

Pilot Design for Sparse Channel Estimation in Orthogonal Frequency Division Multiplexing Systems

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Abstract—Orthogonal Frequency Division Multiplexing (OFDM) is a well-known technique used in modern wide band wireless communication systems. Coherent OFDM systems achieve its advantages over a multipath fading channel, if channel impulse response is estimated precisely at the receiver. Pilot-aided channel estimation in wide band OFDM systems adopts the recently explored compressive sensing technique to decrease the transmission overhead of pilot subcarriers, since it exploits the inherent sparsity of the wireless fading channel. The accuracy of compressive sensing techniques in sparse channel estimation is based on the location of pilots among OFDM subcarriers. A sufficient condition for the optimal pilot selection from Sylow subgroups is derived. A Sylow subgroup does not exist for most practical OFDM systems. Therefore, a deterministic pilot search algorithm is described to select pilot locations based on minimizing coherence, along with minimum variance. Simulation results reveal the effectiveness of the proposed algorithm in terms of bit error rate, compared to the existing solutions.

Keywords—channel estimation, compressive sensing, minimum coherence, minimum variance, pilot pattern.

1. Introduction

Orthogonal Frequency Division Multiplexing (OFDM) is a multi-carrier modulation technique used in wideband wireless communication systems due to its high spectral efficiency [1]. In OFDM systems, each subcarrier has a narrow bandwidth which ensures signal robustness against frequency selectivity caused by the multipath delay spread. Although coherent, non-coherent and partially coherent detection techniques are deployed in OFDM systems, coherent detection attracts wider interest, as it supports a higher data rate than the other schemes. Coherent communication in OFDM systems allows arbitrary signal constellations for high data rates, but efficient channel estimation strategies are required for detection and decoding of information at the receiver. The channel can be estimated in the receiver using the pilot-aided method, where the receiver makes use of the known transmitted symbols, also known as pilots in, a set of predetermined subcarriers of the OFDM system, or

by learning the statistics of the information bearing signals which are referred to as a blind technique. As such an approach involves more complex signal processing and computationally expensive operations to ensure efficient blind methods, pilot-aided methods evoke considerable interest in the recent technologies which are capable of tracking the channel based on coherence time whose duration is in the order of one OFDM symbol [2].

The majority of research concerned with pilot-aided channel estimation is devoted to the selection of pilot locations. Equally spaced pilot locations become the optimal selection when the maximum likelihood (ML) rule is employed in the receiver, which is computationally expensive [3], [4]. Further, several investigations show that many wideband OFDM systems tend, in practice, to have their wireless channel dominated by a relatively small number of coefficients, i.e. most channel coefficients are nearly zero and do not contribute significantly, and the number of effective channel coefficients is relatively much lower than the channel delay spread (length of the channel impulse response). The sparseness of the channel leverages the application of sparse signal processing techniques in the framework of compressive sensing (CS) [5] for channel estimation problems, which can drastically reduce the number of pilots required to estimate the channel, thereby increasing bandwidth efficiency. CS recovery algorithms, such as l_1 norm minimization, orthogonal matching pursuit and iterative thresholding, have been adopted for sparse channel estimation, which enables efficient reconstruction of the sparse channel with less pilot overhead than in the case of conventional methods [6]. However, there is no general theory on the optimal pilot selection for sparse channel estimation using CS techniques, such as the optimal equally spaced pilots for conventional channel estimation methods.

A few works of literature deal with the design of a pilot pattern for sparse channel estimation. Deterministic pilot selection [7] is proposed for OFDM systems with the number of subcarriers N being a prime. A pilot generated randomly can be updated by sequentially evolving towards a global optimizer with offline channel data, as discussed in [8]. Pilot design for under water acoustic chan-

nels, based on cluster pilot design and data subcarrier as additional observation for channel estimation, is described in [9]. The tree-based backward pilot generation [10] iteratively removes a subcarrier from N subcarriers of OFDM systems in a backward direction to generate a pilot pattern. Optimum pilot generation by minimizing coherence of the DFT submatrix and cross entropy optimization, to place the pilots at an optimal location, is described in [11], [12]. The first subcarrier is fixed as the first pilot, and the remaining pilot locations are sequentially assigned by minimizing the variance of the multiset formed using the current pilot location set [13]. Statistic serial, parallel and iterative group shrinking was proposed [14] for minimum coherence. Three greedy deterministic pilot search algorithms [15] are stated based on minimizing coherence through a straightforward search.

The remainder of this paper is organized as follows. Section 2 deals with the OFDM system modeling framework and formulates the estimation problem of sparse channel impulse response. In Section 3, optimal pilot design from the Sylow subgroup is analyzed. The proposed deterministic pilot search algorithm is presented in Section 4. The simulation results shown in Section 5 reveal the performance of the proposed algorithm's pilot pattern in sparse channel estimation of wideband OFDM systems and, finally, conclusions are provided in Section 6.

The notations used in this paper are: \emptyset , \setminus , $|$, \dagger , $(\cdot)^T$, $(\cdot)^H$, $(\cdot)^{-1}$, $\|\cdot\|$, $\langle \cdot \rangle$, \otimes , \oplus , $[\cdot]$, $[\cdot]$, and $\mathcal{O}(\cdot)$ meaning: empty, exclusion, divide, does not divide, matrix transpose, conjugate transpose, matrix inverse, norm of a vector, inner product of a vector, modulus, multiplication modulo, addition modulo, floor of a value, ceiling of a value and order, respectively.

