

1 **Testing the assumptions underlying ocean mixing methodologies using**
2 **direct numerical simulations**

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ABSTRACT

18 Direct numerical simulations of stratified turbulence are used to test several
19 fundamental assumptions involved in the Osborn, Osborn-Cox, and Thorpe
20 methods commonly used to estimate the turbulent diffusivity from field mea-
21 surements. The forced simulations in an idealized triply periodic computa-
22 tional domain exhibit characteristic features of stratified turbulence includ-
23 ing intermittency and layer formation. When calculated using the volume-
24 averaged dissipation rates from the simulations, the vertical diffusivities in-
25 ferred from the Osborn and Osborn-Cox methods are within 40% of the value
26 diagnosed using the volume-averaged buoyancy flux for all cases, while the
27 Thorpe scale method performs similarly well in the simulation with a rela-
28 tively large buoyancy Reynolds number ($Re_b \simeq 240$) but significantly overes-
29 timates the vertical diffusivity in simulations with $Re_b < 60$. The methods are
30 also tested using a limited number of vertical profiles randomly selected from
31 the computational volume. The Osborn, Osborn-Cox and Thorpe scale meth-
32 ods converge to their respective estimates based on volume-averaged statis-
33 tics faster than the vertical diffusivity calculated directly from the buoyancy
34 flux which is contaminated with reversible contributions from internal waves.
35 When applied to a small number of vertical profiles, several assumptions un-
36 derlying the Osborn and Osborn-Cox methods are not well-supported by the
37 simulation data. However, the vertical diffusivity inferred from these methods
38 compares reasonably well to the exact value from the simulations and out-
39 performs the assumptions underlying these methods in terms of the relative
40 error. Motivated by a recent theoretical development, it is speculated that the
41 Osborn method might provide a reasonable approximation to the diffusivity
42 associated with the *irreversible* buoyancy flux.

43 1. Introduction

44 Small-scale turbulence, defined here as three-dimensional overturning motions, plays an impor-
45 tant role in setting the large-scale properties and circulation of the ocean. Turbulence influences
46 the depth of the surface and bottom mixed layers by entraining stratified water into the mixed
47 layer (e.g. Large et al. (1994); Pacanowski and Philander (1981)) thereby influencing biological
48 productivity and the exchanges of heat and carbon between the atmosphere and ocean (Marra et al.
49 1990). On long timescales, turbulence gradually mixes distinct water masses in the ocean interior,
50 thereby influencing the pathways of the global overturning circulation (Wunsch and Ferrari 2004;
51 Marshall and Speer 2012).

52 Here we use the term ‘mixing’ to refer to the irreversible homogenization of a scalar quantity.
53 This stands in contrast to ‘stirring’ which refers to the down-scale transfer of scalar variance and
54 the generation of structures such as filaments by turbulent motions. Mixing relies on molecular
55 diffusion of the scalar substance (e.g. heat or salt) which occurs at very small scales, while stirring
56 is inevitably associated with larger scales. For a statistically homogeneous turbulent flow, mixing
57 occurs at scales close to the Batchelor scale, $l_B = l_K / \sqrt{Pr}$ where $l_K = (\nu^3 / \epsilon)^{1/4}$ is the Kolmogorov
58 scale, $Pr = \nu / \kappa_m$ is the Prandtl (or Schmidt) number, ν is the kinematic viscosity of the fluid, κ_m
59 is the molecular scalar diffusivity, and ϵ is the dissipation rate of kinetic energy. For typical
60 open ocean conditions where $\epsilon \simeq 10^{-10} - 10^{-6} \text{m}^2/\text{s}^3$, the corresponding Kolmogorov scale is
61 $l_K \simeq 1 \text{mm} - 1 \text{cm}$ and the thermal Batchelor scale is $l_B \simeq 0.3 - 3 \text{mm}$ while the haline Batchelor
62 scale is an order of magnitude smaller. The very small scales involved make it difficult, if not
63 impossible, currently to resolve scalar mixing in measurements or models.

64 Due to the difficulty associated with resolving the small scales involved in scalar mixing, ob-
65 servational methods generally involve calculating various proxies for mixing. A near-universal

66 assumption in the ocean mixing literature is that an ensemble of turbulent motions can be mod-
67 elled through a turbulent diffusivity, defined as the ensemble-averaged scalar flux (in a particular
68 coordinate direction) divided by the ensemble-averaged gradient (in an independently chosen di-
69 rection). Although the turbulent diffusivity is a second rank tensor, our focus here will be on the
70 vertical component, which we define as

$$\kappa \equiv \frac{-\langle w'c' \rangle}{\partial \langle c \rangle / \partial z}, \quad (1)$$

71 where w is the vertical velocity, c is a scalar quantity, angle brackets indicate an unspecified averag-
72 ing operator assumed to be equivalent to ensemble-averaging, and primes denote departures from
73 this average. Note that in some contexts (e.g. at fronts or in isopycnal coordinate ocean models)
74 the diapycnal diffusivity might be more appropriate than the vertical diffusivity. In the simulations
75 that will be analyzed here, the large-scale buoyancy gradient is aligned with the vertical direction,
76 and hence the vertical and diapycnal diffusivities are equivalent by construction.

77 Indeed, estimating κ is one of the central aims of the ocean mixing community. Perhaps the
78 most direct approach is to measure the vertical turbulent scalar flux $\langle w'c' \rangle$ through simultaneous
79 measurements of the vertical velocity and scalar concentration. While this method is in princi-
80 ple possible (e.g. Moum (1996)), it can be extremely difficult to measure the vertical velocity
81 accurately, and the correlation between the velocity and scalar concentration introduces another
82 possible source of error. In addition, as we will see later, internal waves can induce a significant
83 *reversible* contribution to the turbulent scalar flux and removing these contributions can be very
84 difficult.

85 Other indirect methods of measuring the turbulent diffusivity necessarily rely on assumptions
86 about the nature of small-scale turbulence. Indirect methods can be arranged in two categories:
87 ‘finescale’ methods and ‘microstructure’ methods, each based around different assumptions. Sev-

88 eral finescale methods rely on the assumption that small-scale turbulence in the ocean interior is
89 forced by the ambient internal wave field. These methods then link the mixing via small-scale
90 turbulence with the properties of the internal wave field (e.g. Henyey et al. (1986); Gregg (1989a);
91 Polzin et al. (1995); MacKinnon and Gregg (2003)).

92 Rather than relying on measurements of internal waves, microstructure methods use measure-
93 ments of small-scale turbulence to infer the turbulent diffusivity. Two prominent microstructure
94 methods are the Osborn-Cox method (Osborn and Cox 1972), which uses measurements of tem-
95 perature or salinity variance and infers the scalar variance dissipation rate and diffusivity; and
96 the Osborn method (Osborn 1980), which relates measurements of shear to the turbulent dissi-
97 pation rate, and hence to the diffusivity. Gregg et al. (2018) provide a review and discussion of
98 microstructure methods and their underlying assumptions.

99 An additional method for inferring the rate of mixing is the Thorpe-scale method. This method
100 is perhaps best classified as intermediate between finescale and microstruture methods as it uses
101 measurements of the scalar fields to infer the size of the largest turbulent motions. In this method
102 unstable ‘overturns’ in a measured temperature, salinity, or density profile are first related to the
103 dissipation rate and then to the turbulent diffusivity following the Osborn method (Osborn 1980).
104 These methods and their underlying assumptions will be described in more detail in Section 3c
105 below.

106 The primary objective of this paper is to evaluate microstructure and Thorpe-scale methods using
107 output from direct numerical simulations (DNS) of forced stratified turbulence. By definition
108 a DNS resolves *all* scales of turbulent motion. The simulations here have a molecular Prandtl
109 number $Pr = 7$, a typical value corresponding to the diffusion of heat in seawater. Hence, the
110 resolution of the simulations must be sufficient to capture scales near the Batchelor scale ($\sim 1\text{mm}$
111 in dimensional terms). Our aim is to simulate typical turbulent conditions in the ocean interior.

112 Even with a limited domain size, this makes the simulations extremely computationally expensive
113 - here the simulations exceed 10^{12} gridpoints. The advantage of DNS is that turbulent quantities
114 such as the dissipation rate and scalar flux can be evaluated exactly. This allows us to distinguish
115 between uncertainties associated with measurement techniques from uncertainties associated with
116 the underlying assumptions inherent in each method. Here, our focus is on such assumption-
117 associated uncertainties.

118 The DNS that are analyzed here simulate turbulence in a relatively small ($\sim 5 - 10\text{m}$) three-
119 dimensional domain. Periodic boundary conditions are applied to the velocity in all three direc-
120 tions, while a constant vertical background stratification is imposed. The computational domain
121 can be interpreted as a small region embedded in the ocean interior. The simulations are forced
122 by applying a scale-selective deterministic body force to the momentum equations to energize the
123 large scales of the horizontal velocity. While the forcing term is intended to represent energy in-
124 put from uncaptured large-scale motions, we do not attempt to simulate a particular internal wave
125 spectrum at the large scales. We therefore do not attempt to test any finescale parameterizations
126 and instead focus on microstructure and Thorpe-scale-based methods.

127 Many microstructure measurement techniques involve fitting a canonical spectrum to the mea-
128 sured spectrum obtained from a depth window (Gregg 1999) or spatially averaging over a pre-
129 scribed depth interval (Moum et al. 1995) or an identified turbulent patch (Moum 1996). This ef-
130 fectively produces one value of dissipation or diffusivity for a given depth interval. Similarly, the
131 Thorpe-scale method requires the calculation of the root-mean-square (*rms*) displacement scale
132 with respect to a finite depth window. In section 3d we will apply the Osborn, Osborn-Cox,
133 and Thorpe-scale methods to quantities calculated from vertical profiles extracted from the DNS,
134 which generically can cover more than one ‘patch’ of turbulence in any single profile.

135 Turbulence in strongly stratified fluids is often highly intermittent in space and time (see e.g.
136 Rorai et al. (2014); Portwood et al. (2016)). This raises the following question: how well can a
137 limited set of observations reproduce the volumetrically-averaged turbulent diffusivity? In section
138 3d, we will also address this question by calculating the turbulent diffusivity with a limited number
139 of vertical profiles extracted from the DNS. This can be interpreted as a best case scenario for
140 observations of turbulent mixing without any measurement errors. In section 4, we discuss our
141 results, and draw some conclusions.

142 **2. Simulation setup and methodology**

143 *a. Governing Equations*

144 The objective of the DNS is to simulate stratified turbulence in a quasi-equilibrated state where
145 the energy input from large-scale forcing is balanced by small-scale dissipation and mixing. Peri-
146 odic boundary conditions are applied in all three spatial directions, the details of which are given
147 below. We do not directly consider the influence of any physical boundary and hence the compu-
148 tational domain can be viewed as a relatively small box embedded within the water column.

