

ORIENTED MANIFOLDS WITH COMPACT SUPPORT AND COHOMOLOGY ALGEBRA

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Abstract

The cohomology of M with compact supports is the graded algebra $\Omega(G_c(M), \delta)$ and is given by $\Omega_c(M) = \sum_{k=0}^n \Omega_c^k(M)$. The bilinear map $\Omega(M) \times \Omega_c(M) \rightarrow \Omega_c(M)$ is induced by $G(M) \times G_c(M) \rightarrow \Omega_c(M)$ and makes $\Omega_c(M)$ into a left graded $\Omega(M)$ -module. $\Omega(S^n)$, which is the cohomology of S^n , is determined by $\Omega^0(S^n) \cong \Omega^n(S^n) \cong \mathbb{R}$ and $\Omega^k(S^n) = 0$ for $n \geq 1$. Also, we determine the cohomology of \mathbb{R}^n with compact supports. Finally, it is shown that the map $i_M: \Omega(M) \rightarrow \Omega_c(M)^*$ is a linear isomorphism.

Keywords: Compact manifold, cohomology, graded algebra, isomorphism, bilinear map.

1. Introduction

Let M be an n -manifold, then the graded algebra of differential forms on M is defined as $G(M) = \sum_{k=0}^n G^k(M)$ and $G(M)$ is converted into a graded differential algebra by the exterior derivative (Greub et al., 1972). The differential forms Φ satisfying the condition $\delta\Phi = 0$ construct cocycles in this differential algebra and this differential form is closed. The closed forms are graded subalgebra $Z(M)$ of $G(M)$ as δ is an antiderivation (Bott and Tu, 1982). The subset $H(M) = \delta G(M)$ is a graded ideal in $Z(M)$. The differential forms in $G(M)$ are called coboundaries and the corresponding cohomology algebra is defined by $\Omega(M) = Z(M)/H(M)$ and this cohomology algebra is called the de Rham cohomology algebra of M (Iversen, 1986).

The cohomology of M with compact supports is the graded algebra $\Omega(G_c(M), \delta)$ (Grivaux, 2010). It is denoted by $\Omega_c(M)$ and is defined by

$$\Omega_c(M) = \sum_{k=0}^n \Omega_c^k(M), \quad n = \dim M.$$

Multiplication in $G(M)$ is restricted to a real bilinear map as $G_c(M)$ is an ideal (Kobayashi and Nomizu, 1963). $G_c(M)$ is confined into a left graded $G(M)$ -module by this multiplication which is given by

$$G(M) \times G_c(M) \rightarrow \Omega_c(M).$$

The bilinear map $\Omega(M) \times \Omega_c(M) \rightarrow \Omega_c(M)$ is induced by the above map and makes $\Omega_c(M)$ into a left graded $\Omega(M)$ -module (Sternberg, 1964). This map can be written as

$$(\lambda, \mu) \mapsto \alpha * \beta, \quad \lambda \in \Omega(M), \mu \in \Omega_c(M).$$

In the same way, $\Omega_c(M)$ can be converted into a right graded $\Omega(M)$ -module and we can write $\mu * \lambda, \mu \in$

$\Omega_c(M), \lambda \in \Omega(M)$. Also, the algebra homomorphism

$$(\tau_M)_\#: \Omega_c(M) \rightarrow \Omega(M)$$

is induced by the inclusion map $\tau_M: G_c(M) \rightarrow G(M)$. The above module structures can be converted to ordinary multiplication by this homomorphism (Haller and Rybicki, 1999).

2. Preliminaries and Auxiliary Results

Let $\Omega: \mathbb{R} \times M \rightarrow N$ be a smooth map. Two smooth maps $f, g: M \rightarrow N$ are said to be homotopic (Eilenberg and Maclane, 1950) if $\Omega(0, x) = f(x)$ and $\Omega(1, x) = g(x)$. We can define a linear map $h: G(N) \rightarrow G(M)$ homogeneous of degree -1 for such a homotopy Ω by

$$h = I_0^1 \circ i(T) \circ \Omega^*$$

Consider the spaces $\Omega^k(M)$ having finite dimension, then the k th Betti number of M is defined by $b_k = \dim \Omega^k(M)$ and the Poincaré polynomial of M is defined by

$$p_M(t) = \sum_{k=0}^n b_k t^k.$$

If M consists of a single point, then $\Omega^k(M) = 0$ ($k \geq 1$) and $\Omega^0(M) = \mathbb{R}$.

