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Estimating Population Exposure to Fine Particulate Matter in the Conterminous U.S. using Shape Function-based Spatiotemporal Interpolation Method

A County Level Analysis

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Abstract — This paper investigates spatiotemporal interpolation methods for the application of air pollution assessment. The air pollutant of interest in this paper is fine particulate matter PM_{2.5}. The choice of the time scale is investigated when applying the shape function-based method. It is found that the measurement scale of the time dimension has an impact on the quality of interpolation results. Based upon the result of 10-fold cross validation, the most effective time scale out of four experimental ones was selected for the PM_{2.5} interpolation. The paper also estimates the population exposure to the ambient air pollution of PM_{2.5} at the county-level in the contiguous U.S. in 2009. The interpolated county-level PM2.5 has been linked to 2009 population data and the population with a risky PM_{2.5} exposure has been estimated. The risky PM_{2.5} exposure means the PM_{2.5} concentration exceeding the National Ambient Air Quality Standards. The geographic distribution of the counties with a risky PM_{2.5} exposure is visualized. This work is essential to understanding the associations between ambient air pollution exposure and population health outcomes.

Keywords- spatiotemporal interpolation, fine particulate matter, air pollution exposure, time scale

I. INTRODUCTION

Spatial interpolation methods have been well developed to estimate values at unknown locations based upon values that are spatially sampled in GIS (Geographic Information Systems). These methods assume a stronger correlation among points that are closer than those farther apart. They are characterized as either deterministic or stochastic depending on whether statistical properties are utilized. Deterministic interpolation methods determine an unknown value using mathematical functions with predefined parameters such as distances in Inverse Distance Weighting (IDW) [1], areas and volumes in shape function (SF) based methods [2-5], while stochastic interpolation methods such as Kriging [6, 7], investigate the spatial autocorrelation. Xingyou Zhang, James B. Holt Centers for Disease Control and Prevention Atlanta, GA, U.S.A. gyx8@cdc.gov, jgh4@cdc.gov

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Although spatial interpolation methods have been adopted in various applications, many critical problems remain unsolved. One of them is that traditional GIS researchers tend to treat space and time separately when interpolation needs to be conducted in the continuous space-time domain. The primarily strategy identified from the literature is to reduce spatiotemporal interpolation problems to a sequence of snapshots of spatial interpolations [8]. In order to interpolate for an unmeasured time instance, temporal interpolation can then be conducted based on the spatial interpolation results at each location [9].

A. Motivation

Integrating space and time simultaneously is anticipated to yield better interpolation results than treating them separately for certain typical GIS applications. For example, the following set of ozone data collected 8 annual ozone concentration measurements in 1994, 4 in 1995, 3 in 1996, 6 in 1997, and 8 in 1998, as shown by the solid circular dots in Fig. 1. Suppose we need to estimate the ozone concentration at the location illustrated by the empty dot W in 1996. The traditional strategy can only utilize the existing measurements at the locations A, B and C in 1996 to interpolate the ozone concentration at the location W, although A, B and C are rather far away from W. It would be inappropriate to use the ozone concentrations around the San Francisco area to interpolate the concentrations for New York, even if they were from the same time instance.

Therefore, a more integrative research framework that allows us to incorporate measurements from other years in the interpolation for the space-time point W needs to be developed. Depending on the characteristics of various spatiotemporal interpolation methods, different groups of measurements may be chosen to interpolate for W. One possibility would be choosing F and G in 1997 and D and E in 1995 since these four points are relatively closer to W in space and time. In general, spatiotemporal interpolation is based on the assumption: things that are closer in the space-time domain are more alike than those that are farther apart.

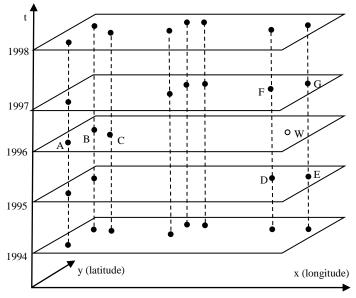


Figure 1. Annual ozone concentration sample points from 1994 to 1998. The solid circular dots (\bullet) are the points with known measurements, while the empty dot (o) is unmeasured and needs to be interpolated for 1996.

