge y \mid x, y \in \mathscr{V}\}$ to $\mathscr{X} \cup \mathscr{V}$. It is easy to check the conditions (1),(2),(3),(4) are satisfied.

Example 7.10. We present some examples of the derivation of 2nd-Gen. Recall that the symbol $\wedge$ cancels the substitution $\theta$, that is, $\theta(s \wedge t)=s \wedge t$.

1. $\langle f(x, x, x) \wedge g(y, y), \emptyset\rangle \rightsquigarrow_{G e n}\left\langle p(x \wedge y, x, x \wedge y),\left\{f\left(\square_{1}, \square_{2}, \square_{3}\right) \wedge g\left(\square_{1}, \square_{3}\right) \mapsto p\right\}\right\rangle \rightsquigarrow_{\text {Var }}$ $\left\langle p(z, z, x \wedge y),\left\{f\left(\square_{1}, \square_{2}, \square_{3}\right) \wedge g\left(\square_{1}, \square_{3}\right) \mapsto p, x \wedge y \mapsto z\right\}\right\rangle \rightsquigarrow \operatorname{Var}\left\langle p(z, z, z),\left\{f\left(\square_{1}, \square_{2}, \square_{3}\right) \wedge\right.\right.$ $\left.\left.g\left(\square_{1}, \square_{3}\right) \mapsto p, x \wedge y \mapsto z\right\}\right\rangle$.
2. $\langle f(x, h(x)) \wedge f(y, g(y)), \emptyset\rangle \rightsquigarrow_{\text {Div }}\langle f(x \wedge y, h(x) \wedge g(y)), \emptyset\rangle \rightsquigarrow \operatorname{Var}\langle f(z, h(x) \wedge g(y)),\{x \wedge y \mapsto$ $z\}\rangle \rightsquigarrow \operatorname{Gen}\left\langle f(z, q(x \wedge y)),\left\{x \wedge y \mapsto z, h\left(\square_{1}\right) \wedge g\left(\square_{1}\right) \mapsto q\right\}\right\rangle \rightsquigarrow \operatorname{Var}\langle f(z, q(z)),\{x \wedge y \mapsto$ $\left.\left.z, h\left(\square_{1}\right) \wedge g\left(\square_{1}\right) \mapsto q\right\}\right\rangle$.

We next show that the procedure 2nd-Gen eventually terminates for any input, by using the following measure.

Definition 7.11. For $t \in \mathrm{~T} \wedge(\mathscr{F} \cup \mathscr{X}, \mathscr{V})$, the weight $w(t)$ of a coupled term pattern $t$ is a multiset of natural numbers defined as follows:

$$
w(t)= \begin{cases}{[]^{[ }} & \text {if } t \in \mathrm{~T}(\mathscr{F} \cup \mathscr{X}, \mathscr{V}) \\ \bigsqcup_{i=1}^{n} w\left(s_{i}\right) & \text { if } t=p\left(s_{1}, \ldots, s_{n}\right) \\ {\left[\left|s_{1}\right|+\left|s_{2}\right|\right]} & \text { if } t=s_{1} \wedge s_{2}\end{cases}
$$

where $|s|$ denotes the number of symbol occurrences.
Theorem 7.12. The procedure $\mathbf{2 n d}$-Gen terminates for any input.
Proof. It suffices to show $\rightsquigarrow$ is well-founded. Thus, we prove that $\langle s, \Phi\rangle \rightsquigarrow\left\langle s^{\prime}, \Phi^{\prime}\right\rangle$ implies $w(s) \gg w\left(s^{\prime}\right)$ where $\gg$ is the multiset extension of $>[1]$. We distinguish cases by the inference rule applied in the step $\langle s, \Phi\rangle \rightsquigarrow\left\langle s^{\prime}, \Phi^{\prime}\right\rangle$.
(Var) One occurrence of $x \wedge y$ is replaced by $z$, and thus $w(s)=w\left(s^{\prime}\right) \sqcup[2]$. Hence $w(s) \gg w\left(s^{\prime}\right)$.
(Div) One occurrence of $p\left(s_{1}, \ldots, s_{n}\right) \wedge p\left(t_{1}, \ldots, t_{n}\right)$ is replaced by $p\left(s_{1} \wedge t_{1}, \ldots, s_{n} \wedge t_{n}\right)$. Since $\left|p\left(s_{1}, \ldots, s_{n}\right) \wedge p\left(t_{1}, \ldots, t_{n}\right)\right|=\left|s_{1}\right|+\cdots+\left|s_{n}\right|+\left|t_{1}\right|+\cdots+\left|t_{n}\right|+2$ and $\left[\left|s_{1} \wedge t_{1}\right|, \ldots,\left|s_{n} \wedge t_{n}\right|\right]=$ $\left[\left|s_{1}\right|+\left|t_{1}\right|, \ldots,\left|s_{n}\right|+\left|t_{n}\right|\right]$, we have $w(s) \gg w\left(s^{\prime}\right)$.
(Gen) In this case, we have $w\left(p\left(\alpha_{1}, \ldots, \alpha_{n}\right)\right)=\left[\left|s_{i}\right|+\left|t_{i}\right| \mid \square_{i} \in \mathscr{H}\left(C_{1}\right) \cap \mathscr{H}\left(C_{2}\right)\right]$ and $w\left(C_{1}\left\langle s_{1}, \ldots, s_{n}\right\rangle \wedge C_{2}\left\langle t_{1}, \ldots, t_{n}\right\rangle\right)=\left[\left|C_{1}\left\langle s_{1}, \ldots, s_{n}\right\rangle\right|+\left|C_{2}\left\langle t_{1}, \ldots, t_{n}\right\rangle\right|\right]$. Since $\square_{i} \in \mathscr{H}\left(C_{1}\right) \cap$ $\mathscr{H}\left(C_{2}\right)$ implies $s_{i} \unlhd C_{1}\left\langle s_{1}, \ldots, s_{n}\right\rangle$ and $t_{i} \unlhd C_{2}\left\langle t_{1}, \ldots, t_{n}\right\rangle,\left|C_{1}\left\langle s_{1}, \ldots, s_{n}\right\rangle\right|+\left|C_{2}\left\langle t_{1}, \ldots, t_{n}\right\rangle\right| \geq$ $\left|s_{i}\right|+\left|t_{i}\right|$ for $i$ such that $\square_{i} \in \mathscr{H}\left(C_{1}\right) \cap \mathscr{H}\left(C_{2}\right)$. Thus the case $s_{i} \neq C_{1}\left\langle s_{1}, \ldots, s_{n}\right\rangle$ or $t_{i} \neq C_{2}\left\langle t_{1}, \ldots, t_{n}\right\rangle$ follows clearly. If $s_{i}=C_{1}\left\langle s_{1}, \ldots, s_{n}\right\rangle$ and $t_{i}=C_{2}\left\langle t_{1}, \ldots, t_{n}\right\rangle$ then $C_{1}=\square_{1}=C_{2}$, thus this case does not happen by the condition of the inference rule.

Now we show the soundness of the procedure 2 nd-Gen, that is, every output of 2 nd-Gen is a generalization of two input term patterns. The following lemma is shown easily.

Lemma 7.13. For any indexed context $C$ such that $\square_{i} \notin \mathscr{H}(C)$ and any term patterns $s_{1}, \ldots, s_{n}, t_{i}, C\left\langle s_{1}, \ldots, s_{i}, \ldots, s_{n}\right\rangle=C\left\langle s_{1}, \ldots, t_{i}, \ldots, s_{n}\right\rangle$.

We now prove the main lemma for the soundness theorem.
Lemma 7.14. Let $\langle s, \Phi\rangle \rightsquigarrow\left\langle s^{\prime}, \Phi^{\prime}\right\rangle$. Let $\mathscr{V}_{1}$ and $\mathscr{V}_{2}$ be disjoint sets of local variables. Suppose that, for $i \in\{1,2\}$, (1) $\mathscr{V}\left(\Phi_{[i]}^{-1}\left(\pi_{i}(s)\right)\right) \subseteq \mathscr{V}_{i}$ and (2) for any $\wedge$-top subterm $u_{1} \wedge u_{2}$ of $s$, $\mathscr{V}\left(u_{i}\right) \subseteq \mathscr{V}_{i}$. Then, for each $i \in\{1,2\}, \Phi_{[i]}^{-1}\left(\pi_{i}(s)\right)=\Phi_{[i]}^{\prime-1}\left(\pi_{i}\left(s^{\prime}\right)\right)$. Also, conditions (1) and (2) hold for $\Phi^{\prime}$ and $s^{\prime}$.

