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# M4 Controller Diagnostic Database

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# **M4 Controller Diagnostic Database**

A graduate project submitted to Dakota State University in partial fulfillment of the  
requirements for the degree of

Master of Science

In

Information Systems

5 Feb, 2009

By

Naveen Kumar Kota

Project Committee:

Dr. Ronghua Shan

Dr. Stephen Krebsbach

Dr. Joyce Havlik





## PROJECT APPROVAL FORM

We certify that we have read this project and that, in our opinion, it is satisfactory in scope and quality as a project for the degree of Master of Science in Information Systems.

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Master's Project Title: M4 Controller Diagnostic Database

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Committee member: George Hawley Date: 3-31-2009

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## ABSTRACT

The M4 controller which is under development is the latest version for the M2 and M3 based Controller. The purpose of the controller design is to provide a core platform that can be used across multiple display products. Currently M2 and M3 Controllers retrieve the data from MLC and Modules' and transfer data to the Server side Diagnostic Database which generate notifications using analysis engine. In the M4 controller, this notification is generated from the controller instead of the server side by using the data which are available at the user level database. Currently, the primary goal of the M4 controller is to build a diagnostic database at the user level to generate the notifications.

M4 uses Embedded Linux based platform using Ubuntu Operating System. Research it found that SQLite is a self-contained, server less, Zero configuration and transactional Database Engine that to build the user level Database on the M4 Controller by retrieving the data from Dynamic, Static, Various and Created type files from kernel level diagnostic database using API.

Diagnostics - The process of recording operational status of display hardware components.

Diagnostic Database- is the storage of all the operational status of display Hardware components and notifications which need to be generated.

## DECLARATION

I hereby certify that this project constitutes my own product, that where the language of others is set forth, quotation marks so indicate, and that appropriate credit is given where I have used the language, ideas, expressions or writings of another.

I declare that the project describes original work that has not previously been presented for the award of any other degree of any institution.



Signed,

\_\_Naveen Kumar Kota\_\_

<Student name>

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# CHAPTER 1

## INTRODUCTION

The M4 controller which is under the development is going to be a latest version for M2 and M3 based Controller. The purpose of the controller design is to provide a core platform that can be used across multiple display products. Currently M2 and M3 Controllers retrieve the data from Multiple Line Controller (MLC) and Modules' and transfer data to the Server side Diagnostic Database which generate notifications using analysis engine, in the M4 controller this notification should be generated from controller instead of server side by using the data which is available in controller at user level Database. Now the primary goal of the M4 controller is to build a diagnostic database at the user level to generate the notifications.

M4 uses an embedded Linux based platform using the Ubuntu Operating System. By research it found that SQLite is the self-contained, server less, Zero configuration and transactional Database Engine which would be helpful to build the user level Database on the M4 Controller by retrieving the data from dynamic, static, various and created type files from a kernel level diagnostic database using API.

Diagnostics is the process of recording the operational status of display hardware components.

Diagnostic database is the storage of all the operational status of display hardware components and notification which are needed to be generated.

## CHAPTER 2

### LITERATURE REVIEW

#### 2.1 SQLite

##### 2.1.1 SQLite Is Self-Contained

SQLite is largely self-contained. It requires very minimal support from external libraries or from the operating system. This makes it well suited for use in embedded devices that lack the support infrastructure of a desktop computer. This also makes SQLite appropriate for use within applications that need to run without modification on a wide variety of computers of varying configurations. SQLite is written in ANSI-C and should be easily compiled by any standard C compiler. It makes minimal use of the standard C library. The only required C library functions called are:

- \* memset()
- \* memcpy()
- \* memcmp()
- \* strcmp()
- \* malloc(), free(), and realloc()

SQLite can be configured at start-time to use a static buffer in place of calling malloc for the memory it needs. The date and time Structured Query Language (SQL) functions provided by SQLite require some additional C library support, but those functions can also be omitted from the build using compile-time options.

Communications between SQLite and the operating system and disk are mediated through an interchangeable Virtual File System (VFS) layer. VFS modules for Unix (linux and MacOSX), OS/2, Win32, and WinCE are provided in the source tree. It is a simple matter to devise an alternative VFS for embedded devices.

For safe operation in multi-threaded environments, SQLite requires the use of mutexes. Appropriate mutex libraries are linked automatically for Win32 and Unix platforms. For other systems, mutex primitives can be added at start-time. Mutexes are only required if SQLite is used by more than one thread at a time.

The SQLite source code is available as an "amalgamation" - a single large C source code file. Projects that want to include SQLite can do so simply by dropping this one source file (named "sqlite3.c") and its corresponding header ("sqlite3.h") into their source tree and compiling it together with the rest of the code. SQLite does not link against any external libraries (other than the C library, as described above) and does not require any special build support.

### **2.1.2 SQLite Is Serverless**

Most SQL database engines are implemented as a separate server process. Programs that want to access the database communicate with the server using some kind of interprocess communication (typically TCP/IP) to send requests to the server and to receive back results. SQLite does not work this way. With SQLite, the process that wants to access the database reads and writes directly from the database files on disk. There is no intermediary server process. There are advantages and disadvantages to being serverless. The main advantage is that there is no separate server process to install, setup, configure, initialize, manage, and troubleshoot. This is one reason why SQLite is a "zero-configuration" database engine.

Programs that use SQLite require no administrative support for setting up the database engine before they are run. Any program that is able to access the disk is able to use a SQLite database. On the other hand, a database engine that uses a server can provide better protection from bugs in the client application - stray pointers in a client cannot corrupt memory on the server. A server is a single persistent process so it is able control database access with more precision, allowing for finer grain locking and better concurrency.

Most SQL database engines are client/server based. Of those that are serverless, SQLite is the only one known to this author that allows multiple applications to access the same database at the same time.

### **2.1.3 SQLite Is a Zero-Configuration Database**

SQLite does not need to be "installed" before it is used. There is no "setup" procedure. There is no server process that needs to be started, stopped, or configured. There is no need for an administrator to create a new database instance or assign access permissions to users. SQLite uses no configuration files. Nothing needs to be done to tell the system that SQLite is running. No actions are required to recover after a system crash or power failure. There is nothing to troubleshoot SQLite just works. Other database engines may run great once you get them going but doing the initial installation and configuration can often be intimidating.

### **2.1.4 SQLite is Transactional**

A transactional database is one in which all changes and queries appear to be Atomic, Consistent, Isolated, and Durable (ACID). SQLite implements serializable transactions that are Atomic, Consistent, Isolated, and Durable, even if the transaction is interrupted by a program crash, an operating system crash, or a power failure to the computer.

We restate and amplify the previous sentence for emphasis: all changes within a single transaction in SQLite either occur completely or not at all, even if the act of writing the change out to the disk is interrupted by

- \* a program crash,
- \* an operating system crash, or
- \* a power failure.

The claim of the previous paragraph is extensively checked in the SQLite regression test suite using a special test harness that simulates the effects on a database file of operating system crashes and power failures.

## **2.2 M4 Debugging Setup**

### Tools Required

- PC Running Ubuntu 7.10 Linux or newer ([www.ubuntu.com](http://www.ubuntu.com))
- Eclipse IDE CDT C++ ([www.eclipse.org](http://www.eclipse.org))
- JRE 5.0 or newer
- M4 Linux Tools 0.0.3 or newer

After installing the above files, open the Eclipse development environment.

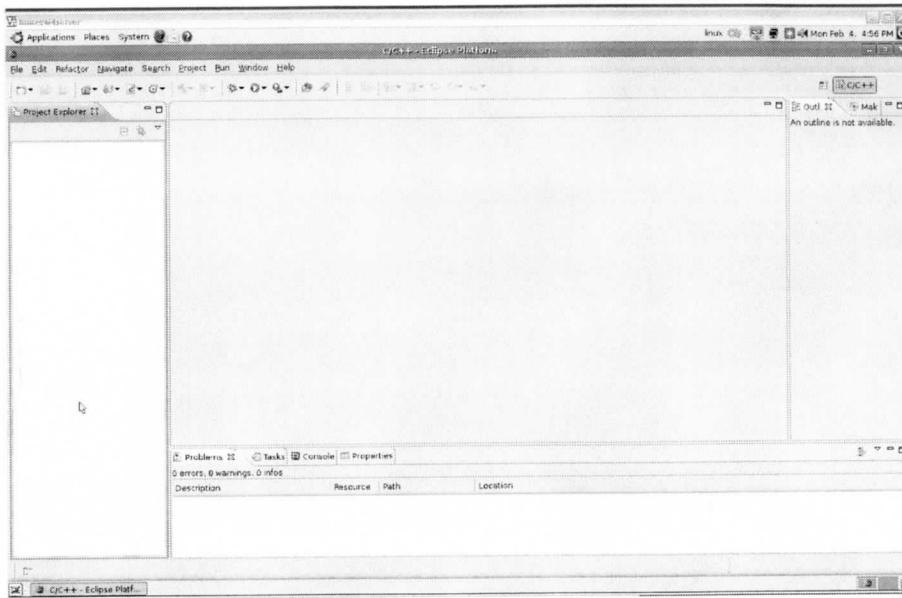


Figure 1: Eclipse edit page

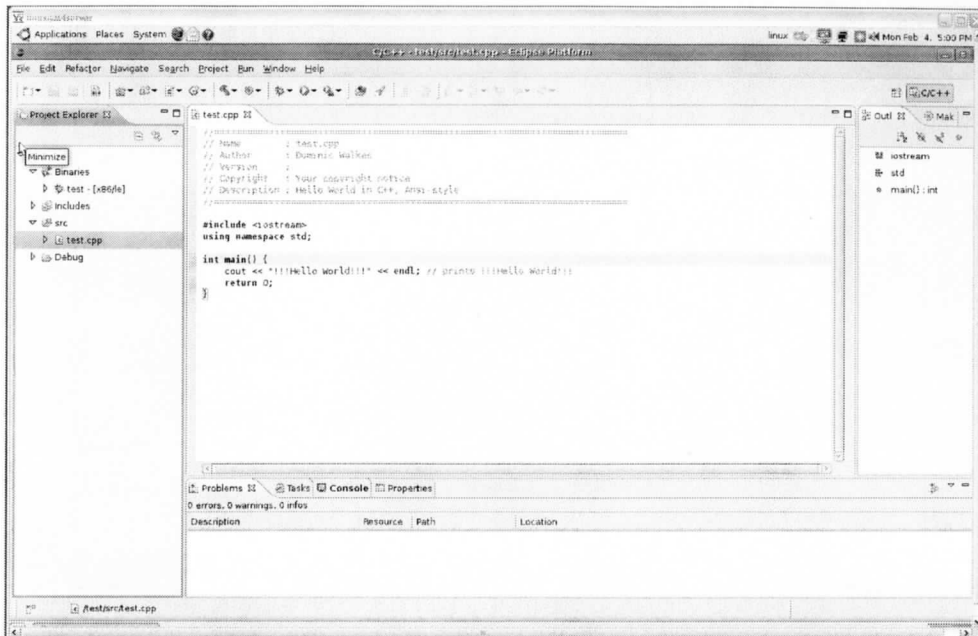
Select File->Project->C++ Project

Project Name: test

Under Executable – select Hello World C++ Project

Toolchain: Linux GCC

Select Finish



Project->Properties

Under "C/C++ Build" Select "Settings"

The Command: g++ is using the internal g++ compiler for the x86, so let's call out the cross compiler for the powerpc here – if you installed your tools to "opt/crostoool" – which is the default, you should be able to link in with:

GCC C++ Compiler: /opt/crostoool/gcc-4.0.2-glibc-2.3.6/powerpc-405-linux-gnu/bin/powerpc-405-linux-gnu-g++

GCC C Compiler: /opt/crostoool/gcc-4.0.2-glibc-2.3.6/powerpc-405-linux-gnu/bin/powerpc-405-linux-gnu-gcc-4.0.2

GCC C++ Linker: /opt/crostoool/gcc-4.0.2-glibc-2.3.6/powerpc-405-linux-gnu/bin/powerpc-405-linux-gnu-g++

GCC Assembler: /opt/crostoool/gcc-4.0.2-glibc-2.3.6/powerpc-405-linux-gnu/bin/powerpc-405-linux-gnu-as

Rebuild the project with the new compiler settings.

