# Trace parameters for Teichmüller space of genus 2 surfaces and mapping class group 


#### Abstract

We obtain a representation of the mapping class group of genus 2 surface in terms of a coordinate system of the Teichmüller space defined by trace functions.


1. Introduction. We identify $P S L(2, \mathbb{R})$ with the group of orientationpreserving isometries of the upper half plane $\mathbb{H}=\{z \in \mathbb{C}: \operatorname{Im} z>0\}$ equipped with the hyperbolic metric $|d z| /(\operatorname{Im} z)$.

A Fuchsian subgroup $G$ of $\operatorname{PSL}(2, \mathbb{R})$ is said to be of type $(2 ;-;-;-)$ ( $[5$, p. 38]) if $\mathbb{H} / G$ is a closed surface of genus 2 and the projection $\pi: \mathbb{H} \rightarrow \mathbb{H} / G$ is an unbranched covering. $G$ has a canonical generator system or a marking $E=(A, B, C, D)$ which satisfies

$$
[A, B][C, D]=1,
$$

where $[a, b]=a b a^{-1} b^{-1}$ is the commutator of $a$ and $b$, and 1 stands for the unit matrix. We call the pair $(G, E)$ a marked Fuchsian group of type $(2 ;-;-;-)$. Two marked Fuchsian groups $\left(G_{1}, E_{1}\right)$ and $\left(G_{2}, E_{2}\right)$ are equivalent if there exists a matrix $P \in \operatorname{PSL}(2, \mathbb{R})$ such that

$$
A_{2}=P^{-1} A_{1} P, B_{2}=P^{-1} B_{1} P, C_{2}=P^{-1} C_{1} P, D_{2}=P^{-1} D_{1} P,
$$

[^0]where $E_{j}=\left(A_{j}, B_{j}, C_{j}, D_{j}\right), j=1,2$. The Teichmüller space $\mathcal{T}_{2}$ of type $(2 ;-;-;-)$ is the space of all equivalence classes of marked Fuchsian groups of type $(2 ;-;-;-)$. Each marked Fuchsian group $(G, E)$ can be represented by a tuple $(A, B, C, D)$ of matrices in $S L(2, \mathbb{R})$ such that
\[

$$
\begin{equation*}
\operatorname{tr} A>0, \operatorname{tr} B>0, \operatorname{tr} C>0 \text { and } \operatorname{tr} D>0 \tag{1.1}
\end{equation*}
$$

\]

Therefore, for the rest of this paper, we always assume that $E=(A, B, C, D)$ consists of matrices satisfying (1.1). In this case $\operatorname{tr} A B$ and $\operatorname{tr} C D$ are both positive (this follows from $[5,33.17(\mathrm{~b})]$ ). In $[3]$ we considered the following traces as functions of $\left[(G, E=(A, B, C, D)]\right.$ in $\mathcal{T}_{2}$ :

$$
\begin{align*}
& a=\operatorname{tr} A, b=\operatorname{tr} B, z=\operatorname{tr} A B, u=-\operatorname{tr} A C D C^{-1} \\
& v=-\operatorname{tr} A C D^{2}, w=-\operatorname{tr} A C D, t=\operatorname{tr} C D \tag{1.2}
\end{align*}
$$

Since all non trivial elements of $G$ are hyperbolic, their traces take values in $\mathbb{R}_{>2}=\{x: x>2\}$. It is shown in [3] (see also [4]) that the mapping $\Phi: \mathcal{T}_{2} \rightarrow \mathbb{R}_{>2}^{7}$ defined by $\Phi([G, E])=(a, b, z, u, v, w, t)$ is an embedding and $a, b, z, u, v, w, t$ satisfy the identity

$$
\begin{equation*}
a w t+a^{2}+w^{2}+t^{2}+K^{2}+S^{2}+4-w \sqrt{\left(K^{2}+4\right)\left(S^{2}+4\right)}=0 \tag{1.3}
\end{equation*}
$$

where

$$
K=\sqrt{a b z-a^{2}-b^{2}-z^{2}} \text { and } S=\sqrt{u v t-u^{2}-v^{2}-t^{2}}
$$

The mapping class group $\mathcal{M} C_{2}$ is the group of isotopy classes of orienta-tion-preserving homeomorphisms of the orientable closed surface $S$ of genus 2. It is a subgroup of outer automorphisms of the fundamental group of $S$ (see [5]). $\mathcal{M} C_{2}$ acts on the Teichmüller space $\mathcal{T}_{2}$ by changing the marking. The purpose of this paper is to describe a generating system of $\mathcal{M C} C_{2}$ by using the coordinate-system $(a, b, z, u, v, w, t)$. It is an interesting observation that $\mathcal{M} C_{2}$ acts on $\mathcal{T}_{2}$ as a group of rational transformations.

