

# New Multi-Step Runge –Kutta Method For Solving Fuzzy Differential Equations

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#### Abstract

This paper presents solution for the first order fuzzy differential equation by Runge –Kutta method of order two with new parameters and Harmonic mean of  $k_i$ 's which are used in the main formula in order to increase the order of accuracy of the solution. This method is discussed in detail followed by a complete error analysis. The accuracy and efficiency of the proposed method is illustrated by solving a fuzzy initial value problem.

**Keywords:** Fuzzy differential equations, multi-step Runge-Kutta method, higher order derivative approximations, harmonic mean.

### **1. Introduction**

Fuzzy Differential Equation (FDE) models have wide range of applications in many branches of engineering and in the field of medicine. The concept of fuzzy derivative was first introduced by S.L.Chang and L.A.Zadeh [7].D.Dubois and Prade [8] discussed differentiation with fuzzy features.M.L.puri and D.A.Ralesec [18] and R.Goetschel and W.Voxman [10] contributed towards the differential of fuzzy functions. The fuzzy differential equation and initial value problems were extensively studied by O.Kaleva [11,12] and by S.Seikkala [19].Recently many research papers are focused on numerical solution of fuzzy initial value problems (FIVPS).Numerical Solution of fuzzy differential equations has been introduced by M.Ma, M. Friedman, A. Kandel [14] through Euler method and by S.Abbasbandy and T.Allahviranloo [2] by Taylor method.Runge – Kutta methods have also been studied by authors [3,17]. Numerical Solution of fuzzy differential equations by Runge –Kutta method of order two with new parameters has been by V.Nirmala, Saveetha, N and S.Chenthur Pandian[15] and by Runge –Kutta method of order four with new parameters by V.Nirmala and S.Chenthur Pandian [16].

This paper is organised as follows: In section 2, some basic results on fuzzy numbers and definition of fuzzy derivative are given. Section 3 contains fuzzy Cauchy problem whose numerical solution is the main interest of this paper. Second order multi -step Runge –Kutta method with new parameters based on harmonic mean is discussed in section 4. The proposed method is illustrated by a solved numerical example in section 5and the result is compared with Euler's approximation and with the approximation by Runge-Kutta method proposed in [15] and conclusion is in section 6.

#### 2. Preliminaries

Consider the initial value problem

$$y'(t) = f(t, y(t)); t_0 \le t \le b$$
  
 $y(t_0) = y_0$  (2.1)

We assume that

1.f(t, y(t)) is defined and continuous in the strip  $t_0 \le t \le b, -\infty < y < \infty$  with  $t_0$  and b finite. 2. There exists a constant L such that for any 't' in  $[t_0, b]$  and any two numbers y and  $y^*, |f(t, y) - f(t, y^*)| \le L|y - y^*|$ 



These conditions are sufficient to prove that there exists on  $[t_0, b]$ , a unique continuous, differentiable function y(t) satisfying (2.1).

The basis of all Runge-Kutta methods is to express the difference between the value of y at  $t_{n+1}$  and  $t_n$ as  $y_{n+1} - y_n = \sum_{i=0}^m w_i k_i$  (2.2) Where  $w_i$ 's are constant for all i and  $k_i = hf(t_n + a_ih, y_n + \sum_{j=1}^{i-1} c_{ij}k_j)$  (2.3) Most efforts to increase the order of accuracy of the Runge-Kutta methods have been accomplished by increasing the number of Taylor's series terms used and thus the number of functional evaluations required [6]. The method proposed by Goeken .D and Johnson .O[9] introduces new terms involving higher order derivatives of 'f' in the Runge-Kutta  $k_i$  terms (i > 1) to obtain a higher order of accuracy without a corresponding increase in evaluations of'f', but with the addition of evaluations of f'.

