



**3D INTRINSIC SCENE CHARACTERISTICS  
EXTRACTION FRAMEWORK  
FOR A SINGLE IMAGE**

**HABIBULLAH AKBAR**

**DOCTOR OF PHILOSOPHY**

**2016**

**HABIBULLAH AKBAR**

**DOCTOR OF PHILOSOPHY**

**2016**



**Faculty of Information and Communication Technology**

**3D INTRINSIC SCENE CHARACTERISTICS EXTRACTION  
FRAMEWORK FOR A SINGLE IMAGE**

**Habibullah Akbar**

**Doctor of Philosophy**

**2016**

**3D INTRINSIC SCENE CHARACTERISTICS EXTRACTION FRAMEWORK  
FOR A SINGLE IMAGE**

**HABIBULLAH AKBAR**

**A thesis submitted  
in fulfillment of the requirements for the degree of Doctor of Philosophy**

**Faculty of Information and Communication Technology**

**UNIVERSITI TEKNIKAL MALAYSIA MELAKA**

**2016**

## DECLARATION

I declare that this thesis entitled “3D Intrinsic Scene Characteristics Extraction Framework for a Single Image” is the result of my own research except as cited in the references. The thesis has not been accepted for any degree and is not concurrently submitted in candidature of any other degree.

Signature :

Name : Habibullah Akbar

Date :

## **APPROVAL**

I hereby declare that I have read this thesis and, in my opinion, this thesis is sufficient in terms of scope and quality for the award of Doctor of Philosophy.

Signature :

Supervisor Name : Prof. Dr. Nanna Suryana Herman

Date :

## **DEDICATION**

To my beloved mother, father, wife, daughter and sons

## ABSTRACT

Three-Dimensional (3D) shape reconstruction is an important area of computer vision research because it has numerous potential applications from entertainment production to industrial inspection and clinical analysis. Existing 3D Intrinsic Scene Characteristics (3D-ISCs) extraction methods for a single image have focused solely on estimating diffuse characteristics, i.e. 3D shape, illumination, and reflectance models, of an object. As a result, they have neglected the specular characteristic, the shiny areas of a glossy surface. In reality, many real-world objects emit both specular and diffuse reflections, and thus the specular component may decrease the performance of the 3D-ISCs methods. This study has developed a framework to extract all of these characteristics. The framework combines a Specular Removal (SR) method and a Shape, Illumination, and Reflectance From Shading (SIRFS) method under a Bidirectional Reflectance Distribution Function (BRDF) model. Since the previous SR methods suffered from hue-saturation ambiguity, they are not suitable for this framework. To solve this problem, two SR methods were developed, evaluated, and compared with the standard SR methods. The proposed SR methods are referred as Chaotic Segmentation (CS) and Sparse Coding (SC) methods. To combine the SR and SIRFS methods, two BRDF models were also developed, evaluated, and compared. These models are referred as Modified Dichromatic Reflectance (MDR) and Modified Blinn-Phong (MBP) models. The performances of the proposed SR methods and the BRDF models for extracting 3D-ISCs were evaluated based on public datasets. The results showed that the SC method was more satisfactory compared to the CS and the benchmark method (iterative method). The accuracies of the diffuse and specular characteristics were improved by 7.6% and 53.5% respectively. Moreover, the combination of SC method and MDR model was capable of outperforming the SIRFS method. The computational speed was 19.2% faster. Meanwhile, the average accuracies of depth, surface normal, illumination, shading, and reflectance were improved by 11.4%, 6.5%, 50.5%, 35.2%, and 5.1% respectively. This study indicates that the specular reflection is an important aspect of 3D reconstruction from a single image. The proposed framework has also made considerable improvements in terms of accuracy and computational time of extracting 3D-ISCs.



