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AN ASYNCHRONOUS CIRCUIT DESIGN LANGUAGE SYSTEM

## by

GREGORY MARTIN BEDNAR, 1944-

A DISSERTATION
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## ABSTRACT

This paper presents a system for specifying the behavior of asynchronous sequential circuits. The system consists of a special purpose Asynchronous Circuit Design Language (ACDL), a translator and a flow table generation algorithm. The language includes many special features which permit quick and precise specification of terminal behavior. It is best suited for problems originating from a word description of the circuit's operation. The translator is written with the XPL Translator Writing System and is a syntax-directed compilation method. From the translated ACDL specifications, the flow table algorithm generates a primitive flow table which is the required input for the conventional synthesis procedures of asynchronous sequential circuits. A thorough description of the translator and flow table programs is given in the Appendices. In addition a number of example problems illustrating the use of $A C D L$ are provided.

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## I. INTRODUCTION

A number of synthesis procedures for asynchronous sequential circuits now exist and many of these have been programmed for computer application. Although considerable work has been directed toward improving the synthesis procedures, little has been done in interfacing the user to these procedures.

This dissertation presents an Asynchronous Circuit Design Language (ACDL) system which interfaces the user to the conventional synthesis procedures of asynchronous sequential circuits as illustrated in Figure 1. ACDL is a special purpose language used to describe the terminal behavior of asynchronous sequential circuits. This description is then translated, and interpreted into a primitive flow table which is the initial input requirement of the conventional synthesis procedures.


Figure 1. The Interfacing Characteristic of ACDL

Presently, a few procedures exist for specifying asynchronous sequential circuits when the terminal characteristics of the machine are easily expressed in input/output sequences $[1,2]$. However, only a small percentage of the designs are suitable for this type of terminal description. Hence typically, the designer will hand-construct a
primitive flow table from a word statement or mental conception of the problem. This is not an easy or straightforward task since word statements and mental conceptions are informal descriptions of the problem.

After studying the specification problem for some time, it was decided that a language was needed that had the following three important characteristics:

1) it should permit ease of expression by coinciding with the designer's thinking process,
2) it should retain a formal meaning of the circuit description,
3) it should have a structure which would permit relatively easy automatic translation.

A review of all the well-known digital design languages was made to determine their applicability to the asynchronous circuit specification problem $[3-9]$. In general, it was found that these 1 anguages were intended for networks whose designs could best be described by functional operations and information transfers between basic hardware elements such as registers, switches, terminals, memory etc. None of the above languages were found to satisfy all of the desired characteristics mentioned for specifying the terminal (input/output) behavior of an asynchronous sequential circuit. Specific drawbacks of these languages included the inability to assign transition values to variables, the inability to make proper declarations such as "input constraints" and the inability to list multiple independent sequence paths without introducing additional control variables or cluttering the listing with many "go to" type statements.

ACDL was developed to meet the three important characteristics of the desired language and to overcome the drawbacks of the digital design
languages noted above. This language provides a means to satisfy the specification problem by enabling the user to express his circuit characteristics formally, so the design can be carried out automatically.

## II. ASYNCHRONOUS SEQUENTIAL CIRCUITS

Sequential circuits whose operation is not synchronized with clock pulses are called asynchronous sequential circuits. An important advantage of asynchronous sequential circuits is their ability to respond to input changes at basic device speed, rather than having to await the arrival of clocking signals. Also, many small circuits can be designed more easily and efficiently asychronously because it is not necessary to build a clock and synchronization circuitry. A further advantage of asynchronous design is seen in large circuits where signal lines are long and the skewing effect (difference in path propagation times) of the distributed clocking signals becomes a serious problem.

The operation of an asynchronous sequential circuit is often described by means of a flow table. As shown in Table I, it is a twodimensional array consisting of next-state entries with its columns representing the input states and its rows representing the internal states of the circuit. The row in which the circuit is currently operating is often referred to as the present internal state or just the present state. For example, if the present state of the circuit described by Table $I$ is 1 and then an input of $I_{2}$ is applied, the next state or state that the circuit will go to is 2 .

TABLE I. FLOW TABLE
Lnternal $2 \times$ Input states

If a next-state entry is found to be the same as the internal state representing that row, then the internal state is said to be stable with respect to that input column and is denoted by a circled next-state entry. Output states are usually only associated with stable next states as shown.

An asynchronous circuit is said to be operating in fundamental mode if the inputs are never changed unless the circuit is in a stable state. This paper only treats asynchronous circuits operating in fundamental mode. Further information on this class of circuits can be found in references [10] and [11].
A. The Conventional Design Process

The design process for asynchronous circuits can be divided into two major parts. The first part provides a formal description of the circuit's behavior such as a flow table. Based upon this formal description, the second part applies established synthesis techniques to generate the circuit design equations. These techniques include flow table reduction, internal-state assignment, hazard elimination and nextstate and output equation generation $[10,11]$.

Computer programs have made the synthesis techniques entirely automated. D. G. Raj-Karne [12] has recently programmed algorithms to provide either a Unicode Single Transition Time (USTT), Universal Totally Sequential (UTS) or combination USTT and UTS (Mixed Mode) state assignment. A flow table reduction algorithm and an algorithm to generate the static-hazard-free design equations have been programmed by R. J. Smith et al. [2,13].
B. Circuit Specification

1. Initial Descriptions

Presently, the most common initial description of a design is the English-word statement. This is an informal description that must be reworked into some type of formal description (usually a flow table). The word statement lacks total preciseness and often reflects uncertainty for many input/output conditions. An example of a typical word statement description is:

A sequential circuit is to have two inputs $A$ and $B$ and one output $Z$. $Z$ is to turn on only when $B$ turns on, provided A is already on. $Z$ is to turn off only when $B$ turns off. Only one input can change state at a time.

In some designs a word statement may be accompanied by a timing chart [14,15] to express more explicitly particular input/output sequences required of the circuit. The timing chart usually does not show all possible input/output sequences of the circuit but rather shows important sequences which may help clarify the word statement. An example of the timing chart for the above word statement is shown in Figure 2.


Figure 2. Timing Chart

## 2. Primitive Flow Table

In order to make the initial description more precise and appropriate for formal manipulation in the conventional synthesis procedures, the circuit specifications are made in the form of a flow table having exactly one stable state per row. This special table is called a primitive flow table $[10,11,14,15]$ and is illustrated in Table II for the word statement description discussed earlier.

TABLE II. PRIMITIVE FLOW TABLE

| Internal State | $A B$ |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | $00$ | 01 | 11 | 10 | Z |
| 1 | (1) | 2 | - | 3 | 0 |
| 2 | 1 | (2) | 4 | - | 0 |
| 3 | 1 | - | 5 | (3) | 0 |
| 4 | - | 2 | (4) | 3 | 0 |
| 5 | - | 6 | (5) | 3 | 1 |
| 6 | 1 | (6) | 5 | - | 1 |

In constructing the primitive flow table, first a static situation corresponding to the initial state of the circuit is defined. This is usually (but not always) the state where all inputs and outputs are zero as indicated by stable state 1 in Table II. When operating in the initial stable state, the remaining next-state entries for row 1 are completed. Dash entries represent illegal input transitions which are later used in the synthesis as don't-cares. The dash in row 1 means the input transition 00 to 11 is illegal which agrees with the word description constraint of no inputs changing simultaneously. It isn't until state

5 is reached via state 3 that the output is set which concurs with the word description for setting $Z$.

For practice, the inexperienced reader should verify the remaining rows of the flow table. As seen from this example, considerable thought and time is required to construct the primitive flow table.
3. Other Methods

A method of specifying asynchronous circuits using input/output (I/O) sequences which could be translated into a flow table was developed by Altman [1]. However, the inefficiency of having to repeat long specification lists of I/O pairs at branch points and the inability to describe cyclic behavior of indeterminate duration greatly restricts the use of this method.

By developing a looping and branching technique and enabling the use of don't-care specifications, Smith [2] extended Altman's method to satisfy the above deficiencies. Smith's method is based on the philosophy that independent $I / O$ sequences define submachines or modules; and when properly interconnected, these modules form the required sequential circuit. The method was primarily intended for those designs which originate from a circuit description having a set of I/O sequences and hence, is too restrictive to be a good, generalized design method. Since most designs originate from word descriptions or mental conceptions of an operative nature, listing the set of all independent I/O sequences for these designs becomes a difficult and confusing task.