The second order Runge-Kutta method for autonomous systems proposed by Goeken.D and Johnson.O [9]:

Consider 
$$y_{n+1} = y_n + b_1 k_1 + b_2 k_2$$
 (2.4)  
Where  $k_1 = hf(y_n)$  (2.5)  
 $k_2 = hf(y_n + a_{21}k_1 + ha_{22}f_y(y_n)k_1)$  (2.6)

New Multi-step Runge- Kutta method with harmonic mean was discussed and used approximate f' in the stage  $k_2$  by Ababneh,O.Y,Ahmad,R.,and Ismail,E.S [1]. In this paper, we use exact f' in stage  $k_2$ . Then, the new multi-step Runge –Kutta method of order two is given by

$$y_{n+1} = y_n + \frac{2k_1k_2}{k_1+k_2}$$
(2.7)  
Where  $k_1 = hf(y_n)$ 
(2.8)  
 $k_2 = hf(y_n + a_{21}k_1 + ha_{22}f_y(y_n)k_1)$ 
(2.9)  
Utilizing the Taylor's series expansion techniques in (2.7), we get the parameter  $a_{21}$  =

Utilizing the Taylor's series expansion techniques in (2.7),we get the parameter  $a_{21} = 1$ and there is no any order condition to choose  $a_{22}$  and hence we take  $a_{22} = 9/10$ Runge-Kutta method of order two is given by:

$$y(t_{n+1}) = y(t_n) + \frac{2k_1k_2}{k_1 + k_2}$$
(2.10)  
Where  $k_1 = hf(y(t_n))$   
 $k_2 = hf(y(t_n) + k_1 + h\frac{9}{10}(f_y(y(t_n))k_1))$   
(2.12)

Theorem 2.1. Let f(t, y) belong to  $C^2[a, b]$  and its partial derivatives be bounded and let us assume that there exist positive constants L, M, such that |f(t, y)| < M,  $\left|\frac{\partial^{i+j}f}{\partial t^i \partial y^j}\right| < \frac{L^{i+j}}{M^{j-1}}$ ,  $i + j \le m$ , then in the Runge –Kutta method of order two ,we have([13]),

$$y(t_{i+1}) - y_{i+1} \cong (63/30)ML^2h^3 + O(h^4)$$

Definition 2.1. A fuzzy number u is a fuzzy subset of R (ie)  $u: R \rightarrow [0,1]$  satisfying the following conditions:

1.*u* is normal (ie)  $\exists x_0 \in R$  with  $u(x_0) = 1$ .

2.u is convex fuzzy set

(ie) 
$$u(tx + (1 - t)y) \ge \min\{u(x), u(y)\}, \forall t \in [0,1], x, y \in R.$$

3.*u* is upper semi continuous on *R*. 4.{ $x \in R, u(x) > 0$ } is compact.

Let *E* be the class of all fuzzy subsets of *R*. Then *E* is called the space of fuzzy numbers [11]. Clearly,  $R \subset E$  and  $R \subset E$  is understood as  $R = \{\aleph_x : \aleph \text{ is usual real number}\}$ . An arbitrary fuzzy number is represented by an ordered pair of functions

 $(\underline{u}(r), \overline{u}(r)), 0 \le r \le 1$  that satisfies the following requirements.

 $1.\underline{u}(r)$  is a bounded left continous non-decreasing function over [0,1], with respect to any 'r'.

2.  $\overline{u}(r)$  is a bounded right continuous non-increasing function over [0,1] with respect to any 'r'.



3. 
$$u(r) \leq \overline{u}(r), 0 \leq r \leq 1$$
.

Then the r-level set is  $[u]_r = \{x \setminus u(x) \ge r\}, 0 < r \le 1$  is a closed and bounded interval, denoted by  $[u]_r = [\underline{u}(r), \overline{u}(r)]$ . And clearly,  $[u]_0 = \{x \setminus u(x) > 0\}$  is compact.

Definition 2.2. A triangular fuzzy number u is a fuzzy set in E that is characterized by an ordered triple  $(u_l, u_c, u_r) \in \mathbb{R}^3$  with  $u_l \leq u_c \leq u_r$  such that  $[u]_0 = [u_l; u_r]$  and  $[u]_1 = \{u_c\}$ .

The membership function of the triangular fuzzy number u is given by

$$u(x) = \begin{cases} \frac{x - u_l}{u_c - u_l}, & u_l \le x \le u_c \\ 1, x = u_c \\ \frac{u_r - x}{u_r - u_c}, & u_c \le x \le u_r \end{cases}$$

We will write (i) u > 0, if  $u_l > 0$ . (ii)  $u \ge 0$ , if  $u_l \ge 0$ . (iii) u < 0, if  $u_c < 0$ . (iv)  $u \le 0$ , if  $u_c \le 0$ .

