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Richard Denton
Dartmouth College

O. Sonnerup
Dartmouth College

H. Hasegawa
Institute of Space and Astronautical Science, JAXA, Sagamihara, Japan

D. Phan
University of California - Berkeley

C.T. Russell
University of California, Los Angeles

See next page for additional authors

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Authors

Richard Denton, O. Sonnerup, H. Hasegawa, D. Phan, C.T. Russell, B.L. Giles, D. Gershman, and R.B. Torbert

₁ Motion of the MMS Spacecraft Relative to the
₂ Magnetic Reconnection Structure Observed on 16
₃ Oct 2015 at 1307 UT

R. E. Denton¹, B.U.Ö. Sonnerup², H. Hasegawa³, T. D. Phan⁴,

C. T. Russell⁵, R. J. Strangeway⁵, B. L. Giles⁶, D. Gershman^{6,7}, and

R. B. Torbert⁸

4 **Abstract.** We analyze a magnetopause crossing by the Magnetospheric
5 Multiscale (MMS) spacecraft at 1307 UT on 16 Oct 2016 that showed fea-
6 tures of electron scale reconnection. For this event, we find orthonormal LMN
7 coordinates from the magnetic field, with N and L varying respectively along
8 the maximum gradient and maximum variance directions. We find the mo-

R. E. Denton, 32 Oak Tree Dr., New Smyrna Beach, FL 32169, USA. (redenton@dartmouth.edu)

D. Gershman, (daniel.j.gershman@nasa.gov)

B. L. Giles, Mail Code 673, Building 21, Room 063, Goddard Space Flight Center, Greenbelt MD 20771, USA. (barbara.giles@nasa.gov)

H. Hasegawa, Institute of Space and Astronautical Science, JAXA, Yoshinodai 3-1-1, Chuo-ku, Sagamihara, Kanagawa, 252-5210, Japan. (hase@stp.isas.jaxa.jp)

T. D. Phan, Space Sciences Laboratory, UC Berkeley, 7 Gauss Way, Berkeley, CA 94720, USA. (phan@ssl.berkeley.edu)

C. T. Russell, and R. J. Strangeway, Institute of Geophysics and Planetary Physics, UCLA, Los Angeles, CA 90024-1567, USA. (ctrussel@igpp.ucla.edu, strange@igpp.ucla.edu)

B.U.Ö Sonnerup, Thayer School of Engineering, Dartmouth College, Hanover, NH 03755, USA. (bengt.u.o.sonnerup@dartmouth.edu)

R. B. Torbert, Institute for the Study of Earth, Oceans, and Space, Morse Hall, UNH, 8 College Road, Durham, NH 03824-3525, USA. (Roy.Torbert@unh.edu)

¹Department of Physics and Astronomy,

9 tion along N from the Spatio-Temporal Difference analysis and motion along
10 L from measured particle velocities. We locate the position of the magnetic
11 X point, finding that MMS-4 passed within about 1.4 km from the X point
12 and that MMS-3 and MMS-2 passed within about 1.7 km and 2.4 km, re-
13 spectively, from the position of maximum out of plane current.

Dartmouth College, Hanover, New

Hampshire, USA

²Thayer School of Engineering,
Dartmouth College, Hanover, New
Hampshire, USA

³Institute of Space and Astronautical
Science, JAXA, Sagamihara, Japan.

⁴Space Science Laboratory, University of
California at Berkeley, Berkeley, California,
USA.

⁵Institute of Geophysics and Planetary
Physics, University of California at Los
Angeles, Los Angeles, California, USA.

⁶NASA Goddard Space Flight Center,
Greenbelt, MD, USA.

⁷Department of Astronomy, University of
Maryland, College Park, Maryland, USA.

⁸Institute for the Study of Earth, Oceans,
and Space, University of New Hampshire,
Durham, New Hampshire, USA.

1. Introduction

14 The primary goal of NASA’s Magnetospheric Multiscale (MMS) mission is to investigate
15 the kinetic processes occurring in the small-scale region called the electron diffusion region
16 [*Hesse et al.*, 2014; *Burch et al.*, 2015]. In this region neither particle species is “frozen-in”
17 or carried along with magnetic flux in directions perpendicular to the magnetic field \mathbf{B} .
18 Recently the MMS Science Working Team has identified an event observed by the MMS
19 spacecraft at 16 Oct 2015, 1307 UT, as possibly probing this region [*Burch et al.*, 2016].

20 Our purpose here is to identify for this event the directions that describe the recon-
21 necting magnetic structure, the velocity of that structure relative to the spacecraft, and
22 the paths of the spacecraft relative to that structure. We define the X point as the posi-
23 tion where the magnetic field reverses in direction and away from which the reconnected
24 plasma is ejected.

25 Methods to determine the orientation and velocity from single spacecraft data have been
26 described by *Sonnerup and Scheible* [1998], *Khrabrov and Sonnerup* [1998], *Sonnerup et al.*
27 [2013], and references therein. Methods using multi spacecraft data have been described
28 by *Schwartz* [1998], *Dunlop and Woodward* [1998], *Shi et al.* [2005], *Shi et al.* [2006],
29 *Denton et al.* [2012], and references therein.

2. Event and Data

30 On 16 Oct 2015 at 1307 UT, the four MMS spacecraft were at X , Y , and Z Geocentric
31 Solar Magnetospheric (GSM) coordinates of 8.30, 7.05, and -4.82, respectively, in units of
32 the Earth’s radius, R_E . The spacecraft were in an approximately symmetric tetrahedral
33 configuration with a nominal separation of 10 km.