## 2. Trace identities.

2.1. Basic trace identities. The matrices $A, B$ and $C$ in $S L(2, \mathbb{R})$ satisfy the following identities (see $[2, \S 3.4]$ ):
(I1) $\operatorname{tr} A=\operatorname{tr} A^{-1}$,
(I2) $\operatorname{tr} A B+\operatorname{tr} A B^{-1}=\operatorname{tr} A \operatorname{tr} B$,
(I3) $\operatorname{tr} A B C=\operatorname{tr} A \operatorname{tr} B C+\operatorname{tr} B \operatorname{tr} C A+\operatorname{tr} C \operatorname{tr} A B-\operatorname{tr} A \operatorname{tr} B \operatorname{tr} C-\operatorname{tr} A C B$.
We shall use repeatedly the following identities, which are consequences of (I1), (I2) and (I3) above:

$$
\begin{align*}
\operatorname{tr}[A, B] & =\operatorname{tr} A B A^{-1} B^{-1}  \tag{2.1a}\\
& =(\operatorname{tr} A)^{2}+(\operatorname{tr} B)^{2}+(\operatorname{tr} A B)^{2}-\operatorname{tr} A \operatorname{tr} B \operatorname{tr} A B-2 \\
\operatorname{tr} A B C B & =\operatorname{tr} A B \operatorname{tr} B C+\operatorname{tr} A C-\operatorname{tr} A \operatorname{tr} C  \tag{2.1b}\\
\operatorname{tr} A B C B^{-1} & =\operatorname{tr} A \operatorname{tr} C-\operatorname{tr} A C-\operatorname{tr} A B \operatorname{tr} B C+\operatorname{tr} B \operatorname{tr} A B C \tag{2.1c}
\end{align*}
$$

Let $G$ be a group generated by a finite number of matrices $A_{1}, \ldots, A_{n} \in$ $S L(2, \mathbb{R})$ and

$$
\begin{equation*}
\mathcal{S}=\left\{\operatorname{tr}\left(A_{i_{1}} A_{i_{2}} \cdots A_{i_{r}}\right): 1 \leq i_{1}<i_{2}<\cdots<i_{r} \leq n, 1 \leq r \leq n\right\} \tag{2.2}
\end{equation*}
$$

Then the following fact is well known (see [2, §3.5]).
Lemma 2.1. Let $g \in G$. Then $\operatorname{tr} g$ is an integer polynomial in $\mathcal{S}$.
2.2. Trace identities for genus 2 surface. Let $E=(A, B, C, D)$ be a marking of a Fuchsian group $G$ of type $(2 ;-;-;)$. Let $c=x_{1}=\operatorname{tr} C$ and $d=x_{2}=\operatorname{tr} D, x_{3}=\operatorname{tr} A C, x_{4}=\operatorname{tr} A D, x_{5}=\operatorname{tr} B C, x_{6}=\operatorname{tr} B D$, $x_{7}=\operatorname{tr} A B C, x_{8}=\operatorname{tr} A B D, x_{9}=\operatorname{tr} B C D$ and $x_{10}=\operatorname{tr} A B C D$. Then the set $\mathcal{S}$ for $G$ with respect to $(A, B, C, D)$ is

$$
\mathcal{S}=\left\{a, b, c, d, z, x_{3}, x_{4}, x_{5}, x_{6}, t, x_{7}, x_{8}, x_{9}, x_{10}\right\}
$$

The purpose of this section is to find expressions of $x_{1}, \ldots, x_{10}$ in $\{a, b, z, u, v$, $w, t\}$ of (1.2). Then by Lemma 2.1 we can express the trace of any element of $G$ in $\{a, b, z, u, v, w, t\}$. We shall apply this fact to obtain a representation of the mapping class group $\mathcal{M} C_{2}$ via rational transformations.
(1) Since $[A, B]=[C, D]^{-1}$, we obtain by (2.1a)

$$
\begin{equation*}
a b z-a^{2}-b^{2}-z^{2}=c d t-c^{2}-d^{2}-t^{2} \tag{2.3}
\end{equation*}
$$

Note that $\operatorname{tr}[A, B]=a^{2}+b^{2}+z^{2}-a b z-2<-2$, since $G$ is discrete (see, for example $[5,33 \mathrm{D}])$. In what follows $K=\sqrt{a b z-a^{2}-b^{2}-z^{2}}$.
(2) From $B A B^{-1}=C D C^{-1} D^{-1} A$ and the basic identity (I3) we obtain

$$
a=\operatorname{tr}\left((A C D) \cdot C^{-1} \cdot D^{-1}\right)=-w t+c x_{3}-u d+w c d-a
$$