## ABSTRAK

*Pembinaan semula bentuk Tiga-Dimensi (3D) merupakan bidang penting dalam penyelidikan visi komputer kerana ia mempunyai banyak aplikasi yang berpotensi daripada pengeluaran hiburan kepada pemeriksaan industri dan analisis klinikal. Kewujudan kaedah-kaedah pengekstrakan Ciri-ciri Paparan Instrinsik 3D (CPI-3D) untuk imej tunggal hanya tertumpu kepada ciri-ciri peresapan seperti model bentuk 3D, pencahayaan dan pembalikan sesuatu objek. Kaedah-kaedah ini mengabaikan ciri spekulat (kawasan permukaan objek yang berkilat). Dalam keadaan realiti, kebanyakan objek sebenar memancarkan kedua-dua pantulan spekulat dan peresapan, dan ini menjadikan komponen spekulat mungkin mengurangkan prestasi kaedah CPI-3D. Kajian ini telah membangunkan kerangka kerja untuk mengekstrak CPI-3D. Kerangka kerja ini menggunakan kaedah Penyingkiran Spekulat (PS) dan kaedah Bentuk, Pencahayaan serta Kepantulan dari Pembayangan (BPKP) di bawah model Fungsi Taburan Kepantulan Dwiarah (FTKD). Oleh kerana kaedah-kaedah PS sebelum ini mengalami kesamaran ketepatan warna, ia tidak sesuai untuk kerangka kerja ini. Bagi menyelesaikan masalah tersebut, dua kaedah PS telah dibangunkan, dinilai dan dibandingkan dengan kaedah standard PS. Kedua-duanya merujuk kepada Pensegmenan Camuk (PC) dan Pengkodan Bersela (PB). Bagi menggabungkan kaedah PS dan BPKP, dua model FTKD telah dibangunkan, dinilai dan dibandingkan. Kedua-duanya merujuk kepada Pengubahsuaian Kepantulan Dikromatik (PKD) dan Pengubahsuaian Blinn-Phong (PBP). Prestasi kaedah PS dan model FTKD yang dicadangkan untuk mengekstrak CPI-3D telah dinilai berdasarkan kepada set data awam. Keputusan menunjukkan kaedah PB lebih memuaskan berbanding PC dan kaedah penanda aras (kaedah lalaran). Ketepatan peresapan dan specular telah meningkat masing-masing sebanyak 7.3% dan 53.5%. Gabungan kaedah PB dan model PKD mampu menyaingi kaedah BPKP. Kelajuan pengiraan telah meningkat sebanyak 19.2% manakala ketepatan purata kedalaman, permukaan normal, pencahayaan, pembayangan serta kepantulan telah meningkat masing-masing sebanyak 11.4%, 6.5%, 50.5%, 35.2% dan 5.1%. Kajian ini menandakan bahawa kerangka kerja pengekstrakan CPI-3D cadangan telah menunjukkan kemajuan besar dari segi ketepatan dan masa pengiraan.*

## ACKNOWLEDGEMENTS

*In the name of Allah, The Most Gracious and The Most Merciful.* I wish to express my sincerest appreciation and gratitude to Prof. Dr. Nanna Suryana Herman for his valuable advice, patience, and support during my Ph.D. journey at Universiti Teknikal Malaysia Melaka. With his vision and guidance, this thesis may never have been completed on time. My deepest appreciation also to Prof. Datuk Dr. Shahrin Sahib for his help in developing motivation, ideas, and for willingly sharing his expertise and in-depth knowledge. I appreciate their available time for solid discussion despite their tight schedule. I wish to thank all my fellow postgraduate students for their discussions, support, and friendship. I also thank the staff, lecturers, and technicians in the Faculty of Information and Communication Technology for their help, cooperation, and encouragement. My deepest appreciation also to my parents, Tasman Abbas and Djasminar Anwar, for their prayer, love, and care. I pray their efforts will be rewarded by Allah in this world and the hereafter. I would like to thank my brother, Abdullah Denovan, and my sister, Nila Novari. I would also like to thank my wife (Nancy Kuspriyati), my daughter (Aisyah Syarafana), and my sons (Izdihar Zidan and Ashraf Ruwai fi) for their love, support, and patience. This work was supported by Universiti Teknikal Malaysia Melaka under Zamalah Scheme.