Proof. We distinguish cases by the inference rule applied in the step $\langle s, \Phi\rangle \rightsquigarrow\left\langle s^{\prime}, \Phi^{\prime}\right\rangle$. We show only $\Phi_{[1]}^{-1}\left(\pi_{1}(s)\right)=\Phi_{[1]}^{\prime-1}\left(\pi_{1}\left(s^{\prime}\right)\right)$ in each case. The case $i=2$ is shown similarly.
(Var) We have $s=C[x \wedge y], s^{\prime}=C[z] \theta$ where $\theta=\{x:=z, y:=z\}$ is a substitution, and $\Phi^{\prime}=\Phi \cup\{x \wedge y \mapsto z\}$ for some $C, x, y$. Then

$$
\begin{aligned}
& \Phi_{[1]}^{-1}\left(\pi_{1}(s)\right) \\
& =\Phi_{[1]}^{-1}\left(\pi_{1}(C[x \wedge y])\right) \\
& =\Phi_{[1]}^{-1}\left(\pi_{1}(C)[x]\right) \quad \text { by Lemma } 7.6(3) \\
& =\left(\Phi_{[1]}^{-1}\left(\pi_{1}(C)\right)\right)\left[\Phi_{[1]}^{-1}(x), \ldots, \Phi_{[1]}^{-1}(x)\right] \\
& =\left(\Phi_{[1]}^{-1}\left(\pi_{1}(C\{y:=z\})\right)\right)[\ldots] \text { by } y \in \mathscr{V}_{2} \\
& =\left(\Phi_{[1]}^{-1} \cup\{z \mapsto x\}\left(\pi_{1}(C \theta)\right)\right)[\ldots] \\
& =\left(\Phi_{[1]}^{\prime-1}\left(\pi_{1}(C \theta)\right)\right)\left[\Phi_{[1]}^{-1}(x), \ldots, \Phi_{[1]}^{-1}(x)\right] \\
& =\left(\Phi_{[1]}^{\prime-1}\left(\pi_{1}(C \theta)\right)\right)\left[\Phi_{[1]}^{-1} \cup\{z \mapsto x\}(z), \ldots\right] \\
& =\left(\Phi_{[1]}^{\prime-1}\left(\pi_{1}(C \theta)\right)\right)\left[\Phi_{[1]}^{\prime-1}(z), \ldots, \Phi_{[1]}^{\prime-1}(z)\right] \\
& =\Phi_{[1]}^{\prime-1}\left(\pi_{1}(C \theta[z])\right) \\
& =\Phi_{[1]}^{\prime-1}\left(\pi_{1}(C[z] \theta)\right) \\
& =\Phi_{[1]}^{\prime-1}\left(\pi_{1}\left(s^{\prime}\right)\right)
\end{aligned}
$$

Clearly, conditions (1),(2) hold for $\Phi^{\prime}$ and $s^{\prime}$.
(Div) We have $s=C\left[p\left(s_{1}, \ldots, s_{n}\right) \wedge p\left(t_{1}, \ldots, t_{n}\right)\right]$ and $s^{\prime}=C\left[p\left(s_{1} \wedge t_{1}, \ldots, s_{n} \wedge t_{n}\right)\right]$ for some
$C, p, s_{1}, \ldots, t_{n}$ and $\Phi=\Phi^{\prime}$. Then

$$
\begin{aligned}
& \Phi_{[1]}^{-1}\left(\pi_{1}(s)\right) \\
& =\Phi_{[1]}^{-1}\left(\pi _ { 1 } \left(C \left[p\left(s_{1}, \ldots, s_{n}\right)\right.\right.\right. \\
& \left.\left.\left.\wedge p\left(t_{1}, \ldots, t_{n}\right)\right]\right)\right) \\
& \left.=\Phi_{[1]}^{-1}\left(\pi_{1}\left(C\left[p\left(s_{1}, \ldots, s_{n}\right)\right)\right]\right)\right) \\
& \quad \text { by Lemma } 7.6(3) \\
& =\Phi_{[1]}^{-1}\left(\pi_{1}\left(C\left[p\left(s_{1} \wedge t_{1}, \ldots, s_{n} \wedge t_{n}\right)\right]\right)\right)
\end{aligned}
$$

by applying Lemma 7.6 (3) repeatedly

$$
=\Phi_{[1]}^{-1}\left(\pi_{1}\left(s^{\prime}\right)\right)
$$

$$
=\Phi_{[1]}^{\prime-1}\left(\pi_{1}\left(s^{\prime}\right)\right)
$$

Clearly, conditions (1),(2) hold for $\Phi^{\prime}$ and $s^{\prime}$.
(Gen) We have $s=C\left[C_{1}\left\langle s_{1}, \ldots, s_{n}\right\rangle \wedge C_{2}\left\langle t_{1}, \ldots, t_{n}\right\rangle\right], s^{\prime}=C\left[p\left(\alpha_{1}, \ldots, \alpha_{n}\right)\right], \Phi^{\prime}=\Phi \cup\left\{C_{1} \wedge\right.$ $\left.C_{2} \mapsto p\right\}$ for some $C, C_{1}, C_{2}, p, s_{1}, \ldots, t_{n}$. Then

$$
\begin{aligned}
& \Phi_{[1]}^{-1}\left(\pi_{1}(s)\right) \\
& =\Phi_{[1]}^{-1}\left(\pi _ { 1 } \left(C \left[C_{1}\left\langle s_{1}, \ldots, s_{n}\right\rangle\right.\right.\right. \\
& \left.\left.\left.\wedge C_{2}\left\langle t_{1}, \ldots, t_{n}\right\rangle\right]\right)\right) \\
& =\Phi_{[1]}^{-1}\left(\pi_{1}\left(C\left[C_{1}\left\langle s_{1}, \ldots, s_{n}\right\rangle\right]\right)\right) \\
& \text { by Lemma } 7.6(3) \\
& =\pi_{1}\left(\Phi_{[1]}^{-1}\left(C\left[C_{1}\left\langle s_{1}, \ldots, s_{n}\right\rangle\right]\right)\right) \\
& \text { by Lemma } 7.6(2) \\
& =\pi_{1}\left(\Phi _ { [ 1 ] } ^ { - 1 } ( C ) \left[\Phi_{[1]}^{-1}\left(C_{1}\left\langle s_{1}, \ldots, s_{n}\right\rangle\right),\right.\right. \\
& \left.\left.\ldots \Phi_{[1]}^{-1}\left(C_{1}\left\langle s_{1}, \ldots, s_{n}\right\rangle\right)\right]\right) \\
& =\pi_{1}\left(\Phi _ { [ 1 ] } ^ { - 1 } ( C ) \left[C_{1}\left\langle s_{1}, \ldots, s_{n}\right\rangle\right.\right. \\
& \left.\left.\ldots C_{1}\left\langle s_{1}, \ldots, s_{n}\right\rangle\right]\right)
\end{aligned}
$$

since variables in $\operatorname{dom}\left(\Phi_{[1]}^{-1}\right)$ are fresh. We now show that $\left.\pi_{1}\left(C_{1}\left\langle\ldots s_{i} \ldots\right\rangle\right)=\pi_{1}\left(C_{1}\left\langle\ldots \Phi_{[1]}^{\prime-1}\left(\alpha_{i}\right) \ldots\right\rangle\right)\right)$ holds for any $i$. We distinguish three cases.
(a) Case of $\square_{i} \in \mathscr{H}\left(C_{1}\right) \cap \mathscr{H}\left(C_{2}\right)$. Then

$$
\begin{aligned}
& \pi_{1}\left(C_{1}\left\langle\ldots s_{i} \ldots\right\rangle\right) \\
= & \pi_{1}\left(C_{1}\left\langle\ldots s_{i} \wedge t_{i} \ldots\right\rangle\right) \\
= & \pi_{1}\left(C_{1}\left\langle\ldots \Phi_{[1]}^{\prime-1}\left(s_{i} \wedge t_{i}\right) \ldots\right\rangle\right) \\
= & \pi_{1}\left(C_{1}\left\langle\ldots \Phi_{[1]}^{\prime-1}\left(\alpha_{i}\right) \ldots\right\rangle\right)
\end{aligned}
$$

(b) Case of $\square_{i} \in \mathscr{H}\left(C_{1}\right) \backslash \mathscr{H}\left(C_{2}\right)$.

$$
\begin{aligned}
& \pi_{1}\left(C_{1}\left\langle\ldots s_{i} \ldots\right\rangle\right) \\
&= \pi_{1}\left(C_{1}\left\langle\ldots \Phi_{[1]}^{\prime-1}\left(\Phi_{[1]}\left(s_{i}\right)\right) \ldots\right\rangle\right) \\
& \text { by Lemma } 7.8 \\
&= \pi_{1}\left(C_{1}\left\langle\ldots \Phi_{[1]}^{\prime-1}\left(\alpha_{i}\right) \ldots\right\rangle\right)
\end{aligned}
$$

(c) Case of $\square_{i} \in \mathscr{H}\left(C_{2}\right) \backslash \mathscr{H}\left(C_{1}\right)$. Then since $\square_{i} \notin \mathscr{H}\left(C_{1}\right)$, by Lemma $7.13, \pi_{1}\left(C_{1}\left\langle\ldots s_{i} \ldots\right\rangle\right)=$ $\pi_{1}\left(C_{1}\left\langle\ldots \Phi_{[1]}^{\prime-1}\left(\alpha_{i}\right) \ldots\right\rangle\right)$.