Now we are ready to try and run the program. Using a File Transfer Protocol (FTP) program – Firefox FireFTP is handy, connect to a M4/Evaluation board. Transfer the “test” file from your Linux workspace onto the remote target. After transferring, select the file on the remote target and change the properties to allow executing.

Connect over either serial or Transmission Control Protocol (TCP) telnet. Launch the test file with:

“<stored directory>/test” – you should see “hello world” print on the console.

Now we are ready to set up a simple debug session. First, FTP the following file to the working directory that you downloaded “test” into -

/opt/crosstool/PPC405\_Debugger/gdbserver/bin/gdbserver

You may need to change the file permissions to allow executing this program as well.

Now let’s set up the GDB (GNU Debugger) Server, that will run on the remote target:

Create a new Program

Name: test\_gdbserver

Location: /opt/crosstool/gdb\_script

Arguments: <remote ip> <remote\_location>/test



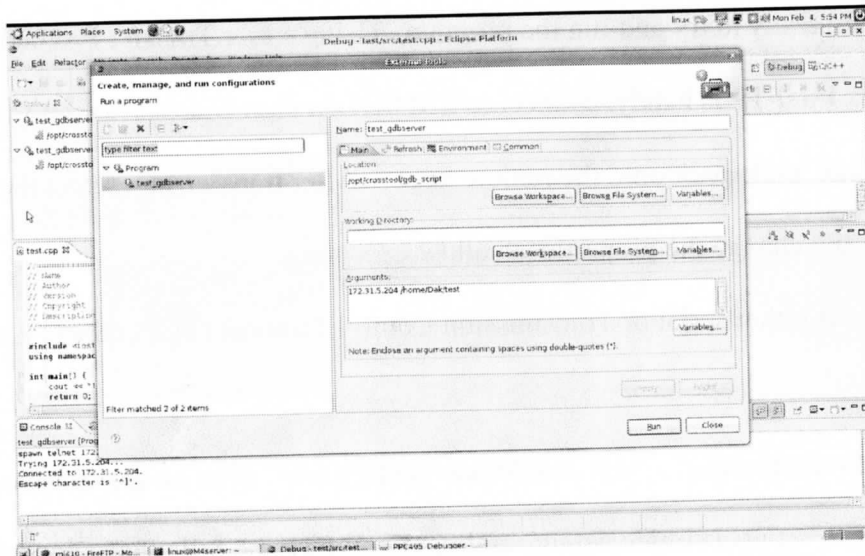


Figure 2: GDB server setup in Eclipse

In this case, my remote target was 172.31.5.204 and the program was stored to “/home/Dak/test”

Note!! On tools rev 0.0.3 the following must be replaced in /opt/crostool/gdb\_script:

```
#!/usr/bin/expect -f
```

```
if {$argc==0} {
```

```
    send_user "usage: $argv0 IP_ADDRESS Prg_to_Debug\n"
```

```
    exit }
```

```
set timeout -1
```

```
set ip [lindex $argv 0]
```

```
set login "root\r"
```

```
#set passwd "Dak\r"
```

```
set prg [lindex $argv 1]
```

```
set cmd "/home/Dak/gdbserver host:2345 $prg\r"
```

```
spawn telnet $ip
```

```
expect "M4 login: "
```

```
send $login
```

```
#expect "Password: "
```

```
#send $passwd
```

```
expect "root@M4 ~ # "
```

```
send $cmd
```

```
expect "Listening on port 2345"
```

```
expect "root@M4 ~ # "
```

```
send "exit\r"
```

Select Run -> you should see:

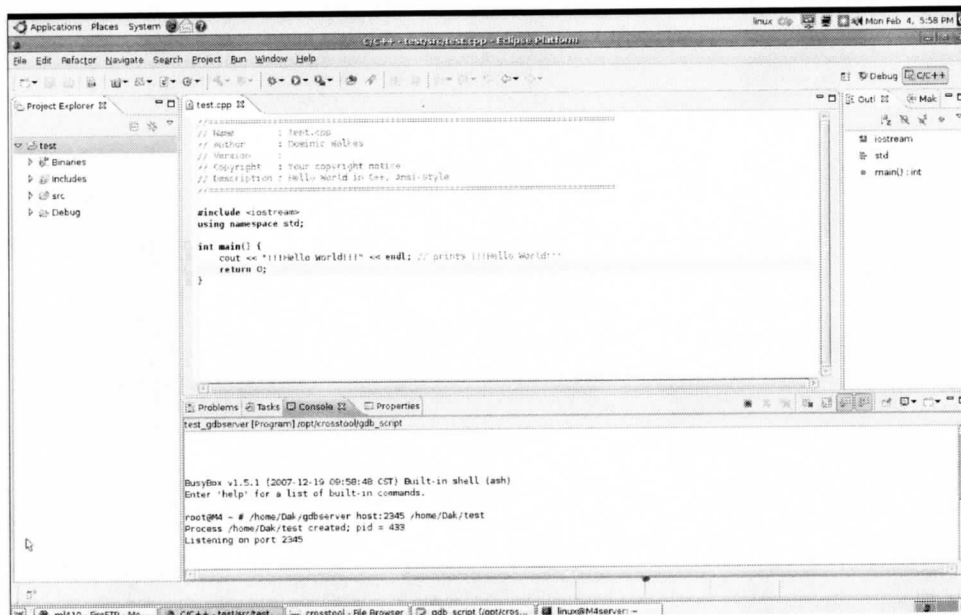


Figure 3: console checkup

In the console, make sure it says “Listening on port 2345” – if it does not debugging will not work! Now, back in the eclipse environment select Run->Open Debug Dialog

Create a new “C/C++ Local Application”

**In the Main Tab-Name: Test Debug**

**Project: Test**

C/C++ Application: Browse to <workspace\_location>/test/Debug and select “test”

**In the Debugger Tab**-Debugger: gdbserver Debugger

MainTab-GDB Debugger: /opt/crosstool/PPC405\_Debugger/bin/powerpc-405-linux-gnu-gdb

GDB command file: /opt/crosstool/PPC405\_Debugger/gdb\_setupShared Libraries:

Add -> /opt/crosstool/ml410\_rfs

Connection:Type: TCP

Host Name: the remote location – 172.31.5.204 for example

Port Number 2345

Select RUN and you should be good to go!

## CHAPTER 3

### OBJECTIVE AND DELIVERABLE OF THE PROJECT

#### 3.1 The objective of the project

M4 is the controller which will collect and store, in real time, diagnostic information for all internal components of the display for retrieval by the display control system. It is an embedded Linux based platform. The internal components which are stored in M4 Linux-kernel space diagnostic data is polled to the Linux-user Space diagnostic database using Application Program Interface(API).Project is to build the Linux-User Space Diagnostic database to generate the diagnostic notifications using the data provided from M4-Linux Kernel space.

Internal components polled for diagnostic data include:

- Controller status information (similar to the Get Status command of the control channel)
- Pixel failures
- Calibration data
- Component temperatures
- Display cooling assemblies along with on/off/speed control
- Power supply
- Display peripherals (i.e. temperature sensor, light detector, etc...)
- Other internal components required for display operation (i.e. MLC's, DD's, etc...)

The controller will provide diagnostic data for failed components only or a full status as defined by the requesting command. Diagnostic information will be returned in an Extensible Markup Language (XML) style of document to the display control application as part of the diagnostic data, a representation of the display component configuration shall be returned for use by the control application. ( i. e. locations controlled by an MLC, area powered by a power supply, etc...).

The following is the plan to build the user level diagnostic database based on the index available from API and this Data is available at the Kernel level Diagnostic Database.

