



### Three Phase Modular Multilevel PV Inverter With Distributed MPPT for Grid-Connected Applications

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**Abstract-** In this paper a three - stage modular cascaded H-bridge multilevel inverter for a grid associated photovoltaic (PV) framework is depicted . To expand the solar energy extraction of each PV string, an individual most extreme power point tracking (MPPT) control plan is connected, which permits the autonomous control of every dc-interface voltage. PV confuses may acquaint uneven power provided with the three-stage framework. To fathom this issue, a control plot with modulation compensation is proposed. The three-stage modular cascaded multilevel inverter model has been constructed. A fuzzy controller is actualized in this venture in the place of PI controller . Every H-bridge module is associated with a 185-W solar panel. Simulation results are exhibited to confirm the achievability of the proposed approach in MATLAB/SIMULINK environment.

**Index Terms**— Cascaded multilevel inverter, distributed maximum power point (MPP) tracking (MPPT), modular, modulation compensation, photovoltaic (PV),Fuzzy controller

#### INTRODUCTION

DUE to the shortage of fossil fuels and environmental problems caused by conventional power generation, renewable energy, particularly solar energy, has become very popular. Solar-electric-energy demand has grown consistently by 20%–25% per annum over the past 20 years [1], and the growth is mostly in grid-connected applications. With the extraordinary market growth in grid-connected photovoltaic (PV) systems, there are increasing interests in grid-connected PV configurations. Five inverter families can be defined, which are related to different configurations of the PV system: 1) central inverters; 2) string inverters; 3) multi string inverters; 4) ac-module inverters; and 5) cascaded inverters [2]–[7]. The configurations of PV systems are shown in Fig. 1. Cascaded inverters consist of several converters connected in series; thus, the high power and/or high voltage from the combination of the multiple modules

would favor this topology in medium and large grid-connected PV systems [8]–[10]. There are two types of cascaded inverters. Fig. 1(e) shows a cascaded dc/dc converter connection of PV modules [11], [12]. Each PV module has its own dc/dc converter, and the modules with their related converters are still associated in arrangement to make a high dc voltage, which is given to a streamlined dc/air conditioning inverter. This approach joins parts of string inverters and air conditioning module inverters and offers the benefits of individual module most extreme power point (MPP) following (MPPT), yet it is not so much exorbitant but rather more proficient than air conditioning module inverters. Be that as it may, there are two power change organizes in this arrangement. Another fell inverter is appeared in Fig. 1(f), where each PV board is associated with its own particular dc/air conditioning inverter, and those inverters are then set in arrangement to achieve a high-voltage level [13]–[16]. This fell inverter would keep up the advantages of "one converter for each board, for example, better use per PV module, ability of blending diverse sources, and excess of the framework. Furthermore, this dc/air conditioning fell inverter evacuates the requirement for the per-string dc transport and the focal dc/air conditioning inverter, which additionally enhances the general productivity. The measured fell H-connect multilevel inverter, which requires a segregated dc hotspot for every H-extension, is one dc/air conditioning fell inverter topology. The different dc interfaces in the multilevel inverter make free voltage control conceivable. Subsequently, individual MPPT control in each PV module can be accomplished, and the vitality reaped from PV boards can be amplified. In the mean time, the measured quality and minimal effort of Multi level converters would position them as a prime possibility for the up and coming era of effective, vigorous, and solid lattice associated sun based power gadgets. A secluded fell H-connect multilevel inverter topology for single-or three-stage lattice associated PV frameworks is displayed in this paper. The board crisscross issues are tended to demonstrate the need of individual MPPT control, and a

control plot with circulated MPPT control is then proposed. The dispersed MPPT control plan can be connected to both single and three-stage frameworks.