Hence

$$
\begin{gathered}
\pi_{1}\left(\Phi _ { [ 1 ] } ^ { - 1 } ( C ) \left[C_{1}\left\langle s_{1}, \ldots, s_{n}\right\rangle\right.\right. \\
\left.\left.\ldots C_{1}\left\langle s_{1}, \ldots, s_{n}\right\rangle\right]\right) \\
=\pi_{1}\left(\Phi _ { [ 1 ] } ^ { \prime - 1 } ( C ) \left[C_{1}\left\langle\Phi_{[1]}^{\prime-1}\left(\alpha_{1}\right), \ldots,\right\rangle\right.\right. \\
\left.\left.\quad \ldots C_{1}\left\langle\Phi_{[1]}^{\prime-1}\left(\alpha_{1}\right), \ldots,\right\rangle\right]\right) \\
=\pi_{1}\left(\Phi _ { [ 1 ] } ^ { \prime - 1 } ( C ) \left[\Phi_{[1]}^{\prime-1}\left(p\left(\alpha_{1}, \ldots, \alpha_{n}\right)\right)\right.\right. \\
\left.\left.\quad \ldots \Phi_{[1]}^{\prime-1}\left(p\left(\alpha_{1}, \ldots, \alpha_{n}\right)\right)\right]\right) \\
=\pi_{1}\left(\Phi_{[1]}^{\prime-1}\left(C\left[p\left(\alpha_{1}, \ldots, \alpha_{n}\right)\right]\right)\right) \\
=\Phi_{[1]}^{\prime-1}\left(\pi_{1}\left(C\left[p\left(\alpha_{1}, \ldots, \alpha_{n}\right)\right]\right)\right) \\
=\Phi_{[1]}^{\prime-1}\left(\pi_{1}\left(s^{\prime}\right)\right) \quad \text { by Lemma } 7.6(2)
\end{gathered}
$$

Clearly, conditions (1),(2) hold for $\Phi^{\prime}$ and $s^{\prime}$.

Now we have the following soundness theorem of 2 nd-Gen.
Theorem 7.15. Suppose $\langle s \wedge t, \emptyset\rangle \stackrel{*}{\rightsquigarrow}\langle u, \Phi\rangle$ and $\mathscr{V}(s) \cap \mathscr{V}(t)=\emptyset$. If $u$ is $\wedge$-free then $u$ is a generalization of $s$ and $t$. Moreover, $\Phi_{[1]}^{-1}(u)=s$ and $\Phi_{[2]}^{-1}(u)=t$.

Proof. By the assumption $\mathscr{V}(s) \cap \mathscr{V}(t)=\emptyset$, we can apply Lemma 7.14 repeatedly so to obtain $\Phi_{[1]}^{-1}\left(\pi_{1}(u)\right)=s$ and $\Phi_{[2]}^{-1}\left(\pi_{2}(u)\right)=t$. Since $u$ is $\wedge$-free, $\pi_{1}(u)=\pi_{2}(u)=u$ by Lemma 7.6 (1). Thus $\Phi_{[1]}^{-1}(u)=s$ and $\Phi_{[2]}^{-1}(u)=t$. This means that $u$ is a generalization of $s$ and $t$.

### 7.2 Generalization of TRSs

In this section, we give the TRS generalization procedure TRS-Gen based on the term generalization procedure 2nd-Gen given in the previous section. We also present heuristics to drop solutions of generalization useless for constructing transformation patterns.

TRS-Gen generalizes two TRSs with an input memorizing function by generalizing each rewrite rule in sequence. A rewrite rule is treated as a term pattern whose root symbol is $\rightarrow$ in TRS-Gen. A memorizing function which is an input of TRS-Gen is used to keep consistent with the preceding generalizations.

Definition 7.16. Let $\mathcal{R}_{1}=\left\{l_{1} \rightarrow r_{1}, \ldots, l_{n} \rightarrow r_{n}\right\}$ and $\mathcal{R}_{2}=\left\{l_{1}^{\prime} \rightarrow r_{1}^{\prime}, \ldots, l_{n}^{\prime} \rightarrow r_{n}^{\prime}\right\}$ be TRS patterns over $\mathscr{F}$ and $\rightarrow$ a special binary function symbol such that $\rightarrow \notin \mathscr{F}$. The TRS generalization procedure TRS-Gen is given as follows:
Input: TRS patterns $\mathcal{R}_{1}$ and $\mathcal{R}_{2}$ and
a memorizing function $\Phi$.
begin

1. Rename local variables so that sets of local variables of each rewrite rule in $\mathcal{R}_{1}$ and $\mathcal{R}_{2}$ are mutually disjoint.
2. $\Phi_{0}=\Phi$
3. $\operatorname{For}(i=0$ to $i=n)$
begin
Compute $\tilde{l}_{i} \rightarrow \tilde{r}_{i}$ where
$\left\langle\rightarrow\left(l_{i} \wedge l_{i}^{\prime}, r_{i} \wedge r_{i}^{\prime}\right), \Phi_{i-1}\right\rangle \stackrel{*}{\rightsquigarrow}\left\langle\rightarrow\left(\tilde{l}_{i}, \tilde{r}_{i}\right), \Phi_{i}\right\rangle$
using 2nd-Gen.
end
4. Output $\tilde{\mathcal{R}}=\left\{\tilde{l}_{1} \rightarrow \tilde{r}_{1}, \ldots, \tilde{l}_{n} \rightarrow \tilde{r}_{n}\right\}$
and $\Phi_{n}$.
end
The following is a corollary of Theorem 7.15.
Theorem 7.17. Let $\tilde{\mathcal{R}}$ and $\tilde{\Phi}$ be outputs of $\operatorname{TRS}$-Gen whose inputs are $\mathcal{R}_{1}, \mathcal{R}_{2}$ and $\Phi . \tilde{\mathcal{R}}$ is a generalization of $\mathcal{R}_{1}$ and $\mathcal{R}_{2}$. More precisely, $\Phi_{[1]}^{-1}(\tilde{\mathcal{R}})=\mathcal{R}_{1}, \Phi_{[2]}^{-1}(\tilde{\mathcal{R}})=\mathcal{R}_{2}$ (up to renaming local variables) and $\Phi \subseteq \tilde{\Phi}$.

We have implemented 2nd-Gen and TRS-Gen using modules of program transformation system RAPT and performed experiments. It turned out that our algorithms tend to produce many solutions which are obviously useless to make transformation patterns. For example, the number of solutions of a generalization of $\operatorname{sum}(\operatorname{cons}(x, x s))$ and $\operatorname{cat}(\operatorname{cons}(y, y s))$ is over 1,000 . Furthermore, it contains many solutions such as $\mathrm{p}(\operatorname{sum}(\operatorname{cons}(x, x s))$, $\operatorname{cat}(\operatorname{cons}(y, y s)))$ which are obviously useless for transformation patterns.

Even if many solutions of generalization are obtained, they have to be enriched into correct templates by adding appropriate hypotheses in order to use for program transformation. Since such enrichment is not always possible, it is preferred that obviously useless solutions are omitted beforehand. Below, we report several heuristics which work well in our experiment.

We first introduce two notions that are necessary for describing our heuristics. A notion of I-match is useful to reduce possibilities of application of Gen.
Definition 7.18. Let $C \in \mathrm{~T}_{n}^{\square}(\mathscr{F} \cup \mathscr{X})$ be an indexed context, and $t \in \mathrm{~T}(\mathscr{F} \cup \mathscr{X}, \mathscr{V})$ a term pattern. We say $C$ I-matches to $t$ if there exist term patterns $s_{1}, \ldots, s_{n}$ such that $C\left\langle s_{1}, \ldots s_{n}\right\rangle=$ $t$.

