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M. T. Lam

J. M. Cordes

S. Chatterjee

M.L.Jones

M.A. McLaughlin

See next page for additional authors

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Authors

M. T. Lam, J. M. Cordes, S. Chatterjee, M. L. Jones, M. A. McLaughlin, and J. W. Armstrong



SYSTEMATIC AND STOCHASTIC VARIATIONS IN PULSAR DISPERSION MEASURES

M. T. LAM¹, J. M. CORDES¹, S. CHATTERJEE¹, M. L. JONES², M. A. MCLAUGHLIN², AND J. W. ARMSTRONG³

¹ Department of Astronomy and Cornell Center for Astrophysics and Planetary Science, Cornell University, Ithaca, NY 14853, USA; mlam@astro.cornell.edu ² Department of Physics and Astronomy, West Virginia University, Morgantown, WV 26506, USA

³ Jet Propulsion Laboratory, California Institute of Technology, 4800 Oak Grove Drive, Pasadena, CA 91109, USA

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ABSTRACT

We analyze deterministic and random temporal variations in the dispersion measure (DM) from the full threedimensional velocities of pulsars with respect to the solar system, combined with electron-density variations over a wide range of length scales. Previous treatments have largely ignored pulsars' changing distances while favoring interpretations involving changes in sky position from transverse motion. Linear trends in pulsar DMs observed over 5-10 year timescales may signify sizable DM gradients in the interstellar medium (ISM) sampled by the changing direction of the line of sight to the pulsar. We show that motions parallel to the line of sight can also account for linear trends, for the apparent excess of DM variance over that extrapolated from scintillation measurements, and for the apparent non-Kolmogorov scalings of DM structure functions inferred in some cases. Pulsar motions through atomic gas may produce bow-shock ionized gas that also contributes to DM variations. We discuss the possible causes of periodic or quasi-periodic changes in DM, including seasonal changes in the ionosphere, annual variations of the solar elongation angle, structure in the heliosphere and ISM boundary, and substructure in the ISM. We assess the solar cycle's role on the amplitude of ionospheric and solar wind variations. Interstellar refraction can produce cyclic timing variations from the error in transforming arrival times to the solar system barycenter. We apply our methods to DM time series and DM gradient measurements in the literature and assess their consistency with a Kolmogorov medium. Finally, we discuss the implications of DM modeling in precision pulsar timing experiments.

Key words: ISM: general – pulsars: general

1. INTRODUCTION

Free electrons in the interstellar medium (ISM) affect pulsar signals by introducing a frequency-dependent dispersion delay. Dispersion delays need to be removed as part of search algorithms in pulsar surveys and for precision time-of-arrival (TOA) measurements that are used for determinations of orbital elements, tests of General Relativity and other theories of gravity, and the detection of long-wavelength gravitational waves (GWs). Besides being used for correction, dispersion measures (DMs) are the the primary means of determining electron column densities on Galactic and, in some cases, extragalactic lines of sight (LOSs). They serve as important input data for Galactic models of the electron density and in studies of stochastic variations in electron density on length scales $\sim 1-100$ au. Dispersion and scattering, a related frequency-dependent phenomenon due to multi-path propagation, are assumed to result from cold plasma in the high-frequency limit with negligible contributions from magnetic fields (see Cordes 2002 or Lorimer & Kramer 2012 for a review).

In this paper, we discuss the inferences that can be made about the ISM using epoch-dependent DM measurements. We analyze DMs in terms of the full three-dimensional motions of pulsars, the changes in electron density along the entire LOS, and the solar system motion through the ISM. The DM is the LOS integral

$$DM(t) = \int_0^{D(t)} ds \, n_e(s\hat{n}(t), t),$$
(1)

where D(t) is the pulsar's distance, n_e is the electron density, and $\hat{n}(t)$ is a unit vector from the observer to the pulsar, with all three quantities generally being epoch-dependent. Many pulsars have much higher velocities than bulk ISM motion,

and so variations in DM are usually dominated by the changing LOS, including both the distance and direction. Therefore, we generally drop the explicit time dependence of the electron density, though we will show that this assumption does not hold within the solar system. While epoch-dependent distances are an obvious consequence of high velocities, most quantitative analyses of DMs have focused on how the LOS changes from transverse motions.

We report on measured DM variations in the literature in Section 2. In Section 3, we develop the formalism for DM variations from changing LOS integrals through electron-filled media and we discuss the resulting linear trends in DM time series in Section 4. We consider the DM struture function (SF) and contributions to it from stochastic DM variations in Section 5. In Section 6, we discuss the impact of refraction on timing delays and subsequently the measured DM. We interpret the causes of linear and non-monotonic trends seen in several pulsars in the literature in Section 7 and periodic DM variations in Section 8. In Section 9, we report the impact of DM variations on ISM study and on timing precision. We summarize our findings and conclusions in Section 10. A list of symbols and acronyms used throughout the paper can be found in Table 1.

2. MEASURED DM VARIATIONS

Time variability in DM is a well-known phenomenon in pulsar timing. Epoch-dependent variations were first detected in the Crab Pulsar (Rankin & Roberts 1971). Isaacman & Rankin (1977) measured DM variations in the Crab Pulsar over a five-year span and suggested that the changes in DM come from within the Crab Nebula. Hamilton et al. (1985) found a

 Table 1

 Symbols and Acronyms Used

Symbols	Definition	Characteristic Units
a	Characteristic scale of ISM structure	Length
Α	Spectral coefficient	
с	Speed of light	$\mathrm{cm} \mathrm{s}^{-1}$
C	Arbitrary amplitude	
C_1	Constant in uncertainty rela- tion, $2\pi\Delta\nu_{ISS}\tau_{ISS} = C_1$	
C_n^2	Coefficient in electron-density wavenumber	Length $^{-(\beta+3)}$
D	spectrum Earth-Pulsar distance	kpc
DM	Dispersion Measure	pc cm ^{-3}
$D_{\rm DM}$	DM structure function	$[pc cm^{-3}]^2$
D_t	Time structure function	s ²
D_{ϕ}	Phase structure function	radians ²
Ė	Pulsar energy loss rate	erg s ⁻¹
f	Spectral frequency	$Time^{-1}$
$f_1 f_2$	Lower and upper spectral cutoffs of S_{DM}	Time ⁻¹
f_{β} h	Numerical factor in DM structure function Planck constant	org s
h_s	Height above Earth's surface	erg s km
H	Characteristic thickness of ionospheric layer	km
k	Boltzmann constant	erg K^{-1}
K	Dispersion constant ($\equiv cr_e/2\pi$)	ms
		GHz^2
		$pc^{-1}cm^{-3}$
l	Characteristic scale of ISM structure	Length
l_g, b_g	Galactic coordinates (longitude, latitude)	deg
$l_{\rm HI}$	Mean free path for neutral-hydrogen-ionizing radiation	cm
m_p	Proton mass	g
n_e	Electron density	cm^{-3}
$n_{\rm HI}$	Effective hydrogen density	cm ⁻³
n_p	Proton density	cm^{-3}
N _e N _{H1}	Electron column density	cm^{-2} cm^{-2}
$P_{\delta n_{e}}$	Hydrogen column density Wavenumber spectrum for the electron density	Length ⁻³
e	Wavenumber Wavenumber	Length ⁻¹
q_{1,q_2}	Lower and upper wavenumber cutoffs of $P_{\delta n_{e}}$	Length ⁻¹
r	Position	Length
r _e	Classical electron radius	cm
rs	Bow-shock standoff radius	cm
r_{\oplus}	Earth-Sun distance	au
$R_{d\mathrm{DM}/dt}$	ratio of linear trend to rms linear trend from a Kolmogorov medium	
<i>R</i> _{rms}	ratio of rms DM after and before a linear trend is removed	
s	Represents a generic position along the LOS	Length
S	Power spectrum	$1 \dots \dots$
SM	Scattering Measure	kpc m ^{$-(\beta+3)$}
t T	Time Total observing span	Time Time
r v	Velocity	$km s^{-1}$
x	Position	Length
z	Represents a position along the LOS	Length
â	Arbitrary spectral index	e
α_e, δ_e	Equatorial coordinates (RA, declination)	deg
β	Exponent in wavenumber spectrum for n_e	
Γ	Gamma function	
γ	Exponent in power law of red noise process	
Δ	Difference/Increment	
$\Delta \nu_{\rm ISS}$	Scintillation bandwidth	MHz
Δt $\Delta t_{\rm rec}$	Time delay Scintillation timescale	Time
$\Delta t_{\rm ISS}$	Somunation unescale	S

Table 1 (Continued)

Symbols	Definition	Characteristic Units
η_s	Shock compression factor	
θ_i	Incidence angle	rad
θ_r	Refraction angle	rad
θ_z	Zenith angle	deg
λ, ν	Electromagnetic wavelength and frequency	cm, GHz
λ_e, β_e	Ecliptic coordinates (longitude, latitude)	deg
λ_h, β_h	Heliographic coordinates (longitude, latitude)	deg
ρ	Mass density	g cm ⁻³
σ	rms	
$\sigma_{\rm HI}$	Photoionoization cross section for neutral hydrogen	cm^{-2}
τ	Time lag	Time
$\tau_{\rm ISS}$	Scattering timescale	$\mu { m s}$
ϕ	Phase perturbation from refractive index perturbations	rad
ϕ_g, λ_g	Geographic coordinates (latitude, longitude)	deg
ϕ	Sinusoidal phase	rad
ώ	Sinusoidal angular frequency	Angle/Time

large gradient in the DM of the Vela Pulsar over 15 years and attributed it to the LOS changing with the transverse velocity of the pulsar relative to the supernova remnant. Spatial variations in DM on sub-parsec scales have also been seen (see Manchester et al. 1991 and Freire et al. 2001, who discuss changes in DM over different LOSs to pulsars in the center of the globular cluster 47 Tucanae).

Published time series of DM in the literature show several types of behavior. Some show deterministic linear trends superposed with correlated, stochastic variations. A few show piecewise linear variations that signify change points in the time derivative dDM/dt associated with structure in the ISM on scales of 1–100 au. Many also show periodic variations, either smoothly sinusoidal or sharp with distinct features, often with a period of roughly one year. The amplitudes of these variations have also been seen to change with time. In some cases, both linear and periodic variations are seen. Others show only correlated, stochastic variations without an obvious trend.

Phillips & Wolszczan (1991) reported results on five pulsars, four of which show long-term trends with slopes $|dDM/dt| \sim 10^{-3} \text{ pc cm}^{-3} \text{ yr}^{-1}$ (increasing: PSRs B0823 +26, B0834+06, and B1237+25; decreasing: PSR B0919 +06). They assert that the rms of the DM variations is correlated with the average DM but with significant scatter about a best-fit relation $\sigma_{DM} \propto DM^{1.3\pm0.3}$. A trend of this type would generally signify that the DM variations are associated with accumulated effects along the LOS, but the correlation is affected by long-term trends that may be due to parallel motion through ionized gas near the pulsars.

Keith et al. (2013, see also You et al. 2007; Petroff et al. 2013) give DM(t) time series over roughly ~6 yr for 20 millisecond pulsars (MSPs) that were monitored in the Parkes Pulsar Timing Array (PPTA) program. Of these, 11 show prevailing trends of increasing DM (PSRs J1024–0719, J1730–2304, J1732–5049, and J1857+0943) or decreasing DM (PSRs J1045–4509, J1600–3053, J1643–1224, J1744–1134, J1909–3744, J1939+2134, and J2129–5721). Two others show overall trends but with a localized DM "event" that

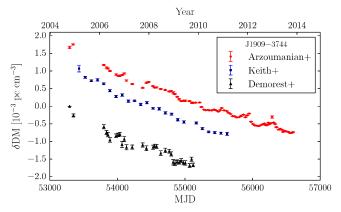


Figure 1. DM offsets $\delta DM(t) = DM(t) - DM_{nominal}$ for PSR J1909–3744, reported in Arzoumanian et al. (2015b, red circles), Keith et al. (2013, blue squares), and Demorest et al. (2013, black triangles). $DM_{nominal} = 10.394680, 10.392717, 10.392031 \text{ pc m}^{-3}$, respectively. The nominal DM differs due to different methods to account for frequency-dependent pulse shape changes in the timing models.

breaks the trend (PSRs J1603–7202 and J1824–2452). The remaining seven objects show non-monotonic variations with various degrees and timescales of temporal correlation. Reardon et al. (2016) find evidence for significant linear trends in 13 pulsars and sinusoidal, annual variations in four pulsars in the extended PPTA data release 1. The approximate derivative for PSR J1939+2134 (B1937+21) is about half the value of the 20 year trend reported by Ramachandran et al. (2006) and is consistent with changes in slope seen in the 20 year time series.

Demorest et al. (2013) present DM(t) time series for 14 out of 17 pulsars that were part of the first data release of the North American Nanohertz Observatory for GWs (NANOGrav), based on five years of data. Of these, the seven objects that overlap with the Keith et al. (2013) sample show consistent trends. Of the others, several objects show very weak DM variation while two pulsars, PSRs B1855+09 and J2317 +1439, show strong trends superposed with correlated, stochastic variations.

PSR J1909–3744 exemplifies several types of variations in DM that motivate our study. Demorest et al. (2013) see a monotonic decrease in DM over 5 years. Keith et al. (2013) also note the linearity of DM(t), with a change in $1.85 \times 10^{-3} \,\mathrm{pc} \,\mathrm{cm}^{-3}$ over 6 years, and find that the SF of their time series exceeds, for every lag, the SF prediction from dynamic spectrum estimates by a factor of ~ 5 . They suggest that the SF excess implies an electron-density wavenumber spectrum steeper than that of a turbulent, Kolmogorov medium. Recently, the NANOGrav Nine-Year Data Release (Arzoumanian et al. 2015b; hereafter NG9) showed that the decreasing trend continued, spanning all nine years of data, along with a superposed annual variation. Figure 1 shows the DM offsets $\delta DM(t) = DM(t) - DM_{nominal}$ as presented by the three data sets, where $DM_{nominal} = 10.394680 \text{ pc cm}^{-3}$ for Demorest et al. (2013), 10.392717 pc cm⁻³ for Keith et al. (2013), and 10.392031 pc cm⁻³ for NG9. Differences in the absolute DM are caused by different methods of frequency-dependent pulse shape variation removal from the TOAs. An in-depth analysis of the DM variations of all of the MSPs in NG9 will be presented in the future (M. L. Jones et al. 2016, in preparation).

Fonseca et al. (2014) present DM(*t*) for the relativistic binary PSR B1534+12 and fit for derivatives dDM/dt in five separate time blocks. The overall trend is a decrease with time

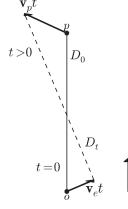


Figure 2. Geometry showing the change in LOS due to motion of the pulsar p and observer o. DM is calculated by integrating along the z-axis taking into account the change in LOS.

that is interrupted by episodic flattenings or increases in DM. The variation of DM(t) from 1990 to 2012 is dominated by five piecewise linear segments lasting three to five years with slopes $dDM/dt = \{-3.16, -0.43, -2.94, 10.1, -0.1\}$ $\times 10^{-4}$ pc cm⁻³ yr⁻¹. The DM SF scales as $\tau^{3.70\pm0.04}$ for lags between 70 and 90 days, consistent with a Kolmogorov scaling. The best-fit SF implies a diffractive scintillation timescale of $\Delta t_{\rm ISS} = 3.0 \pm 0.8$ minutes at 0.43 GHz, which is considerably smaller than the range of 11 ± 3 minutes directly measured by Bogdanov et al. (2002) from twodimensional (2D) autocorrelation functions of dynamic spectra. While epoch-dependent scintillation may play a role in this difference, the shorter timescale inferred from the SF fit is consistent with the presence of contamination from non-Kolmogorov fluctuations on length scales relevant to the DM variations.

