

## Fixed Point Theorems in 2- Metric Space with Continuous Convex Structure

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### Abstract

In the present paper fixed point theorems are proved for 2- metric spaces with continuous convex structure for more generalized conditions.

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**1. Introduction & Preliminaries:** Since Banach's fixed point theorem in 1922, because of its simplicity and usefulness, it has become a very popular tool in solving the existence problems in many branches of nonlinear analysis. For some more results of the generalization of this principle.

**Theorem 1A:** Banach [1] The well known Banach contraction principle states that "If X is complete metric space and T is a contraction mapping on X into itself, then T has unique fixed point in X".

**Theorem 1 B:** Kanan [16] proved that "If T is self mapping of a complete metric space X into itself satisfying:

$$d(Tx, Ty) \leq \eta [d(x, Tx) + d(y, Ty)]$$

for all  $x, y \in X$ , and  $\eta \in [0, \frac{1}{2}]$ . Then T has unique fixed point in X.

**Theorem 1C:** Fisher [9] proved the result with

$$d(Tx, Ty) \leq \mu [d(Tx, x) + d(Ty, y)] + \delta d(x, y)$$

for all  $x, y \in X$ , and  $\mu, \delta \in [0, \frac{1}{2}]$ . Then T has unique fixed point in X.

**Theorem 1D:** A similar conclusion was also obtained by Chaterjee [3].

$$d(Tx, Ty) \leq \mu [d(Ty, x) + d(Tx, y)]$$

for all  $x, y \in X$ , and  $\eta \in [0, \frac{1}{2}]$ . Then T has unique fixed point in X.

**Theorem 1E:** Ciric [5] proved the result

$$d(Tx, Ty) \leq \eta [d(x, Tx) + d(y, Ty)] + \mu [d(x, Ty) + d(y, Tx)]$$

+  $\delta d(x, y)$

for all  $x, y \in X$ , and  $\eta, \mu, \delta \in [0, 1)$ . Then T has unique fixed point in X.

**Theorem 1F:** Reich [22] proved the result

$$d(Tx, Ty) \leq \mu [d(x, Ty) + d(y, Tx)] + \delta d(x, y)$$

for all  $x, y \in X$ , and  $\mu, \delta \in [0, 1)$ . Then T has unique fixed point in X.

**Theorem 1 G:** In 1977, the mathematician Jaggi [14] introduced the rational expression first

$$d(Tx, Ty) \leq \beta \frac{d(x, Tx)d(y, Ty)}{d(x, y)} + \delta d(x, y)$$

for all  $x, y \in X, x \neq y$ ,  $\beta, \delta \in [0, 1)$  and  $0 \leq \delta + \beta < 1$ . Then T has unique fixed point in X.

**Theorem 1H:** In 1980 the mathematicians Jaggi and Das [15] obtained some fixed point theorems with the mapping satisfying:

$$d(Tx, Ty) \leq \alpha d(x, y) + \beta \frac{d(x, Tx)d(y, Ty)}{d(x, y) + d(y, Tx) + d(x, Ty)}$$

for all  $x, y \in X, x \neq y, \beta, \delta \in [0,1)$  and  $0 \leq \delta + \beta < 1$ . Then T has unique fixed point in X.

These are extensions of Banach contraction principle [1] in terms of a new symmetric rational expression. Takahashi [30] has introduced the definition for convexity in metric space and generalized some fixed point theorems previously proved for the Banach space. Subsequently, Mochado [28], Tallman [31], Nainpally and Singh [29], Guay and Singh [26], Hadzic and Gajic [27] were among others who obtained results in this setting. This paper is a continuation of the investigation in the same setting in form of Altering distance function motivated by Sharma and Devangan [23], Sharma, Sharma, Iskey [24]

**To prove the main result we need following modified definitions:**

**Definition 2.1.** Let  $X$  be a 2-metric space and  $I$  be the closed unit interval. A mapping  $W: X \times X \times I \rightarrow X$  is said to be a convex structure on  $X$  if for all  $x, y \in X, \lambda \in I, a > 0$

$$d(u, (W(x, y, \lambda), a)) \leq \lambda d(u, x, a) + (1 - \lambda) d(u, y, a), \text{ for all } u \in X.$$

The metric space  $(X, d)$  together with a convex structure is called the Takahashi convex metric space.

