



Power Quality Improvement Features For A Distributed Generation System Using Grid Interface Inverter

Badavath Srinu¹, Sadik Ahamad Khan², Subrahmanyam P³

¹*Pursuing M.Tech in the field of POWER SYSTEMS

²*Working as Assistant Professor in the EEE Department

³*Working as Assistant Professor in the EEE Department

ABSTRACT:

This paper presents that, the renewable energy resources are being increasingly connected to distribution systems by utilizing power electronic converters. And it presents a novel control strategy for achieving maximum benefits from these grid-interfacing inverters when installed in 3-phase 4-wire distribution systems. It is controlled to perform as a multi-function device by incorporating active power filter functionality. The inverter can thus be utilized as: power converter to inject power generated from RES to the grid, and shunt APF to compensate current unbalance, load current harmonics, load reactive power demand and load neutral current. All of these functions may be accomplished either individually or simultaneously. With such a control, the combination of grid-interfacing inverter and the 3-phase 4-wire linear/non-linear unbalanced load at point of common coupling appears as balanced linear load to the grid.

Key words- *power quality, 3 Phase inverter, RES, APF*

I. INTRODUCTION:

In the last few years, electricity market deregulation, together with growing economic, environmental, and social concerns, has increased the difficulty to burn fossil fuels, and to obtain new licenses to build transmission lines (rights-of-way) and high-power facilities. This situation started the growth of decentralized electricity generation (using renewable energy resources). Seventy five percent of total global energy demand is supplied by the burning of fossil fuels. But increasing air pollution, global warming concerns, diminishing fossil fuels and their increasing cost have made it necessary to look towards renewable sources as a future energy solution. Since the past decade, there has been an enormous interest in many countries on renewable energy for power generation. The market liberalization and government's incentives have further accelerated the renewable energy sector growth. Renewable energy source (RES) integrated at distribution level is termed

as distributed generation (DG). The utility is concerned due to the high penetration level of intermittent RES in distribution systems as it may pose a threat to network in terms of stability, voltage regulation and power-quality (PQ) issues.

Therefore, the DG systems are required to comply with strict technical and regulatory frameworks to ensure safe, reliable and efficient operation of overall network. With the advancement in power electronics and digital control technology, the DG systems can now be actively controlled to enhance the system operation with improved PQ at PCC. However, the extensive use of power electronics based equipment and non-linear loads at PCC generate harmonic currents, which may deteriorate the quality of power.

Generally, current controlled voltage source inverters are used to interface the intermittent RES in distributed system. Recently, a few control strategies for grid connected inverters incorporating PQ solution have been proposed. An inverter operates as active inductor at a certain frequency to absorb the harmonic current. But the exact calculation of network inductance in real-time is difficult and may deteriorate the control performance.

A similar approach in which a shunt active filter acts as active conductance to damp out the harmonics in distribution network. A control strategy for renewable interfacing inverter based on α - β theory is proposed. In this strategy both load and inverter current sensing is required to compensate the load current harmonics. The non-linear load current harmonics may result in voltage harmonics and can create a serious PQ problem in the power system network. Active power filters (APF) are extensively used to compensate the load current harmonics and load unbalance at distribution level.

This results in an additional hardware cost. However, in this paper authors have incorporated the features of APF in the, conventional inverter interfacing renewable with the grid, without any additional hardware cost. Here, the main idea is the maximum utilization of inverter rating which is most of the time

underutilized due to intermittent nature of RES. It is shown in this paper that the grid-interfacing inverter can effectively be utilized to perform following important functions: 1) transfer of active power harvested from the renewable resources (wind, solar, etc.); 2) load reactive power demand support; 3) current harmonics compensation at PCC; and 4) current unbalance and neutral current compensation in case of 3-phase 4-wire system. Moreover, with adequate control of grid-interfacing inverter, all the four objectives can be accomplished either individually or simultaneously

II. PROPOSED SYSTEM DESCRIPTION:

The proposed system consists of RES connected to the dc-link of a grid-interfacing inverter as shown in Fig. 1. The voltage source inverter is a key element of a DG system as it interfaces the renewable energy source to the grid and delivers the generated power. The RES may be a DC source or an AC source with rectifier coupled to dc-link. Usually, the fuel cell and photovoltaic energy sources generate power at variable low dc voltage, while the variable speed wind turbines generate power at variable ac voltage. Thus, the power generated from these renewable sources needs power conditioning (i.e., dc/dc or ac/dc) before connecting on dc-link. The dc-capacitor decouples the RES from grid and also allows independent control of converters on either side of dc-link.