3. LINE OF SIGHT INTEGRALS

In the following, we will develop the mathematical framework for variations in DM that we will use in following sections. Consider changes in DM that result from the relative motion of the pulsar and observer, which changes both the distance to the pulsar and the direction of the LOS, as shown in Figure 2. For an initial pulsar position \mathbf{x}_{p_0} and Earth position \mathbf{x}_{e0} , the initial distance $D_0 = |\mathbf{x}_{p_0} - \mathbf{x}_{e0}|$ increases (to first order in time) as

$$D(t) \approx D_0 + (\mathbf{v}_p - \mathbf{v}_e) \cdot \hat{\mathbf{n}}_0 \ t \equiv D_0 + \Delta v_{\parallel} t, \tag{2}$$

where v_p and v_e are the pulsar and Earth velocity vectors, respectively, $\hat{n}_0 = \Delta x_0/D_0 = (x_{p_0} - x_{e0})/D_0$ is the unit vector to the pulsar at t = 0, and Δv_{\parallel} is the apparent velocity of the pulsar parallel to the LOS. The next, quadratic term, $(\Delta v_{\perp} t)^2/2D_0$, where Δv_{\perp} is the apparent velocity of the pulsar perpendicular to the LOS, is a factor of $\Delta v_{\perp} t/D_0 \sim 10^{-6}$ times smaller than the linear term for typical parameters of $\Delta v \sim$ 100 km s⁻¹ (Faucher-Giguère & Kaspi 2006), timespan $T \sim 10$ years, and $D \sim 1$ kpc (Cordes & Lazio 2002), and therefore can be ignored when calculating the distance. Conversely, the change in direction is determined by the transverse velocity

$$\hat{\boldsymbol{n}}(t) = \hat{\boldsymbol{n}}_0 + D_0^{-1} \Delta \boldsymbol{v}_{\perp} t.$$
(3)

Let the initial LOS at t = 0 be the *z*-axis and integrate over the locations $x_0(z) = z\hat{z}$ to get the initial DM,

$$DM_0 = \int_{z_{e_0}}^{z_{p_0}} dz \ n_e(\mathbf{x}_0(z)). \tag{4}$$

For t > 0 we integrate over a new interval $[z_e, z_p]$, where

$$z_e = z_{e_0} + v_{e_{\parallel}}t, \quad z_p = z_{p_0} + v_{p_{\parallel}}t.$$
 (5)

The sampled locations are now $\mathbf{x}(z, t) = \mathbf{r}(z, t) + z\hat{z}$, where $\mathbf{r}(z, t)$ is transverse to \hat{z} ,

$$\boldsymbol{r}(z,t) = \boldsymbol{v}_{\mathrm{eff}_{\perp}}(z)t \tag{6}$$

$$\boldsymbol{\nu}_{\mathrm{eff}_{\perp}}(z) = \boldsymbol{\nu}_{e_{\perp}} + (\boldsymbol{\nu}_{p_{\perp}} - \boldsymbol{\nu}_{e_{\perp}}) \left(\frac{z - z_e}{z_p - z_e} \right).$$
(7)

The locations z_e and z_p are evaluated at time *t* and it is assumed that there is no significant acceleration correction over the times of interest (weeks to decades). The effective transverse velocity, $v_{eff_{\perp}}$, is a weighted sum of the velocities of the pulsar and Earth. This is consistent with that given in Equation (3) of Cordes & Rickett (1998), which also includes a term $-V_m$ for the velocity of the medium, and also with Equation C15 of Gupta et al. (1994).

The simplest approach is to evaluate the electron density for the t > 0 LOS in terms of its values for the initial LOS:

$$n_{e}(\mathbf{x}(z,t)) = n_{e}(\mathbf{x}_{0}(z)) + [n_{e}(\mathbf{x}(z,t)) - n_{e}(\mathbf{x}_{0}(z))]$$

$$\equiv n_{e}(\mathbf{x}_{0}(z)) + \Delta n_{e}(\mathbf{x}(z,t)).$$
(8)

The DM integral over $[z_e, z_p]$ can be expanded into integrals over the three intervals $[z_{e_0}, z_p]$, $[z_{e_0}, z_e]$, and $[z_{p_0}, z_p]$ to get

$$DM(t) = \int_{z_e}^{z_p} dz \, n_e(\mathbf{x}(z, t)) = \int_{z_{e_0}}^{z_{p_0}} dz \, n_e(\mathbf{x}(z, t)) \\ + \int_{z_{p_0}}^{z_p} dz \, n_e(\mathbf{x}(z, t)) - \int_{z_{e_0}}^{z_e} dz \, n_e(\mathbf{x}(z, t)).$$
(9)

For the first integral, we expand the integrand using Equation (8) to get

$$\int_{z_{e_0}}^{z_{p_0}} dz \ n_e(\mathbf{x}(z,t)) = \mathrm{DM}_0 + \int_{z_{e_0}}^{z_{p_0}} dz \ \Delta n_e(\mathbf{x}(z,t)).$$
(10)

This gives

$$DM(t) = DM_0 + \int_{z_{e_0}}^{z_{p_0}} dz \ \Delta n_e(\mathbf{x}(z, t)) + \int_{z_{p_0}}^{z_p} dz \ n_e(\mathbf{x}(z, t)) - \int_{z_{e_0}}^{z_e} dz \ n_e(\mathbf{x}(z, t)).$$
(11)

 DM_0 is the DM measured at time t = 0, the first integral is the change in DM over the initial LOS (density fluctuation term), the second integral is the change in DM due to the pulsar's motion through its local environment (pulsar term), and the third integral is the change in DM due to the Earth/solar system motion through its local environment (Earth term).

The integrand $\Delta n_e(\mathbf{x}(z, t))$ of the density fluctuation term needs to be considered only if electron-density variations are significant on length scales of the order of the offset between

the LOS at t and the initial LOS at t = 0, i.e., $|\Delta \mathbf{x}(z, t)| = |\mathbf{x}(z, t) - \mathbf{x}_0(z)| \ll D_0$. For example, this offset $\ell \sim 20$ au $v_{\text{eff}_{\perp 100}} t_{\text{yr}}$ for a fiducial velocity of 100 km s⁻¹ and a year-long timespan. All of the evidence from the last few decades of interstellar scintillation studies are consistent with there being variations on these (multiples of au) and smaller scales (Coles et al. 1987; Armstrong et al. 1995; Rickett et al. 2000). However, the detailed spectrum of variations on au scales is not well known and appears to differ between the LOSs to different pulsars (Stinebring et al. 2000).

The pulsar and Earth terms in Equation (11) are over small intervals, $z_p - z_{p_0} = v_{p_{\parallel}}t$ and $z_e - z_{e_0} = v_{e_{\parallel}}t$, so to first order in these intervals, the two terms give $\bar{n}_e(\bar{\mathbf{x}}_p)v_{p_{\parallel}}t$ and $\bar{n}_e(\bar{\mathbf{x}}_e)v_{e_{\parallel}}t$, where $\bar{n}_e(\bar{\mathbf{x}}_p)$ and $\bar{n}_e(\bar{\mathbf{x}}_e)$ are the averages over the respective intervals centered on $\bar{\mathbf{x}}_p = \mathbf{x}_{p_0} + (v_{p_{\parallel}}t/2)\hat{\mathbf{n}}(t)$ and $\bar{\mathbf{x}}_e = \mathbf{x}_{e_0} + (v_{e_{\parallel}}t/2)\hat{\mathbf{n}}(t)$, respectively. Unless there are large variations over the intervals, these average locations can be taken as the initial ones at t = 0. The DM variations from these two terms are a simple consequence of the change in pulsar distance due to parallel motion because, as noted earlier, the transverse velocities enter only to second order and therefore are negligible in these terms.

We assume that true *temporal* changes in electron density are negligible. This is often a good assumption because turbulent ISM velocities (of the order of a few km s⁻¹) are typically much smaller than pulsar velocities (Faucher-Giguère & Kaspi 2006; Frisch et al. 2011). For slow pulsars and fast plasma screens (e.g., shock fronts), the ISM velocity needs to be included and adds a term $-v_m(z)$ (with *m* for medium) to the effective velocity defined in Equation (7). For a purely turbulent medium, the velocity is stochastic and would depend on wavenumber. However, a moving screen is easily described by a translational velocity.

4. LINEAR TRENDS IN DM

For a perfectly uniform medium with density n_e , the difference $\Delta n_e(\mathbf{x}(z, t))$ vanishes and the total DM (found by combining Equations (5) and (11)) is

$$DM(t) = DM_0 + n_e (v_{p_{\parallel}} - v_{e_{\parallel}})t, \qquad (12)$$

giving a time derivative of

$$\frac{d\mathrm{DM}}{dt} = n_e (v_{p_{\parallel}} - v_{e_{\parallel}}) \approx 10^{-5} v_{100} n_{e_{0.1}} \,\mathrm{pc} \,\mathrm{cm}^{-3} \,\mathrm{yr}^{-1}, \quad (13)$$

where the approximate estimate uses a fiducial relative velocity of 100 km s⁻¹ and an electron density of 0.1 cm⁻³ (Frisch et al. 2011). Observed DM derivatives range from approximately the nominal value in Equation (13) up to values as large as 0.01 pc cm⁻³ yr⁻¹, indicating that if the changing distance is the primary contribution to the observed trend, then the product $v_{100}n_{e_{0.1}}$ is as large as 1000.

A slightly different form results for a medium with changes in density only on large length scales $\gg |v_{p_{\parallel}} - v_{e_{\parallel}}|t$,

$$\frac{d\mathrm{DM}}{dt} = n_e(\boldsymbol{x}_{p_0})v_{p_{\parallel}} - n_e(\boldsymbol{x}_{e_0})v_{e_{\parallel}}, \qquad (14)$$

which indicates that changes in DM are affected by the local electron density on both ends of the LOS. For similar electron densities at the two locations, we expect the pulsar term to dominate because pulsar velocities are typically much larger than the Earth's orbital motion and the Sun's peculiar motion through the Local Interstellar Cloud (LIC), with the latter being about 28 km s⁻¹ (Faucher-Giguère & Kaspi 2006; Frisch et al. 2011). There will be exceptions, of course, for pulsars with low velocities or with small parallel velocity components.

The LIC is about 2.5 pc across and has an internal gas density of $\approx 0.1-0.2$ cm⁻³ at a temperature of 7000 K (Frisch et al. 2011). Assuming a completely ionized, uniform medium, the total DM through the cloud is at most $DM_{LIC} \approx 0.5$ pc cm⁻³, and the maximum derivative is

$$\frac{d DM_{LIC}}{dt} \approx 5.7 \times 10^{-6} \,\mathrm{pc} \,\mathrm{cm}^{-3} \,\mathrm{yr}^{-1}.$$
 (15)

The Earth's orbital motion is not relevant for the calculation of DM variations due to parallel motions because Earth resides inside the heliosphere. A simplified form of Equation (11) is therefore

$$DM(t) = DM_0 + [n_e(\mathbf{x}_{p_0})v_{p_{\parallel}} - n_e(\mathbf{x}_{e_0})v_{e_{\parallel}}]t + \int_{z_{e_0}}^{z_{p_0}} dz \,\Delta n_e(\mathbf{x}(z,t)).$$
(16)

However, Earth's motion will matter when we later consider the interplanetary medium. In addition, the Earth term raises the interesting possibility that DM variations are partially correlated between different LOSs with an angular dependence that depends on the local ISM and on the direction of the Sun's peculiar velocity.

While linear trends in DM(t) have been recognized for many years, it is not a priori obvious whether they should be associated with the explicitly linear term or with the density fluctuation term, which may quantify gradients transverse to the LOS. Some pulsars will show DM(t) variations where parallel motion is more important than transverse motion, and vice versa. The two kinds of variations may be distinguishable. If gradients and transverse motion are dominant, then there should also be epoch-dependent refraction and flux-density variations on the same timescales. However, parallel-motion effects need not be accompanied by strong modulations of scintillation parameters and flux densities because the structure of the ISM along the LOS will remain the same. We note that DM(t) will vary with time from parallel motion alone regardless of whether or not the ISM is uniform; no gradients in electron density n_e are needed. The variations will be monotonically increasing or decreasing with time if there is no transverse motion (of the pulsar, solar system, or medium). However, DM variations from transverse motion alone require gradients in n_e that have components transverse to the LOS, i.e., $\nabla n_e \cdot \mathbf{r}(z, t) \neq 0$. Any gradients in n_e will generally be manifested from both parallel and transverse motion. DM variations from parallel motion do not depend on the pulsar distance, but the transverse change in LOS does depend on the location along the LOS, therefore influencing the observable effect from a transverse gradient. When the Earth's orbital velocity is important, such as for an MSP with low translational velocity, the contribution to DM(t) depends on $\nabla n_e \cdot v_{eff_1}(z, t)$ and therefore will show a sinusoidal variation.

5. STOCHASTIC VARIATIONS IN DM

Electron-density variations in the ISM can cause fluctuations in DM(t) that combine with the DM variations previously discussed. Many DM(t) time series have been shown to be consistent with purely stochastic variations in electron density; a list of references for epoch-dependent DM variations can be found in Lam et al. (2015). Following their treatment, we can describe the stochastic variations by a power-law wavenumber spectrum:

$$P_{\delta n_e}(\boldsymbol{q}) = C_n^2 q^{-\beta}, \qquad q_1 \leqslant q \leqslant q_2, \tag{17}$$

where the wavenumber cutoffs, related to the inner and outer physical scales ℓ_2 and ℓ_1 , respectively, are $q_1 = 2\pi/\ell_1$ and $q_2 = 2\pi/\ell_2$, and C_n^2 is the spectral coefficient. Equation (17) assumes that the scattering irregularities are isotropic and the spectrum depends only on the magnitude of the wavenumber. Evidence for anisotropic scattering exists along certain LOSs (e.g., Brisken et al. 2010) but the analysis is accordingly more tedious. The rms electron density is dominated by the largest scales ($\sim 1 - 100$ pc, except in dense, compact regions) for $\beta > 3$ and $q_1 \ll q_2$. For a Kolmogorov medium, $\beta = 11/3$ (Rickett 1990).