We note that the notion of I-match is a variant of the first-order matching, which is decidable and has a unique solution up to renaming local variables.

Definition 7.19. (1) The set of positions of a term $s$ is a set $\operatorname{Pos}(s)$ of sequences of integers, which is inductively defined as follows: (i) If $s=x \in \mathscr{V}$, then $\operatorname{Pos}(s)=\{\epsilon\}$ where $\epsilon$ represents empty sequence; (ii) If $s=q\left(s_{1}, \ldots, s_{n}\right)$, then $\operatorname{Pos}(s)=\{\epsilon\} \cup \bigcup_{i=1}^{n}\left\{i p \mid p \in \operatorname{Pos}\left(s_{i}\right)\right\}$. (2) Let $s$ be a term pattern. A position $p$ of $s$ is shallower than a position $q$ of $s$ if $|p| \leq|q|$. The position $p$ is the shallowest and leftmost in $t$ if (i) $p$ is the shallowest in $t$; (ii) for any shallowest position $q$ such that $q \neq p$, there exist $p^{\prime}, i, j, q_{1}$, and $q_{2}$ such that $p=p^{\prime} i q_{1}, q=p^{\prime} j q_{2}$ and $i<j$.

Our heuristics are as follows:
H1 Gen is applied only when neither Var nor Div can be applied.
H2 For a coupled term pattern $s$ and memorizing function $\Phi$, we chose the shallowest and leftmost $\wedge$-top subterm to apply 2nd-Gen.
H3 When $\left\langle C\left[C_{1}\left\langle s_{1}, \ldots, s_{n}\right\rangle \wedge C_{2}\left\langle t_{1}, \ldots, t_{n}\right\rangle\right], \Phi\right\rangle \rightsquigarrow\left\langle C\left[p\left(\alpha_{1}, \ldots, \alpha_{n}\right)\right], \Phi^{\prime}\right\rangle$ applying Gen, we restrict that the depth of each indexed context $C_{1}$ and $C_{2}$ is equal to or less than 1 .

H4 For $\langle C[s \wedge t]$, $\Phi\rangle$, we choose $C_{1}$ and $C_{2}$ to apply Gen if there exists $C_{1} \wedge C_{2} \mapsto p \in \Phi$ such that $C_{1} \mathrm{I}$-matches to $s$ and $C_{2} \mathrm{I}$-matches to $t$.

H5 When H4 cannot be applied to $\langle C[s \wedge t], \Phi\rangle$, we choose $C_{1}$ and $C_{2}$ to apply Gen, if there exist $C_{1}, s_{1}, \ldots, s_{n}, C_{2}, t_{1}, \ldots, t_{n}, k$, and $C_{1}^{\prime} \wedge C_{2}^{\prime} \mapsto p \in \Phi$ such that $s=C_{1}\left\langle s_{1}, \ldots, s_{n}\right\rangle$, $t=C_{2}\left\langle t_{1}, \ldots, t_{n}\right\rangle$, and $\square_{k} \in \mathscr{H}\left(C_{1}\right) \cap \mathscr{H}\left(C_{2}\right)$, and $C_{1}^{\prime}$ and $C_{2}^{\prime}$ I-match $s_{k}$ and $t_{k}$, respectively.

H6 When H4 and H5 cannot apply to $\langle C[s \wedge t]$, $\Phi\rangle$, we choose arbitrary indexed contexts satisfying H3 to apply Gen.

Gen can be applied even when Var or Div can be done. One can obtain more concrete generalizations by giving higher priority to Var and Div than Gen. Here, we say a term pattern $s$ is more concrete than a term pattern $t$ if there exists a term homomorphism $\varphi$ such that $\varphi(t)=s$. For example, let $x, y$ be local variables. Without heuristics, Var and Gen can be applied to a pair $\langle x \wedge y, \emptyset\rangle$. If Var is applied then the pair $\langle z,\{x \wedge y \mapsto z\}\rangle$ is obtained. If Gen is applied then the pair $\left\langle p(x, y),\left\{\square_{1} \wedge \square_{2} \mapsto p\right\}\right\rangle$ is obtained. The former is more concrete than the latter.

By H3, the number of possibilities of application for Gen is reduced drastically. For example, there are 225 possibilities for applying Gen to $\langle+(\mathrm{s}(x), y) \wedge \operatorname{app}(\operatorname{cons}(z, z s), w s), \Phi\rangle$ without our heuristics while 81 possibilities for applying Gen with heuristic H3 according to our experiment. In our experiments, heuristic H3 seems to work well. However, there may exist transformations which the depth defined in H3 should be increased.

Intuitively, H4 and H5 force to generalize common patterns by the same pattern variables. In our experiments, one can obtain more concrete generalizations with helps of H4 and H5. For example, pars of generalizations of $\mathrm{f}(\mathrm{f}(x))$ and $\mathrm{g}(\mathrm{g}(y))$ are $\mathrm{p}(\mathrm{q}(v))$ and $\mathrm{p}(\mathrm{p}(v))$. The latter is more concrete than the former and produced using H4 and H5.

Below we demonstrate one of the derivations following our heuristics (Fig. 7.3).
Step (a): We choose the shallowest and leftmost $\wedge$-top subterm $+(\mathbf{s}(x), y) \wedge \operatorname{app}(\operatorname{cons}(z, z s), w s)$ to apply 2nd-Gen by H2. Var, Div, H4 and H5 cannot apply to this subterm. So, we choose $C_{1}=+\left(\square_{1}, \square_{2}\right)$ and $C_{2}=\operatorname{app}\left(\square_{1}, \square_{2}\right)$ to apply Gen to this subterm. As mentioned before, there are 81 possibilities of applying Gen to this subterm.

Step (b): The shallowest and leftmost $\wedge$-top subterm is $\mathbf{s}(+(x, y)) \wedge \operatorname{cons}(z, \operatorname{app}(z s, w s))$. Since $+\left(\square_{1}, \square_{2}\right)$ I-matches to $+(x, y)$ and app $\left(\square_{1}, \square_{2}\right)$ I-matches to $\operatorname{app}(z s, w s)$, we choose $C_{1}=\mathrm{s}\left(\square_{1}\right)$ and $C_{2}=\operatorname{cons}\left(\square_{2}, \square_{1}\right)$ to apply Gen to this subterm by $\mathbf{H 5}$.

Step (c): The shallowest and leftmost $\wedge$-top subterm is $\mathbf{s}(x) \wedge$ cons $(z, z s)$. Since $\mathbf{s}\left(\square_{1}\right)$ I-matches to $\mathrm{s}(x)$ and $\operatorname{cons}\left(\square_{2}, \square_{1}\right)$ I-matches to cons $(z, z s)$, we choose $C_{1}=\mathrm{s}\left(\square_{1}\right)$ and $C_{2}=$ cons $\left(\square_{2}, \square_{1}\right)$ to apply Gen to this subterm by $\mathbf{H} 4$.

Step (d): We apply $\mathbf{H 2}$ and $\mathbf{H 4}$ as the step (c).
Step (e): The shallowest and leftmost $\wedge$-top subterm is $x \wedge z s$. We apply Var to this subterm by H1.

Steps (f), (g), and (h): We apply Var in the way similar to the step (e).
Example 7.20. Let $\mathcal{R}_{\text {sum }}$ and $\mathcal{R}_{\text {cat }}$ be TRSs which appear in Chapter 3. The following $T R S$ pattern $\tilde{\mathcal{P}}$ is one of outputs of our implementation with heuristics whose inputs are $\mathcal{R}_{\text {sum }}, \mathcal{R}_{\text {cat }}$ and $\emptyset$ :

$$
\tilde{\mathcal{P}} \begin{cases}\mathrm{p}(\mathrm{r}) & \rightarrow \mathrm{q} \\ \mathrm{p}(\mathrm{p} 2(u, v)) & \rightarrow \mathrm{p} 1(u, \mathrm{p}(v)) \\ \mathrm{p} 1\left(\mathrm{q}, v_{1}\right) & \rightarrow \\ \mathrm{p} 1\left(\mathrm{p} 3\left(v_{7}, v_{4}\right), v_{8}\right) & \rightarrow \mathrm{p} 3\left(\mathrm{p} 1\left(v_{7}, v_{8}\right), v_{4}\right)\end{cases}
$$

The TRS pattern $\tilde{\mathcal{P}}$ above is a generalization of $\mathcal{R}_{\text {sum }}$ and $\mathcal{R}_{\text {cat }}$.

### 7.3 Generalization of transformations

In this section, we discuss how to construct transformation templates using our generalization algorithm.