A. DC-Link Voltage and Power Control Operation:

Due to the intermittent nature of RES, the generated power is of variable nature. The dc-link plays an important role in transferring this variable power from renewable energy source to the grid. RES are represented as current sources connected to the dc-link of a grid-interfacing inverter. Fig. 2 shows the systematic representation of power transfer from the renewable energy resources to the grid via the dc-link. The current injected into dc-link at voltage level V_{dc} can be given as

$$I_{dc1} = \frac{P_{res}}{V_{dc}} \quad (1)$$

Where P_{RES} is the power generated from RES.

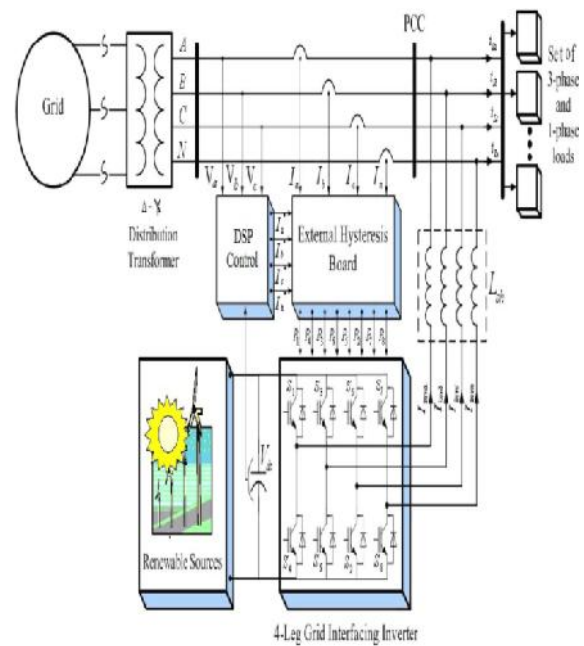


Fig.1: Schematic of proposed renewable based distributed generation system

The current flow on the other side of dc-link can be represented as,

$$I_{dc2} = \frac{P_{inv}}{V_{dc}} = \frac{P_g + P_{loss}}{V_{dc}} \quad (2)$$

Where P_{inv} , P_g and P_{loss} are total power available at grid interfacing inverter side, active power supplied to the grid and inverter losses, respectively. If inverter losses are negligible then, $P_{res} = P_g$

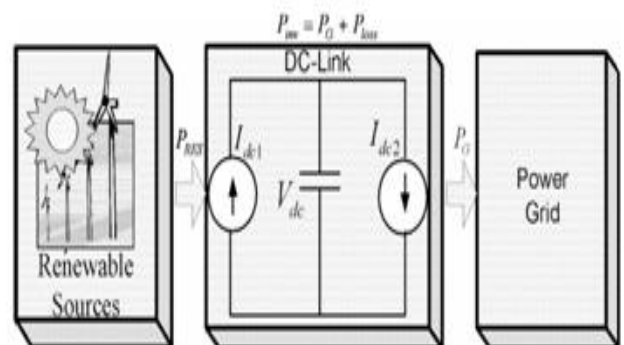


Fig.2: DC-Link equivalent diagram

B. Control of Grid Interfacing Inverter:

The control diagram of grid interfacing inverter for a 3-phase, 4-wire system is shown in Fig. 3. The fourth leg of inverter is used to compensate the neutral current of load. The main aim of proposed approach is to regulate the power at PCC during:

$$1. P_{res} = 0$$

2. $P_{res} < \text{Total load power } (P_L)$
3. $P_{res} > P_L$

While performing the power management operation, the inverter is actively controlled in such a way that it always draws/supplies fundamental active power from/ to the grid. If the load connected to the PCC is non-linear or unbalanced or the combination of both, the given control approach also compensate the harmonics, and neutral current. The duty ratio of inverter switches are varied in a power cycle such that the combination of load and inverter injected power appears as balanced resistive load to the grid. The regulation of dc-link voltage carries the information regarding the exchange of active power in between renewable source and grid. Thus the output of dc-link voltage regulator results in an active current (I_m). The multiplication of active current component (I_m) with unity grid voltage vector templates (U_a , U_b and U_c) generates the reference grid currents (I_a^* , I_b^* and I_c^*). The reference grid neutral current (I_n) is set to zero, being the instantaneous sum of balanced grid currents. The grid synchronizing angle (θ) obtained from phase locked loop (PLL) is used to generate unity vector template as

