

High Impedance Fault Detection on Power Distribution Feeder

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Abstract – This paper presents an intelligent algorithm using a Takagi Sugeno-Kang (TSK) fuzzy modeling approach based on subtractive clustering to detect high impedance fault. High impedance fault (HIF) is abnormal event on electric power distribution feeder which does not draw enough fault current to be detected by conventional protective devices. The algorithm for HIF detection based on the amplitude ratio of second and (3rd, 5th, 7th, 9th, 11th) harmonics to fundamental is presented.

Fast Fourier Transformation (FFT) is used to extract the feature of the fault signal and other power system events. The effect of capacitor banks switching, non-linear load current, no-load line switching and other normal event on distribution feeder harmonics is discussed. HIF and other operation event data were obtained by simulation of a 13.8 kV distribution feeder using PSCAD. The results show that the proposed algorithm can distinguish successfully HIFs from other events in distribution power system. Copyright © 2012 Praise Worthy Prize S.r.l. - All rights reserved.

Keywords: High Impedance Faults, FFT, TSK Fuzzy Modeling, Power Distribution Feeder

Nomenclature

ANFIS	Adaptive Neural Fuzzy Inference System
ANN	Artificial Neural Network
DFT	Discrete Fourier Transform
DST	Discrete S-Transform DST
DTT	Discrete Wavelet Transform
DWT	Discrete Time-Time Transform
FFT	Fast Fourier Transform
FIS	Fuzzy Inference System
HIF	High Impedance Fault
RBFN	Radial Basis Function Network
RMSE	Root Mean Squared Error
TSK	Takagi Sugeno-Kang

I. Introduction

A High Impedance Fault (HIF) is a weird event and difficult to detect on electric power distribution feeder [1]. A high impedance ground fault results when a primary conductor makes poor electrical contact with a road surface, sod, tree limb, sidewalk, with some other surface, or object which restricts the flow of fault current to a level lower than that reliably detectable by conventional over current devices.

The resulting level of fault current is usually less than the normal current (about 10 to 50 A) of the electric power distribution feeder [1], the failure of HIF detection leads to serious threat in electric shock to human beings and potential fire hazards. HIF does not usually pose any risk to the electric power distribution feeder; however, the protection against them desirable.

The nature of HIFs has been studied since the early 1970's with the hope of discovery some characteristic in the current or voltage waveform that would make detection possible and practical [1].

HIF has many characteristics, the most two characteristics are the low current and arcing. Arcing is the due of air gaps because of the loose contact made with the ground or a grounded object. When the air gap breaks down, a high potential is produced over a short distance and the sustainable current level in the arc is not sufficient to be reliably detected by conventional means.

There are some other electrical events that behave like the HIF (capacitor bank operation where capacitors in power systems are used to supply reactive power for the purpose of loss minimization and voltage profile improvement [2], air switching operation, nonlinear load and starting induction motor), the algorithm which proposed to detect HIF should have ability to discriminate between HIF from other normal event in power distribution system. Most of the detection methods require extensive computation in the reprocessing stage for feature extraction of the input signals. Then a strategy is applied to obtain detection parameters.

Through the past decades, protection engineers and researchers have tried to find a complete solution to this type of fault. The fault has many characteristics like presence of harmonics and high frequency components, detection techniques aim to identify useful features of HIF from the pattern of the voltage or current signals associated. Many detection algorithms have been proposed to detect HIF, some of these have used

frequency-based to extract relevant features of the harmonic components [3]–[7] other have utilized time–frequency-based features to examine the transient phenomena of HIFs signals in both the time and frequency domains [8]–[15], the extracted features usually can be obtained after process the signals with one of methods of signal processing like discrete Fourier transform (DFT), discrete wavelet transform (DWT) and some other time–frequency analysis methods such as discrete S-transform (DST) and discrete time–time transform (DTT) [15].

In the research work [13], a method for HIF detection based on the nonlinear behaviour of current waveforms is presented. This method uses a wavelet multi-resolution signal decomposition method for feature extraction and an adaptive neural fuzzy inference system (ANFIS) for identification and classification. In [12] Wavelet transform and principal component analysis are used for feature extraction/selection. A fuzzy inference system is implemented for fault classification and a genetic algorithm is applied for input membership functions adjustment.

