

# Cost Analysis of a Compound System with the Concept of Waiting

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**Abstract-** In this research paper the authors, Suppose a compound system having two sub-systems namely 'P' and 'Q' connected in chain. Sub-system 'P' consists of  $n$  unlike units in chain, while sub-system 'Q' consists of  $m$  like units chain. The compound system is subjected to minor failure, major failure critical human failure and common cause failure.

**Keywords** – Asymptotic behavior, Availability of function, Abel lemma, Cost function and Supplementary variable technique.

## 1. INTRODUCTION

A compound system having two sub-systems namely 'P' and 'Q' connected in chain. Sub-system 'P' consists of  $n$  unlike units connected in chain, while sub-system 'Q' consists of  $m$  like units in chain. The compound system is subjected to minor failure, major failure, critical human failure and common cause failure. Failures follow exponential time distribution where as repairs follow general time distribution. The system is repaired immediately when it is in the state  $A_1 \dots A_6 \dots A_7 \dots A_8$ . However in the states  $A_2$  &  $A_4$  the system has to wait with a constant rate  $u_i$  till the adequate facilities are made available to repair the system. System goes to reduced efficiency state if  $i^{th}$  unit of sub-system 'P' is failed while system goes to complete breakdown if more than one unit of subsystem 'Q' failed or  $j^{th}$  unit of sub-system 'Q' failed.

Earlier research [1, 2, 3, 4], different techniques have been applied to evaluate the reliability of distribution system, including distributed generation such as an analytical technique using the load duration curve, distributed processing technique, Characteristic function based approach for computing the probability distributors of reliability indices, probabilistic method for assessing the reliability and quantity of power supply to a customer, composite load point model, practical reliability assessment algorithm, validation method and impact of substation on distribution reliability respectively.

## 2. ASSUMPTION

1. Initially at time  $t = 0$ , the system is in good state.
2. The system consists of two sub-systems namely; P and Q connecting in chain.
3. Sub-system P consists of  $n$  –unlike units in chain. While subsystem 'Q' consists of  $m$  like in chain.
4. The system has three states as good, degraded and failed.
5. Each unit of the system has a constant failure rate.
6. All the failures are statistically independent.
7. Common cause failure and human error rates are constant.
8. Repair is giving only when the system is in either degraded or in failed state.
9. After repair, the system works like new one and never damages anything.

## 3. Notations:

The following notations have been used in this paper:

$\bar{f}(s)$	Laplace transform of function $f(t)$
$\int$	Integration in the range 0 to $\infty$
$\alpha_1 / \alpha_2 / \alpha_3 / \alpha_B$	Constant failure rates of state $A_0$ to $A_1 / A_0$ to $A_2 / A_0$ to $A_4 / A_0$ to $A_8$
$\alpha_C / \alpha_{C_i} / \alpha_h / \alpha_{17}$	Constant failure rate of state $A_0$ to $A_6 / A_1$ to $A_6 / A_0$ to $A_7 / A_1$ to $A_7$

$\beta_i(x) \Delta / \eta_i(y) \Delta$	The first order probability that the system will be repaired in the time interval $(x, x + \Delta) / (y, y + \Delta)$ conditioned that it was not repaired up the time $x / y$
$\lambda_j(u)$	General repair rates for sub-system 'B' from state $A_8$ to $A_0$
$r(w) / \mu(z)$	General repair rates for common cause failure and critical human error
$i, j$	Subscript denotes the serial number of $P$ -unit and $Q$ -unit $[i = 1, 2 \dots n], [j = 1, 2 \dots m]$
$P_0(t)$	The probability that at time 't' the system is in good state
$P_1(x, t) \Delta$	The probability that at time 't' the system is in degraded state due to the failure of $i^{th}$ unit of sub-system 'P'. The elapsed repair time lies in the interval $(x, x + \Delta)$
$P_2(t)$	The probability that at time 't' the system is in failed state $A_2$ .
$P_3(y, t) \Delta$	The probability that at time 't' the system is in failed state $A_3$ and the elapsed repair time lies in the interval $(y, y + \Delta)$
$P_4(t)$	The probability that at time 't' the system is in failed state $A_4$
$P_5(y, t) \Delta$	The probability that at time 't' the system is in failed state $A_5$ and the elapsed repair time lies in the interval $(y, y + \Delta)$

