Efficacy of Assistive Devices Produced with Additive Manufacturing

James Pierce M.S.¹, Drew Dudley¹, David Salazar¹, Keaton Young¹, Christopher Copeland¹, Claudia Cortes-Reyes¹, Walker Arce^{1,2}, Jean Peck OTL, CHT³, Jorge Zuniga Ph.D.¹ ¹Department of Biomechanics, University of Omaha, NE, USA ²Department of Electrical Engineering, University of Omaha, NE, USA ³CHI Health Creighton University Medical Center, Omaha 68131, NE, USA

ABSTRACT

Additive manufacturing grants the possibility to produce inexpensive, custom assistive devices. The primary objective of this research was to develop a highly flexible, parametrically-defined assistive device design which has the potential to reduce expert intervention in the fitting of devices, and would allow for fast and easy creation of assistive devices in the treatment of injury. We propose a central hypothesis that these customized assistive devices will produce similar or enhanced function when compared to traditional solutions.

Knowledge gained from this study will validate novel assistive devices which could be used in the treatment of musculoskeletal injury for astronauts' both during spaceflight and after return to Earth. These novel solutions will require less expert intervention and less on-site modifications for fitting.

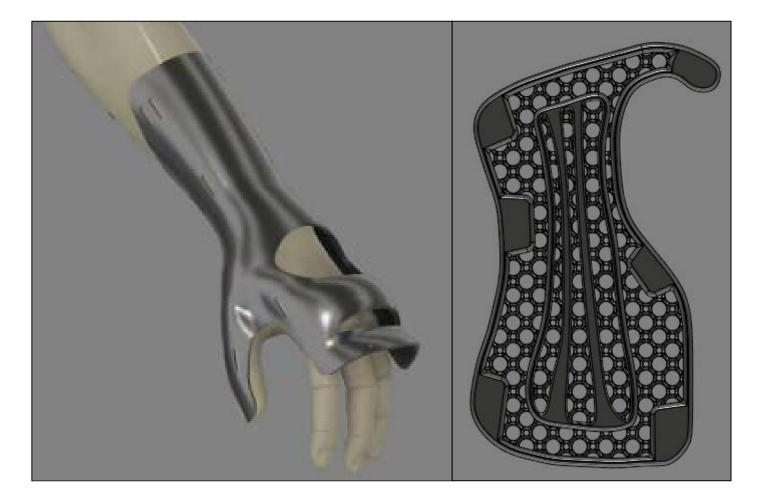
Gross manual dexterity was evaluated using a standardized functional task, while satisfaction with the device was assessed via survey.

Obtained results indicate no functional difference in gross manual dexterity between types of wrist orthosis. The custom design scored better with regard to comfort, donning/doffing, and aesthetic appearance.

INTRODUCTION

Despite the frequency of musculoskeletal injuries such as sprains, broken bones and torn ligaments, [1] treatment options are often costly, time-consuming and illfitted. [2,3] Additive manufacturing ("3D-printing") allows for the production of highlycustomized and inexpensive assistive devices, [4] which suggests potential efficacy in the prescription of splints and casts for musculoskeletal injury. [3]

Emerging studies reference the fact that additive manufacturing can produce clinical improvements in rehabilitation that are similar to traditional methods. [2] It has also been documented that the time required to produce these types of devices is significantly faster and lower cost than traditional methods. [3] To date, no studies have produced a parametric assistive device using additive manufacturing. There exists an opportunity to enhance the function and production speed of these innovative devices through the application of parametric, anthropometric-driven part design. Through this new method, the possibility exists to improve recovery time from injury, decrease risk of further injury, and better utilize materials and time.



The University of Nebraska at Omaha shall not discriminate based upon age, race, ethnicity, color, national origin, gender-identity, sex, pregnancy, disability, sexual orientation, genetic information, veteran's status, marital status, religion, or political affiliation.

Figure 1: A) 3D model of a parametrically-defined hand exoskeleton design, scaled to fit a participant in CAD before part production. B) 3D model of a wrist orthosis, which is printed flat and thermoformed to the contours of the users' upperlimb.



METHODS

Recruitment: A single subject was used to produce the pilot data for this research study (male, age = 26 years).

Device Design: Design of the assistive devices was performed using a computer-aided design (CAD) program (Autodesk Fusion 360, Autodesk, San Rafael, CA, USA). All devices incorporated fully parametric definition; this allowed for morphological device changes to match the anthropometric measurements of participants before part fabrication.

Device Functionality Assessment: To assess the efficacy of the produced orthoses, performance quality during a standard functional task was collected using a contemporary, over-the-counter wrist splint as well as the additively manufactured prototype. The test, called the "Box and Block," utilizes a partitioned tray filled with identical blocks. The number of blocks transferred by the user in one minute is used as a measure of gross manual dexterity. Comfort, ease of donning/doffing and aesthetic appearance were also considered as factors in the efficacy of the device.

MATERIALS

The low-cost 3D printers used in this study were the Ultimaker 2 Extended+ (Ultimaker B.V., Geldermalsen, The Netherlands). The material for printing the orthoses was polylactic acid (PLA), which was selected for its ease to thermoform. The only other component of the orthoses was Velcro, which was used for strapping the orthoses to users.

All parts were printed at 35%-40% infill (hexagon pattern), 60-100 mm/s print speed, 150-200 mm/s travel speed, 50°C heated bed, 0.15-.25 mm layer height, and 0.8mm shell thickness. No rafts or supports were necessary, as the orthoses were printed flat and then thermoformed to users' limbs.

The "Box and Block" was performed using a small, partitioned box filled with 120 identical blocks.



Figure 3: A) Unformed wrist splint; B) A 3D printed wrist splint, thermoformed to fit the user.