$$U_a = \text{Sin}(\theta) \quad (3)$$

$$U_c = \text{Sin}(\theta - \frac{2\pi}{3}) \quad (4)$$

$$U_b = \text{Sin}(\theta + \frac{2\pi}{3}). \quad (5)$$

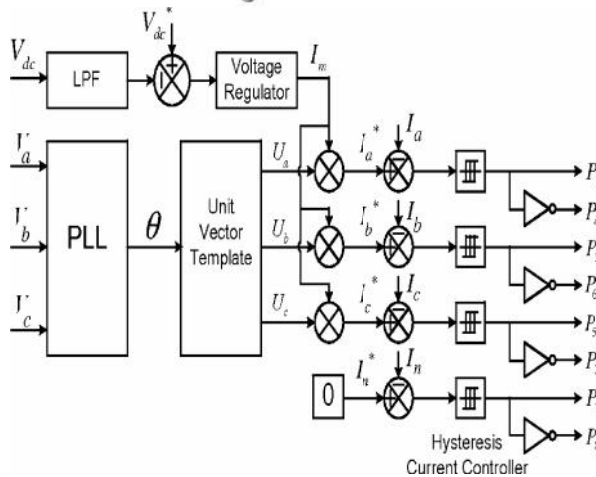


Fig.3: Block diagram representation of grid interfacing inverter control

The actual dc-link voltage (V_{dc}) is sensed and passed through a first-order low pass filter (LPF) to eliminate the presence of switching ripples on the dc-link voltage and in the generated reference current signals. The difference of this filtered dc-link voltage and reference dc-link (V_{dc}^*) is given to a discrete-PI regulator to maintain a constant dc-link voltage under varying generation and load conditions. The dc-link

voltage error $V_{dcerr(n)}$ at nth sampling instant is given as:

$$V_{dcerr(n)} = V_{dc(n)}^* - V_{dc(n)}. \quad (6)$$

The output of discrete-PI regulator at nth sampling instant is expressed as,

$$I_m(n) = I_m(n-1) + K_{PV_{dc}}(V_{dcerr(n)} - V_{dcerr(n-1)}) + K_{IV_{dc}}V_{dcerr(n)} \quad (7)$$

The instantaneous values of reference three phase grid currents are computed as

$$I_a^* = I_m \cdot U_a \quad (8)$$

$$I_b^* = I_m \cdot U_b \quad (9)$$

$$I_c^* = I_m \cdot U_c. \quad (10)$$

The neutral current, present if any, due to the loads connected to the neutral conductor should be compensated by forth leg of grid-interfacing inverter and thus should not be drawn from the grid. In other words, the reference current for the grid neutral current is considered as zero and can be expressed as

$$I_n^* = 0. \quad (11)$$

The reference grid currents (I_a^* , I_b^* , I_c^* and I_n^*) are compared with actual grid currents (I_a , I_b , I_c and I_n) to compute the actual error as

$$I_{aerr} = I_a^* - I_a \quad (12)$$

$$I_{berr} = I_b^* - I_b \quad (13)$$

$$I_{cerr} = I_c^* - I_c \quad (14)$$

$$I_{nerr} = I_n^* - I_n. \quad (15)$$

These current errors are given to hysteresis current controller. The hysteresis controller then generates the switching pulses (P_1 to P_8) for the gate drives of grid-interfacing inverter. The average model of 4-leg inverter can be obtained by the following state space equations,

$$\frac{dI_{Inva}}{dt} = \frac{(V_{Inva} - V_a)}{L_{sh}} \quad (16)$$

$$\frac{dI_{Invb}}{dt} = \frac{(V_{Invb} - V_b)}{L_{sh}} \quad (17)$$

$$\frac{dI_{Invc}}{dt} = \frac{(V_{Invc} - V_c)}{L_{sh}} \quad (18)$$

$$\frac{dI_{Invn}}{dt} = \frac{(V_{Invn} - V_n)}{L_{sh}} \quad (19)$$

$$\frac{dV_{dc}}{dt} = \frac{(I_{Invad} + I_{Invbd} + I_{Invcd} + I_{Invnd})}{C_{dc}} \quad (20)$$