2. Problem Statement

In this section, we describe the system model for pilot-aided sparse channel estimation in an OFDM system with the canonical discrete time channel model. Assume that information is transmitted through an OFDM symbol that consist of N subcarriers and has a cyclic prefix length of $N/4$. Among N subcarriers, N_p subcarriers are used to transmit pilots with locations represented as $[p_1, p_2, \dots, p_{N_p}]$, where $1 \leq p_1 < p_2 \dots < p_{N_p} \leq N$ and $N_d = N - N_p$ subcarriers transmit information. The transmitted and received pilot symbols on pilot subcarrier locations are $x = [x(p_1), x(p_2), \dots, x(p_{N_p})]^T$ and $y = [y(p_1), y(p_2), \dots, y(p_{N_p})]^T$ respectively. Then the frequency domain sparse channel estimation of a pilot-aided OFDM system at the receiver can be modeled as:

$$y = Ah + n, \quad (1)$$

where $A = X.F_{N_p \times L}$ is a sensing matrix. X is a diagonal matrix of transmitted pilot symbols $X = \text{diag}\{x(p_1), x(p_2), \dots, x(p_{N_p})\}$ and $F_{N_p \times L}$ is a discrete Fourier submatrix constructed by selecting first L columns and N_p rows

stated by pilot locations $[p_1, p_2, \dots, p_{N_p}]$ from a standard Fourier matrix $N \times N$.

$$F_{N_p \times L} = \frac{1}{\sqrt{N}} \begin{bmatrix} 1 & \omega^{p_1} & \dots & \dots & \omega^{p_1(L-1)} \\ 1 & \omega^{p_2} & \dots & \dots & \omega^{p_2(L-1)} \\ \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots \\ 1 & \omega^{p_{N_p}} & \dots & \dots & \omega^{p_{N_p}(L-1)} \end{bmatrix} \quad (2)$$

where $\omega = e^{-j\frac{2\pi}{N}}$ and $n = [n(1), n(2), \dots, n(N_p)]^T$ is the Additive White Gaussian Noise (AWGN) vector with zero mean and variance σ_n^2 . $h = [h(1), h(2), \dots, h(L)]^T$ is the discrete channel impulse response vector with L coefficients. The multipath wireless channel gives rise to multiple attenuated and delayed copies of transmitted signal at the receiver, due to the number of scatters in the surrounding environment. We consider a transmission over such a multipath wireless channel with L resolvable paths (coefficients), and each path has a complex path gain α_i and a delay spread τ_i . The time domain baseband channel model is given by:

$$h(\tau) = \sum_{i=1}^L \alpha_i \delta(\tau - \tau_i), \quad (3)$$

where $\delta(\cdot)$ is a Dirac delta function. The equivalent discrete channel model can be represented as:

$$h(n) = \sum_{i=1}^L \alpha_i \delta((n - \tau_i)T_s), \quad (4)$$

where T_s is the sampling interval which holds a very small value compared to the maximum delay spread for practical wide band wireless channels. In such cases the impulse response h is dominated by relatively few resolvable paths over the maximum paths L , and these channels are often termed as sparse channels. Assuming the frequency domain channel impulse response h is having $\|h\|_0 \leq k \ll L$, then the multipath wireless channel is termed as k sparse channel.

The reconstruction of channel impulse response h at the receiver is essential for coherent detection. The competent pilot aided channel estimation for today's wireless systems involves either linear or nonlinear techniques. Conventional pilot-aided methods typically depend on linear reconstruction techniques with the resulting sensing matrix A of N_p rows and L columns, such that $N_p > L$. Considering the inherent sparsity of the wireless channel, the number of pilots N_p is kept lower than maximum channel coefficients L , i.e. $N_p < L$, then system will become an underdetermined system, but improves the system data rate. Thus, linear reconstruction methods do not provide an accurate solution. CS-based methods provide a nonlinear way to reconstruct these under determined systems by exploiting the sparsity of the channel. However, the reliable and efficient reconstruction of sparse vector h by using CS recovery

techniques is based on proper selection of N_p rows for the sensing matrix A from the Fourier matrix, i.e. selection of pilot locations in subcarriers.

3. Optimal Pilot Analysis

Proper selection of the pilot pattern influences the sparse channel estimation of OFDM systems using CS reconstruction algorithms. Indeed, sparse vector h is guaranteed for nonlinear reconstruction by CS if A satisfies the Restricted Isometry Property (RIP).

A sensing matrix A satisfies the RIP of order k if there exists a constant δ such that:

$$(1 - \delta)\|h\|_2^2 \leq \|Ah\|_2^2 \leq (1 + \delta)\|h\|_2^2, \quad (5)$$

for any k sparse vector. The minimum of all constants δ satisfying the above condition is called the isometric constant δ_k . But there is no algorithm to check the RIP, since it involves combinatorial computation complexity. Other than RIP, the widely used condition that guarantees the reconstruction of the sparse vector is *coherence* [16].

Coherence μ of a sensing matrix A , is the largest absolute inner product between any two columns a_m and a_n of A :

$$\begin{aligned} \mu(A) &= \max_{1 \leq m < n \leq L} |\langle a_m, a_n \rangle| \\ &= \max_{1 \leq m < n \leq L} \left| \sum_{i=1}^{N_p} |x(p_i)|^2 \omega^{p_i(n-m)} \right|. \end{aligned} \quad (6)$$

Let $c \triangleq n - m$ then

$$\mu(A) = E \max_{1 \leq c \leq L-1} \left| \sum_{i=1}^{N_p} \omega^{p_i c} \right|,$$

where energy of pilot E is treated as one.