A different approach to the synthesis of fundamental-mode asynchronous circuits was developed by Chuang [16] and is referred to as the transition logic synthesis method. In this method a binary level

```
transition of 0 to 1 or 1 to 0 is considered as a pulse, and the reali-
zation of the circuit is similar to the standard pulse sequential cir-
cuit synthesis method [10]. Since no distinction is made between 0 to
l and l to O transitions, the application of this method is limited to problems such as counters, where the toggling effect of the transition is of interest rather than the value of the transition's ending state. The specifications are made into an array called a transition flow table. Although the table may have fewer states than an equivalent primitive flow table, the unnatural specification method of flow table construction still exists.
```

III. A DESCRIPTION OF ACDL

This chapter contains a syntactic and semantic description of ACDL. The description begins with the lowest structural level of symbols and progresses to the higher structural levels of statements and programs. A. The Definition of a Metalanguage

To prevent any ambiguities or paradoxes in the definition of ACDL, a metalanguage which is completely distinguishable from ACDL will be used in its description. To formalize the definitions in the metalanguage, each definition is given in the form of a statement or construct, which is analogous to a formula. The metalanguage employed is Backus Normal Form (BNF) [17] and consists of the following symbols:
$\langle x\rangle$ to be read as "the object named $x$ " $::=$ to be read as "can be formed from"
| to be read as "or" (exclusive or)
The metalanguage construct takes on the following meaning: "the object named in the corner braces may be formed from the objects named or specified on the right". Concatenation of names or objects is implied by the juxtaposition of names or objects in the construct. For clarity, those characters which are to form part of $A C D L$ and the metalanguage symbols will be set in standard type while the names of objects enclosed in corner braces will be italicized.
B. Vocabulary of ACDL

1. Symbols

The set of symbols used in ACDL are defined as follows:

Binary digit>: $=0 \mid 1$

Monbinary digit>:: $=2|3| 4|51617| 8 \mid 9$
<digit>:: = <binary digit>| nonbinary digit>
<special character>::= "|/|?
$\langle$ separator $\rangle:=,|;|:|\cdot|(1)$
<eelation symbol>::= $=|->|=>$
<peplacement op>::=<-
<Logical op>::= $\rightarrow|\&|+$
The relation symbol ' $->$ ' is the transition symbol and is read as "makes a transition to', and ' $=>$ ' is the implication symbol which is read as "implies that" or "causes". The special characters have special meanings in $A C D L$, and each will be explained later in the description at the place it is used. All other symbols take on their standard interpretations [3-9], [18].
2. Constants and Identifiers

The rules for constructing constants and identifiers from the symbols of ACDL are:

```
<constant>::= <number>|<level>|<transition>
<number>::= <digit>|<number>digit>
<level>::= <binary digit>
<transition>::= <long transition> Kshort transition>
<long transition>::= 0->1|1->0
<short transition>::= ->1|->0 |->?
<identifier>::= Letter>|<identifier> Letter>|<identifier> <digit>
Circuit input variables will take on transition values as well as
level values. In many cases, both the beginning and ending states of
an input transition are important in determining the resulting output
```

level. The transition constant ' $0->1^{\prime}$ indicates a transition from 0 to 1 . The short transition is a shorthand notation for a long transition constant. For example, ' $\rightarrow 1^{\prime}$ ' and ' $->0^{\prime}$ are short for ${ }^{\prime} 0->1^{\prime}$ and ' 1 - $>0$ ', respectively. The short transition '->?' represents a don'tcare transition which essentially says that a transition is to occur and "you don't care" if it is a ' $0->1^{\prime}$ or a ' $1 \rightarrow 0^{\prime}$ transition. This shorthand notation is a valuable asset to the user in making quick and easy specifications.

As in PL/I [18], the identifier may consist of both letters and digits with the restriction of beginning with a letter. Ideally, ACDL permits identifiers to be of an arbitrary length. However due to implementation restrictions of the current ACDL translator, the length of an identifier is Iimited to 256 characters.
3. Relations and Expressions

All expressions in ACDL are logical expressions. There are two types of logical expressions: the transition relation expressions and the Boolean variable expressions. The following rules for constructing these expressions will become more clear as the discussion progresses.

$$
\begin{aligned}
& \text { <level relation }:=\text { <identifier }>=\text { <level>1<level relation }\rangle \\
& \text { \& <identifier }>=\text { <level } \mid(<\text { level relation }>\text { ) } \\
& \text { <transition relation>: := <identifier> = <long transition> } \\
& 1<\text { identifier }>\text { <short transition> } \\
& 1<\text { transition relation }>\text { \& <identifier }> \\
& =<\text { Zong transition }>\mid<\text { transition relation }> \\
& \text { \& <identifier }><\text { short transition } \mid \text { ( }<\text { tran- } \\
& \text { sition relation }>\text { ) }
\end{aligned}
$$

<empound relation>: = <transition relation> WHILE Level relation> <transition expression>: $=$ <transition relation>|<compund relation $>\mid<$ transition expression $>+$ tran sition relation>|<transition expression> + <compound expression $>1<$ dummy term $>1$ (<transition expression>)
<dunmy term>::= LINKTEST | LK'T
$<$ Boolean expression $>:=\quad<$ logical factor> $\mid<$ Boolean expression $>$ $+<$ logical factor>
$<$ logical factor $\rangle:==<$ logical term $>1<$ logical factor $\rangle \&<$ logical term>
$<$ logical term>::= <logical primary> $\left.\right|^{7}<$ logical primarys
$<$ logical primary>: : = <level>|<identifier>|(<Boolean expression $\rangle$ )
Since all expressions are logical quantities, they evaluate to either of two values; true or false. The level and transition relations become true whenever the values of the identifiers equal the values of the constants. Similarly, the compound relation becomes true whenever the transition relation becomes true while the level relation is true. In circuit terminology this means some variables are to make a transition while others remain fixed. The dummy term, LINKTEST (LK'T) serves a special function which is described later in conjunction with the 1 ink statement.

The Boolean expression is the standard logical variable expression [3-10],[18]. Examples of this Boolean expression are given in Table III.

Free parenthetical form is permitted in Boolean expressions. However, if the order of logical operations is not specified by parenthesis, then the logical operators are applied in the standard hierarchical order


Table IV further explains the use of the shorthand transition notation discussed earlier, and examples of the relation expression are given in Table $V$.

TABLE IV. SHORTHAND NOTATION FOR RELATION EXPRESSIONS

table v. EXAMPLES OF THE RELATION EXPRESSION

| Expression | Read As | Logical Meaning | Informal Meaning |
| :---: | :---: | :---: | :---: |
| X1->1 | X1 makes a transition to 1 | X 1 goes from 0 to 1 | X1 turns on Xl goes up etc. |
| $\begin{aligned} & \mathrm{X} 1->1 \& \\ & \mathrm{X} 2->0 \end{aligned}$ | Xl makes a transition to 1 and X 2 makes a transition to 0 simultaneously | Xl goes from 0 to 1 and X2 goes from 1 to 0 simultaneously | X1 turns on at the same time X2 turns off |
| $\mathrm{X} 1->1+\mathrm{X} 2->0$ | X1 makes a transition to 1 or X2 makes a transition to 0 | X1 goes from 0 to 1 or X2 goes from 1 to 0 | Xl is to turn on or X 2 is to turn off |
| X1->? | X1 makes a transition | Xl goes from 0 to 1 or Xl goes from 1 to 0 | Xl changes state i.e. it either turns on or turns off |
| $\begin{aligned} & \mathrm{X1}->? \& \\ & \mathrm{X} 2->? \end{aligned}$ | Xl makes a transition and X2 makes a transition simultaneously | $\begin{aligned} & \text { X1 and X2 go from } \\ & 00 \text { to } 11 \\ & \text { or } 11 \text { to } 00 \\ & \text { or } 01 \text { to } 10 \\ & \text { or } 10 \text { to } 01 \end{aligned}$ | X 1 and X 2 change state simultaneously |
| $\begin{aligned} & \mathrm{X} 1->1 \text { WHILE } \\ & \mathrm{X} 2=1 \end{aligned}$ | Xl makes a transition to 1 while $X 2$ equals 1 | Xl goes from 0 to 1 while X2 stays at 1 i.e., inputs $\mathrm{X} 1, \mathrm{X} 2$ go from state 01 to 11 | Xl turns on while X 2 is held on |

```
<output Zabel>::= Z <output code> Z (coutput state set>)
coutput state set>::= coutput code>l coutput state set>, coutput
    code>
<output code>::= <binary digit>|<output code> binary digit>|
    <output code>/<number>
```

The letter $Z$ is reserved for the beginning character of output labels, and it is followed by the current output state of the circuit. Hence, the output label serves two major purposes: 1) it provides the designer with the value of the present output state at a particular point in the design sequence; and 2) it indicates the next statement to be executed from that particular output state. The output state of the label is followed by a / <number> when it is necessary to distinguish a previous output label having the same output state. If the / <number> is not specified with the output label, the ACDL translator will assume a default value of $/ 1$ for the label. An output label may also be used to specify multiple output states in cases where the next statement to be executed is the same for each state.

