

Faculty of Electrical Engineering

STUDIES BETWEEN CLARKE TRANSFORMATION AND SYMMETRICAL COMPONENTS FOR FAULT ANALYSIS OF POWER DISTRIBUTION SYSTEM USING PSCAD

Ali Abdulhasan Abdulzahra

Master of Electrical Engineering (Industrial Power)

2016

STUDIES BETWEEN CLARKE TRANSFORMATION AND SYMMETRICAL COMPONENTS FOR FAULT ANALYSIS OF POWER DISTRIBUTION SYSTEM USING PSCAD

ALI ABDULHASAN ABDULZAHRA

A dissertation submitted in partial fulfillment of the requirements for the degree of Master of Electrical Engineering (Industrial Power)

Faculty of Electrical Engineering

UNIVERSITI TEKNIKAL MALAYSIA MELAKA

2016

DECLERATION

I declare that this research entitle "Comparative Studies between Clarke Transformation and Symmetrical Components for Fault Analysis of Power Distribution System using PSCAD " is the result of my own research except as cited in the references. The research has not been accepted for any degree and is not concurrently submitted in candidature of any other degree.

Signature	:	
Name	:	Ali Abdulhasan Abdulzahra
Date	:	

APPROVAL

I hereby declare that I have read this research and in my opinion this report is sufficient in terms of scope and quality as a partial fulfillment of Master of Electrical Engineering (Industrial Power).

Signature	:	
Suprvisor Name	:	Prof. Dr. Marizan Bin Sulaiman
Date	:	



DEDICATION

To my beloved parents, and my dear wife

ABSTRACT

Fault analysis studies are essential analytic tool for designing and planning of power systems. They are considered the most important and complicated matter in power engineering. Customarily, analyzing of power systems under fault conditions is restricted to using of Symmetrical Components method although there is another useful method such as Clarke Transformation. This research presents performing theoretical and simulation fault analysis studies for low voltage distribution system using both Symmetrical Components and modified Clarke Transformation methods, comparing between both techniques, and highlighting the interrelation between them. This research gives a general derivations of equivalent circuits for various operating conditions in power system based on modified Clarke Transformation. A comprehensive theoretical fault analysis for 3-PH, 3-PH-G, S-L-G, L-T-L, and D-L-G fault conditions in power distribution system have been implemented based on Symmetrical Components and modified Clarke Transformation. Moreover, simulation fault analysis studies using PSCAD/EMTDC Software are presented in this research for performing the fault conditions using both methods. The findings of this research show some advantages for using Clarke Transformation method in fault analysis compared to using Symmetrical Components. Analysis results show that Clarke Transformation provides easier solution and equivalent circuits for most of fault conditions. Furthermore, simulation results show that fault conditioning provided by Clarke Transformation is clearer and simpler than thus provided by Symmetrical Components.

ABSTRAK

Kajian analisis kerosakan merupakan analisis penting untuk mereka bentuk dan perancangan bagi sistem kuasa. Ianya dianggap perkara yang paling penting dan rumit dalam bidang kejuruteraan kuasa. Lazimnya, menganalisis sistem kuasa di bawah keadaan kerosakan adalah terhad dengan menggunakan kaedah Komponen Simentri walaupun terdapat kaedah lain yang berguna seperti Transformasi Clarke. Kajian ini membentangkan pelaksanaan secara teori dan analisis simulasi kerosakan untuk sistem pengagihan voltan rendah dengan menggunakan kedua-dua kaedah iaitu Komponen Simetri dan Transformasi Clarke yang telah diubahsuai, perbandingan antara kedua-dua teknik, dan hubungkait di antara keduanya ditekankan. Kajian ini memberikan terbitan umum litar setara bagi pelbagai keadaan operasi dalam sistem kuasa berdasarkan Transformasi Clarke yang telah diubah suai. Sebuah analisis komphrehensif mengenai teroi kerosakan untuk 3-PH, 3-PH-G, S-L-G, L-T-L, dan keadaan kerosakan D-L-G dalam sistem pengagihan kuasa telah dilaksanakan berdasarkan kaedah Komponen Simetri dan Transformasi Clarke yang telah diubah suai. Selain itu, kajian simulasi analisis kerosakan menggunakan perisian PSCAD / EMTDC Software juga dibentangkan dalam kajian ini untuk melaksanakan keadaan kerosakan menggunakan kedua-dua kaedah tersebut. Dapatan kajian ini menunjukkan beberapa kelebihan menggunakan kaedah Transformasi Clarke dalam analisis kerosakan berbanding menggunakan Komponen Simetri. Keputusan analisis menunjukkan bahawa Transformasi Clarke memberikan penyelesaian yang mudah dan litar setara bagi kebanyakan keadaan kerosakan. Tambahan pula, keputusan simulasi menunjukkan bahawa keadaan kerosakan diberikan oleh Transformasi Clarke adalah lebih jelas dan lebih mudah daripada kaedah Komponen Simetri.