	<b>TABLE OF CONTENTS</b>	<b>PAGE</b>
<b>DECLARATION</b>		
<b>APPROVAL</b>		
<b>DEDICATION</b>		
<b>ABSTRACT</b>		<b>i</b>
<b>ABSTRAK</b>		<b>ii</b>
<b>ACKNOWLEDGEMENTS</b>		<b>iii</b>
<b>TABLE OF CONTENTS</b>		<b>iii</b>
<b>LIST OF TABLES</b>		<b>v</b>
<b>LIST OF FIGURES</b>		<b>vi</b>
<b>LIST OF ABBREVIATIONS</b>		<b>vii</b>
<b>LIST OF SYMBOLS</b>		<b>ix</b>
<b>LIST OF PUBLICATIONS</b>		<b>xi</b>
<b>CHAPTER</b>		<b>1</b>
<b>1 INTRODUCTION</b>		<b>1</b>
1.1 Research Background		1
1.2 Problem Statement		6
1.3 Research Questions		7
1.4 Research Objectives		8
1.5 Research Scope		9
1.6 Thesis Structure		9
<b>2 LITERATURE REVIEW</b>		<b>12</b>
2.1 Overview		12
2.2 Bidirectional Reflectance Distribution Function (BRDF)		12
2.2.1 Lambertian Model		15
2.2.2 Oren-Nayar Model		16
2.2.3 Phong Model		17
2.2.4 Blinn-Phong Model		19
2.2.5 Dichromatic Reflectance Model (DRM)		20
2.3 Shape From Shading (SFS)		21
2.3.1 Analytical Approach		26
2.3.2 Approximation Approach		31
2.3.3 Optimization Approach		32
2.4 Intrinsic Image (II)		40
2.4.1 Retinex Approach		43
2.4.2 Machine Learning Approach		48
2.5 Specular Removal (SR)		50
2.5.1 Color Space Segmentation Approach		52
2.5.2 Specular-free Approach		53

2.5.3	Partial Differential Equation Approach	58
2.5.4	Inpainting Approach	59
2.5.4.1	Manual Thresholding	60
2.5.4.2	Automated Thresholding	61
2.5.4.3	Clonal Selection Algorithm (ClonalG)	64
2.5.4.4	Particle Swarm Optimization (PSO)	65
2.6	Research Methods in Computer Vision	66
2.7	Research Gap	68
2.8	Summary	69
<b>3</b>	<b>RESEARCH METHODOLOGY</b>	<b>71</b>
3.1	Overview	71
3.2	Quantitative Research Methodology	71
3.3	Research Phases	72
3.4	Problem Identification Phase	74
3.5	Literature Review Phase	76
3.6	Development Phase of 3D-ISCs Extraction Framework	78
3.6.1	Framework Description	79
3.6.2	Chaotic Segmentation Method	81
3.6.2.1	Formulation of Specular Removal Problem	81
3.6.2.2	Proposed Specular Removal Method	84
3.6.2.3	Chaotic ClonalG	89
3.6.2.4	Coherency Sensitive Hashing	96
3.6.3	Sparse Coding Method	97
3.6.3.1	Formulation of Specular Removal Problem	98
3.6.3.2	Proposed Specular Removal method	101
3.6.3.3	Specular-Free Images	102
3.6.3.4	XYZ color space	103
3.6.3.5	Dictionary Construction	105
3.6.4	Modified Blinn-Phong Model	107
3.6.4.1	Formulation of Proposed 3D-ISCs Extraction Framework	108
3.6.4.2	Proposed MBP Model	108
3.6.5	Modified Dichromatic Reflectance Model	110
3.6.5.1	Proposed MDR Model	113
3.6.5.2	3D Reconstruction	115
3.6.5.3	Reflectance Image	116
3.6.5.4	Illumination Estimation	117
3.6.5.5	Modified Dichromatic Reflectance Model	117
3.7	Experimental Phase	118
3.7.1	Data Collection	118
3.7.1.1	DECSAI, Berkeley, SIPI and Tennessee Dataset	119
3.7.1.2	MIT Intrinsic Images Dataset	119
3.7.1.3	MIT-Berkeley Intrinsic Images Dataset	119
3.7.1.4	MIT-Berkeley-UTeM Intrinsic Images Dataset	120
3.7.2	Method Comparison	120
3.7.3	Experimental Settings	121

