

Spherical Linkages Analysis and Synthesis by Special Unitary Matrices for Solution via Numerical Algebraic Geometry

Introduction

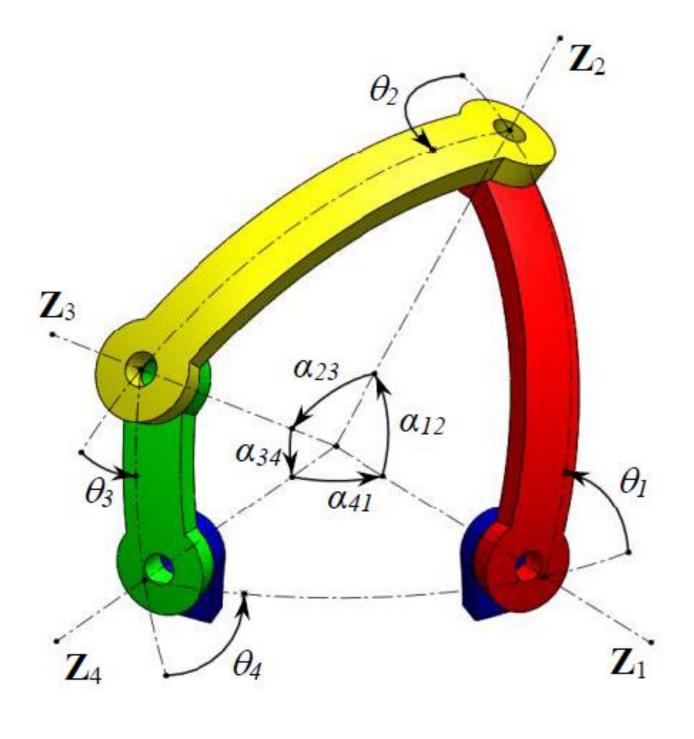
This research seeks to develop methods to solve analysis and synthesis problems for spherical linkages. Spherical linkages meet a variety of common needs in mechanical engineering practice. However, due to the intense mathematics associated with their design, these linkages have received little attention in literature when compared to planar linkages.

Method

The method used in this research exploits the structure of the special unitary matrices SU(2) in forming a system of equations that govern the behavior of spherical mechanisms. Special unitary matrices can be used to represent spatial displacement in an efficient and compact form that is suited to employ the tools of numerical algebraic geometry. The general form for an element of SU(2) to describe a rotation about an angle ϕ and s-axis of rotation is given as

$$Q(\mathbf{s}, \phi) = \begin{bmatrix} \cos\frac{\phi}{2} + is_z \sin\frac{\phi}{2} & s_y \sin\frac{\phi}{2} - is_x \sin\frac{\phi}{2} \\ -s_y \sin\frac{\phi}{2} - is_x \sin\frac{\phi}{2} & \cos\frac{\phi}{2} - is_z \sin\frac{\phi}{2} \end{bmatrix}$$