149 The simulations solve the non-hydrostatic Boussinesq equations that can be written in non-
150 dimensional form normalized by a characteristic velocity scale, U , length scale, L , and background
151 buoyancy frequency, N_0 . The non-dimensional equations are

$$\nabla \cdot \mathbf{u} = 0 \tag{2a}$$

$$\frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} = - \left(\frac{1}{\text{Fr}} \right)^2 \rho \hat{\mathbf{z}} - \nabla p + \frac{1}{\text{Re}} \nabla^2 \mathbf{u} + \mathcal{F} \tag{2b}$$

$$\frac{\partial b}{\partial t} + \mathbf{u} \cdot \nabla b + w = \frac{1}{\text{RePr}} \nabla^2 b, \tag{2c}$$

154 where the nondimensional parameters are a characteristic Froude number, the Prandtl number and
 155 a characteristic Reynolds number, defined as

$$\text{Fr} \equiv \frac{U}{N_0 L}, \quad \text{Pr} \equiv \frac{\nu}{\kappa_m} \quad \text{and} \quad \text{Re} \equiv \frac{UL}{\nu}.$$

156 Note that the diffusion of the scalar is specified by a characteristic Péclet number $\text{Pe} \equiv UL/\kappa_m =$
 157 RePr . The buoyancy, $b \equiv -g\rho/\rho_0$ can be related to temperature through a linear equation of
 158 state, $b = \alpha g(T - T_0)$ where ρ_0 and T_0 are reference density and temperature and α is the thermal
 159 expansion coefficient. The buoyancy b in Eq. 2c is defined as the departure from an imposed
 160 background gradient such that the total buoyancy is $b_T = b + N_0^2 z$. Periodic boundary conditions
 161 are then applied to b . In effect, this maintains a constant buoyancy difference between the top and
 162 bottom of the computational domain.

163 The periodic boundary conditions that are used here have implications for the flow that can de-
 164 velop. First, the relatively small domain size limits the scale of the motions that we are able to
 165 directly simulate. The body force (\mathcal{F} in Eq. 2b) is meant to mimic the down-scale transfer of
 166 momentum and energy from motions that are larger than our computational domain, albeit in an
 167 idealized way. The periodic boundary conditions applied to the velocity and the departures from
 168 the background stratification imply that the local momentum and buoyancy flux at the top of the
 169 computational domain match the values at the bottom of the computational domain. However,
 170 these fluxes do not need to remain constant within the domain. As a result (and as we will see be-
 171 low), the simulations develop layers with relatively weak and strong stratification and the vertical
 172 shear associated with the horizontally-averaged velocity is non-zero.

173 *b. Numerical methods*

174 Equations (2) are solved in a triply periodic domain with the pseudospectral technique discussed
175 in Almalkie and de Bruyn Kops (2012b). Spatial derivatives are computed in Fourier space, the
176 nonlinear terms are computed in real space, and the solution is advanced in time in Fourier space
177 with the variable-step, third-order, Adams-Bashforth algorithm with pressure projection. The non-
178 linear term in the momentum equation is computed in rotational form, and the advective term in
179 the internal energy equation is computed in conservation and advective forms on alternate time
180 steps. These techniques are standard to ensure conservation of energy and to eliminate most alias-
181 ing errors, but the simulations reported in this paper are fully de-aliased in accordance with the 2/3
182 rule via a spectral cutoff filter.

183 The body force \mathcal{F} in (2) is implemented using the deterministic forcing schema denoted Rf
184 in Rao and de Bruyn Kops (2011). The objective is to force all the simulations to have the same
185 spectra $E_h(\kappa_h, \kappa_z)$ with $\kappa_h < \kappa_f$ and $\kappa_z = 0$. E_h is the power spectrum of the horizontal contribution
186 to kinetic energy averaged over annuli of constant horizontal wave number κ_h and vertical wave
187 number κ_z . The highest wave number forced is $\kappa_f = 16\pi/L_h$, with L_h the horizontal dimension of
188 the numerical domain. Deterministic forcing requires choosing a target spectrum $E_f(\kappa_h < \kappa_f, 0)$.
189 In contrast to turbulence that is isotropic and homogeneous in three dimensions, there are no
190 theoretical model spectra for E_f (c.f. (Overholt and Pope 1998)). Therefore, run 2 from Lindborg
191 (2006) was rerun using a stochastic forcing schema similar to that used by Lindborg and denoted
192 schema Qg in Rao and de Bruyn Kops (2011). The spectrum for $E_h(\kappa_h < \kappa_f, 0)$ was computed
193 from this simulation and used as the target for the simulations reported in the current paper.

194 In addition to forcing the large horizontal scales, 1% of the forcing energy is applied stochas-
195 tically to the horizontal velocity components through wave number modes with $\kappa_h = 0$ and

196 $\kappa_z = 2\pi j/L_v$, $j = 2, 3, 4$. Here L_v is the vertical dimension of the numerical domain. This random
197 forcing induces some vertical shear (Lindborg 2006). There is no forcing of the vertical velocity
198 in the simulations.

199 The extent of the domain in the horizontal and vertical directions are L_h and L_v with L_h/L_v
200 chosen to accommodate the vertical motions that develop in the flow. While the simulation do-
201 mains are not cubes and the vertical extent of the domain varies with the chosen characteristic
202 Froude number, the grid spacing Δ is the same in all directions. It is assumed for the purpose
203 of choosing the resolution of the numerical grid that the flows are approximately isotropic at
204 the smallest length scales in the simulation. Therefore, a three-dimensional grid with spacing
205 $\Delta = L_h/N_x = L_h/N_y = L_v/N_z$ with N_x , N_y , and N_z being the number of grid points in the x , y , and
206 z directions, respectively, is used and any small-scale anisotropy in the flows can be attributed to
207 flow physics rather than to numerical artifacts of an anisotropic grid (c.f. Waite (2011)).

208 *c. Parameters*

209 Three simulations (labeled A, B and C) are analyzed here, and the related non-dimensional pa-
210 rameters are listed in Table 1. In each case the non-dimensional horizontal domain size is 2π .
211 Simulations A and B have the same characteristic Froude number, $Fr = 0.0416$, representing
212 relatively strong stratification. The Reynolds number is larger in Simulation A compared to Simu-
213 lation B. Simulation C has a moderate Reynolds number and a larger characteristic Froude number
214 representing weaker stratification.

215 Equations (2) are time-stepped until a statistically steady state is reached. The simulations can be
216 described using non-dimensional parameters derived using turbulent properties in the final state.
217 For this purpose it is useful to define the turbulent kinetic energy (TKE), $k \equiv \langle \mathbf{u}' \cdot \mathbf{u}' \rangle_V^{1/2} / 2$, and

218 the TKE dissipation rate, $\langle \varepsilon \rangle_V \equiv 2\nu \langle s_{ij}s_{ij} \rangle_V$, where

$$s_{ij} \equiv \frac{1}{2} \left(\frac{\partial u'_i}{\partial x_j} + \frac{\partial u'_j}{\partial x_i} \right) \quad (3)$$

219 is the fluctuating rate of strain tensor, $\langle \cdot \rangle_V$ denotes an average over the full computational volume
 220 and primes denote departures from this volume average. The Reynolds number of the turbulent
 221 flow can then be characterized using the horizontal *rms* velocity, $u_{rms} \equiv \langle \mathbf{u}'_h \cdot \mathbf{u}'_h \rangle_V^{1/2}$ and a char-
 222 acteristic length scale. Two choices for the length scale are the integral length scale, L_h , and the
 223 turbulent length scale, $L_t \equiv \langle k \rangle_V^{3/2} / \langle \varepsilon \rangle_V$, thereby forming two derived Reynolds numbers,

$$Re_h \equiv \frac{u_{rms} L_h}{\nu}, \quad \text{and} \quad Re_t \equiv \frac{u_{rms} L_t}{\nu}. \quad (4)$$

224 Here L_h is computed from the longitudinal horizontal velocity spectra using the method of Comte-
 225 Bellot and Corrsin (1971) (see their Appendix E). Similarly, the relative strength of stratification
 226 can be quantified by two derived Froude numbers,

$$Fr_h \equiv \frac{u_{rms}}{N_0 L_h}, \quad \text{and} \quad Fr_t \equiv \frac{u_{rms}}{N_0 L_t}. \quad (5)$$

227 The integral scale L_h is a direct estimate of the length scale of the motions responsible for most
 228 of the kinetic energy in a flow. Since calculation of L_h requires two point statistics to compute,
 229 L_t has long been used as a surrogate, and we provide it here to facilitate comparisons with other
 230 data. For isotropic homogeneous turbulence, $\mathcal{D} \equiv L_h/L_t \approx 0.5$ (Pope 2000), and for decaying
 231 unstratified turbulence it has been observed to be as high as 1.81 (Sreenivasan 1998; Wang et al.
 232 1996). For stratified turbulence with unity Pr , \mathcal{D} ranges from 0.3 to 0.5 (de Bruyn Kops 2015;
 233 Maffioli and Davidson 2016) and decreases with decreasing buoyancy Reynolds number (defined
 234 in the next paragraph) (de Bruyn Kops and Riley 2019). In the current simulations with $Pr = 7$, \mathcal{D}
 235 is approximately 0.1.

236 Stratification and viscosity can both act to inhibit turbulence motions. The combination of these
 237 effects can be quantified using a buoyancy Reynolds number (also referred to as a turbulent activity

238 coefficient Dillon and Caldwell (1980); Gibson (1980)),

$$Re_b \equiv \frac{\langle \varepsilon \rangle_V}{\nu N_0^2}. \quad (6)$$

239 From this definition, the buoyancy Reynolds number can be related to a ratio of Ozmidov and
 240 Kolmogorov scales, $Re_b = (L_O^V/L_K^V)^{4/3}$, where

$$L_K^V \equiv \left(\frac{\nu^3}{\langle \varepsilon \rangle_V} \right)^{1/4}, \quad \text{and} \quad L_O^V \equiv \frac{\langle \varepsilon \rangle_V^{1/2}}{N_0^{3/2}}. \quad (7)$$

241 Loosely, the Ozmidov scale characterizes the size of the largest turbulent overturns permitted by
 242 stratification and the Kolmogorov scale characterizes the size of the smallest motions permitted
 243 by viscosity. Therefore, Re_b provides a measure of the dynamic range associated with turbulent
 244 overturning motions, largely unaffected by either buoyancy or viscosity. The simulations in Table
 245 1 are listed in order of increasing Re_b . Values of Re_b in this range are common in the ocean
 246 interior according to a recent estimate based on ARGO data (Salehipour et al. 2016) and fine-scale
 247 parameterizations (Gregg 1989b). Larger values of Re_b are also observed (Moum 1996), but these
 248 are not currently accessible with DNS of strongly stratified flows with realistic Pr .

249 For comparison with observations it is useful to construct a set of dimensional parameters for
 250 each simulation. Here, this is done by setting the dimensional vertical domain size to 5m and
 251 the kinematic viscosity to $10^{-6}\text{m}^2\text{s}^{-1}$, appropriate for water. The dimensional domain size was
 252 chosen to match roughly the size of typical turbulent patches in the ocean interior and the vertical
 253 size typically used for averaging microstructure measurements (Moum 1996; Smyth et al. 2001).
 254 The horizontal dimensional domain size is 40m in Simulations A and B and 10m in Simulation
 255 C. As we will see, the domain size is sufficient to accommodate many turbulent overturns. For
 256 comparison the largest dimensional domain size used in the simulations of Smyth et al. (2001) (for
 257 $Pr = 7$) was $2.73 \times 1.36 \times 0.34\text{m}$.

