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1 **Human feeding biomechanics: performance, variation, and** 2 **functional constraints**

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46 **ABSTRACT**

47 The evolution of the modern human (*Homo sapiens*) cranium is characterized by a
48 reduction in the size of the feeding system, including reductions in the size of the facial skeleton,
49 postcanine teeth, and the muscles involved in biting and chewing. The conventional view
50 hypothesizes that gracilization of the human feeding system is related to a shift toward eating
51 foods that were less mechanically challenging to consume and/or foods that were processed
52 using tools before being ingested. This hypothesis predicts that human feeding systems should
53 not be well-configured to produce forceful bites and that the cranium should be structurally
54 weak. An alternate hypothesis states that the modern human face is adapted to generate and
55 withstand high biting forces. We used finite element analysis (FEA) to test two opposing
56 mechanical hypotheses: that compared to our closest living relative, chimpanzees (*Pan*
57 *troglydytes*), the modern human craniofacial skeleton is 1) less well configured, or 2) better
58 configured to generate and withstand high magnitude bite forces. We considered intraspecific
59 variation in our examination of human feeding biomechanics by examining a sample of
60 geographically diverse crania that differed notably in shape. We found that our biomechanical
61 models of human crania had broadly similar mechanical behavior despite their shape variation
62 and were, on average, less structurally stiff than the crania of chimpanzees during unilateral
63 biting when loaded with physiologically-scaled muscle loads. Our results also show that modern
64 humans are efficient producers of bite force, consistent with previous analyses. However, highly
65 tensile reaction forces were generated at the working (biting) side jaw joint during unilateral
66 molar bites in which the chewing muscles were recruited with bilateral symmetry. In life, such a
67 configuration would have increased the risk of joint dislocation and constrained the maximum
68 recruitment levels of the masticatory muscles on the balancing (non-biting) side of the head. Our

69 results do not necessarily conflict with the hypothesis that anterior tooth (incisors, canines,
70 premolars) biting could have been selectively important in humans, although the reduced size of
71 the premolars in humans has been shown to increase the risk of tooth crown fracture. We
72 interpret our results to suggest that human craniofacial evolution was probably not driven by
73 selection for high magnitude unilateral biting, and that increased masticatory muscle efficiency
74 in humans is likely to be a secondary byproduct of selection for some function unrelated to
75 forceful biting behaviors. These results are consistent with the hypothesis that a shift to softer
76 foods and/or the innovation of pre-oral food processing techniques relaxed selective pressures
77 maintaining craniofacial features favoring forceful biting and chewing behaviors, leading to the
78 characteristically small and gracile faces of modern humans.

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94 **INTRODUCTION**

95 Human craniofacial architecture is extreme among living primate species. In particular,
96 modern humans (*Homo sapiens*) exhibit a tall braincase and a small and short maxilla which
97 distinguishes them from even our closest living relatives, the chimpanzees and bonobos of genus
98 *Pan* (Fleagle, Gilbert & Baden, 2010). Reductions in the size and prognathism of the face,
99 combined with increases in neurocranial globularity, have also been shown to differentiate
100 modern humans from some extinct members of the genus *Homo* (Lieberman, McBratney &
101 Krovitz, 2002). *Homo* exhibits an even more pronounced reduction in the size and robusticity of
102 the facial skeleton, as well as in the size of the postcanine dentition and masticatory muscles
103 (e.g., Robinson, 1954; Rak, 1983; Demes & Creel, 1988), relative to australopiths, an extinct
104 informal group of early hominins from which modern humans are likely to be descended (e.g.,
105 Walker, 1991; Wood, 1992; Skelton & McHenry, 1992; Strait, Grine & Moniz, 1997; Strait &
106 Grine, 2004; Kimbel, Rak & Johanson, 2004; Berger et al., 2010). Theories purporting to explain
107 the adaptive significance of masticatory reduction in *Homo* frequently stress the importance of
108 changes in diet, usually involving a shift to foods that require less extensive intra-oral processing
109 (e.g., Robinson, 1954; Rak, 1983; Brace, Smith & Hunt, 1991; Wrangham et al., 1999;
110 Lieberman et al., 2004; Ungar, Grine & Teaford, 2006; Wood, 2009). However, Wroe et al.
111 (2010) suggest that modern human crania are instead adapted to produce forceful bites, based on
112 their conclusion that the human feeding apparatus is mechanically efficient, requires less muscle
113 force than most other hominoids in order to generate comparable bite reaction forces, and should

114 therefore require a less robust structure. This paper evaluates these two alternatives by
115 comparing feeding biomechanics in modern *H. sapiens* to that of chimpanzees (*Pan troglodytes*).

116 A conventional view of cranial gracilization in the lineage leading to modern *Homo* states
117 that this process was spurred by the development of stone tool technologies (e.g., Ungar, Grine
118 & Teaford, 2006), as tool use reduces food particle size (Lucas, 2004), allowing a reduced bite
119 force per chew and/or fewer chews per feeding bout (Lucas & Luke, 1984; Agrawal et al., 1997;
120 Zink & Lieberman, 2016). Under this hypothesis, tool use reduces the selective advantage
121 offered by anatomical features that increase muscle force leverage and/or buttress the face
122 against feeding loads. In addition to tool use, increased reliance on meat eating may have played
123 a role in the initial stages of masticatory reduction in early *Homo* (Lieberman, 2008; Ungar,
124 2012; Zink & Lieberman, 2016). Further gracilization of the jaws and teeth is hypothesized to
125 have occurred with the advent of cooking, which may have been practiced by *H. erectus*
126 (Wrangham, 2009; Organ et al., 2011), by reducing masticatory stresses (Lieberman et al., 2004;
127 Lucas, 2004) and increasing digestive efficiency (Wrangham et al., 1999; Carmody &
128 Wrangham, 2009; Carmody, Weintraub & Wrangham, 2011; Groopman, Carmody &
129 Wrangham, 2015). If gracilization in *Homo* is a consequence of the removal of selection pressure
130 to maintain and resist high magnitude or repetitive bite forces, then human feeding systems
131 should not be optimized to produce high biting forces and the cranium could be structurally weak
132 (i.e., exhibit high stress and strain when exposed to feeding loads).

133 The hypothesis described above is opposed by an alternative interpretation of human
134 feeding mechanics. A paradox of the human cranium is that the marked facial orthognathism
135 exhibited by recent modern humans increases the mechanical advantage (i.e., leverage) of the
136 muscles responsible for elevating the mandible, allowing humans to generate a given bite force

137 with relatively low muscular effort (Spencer & Demes, 1993; O'Connor, Franciscus & Holton,
138 2005; Lieberman, 2008, 2011; Wroe et al., 2010; Eng et al., 2013). Many studies interpret bite
139 force efficiency among primate species as being significant in an adaptive sense (Rak, 1983;
140 Strait et al., 2013; Smith et al., 2015a; Ross & Iriarte-Diaz, 2014), with increases in leverage
141 predicted for species that rely on foods that require forceful biting in order to be processed (e.g.,
142 hard seeds or nuts). Therefore, high biting leverage among humans seemingly contrasts with the
143 hypothesis that the human craniofacial skeleton has experienced relaxed selection for traits that
144 favor forceful biting and chewing behaviors (e.g., Brace, Smith & Hunt, 1991; Lieberman et al.,
145 2004; Ungar, Grine & Teaford, 2006; Wood, 2009). However, Wroe et al. (2010) present an
146 alternative view based on their analysis of modern human, extant ape, and fossil australopith
147 feeding biomechanics. Using finite element analysis (FEA), Wroe et al. (2010) found that their
148 human model was mechanically more efficient at producing bite forces than the other hominoids
149 in their sample. Additionally, they found that the human cranium experienced stresses similar to
150 those in 3 of the 5 other species when models were scaled to the same surface area and bite force,
151 including *Pan*. Consequently, Wroe et al. (2010) conclude that the human skull need not be as
152 robust in order to generate, or sustain, bite reaction forces comparable to those of other
153 hominoids, and that powerful biting behaviors may have been selectively important in shaping
154 the modern human cranium.

155 Here, we use FEA to test two opposing mechanical hypotheses: that relative to
156 chimpanzees, the modern human craniofacial skeleton is 1) less well configured, or 2) better
157 configured to *generate* and *withstand* high magnitude unilateral bite forces. Our analysis builds
158 on previous research into human craniofacial function (e.g., Lieberman, 2008; Wroe et al., 2010;
159 Szwedowski, Fialkov & Whyne, 2011; Maloul et al., 2012) by examining masticatory

160 biomechanics within the context of the constrained lever model (Greaves, 1978; Spencer and
161 Demes, 1993; Spencer, 1998, 1999), which predicts that bite force production in mammals is
162 constrained by the risk of generating distractive (tensile) forces at the working (biting) side TMJ.
163 Under this model, during unilateral biting, reaction forces are produced at the bite point and the
164 working and balancing (non-biting) side TMJs. These three points form a “triangle of support”,
165 and the line of action of the resultant vector of the jaw elevator muscle forces must intersect this
166 triangle in order to produce a “stable” bite in which compressive reaction forces are generated at
167 all three points (Fig. 1A). The resultant vector lies in the midsagittal plane when the muscles are
168 recruited with bilateral symmetry and will pass through the triangle of support during bites on
169 the incisors, canines, and premolars. However, molar biting changes the shape of the triangle
170 such that a midline muscle result may lie outside of the triangle of support. If this occurs, a
171 distractive (tensile) force is generated in the working side TMJ that “pulls” the mandibular
172 condyle from the articular eminence (Fig. 1B). In the case of the mammalian jaw, the soft tissues
173 of the TMJ are well suited to resist compressive joint reaction forces in which the mandibular
174 condyle is being “driven” into the cranium, but they are poorly configured to resist distractive
175 joint forces in which the condyle is being “pulled away” from the cranium (Greaves, 1978).
176 Mammals, including humans (Spencer, 1998), avoid this by reducing the activity of the chewing
177 muscles on the balancing side during bites on the posterior teeth. This draws the muscle resultant
178 vector toward the working side and back within the triangle, but the total muscle force available
179 for biting is reduced, thereby reducing peak bite force magnitudes. Thus, although one might
180 expect that a bite on a distal tooth would produce an elevated bite force due to a short load arm
181 (per a given muscle force), this effect is mitigated by the constraint that the muscle force vector
182 must lie within the triangle of support. A finding that constraints on bite force production were

183 especially strong in humans would be consistent with the hypothesis that the human cranium is
184 poorly configured to generate high unilateral bite forces, and inconsistent with the opposing
185 hypothesis.

186 We further build on previous work by considering intraspecific variation in our analysis
187 of human feeding biomechanics. Our prior work has shown that high degrees of intraspecific
188 variation in cranial shape need not necessarily produce a high degree of intraspecific mechanical
189 variation (Smith et al., 2015b), implying that mechanical patterns are conservative and reflect an
190 underlying common geometry that may be overlain by skeletal traits that can vary without
191 dramatically altering the fundamental mechanical framework of the cranium. A caveat, however,
192 is that Smith et al. (2015b) examined only one species, *P. troglodytes*. Thus, it has yet to be
193 established if this pattern is generalizable across primates (or other vertebrates). Accordingly, we
194 examined mechanical variation among a sample of geographically diverse human crania found to
195 differ notably in shape.

196

197 **MATERIALS & METHODS**

198 **Analysis of human cranial shape variation and selection of specimens for FEA**

199 We analyzed finite element models (FEMs) of six crania lying at the extremes of human
200 variation, as well as one “average” specimen found to conform closely to an average shape. To
201 select specimens, we analyzed shape variation within a sample of modern human (*H. sapiens*)
202 crania using previously collected geometric morphometric (GM) data (Baab et al., 2010). We
203 analyzed 85 landmarks collected from a sample of 88 Holocene human crania housed at the
204 American Museum of Natural History (AMNH) (Tables 1, 2). These included mainly facial
205 landmarks combined with a few that characterize neurocranial shape, corresponding to our focus

206 on facial biomechanics in this study. This sample includes individuals from diverse regions
207 across the globe, and provides a cross-section of populations that differ in cranial robusticity
208 (Baab et al., 2010). Landmark data from these 88 specimens were converted to shape coordinates
209 by Generalized Procrustes analysis (e.g., Bookstein, 1991; Slice, 2005) and analyzed using
210 principal components analysis (PCA). We found that the first 3 principal components (PCs)
211 described 39% of the shape variation in our sample (Fig. 2). In order to maximize shape-related
212 biomechanical variation in our FEMs, we considered variation from all 88 PCs when selecting
213 specimens to be modeled. We first determined those individuals exhibiting the largest distances
214 from the group centroid (i.e., consensus shape), calculated as Euclidean distance using all 88 PCs
215 (Table 3). From among these individuals, we chose the six specimens that exhibited the largest
216 pairwise distances, excluding insufficiently preserved crania, those missing many teeth, and
217 those unavailable for loan (Table 4). These six “extreme” modern human crania included: one
218 male and one female Khoe-San from South Africa (AMNH VL/2463 and AMNH VL/2470,
219 hereafter referred to as “KSAN1” and “KSAN2”); a male from Greifenberg, Austria (AMNH
220 VL/3878, “BERG”); a female from the Malay Archipelago (AMNH 99/7889, “MALP”); a male
221 from the Tigara culture at Point Hope, Alaska (AMNH 99.1/511, “TIGA”); and a male from
222 Ashanti, West Africa (AMNH VL/1602, “WAFR”). An additional specimen, a Native American
223 male from Grand Gulch, Utah (AMNH 99/7365, “GRGL”), was chosen as an “average”
224 representative of human cranial shape based on its close proximity (i.e., small Euclidean
225 distance) to the group centroid and its availability for loan (see Table 3). Note that this individual
226 was incorrectly transcribed as AMNH 99/7333 by Ledogar (2015).

227

228 **Creation of finite element models from “extreme” and “average” human specimens**

229 *Construction of solid models*

230 The seven specimens chosen for analysis were CT-scanned at Penn State's Center for
231 Quantitative Imaging (pixel size = 0.16 mm) and the 2D digital image stacks were used to create
232 seven solid meshes (Fig. 3) using Mimics v 14.0 (Materialise, Ann Arbor, MI, USA), following
233 the methods outlined by Smith et al., 2015 (a,b). Mandibles corresponding to the seven crania
234 (except for BERG and KSAN2, which lacked mandibles; see below) were also scanned so that
235 they could be used to direct muscle force vectors in the loading simulations described below. The
236 crania were solid-meshed at similar densities using tet4 elements (element count:
237 GRGL=2,118,350; BERG=1,928,931; KSAN1=1,620,112; KSAN2=1,392,417;
238 MALP=1,323,093; TIGA=2,059,433; WAFR=1,831,053). Solid meshes were then imported as
239 Nastran (NAS) files into Strand7 (Strand7 Pty Ltd) FEA software.

240 We created two sets of human FEMs that differed in their assigned muscle force and
241 bone properties. One set of human FEMs ("ALL-HUM" models) was assigned human properties
242 for bone tissue and masticatory muscle force, whereas chimpanzee properties were applied to the
243 second set ("CHIMPED" models). The ALL-HUM models provide the most realistic assessment
244 of human cranial mechanics, in terms of the predicted strains and bite forces. These models also
245 allow for a more thorough examination of intraspecific variation in humans. In contrast, the
246 CHIMPED models permit direct comparisons between our humans FEMs and our previously
247 analyzed FEMs of chimpanzees and fossil hominins (Smith et al., 2015a,b). These comparisons
248 focus on shape-related differences in mechanical performance that are free of the effects of
249 differences in cranial size and bone material properties. Therefore, the comparisons between the
250 CHIMPED human models and the chimpanzee data from Smith et al. (2015a,b) most directly

251 address our mechanical hypothesis described above because the hypotheses relate specifically to
252 the mechanical consequences of shape differences.

253

254 *Material properties of tissues*

255 Human cortical bone material properties assigned to the ALL-HUM models were
256 collected from various locations across the craniofacial skeletons of two fresh-frozen human
257 cadavers (female, aged 22; male, aged 42) by measuring their resistance to ultrasonic wave
258 propagation (see Supplementary Information). Previous studies show that freezing has only a
259 very minimal effect on ultrasonic measurements and elasticity of cortical bone (Zioupos et al.,
260 2000). For each location sampled, the elastic (Young's) modulus in the axis of maximum
261 stiffness (E_3) was averaged between the human donors and used to distribute spatially
262 heterogeneous isotropic material properties throughout the seven human FEMs using a method
263 (Davis et al., 2011) analogous to the diffusion of heat through a highly conductive material. To
264 achieve this, values at each of the sampled locations, which ranged from 17.92 GPa to 25.52 GPa
265 (mean=20.61 GPa, SD=1.92), were converted to temperatures and distributed throughout the
266 cortical volume of the FEM. The elastic modulus of cortical bone was then set to vary with
267 temperature during the subsequent loading analysis, with any thermally-induced strains removed
268 from the analysis. For Poisson's ratios, models were each assigned the average of the sampled
269 locations ($\nu_{23} = 0.293$). The same procedure was used to diffuse chimpanzee material properties
270 to the CHIMPED model variants using data collected from a cadaveric female chimpanzee at 14
271 craniofacial regions (Smith et al., 2015a,b). In both the ALL-HUM and CHIMPED sets of model
272 variants, homogeneous isotropic properties were used to model both trabecular bone ($E_3=637$
273 MPa; $\nu_{23}=0.28$) and enamel ($E_3=80,000$ MPa; $\nu_{23}=0.28$), following Smith et al. (2015a,b).