**Transition State Diagram**

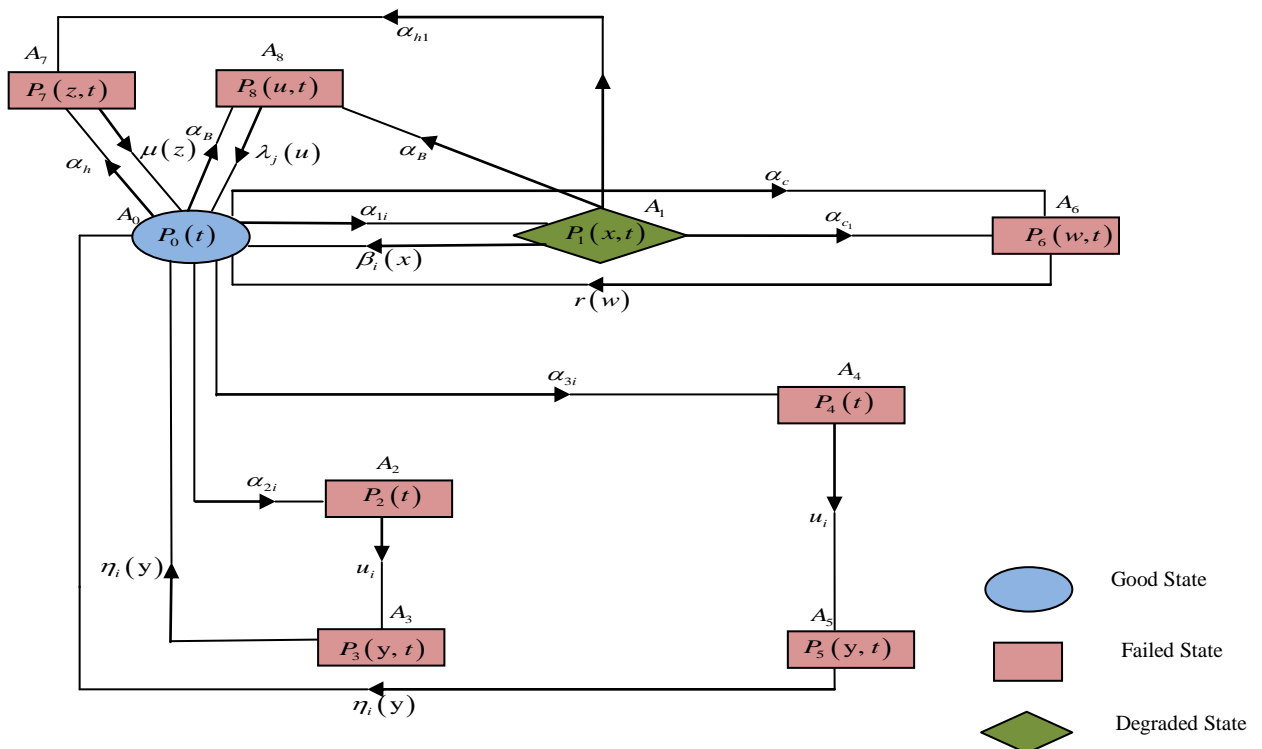


Figure 1 represents the state transition diagram of the system.

#### 4. FORMULATION OF THE MATHEMATICAL MODEL

The analysis crucially depends on the method of supplementary variables technique and the supplementary variable  $x$  denotes the time that a unit has been elapsed undergoing repair. Viewing the nature of the problem, we obtain the following set of difference-differential equations:

$$\begin{aligned} \left[ \frac{\partial}{\partial t} + \alpha_1 + \alpha_2 + \alpha_3 + \alpha_c + \alpha_h + \alpha_B \right] P_0(t) &= \sum_i \int P_1(x, t) \beta_i(x) dx + \sum_i \int P_3(y, t) \eta_i(y) dy \\ &+ \sum_i \int P_5(y, t) \eta_i(y) dy + \int P_6(w, t) r(w) dw + \int P_7(z, t) \mu(z) dz \\ &+ \sum_j \int P_8(u, t) \psi_j(u) du \end{aligned} \quad \dots (1.1)$$