A standard label is essentially a valid identifier with the restriction that the first character of the label cannot be the letter " Z ". Examples of standard and output labels are given in Table VI. TABLE VI. EXAMPLES OF LABELS

| Label Type | Examples |
| :---: | :---: |
| Standard | FIRST: |
| Standard | $\$ 31:$ |
| Standard | BEGIN_HERE: |
| Output | Z00: |
| Output | $Z(00,01 / 2,11):$ |
| Output | Z110/3: |

## 5. Statements

There are nine types of statements in ACDL. As in PL/I [18], all statements must be separated by a semicolon; otherwise, they can be written in free format. Each is described below.
a. Design Statement

A description of the design statement is given below. <design statement>: : = DESIGN | DESIGN <accounting information> <accounting information>::= <design number>1<design number>, <designer's name>Kdesign number>, <designer's nome>, <date>
<design number>: : = <number> <designer's nome>::= <identifier>kdesigner's nome><identifier> <date>:: = <identifier> <number>, <number>

The design statement indicates the beginning of a new circuit design. The accounting information is optional and may indicate the design number, designer's name and date.
b. Declare Statement

The following is a description of the declare statement. $<$ declare statement $>:=$ DECLARE<declaration type $>$ |<declare statement> <declaration type>
<declaration type>:: = <input declaration>|<constraints declaration> $1<0$ utput declaration $>1<g$ Zobal declaration>
<input declaration>::= INPUTS: <variabze definition>kinput declarations, <vamiable definitions
<variable definition>: : = <identifier>|<identifier> =initial condition
<initial condition>::= (<level>)

```
<constraints decIaration>::= CONSTR: <constraints>
constraints>::= NONE|AUS|SIC | <transition expression>
    |<level relation>|<constraints>,
    <transition expression> i<constraints>,
    <level rezation>
<output declaration>::= OUTPUTS: <variable definition>
    | <output declaration>, <variable definition>
GZobal declaration>::= GLOBAL: <list>
Iist>::= <automatic link transition statement>|<list>,
    <automatic link transition statement>
```

The input and output declarations indicate the number and names of the input and output variables required in the design. The initial condition for each variable may or may not be given. If no initial value is explicitly shown, then an initial value of zero is assumed by default.

The constraints declaration indicates those input transitions that are not allowed. To assist the designer in problems which permit only single inpui changes, the constraints specification is given by the mneumonic SIC which stands for "Single Input Change." The mneumonic AUS means thai "All Unspecified Sequences" of input transitions, i.e. Chose sequences which are not explicitly described in the design, are not permitted to occur. This constraint is extremely useful in problems where only a specific number of allernative sequences can occur. Level relation constraints restrict transitions to those input states which agree with the value of the relation. If there are no input transition constraints the word "NONE" must be written.

The global declaration is used when there are certain transition conditions which arise frequently throughout the design and are independent of any particular $I / O$ sequence. Instead of repeating the transition statement many times in the design specifications, the statements are listed once in a global declaration. The global list consists of automatic link transition statements which are discussed later.

Some examples of the design and declare statements are given in Table VII.

TABLE VII. EXAMPLES OF THE DESIGN AND DECLARE STATEMENTS


The initial conditions for the input variables are explicitly given in the example of the second declare statement, while they are left to default to zero in the first declare statement.
c. Start Statement

The start statement is defined as:
<start statement>: : START
This is always the first statement in the circuit's behavior description. Therefore, it acts as the starting point for the design sequences by invoking the initial $I / O$ conditions and establishing the initial state of the machine.
d. Transition Statement

This statement is used to show input transitions and may re-
late an input transition to an output change. A description of this statement is shown below.
<transition statement>: := <basic transition statement>
|<automatic link transition statement>
<basic transition statement>: : = <transition expression> 1<transition expression> $\Rightarrow$ <output change>
<output change>: : = <identifier $\rangle<-<$ Boolean expression $>$
1-output change>, <identifier><-
$<$ Boolean expression $>$
<automatic Zink transition statement>: : = <transition expression> $\Rightarrow$ <output change>
<autozink>
<auto Link>: : $=1 / /<$ number>
Since the imputs to the circuit change at random, the input transitions specified by the transition expression are essentially test conditions for particular changes. When the test conditions are satisfied the specified output change occurs.

The slash following the output change is an optional character used when automatic linking is desired. This concept is explained in a subsequent section on the list statement. Examples of basic transition statements are shown in Table VIII.

TABLE VIII. EXAMPLES OF THE TRANSITION STATEMENT

| Statement | Explanation |
| :---: | :---: |
| $A->1 ;$ | Input $A$ is to make a transition to 1 |
| $A \rightarrow>0>Z\langle-1 ;$ | Input A making a transition to 0 implies |
|  | that output $Z$ changes to 1 if not already 1 |
| $(C->1)+(B->1)$ | Input $C$ making a transition to 1 or input |
| $\Rightarrow G<-1, R<-0 ;$ | $B$ making a transition to 1 causes output |
|  | G to be replaced to 1 and $R$ to be replaced |
|  | to 0 |

## e. Link Statement

Generally, there will be many sequences of transition statements in a design specification and some subsequences of transition statements will be common to more than one sequence. Whenever a subsequence leads to two or more sequence paths, as in the case of alternate behaviors at a branch point, it is necessary to make the proper connection to each of these paths. These connections can be made with the link statement defined below.
$<$ link statement $>:=$ <link conditional $>1<$ link unconditional $>$
$<$ link conditionaß: $:=$ <tests $\rangle$ Sranch points>
$<$ tests>: $:=(<$ test condition> $\mid<t e s t s>$, <test condition>
$<$ test condition>: $:=$ <transition expression $>\mid<$ level relation $>$
|ELSE
<branch points>:: $=$ )<singZe label>kbranch points>, <single label>
<single label>::= <standaxd label>|Z<output code>
$<$ link unconditional>: $=$ LINK <single label>
The tests listed in the conditional link statement are the test conditions of the next transition statement for each new path, respectively. The next statement following the test condition for each path is given by the label corresponding by position to the test condition. Multiple output labels are not allowed in the 1 ink statement. This restriction, however, causes no branching limitations. Any statement having a multiple output label can be located by any one of its output states.

Whenever an output change follows a test condition of the LINK, it is shown as the first statement of the new path. In this case the dummy term LINKTEST (abbrev. LK' I ) is inserted as the transition expression for this transition statement. This implies that the same test condition causing the link also causes the output change.

The link unconditional is the same as a "go to" statement and is primarily used for branching back to a previously specified statement.

## f. Statement Block

Closely associated with the link statement are statement
blocks. A description of the statement block is given below.
$<$ statement block: $:=$ beginning><statement list><ending>
$\langle$ beginning>::= BEGIN; | <label> BEGIN;
<ending>: := END|<label> END
Actually the BEGIN and END statements act as separators which serve to segregate a block of statements from other statements. This block of statements between a BEGIN and END is called a statement block and can
only be entered from a link or list statement. Statement blocks may be nested within other statement blocks. After a statement block has been completed, control is transferred to the next statement in the listing which does not belong to another statement block of the same nested level. Examples of the link statement and statement blocks are given in Table IX.

TABLE IX. EXAMPLES OF LINK STATEMENTS

| Statements | Explanation |
| :---: | :---: |
| LINK L3; | Link to the statement having the label L3 |
|  | The lst test condition transfers control to statement block Ll where the 1st statement says that the link test $B->1$ causes $Z\langle-1$. After the lst statement block is completed, control is transferred to the transition statement $B->0$. If none of the Link statement test conditions are true for the current input transition, the sequence will not advance, but rather will remain at the Link statement until a test condition becomes true for some later transition. |
| $\operatorname{LINK}(A=1, E L S E) \operatorname{RESET}$, CONTINUE; <br> RESET: A $\rightarrow 0$; <br> CONTINUE: $B \rightarrow 1$; | If input variable $A$ is currently equal to 1 , then branch to RESET else branch to CONTINUE |

g. Automatic Linking and the List Statement

Earlier it was noted that a slash "/" could follow the output change of a transition statement, and this slash meant automatic inking. This linking is accomplished by branching to the statement
identified by an output label having the current output state. The current output state is the state entered after the output change of the transition statement has taiken place. Therefore, if automatic linking is designated with the slash, the designer must ensure that a unique and correci output label has been assigned to some statement. To distinguish between output states having the same value, but occur at different points in the sequence, the designer follows the slash with a digit which must agree with the trailing digit of the correct output state label. Again if no digit is specified after the slash, a default value of 1 is assumed. Automatic linking saves the designer having to explicitly specify a link statement and hence, improves the clarity of the specification listing. It was the automatic linking feature which led to the development of the list statement defined as:

```
<list statement>::= LIST <list>
<list>::= <automatic link transition statement>|<list>,
    <automatic link transition statement>
```

The list statement is a special purpose link statement in which all test conditions lead directly to an output change. It does not specify an executable sequence of transition statements, but rather, it is a set of statements from which only one is selected and executed. The test conditions of all automatic link transition statements in the list are scanned concurrently, and only one test condition may be true at a time. When a test condition becomes true, its corresponding output change indicates the next statement in the sequence via automatic linking. The transition statements within a LIST statement are separated by commas, while the end of the list is indicated by the LIST
statement's semicolon. Some examples of the list statement are given in Table X .