Let I be a real interval. A mapping  $y: I \to E$  is called a fuzzy process, and its  $\alpha - level$  set is denoted by  $[y(t)]_{\alpha} = \begin{bmatrix} y(t; \alpha), \overline{y}(t; \alpha) \\ f(t; \alpha) \end{bmatrix}, t \in I, 0 < \alpha \leq I$ . The seikkala derivative y'(t) of a fuzzy process is defined by  $[y'(t)]_{\alpha} = \begin{bmatrix} y'(t; \alpha), \overline{y}'(t; \alpha) \\ f(t; \alpha), \overline{y}'(t; \alpha) \end{bmatrix}, t \in I, 0 < \alpha \leq I$ , provided that this equation defines a fuzzy number, as in [19].

Lemma2.1. Let  $u, v \in E$  and s scalar, then for  $r \in (0,1]$ 

$$\begin{split} &[u+v]_r = [\underline{u}(r) + \underline{v}(r), \overline{u}(r) + \overline{v}(r)] \\ &[u-v]_r = [\underline{u}(r) - \overline{v}(r), \overline{u}(r) - \underline{v}(r)] \\ &[u,v]_r = [\min\{\underline{u}(r), \underline{v}(r), \underline{u}(r), \overline{v}(r), \overline{u}(r), \underline{v}(r), \overline{u}(r), \overline{v}(r)\}, \\ &\max\{\underline{u}(r), \underline{v}(r), \underline{u}(r), \overline{v}(r), \overline{u}(r), \underline{v}(r), \overline{u}(r), \overline{v}(r)\}], \end{split}$$

$$[su]_r = s \ [u]_r$$

#### **3. A Fuzzy Cauchy Problem**

Consider the fuzzy initial value problem

$$\begin{cases} y'(t) = f(t, y(t)), t \in I = [0, T] \\ y(0) = y_0. \end{cases}$$
(3.1)

Where f is a continuous mapping from  $R_+ X R$  into R and  $y_0 \in E$  with r-level sets  $[y_0]_r = [\underline{y}(0,r), \overline{y}(0,r)], r \in (0,1].$ 

The extension principle of Zadeh leads to the following definition of f(t, y) when y = y(t) is a fuzzy number,  $f(t, y)(s) = \sup\{y(\tau) \setminus s = f(t, \tau)\}, s \in R$ . It follows that,  $[f(t, y)]_r = [f(t, y; r), \overline{f}(t, y; r)], r \in (0,1]$ , Where  $f(t, y; r) = \min\{f(t, u) \setminus u \in [\underline{y}(r), \overline{y}(r)]\}$ ,  $\overline{f}(t, y; r) = \max\{f(t, u) \setminus u \in [\underline{y}(r), \overline{y}(r)]\}$ .

Theorem3.1. Let f satisfy  $|f(t,v) - f(t,v)| \le g(t, |v - \overline{v}|), t \ge 0, v, \overline{v} \in R$ , (3.2) where  $g: R_+ X R_+ \to R_+$  is a continuous mapping such that  $r \to g(t,r)$  is non decreasing, the initial value problem  $u'(t) = g(t, u(t)), u(0) = u_0$ , (3.3)

has a solution on  $R_+$  for  $u_0 > 0$  and that  $u(t) \equiv 0$  is the only solution of (3.3) for  $u_0 = 0$ . Then the fuzzy initial value problem (3.1) has a unique fuzzy solution.

Proof: see [19].

In this paper we suppose (3.1) satisfies the hypothesis of theorem 3.1, also.