The Euler-Poincaré characteristic of M is defined by the alternating sum $\zeta_M = \sum_{k=0}^n (-1)^k b_k = p_M(-1)$.

Now, we discuss the axioms for de Rham cohomology. The axioms for de Rham cohomology are given below:

- (a) $\Omega(\text{point}) = \mathbb{R}$
- (b) If M is the disjoint union of open submanifolds M_α , then

$$\Omega(M) \cong \prod_\alpha \Omega(M_\alpha) \text{ (disjoint union)}$$

- (c) If $f \sim g: M \rightarrow N$, then $f^\# = g^\#$ (homotopy axiom)
- (d) If $M = U \cup V$ (U, V are open), there is an exact triangle (Mayer-Vietoris)

$$\begin{array}{ccc}
 \Omega(M) & \xrightarrow{\quad} & \Omega(U) \oplus \Omega(V) \\
 & \searrow & \swarrow \\
 & & \Omega(U \cap V)
 \end{array}$$

Consider a manifold M which is the disjoint union $M = \cup_\nu M_\nu$ of open submanifolds M_ν . A

homomorphism $h_v^*: G(M) \rightarrow G(M_v)$ is induced by the inclusion map $h_v^*: M_v \rightarrow M$. We obtain a homomorphism $h^*: G(M) \rightarrow \prod_v G(M_v)$ given by $(h^*\Phi)_v = h_v^*$, where $\Phi \in G(M)$ and $\prod_v G(M_v)$ is the direct product of the algebras $G(M_v)$.

If δ_v denotes the exterior derivative in $\Omega(M_v)$, then $\prod_v \Omega(M_v)$ is given by the differential operator $\prod_v \Omega(M_v)$. As a result, h^* is an isomorphism of graded differential algebras $\Omega(M_v)$ and h^* induces the following isomorphism

$$h^*: \Omega(M) \xrightarrow{\cong} \prod_v \Omega(M_v)$$

given by

$$(h^*\gamma)_v = h_v^*(\gamma), \quad \gamma \in \Omega(M).$$

Consider a manifold M and two open subsets X_1, X_2 such that $X_1 \cup X_2 = M$. Let us consider the following inclusion maps

$$\begin{aligned} u_1: X_1 \cap X_2 &\rightarrow X_1, & u_2: X_1 \cap X_2 &\rightarrow X_2 \\ v_1: X_1 &\rightarrow M, & v_2: X_2 &\rightarrow M. \end{aligned}$$

which induce a sequence of linear mappings

$$0 \longrightarrow \Omega(M) \xrightarrow{\lambda} \Omega(X_1) \oplus \Omega(X_2) \xrightarrow{\mu} \Omega(X_1 \cap X_2) \longrightarrow 0$$

given by

$$\lambda\Phi = (v_1^*\Phi, v_2^*\Phi), \quad \Phi \in \Omega(M)$$

and

$$\mu(\Phi_1, \Phi_2) = u_1^*\Phi_1 - u_2^*\Phi_2, \quad \Phi_i \in \Omega(U_i), \quad i = 1, 2.$$

Let $\delta_1, \delta_2, \delta_{12}$ and δ be the exterior derivatives in $\Omega(X_1), \Omega(X_2), \Omega(X_1 \cap X_2)$ and $\Omega(M)$ respectively, then we have

$$\lambda \circ \delta = (\delta_1 \oplus \delta_2) \circ \alpha \quad \text{and} \quad \mu \circ (\delta_1 \oplus \delta_2) = \delta_{12} \circ \mu.$$

Consequently, the following linear maps are induced by λ and μ :

$$\lambda_{\#}: \Omega(M) \rightarrow \Omega(X_1) \oplus \Omega(X_2), \quad \mu_{\#}: \Omega(X_1) \oplus \Omega(X_2) \rightarrow \Omega(X_1 \cap X_2).$$

Lemma 1. The following sequence of linear mappings is exact

$$0 \longrightarrow \Omega(M) \xrightarrow{\lambda} \Omega(X_1) \oplus \Omega(X_2) \xrightarrow{\mu} \Omega(X_1 \cap X_2) \longrightarrow 0.$$

Proof. We have to consider the following three cases:

- (a) $\ker \mu = \text{Im } \lambda$
- (b) λ is injective
- (c) μ is surjective

(a) Since it is obvious $\mu \circ \lambda = 0$, so $\text{Im } \lambda \subset \ker \mu$. We need only to show that $\ker \mu \subset \text{Im } \lambda$.