### 3.1.1 Black Box Diagnostic Database

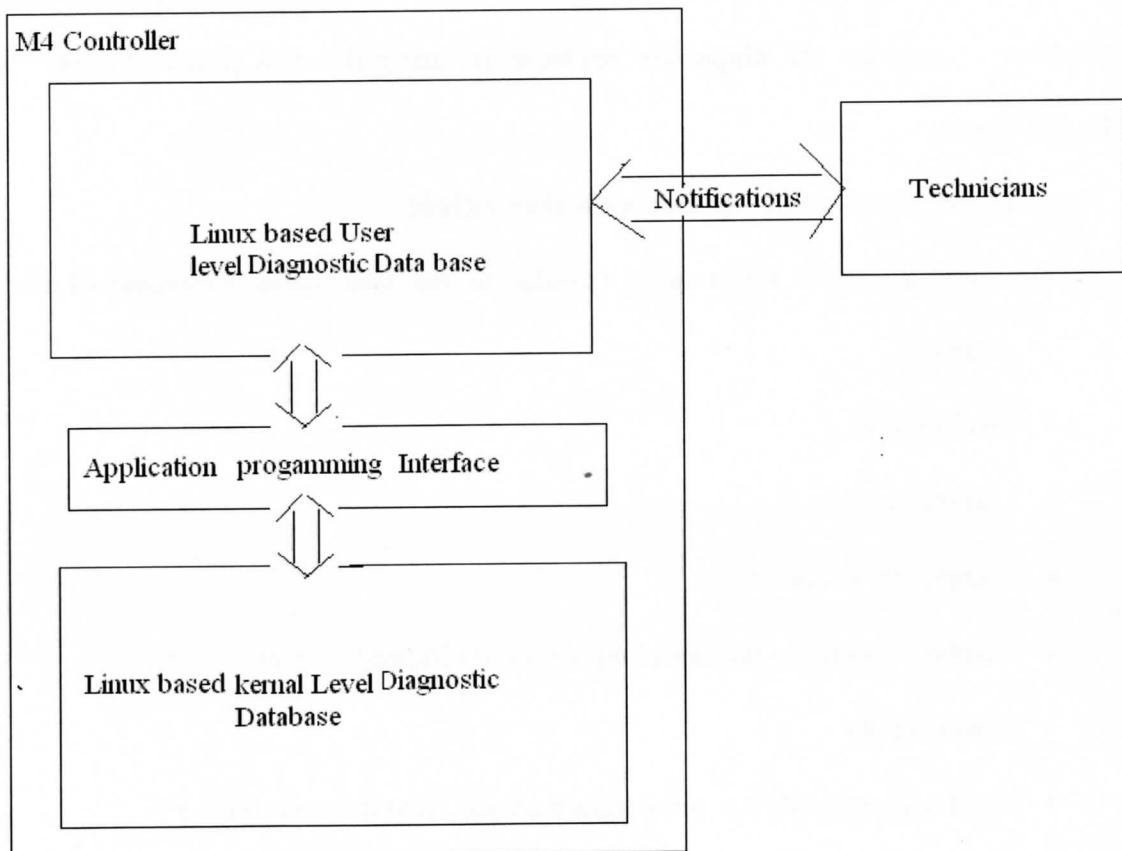


Figure 4: Black Box Diagnostic Database

### 3.1.2 Proposed M3/M4 Diagnostics

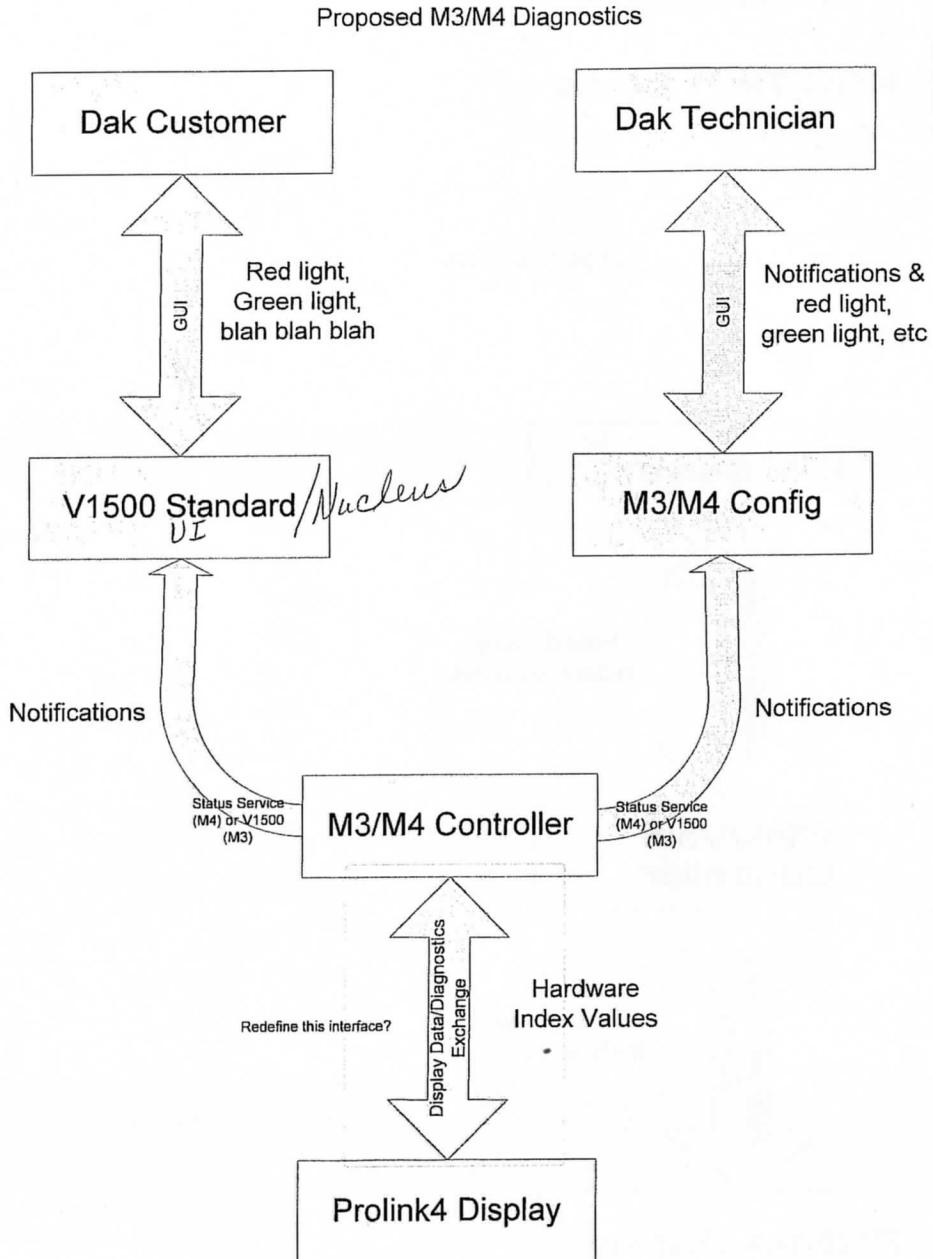


Figure 5: Proposed M3/M4 Diagnostics

### 3.1.3 Current Diagnostic Database

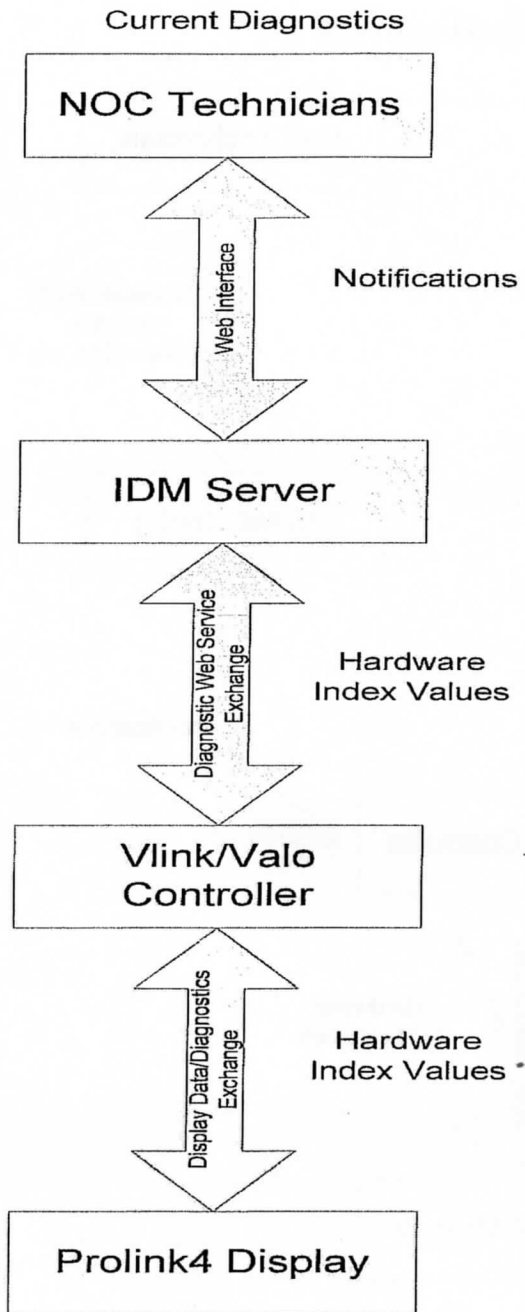


Figure 6: Current Diagnostic Database

### 3.2 Statement of the problem

Below are the current Diagnostic notifications generating functionality for controllers at server level. The above diagram is a designed diagnostic database based on this current structure.

#### 3.2.1 Functionality of Controller

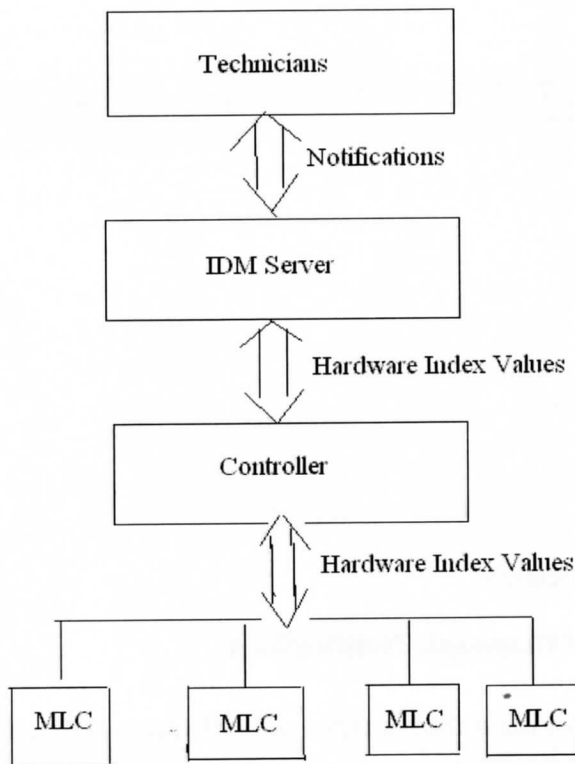


Figure 7: Functionality of Controller

The following screen shot is a sample notification generated at the server level diagnostic database site to show the issues in the controller. Similarly, we need to generate the notification for the M4 Controller in the future after building the database on the M4



controller. These notifications would be useful to store in the database to generate notifications. The difference is the Intelligent Device Management (IDM) is Server side Database and Database which we are trying to build is on M4 controller.

### 3.2.2. Sample Notification at Server level

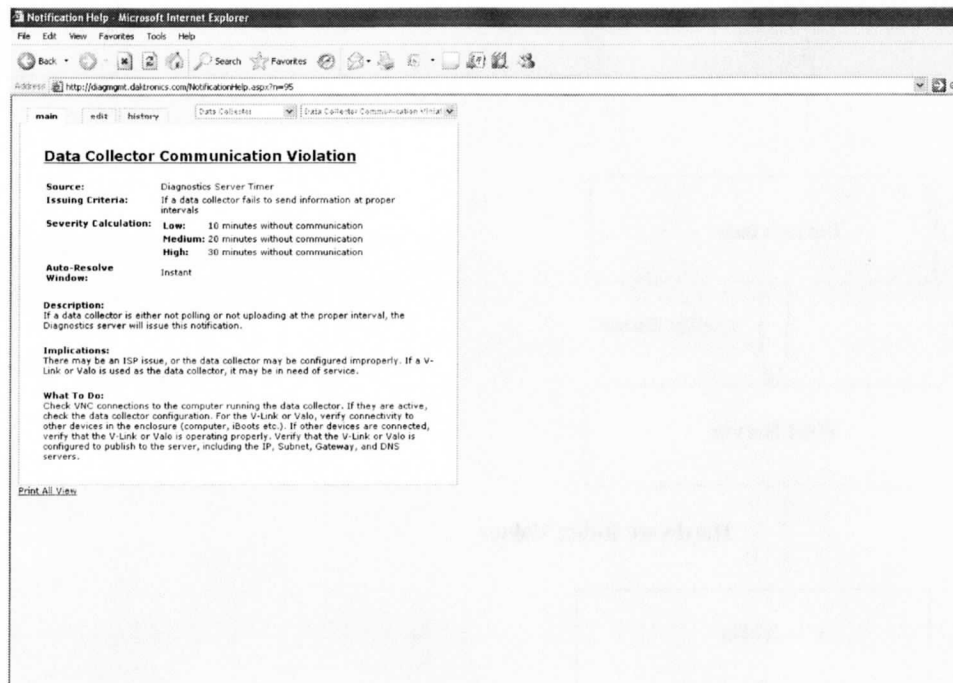


Figure 8: Screenshot of sample notification

### 3.2.3 The Matrix representation of Diagnostic Notifications

The following is the matrix for the different types of hardware and diagnostic notifications which are generated when the display problem and other problems occur in the M4 controller and are stored in the diagnostic database on the server side. Based on these notifications we need to build the notifications for the M4 Diagnostic Database. In order to do that we need to filter understand and store the M4 controller notification in the Controller

User Level Database.