274

275 *Muscle forces and constraints*

276 Jaw adductor muscle forces were applied to both sets of FEMs for the anterior
277 temporalis, superficial masseter, deep masseter, and medial pterygoid under the assumption that
278 the chewing muscles were acting at peak activity levels on both sides of the cranium. These
279 loads allow an estimate of the maximum bite force produced by each individual. In the ALL-
280 HUM variants, muscle forces were applied based on muscle physiological cross-sectional area
281 (PCSA) data reported by van Eijden, Korfagen & Brugman (1997), with forces corrected to
282 account for pennation and differences in gape during fixation using formulae from Taylor &
283 Vinyard (2013). Corrected PCSAs were then used to calculate forces in Newtons (N) such that
284 each cm² of muscle was equivalent to 30 N (Murphy, 1998). These unscaled forces were applied
285 to the “average” specimen (GRGL), while the six “extreme” variants were applied forces that
286 were either scaled up or down based on differences in model size (Table 5), with size represented
287 by model volume (i.e., the summed volume of all tet4 elements in mm³) to the two-thirds power.
288 This muscle force scaling procedure removes the effects of differences in model size on stress,
289 strain, and strain energy density from the mechanical results (Dumont, Grosse & Slater, 2009;
290 Strait et al., 2010). The CHIMPED model variants were also assigned forces that were scaled
291 dependent on their size using PCSA data from an adult female chimpanzee (Strait et al., 2009;
292 Smith et al., 2015a,b). However, rather than scaling the FEMs around the “average” specimen
293 (GRGL), we scaled the forces applied to the CHIMPED models (see Table 5) from the baseline
294 chimpanzee model used for scaling purposes (PC1+) in the analysis by Smith et al. (2015b),
295 permitting size-free comparisons between humans and chimps. For both sets of muscle loadings,
296 plate elements modeled as 3D membrane were “zipped” at their nodes to the surface faces of tet4

297 elements representing each muscle's origin. The scaled muscle forces for each set of analyses
298 were applied using Boneload (Grosse et al., 2007) to the normal surfaces of the plate elements as
299 tractions directed toward their respective insertions on the mandible, with the mandible slightly
300 depressed and the condyles translated onto the articular eminences (Dumont, Piccirillo & Grosse,
301 2010). Mandibles were only used here to direct these vectors. In the case of the BERG specimen,
302 which was lacking its mandible, a scaled version of the GRGL mandible was used to define the
303 orientation of muscle force vectors. Similarly, a scaled version of the KSAN1 mandible was used
304 to replace the missing mandible in KSAN2.

305 For both sets of biting simulations, each of the seven FEMs was oriented such that one of
306 three axes (i.e., X, Y, or Z) was parallel to the occlusal plane. Each model was constrained at a
307 single node against translation in all axes at the working-side TMJ, while the balancing-side TMJ
308 was constrained only in the superoinferior and anteroposterior directions (Strait et al., 2009;
309 Smith et al., 2015a,b), thus creating an axis of rotation around the TMJs. Models were subjected
310 to simulations of left premolar (P³) and left molar (M²) biting by constraining a node in the
311 center of occlusal surface in each tooth, respectively, in the superoinferior direction. These
312 constraints generated strains in the craniofacial skeleton, as well as reaction forces at the TMJs
313 and bite point, upon the application of muscle forces.

314

315 *Analysis of model output parameters*

316 Following Smith et al (2015a,b), we displayed global strain patterns using strain maps.
317 These maps are analogous to histograms in that they illustrate strain magnitudes at thousands of
318 nodes simultaneously, but have the added advantage of preserving spatial information. In
319 addition, we collected strain data generated by each FEM from surface elements at 14 locations

320 across the craniofacial skeleton (Fig. 4). These locations correspond to those included in
321 previous *in vitro* and *in silico* (e.g., FEA) studies on primate feeding biomechanics (e.g.,
322 Hylander and Johnson, 1991, 1997; Ross et al., 2011; Smith et al., 2015a,b). At each location, we
323 examined several strain metrics from each of the seven FEMs in order to understand patterns of
324 deformation. These included maximum principal strain (tension), minimum principal strain
325 (compression), maximum shear strain (maximum principal strain – minimum principal strain),
326 von Mises strain (distortional strain or non-isometric strain), and strain energy density (SED, the
327 strain energy stored at a given point). Additionally, strain mode, the absolute value of maximum
328 principal strain divided by minimum principal strain, was recorded for each location. This
329 measure indicates whether tension or compression is dominant at a given location.

330 Data on the reaction forces generated at constrained nodes (i.e., the bite point and two
331 TMJs) were recorded in Newtons (N). Reaction forces at the P³ and M² were recorded relative to
332 the occlusal plane, while reaction forces at the left and right TMJs were recorded and compared
333 relative to a user-defined “triangle of support” Cartesian coordinate system, with one of three
334 axes perpendicular to a reference plane defined by the “triangle of support” formed by the
335 constrained nodes at the bite point and two articular eminences (Smith et al., 2015a,b). The
336 efficiency of bite force production at a given bite point in each model was also compared using
337 the mechanical advantage (MA), a measure of masticatory muscle efficiency or leverage,
338 calculated as the ratio of bite force output to muscle force input.

339 In the evaluation of our mechanical hypothesis, we first inspected data collected from the
340 ALL-HUM models for large levels of intraspecific variation that could potentially invalidate the
341 functional significance of our results. Strain magnitudes and SED at each of the 14 sampled
342 locations were examined for large differences between individuals, in addition to a comparison

343 of coefficients of variation (CVs) at specific locations. Differences in the spatial patterning of
344 strain magnitudes between the ALL-HUM models were also compared using strain maps, in
345 addition to variation in biting efficiency (i.e., MA). Lastly, we also calculated CVs for von Mises
346 strain and MA in the CHIMPED model variants for direct comparison with the chimpanzee CVs
347 reported by Smith et al. (2015b) using the Fligner-Killeen test for equal CVs.

348 To analyze relative mechanical performance in our human FEMs, we focused on
349 comparisons between the CHIMPED humans and our previously analyzed FEMs of chimpanzee
350 crania (Smith et al., 2015b). Specifically, we compared the magnitudes of von Mises strain,
351 considered to be a key metric in assessing regional bone strength (Keyak & Rossi, 2000), at the
352 14 sampled locations, as well as differences in biting efficiency, between humans and chimps.
353 We tested for significant differences between species using the Mann-Whitney U test.

354

355 ***In vitro* validation of specimen-specific human cranial FEM**

356 Data on *in vitro* bone strain collected during simulated P³ biting in a cadaveric human
357 head were used to validate our results. As noted above, two human heads were used to gather
358 data on the properties of craniofacial cortical bone. Before the removal of bone samples, the
359 male specimen was CT-scanned, and strain data from 14 craniofacial locations were collected
360 during a series of *in vitro* loading analyses (see Supplementary Information). Digital images of
361 the specimen were then used to construct an eighth FEM, the *in vitro* loadings were replicated
362 using FEA, and strain data were collected from the FEM at locations corresponding to the 14
363 gage sites. The *in vitro* and *in silico* strain data were then compared in order to establish the
364 degree to which assumptions regarding geometry and material properties introduce error into an
365 FEM, where error is represented by the differences between the *in vitro* (observed) and *in silico*

366 (expected) results, divided by the expected results. These data were also analyzed using ordinary
367 least squares (OLS) regression. Lastly, the orientations for both maximum and minimum
368 principal strain in FEM were visually compared to those recorded during the *in vitro* loadings.

369

370 RESULTS

371 *In vitro* validation of specimen-specific human cranial FEM

372 Strain magnitudes recorded during *in vitro* P³ loadings of the human cadaveric specimen
373 and the results of the specimen-specific FEA are listed in Table 6. Comparisons of these data
374 reveal that the specimen-specific FEM generated strains very similar in magnitude to those
375 generated during the *in vitro* loadings. Results of the regression analysis on log-transformed
376 strain data confirm a close correspondence between *in vitro* and *in silico* results, with significant
377 regressions of $0.845x+0.194$ ($r^2=0.909$, $p<0.001$) and $0.849x+0.186$ ($r^2=0.953$, $p<0.001$) for
378 maximum principal strain and minimum principal strain, respectively. However, assumptions
379 regarding geometry and material properties did introduce error into the FEM (see Table 6).
380 Visual inspection of principal strain orientations in the specimen-specific FEA reveals that
381 orientations for both maximum principal strain and minimum principal strain at the 14 sampled
382 locations were also very similar to those recorded from the 14 gage locations during the *in vitro*
383 analysis (Fig. S3 – Fig. S7).

384

385 Shape-related variation in human feeding biomechanics

386 *Variation in strain magnitude and spatial patterning*

387 Box-plots of strain and SED distributions recorded from the ALL-HUM models at the 14
388 sampled locations during premolar (P³) and molar (M²) biting are shown in Fig. 5 (see also

389 Tables S1 and S2). Despite notable differences in craniofacial morphology between the models,
390 comparisons of strain magnitudes reveal strong similarities. For P³ biting, the highest strain
391 magnitudes were experienced at the working nasal margin (Location 12), although on average
392 higher tensile strain magnitudes were generated at the working and balancing postorbital bars
393 (Locations 4 and 5). During M² biting, the working zygomatic root (Location 8) was subjected to
394 the highest strain magnitudes, except that tension was greatest at the balancing postorbital bar.
395 During both bites, low strain magnitudes were generated along the supraorbital torus (Locations
396 1-3), the balancing zygomatic root (Location 9), balancing infraorbital (Location 11), and the
397 zygomatic bodies (Locations 13 and 14). All FEMs of human crania were found to exhibit this
398 general pattern.

399 Some regions of the face did exhibit large differences among individuals. In particular,
400 the FEMs were found to differ in von Mises strain magnitude by as much as 210% at the nasal
401 margin, which also has the highest CVs for all forms of strain during both P³ and M² biting
402 (Table 7), with the exception of minimum principal strain at the working dorsal orbital (Location
403 2) and balancing infraorbital (Location 11) during P³ biting, SED at the working dorsal orbital
404 (Location 2) during P³ biting, and the balancing zygomatic body (Location 14) for both bites.

405 Strain mode was nearly always compressive or tensile at a given location across the seven
406 ALL-HUM models (Fig. 6), with a few exceptions. During premolar biting, only 3 locations
407 varied with respect to strain mode (Locations 1, 10, 11), with only one FEM differing from the
408 other models in each case. These three locations also differed in strain mode during molar biting,
409 with Locations 1 and 10 exhibiting slightly higher levels of variation, in addition to variation in
410 strain mode at Location 4.

411 By comparison with CHIMPED FEMs, humans were found to exhibit lower levels of
412 shape-related variation in von Mises strain magnitude and lower CVs than chimpanzees at the 14
413 sampled locations (Table 8). However, results of the Fligner-Killeen tests reveal that only 3 of
414 the 14 “gage sites” exhibit significant differences in CV values. Specifically, humans were found
415 to exhibit a significantly lower CV at the zygomatic arches during both P³ and M² biting at the
416 working infraorbital during P³ biting.

417

418 *Variation in the spatial patterning of strain concentrations*

419 Despite some large differences in strain magnitude, the spatial patterning of strain
420 distributions was similar across the ALL-HUM models. The color maps during P³ biting (Fig. 7)
421 reveal two predominant deformation regimes that are common across the seven FEMs: (1)
422 superior displacement of the anterior maxilla in proximity to the loaded P³, which creates highly
423 tensile and compressive (hence highly shearing) strains surrounding the root of the nasal margin,
424 compression along the nasal margin, and compression at the working zygomatic root; and (2)
425 frontal bending of the zygomae under the inferiorly directed pulling action of the masticatory
426 muscles, which generates tension at the zygomatic body and near the zygomaticomaxillary
427 junction, particularly at the working-side, and deforms the orbit such that it is tensed along an
428 inferolaterally-oriented axis and compressed along a superolaterally-oriented axis.

429 The color maps of strain patterning during M² biting were also generally similar across
430 the ALL-HUM models (Fig. 8). As expected, all models exhibited lower strain magnitudes in the
431 lower maxillary region during molar biting compared to premolar biting, but higher
432 concentrations of compressive strain at the working zygomatic root. Molar biting was also
433 associated with the same type of frontal bending, zygomatic torsion, and orbital deformation that

434 was observed for premolar biting, with relatively large concentrations of strain at the postorbital
435 bars, orbital margins, and medial infraorbital.

436 In their study of chimpanzee biomechanical variation, Smith et al. (2015b) compared
437 color maps of principal strain magnitudes in their 6 models with the scales normalized to an
438 average of 10 landmarks (Locations 1-5, 8-12). They suggest that, by illuminating similarities
439 and differences between individuals in the concentrations of relatively high and low strain
440 concentrations through this normalization step, such “relative strain” maps strain may be
441 particularly informative in comparative analyses of craniofacial function. When viewed in this
442 manner (Fig. 9), the CHIMPED human models more clearly reveal a shared pattern of facial
443 deformation that differs from that of chimpanzees under identical loading conditions, which was
444 predominantly characterized by torsion of the zygoma and resulting orbital deformation under
445 the inferiorly-directed masseteric muscle force.

446

447 *Variation in bite force production and efficiency*

448 The ALL-HUM models exhibit moderate differences in bite force production and
449 efficiency (mechanical advantage, MA) at P³ and M² bite points (Table 9). With respect to bite
450 force production, humans generated premolar bite forces that ranged from 333 to 507 N when
451 loaded with scaled masticatory muscle forces. The MA range for premolar biting was 0.34-0.43
452 with all but one individual (WAFR) occupying a narrower range of 0.39-0.43. Molar bite forces
453 ranged from 496 to 756 N. In terms of leverage, most FEMs exhibited molar MAs of 0.57-0.64,
454 but with the WAFR model again being considerably less efficient (0.53).

455 When compared to the chimpanzee data in Smith et al. (2015a), the CHIMPED human
456 models analyzed here were found to exhibit somewhat lower ranges of variation in biting MA.

457 However, results of the Fligner-Killeen tests reveal no significant differences in CV values
458 between the species at either the P³ (chimp=8.67, human=5.65; p=0.18) or M² (chimp=8.11,
459 human=6.67; p=0.13) bite point.

460

461 *Variation in reaction forces generated at the temporomandibular joints*

462 During premolar biting, all seven of the ALL-HUM models generated strongly
463 compressive reaction forces at both TMJs (see Table 9), similar to the results for chimpanzees
464 (Smith et al., 2015b). However, unlike in chimpanzees, M² biting generated distractive (tensile)
465 reaction forces at the working-side TMJ that would have “pulled” the mandibular condyle away
466 from the articular eminence in five of the seven models. In order to remove distractive forces,
467 these models required reductions in the muscle force applied to the balancing-side, which ranged
468 from 5% to 15% (see Table 9). Interestingly, when loaded with chimpanzee muscle forces, all
469 seven of the CHIMPED human models exhibit distractive forces in the working TMJ during M²
470 biting, with larger muscle force reductions required to eliminate the distraction (see below).

471

472 **Biomechanical “performance” of human feeding**

473 *Structural stiffness of the human craniofacial skeleton*

474 Direct comparisons of shape-related mechanical performance between our human FEMs
475 and our previously analyzed chimpanzee FEMs (Smith et al., 2015a,b) were permitted by the
476 CHIMPED models. These comparisons reveal that the human craniofacial skeleton is less stiff
477 and experiences von Mises strains that are elevated relative to those experienced by chimpanzees
478 when subjected to identical loading conditions (Fig. 10). Several of the sampled locations were
479 found to experience significantly higher magnitudes in humans during both P³ and M² biting

480 following the results of Holm-Bonferroni-corrected Mann-Whitney U tests (Table 10). These
481 included the working nasal margin (Location 12), postorbital bars (Locations 4 and 5), working
482 zygomatic root (Location 8), and the working dorsal orbital (Location 2). However, strains at the
483 mid-zygomatic arches in humans were within the range observed for chimpanzees (which are
484 extremely variable). Additionally, human zygomatic bodies were found to be structurally stiff,
485 with significantly lower von Mises strain magnitudes than chimpanzees.