Let $(\Phi_1, \Phi_2) \in \ker \mu$. If $x \in X_1 \cap X_2$, then $\Phi_1(x) = \Phi_2(x)$. Consequently, we can find a differential form $\Phi \in \Omega(M)$ which is given by

$$\Phi(x) = \begin{cases} \Phi_1(x), & x \in X_1 \\ \Phi_2(x), & x \in X_2 \end{cases}$$

Since $\lambda\Phi = (\Phi_1, \Phi_2)$, so $\ker \mu \subset \text{Im } \lambda$. Therefore, $\ker \mu = \text{Im } \lambda$.

(b) Let $x \in X_1 \cup X_2 = M$. If $\lambda\Phi = 0$, then $\Phi(x) = 0$ for $x \in X_1 \cup X_2 = M$.

(c) Consider the covering X_1, X_2 of M . Let x_1, x_2 be subordinate to the covering X_1, X_2 . Thus, $\{x_1, x_2\}$ is a partition of unity for M . Then, $\text{carr } v_1^*x_2, \text{ carr } v_2^*x_1 \subset X_1 \cup X_2$.

For $\Phi \in \Omega(X_1 \cap X_2)$, we define

$$\Phi_1 = v_1^*x_2 \cdot \Phi \in \Omega(X_1), \quad \Phi_2 = v_2^*x_1 \cdot \Phi \in \Omega(X_2).$$

Consequently, we have $\Phi = \mu(\Phi_1, -\Phi_2)$. □

Consider a compact oriented n -manifold M . Then, we have

$$\Omega_c(M) = \Omega(M) \text{ and } i_M : \Omega(M) \xrightarrow{\cong} \Omega(M)^*.$$

Therefore, the bilinear map $\mathcal{P}_M^k : \Omega^k(M) \times \Omega^{n-k}(M) \rightarrow \mathbb{R}$ represents the Poincaré scalar product.

Theorem 1. If M is any compact manifold, then the dimension of $\Omega(M)$ is finite.

Proof. First we assume that the compact manifold M is orientable. Then the Poincaré scalar product is given by the bilinear map $\mathcal{P}_M^k : \Omega^k(M) \times \Omega^{n-k}(M) \rightarrow \mathbb{R}$ and \mathcal{P}_M^k induces the following two linear isomorphisms

$$\Omega^k(M) \xrightarrow{\cong} \Omega^{n-k}(M)^*$$

and

$$\Omega^{n-k}(M) \xrightarrow{\cong} \Omega^k(M)^*.$$

Now, from the related results of elementary linear algebra we can observe that each $\Omega^k(M)$ has finite dimension; hence the theorem is proved in this case.

Again, we assume that the compact manifold M is nonorientable. In this case, the double cover \tilde{M} is orientable and compact. Consequently, we have

$$\dim \Omega(M) = \dim \Omega_+(\tilde{M}) \leq \dim \Omega(\tilde{M}) < \infty.$$

Thus the dimension of $\Omega(M)$ is finite. □

Lemma 2. $\int_M^\# : \Omega_c^n(M) \rightarrow \mathbb{R}$ is a linear isomorphism if M is a connected oriented n -manifold.

Proof. Let $\Omega(M)$ be the cohomology of an oriented manifold M and $\Omega_c(M)$ be the cohomology of M with compact support. Then the map

$$i_M : \Omega(M) \rightarrow \Omega_c(M)^*$$

is a linear isomorphism. Also, we have

$$\dim \Omega_c^n(M) = \dim \Omega^0(M) = 1.$$

Moreover, $\int_M^\#$ is surjective. Therefore, $\int_M^\# : \Omega_c^n(M) \rightarrow \mathbb{R}$ is a linear isomorphism if M is a connected oriented n -manifold. □

Consider an oriented n -manifold M . The linear map $\int_M : G_c^n(M) \rightarrow \mathbb{R}$ satisfies $\int_M \circ \delta = 0$ and it is surjective map. The linear map $\int_M^\# : \Omega_c^n(M) \rightarrow \mathbb{R}$ is induced by $\int_M : G_c^n(M) \rightarrow \mathbb{R}$ and this map is also surjective. Let $\lambda \in \Omega^k(M)$ and $\mu \in \Omega_c^{n-k}(M)$. The Pioncaré scalar product

$$\mathcal{P}_M^k : \Omega^k(M) \times \Omega_c^{n-k}(M) \rightarrow \mathbb{R}$$

can be expressed as the following bilinear map $\mathcal{P}_M^k(\lambda, \mu) = \int_M^\# \lambda * \mu$.