V-Link 1500 DVI ProLink4

Control Enclosure Open

Light Sensor Violation

Non-DVI Signal Source

Too Bright at Night!

V-Link Not Receiving Video

V-Link Over Temperature

V-Link Thermal Dimming

V-Link 1500 DVI VMAX4

Control Enclosure Open

Light Sensor Violation

Non-DVI Signal Source

Security Sensor 1 (Catwalk Back A) Tripped

Security Sensor 2 (Catwalk Back B) Tripped

Security Sensor 3 (Catwalk Back A) Tripped

Security Sensor 4 (Catwalk Back B) Tripped

Security Sensor 5 (Ladder Top) Tripped

Security Sensor 6 (Ladder Bottom) Tripped

Too Bright at Night!

V-Link Not Receiving Video

V-Link Over Temperature

ValoPlay ProLink4

Control Enclosure Open

Error Downloading Alerts Schedule from

Visiconn

Error Downloading Content from Visiconn

Error Downloading Schedule from Visiconn

Error Uploading Error Log to Visiconn

Error Uploading Runtime Log to Visiconn

Light Sensor Violation

Missed Scheduled Poll with Visiconn

No Content Scheduled

Playback Error

Schedule Abnormality Detected

SD Card Failure

Security Failure with Visiconn

Too Bright at Night!

Valo Over Temperature

Valo Running on Battery Backup

Valo Thermal Dimming

ValoPlay Reset

ValoPlay VMAX4

Control Enclosure Open

Error Downloading Alerts Schedule from

Visiconn

Error Downloading Content from Visiconn  
Error Downloading Schedule from Visiconn  
Error Uploading Error Log to Visiconn  
Error Uploading Runtime Log to Visiconn  
Light Sensor Violation  
Missed Scheduled Poll with Visiconn  
No Content Scheduled  
Playback Error  
Schedule Abnormality Detected  
SD Card Failure  
Security Failure with Visiconn  
Too Bright at Night!  
Valo Over Temperature  
Valo Running on Battery Backup  
Valo Thermal Dimming  
ValoPlay Reset

V-Net 4

Data Error

Error Downloading Alerts Schedule from  
Visiconn

Error Downloading Content from Visiconn  
Error Downloading Schedule from Visiconn  
Error Uploading Error Log to Visiconn

Error Uploading Runtime Log to Visiconn

File Duration Exceeded

Missed Scheduled Poll with Visiconn

No Content Scheduled

Playback Error

Player Manager Not Running

Player Manager Reset

Player Not Running

Unable to Activate Schedule

Data Collector

Data Collector Communication Violation

DD 4030

DD Communication Failure

DD Diagnostic Data Violation

DD Display Data Violation

DD Input Signal Not Locked

DD Reset

DD Thermal Dimming

Too Bright at Night!

DD 404X

DD Communication Failure

DD Diagnostic Data Violation

DD Display Data Violation

DD PCB Over Temperature

DD Input Signal Not Locked

DD Reset

DD Startup Error - FPGA Not Configured

DD Startup Error - Memory Self Test Failed

DD Startup Error - Test Pattern Blanking

Failed

DD Startup Error - Translation Table

Checksum Failed

DD Startup Error - Translation Table Not

Enabled

DD Thermal Dimming

MLC 3050

MLC Diagnostic Data Violation

MLC Display Clock Violation

MLC Display Data Violation

MLC Reset

MLC 4050

MLC Diagnostic Data Violation

MLC Primary Signal Display Data Violation

MLC Primary Signal Out of Sync

MLC Reset

MLC Secondary Signal Display Data

Violation

MLC Secondary Signal Out of Sync

MOD 2X14	Module Diagnostic Data Violation
	Module Display Data Violation
	Module Over Temperature
MOD HD-16	Module Diagnostic Data Serial Violation
	Module Diagnostic Data Violation
	Module Display Data Violation
	Module Over Temperature
Sony FWD-50PX2	Screen Communication Failure
	Screen in Stand By Mode
	Screen Over Temperature
Sony FWD-50PX3	Screen Communication Failure
	Screen in Stand By Mode
	Screen Over Temperature

### 3.3 The Deliverable of the project

#### 3.3.1 Overview of Data

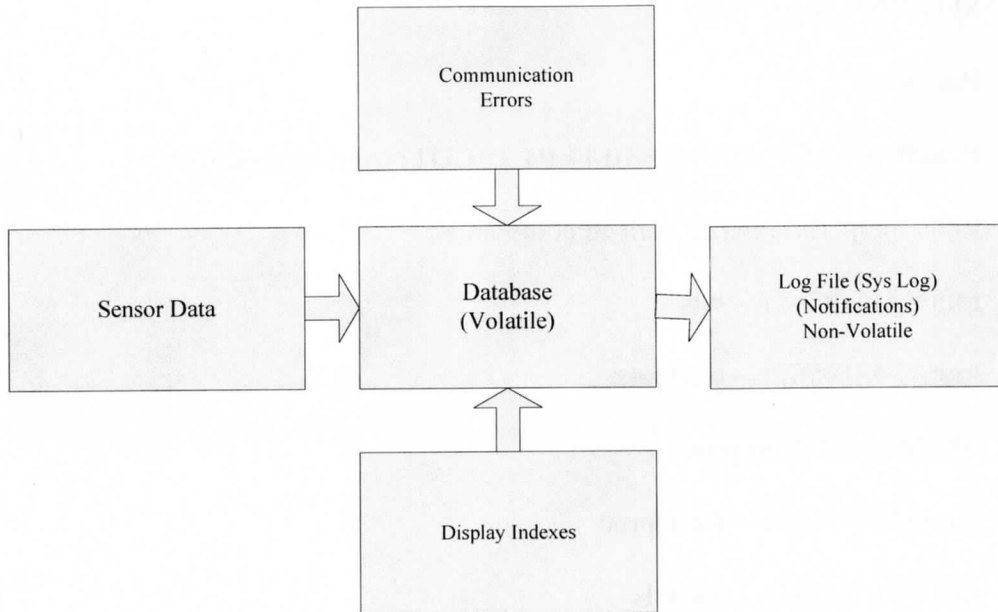


Figure 9: overview of Data

#### 3.3.2 Telenet of M4 Controller Display Data

The following is the M4 Controller display data retrieved through the telnet the process file system at the terminal in the Ubuntu. To get basic idea of the how the data is stored in the M4 Controller.

```
nkota@D6678-linux:~$ telnet m4195671
```

```
Trying 172.31.5.69...
```

```
Connected to m4195671.daktronics.lan.
```

```
Escape character is '^]'.
```

```
=====
```



M4 PPC Linux 2.6.21

Linux/ppc 2.6.21

=====

M4195671 login: root

Password:

BusyBox v1.5.1 (2008-06-10 14:04:35 CDT) Built-in shell (ash)

Enter 'help' for a list of built-in commands.

root@M4195671 ~ # ls

root@M4195671 ~ # cd proc

-sh: cd: can't cd to proc

root@M4195671 ~ # cd /proc

root@M4195671 /proc # ls

1	126	21346	242	285	4	bus	fs	loadavg
partitions	tty							
10	134	21347	261	286	5	cmdline	interrupts	
locks	scsi	uptime						
100	137	21822	266	287	6	cpuinfo	iomem	
meminfo	self	version						
103	141	21830	278	288	7	devices	ioports	misc
slabinfo	vmstat							
107	14823	223	279	289	77	diskstats	irq	
modules	stat	zoneinfo						

```
11      152      226      280      3      8      driver  kallsyms  mounts
sys
```

```
111     2        227      281     34     9      execdomains kcore  mtd
sysvipc
```

```
12      202      228      282     35     buddyinfo filesystems kmsg
net      timer_list
```

```
root@M4195671 /proc # cd /driver
```

```
-sh: cd: can't cd to /driver
```

```
root@M4195671 /proc # cd driver
```

```
root@M4195671 /proc/driver # ls
```

```
M4Hdwr      display_driver light      mpegdecode  prolink4    temp
```

```
compositor  frame_control lm86      pl4_diag    rtc
```

```
root@M4195671 /proc/driver # ls
```

```
M4Hdwr      display_driver light      mpegdecode  prolink4    temp
```

```
compositor  frame_control lm86      pl4_diag    rtc
```

```
root@M4195671 /proc/driver # cd pl4_diag
```

```
root@M4195671 /proc/driver/pl4_diag # ls
```

```
debug  port_0  port_1  status
```

```
root@M4195671 /proc/driver/pl4_diag # cd port_0
```

```
root@M4195671 /proc/driver/pl4_diag/port_0 # ls
```

```
isac_0  mlc_0  mod_1  mod_11  mod_13  mod_15  mod_17  mod_3  mod_5  mod_7
```

```
mod_9
```

isac\_1 mod\_0 mod\_10 mod\_12 mod\_14 mod\_16 mod\_2 mod\_4 mod\_6  
mod\_8

```
root@M4195671 /proc/driver/pl4_diag/port_0 # cd mlc_0
```

```
root@M4195671 /proc/driver/pl4_diag/port_0/mlc_0 # ls
```

```
created dynamic generic static various
```

```
root@M4195671 /proc/driver/pl4_diag/port_0/mlc_0 # cd created
```

```
-sh: cd: can't cd to created
```

```
root@M4195671 /proc/driver/pl4_diag/port_0/mlc_0 # cat created
```

```
PDA2
```

```
0000root@M4195671 /proc/driver/pl4_diag/port_0/mlc_0 # cat PDA@
```

```
cat: PDA@: No such file or directory
```

```
root@M4195671 /proc/driver/pl4_diag/port_0/mlc_0 # cat PDA2
```

```
cat: PDA2: No such file or directory
```

```
root@M4195671 /proc/driver/pl4_diag/port_0/mlc_0 # cd dynamic
```

```
-sh: cd: can't cd to dynamic
```

```
root@M4195671 /proc/driver/pl4_diag/port_0/mlc_0 # cat dynamic
```

```
PDA2
```

```
0030
```

```
0840
```

```
0000
```

```
0021
```

```
0031
```

```
ffff
```

ffff  
0000  
0001  
00ff  
0000  
010a  
0001  
ffff  
ffff  
ffff  
05dc  
2db4  
ffff  
0001  
0000  
003c  
0000  
0001  
0002  
e26d  
0000  
0001  
0000