258 Once the dimensional domain size and kinematic viscosity are set, the dimensional time scale
 259 can be found from the characteristic Reynolds number, Re . Some of the dimensional parameters
 260 are listed in Table 2. The dimensional values of the background buoyancy frequency, N_0 , are in the
 261 range $3.7 \times 10^{-3} \text{s}^{-1}$ to $1.4 \times 10^{-2} \text{s}^{-1}$, corresponding to buoyancy periods ranging from 28.0 to 7.4
 262 min. The weakest stratification considered here is within the range observed by Moum (1996) in
 263 the main thermocline while the strongest stratification considered here is more typical of the sea-
 264 sonal pycnocline (e.g. Alford and Pinkel (2000b)). The dimensional average turbulent dissipation
 265 rate spans more than two orders of magnitude and contains values typically measured in the ocean
 266 interior (e.g. Moum (1996); Gregg (1989b)). The vertical turbulent diffusivity calculated with the
 267 volume-averaged horizontal buoyancy flux, $\kappa_d^V \equiv -\langle B \rangle_V / \langle N^2 \rangle_V$ ranges from $2.2 \times 10^{-6} \text{m}^2 \text{s}^{-1}$
 268 in Simulation A to $7.2 \times 10^{-5} \text{m}^2 \text{s}^{-1}$ in Simulation C. The very small diffusivity in Simulation
 269 A is consistent with the observation by Ivey and Imberger (1991) that turbulence collapses for
 270 $Re_b \lesssim 15$. However, as discussed by Rorai et al. (2014); Portwood et al. (2016), strongly stratified
 271 turbulence is highly intermittent in space and time and (as we will see below) the volume-averaged
 272 statistics are not indicative of the turbulence at single points in space.

273 3. Results

274 *a. Vertical section and profiles*

275 Turbulence and mixing are intermittent across a wide range of scales in the DNS. On small
 276 scales, the statistics of energy and buoyancy variance dissipation are skewed with a small number
 277 of large events dominating the volume average. This is a well-known property of high Reynolds
 278 number turbulence in unstratified flows (Sreenivasan and Antonia 1997) and intermittency in scalar
 279 mixing is discussed extensively in Warhaft (2000). On larger scales, turbulence occurs in localized

280 bursts separated by relatively quiescent flow. Similar behavior has been observed in numerous
 281 previous studies (e.g. Riley and de Bruyn Kops (2003); Hebert and de Bruyn Kops (2006a); Rorai
 282 et al. (2014); Portwood et al. (2016)).

283 The top row in Figure 1 shows a vertical cross-section of buoyancy, b , and the TKE dissipation
 284 rate, ε , from Simulation C. The other simulations (not shown) have qualitatively similar features.
 285 A series of distinct layers are visible in the buoyancy field with relatively thick weakly stratified
 286 regions separated by relatively thin and more strongly stratified interfaces. The turbulent dissi-
 287 pation rate exhibits localized patches of strong turbulence similar to those described in Portwood
 288 et al. (2016). Maximum local values of ε are up to 30 times larger than the volume average.

289 The lower panels in Figure 1 show a close-up view of the flow in the boxed regions labeled 1, 2,
 290 and 3 in the top panels. In order to quantify mixing in each region, it is convenient to introduce the
 291 perturbation potential energy. In a volume with constant background buoyancy gradient N_0^2 , the
 292 perturbation potential energy is $\langle b'^2 \rangle_V / (2N_0^2)$ and its associated dissipation rate can be written as

$$\chi \equiv \frac{\kappa_m \nabla b' \cdot \nabla b'}{N_0^2}. \quad (8)$$

293 Since N_0^2 is constant in our simulations, χ is proportional to the dissipation rate of buoyancy
 294 variance, and hence is a natural measure of irreversible mixing (see Salehipour and Peltier (2015)
 295 for a detailed discussion).

296 Region 1 is associated with relatively large kinetic and potential energy dissipation rates. As
 297 seen in the buoyancy field, in the middle of this region is a ~ 0.5 m vertical overturn. At the center
 298 of the overturn χ is relatively weak while ε remains large. Along the edges of the overturn χ and
 299 ε are of similar magnitude. In other words, mixing is more efficient on the flanks of the overturn
 300 than in the center of the overturn.

301 Region 2 exhibits a moderate value of ε and an undulating density interface passes through
302 the region. While ε is relatively uniform in the region, χ is significantly larger near the density
303 interface than in the mixed regions above and below the interface. Small overturns, 5-10 cm in
304 height, appear along the density interface, but these features appear irregular.

305 Region 3 is characterized by relatively small values of ε and a relatively flat density interface.
306 A vertically-sheared flow exists on either side of the density interface (not shown) and a series of
307 what appear to be shear-induced billows can be seen. These billow-like structures are highlighted
308 by relatively large values of χ .

309 Statistics collected along a single vertical profile corresponding to the white dashed line in Fig-
310 ure 1 are shown in Figure 2. The red dashed line in Figure 2(a) shows the 1D sorted buoyancy
311 profile. The displacement scale L_d is the change in height of a fluid parcel from its unsorted to
312 sorted positions. Several features in the profiles shown in Figure 2 resemble qualitatively the ob-
313 served profiles reported in Moum (1996) such as the step-like structure in the density field and the
314 corresponding structure in the Thorpe displacement scale (see, e.g. Figure 1b in Moum (1996)).
315 The buoyancy flux, $w'b'$, alternates in sign along the vertical profile, indicating reversible transfer
316 between perturbation potential and kinetic energy.

317 The kinetic and potential energy dissipation rates are highly intermittent (see panels d and 3 in
318 Figure 2). There is no clear correlation between locations with large ε and χ . As a result, a local
319 mixing efficiency, $\eta(\mathbf{x}, t)$, which may be defined as

$$\eta(\mathbf{x}, t) \equiv \frac{\chi}{\chi + \varepsilon}, \quad (9)$$

320 fluctuates rapidly between 0 and 1 (Figure 2f).

321 *b. Length scales*

322 The relative importance of stratification and viscosity to the turbulent motions at a particular
 323 scale can be quantified by comparing various length scales associated with stratified turbulence
 324 (Smyth and Moum 2000). Figure 3 shows characteristic length scales for each simulation, plotted
 325 as a function of the buoyancy Reynolds number, Re_b . Here, dimensional values are plotted, where
 326 the vertical domain size is set to 5m as discussed above.

327 In dimensional terms, the Kolmogorov scale, L_K , ranges from 2.4mm to 8.7mm, while the Batch-
 328 elor scale, $L_B = L_K / \sqrt{Pr}$ ranges from 0.9mm to 3.3mm. The isotropic grid spacing, $\Delta_{x,y,z}$ is always
 329 less than twice the Batchelor scale, ensuring that the DNS is sufficiently well-resolved. The wide
 330 scale separation between the domain size and the grid spacing gives an indication of the large
 331 computational cost of these simulations.

332 There are several different ways to construct a Thorpe scale from a three-dimensional dataset
 333 (see Smyth and Moum (2000) and Mashayek et al. (2017a) for further discussion). For example, it
 334 would be possible to sort a three-dimensional density field (e.g. Winters and D’Asaro (1996)) and
 335 calculate the Thorpe scale from the *rms* vertical displacements with respect to the volumetrically-
 336 sorted profile. Here, motivated by oceanographic observations where three-dimensional sorting is
 337 typically not possible, we instead vertically sort the density profile at each horizontal gridpoint.
 338 The Thorpe scale is then calculated from each vertical profile and the result shown in Figure 3 is
 339 averaged over all horizontal gridpoints. Specifically,

$$L_T^V \equiv \left\langle \left\langle L_d^2 \right\rangle_z^{1/2} \right\rangle_{x,y}, \quad (10)$$

340 where $\langle \cdot \rangle_z$ denotes an average in the vertical direction and $\langle \cdot \rangle_{x,y}$ denotes an average in the horizon-
 341 tal directions. Later, in section 3d, we will examine the sensitivity of the Thorpe scale estimates
 342 calculated with a limited number of vertical profiles.

343 The dimensional Thorpe and Ozmidov scales calculated using volumetric simulation data, L_T^V
344 and L_O^V are both $\simeq 10$ cm and increase somewhat with increasing buoyancy Reynolds number.
345 The Ozmidov scale increases with Re_b faster than the Thorpe scale such that the ratio L_O^V/L_T^V is
346 0.53 in simulation A, 0.56 in simulation B, and 0.92 in simulation C. This can be compared with
347 $L_O/L_T \simeq 0.8$ suggested by Dillon and Caldwell (1980). The dependence of this ratio on the flow
348 parameters is consistent with the recent conclusions of Mater et al. (2015) and Scotti (2015).

349 *c. Testing of Osborn, Osborn-Cox, and Dillon methods*

350 In this section, we will compare the vertical turbulent diffusivity diagnosed directly from the
351 simulations with values inferred from the Osborn, Osborn-Cox, and Dillon methods. Before giving
352 the results, a brief description of each method is given below, highlighting in particular some of
353 the key assumptions behind each method.

354 1) OSBORN-COX METHOD

355 Starting from an equation for entropy density, Osborn and Cox (1972) derived a method to
356 estimate the vertical turbulent diffusivity from measurements of microscale temperature or con-
357 ductivity. Here, we will write the equations in terms of buoyancy b with the understanding that
358 this is more closely related to temperature than salinity since the Prandtl number is 7 in the DNS.
359 The buoyancy variance budget (as noted above this is linearly related to the perturbation potential
360 energy in this context) can be written as

$$\left(\frac{\partial}{\partial t} + \langle \mathbf{u} \cdot \nabla \rangle \right) \langle b'^2 \rangle + \nabla \cdot (\langle \mathbf{u}' b'^2 \rangle - \kappa_m \nabla \langle b'^2 \rangle) = -2 \langle \mathbf{u}' b' \rangle \cdot \nabla \langle b \rangle - 2 \kappa_m \langle \nabla b' \cdot \nabla b' \rangle, \quad (11)$$

361 where angle brackets denote an average over some arbitrary volume (e.g. Pope (2000)). Assuming
362 that terms on the left hand side, the time rate of change and flux divergence, are both small, Eq. 11

363 reduces to a production-dissipation balance

$$-\langle \mathbf{u}'b' \rangle \cdot \nabla \langle b \rangle = \kappa_m \langle \nabla b' \cdot \nabla b' \rangle = \langle \chi \rangle \langle N^2 \rangle, \quad (12)$$

364 using Eq. 8. Further neglecting the horizontal buoyancy flux and defining the vertical diffusivity in
 365 terms of these (arbitrary) volume average, i.e. $\kappa \equiv -\langle B \rangle / \langle N^2 \rangle$ yields an estimate of the vertical
 366 turbulent diffusivity,

$$\kappa_{O-C} \equiv \frac{-\langle B \rangle}{\langle N^2 \rangle} \simeq \frac{\langle \chi \rangle}{\langle N^2 \rangle}. \quad (13)$$

367

368 2) OSBORN METHOD

369 The Osborn method (Osborn 1980) provides a way to estimate the vertical diffusivity associated
 370 with small-scale turbulence from the TKE dissipation rate. In deriving the method, Osborn made
 371 several key assumptions (see e.g. Mashayek et al. (2013) for further discussion), including that the
 372 vertical diffusivity is dominated by fully developed turbulence, and that the turbulence exhibits a
 373 quasi-steady balance between production, dissipation and diapycnal mixing *when suitably aver-*
 374 *aged* so that the mixing can be related to the dissipation rate. Therefore, the TKE budget reduces
 375 to a balance between production, buoyancy flux, and dissipation, (with crucially no contribution
 376 from advective or boundary processes) i.e.

$$\langle P \rangle = \langle \varepsilon \rangle - \langle B \rangle, \quad (14)$$

377 where

$$\langle P \rangle \equiv -\langle u'_i u'_j \rangle \frac{\partial \langle u_i \rangle}{\partial x_j} \quad (15)$$

378 is the turbulent shear production. Osborn (1980) further assumed that small-scale turbulence is
 379 isotropic so that the dissipation rate can be determined from just one component of the defor-
 380 mation rate tensor. We do not test this assumption here and instead evaluate the production and

381 dissipation using the full deformation rate tensor. The appropriateness of the assumption of small-
 382 scale isotropy for stratified turbulence has been discussed extensively in recent papers (e.g. Hebert
 383 and de Bruyn Kops (2006b); Almalkie and de Bruyn Kops (2012a); de Bruyn Kops (2015)). Os-
 384 born (1980) further suggested that the assumption of quasi-steadiness and hence the averaging
 385 operator could be applied to vertical profiles through turbulent patches ranging from 1-10 m in
 386 size.