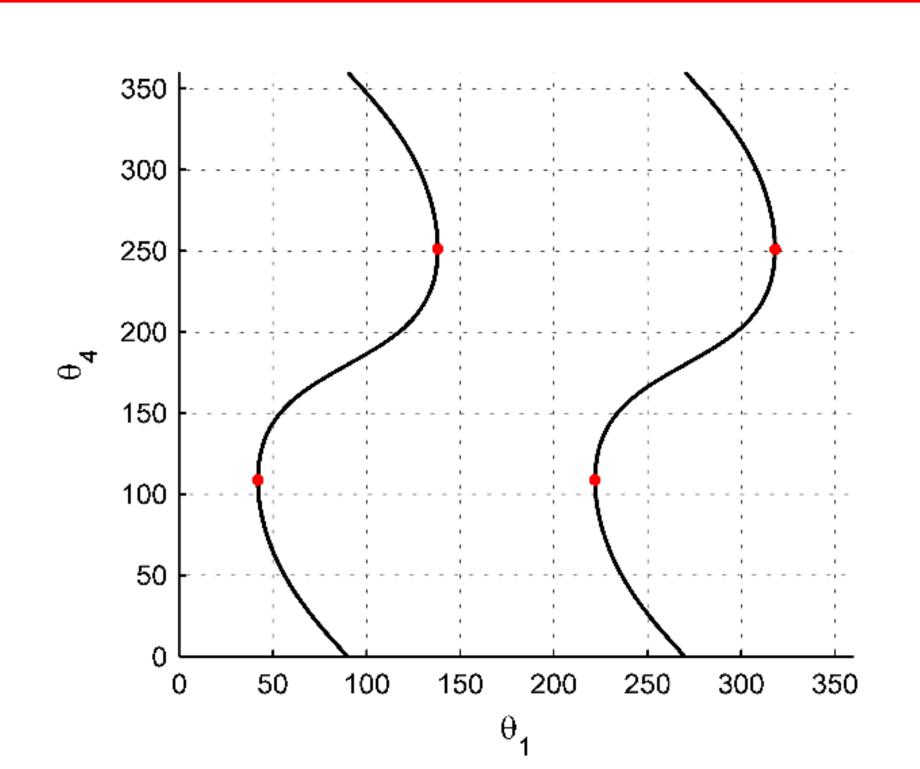
Spherical four-bar



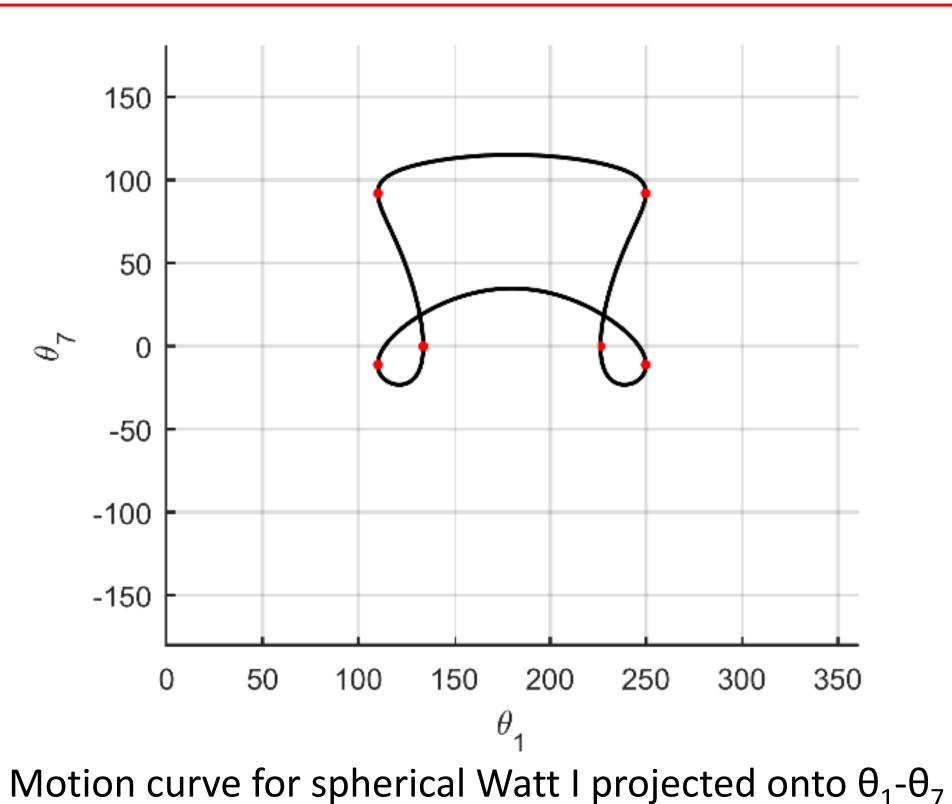
Spherical four-bar linkage schematic diagram