A pair $\left\langle\mathcal{R}, \mathcal{R}^{\prime}\right\rangle$ of TRSs is called a TRS transformation. We usually write the TRS transformation $\left\langle\mathcal{R}, \mathcal{R}^{\prime}\right\rangle$ as $\mathcal{R} \Rightarrow \mathcal{R}^{\prime}$. A transformation pattern $\mathcal{P} \Rightarrow \mathcal{P}^{\prime}$ is a generalization of TRS transformations $\mathcal{R}_{1} \Rightarrow \mathcal{R}_{1}^{\prime}$ and $\mathcal{R}_{2} \Rightarrow \mathcal{R}_{2}^{\prime}$ if there exist term homomorphisms $\varphi_{1}, \varphi_{2}$ such that $\varphi_{i}(\mathcal{P})=\mathcal{R}_{i}$ and $\varphi_{i}\left(\mathcal{P}^{\prime}\right)=\mathcal{R}_{i}^{\prime}(i=1,2)$ up to renaming local variables.

Definition 7.21. Let $\mathcal{R}_{1} \Rightarrow \mathcal{R}_{1}^{\prime}$ and $\mathcal{R}_{2} \Rightarrow \mathcal{R}_{2}^{\prime}$ be TRS transformations where $\left|\mathcal{R}_{1}\right|=\left|\mathcal{R}_{2}\right|$, $\left|\mathcal{R}_{1}^{\prime}\right|=\left|\mathcal{R}_{2}^{\prime}\right|$. Here, $|\mathcal{R}|$ denotes the number of rewrite rules appearing in $\mathcal{R}$. The procedure Trans-Gen is given as follows:
Input: $\mathcal{R}_{1} \Rightarrow \mathcal{R}_{1}^{\prime}$ and $\mathcal{R}_{2} \Rightarrow \mathcal{R}_{2}^{\prime}$
begin

1. Compute $\mathcal{P}$ and $\Phi$ by applying

TRS-Gen to $\mathcal{R}_{1}, \mathcal{R}_{2}$ and $\emptyset$.
2. Compute $\mathcal{P}^{\prime}$ and $\Phi^{\prime}$ by applying

TRS-Gen to $\mathcal{R}_{1}^{\prime}, \mathcal{R}_{2}^{\prime}$ and $\Phi$.
3. Output $\mathcal{P} \Rightarrow \mathcal{P}^{\prime}$.
end
The following is a corollary of Theorem 7.17.
Theorem 7.22. Let $\mathcal{R}_{1} \Rightarrow \mathcal{R}_{1}^{\prime}$ and $\mathcal{R}_{2} \Rightarrow \mathcal{R}_{2}^{\prime}$ be $T R S$ transformations, and $\mathcal{P} \Rightarrow \mathcal{P}^{\prime}$ an output of Trans-Gen whose inputs are $\mathcal{R}_{1} \Rightarrow \mathcal{R}_{1}^{\prime}$ and $\mathcal{R}_{2} \Rightarrow \mathcal{R}_{2}^{\prime}$. Then $\mathcal{P} \Rightarrow \mathcal{P}^{\prime}$ is a generalization of $\mathcal{R}_{1} \Rightarrow \mathcal{R}_{1}^{\prime}$ and $\mathcal{R}_{2} \Rightarrow \mathcal{R}_{2}^{\prime}$.

Example 7.23. Applying Trans-Gen to $\mathcal{R}_{\text {sum }} \Rightarrow \mathcal{R}_{\text {sum }}^{\prime}$ and $\mathcal{R}_{\text {cat }} \Rightarrow \mathcal{R}_{\text {cat }}^{\prime}$ which appear in Section 1 , the transformation pattern $\tilde{\mathcal{P}} \Rightarrow \tilde{\mathcal{P}}^{\prime}$ is produced where

$$
\tilde{\mathcal{P}}^{\prime} \begin{cases}\mathrm{p}\left(v_{11}\right) & \rightarrow \mathrm{p} 4\left(v_{11}, \mathrm{q}\right) \\ \mathrm{p} 4\left(\mathrm{r}, v_{14}\right) & \rightarrow v_{14} \\ \mathrm{p} 4\left(\mathrm{p} 2\left(v_{23}, v_{21}\right), v_{22}\right) & \rightarrow \\ \multicolumn{1}{c}{\mathrm{p} 4\left(v_{21},\right.} & \left.\mathrm{p} 1\left(v_{22}, v_{23}\right)\right) \\ \mathrm{p} 1\left(\mathrm{q}, v_{26}\right) \quad & \rightarrow v_{26} \\ \mathrm{p} 1\left(\mathrm{p} 3\left(v_{32}, v_{29}\right), v_{33}\right) & \rightarrow \\ r \mathrm{p} 3\left(\mathrm{p} 1\left(v_{32}, v_{33}\right), v_{29}\right)\end{cases}
$$

and $\tilde{\mathcal{P}}$ is the TRS pattern which appears in Example 7.20. We note that there exists little difference between $\mathcal{P} \Rightarrow \mathcal{P}^{\prime}$ which appears in Section 1 and $\tilde{\mathcal{P}} \Rightarrow \tilde{\mathcal{P}}^{\prime}$. But both of them is a generalization of $\mathcal{R}_{\text {sum }} \Rightarrow \mathcal{R}_{\text {sum }}^{\prime}$ and $\mathcal{R}_{\text {cat }} \Rightarrow \mathcal{R}_{\text {cat }}^{\prime}$.

To verify the correctness of transformations automatically, correct templates have to be constructed. One has to look for an appropriate hypothesis to construct a correct template from transformation patterns generated by Trans-Gen.

Example 7.24. Let $\tilde{\mathcal{P}} \Rightarrow \tilde{\mathcal{P}}^{\prime}$ be the transformation pattern appearing in Example 7.23 and $\tilde{\mathcal{H}}$ the following hypothesis.

$$
\tilde{\mathcal{H}} \begin{cases}\mathrm{p} 1(\mathrm{q}, y) & \approx \mathrm{p} 1(y, \mathrm{q}) \\ \mathrm{p} 1(x, \mathrm{p} 1(y, z)) & \approx \mathrm{p} 1(\mathrm{p} 1(x, y), z)\end{cases}
$$

It can be shown that the template $\left\langle\tilde{\mathcal{P}}, \tilde{\mathcal{P}}^{\prime}, \tilde{\mathcal{H}}\right\rangle$ is correct.
Let us consider another example of generalization.

Example 7.25. The following $T R S$ transformations $\mathcal{R}_{\text {onesadd }} \Rightarrow \mathcal{R}_{\text {onesadd }}^{\prime}$ and $\mathcal{R}_{\text {lenapp }} \Rightarrow$ $\mathcal{R}_{\text {lenapp }}^{\prime}$ represent the well-known program transformation called fusion transformation.

$$
\begin{aligned}
& \mathcal{R}_{\text {onesadd }} \begin{cases}\operatorname{onesadd}(x, y) & \rightarrow \text { ones }(+(x, y)) \\
\operatorname{ones}(0) & \rightarrow \text { nil } \\
\operatorname{ones}(\mathbf{s}(x)) & \rightarrow \\
& \operatorname{cons}(\mathrm{s}(0), \text { ones }(x)) \\
+(0, x) & \rightarrow x \\
+(\mathrm{s}(x), y) & \rightarrow \mathrm{s}(+(x, y))\end{cases} \\
& \mathcal{R}_{\text {onesadd }}^{\prime} \begin{cases}\operatorname{onesadd}(0, u) & \rightarrow \text { ones }(u) \\
\text { onesadd }(\mathbf{s}(v), w) & \rightarrow \\
\operatorname{cons}(\mathbf{s}(0), & \text { onesadd }(v, w)) \\
\operatorname{ones}(0) & \rightarrow \text { nil } \\
\operatorname{ones}(\mathbf{s}(v)) & \rightarrow \\
& \operatorname{cons}(\mathbf{s}(0), \text { ones }(v)) \\
+(0, u) & \rightarrow u \\
+(\mathrm{s}(v), w) & \rightarrow \mathbf{s}(+(v, w))\end{cases} \\
& \mathcal{R}_{\text {lenapp }} \begin{cases}\operatorname{lenapp}(x, y) & \rightarrow \operatorname{len}(\operatorname{app}(x, y)) \\
\operatorname{len}(\operatorname{nil}) & \rightarrow 0 \\
\operatorname{len}(\operatorname{cons}(x, y)) & \rightarrow \mathbf{s}(\operatorname{len}(y)) \\
\operatorname{app}(\operatorname{nil}, y) & \rightarrow y \\
\operatorname{app}(\operatorname{cons}(x, y), z) \rightarrow \\
& \operatorname{cons}(x, \operatorname{app}(y, z))\end{cases} \\
& \mathcal{R}_{\text {lenapp }}^{\prime} \begin{cases}\operatorname{lenapp}(\operatorname{nil}, u) & \rightarrow \operatorname{len}(u) \\
\operatorname{lenapp}(\operatorname{cons}(u, v), w) & \rightarrow \\
& \quad \mathrm{s}(\operatorname{lenapp}(v, w)) \\
\operatorname{len}(\operatorname{nil}) \quad & \rightarrow 0 \\
\operatorname{len}(\operatorname{cons}(u, v)) & \rightarrow \mathbf{s}(\operatorname{len}(v)) \\
\operatorname{app}(\operatorname{nil}, u) & \rightarrow u \\
\operatorname{app}(\operatorname{cons}(u, v), w) & \rightarrow \\
r \operatorname{cons}(u, & \operatorname{app}(v, w))\end{cases}
\end{aligned}
$$