Using asymptotic values for the magnetosphere and magnetosheath from the Movie 1 caption of *Burch et al.* [2016] and formulas by *Cassak and Shay* [2007], we find the outflow speed $V_{\text{out,CS}} = 241$ km/s and the hybrid density $n_{\text{out,CS}} = 7.4$ cm⁻³, from which we find the ion inertial length, $\delta_{\text{ion}} = 84$ km. (The Cassak and Shay formulas do not include a guide field [out of reconnection plane]; a small guide field seems to be present for this event [section 5].)

We used burst mode FluxGate Magnetometer (FGM) data [*Russell et al.*, 2014]. The data with a resolution of 0.0078 s were boxcar averaged every five data points yielding a resolution of 0.039 s.

We used burst mode ion and electron bulk velocity moments from the Fast Plasma Instrument (FPI) [*Pollock et al.*, 2016]. The resolution of the electron moments was 30 ms, and that of the ions (measured collectively) was 150 ms. We verified that ion density was within about 10% of the electron density at the resolution of the ion instrument.

3. Orientation of the Reconnecting Structure

We define an orthogonal “*LMN*” coordinate system with \mathbf{e}_L along the reconnection magnetic field roughly northward, \mathbf{e}_N across the current sheet roughly outward, and \mathbf{e}_M roughly westward. Figure 1c shows the magnetic field averaged over the four spacecraft, \mathbf{B}_{av} , for a period of five seconds using the *LMN* coordinates described below. In this paper, time t will always indicate seconds following 1307 UT.

To get the *L* direction, we found the direction of maximum variance of the magnetic field [*Sonnerup and Scheible*, 1998], collecting the data from all four spacecraft. Concentrating on the current sheet crossing, we used the time interval 2.3 ± 0.5 s to find $\mathbf{e}_L = (0.311, 0.488, 0.816)$ in GSM. The statistical uncertainty using equation 8.23 of *Sonnerup*

56 *and Scheible* [1998] is 2.3° . Using time intervals up to a factor of 4 larger yielded variation
 57 in the direction of less than 3° , suggesting that the statistical error is reasonable.

58 To get the N direction, we used the technique of *Shi et al.* [2005], that they call Minimum
 59 Directional Derivative analysis. This method computes a matrix from the gradient of
 60 the vector magnetic field calculated using the field and positions of the four spacecraft,
 61 $\partial_i B_j$, then multiplies this matrix by its transpose to form a symmetric matrix. This
 62 second matrix is diagonalized to find the eigenvalues and eigenvectors associated with
 63 the gradient. We get \mathbf{e}_N from the maximum gradient direction that is across the current
 64 sheet. Results were similar using the modified method with the perturbed gradient as
 65 described by *Denton et al.* [2010, 2012].

66 It was necessary to use both of these methods to define the LMN coordinate system for
 67 this time interval because the intermediate and minimum eigenvalues for both methods
 68 were not well separated (factor of 5.1 for the magnetic variance and factor of 1.7 for the
 69 Shi method matrix), indicating a poor determination of the other directions.

70 The eigenvalues from the Shi et al. method are shown in Figure 1a. Separation of the
 71 maximum eigenvalue (black curve in Figure 1a) from the other eigenvalues (blue and red
 72 curves in Figure 1a) was good for much of the time interval plotted. To get \mathbf{e}_N , we used
 73 the maximum gradient direction $\mathbf{e}_{G,\max}$ in the same time interval, 2.3 ± 0.5 s. The vector
 74 $\mathbf{e}_{G,\max}$ is time dependent and defines a time varying direction $\mathbf{e}_{N'}$ (Figure 1b). To obtain
 75 a single N direction, we averaged the squared gradient matrix [*Denton et al.*, 2010, 2012]
 76 to find the maximum gradient eigenvector (0.803,0.274,-0.529), plotted as the asterisks
 77 in Figure 1b. This direction is 92.7° from \mathbf{e}_L determined above. The standard deviation
 78 $\mathbf{e}_{N'}$ away from the average direction was 17.5° , but the uncertainty of the mean (dividing

79 by $\sqrt{N-1}$) was only 3.5° . Subtracting off the component of the vector parallel to \mathbf{e}_L
 80 and re-normalizing, we found $\mathbf{e}_N = (0.819, 0.296, -0.490)$, plotted as the open circles in
 81 Figure 1b. Then $\mathbf{e}_M = \mathbf{e}_N \times \mathbf{e}_L = (0.480, -0.820, 0.307)$. The \mathbf{e}_N direction is 14° off from
 82 the normal from the *Shue et al.* [1998] magnetopause model. Note that we could have
 83 equally well used \mathbf{e}_N without adjustment, and adjusted \mathbf{e}_L ; or we could have made some
 84 intermediate choice.

85 Close to the current sheet, the minimum gradient direction, which was erratic, tended
 86 to be more aligned with our maximum variance direction L than with our M direction.
 87 This indicates that the structure probably had significant variation in all three directions.
 88 Nevertheless we will describe the average two dimensional structure in what we call the
 89 reconnection plane that includes L and N .

90 In Figure 1c, the L component of \mathbf{B}_{av} , $B_{av,L}$, was largest and positive for $t < 2.3$ s,
 91 indicating that the spacecraft crossed from the magnetosphere into the magnetosheath.
 92 The oscillations in $B_{av,L}$ may indicate non-monotonic motion.