B. Existing Approach and Its Limitation

In order to integrate space and time simultaneously, a so called "extension approach" has been proposed in [4, 10]. This approach treats time as another dimension in space and therefore extending the spatiotemporal interpolation problem into a higher-dimensional spatial interpolation problem. Some applications using the extension approach can be found in [3, 11-13].

Although the idea of the extension approach is intriguing, extending spatial interpolation to incorporate a dimension of time poses many challenges. One of the biggest challenges is that space and time have different and incomparable scales. The physically sound distance in a space-time domain is therefore difficult to define or compute. For example, how would you define the spatiotemporal distance between two points P_1 (x_1 , y_1 , t_1) and P_2 (x_2 , y_2 , t_2) when the extension approach of IDW is applied? This challenge has been rarely investigated and impedes to a very large degree the development of a more generalized and logically sound approach of spatiotemporal interpolation. The existing practice used in references [3, 11, 12] is to choose some convenient scales coming from the raw GIS data.

C. Contributions

There are two main contributions of our paper. The first contribution is to examine whether the choice of time scale affects the quality of SF (Shape Function) based spatiotemporal interpolation results. SF-based 2-D triangular interpolation methods are proven to be invariant to coordinate scales [3]. However, in reference [3], the authors did not realize that the invariance is only true after the mesh is constructed. Mesh generation is the foundation of SF-based interpolation methods.

It divides the total domain into a finite number of simple subdomains that can be triangles in the case of 2-D problems and tetrahedra in the case of 3-D problems. However, will a different choice of time scale (e.g. month or day) influence the construction of a mesh and thereafter the performance of a spatiotemporal interpolation? According to our knowledge, this is a topic that has been rarely investigated.

The second contribution is to set an important initial step to investigate the associations between ambient air pollution exposure and population health outcomes. Since $PM_{2.5}$ concentrations are only measured at certain monitoring sites and time instances, the $PM_{2.5}$ concentrations at unsampled locations and times need to be estimated using an effective method. In this paper, an efficient 3-D SF-based spatiotemporal interpolated county-level $PM_{2.5}$ has been linked with 2009 population data and the population with a risky $PM_{2.5}$ exposure has been estimated. The geographic distribution of the counties exceeding the $PM_{2.5}$ air quality standards is displayed.

II. SF-BASED SPATIOTEMPORAL INTERPOLATION AND ITS INVARIANCE AND VARIANCE TO COORDINATE SCALES

Shape functions, which can be viewed as a spatial interpolation method, are popular in engineering applications such as finite element algorithms [14, 15]. There are various types of 2-D and 3-D shape functions. We are interested in 2-D shape functions for triangles and 3-D shape functions for tetrahedra, both of which are linear approximation methods. Shape functions have been adopted and further developed as spatiotemporal interpolation methods for GIS applications [3, 16, 17]. Reference [3] also describes IDW and Kriging based spatiotemporal interpolation methods and compares them to SF-based methods by using an actual real estate data set with house prices. SF-based spatiotemporal interpolations including air quality mapping [11, 12] and many others [18-20].

A. SF-based Spatiotemporal Interpolation: A Review

At the beginning stage of applying SF-based interpolation methods, a mesh that divides the total domain into a finite number of simple sub-domains or elements should be generated. For example,

- for a 2-D spatial problem, a mesh composed of triangular elements should be generated if one wants to use shape functions for triangles to interpolate unknown values in the (x, y) coordinate system;
- for a 3-D spatial problem, a mesh composed of tetrahedral elements should be generated if one wants to use shape functions for tetrahedra to interpolate unknown values in the (x, y, z) coordinate system.

Quite successful algorithms have been developed to generate triangular or tetrahedral meshes, including the popular method of Delaunay triangulation meshing [21, 22]. Delaunay triangulation is related to the construction of the so called "Voronoi diagram", which is related to "Convex Hull" problems. The techniques to compute 2-D Delaunay triangulations can be extended to create 3-D tetrahedral meshes. Fig. 2 shows a tetrahedron.

