Dry-Ice Blasting of Auto Robotic Assemblies

Nazim Baluch*1, Shahimi Mohtar2, Che Sobry Abdullah3

1.2.3 School of Technology Management and Logistics,
College of Business, Universiti Utara Malaysia
06010 Sintok, Kedah, Malaysia
*1nazimbaluch@uum.edu.my
2shahimi@uum.edu.my
3sobry@uum.edu.my

Abstract - Welding robots are extensively applied in the automotive assemblies and 'Spot Welding' is the most common welding application practiced in the auto stamping assembly manufacturing. Though adaptive resistance welding control automatically compensates to keep production and quality up to the levels needed as welding gun tips undergo wear so that the welds remain reliable; the system cannot compensate for deterioration caused by the slag and spatter on the part holding fixtures, sensors, and gun tips. To cleanse welding robots of slag and spatter, dry-ice blasting has proven to be an effective antidote. This paper describes Spot welding process, analyses the slag and spatter formation during robotic welding of stamping assemblies, and concludes that the dry ice blasting process's utility in cleansing of welding robots in auto stamping plant operations is preeminent.

Keywords - Dry Ice Blasting, Robotic Assemblies, Spot Weld, Slag, Welding Robots

1. Background

According to Steinke and Rickel (2015) nothing throws off a manufacturing schedule as quickly or drastically as downtime from an unscheduled equipment failure. That's why diligent, regular predictive and preventive maintenance (PM) is crucial to the success and efficiency of any manufacturing operation. Sensitive automated equipment, such as a robotic welding cell, for example, requires a targeted, routine predictive and preventive maintenance management program to ensure proper operational reliability and provide maximum in-service lifespan. An effective program involves a routine, systematic inspection, adjustment, lubrication, and replacement of components, as well as software upgrades and

performance testing and analysis. Developing the best routine preventive maintenance program for automated welding systems depends on employing in-house capabilities or choosing a provider whose experience and process best suits production needs. However, working with third-party PM provider's equipment will allow plant's in-house maintenance staff to focus on their core competencies and leave the inspections, cleaning and maintenance to seasoned preventive maintenance experts who are well versed in automated welding equipment. These experts will examine operations and equipment, assess manufacturing environment and help determine the right course of action for plant's manufacturing facility and, in particular, the automated equipment. However, the frequency and scope of any PM plan for automated components is dependent on the nature of the manufacturing operation and the plant environment [1].

Simply put, explain Steinke and Rickel (2015) that there's more to maintaining an automated welding power source than blowing the dirt out of it; some methods of cleaning and degreasing are more effective for this application than others. Special processes are required to fully clean and degrease a power source exposed to months or years of shop environmental contaminants. Environment-friendly degreasing is another must in this era of environmental regulations. Not all shops offer this benefit; it is, therefore, imperative that the prospective service providers ensure the process they use is environmentally safe [1]. Dry-Ice Blasting, besides being environmentally friendly, can also reduce the time spent using traditional cleaning methods within an automotive plant and increase productivity. This means the plant does not need to be shut down, there is no clean up after and there is no need for cool down or drying time, which can result in a cleaning within hours versus days.

2. Introduction

Matsubara et al., (2010) point out that robot welding is a relatively new application of robotics; it is the branch of technology that deals with the design, construction, operation, and application of robots as well as computer systems for their control, sensory feedback, and information processing. Even though robots were first introduced into US industry during the 1960s, the use of robots in welding did not take off until the 1980s, when the automotive industry began using robots extensively for spot welding. Since then, both the number of robots used in industry and the number of their applications has grown tremendously. Investing in welding automation can be a relatively quick way for companies to achieve greater productivity, improve weld quality and reduce costs [2]. But protecting that investment is the key to maintaining these benefits over the long term. Preventive and predictive maintenance programs are an easy and cost-effective way to help. These programs not only protect against costly downtime, but they can also help lower labor costs, reduce waste and minimize rework [3]. The robot may weld a pre-programmed position, be guided by machine vision, or by a combination of the two methods. However, the many benefits of robotic welding have proven to make it a technology that helps many original equipment manufacturers (OEM) increase; accuracy, repeatability, and throughput [4].