4. Motion of the Magnetic Structure

93 The *Shi et al.* [2006] method, that they call ‘‘Spatio-Temporal Difference’’ analysis,
 94 can be used to get the velocity of the magnetic structure relative to the average position
 95 of the spacecraft, $\mathbf{V}_{str} = -\mathbf{V}_{sc}$, where \mathbf{V}_{sc} is the velocity of the spacecraft relative to
 96 the structure. At each moment in time, the structure is assumed to be time invariant
 97 and moving with constant velocity so that the observed rate of change of \mathbf{B} is $d\mathbf{B}/dt =$
 98 $\mathbf{V}_{sc} \cdot \nabla \mathbf{B}$. Given that $\nabla \mathbf{B}$ is known from the *Shi et al.* [2005] method discussed in section 3,
 99 this equation can be inverted to yield \mathbf{V}_{sc} versus time from the observed $d\mathbf{B}_{av}/dt$.

100 Since the inversion schematically divides $d\mathbf{B}/dt$ by the gradient of \mathbf{B} , the resulting
 101 values of $\mathbf{V}_{\text{str}} = -\mathbf{V}_{\text{sc}}$ will have large errors in the directions for which $\nabla\mathbf{B}$ is small.
 102 Typically the component in the direction of the minimum gradient eigenvector from the
 103 *Shi et al.* [2005] method is greatly in error [*Denton et al.*, 2010, 2012]. For our event,
 104 the intermediate gradient component may also at times be unreliable. In Figure 2b, we
 105 show $V_{\text{str},N}$, the N component of \mathbf{V}_{str} , calculated in three different ways. The gold curve
 106 uses the full vector velocity constructed from all three components of the point by point
 107 \mathbf{V}_{str} , the green curve uses only the point by point maximum and intermediate gradient
 108 directions, and the blue curve uses only the point by point maximum gradient direction.
 109 In each case, the velocity constructed from these components is dotted into \mathbf{e}_N .

110 The gold, green, and blue curves in Figure 2c show the time integral of the correspond-
 111 ing velocity components plotted in Figure 2b, yielding the displacement of the structure
 112 relative to the spacecraft in the N direction, dN_{str} . All three curves are very consistent
 113 between about $t = 1.8$ s and 2.7 s. This region includes $t \sim 2.3$ s, the time of steepest
 114 gradient in $B_{\text{av},L}$ (Figure 2a), the magnetic reversal ($B_{\text{av},L} = 0$), marked by the vertical
 115 gray dotted lines in Figure 2a–c, and the flow reversal in the L direction, as we will show
 116 below. Therefore this region will turn out to be the crucial region for determining the
 117 position of the X point.

118 Outside of this interval, we do not know, a priori, which calculation of dN_{str} is more
 119 accurate. Potentially, the gold curve in Figure 2c, having been calculated using all three
 120 components of the point by point \mathbf{V}_{str} , could contain the most information. The gold
 121 curve in Figures 2b and 2c is fairly well behaved between $t = 1.77$ s and 3.49 s. But
 122 the large off scale oscillations for the gold curve outside of that interval suggest that it

123 is unreliable at those times. Note that if the magnetic structure moves outward, then
 124 the spacecraft will be moving into the magnetosphere where B is larger. So if the time
 125 variation of $B_{av,L}$ in Figure 2a results mainly from motion normal to the current sheet
 126 (across a gradient in $B_{av,L}$), then the time dependence of the displacement in Figure 2c
 127 ought to look similar to the time dependence of $B_{av,L}$ in Figure 2a. Both the green and
 128 blue curves in Figure 2c show some similarity to $B_{av,L}$.

129 For reasons that we will be easier able to explain later, we use, for the purposes of cal-
 130 culating the spacecraft motion, the average of the gold curve and blue curve in Figure 2b
 131 for $\mathbf{V}_{str,N}$ for $t = 1.77$ s to 3.49 s, and the average of the green and blue curve in Figure 2b
 132 for $\mathbf{V}_{str,N}$ outside of that time interval. (A rough estimate of the gradient due to fluctu-
 133 ations at the precision of the magnetometers suggests that the gold curve could possibly
 134 be accurate in most of the region $t = 1.77$ s to 3.49 s.) This procedure is a compromise
 135 in each region, inner and outer, between the potentially more accurate velocity and the
 136 safer velocity from the maximum gradient direction alone. The displacement calculated
 137 using this hybrid velocity leads to the gray dashed curve in Figure 2c. Using this curve
 138 for the displacement leads to better agreement with the observations, as we will discuss
 139 in section 5.

140 For reasons not understood, the electron and ion velocities along our N direction (not
 141 shown) have large opposite flow during the time interval from $t = 0$ to the vertical dotted
 142 line in Figure 2a–c, with the electrons moving outward (positive N direction) and the ions
 143 moving inward. If, instead, we dot the electron and ion velocities with the instantaneous
 144 normal directions, $\mathbf{e}_{N'}$, and integrate that velocity to find a normal displacement, both the
 145 electrons and ions oscillate in and out in a manner similar to the motion in Figure 2c, but

146 with different velocities. The electron velocity is the largest, and the magnetic structure
 147 has a normal velocity intermediate between the electron and ion velocities.

148 As a check of our values of $V_{\text{str},N}$, we used the timing analysis described by *Schwartz*
 149 [1998]. In Figure 3a, we show B_L for the four MMS spacecraft (solid curves) and the
 150 same data smoothed with a running average over 5 data points (dotted curves). Using
 151 spacecraft positions at the times of maximum gradient (circles in Figure 3a), we found the
 152 normal direction and velocity of a plane crossing the spacecraft. This normal direction
 153 was (0.692,0.431,-0.579), which is 12.1° from our more accurate N direction. The normal
 154 velocity from the timing analysis was -43. km/s (red dot in Figure 2b; *Burch et al.* [2016]
 155 found -45 km/s), 10% off from the average of the gold and blue curves in Figure 2b at
 156 that time (-48 km/s).