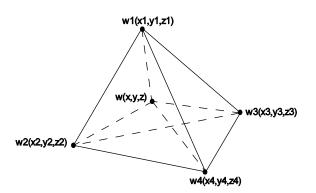


Figure 2. Computing 3-D shape functions by tetrahedral volume divisions. w_1 , w_2 , w_3 and w_4 are measured values, while the value w at location (x, y, z) is unmeasured and needs to be interpolated.

Considering the tetrahedron in Fig. 2, the SF-based interpolation result at a point (x, y, z) located inside the tetrahedron can be obtained by using the measurement values w_1 , w_2 , w_3 , and w_4 at the four corners as below [3]:

$$w(x, y, z) = N_1(x, y, z)w_1 + N_2(x, y, z)w_2 + N_3(x, y, z)w_3 + N_4(x, y, z)w_4$$
(1)

where N1, N2, N3 and N4 are the following shape functions

$$N_{1}(x, y, z) = \frac{V_{1}}{V}, N_{2}(x, y, z) = \frac{V_{2}}{V},$$

$$N_{3}(x, y, z) = \frac{V_{3}}{V}, N_{4}(x, y, z) = \frac{V_{4}}{V}$$
(2)

 V_1 , V_2 , V_3 , and V_4 are the volumes of the four sub-tetrahedra $ww_2w_3w_4$, $w_1ww_3w_4$, $w_1w_2ww_4$, and $w_1w_2w_3w$, respectively; and V is the volume of the outside tetrahedron $w_1w_2w_3w_4$ as shown in Fig. 2.

Our paper focuses on spatiotemporal interpolation problems in the domain of 2-D space and 1-D time. Using the extension approach of SF-based interpolation methods, we treat time as the imaginary third dimension z in space. Therefore, substituting the z variable by the time variable t in (1) and (2) gives a SF-based spatiotemporal interpolation method for 2-D space and 1-D time problems:

$$w(x, y, t) = N_1(x, y, t)w_1 + N_2(x, y, t)w_2 + N_3(x, y, t)w_3 + N_4(x, y, t)w_4$$
(3)

where N_1 , N_2 , N_3 and N_4 are the following shape functions

$$N_1(x, y, t) = \frac{V_1}{V}, N_2(x, y, t) = \frac{V_2}{V}, N_3(x, y, t) = \frac{V_3}{V}, N_4(x, y, t) = \frac{V_4}{V}$$
(4)

Extending spatial interpolation to incorporate a dimension of time using the SF-based interpolation method has shown promising results compared with the extension methods based on IDW and Kriging [3, 12]. The challenge of mixing incomparable scales of space and time has been investigated in [3]. It has been proven that the SF-based 2-D triangular interpolation method is invariant to coordinate scales. However, the invariance only holds after the mesh is generated. From the application point of view, one often needs to decide coordinate scales before meshing, especially the time scale for spatiotemporal interpolation. There is a lack of literature investigating the metrical integration of space and time prior to the mesh construction. For the rest of this section, we first show the proof of the invariance to coordinate scales of 3-D tetrahedral shape functions after meshing. Then we investigate its variance to coordinate scales before meshing.

B. Invariance to Coordinate Scaling After Meshing

Lemma 1. 3-D tetrahedral shape functions are invariant to coordinate scaling after the mesh construction.

Proof. Similar as the proof for 2-D triangular shape functions in [3], we obtain a proof for the invariance of 3-D tetrahedral shape functions to coordinate scaling after meshing as below.

Since it is assumed that coordinate scaling happens after the mesh is constructed, each tetrahedron in the mesh has the same set of corner vertices before and after coordinate scaling. For a given tetrahedron, comparison can be made for the value of $N_I(x, y, t)$ in (3) and (4) before and after coordinate scaling. We first calculate the results of V_1 , V_2 , V_3 , and V_4 in (4) using the coordinates of the corner vertices. Then we have