#### 4 .The Second Order Runge -Kutta Method with Harmonic Mean

Let the exact solution 
$$[Y(t)]_r = [\underline{Y}(t;r), \overline{Y}(t;r)]$$
 is approximated by some  $[y(t)]_r = [\underline{y}(t;r), \overline{y}(t;r)]$ .From (2.7) to (2.9), we define  
 $\underline{y}(t_{n+1};r) - \underline{y}(t_n;r) = 2 \frac{\underline{k_1}(t_n, y(t_n;r)) + \underline{k_2}(t_n, y(t_n;r))}{\underline{k_1}(t_n, y(t_n;r)) + \underline{k_2}(t_n, y(t_n;r))}$ 
(4.1)  $\overline{y}(t_{n+1};r) - \overline{y}(t_n;r) = 2 \frac{\overline{k_1}(t_n, y(t_n;r)) + \underline{k_2}(t_n, y(t_n;r))}{\overline{k_1}(t_n, y(t_n;r)) + \overline{k_2}(t_n, y(t_n;r))}$ 
(4.2)  
 $\underline{k_1}(t, y(t;r)) = \min\{h. f(t, u) \setminus u \in [\underline{y}(t, r), \overline{y}(t, r)]\}$ 
(4.3)  
 $\overline{k_1}(t, y(t, r)) = \max\{h. f(t, u) \setminus u \in [\underline{y}(t, r), \overline{y}(t, r)]\}$ 
(4.4)  
 $\underline{k_2}(t, y(t, r)) = \min\{h. f(t, u) \setminus u \in [\underline{z_1}(t, y(t, r)), \overline{z_1}(t, y(t, r))]\}$ 
(4.5)  
 $\overline{k_2}(t, y(t, r)) = \max\{h. f(t, u) \setminus u \in [\underline{z_1}(t, y(t, r)), \overline{z_1}(t, y(t, r))]\}$ 
(4.6)  
Where  
 $\underline{z_1}(t, y(t, r)) = \overline{y}(t, r) + \underline{k_1}(t, y(t, r)) + \frac{9}{10}\overline{a}$   
 $\underline{a} = \min\{h. f_y(t, u). v \setminus u \in [\underline{y}(t, r), \overline{y}(t, r)] \& v \in [\underline{k_1}(t, y(t; r)), \overline{k_1}(t, y(t; r))]\}$ 

Define,

$$F[t, y(t; r)] = 2 \frac{\underline{k_1}(t, y(t; r)) \underline{k_2}(t, y(t; r))}{\underline{k_1}(t, y(t; r)) + \underline{k_2}(t, y(t; r))}$$
(4.7)  

$$C[t, y(t; r)] = 2 \frac{\overline{k_1}(t, y(t; r)) + \underline{k_2}(t, y(t; r))}{\overline{k_2}(t, y(t; r))}$$
(4.8)

 $G[t, y(t; r)] = 2 \frac{n_1(t, y(t; r)) + n_2(t, y(t; r))}{\overline{k_1}(t, y(t; r)) + \overline{k_2}(t, y(t; r))}$ (4.8) The exact and approximate solutions at  $t_n, 0 \le n \le N$  are denoted by  $[Y(t_n)]_r = [\underline{Y}(t_n; r), \overline{Y}(t_n; r)] \text{ and } [y(t_n)]_r = [\underline{y}(t_n; r), \overline{y}(t_n; r)], \text{respectively}$ The solution is calculated by grid points at  $a = t_0 \le t_1 \le t_2 \le \cdots \ldots \ldots \le t_N = b$ and  $h = \frac{(b-a)}{N} = t_{n+1} - t_n$ . Therefore, we have  $\underline{Y}(t_{n+1}; r) = \underline{Y}(t_n; r) + F[t_n, Y(t_n, r)]$ (4.9)  $\overline{Y}(t_{n+1}; r) = \overline{Y}(t_n; r) + F[t_n, y(t_n, r)]$ (4.10) And  $\underline{y}(t_{n+1}; r) = \overline{y}(t_n; r) + F[t_n, y(t_n, r)]$ (4.11)  $\overline{y}(t_{n+1}; r) = \overline{y}(t_n; r) + G[t_n, y(t_n, r)]$ (4.12)

The following lemmas will be applied to show the convergences of theses approximates. i.e.,  $\lim_{h\to 0} \underline{y}(t,r) = \underline{Y}(t,r)$  and  $\lim_{h\to 0} \overline{y}(t,r) = \overline{y}(t,r)$ . Lemma: 4.1 Let a sequence of numbers  $\{W_n\}_{n=0}^N$  satisfy  $|W_{n+1}| \le A|W_n| + B$ ,  $0 \le n \le N-1$ , for some given positive constants A and B, then  $|W_n| \le A^n |W_0| + B \frac{A^{n-1}}{A-1}, 0 \le n \le N-1$ . Proof: see [14]