In [16] the author uses (ANFIS) as a classifier to detect HIF. The 3rd harmonics, magnitude and angle, for the 3 phase currents are uses as features of HIF. And in [17] a collection of dominant key harmonic signals forms the basis for a ‘feature’ or ‘diagnostic’ vector instead of a single dominant harmonic signal. Fast Fourier Transform (FFT) is used to extract the vector comprising the 3rd and 5th harmonics of the voltage, current and power signals are developed.

Neural networks and fuzzy inference systems are complementary technologies in the design of adaptive intelligence system. Artificial Neural Network (ANN) learns from scratch by adjusting the interconnections between layers. Fuzzy Inference System (FIS) is a popular computing framework based on the concept of fuzzy set theory, fuzzy if-then rules, and fuzzy reasoning.

A neuro-fuzzy system is simply a fuzzy inference system trained by a neural network-learning algorithm.

The learning mechanism fine-tunes the underlying fuzzy inference system. Fuzzy system faces difficulties like a lack of completeness of the rule base and a lack of definite criteria for selection of the shape of membership functions, their degree of overlapping, and the levels of data quantization. Some of these problems can be solved if the neural technique is used for fuzzy reasoning.

This paper describes fault detection of HIF using Adaptive Neural subtractive Clustering Fuzzy Inference system as classifier. FFT is used to extract the features and the data for training and testing the ANFIS was produced by simulation of 13.8kV distribution feeder using PSCAD.

II. ANFIS Classification Strategy

ANFIS is a fuzzy Sugeno model of integration where the final fuzzy inference system is optimized via the

ANNs training. ANFIS can be viewed as a class of adaptive networks which are functionally equivalent to fuzzy inference system. It maps inputs through input membership function and associated parameters, and then through output membership function to outputs. ANFIS uses back-propagation or a combination of least square estimation and back-propagation for membership function parameter estimation.

The most important point in data classification by ANFIS is designing of fuzzy rules. To solve this problem, data clustering algorithms are used to categorize and organize data. The clustering in the fuzzy system is useful for reducing the dimension of fuzzy system rules while still representing the overall system.

Clustering partitions a data set into several clusters where each data points in a cluster has more similarity than the one among the clusters. In neuro-fuzzy systems, clustering is used to determine the initial locations and the number of IF-THEN rules. There are several clustering techniques that are used for this purpose and the most common ones are: K- means, fuzzy C-means, mountain clustering method and subtractive clustering. In this study, subtractive clustering is used in which each cluster represents one independent rule [18].

II.1. Subtractive Clustering

A Data clustering is a process of putting similar data into groups. A clustering algorithm partitions a data set into several groups such that the similarity within a group is larger than among groups. Clustering algorithms are used extensively not only to organize and categorize data, but are also helpful for model construction and data compression.

Clustering techniques are used in conjunction with radial basis function networks or fuzzy modeling primarily to determine initial location for radial basis functions or fuzzy if-then rules. There are different clustering technique such as k-means clustering, fuzzy c-means clustering, mountain clustering and subtractive clustering.

If there is no clear idea how many clusters there should be for a given set of data, subtractive clustering is a fast, one-pass algorithm for estimating the number of clusters and the cluster centers in a set of data.

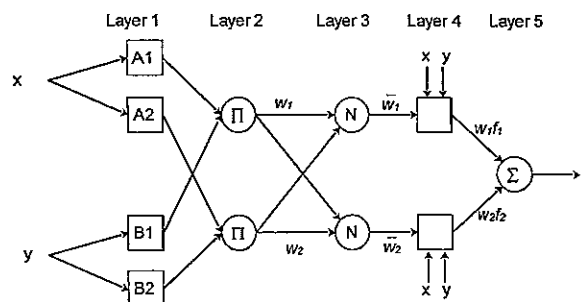


Fig. 1. The general of ANFIS used classification

Consider a collection of n data points in an m -dimensional space. Without loss of generality, the data points are assumed to have been normalized within a hypercube. Since each data point is a candidate for cluster centers, a density measure at data point x_i is defined as:

$$D_i = \sum_{j=1}^n \exp\left(-\frac{x_i - x_j^2}{(r_a/2)^2}\right) \quad (1)$$

where r_a is a positive constant. Hence a data point will have a high density value if it has many neighbouring data points. The radius r_a defines a neighbourhood; data points outside this radius contribute only slightly to the density measure. After the density measure of each data point has been calculated, the data point with the highest density measure is selected as the first cluster center. Let x_{c1} be the point selected and D_{c1} its density measure. Next the density measure for each data point x_i is recalculated by the formula:

