

Design and Implementation of a Laboratory-Scale Single Axis Solar Tracking System

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Abstract

The renewable solar energy can be produced by using the Photovoltaic (PV) panel which converts the solar energy to the electrical energy. Global warming can be reduced by using the solar energy to generate electricity. Therefore in this project, an active type single axis solar tracking system is designed and constructed. The solar tracking system can enhance the amount of solar energy harvest throughout the day as compared to the fixed solar panel. A laboratory-scale single axis solar tracking system is developed to have a better understanding on the working mechanism of the solar tracking system. By using the laboratory-scale system, the system becomes portable and convenient to be allocated at the suitable workplace for solar tracking process. Moreover, the laboratory scale solar tracking system can be easily controlled and programmed by the users such as angle of rotation of the solar panel and the direction of rotation. In this project, microcontroller is used as an integrated control unit and the plant is actuated by the DC geared motor.

The validity of the laboratory-scale single axis solar tracking system was examined experimentally. The solar tracking system operates by rotating to the desired angle in every hour. The workspace of the solar tracking system is determined and identified. The solar tracking system workspace must be identified and examined carefully before the installation to prevent any accidents occurred during operation. This research is important for Faculty of Electrical Engineering of Universiti Teknikal Malaysia Melaka (UTeM) to identify the safety workspace for the solar tracking system due to the actual solar tracking system plant is still cannot be operated because of the limited workspace.

Keywords. Solar Tracking System; MPPT; Single Axis

1. Introduction

The world population is increasing throughout the year and the electricity demand is also growing rapidly. Most of the countries use fossil fuels such as crude oil to generate the electricity and the carbon dioxide, CO_2 will be produced and causes global warming. The temperature on our earth is increasing throughout the year and the scientists estimate that the world temperature will raise up six degree if the greenhouse gases emissions are let uncontrollable [1]. Solar energy has more benefits compare to other renewable energy due to solar energy is inexhaustible and environment friendly. The solar energy can be converted into electricity by using the photovoltaic panels [2]. Malaysia government is supportive in development of renewable energy such as solar energy by developing the Sustainable Energy Development Authority (SEDA Malaysia). SEDA is a statutory body under the Ministry of Energy, Green Technology and Water. Malaysia Feed in Tariff (FiT) scheme is managed by SEDA Malaysia. The house owners who install the home solar system can sell the generated electricity to Tenaga Nasional Berhad (TNB) through the national grid network [3]. In this project, an active type single axis solar tracking system will be designed and developed. By constructing the laboratory-scale single axis solar tracking system, the electromechanical system of the solar tracking system can be studied. Besides, the laboratory-scale solar tracking system can be easily controlled by the users based on the understanding of the system. Moreover, the laboratory-scale solar tracking system is convenient to move for doing the experiment. The laboratory-scale solar tracking system can also be used in the teaching and learning process for understanding the behavior and operation of the solar tracking system.

2. BACKGROUND STUDY

Malaysia is very suitable to install the solar PV system due to the coordinate on the earth. Malaysia is at the equator of the earth which lies between $1^{\circ}N$ and $7^{\circ}N$, and $100^{\circ}E$ and $119^{\circ}E$. Malaysia receives more

than 10 hours sunlight every day and 6 hours direct sunlight which has the solar irradiation level between $800\text{W}/\text{m}^2$ and $1000\text{W}/\text{m}^2$. Due to the long period of receiving sunlight, Malaysia has a great potential to develop the solar energy[4-5]. The active type solar tracking system consists of controller, sensor and actuator to function the system. Active type solar tracking system is chosen in this research due to it has the greater accuracy as compared to passive type solar tracking system [5]. In Malaysia, the sunlight is always directly located on the land and its solar radiance does not vary by seasons. Malaysia is at equator and do not have four seasons' occur; therefore, it is suitable to use the single axis tracking system instead of dual axis tracking system. In Malaysia, the altitude of the sun's position does not change much [4]. According to [6] and [7], if the altitude is slightly misaligned, it only causes less power loss. According to [8], the greatest sun elevation difference in UTeM, Melaka is only 13.27° which lead to only less than 3.4% of power loss. Table 1 shows the direct power loss due to solar panel misalignment is shown where $\text{loss}=1-\cos(\theta)$ [6].