Snide (1992) expounds that Dry-Ice is the solid form of Carbon Dioxide (CO2). Though it is present, in our atmosphere in relatively small quantities (about 0.03% by volume), it is one of the most important gases we know of. In the early 1930's, the manufacture of solid phase CO₂ became possible. As the procedure for making dry ice became readily available, applications for this innovative substance grew. Obviously, the first use was in refrigeration, and dry ice is still widely used in the Food Industry for packaging and protecting perishable foods today. In August 1977, Calvin Fong received a patent on "Sandblasting with pellets of material capable of sublimation". The work and success of these early pioneers led to the formation of several companies in the early 1980's that pursued the development of dry ice blasting technology. In 1986, Cold Jet®, Inc. was founded in the State of Ohio by Mr. Newell Crane. Dry ice pelletizers and dry ice blasting machines entered the industrial markets in the late 1980's. At that time the blasting machines were physically large,

expensive, and they required high air pressure for operation (pressures greater than 200 psi or 13.8) bars). As the CO₂ / dry ice blasting technology advanced, the dry ice blasting machines' size and cost dropped, and presently, the latest nozzle technology has made blasting effective at shop air pressures of 80 psi or 5.5 bar [5]. Nowadays, CO₂ / dry ice blasting is being effectively used in a wide array of applications from heavy slag removal to delicate semiconductor and circuit board cleaning; a process that can be used on-line without damaging equipment or requiring a machine "teardown". Virtually any item that is part of a production process and is difficult to clean on-line or during production hours by traditional means may be an excellent dry ice application such as removing weld slag from Robotics, Fixtures, and Carriers [6].

3. Spot resistance welding

The two most common welding process are; spot and seam welding that produce coalescence of faying surfaces where heat to form the weld is generated by the electrical resistance of material combined with the time and the force used to hold the materials together during welding. Spot Welding process uses two shaped copper alloy electrodes to concentrate welding current into a small "spot" and to simultaneously clamp the sheets together.

Weman (2003) in the 'Welding Handbook' elaborates that welding is a fabrication or sculptural process that joins materials, usually metals or thermoplastics, by causing coalescence. This is often done by melting the work pieces and adding a filler material to form a pool of molten material (the weld pool) that cools to become a strong joint, with pressure sometimes used in conjunction with heat, or by itself, to produce the weld. This is in contrast with soldering and brazing, which involve melting a lower-melting-point material between the work pieces to form a bond between them, without melting the work pieces [7].

Spot Welding - Resistance Spot Welding (RSW) as explicated by Weman (2003) in the 'Welding Handbook' is a process in which contacting metal surfaces are joined by the heat obtained from resistance to electric current. Work-pieces are held together under pressure exerted by electrodes. Typically the sheets are in the 0.5 to 3 mm (0.020 to 0.12 in) thickness range. The process uses two shaped copper alloy electrodes to concentrate

welding current into a small "spot" and to simultaneously clamp the sheets together. Forcing a large current through the spot will melt the metal and form the weld. The attractive feature of spot welding is that a lot of energy can be delivered to the spot in a very short time (approximately ten milliseconds). That permits the welding to occur without excessive heating to the remainder of the sheet [7]. During spot welding, the large electric current induces a large magnetic field, and the electric current and magnetic field interact with each other to produce a large magnetic force field too, which drives the melted metal to move very fast at a velocity up to 0.5 m/s. As such, the heat energy distribution in spot welding could be dramatically changed by the fast motion of the melted metal [8]. The amount of heat (energy) delivered to the spot is determined by the resistance between the electrodes and the amperage and duration of the current. The amount of energy is chosen to match the sheet's material properties, its thickness, and type of electrodes. Applying too little energy won't melt the metal or will make a poor weld. Applying too much energy will melt too much metal, eject molten material, and make a hole rather than a weld. Another attractive feature of spot welding is the energy delivered to the spot can be controlled to produce reliable welds [9].

4. Industrial robots in welding and assembly

Industrial robots are programmable, multifunction manipulators designed to automate tasks such as welding or the movement of materials through variable programmed motions. There are two popular types of industrial welding robots. The two are articulating robots and rectilinear robots. Robotics controls the movement of a rotating wrist in space. Rectilinear robots move in line in any of three axes (X, Y, & Z). In addition to linear movement of the robot along axes there is a wrist attached to the robot to allow rotational movement. This creates a robotic working zone that is box shaped. Articulating robots employ arms and rotating joints. These robots move like a human arm with a rotating wrist at the end. This creates an irregularly shaped robotic working zone.