$$D_i = D_i - D_{c1} \exp\left(-\frac{\|x_i - x_{c1}\|^2}{(r_b/2)^2}\right) \quad (2)$$

where r_b is a positive constant. Therefore, the data points near the first cluster center x_{c1} will have significantly reduced density measures, thereby making the points unlikely to be selected as the next cluster center. The constant r_b defines a neighbourhood that has measurable reductions in density measure. The constant r_b is normally larger than r_a to prevent closely spaced cluster centers; generally r_b is equal to $1.5 r_a$. After the density measure for each data point is recalculated, the next cluster center x_{c2} is selected and all of the density measures for data points are recalculated again. This process is repeated until a sufficient number of cluster centers are generated.

When applying subtractive clustering to a set of input-output data, each of the cluster centers represents a prototype that exhibits certain characteristics of the system to be modeled. These cluster centers would be reasonably used as the centers for the fuzzy rules' premise in a zero-order Sugeno fuzzy model, or radial basis functions in a Radial Basis Function Network (RBFN). For instance, assume that the center for the i -th cluster is c_i in an M dimension. The c_i can be decomposed into two component vectors p_i and q_i , where p_i is the input part and it contains the first N element of c_i ; q_i is the output part and it contains the last $M - N$ elements of c_i .

Then given an input vector x , the degree to which fuzzy rule i is fulfilled is defined by:

$$u_i = \exp\left(-\frac{\|x - P_i\|^2}{(r_a/2)^2}\right) \quad (3)$$

this is also the definition of the i -th radial basis function if we adopt the perspective of modeling using RBFNs.

Once the premise part (or the radial basis functions) has been determined, the consequent part (or the weights for output unit in an RBFN) can be estimated by the least-squares method. After these procedures are completed, more accuracy can be gained by using gradient descent or other advanced derivative based optimization schemes for further refinement [18].

III. System Modeling

III.1. Distribution Feeder

A 13.8 kV distribution feeder was performed in PSCAD/EMTDC. That consists of a substation and three distribution feeders with radial network. The schematic diagrams are given in Fig. 2.

The generator is of 30 kV and 10 MV connected to the transformer with 30/13.8 kV and 10 MVA. The distribution network operates at 13.8 kV voltages. The distribution line is a 20 km long continuously transposed line. The 6-pulse rectifier is used to represent the nonlinear load. The simulation models are developed using PSCAD and the sampling rate chosen is 15.36 kHz.

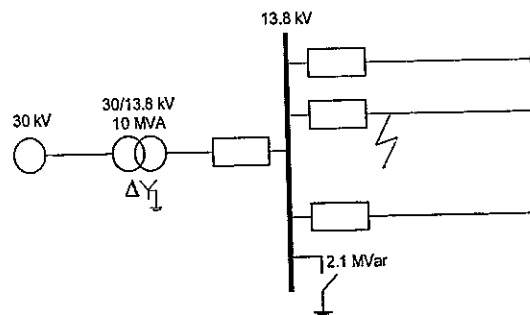


Fig. 2. Three phase distribution feeder

The arcing and nonlinear characteristics of the current signals due to HIFs are similar to other events like load changes and switching operations. Therefore, the simulation of distribution system has been included linear load, non-linear loads and the effect of switching operation, the transient phenomena produced by capacitor switching similar to those of HIFs in frequency domain, so it is necessary to test the reliability of any HIF algorithm under this event.

Many of capacitor energisation events have been taken into consideration in the studied distribution system. The conditions for these simulations are summarized in Table I, where for each case, the current waveform on the feeder is calculated and processed.

III.2. HIF Simulation

In the past, there are several models of HIF have proposed.

TABLE I
THE CONDITIONS FOR THESE SIMULATIONS ARE SUMMARIZED IN

Event	Simulation conditions
Sending and receiving end capacitor bank operation	operation conditions: on and off Load levels: 30, 70 and 100 percent of the full load Source voltage phase angle: (0, 180) Sending Capacitor operation: 2.1 and 4.2 MVar Receiving Capacitor operation: 2.1 MVar Existing sending / receiving capacitor: 0 and 2.1 MVar
Load operation on the feeder	operation conditions: three and single phase Load levels operation: 30-70, 70-100 percent of the full load Source voltage phase angle: (0, 180) Existing sending / receiving capacitor: 0, 2.1 and 4.2 MVar
Non-linear load operation on the feeder	operation conditions: three phase Load levels operation: 30-70, 70-100 percent of the full load Source voltage phase angle: (0, 180) Existing sending / receiving capacitor: 0, 2.1 and 4.2 MVar