and hence

$$
\begin{equation*}
2 a+w t-c x_{3}+u d-w c d=0 \tag{2.4}
\end{equation*}
$$

(3) From (I2), $v=-\operatorname{tr} A C D \cdot D=-(\operatorname{tr} A C D \operatorname{tr} D-\operatorname{tr} A C)=w d+x_{3}$ and so

$$
\begin{equation*}
x_{3}=v-d w . \tag{2.5}
\end{equation*}
$$

From this and (2.4) it follows that

$$
\begin{equation*}
2 a+w t-c v+u d=0 \tag{2.6}
\end{equation*}
$$

(4) From (I3),

$$
\begin{aligned}
-u & =\operatorname{tr} A \cdot C D \cdot C^{-1}=a d+t\left(\operatorname{tr} A C^{-1}\right)-w c-a t c-x_{4} \\
& =a d+t\left(a c-x_{3}\right)-w c-a t c-x_{4}
\end{aligned}
$$

It follows from this and (2.5) that

$$
\begin{equation*}
x_{4}=u+a d-t x_{3}-w c=u+a d-t v+t w d-c w . \tag{2.7}
\end{equation*}
$$

By substituting $d=u^{-1}(c v-2 a-w t)$ (see (2.6)) into (2.3) we obtain

$$
\left(u v t-u^{2}-v^{2}\right) c^{2}-(2 a+w t)(t u-2 v) c-\left(K^{2}+t^{2}\right) u^{2}-(2 a+t w)^{2}=0
$$

If this identity is regarded as a quadratic equation in $c$, it always has a negative root because

$$
u v t-u^{2}-v^{2}=\left(-\operatorname{tr}\left[C D^{-1} C^{-1} A^{-1}, A C D^{2}\right]-2\right)+t^{2}>t^{2}>0
$$

(see $[5,33 \mathrm{D}])$ and $-\left(K^{2}+t^{2}\right) u^{2}-(2 a+t w)^{2}<0$. Hence the condition $c=\operatorname{tr} C>2$ yields

$$
\begin{align*}
& c=\frac{(2 a+t w)(u t-2 v)+u \sqrt{(2 a+t w)^{2}\left(t^{2}-4\right)+4\left(K^{2}+t^{2}\right)\left(S^{2}+t^{2}\right)}}{2\left(S^{2}+t^{2}\right)}  \tag{2.8}\\
& d=\frac{c v-2 a-w t}{u}
\end{align*}
$$

where $S=\sqrt{u v t-u^{2}-v^{2}-t^{2}}$. By using (1.3) we see that $(2 a+t w)^{2}\left(t^{2}-4\right)$ $+4\left(K^{2}+t^{2}\right)\left(S^{2}+t^{2}\right)$ equals

$$
\begin{aligned}
& \left(\left(t^{2}-4\right) w+2 \sqrt{\left(S^{2}+4\right)\left(K^{2}+4\right)}\right)^{2} \\
& \quad=\left(\left(t^{2}-4\right) w+\frac{2\left(a w t+a^{2}+t^{2}+K^{2}+S^{2}+4\right)}{w}\right)^{2}
\end{aligned}
$$

Now from (2.8) we obtain

$$
\begin{align*}
& c=\frac{\left(K^{2}+S^{2}+t^{2}+a^{2}+4\right) u+w\left(2 a t u-2 a v-u w+t^{2} u w-t v w\right)}{w\left(S^{2}+t^{2}\right)} \\
& d=\frac{\left(K^{2}+S^{2}+t^{2}+a^{2}+4\right) v+w(2 a u+t w u-v w)}{w\left(S^{2}+t^{2}\right)} \tag{2.9}
\end{align*}
$$

By (2.5), (2.7) and (2.9), we can obtain the expressions of $x_{3}=\operatorname{tr} A C$ and $x_{4}=\operatorname{tr} A D$ in $(a, b, z, u, v, w, t)$,

$$
\begin{align*}
& x_{3}=-\frac{u w(2 a+t w)+v\left(4+a^{2}+K^{2}-w^{2}\right)}{S^{2}+t^{2}} \\
& x_{4}=(a d+u-c w)+t \frac{\left(4+a^{2}+K^{2}-w^{2}\right) v+w u(2 a+t w)}{S^{2}+t^{2}} \tag{2.10}
\end{align*}
$$

(5) From (I2) and (2.1c) applied to $B C D C^{-1}$ we obtain

$$
\begin{align*}
\operatorname{tr} B^{-1}\left(C D C^{-1}\right) & =b d-\operatorname{tr} B C D C^{-1}  \tag{2.11}\\
& =b d-\left(b d-x_{6}-x_{5} t+c x_{9}\right)=x_{6}+t x_{5}-c x_{9} .
\end{align*}
$$