ACKNOWLEDGEMENT

First and foremost, all praises and thanks to ALLAH, the almighty. Alhamdulillah, and peace and blessings of ALLAH be upon the last Prophet Mohamed S.A.W. I am ever grateful to HIS endless blessings throughout my research work which is the main reason behind the success for the completion of this research.

I would like to express my deepest gratitude and appreciation to Engr. Professor Dr. Marizan bin Sulaiman, my supervisor, from Faculty of Electrical Engineering Universiti Teknikal Malaysia Melaka (UTeM) for his encouragement, patience, and guidance during my study.

I am extremely grateful to my beloved parents for their love and prayers. I am also very much thankful to my wife for her love, understanding, prayers and continuing support to complete this research work. My sincere thanks to my family, my relatives, and friends who all gave me courage and support.

I would like to thank Ministry of Electricity/Republic of Iraq (MOE) and general directorate of electrical distribution for the south for the financial support during my study in Malaysia.

Finally, I am extending my thanks to all the people who have supported me to complete the research work directly or indirectly.

TABLE OF CONTENTS

DEC	CLAR	RATION	
DEL	DICA	TION	
APP	ROV	YAL	
ABS	TRA	СТ	i
ABS	TRA	K	ii
ACF	KNOV	WLEDGEMENTS	iii
TAE	BLE (DF CONTENTS	iv
LIST	ГOF	TABLES	vii
LIST	ГOF	FIGURES	viii
LIST	ГOF	ABBREVIATIONS	xii
LIS	ГOF	SYMBOLS	xiii
CHA	APTE	CR CR	
1.	INT	TRODUCTION	1
	1.1	Background	1
	1.2	Motivation of Research	3
	1.3	Problem Statement	4
	1.4	Objectives of Research	4
	1.5	Scope of Research	5
	1.6	Contribution of Research	6
	1.7	Organization of Research	7
2.	LIT	ERATURE REVIEW	9
	2.1	Introduction	9
	2.2	Fault Analysis	9
	2.3	Symmetrical Sequence Components	11
	2.5	2.3.1 Fundamental Concept of Symmetrical Components	11
		2.3.2 Definition and Theory of Symmetrical Components	13
		2.3.2 Demittion and Theory of Symmetrical Components	15
		2.3.2 Operator a 2.3.2 Power Calculation in Symmetrical Components	16
	21	Eault Analysis Using Symmetrical Components	10
	2.4	2 4 1 Three Phase Fault	10
		2.4.1 Finder hast raun	21
		2.4.2 Single-Line-to-Oround Fault	21
		2.4.5 Line-to-Line Fault	22
	2.5	2.4.4 Double-Line-to-Ground Fault	24
	2.5	Clarke Transformation	25
		2.5.1 Concept of Clarke Transformation	25
		2.5.2 Clarke Transformation In Fault Analysis	30
		2.5.3 Applications of Clarke Transformation in Power System	34
		2.5.4 Modified Clarke Transformation	35
	2.6	Linear Transformation and Power Invariant Requirement	36
		2.6.1 Linear Transformation Concept	36
		2.6.2 Power Invariant Requirement	38
	2.7	Per-Unit Calculations in Fault Analysis	39