724a

0000

0001

0002

e26d

0000

0001

00ff

ffff

ffff

0006

0004

0059

0009

5edd

0003

ed15

0002

da62

0002

```
root@M4195671 /proc/driver/pl4_diag/port_0/mlc_0 # ls
```

```
created dynamic generic static various
```

```
root@M4195671 /proc/driver/pl4_diag/port_0/mlc_0 # cat generic
```

gd\_proc generic

port 0 type 2 num 0

root@M4195671 /proc/driver/pl4\_diag/port\_0/mlc\_0 # cat port 0

cat: port: No such file or directory

cat: 0: No such file or directory

root@M4195671 /proc/driver/pl4\_diag/port\_0/mlc\_0 # cat static

PDA2

0031

1302

0020

0033

0054

0039

0006

0001

0000

7911

c7bd

002f

0001

005f

0003

0015

0015

0015

0015

0015

0015

fff

fff

0c5f

0c5f

0c5f

0c5f

0c5f

0c5f

0c5f

0c5f

0c5f

0c5f

0c5f

0c5f

fff

fff

fff

fff

0000

0000

29ad

0046

0016

0000

0000

0000

0000

0000

0007



### 3.3.3 Flow of Data

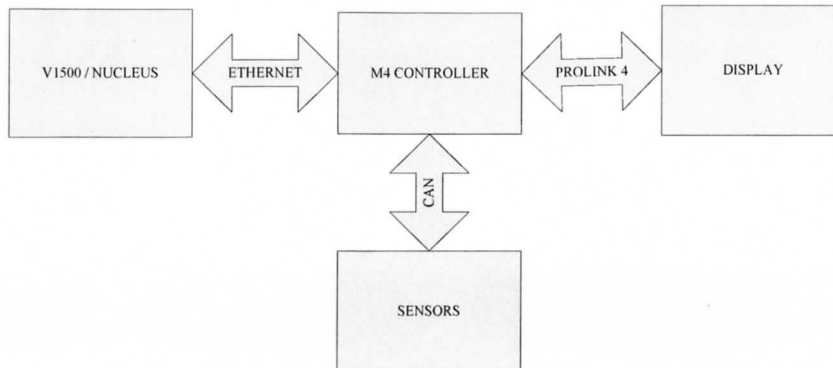


Figure 10: Figure-10 Flow of Data

### 3.3.4 Telnet of M4 Controller Sensor Data

The following is the M4 controller Sensor data retrieved through the telnet the process file system at the terminal in the Ubuntu to get basic idea of the how the data is stored in the M4 Controller.

```
nkota@D6678-linux:~$ telnet mm4
```

```
Trying 10.6.70.131...
```

```
Connected to mm4.daktronics.lan.
```

```
Escape character is '^['.
```

```
=====
```

```
M4 PPC Linux 2.6.21
```

Linux/ppc 2.6.21

=====

MM4 login: root

Password:

BusyBox v1.5.1 (2008-06-10 14:04:35 CDT) Built-in shell (ash)

Enter 'help' for a list of built-in commands.

root@MM4 ~ # ls

discoveryd

root@MM4 ~ # cd /proc

root@MM4 /proc # ls

1	16866	21582	4	fs	net
10	16951	216	5	interrupts	partitions
101	16955	217	6	iomem	scsi
11	16956	259	7	ioports	self
12	16957	2687	8	irq	slabinfo
126	16958	2688	9	kallsyms	stat
129	16963	2967		buddyinfo	kcore sys
152	16968	2975	bus	kmsg	sysvipc
156	16969	3	cmdline	loadavg	timer_list
164	16970	34	cpuinfo	locks	tty
16673	183	35	devices	meminfo	uptime

```
16792    2    354    diskstats  misc    version
16793   211    363    driver    modules  vmstat
16794   214    37     execdomains mounts  zoneinfo
168     21578   38     filesystems mtd
```

```
root@MM4 /proc # cd light
```

```
-sh: cd: can't cd to light
```

```
root@MM4 /proc # cd /light
```

```
-sh: cd: can't cd to /light
```

```
root@MM4 /proc # cd /driver
```

```
-sh: cd: can't cd to /driver
```

```
root@MM4 /proc # cd driver
```

```
root@MM4 /proc/driver # ls
```

```
M4Hdwr    frame_control  mpegdecode    rtc
```

```
compositor  light    pl4_diag    temp
```

```
display_driver  lm86    prolink4
```

```
root@MM4 /proc/driver # cd light
```

```
root@MM4 /proc/driver/light # ls
```

```
address one    rev    ten    timer
```

```
root@MM4 /proc/driver/light # ls
```

```
address one    rev    ten    timer
```

```
root@MM4 /proc/driver/light # cat address
```

```
0x42012root@MM4 /proc/driver/light # cd address
```

```
-sh: cd: can't cd to address
```

```

root@MM4 /proc/driver/light # cat one
one_minute_avg = 49
root@MM4 /proc/driver/light # cat rev
rev = 8
root@MM4 /proc/driver/light # cat ten
ten_minute_avg = 49
root@MM4 /proc/driver/light # cat timer
30
root@MM4 /proc/driver/light # cd ..
root@MM4 /proc/driver # ls
M4Hdwr      display_driver light      mpegdecode  prolink4    temp
compositor  frame_control lm86      pl4_diag    rtc
root@MM4 /proc/driver # cd pl4_diag
root@MM4 /proc/driver/pl4_diag # ls
debug  port_0  port_1  status
root@MM4 /proc/driver/pl4_diag # cd port_0
root@MM4 /proc/driver/pl4_diag/port_0 # ls
mlc_0  mod_124  mod_152  mod_180  mod_208  mod_236  mod_264  mod_292
mod_32  mod_348  mod_376  mod_403  mod_431  mod_46   mod_488  mod_55   mod_83
mlc_1  mod_125  mod_153  mod_181  mod_209  mod_237  mod_265  mod_293
mod_320  mod_349  mod_377  mod_404  mod_432  mod_460  mod_489  mod_56   mod_84
mod_0   mod_126  mod_154  mod_182  mod_21   mod_238  mod_266  mod_294
mod_321  mod_35   mod_378  mod_405  mod_433  mod_461  mod_49   mod_57   mod_85

```

mod\_1 mod\_127 mod\_155 mod\_183 mod\_210 mod\_239 mod\_267 mod\_295  
mod\_322 mod\_350 mod\_379 mod\_406 mod\_434 mod\_462 mod\_490 mod\_58 mod\_86  
mod\_10 mod\_128 mod\_156 mod\_184 mod\_211 mod\_24 mod\_268 mod\_296  
mod\_323 mod\_351 mod\_38 mod\_407 mod\_435 mod\_463 mod\_491 mod\_59 mod\_87  
mod\_100 mod\_129 mod\_157 mod\_185 mod\_212 mod\_240 mod\_269 mod\_297  
mod\_324 mod\_352 mod\_380 mod\_408 mod\_436 mod\_464 mod\_492 mod\_6 mod\_88  
mod\_101 mod\_13 mod\_158 mod\_186 mod\_213 mod\_241 mod\_27 mod\_298  
mod\_325 mod\_353 mod\_381 mod\_409 mod\_437 mod\_465 mod\_493 mod\_60 mod\_89  
mod\_102 mod\_130 mod\_159 mod\_187 mod\_214 mod\_242 mod\_270 mod\_299  
mod\_326 mod\_354 mod\_382 mod\_41 mod\_438 mod\_466 mod\_494 mod\_61 mod\_9  
mod\_103 mod\_131 mod\_16 mod\_188 mod\_215 mod\_243 mod\_271 mod\_3  
mod\_327 mod\_355 mod\_383 mod\_410 mod\_439 mod\_467 mod\_495 mod\_62 mod\_90  
mod\_104 mod\_132 mod\_160 mod\_189 mod\_216 mod\_244 mod\_272 mod\_30  
mod\_328 mod\_356 mod\_384 mod\_411 mod\_44 mod\_468 mod\_496 mod\_63 mod\_91  
mod\_105 mod\_133 mod\_161 mod\_19 mod\_217 mod\_245 mod\_273 mod\_300  
mod\_329 mod\_357 mod\_385 mod\_412 mod\_440 mod\_469 mod\_497 mod\_64 mod\_92  
mod\_106 mod\_134 mod\_162 mod\_190 mod\_218 mod\_246 mod\_274 mod\_301  
mod\_33 mod\_358 mod\_386 mod\_413 mod\_441 mod\_47 mod\_498 mod\_65 mod\_93  
mod\_107 mod\_135 mod\_163 mod\_191 mod\_219 mod\_247 mod\_275 mod\_302  
mod\_330 mod\_359 mod\_387 mod\_414 mod\_442 mod\_470 mod\_499 mod\_66 mod\_94  
mod\_108 mod\_136 mod\_164 mod\_192 mod\_22 mod\_248 mod\_276 mod\_303  
mod\_331 mod\_36 mod\_388 mod\_415 mod\_443 mod\_471 mod\_5 mod\_67 mod\_95

mod\_109 mod\_137 mod\_165 mod\_193 mod\_220 mod\_249 mod\_277 mod\_304  
mod\_332 mod\_360 mod\_389 mod\_416 mod\_444 mod\_472 mod\_50 mod\_68 mod\_96  
mod\_11 mod\_138 mod\_166 mod\_194 mod\_221 mod\_25 mod\_278 mod\_305  
mod\_333 mod\_361 mod\_39 mod\_417 mod\_445 mod\_473 mod\_500 mod\_69 mod\_97  
mod\_110 mod\_139 mod\_167 mod\_195 mod\_222 mod\_250 mod\_279 mod\_306  
mod\_334 mod\_362 mod\_390 mod\_418 mod\_446 mod\_474 mod\_501 mod\_7 mod\_98  
mod\_111 mod\_14 mod\_168 mod\_196 mod\_223 mod\_251 mod\_28 mod\_307  
mod\_335 mod\_363 mod\_391 mod\_419 mod\_447 mod\_475 mod\_502 mod\_70 mod\_99  
mod\_112 mod\_140 mod\_169 mod\_197 mod\_224 mod\_252 mod\_280 mod\_308  
mod\_336 mod\_364 mod\_392 mod\_42 mod\_448 mod\_476 mod\_503 mod\_71  
mod\_113 mod\_141 mod\_17 mod\_198 mod\_225 mod\_253 mod\_281 mod\_309  
mod\_337 mod\_365 mod\_393 mod\_420 mod\_449 mod\_477 mod\_504 mod\_72  
mod\_114 mod\_142 mod\_170 mod\_199 mod\_226 mod\_254 mod\_282 mod\_31  
mod\_338 mod\_366 mod\_394 mod\_421 mod\_45 mod\_478 mod\_505 mod\_73  
mod\_115 mod\_143 mod\_171 mod\_2 mod\_227 mod\_255 mod\_283 mod\_310  
mod\_339 mod\_367 mod\_395 mod\_422 mod\_450 mod\_479 mod\_506 mod\_74  
mod\_116 mod\_144 mod\_172 mod\_20 mod\_228 mod\_256 mod\_284 mod\_311  
mod\_34 mod\_368 mod\_396 mod\_423 mod\_451 mod\_48 mod\_507 mod\_75  
mod\_117 mod\_145 mod\_173 mod\_200 mod\_229 mod\_257 mod\_285 mod\_312  
mod\_340 mod\_369 mod\_397 mod\_424 mod\_452 mod\_480 mod\_508 mod\_76  
mod\_118 mod\_146 mod\_174 mod\_201 mod\_23 mod\_258 mod\_286 mod\_313  
mod\_341 mod\_37 mod\_398 mod\_425 mod\_453 mod\_481 mod\_509 mod\_77