Where V_{inva} , V_{invb} , V_{invc} and V_{invn} are the three-phase ac switching voltages generated on the output terminal of inverter. These inverter output voltages can

be modeled in terms of instantaneous dc bus voltage and switching pulses of the inverter as

$$V_{Inva} = \frac{(P_1 - P_4)}{2} V_{dc} \quad (21)$$

$$V_{Invb} = \frac{(P_3 - P_6)}{2} V_{dc} \quad (22)$$

$$V_{Invc} = \frac{(P_5 - P_2)}{2} V_{dc} \quad (23)$$

$$V_{Invd} = \frac{(P_7 - P_8)}{2} V_{dc} \quad (24)$$

Similarly the charging currents I_{Invad} , I_{Invbd} , I_{Invcd} and I_{Invnd} on du bus due to each leg of inverter can be expressed as

$$I_{Invad} = I_{Inva}(P_1 - P_4) \quad (25)$$

$$I_{Invbd} = I_{Invb}(P_3 - P_6) \quad (26)$$

$$I_{Invcd} = I_{Invc}(P_5 - P_2) \quad (27)$$

$$I_{Invnd} = I_{Invn}(P_7 - P_8) \quad (28)$$

The switching pattern of each IGBT inside inverter can be formulated on the basis of error between actual and reference current of inverter, which can be explained as:

If $I_{Inva} < (I_{Inva}^* - h_b)$, then upper switch S_1 will be OFF ($P_1 = 0$) and lower switch S_4 will be ON ($P_4 = 1$) in the phase "a" leg of inverter.

If $I_{Inva} > (I_{Inva}^* + h_b)$, then upper switch S_1 will be ON ($P_1 = 1$) and lower switch S_4 will be OFF ($P_4 = 0$) in the phase "a" leg of inverter.

Where h_b is the width of hysteresis band, on the same principle, the switching pulses for the other remaining three legs can be derived.

III. SIMULATON RESULTS:

The simulation results of proposed system are clearly shown in below figures 4, 5 and 6. The PQ results of different type of grids are shown in below fig 4.

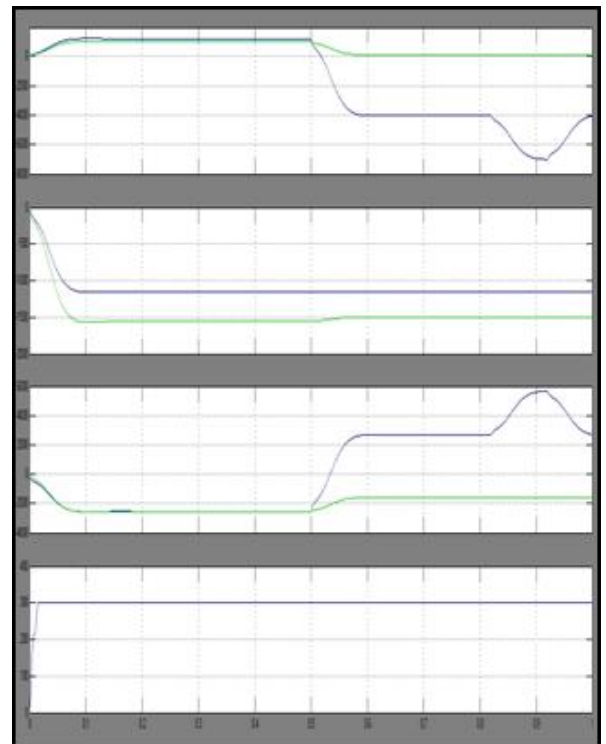


Fig.4: Simulation results: (a) PQ-Grid, (b) PQ-Load, (c) PQ-Inverter, (d) dc-link voltage

The Simulation results of Grid voltages, Grid currents, unbalanced load currents and inverter currents are shown in below fig 5. Similarly an experiment result of dynamic performance of proposed approach is clearly shown in below fig 6.