There are many factors that need to be considered when setting up a robotic welding facility such as; accuracy and repeatability, number of axes, reliability, fixtures, programming, seam tracking systems, maintenance, controls, weld monitors, welding equipment, positioners, and part

transfer. A robotic welding system may perform more repeatably than a manual welder because of the monotony of the task. However, robots may necessitate regular recalibration or reprogramming. Robots should have the number of axes necessary to permit the proper range of motion and the robot arm should be able to approach the work from multiple angles. The axes of movement that a robot has are referred to as degrees of freedom. Typical vertically articulated robots feature a 6-axis configuration, or six degrees of freedom. Six Industrial Robot Configurations include: Vertically Articulated; Cartesian; SCARA; Cylindrical; Polar; and Delta.

Robotic welding systems are able to operate continuously, provided appropriate maintenance procedures are adhered to. Continuous production line interruptions can be minimized with proper robotic system design and robust maintenance management system in place. Besides quick weld tip change over, planning for the following contingencies needs to be completed; rapid substitution of the inoperable robots, installing backup robots in the production line and redistributing the welding of broken robots to functioning robots close by.

Welding Robots are extensively applied in the automotive assemblies and 'Spot Welding' is the most common welding application found in the auto stamping assembly manufacturing. While it is commonly used in the automotive industry to join sheet metal frames together, the spot welding application has a variety of project uses. Automating spot welding is quick, easy and a great economic solution. Spot welding robots have the ability to overcome difficult welds while providing consistent quality. A spot welding robot is cost effective and various kinds offer floor space savings, which is why so many automotive manufacturing companies have incorporated this kind of robot into their plant. When specifying for heavier loads, consideration should be given to: Number of axis; Payload; H-Reach; Repeatability; and Robot Mass.

Steed (2013) elucidates that a robotic welding cell is devoted to manufacturing products requiring similar operations; these welding cells, a type of cellular manufacturing, represent an alternative structure that reduces manufacturing lead times, improve product cost and quality. Modern welding cells provide a high level of flexibility, allowing for potential engineering and future design changes. They also have reduced manpower requirements. The robotic welding cells have been the bridge needed to achieve the quality, throughput and machine reliability required. Assembly robots have

expanded production capabilities in the manufacturing world. The assembly process is faster, more efficient and precise than ever before. End of arm tooling can be customized for each assembly robot to fit any assembly needs. Robots have saved workers from tedious and dull assembly line jobs, while increasing production and savings in the process [10]. However, the new ultra-high strength steels (UHSS) are presenting the welding engineer with new challenges, i.e. smaller welding windows (less robustness), more complicated fracture mechanisms, potentially weaker welds, different fatigue behavior and more complex quality checking in production. The classic problems at resistance spot welding, such as electrode alignment, the presence of adhesives and sealants as well as various types of zinc coatings have a larger effect on the welding of UHSS compared to conventional mild steels; nevertheless. weld performance can be improved with adaptive controls.

5. Pernicious ramifications of weld slag and spatter

Slag - Minnick (2007) explicates in the welding hand book that slag is the residue left on a weld bead from the flux; flux shields the hot metal from atmospheric contaminants that may weaken the weld joint. Slag can also be globules of molten metal that are expelled from the joint and then resolidify on the metal surface. Slag inclusions are non-metallic solid material entrapped in weld metal or between weld metal and base metal. Slag inclusions are regions within the weld cross section or at the weld surface where the once-molten flux used to protect the molten metal is mechanically trapped within the solidified metal. This solidified slag represents a portion of the weld's cross-section where the metal is not fused to itself. This can result in a weakened condition which could impair the serviceability of the component. Inclusions may also appear at the weld surface. Like incomplete fusion, slag inclusions can occur between the weld and base metal or between individual weld passes. In fact, slag inclusions are often associated with incomplete fusion [11].

Spatter - is essentially little droplets of molten material that are generated at or near the welding arc. Spatter is generally regarded as a nuisance and is a critical factor that needs to be taken into consideration when developing an application. Some of the problems associated with spatter include; spatter balls sticking to work pieces or tooling, spatter burning auxiliary wire and connectors, loss of material from the arc and weld, and excessive clean-up of spatter. Most manufactures strive to reduce the amount of spatter

generated, if not eliminate it all together. Spatter is caused by several factors, the main factor being a disturbance in the molten weld pool during the transfer of wire into the weld. Typically this is caused by the relationship between amperage and voltage. This is usually seen when the welding voltage is too low or the amperage is too high for a given wire and gas combination. In this situation, the arc is too cold to keep the wire and pool molten and causes a stubbing effect of the wire. This can occur at both high and low current ranges. Spatter may be generated as a result of the gas selected [12]