mod\_119 mod\_147 mod\_175 mod\_202 mod\_230 mod\_259 mod\_287 mod\_314  
mod\_342 mod\_370 mod\_399 mod\_426 mod\_454 mod\_482 mod\_51 mod\_78  
mod\_12 mod\_148 mod\_176 mod\_203 mod\_231 mod\_26 mod\_288 mod\_315  
mod\_343 mod\_371 mod\_4 mod\_427 mod\_455 mod\_483 mod\_510 mod\_79  
mod\_120 mod\_149 mod\_177 mod\_204 mod\_232 mod\_260 mod\_289 mod\_316  
mod\_344 mod\_372 mod\_40 mod\_428 mod\_456 mod\_484 mod\_511 mod\_8  
mod\_121 mod\_15 mod\_178 mod\_205 mod\_233 mod\_261 mod\_29 mod\_317  
mod\_345 mod\_373 mod\_400 mod\_429 mod\_457 mod\_485 mod\_52 mod\_80  
mod\_122 mod\_150 mod\_179 mod\_206 mod\_234 mod\_262 mod\_290 mod\_318  
mod\_346 mod\_374 mod\_401 mod\_43 mod\_458 mod\_486 mod\_53 mod\_81  
mod\_123 mod\_151 mod\_18 mod\_207 mod\_235 mod\_263 mod\_291 mod\_319  
mod\_347 mod\_375 mod\_402 mod\_430 mod\_459 mod\_487 mod\_54 mod\_82

```
root@MM4 /proc/driver/pl4_diag/port_0 # cd mlc_0
```

```
root@MM4 /proc/driver/pl4_diag/port_0/mlc_0 # ls
```

```
created dynamic generic static various
```

```
root@MM4 /proc/driver/pl4_diag/port_0/mlc_0 # cat dynamic
```

```
PDA2
```

```
0000root@MM4 /proc/driver/pl4_diag/port_0/mlc_0 # cat created
```

```
PDA2
```

```
0000root@MM4 /proc/driver/pl4_diag/port_0/mlc_0 # cat generic
```

```
gd_proc generic
```

```
port 0 type 2 num 0
```

```
root@MM4 /proc/driver/pl4_diag/port_0/mlc_0 #
```

\_149 mod\_177 mod\_204 mod\_232 mod\_260 mod\_289 mod\_316 mod\_344  
mod\_372 mod\_40 mod\_428 mod\_456 mod\_484 mod\_511 mod\_8

mod\_121 mod\_15 mod\_178 mod\_205 mod\_233 mod\_261 mod\_29 mod\_317  
mod\_345 mod\_373 mod\_400 mod\_429 mod\_457 mod\_485 mod\_52 mod\_80

mod\_122 mod\_150 mod\_179 mod\_206 mod\_234 mod\_262 mod\_290 mod\_318  
mod\_346 mod\_374 mod\_401 mod\_43 mod\_458 mod\_486 mod\_53 mod\_81

mod\_123 mod\_151 mod\_18 mod\_207 mod\_235 mod\_263 mod\_291 mod\_319  
mod\_347 mod\_375 mod\_402 mod\_430 mod\_459 mod\_487 mod\_54 mod\_82

```
root@MM4 /proc/driver/pl4_diag/port_0 # cd mlc_0
```

```
root@MM4 /proc/driver/pl4_diag/port_0/mlc_0 # ls
```

```
created dynamic generic static various
```

```
root@MM4 /proc/driver/pl4_diag/port_0/mlc_0 # cat dynamic
```

```
PDA2
```

```
0000root@MM4 /proc/driver/pl4_diag/port_0/mlc_0 # cat created
```

```
PDA2
```

```
0000root@MM4 /proc/driver/pl4_diag/port_0/mlc_0 # cat generic
```

```
gd_proc generic
```

```
port 0 type 2 num 0
```

```
root@MM4 /proc/driver/pl4_diag/port_0/mlc_0 #
```



### 3.3.5 Flow Chart for Diagnostic Database

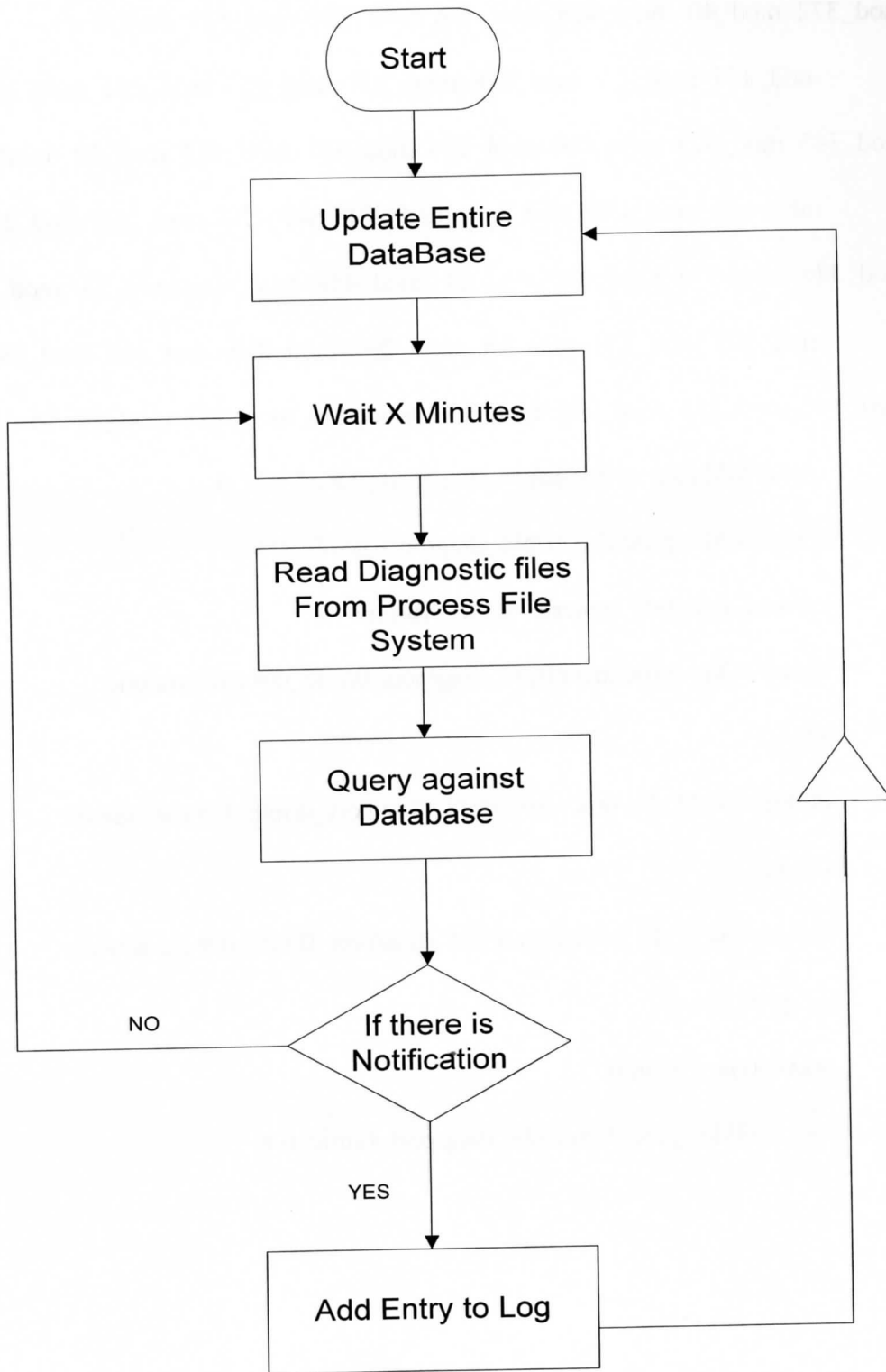


Figure 11: Flow Chart for Diagnostic Database

## CHAPTER 4

### SYSTEM DESIGN & RESULTS

#### 4.1 M4 Notify Log Messages

##### Abstract

The M4 notification log system is handled by the Notify application which uses the CNotifyLog class to create, manage, and query an in memory SQLite database.

##### 4.1.1 Notify Application

Notify, the application used to manage this system, creates an SQLite database as shown by Figure 13. This database can be created on a disk using the “-f” switch. I will create an SQLite database named “notifyetd.db”, i.e. notify extended database. If the “-f” switch is not specified the database name is “:memory:” which SQLite interprets as being in memory, i.e. it lasts only as long as the Notify application is running.

