## Simulation Approach for Localizing Roots of Real Coefficients Complex Equation

Sasa Dimitrijevic, Bratislav Dankovic, and Dragan Antic

This paper presents a new approach for solving real coefficients complex equation based on simulation. The procedure is used for n-th order complex equation, in the form:

$$f(z) = a_n z^n + a_{n-1} z^{n-1} + \Lambda + a_1 z^1 + a_0 \tag{1}$$

where  $a_i$ ,  $i = 1, \Lambda$ , n are real coefficients, n is equation order and z = x + iy is a complex variable. The technique relates solving complex equation:

$$f(x+iy) = 0 (2)$$

what can be written in the form:

$$Re\{f(x+iy) = 0\} + iIm\{f(x+iy) = 0\} = 0$$
(3)

The condition (3) is fulfilled if both absolute values of real and imaginary part are equal to zero:

$$|Re\{f(x+iy)\}| + |Im\{f(x+iy)\}| = 0$$
 (4)

Considering that this approach is used for localization of equation (1) roots, equation (4) model will be:

$$\varepsilon = \min_{x,y} |Re\{f(x+iy)\}| + |Im\{f(x+iy)\}|$$
 (5)

The x, y values which correspond to minimum will be the roots of equation (1).

Simulation is conducted using block diagram simulation languages (SIMULINK, etc.) where x = time and as a result of simulation value  $\varepsilon$  for  $y = y_0 = const$  is obtained.

$$\varepsilon = \min_{y} \min_{x} | Re\{f(x+iy)\}| + | Im\{f(x+iy)\}|$$
 (6)

Repeated simulations for different values of  $y=y_0=const$  are performed using MATLAB programming. When the desired accuracy is accomplished, the obtained values  $x=x_0,y=y_0$ , will represent one of the equation (1) roots. The procedure is then repeated for different values y=y. In that manner, all other roots can be localized.

## References

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- [3] Kuo F. F. ed., Computer Simulation of Dynamic Systems, Prentice-Hall, New Jersey, 1972.