One useful statistic for quantifying DM variations is the DM structure function (SF),

$$D_{\rm DM}(\tau) \equiv \langle [\mathbf{DM}(t+\tau) - \mathbf{DM}(t)]^2 \rangle$$
$$= \langle |\Delta^{(1)}\mathbf{DM}(t,\tau)|^2 \rangle, \tag{18}$$

where $\Delta^{(1)}$ DM (t, τ) is the first-order DM increment, because it removes any constant term and is closely related to the spectral index of the wavenumber spectrum when β is in the scintillation regime (for wavenumbers $q_1 \ll q \ll q_2$ and $2 < \beta < 4$; Lam et al. 2015). We can relate it to similar SFs found in the literature for the electromagnetic phase perturbation imposed by the interstellar plasma ϕ and for the resulting dispersive time delay, t. These are, respectively, $\phi = -cr_e \nu^{-1}$ DM, where r_e is the classical electron radius, and $t = d\phi/2\pi d\nu = K\nu^{-2}$ DM with $K \equiv cr_e/2\pi$. We thus have

$$D_t(\tau) = K^2 \nu^{-4} D_{\rm DM}(\tau) = (2\pi\nu)^{-2} D_\phi(\tau).$$
(19)

The DM SF includes the effects of the systematic DM term due to the change in distance as well as the term involving the integrated difference $\Delta n_e(\mathbf{x}(t))$. Small-scale, discrete structures on au scales can contribute to $\Delta n_e(\mathbf{x}(t))$ along with stochastic variations.

Together, discrete structures and the changing distance will produce contributions to the SF that are *quadratic* in τ and will contaminate the SF of the stochastic variations. A general feature of SFs is that they are quadratic when the lag τ is smaller than any characteristic timescale in the time series. So for structures in the ISM with scale sizes ℓ of tens of au that have characteristic crossing times of $\ell/v_{eff} \sim$ many years, quadratic SFs will be seen for lags of a few years or less. For the case where only the distance-change term is relevant, $DM(t + \tau) - DM(t) \propto \tau$, it is easy to show that the SF is

$$D_{\rm DM}(\tau) = [n_e(\mathbf{x}_{p_0})v_{p_{\parallel}} - n_e(\mathbf{x}_{e_0})v_{e_{\parallel}}]^2 \tau^2.$$
(20)

More generally, if DM variations are dominated by a linear gradient dDM/dt, then the SF is

$$D_{\rm DM}^{\rm (lin)}(\tau) = \left[\frac{d\rm DM}{dt}\right]^2 \tau^2.$$
 (21)

The SF of purely periodic variations in DM of the form $DM(t) = C \cos(\omega t + \varphi)$ can easily be calculated as

$$D_{\rm DM}^{\rm (per)}(\tau) = C^2 [1 - \cos(\omega \tau)].$$
 (22)

While the DM SF is typically calculated with time lags of days to years, it can be related to the implied phase SF on the diffractive interstellar scintillation (DISS) timescale of minutes to hours. To do so, we use Equation (19) along with the fact that the scintillation timescale $\Delta t_{\rm ISS}$ corresponds to $D_{\phi}(\Delta t_{\rm ISS}) \equiv 1 \text{ rad}^2$. The corresponding DM SF value (using $\lambda = c/\nu$) is

$$D_{\rm DM}(\Delta t_{\rm ISS}) = (\nu/2\pi K)^2 D_{\phi}(\Delta t_{\rm ISS}) = (\lambda r_e)^{-2}$$

= 1.47 × 10⁻¹⁵ $\nu_{\rm GHz}^2$ (pc cm⁻³)², (23)

Similarly,

$$D_t(\Delta t_{\rm ISS}) = (2\pi\nu)^{-2} = 0.0253\nu_{\rm GHz}^{-2} \,{\rm ns}^2.$$
 (24)

The SF can be extrapolated to larger time lags, and for the stochastic, Kolmogorov medium where $\beta = 11/3$,

$$D_{\rm DM}^{\rm (sto)}(\tau) = (\lambda r_e)^{-2} (\tau / \Delta t_{\rm ISS})^{5/3}$$
 (25)

$$D_t^{(\text{sto})}(\tau) = (2\pi\nu)^{-2} (\tau/\Delta t_{\text{ISS}})^{5/3}.$$
 (26)

In general, the total DM SF can be written as the sum of the contributions from the systematic term and from the extrapolated stochastic term:

$$D_{\rm DM}^{\rm (tot)}(\tau) = D_{\rm DM}^{\rm (sys)}(\tau) + D_{\rm DM}^{\rm (sto)}(\tau).$$
(27)

However, the systematic term cannot be separated as it will contain cross-terms if two or more components (e.g., linear plus periodic) are added together. For cases where the systematic term is significant, the time series for DM could be de-trended before calculating the SF, though de-trending can remove variance due to the electron-density wavenumber spectrum. Similar to other discussions in the literature, when a power-law wavenumber spectrum dominates electron-density variations, the SF is essentially the SF of the density fluctuation term given in Equation (11).

We can relate the DM SF from the random component to the rms of the DM variations. For a power-law wavenumber spectrum, the DM SF is

$$D_{\rm DM}(\tau) = f_{\beta} \int_{z_{e_0}}^{z_{p_0}} dz \ C_n^2(z) [v_{\rm eff_{\perp}}(z)\tau]^{\beta-2}, \qquad (28)$$

where (Cordes & Rickett 1998, Equation (B6))

$$f_{\beta} = \frac{8\pi^2}{(\beta - 2)2^{\beta - 2}} \frac{\Gamma(2 - \beta/2)}{\Gamma(\beta/2)}.$$
 (29)

The numerical factor is $f_{11/3} = 88.3$ for a Kolmogorov wavenumber spectrum. Using the effective velocity of Equation (7) evaluated for the case where it is dominated by the pulsar velocity, and assuming that C_n^2 is constant along the LOS, the DM SF yields an rms DM on a timescale τ for a Kolmogorov medium,

$$\sigma_{\rm DM}(\tau) = \left[\frac{1}{2}D_{\rm DM}(\tau)\right]^{1/2} = \left(\frac{\sqrt{3}f_{11/3}}{4}\right) SM^{1/2} (\mathbf{v}_{p_{\perp}}\tau)^{5/6}$$
$$= 1.9 \times 10^{-4} \text{ pc cm}^{-3}$$
$$\times \left(\frac{SM}{10^{-4} \text{ kpc m}^{-20/3}}\right)^{1/2} (\mathbf{v}_{p_{\perp}100}\tau_{\rm yr})^{5/6},$$
(30)

where the scattering measure (SM) is the LOS integral (Cordes & Lazio 1991):

$$SM = \int_0^D ds \ C_n^2(s). \tag{31}$$

When the effective velocity is instead dominated by the Earth's velocity, as can be the case for some slow-moving MSPs, the same expression applies but with $v_{p_{\perp}}$ replaced by $v_{e_{\perp}}$. If both velocities are important, then the integral in Equation (28) needs to be evaluated explicitly.

Following Equation (30), an estimate of the rms DM gradient is

$$\sigma_{\rm dDM/dt} \approx \frac{\sigma_{\rm DM}(\tau)}{\tau} = 1.9 \times 10^{-4} \,\mathrm{pc} \,\mathrm{cm}^{-3} \,\mathrm{yr}^{-1} \\ \times \left(\frac{\mathrm{SM}}{10^{-4} \,\mathrm{kpc} \,\mathrm{m}^{-20/3}}\right)^{1/2} \nu_{p_{\perp}100}^{5/6} \tau_{\rm yr}^{-1/6}.$$
(32)

The rms can be evaluated by using scintillation measurements to evaluate the SM (Cordes & Lazio 1991) and by using proper-motion measurements with distance estimates (from parallaxes or from DM and a Galactic electron-density model) to estimate the pulsar velocity.

One approach for comparing the measured DM gradients with those expected from a Kolmogorov medium with no change in distance is to calculate the signal-to-noise-like ratio

$$R_{dDM/dt} = \frac{|dDM/dt|}{\sigma_{dDM/dt}}.$$
(33)

When the gradient exceeds the prediction for a Kolmogorov model by a large factor, one of two interpretations may apply. First, the medium may not have a Kolmogorov spectrum that encompasses both the small length scales that cause scintillation and the large 1–100 au scales associated with DM variations. Alternately, the excess derivative amplitudes can be caused by the changing pulsar distance as described above. Identifying which of these interpretations apply requires consideration of other factors. Transverse motions of the pulsar that cause the LOS to sample different irregularities will yield DM derivatives that are correlated with the absolute DM value, whereas parallel motions that change the distance will not.

Another approach compares the rms of the DM time series before and after the removal of a linear trend. Letting $\sigma_{\text{tot}}^2 = \sigma_{\text{sto}}^2 + \sigma_{\text{lin}}^2$ be the total variance of the time series, we can define the ratio of rms after the removal of a linear trend to

the rms before the removal as

$$R_{\rm rms} = \frac{(\sigma_{\rm tot}^2 - \hat{\sigma}_{\rm lin}^2)^{1/2}}{\sigma_{\rm tot}},\tag{34}$$

where $\hat{\sigma}_{lin}^2$ is the estimated variance of the linear trend. This definition restricts $0 \leq R_{rms} \leq 1$. Realizations of DM time series will appear more linear when the wavenumber spectral index β is large and the removal of the best-fit line for the time series will absorb low-frequency power from the frequency spectrum of the DM. Conversely, when β is low, the time series will appear closer to a white noise process, and the removal of a best-fit line will not change the resultant time series greatly.

We can solve for how σ_{sto} and σ_{lin} scale with observing timespan *T*. Let the stochastic DM variation be a power spectrum $S_{\text{DM}}(f) = Af^{-\gamma}$, where *A* is a spectral coefficient related to Δt_{ISS} and $\gamma = \beta - 1$ (see Appendix A for more details). The variance is then

$$\sigma_{\rm sto}^2 = \int_{f_1}^{f_2} S_{\rm DM}(f) df = \int_{f_1}^{f_2} A f^{-\gamma} df, \qquad (35)$$

where f_1 and f_2 are the low- and high-frequency cutoffs, respectively, related to the wavenumber cutoffs q_1 and q_2 . In the scintillation regime with $1 < \gamma < 3$, assuming $f_1 \ll 1/T \ll f_2$, the integral can be approximated as

$$\sigma_{\rm sto}^2 \approx \frac{A}{\gamma - 1} T^{\gamma - 1},\tag{36}$$

which for the Kolmogorov case implies $\sigma_{\text{sto}} \propto T^{5/6}$. The variance from a deterministic, linear trend is

$$\sigma_{\rm lin}^2 = \frac{1}{T} \int_{-T/2}^{T/2} \left(\frac{d\rm DM}{dt}t\right)^2 dt$$
$$= \frac{1}{12} \left(\frac{d\rm DM}{dt}\right)^2 T^2. \tag{37}$$

Therefore $\sigma_{\text{lin}} \propto T$, and if a deterministic, linear trend is present, then σ_{lin} will increase over σ_{sto} and R_{rms} will increase for longer observing timespans.

In addition to single, linear trends in DM, we can test for discrete changes in underlying linear trends in DM, such as from an ionizing bow shock (see Section 7.2.1), versus stochastic changes from the turbulent medium by calculating second-order the increments of DM(t). $\Delta^{(2)} DM(t, \tau) = DM(t - \tau) - 2DM(t) + DM(t + \tau),$ which remove linear components and relate to the curvature of the time series. The increments at a given τ will have a Gaussian distribution and deviations from this distribution will be indicative of structure other than from a turbulent medium. We can determine the variance in the distribution of increments at a given τ , $\sigma^2_{\Delta^{(2)}DM}(\tau)$, from the second-order DM SF, which can be written as

$$D_{\rm DM}^{(2)}(\tau) = \langle |\Delta^{(2)} \mathrm{DM}(t,\tau)|^2 \rangle.$$
(38)

For a Kolmogorov wavenumber spectrum, the second-order SF is related to the first-order SF, as well as the variance in the second-order increments, by

$$D_{\rm DM}^{(2)}(\tau) = \sigma_{\Delta^{(2)}\rm DM}^2(\tau) \approx 0.8252 D_{\rm DM}^{(1)}(\tau).$$
(39)

The derivation is provided in Appendix A. We can use Equations (25) and (39) to analytically estimate the rms of the

second-order DM increments given Δt_{ISS} , which we use to analyze the slope changes in DM(*t*) for PSR B1534+12 in Section 7.

6. REFRACTION EFFECTS AND TIMING

Refraction of a radio point source by a high-density region in the ISM has been known to cause irregularities in electrondensity time series. See Clegg et al. (1998) and references therein for the case of a Gaussian plasma lens, to be considered shortly, and Coles et al. (2015) for recent evidence of scattering events in pulsar timing data. One of the timing delays associated with refraction scale as ν^{-2} and is therefore degenerate with the dispersion delay, causing changes in the estimated DM. Consider a single ionized cloud that has characteristic scales a_{\parallel} parallel and a_{\perp} transverse to the LOS and with a column density of $DM_c = N_{e_c} \sim n_{e_c} a_{\parallel}$ through the cloud along the LOS. The maximum phase change due to the clump is $|\phi_c| \sim \lambda r_e N_{e_c}$ and the dispersion delay is

$$\Delta t_{\rm DM_c} = \frac{\phi_c}{2\pi\nu} = \frac{\lambda^2 r_e N_{e_c}}{2\pi c}.$$
(40)

The phase gradient across the LOS is then $|\nabla_{\perp}\phi| \sim \lambda r_e N_{e_c}/a_{\perp}$ and the refraction angle is

$$\theta_{r_c} = \frac{\lambda |\nabla_{\!\!\perp} \phi|}{2\pi} \sim \frac{\lambda^2 r_e N_{e_c}}{2\pi a_{\!\!\perp}} \sim \frac{c \Delta t_{\rm DM_c}}{a_{\!\!\perp}}.$$
(41)

There are two time delays introduced by refraction into the barycentric arrival times. The first is associated with the translation of the topocentric TOAs by the propagation delay from the geocenter to the solar system barycenter. The direction to the pulsar is a key part of the translation, and refraction will induce an error in the barycentered arrival times. Chromatic refraction causes the angle of arrival to differ from an assumed direction, implying a delay (Foster & Cordes 1990) that varies sinusoidally with an annual period and an amplitude

$$\Delta t_{\text{bary}_c} \sim \frac{r_{\oplus} \theta_{r_c}}{c} \sim \left(\frac{r_{\oplus}}{a_{\perp}}\right) \Delta t_{\text{DM}_c} \sim \frac{\Delta t_{\text{DM}_c}}{a_{\perp au}}, \quad (42)$$

where $r_{\oplus} = 1$ au. The second delay is the geometric increase in propagation path that is roughly

$$\Delta t_{\text{geo}_c} \sim \frac{D\theta_{r_c}^2}{2c} \sim \frac{cD(\Delta t_{\text{DM}_c})^2}{2a_{\perp}^2} \sim \frac{cD}{2r_{\oplus}^2} \left(\frac{\Delta t_{\text{DM}_c}}{a_{\perp \text{au}}}\right)^2.$$
(43)

For a single clump, Equations (42) and (43) indicate that the barycentric delay Δt_{bary_c} and geometric delay Δt_{geo_c} are linear and quadratic, respectively, in the dispersion delay, $\Delta t_{\text{DM}c}$ ($\propto \nu^{-2}$ and ν^{-4} , respectively). The barycentric and geometric delays are comparable for pulsars within about 1 kpc because $\theta_r \sim 1$ mas and $D\theta_r \sim 1$ au, although there are wide variations of these values.