From (I3), $\operatorname{tr} B^{-1} C D=b t-x_{9}$. Then, from the trace of $A B^{-1} A^{-1}=$ $B^{-1} C D \cdot C^{-1} \cdot D^{-1}$, (I2), (I3) and (2.11),

$$
\begin{aligned}
b & =\left(\operatorname{tr} B^{-1} C D\right) t+c \operatorname{tr} B^{-1} C+d \operatorname{tr}\left(B^{-1} C D \cdot C^{-1}\right)-\left(\operatorname{tr} B^{-1} C D\right) c d-b \\
& =\left(b t-x_{9}\right)(t-c d)+c\left(b c-x_{5}\right)+d\left(x_{6}+t x_{5}-c x_{9}\right)-b
\end{aligned}
$$

Hence

$$
(d t-c) x_{5}+d x_{6}-t x_{9}=2 b-b t^{2}+b c d t-b c^{2}
$$

(6) From (I2), $\operatorname{tr} A^{-1} C D=a t+w$, and from (I2) and (I3),

$$
\begin{aligned}
\operatorname{tr} B^{-1} A^{-1} \cdot C \cdot D & =z t+c \operatorname{tr} A B D^{-1}+d \operatorname{tr} A B C^{-1}-z c d-\operatorname{tr} B^{-1} A^{-1} D C \\
& =z t+c\left(z d-x_{8}\right)+d\left(z c-x_{7}\right)-z c d-\operatorname{tr} B^{-1} A^{-1} D C \\
& =z t+c d z-d x_{7}-c x_{8}-\operatorname{tr} B^{-1} A^{-1} D C
\end{aligned}
$$

Substituting these into the next equation obtained from $B^{-1} A^{-1} D C=$ $A^{-1} \cdot B^{-1} \cdot C D$ and (I3),

$$
\begin{aligned}
\operatorname{tr} B^{-1} A^{-1} D C= & a \operatorname{tr} B^{-1} C D+b \operatorname{tr} A^{-1} C D+z t-a b t-\operatorname{tr} B^{-1} A^{-1} C D \\
= & a\left(b t-x_{9}\right)+b(a t+w)+z t-a b t \\
& -z t-c d z+d x_{7}+c x_{8}+\operatorname{tr} B^{-1} A^{-1} D C
\end{aligned}
$$

we obtain

$$
d x_{7}+c x_{8}-a x_{9}=-a b t-b w+c d z
$$

(7) From $B^{-1} C D C^{-1}=\operatorname{tr} A B^{-1} A^{-1} D, \operatorname{tr} B^{-1}\left(C D C^{-1}\right)$ equals

$$
\begin{aligned}
\operatorname{tr} A B^{-1} A^{-1} D & =\operatorname{tr} B \operatorname{tr} A A^{-1} D-\operatorname{tr} A B A^{-1} D=b d-\operatorname{tr} D A B A^{-1} \\
& =b d-(\operatorname{tr} B \operatorname{tr} D-\operatorname{tr} B D-\operatorname{tr} B A \operatorname{tr} A D+\operatorname{tr} A \operatorname{tr} A B D) \\
& =x_{6}+z x_{4}-a x_{8}
\end{aligned}
$$

Here we have used (I2) and (2.1c). Then from (2.11),

$$
t x_{5}+a x_{8}-c x_{9}=z x_{4}
$$

(8) From $B A^{-1} B^{-1} C=A^{-1} D C D^{-1}$ and (I2), we have

$$
a c-\operatorname{tr} B A B^{-1} C=\operatorname{tr} B A^{-1} B^{-1} C=\operatorname{tr} A^{-1} D C D^{-1}=a c-\operatorname{tr} A D C D^{-1},
$$

and hence $\operatorname{tr} C B A B^{-1}=\operatorname{tr} A D C D^{-1}$. We have by using (2.1c)

$$
\begin{aligned}
\operatorname{tr} C B A B^{-1}= & \operatorname{tr} C \operatorname{tr} A-\operatorname{tr} A C-\operatorname{tr} B C \operatorname{tr} A B+\operatorname{tr} B \operatorname{tr} C B A \\
= & a c-x_{3}-z x_{5}+b(\operatorname{tr} C \operatorname{tr} B A+\operatorname{tr} B \operatorname{tr} C A+\operatorname{tr} A \operatorname{tr} C B \\
& -\operatorname{tr} A \operatorname{tr} B \operatorname{tr} C-\operatorname{tr} A B C) \\
= & a c-x_{3}-z x_{5}+b c z+b^{2} x_{3}+a b x_{5}-a b^{2} c-b x_{7}
\end{aligned}
$$

and

$$
\begin{aligned}
\operatorname{tr} A D C D^{-1}= & \operatorname{tr} A \operatorname{tr} C-\operatorname{tr} A C-\operatorname{tr} A D \operatorname{tr} D C+\operatorname{tr} D \operatorname{tr} A D C \\
= & a c-x_{3}-t x_{4}+d(\operatorname{tr} A \operatorname{tr} C D+\operatorname{tr} D \operatorname{tr} A C+\operatorname{tr} C \operatorname{tr} A D \\
& -\operatorname{tr} A \operatorname{tr} D \operatorname{tr} C-\operatorname{tr} A C D) \\
= & a c-x_{3}-t x_{4}+a d t+d^{2} x_{3}+c d x_{4}-a d^{2} c+w d .
\end{aligned}
$$