157 Figure 3b shows the L component of the electron velocity, $V_{e,L}$, for the four MMS
 158 spacecraft, and Figure 3c shows the average L component of the electron velocity, $V_{e,\text{av},L}$
 159 (green curve) and ion velocity, $V_{\text{ion},\text{av},L}$ (blue curve). There is a lot of spatial structure
 160 in the electron velocity leading to the differences between the curves for the different
 161 spacecraft in Figure 3b, but $V_{e,\text{av},L}$ (green curve in Figure 3c) exhibits a clear linear ramp
 162 between $t = 2.03$ s and 2.47 s, marked off by the two vertical dotted lines in Figure 3c.
 163 At the midpoint of this ramp, $t = 2.25$ s, the blue curve for $V_{\text{ion},\text{av},L}$ crosses the green
 164 curve for $V_{e,\text{av},L}$. We infer that the centroid of the spacecraft passed the X point in the
 165 L direction at that time, and that the common velocity at that time, -97 km/s, is the
 166 L component of the velocity of the reconnection structure. Both $V_{e,\text{av},L}$ and $V_{\text{ion},\text{av},L}$ are
 167 more negative than that velocity for $t < 2.25$ s and more positive for $t > 2.25$ s. So both
 168 the electrons and ions are flowing outward in the L direction away from the X point. Since

169 the L direction is northward and the spacecraft are at negative Z , this means that the X
 170 point is moving away from the magnetic equator. Relative to the X point, the plasma is
 171 flowing away from the magnetic equator for $t < 2.25$ s, and toward the magnetic equator
 172 for $t > 2.25$ s. Based on the 97 km/s structure velocity, the end of the linear ramp in
 173 Figure 3c is $0.25 \delta_{\text{ion}}$ downstream.

174 The green and blue curves in Figure 2d are respectively $V_{e,av,L}$ and $V_{ion,av,L}$ shifted up by
 175 97 km/s for a longer time interval, $t = -5$ s to 8 s. The vertical solid line is at $t = 2.25$ s,
 176 where the electron and ion L velocities diverge from zero, and the adjacent vertical dotted
 177 lines are drawn at the limits of the linear ramp in $V_{e,av,L}$ from Figure 3c; the ion velocity
 178 also has a roughly linear ramp between the more separated vertical dashed lines. Moving
 179 to the left in Figure 2d from the flow reversal at 2.25 s, the ion velocity is smaller than the
 180 electron velocity until the end of the ion velocity ramp $7.2 \delta_{\text{ion}}$ downstream. The electron
 181 velocity and the ion velocity on the left side of Figure 2d accelerate to an outflow speed
 182 matching $V_{\text{out,CS}}$, the Cassak-Shay outflow jet speed (horizontal dotted lines in Figure 2d).

5. Paths of the Spacecraft Relative to the Reconnection Structure

183 We have assumed that the reconnection structure is moving in the L direction with
 184 the common velocity -97 km/s of the electrons and ions (Figure 3c) at $t = 2.25$ s. The
 185 roughly linear variation of $V_{ion,av,L}$ (Figure 2d) indicates that the L component of the
 186 structure velocity does not vary greatly in an interval around $t = 2.25$ s. For the purpose
 187 of visualizing the spacecraft paths, we assume that this velocity is constant.

188 In Figure 4c the black arrows, short magenta arrows, and long magenta arrows show
 189 respectively the directions of the reconnection magnetic field B_L , the plasma inflow ve-
 190 locity V_{in} , and the plasma outflow velocity V_{out} . The thick gold curve in Figure 4c is the

191 trajectory of the centroid of the MMS spacecraft (“MMS-Av”) relative to the magnetic
 192 structure in the L - N plane. The displacement in the N direction, $N_{\text{sc,Shi}}$, is the negative of
 193 the gray dashed curve for dN_{str} in Figure 2c, defined so it is zero at the magnetic reversal
 194 at $t = 2.47$ s. The displacement in the L direction is $L_{\text{sc},97\text{km/s}} = (t - 2.25 \text{ s})(97 \text{ km/s})$,
 195 so that it is zero at the flow reversal at $t = 2.25$ s. So the origin is where we estimate
 196 the X point to be. Based on the gold curve in Figure 4c, the spacecraft oscillated toward
 197 and away from the current sheet, crossed $L = 0$ (flow reversal), crossed $N = 0$ (magnetic
 198 reversal), wandered in the L direction, and then crossed back over $N = 0$ near $t = 5$ s.

199 Figure 4c also shows the trajectories of the individual MMS spacecraft using the colors
 200 indicated in the legend. These trajectories are displaced from the trajectory of the centroid
 201 by the relative displacement of each spacecraft (see starting point of curves).

202 Figure 4a shows B_L averaged over the four spacecraft (“MMS-Av”) and for the individ-
 203 ual spacecraft, versus the time t_{Av} . This time is equivalent to t only for MMS-Av. The
 204 other curves have been shifted horizontally so that the observed field components line up
 205 vertically with the corresponding position in panel c (see starting point of curves). The
 206 oscillations in $N_{\text{sc,Shi}}$ to the left of the vertical line in Figure 4c are strongly correlated
 207 with the oscillations in B_L in Figure 4a. Generally the lowest B_L values in Figure 4a
 208 occur for the spacecraft with the largest $N_{\text{sc,Shi}}$ values. The MMS-2, MMS-3, and MMS-4
 209 spacecraft passed quickly through the magnetic reversal at $N_{\text{sc,Shi}} = 0$, and correspond-
 210 ingly B_L in Figure 4a reversed quickly for these spacecraft. But the motion in the N
 211 direction stagnated when MMS-1 was near the magnetic reversal ($L_{\text{sc},97\text{km/s}} \sim 75$ km in
 212 Figure 4c). Correspondingly, MMS-1 observed B_L near zero at that time (Figure 4a).