Numerically, the refraction and dispersion delays are comparable for nominal parameter values, but any one of the three delays can dominate the other two for reasonable distances and transverse scale lengths:

$$\Delta t_{\text{bary}_c} \sim 1 \ \mu s \left(\frac{\Delta t_{\text{DM}_c,\mu s}}{a_{\perp au}} \right),$$
 (44)

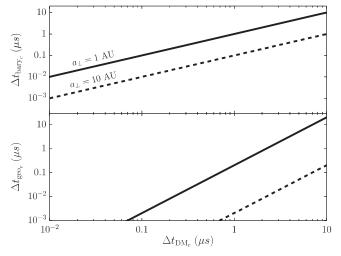


Figure 3. Refraction delays plotted against DM delay from a single cloud at a distance D = 1 kpc. (Top) The barycentric delay for two clump scale sizes, as labeled. (Bottom) The geometric delay for the same two clump sizes.

and

$$\Delta t_{\text{geo}_c} \sim 0.2 \ \mu \text{s} \ D_{\text{kpc}} \left(\frac{\Delta t_{\text{DM}_c,\mu \text{s}}}{a_{\perp \text{au}}} \right)^2. \tag{45}$$

Figure 3 shows Δt_{bary_c} and Δt_{geo_c} plotted against Δt_{DM_c} for D = 1 kpc and for two transverse scale lengths ($a_{\perp} = 1$ and 10 au).

A final consideration is multiple imaging. Clegg et al. (1998) analyze flux variations and caustics for an interstellar Gaussian plasma lens, i.e., a cloud with a Gaussian electron-density profile. The focal distance D_f of a clump is the minimum distance from the clump at which rays can cross,

$$D_f \sim \frac{a_\perp}{\theta_{r_c}} \sim \frac{a_\perp^2}{c\Delta t_{\rm DM_c}} \sim 2.4 \text{ kpc } a_{\perp au}^2 \Delta t_{\rm DM_c, \mu s}.$$
 (46)

We therefore do not expect ray crossing and multiple images from nearby pulsars unless a clump is small and dense.

We can solve for the three time delays associated with refraction (dispersion, barycentric, and geometric) by considering rays traveling through a Gaussian lens in the ISM. Following the treatment in Clegg et al. (1998), for a thinscreen approximation of the lens, the column density in two dimensions can be written as

$$N_{e_c}(\mathbf{x}) = N_0 \exp(-[|\mathbf{x} - \mathbf{x}_c|/a]^2), \qquad (47)$$

where N_0 is the maximum central column density and *a* is the characteristic size of the lens. The screen phase ϕ is related to the electron density by

$$\phi(\mathbf{x}) = -\lambda r_e \int_{\text{screen}} dz \ n_e(\mathbf{x}, z) \equiv -\lambda r_e N_e(\mathbf{x}). \tag{48}$$

For the Gaussian cloud, we therefore have

$$\phi_c(\mathbf{x}) = -\lambda r_e N_0 \exp\left(-[|\mathbf{x} - \mathbf{x}_c|/a]^2\right). \tag{49}$$

Using Equation (41), the refraction angle is

$$\boldsymbol{\theta}_{r_c}(\boldsymbol{x}) = \frac{\lambda^2 r_e N_0}{\pi a^2} \boldsymbol{x} \exp\left(-[|\boldsymbol{x} - \boldsymbol{x}_c|/a]^2\right), \quad (50)$$

In general, the location of the incident ray paths on the Earth at location x_e intersecting the cloud at x_c from a pulsar at x_p must

satisfy the equation

$$\mathbf{x}_e = \mathbf{x}_c - [\boldsymbol{\theta}_{r_c}(\mathbf{x}_c) + \boldsymbol{\theta}_i(\mathbf{x}_p)]D, \qquad (51)$$

where θ_i is the incidence angle of the pulsar rays on the screen.

7. INTERPRETATION OF OBSERVED PULSAR PHENOMENA

7.1. Linear Trends Versus Stochastic Variations

We look at several examples of deterministic, linear DM trends seen in the literature below. To test our interpretations, we compare the time series against simulated DM variations with a Kolmogorov wavenumber spectral index following the same procedure as described in Lam et al. (2015) by transforming scaled, complex white noise in the frequency domain to the time domain. The power spectrum of the electron-density variations, $S_{\rm DM}(f) \propto f^{-\gamma}$, has a spectral index of $\gamma = \beta - 1 = 8/3$ for the Kolmogorov case. The scalings of the coefficient of the power spectrum are consistent with the extrapolation of the SF $D_{\rm DM}$ by the scintillation timescale (see Equation (25)).

7.1.1. PSR J1909-3744

As described in Section 2, the DM time series shows a decreasing, linear trend (Demorest et al. 2013; Keith et al. 2013; Arzoumanian et al. 2015b) over a ~9 year timespan. Keith et al. (2013) compare SFs of dispersion delay D_t on long timescales with the extrapolations from the DISS timescale assuming a Kolmogorov spectrum. In several cases, they find that the actual measurements exceed the extrapolation by large factors and that the slope of D_t is larger than the Kolmogorov slope of 5/3. They conclude that the wavenumber spectrum is steeper than Kolmogorov. In the case of J1909 – 3744, they find that the value of the DM SF for measured lags is about a factor of five higher than the extrapolation from the DISS timescale using a Kolmogorov scaling.

We present an alternative interpretation that recognizes that the contribution to DM(t) from Kolmogorov fluctuations combined with the transverse motion of the LOS can be contaminated by the changing distance between the pulsar and Earth from parallel motion, as discussed previously (see Equation (27)). This contamination contributes a term to the SFs that scales as τ^2 , i.e., steeper than Kolmogorov, which can dominate the overall amplitude of the SFs.

The top left panel of Figure 4 is identical to Figure 1 and shows the time series of the DM offsets, $\delta DM(t)$, as reported in Demorest et al. (2013), Keith et al. (2013), and Arzoumanian et al. (2015b, NG9). Again, the total measured DM is found by adding a constant DM_{nominal} to the DM offsets, although the values will still differ due to other frequency-dependent parameters included in the timing models in each paper. Since the SF removes the mean, the differences are not important here. The bottom left panel shows $\delta DM(t)$ after a linear trend has been removed. A periodic trend remains in the time series with a roughly one-year period. The panels on the right show the corresponding DM SFs of the time series on the left. In the top right, we show the extrapolation of D_{DM} assuming a purely Kolmogorov medium and using a scintillation timescale of 2258 s at 1.5 GHz (solid black line; Keith et al. 2013) and note that all three SFs lie well above this extrapolation. We calculate the SF for the Keith et al. (2013)DM(t) with lag bins that are multiples of 0.25 yr (91.3 days), which is equal to the

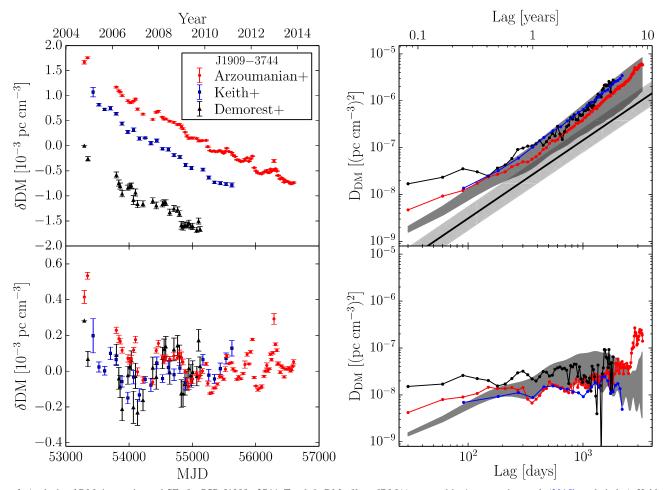


Figure 4. Analysis of DM time series and SFs for PSR J1909–3744. Top left: DM offsets δ DM(*t*) reported in Arzoumanian et al. (2015b, red circles), Keith et al. (2013, blue squares), and Demorest et al. (2013, black triangles); see Figure 1 for more details. Top right: DM SFs for the three time series in the top left (with matching colors). The solid black line indicates the value of the SF inferred from the scintillation timescale and assuming DM variations only from a Kolmogorov wavenumber spectrum for the ISM. The light gray, hatched region shows nominal errors on the inferred SF from a multiplicative factor of $\sqrt{2}$ error on the scintillation timescale. The dark gray region indicates the $\pm 1\sigma$ deviations from the mean SF for simulations of DM variations over nine years that include a Kolmogorov medium, a linear component from motion parallel to the LOS, a sinusoidal component, and measurement errors (see text for more information). Bottom left: DM offsets of the time series in the top left after a linear trend has been removed. Bottom right: DM SFs for the three time series in the bottom left. The gray region indicates the same as in the top right, except that the best-fit linear trend has been removed from the simulated time series before calculating the SF.

minimum sampling time for Keith et al. (2013). For the other two SFs, we use bins that are multiples of 30 days. The light gray, hatched region denotes nominal errors in the extrapolation from a multiplicative error of $\sqrt{2}$ on the scintillation timescale, known for PSR B1937+21 (Cordes et al. 1986, 1990; Keith et al. 2013). The dark gray region shows the $\pm 1\sigma$ deviations from the mean DM SF for simulations of nine years of DM variations that include the following: a Kolmogorov wavenumber spectrum; the best-fit linear trend of the data $(dDM/dt = -2.27 \pm 0.04 \times 10^{-4} \text{ pc cm}^{-3} \text{ yr}^{-1})$; a sinusoid with a one-year period and an amplitude of 5 \times 10⁻⁵ pc cm⁻³; and white, Gaussian noise with an rms of $\sigma_n = 2.4 \times 10^{-5} \text{ pc cm}^{-3}$ in the first five years and $1.2 \times 10^{-5} \text{ pc cm}^{-3}$ in the last four years, which is equal to the median error corresponding to each of the backends used in the NG9 data set. The DM SF from NG9 is consistent with these simulations. In the bottom right, we show the results of simulations when all of the above are included but a linear trend is fit and subsequently removed from the time series before computing the SF, which can remove power from both the linear component and some low-frequency structure in a

given time series. The shape of the gray region matches some of the shape present in the SF, although the position indicates that the sinusoidal term should possibly have a smaller amplitude with a more peaked shape. Few numbers of DM increments in bins at large time lags lead to deviations from the mean SF. A more detailed analysis of the DM time series for J1909–3744 will be presented by M. L. Jones et al. (2016, in preparation).

Using Equation (14) and its assumption of density changes occurring at large length scales only, we can use our measured, best-fit dDM/dt to infer the electron density at the pulsar, $n_e(\mathbf{x}_{p_0})$. The transverse components of the velocity are $v_{\alpha} = -50.61 \pm 0.01$ km s⁻¹ and $v_{\delta} = -192.32 \pm 0.01$ km s⁻¹ with a distance of $1.14^{+0.04}_{-0.03}$ kpc (Jacoby et al. 2005; Antoniadis 2013). The barycentric, systemic radial velocity is -37 ± 11 km s⁻¹ (J. Antoniadis 2016, private communication). We find the pulsar parallel velocity component $v_{p_{\parallel}}$ by removing the local solar motion and correcting for differential Galactic rotation. We take the local solar motion to be 18.0 ± 0.9 km s⁻¹ in the direction $(l_g, b_g) = (47.9 \pm 3.0, 23.8 \pm 2.0)$ and assume a locally

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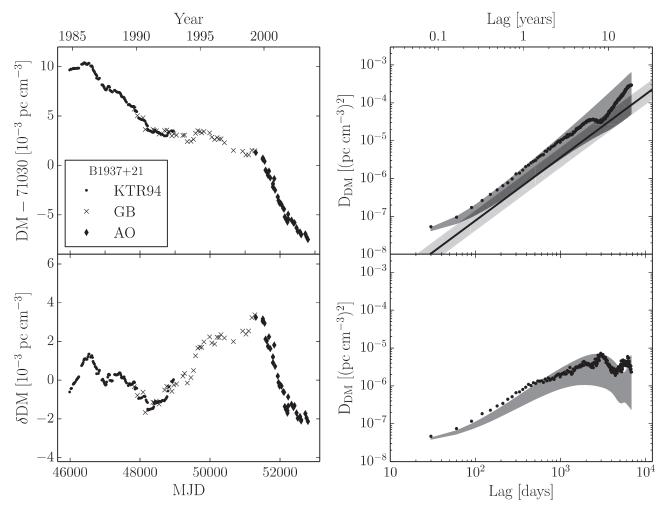


Figure 5. Analysis of DM time series and SFs for PSR B1937+21. The format is the same as in Figure 4. The dots are from Kaspi et al. (1994) while the crosses and diamonds are from Ramachandran et al. (2006) for the Green Bank (GB) 140-foot telescope and the Arecibo Observatory (AO), respectively.

flat, galactic rotation curve (Frisch et al. 2011). J1909–3744 lies nearly in the direction of the Galactic center with $(l_g, b_g) = (359^\circ.7, -19^\circ.6)$ and therefore the change in the velocity vector due to differential galactic rotation are negligible and we can ignore transverse components in our calculation. Taking the electron density of the LIC to be $n_e(\mathbf{x}_{e_0}) \approx 0.15 \pm 0.05 \text{ cm}^{-3}$ (Frisch et al. 2011), we find $n_e(\mathbf{x}_{p_0}) = 7.6 \pm 2.9 \text{ cm}^{-3}$, which is about two orders of magnitude greater than the average local electron density of the galaxy in that region (Cordes & Lazio 2002; Frisch et al. 2011).

7.1.2. PSR B1937+21

Ilyasov et al. (2005) show a long-term trend in a 20 year DM time series extending to ~2003.5 (MJD 52800) that has a strong, decreasing trend with an average derivative of $dDM/dt \approx -1.14 \pm 0.03 \times 10^{-3} \text{ pc cm}^{-3} \text{ yr}^{-1}$. Ramachandran et al. (2006) show similar results. Long-term correlated variations are superposed with the linear trend. The best-fit line of the SF is $\beta = 3.66 \pm 0.04$, although the analysis from Kaspi et al. (1994) on DM variations up to 1993 alone suggests $\beta = 3.874 \pm 0.011$. Both Kaspi et al. (1994) and Ramachandran et al. (2006) fit the $D_{\phi}(\tau)$ to determine $\Delta t_{\rm ISS}$, which will be a biased estimator if a deterministic, linear trend is present.

We repeat our SF analysis as before, shown now in Figure 5, using the Ramachandran et al. (2006) data. They include the time series from Kaspi et al. (1994, circles), measured at 1400 and 2200 MHz. The crosses are measurements from the Green Bank (GB) 140-foot telescope between 800 and 1400 MHz, and the diamonds are measurements from the Arecibo Observatory (AO) between 1400 and 2200 MHz. Differences in the DM estimation and the frequency-dependent delays that we used mean that we currently cannot align the Ramachandran et al. (2006) time series with the Keith et al. (2013) time series measured at later epochs. Therefore, we ignore the latter time series here and in subsequent analyses.