3.7.4	Performance Measures	121
3.8	Application Phase	123
3.9	Summary	123
<b>4</b>	<b>EXPERIMENTAL RESULTS AND DISCUSSION</b>	<b>125</b>
4.1	Overview	125
4.2	Experimental Results of Chaotic Segmentation	125
4.2.1	Results and comparative performance of Segmentation Step	125
4.2.1.1	Fitness evaluation	126
4.2.1.2	Stability comparison	126
4.2.1.3	Efficiency comparison	132
4.2.2	Result on Images with Significant Specularity	135
4.2.3	Result on Synthetic Images	143
4.2.4	Result on Images without Significant Specularity	145
4.2.5	Discussion	147
4.3	Experimental Results of Sparse Coding	148
4.3.1	Result on Images with Significant Specularity	148
4.3.2	Result on Synthetic Images	154
4.3.3	Result on Images without Specularity	156
4.3.4	Discussion	156
4.4	Experimental Results of Modified Blinn-Phong Model	159
4.4.1	Specular from Reflectance Image	159
4.4.2	Results on Images with Significant Specularity	161
4.4.3	Discussion	164
4.5	Experimental Results of Modified Dichromatic Reflectance Model	165
4.5.1	Results on Images with Significant Specularity	165
4.5.2	Results of Real-World Images	170
4.5.3	Discussion	172
4.6	3D Rendering Applications of the Proposed Framework	173
4.6.1	Optimal Linear Direction	174
4.6.2	Rendering Engine for Highlight image	176
4.6.3	Blinn-Phong Extension	177
4.6.4	Dichromatic Editing	177
4.6.5	Object Recoloring based on Intrinsic Image Estimation	177
4.7	Summary	178
<b>5</b>	<b>CONCLUSIONS</b>	<b>180</b>
5.1	Overview	180
5.2	Review of Research Objectives	180
5.3	Conclusions	181
5.3.1	Conclusion related to <i>RO 1</i> .	181
5.3.2	Conclusion related to <i>RO 2</i> .	182
5.3.3	Conclusion related to <i>RO 3</i> .	183
5.3.4	Conclusion related to <i>RO 4</i> .	185
5.3.5	Conclusion related to <i>RO 5</i> .	185
5.4	Research Contributions	186

5.5	Recommendation for Future Research	187
5.6	Summary	188
<b>REFERENCES</b>		<b>189</b>

## LIST OF TABLES

TABLE	TITLE	PAGE
2.1	List of Constraints to Modify the Functional	34
2.2	Different Types of Specular-free Images	57
2.3	A Comparison of Computer Vision Methods with regard to Different Types of Characteristics	69
4.1	Ground Truth Value by an Exhaustive search (Otsu Method) for the Test Images	130
4.2	Mean Values and Standard Deviation of the Objective Function for 50 Runs	133
4.3	Thresholds Value of the Algorithms	134
4.4	Mean Values of the Computational Time and Iteration (it) for 50 Runs	136
4.5	Accuracy Performance of PSO, ClonalG, CS Methods on Images with Significant Specularity	139
4.6	Speed Performance of PSO, ClonalG, CS on Images with Significant Specularity	141
4.7	Accuracy Performance of PSO, ClonalG, CS on Synthetic Images	143
4.8	Speed Performance of PSO, ClonalG, CS on Synthetic Images	144
4.9	Accuracy Performance of PSO, ClonalG, CS on Images without Significant Specularity	146

4.10	Speed Performance of PSO, ClonalG, CS on Images without Significant Specularity	146
4.11	Accuracy Performance of MZK06, YCK06, YWA10, SC09 on Images with Significant Specularity	150
4.12	Speed Performance of MZK06, YCK06, SC09 on Images with Significant Specularity	150
4.13	Accuracy Performance of SF1, SF2, Both SF on Images with Significant Specularity	153
4.14	Speed Performance of SF1, SF2, Both SF methods on Images with Significant Specularity	153
4.15	Accuracy Performance of SF1, SF2, Both SF on Synthetic Images	154
4.16	Speed Performance of SF1, SF2, Both SF on Synthetic Images	155
4.17	Accuracy Performance of SF1, SF2, Both SF on Images without Significant Specularity	157
4.18	Speed Performance of SF1, SF2, Both SF on Images without Significant Specularity	157
4.19	Accuracy Performance of SIRFS, SIRFS-MZK06, SIRFS-YCK06, SIRFS-MBP on Images with Significant Specularity	162
4.20	Speed Performance of MZK06, YCK06, MBP Both SF on Images without Significant Specularity	162
4.21	Accuracy Performance of SIRFS, MZK06-SIRFS, YCK06-SIRFS, MDR-SIRFS on MIT-Berkeley Intrinsic Images Dataset	166



4.22 Speed Performance of SIRFS, MZK06-SIRFS, YCK06-SIRFS, MBP-SIRFS  
on MIT-Berkeley Intrinsic Images Dataset

166

## LIST OF FIGURES

FIGURE	TITLE	PAGE
1.1	An Example of a Commercial 3D Scanner, Manufactured by <i>Breuckmann Opto-TOP HE</i>	2
1.2	The Best Method in (Zhang et al., 1999) Review: (left) (Zheng and Chellappa, 1991) Method and (right) (Lee and Kuo, 1993) Method	3
1.3	The Best Method in (Durou et al., 2008) Review: (left) (Falcone and Sagona, 1997) Method and (right) (Daniel and Durou, 2000) Method	4
1.4	The original Pepper image (Petitcolas, 2014)	5
1.5	(a) input image, (b) orientation of surface normals, (c) illumination, and (d) reflectance	5
1.6	Thesis Structure	10
2.1	Bidirectional Reflectance Distribution Functions: adopted from (Kurihara and Takaki, 2001)	15
2.2	Phong model	19
2.3	a) An ideal of a shading image and (b) the corresponding 3D model.	22
2.4	(Weiss, 2001) Intrinsic-images: (a) an input image, (b) reflectance image, (c) shading image	42