213 The L and N axes in Figure 4c divide space into four quadrants. For symmetric (same
 214 conditions in magnetosphere and magnetosheath) anti-parallel (no guide field) recon-
 215 necting, the sign of B_M should be positive into the page in the bottom left and upper right
 216 quadrants of Figure 4c [e.g., Figure 5c of *Sonnerup et al.*, 2016], as indicated by the green
 217 arrow heads pointing into the page in Figure 4c. Then B_M would be negative out of the
 218 page in the upper left and bottom right quadrants of Figure 4c. For asymmetric recon-
 219 nection, this quadrupolar structure is not necessarily expected [*Mozer et al.*, 2008], but
 220 the structure of B_M does appear to be quadrupolar for this event. Note that during the
 221 time that MMS-Av crossed into the lower right quadrant (just to the right of the origin in
 222 Figure 4c), the average B_M is negative. According to Figure 4c, MMS-1 penetrated most
 223 deeply (near $L_{sc,97km/s} = 0$) into the lower right quadrant. Correspondingly, B_M became
 224 most negative for MMS-1. MMS-1 penetrated the least into the magnetosheath (upper
 225 region in Figure 4c), and correspondingly, B_M became least positive for MMS-1 on the
 226 right side of Figure 4b. When MMS-4 was near the X point (the origin in Figure 4c), it
 227 observed a minimum in B_M , ~ -2.5 nT. This suggests that there was a small guide field
 228 of about 1/10 of the asymptotic magnetosheath field.

229 According to Figure 4, MMS-4 passed nearest to the X point, within 1.3 km on the
 230 lower right side of the X point in Figure 4 at $t = 2.35$ s. Supplementary Figure S1 shows
 231 that MMS-4 measured a minimum in the total magnetic field B or the magnetic field
 232 calculated from the L and N components (allowing for the possibility of a guide field),
 233 B_{LN} , between about $t = 2.3$ s and 2.33 s.

234 According to *Burch et al.* [2016], the electron dissipation region where the electron
 235 kinetic effects were most important was not at the magnetic reversal, but at the peak in

236 the M component of the plasma current, J_M . We calculated the average current density
 237 using FPI data, and found that this peaked at $t = 2.20$ s. The position of MMS-Av at
 238 this time is marked by the intersection of the thick gold curve with the horizontal dotted
 239 line in Figure 4. We assume that the intersection of this line with the flow reversal is
 240 where the greatest amount of dissipation occurred. According to our model, MMS-2 and
 241 MMS-3 had the closest approach to this intersection, with MMS-3 coming within 1.7 km
 242 at $t = 2.19$ s and MMS-2 within 2.4 km at $t = 2.21$ s. According to our calculations using
 243 the FPI data, MMS-3 observed the largest negative J_M , $-11,800$ e cm $^{-3}$ km/s (where e is
 244 the proton charge) at $t = 2.22$ s, and MMS-2 observed the second largest negative value,
 245 $-10,800$ e cm $^{-3}$ km/s at $t = 2.19$ s, followed by MMS-4 with $-10,500$ e cm $^{-3}$ km/s at
 246 $t = 2.14$ s and MMS-1 with $-8,200$ e cm $^{-3}$ km/s at $t = 2.55$ s.

247 We are not claiming that the trajectories in Figure 4 are exact. For instance, if we used
 248 the green curve in Figure 2c rather than the gray dashed curve to get $N_{sc,Shi}$ in Figure 4c,
 249 we would find that MMS-4 passed within 1.9 km of the X point on the upper left side,
 250 rather than the lower right side, of the X point in Figure 4. But Figure 4c probably does
 251 correctly indicate that MMS-4 had the closest approach to the X point and that MMS-2
 252 and MMS-3 had the closest approaches to the point where J_M peaks and the flow reverses.

253 We are most confident about the motion between $t = 1.8$ s and 2.7 s, during which
 254 all the curves in Figure 2c agree; the positions at the limits of this interval are marked
 255 by gold filled circles on the thick gold curve in Figure 4c. The reason that we defined
 256 the hybrid velocity leading to the gray dashed curve in Figure 2c is because use of the
 257 gray dashed curve led to better agreement with the observations outside of the gold filled
 258 circles in Figure 4c. Using the gray dashed curve, the trajectory of MMS-1 (black curve

259 in Figure 4c) is very close to $N = 0$ when B_L for MMS-1 is close to zero (black curve in
260 Figure 4a) and the magnetic field observed by MMS-1 is at a minimum (black curve in
261 Figure S1e). If we had used the gold curve alone in the central region, MMS-1 would have
262 gone more deeply into the magnetosheath, whereas if we had used the blue curve alone in
263 the central region, MMS-1 would have stayed more deeply in the magnetosphere. If we
264 had used the blue curve alone for the outer region, MMS-4 would have oscillated across the
265 magnetic reversal ($N = 0$) at early times, whereas B_L in Figure 4a suggests that MMS-4
266 stayed within the magnetosphere during the oscillations. Or if we had used the green
267 curve alone for the outer region, MMS would not have returned into the magnetosphere
268 near $t_{Av} = 4.7$ s as suggested by B_L in Figure 4a.