387 Using the classical definition of the flux Richardson number, $R_f \equiv -\langle B \rangle / \langle P \rangle$ (or $R_f =$
 388 $\langle B \rangle / (\langle B \rangle - \langle \varepsilon \rangle)$) using Eq. 14) the buoyancy flux may be expressed in terms of the TKE dissi-
 389 pation rate ε as

$$\langle B \rangle = - \left(\frac{R_f}{1 - R_f} \right) \langle \varepsilon \rangle. \quad (16)$$

390 Then, the vertical turbulent diffusivity, $\kappa = -\langle B \rangle / \langle N^2 \rangle$, can be related to ε to yield the estimate

$$\kappa_O = \Gamma \frac{\langle \varepsilon \rangle}{\langle N^2 \rangle}, \quad (17)$$

391 where $\Gamma \equiv \left(\frac{R_f}{1 - R_f} \right)$. The turbulent flux coefficient Γ is often referred to as a ‘mixing efficiency’,
 392 although in principle it can be greater than one, and there has been much recent activity attempting
 393 to produce appropriate parameterizations for this quantity in terms of various flow parameters, see
 394 for example Salehipour et al. (2016); Mashayek et al. (2017b); Monismith et al. (2018).

395 3) THORPE-SCALE METHOD

396 Thorpe (1977) proposed a method to estimate the averaged dissipation rate based on vertical
 397 profiles of potential density. An advantage of this method is that it can be applied to more readily
 398 available data (Gargett and Garner 2008). To calculate the Thorpe scale, a density profile is first
 399 sorted so that the sorted density is a monotonic function of height. The displacement length L_d
 400 is the difference in height of a water parcel from its unsorted to sorted location (figure 2(c)). The

401 Thorpe scale is then calculated by taking the root mean square of L_d , i.e.

$$L_T^P = \langle L_d^2 \rangle_P^{1/2}, \quad (18)$$

402 where angle brackets are typically taken to represent an appropriate ‘patch’ average, for example
 403 taken over a single overturning turbulent patch or an ensemble of such patches obtained from
 404 vertical profiling instruments (Thorpe 2005). Thorpe (1977) conjectured that L_T^P may be linearly
 405 related to the Ozmidov scale calculated with patch-averaged quantities, $L_O^P = \langle \varepsilon \rangle_P^{1/2} \langle N^2 \rangle_P^{-3/2}$.
 406 This then gives an estimate of the dissipation rate

$$\langle \varepsilon \rangle_P = R_{OT}^2 (L_T^P)^2 \langle N^2 \rangle_P^{3/2}, \quad (19)$$

407 where the coefficient of proportionality, $L_O^P/L_T^P \equiv R_{OT} \simeq 0.8$, is based on observations by Dillon
 408 and Caldwell (1980), although there is mounting evidence that estimates of this coefficient can be
 409 both biased and uncertain (Mater et al. 2015; Scotti 2015; Mashayek et al. 2017a). Then, using
 410 Eq. 17 yields an estimate for the vertical turbulent diffusivity,

$$\kappa_T = 0.64\Gamma (L_T^P)^2 \langle N^2 \rangle_P^{1/2}. \quad (20)$$

411 4) COMPARISON

412 The underlying assumptions behind the three methods described above are questionable in
 413 strongly stratified flows where turbulent events are highly intermittent in time and space as il-
 414 lustrated in Figure 1. This concern becomes stronger when a small subset of the flow is sampled,
 415 for example using a small number of vertical profiles, since the various averages being taken be-
 416 come less reliable as representative of turbulent mixing events within the flow. Before addressing
 417 the issue of incomplete sampling and averaging, we will first examine the performance of the ap-
 418 proximate methods described above, compared with the ‘direct’ calculation of κ formed using the

419 volume-averaged buoyancy flux and stratification, i.e.

$$\kappa_d^V = \frac{-\langle B \rangle_V}{\langle N^2 \rangle_V}. \quad (21)$$

420 When calculated using data from the full computational volume, the vertical turbulent diffusivity
 421 associated with the Osborn-Cox, Osborn, and Thorpe methods can be written

$$\kappa_{O-C}^V = \frac{\langle \chi \rangle_V}{\langle N^2 \rangle_V}, \quad \kappa_O^V = \Gamma \frac{\langle \varepsilon \rangle_V}{\langle N^2 \rangle_V}, \quad \kappa_T^V = 0.64 \Gamma (L_T^V)^2 \langle N^2 \rangle_V^{1/2}, \quad (22)$$

422 respectively, where $\langle \cdot \rangle_V$ denotes an average over the full computational volume and L_T^V is de-
 423 fined in Eq. 10. Figure 4 shows κ_{O-C}^V , κ_O^V and κ_T^V , normalized by κ_d^V as defined in Eq. 21 and
 424 plotted against the buoyancy Reynolds number to differentiate the three simulations. The dimen-
 425 sional values of κ_d^V are $2.2 \times 10^{-6} \text{m}^2 \text{s}^{-1}$ in Simulation A, $1.8 \times 10^{-5} \text{m}^2 \text{s}^{-1}$ in Simulation B, and
 426 $7.2 \times 10^{-5} \text{m}^2 \text{s}^{-1}$ in Simulation C, roughly spanning typical values found in the ocean interior
 427 (Waterhouse et al. 2014).

428 Even with perfect sampling of the 3D volume, there are significant differences between the var-
 429 ious estimates of κ . The estimates using the Osborn and Osborn-Cox methods, κ_O^V and κ_{O-C}^V are
 430 within 40% of κ_d^V , and there is no clear trend with Re_b . The Thorpe-scale method underestimates
 431 κ_d^V by about 50% in Simulation C, but significantly overestimates κ_d^V in Simulations A and B.
 432 Recall that our simulations are analyzed at a statistically steady state. It is possible that temporal
 433 variability could lead to larger biases when these methods are applied to oceanographic data. In
 434 addition, when the Thorpe scale is small and/or when the density contrast is weak, it can be dif-
 435 ficult to distinguish between real overturns and measurement error associated with a CTD profile
 436 (Ferron et al. 1998; Alford and Pinkel 2000a; Johnson and Garrett 2004).

437 *d. Vertical profile-averaged statistics*

438 The estimates of the vertical turbulent diffusivity described above were calculated using simu-
439 lation data extracted from the full three-dimensional volume. In contrast, data collected from the
440 ocean are necessarily much more limited. In this section, we explore the sensitivity of the esti-
441 mates of κ when calculated with limited data. Note that we do not consider instrument error or
442 biases introduced when converting measured quantities into physical quantities like the dissipa-
443 tion rate. Instead, we assume that the simulated field can be sampled perfectly at discrete points
444 in space and focus on the influence of limited data availability.

445 The most common sampling strategy to infer κ is to collect velocity, temperature and/or con-
446 ductivity along roughly vertical profiles. Measurements from distinct regions within one or more
447 profiles are often averaged to reduce the uncertainty in the measurement. Here, we will calculate
448 κ using the methods described in the previous section based on a limited number of 1D vertical
449 profiles extracted from the simulations. Note that the profiles that we use are taken instantaneously
450 and are perfectly vertical. How well this describes oceanographic measurements depends on the
451 fall speed of the instrument and the speed of the currents. Some platforms such as microstructure
452 gliders make significantly inclined profiles, although these data are often analyzed in a similar way
453 to free-falling profilers (e.g. Palmer et al. (2015)).

454 We extract data from the simulations by randomly selecting a set of vertical profiles from a sin-
455 gle three-dimensional field. Since the simulations were sampled when the flow is in a statistically
456 stationary state, sampling at different spatial locations should give the same statistical result as
457 sampling at different time intervals. Treating a limited number of samples as independent verti-
458 cal profiles is justified by the horizontal de-correlation of statistical quantities. For example, the
459 horizontal autocorrelation length associated with the profile-averaged TKE dissipation rate $\langle \epsilon \rangle_z$

460 drops to zero at a distance of $L_z/2$ or 5 m in Simulation C and a distance of $\sim 2L_z$ or ~ 10 m
 461 in Simulations A and B. Note that the properties of the large-scale flow in the simulations will
 462 be influenced by the forcing scheme used. In the ocean, where turbulence is associated with ed-
 463 dies, internal waves, and shear layers across a wide range of horizontal scales, the de-correlation
 464 distance between profile-averaged statistics could be much larger than 10 m.

465 Before testing the methods for estimating κ it is useful to quantify the variability in profile-
 466 averaged statistics induced by intermittent stratified turbulence. Figure 5 shows the probability
 467 density function (PDF) of the buoyancy flux, TKE and potential energy dissipation rates, and
 468 squared Thorpe scale, each normalized by the corresponding volume average. Here the Thorpe
 469 scale is calculated by averaging the *rms* displacement over one vertical profile such that

$$L_T^z \equiv \langle L_d^2 \rangle_z^{1/2}. \quad (23)$$

470 Each PDF is calculated using the full 3D computational volume (i.e. vertical profiles were col-
 471 lected at every horizontal gridpoint). The Thorpe scale is squared for comparison with the other
 472 quantities since this quantity appears in the expression for κ_T .

473 The modes of the PDFs for all quantities shown in Figure 5 are skewed towards values smaller
 474 than the volume average. It is well known in the turbulence literature that the point-wise TKE and
 475 variance dissipation rates are similarly skewed such that a small number of large values contribute
 476 significantly to the volume average (Pope 2000). The PDFs of local (pointwise) ε and χ are
 477 typically assumed to be lognormal, following Kolmogorov (1962). de Bruyn Kops (2015) shows
 478 that distributions of local ε and χ in stratified turbulence are well-approximated by the lognormal
 479 model provided that $Re_b > O(10)$. The TKE dissipation rate measured in the ocean thermocline is
 480 similarly skewed (Baker and Gibson 1987; Gregg et al. 1996). Evidently the intermittency inherent
 481 in the point-wise statistics extends to the profile-averaged statistics.

482 Here, we calculate ε and χ using derivatives of all three velocity components and buoyancy in
483 all three spatial directions. Field measurements of these quantities generally involve a subset of the
484 velocity and/or gradient information and assumptions about the isotropy of the small-scale turbu-
485 lence are invoked to fill in the missing information. The PDFs of the surrogates for ε and χ based
486 on a subset of the velocity and scalar gradients are significantly different from those of the exact
487 quantities. In particular, the left side of the distributions of the surrogates tend toward exponential
488 (Almalkie and de Bruyn Kops 2012a; de Bruyn Kops 2015) and the mean of the surrogates are
489 significantly different from the exact values when Re_b is low (Hebert and de Bruyn Kops 2006b).