100

Moore (2012) determines that in order to ensure integrity of welds, it is vital to remove weld slag as many products are constructed from a series of stamped and formed panels that are spot-welded together making a unibody frame. An epoxy sealer is applied between the panels before they are spot welded; this sealer is splattered along with welding slag during the welding process. After a period of time, this "spatter" builds up on the robot joints and other ancillary equipment. It can become difficult to perform regular maintenance on the equipment and the range of motion of the robot will be reduced. The production line may need to be shut down to remedy problems caused by this excess accumulation of slag and sealant. As auto frames pass through welding lines they can catch on this slag build-up, robots apply sealant in the wrong locations and weld quality is therefore compromised. During preventative maintenance, skilled electricians and mechanics spend a disproportionate amount of time cleaning troubled areas rather than focusing on items requiring repair/maintenance. E-coat is another problem area whereby epoxy coating builds up and affects the effectiveness of holding clamps and contact shoes. Traditional cleaning methods tend to damage the delicate sensors and electrical devices in the area. Manual scraping and wiping doesn't clean very effectively and it is very time consuming. Though adaptive resistance welding control, aided by signature image processing for weld consistency, automatically compensates to keep production and quality up to the levels needed as gun tips undergo wear; these systems can not compensate for the deterioration in weld quality due to slag and spatter damage to guns and sensors [13]-[14]. Dry ice blasting method, explained in the following paragraph, is highly effective to rid welding guns and fixtures of slag and spatter.

6. Dry-Ice and Dry ice blasting

Dry-Ice is the solid form of Carbon Dioxide (CO₂), which is a colourless, tasteless, odourless gas. With a low temperature of -109 $^{\circ}$ F (-78 $^{\circ}$ C), solid CO₂ (dry ice) has an inherent thermal energy ready to be tapped. At atmospheric pressure, dry ice sublimates

Vol. 5, No. 4, December 2016 Int. J Sup. Chain. Mgt.

directly to vapour without going through a liquid phase. This is a unique property meaning that the blast media simply disappears, leaving only the original contaminant to be disposed of. In addition, blast cleaning in water sensitive areas is now practicable. The grade of CO2 used in dry ice blasting is the same as that used in the food and beverage industry and has been specifically approved by the FDA (Food and Drug Administration), the **EPA** (Environmental Protection Agency) and the USDA (United States Department of Agriculture). CO2 is a nonpoisonous, liquefied gas that is both inexpensive and easily stored at work sites. Of equal importance is its non-conductive and non-flammable nature. CO₂ is a natural by-product of several industrial manufacturing processes such as fermentation and petro-chemical refining. The CO₂ given off by the above production processes is captured and stored without losses until needed. When the CO2 is returned to the atmosphere during the blasting process, no new CO₂ is produced. Instead, only the original CO₂ by-product is released [6].

6.1 How does dry ice blasting work?

The system uses small rice size pellets of dry ice shooting them out of a jet nozzle with compressed air. It works somewhat like sandblasting or highpressure water or steam blasting, with superior results. The frigid temperature of the dry ice -109.3°F or -78.5°C "blasting" against the material to be removed causes it to shrink and lose adhesion from its sub surface. Additionally when some of dry ice penetrates through the material to be removed, it comes in contact with the underlying surface. The warmer sub surface causes the dry ice to convert back into CO₂. The gas, having 800 times greater volume, expands behind the material speeding up its removal. Paint, oil, grease, asphalt, slag, spatter, tar, decals, soot, dirt, ink, resins, and adhesives are some of the materials removed by this procedure. Only the removed material must be disposed of, as the dry ice sublimes into the atmosphere [6]. In dry ice blasting, there are several methods used to manufacture the dry ice blasting media: One technique is to shave dry ice granules from a solid CO2 (dry ice) block at the blasting machine and another is to manufacture hard pellets of dry ice in a pelletizer. The first technique, shaving dry ice granules, generally produces sugar-crystal sized dry ice granules, which must be used quickly due to rapid sublimation; which is due to their high surface area-to-volume ratio.

The other technique is to manufacture hard pellets of dry ice in a pelletizer then immediately blast with the pellets or store the pellets in an insulated container until they are needed. These dry ice pellets are generally on the order of 0.08" to 0.12" (0.2cm to 0.3cm) in diameter, and 0.1" to 0.4" (0.25cm to 1cm) in length.