		2.7.1 Per-Unit System	39
		2.7.2 Three-Phase System Analysis	40
		2.7.3 Change of Base	41
	2.8	Using of Power System Computer Aided Design in Fault Analysis	42
		2.8.1 Definition of Power System Computer Aided Design	42
		2.8.2 The PSCAD Environment	43
		2.8.3 The Implementations of PSCAD/EMTDC in Fault Analysis	43
	2.9	Summary	45
3.	RES	SEARCH METHODOLOGY	46
	3.1	Introduction	46
	3.2	Research Procedure	46
	3.3	Power Invariant Requirement	94
		3.3.1 Symmetrical Sequence Components under Power	44
		Invariant requirement	
		3.3.2 Clarke Transformation under Power Invariant	51
		Requirement	
	3.4	Interrelation between Clarke Transformation and Symmetrical	59
		Components	
	3.5	Interrelation between Clarke Voltage and Current Components	58
	3.6	Interrelation between Clarke and Sequence Impedance Matrices	60
	3.7	Equivalent Circuits of 0-α-β Components	61
		3.7.1 Normal Balanced Condition	61
		3.7.2 Balanced Fault Condition	69
		3.7.3 Single-Line-to-Ground Fault Condition	65
		3.7.4 Line-to-Line Fault Condition	67
	• •	3.7.5 Double-Line-to-Ground Fault Condition	68
	3.8	Fault Circuit Analysis Event	70
		3.8.1 Analyzing using Real Values	71
		3.8.1.1 Fault Analysis Using Symmetrical Sequence	13
		Components	72
		3.8.1.1.1 Infee Phase-to-Ground Fault	13
		3.8.1.1.2 Single-Line-to-Ground fault	() 77
		2.8.1.1.2 Line-to-Line Fault	// 74
		2.8.1.2 Foult Analysis Using Clarks Transformation	/4 Q1
		5.6.1.2 Fault Allarysis Using Clarke Halistonnation	01 Q1
		3.8.1.2.1 Finds Fault Condition	01 92
		3.8.1.2.2 Single-Line-to-Oround fault	80
		3.8.1.2.4 Double Line to Ground fault	86
		3.8.2 Analyzing Using Per Unit Values	87
		3.8.2 Analyzing Using FCI Unit Values	90
		Components	70
		3 8 2 1 1 Three Phase Fault Condition	90
		38212 Single-Line-to-Ground Fault	92
		38213 Line-to-Line Fault	93
		3 8 2 1 4 Double-Line-to-Ground fault	95
			20

v

		3.8	8.2.2 Fault Ana	lysis Using Interrelation Formulas	97
			3.8.2.2.1	Three Phase Fault Condition	98
			3.8.2.2.2	Single-Line-to-Ground Fault	44
			3.8.2.2.3	Line-to-Line Fault	100
			3.8.2.2.4	Double-Line-to-Ground fault	101
		3.9 Asso	essment and Com	parison between both Techniques	103
		3.10 Sum	imary		105
4.	RES	SULTS AN	D DISCUSSION	1	10 6
	4.1	Introducti	on		106
	4.2	Case for S	Simulation Study		106
		4.2.1 Cr	eating New Com	ponents	108
	4.3	Normal S	teady State Opera	tion Condition	104
	4.4	Continuou	us Fault Condition	ns	112
		4.4.1 Th	ree-Phase Fault		112
		4.4.2 Th	ree-Phase-to-Gro	ound Fault	115
		4.4.3 Si	ngle-Line-to-Gro	und Fault	116
		4.4.4 Li	ne-to-Line Fault		114
		4.4.5 Do	ouble-Line-to-Gro	ound Fault	121
	4.5	Fault Con	ditions with Clea	ring Time	129
		4.5.1 Th	ree-Phase Fault	-	125
		4.5.2 Th	ree-Phase-to-Gro	ound Fault	131
		4.5.3 Si	ngle-Line-to-Gro	und Fault	137
		4.5.4 Li	ne-to-Line Fault		143
		4.5.5 Do	ouble-Line-to-Gro	ound Fault	194
	4.6	Discussio	n of Simulation R	Results	155
	4.7	Chapter S	ummary		154
5.	CO	NCLUSIO	N		16 0
	5.1	Conclusio	n		160
	5.2	Attainme	nt of Research Ob	ojectives	161
	5.3	Significar	ice of Research C	outcomes	162
	5.4	Suggestio	ns for Future Res	earch	163
RE	FERE	INCES			16 9
LIS	ST OF	APPEND	ICES		17 2