486

487 *Human bite force production and mechanical efficiency*

488 Analysis of our CHIMPED human FEMs reveals that human crania are capable of
489 generating bite forces with higher mechanical efficiency than chimpanzees (Fig. 11). Pairwise
490 comparisons using the Mann-Whitey U test demonstrate that these differences are significant at
491 both P³ ($U=1.5$, $z=-2.73$, exact $p=0.003$) and M² ($U=1$, $z=-2.79$, exact $p=0.002$) bite points.
492 However, unlike chimpanzees, all seven of the CHIMPED human models generated highly
493 distractive (tensile) reaction forces at the working-side TMJ during molar biting. Therefore,
494 molar biting in humans increases the risk of having the muscle resultant vector fall outside the
495 triangle of support. To bring the joint back into compression, a reduction in balancing side
496 muscle force of 15%-30% was required (Table 11).

497

498 **DISCUSSION**

499 *In vitro* validation

500 In order to validate the findings of our mechanical analysis, we compared *in vitro* bone
501 strain in a cadaveric human head during simulated P³ biting to the results of a specimen-specific
502 FEA. We found the results of our specimen-specific FEA corresponded quite well with *in vitro*

503 data. In addition to the notable similarities in strain orientation at the 14 sampled locations,
504 results of the regression analysis reveal that FEA can predict *in vitro* strain magnitudes with a
505 high degree of accuracy (r^2 values >0.9). Similarly, Nagasao et al. (2005) were able to validate a
506 dry bone human cranium with a high degree of accuracy ($r^2=0.989$). However, these authors
507 examined only 2 gage sites and they simulated biting by applying forces to teeth, thus omitting
508 the impact of muscle loading. A greater number of sites were included in an analysis by
509 Szwedowski, Fialkov & Whyne (2011), who found that their FEM results predicted *in vitro* data
510 with an r^2 of 0.73. Toro-Ibacache et al. (2015) also applied point loads to a cadaveric human
511 head and validated strains at two locations in a specimen-specific FEM, finding broad
512 similarities.

513 Although we found excellent correspondence between *in vitro* and *in silico* results, it is
514 clear that FEA does incorporate error (see Table 6). This error was deceptively large at some
515 “gage sites,” particularly in areas of low strain. For example, error for maximum principal strains
516 at the balancing dorsal orbital (Location 3) was 80%, but this represents a difference between
517 experimental and FEA results of only 2.67 microstrain ($\mu\epsilon$). Generally speaking, this is not a
518 meaningful difference in the context of vertebrate feeding biomechanics, where some regions of
519 the cranium can experience strain in the thousands of microstrain. However, some moderately
520 strained areas exhibited high error percentages. In particular, the working infraorbital validated
521 well for minimum principal strain, but error for maximum principal strain was nearly 50%. This
522 discrepancy may be related to the morphology of the bone that forms the thin anterior wall of the
523 maxillary sinus, which is susceptible to large modeling errors (Maloul, Fialkov & Whyne, 2011),
524 or could be a result of simplifications to the thin bones of the nasal cavity (see Toro-Ibacache et
525 al., 2015).

526

527 **Mechanical variation**

528 We found that the ALL-HUM models exhibited generally low levels of shape-related
529 mechanical variation in strain magnitude and bite force production. Additionally, though some
530 regions (e.g., the nasal margin) were found to exhibit large differences in strain magnitude, our
531 human FEMs shared a common pattern of the spatial distribution of relatively high and low
532 strain concentrations. These findings are similar to those of Smith et al. (2015b), who found
533 broad similarities in strain patterning among on a sample of chimpanzee FEMs that differed
534 notably in shape. Similarly, Toro-Ibacache, Zapata Muñoz & O'Higgins (2015) found broad
535 similarities between two notably distinct human cranial FEMs. Our finding that the ALL-HUM
536 models exhibit low levels of mechanical variation supports the functional significance of the
537 comparisons of shape-related mechanical performance made between our CHIMPED human
538 FEMs and our previously analyzed chimpanzee FEMs (Smith et al., 2015a,b), which focused
539 purely on mechanical differences resulting from geometrical/architectural variation in the
540 craniofacial skeleton.

541

542 **Mechanical performance in humans and chimpanzee**543 *Craniofacial strength: Is the human face weak?*

544 Our results suggest that the modern human craniofacial skeleton is structurally less
545 strong, in terms of resistance to masticatory stress, than that of chimpanzees when subjected to
546 identical loading conditions (i.e., same properties and constraints, muscle forces scaled to model
547 size). In the CHIMPED variants of our human FEMs, most of the locations analyzed experienced
548 von Mises strain magnitudes that were elevated relative to chimpanzees, in particular the

549 working nasal margin, the postorbital bars, the working zygomatic root, and the working dorsal
550 orbital region. Exceptions to this pattern include the zygomatic arches, where strains were
551 bracketed by the range of values seen in chimp FEMs, and the prominence of the zygomatic
552 body (i.e., the “cheek bone”), which is apparently strong in modern humans.

553 During unilateral P³ biting, the nasal margin of modern humans experienced von Mises
554 strains that were on average more than 350% greater than chimpanzees. Similarly, previous
555 investigations identify the “root” of the nasal margin to be an area of high stress and strain
556 during masticatory loading in humans (Endo, 1965, 1966; Arbel, Hershkovitz & Gross, 2000;
557 Szwedowski, Fialkov & Whyne, 2011; Maloul et al., 2012). This region is often described as a
558 pillar-like structure (Benninghoff, 1925; Bluntschili, 1926), or section of a frame-like structure
559 (Görke, 1902; Endo, 1965, 1966), that resists mainly compression during anterior tooth biting.
560 The results of our analysis are in general agreement with these findings, except that tension at the
561 nasal margin was also found to be high in magnitude, indicating intense bending and shearing of
562 the lower maxillary region during anterior tooth biting (see Fig. 7 and Fig. 9).

563 In addition to the nasal margin, the postorbital bars of the human FEMs were also found
564 to experience highly elevated von Mises strain magnitudes compared to chimpanzees. However,
565 adjacent regions, including the zygoma/zygomatic body (“cheek bone”) region and zygomatic
566 arch, were found to be similar in strength to the lower end of the chimpanzee range. Mechanical
567 analyses of *Paranthropus boisei* and *Australopithecus africanus* (Smith et al., 2015a) show a
568 similar pattern of relatively low strains in the zygomatic body. Smith et al. (2015a) suggest that
569 the structural strength of the zygomatic body in australopiths could be adaptively significant,
570 offering as one possibility that it serves to reduce strains in the nearby zygomatico-maxillary
571 suture. In pigs, it has been demonstrated that unfused sutures can fail at relatively modest stress

572 levels (e.g., Popowics & Herring, 2007), so some bony facial regions may serve to shield nearby
573 sutures from masticatory stresses rather than bone itself (Wang et al., 2012). Among smaller-
574 faced modern human crania, the zygomatico-maxillary suture may be especially prone to
575 experiencing relatively large masticatory stresses. In our FEMs, the largest strains in this region
576 of the mid-face were generated medial to the zygomatico-maxillary suture. The location of these
577 elevated strain magnitudes corresponds roughly to the location of facial fractures experienced
578 commonly during physical altercations (Ellis, El-Attar & Moos, 1985). Facial fractures are also
579 common at the postorbital bar, as opposed to the zygomatic body or zygomatico-maxillary
580 suture, when the zygomatic body is exposed to traumatic blows (Ellis, 2012; Pollock, 2012).
581 Therefore, it is possible that the strength of the human zygomatic body, and perhaps the relative
582 weakness of the postorbital bar, is related to diverting stress from sutures that might otherwise
583 fail under relatively lower stress magnitudes.

584 In addition to the zygomatic body (“cheek bone”) region, humans were found to exhibit
585 lower average von Mises strains and markedly lower peak strains than chimpanzees at the mid-
586 zygomatic arch, although human values were bracketed by the range of chimp values. This
587 potentially reflects differences in arch length. Specifically, the size of the temporalis muscle,
588 which is correlated with the area of the infratemporal fossa (Weijjs & Hillen, 1984), is
589 significantly reduced in humans compared to that of chimpanzees (Taylor & Vinyard, 2013).
590 Demes & Creel (1988) show that the area of the infratemporal fossa is nearly half that of
591 chimpanzees, meaning that the total length of the zygomatic arch is also reduced. Bone strain
592 analyses demonstrate that the arch is subjected to sagittal bending, as well as torsion along its
593 long axis (e.g., Hylander, Johnson & Picq, 1991; Hylander and Johnson, 1997; Ross, 2001; Ross
594 et al., 2011). Predictions based on beam theory therefore suggest that a decrease in the length of

595 the arch will lessen these bending and torsional moments, whereas a reduction in the height
596 and/or breadth of the arch will weaken it under bending and shear, respectively.

597 Functional interpretations based on the morphology of the zygomatic arch are
598 complicated by the fact that the temporalis fascia has been hypothesized to stabilize it from the
599 inferiorly-directed pulling action of the masseter muscle (Eisenberg & Brodie, 1965). Curtis et
600 al. (2011) tested this hypothesis using FEA and found that models that do not include the
601 temporalis fascia will overestimate strains in the arch and surrounding regions, including the
602 postorbital bar and infraorbital. However, they also found that their models lacking a fascia
603 generated strains more similar in magnitude to those collected during *in vivo* experiments
604 (Hylander, Johnson & Picq, 1991; Hylander and Johnson, 1997; Ross, 2001; Ross et al., 2011).
605 Similarly, previous FEA studies on primate crania that have not included a modeled fascia (e.g.,
606 Ross et al., 2005, 2011; Strait et al., 2005) also find broad agreement with *in vivo* data.
607 Therefore, we did not feel that it was necessary to include this structure in our FEMs.
608 Importantly, Curtis et al. (2011) did not actually model the temporalis fascia, rather, they applied
609 external forces along the margin of the attachment of the fascia. This procedure assumes that the
610 load transferred to bone by the fascia is evenly distributed around its perimeter. However, the
611 fascia is subjected to load by the inferiorly directed force produced by those temporalis fibers
612 that arise off of the deep surface of the fascia. This force should elevate tension in the fascia
613 along its superior margin (i.e., where it arises off of the superior temporal line) while reducing
614 tension along its inferior margin (i.e., along the arch). This factor may mitigate the role of the
615 fascia in resisting the contraction of the masseter muscle.

616 Although the brow ridges are not thought to play an important role in masticatory stress
617 resistance (e.g., Picq & Hylander, 1989; Hylander, Johnson & Picq, 1991; Ravosa, 1991a,b;

618 Ravosa et al., 2000) it is interesting to note that our human FEMs experienced higher von Mises
619 strain magnitudes than chimpanzees at all three of the supraorbital sites examined, particularly
620 during premolar biting. Between the human and chimpanzee samples, differences were found to
621 be greatest at the working and balancing dorsal orbitals, not the dorsal interorbital, supporting the
622 idea that the brow ridge cannot be modeled as a bent beam (Picq & Hylander, 1989; see also
623 Chalk et al., 2011). The fact that the smaller brows of humans experienced elevated strain
624 magnitudes during biting could be interpreted as meaning that large brow ridges are an
625 adaptation to resist masticatory loads. However, a wealth of experimental data on humans and
626 non-human primate species has shown (e.g., Hylander, Johnson & Picq, 1991; Ravosa et al.,
627 2000; Szwedowski, Fialkov & Whyne, 2011; Ross et al., 2011; Maloul et al., 2012) that strains
628 along the supraorbital margin are relatively low during biting and chewing, which is supported
629 by the results presented here. Therefore, it is more reasonable to interpret differences in
630 supraorbital morphology between humans and chimpanzees as being related to some non-dietary
631 function, and that the resulting increases in brow ridge strain among humans are experienced as a
632 secondary byproduct. For example, Moss and Young (1966) suggest that a large separation is
633 formed posterior to the orbits when brain size is small, forming a supraorbital ridge. When brain
634 size is large, the frontal bone is more steeply inclined posterior to the orbits, forming a vertical
635 forehead rather than a large torus. A byproduct of this missing bar of bone above the orbits
636 among modern humans could be that strain magnitudes are mildly elevated in that region.

637 Overall, our findings show that the human craniofacial skeleton is weaker than that of
638 chimpanzees when subjected to feeding loads. These findings support the hypothesis that dietary
639 changes involving a shift to softer and/or more processed foods along the modern human lineage
640 has led to masticatory gracilization and reduced structural strength of the bony facial skeleton

641 (e.g., Lieberman et al., 2004). However, in their biomechanical analysis, Wroe et al. (2010)
642 recently found that although the human cranium is less robust, it experiences low peak strains
643 and an even distribution of facial strain magnitudes compared to extant apes and fossil
644 australopith species. Differences between our results and those of Wroe et al. (2010) could
645 reflect differences in the way muscle loads were applied to the models in each analysis and/or the
646 manner in which models were constrained. For example, we applied both normal and tangential
647 tractions over entire muscle areas using Boneload (Grosse et al., 2007), whereas Wroe et al.
648 (2010) loaded their models with muscles modeled as straight pre-tensioned beam elements.
649 However, we conducted a sensitivity analysis to explore this possibility further (see
650 Supplementary Information) and found that these differences in methodology only resulted in
651 small differences in strain magnitude at most locations across the craniofacial skeleton.

652 Another possible explanation for the differences between our study and the study by
653 Wroe et al. (2010) relates to the magnitudes of the applied muscle forces. Wroe et al. (2010)
654 subjected their FEMs to three sets of simulated biting on various teeth. In their first simulation of
655 the three, FEMs were assigned a set of species-specific muscle forces (or muscle force estimates)
656 from the literature. In a second simulation, models were scaled to the surface area of their
657 chimpanzee model and re-loaded using chimpanzee muscle forces. Lastly, in the third
658 simulation, models were scaled to the surface area of their chimpanzee model and loaded with
659 muscle loads required to generate an equivalent bite force. In this third simulation, the high
660 biting leverage offered by the retracted human face meant that the forces required to generate a
661 bite compared to the other hominoids examined were relatively low. Therefore, Wroe et al.
662 (2010) concluded that the human facial skeleton may in fact be well-adapted to resist masticatory
663 stresses generated during high magnitude biting. Importantly, however, mean element von Mises

664 stresses were found to be relatively high in their human FEM during the second simulation,
665 where FEMs were scaled to the same surface area and loaded with equivalent muscle forces.
666 This is the most similar of their three scaling procedures to the scaling performed here (scaling
667 muscle forces to model volume^{2/3}), which we believe is the best means for removing the effects
668 of size on comparisons of mechanical performance (e.g., Dumont, Grosse & Slater, 2009; Strait
669 et al., 2010).

670

671 *Bite force production and efficiency: are humans suited to produce large biting forces?*

672 When analyzed using human bone and muscle properties (i.e., ALL-HUM models), our
673 human FEMs produced bite forces of 333-507 N at the premolar (P³) and 496-756 N at the molar
674 (M²). These results are similar to, but lower than, previous estimates of human bite force
675 production using both 2D and 3D modeling techniques (e.g., Wroe et al., 2010; Eng et al., 2013).
676 For example, using skeletal measurements and data on muscle cross-section, Eng et al. (2013)
677 recently estimated that humans are capable of producing approximately 660-1106 N of M² bite
678 force, while Wroe et al. (2010) estimated a maximum unilateral M² bite force of 1109-1317 N
679 using FEA. However, our M² bite force results are bracketed by bite force transducer data
680 collected from various western populations, which range from approximately 368 N (Sinn, de
681 Assis & Throckmorton, 1996) to around 911 N (Waltimo, Nystram & Kananen 1994), although
682 Inuit males have been shown to produce an average of 1277 N in M² bite force (Waugh, 1937).
683 Therefore, our results for bite force production lie within and do not exceed the known range of
684 *in vivo* variation exhibited by recent human populations.

685 Because chimpanzees have absolutely and relatively larger jaw adductor muscles than
686 humans (e.g., Taylor & Vinyard, 2013), it is no surprise that the chimp FEMs were capable of

687 producing more forceful bites than our human FEMs when loaded with species-specific muscle
688 forces (compare data in Table 9 to Smith et al., 2015b, Table 4). However, when loaded with
689 muscle forces scaled to remove differences in size (as in the CHIMPED model variants), we
690 found that humans are more *efficient* producers of bite forces, in terms of biting leverage,
691 consistent with the findings of Wroe et al. (2010). Specifically, the mechanical advantage (MA)
692 for P³ biting in humans ranged 0.39-0.47, compared to 0.32-0.42 in chimpanzees (Smith et al.,
693 2015b), with only two chimps overlapping the human range. Humans were found to exhibit even
694 more elevated leverage during M² biting (0.60-0.71), with only one individual overlapping the
695 chimpanzee range (0.49-0.61). When comparing these data using statistical analysis as a
696 heuristic guide, humans were found to be significantly more efficient at producing bite forces at
697 both mesial and distal bite points. The CHIMPED humans were even found to exhibit a biting
698 efficiency similar to that observed in australopiths (Smith et al., 2015a). In fact, P³ MA in *P.*
699 *boisei* (0.40) and *A. africanus* (0.41) were near the lower end observed in humans. The FEM of
700 *A. africanus* also generated M² bites with similar efficiency (0.62) to humans, whereas *P. boisei*
701 produced more mechanically efficient (0.75) molar bites (Smith et al., 2015a).