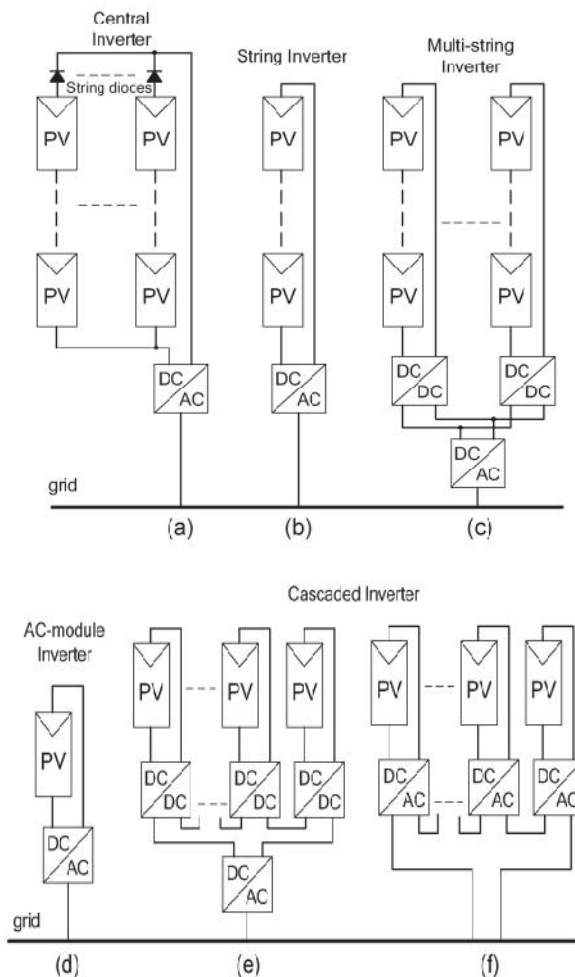


Fig. 1. Configurations of PV systems. (a) Central inverter. (b) String inverter. (c) Multi string inverter. (d) AC-module inverter. (e) Cascaded dc/dc converter. (f) Cascaded dc/ac inverter.

. What's more, for the displayed three-stage lattice associated PV framework, if each PV module is worked at its own MPP, PV bungalows may acquaint unequal power provided with the three-stage multilevel inverter, prompting to lopsided infused matrix current. To adjust the three-stage lattice current, tweak remuneration is likewise added to the control framework. A three-stage measured fell multilevel inverter model has been fabricated. Every H-scaffold is associated with a 185-W sun oriented board. The secluded outline will build the adaptability of the framework and decrease the cost also. Reproduction results are given to exhibit the created control plot.

## II. SYSTEM DESCRIPTION

Secluded fell H-connect multilevel inverters for single and three-stage lattice associated PV frameworks are appeared in Fig. 2. Every stage comprises of  $n$  H-connect converters associated in arrangement, and the dc connection of every H-extension can be encouraged by a PV board or a short string of PV boards. The fell multilevel inverter is associated with the matrix through L channels, which are utilized to diminish the sounds in the current. By various mixes of the four switches in every H-connect module, three yield voltage levels can be created:  $-v_{dc}$ ,  $0$ , or  $+v_{dc}$ . A cascaded multilevel inverter with  $n$  input sources will provide  $2n + 1$  levels to synthesize the ac output waveform. This  $(2n + 1)$ -level voltage waveform enables the reduction of harmonics in the synthesized current, reducing the size of the needed output filters. Multilevel inverters also have other advantages such as reduced voltage stresses on semiconductor switches and having higher efficiency when compared to other converter topologies [17].

## III. PANEL MISMATCHES

PV mismatch is an important issue in the PV system. Due to the unequal received irradiance, different temperatures, and aging of the PV panels, the MPP of each PV module may be different. If each PV module is not controlled independently, the efficiency of the overall PV system will be decreased. To show the necessity of individual MPPT control, a five-level two-H-bridge single-phase inverter is simulated in MATLAB/SIMULINK. Each H-bridge has its own 185-W PV panel connected as an isolated dc source. The PV panel is modeled according to the specification of the commercial PV panel from A strong energy CHSM-5612M. Consider an operating condition that each panel has a different irradiation from the sun; panel 1 has irradiance  $S = 1000 \text{ W/m}^2$ , and panel 2 has  $S = 600 \text{ W/m}^2$ . If only panel 1 is tracked and its MPPT controller determines the average voltage of the two panels, the power extracted from panel 1 would be 133 W, and the power from panel 2 would be 70 W, as can