269 Though there is evidence of significant spacecraft dependent structure in the M di-
270 rection, we have nevertheless found a good description of the average structure in the
271 reconnection plane including the reconnection magnetic field and the direction across the
272 current sheet at 1307 UT. By using the data from multiple spacecraft, we have been
273 able to determine the orientation of the magnetic structure, the velocity of the magnetic
274 structure in the L - N plane, and the paths of the spacecraft relative to that structure.

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281 available at <https://lasp.colorado.edu/mms/sdc/public/links>. Supplementary data from

our calculations can be found in the Supplementary Information file. In addition to Supplementary Figure S1 referenced in the text, Supplementary Text S1 to S3 has more detail on the calculation of the LMN coordinate system. Supplementary Dataset S1 lists the velocities and directions from the *Shi et al.* [2005, 2006] method, while Dataset S2 lists the L and N positions that we calculated.

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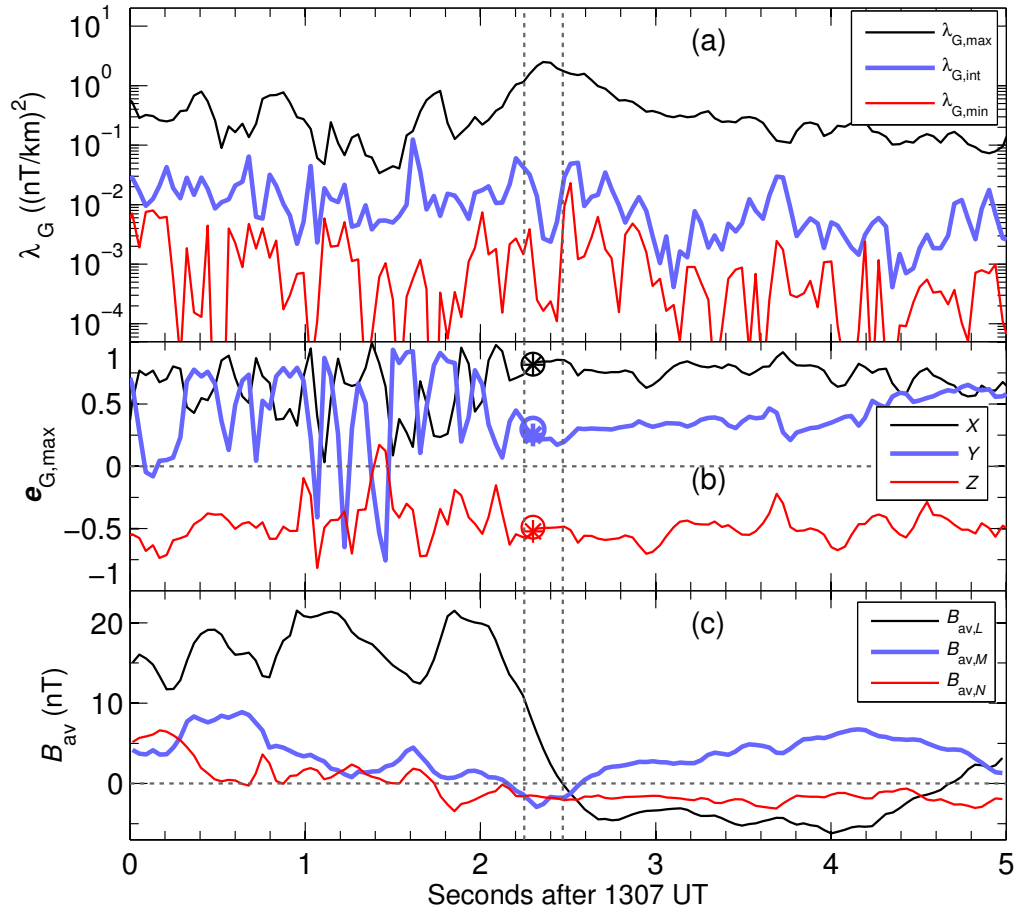


Figure 1. Results from Shi et al. method versus time: (a) Squared gradient eigenvalues λ_G . (b) GSM X , Y , and Z components of the maximum gradient eigenvector, $\mathbf{e}_{G,\max}$. The asterisks and circles show, respectively, components of \mathbf{e}_N from the average matrix before and after subtracting off the projection in the L direction. (c) \mathbf{B}_{av} in the LMN coordinate system. The left and right vertical dotted lines show, respectively, the time of plasma flow reversal in the L direction and time of $B_{\text{av},L}$ reversal.