We measure $dDM/dt = -8.39 \pm 0.14 \times 10^{-4} \text{ pc cm}^{-3} \text{ yr}^{-1}$ for the Ramachandran et al. (2006) data, suggesting that a long-term linear trend remains present in the time series. We again simulate a Kolmogorov medium with $\Delta t_{\text{ISS}} = 327 \text{ s}$ at 1.5 GHz (Keith et al. 2013) and include a linear trend with slope measured above and additive, Gaussian white noise. The varying scintillation timescale over years is not included in the realizations and biases our overall results, but not the conclusions. We find the rms of the noise by modeling the SF as $D_{\text{DM}}(\tau) = C\tau^{\alpha} + 2\sigma_n^2$ (see Appendix B for more details) and find $\sigma_n = 1.3 \times 10^{-4} \text{ pc m}^{-3}$. Again, the measured SF shows good agreement with our realizations.

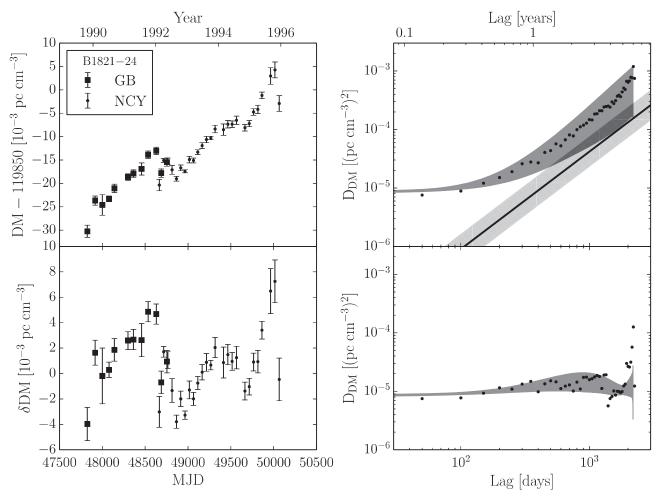


Figure 6. Analysis of DM time series and SFs for PSR B1821–24. The format is the same as in Figure 4. The squares show measurements from the Green Bank (GB) 140-foot telescope (Backer et al. 1993) while dots show measurements from the Nançay radio telescope (NCY; Cognard & Lestrade 1997).

7.1.3. PSR B1821-24

Cognard & Lestrade (1997, see also Backer et al. 1993) show a DM time series with a long-term increasing trend with $dDM/dt \approx 0.005 \text{ pc cm}^{-3} \text{ yr}^{-1}$ over a six-year period. Again, we ignore the DM variations from Keith et al. (2013) because of the absolute DM difference. Using measurements from GB and the Nançay radio telescope, Cognard & Lestrade (1997) find that the spectral index of the wavenumber spectrum is $\beta = 3.727 \pm 0.211$. Figure 6 shows our SF analysis, with red noise realizations with $\Delta t_{\rm ISS} = 75$ s at 1.5 GHz (Keith et al. 2013) and an estimated $\sigma_n = 2.1 \times 10^{-3} \text{ pc cm}^{-3}$. The LOS to PSR B1821–24 is also consistent with a Kolmogorov medium.

7.1.4. Deterministic Linear Trends from DM Derivatives

We calculate $R_{dDM/dt}$ for pulsars in the literature with measured dDM/dt. To calculate $\sigma_{dDM/dt}$, we use pulsars with a measured scintillation bandwidth $\Delta \nu_{ISS}$ or those that can be estimated from the scattering timescale τ_{ISS} using $2\pi\Delta \nu_{ISS}\tau_{ISS} = C_1$, where $C_1 = 1.16$ for a uniform medium with a Kolmogorov wavenumber spectrum. Assuming such a medium, we estimate the SM using Equation (10) of Cordes & Lazio (2002) as

$$SM = 7.15 \times 10^{-4} \text{ kpc m}^{-20/3} \\ \times (\Delta \nu_{\text{ISS,MHz}} \nu_{\text{GHz}}^{-22/5} D_{\text{kpc}})^{-5/6}.$$
(52)

We either use parallax distances or binary orbital period derivative (\dot{P}_b) distances to estimate SM when available, and otherwise use DM distances from NE2001 (Cordes & Lazio 2002). We convert proper-motion measurements into pulsar perpendicular velocities assuming that $v_{p_{\perp}}$ dominates $v_{\text{eff}_{\perp}}$ (which may not be true for slow moving MSPs) and differential galactic rotation is negligible, both of which may contribute systematic uncertainties in our analysis. However, under these assumptions, we combine SM, $v_{p_{\perp}}$, and the total observing span *T* to calculate $\sigma_{dDM/dt}$, and thus $R_{dDM/dt}$.

Table 2 lists the pulsar values we use from the literature in our analysis and the results. Figure 7 shows |dDM/dt| versus $\sigma_{dDM/dt}$ for slow-period canonical pulsars (CPs, red triangles) and MSPs (black circles). We also highlight the five linear trends of the MSP B1534+12 (blue squares; discussed in the following section) and J1909–3744 (blue star). The lines represent $R_{dDM/dt} = 1$ (solid) and 5 (dashed), where higher $R_{dDM/dt}$ (increasing exponentially to the top left) represents

Table 2Measurements of DM Derivatives and $R_{dDM/dt}$

Pulsar Parameters				Scintillation Parameters ^a		DM Derivatives ^b		Derived Results		
Pulsar	DM ^c pc cm ⁻³	PM ^c mas yr ⁻¹	D ^d kpc	ν GHz	$\Delta u_{ m ISS}$ MHz	$\Delta t_{\rm ISS} \atop { m s}$	T yr	$\frac{d\mathrm{DM}/dt^{\mathrm{e}}}{10^{-3} \mathrm{ \ pc \ cm^{-3}}}$	$\sigma_{d{ m DM}/dt}$ yr ⁻¹	$R_{d \mathrm{DM}/dt}$
J0358+5413	57.14	12.3 ± 0.3	1.1 ± 0.2	1.0	0.789		16.4	$-2.6\pm0.8^{\rm f}$	0.24	11.1
J0543+2329	77.71	22 ± 8	2.06	1.0	0.069		20.7	$-4.9\pm0.6^{ m f}$	1.3	3.7
J0835-4510	67.99	57.98 ± 0.08	0.29 ± 0.02	0.61	$1.5 imes10^{-4}$	3	5.7	5 ± 1^{g}	9.4	0.53
J1024-0719	6.49	59.7 ± 0.3	0.53 ± 0.22	1.5	268	4180	15.1	0.22 ± 0.06	0.047	4.7
J1045-4509	58.17	8.0 ± 0.2	0.30 ± 0.17	1.5	0.094	119	17.0	-3.66 ± 0.13	0.90	4.1
B1534+12 ^h	11.62	25.328 ± 0.012	1.051 ± 0.005	0.43	1.1	660	3.3	-0.316 ± 0.010	0.081	3.9
							5.0	-0.043 ± 0.008	0.076	0.57
							4.7	-0.294 ± 0.007	0.077	3.8
							2.3	1.01 ± 0.03	0.086	11.7
							2.3	-0.01 ± 0.05	0.086	0.12
J1543+0929	35.24	8.13 ± 0.07	7.7 ± 1.2	1.0	0.299		21.4	$26\pm5^{ m f}$	0.54	48.5
J1600-3053	52.33	7.2 ± 0.3	5.0 ± 3.8	1.5	0.09	271	9.1	-0.63 ± 0.3	0.50	1.3
J1643-1224	62.41	7.3 ± 0.3	0.45 ± 0.08	1.5	0.022	582	17.0	-1.23 ± 0.05	0.24	5.2
J1730-2304	9.62	20.27 ± 0.06	0.53	1.5	12.4	1615	16.9	0.56 ± 0.05	0.10	5.5
J1732-5049	56.82	9.9 ± 0.3	1.41	1.5	5.4	1200	8.0	-0.88 ± 0.12	0.15	6.0
J1744-1134	3.14	21.02 ± 0.03	0.42 ± 0.02	1.5	60	2070	16.1	-0.132 ± 0.018	0.084	1.9
J1833-0827	411	34 ± 6	4.5	1.0	$1.6 imes10^{-4}$		5.7	$-130\pm20^{ m g}$	40.6	3.2
J1909+1102	149.98	9 ± 8	4.8	1.0	0.012		15.1	-15.8 ± 1.2^{f}	1.9	8.3
J1909-3744	10.39	37.10 ± 0.02	1.27 ± 0.03	1.5	37	2258	8.2	-0.297 ± 0.006	0.087	3.4
J1935+1616	158.52	16.13 ± 0.15	4.55	0.61	0.002	18	34.1	2.3 ± 0.3^{f}	1.6	1.5
B1937+21	71.02	0.421 ± 0.003	7.7 ± 3.8	1.5	1.2	327	15.5	-0.59 ± 0.03	0.39	1.5
J2129-5721	31.85	13.3 ± 0.1	0.53 ± 0.25	1.5	17.1	3060	15.4	-0.16 ± 0.04	0.061	2.6

Notes.

^a Parameters for $\nu = 0.43$ GHz measurements from Bogdanov et al. (2002), for $\nu = 0.61$ GHz measurements from Stinebring et al. (2000), for $\nu = 1.0$ GHz measurements from PSRCAT (Manchester et al. 2005, using $2\pi\Delta\nu_{\rm ISS}\tau_{\rm ISS} = C_{\rm I} = 1.16$), and for $\nu = 1.5$ GHz measurements from Keith et al. (2013). The number of significant digits are provided by the individual references.

^b Timespan and dDM/dt references match.

^c Column data from PSRCAT (Manchester et al. 2005) unless otherwise marked.

^d Distances with errors from parallax measurements (http://www.astro.cornell.edu/research/parallax/ and references therein), distances without errors from NE2001 (errors are \sim 20%), and distance for PSR B1534+12 from binary orbital period derivative (Fonseca et al. 2014).

^e Values from Reardon et al. (2016) unless otherwise marked.

^f Hobbs et al. (2004).

^g Petroff et al. (2013).

^h All values from Fonseca et al. (2014) except the scintillation parameters (Bogdanov et al. 2002).

greater inconsistency with a Kolmogorov medium. J1909 -3744 shows some evidence for deviations from a Kolmogorov medium. Several other pulsars show marginal or large deviations, including some MSPs with known chromatic timing noise such as PSR J1643-1224 in NG9 (see also Arzoumanian et al. 2015a). Figure 8 shows the ratio $R_{\rm rms}$ (Equation 34) for the DM time series of the pulsars examined so far, with J1909-3744 showing the most deviation (more toward the left) from a Kolmogorov spectral index, consistent with the conclusion from the $R_{dDM/dt}$ metric.

7.2. Non-monotonic Trends from Electron-density Structures in the ISM

DM(t) time series from pulsars show a combination of linear trends, stochastic variations, and, in a few cases, fast changes in slope that are both positive and negative. Apparent slope changes can appear in particular realizations of a stochastic process with a red power spectrum. However, they can also result from slab-like structures if they are suitably oriented relative to the LOS and the pulsar velocity. Such slabs may represent static increases and deficits over the local mean electron density that contribute as the LOS changes with time. Alternatively, they could be time-

dependent owing to motions of the shock front through neutral gas. Bow shocks produced by the pulsars themselves may ionize atomic (and, less likely, molecular) structures as they move through the ISM.

Backer et al. (1993) proposed that plasma wedges are responsible for linear trends in DM(t). A plasma wedge has linearly increasing column density $N_e(x)$ transverse to the LOS. As the LOS moves across it, DM(t) will change linearly until the wedge boundary is reached, if there is one. The wedge will also refract by a constant refraction angle. Unlike other structures, however, a wedge of this type will have a zero transverse second derivative (except at the boundaries) and therefore will not cause changes in the measured flux density.

The effects of different geometries include the following.

Transverse motion $(v_{p_{\parallel}} = 0)$: for a density enhancement that is aligned with the LOS, $DM_{slab}(t)$ will consist of a positive-going "pulse" with a duration equal to the pulsar travel time across the slab thickness. For a density deficit (e.g., from encountering a slab of atomic gas), the pulse will be negative-going. To first

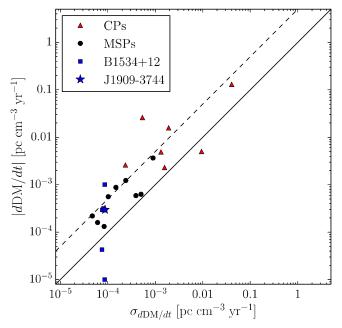


Figure 7. DM time derivative dDM/dt vs. the rms DM gradient $\sigma_{dDM/dt}$. Canonical pulsars (CPs) are shown in red triangles and MSPs in black circles. We highlight the linear DM segments of the MSP B1534+12 in blue squares and the blue star for MSP J1909-3744. Two of the blue squares for B1534+12 closely overlap with J1909-3744. The solid line represents $R_{dDM/dt} = 1$, whereas the dashed line represents $R_{dDM/dt} = 5$, exponentially increasing to the top left.

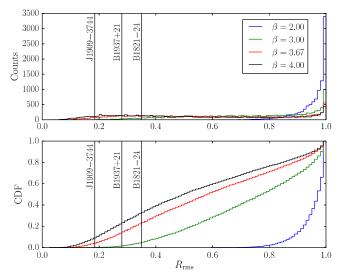


Figure 8. Top: histograms of the ratio $R_{\rm rms}$ for 10,000 red noise process realizations with spectral index $\gamma = \beta - 1$. Bottom: cumulative distribution functions of the histograms. The value of the $R_{\rm rms}$ is shown for the three pulsars in our analysis with single, linear trends. Lines toward the left indicate potential deviations from a wavenumber spectrum with spectral index β .

order, the pulsar distance does not change, and so the unperturbed DM is constant in time.

Pulsar velocity component along the LOS $(v_{p_{\parallel}} \neq 0)$ and aligned slabs: when the density slabs are aligned with the LOS, DM(t) again show square-wave-type pulses. The prevailing trend is for DM(t) to decrease as the pulsar

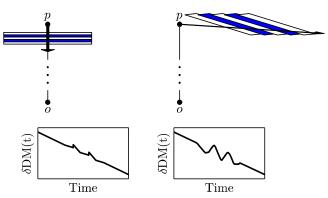


Figure 9. Two cartoon geometries for a pulsar *p* moving in different directions with respect to the line of sight between the pulsar at *p* and the observer at *o*. Blue represents high-density structures and white represents low-density structures. The bottom graphics show DM variations, $\delta DM(t)$, that are monotonic on long timescales.

distance gets smaller, but this is interrupted by the density deficits and enhancements.

Pulsar velocity component along the LOS $(v_{p_{\parallel}} \neq 0)$ and slanted slabs: when the density slabs are slanted from the LOS, DM(*t*) can show a saw-tooth pattern where it has a larger slope than the prevailing trend or a slope with opposite sign. As in the previous case, the prevailing trend is for DM(*t*) to decrease as the pulsar distance becomes smaller, but this is interrupted by the density deficits and enhancements.

Pulsar velocity toward the observer $(v_{p_{\perp}} = 0)$: in this case, the pulsar can ionize atomic hydrogen as it passes into the slab. The DM can increase even if the pulsar moves toward the observer and the prevailing trend is for a declining DM.