be seen in Fig. 3. Without individual MPPT control, the total power harvested from the PV system is 203 W. However, Fig. 4 shows the MPPs of the PV panels under the different irradiance. The maximum output power values will be 185 and 108.5 W when the  $S$  values are 1000 and 600  $\text{W/m}^2$ , respectively, which means that the total power harvested from the PV system would be 293.5 W if individual MPPT can be achieved. This higher value is about 1.45 times of the one before. Thus, individual MPPT control in each

PV module is required to increase the efficiency of the PV system. In a three-phase grid-connected PV system, a PV mismatch may cause more problems. Aside from decreasing the efficiency, this could even introduce unbalanced power supplied to the three-phase grid-connected system. If there are PV mismatches between phases, the input power of each phase would be different. Since the grid voltage is balanced, this difference in input power will cause unbalanced current to the grid, which is not allowed by grid standards. For example, to unbalance the current per phase more than 10% is not allowed for some utilities, where the percentage imbalance is calculated by taking the maximum deviation from the average current and dividing it by the average current [18]

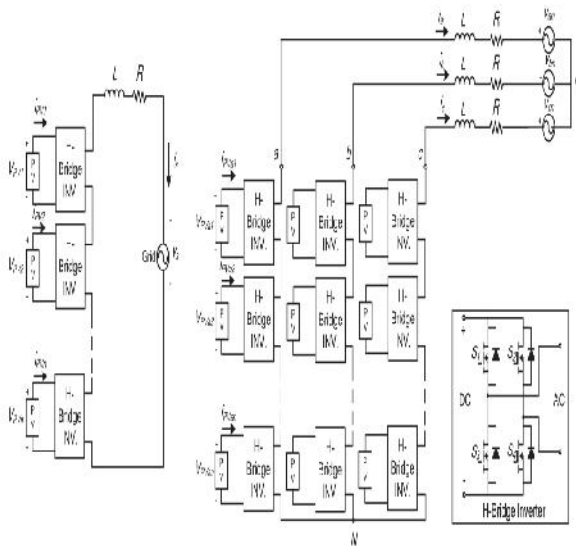


Fig. 2. Topology of the modular cascaded H-bridge multilevel inverter for grid-connected PV systems.