LIST OF TABLES

TABLE	TITLE	PAGE
2.1	Relation between 0, α , and β Components of Voltages and Currents	30
	during Faults In Three Phase Power System	
3.1	The Scalar Relation between Fault Currents and Clarke	109
	Current Components	
3.2	Clarke and Symmetrical Components' Specifications at	105
	Different Fault Conditions	
4.1	Fault Recognition based on Clarke Components Specifications	157
4.2	Fault Recognition based on Symmetrical Components Specifications	158

LIST OF FIGURES

TITLE

PAGE

FIGURE

2.1	Types of Faults	10
2.2	Decomposing of Phases a-b-c Quantities Into Their Sequence Components	12
2.3	Phasor Diagram of Various Powers and Functions of Operator A	16
2.4	Equivalent Circuits Of Balanced Power System in a-b-c Coordinate	19
2.5	0-1-2 Network Connection During Three-Phase Fault Condition	20
2.5	0-1-2 Network Connection During Single-Phase-To-Ground Fault Condition	n 22
2.7	0-1-2 Network Connection During Line-To- Line Fault Condition	23
2.8	0-1-2 Network Connection During Double-Line-To- Ground Fault	25
	Condition	
2.9	The $0\alpha\beta$ -Component Currents Through Power System During	26
	Single-Line- To Ground Fault Condition	
2.10	Graphical Representation of Clarke Transformation	29
2.11	Equivalent Circuit of $0-\alpha-\beta$ Components and It's Network Connections	32
	During Various Fault Conditions	
3.1	Flowchart of the Research Procedure	47
3.2	Flowchart of Implementation of Fault Analysis	94
3.3	Equivalent Circuits of Power System in 0-1-2 and $0-\alpha-\beta$ Coordinates	63
3.4	$0-\alpha-\beta$ Networks Connection During Three-Phase Fault Condition	65
3.5	0-α-β Networks Connection During Single-Line-To-Ground Fault	66
	Condition	
3.6	$0-\alpha-\beta$ Networks Connection During Line-To- Line Fault Condition	68
3.7	0-α-β Networks Connection During Double-Line-To-Ground Fault	70
	Condition	
3.8	Fault Analysis on Power Distribution System Configuration	71
3.9	The Positive Sequence Network for Per-Unit Analysis	79
3.10	Sequence Networks Connection for S-L-G Fault	75