All of these are based on Emanuel arc model and researchers have tried to complete it and come up to a better model for HIF. A simplified Emanuel model was introduced in 2003. The Two varying resistors were used to represent the fault resistance. A simplified two-diode model of HIF, shown in Fig. 3[4]. It was used to generate different HIF currents by changing the parameters (resistors and DC source). Resistances ranging from 50 to 1500 ohms were varied and The DC source values were selected from 1 to 10 kV, which led to current value of the simulated HIFs in the range of 8–300 A. Fig. 4(a) shows that real measured HIF current waveform extracted from [19] and Fig. 4(b) shows the simulated waveform current. The qualitative comparison indicates that there is a relatively good correspondence between the real and simulation waveforms.

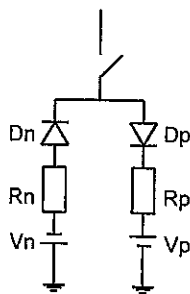


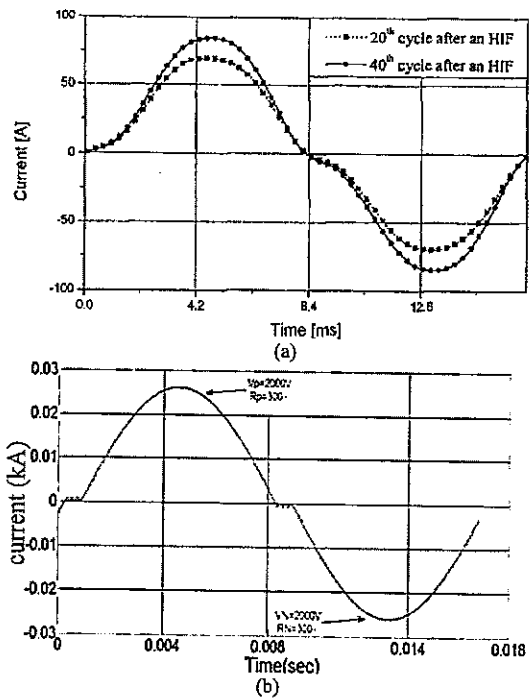
Fig. 3. A simplified two-diode model of HIF

IV. The Proposed Algorithm

The proposed algorithm includes three important parts: input data preparation, features generation and fault classification. Input data preparation part is described in simulation section. The rest parts are detailed in the next section. Fig. 5 showed the Structure of the proposed algorithm.

IV.1. Features Generation

On the modeled distribution system, different operation conditions have been simulated by using PSCAD/ EMTDC.



Figs. 4. Comparison of simulated and measured HIF currents
(a) Real waveform
(b) Simulated waveform

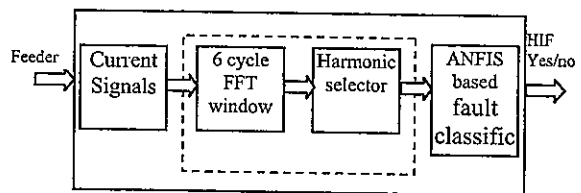


Fig. 5. Structure of the proposed algorithm

The simulated data then were transferred to MATLAB to complete the rest algorithm. The main goal of algorithm is to discriminate between HIFs and other similar waveforms.

In this algorithm, the current waveforms of distribution power are used only to extract the features of HIFs, but not on voltage waveforms. The discrimination

is based on the amplitude of fundamental and other harmonics current waveforms in the frequency domain. A Fast Fourier Transform (FFT) method is used for feature extraction.

The analysis is focused on current waveform which is obtained from the distribution power system feeder. In the frequency domain, odd harmonics, such as the 3rd, 5th, 7th and 9th, are predominant also some even harmonics, such as 2nd, have significant amplitudes.

However, the fundamental harmonic is decreased when the fault is occurred.

A normal current waveform, when a capacitor bank is present, appears no significant varies in phase current in the amplitude, the odd harmonics are predominant also even harmonics can be seen to some extent. In this paper, various waveforms were obtained by changing different parameters.

When all these waveforms were obtained, useful relevant data were used to find the features that were common to all and can discriminate HIF from other signals. These investigations led us to define the following features.