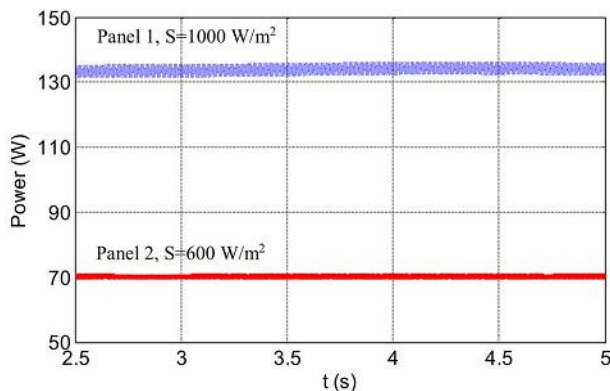


Fig. 3. Power extracted from two PV panels

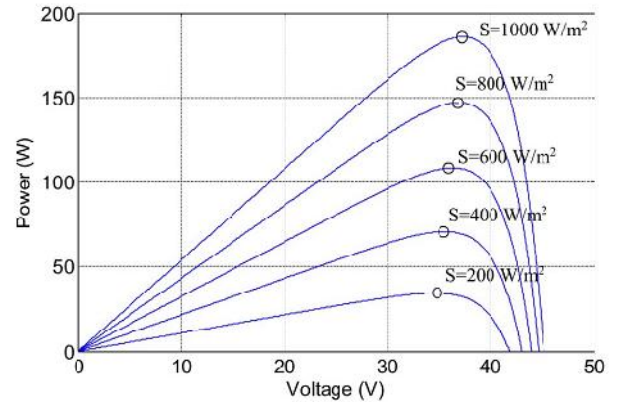


Fig. 4.  $P-V$  characteristic under the different irradiance

#### IV. CONTROL SCHEME

##### A. Distributed MPPT Control

In order to eliminate the adverse effect of the mismatches and increase the efficiency of the PV system, the PV modules need to operate at different voltages to improve the utilization per PV module. The separate dc links in the cascaded H-bridge multilevel inverter make independent voltage control possible. To realize individual MPPT control in each PV module, the control scheme proposed in [19] is updated for this application. The distributed MPPT control of the three-phase cascaded H-bridge inverter is shown in Fig. 5. In each H-bridge module, an MPPT controller is added to generate the dc-link voltage reference. Each dc-link voltage is compared to the corresponding voltage reference, and the sum of all errors is controlled through a total voltage controller that determines the current reference  $I_{dref}$ . The reactive current reference  $I_{qref}$  can be set to zero, or if reactive power compensation is required,  $I_{qref}$  can also be given by a reactive current calculator [20], [21]. The synchronous reference frame phase-locked loop (PLL) has been used to find the phase angle of the grid voltage [22]. As the classic control scheme in three-phase systems, the grid currents in abc coordinates are converted to dq coordinates and regulated through proportional-integral (PI) controllers to generate the modulation index in the dq coordinates, which is then converted back to three phases. The distributed MPPT control scheme for the single-phase system. The total voltage controller gives the magnitude of the active current reference, and a PLL provides the frequency and phase angle of the active current reference. The current loop then gives the modulation index. To make each PV module operate at its own MPP, take phase a as an example; the voltages  $v_{dc a2}$  to  $v_{dc a}$  are controlled individually through  $n - 1$  loops. Each voltage controller gives the modulation index proportion of one H-bridge module in phase a. After multiplied by the modulation index of phase a,  $n - 1$  modulation indices can be obtained. Also, the modulation index for

the first H-bridge can be obtained by subtraction. The control schemes in phases b and c are almost the same. The only difference is that all dc-link voltages are regulated through PI controllers, and n modulation index proportions are obtained for each phase .

A phase-shifted sinusoidal pulse width modulation switching scheme is then applied to control the switching devices of each H-bridge. It can be seen that there is one H-bridge module out of  $N$  modules whose modulation index is obtained by subtraction. For single-phase systems,  $N = n$ , and for three-phase systems,  $N = 3n$ , where  $n$  is the number of H-bridge modules per phase. The reason is that  $N$  voltage loops are necessary to manage different voltage levels on  $N$  H-bridges, and one is the total voltage loop, which gives the current reference. So, only  $N - 1$  modulation indices can be determined  $N-1$  voltage loops, and one modulation index has to be obtained by subtraction. Many MPPT methods have been developed and implemented . The incremental conductance method has been used in this paper..

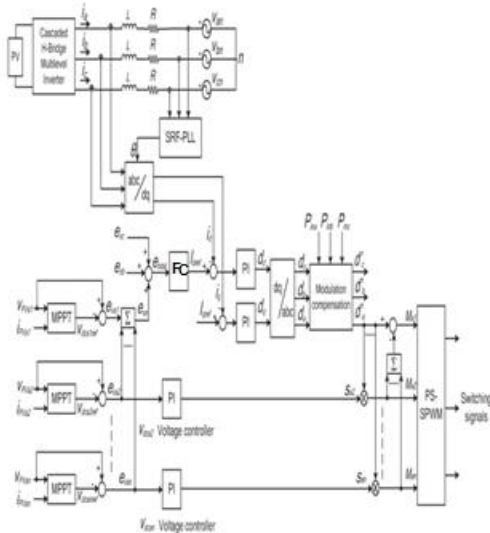


Fig. 5. Control scheme for three-phase modular cascaded H-bridge multilevel PV inverter.