viii

3.11	Sequence Networks Connection for D-L-G Fault	78
3.12	Sequence Networks Connection for D-L-G Fault	79
3.13	Power System Representation With Base Voltage Indication	88
3.14	The Positive Sequence Network during Three-Phase Fault Condition	90
4.1	The System Configuration in PSCAD	107
4.2	Clarke Transformation Component With Its Script in PSCAD	108
4.3	Inverse Clarke Transformation Component With Its Script in PSCAD	108
4.4	Clarke Transformation Component With Phasor Sequence Components	109
	Input And Its Script in PSCAD	
4.5	Component for Instantaneous Symmetrical Components in PSCAD	109
4.6	Current Waveforms for a-b-c System, Sequence Components, and $0-\alpha$ - β	111
	Coordinates at Normal Load Condition	
4.7	Voltage Waveforms for a-b-c System, Sequence Components, and $0-\alpha-\beta$	112
	Coordinates at Normal Load Condition	
4.8	Current Waveforms for a-b-c System, Sequence Components, and $0-\alpha-\beta$	113
	Coordinates at 3-Ph Fault Condition	
4.9	Voltage Waveforms for a-b-c System, Sequence Components, and $0\text{-}\alpha\text{-}\beta$	114
	Coordinates at 3-Ph Fault Condition	
4.10	Current Waveforms for a-b-c System, Sequence Components, and $0-\alpha-\beta$	115
	Coordinates at 3-Ph-G Fault Condition	
4.11	Voltage Waveforms for a-b-c System, Sequence Components, and $0\text{-}\alpha\text{-}\beta$	116
	Coordinates at 3-Ph-G Fault Condition	
4.12	Current Waveforms In a-b-c System, Sequence Components, and $0\alpha\beta$	117
	Coordinates at S-L-G Fault Condition	
4.13	Voltage Waveforms In a-b-c System, Sequence Components, and $0\text{-}\alpha\text{-}\beta$	118
	Coordinates at S-L-G Fault Condition	
4.14	Current Waveforms In a-b-c System, Sequence Components, and $0\text{-}\alpha\text{-}\beta$	120
	Coordinates at D-L Fault Condition	
4.15	Voltage Waveforms In a-b-c System, Sequence Components, and $0\text{-}\alpha\text{-}\beta$	121
	Coordinates at D-L Fault Condition	
4.16	Current Waveforms In a-b-c System, Sequence Components, and $0\text{-}\alpha\text{-}\beta$	123
	Coordinate at D-L-G Fault Condition	
4.17	Voltage Waveforms In a-b-c System, Sequence Components, and $0\text{-}\alpha\text{-}\beta\text{-}$	124
	Coordinates at D-L-G Fault Condition	

- 4.18Current Waveforms In a-b-c System, Sequence Components, and $0-\alpha-\beta$ 125Coordinates at 3-Ph Fault Condition With Fault Clearing Time 0.2 Second
- 4.19 Transient Current Waveforms In a-b-c System, Sequence Components, and 127
 0-α-β Coordinates After 3-Ph Fault Ocurring
- 4.20 Transient Current Waveforms In a-b-c System, Sequence Components, and 128
 0-α-β Coordinates After 3-Ph Fault Clearing
- 4.21Voltage Waveforms In a-b-c System, Sequence Components, and $0-\alpha-\beta$ 129Coordinates at 3-Ph Fault Condition With Fault Clearing Time 0.2 Second
- 4.22 Transient Voltage Waveforms In a-b-c System, Sequence Components, and 130
 0-α-β Coordinates After 3-Ph Fault Ocurring
- 4.23 Transient Voltage Waveforms In a-b-c System, Sequence Components, and 131
 0-α-β Coordinates After 3-Ph Fault Clearing
- 4.24Current Waveforms In a-b-c System, Sequence Components, and $0-\alpha-\beta$ 132Coordinates at 3-Ph-G Fault Condition With Fault Clearing Time 0.2 Second
- 4.25 Transient Current Waveforms In a-b-c System, Sequence Components, and 133
 0-α-β Coordinates After 3-Ph-G Fault Ocurring
- 4.26 Transient Current Waveforms In a-b-c System, Sequence Components, and 134
 0-α-β Coordinates After 3-Ph-G Fault Clearing
- 4.27 Voltage Waveforms In a-b-c System, Sequence Components, and 0-α-β 135
 Coordinates at 3-Ph-G Fault Condition And Fault Clearing Time 0.2 Second
- 4.28 Transient Voltage Waveforms In a-b-c System, Sequence Components, and 136
 0-α-β Coordinates After 3-Ph-G Fault Incident
- 4.29 Transient Voltage Waveforms In a-b-c System, Sequence Components, and 137
 0-α-β Coordinates After 3-Ph-G Fault Clearing
- 4.30 Current Components In a-b-c System, Sequence Components, and 0-α-β 138
 Coordinates at S-L-G Fault Condition With Fault Clearing Time 0.2 Second
- 4.31 Transient Current Waveforms In a-b-c System, Sequence Components, and 139
 0-α-β Coordinates After S-L-G Fault Ocurring
- 4.32 Transient Current Waveforms In a-b-c System, Sequence Components, and 140
 0-α-β Coordinates After S-L-G Fault Clearing
- 4.33 Voltage Waveforms In a-b-c System, Sequence Components, and $0-\alpha-\beta$ 141 Coordinates at S-L-G Fault Condition With Fault Clearing Time 0.2 Second
- 4.34 Transient Voltage Waveforms In a-b-c System, Sequence Components, and 142
 0-α-β Coordinates After S-L-G Fault Ocurring