2.5	(a) Input image. (b) Kim et al. (2013) result. (c) Dark channel. (d) Result of (Tan and Ikeuchi, 2005)	57
3.1	Overview of Research Phases	73
3.2	A visualization of 3D-ISCs extraction problem in this study. Given a single input image, the task is to derive the object into these characteristics: (b) diffuse, (c) reflectance, (d) illumination, (e) specular, (f) shading, and (g) 3D shape characteristics.	75
3.3	3D Intrinsic Scene Characteristics Extraction Framework	79
3.4	The Extraction process of diffuse and specular characteristics using CS method. Initially, the input image is segmented into diffuse and specular pixels using the proposed SR method. Then, the specular pixel is replaced based on the information from the neighbors using inpainting method.	85
3.5	The curve of mutation rate is affected by the value of parameter $\rho$	88
3.6	Diagram of logistic map bifurcation (Bresten and Jung, 2009)	91
3.7	Distribution of logistic map	92
3.8	Comparison of histogram of logistic map distribution and Matlab pseudo-random number distribution. (a) Logistic Map with uniform distribution, (b) Matlab random generator with uniform distribution	92
3.9	The Extraction process of diffuse and specular characteristics using SC method. Initially, the input image is processed using specular-free methods. The output is the $n$ specular-free images. These images then are used to reconstruct a dictionary. From the dictionary, the SC method generates the diffuse and specular images.	101

3.10	The Extraction Process of 3D-ISCs using MBP Model. Initially, the input image is processed using SIRFS method. The output is the shading and reflectance image. The shading is rendered using a shader from the 3D shape and illumination model. The SR method then process reflectance image to extract specular and diffuse characteristics.	109
3.11	The extraction process of 3D-ISCs using MDR Model. Initially, the input image is processed using SR method. The output is the diffuse image. The SIRFS then extract the reflectance and shading image. From the shading image is rendered using a shader from the 3D shape and illumination model.	111
3.12	Pixel histograms of filter output from diffuse (left) and from specular (right). It is clearly that the filter output histograms have distinctly noticeable difference shape between diffuse and specular reflection.	114
4.1	Original image and their histogram	127
4.2	Original image and their histogram (continued)	128
4.3	Original image and their histogram (continued)	129
4.4	Thresholded image obtained by CS (a) represents $K = 3$ , (b) represents $K = 4$ , (c) represents $K = 5$	137
4.5	Thresholded image obtained by CS (a) represents $K = 3$ , (b) represents $K = 4$ , (c) represents $K = 5$ (continued)	138
4.6	The Ground Truth Images. (top) Input images, (middle) Diffuse Images, (bottom) Specular Images. From left to right: Apple, Pear, Potato, Teabag1, Teabag2	139

4.7	Thresholded image obtained by CS (a) represents $K = 1$ , (b) represents $K = 2$ , (c) represents $K = 3$	140
4.8	Thresholded image obtained by CS (a) represents $K = 1$ , (b) represents $K = 2$ , (c) represents $K = 3$ (continued)	141
4.9	PSO: (top) Diffuse Results, (bottom) Specular Results. From left to right: Apple, Pear, Potato, Teabag1, Teabag2	142
4.10	ClonalG: (top) Diffuse Results, (bottom) Specular Results. From left to right: Apple, Pear, Potato, Teabag1, Teabag2	142
4.11	CS: (top) Diffuse Results, (bottom) Specular Results. From left to right: Apple, Pear, Potato, Teabag1, Teabag2	142
4.12	PSO: (top) Diffuse Results, (bottom) Specular Results. From left to right: Apple, Pear, Potato, Teabag1, Teabag2	144
4.13	ClonalG: (top) Diffuse Results, (bottom) Specular Results. From left to right: Apple, Pear, Potato, Teabag1, Teabag2	144
4.14	CS: (top) Diffuse Results, (bottom) Specular Results. From left to right: Apple, Pear, Potato, Teabag1, Teabag2	145
4.15	PSO: (top) Diffuse Results, (bottom) Specular Results. From left to right: Apple, Pear, Potato, Teabag1, Teabag2	146
4.16	ClonalG: (top) Diffuse Results, (bottom) Specular Results. From left to right: Apple, Pear, Potato, Teabag1, Teabag2	147
4.17	CS: (top) Diffuse Results, (bottom) Specular Results. From left to right: Apple, Pear, Potato, Teabag1, Teabag2	147