TABLE X. EXAMPLES OF THE LIST STATEMENT

6. Structure of an ACDL Program

Now that the statements have been defined, it is worth examining the overall structure of a program.

```
<progran>: := <program head> <statement list> <ending>.
<progran head>::= <design statement>; declare statement>;
    <start statement>;
<statement list>::= <statement>|<statement list> <statement>
<statement>::= <basic statement>|<statement block>;
\(<\) basic statement>: := <transition statement>; |<link statement>;
    \(\mid<\) list statement \(>\); \(\mid<\) label \(><\) basic statement \(>\)
It is seen that the program ending also uses the word END. In
``` this case END is followed by a period rather than a semicolon. The period signifies the end of the design as opposed to the end of a statement block. All links to this ending will indicate the end of certain sequences within the specifications.

The statements which make up the program head must be listed in the order shown. These statements are not part of the input/output behavior of the design, but rather provide basic information about the design. For this reason labels are not assigned to statements in the program head.
7. Comments and Translator Control Toggles

Comments are defined as follows:
<comment>::= "<almost anything>"
<almost anything>::= <any string of valid system 360 characters that does not contain a ">

Comments help explain the program to persons reading it and are normally ignored by the translator. They do not result in the production of any translated text and they may be inserted any place a blank is allowed.

There is one case in which comments are not ignored. They may serve the special function of specifying control options which designate how the program is to be treated. For instance, a control option to perform and output a logic trace during the translation and/or execution of a program can be specified. A \(\$\) within a comment specifies that the next character is a control character. The valid control characters in ACDL are given in Table XI. Each control character acts as a toggle which can have the value of true or false. When \(\$<c h a r\) acter> is encountered by the translator, the value of the corresponding toggle is complemented. Therefore at the point where " \(\$ W\) " is first specified, the logic trace will be turned on, and will remain on until another " \(\$ W\) " is encountered which causes the trace to turn off. A more detailed description and use of the logic trace is given in Appendix \(B\).

TABLE XI. COMMENT CONTROL OPTIONS
\begin{tabular}{|c|c|}
\hline Character & Control Option \\
\hline D & Print translation statistics, sequence tables and symbol tables at end of translation (Initially disabled) \\
\hline L & List the source program (Initially enabled)* \\
\hline T & Begin a machine code trace of the ACDL translator and interpreter (Initially disabled)* \\
\hline U & Terminate the machine code trace of the ACDL translator and interpreter (Initially disabled)* \\
\hline W & Begin high level trace of translation and execution (Initially disabled) \\
\hline 1 & Set Margin. The portion of succeeding cards starting from the column containing the \(\mid\) will be ignored. \\
\hline
\end{tabular}

\footnotetext{
*These options were already a part of the XPL system (See reference [17]).
}
C. Sequences

Statements in ACDL are executed in the sequential order in which they are listed, except when the physical sequence is interrupted by branching which results from explicit or automatic linking. The rules for interpreting sequences written in ACDL are:
1) In a test condition of an ACDL statement, any undesignated input variables are considered as don't-cares in the specified input state transition.
2) The sequence will advance to the next statement for any input state transition which agrees with a test condition of the current statement.
3) The sequence remains quiescent (i.e. does not move) for any input state transition which does not agree with a test condition of the current statement.

Before the designer can efficiently use ACDL, some idea as to what information is necessary for correctly specifying the operation of the sequential circuit is required.

Definition: A set of minimum length sequences of input states which cause the next output change and starts from the \(I / O\) state resulting from the previous output change is called a critical event.

A critical event may be an incompletely specified sequence i.e., a sequence which contains don't-care variables in some states. In this case the critical event will actually represent more than one possible sequence resulting from the random changing of the don't-care variables. However, any intermediate states that are introduced by the don't-care variables will not affect the integrity of the critical event, i.e.,
these states neither cause an output change nor destroy any past history of the critical event.

The designer must specify in \(A C D L\) all critical events of the circuit. This is done by starting from the initial state of the circuit and listing the critical events which cause the first output changes. Continuing from these points in the sequences all subsequent critical events which cause further output changes are listed. The tree process is continued until the critical events for all possible output changes have been listed.

Definition: A proposition of the design is a word statement (or mental conception) which implies one or more critical events.

From the design propositions, the designer should be able to formally specify the critical events in ACDL. Likewise from the ACDL specifications, the propositions should be easily determined. Examples of various types of circuit designs in \(A C D L\) are given in Chapter \(V\).
D. Summary

Table XII summarizes the statements available in ACDL.