- 4.35 Transient Voltage Waveforms In a-b-c System, Sequence Components, and 143
 0-α-β Coordinates After S-L-G Fault Clearing
- 4.36 Current Waveforms In a-b-c System, Sequence Components, and 0-α-β
 144 Coordinates at D-L Fault Condition With Fault Clearing Time 0.2 Second
- 4.37 Transient Current Waveforms In a-b-c System, Sequence Components, and 145
 0-α-β Coordinates After D-L Fault Ocurring
- 4.38 Transient Current Waveforms In a-b-c System, Sequence Components, and 146
 0-α-β Coordinates After D-L Fault Clearing
- 4.39 Voltage Waveforms In a-b-c System, Sequence Components, and 0-α-β
 147 Coordinates at D-L Fault Condition With Fault Clearing Time 0.2 Second
- 4.40 Transient Voltage Waveforms In a-b-c System, Sequence Components, and 148
 0-α-β Coordinates After D-L Fault Ocurring
- 4.41 Transient Voltage Waveforms In a-b-c System, Sequence Components, and 149
 0-α-β Coordinates After D-L Fault Clearing
- 4.42 Current Waveforms In a-b-c System, Sequence Components, and 0-α-β 150
 Coordinate at D-L-G Fault Condition With Fault Clearing Time 0.2 Second
- 4.43 Transient Current Waveforms In a-b-c System, Sequence Components, and 151
 0-α-β Coordinates After D-L-G Fault Ocurring
- 4.44 Transient Current Waveforms In a-b-c System, Sequence Components, and 152
 0-α-β Coordinates After D-L-G Fault Clearing
- 4.45 Voltage Waveforms In a-b-c System, Sequence Components, and 0-α-β
 153 Coordinates at D-L-G Fault Condition With Fault Clearing Time 0.2 Second
- 4.46 Transient Voltage Waveforms In a-b-c System, Sequence Components, and 154
 0-α-β Coordinates After D-L-G Fault Ocurring
- 4.47 Transient Voltage Waveforms In a-b-c System, Sequence Components, and 155
 0-α-β Coordinates After D-L-G Fault Clearing

LIST OF ABBREVIATIONS

3-РН	-	Three-Phase
S-L-G	-	Single-Line-to-Ground
D-L	-	Line-to-Line
D-L-G	-	Double-Line-to-Ground
0-1-2	-	Symmetrical Sequence Components
0	-	Zero Sequence Component
1	-	Positive Sequence Component
2	-	Negative Sequence Component
0-α-β	-	Clarke Transformation Components
PSCAD	-	Power System Computer Aided Design
//	-	Parallel connection of impedances
Υ/Δ	-	Star / Delta Connection