Lemma: 4.2 Let the sequence of numbers  $\{W_n\}_{n=0}^N$ ,  $\{V_n\}_{n=0}^N$  satisfy  $|W_{n+1}| \le |W_n| + Amax\{|W_n|, |V_n|\} + B$ , for some given positive constants A and B, and denote  $U_n = |W_n| + |V_n|, 0 \le n \le N$ . Then  $U_n \le \overline{A^n}U_0 + \overline{B}\frac{\overline{A^n-1}}{\overline{A-1}}, 0 \le n \le N$ , where  $\overline{A} = 1 + 2A$  and  $\overline{B} = 2B$ Proof: see [14]. Let F(t, u, v) and G(t, u, v) be obtained by substituting  $[y(t)]_r = [u, v]$  in (4.7&4.8),  $F[t, u, v] = 2\frac{K_1[t, u, v]K_2[t, u, v]}{K_1[t, u, v] + K_2[t, u, v]}, G[t, u, v] = 2\frac{\overline{K_1}[t, u, v]K_2[t, u, v]}{K_1[t, u, v] + \overline{K_2}[t, u, v]}$ . The domain where F and G are defined is therefore  $K = \{(t, u, v) \setminus 0 \le t \le T, -\infty < v < \infty, -\infty < u \le v\}$ . Theorem 4.1: let F(t, u, v) and G(t, u, v) belong to  $C^2(K)$  and let the partial derivatives of F and G

be bounded over K. Then, for arbitrary fixed  $r, 0 \le r \le 1$ , the approximate solutions (4.11&4.12)

converge to the exact solutions Y(t; r) and  $\overline{Y}(t; r)$  uniformly in t.

Proof: See [14].

#### **5** .Numerical Example

Example 1. Consider the fuzzy initial value problem,

$$\begin{cases} y'(t) = y(t), t \in [0,1], \\ y(0) = (0.75 + 0.25r, 1.125 - 0.125r), 0 < r \le 1. \\ exact solution is given by \underline{Y}(t;r) = \underline{y}(t;r)e^{t}, \overline{Y}(t;r) = \overline{y}(t;r)e^{t}, \text{which at} t = 1, \end{cases}$$

$$Y(1; r) = [(0.75 + 0.25r)e, (1.125 - 0.125r)e], 0 < r \le 1$$

The exact and approximate solutions obtained by the Euler method and by the Runge-Kutta method of order two with new parameters [New RK] [15] and by the proposed New Multi-Step Runge-Kutta method

[New MSRK] with 'h = 0.1' are given in Table: 1

#### 6. Conclusion

The

In this work, we have used the proposed second-order Runge-Kutta method to find a numerical solution of fuzzy differential equations. Taking into account the convergence order of the Euler method is O(h), a higher order of convergence  $O(h^3)$  is obtained by the proposed method and by the method proposed in [15]. Comparison of the solutions of example 5.1 shows that the proposed method gives a better solution than the Euler method and by the Runge-Kutta method of order 2 proposed in [15].

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r	Exact solution	Euler's Approximation	New RKApproximation	New MSRK Approximation
0	2.0387113,3.0580670	1.9453068,2.9179603	2.0386329,3.0579494	2.0386636,3.0579953
0.2	2.1746254,2.9901100	2.074994,2.8531167	2.1745418,2.989995	2.1745745,2.9900399
0.4	2.3105395,2.9221529	2.2046811,2.7882731	2.3104507,2.9220406	2.3104854,2.9220844
06	2.4464536,2.8541959	2.3343682,2.7234296	2.4463595,2.8540861	2.4463963,2.854129
0.8	2.5823677,2.7862388	2.4640553, 2.658586	2.5822684,2.7861317	2.5823072,2.7861735
1	2.7182818,2.7182818	2.5937425,2.5937425	2.7181773,2.7181773	2.7182181,2.7182181

## Table: 1 Comparison of Results

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