Any subset of a Banach space is a Takahashi convex metric space with

$$W(x, y, \lambda) = \lambda x + (1 - \lambda)y.$$

**Definition 2.2** Let  $X$  be a convex 2-metric space. A nonempty subset  $K$  of  $X$  is said to be convex if and only if  $W(x, y, \lambda) \in K$  whenever  $x, y \in K, \lambda \in I$ .

Takahashi [5] has shown that the open and closed balls are convex and that an arbitrary intersection of convex sets is also convex.

For an arbitrary  $A \subset X$ , let

$$(1) \quad \tilde{W}(A) = \{W(x, y, \lambda) : x, y \in A, \lambda \in I\}.$$

It is easy to see that

$\tilde{W}: P(X) \rightarrow P(X)$  is a mapping with the properties:

- (i)  $A \subset \tilde{W}(A)$ , for  $A \subset X$ ,
- (ii)  $A \subset B \Rightarrow \tilde{W}(A) \subset \tilde{W}(B)$ , for  $A, B \in P(X)$ ,
- (iii)  $\tilde{W}(A \cap B) \subset \tilde{W}(A) \cap \tilde{W}(B)$ , for any  $A, B \in P(X)$ .

Using this notation we can see that  $K$  is convex iff  $\tilde{W}(K) \subset K$ .

**Definition 2.3.** A convex 2-metric space  $X$  will be said to have property (C) iff every bounded decreasing set of nonempty closed convex subset of  $X$  has nonempty intersection.

**Definition 2.4.** Let  $X$  be a convex 2-metric space and  $A$  be a nonempty closed, convex bounded set in  $X$ . For  $x \in X, a > 0$  let us set

$$r_x(A) = \sup_{y \in A} d(x, y, a).$$

$$\text{And } r(A) = \inf_{x \in A} r_x(A).$$

We thus define  $A_c = \{x \in A : r_x(A) = r(A)\}$  to be the centre of  $A$ .

We denote the diameter of a subset  $A$  of  $X$  by

$$\delta(A) = \sup\{d(x, y, a) : x, y \in A\}.$$

**Definition 2.5.** A point  $x \in A$  is a diametral point of  $A$  iff

$$\sup_{y \in A} d(x, y, a) = \delta(A).$$

**Definition 2.6.** A convex 2-metric space  $X$  is said to have normal structure iff for each closed bounded, convex subset  $A$  of  $X$ , containing at least two points, there exists  $x \in A$ , which is not a diametral point of  $A$ .

**Remarks** Any compact convex 2-metric space has a normal structure.

**Definition 2.7.** A Convex hull of the set  $A (A \subset X)$  is the intersection of all convex sets in  $X$  containing  $A$ , an is denoted by convex  $A$ .

It is obvious that if  $A$  is a convex set, then

$$\tilde{W}^n(A) = \tilde{W}(\tilde{W}(\tilde{W}(A) \dots)) \subset A \text{ for any } n \in \mathbb{N}.$$

If we set

$$A_n = \tilde{W}^n(A), (A \subset X),$$

Then the sequence  $\{A_n\}_{n \in \mathbb{N}}$  will be increasing and  $\limsup A_n$  exists, and  $\limsup A_n = \liminf A_n = \lim A_n = \bigcup_{n=1}^{\infty} A_n$ .

In 1984, M.S. Khan, M. Swalech and S.Sessa [19] expanded the research of the metric fixed point theory to a

new category by introducing a control function which they called an altering distance function. Motivated by them we find the same for 2- metric spaces as follows

**Definition 2.8** ([19]) A function  $\psi : \mathfrak{R}_+ \rightarrow \mathfrak{R}_+$  is called an altering distance function if the following properties are satisfied:

- ( $\psi_1$ )  $\psi(t) = 0 \Leftrightarrow t = 0$
- ( $\psi_2$ )  $\psi$  is monotonically non-decreasing.
- ( $\psi_3$ )  $\psi$  is continuous.

By  $\Psi$  we denote the set of the all altering distance functions.