4.18	The Ground Truth Images. (top) Input images, (middle) Diffuse Images, (bottom) Specular Images. From left to right: Apple, Pear, Potato, Teabag1, Teabag2	149
4.19	MZK06: (left) Original, (middle) Diffuse, and (right) Specular	151
4.20	YCK06: (left) Original, (middle) Diffuse, and (right) Specular	151
4.21	YWA10: (left) Original, (middle) Diffuse, and (right) Specular	152
4.22	SC09: (left) Original, (middle) Diffuse, and (right) Specular component	152
4.23	Proposed Method: (top) Diffuse Results, (bottom) Specular Results. From left to right: Apple, Pear, Potato, Teabag1, Teabag2	153
4.24	Proposed Method: (top) Diffuse Results, (bottom) Specular Results. From left to right: Apple, Pear, Potato, Teabag1, Teabag2	155
4.25	MZK06: (top) Diffuse Results, (bottom) Specular Results. From left to right: Apple, Pear, Potato, Teabag1, Teabag2	155
4.26	YCK06: (top) Diffuse Results, (bottom) Specular Results. From left to right: Apple, Pear, Potato, Teabag1, Teabag2	156
4.27	Proposed Method: (top) Diffuse Results, (bottom) Specular Results. From left to right: Apple, Pear, Potato, Teabag1, Teabag2	157
4.28	MZK06: (top) Diffuse Results, (bottom) Specular Results. From left to right: Apple, Pear, Potato, Teabag1, Teabag2	158
4.29	YCK06: (top) Diffuse Results, (bottom) Specular Results. From left to right: Apple, Pear, Potato, Teabag1, Teabag2	158
4.30	Intrinsic Scene Characteristics from SIRFS for pear	160
4.31	Intrinsic Scene Characteristics from SIRFS for potato	161

4.32	Intrinsic Scene Characteristics from SIRFS for teabag1	161
4.33	MZK06: From top-left to top-right is the diffuse images of pear, potato, and teabag1 while from bottom-left to bottom-right is the specular images of pear, potato, and teabag1	163
4.34	YCK06: From top-left to top-right is the diffuse images of pear, potato, and teabag1 while from bottom-left to bottom-right is the specular images of pear, potato, and teabag1	163
4.35	MDR: From top-left to top-right is the diffuse images of pear, potato, and teabag1 while from bottom-left to bottom-right is the specular images of pear, potato, and teabag1	164
4.36	MZK06-SIRFS on Pear: (left to right) diffuse, reflectance, shading, surface normals, and illumination images	167
4.37	MZK06-SIRFS on Potato: (left to right) diffuse, reflectance, shading, surface normals, and illumination images	168
4.38	MZK06-SIRFS on Teabag1: (left to right) diffuse, reflectance, shading, surface normals, and illumination images	168
4.39	YCK06-SIRFS on Pear: (left to right) diffuse, reflectance, shading, surface normals, and illumination images	168
4.40	YCK06-SIRFS on Potato: (left to right) diffuse, reflectance, shading, surface normals, and illumination images	169
4.41	YCK06-SIRFS on Teabag1: (left to right) diffuse, reflectance, shading, surface normals, and illumination images	169

4.42	MDR-SIRFS on Pear: (left to right) diffuse, reflectance, shading, surface normals, and illumination images	169
4.43	MDR-SIRFS on Potato: (left to right) diffuse, reflectance, shading, surface normals, and illumination images	170
4.44	MDR-SIRFS on Teabag1: (left to right) diffuse, reflectance, shading, surface normals, and illumination images	170
4.45	Results of ISC estimation using the proposed model on real-world Pebbles image, manually cropped color images of objects.	171
4.46	Results of ISC estimation using the proposed model on real-world Toy image, manually cropped color images of objects.	171
4.47	Results of ISC estimation using the proposed model on real-world Fruits image, manually cropped color images of objects.	172
4.48	Results of ISC estimation using the proposed model on real-world Toothpaste image, manually cropped color images of objects.	172
4.49	Specular highlight on sphere for different type of light source	174
4.50	Dichromatic Editing of Pear	178
4.51	Reflectance Editing of Pear	178