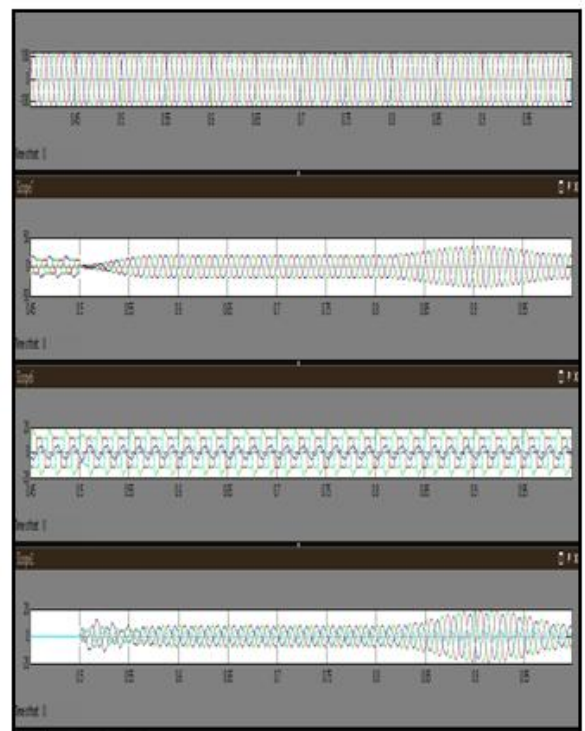


Fig.5: Simulation results: (a) Grid voltages, (b) Grid Currents (c) Unbalanced load currents, (d) Inverter Currents

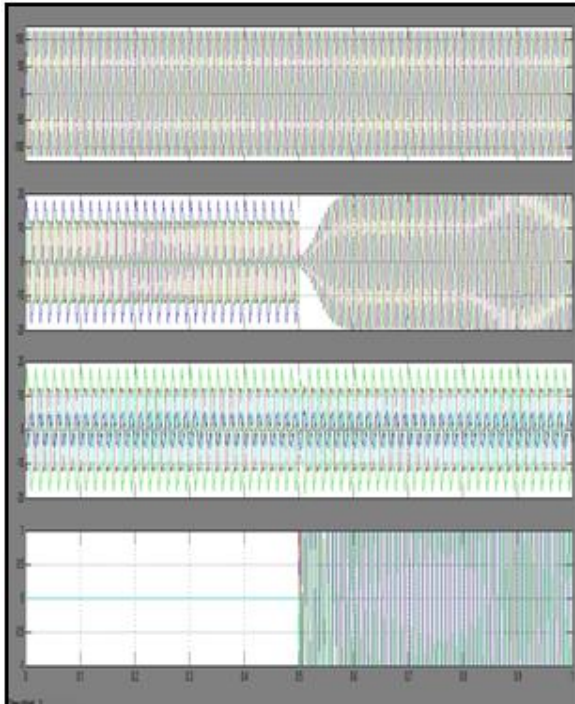


Fig.6: Experimental results: Dynamic performance of proposed approach

IV. CONCLUSION:

A Novel control of an existing grid-interfacing inverter to improve the quality of power at PCC for a 3-phase 4-wire DG system. The grid-interfacing inverter can be effectively utilized for power conditioning without affecting its normal operation of real power transfer. The grid-interfacing inverter with the proposed approach can be utilized to Inject real power generated from RES to the grid, and/or Operate as a shunt Active Power Filter (APF). This approach thus eliminates the need for additional power conditioning equipment to improve the quality of power at PCC. It is further demonstrated that the PQ enhancement can be achieved under three different scenarios: $P_{res} = 0$, $P_{res} < P_L$, $P_{res} > P_L$.

The current unbalance, current harmonics and load reactive power, due to unbalanced and non-linear load connected to the PCC, are compensated effectively such that the grid side currents are always maintained as balanced and sinusoidal at unity power factor. Moreover, the load neutral current is

prevented from flowing into the grid side by compensating it locally from the fourth leg of inverter. When the power generated from RES is more than the total load power demand, the grid-interfacing inverter with the proposed control approach not only fulfills the total load active and reactive power demand but also delivers the excess generated sinusoidal active power to the grid at unity power factor.

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AUTHOR PROFILE:

1*BADAVATH SRINU Pursuing M.Tech in Nimra College of Engineering and Technology at Vijayawada. His specialization is Power System. He graduated in Electrical and Electronics Engineering from JNTU Hyderabad. His research interest includes Power flow control, power quality control and Control strategies. (bsrinu89@gmail.com)

2*SADIK AHAMAD KHAN is currently working as a Assistant Professor in Electrical and Electronics Engineering Department, Nimra College of Engineering and Technology (NCET), Vijayawada. He obtained his M.Tech Degree from JNTU University. He received B.Tech degree in Electrical and Electronics Engineering. His research interest includes Power flow control, power quality control and includes Power Electronic Converters and applications.

3*P SUBRAHMANYAM is currently working as a Assistant professor in MGIT, Hyderabad. He graduated in Electrical and Electronics Engineering from JNTU Anantapur. He obtained his M.Tech Degree from Osmania University. He received B.Tech degree in Electrical and Electronics Engineering from JNTU University, Hyderabad. His research interest includes Power flow control, Power quality control. (pschowdaryme@gmail.com)