Table 1. Direct power loss (%) due to misalignment (angle) [6]

| Misalignment (θ°) | Direct power loss (%) |
|------------------------------------|-----------------------|
| 0 | 0 |
| 1 | 0.015 |
| 3 | 0.14 |
| 8 | 1 |
| 15 | 3.4 |
| 23.4 | 8.3 |
| 30 | 13.4 |
| 45 | 30 |
| 60 | >50 |
| 75 | >75 |

In this project, system is chosen solar tracking system compared to dual axis solar tracking system such as simpler mechanism, low installation cost and less maintenance is required.

single axis solar tracking rather than the dual axis system. Single axis solar has more beneficial as

According to Davidsson H. and Niko G. in [9-10], the flexible and laboratory scale solar tracking system can be used for the teaching facilities and provide an opportunity for the researchers to perform the research based on the solar energy. Furthermore, the laboratory scaled solar system can also be used as a basic set of tools or start up for the local researcher [10]. They can perform the installation and maintenance on the solar system independently without required any oversea expertise. The researchers can also enhance and improve the existing solar system by using the knowledge gained such as including the tracking system and maximum power point tracking (MPPT) controller into the system to increase its efficiency. The laboratory scale solar system is very important to the developing countries such as Africa countries. In Africa, there is less than 25% of the population who has access to electricity[9]. By introducing the small-scaled stand-alone PV system to the African, they can generate their own electricity by using the solar source which is always available and free [9]. The laboratory-scale solar tracking system can be used as a teaching utility in university and generate electricity in the rural area.

3. RESULTS AND DISCUSSION

Figure 1 shows the actual solar tracking system plant in FKE, UTeM with the dimension of 11800 (l) \times 6000 (w) mm and have the total surface area around 70m^2 . In this project, the laboratory-scale solar tracking system is scaled down to ratio 462: 1 in comparison to the actual plant. The dimension of the laboratory-scale solar panel is 450 (w) \times 340(l) mm (see Figure 2). The solar tracking mechanism is driven by DC geared motor. The schematic diagram of the DC motor geared mechanism is illustrated in Figure 3.

The relationship between the armature current, $i_a(t)$, the applied armature voltage, $e_a(t)$ and the back emf, $v_b(t)$, is :

$$R_a I_a(s) + L_a s I_a(s) + v_b(s) = E_a(s) \tag{1}$$



Figure 1. Actual solar tracking system plant in UTeM, FKE

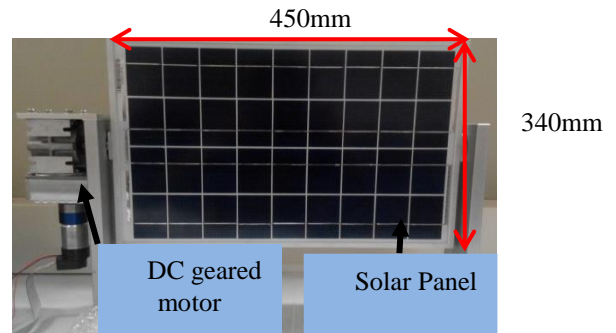
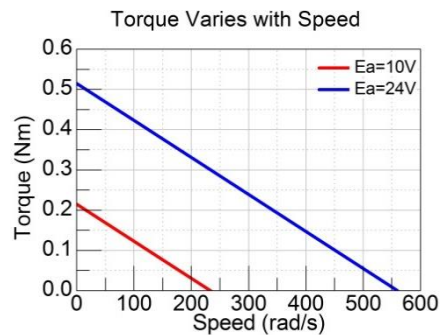
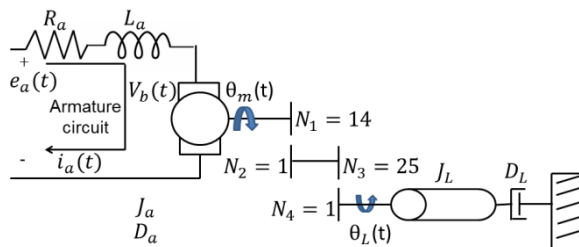