490 The variance associated with the buoyancy flux is much larger than the variance in other quan-
491 tities. This appears to be associated with a large contribution from internal waves. Figure 2 shows
492 regions with alternating sign of $w'b'$, indicating active exchange between kinetic and potential en-
493 ergy. The profile-averaged buoyancy flux is often negative (not shown in Figure 5). As we will
494 see below, the large variability in the profile-averaged buoyancy flux has significant implications
495 for the estimates of κ .

496 Based on simulations of Kelvin-Helmholtz (K-H) instability, Smyth et al. (2001) proposed that
497 the ratio of the Ozmidov and Thorpe scales provides a measure of the ‘age’ of a turbulent event.
498 Their simulations started with a laminar stratified shear layer that was unstable to K-H. During
499 initial roll-up of the K-H billows, they found that the Thorpe scale grows quickly, but dissipa-
500 tion remains low and as a result $L_O/L_T \ll 1$. In the later stages of their simulations, three-
501 dimensional turbulence develops, and $L_O \sim L_T$. In simulations at substantially higher Reynolds
502 number, Mashayek et al. (2017a) found analogous behaviour, although they interpreted the (over-
503 all) monotonic increase in L_O/L_T during the turbulent life cycle as being due to the relatively
504 slower decrease in L_O compared to L_T during the turbulent decay phase of the life cycle. Mater
505 et al. (2015) apply a similar argument to explain variations in L_O/L_T in convectively-generated

506 turbulence. Observations reported in Smyth et al. (2001), Mater et al. (2015) and Mashayek et al.
507 (2017a) all show relatively broad distributions of L_O/L_T .

508 Probability density functions of L_O^z/L_T^z (where the dissipation rate and Thorpe displacement are
509 calculated based on averages over individual vertical profiles) is shown in Figure 6(a). The peak
510 in the distribution for Simulation C is relatively close to the value of $L_O/L_T = 0.8$ proposed by
511 Dillon and Caldwell (1980), and the distribution qualitatively resembles the observations reported
512 in Smyth et al. (2001). The ratio of the Ozmidov to Thorpe scale is somewhat smaller in Sim-
513 ulations A and B. This is consistent with the observations reported in Mater et al. (2015) which
514 suggest that L_O/L_T is not constant and depends on the properties of the flow. The spread in the
515 distributions of L_O^z/L_T^z suggests that the collection of profile-averaged statistics can be viewed as
516 an ensemble of turbulent events as visualized in Figure 1.

517 Figure 6(b) shows PDFs of mixing efficiency calculated using the profile-averaged dissipation
518 rates, i.e. $\langle \chi \rangle_z / (\langle \chi \rangle_z + \langle \varepsilon \rangle_z)$, which exhibits significant scatter about the volume average. The
519 mean and mode of the distributions increase from Simulation A to Simulation C as the buoyancy
520 Reynolds number increases. The mean values are somewhat larger than the canonical value of
521 $1/6$, ranging from 0.18 in Simulation A to 0.28 in simulation C, although the spread about the
522 mean is considerable. For example $\sim 22\%$ of the profiles taken from Simulation C have a mixing
523 efficiency larger than 0.4, although such large values do arise in idealised flows subject to strong
524 Kelvin-Helmoltz-like shear-driven overturning motions (see for example Mashayek et al. (2013,
525 2017a)).

526 Some recent studies have suggested that the mixing efficiency depends on the buoyancy
527 Reynolds number, $Re_b \equiv \varepsilon / (\nu N^2)$ (e.g. Shih et al. (2005); Mater and Venayagamoorthy (2014);
528 Salehipour et al. (2016); Mashayek et al. (2017b); Monismith et al. (2018)). Although there are
529 differences in the details of various proposed scalings, most of the observations and simulations

530 reported in these papers suggest a decrease in the mixing efficiency when Re_b exceeds a critical
531 value. Figure 6(c) shows the mixing efficiency plotted against Re_b , with each quantity calculated
532 from the profile-averaged dissipation rates. For small Re_b the mixing efficiency is very close to
533 the value of 0.17 proposed by Osborn (1980), and consistent with previous numerical simulations
534 (e.g. Shih et al. (2005)). A peak in mixing efficiency for moderate values of Re_b as seen in Figure
535 6(c) also occurs in some of the simulations from Shih et al. (2005) (see also Mater and Venayag-
536 amoorthy (2014) and Salehipour and Peltier (2015)). Here, the mixing efficiency decreases with
537 increasing buoyancy Reynolds number for $Re_b \gtrsim 800$. This value is significantly larger than the
538 threshold value found by Shih et al. (2005), but smaller than the value from observations reported
539 in Lozovatsky and Fernando (2013) and well within the range of other simulations and observa-
540 tions (Mater and Venayagamoorthy 2014; Monismith et al. 2018).

541 Estimates of the vertical diffusivity calculated using sets of randomly selected vertical profiles
542 are shown in Figure 7. Specifically, when applied to n vertical profiles, the vertical diffusivity
543 estimated from the Osborn-Cox, Osborn, and Thorpe methods can be written

$$\kappa_{O-C}^{z,n} = \frac{\langle \chi \rangle_{z,n}}{\langle N^2 \rangle_{z,n}}, \quad \kappa_O^{z,n} = \Gamma \frac{\langle \epsilon \rangle_{z,n}}{\langle N^2 \rangle_{z,n}}, \quad \kappa_T^{z,n} = 0.64\Gamma (\langle L_T^z \rangle_n)^2 \langle N^2 \rangle_{z,n}^{1/2}, \quad (24)$$

544 respectively, where $\langle \cdot \rangle_{z,n}$ denotes an average over n vertical profiles and L_T^z is defined in Eq. (23).

545 Similarly, the vertical diffusivity associated with the direct method applied to n vertical profiles is

$$\kappa_d^{z,n} = \frac{-\langle B \rangle_{z,n}}{\langle N^2 \rangle_{z,n}}. \quad (25)$$

546 Note that here $\langle N^2 \rangle_{z,n} = N_0^2$ due to the periodicity of the computational domain. In Figure 7 each
547 estimate of κ is dimensionalized such that the height of the vertical domain and the length of
548 each profile is 5 m. Solid colored lines show ± 1 standard deviation about the mean and the area
549 between these curves is shaded to highlight the uncertainty associated with each estimate. Black

550 dashed lines indicate the vertical diffusivity calculated with the volume-averaged buoyancy flux,
551 i.e. κ_d^V .

552 In all cases, $\kappa_d^{z,n}$ converges very slowly to κ_d^V . Figure 8 shows the standard deviation of the
553 averages of the buoyancy flux, kinetic and potential energy dissipation rates, and the squared
554 Thorpe scale for a given number of vertical profiles. In all cases the standard deviation decreases
555 with the square root of the number of profiles (compare with dashed line) as expected from the
556 central limit theorem for independent random variables. However, even with 20 profiles, negative
557 values of $\kappa_d^{z,n}$ are within one standard deviation of the mean in Simulations A and B. The variance
558 is smaller in Simulation C where the flow is more turbulent.

559 The standard deviations associated with the profile-averaged dissipation rate and Thorpe scales
560 are much smaller than the standard deviation of the buoyancy flux in Simulations A and B. As
561 seen in Figure 4, the Osborn and Osborn-Cox methods give a relatively good estimate of κ_d^V
562 in these cases. Interestingly, the standard deviations of $\langle \epsilon \rangle_{z,n}$ and $\langle \chi \rangle_{z,n}$ are significantly larger
563 in Simulation C and as a result the Osborn and Osborn-Cox methods require more profiles to
564 converge in this case. Since Simulation C is the most turbulent, having the largest dissipation rate,
565 diffusivity, and buoyancy Reynolds number, the slow convergence of the Osborn and Osborn-
566 Cox methods is unexpected and an explanation for this behavior is not immediately clear. In
567 comparison, the Thorpe-scale method converges relatively quickly in Simulation C.

568 *e. Validity of assumptions underlying the Osborn and Osborn-Cox methods*

569 Remarkably, when applied to a limited number of vertical profiles, the Osborn and Osborn-Cox
570 relations (Equations 17 and 13) outperform their underlying assumptions. Figure 9 shows the
571 normalized residual associated with the classic Osborn relation (Eq. 17, solid blue curve) and the
572 classic Osborn-Cox relation (Eq. 13, dashed blue curve). Here, the normalized residual is defined

573 as the absolute value of the sum of the terms in each relation (with all terms on one side of the
574 relevant equation) divided by the sum of the absolute values of each individual term.

575 For the Osborn model, we also evaluate the assumption that the turbulent flux coefficient Γ is
576 constant (solid green curve), and the assumed quasi-steady balance (unaffected by advection) in
577 the TKE budget (Eq. 14, solid red curve). The vertical and profile average is not shown in the
578 legend for notational clarity but is applied to ε , B , P , and N^2 individually. We also evaluate the
579 assumption underlying the Osborn-Cox model that the buoyancy variance budget reduces to a
580 production/dissipation balance with $B \simeq \chi$ (dashed red curve).

581 One might expect the error associated with the Osborn and Osborn-Cox relations to be at least
582 as large as that of the worst assumption underlying these relations. Instead, the error associated
583 with the Osborn relation is significantly less than the errors associated with the equations for the
584 flux coefficient and TKE budgets for Simulations A and B. In case C the error in the Osborn re-
585 lation is comparable to the error associated with the flux coefficient and smaller than the error
586 associated with the TKE budget. A similar conclusion applies to the Osborn-Cox model where the
587 Osborn-Cox relation (dashed blue curve in Fig. 9) significantly outperforms the assumption of pro-
588 duction/dissipation balance in the buoyancy variance equation (dashed red curve) in Simulations
589 A and B.

590 An important difference between the Osborn and Osborn-Cox relations and the equations for the
591 flux coefficient and the TKE and buoyancy variance budgets underlying these relations is that the
592 buoyancy flux does not appear explicitly in the Osborn or Osborn-Cox relations. Figure 7 showed
593 that the buoyancy flux exhibits very large scatter about its mean value, and this is particularly true
594 in Simulations A and B. One explanation for the relatively low normalized residuals associated
595 with the Osborn and Osborn-Cox relations is they are it is not influenced by the reversible contri-
596 butions of internal waves to the buoyancy flux. Indeed, central to the averaging at the heart of the

597 Osborn method is the assumption that reversible processes in the buoyancy flux are filtered out,
598 leaving only the irreversible component, capturing the actual mixing occurring within the flow.

599 Relatively recently, Salehipour and Peltier (2015) proposed a ‘generalized Osborn relation’ us-
600 ing the framework introduced by Winters and D’Asaro (1996), designed explicitly to identify, as
601 a function of time, the diapycnal diffusivity in terms of an appropriate definition for an inherently
602 irreversible mixing efficiency. They showed that the diapycnal diffusivity κ_ρ can be written as

$$\kappa_\rho = \frac{\mathcal{E}}{1 - \mathcal{E}} \frac{\varepsilon}{N_*^2}, \quad (26)$$

603 where \mathcal{E} is the *irreversible* and instantaneous mixing efficiency defined in Caulfield and Peltier
604 (2000) and N_* is the buoyancy frequency calculated using the sorted density profile. Since this
605 expression relies on quantities calculated from (volume) sorted data, it is a global measure of the
606 mixing within the entire domain under consideration, but can in principle be calculated at every
607 time instant within a temporally evolving flow. As the key parameters (such as an appropriately
608 defined buoyancy Reynolds number and Richardson number) describing their simulated flow also
609 vary in time, the results of their simulations, showing temporal variation of \mathcal{E} can be interpreted as
610 evidence that \mathcal{E} depends on such parameters (Salehipour and Peltier 2015; Salehipour et al. 2016).
611 Importantly, Eq. (26) does not rely on any assumptions aside from the Boussinesq approximation.