$$N_1(x, y, t) =$$

$$\begin{bmatrix} x_2 y_3 t_4 - x_2 y_4 t_3 - x_3 y_2 t_4 + x_3 y_4 t_3 + x_4 y_2 t_3 - x_4 y_3 t_3 + (-y_3 t_4 + y_4 t_3 + y_2 t_4 - y_4 t_2 - y_2 t_3 + y_3 t_2) x + (-x_2 t_4 + x_2 t_3 + x_3 t_4 - x_3 t_2 - x_4 t_3 + x_4 t_2) y + (-x_2 y_3 + x_2 y_4 + x_3 y_2 - x_3 y_4 - x_4 y_2 + x_4 y_3) t \end{bmatrix} \div \\ \begin{bmatrix} (x_2 y_3 t_4 - x_2 t_3 y_4 - x_3 y_2 t_4 + x_3 t_2 y_4 + x_4 y_2 t_3 - x_4 t_2 y_3 - x_1 y_3 t_4 + x_1 t_3 y_4 + x_3 y_1 t_4 - x_3 t_1 y_4 - x_4 y_1 t_3 + x_4 t_1 y_3 + x_1 y_2 t_4 - x_1 t_2 y_4 - x_2 y_1 t_4 + x_2 t_1 y_4 + x_4 y_1 t_2 - x_4 t_1 y_2 - x_1 y_3 t_3 + x_1 t_2 y_3 + x_2 y_1 t_3 - x_3 t_1 y_4 - x_3 t_1 y_4 + x_1 t_2 y_3 + x_2 y_1 t_3 - x_3 t_1 y_4 + x_2 t_1 y_4 + x_4 y_1 t_2 - x_4 t_1 y_2 - x_1 y_3 t_3 + x_1 t_2 y_3 + x_2 y_1 t_3 - x_3 t_1 y_4 - x_3 t_1 y_2) \end{bmatrix}.$$

Assume that the *t* dimension enlarges to *n* times of the original scale. Then N_1 will be calculated as b after the scaling

$$\begin{split} \dot{N_{1}}(x, y, t) &= \\ & [nx_{2}y_{3}t_{4} - nx_{2}y_{4}t_{3} - nx_{3}y_{2}t_{4} + nx_{3}y_{4}t_{3} + nx_{4}y_{2}t_{3} - nx_{4}y_{3}t_{3} + (-ny_{3}t_{4} + ny_{4}t_{3} + ny_{2}t_{4} - ny_{4}t_{2} - ny_{2}t_{3} + ny_{3}t_{2})x + (-nx_{2}t_{4} + nx_{2}t_{3} + nx_{3}t_{4} - nx_{3}t_{2} - nx_{4}t_{3} + nx_{4}t_{2})y + (-x_{2}y_{3} + x_{2}y_{4} + x_{3}y_{2} - x_{3}y_{4} - x_{4}y_{2} + x_{4}y_{3})nt] \\ & \div \\ & [(nx_{2}y_{3}t_{4} - nx_{2}t_{3}y_{4} - nx_{3}y_{2}t_{4} + nx_{3}t_{2}y_{4} + nx_{4}y_{2}t_{3} - nx_{4}t_{2}y_{3} - nx_{1}y_{3}t_{4} + nx_{1}t_{3}y_{4} + nx_{3}y_{1}t_{4} - nx_{3}t_{1}y_{4} - nx_{4}y_{1}t_{3} + nx_{4}t_{1}y_{3} + nx_{1}y_{2}t_{4} - nx_{1}t_{2}y_{4} - nx_{2}y_{1}t_{4} + nx_{2}t_{1}y_{4} + nx_{4}y_{1}t_{2} - nx_{4}t_{1}y_{2} - nx_{1}y_{2}t_{3} + nx_{2}y_{1}t_{3} - nx_{3}t_{1}y_{4} - nx_{3}t_{1}y_{4} - nx_{4}t_{1}y_{2} - nx_{1}y_{2}t_{3} + nx_{1}t_{2}y_{3} + nx_{2}y_{1}t_{3} - nx_{3}t_{1}y_{4} - nx_{3}t_{1}y_{2} - nx_{4}t_{1}y_{2} - nx_{1}y_{2}t_{3} + nx_{1}t_{2}y_{3} + nx_{2}y_{1}t_{3} - nx_{3}t_{1}y_{4} - nx_{3}t_{1}y_{2} - nx_{4}t_{1}y_{2} - nx_{1}y_{2}t_{3} + nx_{1}t_{2}y_{3} + nx_{2}y_{1}t_{3} - nx_{3}t_{1}y_{4} - nx_{3}t_{1}y_{2} - nx_{4}t_{1}y_{2} - nx_{1}y_{2}t_{3} + nx_{1}t_{2}y_{3} + nx_{2}y_{1}t_{3} - nx_{3}t_{1}y_{4} - nx_{3}t_{1}y_{2} - nx_{4}t_{1}y_{2} - nx_{1}y_{2}t_{3} + nx_{1}t_{2}y_{3} + nx_{2}y_{1}t_{3} - nx_{3}t_{1}y_{4} - nx_{3}t_{1}y_{4} - nx_{3}t_{1}y_{2} - nx_{1}y_{2}t_{3} + nx_{1}t_{2}y_{3} + nx_{2}y_{1}t_{3} - nx_{3}t_{1}y_{4} - nx_{3}t_{1}y_{2} - nx_{3}t_{1}y_{2} - nx_{1}y_{2}t_{3} + nx_{1}t_{2}y_{3} + nx_{2}y_{1}t_{3} - nx_{3}t_{1}y_{4} - nx_{3}t_{1}y_{4} - nx_{3}t_{1}y_{2} - nx_{1}y_{2}t_{3} + nx_{1}t_{2}y_{3} + nx_{2}y_{1}t_{3} - nx_{3}t_{1}y_{4} - nx_{3}t_{1}y_{2} - nx_{3}t_{1}y_{2} - nx_{3}t_{1}y_{3} + nx_{3}t_{1}y_{3} + nx_{3}t_{1}y_{3} - nx_{3}t_{1}y_{2} - nx_{3}t_{1}y_{2} - nx_{3}t_{1}y_{3} - nx_{3}t_{1}y_{3} + nx_{3}t_{1}y_{3} - nx_{3}t_{1}y_{3}$$