Some examples of the geometries can be seen in Figure 9.

7.2.1. Ionized Bow Shocks

So far, we have assumed that ISM structures are static. However, the pulsar can actively modify its local environment. An extreme case is where the pulsar's motion toward the observer takes it through *atomic* hydrogen (H₁) structures on scales of tens of au and larger, including filaments, with a typical column density of the order of $N_{\rm H\,I} \sim 10^{-20}$ cm⁻² (e.g., Gibson 2007; McClure-Griffiths et al. 2007; Stanimirović et al. 2007). As the pulsar nears a filament, it will ionize the atomic gas through a combination of radiation from the neutron star/magnetosphere and shock heating. The standoff radius of the bow shock is given by the balance of ram pressure and the pulsar's relativistic wind,

$$r_{s} = \left(\frac{\dot{E}}{4\pi\rho v_{p}^{2}c}\right)^{1/2} \approx 266 \text{ au } \dot{E}_{33}^{1/2} n_{\mathrm{H\,I}}^{-1/2} v_{p_{100}}^{-1}, \qquad (53)$$

for $\dot{E} = 10^{33} \dot{E}_{33}$ erg s⁻¹, a pulsar velocity in units of 100 km s⁻¹, and an effective hydrogen density $n_{\rm H\,I}$ cm⁻³. For the measured ranges of pulsar velocities, energy loss rates

(*E*), and ISM densities, the standoff radius of the bow shock is tens of au to ~ 0.1 pc. Therefore, DM(*t*) can show temporary increases even though the prevailing trend would be a decrease because of the decreasing distance.

Bow shocks will cause changes in DM only if the pulsar moves through a changing gas density (see, for example, PSRs J2124-3358 and B2224+65; Gaensler et al. 2002; Chatterjee & Cordes 2004). For completely ionized gas, there may be a weak effect from the shock-enhanced gas density. A much larger effect will occur from neutral gas that is shock-ionized or preionized by radiation from shocked gas. The mean free path for ionizing radiation with $h\nu = 13.6 \text{ eV}$ for a cross section $\sigma_{\rm H\,I} = 6.3 \times 10^{-18} \text{ cm}^2$ is

$$l_{\rm H\,I} = (\sigma_{\rm H\,I} n_{\rm H\,I})^{-1} \approx \frac{1.1 \times 10^4 \,\rm{au}}{n_{\rm H\,I, cm^{-3}}},\tag{54}$$

which is much larger than both the nominal standoff radius and the distance traveled by a pulsar in one year. However, for anticipated gas densities and temperatures (e.g., a shock temperature $T_s \approx 3m_p v_p^2/k \approx 3.6 \times 10^6$ K; m_p = proton mass, v_p = pulsar velocity, k = Boltzmann constant), there are insufficient photons to ionize a region of this size. This is why H α bow shocks are seen around some pulsars (e.g., PSRs B1957+20, B2224+65, and J0437-4715; Brownsberger & Romani 2014) in thin shells of pre-shocked atomic hydrogen that define the bow-shocks contours. For velocities ~100 km s⁻¹ and densities $n_{\rm H\,I} \approx 1$ to 10 cm⁻³, the distance traveled by the pulsar over years is less than or comparable to the standoff radius. The DM increment associated with shock ionized atomic gas is roughly

$$\delta DM_{\text{bow}} \approx \eta_s r_s n_{\text{H I}} \\\approx 1.3 \times 10^{-3} \,\text{pc cm}^{-3} \,\eta_s v_{p_{100}}^{-1} (n_{\text{H I}} \dot{E}_{33})^{1/2}, \qquad (55)$$

where $\eta_s \sim 4$ is a factor that takes into account the compression of interstellar gas and its distribution inside the termination shock (Clegg et al. 1988, p. 174). The nominal value of δDM_{bow} is sufficiently large to be interesting. Given the phase structure of the ISM, we expect that most pulsars will not reside in atomic gas, but perhaps 40% will (Draine 2011).

7.2.2. Small-scale Electron Density Variations

Because the ionized ISM contains a wide range of length scales (Armstrong et al. 1995), the density fluctuation term in Equation (11) involving $\Delta n_e(\mathbf{x}(t))$ also needs to be considered. Its contribution to DM is

$$\delta \mathbf{D}\mathbf{M}(t) = \int_{z_{e_0}}^{z_{p_0}} dz \,\Delta n_e(\mathbf{x}(z, t)). \tag{56}$$

Typical scales transverse to the LOS are $|\mathbf{r}| \sim v_{\perp} t \sim 20$ au $v_{\perp 100} t_{\rm yr}$. The relevant velocity $\mathbf{v}_{\rm eff_{\perp}}(z)$ is largest at the pulsar position (c.f. Equation (7)) for cases where the proper-motion velocity is larger than the Earth's velocity. Elsewhere along the LOS and for slowly moving MSPs, the transverse scale can be substantially smaller.

There is evidence for individual structures in the ISM on au scales based on refraction effects in pulsar dynamic spectra,

extreme scattering events, and intraday variable sources. These are likely confined to a small fraction of the LOS and will produce maximum contributions to DM of the order of $10^{-5}n_e \ell_{10 \text{ au}}$ pc cm⁻³, where $\ell_{10 \text{ au}}$ is the path length through the structure. The timescale for changes depends on the density, size, and velocity of the structure, and so the derivative dDM/dt can be comparable to or much smaller or larger than the contribution from the changing distance analyzed in the previous subsection.

7.2.3. Implications for PSR B1534+12

We make use of the second-order SF approach developed in Section 5 to analyze the DM time series presented in Fonseca et al. (2014). While they note five significant linear trends in DM, they have no temporal information in the first block, and so we remove it from our analysis.

Figure 10 shows the DM time series along with the secondorder increments of DM, which we use to indicate the presence of discrete changes in linear trends over the expectation from a purely Kolmogorov medium. To account for the unequal sampling in $\delta DM(t)$, we calculate increments as a function of τ by finding two points separated from the central time t, one within the range $\tau \pm \tau/2$ and the other within $-\tau \pm \tau/2$. Increasing τ by 30 days at a time, we plot the second-order increments in the top right panel. Combining Equations (25) and (39), the probability distribution of the increments will be a Gaussian function. Using $\Delta t_{\rm ISS} = 660 \pm 180$ s measured at 430 MHz (Bogdanov et al. 2002), the 1σ and 2σ expected regions are shown in the gray bands. The points in the top right of the plot outside of the bands and at $\tau > 500$ days all result from the concave upward turnover between the second and third linear components and represent a \sim 7–14 σ deviation from the expectation of a purely Kolmogorov medium. Points well below the bands come from either of the other two change points. The points deviating from zero at low lags are purely from the noise in the measurements, not accounted for in the gray bands. The bottom left shows 100 realizations of DM purely from Kolmogorov power-law wavenumber spectra, and the full range (minimum to maximum value) of second-order increments for each τ is shown on the bottom right for all 10,000 realizations. We show the results of our simulations to demonstrate that there is good agreement between the rms of the second-order increments from simulations and the analytic solution. Again, the fact that several measured increments for PSR B1534+12, notably those associated with the second change points, fall outside of the expectations from simulations implies that the upturn in DM cannot be due to a purely Kolmogorov medium. The time series is similar to those shown in Figure 9 after a linear trend has been removed, suggesting that there are interleaved density structures along the LOS. Contemporaneous scintillation parameters and pulsar flux-density measurements would be valuable for testing whether or not the DM time series is at all contaminated by diffraction and refraction effects.

8. PERIODIC VARIATIONS IN DM

In this section, we determine how periodic trends can appear in DM time series. DM(t) will vary as the LOS passes across spatial gradients in the electron density. Local electron-density variations in time will also cause DM variations. We assess the

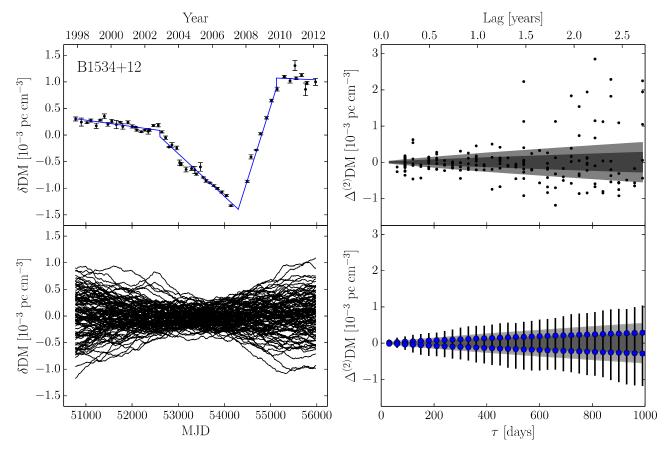


Figure 10. Analysis of DM time series and SFs for PSR B1534+12. Top left: the DM offsets $\delta DM(t)$ from Fonseca et al. (2014, the first, isolated epoch has been removed) with their best-fit linear trends overplotted. Top right: second-order increments of DM, $\Delta^{(2)}DM(t, \tau)$. The gray regions indicate the 1 and 2σ expected regions in Equation (39) assuming a Kolmogorov wavenumber spectrum and the appropriate scintillation timescale, $\Delta I_{ISS} = 660$ s. Bottom left: 100 realizations of $\delta DM(t)$ from a Kolmogorov medium scaled to the appropriate scintillation timescale. Bottom right: the second-order increments of the DM realizations in the bottom left. The shaded regions are the same as in the top right. The black bars indicate the range of increments as calculated from all of the realizations, with the blue circles indicating the 1σ bounds, matching the expectation.

periodicites and phases associated with each periodic contribution to DM.

8.1. Ionosphere

Changes in the electron-density within the ionosphere can cause differences in the DM between observatories. The changes correlate with the incident solar flux at a particular location. Variations are known to occur daily from Earth's rotation, yearly due to Earth's orbital motion, and on 11-year cycles due to changes in solar magnetic activity (see Huang & Roussel-Dupré 2006, for an ionospheric electron-density model over a specific LOS). Measurements of the electron density can be peformed by satellite, rocket, incoherent scatter radar, and ionosonde.

The ionosphere can be represented as a series of semi-Epstein layers (Rawer 1982) with electron density as a function of the normalized distance parameter z,

$$n_e(z) = \frac{4n_0}{[1 + \exp(z)]^2} \exp(z)$$
(57)

with the peak electron density of the layer, n_0 , and $z = (h_s - h_0)/H$, where h_s is the height above the Earth's surface, h_0 is the height of the peak electron density, and *H* is

the characteristic thickness of the layer. Note that as $h_s \gg h_0$, $n_e(z)$ tends toward zero.

Nava et al. (2008, NeQuick 2) model⁴ the E, F1, and F2 ionospheric layers using one semi-Epstein layer to describe the bottom and top sides of each layer. They introduce a "fadeout" function that multiplies z in the E and F1 layer functions to prevent secondary maxima around the F2 peak height. The peak heights, peak electron densities, and thicknesses of each layer change as a function of the latitude and longitude, (ϕ_g, λ_g) , over Earth's surface due to the structure of its timevarying magnetic field. There are additional time-dependent factors regarding the incident solar flux at a given (ϕ_g, λ_g) , including the change in the Sun's zenith angle over a day, the change in the seasons for a given latitude ϕ_g , and the variable solar flux that changes both daily and over a solar cycle. Therefore, the three layer parameters, n_0 , h_0 , and H, are all complex functions of longitude, latitude, and time.

In general, the DM is the integral of the electron density over some path *s* through the atmosphere that depends on the geographic coordinates of the observatory and the apparent coordinates (i.e., altitude and azimuth) of the pulsar, which in turn depend on the equatorial coordinates of the source (α_e , δ_e)

⁴ http://t-ict4d.ictp.it/nequick2

and time t. The path to integrate over is then $s(\phi_g, \lambda_g, \alpha_e, \delta_e, t)$, and the total ionospheric contribution to DM is simply the line integral

$$DM_{ion,NeQuick}(t, \phi_g, \lambda_g, \alpha_e, \delta_e) = \int_0^{s_{max}} \sum_{i=E,F1,F2} n_{e,i}(s(t, \phi_g, \lambda_g, \alpha_e, \delta_e), \phi_g, \lambda_g, t) ds \quad (58)$$

up to some maximum distance s_{max} where we sum the total electron over each layer.

We study the variations of electron density in the ionosphere using two methods. The first estimates the ionospheric contribution to DM using global navigation satellite system (GNSS) measurements from the International GNSS Service (IGS; Dow et al. 2009). The total electron content (TEC) is measured via frequency-dependent signal propagation delays, which are similar to pulsar timing delays but between a ground receiver and a transmitting satellite along a given LOS. Using multiple LOSs at a given time, the IGS constructs a 2D surface map of the ionospheric electron density. These maps typically have time resolution of two hours and spatial resolution of 2.5×5.0 degrees in latitude and longitude, respectively. We linearly interpolate intermediate-TEC values in both space and time. While the original measurements between receiver and satellite are along some altitude and azimuth, the reported TEC values are in the zenith direction. Therefore, we must adjust the measurements for a particular LOS. To simplify, we approximate the ionosphere as a uniform slab of electrons with an inner (s_{\min}) and outer (s_{\max}) height of 60 and 600 km above Earth's surface, respectively. Therefore, we can estimate the TEC along a LOS by multiplying the zenith TEC by a geometric factor $G(\theta_{\tau})$ that accounts for the increase in path length through the ionosphere and depends only on the zenith angle θ_{z} to the pulsar,

$$DM_{\text{ion,IGS}}(t, \phi_g, \lambda_g, \alpha_e, \delta_e) = n_e(\phi_g, \lambda_g, t)(s_{\text{max}} - s_{\text{min}}) \\ \times G(\theta_z(\phi_g, \lambda_g, \alpha_e, \delta_e, t)).$$
(59)

Figure 11 shows our daily estimates of $DM_{ion}(t)$ along the LOS to J1909–3744 from both the Green Bank Telescope (GBT, black) in the Northern Hemisphere and the Parkes Telescope (PKS, blue) in the Southern Hemisphere using the method in Equation (59). The top panel shows the DM measurements at transit on each day. Error bars come from the GNSS measurement errors alone, multiplied by the same geometric factor dependent on the zenith angle. The overall amplitude shift is a result of the constant difference in the zenith angle of the pulsar at transit between the two sites. Differences in DM between GBT and PKS are shown in the sub-panel beneath. The right panel shows the estimated DM observed with PKS versus GBT, with the solid gray line representing the ratio of the geometric factors. For reference, the median DM measurement error at the GBT for this pulsar is $\sim 1 \times 10^{-5} \,\mathrm{pc} \,\mathrm{cm}^{-3}$ for the latest backends (see $\hat{\mathrm{NG9}}$ for information on the GUPPI backend), whereas the value at PKS is $\sim 3 \times 10^{-5} \,\mathrm{pc} \,\mathrm{cm}^{-3}$. Variations in the DM annually and over the solar cycle are visible. The bottom panels of Figure 11 show the result of simultaneous observations of the pulsar at low elevation angles at both telescopes, such that the ratio of the geometric factors is 1:1, i.e., variability is due solely to differences in the ionosphere at different local times. Such an observation occurs 110 minutes after the pulsar transits the

GBT when the zenith angle is $\approx 80^{\circ}3$, yielding a geometric factor of ≈ 3 increase over the zenith TEC measurement. The sites are separated by $\sim 112^{\circ}$ of longitude and observe the pulsar at nearly opposite local times. As the Earth's orbital position shifts, the local observing times shift, producing a phase difference between the two time series. Smaller peaks separated from the yearly peaks by approximately six months are visible as the solar cycle maximum is approached just past the end of the time series (again see Huang & Roussel-Dupré 2006, for this intra-annual variability). Again, the right panel shows the PKS-estimated ionospheric DM versus the GBT-estimated DM, where the estimates in DM can differ by measurable amounts even when observed at the same time. The bimodality results from ionospheric differences between day and night between the sites.