$$\left[ \frac{\partial}{\partial x} + \frac{\partial}{\partial t} + \alpha_{c_1} + \alpha_{i\eta} + \alpha_B + \beta_i(x) \right] P_1(x, t) = 0 \quad \dots (1.2)$$

$$\left[ \frac{\partial}{\partial t} + u_i \right] P_2(t) = \alpha_{2i} P_0(t) \quad \dots (1.3)$$

$$\left[ \frac{\partial}{\partial y} + \frac{\partial}{\partial t} + \eta_i(y) \right] P_3(y, t) = 0 \quad \dots (1.4)$$

$$\left[ \frac{\partial}{\partial t} + u_i \right] P_4(t) = \alpha_{3i} P_0(t) \quad \dots (1.5)$$

##### 4.1 Boundary Conditions

$$P_1(0, t) = \alpha_{i_1} P_0(t) \quad \dots (1.6)$$

$$P_3(0, t) = u_i P_2(t) \quad \dots (1.7)$$

$$P_5(0, t) = u_i P_4(t) \quad \dots (1.8)$$

$$P_6(0, t) = \alpha_c P_0(t) + \alpha_{c_1} P_1(t) \quad \dots (1.9)$$

$$P_7(0, t) = \alpha_h P_0(t) + \alpha_{h_1} P_1(t) \quad \dots (2.0)$$

$$P_8(0, t) = \alpha_j [P_0(t) + P_1(t)] \quad \dots (2.1)$$

##### 4.2 Initial Conditions:

$$P_0(0) = 1, \text{ otherwise zero} \quad \dots (2.2)$$

#### 5. SOLUTION OF THE MODEL

Taking Laplace transforms of equations (1.1) through (2.1) and using initial condition (2.2) one may obtain

$$\begin{aligned} [s + \alpha_1 + \alpha_2 + \alpha_3 + \alpha_c + \alpha_h + \alpha_B] \bar{P}_0(s) &= 1 + \sum_i \int \bar{P}_1(x, s) \beta_i(x) dx + \sum_i \int \bar{P}_3(y, s) \eta_i(y) dy \\ &+ \sum_i \int \bar{P}_5(y, s) \eta_i(y) dy + \int \bar{P}_6(w, s) r(w) dw + \int \bar{P}_7(z, s) \mu(z) dz \\ &+ \sum_j \int \bar{P}_8(u, s) \psi_j(u) du \end{aligned} \quad \dots (2.3)$$

$$\bar{P}_1(0, s) = \alpha_{i_1} \bar{P}_0(s) \quad \dots (2.4)$$

$$\bar{P}_3(0, s) = \mu_i \bar{P}_2(s) \quad \dots (2.5)$$

$$\bar{P}_5(0, s) = \mu_i \bar{P}_4(s) \quad \dots (2.6)$$

After solving the above equations, we get finally

$$\bar{P}_0(s) = \frac{1}{A(s)} \quad \dots (2.7) \quad \bar{P}_1(s) = \frac{\alpha_{i_1}}{A(s)} D_{\beta_i}(s + \alpha_{h_1} + \alpha_{c_1} + \alpha_B) \quad \dots (2.8)$$

$$\bar{P}_2(s) = \frac{\alpha_{2i}}{(s + u_i) A(s)} \quad \dots (2.9) \quad \bar{P}_3(s) = \frac{u_i \alpha_{2i}}{(s + u_i) A(s)} D_{\eta_i}(s) \quad \dots (3.0)$$

$$\bar{P}_4(s) = \frac{\alpha_{3i}}{(s + u_i)A(s)} \quad \dots (3.1) \quad \bar{P}_5(s) = \frac{u_i \alpha_{3i}}{(s + u_i)A(s)} D_{\eta_i}(s) \quad \dots (3.2)$$