Figure 2. Laboratory-Scale Solar tracking system



Figure

The mechanism can be descri

bed in the transfer function:

$$\frac{\theta_m(s)}{E_a(s)} = \frac{K_t / (R_a J_m)}{s \left[s + \frac{1}{J_m} \left(D_m + \frac{K_t K_b}{R_a} \right) \right]} \tag{2}$$

Table 2. Parameter of the DC geared motor mechanism

| | |
|----------------------------|---------------------------|
| Equivalent inertia, J_m | 2731.75 kgm^2 |
| Equivalent damping, D_m | 641 $\times 10^3 Nms/rad$ |
| Terminal resistance, R_a | 2 Ω |
| Back-EMF constant, K_b | 42.88 $mV/rads^{-1}$ |
| Torque constant, K_t | 42.90 mNm/A |

After substitute the value into the Equation 2, the overall DC geared motor transfer function is:

$$\frac{\theta_m(s)}{E_a(s)} = \frac{7.85 \times 10^{-6}}{s(s + 234.68)} \tag{3}$$

Based on Figure 4, when the armature voltage, e_a is reduced to 10V, the motor torque and speed are reduced. However, the geared motor still has the sufficient torque to rotate and hold the load at the static position. The performance of the laboratory-scale solar tracking system is validated by conducting series of experiment at the selected workplace at FKE, UTeM. An experiment has been conducted on March 31, 2015, and Figure 5 shows the solar irradiance level in UTeM, where the weather was partially sunny and cloudy. From 0800 until 1030, the solar irradiance level is increasing and the solar output also increased as shown in Part A in Figure 5 and 6. The power output in Part A (see Figure 6) decreases from 0930 to 1030 because the solar panel is shaded by the fences at the experimental location. The high solar irradiance level at the noon time produces the maximum power output as can be seen at Part B (Figure 6). Unfortunately, the

solar irradiance levels are not constant due to the cloudy condition. In Part C (Figure 6), the power output is low due to the cloudy condition and it started to rain at 1600. This condition can be evidenced by the solar irradiation level in Figure 5. The energy output obtained by the solar panel is 74.3Wh and the energy usage by the solar tracking system only 73.68Wh. It has save around 0.85% energy output.

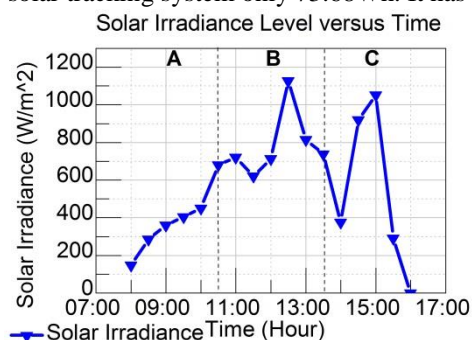


Figure 5. Solar Irradiance Level versus time graph

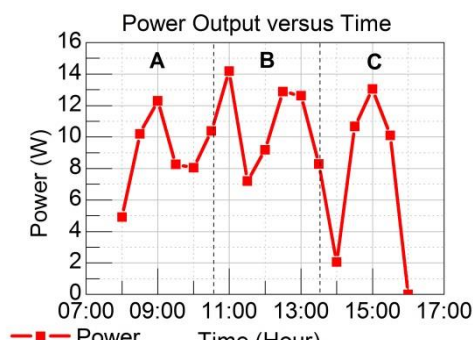


Figure 6. Power Output versus time graph

4. CONCLUSION

The laboratory-scale single axis solar tracking system was successfully designed and constructed. The workspace limitation of the solar tracking system can be identified and determined by using the laboratory-scale solar tracking system. The laboratory-scale solar tracking system can be used in the teaching and learning process. Although the energy output is low at the cloudy condition, but the designed solar tracking system still able to be used as a stand-alone solar tracking system due to the low power consumption of the mechanism. The solar tracking system can be tested at the open area to prevent from shaded to enhance the performance of the system.

5. REFERENCES

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