Lemma 3. Let M, N be two manifolds, then the following diagram commutes.

$$\begin{array}{ccc}
 \Omega(M) & \xleftarrow{\psi^\#} & \Omega(N) \\
 \downarrow i_M & & \downarrow i_N \\
 \Omega_c(M)^* & \xleftarrow{(\psi_c)_\#} & \Omega_c(N)^*
 \end{array}$$

Proof. If $\lambda \in \Omega^k(N)$, $\mu \in \Omega_c^{n-k}$, $\zeta \in G^k(N)$, $\xi \in G_c^{n-k}(M)$, then λ and μ are represented by ζ and ξ respectively. Consequently, $(\psi_c)_\# \mu \in \Omega_c^{n-k}(N)$ is represented by

$$(\psi_c)_* \xi \text{ and } \psi^*(\zeta \wedge ((\psi_c)_* \xi)) = \psi^* \zeta \wedge \xi.$$

Since the Pioncaré scalar product $\mathcal{P}_M^k : \Omega^k(M) \times \Omega_c^{n-k}(M) \rightarrow \mathbb{R}$ is the bilinear map given by

$$\mathcal{P}_M^k(\lambda, \mu) = \int_M^\# \lambda * \mu,$$

thus, $\mathcal{P}_M^k(\psi^\# \lambda, \mu) = \int_M^\# (\psi^\# \lambda) * \mu$ and $\mathcal{P}_N^k(\lambda, (\psi_c)_\# \mu) = \int_M^\# \lambda * (\psi_c)_\# \mu$. Hence we have

$$\mathcal{P}_M^k(\psi^\# \lambda, \mu) = \int_M^\# (\psi^\# \lambda) * \mu = \int_M \psi^* \zeta \wedge \xi = \int_N \zeta \wedge (\psi_c)_* \xi = \int_M^\# \lambda * (\psi_c)_\# \mu = \mathcal{P}_N^k(\lambda, (\psi_c)_\# \mu)$$

Since $\mathcal{P}_M^k(\psi^\# \lambda, \mu) = \mathcal{P}_N^k(\lambda, (\psi_c)_\# \mu)$, we can conclude that the diagram commutes. Hence the proposition is proved. \square

3. Main Results

Theorem 2. For $n \geq 1$, $\Omega(S^n)$ is determined by $\Omega^0(S^n) \cong \Omega^n(S^n) \cong \mathbb{R}$ and $\Omega^k(S^n) = 0$ ($1 \leq k \leq n - 1$).

Proof. First we consider an $(n + 1)$ -dimensional Euclidean space E^{n+1} . Suppose S^n is embedded in E^{n+1} . We know that S^n is connected, thus $\Omega^0(S^n) = \mathbb{R}$. Now let $s \in S^n$ and $\xi \in (0, 1)$ where ξ is fixed. Again, we consider open sets $X_1, X_2 \subset S^n$ defined by

$$X_1 = \{x \in S^n : \langle x, s \rangle > -\xi\}, \quad X_2 = \{x \in S^n : \langle x, s \rangle < \xi\}.$$

As a result, $S^n = X_1 \cup X_2$ and we have the following exact Mayer-Vietoris sequence

$$\dots \rightarrow \Omega^k(S^n) \rightarrow \Omega^k(X_1) \oplus \Omega^k(X_2) \rightarrow \Omega^k(X_1 \cap X_2) \rightarrow \Omega^{k+1}(S^n) \rightarrow \dots$$

It is clear that S^{n-1} is contained in $X_1 \cap X_2$. We observe that X_1 and X_2 are contractible. Consequently, the following exact sequence can be considered as the Mayer-Vietoris sequence

$$\dots \rightarrow \Omega^k(S^n) \rightarrow \Omega^k(\text{point}) \oplus \Omega^k(\text{point}) \rightarrow \Omega^k(S^{n-1}) \rightarrow \Omega^{k+1}(S^n) \rightarrow \dots$$