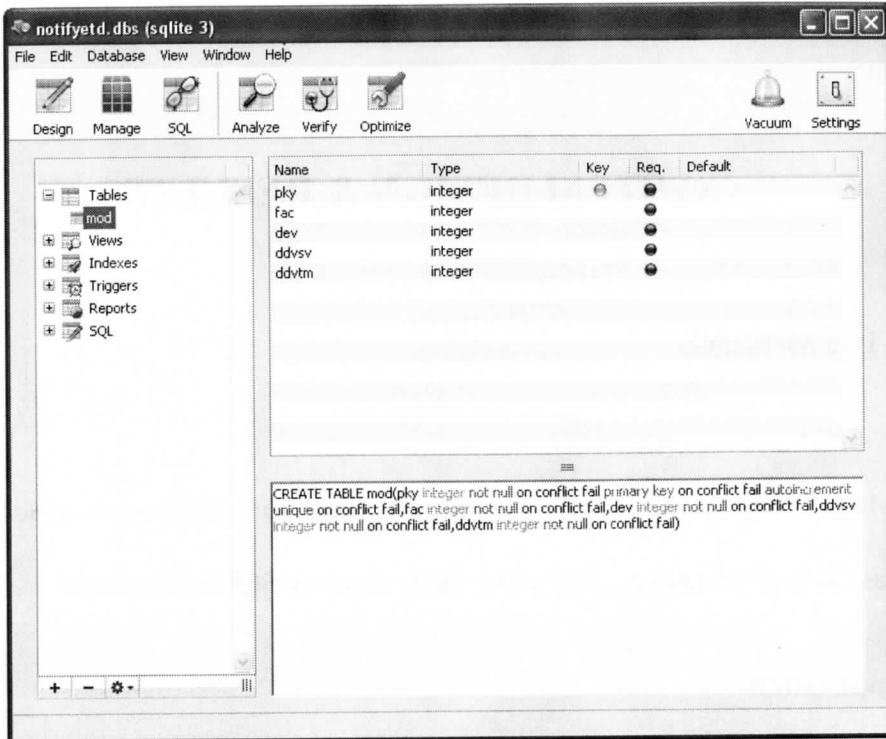


Figure 12: Screen Shot of sample SQLite Database in windows

#### 4.1.2 NotifyLog Class

The CNotifyLog class builds the SQL table as shown in Figure 2. This class creates the table and populates it with the fixed data consisting of the following fields:

- pky - Primary Key (automatically generated)
- fac – Facility Code (defined in Table 1)
- dev – MOD Device (defined as Port times 1000 plus MOD index)

Variable data fields include the following:

- ddvsv – Diagnostics Data Violation Severity (severity is defined in Table 2 and follows the syslog convention)
- ddvtm – Unix Based Time Stamp When ddvsv Detected

Fixed field data is generated by the class logic which attempts to do an fopen on a file given by the following path:

- /proc/driver/pl4\_diag/port\_i/mod\_j/static (for embedded Linux where i is the port number from 0 to 4 and j is the mod index from 0 to 1000)
- C:\proc\driver\pl4\_diag\port\_i\mod\_j\static (for embedded Linux where i is the port number from 0 to 4 and j is the mod index from 0 to 1000)
- /home/nkota//proc/driver/pl4\_diag/port\_i/mod\_j/static (for Ubuntu Linux where i is the port number from 0 to 4 and j is the mod index from 0 to 1000)

#### 4.1.2 NotifyLog Class

pky	fac	dev	ddvsv	ddytm
1	2	0	-1	0
2	2	1	-1	0
3	2	2	-1	0
4	2	3	-1	0
5	2	4	-1	0
6	2	5	-1	0
7	2	6	-1	0
8	2	7	-1	0
9	2	8	-1	0
10	2	9	-1	0
11	2	10	-1	0
12	2	1000	-1	0
13	2	1001	-1	0
14	2	1002	-1	0
15	2	1003	-1	0
16	2	1004	-1	0
17	2	1005	-1	0
18	2	1006	-1	0
19	2	1007	-1	0
20	2	1008	-1	0
21	2	1009	-1	0
22	2	1010	-1	0

22 record(s) (Query time: 0.032 secs)

Figure 13: Screen Shot of MOD Table

<b>Facility</b>	<b>System</b>	<b>Description</b>
0	SYS	System
1	CAN	CAN Sensors
2	DSP	Display
3	ETH	Ethernet

Table 1: Facility Codes

<b>Severity Level</b>	<b>Keyword</b>	<b>Description</b>
0	emergencies	System Unusable
1	alerts	Immediate Action Required
2	critical (high)	Critical Conditions
3	errors (medium)	Error Conditions
4	warnings (low)	Warning Conditions
5	notifications	Normal But Significant Conditions
6	informational	Informational Messages
7	debugging	Debugging Messages

Table 2: Severity Codes

### 4.1.3 Notification XML

#### M4 Notify Log Messages

```
<notify-log-msg>
```

```
  <facility>CAN</facility>
```

```
  <severity>High</severity>
```

```
  <date>2008-09-03</date>
```

```
  <time>15:59:05</time>
```

```
  <zone>-300</zone>
```

```
  <dev>CAN Light Sensor</dev>
```

```
  <msg>Problem Communication</msg>
```

```
</notify-log-msg>
```

```
<notify-log-msg>
```

```
  <facility>DSP</facility>
```

```
  <severity>Medium</severity>
```

```
  <date>2008-09-03</date>
```

```
  <time>15:59:05</time>
```

```
  <zone>-300</zone>
```

```
  <dev>MOD 0</dev>
```

```
  <msg>Problem Module Diagnostics Data Violation</msg>
```

```
</notify-log-msg>
```

## 4.2 Screen Shots of Project implementation

### 4.2.1 The Diagnostic Manager Project built Screen Shot

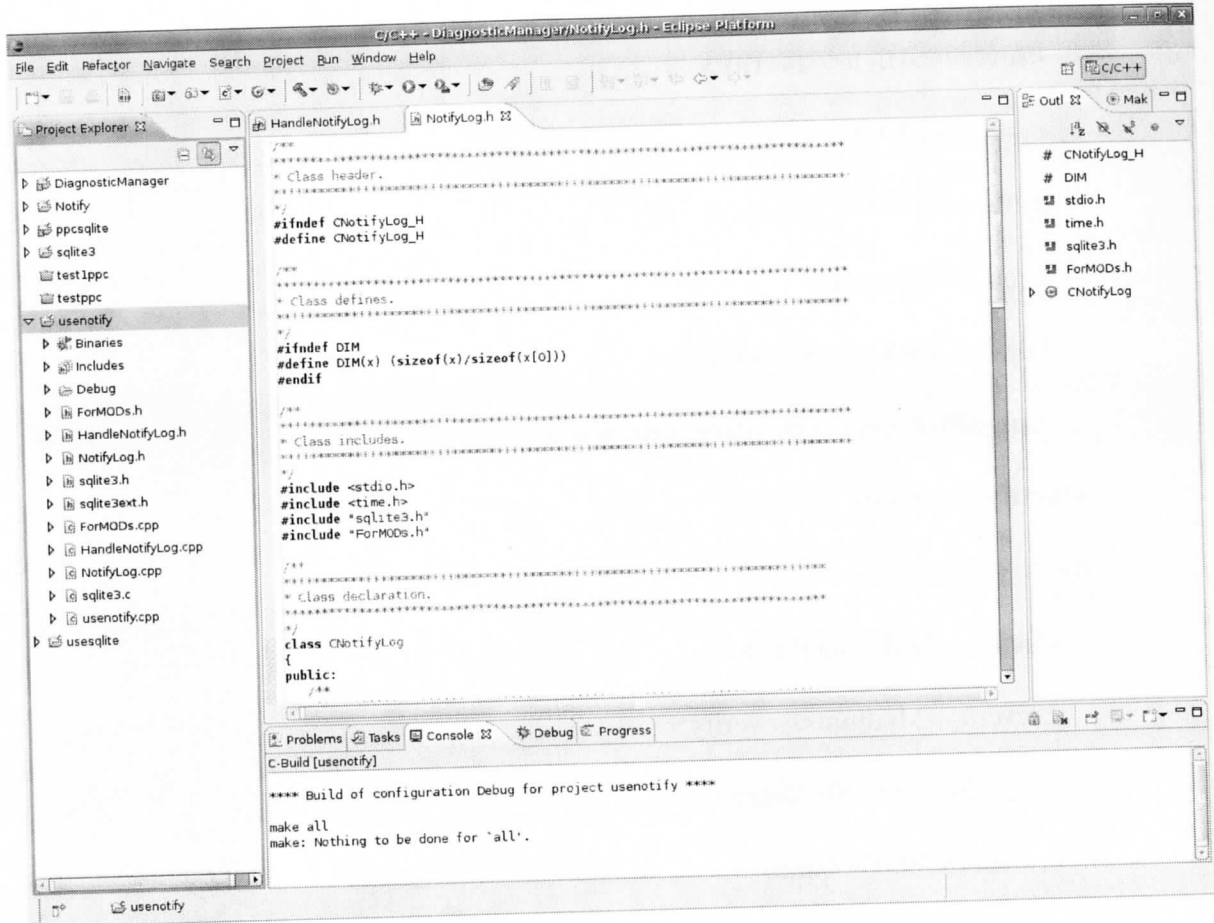


Figure 14: Screen Shot of Diagnostic Manager Project built Screen Shot

## 4.2.2 The Output of Diagnostic Manager Project

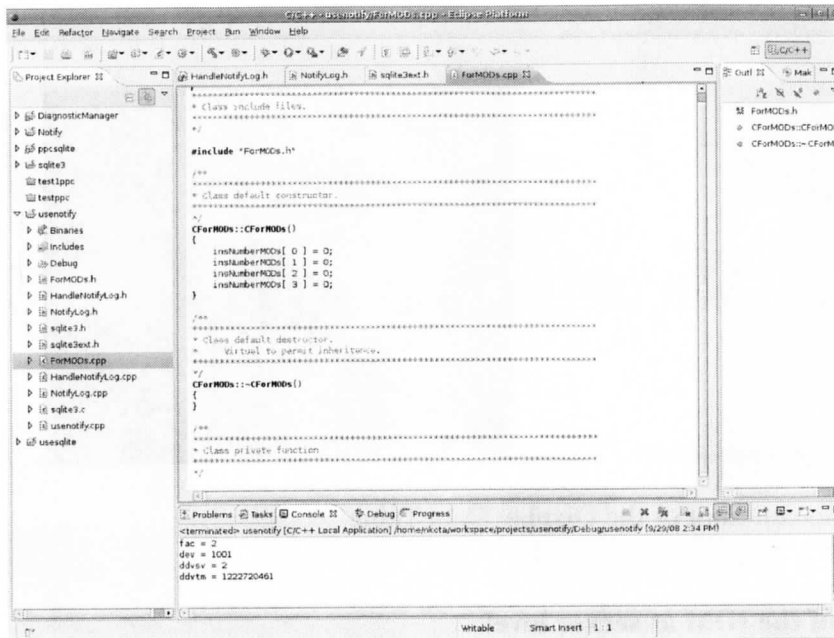
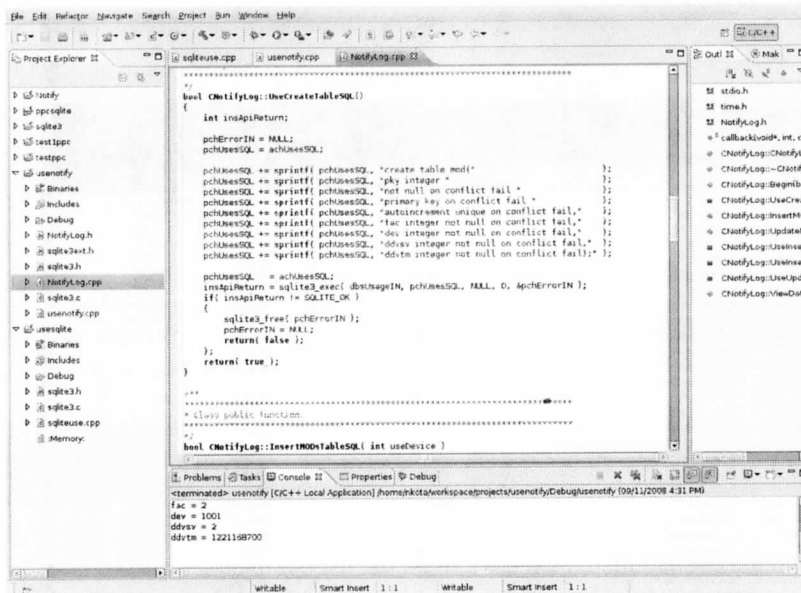