LIST OF SYMBOLS

V_a, V_b, V_c	-	Phase Voltages of Phases a, b and c in phasor form	
v _a , v _b , v _c	-	Phase Voltages of Phases a, b and c in instantaneous form	
V _{ab} , V _{bc} , V _{ca}	-	Line Voltages of Phases a, b and c in phasor form	
V _{af} , V _{bf} , V _{cf}	-	Phase Voltages of Phases a, b and c during Fault Condition	
V ₀ , V ₁ , V ₂	-	Zero, Positive, and Negative sequence Voltages in phasor form	
$V_0, V_{\alpha}, V_{\beta}$	-	Zero, Alpha, and Beta Voltage Components in phasor form	
v ₀ , v _α , v _β	-	Zero, Alpha, and Beta Voltage Components in instantaneous form	
$V_{0f}, V_{\alpha f}, V_{\beta f}$	-	Zero, Alpha, and Beta Voltage Components during Fault Condition	
I _a , I _b , I _c	-	Phase Currents of Phases a, b and c in phasor form	
i _a , i _b , i _c	-	Phase Currents of Phases a, b and c in instantaneous form	
I_{af}, I_{bf}, I_{cf}	-	Phase Currents of Phases a, b and c during Fault Condition	
I ₀ , I ₁ , I ₂	-	Zero, Positive, and Negative sequence Currents in phasor form	

$I_0, I_{\alpha}, I_{\beta}$	-	Zero, Alpha, and Beta Current Components in phasor form
i_0,i_α,i_β	-	Zero, Alpha, and Beta Current Components in nstantaneous form
$I_{0f}, I_{\alpha f}, I_{\beta f}$	-	Zero, Alpha, and Beta Current Components during Fault Condition
[S]	-	Symmetrical Transformation Matrix
[S] ⁻¹	-	Invers Symmetrical Transformation Matrix
[C]	-	Clarke Transformation Matrix
[C] ⁻¹	-	Invers Clarke Transformation Matrix
[A]	-	Forward Linear Transformation Matrix
[A] ⁻¹	-	Invers Linear Transformation Matrix
S _{abc}	-	Complex Power in an original System
S _{ABC}	-	Complex Power in an Transformed System
<i>S</i> ₀₁₂	-	Complex Power in Symmetrical Components Coordinate
$S_{0\alpha\beta}$	-	Complex Power in Clarke Transformation Coordinate
pu	-	Per-Unit
V_b	-	Base Voltage in Three Phase System
V_F	-	Phase Voltage at the Fault Point
V _R	-	Rated Voltage at a certain Point
I _b	-	Base Current in Three Phase System
S _b	-	Base MVA in Three Phase System
S _{pu}	-	Per-Unit Power in Three Phase System
Z_{pu}	-	Per-Unit Impedance in Three Phase System

V _{pu}	-	Per-Unit Voltage in Three Phase System
I _{pu}	-	Per-Unit Current in Three Phase System
a	-	Operator = $1 \ge 120^{\circ}$
$S_{3\phi}$	-	Complex Power in Three Phase System
$P_{3\phi}$	-	Real Power in Three Phase System
$Q_{3\Phi}$	-	Reactive Power in Three Phase System
*	-	conjucate
t	-	Transpose
$Q_{3\Phi}$	-	Reactive Power in Three Phase System
Ζ	-	Impedance
Z _L	-	Load Impedance
Zs	-	Source Impedance
Z _T	-	Transformer Impedance
Z _C	-	Cable Impedance
Х	-	Reactance
X_L	-	Load Reactance
Xs	-	Source Reactance
X _T	-	Transformer Reactance
X _C	-	Cable Reactance
R	-	Resistance
R _L	-	Load Resistance
R _s	-	Source Resistance
R _T	-	Transformer Resistance
R _C	-	Cable Resistance

Z _{eq}	-	Equivalent Impedance
Z_0, Z_1, Z_2	-	Zero, Positive, and Negative sequence Impedance
V	-	Volt
А	-	Amper
kV	-	Kilo Volt
kA	-	Kilo Amper
kVA	-	Kilo Volt Amper
MVA	-	Mega Volt Amper
Ω	-	Ohm

CHAPTER 1

INTRODUCTION

1.1 Background

Fault studies are considered the essential analytic tool for electric power systems. Planning and installing of power systems requires implementing these studies to determine the maximum and minimum fault currents and voltages at different parts of power system for various fault conditions (Kasibama, 1993). Based on fault study's results, the appropriate protective schemes, circuit breakers, and relays can be selected in order to protect the power system against abnormal operation conditions within minimum time (Paithankar, and Bhide, 2010; Abouelenin, 2002). Obviously, withstanding capabilities of electrical power system's equipment and settings of protective relays are determined according to fault analysis results (Mubarak et al., 2015).