TABIE XII. SUMMARY OF ACDL
\begin{tabular}{|c|c|c|}
\hline Statement & General Format Description & Use \\
\hline Design & DESIGN optional accounting information of design 非, designer's name, and date; & Begins ACDL program \\
\hline Declare & \begin{tabular}{l}
DECLARE \\
INPUTS: input names with or without initial conditions \\
CONSTR: keywords, level expressions or transition expression constraints \\
OUTPUT: output names with or without initial conditions \\
gLOBAL: list of automatic link transition statements;
\end{tabular} & Defines all input variables, output variables, constraint transitions and global transitions of the design. \\
\hline Start & START; & The entry point of the sequence specifications. \\
\hline Transition & ```
input transition; (e.g. X->1;)
or
input transition=>output change with or
    without automatic linking specified;
    (e.g. X - > 1 =>Z<-1;)
``` & Expresses the I/0 relationships of the critical events of the design. \\
\hline
\end{tabular}

TABLE XII. (Continued)
\begin{tabular}{lll} 
Link & LINK (test condition list) label list; & \begin{tabular}{l} 
For branching in ACDL, \\
where the test condition \\
is an input level or \\
transition test, causing \\
a branch to the
\end{tabular} \\
corresponding label.
\end{tabular}

\section*{IV. TRANSLATION AND INTERPRETATION}

After the design has been specified in ACDL, a translation process is needed to convert the specifications into appropriate intermediate text. The intermediate text is then interpreted to produce a primitive flow table as the final output.

The translator and interpreter (flow table construction algorithm) is written in XPL, a special purpose translator writing language developed by McKeeman et al. [17]. A brief description of the XPL system follows.
A. The XPL Translator Writing System (TWS)

A diagram of the translator writing system provided with XPL is shown in Figure 3. The major components included in the system are:
1) a grammar analyzer (ANALYZER)
2) a proto-compiler (SKELETON) and
3) The XPL compiler (XCOM).

ANALYZER [17] is a program which reads the BNF grammar describing the syntax of the user's language, determines whether it is acceptable to the parsing algorithm and constructs parsing decision tables for that algorithm. SKELETON [17], which is written in XPL, provides the basic framework of the user's compiler such as, the routines for scanning, input and parse-stack maintenance. XCOM [17] is the compiler for the XPL language, and produces a System 360 machine language object program.

Depending on the amount of information supplied to TWS, the system will produce either a syntax checker, a translator or a combined translator/interpreter. If the user supplies only a syntax description (grammar) of his language in \(B N F\), the resulting ANALYZER output deck


Figure 3. XPL Translator Writing System
and the SKELETON deck produce a syntax checker for the language. If the semantic description of his language (written in XPL) is also inserted into the SKELETON deck, the system will produce a translator. If in addition to the syntax and semantic descriptions, an interpreter is written in XPL and is placed behind the SKELETON deck, the system produces a combined translator/interpreter. It is this case which is illustrated in Figure 3.

An important advantage of TWS is the ease in which changes to the user's language can be made. Only the syntactic definition and semantic description corresponding to the language change are updated in the translator. A detailed description of the current syntactic definition (BNF grammar) and semantic routines of ACDL has been provided in Appendix \(D\) and Appendices \(E\) and \(F\), respectively. Appendix \(C\) lists the job setup requirements for making a computer run to update the \(A C D L\) translator and the job setup for running a standard ACDL program.
B. ACDL Translation

From the syntax of a language, the translator knows what type of symbols are expected at every point in a language statement. The semantic routines then determine what action is to be taken, if any, when these symbols are encountered. They also generate internal data-structures which hold the results of the translation. These data-structures are referred to as the internal form or intermediate text. A description of the internal form used in the ACDL translation follows.
1. Internal Form

The internal form of the ACDL translator consists of tables which can be dumped at the end of the translation (see Table XI). The tables
contain input/output sequence data as well as symbol information. As a means to increase program execution time, all input states are handled internally and recorded in the tables as decimal weights rather than as binary strings.

The main table used to hold the \(I / O\) sequence information is called the Primary Sequence Table. It stores the translated form of the statements making up the critical sequences of the design. The first row of the table is assigned to the START statement, with subsequent rows being assigned to each transition statement and each test condition of a link statement. Input and output secondary tables act as backup for the primary sequence table when statements have more than one input test or output change respectively. This technique of table organization saves storage since the secondary tables do not require all the fields that are needed in the primary table.

A special table called the Global Transition Table holds the information from the globally declared transition statements. The structure of this table is similar to the primary sequence table, and also uses the two secondary tables as backup tables. However, the Global Table functions differently in that all its input tests are queried continuously throughout the design.

The Constraint Transition Table records those input transitions that have been explicitly declared as input constraints. Restricted input transitions resulting from the SIC or AUS declaration are not recorded in this table because violations of these conditions aredetected in an algorithmic manner. The constraint table does not use any backup tables. All restricted transitions are stored in sequential order in the table and are checked before examining any other tables.

The ACDL translation makes use of two separate symbol tables. One table is a standard symbol table used to record input, output and label names and their corresponding attributes. The other table is a special symbol table used to store output labels and statement pointers for automatic linking. Since only one table has to be searched for a particular operation, the two-table organization provides efficient symbol information retrieval and is especially advantageous in the automatic linking process.

A detailed description of the above tables and their corresponding fields is given in Appendix \(A\). The appendix also includes an example program and corresponding table dump.

Another feature of the internal form is the handing of the Boolean output expressions. These expressions are converted from standard infix form to Reverse Polish form. The Reverse Polish form is stored in and executed from a single-dimensioned array. Special terminators are also stored in the array to indicate the beginning and end of an expression. For easy and rapid manipulation, the operators and operands are represented by their precedent values and symbol table indexes, respectively. For this reason, the Polish array was not included in the dump. However, the array is printed out whenever the logic trace is specified.
C. Primitive Flow Table Construction

Once the translation process has been completed, the interpretation process begins. Here the interpreter is an algorithm to construct a primitive flow table from the tables of the internal form. A flow chart describing the basic philosophy of the flow table algorithm is given in Figure 4.


Figure 4. Flow Chart of the Primitive Flow Tahle Construction Algorithm

In addition to the output state, the flow table algorithm assigns input and sequence attributes to each row of the flow table. Each attribute has its own function in the flow table construction algorithm. The sequence attribute is an index which points to the statement in the Primary Sequence Table that is tested during the construction of the corresponding flow table row. It essentially keeps track of a flow table state's position in the design sequence. The input attribute contains the input state for which the corresponding flow table row is stable. Input transitions for a flow table row are simulated by using the input attribute as the beginning state and the column inputs as the ending states. This permits the computation of next-state entries to be conducted in an orderly manner with stable entries being recognized whenever the input attribute equals a column state.

To help understand the flow table algorithm, the following example problem [14] will be considered:

Design a circuit which has two inputs, OSC and BTN, and one output, \(Z\). The input OSC is the output of a square wave oscillator, and BTN is a button which, when depressed, gates one and only one full width oscillator pulse to the output. If the button is depressed for too short of time, a pulse will not occur at the output. An output pulse can occur only if the button depression overlaps the leading edge of an oscillator pulse. The inputs cannot change simultaneously.

The ACDL program for this design is:

DESIGN 1, JOHN BROWN, SEP 27, 1972;

\section*{DECLARE}

INPUTS: OSC, BTN
CONSTR: SIC
OUTPUTS: Z;
Seq. 非
0 START;
1 L2: BTN->1;
2 LINK (OSC->1,
3
BTN \(->0\) ) L1, L2;
\(4 \mathrm{~L} 1: \quad \mathrm{LK}{ }^{1} \mathrm{~T} \Rightarrow\) Z \(\langle-1\);
\(5 \quad\) OSC \(->0 \Rightarrow\) Z \(<-0\);

6
END.
To simulate the internal form, the sequence numbers assigned to the statements in the above program correspond to the row indices of the Primary Sequence Table in which their translated form is stored. The start statement has the sequence number 0 , because the Primary Sequence Table begins at index 0 . The sequence numbers of the above program also relate to the sequence number attribute of each flow table row. The first step in the algorithm is to define the initial state of the circuit. Since the start statement is responsible for seting up the initial conditions, this information is retrieved from row 0 of the Primary Sequence Table and assigned to the attributes of the first flow table row. At this point in the construction, the partial flow table resembles Table XIII (a). The sequence number attribute of flow table row 1 corresponds to the sequence number of the next statement to be executed in the ACDL program.

The next step is to compute next-state entries for row 1 of the flow table. The next state for the first input column is stable since the input attribute equals this input column. For the next input column, the first three input tests of the algorithm failed and the critical transition test is performed. For this test, the flow table transition, 00 to 01 , is compared to the test condition, BTN->1, which is pointed to by the sequence attribute of 1 . The test condition agrees with the flow table transition; therefore, the sequence advances. Since there is no previously defined state with correct attributes (i.e. Seq 非=2, \(I=01, Z=0\) ), the new state 2 is defined as shown in Table XIII (b).

The next input column implies the transition 00 to 10 . Again the first three input tests failed, and since the flow table transition does not agree with the specified transition BTN->l, the critical transition test also fails. Therefore the sequence remains quiescent, and the next state retains the same sequence number and output state attributes as the present state. A new state 3 is defined because there is no previously defined state with the required attributes.

The last input column implies the transition 00 to 11 , which will be detected by the constraint transition test as an illegal transition. A don't care will be entered in this column and row 1 is complete as shown in Table XIII (c). The algorithm moves to the next incomplete flow table row which is row 2 in this example and repeats the same procedure.

After all flow table rows are complete, the algorithm will terminate and produce the resulting flow table shown in Table XIV. From this table it is observed neither the sequence attribute 4 nor 6 is associated with any of the flow table rows. This is due to a property of
the algorithm which advances the sequence through non－active test con－ ditions such as LK＇T，BEGIN，END and ELSE．The reader should now be able to verify the remaining flow table rows．

TABLE XIII．PARTIAL FLOW TABLE
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multicolumn{2}{|l|}{Attributes} & \multirow[t]{2}{*}{Present State} & \multicolumn{2}{|l|}{\multirow[t]{2}{*}{\[
\begin{array}{lc}
\hline \text { OSC } & \text { BTN } \\
00 & 01 \\
\hline
\end{array}
\]}} & \multirow[b]{2}{*}{10} & \multirow[b]{2}{*}{11} & \multirow[b]{2}{*}{\(\underline{\text { Z }}\)} \\
\hline Seq非 & I & & & & & & \\
\hline & 00 & 1 & & & & & 0 \\
\hline \multicolumn{2}{|c|}{（a）} & \multicolumn{5}{|l|}{Definition of the Initial State} & \\
\hline \multicolumn{2}{|l|}{Attributes} & Present & OSC & BTN & & & \\
\hline Seq非 & I & State & 00 & 01 & 10 & 11 & Z \\
\hline 1 & 00 & 1 & （1） & 2 & & & 0 \\
\hline 2 & 01 & 2 & & & & & 0 \\
\hline \multicolumn{8}{|c|}{（b）Definition of State 2} \\
\hline \multicolumn{2}{|l|}{Attributes} & \multirow[t]{2}{*}{Present State} & \multicolumn{2}{|l|}{OSC BTN} & \multirow[b]{2}{*}{10} & \multirow[b]{2}{*}{11} & \multirow[b]{2}{*}{Z} \\
\hline Seq非 & I & & 00 & 01 & & & \\
\hline 1 & 00 & 1 & 1 & 2 & 3 & － & 0 \\
\hline 2 & 01 & 2 & & & & & 0 \\
\hline 1 & 10 & 3 & & & & & 0 \\
\hline \multicolumn{7}{|c|}{（c）Completion of Row 1} & \\
\hline
\end{tabular}

An important feature of the algorithm is its ability to distin－ guish different states having the same input／output attributes．As seen from states 2 and 6 in Table XIV，it is the sequence attribute which provides this distinction．

To simplify the explanation of the flow table construction algorithm the previous example was performed without converting to internal form．Since the internal form is only a translated description
of the ACDL statement, it should be clear that the same philosophy will apply. A more detailed description of the flow table procedures as they utilize the internal form is given in the flow charts of Appendix F .

TABLE XIV. RESULTING FLOW TABLE FOR EXAMPLE DESIGN
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multicolumn{2}{|l|}{Attributes} & \multirow[t]{2}{*}{Present State} & \multicolumn{4}{|l|}{OSC BTN} & \multirow[b]{2}{*}{Z} \\
\hline Seq非 & I & & 00 & 01 & 10 & 11 & \\
\hline 1 & 00 & 1 & (1) & 2 & 3 & - & 0 \\
\hline 2 & 01 & 2 & 1 & (2) & - & 4 & 0 \\
\hline 1 & 10 & 3 & 1 & - & (3) & 5 & 0 \\
\hline 5 & 11 & 4 & - & 6 & 7 & (4) & 1 \\
\hline 2 & 11 & 5 & - & 2 & 3 & (5) & 0 \\
\hline 1 & 01 & 6 & 1 & (6) & - & 8 & 0 \\
\hline 5 & 10 & 7 & 1 & - & (7) & 4 & 1 \\
\hline 1 & 11 & 8 & - & 6 & 3 & (8) & 0 \\
\hline
\end{tabular}

\section*{V. DESIGN EXAMPLES}

This chapter is included to help the user become familiar with the ACDL specification process. It is felt this could best be accomplished by providing a set of example problems which illustrate the different features of the language. In each example a word description of the design is given. A reference number after the word description indicates the source from which the example was selected. The ACDL program and the primitive flow table follow each word description. All flow tables have been generated automatically from the ACDL descriptions. Due to its large size ( 78 rows by 8 columns), the flow table for example 8 is not shown.
A. Example 1

Design a Bounce Eliminator for a two position switch. The output state of the eliminator circuit is to indicate the desired position of the switch regardless of any contact bouncing which may occur when the switch is initially moved. It is assumed that the switch cannot bounce back far enough to contact the other position [19].

The ACDL Design is:
```