The second method used to study the ionospheric DM variations employs the mathematical description above, implemented in the NeQuick 2 model (Nava et al. 2008). NeQuick 2 uses ionosonde measurements to determine the parameters of the semi-Epstein layers (Equation (57)), along with solar radio flux measurements and a model for the magnetic inclination that describes the shape of Earth's magnetic field lines as a function of latitude, longitude, and time. For more details on the implementation, we refer readers to Report ITU-R P.2297-0 (2013). By default, NeQuick 2 contains parameters with a monthly time resolution, and a time series for J1909–3744 is shown in comparison to the DM contribution from the solar wind, discussed in the following subsection, in Figure 12.

8.2. Solar Wind

Particles from the solar corona have enough kinetic energy to escape the Sun's gravity, becoming part of the interplanetary medium. The speeds and compositions of these particles are not uniform, and measurements of the electron density are carried out both from ground-based observing and in situ. Splaver et al. (2005) model the electron density along the LOS to PSR J1713 +0747 due to the solar wind as a power law $n_e(r) = n_0 (1 \text{ au}/r)^2 \text{ cm}^{-3}$, where n_0 is the electron density in cm⁻³ at Earth, based on measurements from the Ulysses spacecraft (Issautier et al. 2001). They note that while the scaling holds over a large range of heliocentric latitudes, it does not consider spatial variations with ecliptic latitude β_e , namely the higher-density slow wind at lower latitudes and the lowerdensity fast wind at higher latitudes, nor does it consider temporal variations. They find that $n_0 = 5 \pm 4 \text{ cm}^{-3}$. You et al. (2007) present a generic two-piece model that accounts for the positional variations using daily solar magnetic field maps from the Wilcox Solar Observatory but do not consider temporal variations; the coefficients for their power-law components come mostly from observations taken at minima in the solar cycle. See the references cited by You et al. (2007) for more details.

Sokół et al. (2013; see also Provornikova et al. 2014) find that the total number density of solar wind protons is ~2–10 cm⁻³ at 1 au over a range of heliolatitudes β_h and over the course of a solar cycle. The highest densities come from $|\beta_h| \leq 20^\circ$. At solar cycle maxima, the total density at 1 au is a weak function of heliolatitude with a value of ~6 cm⁻³. Heading toward solar cycle minima, the proton density becomes more peaked at central heliolatitudes, although the overall quantity drops. We follow the methods in Sokół et al.

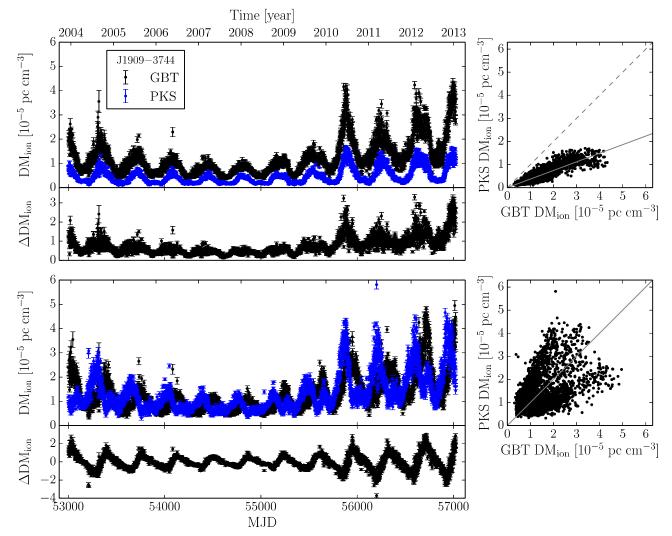


Figure 11. Estimates of the ionospheric contribution to DM from interpolated global navigation system satellite measurements along the LOS to J1909–3744 from Green Bank Telescope (GBT, black) and the Parkes Telescope (PKS, blue) daily over nine years. Top left: measurements of DM computed daily when J1909–3744 transits each telescope. The difference between the GBT and PKS DM estimates are shown in the panel beneath. Top right: DM estimated from Parkes at transit vs. from GBT at transit. The dashed, diagonal line represent the same value at both sites while the solid line is the difference in the geometric factor $G(\theta_z)$ between both sites. Bottom: similar to the top except that DM estimates were determined simultaneously, approximately two hours after transit at GBT so that $G(\theta_z)$ was the same at both sites.

(2013) to create an empirical model of Carrington rotationaveraged (one period is 27.2753 days) proton density as a function of heliolatitude and time spanning from 1990 to 2011. We linearly interpolate in both heliolatitude and time for smoother sampling of the proton density. Inspection of the time series from the Solar Wind Observations Over the Poles of the Sun (SWOOPS⁵) experiment on the *Ulysses* spacecraft show that $n_e \sim n_p$, which we will assume to obtain the electron density at 1 au, $n_0(\beta_h, t)$ (Bame et al. 1992). The model assumes an $n_e \propto r^{-2}$ dependence, which is supported elsewhere in the literature (e.g., Issautier et al. 1998). Therefore, we can write the solar wind DM in the direction of the pulsar as

$$DM_{sw}(t, \beta_h) = 4.848 \times 10^{-6} \text{ pc cm}^{-3}$$
$$\times \int \left(\frac{n_0(\beta_h, t)}{\text{cm}^{-3}}\right) \left(\frac{1 \text{ au}}{r}\right)^2 ds, \qquad (60)$$

where the integration path $s = s(\beta_h, r)$. We limit the integration to within 100 au of the Sun. The typical solar wind speed is of the order of several hundred kilometers per second, and so the propagation time to the integration boundary is of the order of one year (Sokół et al. 2013). However, because of the r^{-2} factor, only the electron density within the inner ≤ 10 au contributes to any currently measurable DM variation, which has a propagation time of approximately one Carrington rotation. Since the intrinsic time-averaging with the model is of this order, exclusion of the time-varying mean speeds of the electrons should not greatly affect our results. We note that Equation (60) only accounts for the average behavior of the solar wind over Carrington rotations and does not include components from transient events such as solar flares or coronal mass ejections.

Figure 12 shows the model solar wind DM and the ionospheric DM from the NeQuick 2 model along the LOS to J1909–3744. For the ionospheric component, we set the observation during pulsar transit once per month. Again, the

⁵ http://spdf.sci.gsfc.nasa.gov/pub/data/ulysses/plasma/swoops/ion/ hires/

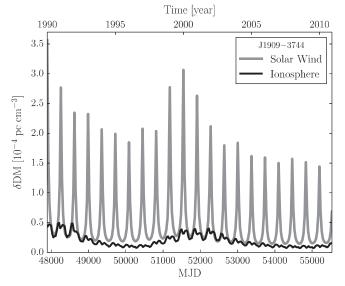


Figure 12. Comparison between the solar wind and ionospheric DM variations, the latter as computed by the NeQuick 2 model.

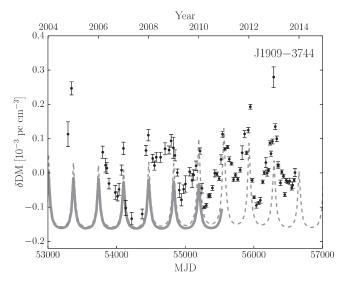


Figure 13. Time series of DM for J1909–3744 from NG9 after a weighted, quadratic trend has been removed as in Figure 1. The solid gray line shows the model $DM_{sw}(t)$ from Figure 12 with an arbitrary vertical offset added. The dashed gray line shows the model shifted forward in time by 11 years (one average solar cycle) to provide a comparison of the periodicity and shape of the model time series with the data at later times.

median error on DM for J1909–3744 measured with GBT is $\sim 1 \times 10^{-5} \,\mathrm{pc} \,\mathrm{cm}^{-3}$, which implies that the ionospheric contribution is marginally detectable in the time series, whereas the solar wind contribution is significantly measurable. Figure 13 shows the predicted solar wind contribution plotted against the J1909–3744 time series with the best-fit quadratic trend removed for clarity. The vertical offset of the predicted time series was set arbitrarily to roughly match the DM offsets (as the nominal DM has already been removed). Even without including transient solar events, our model agrees with the overall periodic trend in the time series, both in the phase and peakedness of the yearly maxima.

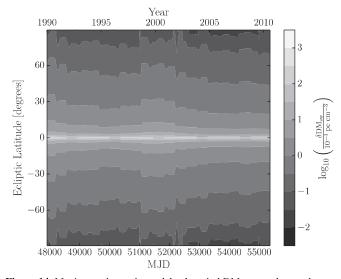


Figure 14. Maximum change in model solar wind DM centered around a oneyear smoothing window at each given epoch for a pulsar at a given ecliptic latitude.

Figure 14 shows the peak-to-peak change in the DM contribution from the solar wind model in a given one-year smoothing window as a function of ecliptic latitude. Pulsars lying closer to the ecliptic plane will have a much greater peak DM since the LOS will cross near the Sun and the electron-density scales as r^{-2} . Pulsars observed far out of the plane will show minimal amounts of solar wind DM variations. For reference, J1909–3744 has $\beta_e \approx -15^{\circ}.2$ with a mean peak-to-peak change around $1.45 \times 10^{-4} \text{ pc cm}^{-3}$, which can also be seen as the predicted amplitude of variations in Figure 13.

8.3. Heliosphere

Particles comprising the solar wind interact with the surrounding ISM at the heliospheric boundary. As the Sun moves through the ISM, it creates a bow shock toward the nose (upwind) direction with a long tail opposite the direction of the solar system's motion. Turbulence generated at the interface creates spatial and temporal variations in electron density. In general, the DM for a specific LOS can be written as

$$DM_{hel}(t, \beta_e, \lambda_e) = \int n_{e,hel}(s(t, \beta_e, \lambda_e), t) ds, \qquad (61)$$

where (λ_e, β_e) are the ecliptic longitude and latitude. The path *s* depends on the position of the Earth in its orbit. For reference, the nose direction of the heliosphere is roughly $(\lambda_e, \beta_e) \approx (254^\circ, 5^\circ)$ (Kurth & Gurnett 2003), which is equivalent to $(\alpha_e, \delta_e) \approx (253^\circ, 3, -17^\circ, 5)$ or $(l_g, b_g) \approx (2^\circ, 6, 16^\circ, 4)$.

Opher et al. (2015) simulate the heliosphere region extending from 30 to 1500 au. They assume a spherically symmetric solar wind flow at the inner boundary with a given speed, number density, and temperature, along with a radial and azimuthal solar magnetic field. The outer boundary interacts with the ISM and also has a relative velocity, number density, and temperature. The interstellar magnetic field is slanted with respect to the downwind direction. They find that the solar magnetic field forces the solar wind plasma into jets which are then blown into the tail direction by the interstellar wind. Turbulent instabilities form into two tails and the

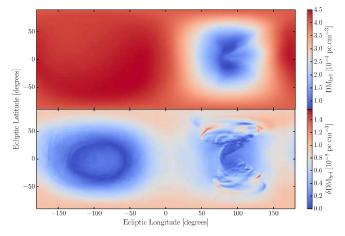


Figure 15. Top: map of $DM_{hel}(\lambda_e, \beta_e)$. The nose direction is in the center of the left half of the image, whereas the tail direction is in the center of the right half. Bottom: maximum change in DM due to Earth's orbital motion around the Sun. Note the different scales between the two panels. The thin, ringed structures visible in the nose direction (not the broad ringed structure) are a result of sampling errors in the 3D grid.

heliosphere retains a two-lobed structure as the tails remain separated.

Figure 15 shows the electron density from simulations in Opher et al. (2015) integrated out to a distance of 1500 au from the Sun. The heliosphere is several times denser through the bow shock region in the nose direction than through the tail direction. The bottom panel shows the peak-to-peak variations in DM due to the changing LOS from Earth orbiting the Sun to the stationary pulsar. The maximum change is $\sim 10^{-8} \,\mathrm{pc} \,\mathrm{cm}^{-3}$ when looking at turbulence through the tail. The effect of the heliosphere, therefore, is approximately three orders of magnitude smaller than the current sensitivity (for J1909–3744 in NG9) and requires ~0.05 ns timing precision to measure. While the heliosphere does change over time, the overall structure remains similar. Since the crossing time for solar wind particles through the heliosphere is of the order of years, changes in the electron density along a given LOS will be small from epoch to epoch. Given that the overall amplitude of the heliospheric DM is below the current sensitivity to DM, we do not consider temporal variations in the heliosphere.

8.4. Gaussian Plasma Lens in the ISM

Using the formalism in Section 6, we simulate a Gaussian, electron-density cloud and solve Equation (51) to trace incident rays back from Earth to the pulsar. We show an example calculation of the ray paths through a cloud with central column density $N_0 = 0.01 \,\mathrm{pc} \,\mathrm{cm}^{-3}$ and size a = 1 au in Figure 16. The pulsar is at a distance of 1 kpc and the cloud is halfway in between.

We numerically integrate through our example cloud and show the delays in the top right panel of Figure 16. The bottom right panel shows the DM delay purely as the integral of the electron density along the ray path (i.e., proportional to $\Delta t_{\rm DM}$ alone; solid line) as well as the estimated DM when all three delays are summed together (dotted line). In our example, both the amplitude and phase change significantly.

To explore the possible parameter space of N_0 and a, we place a pulsar at (1 au, 2 au, 1 kpc), directly in line with the Gaussian cloud at (0 au, 0 au, 0.5 kpc). The Sun is located at

(1 au, -1 au, 0 kpc) with Earth orbiting in the z = 0 plane. Figure 17 shows the peak-to-peak variations in the time delays separately and then when all three are added together.

While we consider the case of the LOS crossing through a Gaussian cloud periodically, the same formalism can be applied to single crossing events (Clegg et al. 1998). Clouds with a small perpendicular velocity will cause periodic DM variations modulated by an envelope with width equal to the timescale of the cloud crossing. In general, the phase of $DM_c(t)$ can be arbitrary with respect to previously mentioned periodic contributions.

9. IMPLICATIONS FOR ISM STUDY AND PRECISION TIMING

Analysis of DM variations can enable the study of the electron density along the entire LOS to a pulsar. While we see that the ISM is consistent with a Kolmogorov medium, interpretations of DM SFs could be used to search for a different wavenumber spectral index or anisotropies along certain LOSs. Measurements of DMs coming from an array of pulsars distributed across the sky have the potential to probe the structure of the ISM and solar wind. Changing DMs due to pulsar motion through the ISM can also be valuable inputs to large-scale electron-density models of the Galaxy.