Applying Trans-Gen to $\mathcal{R}_{\text {onesadd }} \Rightarrow \mathcal{R}_{\text {onesadd }}^{\prime}$ and $\mathcal{R}_{\text {lenapp }} \Rightarrow \mathcal{R}_{\text {lenapp }}^{\prime}$, the transformation pattern $\mathcal{P}_{1} \Rightarrow \mathcal{P}_{1}^{\prime}$ is obtained where

$$
\begin{aligned}
& \mathcal{P}_{1} \begin{cases}\mathrm{p}(v, w) & \rightarrow \mathrm{q}(\mathrm{r}(v, w)) \\
\mathrm{q}(\mathrm{p} 2) & \rightarrow \mathrm{p} 1 \\
\mathrm{q}\left(\mathrm{p} 4\left(v_{3}, v_{1}\right)\right) & \rightarrow \mathrm{p} 3\left(\mathrm{~s}(0), \mathrm{q}\left(v_{3}\right)\right) \\
\mathrm{r}\left(\mathrm{p} 2, v_{6}\right) & \rightarrow v_{6} \\
\mathrm{r}\left(\mathrm{p} 4\left(v_{12}, v_{9}\right), v_{13}\right) & \rightarrow \mathrm{p} 4\left(\mathrm{r}\left(v_{12}, v_{13}\right), v_{9}\right)\end{cases} \\
& \mathcal{P}_{1}^{\prime} \begin{cases}\mathrm{p}\left(\mathrm{p} 2, v_{16}\right) & \rightarrow \mathrm{q}\left(v_{16}\right) \\
\mathrm{p}\left(\mathrm{p} 4\left(v_{22}, v_{19}\right), v_{23}\right) & \rightarrow \\
\mathrm{q}(\mathrm{p} 2) & \mathrm{p} 3\left(\mathrm{~s}(0), \mathrm{p}\left(v_{22}, v_{23}\right)\right) \\
\mathrm{q}\left(\mathrm{p} 4\left(v_{27}, v_{25}\right)\right) & \rightarrow \mathrm{p} 1 \\
\mathrm{r}\left(\mathrm{p} 2, v_{30}\right) & \rightarrow \mathrm{p} 3\left(\mathrm{~s}(0), \mathrm{q}\left(v_{27}\right)\right) \\
\mathrm{r}\left(\mathrm{p} 4\left(v_{36}, v_{33}\right), v_{37}\right) & \rightarrow \mathrm{p} 4\left(\mathrm{r}\left(v_{36}, v_{37}\right), v_{33}\right)\end{cases}
\end{aligned}
$$

Note that the transformation pattern which is obtained from $\mathcal{R}_{\text {onesadd }} \Rightarrow \mathcal{R}_{\text {onesadd }}^{\prime}$ or $\mathcal{R}_{\text {lenapp }} \Rightarrow$ $\mathcal{R}_{\text {lenapp }}^{\prime}$ by replacing function symbols with fresh pattern variables cannot be used as transformation pattern for the other TRS.
Example 7.26. The TRS $\mathcal{R}_{\text {doubleadd }}$ is transformed to $\mathcal{R}_{\text {doubleadd }}{ }^{\prime}$ by the transformation pattern $\mathcal{P}_{1} \Rightarrow \mathcal{P}_{1}^{\prime}$ where

$$
\begin{aligned}
& \mathcal{R}_{\text {doubleadd }} \begin{cases}\text { doubleadd }(x, y) & \rightarrow \\
& \text { double }(+(x, y)) \\
\text { double }(0) & \rightarrow 0 \\
\text { double }(\mathrm{s}(x)) & \rightarrow \\
& \mathrm{s}(\mathrm{~s}(\text { double }(x))) \\
+(0, x) & \rightarrow x \\
+(\mathrm{s}(x), y) & \rightarrow \mathbf{s}(+(x, y))\end{cases} \\
& \mathcal{R}_{\text {doubleadd }}^{\prime}\left\{\right.
\end{aligned}
$$

Example 7.27. The $T R S \mathcal{R}_{\text {el }}$ is transformed to $\mathcal{R}_{\text {el }}^{\prime}$ by the transformation pattern $\mathcal{P}_{1} \Rightarrow \mathcal{P}_{1}^{\prime}$ where

$$
\begin{aligned}
& \mathcal{R}_{e l} \begin{cases}\text { evenlenapp }(x, y) & \rightarrow \text { evenlen }(\operatorname{app}(x, y)) \\
\text { evenlen }(\text { nil }) & \rightarrow \text { true } \\
\text { evenlen }(\operatorname{cons}(x, y)) & \rightarrow \text { not }(\text { evenlen }(y)) \\
\operatorname{app}(\text { nil }, x) & \rightarrow x \\
\operatorname{app}(\operatorname{cons}(x, y), z) & \rightarrow \text { cons }(x, \operatorname{app}(y, z)) \\
\text { not }(\text { true }) & \rightarrow \text { false } \\
\text { not }(\text { false }) & \rightarrow \text { true }\end{cases} \\
& \begin{cases}\text { evenlenapp(nil, } \left.v_{16}\right) & \overrightarrow{\text { evenlen }\left(v_{16}\right)} \\
\text { evenlenapp(cons }\left(v_{19},\right. & \left.\left.v_{22}\right), v_{23}\right) \rightarrow\end{cases} \\
& \text { evenlenapp }\left(\operatorname{cons}\left(v_{19}, v_{22}\right), v_{23}\right) \rightarrow \\
& \operatorname{not}\left(\text { evenlenapp }\left(v_{22}, v_{23}\right)\right)
\end{aligned}
$$

As mentioned before, templates have to be correct to verify the correctness of transformations automatically. In this example, it can be shown that the template $\left\langle\mathcal{P}_{1}, \mathcal{P}_{1}^{\prime}, \emptyset\right\rangle$ is a correct template.

We now note about the implementation of our generalization algorithm. In our implementation, TRS transformations which are input of our algorithm are represented by pairs of two TRSs. The implementation of our generalization algorithm produces all solutions obtained under the heuristics $\mathbf{H 1} \sim \mathbf{H 6}$. Each output of our generalization algorithm is enumerated sequentially using the lazy evaluation technique.

### 7.4 Summary

In this chapter, we gave the term generalization algorithm 2nd-Gen which generalizes two input terms. The soundness of $\mathbf{2 n d}-\mathrm{Gen}$ was shown in Theorem 7.15. We then extended 2nd-Gen to the TRS generalization algorithm TRS-Gen which generalizes two input TRSs. Implementations of 2 nd-Gen and TRS-Gen showed that they produce huge number of solutions which includes many unexpected ones. We reported some heuristics ( $\mathbf{H} \mathbf{1} \sim \mathbf{H 6})$ which reduce numbers of solutions. Trans-Gen, which generalizes two input transformations was given by extending TRS-Gen. We also gave examples of transformation templates produced by Trans-Gen. We checked through experiments that heuristics $\mathbf{H 1} \sim \mathbf{H 6}$ help to construct correct templates.