DESIGN 1 "BOUNCE ELIMINATOR";
DECLARE
INPUTS: A(1), B(0)
CONSTR: A=1 \& B=1
OUTPUTS: Z;
START;
B->1 => Z<-1;
A->1 => Z<-0;
END.

```

TABLE XV. PRIMITIVE FLOW TABLE FOR EXAMPLE 1
\begin{tabular}{|c|c|c|c|c|c|}
\hline \multirow[t]{2}{*}{Present State} & A & & & & \\
\hline & 00 & 01 & 10 & 11 & Z \\
\hline 1 & 2 & 3 & 1 & - & 0 \\
\hline 2 & (2) & 3 & 1 & - & 0 \\
\hline 3 & 4 & 3 & 1 & - & 1 \\
\hline 4 & 4 & 3 & 1 & - & 1 \\
\hline
\end{tabular}
B. Example 2

Design a fundamental mode sequential circuit with two inputs XI
and \(X 2\). The single output \(Z\) is to be 1 only when \(X 1, X 2=01\) provided that this is the fourth of a sequence of input combinations \(00,10,11\), 01. Otherwise, \(Z=0\). Both inputs will not change simultaneously [19]. The ACDL Design is:

DESIGN 2, JOHN BROWN, SEP 25, 1972;
DECLARE
INPUTS: \(\mathrm{X} 1, \mathrm{X} 2\)
CONSTR: SIC
OUTPUTS: Z ;
START;
L1: \(\mathrm{X} 1 \rightarrow 1\) WHILE \(\mathrm{X} 2=0\);
\(\operatorname{LINK}(X 2->1, X 1->0) \mathrm{L} 3, \mathrm{~L} 1 ;\)
L3: LINK (X1->0, X2->0) L4, L1;
L4: \(\mathrm{LK}^{\prime} \mathrm{T} \Rightarrow \mathrm{Z}\langle-1\);
\((X 1->?)+(X 2->?) \Rightarrow Z<-0\);
END.
TABLE XVI. PRIMITIVE FLOW TABLE FOR EXAMPIE 2
\begin{tabular}{|c|c|c|c|c|c|}
\hline \[
\begin{gathered}
\text { Present } \\
\text { State }
\end{gathered}
\] & \[
\begin{aligned}
& \text { X1 X } \\
& 00
\end{aligned}
\] & 01 & 10 & 11 & Z \\
\hline 1 & (1) & 2 & 3 & - & 0 \\
\hline 2 & 1 & (2) & - & 4 & 0 \\
\hline 3 & 1 & - & 3 & 5 & 0 \\
\hline 4 & - & 2 & 6 & 4 & 0 \\
\hline 5 & - & 7 & 6 & 5 & 0 \\
\hline 6 & 1 & - & 6 & 4 & 0 \\
\hline 7 & 1 & (7) & - & 4 & 1 \\
\hline
\end{tabular}
C. Example 3

A circuit is to be designed in which two push buttons \(A\) and \(B\) control the lighting of two lamps \(G\) and \(R\). Whenever both push buttons are released, neither lamp is to be lit. Starting with both buttons released, the operation of either button causes lamp \(G\) to light. Operation of the other button, with the first button still held down, causes lamp R to light. Henceforth, as long as either button remains operated, the button which first caused lamp \(R\) to light controls lamp R--causing it to extinguish when the button is released and to light when the button is operated. The other button controls lamp \(G\) in the same fashion. It is not possible to operate or release both buttons simultaneously [10].

The ACDL Design is:
DESIGN 3;
DECIARE
INPUTS: \(A, B\)
CONSTR: SIC
OUTPUTS: G,R
GLOBAL: \((\mathrm{A} \rightarrow 0\) WHILE \(\mathrm{B}=0)+(\mathrm{B} \rightarrow 0\) WHILE \(\mathrm{A}=\mathrm{O})\)
\(\Rightarrow \mathrm{G}<-\mathrm{O}, \mathrm{R}<-\mathrm{O} /\);
START;
ZOO: LIST
\[
A->1 \Rightarrow G<-1 /,
\]
\[
B->1 \Rightarrow G<-1 / 2 ;
\]
\(\mathrm{Z} 10: \mathrm{B}->1 \Rightarrow \mathrm{R}\langle-1 /\);
Z11: LIST
\(\mathrm{A}->\mathrm{O} \Rightarrow \mathrm{G}<-\mathrm{O} /\), \(\mathrm{B}->\mathrm{O} \Rightarrow \mathrm{R}\langle-\mathrm{O} /\);
ZO1: A->1 \(\Rightarrow \mathrm{G}\langle-1 /\);
\(\mathrm{ZIO} / 2: \mathrm{A}->1 \Rightarrow \mathrm{R}\langle-1 / 2\);
Z11/2: LIST
\[
A->0 \Rightarrow R<-O / 2,
\]
\[
B->O \Rightarrow G<-0 / 2 ;
\]

ZO1/2: \(\mathrm{B}->1 \Rightarrow \mathrm{G}\langle-1 / 2\);
END.

TABLE XVII. PRIMITIVE FLOW TABLE FOR EXAMPLE 3
\begin{tabular}{|c|c|c|c|c|c|}
\hline \multirow[t]{2}{*}{Present State} & \multicolumn{5}{|l|}{A B} \\
\hline & 00 & 01 & 10 & 11 & GR \\
\hline 1 & (1) & 2 & 3 & - & 00 \\
\hline 2 & 1 & (2) & - & 4 & 10 \\
\hline 3 & 1 & - & 3 & 5 & 10 \\
\hline 4 & - & 2 & 6 & 4 & 11 \\
\hline 5 & - & 7 & 3 & 5 & 11 \\
\hline 6 & 1. & - & 6 & 4 & 01 \\
\hline 7 & 1 & (7) & - & 5 & 01 \\
\hline
\end{tabular}
D. Example 4

Design an asynchronous 3 -bit Gray Code counter which has one input \(X\) and 3 outputs, \(Z 1, Z 2, Z 3\). The counter is to count as indicated in Table 18 [20].

TABLE XVIII. THREE BIT GRAY CODE
\begin{tabular}{cccc} 
Count & Zl & Z2 & Z3 \\
0 & 0 & 0 & 0 \\
1 & 0 & 0 & 1 \\
2 & 0 & 1 & 1 \\
3 & 0 & 1 & 0 \\
4 & 1 & 1 & 0 \\
5 & 1 & 1 & 1 \\
7 & 1 & 0 & 0 \\
\hline
\end{tabular}

The ACDL Design is:
"GRAY CODE GOUNTER"
DESIGN 4;
DECLARE
INPUTS: X
CONSTR: NONE
OUTPUTS: Z1, Z2, Z3;
START;
\(\mathrm{Z}(000,011,110,101): \mathrm{X}->1 \Rightarrow \mathrm{Z} 3\langle-\neg \mathrm{Z} 3 /\);
\(\mathrm{Z}(001,111): \mathrm{X}->1 \Rightarrow \mathrm{Z} 2\langle--\mathrm{Z} 2 /\);
\(\mathrm{Z}(010,100): \mathrm{X}->1 \Rightarrow \mathrm{Z} 1<-\neg \mathrm{Z} 1 /\);
END.

TABLE XIX. PRIMITIVE FLOW TABLE FOR EXAMPLE 4
\begin{tabular}{|c|c|c|c|c|c|}
\hline Present State & \[
\begin{gathered}
\mathrm{X} \\
0 \\
\hline
\end{gathered}
\] & 1 & Z1 & 22 & Z3 \\
\hline 1 & (1) & 2 & 0 & 0 & 0 \\
\hline 2 & 3 & (2) & 0 & 0 & 1 \\
\hline 3 & (3) & 4 & 0 & 0 & 1 \\
\hline 4 & 5 & (4) & 0 & 1 & 1 \\
\hline 5 & (5) & 6 & 0 & 1 & 1 \\
\hline 6 & 7 & (6) & 0 & 1 & 0 \\
\hline 7 & (7) & 8 & 0 & 1 & 0 \\
\hline 8 & 9 & (8) & 1 & 1 & 0 \\
\hline 9 & (9) & 10 & 1 & 1 & 0 \\
\hline 10 & 11 & (10) & 1 & 1 & 1 \\
\hline 11 & (11) & 12 & 1 & 1 & 1. \\
\hline 12 & 13 & (12) & 1 & 0 & 1 \\
\hline 13 & (13) & 14 & 1 & 0 & 1 \\
\hline 14 & 15 & (14) & 1 & 0 & 0 \\
\hline 15 & (15) & 16 & 1. & 0 & 0 \\
\hline 16 & 1 & (16) & 0 & 0 & 0 \\
\hline
\end{tabular}

\section*{E. Example 5}

The timing signal Xl alternates between being off for 60 seconds \((X 1=0)\) and on for 30 seconds \((X 1=1)\). The only time Route 1 traffic can see a red light, a condition designated by \(Z=1\), is during an interval in which \(X 1=1\). Only at the start of an \(X 1=1\) interval can \(Z\) go on, and once on, it must remain on for the full interval. If a car on Crumb Road actuates a switch, a condition designated by \(\mathrm{X} 2=1\) (when no car is over such a switch \(X 2=0\) ), while \(Z=0\), then \(Z\) should go on the next time X1 goes on [11].

The ACDL Design is:
DESIGN 5;
DECLARE
INPUTS: \(\mathrm{X} 1, \mathrm{X} 2\)
CONSTR: NONE
OUTPUTS: Z;
START;
X2->1;
\(\mathrm{L} 1: \quad \mathrm{X} 1->1 \Rightarrow \mathrm{Z}\langle-1\);
\(\mathrm{X1}->0 \Rightarrow \mathrm{Z}<-0\);
LINK (X2=1, ELSE) L1, L2;
L2: END.
TABIE XX. PRIMITIVE FLOW TABLE FOR EXAMPLE 5

F. Example 6

Design an asynchronous sequential circuit for which only the four alternative sequences shown in the timing chart of Figure 5 can occur[15].


Figure 5. Timing Chart Indicating Allowable Sequences for Example 6

The ACDL Design is:
```