**Theorem2.9** ( [49] ) Let  $(M, d)$  be a complete 2-metric space, let  $\psi \in \Psi$  and let  $S : M \rightarrow M$  be a mapping  $a > 0$  which satisfies the following inequality

$$\Psi [d(Sx, Sy, a)] \leq \alpha \Psi [d(x, y, a)]$$

For all  $x, y \in M$  and for some  $0 < \alpha < 1$  . Then  $S$  has a unique fixed point  $z_0 \in M$  and moreover for each

$$x \in M \lim_{n \rightarrow \infty} S^n x = z_0$$

**Lemma 2.10** Let  $(M, d)$  be 2- metric space. Let  $\{x_n\}$  be a sequence in  $M$  such that

$$\lim_{n \rightarrow \infty} \Psi [d(x_n, x_{n+1}, a)] = 0$$

If  $\{x_n\}$  is not a Cauchy sequence in  $M$  , then there exist an  $\epsilon_0 > 0$  and sequences of integers positive  $\{m(k)\}$  and  $\{n(k)\}$  with

$$m(k) > n(k) > k$$

Such that  $\Psi [d(x_{m(k)}, x_{n(k)}, a)] \geq \epsilon_0$  ,  $\Psi [d(x_{m(k-1)}, x_{n(k)}, a)] < \epsilon_0$

- (i)  $\lim_{k \rightarrow \infty} \Psi [d(x_{m(k-1)}, x_{n(k+1)}, a)] = \epsilon_0$
- (ii)  $\lim_{k \rightarrow \infty} \Psi [d(x_{m(k)}, x_{n(k)}, a)] = \epsilon_0$
- (iii)  $\lim_{k \rightarrow \infty} \Psi [d(x_{m(k-1)}, x_{n(k)}, a)] = \epsilon_0$

**Remark 2.11** It is easy to get

$$\lim_{k \rightarrow \infty} \Psi [d(x_{m(k+1)}, x_{n(k+1)}, a)] = \epsilon_0$$

**Definition (2.12)** A 2- metric space is a space  $X$  in which for each triple of points  $x, y, z$ , there exists a real function  $d(x, y, z)$  such that

[M<sub>1</sub>] to each pair of distinct points  $x, y, z$ ,

$$d(x, y, z) \neq 0$$

[M<sub>2</sub>]  $d(x, y, z) = 0$  when at least two of  $x, y, z$  are equal

$$[M_3] d(x, y, z) = d(y, z, x) = d(x, z, y)$$

$$[M_4] d(x, y, z) \leq d(x, y, v) + d(x, v, z) + d(v, y, z) \text{ for all } x, y, z, v \text{ in } X.$$

**Definition (2.13):** A sequence  $\{x_n\}$  in a 2-metric space  $(X, d)$  is said to be convergent at  $x$  if

$$\lim_{n \rightarrow \infty} d(x_n, x, z) = 0 \text{ for all } z \text{ in } X.$$

**Definition (2.14)** A sequence  $\{x_n\}$  in a 2-metric space,  $(x, d)$  is said to be Cauchy sequence if

$$\lim_{m, n \rightarrow \infty} d(x_n, x, z) = 0 \text{ for all } z \text{ in } X.$$

**Definition (2.15)** A 2-metric space  $(X, d)$  is said to be complete if every Cauchy sequence in  $X$  is convergent.

Also, we need the following propositions:

Proposition 1[23]. Let  $X$  be a convex 2- metric space. Then

$$(2) \text{ conv } A = \lim A_n = \bigcup_{n=1}^{\infty} A_n, (A \subset X)$$

In the remaining part of this paper  $(X, d)$  will denote a convex 2-metric space.