Figure 15: Screen shot of output of Diagnostic Manager Project





### 4.2.3 Screen Shot of the Display Data Telnet

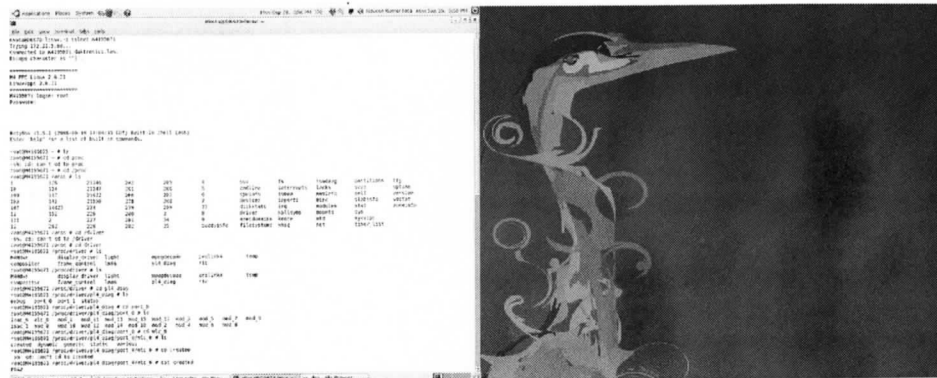


Figure 16: Screen Shot of the Display Data Telnet

### 4.2.4 Screen Shot of the IDM at server level

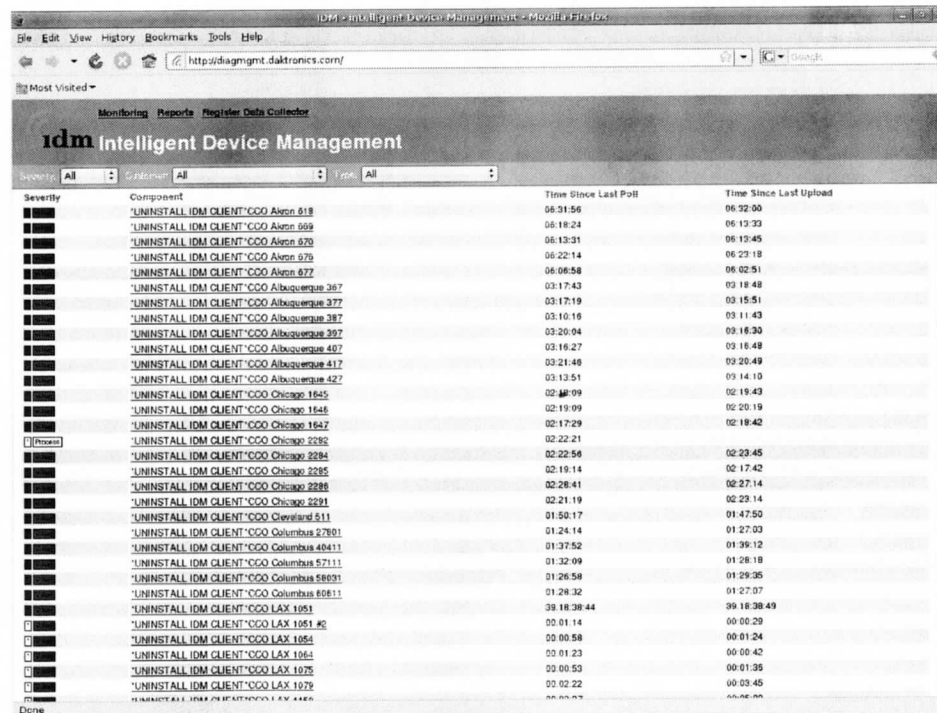


Figure 17: Screen Shot of the IDM at server level

## 4.2.5 Screen Shot of the System Details

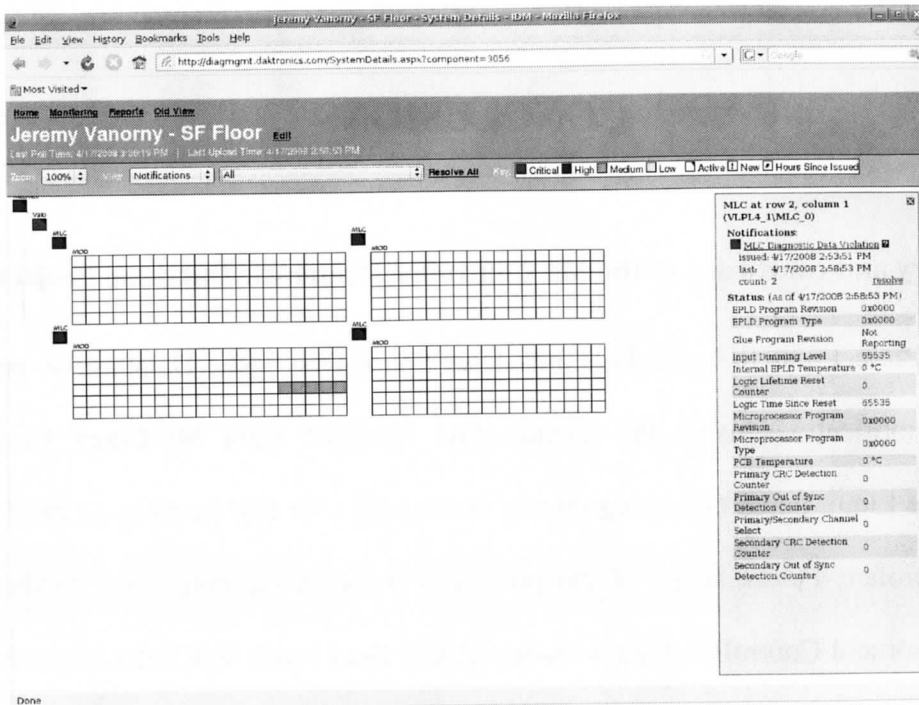


Figure 18: Screen Shot of System Details

## 4.2.6 Screen Shot of the Reports

Component	Type	Notification	Started	Customer	Family
JEREMY TEST	ValsPlay ProLink4	Missed scheduled Poll and Upload	12/28/2007 11:37:21 AM	Daktronics	Daktronics
JEREMY TEST	V-Link 1500 DVI ProLink4	Missed scheduled Poll and Upload	1/8/2008 8:42:49 AM	Daktronics	Daktronics
TEST CONTROLLER	ValsPlay ProLink4	Missed scheduled Poll and Upload	2/15/2008 2:32:21 PM	Daktronics	Daktronics
YPE_QA_VALOPLAY	ValsPlay VMAX4	Missed scheduled Poll and Upload	2/25/2008 1:02:00 PM	Daktronics	Daktronics
Swanton Three	ValsPlay VMAX4	Missed scheduled Poll and Upload	2/26/2008 8:37:29 AM	Daktronics	Daktronics
Fuekas Test Plant	V-Net 4	Missed scheduled Poll and Upload	2/24/2008 12:27:01 PM	Daktronics	Daktronics
Swanton 3	ValsPlay VMAX4	Missed scheduled Poll and Upload	3/5/2008 3:47:01 PM	Daktronics	Daktronics
YPE_QA_VALOPLAY_PL4	ValsPlay ProLink4	Missed scheduled Poll and Upload	3/8/2008 1:22:00 PM	Daktronics	Daktronics
PT A&E	V-Net 4	Missed scheduled Poll and Upload	3/18/2008 9:37:21 AM	Daktronics	Daktronics
Swanton One	ValsPlay VMAX4	Missed scheduled Poll and Upload	3/28/2008 7:47:51 AM	Daktronics	Daktronics
Swanton 2	ValsPlay VMAX4	Missed scheduled Poll and Upload	3/31/2008 2:42:51 PM	Daktronics	Daktronics
Yab Testbed	ValsPlay VMAX4	Missed scheduled Poll and Upload	4/1/2008 11:41:11 AM	Daktronics	Daktronics
MINITEMAIDLVI-S102-01-1	Sony FWD-56PX2	Missed scheduled Poll and Upload	4/7/2008 2:17:01 PM	Minute Maid Park	Media Network
MINITEMAIDLVI-S112-01-3	Sony FWD-56PX2	Missed scheduled Poll and Upload	4/7/2008 2:17:01 PM	Minute Maid Park	Media Network
MINITEMAIDLVI-S120-01-4	Sony FWD-56PX2	Missed scheduled Poll and Upload	4/7/2008 2:17:01 PM	Minute Maid Park	Media Network
MINITEMAIDLVI-S118-02-5	Sony FWD-56PX2	Missed scheduled Poll and Upload	4/7/2008 2:17:01 PM	Minute Maid Park	Media Network
MINITEMAIDLVI-S118-02-6	Sony FWD-56PX2	Missed scheduled Poll and Upload	4/7/2008 2:17:01 PM	Minute Maid Park	Media Network
MINITEMAIDLVI-S118-01-10	Sony FWD-56PX2	Missed scheduled Poll and Upload	4/7/2008 2:17:01 PM	Minute Maid Park	Media Network
MINITEMAIDLVI-S118-01-2	Sony FWD-56PX2	Missed scheduled Poll and Upload	4/7/2008 2:17:01 PM	Minute Maid Park	Media Network
MINITEMAIDLVI-S118-26-7	Sony FWD-56PX2	Missed scheduled Poll and Upload	4/7/2008 2:17:01 PM	Minute Maid Park	Media Network
MINITEMAIDLVI-S118-06-8	Sony FWD-56PX2	Missed scheduled Poll and Upload	4/7/2008 2:17:01 PM	Minute Maid Park	Media Network
MINITEMAIDLVI-S120-06-9	Sony FWD-56PX2	Missed scheduled Poll and Upload	4/7/2008 2:17:01 PM	Minute Maid Park	Media Network

Figure 19: Screen Shot of the Reports



## CHAPTER 5

### CONCLUSIONS

#### 5.0 Summary and conclusion of the M4 Controller Diagnostic Database Project

The Project was to build the Linux-User Space Diagnostic Database to generate the Diagnostic notifications using the display data provided from M4-Linux Kernel space. Ubuntu is the Linux-based Operating system used along with SQLite to build the database on the M4 controller. Future scope of the project is to build the diagnostic database for the display, Sensor and Controller Area Network (CAN) Data which will deliver the notification to Daktronics technicians from the Database which is built on the M4 controller.

This project combines the current technologies and the various knowledge that are learned from the Dakota State University, Master of Science Information Systems degree courses, to successfully produce this M4 Controller diagnostic database with good quality and at low cost. From the project management point of view, this project has delivered the required functionalities, very well met the budget (especially its very low developing cost) and delivered the M4 Controller Diagnostic database on time.

Therefore, this diagnostic project is a successful project because of the excellent performance-over-cost ratio that the project achieved, and the on-time completion of the project.

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## APPENDICES

### APPENDIX A: Users' manual

Code redacted for privacy.