Now $\omega = e^{-j\frac{2\pi}{N}} = e^{-j\theta}$, where $\theta = \frac{q\pi}{N}$.

Then coherence will be:

$$\begin{aligned} \mu(A) &= \max_{1 \leq c \leq L-1} \left| \sum_{i=1}^{N_p} e^{-j c p_i \theta} \right| \\ &= \max_{1 \leq c \leq L-1} \left(N_p + \sum_{i=1}^{N_p} \sum_{j=i+1}^{N_p} 2 \cos \left(c((p_i - p_j) \bmod N) \theta \right) \right)^{\frac{1}{2}} \\ \mu(A) &= \max_{1 \leq c \leq L-1} (N_p + H_c(P))^{\frac{1}{2}}, \end{aligned} \quad (7)$$

where

$$H_c(P) = \sum_{i=1}^{N_p} \sum_{j=i+1}^{N_p} 2 \cos \left(c((p_i - p_j) \bmod N) \theta \right). \quad (8)$$

A different pilot pattern leads to a different sensing matrix A . The objective function Q for selecting an optimal pilot pattern P is to minimize the coherence of A :

$$Q = \arg \min_A \mu(A). \quad (9)$$

A pilot pattern yields minimum coherence $\mu(A)$ if $\cos(c(p_i - p_j)\theta)$ holds minimum for all values of c in Eq. (8). If the most of angles $c(p_i - p_j)\theta$ are occupied in the 2nd and 3rd quadrant, then the cosine angle holds minimum. However, for some specific settings, the optimal pilot can be generated from the Cyclic Difference Set (CDS).

Definition for CDS: For the given (N, N_p) , if λ is an integer where $\lambda = \frac{N_p(N_p-1)}{N-1}$ and $N_p < N$, then CDS is defined as a set of N_p distinct components selected from N denoted as $(p_1, p_2, \dots, p_{N_p})$ satisfying that any integer $x(1 \leq x \leq N-1)$ repeats λ times in the set:

$$\{x = p_i - p_j \pmod{N} \mid 1 \leq i \neq j \leq N_p\}, \quad (10)$$

and the corresponding difference multiset $D = \{a_d\}_{d=1}^{N-1}$, where a_d is the number of pairs (p_i, p_j) in pilot indices set P such that $d = p_i - p_j \pmod{N} \mid 1 \leq i \neq j \leq N_p$, $d = 1, 2, \dots, N-1$. The mean and variance σ_p^2 of the difference multiset are defined as:

$$mean = \frac{1}{N-1} \sum_{i=1}^{N-1} a_d, \quad (11)$$

$$\sigma_p^2 = \sum_{i=1}^{N-1} (a_d - mean)^2. \quad (12)$$

The pilot selection satisfying the definition of CDS is surely the optimal choice for minimum coherence, since the resultant Discrete Fourier Transform (DFT) submatrix achieves the Welch bound. The sufficient condition for CDS to be optimal pilot selection is:

$$L \geq \left\lceil \frac{N}{2} \right\rceil. \quad (13)$$

Nevertheless, for many pairs of N and N_p , there is no CDS. Moreover the channel impulse response length L is less than the cyclic prefix of the practical OFDM system.

In the present work for some specific settings, the optimal pilot selection from a p-Sylow subgroup is analyzed and conditions are obtained for a subgroup to act as an optimal pilot selection.

Definition for p-Sylow: Let (G, \cdot) be a group and p be a prime number. If $(G) = p^\alpha m$, where $p \nmid m$, then a subgroup of order p^α is called the p-Sylow subgroup of G . Existence of the p-Sylow subgroup is guaranteed. If (G, \cdot) is an abelian group, then the p-Sylow subgroup is unique. Let $S \subseteq G$. The subgroup of G generated by S is the smallest subgroup of G containing S and is denoted by $\langle S \rangle$. $\langle S \rangle$ is the set of finite products of elements of S and its inverses. For any subgroup H of an abelian group (G, \cdot) and for any $a \in G$, $aH = \{a \cdot h \mid h \in H\}$ denotes the coset of H in G . Now, for a given (N, N_p) , the optimal pilot selection that can be generated from a subgroup is analyzed. If N and N_p satisfy the conditions stated in the following theorem, then the p-Sylow subgroup will be an optimal pilot selection.

Theorem 1: For a given (N, N_p) , if $(N+1)$ is a prime number q and for some prime p and $N_p = p^\alpha$ for some integer α such that $p^\alpha | N$, $p^{\alpha+1} \nmid N$ with $N_p(N_p - 1) = \lambda N$, where λ is an integer and if P is the unique p-Sylow subgroup of the group (G, \otimes) under multiplication mod $(N+1)$, then P is a CDS and P is the optimal pilot selection for (N, N_p) for $L \geq \frac{N}{2}$ provided given $p_1, p_2, p_3, p_4 \in P$, there exist p'_1, p'_2 such that:

$$(p_1 + p_2) - (p_3 + p_4) \equiv (p'_1 - p'_2) \pmod{(N+1)}, \quad (14)$$

where $G = \{1, 2, \dots, N\}$.

Proof: Let $F = \{0, 1, 3, \dots, N\}$ and $\lambda = 1$. Then (F, \oplus, \otimes) is a field where \oplus and \otimes are the addition $(N+1)$ and multiplication mod $(N+1)$ respectively. Let $P = \{p_1, p_2, p_3, \dots, p_{N_p}\}$ be the unique p-Sylow subgroup of (G, \otimes) .