612 Salehipour and Peltier (2015) noted the clear structural similarity between Eq. (26) and the Os-
613 born relation, Eq. (17). For strongly stratified flows with relatively small isopycnal displacements
614 one might anticipate that the globally sorted buoyancy frequency $N_* \simeq N$. To the extent that the
615 flux coefficient Γ in Eq. (17) approximates the irreversible flux coefficient $\mathcal{E}/(1 - \mathcal{E})$, the Osborn
616 relation could then provide a relatively robust approximation to the diapycnal diffusivity. Funda-
617 mentally, the key point is that assuming that the *irreversible* buoyancy flux is some fraction of the
618 turbulent dissipation rate appears to be a reasonable assumption.

619 The dissipation rates of turbulent kinetic energy (ε) and perturbation potential energy (χ) both
620 represent irreversible losses from turbulence. As noted above, the partitioning of the total energy
621 lost between these two terms is broadly consistent with the value of the flux coefficient used in
622 the Osborn method, even though the theoretical arguments and assumptions presented by Osborn
623 to justify this partitioning are not satisfied, not least due to the contaminating effects of *reversible*
624 processes. The apparently robust partitioning between perturbation kinetic and potential energy
625 dissipation might help explain why the Osborn method, applied using a limited number of vertical
626 profiles, appears to be less prone to errors introduced by the presence of internal waves and other
627 reversible processes than the failure of its underlying assumptions might suggest. It should be
628 kept in mind that this discussion pertains to averaged quantities and that in local, transient mixing
629 events the relative size of ε and χ can vary substantially.

630 **4. Conclusions and discussion**

631 In this paper we tested the performance of the Osborn, Osborn-Cox, and Thorpe-scale meth-
632 ods using high resolution direct numerical simulations (DNS). The simulations used an idealized
633 triply periodic computational domain with an imposed background stratification. Turbulence was
634 forced using a deterministic body force added to the momentum equations. The simulations can
635 be viewed as a model of turbulence in a small region embedded within the thermocline. Three
636 simulations were run with varying stratification and turbulence levels, typical of conditions in the
637 main and seasonal thermoclines.

638 When the Osborn and Osborn-Cox methods are applied to the volume-averaged TKE and pertur-
639 bation potential energy dissipation rate, the resulting estimates of the vertical turbulent diffusivity
640 (κ_O^V and κ_{O-C}^V) are within 40% of the value obtained directly from the volume-averaged turbulent
641 buoyancy flux, κ_d^V . When the Thorpe scale is calculated using individual vertical profiles and then

642 averaged over the full computational domain, the resulting estimate, κ_T^V is very close to κ_O^V in
643 Simulation C but significantly overestimates κ_d^V in Simulations A and B with relatively small Re_b .
644 In Simulation A, κ_T^V is more than 2.5 times larger than κ_d^V .

645 Consistent with previous simulations of forced stratified turbulence, we find that turbulence
646 is inherently patchy and intermittent. For example, the PDFs of the dissipation rates of kinetic
647 energy and buoyancy variance are skewed with a small number of very intense events, associated
648 with vigorous, shear-driven overturnings. We find that this intermittency extends to the statistics
649 averaged over one-dimensional vertical profiles, despite the fact that the simulations are set up
650 such that each profile has the same average stratification.

651 This finding has important implications for the interpretation of limited observational datasets
652 and for sampling strategies. For example, to ensure that the average dissipation rate can be cor-
653 rectly calculated, it would be necessary to ensure that enough of the extreme events are captured.
654 The rate at which the various estimates of κ converge to the values calculated with volume-
655 averaged statistics depends on Re_b . In general, the Osborn and Osborn-Cox methods converge
656 relatively quickly in the simulations with small values of Re_b , while the Thorpe-scale method
657 converges somewhat faster in Simulation C at larger Re_b than in Simulations A and B.

658 In comparison to the Osborn and Osborn-Cox methods, the diffusivity calculated directly from
659 the vertical buoyancy flux using a small number of vertical profiles exhibits a very large scatter
660 about the mean. Remarkably in Simulations A and B, negative values of κ are within one standard
661 deviation of the average even when using 20 vertical profiles, each 5m in length. The convergence
662 to the mean is faster in Simulation C where the flow is more turbulent. The slow convergence of
663 the buoyancy flux for small Re_b appears to be due to large (and inherently reversible) contributions
664 from internal waves. In an internal wave field the sign of $w'b'$ fluctuates as energy is transferred
665 between the kinetic energy reservoir and the potential energy reservoir. A large averaging window

666 (in space, in time or in ensemble) is required to eliminate these reversible contributions to the
667 buoyancy flux.

668 Here, we have not tested the performance of finescale methods which rely on measurements of
669 internal waves. The large-scale forcing that was used to drive turbulence in the DNS was idealized
670 and was not necessarily intended to replicate the properties of the finescale internal wave field.
671 Simulations that simultaneously resolve a typical finescale internal wave spectrum (e.g. Gargett
672 et al. (1981)) while also resolving small-scale turbulence and mixing could be used to test (and
673 perhaps improve) finescale methods.

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832 **Table 1.** Nondimensional simulation parameters and derived quantities. 42

833 **Table 2.** Dimensional simulation parameters and derived quantities. The values here
834 have been made dimensional by setting the vertical domain height $L_z = 5\text{m}$ and
835 kinematic viscosity $\nu = 10^{-6} \text{ m}^2\text{s}^{-1}$ in each simulation. 43

Label	$\tilde{L}_{x,y}$	\tilde{L}_z	$N_{x,y}$	N_z	Re	Fr	Pr	Fr_h	Fr_t	Re_h	Re_t	Re_b
A	2π	$\pi/4$	9216	1152	6452	0.0416	7	0.071	0.0019	7048	82755	12.1
B	2π	$\pi/4$	18432	2304	2410	0.0416	7	0.080	0.0025	23069	231575	57.5
C	2π	π	13104	6552	4679	0.1667	7	0.45	0.015	2985	25597	241.5

TABLE 1. Nondimensional simulation parameters and derived quantities.

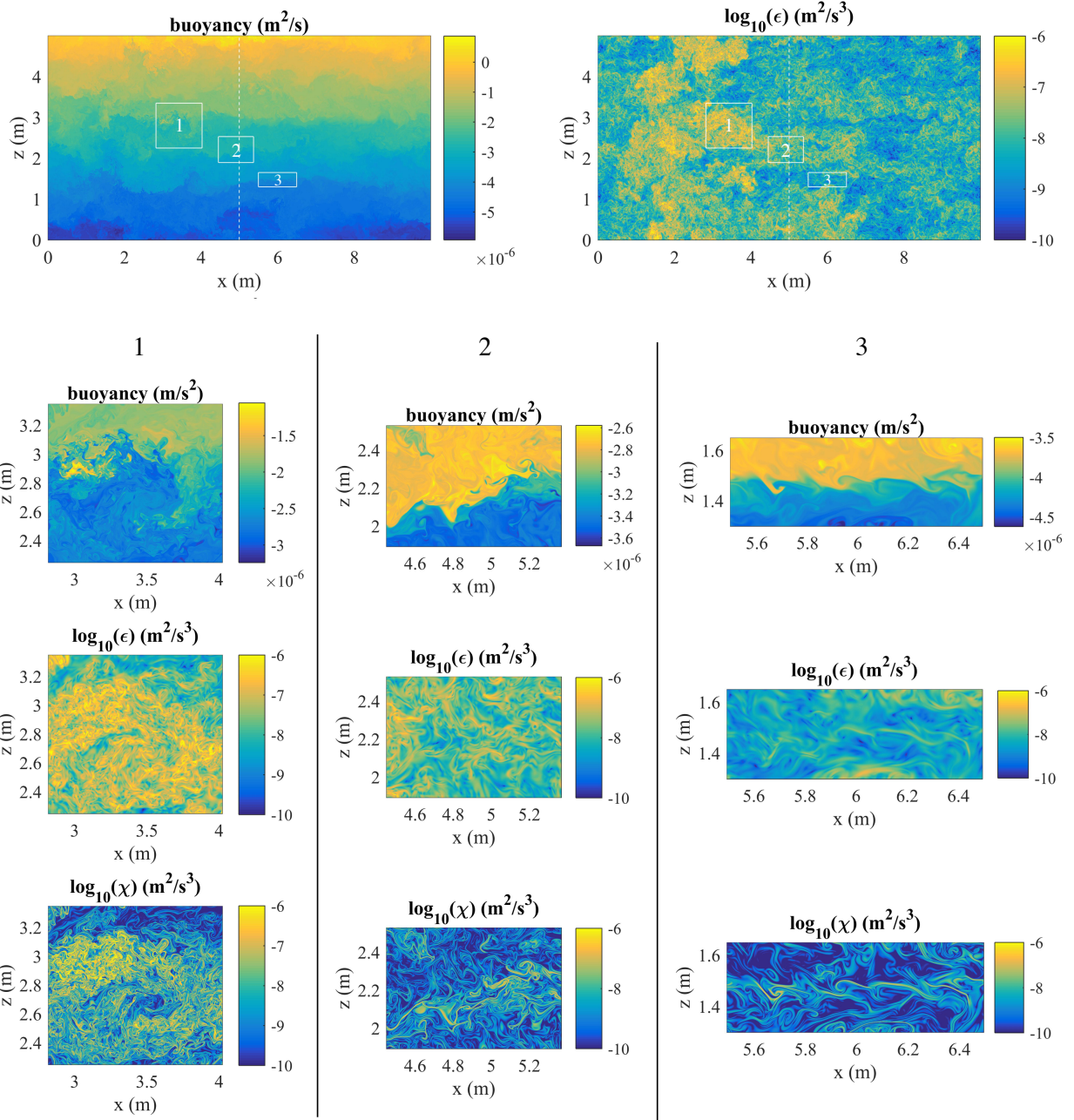
Label	$L_{x,y}$	L_z	$\Delta_{x,y,z}$	N_0^2	$\langle \epsilon \rangle_V$	L_O^V	L_K^V	κ_d^V
A	40m	5m	4.3mm	$1.41 \times 10^{-5} \text{s}^{-2}$	$1.71 \times 10^{-10} \text{m}^2 \text{s}^{-3}$	5.6cm	8.7mm	$2.2 \times 10^{-6} \text{m}^2 \text{s}^{-1}$
B	40m	5m	2.2mm	$2.00 \times 10^{-4} \text{s}^{-2}$	$1.15 \times 10^{-8} \text{m}^2 \text{s}^{-3}$	6.3cm	3.0mm	$1.8 \times 10^{-5} \text{m}^2 \text{s}^{-1}$
C	10m	5m	0.76mm	$1.23 \times 10^{-4} \text{s}^{-2}$	$2.97 \times 10^{-8} \text{m}^2 \text{s}^{-3}$	14.8cm	2.4mm	$7.2 \times 10^{-5} \text{m}^2 \text{s}^{-1}$

836 TABLE 2. Dimensional simulation parameters and derived quantities. The values here have been made dimen-
837 sional by setting the vertical domain height $L_z = 5\text{m}$ and kinematic viscosity $\nu = 10^{-6} \text{m}^2 \text{s}^{-1}$ in each simulation.