702 Our data on bite force efficiency in humans support previous findings that have
703 demonstrated the mechanical advantage of modern human bony facial architecture compared to
704 both non-modern humans and non-human primate species (e.g., Spencer & Demes, 1993;
705 O'Connor, Franciscus & Holton, 2005; Lieberman, 2008, 2011; Wroe et al., 2010; Eng et al.,
706 2013). Using estimates of muscle leverage from 2D measurements (Lieberman, 2008, 2011),
707 humans have been shown to achieve high biting leverage through a marked degree of facial
708 retraction (orthognathism), which reorients the muscles of mastication relative to the tooth rows.
709 As noted above, we found that our human FEMs produced bite forces with leverage ratios

710 similar to those observed in *A. africanus* and *P. boisei* (Smith et al., 2015a). However,
711 australopiths achieve high biting leverage through an anterior positioning of the chewing muscles
712 relative to the tooth rows (Rak, 1983; Strait et al., 2009, 2010; Smith et al., 2015a). In humans,
713 the midfacial region is “tucked” beneath the anterior cranial fossa (Lieberman, McBratney &
714 Krovitz, 2002; Lieberman et al., 2004; Lieberman, 2008, 2011), which similarly places bite
715 points in a position that offers higher mechanical advantage to the jaw adductors.

716 Although the human cranium can theoretically produce mechanically efficient bite forces,
717 the production of unilateral molar (M^2) bite force is limited by the risk of temporomandibular
718 joint (TMJ) distraction, as predicted by the constrained lever model (Greaves, 1978; Spencer,
719 1998, 1999). Specifically, we found that all seven of the CHIMPED human FEMs experienced a
720 highly distractive (tensile) reaction force at the working-side joint during molar biting. These
721 forces have the effect of “pulling” the mandibular condyle from the jaw joint, increasing the risk
722 of joint dislocation (Spencer, 1998, 1999). As noted in the introduction, the soft tissues of the
723 mammalian jaw joint are well suited to resist compressive joint reaction forces, but are poorly
724 configured to resist distractive joint forces that “pull” the mandibular condyle from the cranial
725 base (Greaves, 1978; Spencer, 1998, 1999). In contrast, only one of the six chimpanzee FEMs
726 analyzed by Smith et al. (2015a) generated a tensile force at the working TMJ, and this reaction
727 was only very weakly tensile (12.7 N). Similarly, Smith et al. (2015b) found that their FEMs of
728 *P. boisei* and *A. africanus* lacked working-side distraction and were able to produce “stable”
729 bites on both the premolars and molars, offering these species the ability to produce maximally
730 forceful molar bites with limited risk of causing pain and/or damage to the TMJ capsule.

731 Interestingly, when loaded with human muscle forces (i.e., ALL-HUM), two of the
732 human FEMs (TIGA and WAFR) were capable of maintaining weakly compressive reaction

733 forces at both TMJs during molar biting. Additionally, balancing side force reductions required
734 to eliminate distraction in the remaining models were proportionately less (5-15%) than when
735 applying chimpanzee forces (15%-30%). Comparisons of the muscle loads applied to the models
736 and their force ratios in the ALL-HUM and CHIMPED models (see Tables 9 and 11) reveal that
737 chimpanzees devote a higher proportion of muscle strength to anteriorly-positioned muscle
738 compartments (superficial masseter and anterior temporalis) compared to more posteriorly-
739 positioned ones (deep masseter and medial pterygoid). Therefore, it is tempting to suggest that
740 changes in human jaw muscle force ratios may have coincided with the retraction of the lower
741 face during human evolution in order to reduce the risk of TMJ distraction. Likewise, if the
742 repositioning of cranial elements for reasons other than food processing (Lieberman, 2008;
743 Lieberman & Zink, 2016) led to an increase in biting efficiency but the generation of working
744 side joint distraction during molar biting, the overall reduction of chewing muscle size in *Homo*
745 could also be viewed as a result of positive selection rather than relaxed selection so as to lessen
746 these distractive forces.

747 Our findings that humans are limited in their ability to produce forceful unilateral molar
748 bites are supported by data on bite force and muscle activity in humans. Spencer (1995, 1998)
749 tested some predictions of the constrained lever model and found that humans produced bite
750 forces that increased as the bite point moved from the incisors to the first molar. Moving from
751 M^1 to M^3 , bite forces were found to decrease as a result of the decreasing balancing force muscle
752 recruitment required to avoid joint distraction. Spencer (1995) also notes that most of the
753 participants (8 of 10) in his analysis reported pain near the working-side TMJ when biting
754 forcefully using the back molars. In addition to this study, Hylander (1977) suggests that
755 specialized anterior tooth biting and increased masticatory muscle leverage may be related to the

756 high incidence of third molar reduction and agenesis among modern Inuit due to the increased
757 risk of distraction when biting on these teeth, although the results of our single pre-historic
758 Arctic FEM (TIGA) provide no support for this hypothesis. Similarly, Spencer (2003)
759 demonstrates that seed predating New World primates with adaptations for increased anterior
760 bite force have relatively small third molar roots.

761 As discussed above, Wroe et al. (2010) analyzed human feeding biomechanics within a
762 comparative context. One of the principal findings of their analysis, supported by the data
763 presented here, is that humans are capable of generating bite forces with higher mechanical
764 efficiency than chimpanzees. Wroe et al. use this as evidence to argue that human craniofacial
765 evolution may have been influenced by selection for powerful biting behaviors. However, the
766 results of this study showing the comparative weakness of the human cranium combined with the
767 increased risk of jaw joint distraction during molar biting leads us to interpret the increased
768 biting leverage exhibited by humans, which is particularly high among recent populations
769 (Spencer & Demes, 1993; O'Connor, Franciscus & Holton, 2005), to be a byproduct of human
770 facial orthognathism, which may be at least partly related to facial size reduction. Human facial
771 flatness may also have been acquired through selection for some non-dietary function. For
772 example, Lieberman (2008, 2011) suggests that the marked degree of facial retraction exhibited
773 by modern human crania could be related to changes in brain size and cranial base flexion.
774 However, Ross (2013) shows that basicranial flexion cannot produce significant facial retraction
775 on its own. Alternatively, Holton et al. (2010) propose that dietary shifts leading to reduced
776 facial strain magnitudes among early human species may have led to reduced facial growth and
777 earlier fusion of the maxillary sutures, and thus smaller and more retracted facial skeletons.

778 Although the majority of the morphological and mechanical evidence is not consistent
779 with the hypothesis that the human masticatory apparatus has experienced recent *selection* for
780 high magnitude biting, the results of our analysis cannot reject the hypothesis that, in addition to
781 changes in diet and tool use, increases in muscle force efficiency during human evolution could
782 have led to relaxed selection for large chewing muscle size and reductions in facial size (Wroe et
783 al., 2010) or that humans benefited from increased biting leverage when using submaximal
784 forces by exerting less energy per bite. Our results for premolar biting leverage also do not
785 conflict directly with the hypothesis that anterior tooth biting could have been selectively
786 important in humans. However, the reduced size of the premolar teeth in humans increases the
787 risk of tooth crown fracture (Constantino et al., 2010). Therefore, studies on premolar size and
788 strength are not consistent with the hypothesis that humans are particularly well adapted for
789 forcefully loading their anterior teeth, but such studies have yet to be conducted on incisors or
790 canines, which are the more likely to be used during paramasticatory activities. For example,
791 Hylander (1977) identifies features of the modern Inuit craniofacial skeleton that he argues to be
792 adaptations for powerful biting behaviors using the incisors, although our single pre-historic
793 Arctic FEM (TIGA) was not found to be exceptional in this regard. Additionally, Spencer &
794 Ungar (2000) show that incisor bite force leverage varies in relation to the intensity of incisor
795 tooth use among some Native American populations. Similarly, it is possible that differences in
796 anterior tooth use among “archaic” members of the genus *Homo* are reflected in mechanical
797 differences between the species. In particular, the Neanderthals (*H. neanderthalensis*) exhibit a
798 number of derived characteristics hypothesized to be adaptations for forceful incisor biting (e.g.,
799 Brace, 1962; Smith, 1983; Trinkaus, 1983, 1987; Rak, 1986; Demes, 1987). Notably, Spencer &
800 Demes (1993) show that Neanderthals exhibit high incisor bite force leverage relative to *H.*

801 *heidelbergensis* (but not modern *H. sapiens*). In order to maintain functional use of the posterior
802 dentition (i.e., avoid TMJ distraction), Spencer & Demes (1993) further show that the molar
803 tooth row in Neanderthals was anteriorly shifted, resulting in the characteristic retromolar gap.

804 Data on enamel thickness seemingly contrasts with the hypothesis that humans have
805 experienced relaxed selection for powerful biting behaviors. Specifically, a number of studies
806 find that recent human populations exhibit thick molar enamel (e.g., Martin, 1983, 1985;
807 Olejniczak et al., 2008; Smith et al., 2006; Vogel et al., 2008), which has been interpreted as a
808 primitive retention. However, notwithstanding disagreements over the significance of enamel
809 thickness (Grine, 2005), Smith et al. (2012) recently show that “thick” molar enamel in humans
810 is primarily the result of small coronal dentine areas. They found that enamel area in humans is
811 reduced, but there was a disproportionately large reduction in dentine to enamel as human teeth
812 were evolving smaller size, resulting in a relatively “thick” enamel cap. Thus, Smith et al. (2012)
813 argue that the dichotomy between thick and thin enamel is an oversimplification.

814

815 CONCLUSIONS

816 We examined the biomechanical consequences of human masticatory gracilization and
817 intraspecific variation within the constrained lever model of feeding biomechanics (Spencer,
818 1999) and tested the hypothesis that the human face is well configured to *generate* and *withstand*
819 high biting forces relative to chimpanzees. We found that our biomechanical models of human
820 crania were, on average, less structurally stiff than the crania of chimpanzees when assigned
821 equivalent bone properties, constraints, and physiologically-scaled muscle forces. These results
822 are consistent with the facial reduction exhibited by modern humans. We also found that modern
823 humans are efficient producers of bite force, consistent with previous analyses (Spencer &

824 Demes, 1993; O'Connor, Franciscus & Holton, 2005; Lieberman, 2008, 2011; Wroe et al., 2010;
825 Eng et al., 2013), but that distractive (tensile) reaction forces are generated at the working
826 (biting) side jaw joint during M² biting. In life, such a configuration would have increased the
827 risk of joint dislocation and constrained the maximum recruitment levels of the masticatory
828 muscles, meaning that the human cranium is poorly suited to produce forceful unilateral molar
829 bites. Our results do not conflict directly with the hypothesis that premolar biting could have
830 been selectively important in humans, although the reduced size of these teeth in humans has
831 been shown to increase the risk of tooth crown fracture. We interpret our results to suggest that
832 human craniofacial evolution was probably not driven by selection for high magnitude biting,
833 and that increased masticatory muscle efficiency in humans is likely to be a byproduct of
834 selection for some non-dietary function (Lieberman, 2008) or perhaps related to reduced
835 masticatory strain and sutural growth restrictions (Holton et al., 2010).

836 Our results provide support for the hypothesis that a shift to the consumption of less
837 mechanically challenging foods and/or the innovation of extra-oral food processing techniques
838 (e.g., stone tool use, cooking) along the lineage leading to modern *Homo sapiens* relaxed the
839 selective pressures maintaining features favoring forceful biting and chewing behaviors,
840 including large teeth and robust facial skeletons, leading to the characteristically small and
841 gracile faces of modern humans (e.g., Brace, Smith & Hunt, 1991; Wrangham et al., 1999;
842 Lieberman et al., 2004; Ungar et al., 2006a,b; Wood, 2009). To contribute to our further
843 understanding, future studies should aim to identify the ecological changes that may have led to
844 the emergence of such shifts in dietary behavior. Were these changes initiated by changes in
845 climate, competition, resource availability, or some combination of these factors? To what extent
846 is craniofacial gracilization part of a general pattern of skeletal gracilization in humans (Ruff et

847 al, 1993, 2015; Chirchir et al, 2015; Ryan & Shaw, 2015)? These questions will be addressed by
848 gaining further insight into the dietary ecology and feeding adaptations of species near the
849 origins of the modern human lineage through work on biomechanics, paleoecology, archaeology,
850 bone chemistry, and dental wear, each of which inform key components necessary to obtaining a
851 more complete understanding of human craniofacial evolution.

852

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857

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Table 1 (on next page)

Landmarks used in the geometric morphometric analysis of human craniofacial shape.

Coordinate data on these landmarks were collected by Baab and colleagues (Baab, 2007; Baab et al., 2010). The landmarks chosen for the analysis performed here are a subset of those used by Baab and colleagues, consisting mainly of facial landmarks. Landmark numbers and descriptions correspond to those in Baab (2007).

Landmark	Number ¹	Landmark	Number ¹
Alare (R, L)	13, 40	Lingual canine margin (R, L)	124, 115
Alveolare	11	M1-M2 contact (R, L)	119, 128
Anterior nasal spine	10	M2-M3 contact (R, L)	120, 129
Anterior pterion (R, L)	24, 51	Malar root origin (R, L)	31, 58
Basion	67	Mid post-toral sulcus	6
Bregma	5	Midline anterior palatine	70
Canine-P3 contact (R, L)	116, 125	Mid-torus inferior (R, L)	21, 48
Center of mandibular fossa (R, L)	97, 103	Mid-torus superior (R, L)	22, 49
Dacryon (R, L)	16, 43	Nasion	8
Distal M3 (R, L)	121, 130	Opisthion	66
Frontomalare orbitale (R, L)	20, 47	Orbitale (R, L)	18, 45
Frontomalare temporale (R, L)	19, 46	P3-P4 contact (R, L)	117, 126
Frontosphenomolare (R, L)	23, 50	P4-M1 contact (R, L)	118, 127
Frontotemporale (R, L)	35, 62	Porion (R, L)	27, 54
Glabella	7	Postglenoid (R, L)	94, 100
Hormion	68	Rhinion	9
Incisivon	71	Root of zygomatic process (R, L)	32, 59
Inferior entoglenoid (R, L)	95, 101	Spheno-palatine suture (R, L)	108, 112
Inferior zygotemporal suture (R, L)	72, 78	Staphylion	69
Infraorbital foramen (R, L)	12, 39	Stephanion (R, L)	34, 61
Inion	1	Superior zygotemporal suture (R, L)	25, 52
Jugale (R, L)	26, 53	Supraorbital notch (R, L)	17, 44
Lambda	3	Temporo-sphenoid suture (R, L)	109, 113
Lateral articular fossa (R, L)	96, 102	Zygomaxillare (R, L)	14, 41
Lateral prosthion (R, L)	114, 123	Zygoorbitale (R, L)	15, 42

1 ¹Landmark numbers correspond to those in Baab (2007).

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Table 2 (on next page)

Geographic distribution of human specimens included in the analysis of craniofacial shape variation.

All specimens are housed at the American Museum of Natural History (AMNH).

Region/Population	N
Aboriginal Australian	9
Khoe-San, South Africa	3
China	6
East Africa	7
Grand Gulch, Utah	10
Greifenberg, Carinthia, Austria	6
Heidenheim, Germany	1
Kakoletri, Peloponnesus, Greece	1
Maori, Waitakeri, New Zealand	4
Mongolia	1
Point Hope, Alaska	12
Southeast Asia	12
Tarnapol, Galicia, Poland	2
Tasmanian	4
Tierra del Fuego, Argentina	3
West Africa	7

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Table 3 (on next page)

Human crania sorted by their Euclidean distance from the group centroid.

The first 25 specimens represent the most distant from the group centroid, whereas the bottom row represents an “average” representative of human cranial shape based on its close proximity to the centroid. Values in parentheses represent the distances expressed in units of the mean pairwise distance (0.068), which provides information on how much farther a particular cranium is from the centroid than the mean distance. Specimens are coded here following American Museum of Natural History (AMNH) catalog numbers.