Most faults are frequently occurred in distribution power systems in the form of short-circuiting either to the earth or among live conductors. Almost, these faults consequently cause excessive currents flowing through the short-circuited path which potentially result in overheating, conductor melting, circuit damage, explosion or fire (Oldham-Smith and Madden, 2008; Godse and Bakshi, 2010). Short-circuits are usually caused by equipment damage, flash-over, insulation failure, heavy winds, birds, trees falling on live lines, kites, and human errors (Hambley, 2005). Commonly, short-circuits can be classified into: three-phase, three-phase-to-ground, phase-to-phase, phase-to-phase-to-ground (Sousa Martins et al., 2005).

Fault analysis is usually grouped into symmetrical and asymmetrical fault analysis based on the fault types mentioned above (Adepoju et al., 2013) . The first two types of faults are called symmetrical faults because they cause equal currents flowing through the system phases so that the power system can be analyzed by simple single-phase circuit representation. However, the other types of faults are called asymmetrical faults because of the unequal currents flowing through system phases caused by these types of faults.

The power system under unbalanced conditions cannot be analyzed by simple single phase circuit representation. For this reason, the three phase circuit representation is always very complicated to analyze, even for smaller system models, so the analysis of the three phase circuit is practically impossible and cannot be obtained. Therefore, alternative technique is required to analyze the power systems under these conditions that is symmetrical components technique, which was originally developed by Charles Legeyt Fortescue in 1918.

The symmetrical components technique is considered a type of variables transformation tool from a mathematical perspective. It can provide a good way to simplify and express three phase circuit by analytical equivalent circuits (Hase, 2013). It can express three electrical quantities in a-b-c three phase system by set of three variables named positive (1), negative (2), and zero (0) sequence quantities in 0-1-2 coordinate. Therefore, the power system quantities a-b-c can be transformed into the 0-1-2 quantities for simplifying the analysis process. Then, the obtained solution and results in the 0-1-2 coordinate can be retransformed into the original a-b-c quantities. It can be said that this technique is considered the essential analytical technique for the power system fault analysis that commonly used by designers and engineers. However, the symmetrical

sequence components is not always the best method for solving unbalanced power system problems (Rao et al., 1966).

There is also another transformation can be useful in power system fault analysis that is Clarke Transformation. This transformation can be used to transform a-b-c quantities into $0-\alpha-\beta$ coordinate. According to (Hase, 2013), Clarke Transformation can be considered a complementary analytic tool of Symmetrical Components. Moreover, in some special applications such as transient phenomena, $0-\alpha-\beta$ components provide easier solutions for the problems for which Symmetrical Sequence Components cannot give good solutions (Hase, 2013). Nowadays, Clarke Transformation tool is widely used in power system protection, fault detection and recognition, and control.

This research aims to examine using of both symmetrical components and Clarke transformation in distribution power system fault analysis and point out the specifications, differences, and advantages of each technique analytically and by simulation through PSCAD/EMTDC software. In addition, this study aims to find out the interrelation between the symmetrical components in 0-1-2 coordinate and Clarke components in 0- α - β coordinate.

1.2 Motivation for Research

Fault analysis studies are crucial. It provides important information, which is necessary for relay setting, circuit breaker selection, and the power system stability (Gungor, 1988; Kakilli, 2013). It usually involves unbalanced conditions of power system operation. Unsymmetrical analysis is usually carried out using symmetrical components (0-1-2). However, Clarke Transformation $(0-\alpha-\beta)$ may provide easier solutions for