Thus we obtain
$(z-a b) x_{5}+b x_{7}=\left(b^{2}-d^{2}\right) x_{3}+(t-c d) x_{4}+b c z-a b^{2} c-a d t+a d^{2} c-w d$.
(9) We use $C^{-1} B A=\operatorname{tr} D C^{-1} D^{-1} A B$. Then from (I2) and (I3),

$$
\begin{aligned}
\operatorname{tr} C^{-1} B A & =z c-\operatorname{tr} C B A \\
& =z c-\left(c z+b x_{3}+a x_{5}-a b c-x_{7}\right)=-b x_{3}-a x_{5}+a b c+x_{7} .
\end{aligned}
$$

From (I2) and (2.1c) this equals

$$
\begin{aligned}
\operatorname{tr}\left(D C^{-1} D^{-1}\right) A B= & c z-\operatorname{tr} A B D C D^{-1} \\
= & c z-(\operatorname{tr} A B \operatorname{tr} C-\operatorname{tr} A B C-\operatorname{tr} A B D \operatorname{tr} C D \\
& +\operatorname{tr} D \operatorname{tr}(A B \cdot D \cdot C)) \\
= & x_{7}+t x_{8}-d\left(z t+d x_{7}+c x_{8}-z c d-x_{10}\right) .
\end{aligned}
$$

Hence we obtain

$$
-a x_{5}+d^{2} x_{7}+(c d-t) x_{8}-d x_{10}=-a b c+b x_{3}-d t z+c d^{2} z
$$

(10) We use $D^{-1} C^{-1} B=C^{-1} D^{-1} A B A^{-1}$. From (I2), $\operatorname{tr} D^{-1} C^{-1} B=$ $b t-x_{9}$ and from (I2), (2.1c) and (I3),

$$
\begin{aligned}
\operatorname{tr} C^{-1} D^{-1} A B A^{-1}= & t b-\operatorname{tr}(D C) A B A^{-1} \\
= & t b-(t b-\operatorname{tr} D C B-\operatorname{tr} D C A \operatorname{tr} A B+\operatorname{tr} A \operatorname{tr}(D \cdot C \cdot A B)) \\
= & \left(d x_{5}+c x_{6}+b t-b c d-x_{9}\right)+z\left(d x_{3}+c x_{4}+a t-a c d+w\right) \\
& -a\left(z t+d x_{7}+c x_{8}-z c d-x_{10}\right)
\end{aligned}
$$

we obtain

$$
d x_{5}+c x_{6}-a d x_{7}-a c x_{8}+a x_{10}=b c d-z d x_{3}-z c x_{4}-z w .
$$

Let

$$
M=\left(\begin{array}{cccccc}
d t-c & d & 0 & 0 & -t & 0 \\
0 & 0 & d & c & -a & 0 \\
t & 0 & 0 & a & -c & 0 \\
z-a b & 0 & b & 0 & 0 & 0 \\
-a & 0 & d^{2} & c d-t & 0 & -d \\
d & c & -a d & -a c & 0 & a
\end{array}\right), \vec{x}=\left(\begin{array}{c}
x_{5} \\
x_{6} \\
x_{7} \\
x_{8} \\
x_{9} \\
x_{10}
\end{array}\right)
$$

and

$$
\vec{v}=\left(\begin{array}{c}
2 b-b t^{2}+b c d t-b c^{2} \\
-a b t-b w+c d z \\
z x_{4} \\
\left(b^{2}-d^{2}\right) x_{3}+(t-c d) x_{4}+b c z-a b^{2} c-a d t+a c d^{2}-w d \\
-a b c+b x_{3}-d z t+c d^{2} z \\
b c d-d z x_{3}-c z x_{4}-z w
\end{array}\right) .
$$