- 1- The ratio of harmonics amplitude (2nd, 3rd, 5th, 7th, 9th and 11th) to the fundamental harmonic amplitude:

$$f_1 = \frac{I_2}{I_1} \quad (4)$$

$$f_2 = \frac{I_3}{I_1} \quad (5)$$

$$f_3 = \frac{I_5}{I_1} \quad (6)$$

$$f_4 = \frac{I_7}{I_1} \quad (7)$$

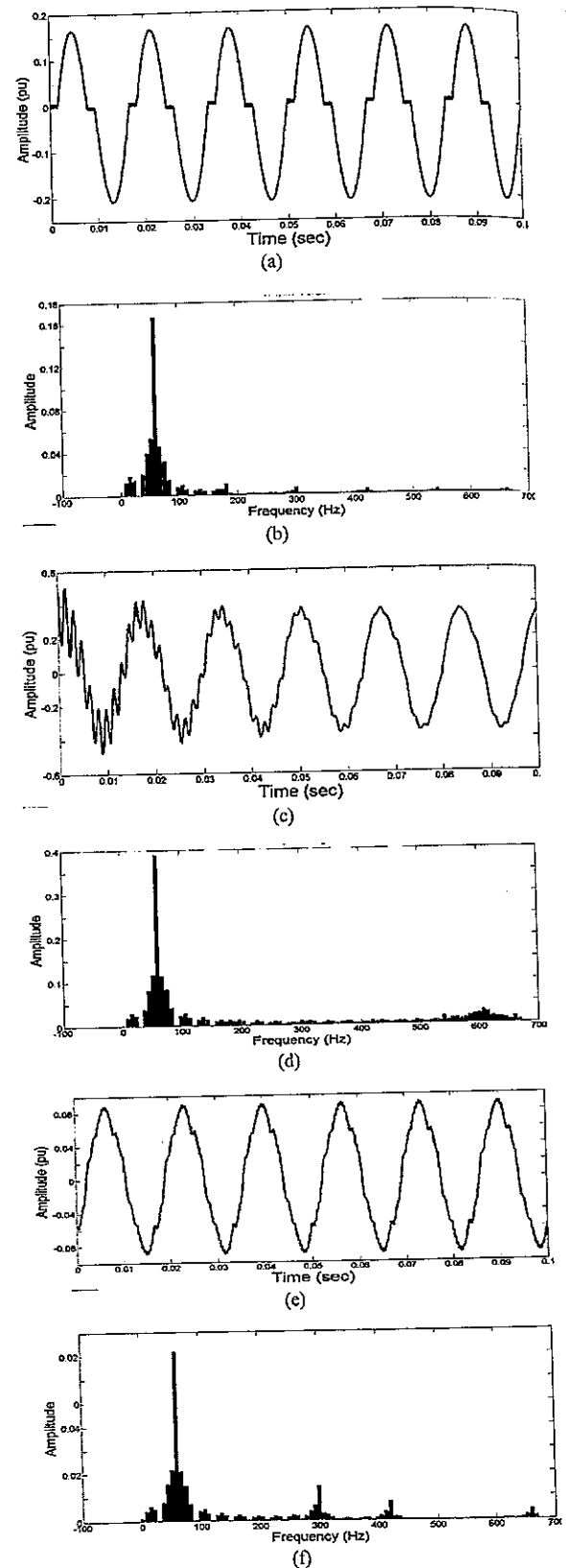
$$f_5 = \frac{I_9}{I_1} \quad (8)$$

$$f_6 = \frac{I_{11}}{I_1} \quad (9)$$

where $I_2, 3, 5, 7, 9$ and 11 represent the 2nd, 3rd, 5th, 7th, 9th and 11th harmonics amplitude of the signal respectively, I_1 represent the fundamental harmonic amplitude, and f_i represent the extracted features.

Gather all the extracted features to obtain one vector which represent the input data to training the adaptive neural subtractive clustering fuzzy system.

The typical signals of HIF fault current under linear load and with capacitor bank also signal of nonlinear current and their spectrum is shown in Figs. 6(a), (b), (c), (d), (e) and (f) respectively.