Proposition 2 [23]. For any subset  $A$  of  $(X, d)$

$$\delta(\text{conv } A) = \delta(A).$$

### 3. Main result

Now we prove the following

**Theorem 3.1.** Let a function  $\psi : \mathfrak{R}_+ \rightarrow \mathfrak{R}_+$  is an altering distance function.  $(X, d)$  be 2- metric space with continuous convex structure and let  $K$  be a closed convex bounded subset of  $(X, d)$  with normal structure and property (C)

If  $A:K \rightarrow K$  is a continuous mapping such that for  $x, y \in K, a > 0$

$$(3) \quad \Psi d(Ax, Ay, a) \leq \Psi \max \left\{ \begin{array}{l} d(x, y, a), d(x, Ax, a), d(y, Ay, a), d(x, Ay, a), d(y, Ax, a) \\ d(x, A^2x, a), d(y, A^2y, a), d(Ax, A^2x, a), d(Ay, A^2y, a) \end{array} \right\}$$

Then  $A$  has a fixed point.

Proof. Let  $F$  be a family of non-empty closed convex subsets  $F \subset K$  so that  $A(F) \subset F$ , then  $F$  is non-empty since  $K \in F$ . We partially order  $F$  by inclusion, and let  $S = \{F_i\}_{i \in \Delta}$  be the decreasing chain in  $F$ . Then by Property (C) we have that

$$F_0 = \bigcap_{i \in I} F_i \neq \emptyset.$$

So,

$$F_0 \in F.$$

Therefore, any chain in  $F$  has a greatest lower bound, and by Zorn's Lemma there is a minimal member  $\mathcal{F}$  in  $F$ . We claim that  $\mathcal{F}$  is a singleton set. If not, then, as shown by Takahashi [5], the centre of  $\mathcal{D}$ , denoted by  $F_C$ , is a non-empty proper closed convex subset of  $\mathcal{F}$ . Now, it is easy to see that

$$\delta(F_C) \leq r(\mathcal{F}) \leq \delta(\mathcal{F}).$$

Now, let us define a sequence  $F_0 = F_C$  and

$$F_{k+1} = \text{conv}(F_k \cup A(F_k)), k = 0, 1, \dots$$

Clearly,  $F_k \subset F_{k+1}, (k = 0, 1, \dots)$ . Thus we shall prove by induction that

$$(4) \quad \delta_k = \delta(F_k) \leq r(\mathcal{F}) = r, \text{ for any } k \in N.$$

For  $k = 0$  (5) is valid. Suppose that it is valid for  $k = 0, 1, \dots, m$ , then we show that it is also valid for  $k = m + 1$ .

By definition of  $\delta(\mathcal{F})$  for any sequence  $\{\varepsilon_n\}, \varepsilon_n > 0 (n \in N), \lim_{n \rightarrow \infty} \varepsilon_n = 0$ , there exist  $\tilde{x}_n, \tilde{y}_n \in F_{m+1}$ , so that  $\delta_{m+1} - \varepsilon_n \leq d(\tilde{x}_n, \tilde{y}_n)$ .

Then, by proposition 2 we have three cases:

- (i)  $\tilde{x}_n, \tilde{y}_n \in F_m (n = 1, 2, \dots)$
- (ii)  $\tilde{x}_n = x_n, \tilde{y}_n = Ay_n (x_n, y_n \in F_m, n = 0, 1, \dots)$
- (iii)  $\tilde{x}_n = Ax_n, \tilde{y}_n = Ay_n (x_n, y_n \in F_m, n = 0, 1, \dots)$

Considering the first case it is clear that  $\delta_{m+1} \leq r$ . So, let us see the second one. For any  $x \in F_0$  thus we have

$$(5) \quad d(x, Ax, a) \leq r$$

We assume that (6) is valid for  $x \in F_k (k = 0, 1, \dots, m - 1)$  and prove that it is valid for  $k = m$ .

For any  $x \in F_m$ , by proposition 1,  $x \in \hat{W}^{n_0}(F_{m-1} \cup A(F_{m-1}))$  for some  $n_0 \in N$ . Then

$$(6) \quad \Psi d(x, Ax, a) \leq \sum_{j \in I_1} \gamma_j \Psi d(x_j, Ax, a) + \sum_{j \in I_2} \gamma_j \Psi d(Ax_j, Ax, a),$$

For  $x_j \in F_{m-1}, j \in I = I_1 \cup I_2$ , ( $I$ -finitary set),  $I_1 \cap I_2 = \emptyset$  and  $\sum_{j \in I} \gamma_j = 1, \gamma_j \geq 0$  for  $j \in I$ . In (7) is sufficient to look only for the case when  $\sum_{j \in I} \gamma_j \neq 0$ .