From the results (5) $-(10)$ we obtain $M \vec{x}=\vec{v}$. The matrix $M$ is singular, if $a=c$. However, by using (2.4) and (2.7) we can deduce:

$$
\begin{align*}
& x_{5}=\frac{c\left(2 b+a^{2} b-2 a z+b K^{2}\right)-t u z+d w\left(a b+z+z K^{2}\right)-v\left(a b+z K^{2}\right)}{K^{2}+a^{2}},  \tag{2.12}\\
& x_{6}=\frac{2(a d z-b d)-u\left(a b+K^{2} z\right)+t v\left(a b+z+K^{2} z\right)+(c-d t) w\left(a b+z+K^{2} z\right)}{K^{2}+a^{2}}, \\
& x_{7}=\frac{-2 c z-b t u+a v z+w d(b-a z)}{K^{2}+a^{2}}, \\
& x_{8}=\frac{d\left(K^{2}+a^{2}+2\right)+a u z+v t(b-a z)+w(b c-b d t-a c z+a d t z)}{K^{2}+a^{2}}, \\
& x_{9}=\frac{t\left(2 b+a^{2} b-2 a z+b K^{2}\right)+d v z+w\left(a b+K^{2} z\right)+u(c z-d t z)}{K^{2}+a^{2}}, \\
& x_{10}=\frac{-2 t z+b(c-d t) u+b d v-a w z}{K^{2}+a^{2}} .
\end{align*}
$$

Expressions for $x_{3}$ and $x_{4}$ are obtained in (2.10).
3. Mapping class group. Let $G$ be a group of type $(2 ;-;-;-)$ and $E=$ $(A, B, C, D)$ a marking (or a canonical generator system) of $G$. We consider the following changes of marking:

$$
\begin{array}{ll}
\omega_{1}(E)=\left(A B^{-1}, B, C, D\right), & \omega_{2}(E)=(B, B A, C, D) \\
\omega_{3}(E)=\left(B^{-1} C A, B, C, B^{-1} C D\right), &  \tag{3.1}\\
\omega_{4}(E)=\left(A, B, C D^{-1}, D\right), & \omega_{5}(E)=(A, B, C, D C)
\end{array}
$$

Each $\omega_{j}$ induces an automorphism of $G$, which is also denoted by $\omega_{j}$. The table below shows the images of the elements in the leftmost column un$\operatorname{der} \omega_{j}$.

|  | $\omega_{1}$ | $\omega_{2}$ | $\omega_{3}$ | $\omega_{4}$ | $\omega_{5}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $A$ | $A B^{-1}$ | $A$ | $B^{-1} C A$ | $A$ | $A$ |
| $B$ | $B$ | $B A$ | $B$ | $B$ | $B$ |
| $A B$ | $A$ | $A B A$ | $B^{-1} C A B$ | $A B$ | $A B$ |
| $A C D C^{-1}$ | $A B^{-1} C D C^{-1}$ | $A C D C^{-1}$ | $B^{-1} C A C B^{-1} C D C^{-1}$ | $A C D C^{-1}$ | $A C D$ |
| $A C D^{2}$ | $A B^{-1} C D^{2}$ | $A C D^{2}$ | $B^{-1} C A C\left(B^{-1} C D\right)^{2}$ | $A C D$ | $A C(D C)^{2}$ |
| $A C D$ | $A B^{-1} C D$ | $A C D$ | $B^{-1} C A C B^{-1} C D$ | $A C$ | $A C D C$ |
| $C D$ | $C D$ | $C D$ | $C B^{-1} C D$ | $C$ | $C D C$ |

Let $\omega_{j *} \in \mathcal{M} C_{2}$ denote the mapping class induced by $\omega_{j}$. Then $\omega_{1 *}, \ldots$, $\omega_{5 *}$ generate $\mathcal{M} C_{2}$ and satisfy the following relations [1, Theorem 4.8]:

$$
\begin{gathered}
\omega_{i *} \omega_{j *}=\omega_{j *} \omega_{i *} \text { if }|i-j| \geq 2,1 \leq i, j \leq 5, \\
\omega_{j *} \omega_{j+1 *} \omega_{j *}=\omega_{j+1 *} \omega_{j *} \omega_{j+1 *}(j=1,2,3,4), \\
\left(\omega_{1 *} \omega_{2 *} \omega_{3 *} \omega_{4 * *} \omega_{5 *}\right)^{6}=1, \\
\omega_{1 *} \omega_{2 *} \omega_{3 *} \omega_{4 *} \omega_{5 *}^{2} \omega_{4 *} \omega_{3 *} \omega_{2 *} \omega_{1 *}=1
\end{gathered}
$$

In this section we represent the action of $\omega_{j *}$ on $\mathcal{T}_{2}$ in the variables $a, b, z, u, v$, $w, t$. More precisely, when $\left(A_{j}, B_{j}, C_{j}, D_{j}\right)=\omega_{j}(A, B, C, D)$, we express

$$
\begin{array}{lll}
a_{j}=\operatorname{tr} A_{j}, & b_{j}=\operatorname{tr} B_{j}, & z_{j}=\operatorname{tr} A_{j} B_{j}, u_{j}=-\operatorname{tr} A_{j} C_{j} D_{j} C_{j}^{-1}, \\
v_{j}=-\operatorname{tr} A_{j} C_{j} D_{j}^{2}, & w_{j}=-\operatorname{tr} A_{j} C_{j} D_{j}, & t_{j}=\operatorname{tr} C_{j} D_{j}
\end{array}
$$