101

Pelletized dry ice is manufactured by flashing pressurized liquid CO₂ into snow, and then compressing the snow into solid form. The snow is either directly nuggetized into pellets (mechanical compression) or is extruded into solid pellet form through a die under hydraulic pressure. The latter process allows for a more efficient conversion from the liquid phase to the solid phase. Generally, it is desirable to have dry ice pellets that are well compacted to minimize the entrapment of gaseous CO₂ and/or air which may affect product quality. The yield achieved when flashing liquid carbon dioxide into snow increases as the temperature of the liquid CO₂ decreases, so it is important to prechill the incoming liquid CO₂ via heat exchangers with the outgoing CO₂ vapour. Because of the solid CO₂ vaporizing, the dry ice blasting process does not generate any secondary waste. All that remains to be collected is the contaminant that is being removed [5].

6.2 **Blast Machine types**

There are two general classes of dry ice blasting machines as characterized by their method of transporting pellets to the nozzle; the two-hose and the single-hose systems. In either type of system, the proper selection of blast hose is important because of the low temperatures involved and the need to preserve particle integrity as the dry ice particles travel through the hose. In the two-hose system, dry Ice particles are delivered and metered by various mechanical means to the inlet end of a hose and are drawn through the hose to the nozzle by means of vacuum produced by an ejector-type nozzle. Inside the nozzle, a stream of compressed air (supplied by the second hose) is sent through a primary nozzle and expands as a high velocity jet confined inside a mixing tube. When flow areas are properly sized, this type of nozzle produces vacuum on the cavity around the primary jet and can therefore draw particles up through the ice hose and into the mixing tube where they are accelerated as the jet mixes with the entrained air/dry ice particle mixture. Advantages of this type of system

are relative simplicity and lower material cost, along with an overall compact feeder system. One primary disadvantage is that the associated nozzle technology is generally not adaptable to a wide range of conditions (i.e. tight turns in a cavity, thinwide blast swaths, etc.). Also, the aggression level and strip rate of the two-hose system is less than comparable to single-hose blast machines. In a single-hose system, particles are fed into the compressed air line by one of several types of airlock mechanisms. Reciprocating and rotary airlocks are both currently used in the industry. The stream of pellets and compressed air is then fed directly into a single hose followed by a nozzle where both air and pellets accelerate to high velocities. Advantages of this type of system are wide nozzle adaptability and the highest available blast aggression levels. Disadvantages include relatively higher material cost due to the complex airlock mechanism.

Electro-pneumatic machines truly are "Environmentally Friendly" because there is no oily exhaust and these machines are more tolerant of moisture and contaminants in the air supply. The electro-pneumatic machines rarely freeze-up which makes them ideal for automated line applications where around-the-clock dry ice blasting is required. Also, these machines provide pulse free blasting for uniform cleansing and efficient use of the dry ice. There is, however, a slight inconvenience factor associated with supplying both electrical power and compressed air to the machine at each blast location.

7. Benefits of dry ice blasting technology

Cost Reduction - The natural sublimation of dry ice particles eliminates the cost of collecting the cleansing media for disposal. Containment and collection costs associated with water/grit blasting procedures are also eliminated. Because CO_2 / dry ice blasting systems provide on-line maintenance capabilities for production equipment (online cleansing), time consuming and expensive detooling procedures are kept to a minimum. Dedicated cleansing cycles are no longer required as preventive maintenance schedules can be adopted, which allow for equipment cleansing during production periods. As a result, throughput is increased without the addition of labor or production equipment.

Extension of Equipment's Useful Life - Unlike sand, walnut shells, plastic beads and other abrasive grit media, dry ice particles are non-abrasive; cleansing with dry ice will not wear tooling, texture surfaces, open tolerances, or damage bearings or machinery. In addition, on-line cleansing eliminates the danger of molds being damaged during handling from press to cleaning area and back.

102

A Dry Process - Unlike steam or water blasting, CO_2 / dry ice blasting will not damage electrical wiring, controls, or switches. Also, any possible rust formation after cleansing is far less likely with dry ice blasting than with steam or water blasting. Also, when used in the Food Industry, dry ice blasting reduces the potential for bacteria growth inherent to conventional water blasting.

Environmental Safety – CO₂ is a non-toxic element which meets EPA, FDA, and USDA industry guidelines. By replacing toxic chemical processes with CO₂ / dry ice blasting systems, employee exposure and corporate liability stemming from the use of dangerous chemical cleaning agents can be materially reduced or eliminated completely. Since CO₂ gas is heavier than air (CO₂ gas displaces oxygen), care must be taken if blasting in enclosed areas or down in a pit. In addition to being clean and safe, it is also important to remember that dry ice is obtained as a by-product of other industrial processes - i.e. it is made from reclaimed CO2. It does not produce CO2 or add CO2 to the atmosphere and therefore does not contribute to the greenhouse effect.