Let $S \triangleq \{(p_i - p_j) \pmod{(N+1)}, p_i \neq p_j\}$, where $r \in \{1, 2, \dots, N\}$. Clearly, S is non empty and $O(S) \leq N_p(N_p - 1) = N$. Let $\langle S \rangle$ be the subgroup of (F, \oplus) generated by S . Now, we show that $\langle S \rangle$ is closed under \otimes .

Let $x, y \in \langle S \rangle$. Suppose $x = s_1 + s_2$, where $s_1, s_2 \in S$. Then $x = \{(p_1 - p_2) + (p_3 - p_4)\} \pmod{(N+1)}$, where $p_i \in P$.

Similarly $y = \{(p'_1 - p'_2) + (p'_3 - p'_4)\} \pmod{(N+1)}$, where $p'_i \in P$.

Using the given condition, we can find $p'_i p'_j$ in P such that $x \cdot y = (p'_i - p'_j) \pmod{(N+1)}$ for some $p'_i, p'_j \in P$. Hence $\langle S \rangle$ is a subring of F . Since F has no proper subring, $\langle S \rangle = F$. Now we show that $\langle S \rangle \setminus \{0\} = S$. Let $y (\neq 0) \in \langle S \rangle$ and let $y = x_1 + x_2$ where $x_1, x_2 \in S$.

Let $x_1 = (p_1 - p_2) \pmod{(N+1)}$ and $x_2 = (p_3 - p_4) \pmod{(N+1)}$. Then:

$$\begin{aligned} x_1 + x_2 &= \{(p_1 + p_2) - (p_3 + p_4)\} \pmod{(N+1)} \\ &= (p'_1 - p'_2) \pmod{(N+1)}, \text{ for some } p'_1, p'_2 \in P, \\ &= x_3, \text{ for some } x_3 \in S; \text{ thus } \langle S \rangle \setminus \{0\} = S. \end{aligned}$$

Hence, $S = 1, 2 \dots N$. Therefore, P is also a CDS and the optimal pilot selection. For any integer $\lambda \neq 1$ the proof is similar.

Corollary: For a given (N, N_p) if N is a prime number q and for some prime p and for some integer α such that $p^\alpha | q - 1$, $p^{\alpha+1} \nmid q - 1$ with $N_p(N_p - 1) = \lambda(N - 1)$ and P is the unique p-Sylow subgroup of (G, \otimes) , under multiplication mod (N) where $G = 1, 2, \dots, N - 1$ such that P satisfies the condition given in theorem 1 then P is the optimal solution.

For the case (N, N_p) where $(N+1)$ is a prime, N_p pilots will be selected from $1, 2, 3, \dots, N$ whereas in the case (N, N_p) , where N is a prime, N_p pilots will be selected from $1, 2, 3, \dots, N - 1$.

The optimal pilot selection for an OFDM system from p-Sylow satisfies the definition of CDS for some specific pairs of (N, N_p) . It is no longer an optimal pilot selection for a practical OFDM system with channel length $L < \lceil \frac{N}{2} \rceil$. For example, $\{1, 7, 9, 10, 12, 16, 26, 33, 34\}$ is a 3-Sylow subgroup which is a CDS for $(37, 9)$. It has the coher-

ence $\mu = 2.6458$ for all range of $L \geq \lceil \frac{N}{2} \rceil$. But if $L = 11 < \lceil \frac{N}{2} \rceil$ there exist a set which is neither a subgroup nor a CDS $\{1, 4, 7, 10, 13, 22, 28, 31, 34\}$ having coherence $\mu = 2.1196$ less than obtained by p-Sylow subgroup and CDS. Practical OFDM systems will have a $\frac{N}{4}$ long cyclic prefix which is usually much larger than the length of the channel. Therefore, it is necessary to explore a pilot search algorithm suitable for wideband OFDM systems.

4. Pilot Search Algorithm

This section describes the deterministic procedure for selecting the pilot locations for a given (N, N_p, L) . Optimal N_p subcarrier selection from N subcarriers of an OFDM system by exhaustive search among all possible ${}^N C_{N_p}$ DFT submatrices is humanly impossible because of its computational complexity. Here, a deterministic approach is proposed that couples variance and coherence minimization to meet the near-optimal pilot selection. The algorithm starts by assigning the first pilot location and selects the remaining locations, one by one, so that a difference multiset of selected pilot locations achieves minimum variance. The minimum variance pilot pattern will not lead to minimum coherence for small L . Therefore, the algorithm updates every candidate of the selected pilot pattern for minimum coherence from all pilot subcarrier candidates. If the candidate pilot subcarriers are considered to range from 1 to N , there is a possibility for the pilot search algorithm to choose pilot subcarriers close to each other. It decreases the efficiency of the pilot pattern in channel estimation [15]. By defining the neighboring optimal distance for pilot subcarriers, the algorithm will not choose the closest subcarriers. In the proposed algorithm index set I_s defined to contain candidate pilot subcarrier locations at optimal distance. The optimal distance of pilot subcarriers for the given N and L is $c = \lfloor \frac{N}{L} \rfloor$.

The proposed algorithm is summarized as Algorithm 1. Initially, the first pilot location is assigned as number one. Next, the second pilot location is selected from the subset \widehat{P}_y generated using $\widehat{P}_{y-1} \cup n | n \in \{I_s\} \setminus P_{y-1}$ for minimum variance. By repeating this, we obtain the pilot pattern $P = [p_1, p_2, \dots, p_{N_p}]$. The minimum variance calculation for subset $\widehat{P}_y = \{P_y(1), P_y(2), \dots, P_y(n)\}$ for each update is given by Eqs. (15)–(19).