Where,

$$A(s) = s + \alpha_1 + \alpha_2 + \alpha_3 + \alpha_c + \alpha_h + \alpha_B - \sum_i \alpha_{1i} \bar{S}_{\beta_i}(s + \alpha_{\eta_i} + \alpha_{c_1} + \alpha_B) - \sum_i \frac{u_i}{s + u_i} (\alpha_{2i} + \alpha_{3i}) \bar{S}_{\eta_i}(s) \\
 - \left[ \alpha_c + \alpha_{c_1} \sum_i \alpha_{1i} D_{\beta_i}(s + \alpha_{\eta_i} + \alpha_{c_1} + \alpha_B) \right] \bar{S}_r(s) - \left[ \alpha_h + \alpha_{\eta_1} \sum_i \alpha_{1i} D_{\beta_i}(s + \alpha_{\eta_i} + \alpha_{c_1} + \alpha_B) \right] \bar{S}_\mu(s) \\
 - \left[ 1 + \sum_i \alpha_{1i} D_{\beta_i}(s + \alpha_{\eta_i} + \alpha_{c_1} + \alpha_B) \right] \sum_j \alpha_j \bar{S}_{\psi_j}(s) \quad \dots (3.3)$$

## 6. ERGODIC BEHAVIOUR OF THE SYSTEM

Using Abel's Lemma  $\lim_{s \rightarrow 0} s \bar{F}(s) = \lim_{t \rightarrow \infty} F(t) = F$  (say), provided the limit on the R.H.S. exists, the time independent probabilities are obtained as follows by making use above lemma in the relations (2.3) through (3.2), then we get the following equations,

$$P_0 = \frac{1}{A'(0)} \quad \dots (3.4) \quad P_1 = \frac{\alpha_{1i}}{A'(0)} D_{\beta_i}(\alpha_{\eta_i} + \alpha_{c_1} + \alpha_B) \quad \dots (3.5)$$

$$P_2 = \frac{\alpha_{2i}}{u_i A'(0)} \quad \dots (3.6) \quad P_3 = \frac{\alpha_{2i}}{A'(0)} M_{\eta_i} \quad \dots (3.7)$$

$$P_4 = \frac{\alpha_{3i}}{u_i A'(0)} \quad \dots (3.8) \quad P_5 = \frac{\alpha_{3i}}{A'(0)} M_{\eta_i} \quad \dots (3.9)$$

$$P_6 = \frac{1}{A'(0)} \left[ \alpha_c + \alpha_{c_1} \sum_i \alpha_{1i} D_{\beta_i}(\alpha_{\eta_i} + \alpha_{c_1} + \alpha_B) \right] M_r \quad \dots (3.10)$$

$$P_7 = \frac{1}{A'(0)} \left[ \alpha_h + \alpha_{\eta_1} \sum_i \alpha_{1i} D_{\beta_i}(\alpha_{\eta_i} + \alpha_{c_1} + \alpha_B) \right] M_\mu \quad \dots (3.11)$$

$$P_8 = \frac{\alpha_j}{A'(0)} \left[ 1 + \sum_i \alpha_{1i} D_{\beta_i}(\alpha_{\eta_i} + \alpha_{c_1} + \alpha_B) \right] M_{\psi_j} \quad \dots (3.12)$$

Where,  $A'(0) = \left[ \frac{d}{ds} A(s) \right]_{s=0}$  and  $M_k = \text{Mean time to repair } k^{\text{th}} \text{ unit} = -\bar{S}'_k(0)$

## 7. EVALUATION OF UP AND DOWN STATE PROBABILITIES

We have,

$$\bar{P}_{up} = \bar{P}_0(s) + \bar{P}_1(s) = \frac{1}{s + \alpha_1 + \alpha_2 + \alpha_3 + \alpha_c + \alpha_h + \alpha_B} \left[ 1 + \frac{\alpha_1}{s + \alpha_{\eta_1} + \alpha_{c_1} + \alpha_B} \right]$$