It is obvious that $N_1'(x,y,t)$ is the same as $N_1(x,y,t)$. Therefore N_1 is invariant to *t* coordinate scaling after meshing. Invariance to *x* or *y* coordinate scaling is straightforward too. Similarly, we can prove that N_2 , N_3 and N_4 in (3) and (4) are also invariant to coordinate scaling after meshing.

C. Variance to Coordinate Scaling Before Meshing

When the SF-based spatiotemporal interpolation using the extension approach is applied, an important question has been neglected in the literature: will different time scales lead to different meshes using the Delaunay triangulation method?

In order to answer this question, a simple 2-D example can demonstrate whether coordinate scales affect the mesh result:

• We first used the 76 house locations of the real estate data in [3] and generated the 2-D Delaunay triangular mesh as shown in Fig. 3.

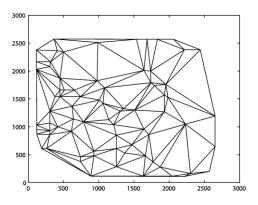


Figure 3. Delaunay triangulation result with the original coordinate scales.

• Then we double the y-coordinate and generated the new mesh as shown in Fig. 4.

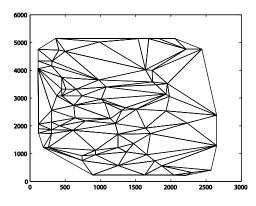


Figure 4. Delaunay triangulation result with the *y* coordinate values doubled.

It is not hard to find that the two triangulations in Figures 3 and 4 are not the same, which gives the proof to Lemma 2. In other words, the construction of a mesh is sensitive to the scales chosen for the dimensions.

Lemma 2. 3-D tetrahedral shape functions are variant to coordinate scaling before the mesh construction.

Different meshes will eventually lead to different interpolation results, because each point to interpolate may be located in different elements. Therefore, a reliable mesh constructed with an appropriate time scale is fundamental to the success of a SF-based spatiotemporal interpolation using the extension approach.

III. APPLICATION

Particle pollution (also known as "particulate matter") in the air includes a mixture of solids and liquid droplets. Such particles are either emitted directly or form in the atmosphere when other pollutants react. Particles come in a wide range of sizes. The EPA (Environmental Protection Agency) is concerned about particles that are 10 micrometers in diameter or smaller because those are the particles that generally pass through the throat and nose and enter the lungs. Ten micrometers are smaller than the width of a single human hair. Once inhaled, these particles can affect the heart and lungs and cause serious health effects. EPA groups particle pollution into two categories (http://www.epa.gov/air/particlepollution):

- Inhalable coarse particles (PM₁₀), such as those found near roadways and dusty industries, are larger than 2.5 micrometers and smaller than 10 micrometers in diameter.
- Fine particles (PM_{2.5}), such as those found in smoke and haze, are 2.5 micrometers in diameter or smaller. These particles can be directly emitted from sources such as forest fires, or they can form when gases emitted from power plants, industries and automobiles.