The above sequence can be split into the following two sequences

$$0 \rightarrow \Omega^0(S^n) \rightarrow \Omega^0(\text{point}) \oplus \Omega^0(\text{point}) \rightarrow \Omega^0(S^{n-1}) \rightarrow \Omega^1(S^n) \rightarrow 0$$

and

$$0 \longrightarrow \Omega^k(S^{n-1}) \xrightarrow{\cong} \Omega^{k+1}(S^n) \longrightarrow 0, \quad k \geq 1.$$

These sequences are exact and from the first sequence we have

$$0 = \dim \Omega^1(S^n) - \dim \Omega^0(S^{n-1}) + 2 \dim \Omega^0(\text{point}) - \dim \Omega^0(S^n).$$

For $n \geq 2$, we observe that S^{n-1} is connected and S^0 consists of two points. Thus we can conclude from the above equation

$$\Omega^1(S^n) \cong \begin{cases} \mathbb{R}, & n = 1 \\ 0, & n > 1 \end{cases}.$$

Since $0 \longrightarrow \Omega^k(S^{n-1}) \xrightarrow{\cong} \Omega^{k+1}(S^n) \longrightarrow 0$ for $k \geq 1$, we have

$$\Omega^k(S^n) \cong \Omega^1(S^{n-k+1}) \quad (1 \leq k \leq n).$$

Therefore, $\Omega^0(S^n) \cong \Omega^n(S^n) \cong \mathbb{R}$ and $\Omega^k(S^n) = 0$. Hence, the proposition is proved. \square

Corollary 1. Consider a connected n -manifold M . Then $\Omega^n(M) \cong \mathbb{R}$ when M is compact and orientable. Otherwise, $\Omega^n(M) = 0$.

Proof. First we assume that M is compact. Then, there are two cases:

- (i) M is orientable
- (ii) M is nonorientable.

If we consider M to be orientable, then from the consequence of Lemma 2 we can deduce that $\Omega^n(M) \cong \mathbb{R}$. If M is nonorientable, then $\Omega^n(M) = 0$.

Next we assume that M is not compact. Then, there are again two cases:

- (i) M is orientable
- (ii) M is nonorientable.

If the manifold M is orientable, then we have $\Omega^n(M) \cong \Omega_c^0(M)^* = 0$.

If the manifold M is nonorientable, then the double cover \tilde{M} must be orientable, connected and noncompact. Consequently, we have

$$\Omega^n(M) \cong \Omega_+^n(\tilde{M}) \subset \Omega^n(\tilde{M}) = 0.$$

Thus, $\Omega^n(M) \cong \mathbb{R}$ when M is compact and orientable, otherwise, $\Omega^n(M) = 0$. □

Corollary 2. $\Omega_c^k(\mathbb{R}^n) = \begin{cases} 0 & \text{when } k < n \\ \mathbb{R} & \text{when } k = n \end{cases}$ gives the cohomology of \mathbb{R}^n with compact supports.

Proof. The case $n = 0$ is trivial. Assume that S^n is the one-point compactification of \mathbb{R}^n for $n > 0$. Let $s \in S^n$ be the compactifying point, thus we can write $\mathbb{R}^n = S^n - \{s\}$.

The differential forms on S^n are zero in a neighbourhood of s and the ideal of differential forms on S^n is denoted by τ_s . It is clear that $\tau_s = G_c(\mathbb{R}^n)$. Consequently, the following sequence is exact

$$0 \rightarrow \tau_s \rightarrow G(S^n) \rightarrow G_s(S^n) \rightarrow 0.$$

In cohomology, we can derive a long exact sequence from the above short exact sequence. As $\Omega(G_b(S^n)) = \Omega(\text{point})$, we can split this long sequence into the following two exact sequences

$$0 \rightarrow \Omega_c^0(\mathbb{R}^n) \rightarrow \Omega^0(S^n) \rightarrow \mathbb{R} \rightarrow \Omega_c^1(\mathbb{R}^n) \rightarrow \Omega^1(S^n) \rightarrow 0$$

and

$$0 \longrightarrow \Omega_c^k(\mathbb{R}^n) \xrightarrow{\cong} \Omega^k(S^n) \longrightarrow 0, \quad k \geq 2.$$