Table 7.1: Example of generalization

| step | coupled term | memorizing function |
| :---: | :---: | :---: |
| 1 |  |  |
| 2 (by II) |  |  |
| 3 (by III) |  | $\mathrm{g}\left(\square_{1}\right) \wedge \square_{1} \quad \mapsto \mathrm{p}$ |
| 4 (by I) |  | $\begin{array}{lll} \hline \mathrm{g}\left(\square_{1}\right) \wedge \square_{1} & \mapsto & \mathrm{p} \\ x \wedge z & \mapsto & v_{1} \end{array}$ |
| 5 (by III) |  | $\begin{array}{lll} \mathrm{g}\left(\square_{1}\right) \wedge \square_{1} & \mapsto & \mathrm{p} \\ x \wedge z & \mapsto & v_{1} \\ \square & & \end{array}$ |
| 6 (by I) |  | $\begin{array}{lll} \mathrm{g}\left(\square_{1}\right) \wedge \square_{1} & \mapsto & \mathrm{p} \\ x \wedge z & \mapsto & v_{1} \\ \square_{1} \wedge \mathrm{~h}\left(\square_{2}, \square_{1}\right) & \mapsto & \mathrm{q} \\ y \wedge w & \mapsto & v_{2} \end{array}$ |

$$
\langle\rightarrow(+(\mathrm{s}(x), y) \wedge \operatorname{app}(\operatorname{cons}(z, z s), w s), \mathrm{s}(+(x, y))) \wedge \operatorname{cons}(z, \operatorname{app}(z s, w s)),\{ \}\rangle
$$

$(a) \rightsquigarrow\langle\rightarrow(\mathrm{p}(\mathrm{s}(x) \wedge \operatorname{cons}(z, z s), y \wedge w s), \mathrm{s}(+(x, y)) \wedge \operatorname{cons}(z, \operatorname{app}(z s, w s)))$, $\left.\left\{+\left(\square_{1}, \square_{2}\right) \wedge \operatorname{app}\left(\square_{1}, \square_{2}\right) \mapsto \mathrm{p}\right\}\right\rangle$
(by H2)
$(b) \rightsquigarrow\langle\rightarrow(\mathrm{p}(\mathrm{s}(x) \wedge \operatorname{cons}(z, z s), y \wedge w s), \mathrm{q}(+(x, y) \wedge \operatorname{app}(z s, w s), z))$,

$$
\left.\left\{\begin{array}{ll}
+\left(\square_{1}, \square_{2}\right) \wedge \operatorname{app}\left(\square_{1}, \square_{2}\right) & \mapsto \mathrm{p} \\
\mathrm{~s}\left(\square_{1}\right) \wedge \operatorname{cons}\left(\square_{2}, \square_{1}\right) & \mapsto \mathrm{q}
\end{array}\right\}\right\rangle
$$

(by H2 and $\mathbf{H 5}$ )
$(c) \rightsquigarrow\langle\rightarrow(\mathrm{p}(\mathrm{q}(x \wedge z s, z), y \wedge w s), \mathrm{q}(+(x, y) \wedge \operatorname{app}(z s, w s), z))$,
$\left.\left\{\begin{array}{ll}+\left(\square_{1}, \square_{2}\right) \wedge \operatorname{app}\left(\square_{1}, \square_{2}\right) & \mapsto \mathrm{p} \\ \mathrm{s}\left(\square_{1}\right) \wedge \operatorname{cons}\left(\square_{2}, \square_{1}\right) & \mapsto \mathrm{q}\end{array}\right\}\right\rangle$
(by $\mathbf{H 2}$ and $\mathbf{H 4}$ )
$\begin{aligned}(d) \rightsquigarrow & \langle\rightarrow(\mathrm{p}(\mathrm{q}(x \wedge z s, z), y \wedge w s), \mathrm{q}(\mathrm{p}(x \wedge z s, y \wedge w s), z)), \\ & \left.\left\{\begin{array}{l}+\left(\square_{1}, \square_{2}\right) \wedge \operatorname{app}\left(\square_{1}, \square_{2}\right) \mapsto \mathrm{p}\end{array}\right\}\right\rangle\end{aligned}$
$\left.\left\{\begin{array}{ll}+\left(\square_{1}, \square_{2}\right) \wedge \operatorname{app}\left(\square_{1}, \square_{2}\right) & \mapsto \mathrm{p} \\ \mathrm{s}\left(\square_{1}\right) \wedge \operatorname{cons}\left(\square_{2}, \square_{1}\right) & \mapsto \mathrm{q}\end{array}\right\}\right\rangle$
(by $\mathbf{H 2}$ and $\mathbf{H 4}$ )
$(e) \rightsquigarrow\left\langle\rightarrow\left(\mathrm{p}\left(\mathrm{q}\left(u_{1}, z\right), y \wedge w s\right), \mathrm{q}(\mathrm{p}(x \wedge z s, y \wedge w s), z)\right)\right.$,
$\left.\left\{\begin{array}{ll}+\left(\square_{1}, \square_{2}\right) \wedge \operatorname{app}\left(\square_{1}, \square_{2}\right) & \mapsto \mathrm{p} \\ \mathrm{s}\left(\square_{1}\right) \wedge \operatorname{cons}\left(\square_{2}, \square_{1}\right) & \mapsto \mathrm{q} \\ x \wedge z s \mapsto u_{1}\end{array}\right\}\right\rangle$
(by H1 and H2)

$$
\begin{aligned}
(f) \rightsquigarrow & \left\langle\rightarrow\left(\mathrm{p}\left(\mathrm{q}\left(u_{1}, z\right), u_{2}\right), \mathrm{q}(\mathrm{p}(x \wedge z s, y \wedge w s), z)\right),\right. \\
& \left.\left\{\begin{array}{l}
+\left(\square_{1}, \square_{2}\right) \wedge \operatorname{app}\left(\square_{1}, \square_{2}\right) \mapsto \mathrm{p} \\
\mathrm{~s}\left(\square_{1}\right) \wedge \operatorname{cons}\left(\square_{2}, \square_{1}\right) \\
x \wedge z s \mapsto u_{1} \quad y \wedge w s \mapsto u_{2}
\end{array}\right\}\right\rangle
\end{aligned}
$$

(by $\mathbf{H 1}$ and $\mathbf{H 2}$ )
$(g) \rightsquigarrow\left\langle\rightarrow\left(\mathrm{p}\left(\mathrm{q}\left(u_{1}, z\right), u_{2}\right), \mathrm{q}\left(\mathrm{p}\left(u_{1}, y \wedge w s\right), z\right)\right)\right.$,
$\left.\left\{\begin{array}{l}+\left(\square_{1}, \square_{2}\right) \wedge \operatorname{app}\left(\square_{1}, \square_{2}\right) \mapsto \mathrm{p} \\ \mathrm{s}\left(\square_{1}\right) \wedge \operatorname{cons}\left(\square_{2}, \square_{1}\right) \\ x \wedge z s \mapsto u_{1} \quad y \wedge w s \mapsto u_{2}\end{array}\right\}\right\rangle$
(by $\mathbf{H 1}$ and $\mathbf{H 2}$ )

$$
\left.\left.\begin{array}{rl}
(h) \rightsquigarrow & \langle\rightarrow \\
& \left\{\mathrm{p}\left(\mathrm{q}\left(u_{1}, z\right), u_{2}\right), \mathrm{q}\left(\mathrm{p}\left(u_{1}, u_{2}\right), z\right)\right), \\
+\left(\square_{1}, \square_{2}\right) \wedge \operatorname{app}\left(\square_{1}, \square_{2}\right) \mapsto \mathrm{p} \\
\mathrm{~s}\left(\square_{1}\right) \wedge \operatorname{cons}\left(\square_{2}, \square_{1}\right) \mapsto \mathrm{q} \\
x \wedge z s \mapsto u_{1} \quad y \wedge w s \mapsto u_{2}
\end{array}\right\}\right\rangle
$$

(by $\mathbf{H 1}$ and $\mathbf{H 2}$ )

Figure 7.3: Example of 2nd-Gen with heuristics

## Chapter 8

## Conclusion

In this thesis, we proposed a new framework of program transformation by templates based on term rewriting. Contributions of this thesis are listed as follows:

1. Introducing the notion of correct templates and giving sufficient conditions which guarantee the correctness of transformations by correct templates.
2. Proposing 2nd-order pattern matching algorithm Match and show its soundness and completeness.
3. Implementing our framework as RAPT and checking its operation through examples.
4. Proposing 2nd-order generalization algorithm 2nd-Gen and showing its soundness.

To guarantee the correctness of transformation within our framework, we introduced a notion of correct templates which are constructed via the step-by-step transformations of TRS patterns. We then showed that in any transformation of programs using the correct templates the correctness of transformation could be verified automatically.

We gave a sound and complete term pattern matching algorithm and showed that how our program transformation is automated using this algorithm. We now compare our framework for the program transformation and those based on lambda calculus $[6,8,9,11,12,22]$.

There is no significant difference between the second-order matching algorithm by Huet and Lang [12] and ours. However, we preferred organizing the matching algorithm in the rewriting framework to encoding it based on the lambda calculus framework. Yokoyama et al. proposed a simpler and efficient matching algorithm for deterministic second-order pattern[27]. By incorporating their ideas to our framework, more efficient and useful algorithm may be found.