Taking inverse Laplace transform on both sides, we get

$$P_{up}(t) = \left[ \frac{\alpha_{c_1} + \alpha_{\eta_1} - \alpha_2 - \alpha_3 - \alpha_c - \alpha_h}{\alpha_{c_1} + \alpha_{\eta_1} - \alpha_1 - \alpha_2 - \alpha_3 - \alpha_c - \alpha_h} \right] \exp[-(\alpha_1 + \alpha_2 + \alpha_3 + \alpha_c + \alpha_h + \alpha_B)t] \\
 + \frac{\alpha_1}{\alpha_1 + \alpha_2 + \alpha_3 + \alpha_c + \alpha_h - \alpha_{\eta_1} - \alpha_{c_1}} \exp[-(\alpha_{c_1} + \alpha_{\eta_1} + \alpha_B)t] \quad \dots (3.13)$$

$$\text{and, } P_{down}(t) = 1 - P_{up}(t) \quad \dots (3.14)$$

## 8. COST PROFIT ANALYSIS FUNCTION

The cost function for the considered system is defined as

$$G(t) = C_1 \int_0^t P_{up}(t) dt - C_2 t \quad \dots (3.15)$$

Where,

$G(t)$  = Expected cost for total time,  $C_1$  = Revenue cost per unit up time and  $C_2$  = Service cost per unit time

Putting the value of  $P_{up}(t)$  in equation (3.15), we get

$$G(t) = C_1 \left[ \frac{\alpha_m + \alpha_{c_1} - \alpha_2 - \alpha_3 - \alpha_c - \alpha_h}{\alpha_m + \alpha_{c_1} - \alpha_1 - \alpha_2 - \alpha_3 - \alpha_c - \alpha_h} \right] \times \left[ \frac{1 - \exp\{-(\alpha_1 + \alpha_2 + \alpha_3 + \alpha_h + \alpha_c + \alpha_B)t\}}{\alpha_1 + \alpha_2 + \alpha_3 + \alpha_h + \alpha_c + \alpha_B} \right] \\ + \frac{C_1 \alpha_1}{\alpha_1 + \alpha_2 + \alpha_3 + \alpha_h + \alpha_c - \alpha_{c_1} - \alpha_m} \times \left[ \frac{1 - \exp\{-(\alpha_m + \alpha_{c_1} + \alpha_B)t\}}{\alpha_m + \alpha_{c_1} + \alpha_B} \right] - C_2 t \quad \dots (3.16)$$

## 9. NUMERICAL COMPUTATION

Suppose the parameters as

(i).  $\alpha_1 = \alpha_h = 0.02$ ,  $\alpha_2 = \alpha_B = 0.03$ ,  $\alpha_3 = 0.04$ ,  $\alpha_c = \alpha_{\eta_i} = \alpha_{\eta_7} = 0.05$ ,  $\alpha_{c_1} = 0.03$  and  $C_1 = \text{Rs. } 3.00$ ,  
 $C_2 = \text{Rs. } 2.00$ , we get

(ii).  $\alpha_1 = \alpha_h = 0.01$ ,  $\alpha_2 = \alpha_B = 0.02$ ,  $\alpha_3 = 0.03$ ,  $\alpha_c = \alpha_{\eta_i} = \alpha_{\eta_7} = 0.04$ ,  $\alpha_{c_1} = 0.02$  and  $C_1 = \text{Rs. } 2.00$ ,  
 $C_2 = \text{Rs. } 1.00$ , we get

### 1. Availability of system:

Putting the parameters (i) in equation (3.13), then we get the expression,

$$P_{up}(t) = 0.75 \exp(-0.19t) + 0.25 \exp(-0.11t)$$

And putting the parameters (ii) in equation (3.13), then we get the expression,

$$P_{up}(t) = 0.08 \exp(-0.13t) + 0.2 \exp(-0.08t)$$

### 2. Cost function of system:

Putting the parameters (ii) in equation (3.16), then we get the expression,

$$G(t) = 1.6 \left[ \frac{1 - e(-0.13t)}{0.13} \right] + 0.4 \left[ \frac{1 - e(-0.08t)}{0.08} \right] - t$$