Figs. 6. Signals of the Feeder
 (a),(c) The typical signals of HIF fault current under linear load and with capacitor bank, (b),(d) FFT for signals in a and b (e),(f) The typical signal of nonlinear load and its FFT

TABLE I
 SAMPLES OF INPUT AND OUTPUT DATA SETS USED FOR TRAINING THE FS BASED SYSTEM

F1	F2	F3	F4	F5	F6	OUTPUT
0.003121	0.00436	0.007109	0.01414	0.036308	0.000994	1
0.008485	0.012223	0.018476	0.030183	0.057404	0.001332	1
0.011268	0.015866	0.022758	0.034506	0.060539	0.001427	1
0.012416	0.016979	0.023728	0.035224	0.060891	0.001465	1
0.012481	0.017005	0.023701	0.035121	0.060648	0.001479	1
0.032304	0.000301	0.027076	0.080406	0.001042	0.00205	0
0.037172	0.000244	0.039103	0.102821	0.001128	0.001989	0
0.012301	0.000266	0.007466	0.022985	0.000754	0.001581	0
0.03542	0.000333	0.023708	0.078716	0.00105	0.002079	0
0.012821	0.000265	0.007728	0.023967	0.000752	0.001565	0
0.000114	0.000123	0.000145	0.000195	0.000357	0.000849	0
0.047463	0.000373	0.029474	0.101041	0.001189	0.00214	0
0.010443	0.000242	0.0076	0.019797	0.000724	0.001517	0
0.000531	0.000161	0.00051	0.000504	0.0005	0.001105	0
0.037024	0.000355	0.018043	0.073426	0.001005	0.001969	0
0.020723	0.000322	0.041246	0.088709	0.000888	0.001642	0
0.009049	0.000153	0.006591	0.013467	0.00061	0.001311	0
0.019342	0.000364	0.038926	0.083703	0.000848	0.001603	0
0.014728	0.000292	0.02328	0.050131	0.00078	0.001563	0
0.0195	0.000375	0.03918	0.084282	0.000871	0.001637	0

IV.2. Classification

Cluster analysis is an exploratory data analysis tool which aims at sorting different objects into groups in a way that the degree of association between two objects is maximal if they belong to the same group and minimal otherwise. Given the above, cluster analysis can be used to discover structures in data without providing an explanation/interpretation. In other words, cluster analysis simply discovers structures in data without explaining why they exist.

Fuzzy Logic allows finding clusters in input-output training data. It can use the cluster information to generate a Sugeno-type fuzzy inference system that best models the data behavior using a minimum number of rules. The rules partition themselves according to the fuzzy qualities associated with each of the data clusters.

Then adaptive neural trains fuzzy inference system to develop IF-THEN fuzzy rules and determine membership functions for the input and output variables of the system under study. Also the neural network associated with the ANFIS trains the membership functions for minimization of error for fault classification.

In this study, adaptive neural subtractive clustering fuzzy logic is used as the classifier to serve for the fuzzy classification. Six extracted features are used to generate fuzzy inference system.

IV.3. Input Data Preparation

Building an adaptive neural fuzzy inference system involves two steps:

- Data preparation and,
- Rules generation and system training.

A) Clustering Data Preparation for ANFIS: Generating an ANFIS requires dividing the training data into two data sets:

- An input data set which has values for the six inputs ($F1, F2, F3, F4, F5, F6$) represent the amplitude ratio of second, third, fifth, seventh, ninth and eleventh harmonic to the fundamental harmonic). 570 input data points were selected from frequency domain of current signals. These points were placed into a single input data set.
- An output data set which has values for the one output (1 or 0). The output of ANFIS either 1 for high impedance fault occurs or zero for other normal event in power system. 570 output data points, corresponding to the selected input points. These points were placed into a single output data set. The other 570 input and output data points, which are different from the training data, will be used for testing purpose. Samples of input and output data sets used for training the ANFIS based system are given as Table II.

B) Rules Generation for ANFIS

The fuzzy subtractive clustering algorithm estimates the cluster centers in a set of data. It assumes each data point is a potential cluster center and calculates a measure of the likelihood that each data point would define the cluster center, based on the density of neighboring data points.

The radii variable is a vector of entries between 0 and 1 that specifies a cluster center's range of influence in each of the data dimensions, assuming the data falls within a unit hyperbox. Small radii values generally result in finding a few large clusters. Good values for radii are usually between 0.2 and 0.5. For this application, a value of 0.2 for all the radii was chosen.

This was found to result in fewer membership functions and higher processing speeds, without sacrificing accuracy.

A hybrid algorithm in ANFIS updates the consequent and premise parameters through a learning procedure

having two parts. In the first part, the entire training patterns are propagated, and the optimal consequent parameters are estimated by an iterative least mean square procedure Fig. 7 shows the architecture of the ANFIS. The hybrid method is used to optimize the fuzzy system parameter with a set of input and output (target) pairs.