8. Conclusion

Dry Ice blasting creates a "No Contact Cleansing" opportunity and can remove slag and spatter in a fraction of time without the added costs and inconvenience of secondary waste treatment and disposal. Advantages include; increased line uptime from the ability to spot problems, and if a break down occurs, problems are able to be fixed quickly without having to first clean the troubled area. Robots and jigs are aesthetically better looking; the copper and brass fittings which become all nicked up from chiselling and scraping maintain a like new appearance when cleansed with dry ice jet. It is easy to clean proximity switches and tight hard to reach by hand areas such as guns and arms of the robot. Solvents used for cleaning the sealant are eliminated. In view of the strenuous nature of robotic assembly operations, it is imperative that auto stamping assembly plants incorporate dry ice (CO₂) blasting for their cleansing to ensure equipment reliability

guaranteeing sustainable production. With the environmental issues and legislation becoming more and more stringent, one thing is certain; the successful shops of the future will have fully incorporated the environmentally safe and dry process of dry ice / CO_2 blasting into their operations.

References

- [1] B. Steinke and B. Rickel(2015), *The Lincoln Electric Company*. Third Party Preventive Maintenance A Smart Decision for Efficient Automated Welding Retrieved from: http://www.lincolnelectric.com/enus/support/welding-solutions/Pages/preventive-maintenance-for-automated-welding.aspx
- [2] T. Matsubara, H. Terasaki, H. Otsuka, and Y. Komizo (2010) "Developments of real-time monitoring method of welding" (paper RAJU-VE1), Proceedings of the Visual-JW2010
- [3] Lisa Nocks (2007), The robot: the life story of a technology. Westport, CT: Greenwood Publishing Group.
- [4] H. B. Cary, and S. C. Helzer, (2005). "Modern Welding Technology". Upper Saddle River, New Jersey: Pearson Education. ISBN 0-13-113029-3.
- [5] J. A. Snide, "CO₂ Pellet Cleaning—A Preliminary Evaluation", Materials & Process Associates, Inc., October 12, 1992. Retrieved on 18 June 2013 from: http://old.coldjet.com/tech-fundamentals.html
- [6] K. Ackerman (2013), Dry Ice Blasting Principles. Retrieved on April 5, 2013 from http://www.dryiceinfo.com/cleaning.htm
- [7] Klas Weman (2003), Welding processes handbook. NY: CRC Press LLC. ISBN 0-8493-1773-8.

- [8] YB. Li, ZQ. Lin, SJ. Hu, & GL. Chen, (2007), Numerical Analysis of Magnetic Fluid Dynamics Behaviors During Resistance Spot Welding. J. Appl. Phys., 2007, 101(5), 053506. Retrieved on April 5, 2013 from https://en.wikipedia.org/wiki/Spot_welding
- [9] G. Shannon, (2007), Advances in Resistance Welding Technology Offer Improved Weld Quality and Reliability for Battery Manufacturers. Battery Power Products & Technology, July/August 2007, Vol 11, Issue 4, retrieved from www.batterypoweronline.com.
- [10] L. Steed, 2013, "WHAT YOU MUST KNOW ABOUT ROBOTIC WELDING", Tregaskiss, Windsor, Ontario, Canada NOR 1L0, www.tregaskiss.com. Retrieved on 21 June 2013 from: http://www.fabricatingandmetalworking.com/2013/05/what-you-must-know-about-robotic-welding/
- [11] MDOT, 2012, "Field Manual for Pile Welding 2012", Michigan Department of Transportation, USA
- [12] W. H. Minnick, (2007), "Gas Metal Arc Welding Handbook", Textbook. Tinley Park: Goodheart–Willcox. ISBN 978-1-59070-866-8.
- [13] B. Moore, (2012), Resistance Welding.
 Retrieve on April 6, 2013 from:
 http://www.boschrexroth.com/country_units/a
 merica/united_states/en/Trends_and_Topics/C
 ase_Studies_and_Tech_Papers/a_downloads_t
 ech_papers/Resistance_Welding/Rexroth_Res
 istance_Welding_L.pdf
- [14] SW. Simpson, (2008), "Fault identification in gas metal arc welding with signature images", *Science & Technology of Welding and Joining*, 13(1), 87–96