Let $P_y = [p_1, p_2, \dots, p_x]$, where $x \leq N_p$ and $y = 1, 2, \dots, n$. Then:

$$mean = \frac{1}{N-1} \sum_{i=1}^{N-1} a_{d_i}, \quad (15)$$

where a_d is a element of $D = \{a_d\}_{d=1}^{N-1}$ defined as number of pairs (p_i, p_j) in selected pilot location set P_y such that $d = p_i - p_j \pmod{N} | 1 \leq i \neq j \leq x$, where $d = 1, 2, \dots, N - 1$, and variance

$$\delta_{P_y}^2 = \sum_{i=1}^{N-1} (a_{d_i} - mean)^2. \quad (16)$$

Algorithm 1: Pseudocode for proposed algorithm

Input: N, N_p, L, t
Initialize: $I_{temp} = \emptyset, I_p = \emptyset, P_c = \emptyset, c = \lfloor \frac{N}{L} \rfloor$
 $I_s = \{1, 1+c, 1+2c, \dots, N\}; \|I_s\| = M$
For $m = 1, 2, \dots, M, P_1 = I_s(m)$
 Generate subset \hat{P}_2 by $P_1 \cup n | n \in \{I_s\} \setminus P_1$
 Obtain $I = [P_2(1), P_2(2), \dots, P_2(t)]$ according to Eq. (17)
For $y = 3, 4, 5, \dots, N_p,$
For $x = 1, 2, \dots, t, P_{y-1} = I(x)$
 Generate subset \hat{P}_y by $P_{y-1} \cup n | n \in \{I_s\} \setminus P_{y-1}$
 Obtain $I = [P_y(1), P_y(2), \dots, P_y(t)]$ according to Eq. (17)
 $I_{temp} \leftarrow [I_{temp}, I]$
End for x
 Obtain I from I_{temp} according to Eq. (17)
End for y
For $z = 1, 2, \dots, t$
 $P_{N_p, z} = I(z)$
For $y = N_p, N_p-1, \dots, 1$
 $P'_{N_p, z} = [p_{1,z}, p_{2,z}, \dots, p_{y,z} = \emptyset, \dots, p_{N_p, z}]$
For $x = 1, 1+c, 1+2c, \dots, \leq N$
If $x \notin P_{N_p, z}$
 $\hat{P} = [p_{1,z}, p_{2,z}, p_{y,z} = x, \dots, p + N_p, z]$
End if
End for x
 Obtain $P'_{N_p, z}$ from \hat{P} according to Eq. (19)
End for y
 $I_p(z) = P'_{N_p, z}$
End for z
 Obtain $P_c(m)$ from I_p according to Eq. (19)
End for m
 $P = \arg \min_P \mu(A)_{P_c}$
Output: pilot pattern P .

To achieve a greater degree of accuracy, instead of selecting a pilot pattern with the least variance, we select t sets of pilot patterns (group selection) having a minimum variance in every pilot location update. The t sets are selected with least $\sigma_{P_y}^2$ among n updated set $P = [P_y(1), P_y(2), \dots, P_y(n)]$ as:

$$I = [P_y(1), P_y(2), \dots, P_y(t)], \quad (17)$$

where $y = 2, 3, 4, \dots, N_p$ and $P_y(1) = P_y(i), P_y(2) = P_y(j) \dots | 0 \leq \sigma_{P_y(i)}^2 \leq \sigma_{P_y(j)}^2 \leq \dots$

The procedure is repeated for every one of the values from index set I_s as first pilot location. The resulting t sets of pilot pattern obtained from the first loop is:

$$I = [P_{N_p}(1), P_{N_p}(2), \dots, P_{N_p}(t)], \quad (18)$$

where $P_{N_p}(i) = [p_{1,i}, p_{2,i}, \dots, p_{N_p,i}]$. All t selected pilot patterns are updated for minimum coherence. Every n -th entry of a pilot pattern P_{N_p} can be updated by selecting the best form $I_s \setminus \{P_{N_p}(j) | j = 1, 2, \dots, N_p, j \neq n\}$. From

the resulting pilot location collection set P , select a pilot location with minimum coherence as:

$$P \leftarrow \arg \min_P \mu(A)_{P(i)}, i = 1, 2, 3, \dots \quad (19)$$

5. Simulation Results

The theoretical distance between the pilot locations is verified practically by simulating the proposed algorithm for

Table 1
Coherence of a pilot pattern generated with various distances selected between pilot subcarriers

N	N_p	L	Distance	μ
256	16	50	1	4.6868
			3	4.8937
			4	4.4308
			5	4.3887
			6	10.8125

Table 2
List of pilot patterns generated for various (N, N_p, L) , using the proposed algorithm