    DESIGN 6;
    DECLARE INPUTS: X1, X2, X3
        CONSTR: AUS
        OUTPUTS: Z1, Z2;
        START;
        LINK(X1->1,X3 ->1)L1, L2;
        LINK(X2->1, X3 ->1)L3, L4;
        L3: BEGIN;
            X3->1 => Z1<-1;
            X3->0 => Z1<-0;
            X2->0;
            END;
    ```
L1: BEGIN;
```

            L4: BEGIN;
            X2->1 => Z2<-1;
            X2->0=>Z2<-0;
            X3->0;
            END;
        X1->0;
        END;
    L2: BEGIN;
        LINK(X1->1, X2->I)L5, L6;
            L5: BEGIN;
            X2->1 => Z1<-1;
            X2->0 => Z1<-0;
            XI->0;
            END;
        L6: BEGIN;
            X1->1=>Z2<-1;
            X1->0 => Z2<-0;
            X2->0;
            END;
        X3 ->0;
        END;
        END.
    ```
G. Example 7
Design an asynchronous version of a clamp-gate circuit. The cir-
```cuit has two serial inputs \(X\) and \(Y\) and an output \(Z\). The characteris-tics are such that \(Z\) is made equal to the present value of \(X\) if \(Y=1\),or to the previous value of X if \(\mathrm{Y}=0\) [20].
```

The ACDL Design ..... is:
DESIGN 7 'CLAMP-GATE CIRCUIT";
DECLARE INPUTS: X,Y
CONSTR: NONE
OUTPUTS: Z;
START;

```
    LINK(Y-> ? WHILE X =0 + Y > ? WHILE X=1, X P ?)L1, L2;
```

L1: BEGIN;

```
            LK'T = Z < X X;
            END;
    L2: BEGIN;
    LK'T => Z<-(Y&X) + ( }-\textrm{Y}&-\textrm{X})
    END;
    END.
```

| Present <br> State | $\begin{aligned} & \text { X1 X2 } \\ & 000 \\ & \hline \end{aligned}$ | $001$ | 010 | 011 | 100 | 101 | 110 | 111 | 21 | Z2 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | (1) | $\stackrel{2}{2}$ | - | - | 3 | - | - | - | 0 | 0 |
| 2 | - | (2) | - | 4 | - | 5 | - | - | 0 | 0 |
| 3 | - |  | - | - | (3) | 6 | 7 | - | 0 | 0 |
| 4 | - | - | - | (4) |  | - | - | 8 | 0 | 0 |
| 5 | - | - | - | - | - | 5 | - | 9 | 0 | 0 |
| 6 | - | - | - | - | - | 6 | - | 10 | 0 | 0 |
| 7 | - | - | - | - | - |  | (7) | 11 | 0 | 0 |
| 8 | - | - | - | 12 | - | - | - | 8 | 0 | 1 |
| 9 | - | - | - | - | - | 13 | - | (9) | 1 | 0 |
| 10 | - | - | - | - | - | 14 | - | (10) | 0 | 1 |
| 11 | - | - | - | - | - | - | 15 | (11) | 1 | 0 |
| 12 | - | 16 | - | (12) | - | ${ }^{-}$ | - | ) | 0 | 0 |
| 13 | - | 16 | - | - | - | (13) | - | - | 0 | 0 |
| 14 | - | - | - | - | 17 | (14) | - | - | 0 | 0 |
| 15 | - | - | - | - | 17 | - | (15) | - | 0 | 0 |
| 16 | 1 | (16) | - | - | - | - | 5 | - | 0 | 0 |
| 17 | 1 | - | - | - | (17) | - | - | - | 0 | 0 |

TABLE XXII. PRIMITIVE FLOW TABLE FOR EXAMPIE 7

| Present State | $\begin{aligned} & \mathrm{X} Y \\ & 00 \end{aligned}$ | 01 | 10 | 11 | Z |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | (1) | 2 | 3 | 4 | 0 |
| 2 | 1 | (2) | 3 | 4 | 0 |
| 3 | 5 | 2 | (3) | 4 | 0 |
| 4 | 5 | 2 | 6 | (4) | 1 |
| 5 | (5) | 2 | 3 | 4 | 1 |
| 6 | 5 | 2 | (6) | 4 | 1 |

H. Example 8

Design an asynchronous circuit which has 3 inputs $A, B$, and $C$ and two outputs Z1 and Z2 and operates according to the following description. If C turns on $Z 1$ goes on, or if A turns on $Z 2$ goes on, provided $B$ has turned on first in either case. However, $B$ is not required to remain on until $A$ or $C$ turn on. $Z 1$ and $Z 2$ turn off whenever $C$ and $A$ turn off, respectively. Only single input changes are permitted.

The ACDL Design is:
DESIGN 8;
DECLARE INPUTS: A, B, C CONSTR: SIC OUTPUTS: Z1, Z2;
START;
ZOO: B->1;
S1: LIST
$\mathrm{C}^{-}>1 \Rightarrow \mathrm{Z} 1<-1 /$,
$A->1 \Rightarrow z 2<-1 / ;$
Z10: LIST

$$
\begin{aligned}
& \mathrm{C}->_{0} \Rightarrow \mathrm{Z} 1<-0 \quad /, \\
& \mathrm{A}->1 \Rightarrow \mathrm{Z} 2<-1
\end{aligned}
$$

Z00/2: LINK (A->1, B->1)L1, S1;
L1: $\mathrm{LK}{ }^{\prime} \mathrm{T} \Rightarrow \mathrm{Z} 2\langle-1 / 2$;