As $\Omega^0(S^n) = \mathbb{R}$ and $\Omega_c^0(\mathbb{R}^n) = 0$, thus the following exact sequence can be derived from the first sequence

$$0 \longrightarrow \Omega_c^1(\mathbb{R}^n) \xrightarrow{\cong} \Omega^1(S^n) \longrightarrow 0.$$

Hence $\Omega_c^k(\mathbb{R}^n) = \begin{cases} 0 & \text{when } k < n \\ \mathbb{R} & \text{when } k = n \end{cases}$ gives the cohomology of \mathbb{R}^n with compact supports. \square

Theorem 3. Let $\Omega(M)$ be the cohomology of an oriented manifold M and $\Omega_c(M)$ be the cohomology of M with compact support. Then the map $i_M: \Omega(M) \rightarrow \Omega_c(M)^*$ is a linear isomorphism.

Proof. To prove the theorem, we have to consider the following three cases:

- (i) $M = \mathbb{R}^n$
- (ii) M is an open subset of \mathbb{R}^n
- (iii) M is arbitrary

(i) We have to show that the map $i: \Omega^0(\mathbb{R}^n) \rightarrow \Omega_c^k(\mathbb{R}^n)^*$ is a linear isomorphism to prove $M = \mathbb{R}^n$ since $\Omega^k(\mathbb{R}^n)$ and $\Omega_c^k(\mathbb{R}^n)$ are given by

$$\Omega^k(\mathbb{R}^n) = \begin{cases} \mathbb{R}, & k = 0 \\ 0, & k \neq 0 \end{cases} \quad \text{and} \quad \Omega_c^k(\mathbb{R}^n) = \begin{cases} \mathbb{R}, & k = n \\ 0, & k \neq n \end{cases}$$

Also, in this case it is sufficient to show that $i \neq 0$ as we have

$$\dim \Omega^0(\mathbb{R}^n) \rightarrow \dim \Omega_c^k(\mathbb{R}^n)^*.$$

Assume that $\varphi \in S(\mathbb{R}^n)$ is a nonnegative function and φ is not identically zero. Consider a positive determinant function Δ in \mathbb{R}^n .

Now, $\int_{\mathbb{R}^n} \varphi \cdot \Delta = \int_{\mathbb{R}^n} \varphi(x) dx^1 \cdots dx^n > 0$ for a suitable basis of \mathbb{R}^n .

Consequently, if μ is a non-zero element in $\Omega_c^n(\mathbb{R}^n)$, μ is represented by $f \cdot \Delta$.

From the definitions we have $\langle i(1), \mu \rangle = \int_{\mathbb{R}^n} 1 \wedge (\varphi \cdot \Delta) = \int_{\mathbb{R}^n} \varphi \cdot \Delta \neq 0$.

Therefore, $\langle i(1), \mu \rangle \neq 0$ implies that $i(1) \neq 0$ and so $i \neq 0$.

(ii) Assume that $\{b_1, \dots, b_n\}$ is a basis of \mathbb{R}^n . Then, for $v \in \mathbb{R}^n$, we have $v = \sum_{k=1}^n v^k b_k$.

Then an i -basis for the topology of \mathbb{R}^n can be represented by the open subsets of the form

$$B = \{x \in \mathbb{R}^n: a^k < x^k < b^k, k = 1, \dots, n\}.$$

By the definition of diffeomorphism, B is diffeomorphic to \mathbb{R}^n . Therefore, with the help of Case (i) and the result of Lemma 3 we conclude that i_B is an isomorphism for each such B . As a result, for every open subset M of \mathbb{R}^n we have $i_M: \Omega(M) \rightarrow \Omega_c(M)^*$ which is an isomorphism.

(iii) Let us assume that every open subset of M is diffeomorphic to open subset of \mathbb{R}^n and \mathcal{B} is the collection of such open subsets of M . Consequently, it is obvious that for the topology of M this collection of open subsets \mathcal{B} is an i -basis. With the help of the results derived in Case (ii) and Lemma 3, we can conclude that i_B is an isomorphism for every $B \in \mathcal{B}$. Therefore, for

every open subset $X \subset M$ we can find an i_X which is an isomorphism. Thus, the map $i_M: \Omega(M) \xrightarrow{\cong} \Omega_c(M)^*$ is a linear isomorphism.

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