Specimen	Region/Population	Distance from centroid
VL/2463 ¹	Khoe-San, South Africa	0.1011 (1.49)
VL/3878 ¹	Greifenberg, Austria	0.0939 (1.38)
99/7889 ¹	Malay Archipelago, SE Asia	0.0918 (1.35)
VL/3818	Greifenberg, Austria	0.0885 (1.31)
VL/269	Tasmanian	0.0881 (1.30)
VL/229	Kalmuk, Western Mongolia	0.0876 (1.29)
VL/408	Mhehe, East Africa	0.0871 (1.28)
99.1/511 ¹	Point Hope, Alaska	0.0871 (1.28)
99/8155	Aboriginal Australian	0.0842 (1.24)
99/6562	Māori, New Zealand	0.0830 (1.22)
VL/271	Tasmanian	0.0824 (1.22)
VL/2470 ¹	Khoe-San, South Africa	0.0788 (1.16)
VL/1902	Māori, New Zealand	0.0777 (1.15)
99.1/490	Point Hope, Alaska	0.0770 (1.14)
99/8165	Aboriginal Australian	0.0767 (1.13)
VL/272	Tasmanian	0.0750 (1.11)
VL3619	Greifenberg, Austria	0.0745 (1.10)
99/7333	Grand Gulch, Utah	0.0741 (1.09)
99/8177	Aboriginal Australian	0.0740 (1.09)
VL/2267	Kakoletri, Greece	0.0733 (1.08)
VL/1729	Tientsin, China	0.0728 (1.07)
VL/1602 ¹	Ashanti, West Africa	0.0727 (1.07)
VL/274	Tasmanian	0.0721 (1.06)
VL/2389	Ashanti, West Africa	0.0721 (1.06)
99/8171	Aboriginal Australian	0.0720 (1.06)
99/7365 ¹	Grand Gulch, Utah	0.0496 (0.73)

1 ¹ Specimens selected to be modeled using FEA.

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Table 4(on next page)

Pairwise distances between the 6 human cranial specimens selected for use in finite element analysis.

Values in parentheses represent the distances expressed in units of the mean pairwise distance (0.068). Specimens are coded here following American Museum of Natural History (AMNH) catalog numbers.

	VL/2463	VL/3878	99/7889	99.1/511	VL/2470	VL/1602
VL/2463		0.1634 (1.70) ¹	0.0938 (0.97)	0.1534 (1.59) ¹	0.1083 (1.12)	0.1145 (1.19)
VL/3878			0.1469 (1.52)	0.1304 (1.35)	0.1230 (1.28)	0.1385 (1.44)
99/7889				0.1526 (1.58) ¹	0.1178 (1.22)	0.1029 (1.09)
99.1/511					0.1330 (1.38)	0.1256 (1.30)
VL/2470						0.1049 (1.09)
VL/1602						

1 ¹These represent the greatest pairwise distances in the final sample.

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Table 5 (on next page)

Muscle force scaling for the ALL-HUM and CHIMPED models of modern human crania.

Muscle forces in Newtons (N) were scaled by model size, where size is represented by model volume in mm³. Models are shown here ordered from smallest to largest in size. AT = anterior temporalis, SM = superficial masseter, DM = deep masseter, MP = medial pterygoid.

Variant	Model	Volume (mm ³)	Volume ^{2/3}	Muscle Force (N)			
				AT	SM	DM	MP
ALL-HUM	KSAN2	331466	4789.53	128.41	105.15	53.29	108.64
	MALP	364129	5099.22	136.72	111.95	56.73	115.67
	KSAN2	433331	5726.38	153.53	125.72	63.71	129.89
	WAFR	475555	6092.57	163.35	133.75	67.79	138.20
	BERG	489588	6211.84	166.55	136.37	69.11	140.90
	GRGL	557223	6771.52	181.55	148.66	75.34	153.60
	TIGA	655320	7544.59	202.28	165.63	83.94	171.14
CHIMPED	KSAN2	331466	4789.53	556.13	572.02	85.07	189.02
	MALP	364129	5099.22	592.09	609.00	90.57	201.24
	KSAN2	433331	5726.38	664.91	683.90	101.71	225.99
	WAFR	475555	6092.57	707.43	727.64	108.22	240.44
	BERG	489588	6211.84	721.28	741.88	110.34	245.15
	GRGL	557223	6771.52	786.26	808.73	120.28	267.24
	TIGA	655320	7544.59	876.02	901.05	134.01	297.74

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Table 6 (on next page)

Results of *in vitro* validation analysis.

Average values and standard deviations for maximum (MaxPrin) and minimum (MinPrin) principal strain magnitudes recorded during three *in vitro* loading trials on the left P³ biting , the results of a specimen-specific *in silico* (FEA) loading analysis, and an estimate of the error in the FEA, where “error” is represented by the difference between *in vitro* (observed) and *in silico* (expected) results, divided by the expected results. See Fig. S3 – Fig. S7 for site locations. Units are in microstrain ($\mu\epsilon$).

Site	Exp.	MaxPrin	MinPrin	Site	Exp.	MaxPrin	MinPrin
1.	<i>In vitro</i>	15.00 (4.36)	-10.33 (2.08)	8.	<i>In vitro</i>	42.33 (2.08)	-109.67 (3.06)
	<i>In silico</i>	14	-15		<i>In silico</i>	37	-105
	Error	6.67%	45.16%		Error	12.60%	4.26%
2.	<i>In vitro</i>	13.00 (1.00)	-11.67 (0.58)	9.	<i>In vitro</i>	7.67 (0.58)	-2.67 (2.08)
	<i>In silico</i>	10	-10		<i>In silico</i>	8	-4
	Error	23.08%	14.29%		Error	4.35%	50.00%
3.	<i>In vitro</i>	3.33 (0.58)	-5.00 (1.00)	10.	<i>In vitro</i>	45.33 (2.08)	-22.33 (1.15)
	<i>In silico</i>	6	-7		<i>In silico</i>	23	-20
	Error	80.00%	40.00%		Error	49.26%	10.45%
4.	<i>In vitro</i>	30.67 (1.15)	-36.00 (0.00)	11.	<i>In vitro</i>	23.67 (0.58)	-10.67 (3.06)
	<i>In silico</i>	29	-34		<i>In silico</i>	22	-13
	Error	5.43%	5.56%		Error	7.04%	21.88%
5.	<i>In vitro</i>	15.00 (2.00)	-14.67 (1.53)	12.	<i>In vitro</i>	108.00 (2.65)	-281.67 (8.33)
	<i>In silico</i>	19	-12		<i>In silico</i>	115	-238
	Error	26.67%	18.18%		Error	6.48%	15.50%
6.	<i>In vitro</i>	11.67 (0.58)	-7.33 (0.58)	13.	<i>In vitro</i>	38.67 (1.15)	-22.00 (1.00)
	<i>In silico</i>	11	-10		<i>In silico</i>	39	-17
	Error	5.71%	36.36%		Error	0.86%	22.73%
7.	<i>In vitro</i>	42.33 (1.53)	-23.33 (2.25)	14.	<i>In vitro</i>	27.67 (2.08)	-42.33 (3.01)
	<i>In silico</i>	42	-17		<i>In silico</i>	38	-25
	Error	0.79%	27.14%		Error	37.35%	40.94%

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Table 7 (on next page)

Variation in strain and strain energy density in the ALL-HUM models.

Coefficients of variation for maximum principal strain (MaxPrin), minimum principal strain (MinPrin), shear strain (Shear), von Mises strain, and strain energy density (SED) at the 14 locations examined during premolar (P³) and molar (M²) biting in the ALL-HUM models of modern human crania. Site numbers follow Figure 4.

Site	Bite	MaxPrin	MinPrin	Shear	von Mises	SED
1	P ³	56.01	34.39	28.49	27.88	59.08
	M ²	43.20	28.62	20.78	22.82	50.07
2	P ³	28.35	41.61	30.51	29.27	78.82
	M ²	27.61	44.20	29.50	29.04	60.38
3	P ³	23.83	26.53	22.94	22.97	52.39
	M ²	25.16	24.29	24.66	24.16	49.48
4	P ³	15.30	21.39	14.75	14.28	27.78
	M ²	34.43	22.83	22.73	21.46	36.89
5	P ³	14.32	13.06	12.77	13.24	26.98
	M ²	12.50	14.22	11.70	12.06	24.53
6	P ³	21.74	12.21	11.77	11.89	23.52
	M ²	17.43	13.56	11.13	12.05	25.11
7	P ³	12.53	8.26	8.09	7.93	15.97
	M ²	11.27	6.05	5.78	5.32	11.98
8	P ³	19.73	2.58	13.87	12.50	25.96
	M ²	20.48	12.04	12.62	11.88	23.36
9	P ³	20.78	21.84	18.18	19.30	39.77
	M ²	12.59	9.28	8.23	8.66	19.36
10	P ³	11.70	33.05	12.32	11.72	21.21
	M ²	35.51	22.16	25.60	25.86	50.44
11	P ³	24.44	37.84	24.15	21.83	36.54
	M ²	25.53	43.20	28.88	26.73	52.39
12	P ³	51.04	35.54	39.39	37.44	64.43
	M ²	52.66	34.33	41.78	40.46	76.44
13	P ³	28.41	34.42	26.48	25.60	51.87
	M ²	14.11	20.80	14.37	13.50	28.05
14	P ³	35.54	22.56	31.16	31.33	68.31
	M ²	39.93	26.73	35.19	35.33	80.97

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Table 8 (on next page)

Variation in von Mises strain magnitudes: Human vs. Chimpanzee.

Comparisons of the coefficients of variation (CVs) for von Mises strain recorded in the CHIMPED human models and the chimpanzee results from Smith et al. (2015b) at each of the 14 craniofacial sites examined. Results of Fligner-Killeen tests for equal CVs between the species are also presented ($\alpha=0.05$). Comparisons that yielded significant results are shown in bold typeface.

Site		P ³	M ²	Site		P ³	M ²
1	CV - Human	29.04	22.68	8	CV - Humans	10.14	12.27
	CV - Chimp	25.91	23.63		CV - Chimps	16.54	25.58
	p (same CV)	0.065	0.141		p (same CV)	0.143	0.130
2	CV - Humans	24.34	23.05	9	CV - Humans	14.12	8.03
	CV - Chimps	46.61	47.07		CV - Chimps	25.7	23.58
	p (same CV)	0.122	0.050		p (same CV)	0.069	0.052
3	CV - Humans	19.71	17.75	10	CV - Humans	8.8	15.46
	CV - Chimps	19.81	20.10		CV - Chimps	17.36	15.30
	p (same CV)	0.386	0.369		p (same CV)	0.039	0.290
4	CV - Humans	13.51	21.12	11	CV - Humans	10.6	14.34
	CV - Chimps	29.98	33.20		CV - Chimps	27.76	28.11
	p (same CV)	0.176	0.359		p (same CV)	0.056	0.100
5	CV - Humans	12.89	11.50	12	CV - Humans	38.05	38.76
	CV - Chimps	27.56	29.40		CV - Chimps	28.23	43.35
	p (same CV)	0.156	0.060		p (same CV)	0.147	0.396
6	CV - Humans	18.15	16.51	13	CV - Humans	24.54	10.39
	CV - Chimps	64.99	66.99		CV - Chimps	17.95	17.52
	p (same CV)	0.022	0.022		p (same CV)	0.157	0.207
7	CV - Humans	11.96	12.07	14	CV - Humans	22.78	23.11
	CV - Chimps	55.83	56.63		CV - Chimps	51.99	55.84
	p (same CV)	0.022	0.022		p (same CV)	0.222	0.166

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Table 9 (on next page)

Bite force production, biting efficiency, and joint reaction forces in the ALL-HUM model variants of human crania.

Bite force (BF), mechanical advantage (MA), working-side TMJ reaction force (RF-WS), and balancing-side TMJ reaction force (RF-BS) for premolar and molar biting. Five of seven ALL-HUM models generated distractive (tensile) reaction forces during molar loading. Therefore, balancing side muscle forces were iteratively reduced by 5% and re-run until distractive forces were eliminated. Bite forces and TMJ reaction forces are in Newtons (N).

Model	Muscle Force	Premolar Bite				Molar Bite			
		BF	MA	RF-WS	RF-BS	BF	MA	RF-WS	RF-BS
GRGL	1118	441	0.39	167.42	349.25	658	0.59	-11.74	329.79
GRGL ¹	1090					642	0.59	-1.37	311.18
GRGL ²	1062					625	0.59	8.98	292.58
BERG	1026	439	0.43	147.72	281.55	663	0.65	-6.98	249.09
BERG ¹	1000					647	0.65	1.29	234.72
KSAN1	946	378	0.40	121.76	295.69	538	0.57	-17.49	280.57
KSAN1 ²	898					511	0.57	0.07	249.74
KSAN2	791	333	0.42	106.83	240.30	496	0.63	-18.86	222.80
KSAN2 ²	751					471	0.63	-4.26	197.88
KSAN2 ³	732					459	0.63	3.04	185.41
MALP	842	344	0.41	131.09	277.66	537	0.64	-19.85	274.49
MALP ²	800					510	0.64	-0.99	242.97
TIGA	1246	507	0.41	187.96	373.24	756	0.61	13.68	336.84
WAFR	1006	341	0.34	149.36	298.77	529	0.53	12.64	273.79

1 ¹Model re-run using muscle forces reduced by 5% on the balancing side.

2 ²Model re-run using muscle forces reduced by 10% on the balancing side.

3 ³Model re-run using muscle forces reduced by 15% on the balancing side.

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Table 10(on next page)

Von Mises strain magnitudes: Human vs. Chimpanzee.

Results of pairwise comparisons (Mann-Whitney *U*-test) of von Mises strain magnitudes at the 14 locations examined between CHIMPED variants of human FEMs and data on chimpanzees from Smith et al. (2015b). Because of small sample sizes, the “exact” variant of *p* is reported (Mundry and Fischer, 1998). Comparisons that yielded significant results following Holm-Bonferroni correction are shown in bold typeface. When significant, humans were found to exhibit the higher average value, with the exception of locations 13 and 14, where humans were found to exhibit significantly lower strain magnitudes.

Site	Bite	U	z	Exact p
1. Dorsal interorbital	Premolar	9	-1.65	0.0967
	Molar	10	-1.50	0.1265
2. Working dorsal orbital	Premolar	0	-2.93	0.0012
	Molar	0	-2.93	0.0012
3. Balancing dorsal orbital	Premolar	4	-2.36	0.0140 ¹
	Molar	7	-1.93	0.0513
4. Working postorbital bar	Premolar	0	-2.93	0.0012
	Molar	1	-2.79	0.0023
5. Balancing postorbital bar	Premolar	0	-2.93	0.0012
	Molar	0	-2.93	0.0012
6. Working zygomatic arch	Premolar	14	-0.93	0.3660
	Molar	14	-0.93	0.3660
7. Balancing zygomatic arch	Premolar	14	-0.93	0.3660
	Molar	14	-0.93	0.3660
8. Working zygomatic root	Premolar	0	-2.93	0.0012
	Molar	0	-2.93	0.0012
9. Balancing zygo root	Premolar	18	-0.36	0.7308
	Molar	11	-1.36	0.1807
10. Working infraorbital	Premolar	2	-2.64	0.0047
	Molar	7.5	-1.86	0.0565
11. Balancing infraorbital	Premolar	6	-2.07	0.0350 ¹
	Molar	12	-1.21	0.2343
12. Working nasal margin	Premolar	0	-2.93	0.0012
	Molar	1	-2.79	0.0023
13. Working zygomatic body	Premolar	0	-2.93	0.0012
	Molar	1	-2.79	0.0023
14. Balancing zygomatic body	Premolar	0.5	-2.86	0.0017
	Molar	1	-2.79	0.0023

1 ¹Result is significant at $p \leq 0.05$.

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Table 11(on next page)

Bite force production, biting efficiency, and joint reaction forces in the CHIMPED model variants of human crania.

Bite force (BF), mechanical advantage (MA), working-side temporomandibular joint reaction force (RF-WS), and balancing-side temporomandibular joint reaction force (RF-BS) for premolar and molar biting. All seven CHIMPED models generated highly distractive (tensile) reaction forces during molar loading that would have increased the chances of joint dislocation and/or injury. Therefore, balancing side muscle forces were iteratively reduced by 5% and re-run until distractive forces were eliminated. Bite forces and TMJ reaction forces are in Newtons (N).