An output vector can be produced by presenting an input pattern to the network. According to the difference between the produced output and the target vector, membership function shapes are adjusted to reduce the output error.

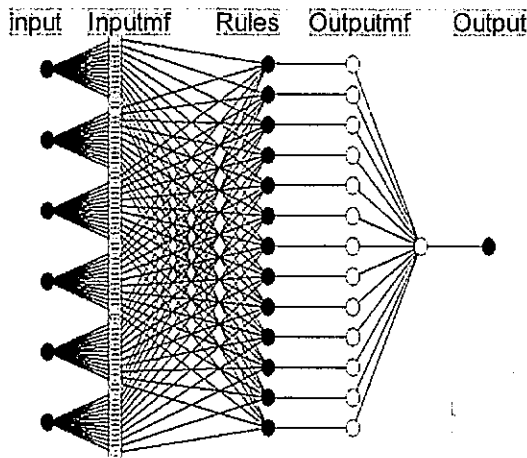


Fig. 7. The architecture of the ANFIS

IV.4. Results and Discussion

570 training cases were selected to train the network. The training sets included 138 HIF cases and the rest are non fault cases. The ANFIS has one output, the output is one when the system detect HIF case and is zero when other cases.

Fig. 8 shows output of the ANFIS to the training data. It is obvious that the HIF detection is successful to detect 97.8% of the fault cases and 99% for non fault cases. The MSE value of the model of training case is 0.0843. The system is trained properly and has categorized different cases effectively.

To evaluate the suitability of proposed algorithm, test data cases were fed to the ANFIS and the obtained output is shown in Fig. 9. It shows that the proposed method could classify different input categories successfully and reliably.

It is found that the proposed algorithm is capable to categorize 96.4% in case of HIF testing and 98% for non HIF testing cases. The MSE value of the model of testing case is 0.1163. Where the output of ANFIS for both cases is

- $I_{HIF} > 0.6$ for HIF conditions
- $I_{HIF} < 0.4$ for no fault conditions

Results of the testing phase, which demonstrates that the algorithm is reasonably reliable.

V. Conclusion

This paper has proposed a framework for the construction of an ANFIS approach based on subtractive clustering technique to detect HIF. In this paper a normal current waveform and HIF waveform of distribution power system were simulated with PSCAD software program.

The current signals were studied in frequency domains after being processed the signal with FFT to extract the relevant features. The ratio of amplitudes of the 2nd, 3rd, 5th, 7th, 9th and 11th harmonics to amplitude of fundamental harmonic was used as a data input to ANFIS. The results show that the ANFIS has the ability to discriminate clearly between fault and non fault events. The algorithm can be expanded and improved considering other comparable waveforms.

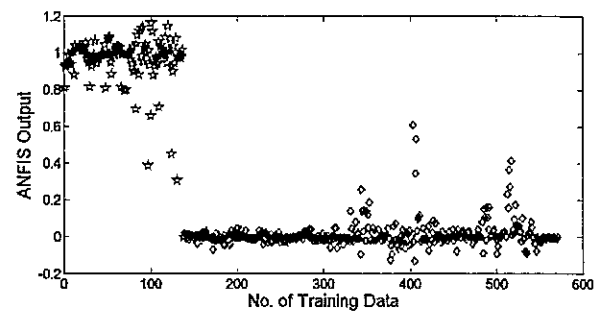


Fig. 8. Output of the ANFIS to the training data

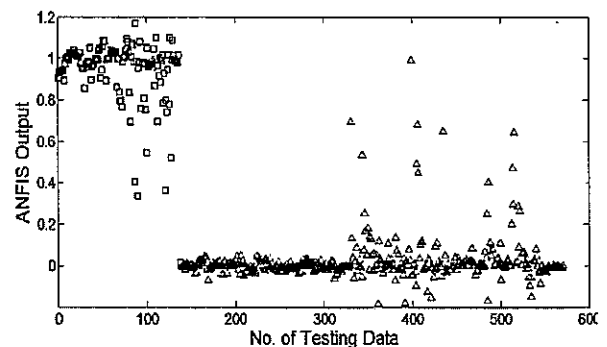


Fig. 9. Output of the ANFIS to the testing data

Acknowledgements

The authors wish to thank the Faculty of Electrical Engineering, UTeM for providing the facilities for this research.

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