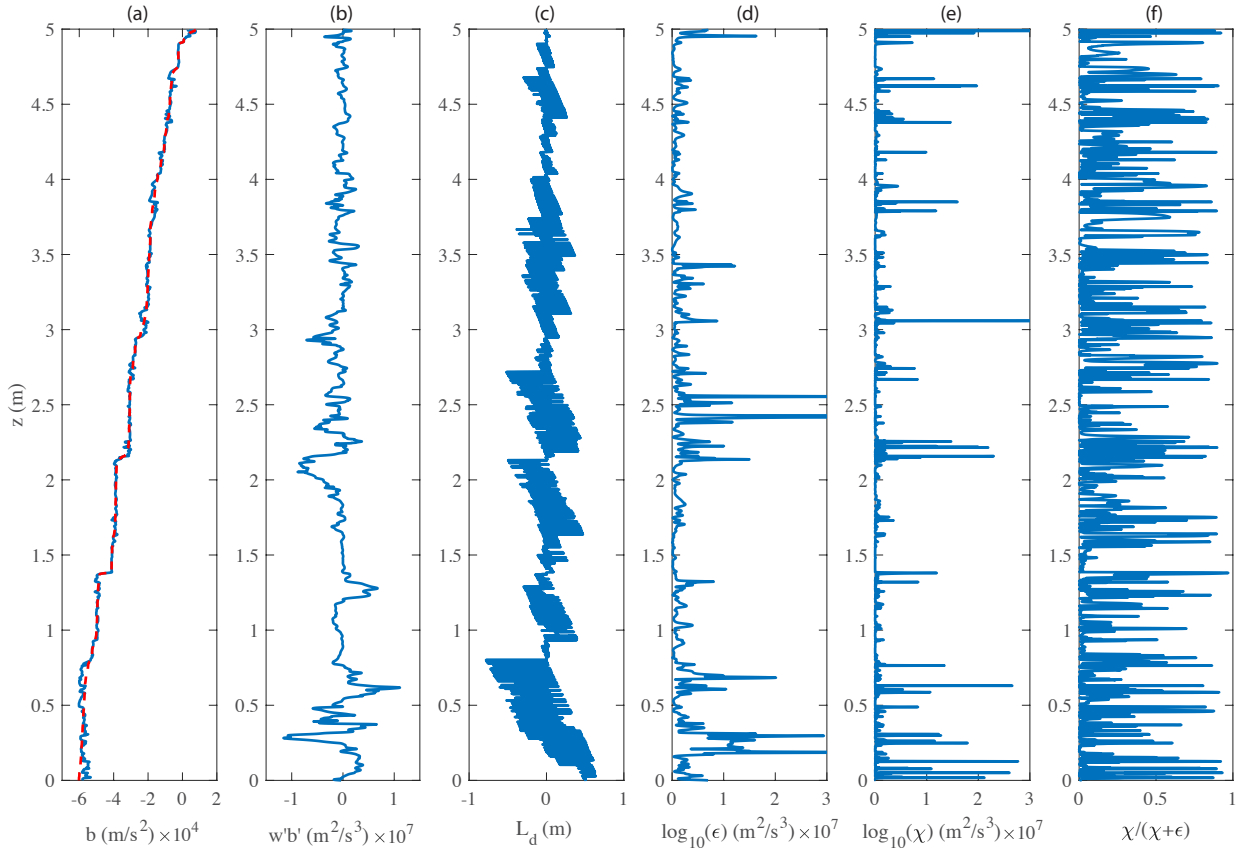
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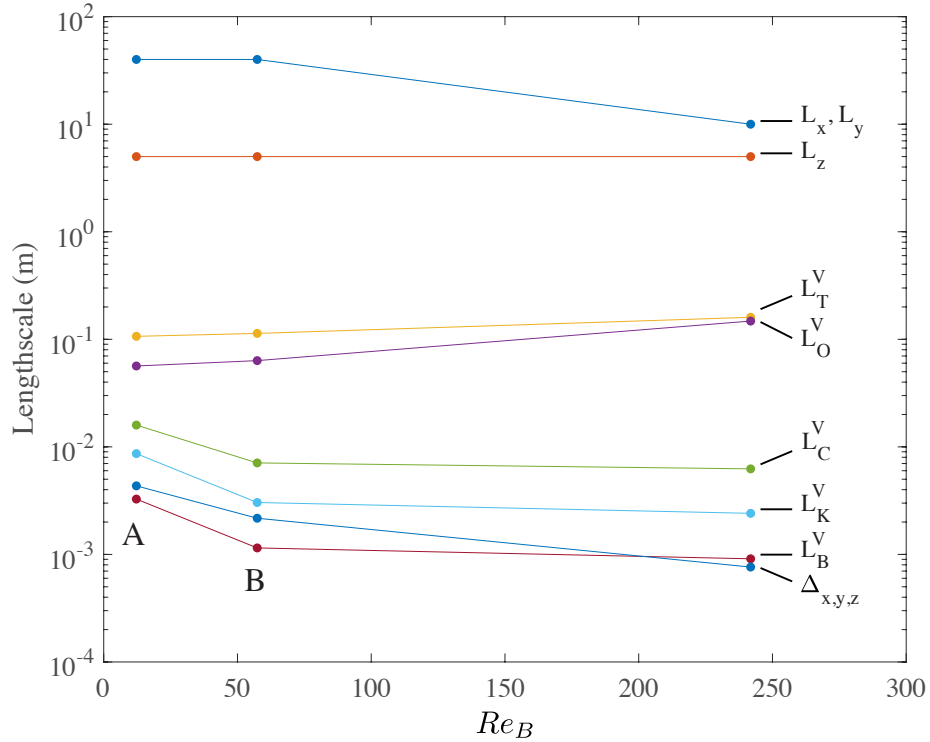
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840	Fig. 1.	Top row: dimensional buoyancy and turbulent kinetic energy dissipation rate (ϵ) on a vertical 2D slice extracted from Simulation C. Panels in columns 1, 2, and 3 show a close-up of regions with strong, moderate, and weak dissipation as indicated by the boxed regions labeled in the top row. The dissipation rate of perturbation potential energy (χ) is also shown. The white dashed lines in the top row indicate the location of the profile shown in Figure 2 45
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845	Fig. 2.	Vertical profiles of (a) buoyancy, (b) buoyancy flux, (c) displacement scale L_d , (d) turbulent kinetic energy dissipation rate, (e) turbulent potential energy dissipation rate, and (f) local mixing efficiency extracted from Simulation C. The profiles are taken from the location indicated with a white dashed line in Figure 1. The dashed red line in (a) is the sorted density profile. 46
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850	Fig. 3.	Dimensional lengthscales: horizontal domain size L_x , L_y , vertical domain size L_z , Thorpe scale L_T^V , Ozmidov scale L_O^V , Kolmogorov scale L_K^V , Batchelor scale L_B^V , and grid spacing $\Delta_{x,y,z}$. Simulation labels are given at the bottom of each series. The volume-averaged dissipation rate was used to calculate L_O^V , L_K^V , and L_B^V , and the Thorpe scale was calculated by sorting individual 1D density profiles and averaging the resulting Thorpe scale over all horizontal grid points. 47
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856	Fig. 4.	Vertical diffusivity estimated using the Osborn method κ_O^V (green circles), Osborn-Cox method κ_{O-C}^V (blue squares), and Thorpe method κ_T^V (magenta triangles), each calculated using data extracted from the full computational volume as defined in Eq. 22 and normalized by the turbulent vertical diffusivity diagnosed directly from the volume-averaged buoyancy flux, κ_d^V 48