Spherical Watt I Spherical Watt I linkage schematic diagram

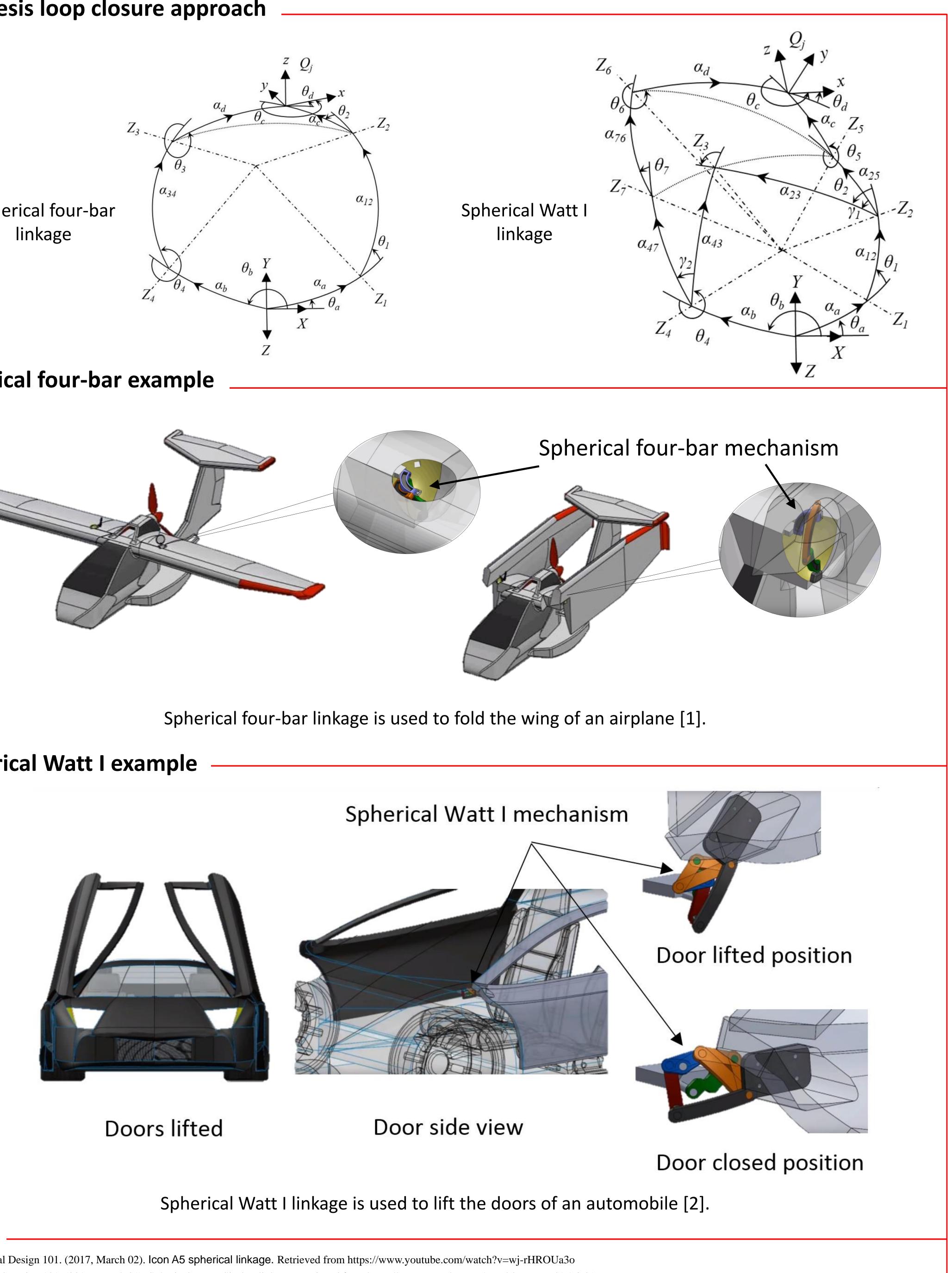