Further, we have

$$\Psi d(x, Ax, a) \leq \sum_{j \in I_1} \gamma_j \Psi d(x_j, Ax, a) + \sum_{j \in I_2^{(1)}} \gamma_j \Psi d(Ax_j, x, a)$$

$$\sum_{j \in I_2^{(2)}} \gamma_j \Psi d(x_j, Ax_j, a) + \sum_{j \in I_2^{(3)}} \gamma_j \Psi d(x_j, Ax, a)$$

$$\sum_{j \in I_2^{(4)}} \gamma_j \Psi d(x_j, Ax, a) + \sum_{j \in I_2^{(5)}} \gamma_j \Psi d(x_j, Ax_j, a)$$

$$\sum_{j \in I_2^{(6)}} \gamma_j \Psi d(x_j, A^2 x_j, a) + \sum_{j \in I_2^{(7)}} \gamma_j \Psi d(x, A^2 x, a) \\
 \sum_{j \in I_2^{(8)}} \gamma_j \Psi d(Ax_j, A^2 x_j, a) + \sum_{j \in I_2^{(9)}} \gamma_j \Psi d(Ax, A^2 x, a)$$

Where we suppose

$$\text{for } I \in I_2^{(1)} \text{ that } \Psi d(Ax_j, Ax, a) \leq \Psi d(x_j, x, a)$$

$$\text{for } I \in I_2^{(2)} \text{ that } \Psi d(Ax_j, Ax, a) \leq \Psi d(x_j, Ax_j, a)$$

$$\text{for } I \in I_2^{(3)} \text{ that } \Psi d(Ax_j, Ax, a) \leq \Psi d(x, Ax, a)$$

$$\text{for } I \in I_2^{(4)} \text{ that } \Psi d(Ax_j, Ax, a) \leq \Psi d(x_j, Ax, a)$$

$$\text{for } I \in I_2^{(5)} \text{ that } \Psi d(Ax_j, Ax, a) \leq \Psi d(x, Ax_j, a)$$

$$\text{for } I \in I_2^{(6)} \text{ that } \Psi d(Ax_j, Ax, a) \leq \Psi d(x_j, A^2 x_j, a)$$

$$\text{for } I \in I_2^{(7)} \text{ that } \Psi d(Ax_j, Ax, a) \leq \Psi d(x, A^2 x, a)$$

$$\text{for } I \in I_2^{(8)} \text{ that } \Psi d(Ax_j, Ax) \leq \Psi d(Ax, A^2 x_j)$$

$$\text{for } I \in I_2^{(9)} \text{ that } \Psi d(Ax_j, Ax, a) \leq \Psi d(Ax, A^2 x, a).$$

Now, using the hypothesis, one can see that

$$\Psi d(x, Ax, a) \leq \sum_{j \in I_1} \gamma_j \Psi d(x_j, Ax, a) + r \sum_{j \in I_2^{(1)}} \gamma_j \\
 + \sum_{j \in I_2^{(2)}} \gamma_j \Psi d(x_j, Ax_j, a) + \sum_{j \in I_2^{(3)}} \gamma_j \Psi d(x_j, Ax, a) \\
 + \sum_{j \in I_2^{(4)}} \gamma_j \Psi d(x_j, Ax, a) + \sum_{j \in I_2^{(5)}} \gamma_j \Psi d(x_j, Ax_j, a) \\
 + \sum_{j \in I_2^{(6)}} \gamma_j \Psi d(x_j, A^2 x_j, a) + \sum_{j \in I_2^{(7)}} \gamma_j \Psi d(x_j, A^2 x, a) \\
 + \sum_{j \in I_2^{(8)}} \gamma_j \Psi d(Ax_j, A^2 x_j, a) + \sum_{j \in I_2^{(9)}} \gamma_j \Psi d(Ax_j, A^2 x, a)$$