**B. Modulation Compensation**

As mentioned earlier, a PV mismatch may cause more problems to a three-phase modular cascaded H-bridge multilevel PV inverter. With the individual MPPT control in each H-bridge module, the input solar power of each phase would be different, which introduces unbalanced current to the grid. To solve the issue, a zero sequence voltage can be imposed upon the phase legs in order to affect the current flowing into each phase [25], [26]. If the updated inverter output phase voltage is proportional to the unbalanced power, the current will be balanced. Thus, the modulation compensation block, as

shown in Fig. 6, is added to the control system of three-phase modular cascaded multilevel PV inverters. The key is how to update the modulation index of each phase without increasing the complexity of the control system.

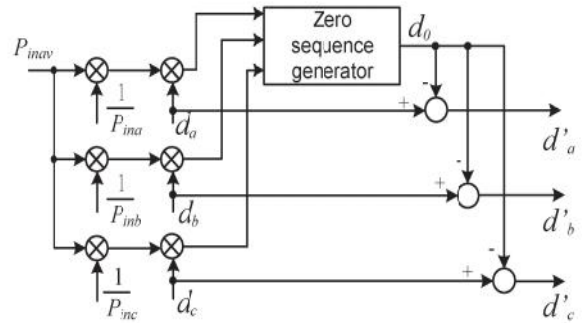


Fig. 6. Modulation compensation scheme.

First, the unbalanced power is weighted by ratio  $r_j$ , which is calculated as

$$r_j = \frac{P_{inav}}{P_{inj}} \tag{1}$$

where  $P_{inj}$  is the input power of phase  $j$  ( $j = a, b, c$ ), and  $P_{inav}$  is the average input power. Then, the injected zero sequence modulation index can be generated as

$$d_0 = \frac{1}{2} [\min(r_a \cdot d_a, r_b \cdot d_b, r_c \cdot d_c) + \max(r_a \cdot d_a, r_b \cdot d_b, r_c \cdot d_c)] \tag{2}$$

where  $d_j$  is the modulation index of phase  $j$  ( $j = a, b, c$ ) and is determined by the current loop controller. The modulation index of each phase is updated by

$$d'_j = d_j - d_0 \tag{3}$$

Only simple calculations are needed in the scheme, which will not increase the complexity of the control system. An example is presented to show the modulation compensation scheme more clearly. Assume that the input power of each phase is unequal

$$P_{ina} = 0.8 \quad P_{inb} = 1 \quad P_{inc} = 1 \tag{4}$$

**V. FUZZY CONTROLLER**

The word Fuzzy means vagueness. Fuzziness occurs when the boundary of piece of information is not clear-cut. In 1965 Lotfi A. Zahed propounded the fuzzy set theory. Fuzzy set theory exhibits immense potential for effective solving of the uncertainty in the problem. Fuzzy set theory is an excellent mathematical tool to handle the uncertainty arising due to vagueness. Understanding human speech and recognizing

handwritten characters are some common instances where fuzziness manifests.

Fuzzy set theory is an extension of classical set theory where elements have varying degrees of membership. Fuzzy logic uses the whole interval between 0 and 1 to describe human reasoning. In FLC the input variables are mapped by sets of membership functions and these are called as “FUZZY SETS”.

Fuzzy set comprises from a membership function which could be defines by parameters. The value between 0 and 1 reveals a degree of membership to the fuzzy set. The process of converting the crisp input to a fuzzy value is called as “fuzzification.” The output of the Fuzzier module is interfaced with the rules. The basic operation of FLC is constructed from fuzzy control rules utilizing the values of fuzzy sets in general for the error and the change of error and control action. Basic fuzzy module is shown in fig.6. The results are combined to give a crisp output controlling the output variable and this process is called as “DEFUZZIFICATION.”