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869	Fig. 7.	Estimates of the vertical diffusivity using the Osborn (green), Osborn-Cox (blue), Thorpe (magenta), and direct methods (red), calculated using n vertical profiles. Lines denote ± 1 standard deviation about the mean and the area between these limits is shaded. The dashed line indicates the vertical diffusivity calculated by directly averaging the flux over the full volume of the simulations as defined in Eq. 21. Note that the limits of the vertical axis are different in each panel. 51
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875	Fig. 8.	Standard deviation associated with quantities averaged over n vertical profiles, normalized by the 3D volume average. Dashed lines show the $n^{-1/2}$ scaling expected from the Central Limit Theorem. 52
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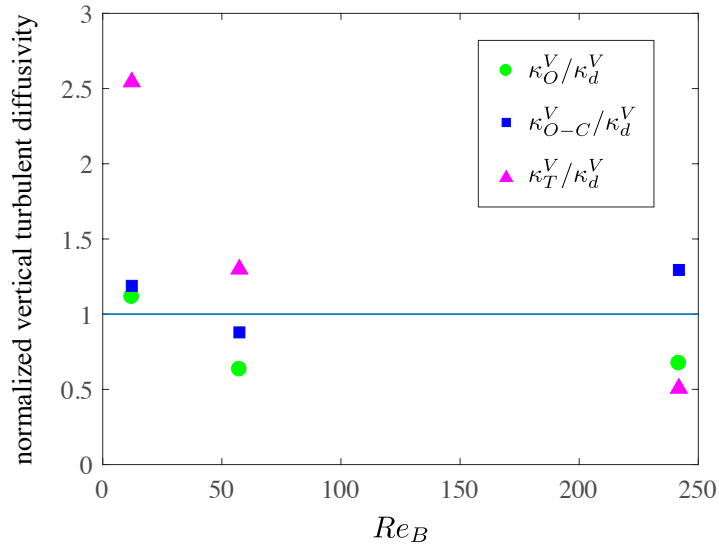
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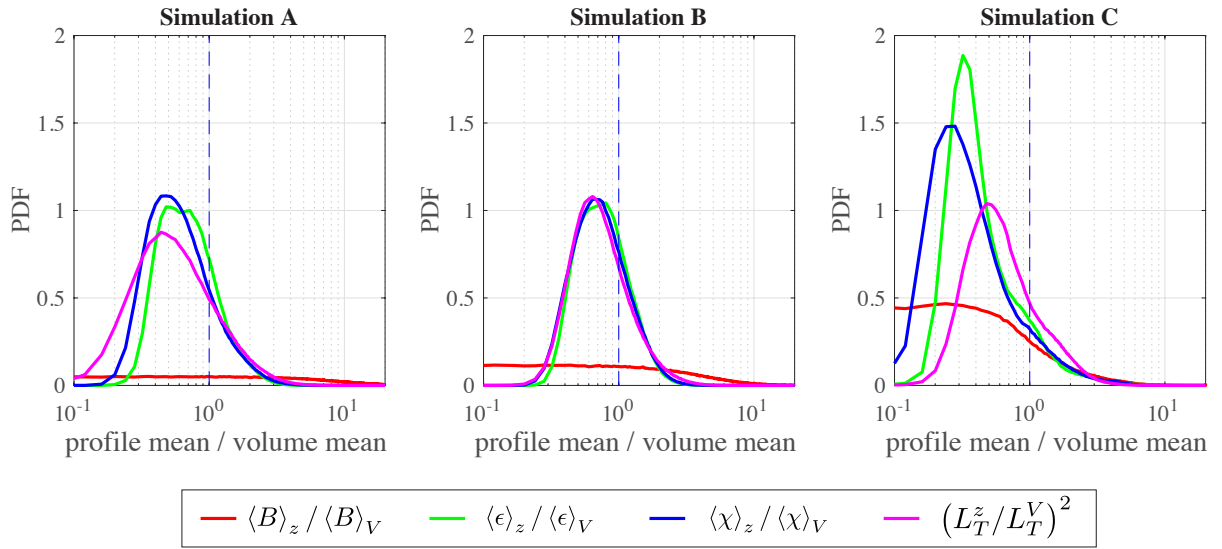
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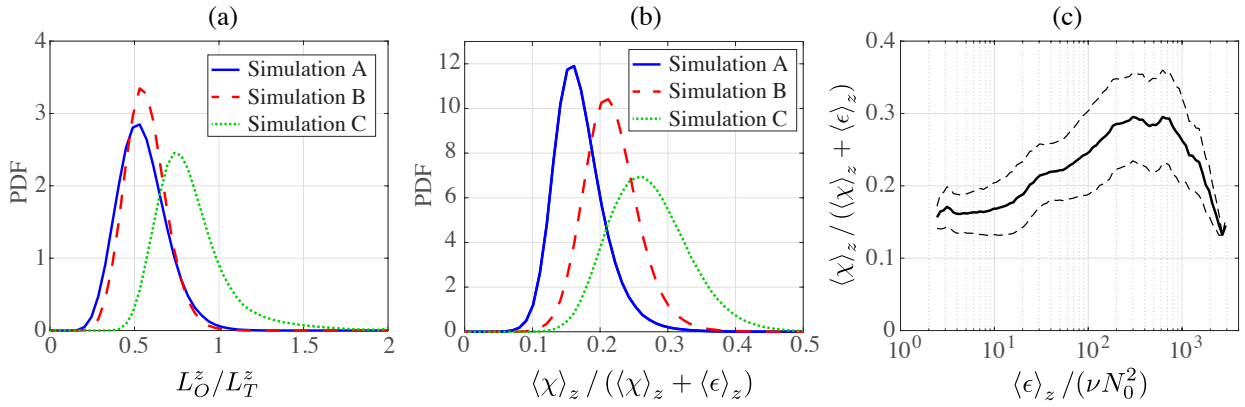
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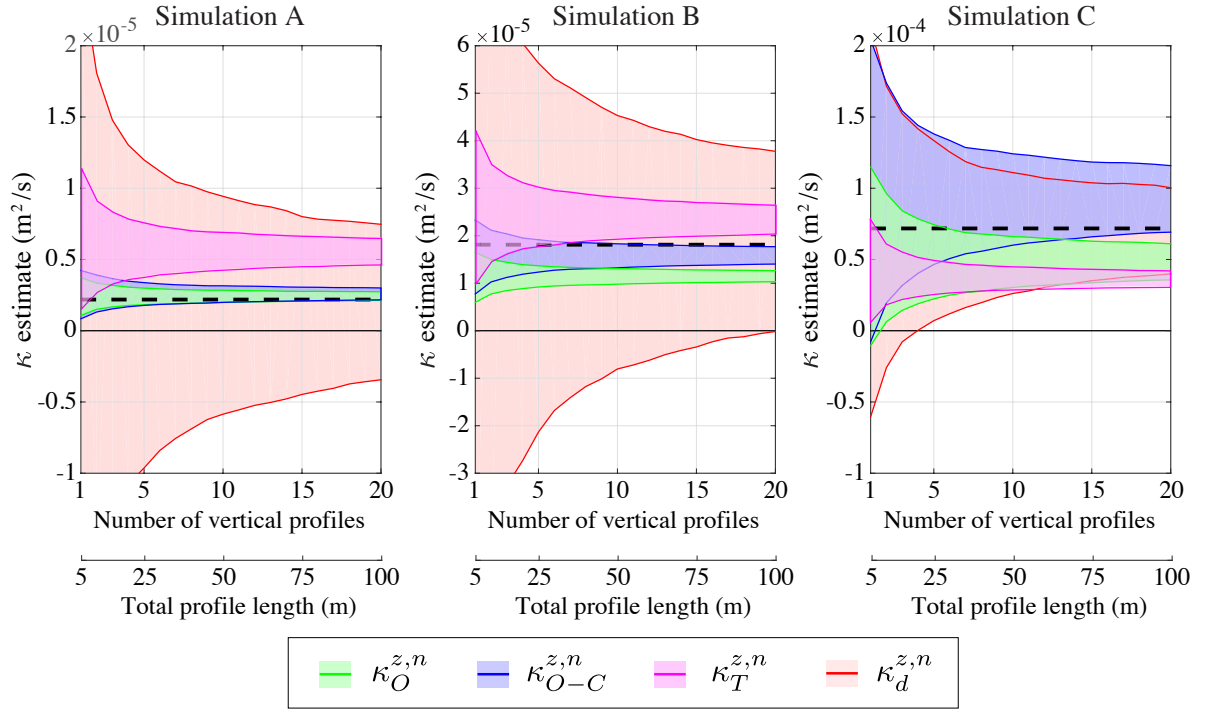
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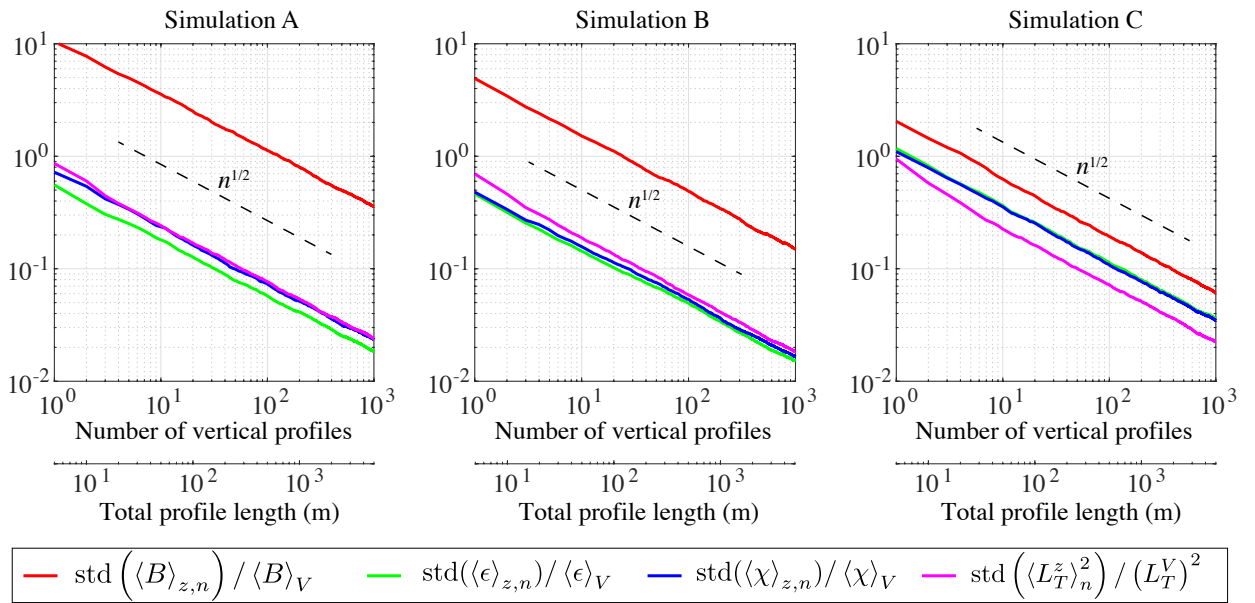
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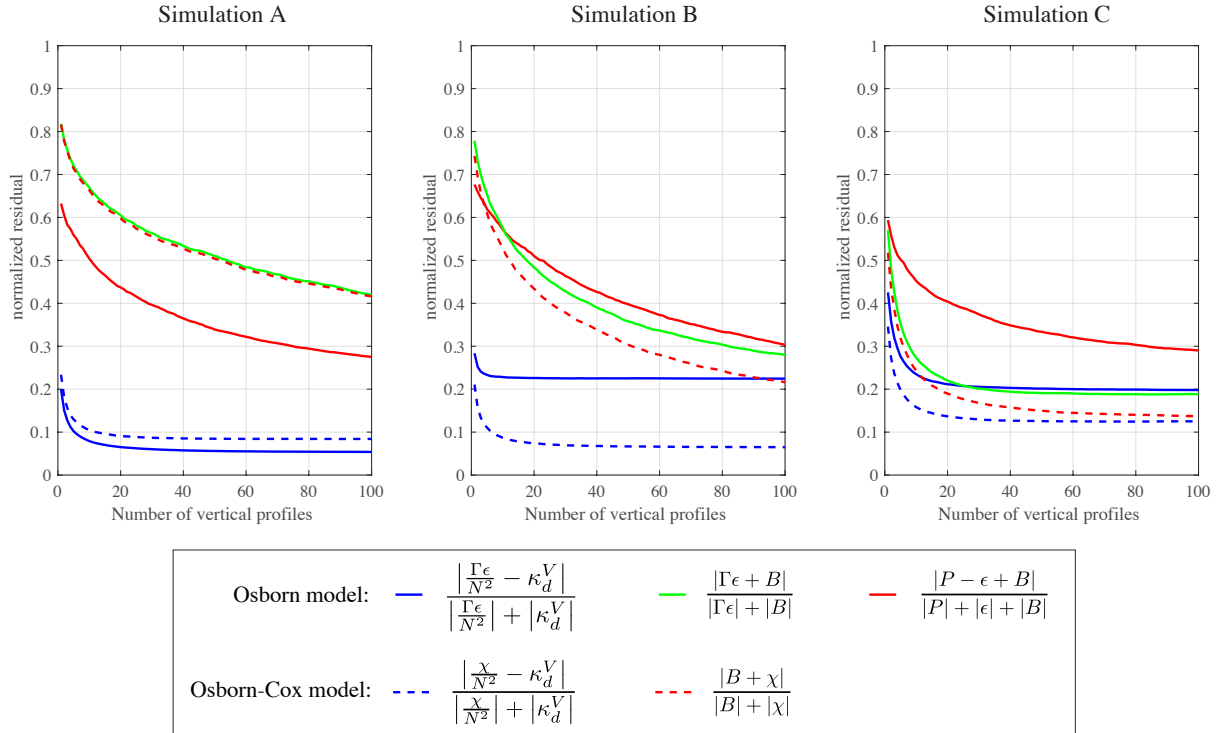
903 FIG. 6. Profile-averaged statistics: (a) Probability density function (PDF) associated with the
 904 Ozmidov and Thorpe scales, (b) PDF of mixing efficiency, (c) mixing efficiency as a function of the buoyancy
 905 Reynolds number. Dashed lines in panel (c) indicate one standard deviation above and below the average value
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907 FIG. 7. Estimates of the vertical diffusivity using the Osborn (green), Osborn-Cox (blue), Thorpe (magenta),
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 911 of the vertical axis are different in each panel.



912 FIG. 8. Standard deviation associated with quantities averaged over n vertical profiles, normalized by the 3D
 913 volume average. Dashed lines show the $n^{-1/2}$ scaling expected from the Central Limit Theorem.



914 FIG. 9. Normalized residual associated with the Osborn and Osborn-Cox relations (blue) and assump-
915 tions used to derive these relations (green and red). The values of ϵ , χ , B , P , and N^2 correspond to an average
916 across the vertical domain and for the specified number of vertical profiles, e.g. $\langle \epsilon \rangle_{z,n}$, and the averaging opera-
917 tors are omitted for clarity.