The data used in this study is daily $PM_{2.5}$ concentration measured in 2009 by monitoring sites over the contiguous U.S.

A. Experimental Data

The PM_{2.5} data set with measurements. The data coverage contains point locations of the monitoring sites, the daily concentration level measurements of PM_{2.5}, and the days of the measurements. We obtained a number of data sets from the U.S. EPA (http://www.epa.gov/ttn/airs/airsaqs/detaildata) and reorganized them into a data set with schema (*id*, *x*, *y*, [*time*], *w*), where x and y are the longitude and latitude coordinates of the monitoring sites, [time] is (year, month, day) when a PM_{2.5} measurement is taken, and w is the measured PM_{2.5} values. The reorganized data set has some entries with PM_{2.5} values as zero, which means no measurements available at a particular site and on a particular day. After all the zero entries are filtered out, there are 146,125 daily measurements at 955 monitoring sites, which are shown as stars (*) in Fig. 5.



Figure 5. Monitoring sites with PM2.5 measurements in 2009.

The county data set with points to interpolate. The data set with locations to interpolate are the centroids of 3,109 counties in the contiguous United States. This data set has the format of (id, x, y). The estimated $PM_{2.5}$ values at each county location and on each day in 2009 need to be computed. Therefore, there are 3,109 × 365 = 1,134,785 spatiotemporal $PM_{2.5}$ values to interpolate.

B. Applying SF-based Spatiotemporal Interpolation using an Appropriate Time Scale

When implementing SF-based spatiotemporal interpolation, it is important to decide the time scale, as discussed in the previous section. The four time scales shown in Table 1 have been tested.

TABLE I. Four times scales tested for the $PM_{\rm 2.5}$ data set.

| time | ScaleA | ScaleB (ScaleA/10) | ScaleC (ScaleA/5) | ScaleD (ScaleA/15) |
|------------|--------|-----------------------|----------------------|-----------------------|
| 01/01/2009 | 1 | 0.1 | 0.2 | 0.067 |
| 01/02/2009 | 2 | 0.2 | 0.4 | 0.133 |
| | ••• | | | |
| 12/31/2009 | 365 | 36.5 | 73 | 24.333 |

In order to decide which is the best time scale to use for interpolation, *10-fold cross validation* [23] was implemented using the following steps.

- 1. The PM_{2.5} data set with measurements was randomly split into ten nearly equally sized folds.
- 2. For each of the four time scales in Table 1, ten iterations of training and validation were performed such that within each iteration a different fold of the data was held-out for validation while the remaining nine folds were used for learning. Within each iteration, the following two actions have been taken:
 - a. The spatiotemporal points in one fold (validation fold) were interpolated using the remaining nine folds (learning folds). Each point in the validation fold had both the original $PM_{2.5}$ measurement and an estimated value, after the interpolation.
 - b. Six accuracy assessments were made to compare the original and estimated PM_{2.5} values in the validation fold: MAE (Mean Absolute Error), MSE (Mean Squared Error), RMSE (Root Mean Squared Error), MARE (Mean Absolute Relative Error), MSRE (Mean Squared Relative Error) and RMSRE (Root Mean Squared Relative Error). They are defined as follows:

$$MAE = \frac{\sum_{i=1}^{N} |I_i - O_i|}{N} \qquad MSE = \frac{\sum_{i=1}^{N} (I_i - O_i)^2}{N}$$

$$RMSE = \sqrt{\frac{\sum_{i=1}^{N} (I_i - O_i)^2}{N}} \qquad MARE = \frac{\sum_{i=1}^{N} \frac{|I_i - O_i|}{O_i}}{N}$$

$$MSRE = \frac{\sum_{i=1}^{N} \frac{(I_i - O_i)^2}{O_i}}{N} \qquad RMSRE = \sqrt{\frac{\sum_{i=1}^{N} \frac{(I_i - O_i)^2}{O_i}}{N}}$$
(5)

where N is the number of observations, Ii's are the interpolated values, and O_i 's are the original values.