Since by induction, similarly, we have

$$\Psi d(x, Ax, a) \leq \sum_{k \in J_j^{(1)}} \beta_k \Psi d(\hat{x}k, x_j, a) \\
 + \sum_{k \in J_j^{(2)}} \beta_k \Psi d(\hat{x}k, A\hat{x}k, a) + \sum_{k \in J_j^{(3)}} \beta_k \Psi d(x_j, Ax_j, a) \\
 + \sum_{k \in J_j^{(4)}} \beta_k \Psi d(\hat{x}k, Ax_j, a) + \sum_{k \in J_j^{(5)}} \beta_k \Psi d(x_j, A\hat{x}k, a) \\
 + \sum_{k \in J_j^{(6)}} \beta_k \Psi d(\hat{x}k, A^2 \hat{x}k, a) + \sum_{k \in J_j^{(7)}} \beta_k \Psi d(x_j, A^2 x_j, a) \\
 + \sum_{k \in J_j^{(8)}} \beta_k \Psi d(A\hat{x}k, A^2 \hat{x}k, a) + \sum_{k \in J_j^{(9)}} \beta_k \Psi d(Ax_j, A^2 x, a),$$

for  $\hat{x}k \in F_{m-1}$  ( $k \in J_i = \cup_{i=1}^9 J_i^{(i)}$ ,  $\sum_{k \in J_j} \beta_k = 1$  and  $B_k \geq 0, k \in J_j, \sum_{k \in J_j^{(1)}} \beta_k \neq 0$ ). Therefore

$$d(x, Ax_j, a) \leq r$$

and

$$\Psi d(x, Ax, a) \leq \sum_{j \in I_1} \gamma_j \Psi d(x_j, Ax, a) + r(\sum_{j \in I_2^{(1)}} + \sum_{j \in I_2^{(2)}} + \sum_{j \in I_2^{(5)}}) \gamma_j \\
 + \sum_{j \in I_2^{(3)}} \gamma_j \Psi d(x, Ax, a) + \sum_{j \in I_2^{(4)}} \gamma_j \Psi d(x, Ax, a) \\
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 + \sum_{j \in I_2^{(6)}} \gamma_j \Psi d(x_j, A^2 x_j, a) + \sum_{j \in I_2^{(7)}} \gamma_j \Psi d(x, Ax, a) \\
 + \sum_{j \in I_2^{(8)}} \gamma_j \Psi d(Ax_j, A^2 x_j, a) + \sum_{j \in I_2^{(9)}} \gamma_j \Psi d(Ax_j, A^2 x, a).$$

After not more than  $n_0$  steps we shall that

$$\Psi d(x, Ax, a) \leq \sum_{j \in I^*} \gamma_j^* \Psi d(v_j, Ax, a) + \gamma_0^* r,$$

for

$$\gamma_j^* \geq 0, i \in \{0\} \cup I^*$$

$$\gamma_0^* + \sum_{j \in I^*} \gamma_j^* = 1$$

And

$$v_j \in F_{0,j} \in I^*.$$

Since  $F_0$  is the centre we have that

$$d(v_j, Ax, a) \leq r,$$

Which implies that

$$\Psi d(x, Ax) \leq r \text{ for all } x \in F_m.$$

Similarly, we can prove that

$$\Psi d(x, Ay, a) \leq r \text{ for all } x, y \in F_m.$$

So, in the second case we have



$$\delta_{m+1} - \varepsilon_n \leq \Psi d(\tilde{x}_n, \tilde{y}_n, a) \\ = \Psi d(x_n, Ay_n) \leq r, \text{ for } n \in N,$$

And consequently

$$\delta_{m+1} \leq r.$$

Using (4) it is easy to prove this inequality for case (iii). Thus,

$$\delta_m \leq r \text{ for all } m \in N.$$

Let us define  $F^\infty = \bigcup_{k=0}^\infty F_k$ .

$F_0$  is non-empty. So,  $F^\infty$  is non-empty too.

Since  $\delta(F^\infty) < r\delta(F)$ ,  $F^\infty$  is a closed proper subset of  $F$ .

Moreover,  $W$  is continuous and that closure of convex set is convex.

Since mapping  $A$  is continuous so,

$A(F^\infty) \subset F^\infty$  And therefore  $F^\infty$  is a subset of  $F$ , which is a contradiction to the minimality of  $F$ . Hence,  $F$  consists of a single element which is a fixed point for  $A$ .

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