For the correctness proof of the transformation, the most significant difference between our approach and and those by Huet and Lang is that our approach is based on the operational semantics while Huet and Lang's one is on the denotational semantics. The basis of our correctness verification method is inductionless induction in which the Church-Rosser property and the sufficient completeness of rewriting systems play essential roles. Contrasted to this, Huet and Lang's approach is based on the fixpoint induction.

We also described the RAPT system, which implements our framework. RAPT transforms a term rewriting system according to a specified program transformation template and automatically verifies the correctness of the transformation. Examples of the correct transformation templates and their application to the transformation of program were also given.

Another implementation of program transformation using templates is the MAG system, which is based on lambda calculus [8, 22]. The correctness of transformation in MAG system is based on Huet and Lang's framework [12]. MAG supports transformations that include modifications of expressions and matching with the help of hypothesis; its target also includes higher-order programs. RAPT does not handle such refinements, and cannot deal with most of the transformations presented by de Moor and Sittampalam [7, 22]. The difference between MAG and RAPT, on the other hand, lies in the approach to verifying the hypothesis. Since such hypotheses are generally different in each transformation, one needs to verify them in all transformations. MAG system users usually need to verify the hypothesis by explicit induction in every different transformation. In contrast to this, RAPT proves the hypothesis automatically without needing the help of users. To the best of our knowledge, the program-transformation systems based on templates described in the literature have rarely cooperated with automated theorem-proving techniques in the verification of hypotheses. RAPT involves an interesting integration of program-transformation and automated theorem-proving techniques.

We have proposed a 2 nd-order generalization procedure 2nd-Gen for term patterns and show its correctness. Based on this procedure, we have given a procedure to construct transformation templates from similar TRS transformations. By using some heuristics, we have constructed correct templates that are suitable for TRS transformations and correctness checking of transformations.

Plotkin proposed a first-order generalization algorithm[20]. The first-order generalization is simulated by treating local variables as fresh constant and permitting pattern variables instantiated only term patterns (i.e. indexed contexts without holes). Therefore, our framework is an extension of first-order generalization. To the best of our knowledge, there is no result of generalization which is specialized for program transformation.

The notion of program transformation by templates was originally introduced by Huet and Lang[12]. They showed the method to construct transformation templates manually. After their work, several results about program transformation by templates have been obtained[6, 8, 27]. In these works, no automated method to construct transformation templates has been proposed.

## Bibliography

[1] F. Baader and T. Nipkow. Term rewriting and all that. Cambridge University Press, 1998.
[2] A. Bundy. The automation of proof by mathematical induction. In Handbook of Automated Reasoning, chapter 13, pages 845-911. Elsevier and MIT Press, 2001.
[3] R.M. Burstall and J. Darlington. A transformation system for developing recursive programs. Journal of the ACM, 24(1):44-67, 1977.
[4] H. Comon. Inductionless induction. In Handbook of Automated Reasoning, chapter 14, pages 913-962. Elsevier and MIT Press, 2001.
[5] H. Comon, M. Dauchet, R. Gilleron, F. Jacquemard, D. Lugiez, S. Tison, and M. Tommasi. Tree automata techniques and applications. 1997. http://www.grappa.univ-lille3.fr/ tata.
[6] R. Curien, Z. Qian, and H. Shi. Efficient second-order matching. In Proceedings of the 7th International Conference on Rewriting Techniques and Applications, volume 1103 of $L N C S$, pages 317-331. Springer-Verlag, 1996.
[7] O. de Moor and G. Sittampalam. Generic program transformation. In Proceedings of the 3rd International Summer School on Advanced Functional Programming, volume 1608 of $L N C S$, pages 116-149. Springer-Verlag, 1999.
[8] O. de Moor and G. Sittampalam. Higher-order matching for program transformation. Theoretical Computer Science, 269:135-162, 2001.
[9] K. Hirata, K. Yamada, and M. Harao. Tractable and intractable second-order matching problems. Journal of Symbolic Computation, 37(5):611-628, 2004.
[10] N. Hirokawa and A. Middeldorp. Tsukuba termination tool. In Proceedings of the 14 th International Conference on Rewriting Techniques and Applications, volume 2706 of LNCS, pages 311-320. Springer-Verlag, 2003.
[11] G. Huet. A unification algorithm for typed $\lambda$-calculus. Theoretical Computer Science, 1:27-57, 1975.
[12] G. Huet and B. Lang. Proving and applying program transformations expressed with second order patterns. Acta Informatica, 11:31-55, 1978.
[13] D. Kapur, P. Narendran, and H. Zhang. On sufficient-completeness and related properties of term rewriting systems. Acta Informatica, 24(4):395-415, 1987.
[14] D. E. Knuth and P. B. Bendix. Simple word problems in universal algebra. In J. Leech, editor, Computational problems in abstract algebra, pages 263-297. Pergamon Press, 1970.
[15] A. Lazrek, P. Lescanne, and J. J. Thiel. Tools for proving inductive equalities, relative completeness, and $\omega$-completeness. Information and Computation, 84:47-70, 1990.
[16] M. H. A. Newman. On theories with a combinatorial definition of 'equivalence'. Annals of Mathematics, 43(2):223-243, 1942.
[17] T. Nipkow and G. Weikum. A decidability result about sufficient-completeness of axiomatically specified abstract data types. In Proceedings of the 6th GI-Conference on Theoretical Computer Science, volume 145 of $L N C S$, pages 257-268. Springer-Verlag, 1983.
[18] R. Paige. Future directions in program transformations. ACM Computing Surveys, 28(4es):170, 1996.
[19] H. Partsch and R. Steinbrüggen. Program transformation systems. ACM Computing Surveys, 15(3):199-236, 1983.
[20] G. D. Plotkin. A note on inductive generalization. In Machine Intelligence, volume 5, chapter 8, pages 153-163. Edinbrgh University Press, 1969.
[21] U. S. Reddy. Term rewriting induction. In Proceedings of the 10th International Conference on Automated Deduction, volume 449 of LNAI, pages 162-177, 1990.
[22] G. Sittampalam. Higher-order matching for program transformation. PhD thesis, Magdalen College, 2001.
[23] Terese. Term rewriting systems. Cambridge University Press, 2003.
[24] Y. Toyama. Commutativity of term rewriting systems. In The Second France-Japan Artificial Intelligence and Computer Science Symposium, 1987.
[25] Y. Toyama. How to prove equivalence of term rewriting systems without induction. Theoretical Computer Science, 90:369-390, 1991.
[26] P. Wadler. Deforestation: transforming programs to eliminate trees. Theoretical Computer Science, 73:231-248, 1990.
[27] T. Yokoyama, Z. Hu, and M. Takeichi. Deterministic second-order patterns. Information Processing Letters, 89(6):309-314, 2004.

## Publications

[i] Yuki Chiba, Takahito Aoto and Yoshihito Toyama, Automatic Construction of Program Transformation Templates, IPSJ Transactions on Programming, Vol.49, No.SIG 1 (PRO 35), pp.14-27, 2008.
[ii] Keiichirou Kusakari, and Yuki Chiba,
A Higher-Order Knuth-Bendix Procedure and its Applications,
IEICE Transactions on Information and Systems, Vol.E90-D, No.4, pp.707-715, Apr 2007.
[iii] Yuki Chiba, Takahito Aoto and Yoshihito Toyama,
Program Transformation by Templates: A Rewriting Framework, IPSJ Transactions on Programming, Vol.47, No.SIG 16 (PRO 31), pp.52-65, 2006.
[iv] Yuki Chiba and Takahito Aoto,
RAPT: A Program Transformation System based on Term Rewriting,
In Proceedings of the 17th International Conference on Rewriting Techniques and Applications (RTA 2006), Seattle, WA, USA, Lecture Notes in Computer Science, Vol.4098, Springer-Verlag, pp.267-276, 2006.
[v] Yuki Chiba, Takahito Aoto and Yoshihito Toyama,
Introducing Sequence Variables in Program Transformation based on Templates, In Proceedings of the Forum on Information Technology 2005 (FIT2005), Information Technology Letters, Vol.4, pp.5-8, 2005 (in japanese).
[vi] Yuki Chiba, Takahito Aoto and Yoshihito Toyama, Program Transformation by Templates based on Term Rewriting, In Proceedings of the 7th ACM-SIGPLAN International Symposium on Principles and Practice of Declarative Programming (PPDP 2005), ACP Press, pp.59-69, 2005.