3. Since there are ten iterations and a different validation fold is chosen within each iteration, for each accuracy assessment, the average of ten accuracy results has been calculated. Table 2 shows the average results of \overline{MAE} , \overline{MSE} , \overline{RMSE} , \overline{MARE} , \overline{MSRE} and \overline{RMSRE} . In Table 2, ScaleA gives different values for \overline{MSRE} and \overline{RMSRE} compared to the other scale results. ScaleB, ScaleC and ScaleD yield similar results. Since ScaleC shows the best result for \overline{MARE} , we decided to use ScaleC for our PM_{2.5} data interpolation.

TABLE II. ACCURACY ASSESSMENTS FOR THE $PM_{2.5}$ data set.

| Accuracy Assessment | ScaleA | ScaleB (ScaleA/10) | ScaleC (ScaleA/5) | ScaleD (ScaleA/15) |
|------------------------|-----------|-----------------------|----------------------|-----------------------|
| MAE | 3.1538 | 3.5621 | 3.2526 | 3.7344 |
| MSE | 77.2331 | 74.5937 | 74.7896 | 73.0842 |
| RMSE | 8.6521 | 8.4539 | 8.4200 | 8.3536 |
| MARE | 3.2384 | 0.4286 | 0.3866 | 0.4486 |
| MSRE | 5462.2800 | 35.4845 | 36.6819 | 35.1620 |
| RMSRE | 73.3605 | 3.1898 | 3.4048 | 3.2607 |

C. SF-based Interpolation Results

The SF-based interpolation for the county-level $PM_{2.5}$ data was implemented in Matlab using *ScaleC*. A total of 1,134,785 (3,109 × 365) $PM_{2.5}$ values were computed for 3,109 county centroids in the contiguous U.S. on each day in 2009.

IV. POPULATION EXPOSURE ANALYSIS

The interpolated county-level $PM_{2.5}$ was linked to 2009 county population data. The population with a risky $PM_{2.5}$ exposure was estimated. The revised EPA National Ambient Air Quality Standards for $PM_{2.5}$ in 2006 was adopted here (http://www.epa.gov/pm/standards.html):

- 35 micrograms per cubic meter (35 μ g/m³) for 24-hours,
- 15 micrograms per cubic meter (15 μ g/m³) for the annual mean.

The results from our spatiotemporal interpolation suggest:

- there is a population of 33,147,335 (33.1million) residing in counties with an annual PM_{2.5} exceeding the national standard of \$15 µg/m³ and
- more than one third of the U.S. population (111,752,669) residing in counties where PM_{2.5} exceeded 35 µg/m³ for at least one day in 2009.

Fig. 6 shows the geographic distribution of such counties with the annual and/or 24-hour $PM_{2.5}$ exceeding EPA National Ambient Air Quality Standards.

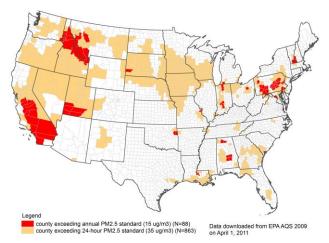


Figure 6. Geographic distribution of counties in the contiguous United States that exceeded the $PM_{2.5}$ air quality standards in 2009.

V. FUTURE WORK

First, we tested only four possible time measurement scales and chose the best one for the $PM_{2.5}$ air pollution data. A more systematic and effective method should however be developed to help decide the most appropriate time scale that should be chosen in a particular application.

Second, the use of county centroids in this study could have caused biases in county population level exposure to $PM_{2.5}$. In future studies, a finer geographic resolution, such as census block groups and tracts, may provide a more solid base for evaluating population exposure to air pollutants.

Third, it would be of great value to link air quality with population health outcomes, such as asthma and other respiratory diseases. Such future study will hopefully further support the utility of our method presented.

DISCLAIMER

The findings and conclusions in this report are those of the authors and do not necessarily represent the official position of the Centers for Disease Control and Prevention (CDC), USA.

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