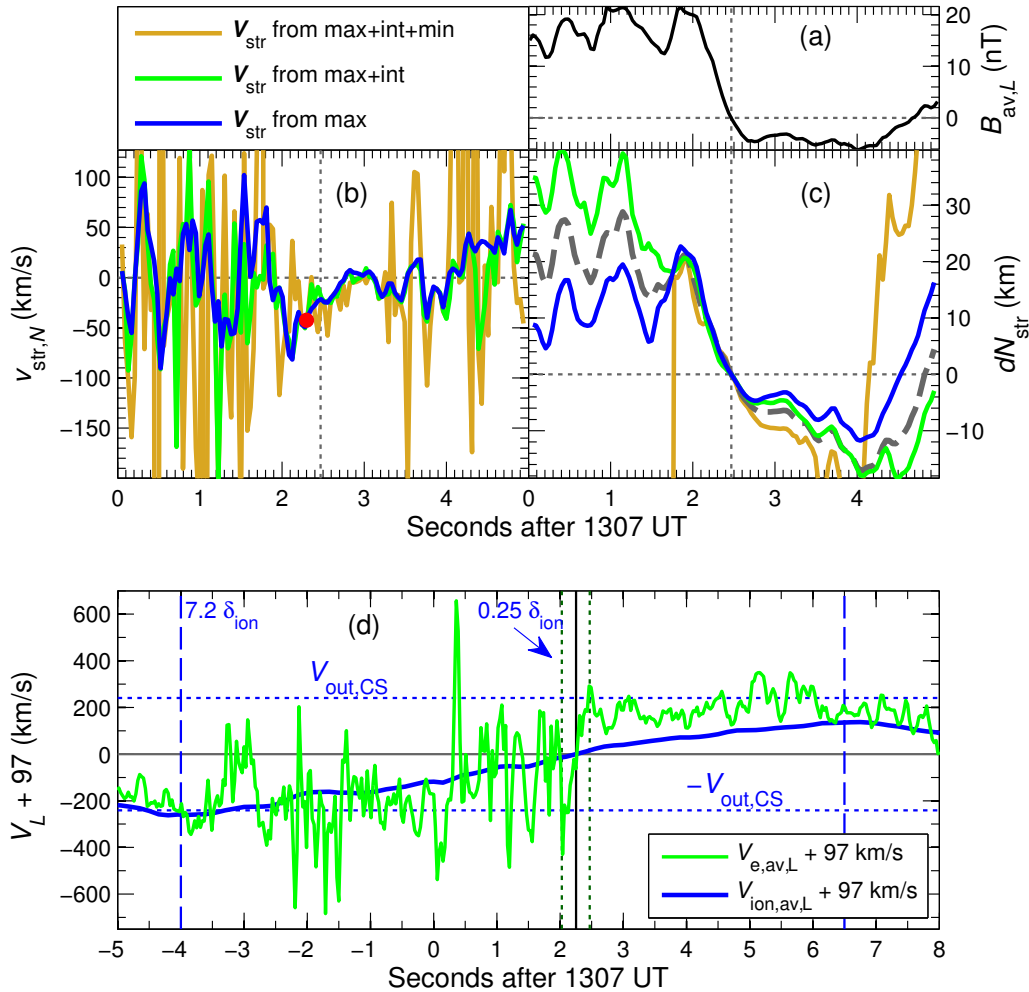


Figure 2. Structure velocities: (a) $B_{av,L}$ versus time. Panels (b) and (c) show, respectively, the velocity and displacement in the N direction using all three components of the point by point \mathbf{V}_{str} (gold curve), using only components in the maximum and intermediate gradient directions (green curve), and using only the component in the maximum gradient direction (blue curve). The red dot in panel (b) shows the result from the timing study. The gray dashed curve in panel (b) is calculated from a hybrid velocity described in the text. Panel (d) shows the average L component of the velocity shifted up by 97 km/s for electrons (green curve) and ions (blue curve). The horizontal dotted lines show the outflow speed $V_{out,CS}$ and the vertical dotted and dashed lines show, respectively, the end of the electron velocity ramp at $0.25 \delta_{ion}$ downstream and the end of the ion velocity ramp at 7.2 (at negative times) δ_{ion} downstream.