## 10. EXPERIMENTAL RESULT IN TABULATION AND FIGURE

### 10.1 Table for $P_{up}(t)$ and Curve:

Table-1

S.No.	t	Pup(t)	Pup(t)
1	0	1	1
2	1	0.8441779	0.8870996
3	2	0.7135258	0.78727
4	3	0.603875	0.6989711
5	4	0.5117589	0.6208462
6	5	0.4342932	0.5517006
7	6	0.3690771	0.4904815
8	7	0.3141112	0.4362612
9	8	0.2677296	0.3882222
10	9	0.2285435	0.345644
11	10	0.1953942	0.3078912
12	11	0.1673147	0.2744037

13	12	0.143497	0.2446874
14	13	0.1232659	0.2183066
15	14	0.1060564	0.1948766
16	15	0.0913957	0.1740581

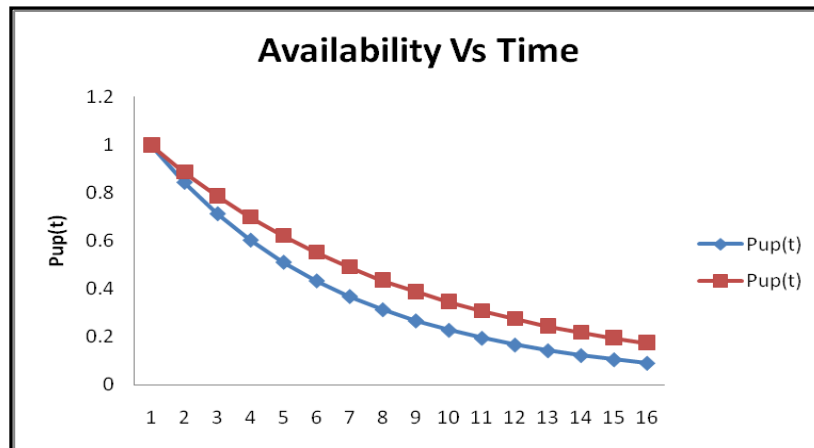
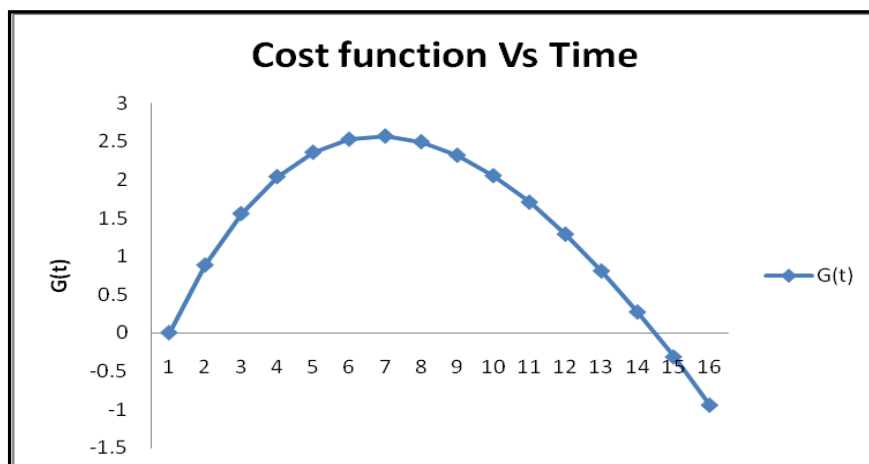


Figure 2 represents the Availability of the system with respect to time.

10.2. Table for  $G(t)$  and Curve:

Table-2

S.No.	t	G(t)
1	0	0
2	1	0.884782195
3	2	1.557107691
4	3	2.041545316
5	4	2.359771147
6	5	2.530913287
7	6	2.57185521
8	7	2.497502693
9	8	2.321018717
10	9	2.054030212
11	10	1.706810034
12	11	1.288437168
13	12	0.806937771
14	13	0.269409372
15	14	-0.317869754
16	15	-0.949344248



*Figure 3 represents the Cost function of the system with respect to time.*

## 11. Conclusion

Table 1 and Figure 2 provide information how availability of the complex engineering repairable system change with respect to time when failure rate increases, then availability of system is decreases.

Table 2 exhibits expected cost function with respect to time and their corresponding Figure 3 shows that when time increase then cost function increase and after some time when time increase, cost function continuously decrease.

The further research area is widely open, where one may think of the application of other members of copula family, MTTF and sensitivity analysis.

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