N	N_p	μ	Pilot pattern	L
64	6	2.6131	1, 5, 9, 17, 33, 45	15
	6	2.6131	1, 13, 29, 33, 37, 53	16
	9	2.5326	1, 5, 13, 21, 29, 33, 37, 49	
73	9	2.7284	1, 11, 12, 14, 17, 26, 42, 47, 65	37
		2.7201	1, 9, 13, 17, 21, 29, 33, 53, 57	18
128	6	2.8840	5, 21, 49, 53, 61, 113	30
	9	3.1350	5, 21, 37, 41, 45, 49, 73, 113, 121	
	12	3.2558	11, 29, 33, 41, 45, 49, 53, 69, 81, 85, 105, 113	
	14	3.3785	1, 5, 9, 17, 25, 29, 37, 61, 65, 69, 81, 105, 109, 121	
50	12	4.1823	1, 6, 21, 41, 81, 146, 151, 156, 176, 201, 211, 246	50
	13	4.3591	1, 6, 31, 41, 46, 81, 86, 141, 151, 206, 211, 226, 236	
	16	4.3887	1, 6, 16, 21, 26, 41, 46, 51, 66, 121, 126, 156, 181, 191, 211, 221	
	23	4.8822	1, 6, 11, 21, 26, 31, 36, 46, 66, 71, 81, 86, 106, 116, 136, 141, 151, 156, 181, 196, 206, 226, 236	
	12	4.0496	1, 29, 73, 77, 93, 97, 101, 109, 129, 141, 153, 161, 165, 201, 217, 245	
	16	4.4308	1, 29, 73, 77, 93, 97, 101, 109, 129, 141, 153, 161, 165, 201, 217, 245	
	24	4.8550	1, 13, 49, 57, 61, 73, 77, 93, 117, 121, 141, 145, 149, 161, 169, 177, 181, 189, 193, 201, 217, 225, 233, 253	
512	40	6.8674	1, 6, 11, 16, 21, 26, 31, 36, 51, 66, 71, 81, 91, 101, 126, 171, 176, 181, 191, 216, 221, 236, 266, 271, 276, 291, 296, 306, 351, 376, 381, 396, 401, 411, 421, 446, 461, 481, 486	90
	27	6.3813	1, 16, 21, 46, 56, 76, 81, 106, 111, 151, 186, 201, 206, 211, 251, 256, 286, 301, 326, 371, 411, 421, 471, 481, 486, 491, 501	93
1024	16	4.4653	1, 21, 41, 101, 141, 161, 221, 261, 321, 341, 421, 601, 621, 661, 761, 801	50

various distances. Table 1 proves that the minimum distance that should be maintained between the pilot locations is $\lfloor \frac{N}{L} \rfloor$ which is 5 for $N = 256$ and $L = 50$.

The pilot patterns generated using the proposed algorithm for various pairs of (N, N_p, L) are presented in Table 2. The results show that if N is a prime, coherence of the proposed algorithm's pilot pattern meets the Welch lower bound and prove the effectiveness of the proposed algorithm. For example, $(N, N_p, L) = (73, 9, 37)$ coherence of the proposed algorithm's pilot location achieves the Welch bound 2.8284. Comparison of coherence obtained by the proposed algorithm with algorithms used in practice for various (N, N_p, L) values is presented in Table 3.

Table 3

Comparison of coherence obtained by the proposed algorithm and by existing pilot search algorithms

N	N_p	L	Algorithm	μ
256	16	60	Stochastic serial search [12]	4.7021
			Greedy deterministic [13]	4.8630
			Proposed algorithm	4.4308
256	16	50	Tree based backward with 11 branches [8]	4.9189
			Greedy deterministic [13]	4.5261
			Proposed algorithm	5.8757
256	13	50	Mahdi-Khosravi & Saeed-Mashhadi [11]	5.8757
			Proposed algorithm	4.3591

An QPSK OFDM system is constructed with 256 sub-carriers and 16 of them are used as pilot sub-carriers for pilot-aided channel estimation. A discrete sparse channel h is realized with 5 dominant coefficients, randomly placed over the maximum of 50 channel coefficients. A typical discrete channel realization is shown in Fig. 1. The chan-

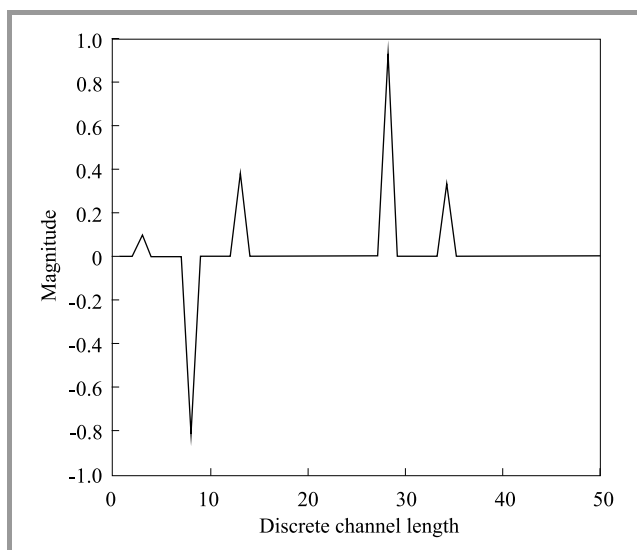


Fig. 1. Typical channel impulse response with 5 dominant coefficients over the maximum discrete channel length.

nel estimation performance of the pilot pattern generated using the proposed algorithm is evaluated at the receiver based on the knowledge of the sensing matrix A and the received pilots vector y using greedy iterative orthogonal matching pursuit (OMP) [17]. The normalized mean square error (MSE) associated with channel vector h and estimated channel \hat{h} is calculated by:

$$MSE = \frac{\|h - \hat{h}\|_2^2}{\|h\|_2^2}. \quad (20)$$

MSE comparison for channel estimation using the proposed and different pilot selection algorithms, comprising, in practice, over 105 iterations for each signal to