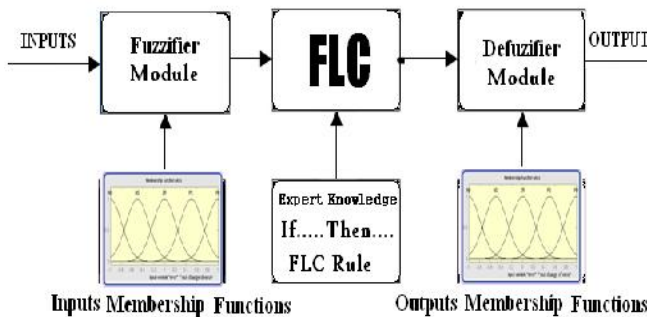


Fig.7. Fuzzy Basic Module

*Fuzzy rules*

In the fuzzy control, input and output variables are the size of the form to describe in words, so to select special vocabulary to describe these variables, generally used in "big, medium and small" Three words to express the controller input and output variables state, plus the positive and negative directions, and zero, a total of seven words : { negative big, negative medium, negative small, zero, positive small, middle, CT }, the general terms used in the English abbreviation prefix : {NB , NM, NS , ZE, PS , PM, PB }.

COE								
E	NB	NM	NS	ZE	PS	PM	PB	
	NB	NB	NB	NB	NM	NS	ZE	

NM	NB	NB	NB	NM	NS	ZE	PS
NS	NB	NM	NS	NS	ZE	PS	PM
ZE	NB	NM	NS	ZE	PB	NS	ZE
PS	NM	NS	ZE	PS	PM	PM	PB
PM	NS	ZE	PS	PM	PB	PB	PB
PB	ZE	PS	PM	PB	PB	PB	PB

Table 1:Fuzzy rules

**VI. Simulation Block Diagram and Results**

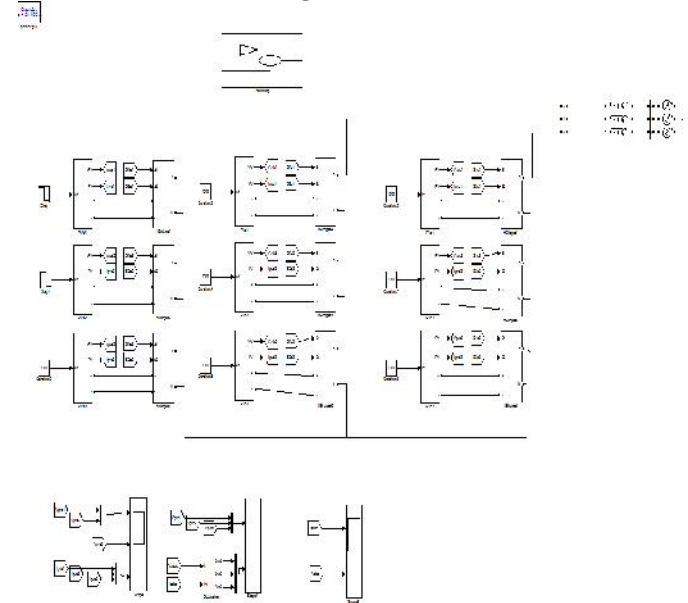


Fig8:Simulation Block diagram

Waveforms:

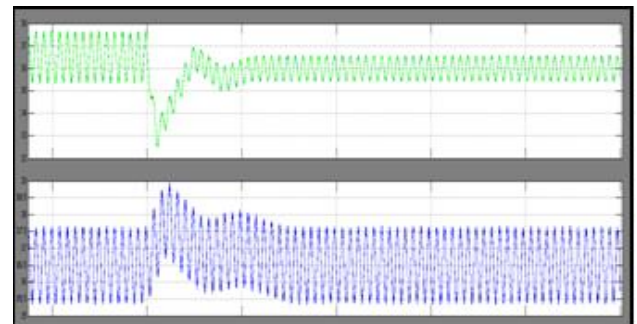


Fig. 9. DC-link voltages of phase a with distributed MPPT (T = 25 C). (a) DC-link voltage of modules 1 and 2. (b) DC-link voltage of module 3.