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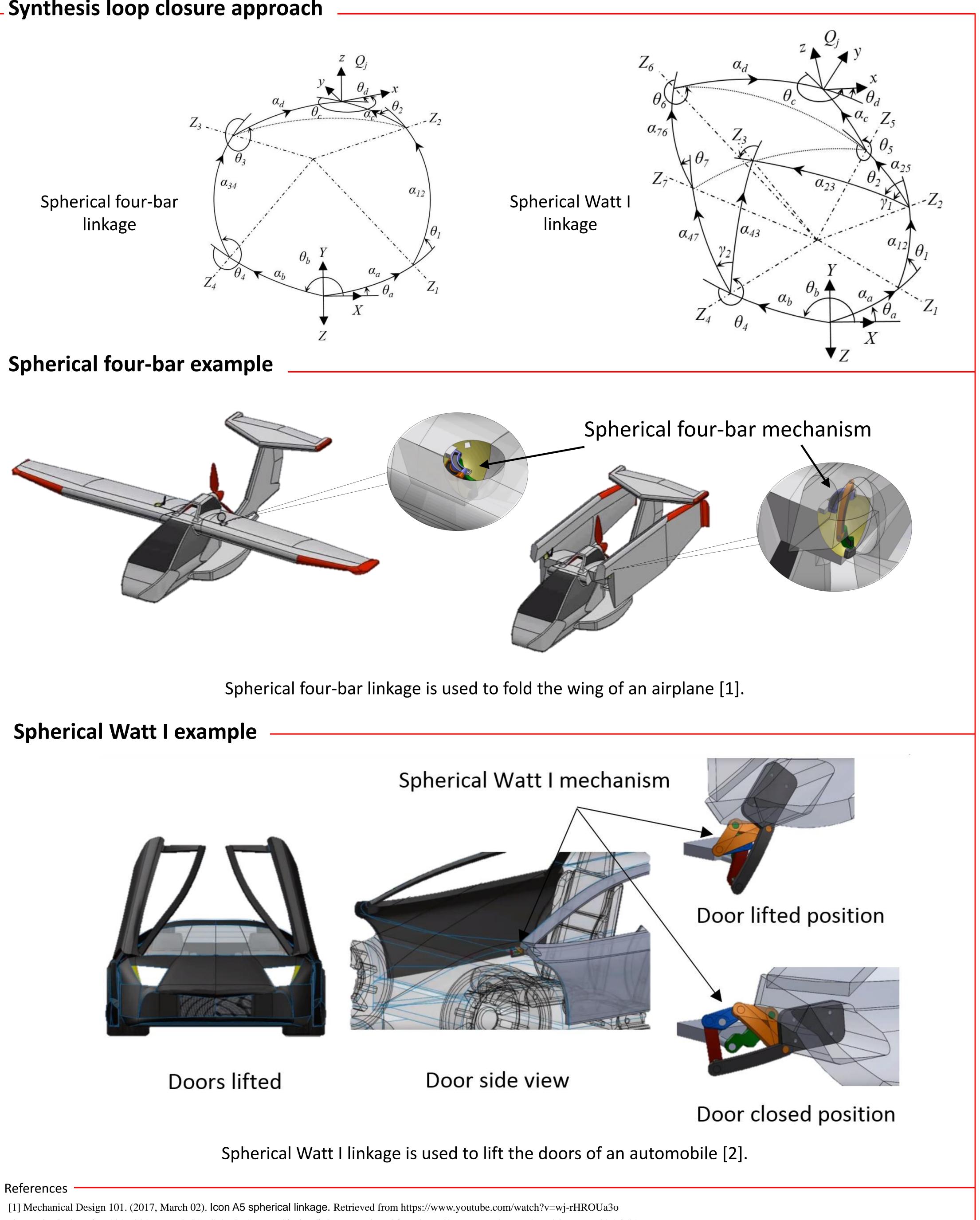