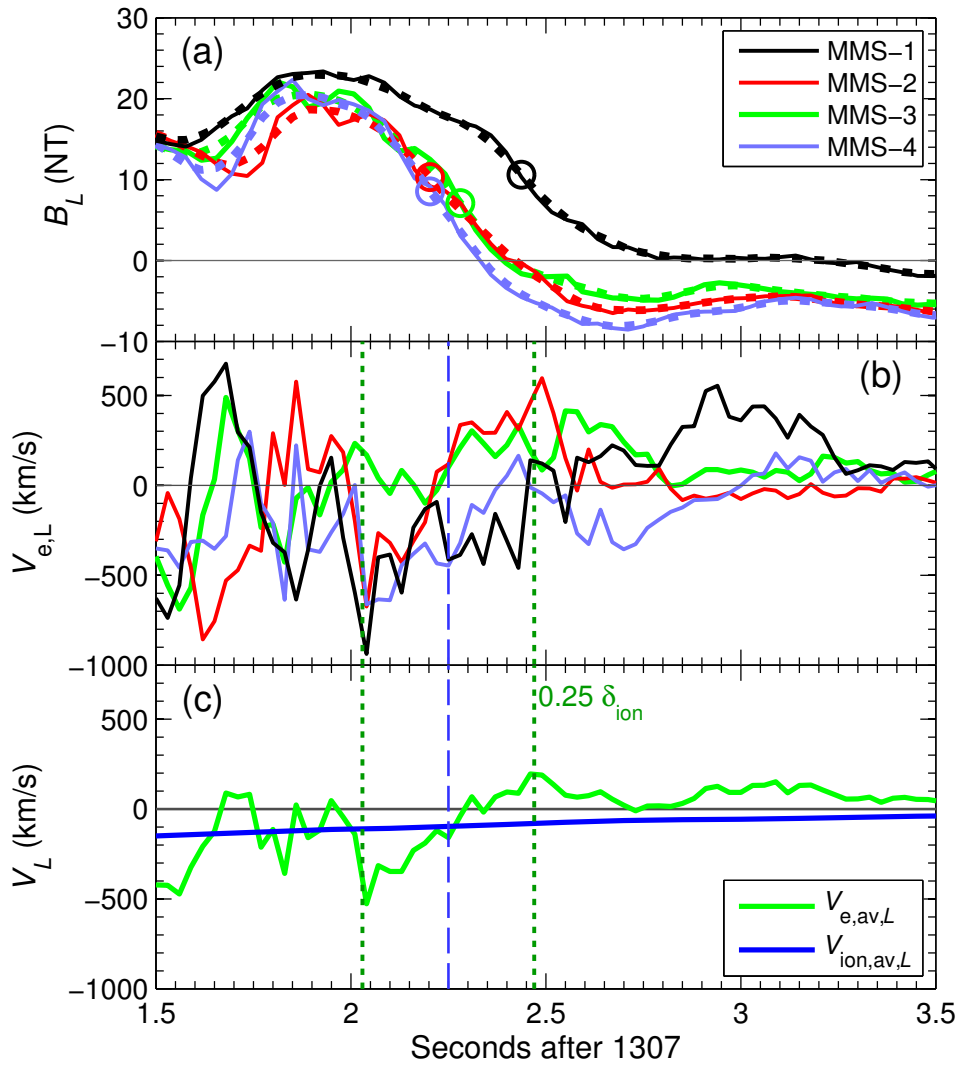


Figure 3. Behavior of L components: (a) B_L for the four MMS spacecraft (solid curves) and the same data smoothed (dotted); (b) the L component of the electron velocity, $V_{e,L}$, for the four MMS spacecraft, using the same colors as in Figure 3a; (c) the average L component of the velocity for electrons (green curve) and for ions (blue curve). The vertical dashed line is where the electron and ion velocities equal -97 km/s, and the vertical dotted lines are at the ends of the electron velocity ramp, $0.25 \delta_{ion}$ downstream (assuming 97 km/s velocity) from the location of common velocity.

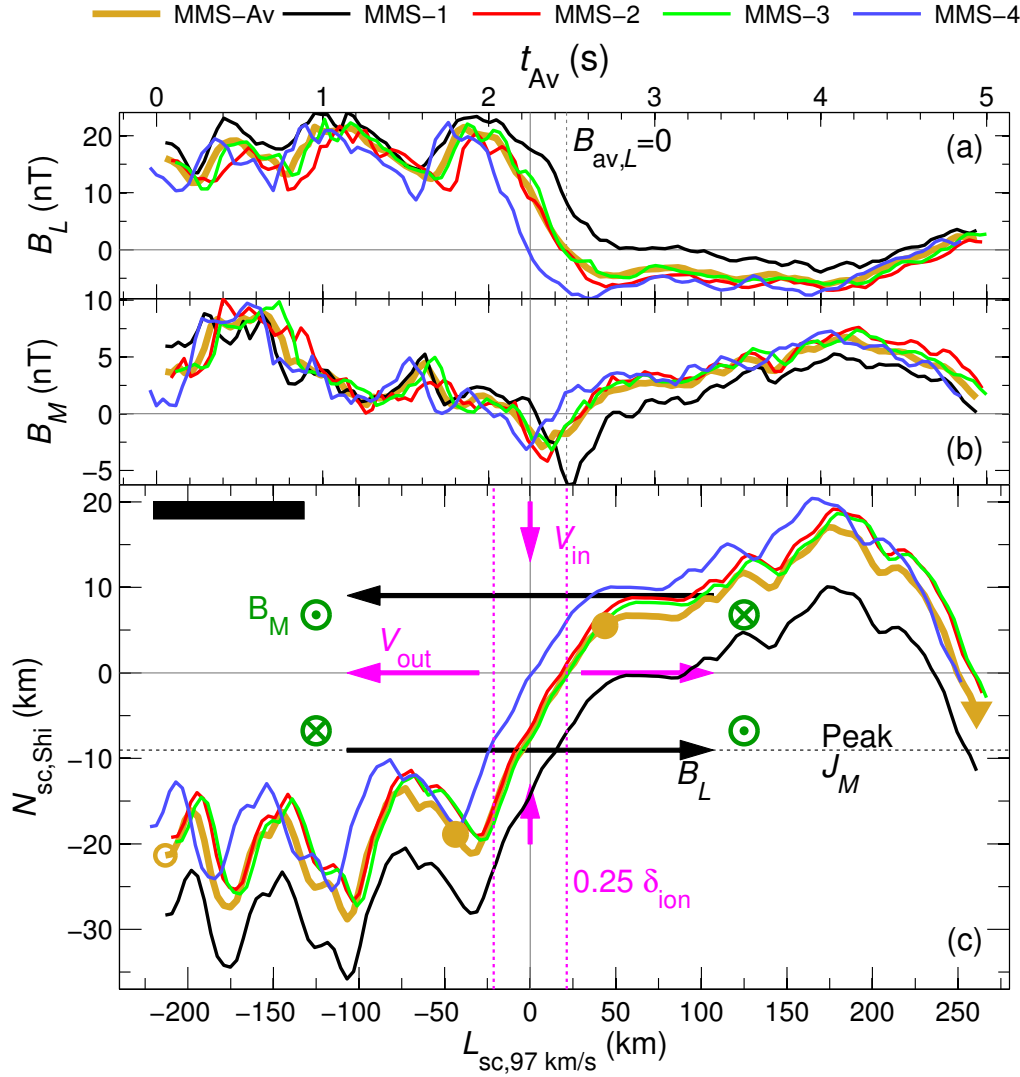


Figure 4. Spacecraft paths: (c) Trajectory of centroid (“MMS-Av”) and of individual MMS spacecraft relative to the reconnection structure in the L - N plane with the X point at the origin. The centroid started at the open gold circle and ended at the downward pointing gold triangle. The gold curve is especially reliable between the gold filled circles. The filled black rectangle in the upper left corner of the panel shows the shape of the panel if the same scale for L and N were used. Panels (a) and (b) show B_L and B_M versus t_{Av} at the top of the plot; t_{Av} is the real time (following 1307 UT) only for MMS-Av. The other curves have been shifted so that the observed field components line up vertically with the corresponding position in panel c.