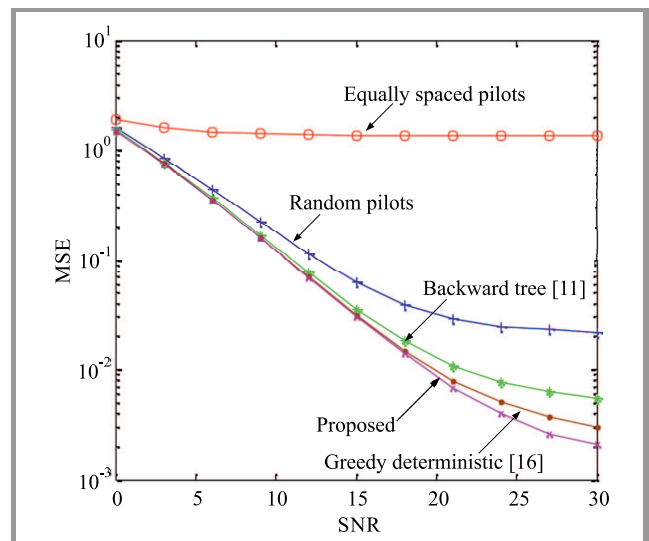


Fig. 2. MSE performance comparison for channel estimation with pilot patterns generated using different schemes for $(N, N_p, L) = (256, 16, 50)$.

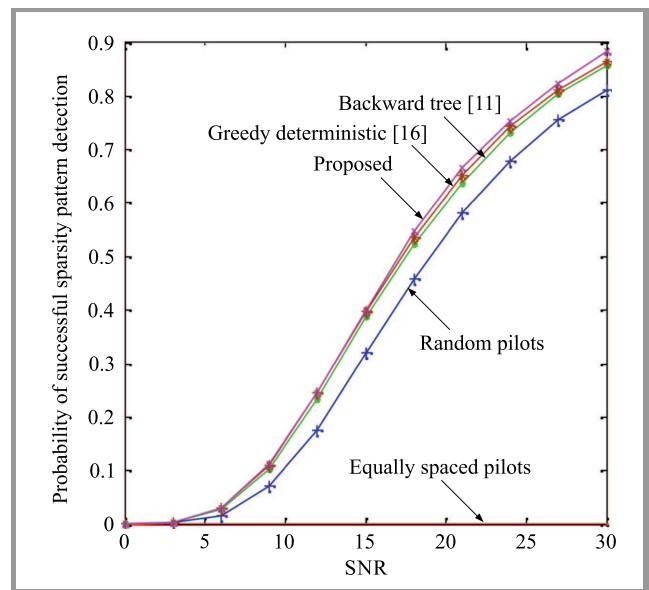


Fig. 3. Detection performance of OMP using proposed and different pilot schemes for $(N, N_p, L) = (256, 16, 50)$.

noise ratio (SNR), is plotted in Fig. 2. The equally spaced conventional pilots and random pilots suggested for the sparse channel are also considered for comparison purposes. Equally spaced pilots are not optimized to minimum coherence and there is no benefit in using them for sparse channel estimation and for random pilot generation, which is difficult for practical systems. We observe that the proposed pilot pattern significantly improves the performance of MSE compared to existing schemes used in practice, with reduced coherence. Detection performance of the sparse reconstruction algorithm gives the percentage of cases of exact recovery of the sparse channel from the received pilots. The comparison of sparse channel detection performance of OMP is presented

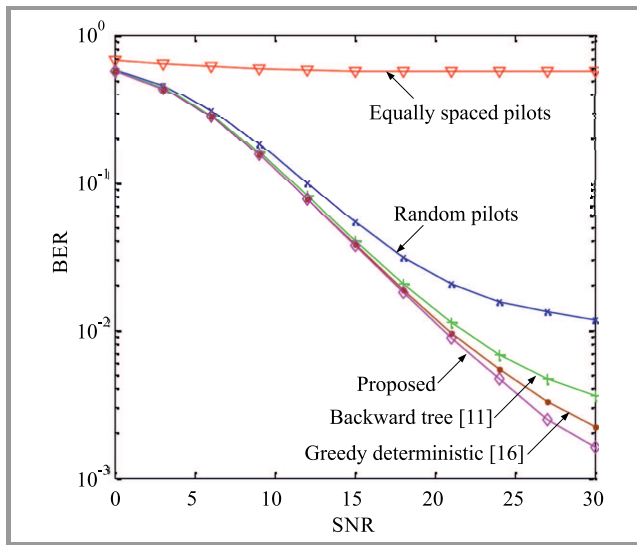


Fig. 4. BER performance comparison of channel estimation for pilot patterns generated using different schemes for $(N, N_p, L) = (256, 16, 50)$.

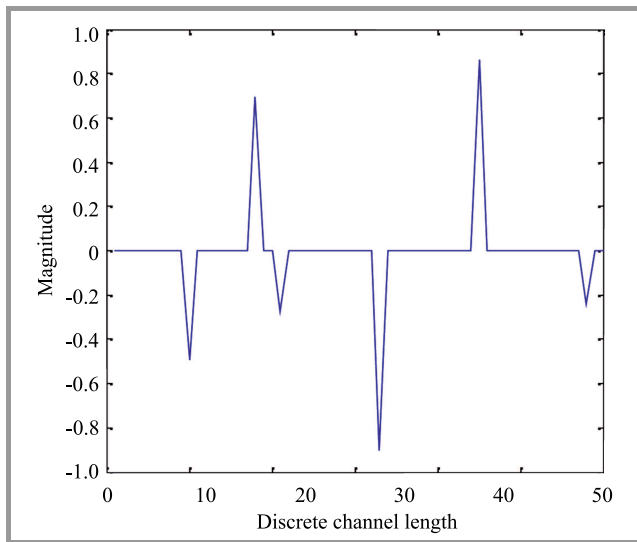


Fig. 5. Typical channel impulse response with 6 dominant coefficients over the maximum discrete channel coefficients $L=60$.