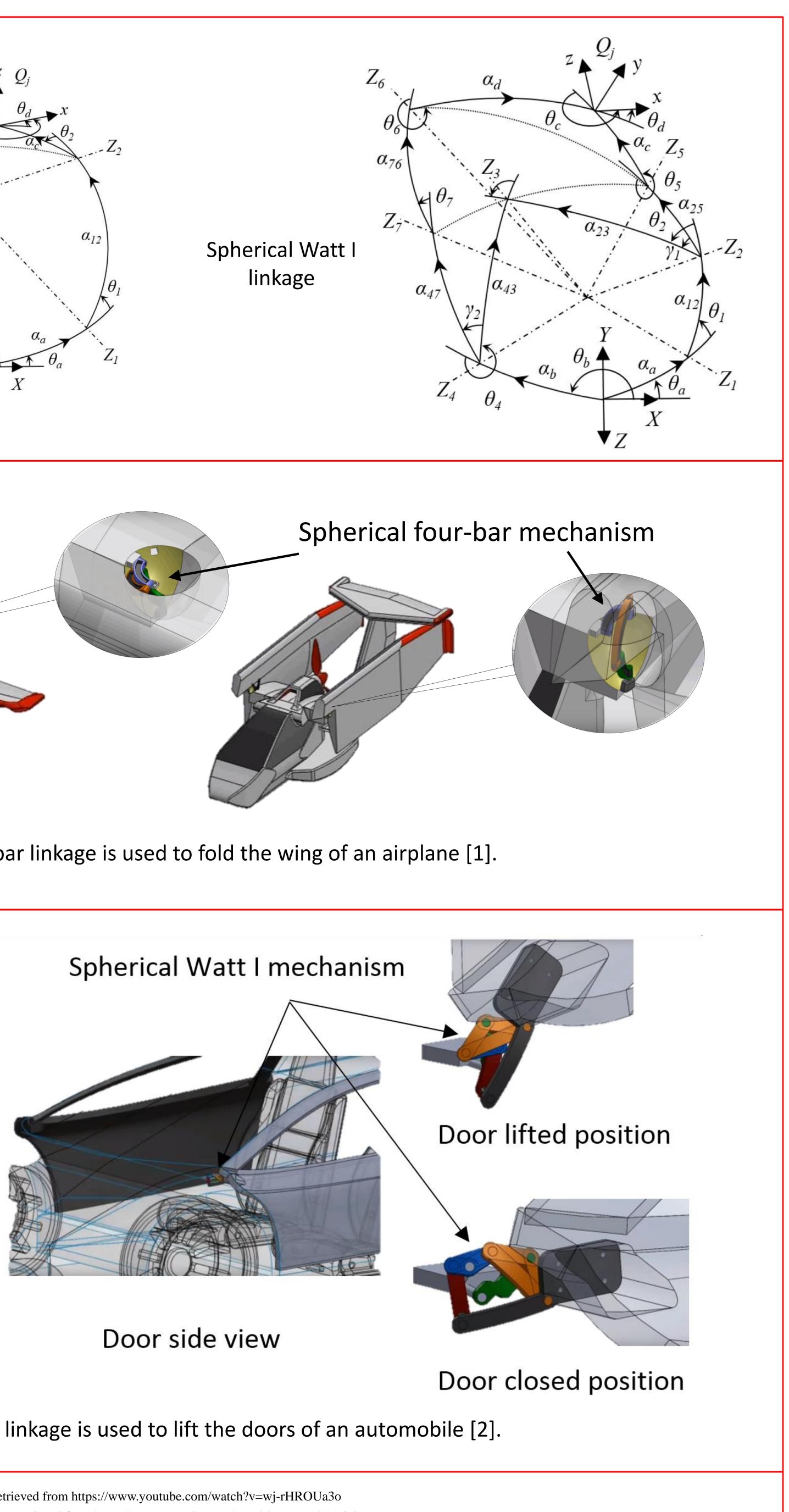


Synthesis loop closure approach









[2] Mechanical Design 101. (2017, March 01). Spherical Watt I Six-bar linkage. Retrieved from https://www.youtube.com/watch?v=N7nDlAAOd5U