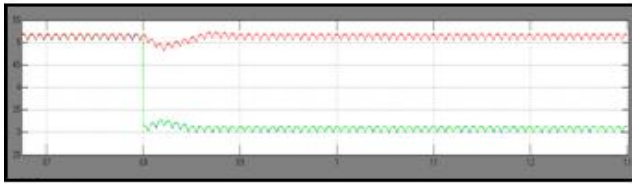


Fig. 10. PV currents of phase *a* with distributed MPPT ( $T = 25$  C).

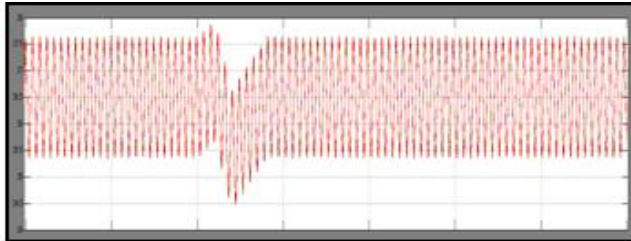


Fig. 11. DC-link voltages of phase *b* with distributed MPPT ( $T = 25$  C).

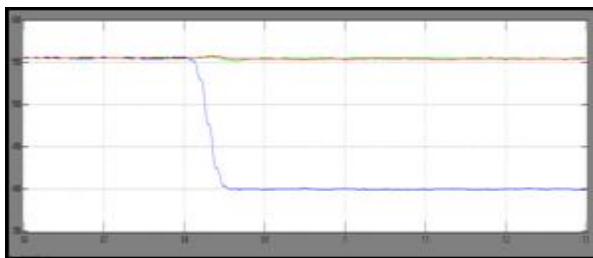


Fig. 12. Power extracted from PV panels with distributed MPPT.

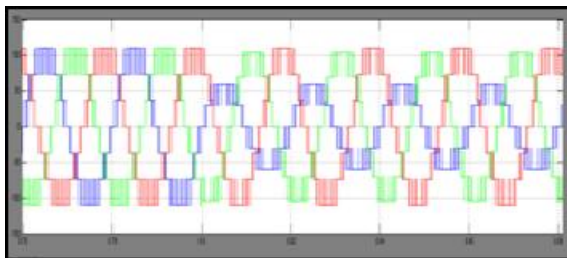


Fig. 13. Three-phase inverter output voltage waveforms with modulation compensation.

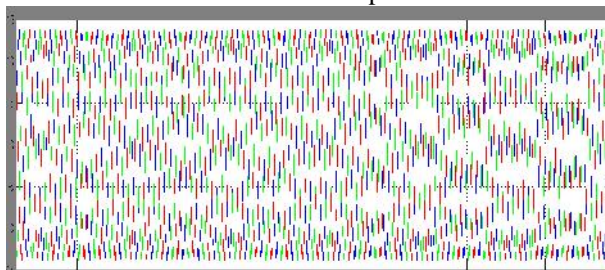


Fig. 14. Three-phase grid current waveforms with modulation compensation.

## VI. CONCLUSION

In this project, a modular cascaded H-bridge multilevel inverter for grid-connected PV applications has been presented. The multilevel inverter topology will help to improve the utilization of connected PV modules if the voltages of the separate dc links are controlled independently. Thus, a distributed MPPT control scheme for both single- and three-phase PV systems has been applied to increase the overall efficiency of PV systems. For the three-phase grid-connected PV system, PV mismatches may introduce unbalanced supplied power, resulting in unbalanced injected grid current. A modulation compensation scheme, which will not increase the complexity of the control system or cause extra power loss, is added to balance the grid current. Fuzzy controller is implemented in this project for the better regulation of the MPPT control of the proposed system. With the proposed control scheme, each PV module can be operated at its own MPP to maximize the solar energy extraction, and the three-phase grid current is balanced even with the unbalanced supplied solar power.

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