Assuming that the only chromatic effect on pulses is the dispersive delay, DM can be estimated on a per-epoch basis using a wide range in frequency coverage. In that case, variations in DM will not affect the pulsar TOAs used for precision timing experiments. Numerous chromatic effects are, however, known to exist.

- 1. Frequency-dependent variations of the pulse profile will change the measured TOAs by a constant offset per frequency and lead to a large error in DM if not globally fit over a many-epoch data set (Liu et al. 2012; Pennucci et al. 2014). Profile evolution is assumed to be time-independent in many pulsars (see Lyne et al. 2010 for counterexamples). A simultaneous fit over parameters that describe the profile evolution and the DM will reduce their covariance. Profile evolution coupled with amplitude modulation from interstellar scintillation will cause an effective shift in the reference frequency that changes the estimated DM on the order of a diffractive timescale.
- 2. Estimates of DM will be contaminated by other chromatic timing effects that result from refraction and multi-path propagation. As shown by Foster & Cordes (1990), if refraction is allowed to contaminate DM estimates, then the SF will show excess amplitude over long times compared to extrapolation from the diffraction timescale and will also lead to an overestimated wavenumber spectral index. Multipath propagation causes temporal broadening of the pulse shapes that increase with lower frequency. Pulse broadening will couple with intrinsic profile shape changes, adding additional time-dependent TOA errors, and thus producing apparent DM changes (Levin et al. 2016).
- 3. Scattering causes spatial averaging over the ISM in any single-epoch measurement of DM (Cordes et al. 2015). DM is therefore a function of frequency.
- 4. DM measured with asynchronous multi-frequency measurements will be mis-estimated because the LOS integral

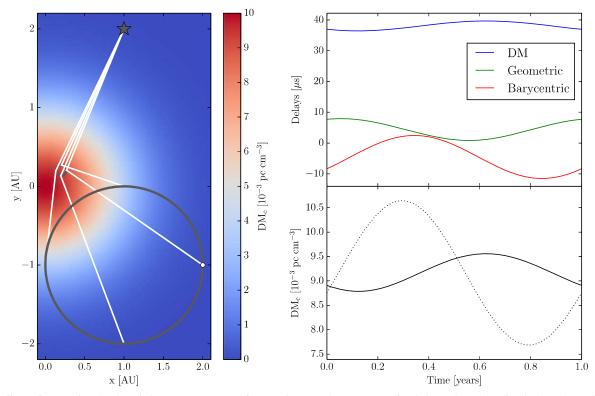


Figure 16. Effects of a Gaussian cloud on timing measurements. Left: example ray-tracing geometry of emission (where the *z*-direction has been collapsed in the image) from a pulsar (gray star) located at (1 au, 2 au, 1 kpc) traveling through a cloud with $N_0 = 0.01 \text{ pc cm}^{-3}$ and a = 1 au located at (0 au, 0 au, 0.5 kpc) hitting Earth in an orbit centered around the Sun located at (1 au, -1 au, 0 kpc). The orbit of Earth (large gray circle, t = 0 yr is given by the white dot) is in the plane of the image (i.e., z = 0 AU at all times). The background colors represent the column density profile of the cloud. The smaller gray circle drawn over the cloud represents the sampling of the cloud screen due to Earth's orbital motion and the position of the pulsar. We integrate at points over the entire orbit; four rays (white lines) have been shown to demonstrate the integration paths from the pulsar to Earth. Top right: the three delays Δt_{DM} (blue), Δt_{geo} (green), and Δt_{bary} (red) in order from top to bottom. Bottom right: DM due solely to the integral of electron density over the ray paths (solid) as compared with the measured DM when all three delays are summed together (dotted).

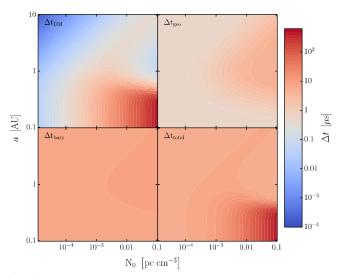


Figure 17. Timing delays associated with a refraction due to a Gaussian plasma lens as a function of N_0 and *a*. Top left: dispersion delay Δt_{DM} . Top right: geometric delay Δt_{geo} . Bottom left: barycentric delay Δt_{bary} . Bottom right: sum of all three delays. The amplitude of the timing delays typically increases toward the bottom right.

will change due to stochastic changes in the ISM and to systematic effects such as the increasing Earth-pulsar distance (Lam et al. 2015).

5. Even simultaneous measurements from different locations on Earth can result in different observed values of DM due to separate LOSs through the ionosphere.

High-precision timing experiments require the minimization of all possible TOA errors, especially those correlated in time. Therefore, the combination of data from multiple telescopes will require care to avoid contamination from the various achromatic effects listed.

The inclusion of DM terms that describe linear or periodic variations can reduce the number of model parameters in a timing fit but will also be highly covariant with other parameters included in the fit (Splaver et al. 2005). Linear terms for DM evolution in a timing model are covariant with pulsar spin and spin-down parameters. In a pulsar timing array experiment intended to detect and study GWs, such terms also remove sensitivity to the lowest-frequency GWs. Annual and semi-annual variations will be covariant with astrometric parameters and GWs with the same frequencies.

The removal of frequency-dependent terms in a timing model other than the DM, such as profile evolution parameters or scattering delays, will change the absolute DM measured. The absolute differences must be taken into account when combining DM measurements obtained by different methods; TOAs incur additional errors otherwise. In addition, even with the same frequency-dependent terms included, different methods exist for DM estimation and removal from TOAs. Keith et al. (2013) utilize information regarding the correlations between epochs in their DM determination; Demorest et al. (2013) do not. Since DM is not independent from epoch to epoch, timing models should account for the correlations between measurements. However, due to the stochastic component of the DM variations, it may be impossible to completely remove per-epoch DM determination from a timing model. Optimal DM estimation and removal strategies are therefore necessary to minimize TOA uncertainties.

10. SUMMARY AND CONCLUSIONS

DM time series show a wide range of correlated variations. We model the possible contributions to DM variations as the sum of systematic and stochastic effects along the LOS through the media between the observatory and the pulsar. Linear trends arise from the average motion of the LOS through the ISM, and the full three-dimensional (3D) motion of the pulsar should be taken into consideration when studying linear trends in DM time series. Disentangling the effects of changing distance and changing LOS from parallel and transverse motion, respectively, is possible if scintillation parameters (including flux density) are also measured. The change in distance over a few years will have no effect on these parameters, whereas transverse gradients in the ISM density will.

Changes in the LOS due to Earth's annual motion, coupled with a variety of effects that will be weighted differently for different pulsars, result in periodic variations in DM. Any DM contribution from the ionosphere, solar wind, or heliosphere will be correlated across pulsars depending on their sky positions and the relative position of the Sun. The relative phases of the three contributions may be misaligned, again depending on the specific positions of the pulsars, and so it is possible to disentangle the effects for a subset of pulsars. In the case of the ionosphere, the periodicity may be semi-annual. In general, both types of variations, linear and periodic, will contrbute to DM time series, along with a stochastic component resulting from the turbulent ISM. The relative importance of each component can only be determined on a pulsar-by-pulsar basis.

SFs are useful statistics for analyzing DM variations. DM time series will generally include systematic trends along with stochastic variations from density variations on a wide range of scales (e.g., Kolmogorov-like variations). The stochastic term can be contaminated by any systematic trend in the time series, and so time series should be de-trended before using DM(t) to infer the properties of the ISM along the LOS. Estimates of the wavenumber spectral index or the scintillation timescale from the SF should also include realization errors. We show that once the linear trends and realization errors are taken into account, PSRs J1909–3744, B1937+21, and B1821–24 show time series consistent with a Kolmogorov electron-density wavenumber spectra. PSR B1534+12, with its non-monotonic trends in DM, is inconsistent with a simple Kolmogorov ISM.

Decomposition of DM time series into known, deterministic causes will allow for the study of the local and interstellar electron density. Future studies of DM time series should model known components to further probe the relative contributions of DM fluctuations along the LOS. Pulsars in a pulsar timing array with many LOSs will see correlated DM variations from the ionosphere and solar wind. As we have shown with J1909–3744, we can probe the local electron

density around a pulsar after careful determination of its radial velocity.

Differences in DM correction methods will become increasingly important in the near future. Optimal correction methods must be implemented for the proper combination of multitelescope data. By appropriately removing the effects of DM variations from TOAs, we will be able to maximize pulsar timing array sensitivity.

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APPENDIX A FUNCTIONAL FORMS FOR STRUCTURE FUNCTIONS OF A POWER-LAW WAVENUMBER SPECTRUM

We will consider the relationships between different SFs of a time-varying DM(t). By taking the Fourier transform of the first-order increment $\Delta^{(1)}$ DM(t, τ) = DM(t) – DM(t + τ), we can write the ensemble-averaged SF in terms of the power spectrum $S_{\text{DM}}(f)$ (see Equation (15) of Lam et al. 2015),

$$D_{\rm DM}^{(1)}(\tau) = \langle [\Delta^{(1)} \rm DM(t, \tau)]^2 \rangle$$

= 4 \int df \S_{\rm DM}(f) \sin^2(\pi f\tau). (62)

A wavenumber spectrum (Equation (17)) with spectral index β will be a red noise process DM(*t*) with an associated powerlaw spectrum that scales as $S_{\text{DM}}(f) = Af^{-\gamma}$, where $\gamma = \beta - 1$ and *A* is a spectral coefficient. For a wavenumber spectrum in the scintillation regime (2 < β < 4, 1 < γ < 3), the integral can be solved as

$$4A \int_0^\infty df f^{-\gamma} \sin^2(\pi f \tau)$$

= $-2A\Gamma(-[\gamma - 1])\cos\left(\frac{\pi [\gamma - 1]}{2}\right)(2\pi \tau)^{\gamma - 1},$ (63)

where Γ is the Gamma function (Gradshteyn et al. 2007, Equation (3.823)). We can relate the spectral coefficient A to

the scintillation timescale Δt_{ISS} by equating this to Equation (23),

$$A = -\frac{\nu^2}{2(cr_e)^2 \Gamma(-[\gamma - 1]) \cos{(\pi [\gamma - 1]/2)} (2\pi \Delta t_{\rm ISS})^{\gamma - 1}}.$$
(64)

Therefore, a Kolmogorov wavenumber spectrum with $\beta = 11/3$ and a time-series power-law spectral index of $\gamma = 8/3$ will have an SF equal to

$$D_{\rm DM}^{(1)}(\tau) = A\Gamma(-5/3)\sqrt{3} (2\pi\tau)^{5/3}$$
(65)

with

$$A = -\frac{\nu^2}{(cr_e)^2 \Gamma(-5/3) \sqrt{3} (2\pi \Delta t_{\rm ISS})^{5/3}},$$
 (66)

which reduces to Equation (25) when combined. In general, the scintillation timescale will vary with frequency as $\Delta t_{\rm ISS} \propto \nu^{2/(\beta-2)}$, so that the SF, proportional to $\nu^2 [\Delta t_{\rm ISS}(\nu)]^{-(\beta-2)}$, will always be independent of frequency in the scintillation regime (2 < β < 4; Lam et al. 2015).

Following a similar procedure using the second-order increment

 $\Delta^{(2)}$ DM (t, τ) =DM $(t - \tau) - 2$ DM(t)+DM $(t + \tau)$, the second-order SF can be written as (Equation (21) of Lam et al. 2015)

$$D_{\rm DM}^{(2)}(\tau) = \left\langle [\Delta^{(2)} \rm DM(t, \tau)]^2 \right\rangle$$
$$= 16 \int df S_{\rm DM}(f) \sin^4(\pi f \tau). \tag{67}$$

Using trigonometic identities, we can write $\sin^4(\theta) = \sin^2(\theta) - (1/4)\sin^2(2\theta)$ and then solve using similar integrals to before. The second-order SF can then be related to the first-order SF for a power-law spectrum

$$D_{\rm DM}^{(2)}(\tau) = -(8 - 2^{-\gamma})A\Gamma(-(\gamma - 1))\cos\left(\frac{\pi(\gamma - 1)}{2}\right) \times (2\pi\tau)^{\gamma - 1} = (4 - 2^{\gamma - 1})D_{\rm DM}^{(1)}(\tau),$$
(68)

which is roughly $0.8252D_{DM}^{(1)}(\tau)$ for the Kolmogorov case. This is equal to the variance of the second-order increments, $\sigma_{\Delta^{(2)}DM}^2(\tau)$. Thus, for a pulsar with scintillation timescale $\Delta t_{ISS}(\nu)$ measured at frequency ν , the second-order increments at a given τ will be drawn from a Gaussian distribution with standard deviation

$$\sigma_{\Delta^{(2)}\text{DM}}(\tau) = [D_{\text{DM}}^{(2)}(\tau)]^{1/2} = \sqrt{4 - 2^{\gamma - 1}} [D_{\text{DM}}^{(1)}(\tau)]^{1/2}$$
$$= \sqrt{4 - 2^{\beta - 2}} \left(\frac{\nu}{cr_{e}}\right) \left[\frac{\tau}{\Delta t_{\text{ISS}}(\nu)}\right]^{(\beta - 2)/2}.$$
(69)

While Equation (30) has the variance of DM(t) equal to half the DM SF, we note that the variance of the DM increments will be equal to the SF only, which is defined as the expectation value of the square of the increments.

APPENDIX B STRUCTURE FUNCTION SLOPE MIS-ESTIMATION FROM ADDITIVE NOISE

The presence of additive noise will also bias the slope α of a power-law SF, $D_x(\tau) = C\tau^{\alpha}$, for a time series x(t). Assuming for now that a linear trend has been removed, since the SFs listed above all have the same slope for a Kolmogorov medium, we let y(t) = x(t) + n(t) be the measured values of a generic, random process, where x(t) is the random process of interest (e.g., DM variations) and n(t) is the measurement error with rms σ_n . The SF of y(t) is then

$$D_{y}(\tau) = (1 - \delta_{\tau 0}) 2\sigma_{n}^{2} + D_{x}(\tau)$$
(70)

where $\delta_{\tau 0}$ is the Kronecker delta. The slope of the SF of y might be used as an estimate for α . For $\tau > 0$, it can be shown that the estimated slope is

$$\hat{\alpha} = \frac{d \ln D_y(\tau)}{d \ln \tau} \equiv \frac{\tau}{D_y(\tau)} \frac{d D_y(\tau)}{d \tau}$$
$$= \alpha \left[\frac{\tau C \tau^{\alpha - 1}}{D_y(\tau)} \right] = \frac{\alpha}{1 + 2\sigma_n^2 / D_x(\tau)}.$$
(71)

Therefore, we see that α is always underestimated if the additive noise contribution to the SF is significant. One method for mitigating the bias is to use a model for the SF that includes a constant term, $\hat{D}_y(\tau) = c\tau^a + b$, where estimates of the three parameters of the least-squares fit would correspond to α , $2\sigma_n^2$, and *C*. It is better to perform the fit in log–log space because the dynamic ranges of τ and $D_y(\tau)$ can be large. The estimated slope $\hat{\alpha}$ will take a more complicated form if the linear trend has not been removed.

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