Model	Muscle Force	Premolar Bite				Molar Bite			
		BF	MA	RF-WS	RF-BS	BF	MA	RF-WS	RF-BS
GRGL	3965	1724	0.43	499.82	1189.57	2570	0.65	-208.16	1113.51
GRGL ¹	3569					2316	0.65	-31.26	841.64
GRGL ²	3469					2252	0.65	12.96	773.68
BERG	3637	1720	0.47	405.08	935.03	2599	0.71	-185.65	819.81
BERG ²	3183					2277	0.71	-6.72	560.17
BERG ³	3092					2213	0.71	29.07	508.24
KSAN1	3353	1462	0.44	343.26	1030.37	2080	0.62	-187.95	975.38
KSAN1 ²	2934					1822	0.62	-0.30	687.33
KSAN1 ³	2850					1771	0.62	37.23	629.72
KSAN2	2804	1272	0.45	311.70	821.79	1895	0.68	-163.75	757.22
KSAN2 ²	2454					1658	0.68	-11.46	529.80
KSAN2 ³	2384					1610	0.68	18.99	484.32
MALP	2986	1358	0.45	384.41	966.38	2118	0.71	-203.31	963.66
MALP ²	2613					1851	0.71	-2.01	667.11
MALP ³	2538					1797	0.71	38.25	607.81
TIGA	4418	1941	0.44	564.13	1288.46	2896	0.66	-107.59	1143.16
TIGA ⁴	4197					2750	0.66	-13.27	997.33
TIGA ⁵	4086					2678	0.66	33.89	924.42
WAFR	3567	1383	0.39	489.34	1103.22	2146	0.60	-61.09	1006.50
WAFR ⁶	3478					2091	0.60	-24.01	946.69
WAFR ⁴	3389					2036	0.60	13.07	886.88

1 ¹Model re-run using muscle forces reduced by 20% on the balancing side.

2 ²Model re-run using muscle forces reduced by 25% on the balancing side.

3 ³Model re-run using muscle forces reduced by 30% on the balancing side.

4 ⁴Model re-run using muscle forces reduced by 10% on the balancing side.

5 ⁵Model re-run using muscle forces reduced by 15% on the balancing side.

6 ⁶Model re-run using muscle forces reduced by 5% on the balancing side.

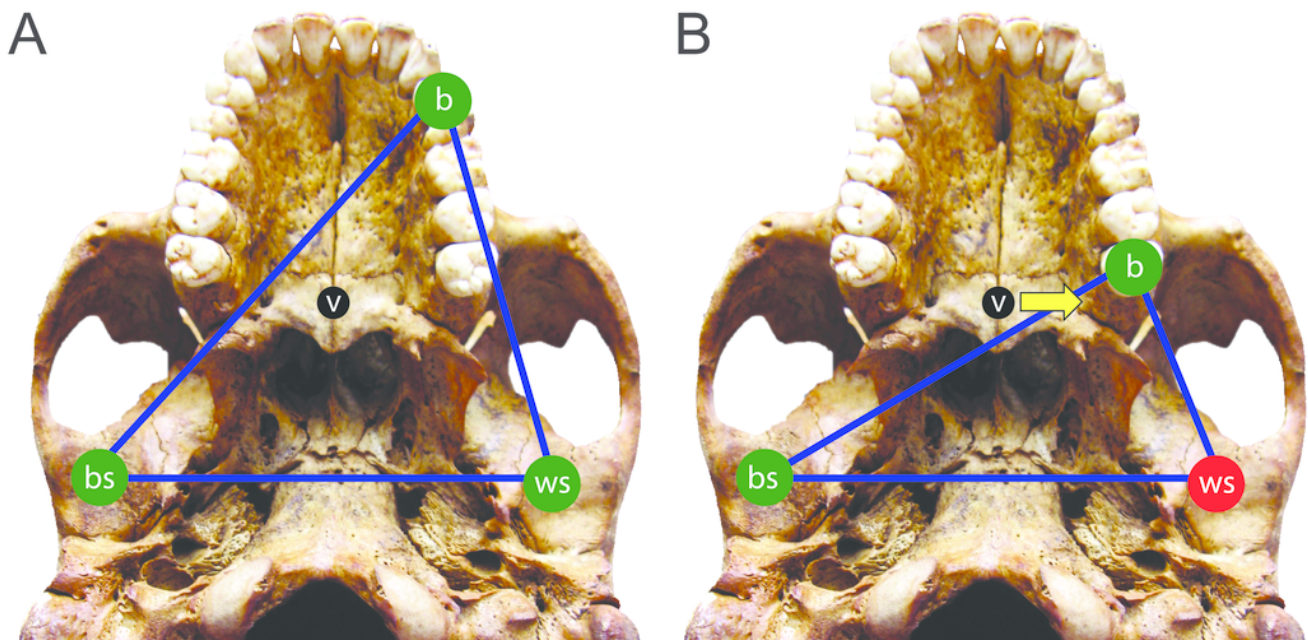
7

8

1

The constrained lever model of jaw biomechanics.

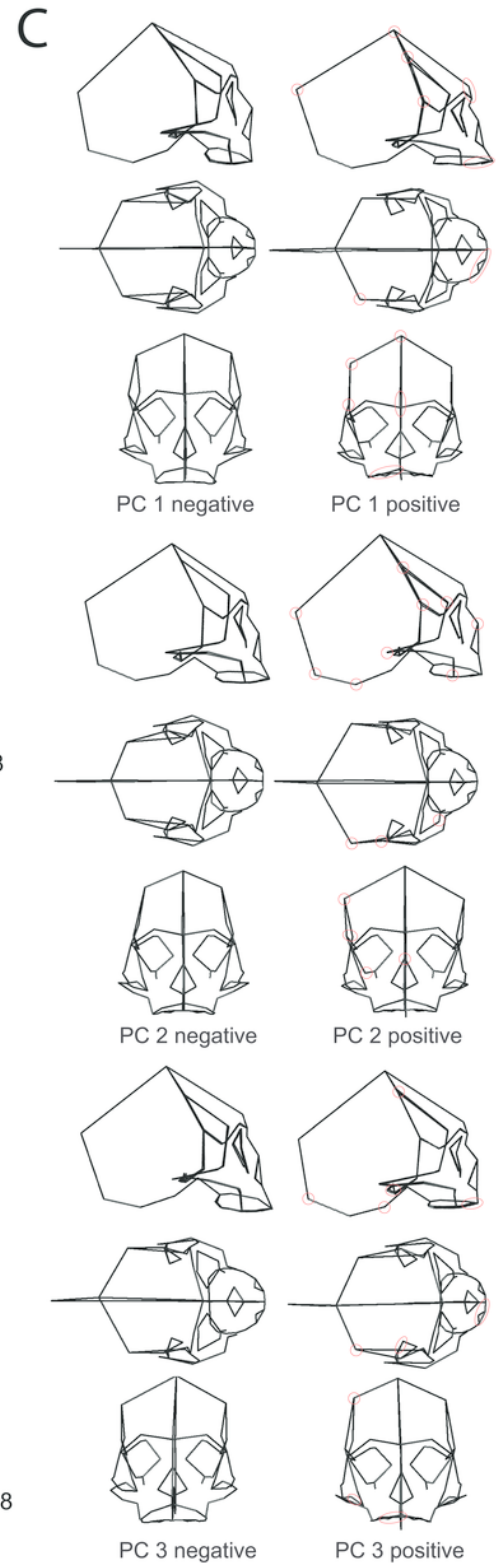
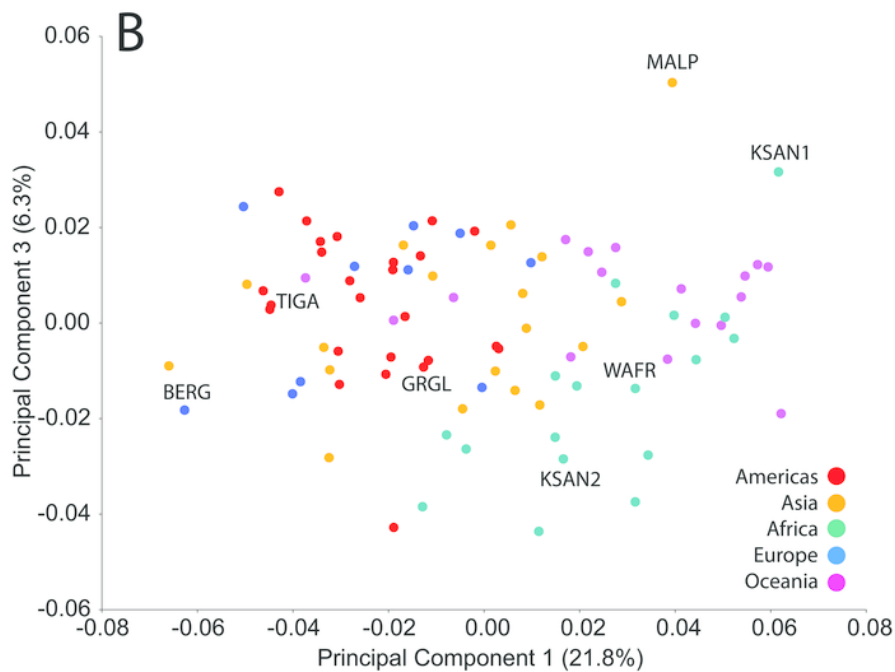
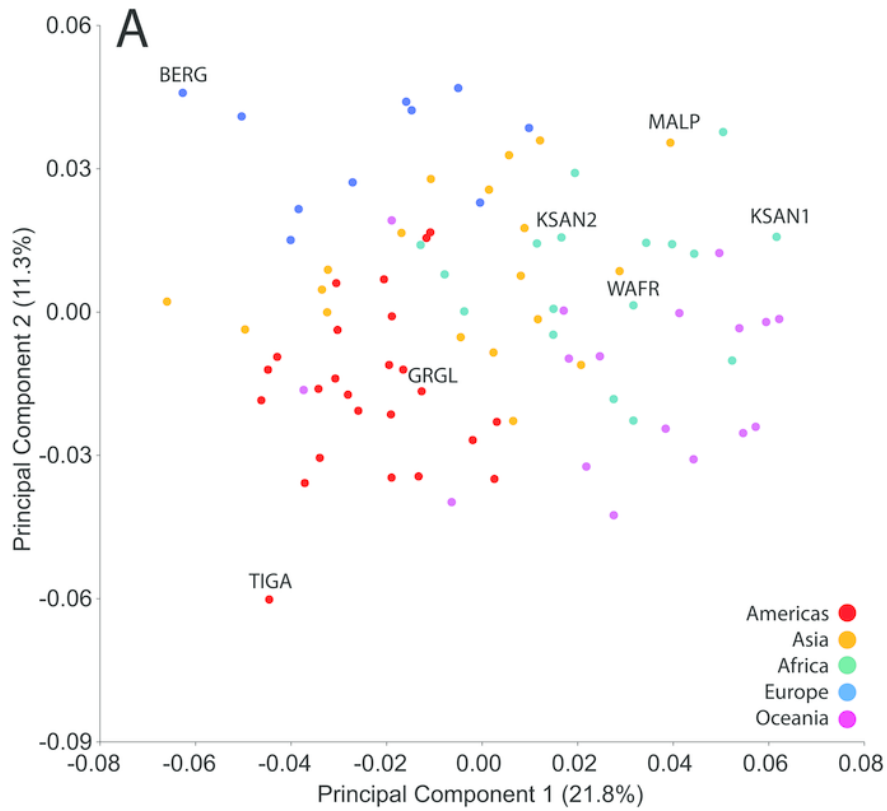
During biting, the bite point (b) and the temporomandibular joints on the working side (ws) and balancing side (bs) form a “triangle of support” that changes shape when biting on different teeth. During a premolar bite (**A**), the resultant vector of the jaw adductor muscles (v) passes through the triangle, producing compression (green circles) at all three points. However, during some molar bites (**B**), the vector falls outside the triangle when the muscles are being recruited equally on both sides of the head, producing compression at the bite point and bs joint, but distraction (red circle) at the ws joint. The recruitment of the balancing side muscles must be lessened in order to eliminate this distraction, thereby causing the vector to shift its position towards the working side and back into the triangle (yellow arrow).



2

Principal component analysis (PCA) of human craniofacial shape variation.

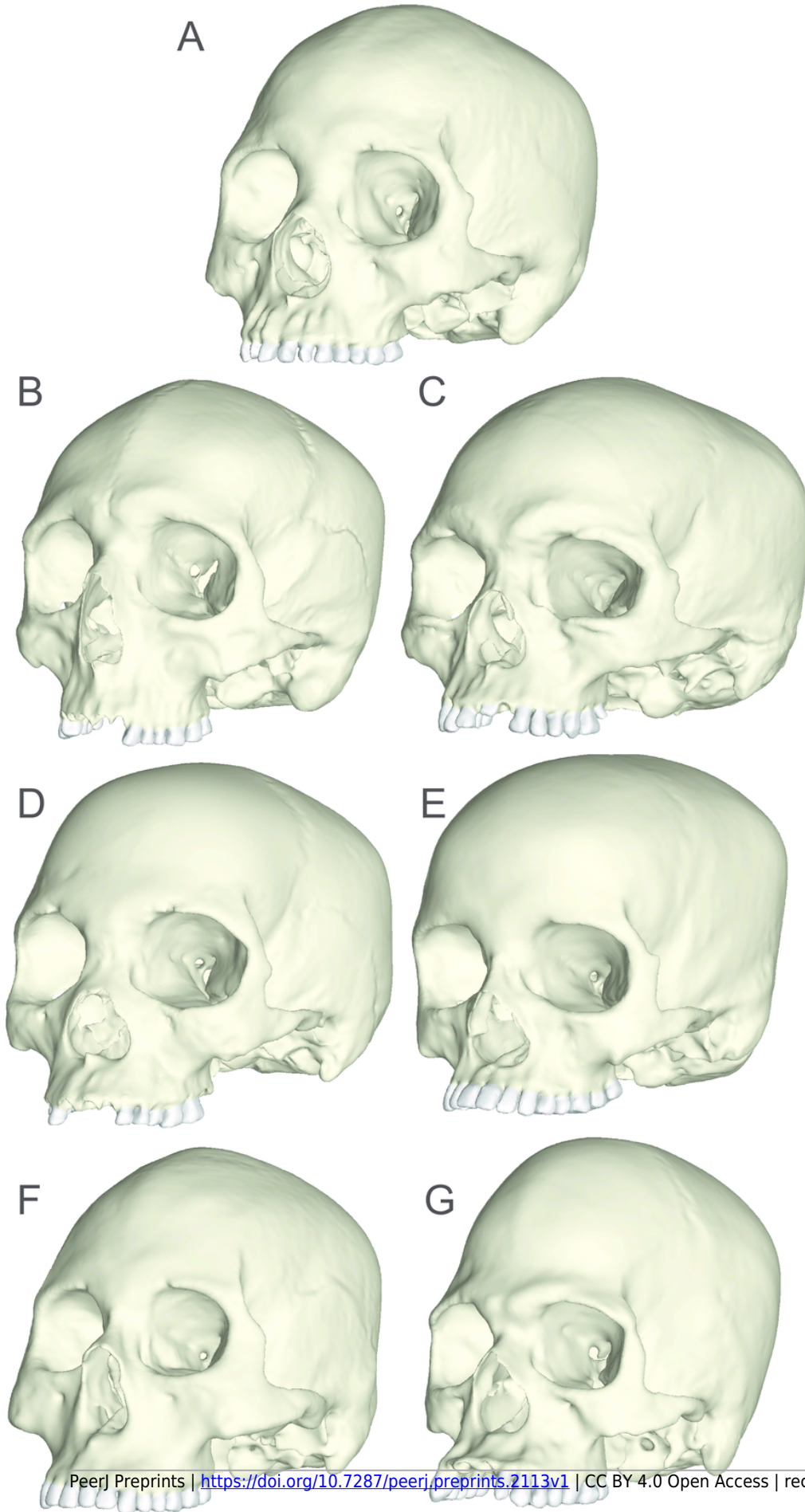
Panels show **(A)** PC1 by PC2, **(B)** PC1 by PC3, and **(C)** wireframes illustrating craniofacial shape change associated with the first three principal components in right lateral, superior, and frontal views. The left and right columns of wireframes represent the negative and positive ends of each component, respectively, scaled to their respective axes. The 10 unique landmarks with the highest loadings for each component are highlighted using a red ellipse on the midline and right side. A single ellipse was used to circle multiple landmarks if they were located close together. Shape differences toward the positive end of PC 1 include: a vertically shorter face with a more projecting brow ridge, a longer and more projecting palate, a more vertical frontal bone that is narrower at pterion, a vault that is expanded posteriorly, and a lower temporal line at stephanion. Shape differences toward the positive end of PC 2 include: a longer cranium with a wider frontal bone, a vault that is angled more postero-inferiorly, wider orbits and a superiorly shifted nasal aperture, and an antero-posteriorly shorter temporal bone. Shape differences toward the positive end of PC 3 include: higher temporal lines at stephanion, a shorter and more orthognathic subnasal region with a less projecting palate, a more inferiorly positioned temporomandibular joint, and a more inferiorly positioned midline cranial base.



3

Human models analyzed in the current study.