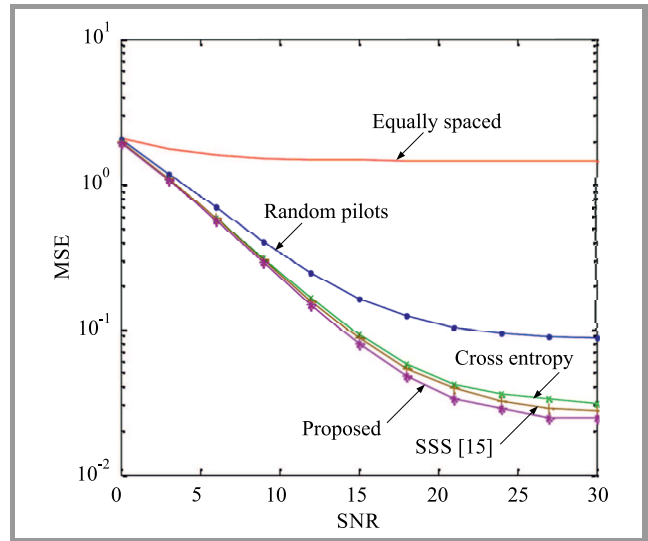


Fig. 6. MSE performance comparison of channel estimation for pilot patterns generated using different schemes for $(N, N_p, L) = (256, 16, 60)$.

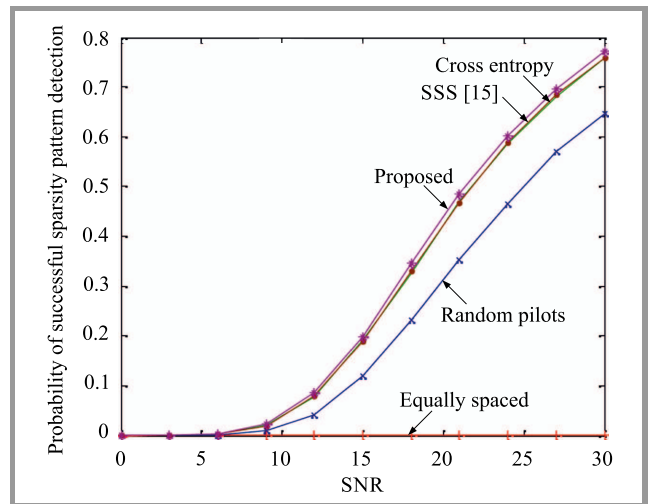


Fig. 7. Detection performance of OMP using proposed and different pilot schemes for $(N, N_p, L) = (256, 16, 60)$.

in Fig. 3. Transmitted data detection performance is shown in Fig. 4 as Bit Error Rate (BER). Performance of the proposed pilot search algorithm is also evaluated for a channel with 6 dominant coefficients spread over the maximum length of 60 in an QPSK OFDM system channel estimation to verify the robustness of the proposed algorithm. Figure 5 represents a typical channel implementation for $L = 60$.

MSE channel estimate, detection performance of the channel estimation algorithm and BER of detected data are given in Figs. 6–8, respectively, for $L = 60$ and show the effectiveness of the proposed pilot search algorithm compared to pilot search algorithms used in practice. The running time of the proposed algorithm required to generate pilots with the length of 16, for the channel length

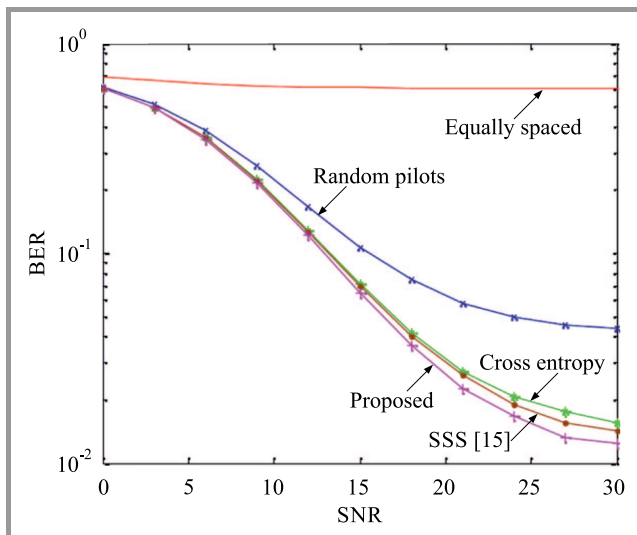


Fig. 8. BER performance comparison of channel estimation for pilot patterns generated using different schemes for $(N, N_p, L) = (256, 16, 60)$.

of $L = 50$ and 60 , is 111 and 188 s over 256 subcarriers, respectively.

6. Conclusions

In this paper, we investigated pilot selection for pilot-aided sparse channel estimation in wide band OFDM systems. Sufficient conditions are derived to guarantee that p-Sylvow is the optimal pilot pattern for some (N, N_p, L) . We have proposed a deterministic procedure to select the pilot pattern for given (N, N_p, L) . If N is a prime, then the proposed algorithm achieves the Welch bound, confirming its effectiveness. Simulation results show that the pilot pattern generated using the proposed scheme significantly improves the key metrics of wireless systems, including MSE and BER, compared to the existing methods with minimized coherence.

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