by using $a, b, z, u, v, w, t$. However, for the case of $\omega_{3}$ we modify the signs of some traces to obtain positive values.
(Case of $\omega_{1 *}$ ) By using basic trace identities we have $\operatorname{tr} A B^{-1}=\operatorname{tr} A \operatorname{tr} B-$ $\operatorname{tr} A B=a b-z$,

$$
\begin{aligned}
w_{1}=-\operatorname{tr} A B^{-1} C D= & -\operatorname{tr} B \operatorname{tr} A C D+\operatorname{tr} A B C D=b w+x_{10}, \\
u_{1}=-\operatorname{tr} A B^{-1} C D C^{-1}= & -\operatorname{tr} B \operatorname{tr} A C D C^{-1}+\operatorname{tr}(A B) C D C^{-1} \quad(\because(\mathrm{I} 2)) \\
= & b u+(\operatorname{tr} A B \operatorname{tr} D-\operatorname{tr} A B D \\
& -\operatorname{tr} A B C \operatorname{tr} C D+\operatorname{tr} C \operatorname{tr} A B C D)(\because(2.1 c)) \\
= & b u+z d-x_{8}-t x_{7}+c x_{10},
\end{aligned}
$$

and

$$
\begin{align*}
v_{1}=-\operatorname{tr} A B^{-1} C D^{2} & =-\operatorname{tr} B \operatorname{tr} A C D^{2}+\operatorname{tr} A B C D^{2} \quad(\because(\mathrm{I} 2)) \\
& =b v+(\operatorname{tr} A B C D \operatorname{tr} D-\operatorname{tr} A B C) \quad(\because(\mathrm{I} 2))  \tag{I2}\\
& =b v+d x_{10}-x_{7} .
\end{align*}
$$

Hence

$$
\omega_{1 *}(a, b, z, u, v, w, t)=\left(a b-z, b, a, u_{1}, v_{1}, w_{1}, t\right) .
$$

(Case of $\omega_{2 *}$ ) Since $\operatorname{tr} A B A=\operatorname{tr} A B \operatorname{tr} A-\operatorname{tr} B=z a-b$,

$$
\omega_{2 *}(a, b, z, u, v, w, t)=(a, z, a z-b, u, v, w, t) .
$$

(Case of $\omega_{3 *}$ ) First we remark that $\operatorname{tr} B^{-1} C A<0$ and $\operatorname{tr} B^{-1} C D<0$. To see $\operatorname{tr} B^{-1} C A<0$, for example, note that $\left(A B^{-1}, B\right)$ is a marking for a group of type $(1 ; 0 ; 0 ; 1)$ and $\operatorname{tr} A$ and $\operatorname{tr} B$ are positive. Then we have $\operatorname{tr} A B^{-1}>0$. Then $\left(A B^{-1}, C\right)$ is a marking for a group of type $(0 ; 0 ; 0 ; 3)$. Since $\operatorname{tr} A B^{-1}$ and $\operatorname{tr} C$ are positive, $\operatorname{tr} A B^{-1} C<0$ (see [5, Section 33 A and D]). The calculation for $\omega_{3 *}$ is the most complicated: By using the basic trace identities we have

$$
a_{3}=\operatorname{tr} B^{-1} C A=\operatorname{tr} B \operatorname{tr} A C-\operatorname{tr} A B C=b x_{3}-x_{7} .
$$