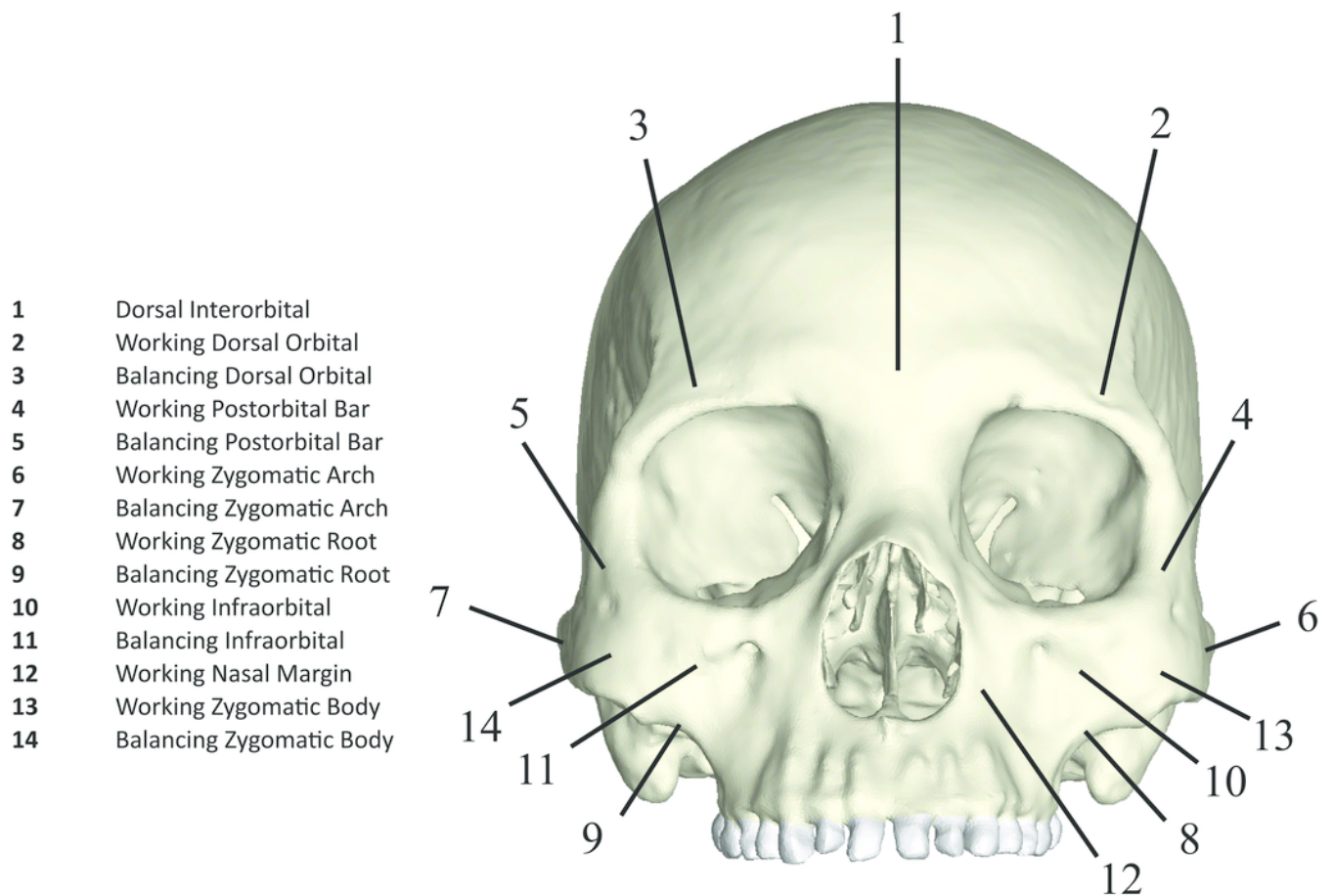
Models include one “average” cranium, GRGL (**A**), and six “extreme” specimens that differ notably in shape, BERG (**B**), KSAN1 (**C**), KSAN2 (**D**), MALP (**E**), TIGA (**F**), and WAFR (**G**).



4

Key to locations where strains were sampled in finite element models.

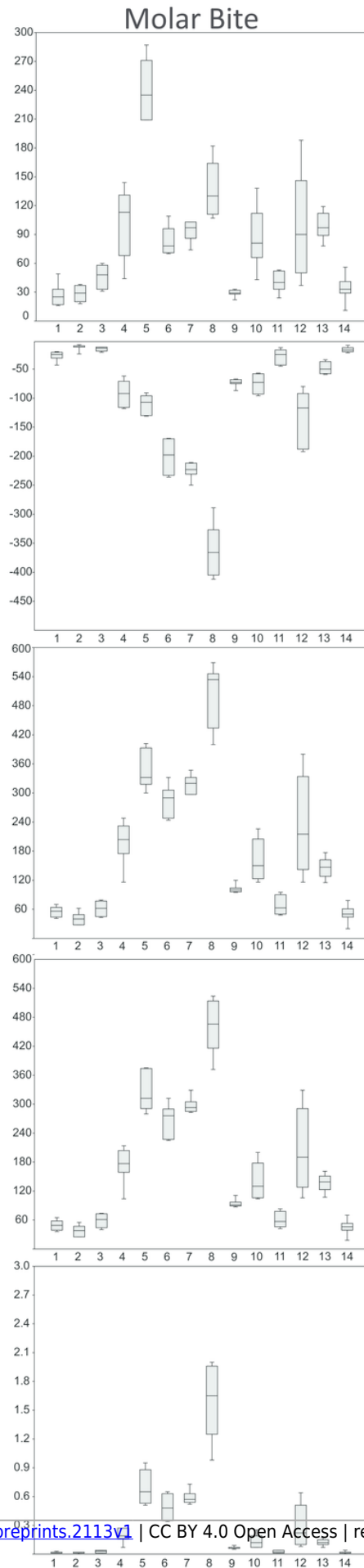
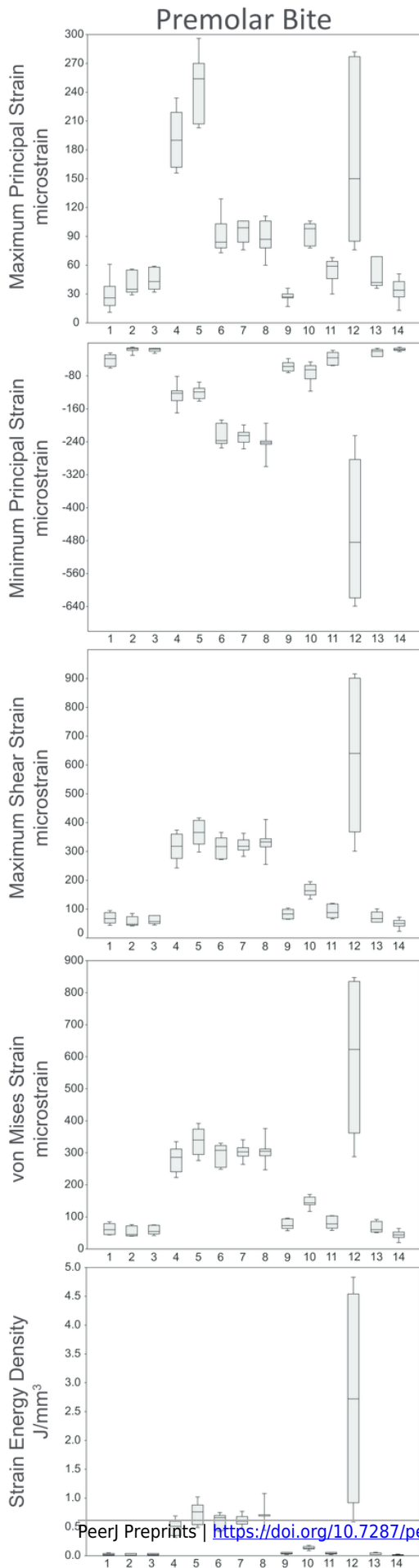
Strain data were collected from ALL-HUM and CHIMPED variants of human FEMs from 14 craniofacial sites, following Smith et al. (2015a,b).



5

Strain and SED generated by the ALL-HUM models.

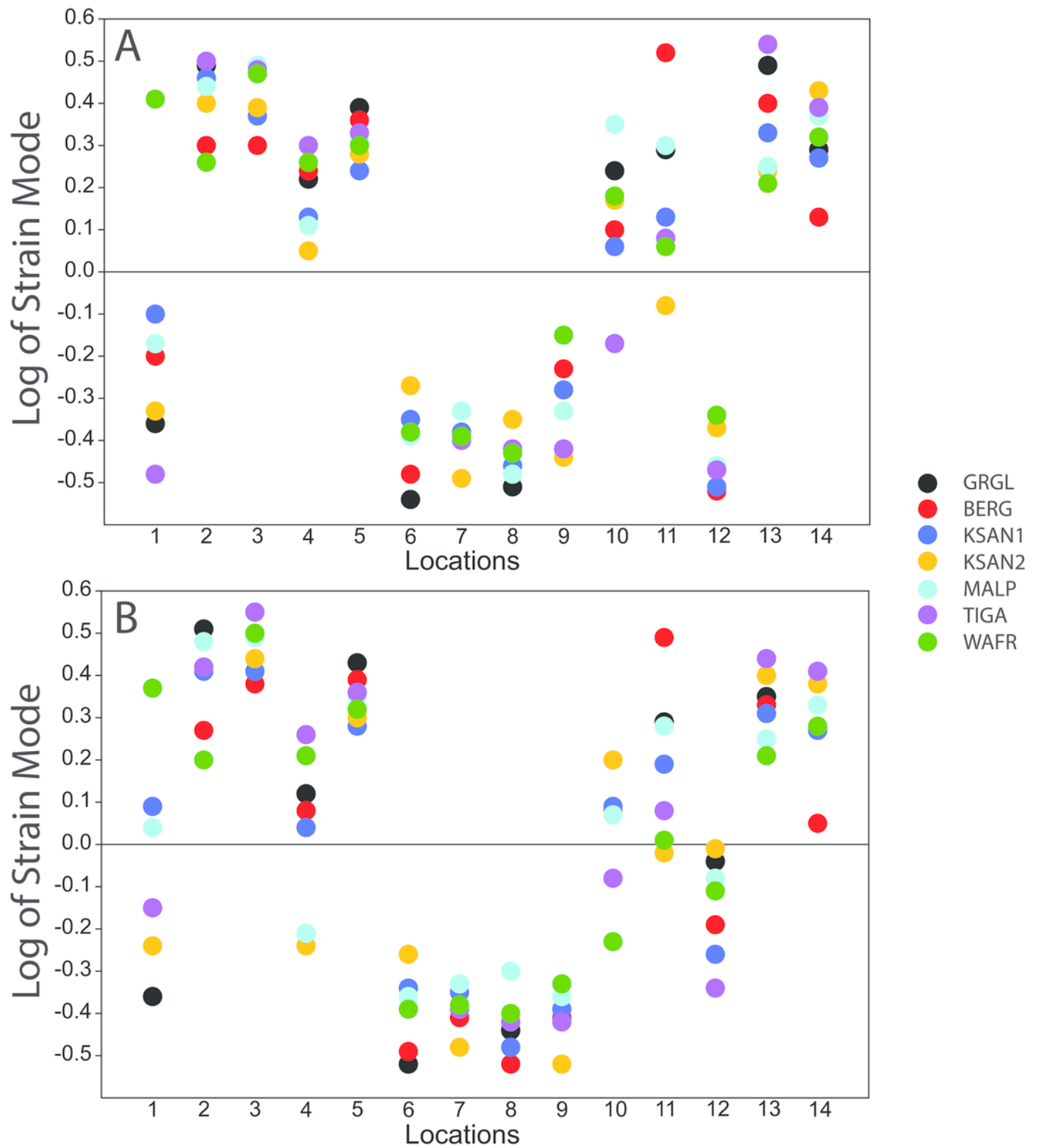
Box-and-whisker plots show the minimum, first quartile, median, third quartile, and maximum for strain and SED magnitudes (y-axis) generated by the ALL-HUM models at the 14 sampled locations (x-axis) during premolar (P³) and molar (M²) biting. Site numbers follow Fig. 4.



6

Strain mode in the ALL-HUM models.

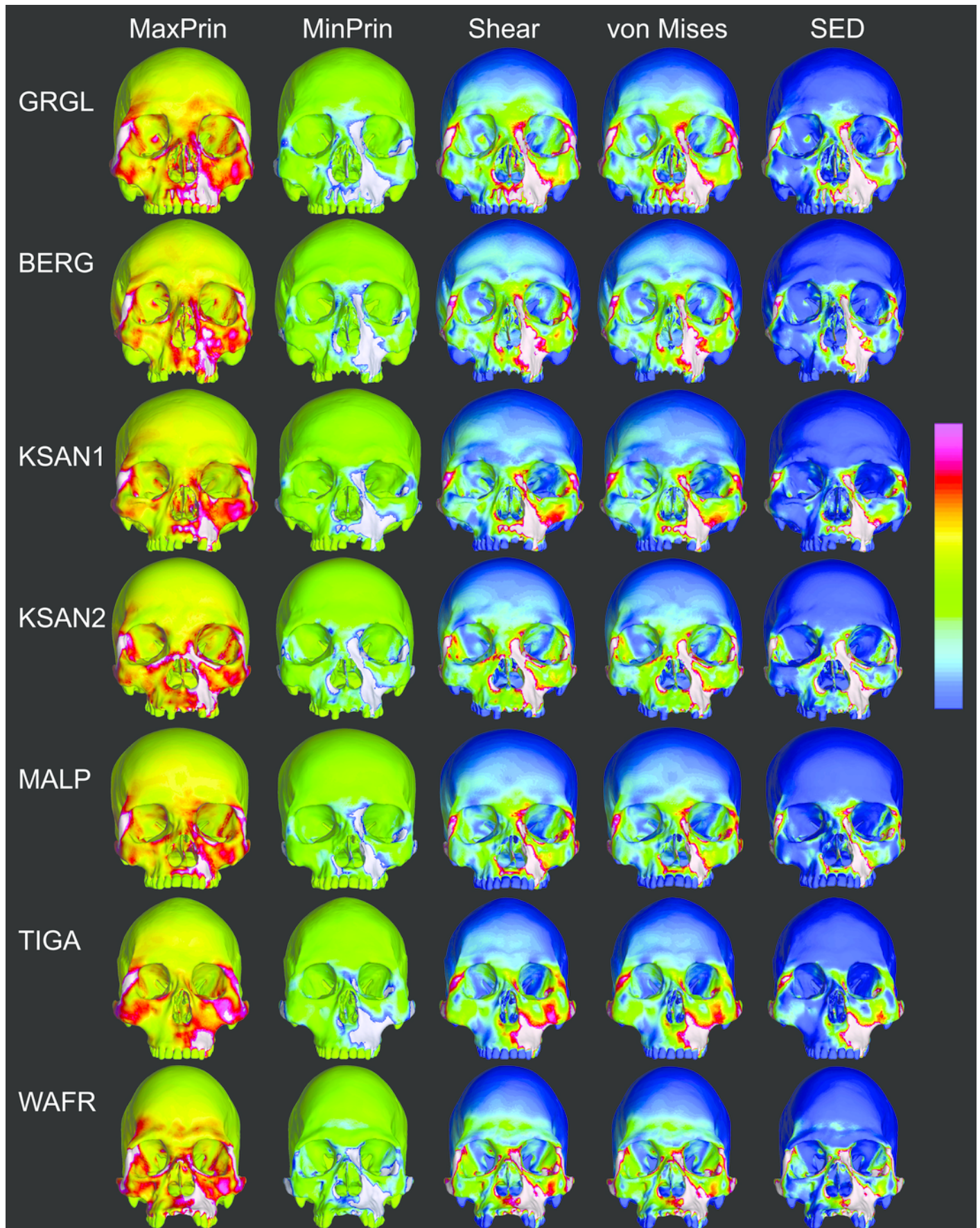
Distribution of strain mode (log of ratio of maximum to minimum principal strain, y-axis) plotted by location (x-axis) in the ALL-HUM models. Plots show **(A)** premolar (P^3) and **(B)** molar (M^2) biting. Logging the data listed in Tables S2 and S3 centers strain mode data around zero. Values above zero indicate mainly tension, while values below zero indicate mainly compression. Site numbers follow Fig. 4.



7

Strain distributions in the ALL-HUM models: P³ biting.

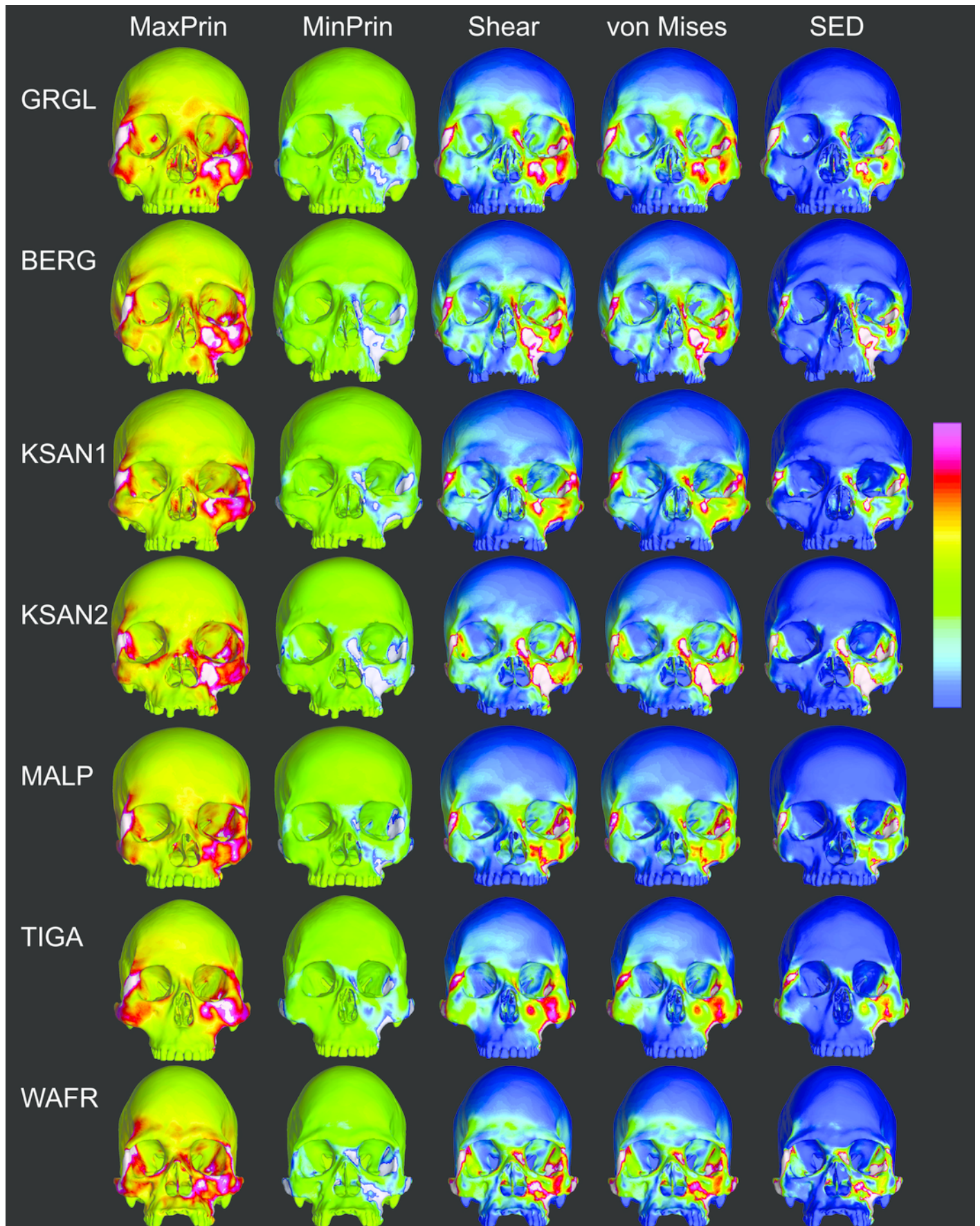
Color maps of strain distributions in the ALL-HUM variants of “extreme” and “average” modern human cranial FEMs during premolar (P³) biting. Scales are set to range from -150 – 150 $\mu\epsilon$ for both maximum principal strain (MaxPrin) and minimum principal strain (MinPrin), from 0 – 300 $\mu\epsilon$ for both maximum shear strain (Shear) and von Mises strain (von Mises), and from 0 – 0.5 J/mm³ for strain energy density (SED). White regions exceed scale. Models are shown at the same height.



8

Strain distributions in the ALL-HUM models: M² biting.

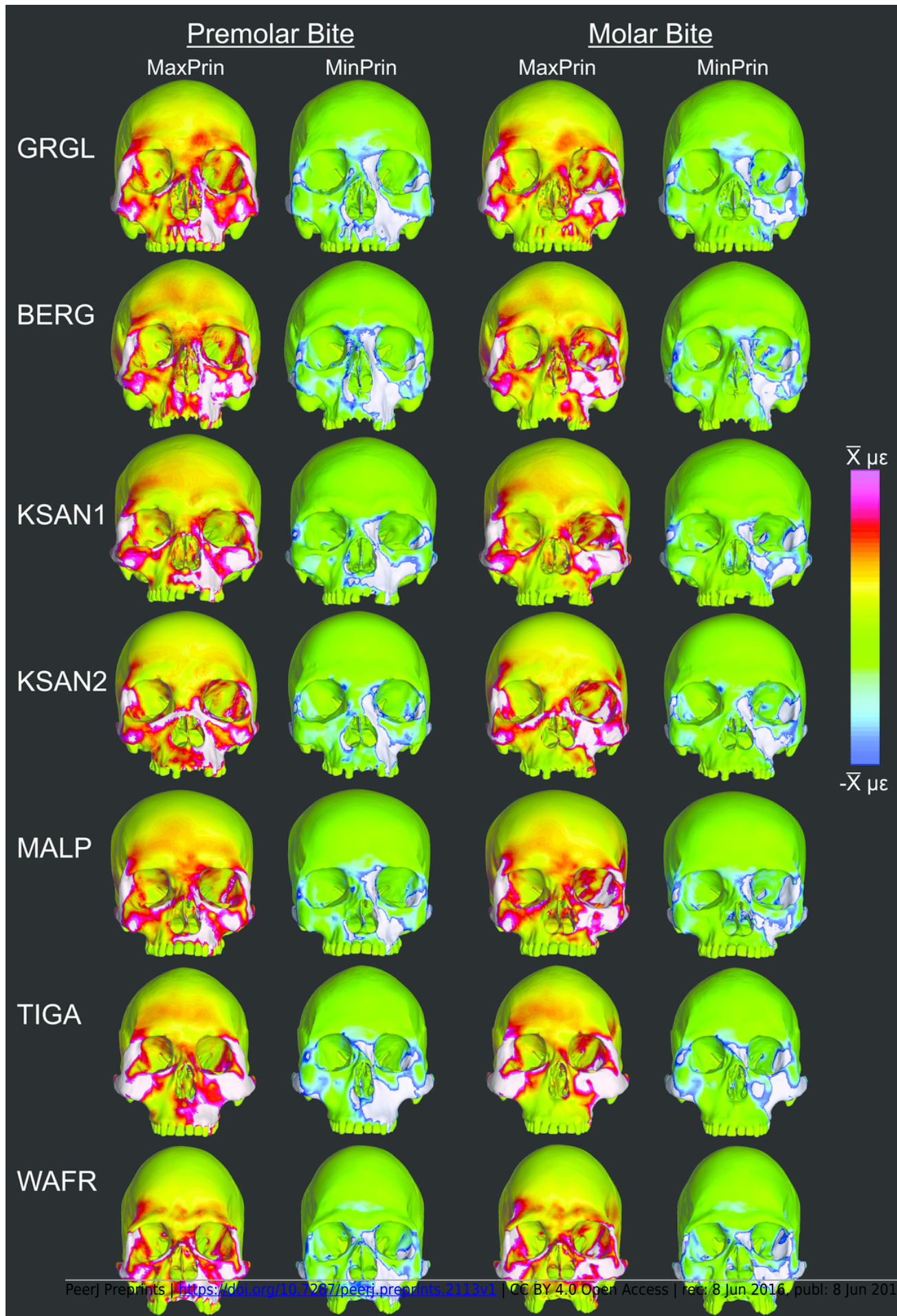
Color maps of strain distributions in the ALL-HUM variants of “extreme” and “average” modern human cranial FEMs during molar (M²) biting. Scales are set to range from -150 – 150 $\mu\epsilon$ for both maximum principal strain (MaxPrin) and minimum principal strain (MinPrin), from 0 – 300 $\mu\epsilon$ for both maximum shear strain (Shear) and von Mises strain (von Mises), and from 0 – 0.5 J/mm³ for strain energy density (SED). White regions exceed scale. Models are shown at the same height.



9

Relative strain distributions.

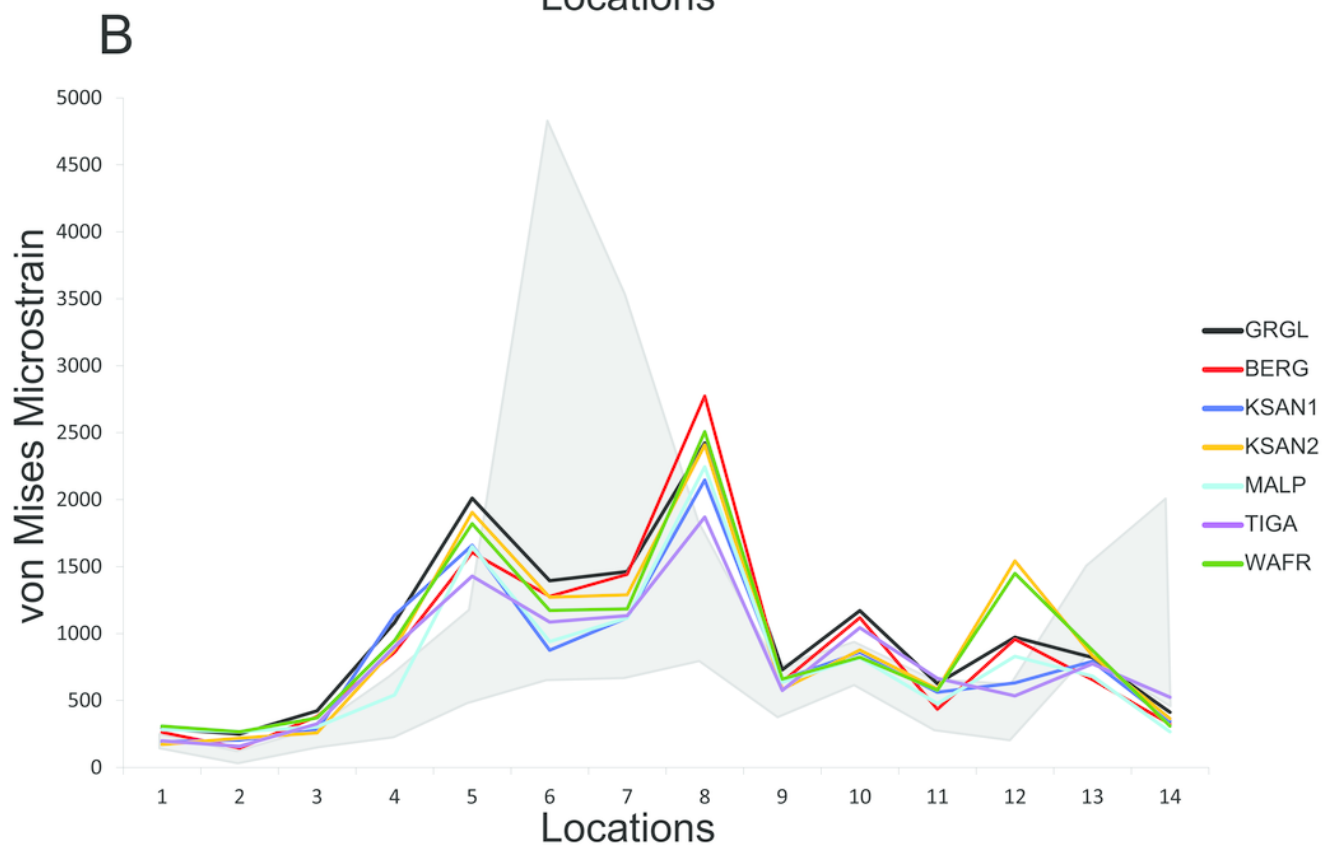
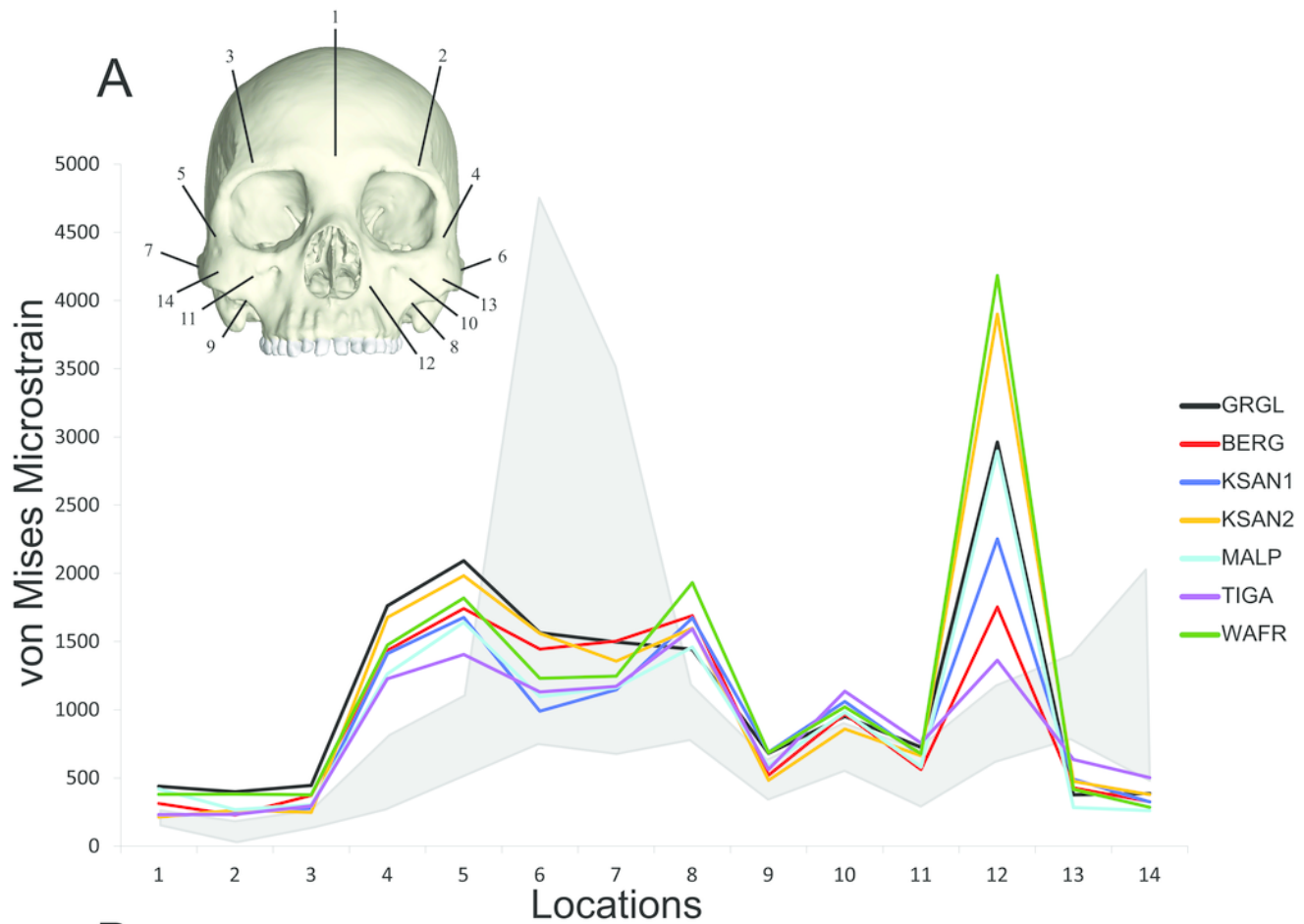
Color maps of “relative” maximum (MaxPrin) and minimum (MinPrin) principal strains in the CHIMPED model variants during premolar (P^3) and molar (M^2) biting. The scales range from $-\bar{x}$ to \bar{x} , where \bar{x} differs in each image as follows: P^3 , MaxPrin/MinPrin: GRGL, 612/644; BERG, 500/534; KSAN1, 508/603; KSAN2, 593/724; MALP, 520/610; TIGA, 455/498; WAFR, 672/742; M^2 , MaxPrin/MinPrin: GRGL, 505/546; BERG, 468/525; KSAN1, 441/473; KSAN2, 505/546; MALP, 433/458; TIGA, 419/420; WAFR, 530/553. White regions exceed scale.



10

Line plots of von Mises microstrain generated during simulated biting in finite element models of humans and chimpanzees.

Strain data correspond to **(A)** left premolar (P^3) and **(B)** left molar (M^2) biting, recorded from 14 homologous locations in the CHIMPED variants of “extreme” and “average” modern human cranial FEMs. The gray region brackets the range of variation observed for chimpanzees by Smith et al. (2015b).



11

Biting efficiency: humans vs. chimpanzees.

Box-and-whisker plots show the minimum, first quartile, median, third quartile, and maximum biting efficiency, as quantified using the mechanical advantage (MA), in the CHIMPED variants of human cranial FEMs vs. chimpanzees at **(A)** premolar (P^3) and **(B)** molar (M^2) bite points. Chimpanzee data is from Smith et al. (2015b).