$$
\begin{aligned}
w_{3}= & -\operatorname{tr}\left(B^{-1} C\right)(A C)\left(B^{-1} C\right) D \\
& =-\operatorname{tr}(A C)\left(B^{-1} C\right) D\left(B^{-1} C\right) \\
& =-\operatorname{tr} A C B^{-1} C \operatorname{tr} B^{-1} C D-\operatorname{tr} A C D+\operatorname{tr} A C \operatorname{tr} D \\
& =-\left(\operatorname{tr} B \operatorname{tr} A C^{2}-\operatorname{tr} A C B C\right)(\operatorname{tr} B \operatorname{tr} C D-\operatorname{tr} B C D)+w+d x_{3} \\
& =-\left[b\left(c x_{3}-a\right)-\left(x_{3} x_{5}+z-a b\right)\right]\left(b t-x_{9}\right)+w+d x_{3} \\
& =\left(x_{3} x_{5}+z-b c x_{3}\right)\left(b t-x_{9}\right)+w+d x_{3}, \\
u_{3}= & -\operatorname{tr}\left(B^{-1} C\right)(A C)\left(B^{-1} C\right)\left(D C^{-1}\right) \\
= & -\operatorname{tr}(A C)\left(B^{-1} C\right)\left(D C^{-1}\right)\left(B^{-1} C\right) \\
= & -\operatorname{tr} A C B^{-1} C \operatorname{tr} B^{-1} C D C^{-1}-\operatorname{tr} A C D C^{-1}+\operatorname{tr} A C \operatorname{tr} D C^{-1} \\
= & -\left(\operatorname{tr} A C \operatorname{tr} B^{-1} C-\operatorname{tr} A B\right)\left(\operatorname{tr} B \operatorname{tr} D-\operatorname{tr} B C D C^{-1}\right)+u+x_{3}(c d-t) \\
= & -\left(x_{3}\left(b c-x_{5}\right)-z\right)\left[b d-\left(b d-x_{6}-t x_{5}+c x_{9}\right)\right]+u+x_{3}(c d-t) \\
= & \left(x_{3} x_{5}+z-b c x_{3}\right)\left(x_{6}+t x_{5}-c x_{9}\right)+u+x_{3}(c d-t), \\
v_{3}= & -\operatorname{tr} B^{-1} C A C\left(B^{-1} C D\right)^{2} \\
= & -\operatorname{tr} B^{-1} C D \operatorname{tr} B^{-1} C A C B^{-1} C D+\operatorname{tr} B^{-1} C A C \\
= & \left(b t-x_{9}\right)\left[\left(x_{3} x_{5}+z-b c x_{3}\right)\left(b t-x_{9}\right)+w+d x_{3}\right]+\left(b c-x_{5}\right) x_{3}-z, \\
& t_{3}=\operatorname{tr} C B^{-1} C D=\operatorname{tr} C B^{-1} \operatorname{tr} C D-\operatorname{tr} B D=\left(b c-x_{5}\right) t-x_{6} .
\end{aligned}
$$

In this case $a_{3}, x_{3}, v_{3}$ and $t_{3}$ are negative. We modify the sign of these parameters and obtain

$$
\omega_{3 *}(a, b, z, u, v, w, t)=\left(-a_{3}, b,-x_{3}, u_{3},-v_{3}, w_{3},-t_{3}\right) .
$$

(Case of $\omega_{4 *}$ ) For the expression of $\omega_{4 *}$ we have easily

$$
\omega_{4 *}(a, b, z, u, v, w, t)=\left(a, b, z, u, w,-x_{3}, c\right) .
$$

(Case of $\omega_{5 *}$ ) Since $-\operatorname{tr} A C D C=-\operatorname{tr} C \operatorname{tr} A C D+\operatorname{tr} A C D C^{-1}=c w-u$,

$$
\begin{aligned}
v_{5} & =-\operatorname{tr} A C(D C)^{2}=-\operatorname{tr} C D \operatorname{tr} A C D C+\operatorname{tr} A C \\
& =-t\left(\operatorname{tr} C \operatorname{tr} A C D-\operatorname{tr} A C D C^{-1}\right)+x_{3} \\
& =c w t-t u+x_{3},
\end{aligned}
$$

and $\operatorname{tr} C D C=c t-d$, we have

$$
\omega_{5 *}(a, b, z, u, v, w, t)=\left(a, b, z, w, c w t-t u+x_{3}, c w-u, c t-d\right) .
$$

Now we conclude

Theorem 3.1. The mapping classes $\omega_{1 *}, \omega_{2 *}, \omega_{3 *}, \omega_{4 *}, \omega_{5 *}$ are represented by the following rational maps in variables $a, b, z, u, v, w, t$ :

$$
\begin{align*}
& \omega_{1 *}(a, b, z, u, v, w, t)=\left(a b-z, b, a, u_{1}, v_{1}, w_{1}, t\right)  \tag{3.2}\\
& \omega_{2 *}(a, b, z, u, v, w, t)=(a, z, a z-b, u, v, w, t) \\
& \omega_{3 *}(a, b, z, u, v, w, t)=\left(-b x_{3}+x_{7}, b,-x_{3}, u_{3},-v_{3}, w_{3},-b c t+x_{5} t+x_{6}\right) \\
& \omega_{4 *}(a, b, z, u, v, w, t)=\left(a, b, z, u, w,-x_{3}, c\right) \\
& \omega_{5 *}(a, b, z, u, v, w, t)=\left(a, b, z, w, c w t-t u+x_{3}, c w-u, c t-d\right),
\end{align*}
$$

where $c, d, x_{3}, x_{4}, x_{5}, x_{6}$ and $x_{7}$ are given in (2.9) and (2.10) and (2.12).
As it is shown in Section $2, x_{1}=c, x_{2}=d, \ldots, x_{10}$ are all rational functions in $(a, b, z, u, v, w, t)$. Hence the inverse mappings of $\omega_{j *}(j=1, \ldots, 5)$ are also rational mappings. The expressions in (3.2) in ( $a, b, z, u, v, t$ ), especially the one for $\omega_{3 *}$, are very complicated.
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