```
Z01/2: LINK (A->0, B->1)L2, Sl;
    L2: LK'T => Z2<-0 /;
    Z11: LIST
    C->0 => Z1<-0 /2,
    A->0 => Z2<-0 /2;
Z10/2: LINK(C->0, B->1)L3,S1;
    L3: TK'T => ZI<-0 /;
    Z01: LIST
                                    C->1 #> Z1<-1 /,
            A->0 => Z2<-0 /3;
Z00/3: LINK(C->1, B->1)L4, S1;
    L4: IK'T => Z1<-1 /2;
            END.
    As noted earlier, this example produces a 78 row primitive flow
table which is not reproduced here.
```


## VI. CONCLUSION

ACDL has proven to be a flexible system for specifying the terminal behavior of asynchronous circuits in terms of its problem versatility which includes designs originating from word descriptions or I/O sequences and other designs such as switches, flip-flops, counters etc. It is, however, best suited for problems originating from a word description of the circuit's operation since it was this type of problem which motivated the development of the language. Problems originating from $I / 0$ sequences are specified easily, but somewhat less naturally, then with the $I / O$ sequence methods of Smith [2] and Altman [1]. The $I / O$ sequences have to be converted to the ACDL transition statements as opposed to a direct listing.

In many problems, the critical event philosophy of listing only minimum sequences of input changes which cause output changes, greatly reduces the amount of information needed for specification. This feature may enable the designer to handle some large problems, but usually the exponential rate of increase of input states and therefore input sequences makes the problem too cumbersome. For this reason, the present implementation of the language is limited to six input variables, but this could easily be extended if necessary.

ACDL has also shown to be an efficient system in terms of computer and user specification times. As an indication of program execution time, the 78 row flow table which was generated for Example 8 of Chapter $V$, took only 6 seconds of CPU time. The byte storage capability of XPL permits efficient memory utilization of 120 K bytes. User specification is easier and saves time compared to constructing the
primitive flow table by hand. Also a problem can be designed in different ways by using the various features available in ACDL.

The ACDL system was tested with many examples including those given in Chapter $V$. The examples tested were an attempt to use every feature of the language to verify the correctness of the flow table generation algorithm. Correct flow tables were produced for every example tested.

Further research in the area of this dissertation may be directed toward:

1) the addition of pulse-mode design to the ACDL system,
2) the capability to connect previously designed networks to a current design by a library call technique and
3) the interconnection of the ACDL system with the available synthesis techniques to permit complete automated design.

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APPENDIX A<br>Description of the Internal Tables

The tables of the internal form are printed whenever the control. toggle $\$ \mathrm{D}$ is specified in a comment statement (See Table XI). A detailed description of each table is given below. To help clarify the description, an example design program is illustrated below and its corresponding table dump is shown in Table XXIII.
"\$DUMP INTERNAL TABLES AT END OF COMPILATION"
DESIGN 9 ;
DECLARE INPUTS: A,B
CONSTR: $A->$ ? \& $B->$ ?
OUTPUTS: Z1, Z2
GLOBAL: $(\mathrm{A}->0$ WHILE $\mathrm{B}=0)+(\mathrm{B}->0$ WHILE $\mathrm{A}=0)$ $\Rightarrow \mathrm{Z} 1<-0, \mathrm{Z} 2<-0 /$;
START ;
ZOO: $\mathrm{A}->1 \Rightarrow \mathrm{Z} 1<-1 /$;
$\mathrm{Z} 10: \mathrm{B}->1 \Rightarrow \mathrm{Z} 2\langle-1 /$;
Z11: LIST
$\mathrm{A}^{-}>0 \Rightarrow \mathrm{Z} 1<-0 /$,
$\mathrm{B}->0 \Rightarrow \mathrm{Z} 2<-0 /$;
Z01: $\mathrm{A}->1 \Rightarrow \mathrm{Z} 1\langle-1 /$;
END.
TABLE XXIII. A TABLE DUMP OF THE INTERNAL FORM FOR EXAMPLE DESIGN 9

PRIMARY SEQUENCE TABLE

| LEVEL_BIT | LINK_BIT | B_INPUT | E_INPUT | TAB1 | OCHANGE | TAB2 | PTRAN | N_STMT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 |
| 0 | 0 | 0 | 2 | 2 | -5 | 0 | 0 | -1 |
| 0 | 0 | 0 | 1 | 3 | -7 | 0 | 0 | -1 |
| 0 | 1 | 2 | 0 | 4 | -9 | 0 | 0 | -1 |
| 0 | 0 | 1 | 0 | 5 | -11 | 0 | 0 | -1 |
| 0 | 0 | 0 | 2 | 6 | -13 | 0 | 0 | -1 |
| 0 | 0 | 22 | 0 | 0 | 0 | 0 | 0 | 1 |

TABLE XXIII. (Continued)


SPECIAL SYMBOL TABLE

| OLABEL | AL_DIGIT | OINDEX |
| :---: | :---: | :---: |
| 00 | 1 | 1 |
| 10 | 1 | 2 |
| 11 | 1 | 3 |
| 01 | 1 | 5 |

1. Primary Sequence Table

The rows of this table hold $I / O$ specifications of the design. The table's indexing begins with row 0 which corresponds to the START statement. All input-state entries in the table are recorded as decimal weights. The fields of the table are:

1) LEVEL BIT - is set to 1 when the test condition of the statement is a level test rather than a transition test.
2) LINK BIT - is set to 1 whenever another test condition of a link or list statement is to be checked next if the current test condition is not true.
3) B_INPUT - holds either a level input test, the beginning input state of a transition test or a special code for LK'T, ELSE, BEGIN and END conditions. The ELSE, BEGIN and END conditions have the code 222 while LK'T (or LINKTEST) has the code 141.
4) E INPUT - holds the ending input state of a transition test.
5) TAB1 - is a pointer to the next input test in secondary table 1 when don't cares or expressions cause more than one test per test condition. A value of 0 indicates no further tests are to be checked.
6) OCHANGE - contains information leading to the output change of a transition statement. A value of $O$ indicates there is no output change. A positive integer is the address of a Boolean output expression. A negative integer is a pointer to the address of an output value in the standard symbol table.
7) TAB2 - is a pointer to the next output variable change in secondary table 2 when more than 1 output variable changes concurrently in a transition statement.
8) PTRAN - is set to 1 when there exists another input test to be checked as part of a multiple transition expression of the current statement.
9) N_STMT - indicates the next statement to be executed. A positive integer is a pointer to a statement in the primary sequence table. A negative integer indicates automatic linking and denotes the automatic link digit.
2. Secondary Table 1

Whenever a test condition of a transition statement or a link statement implies more than one possible input state transition, this table is used to store these extra input tests. For example in a two variable input design, these extra tests can be the result of unspecified variables in a test condition, "Xl->1", a multiple transition expression, "X1->1 + X2->0", or a don't care transition, 'X1->?". The TAB1 field of the primary sequence table is updated to the row number of the secondary table where the first extra test is stored. The four fields of secondary table 1 are:

1) B_INPUT1 - holds either another level test or the beginning input state of another input transition for the current statement.
2) E_INPUT1 - holds the ending input state of another input transition for the current statement.
3) PTR1 - is a pointer set to 1 when the next input test in this table is to follow the present test for the current statement.
4) MTRAN - is set to $I$ whenever the following input test in the table is to be checked as part of a multiple transition expression of the current statement.
3. Secondary Table 2

When a transition statement contains more than one output change, this table holds the addresses of the additional output changes. The fields of this table are:

1) OCHANGE2 - is the same as the output change field (OCHANGE) of the primary sequence table for the additional output variables of a transition statement.
2) PTR2 - is a pointer set to 1 when the next output change in this table is to follow the present output change for the current statement.
4. Global Transition Table

This table is structurally similar to the primary sequence table, however, it only contains data from globally declared transition statements. It also uses the secondary tables as backup tables. The fields of this table are:

1) GB_INPUT - holds the beginning input state of a global transition test.
2) GE_INPUT - holds the ending input state of a global transition test.
3) GTAB1 - same as TAB1 in primary sequence table, except it is used for global statements.
4) GOCHANGE - same as OCHANGE in primary sequence table except it is used for global statements.
5) GTAB2 - same as TAB2 in primary sequence table except it is used for global statements.
6) GAL DIGIT - denotes the automatic link digit of the corresponding global transition statement.
7) GTRAN - same as PTRAN in the primary sequence table except it is used for global transition statements.
5. Constraints Transition Table

This table stores all constrained input transitions except those declared by "SIC" and "AUS". The fields of this table are:

1) CLEVEL_BIT - is set to 1 when the input test of the constrained transition is a level test rather than a transition test. In this case it is the ending state of an input transition for which the level test is made.
2) CB_INPUT - holds the beginning input state of a constrained input transition.
3) CE INPUT - holds the ending input state of a constrained input transition.
4) CTABl - is a pointer set to 1 when the next row in this table contains another constraint to be checked.
6. Standard Symbol Table

The standard symbol table contains the names of input variables, output variables and standard labels and their corresponding attributes. This table includes the following fields:
i) NAME - contains the names of inputs, outputs and standard 1abels.
2) VALUE - contains the value of a variable or the primary sequence table index of a label.
3) TKN - is a token field which is set to 0,1 or 2 for distinguishing labels, input variables, and output variables, respectively.
4) POSITION - indicates the position of the input and output variables in an input and output state, respectively.

## 7. Special Symbol Table

This table is used to hold output labels and associated information. It plays an important role in the automatic linking process. The fields of this table are:

1) OLABEL - contains the binary string representation of an output state which is designated in an output label.
2) AL_DIGIT - contains the automatic link digit of the output label. If no digit is specified it defaults to 1.
3) OINDEX - contains the index of the corresponding statement in the primary sequence table.

## APPENDIX B <br> Use of the Logic Trace Switch "\$W"

The logic trace was extremely useful in debugging the translator/ interpreter program. For this reason the trace was not removed. Instead, it is made readily available to the user in case changes to the language or program are desired in the future. The following will be a general description of the meaning and use of the information obtained when the logic trace is activated.

The logic trace is a built-in trace of the translator and flow table construction program. Within the XPL program listing, the location of trace output statements is easily recognized because they have the following format: "If T_SW>0 then ...".

Whenever the logic trace is activated, the trace information follows the $X P L$ program flow from procedure to procedure and within a procedure. Most of the trace information is just the current values of some variables. In these cases the variable names and their values are given. Comments defining all variables have been given in the program at their place of declaration. In a few cases duplicate information is seen, but two different procedures have output this information which allows the user to follow the procedure to procedure flow more easily.

If the logic trace, $\$ W$, is activated at the beginning of the design, a trace of the entire translation and flow table construction procedure is given. If "\$W" is specified both at the beginning and end (i.e. ahead of END.) of the design, then the trace is only turned
on for the translation process. Similarly if "\$W" is only specified at the end of the design, the trace is just turned on for the flow table construction portion of the program.

## APPENDIX C

Job Setup

This appendix provides the job setup or job control language (JCL) requirements for using the $A C D I$ system on the $I B M$ System 360 computer. The following listing shows the necessary cards to run an ACDL program when the $A C D L$ translator/interpreter program is in object form and is residing on disk.
$/ / \mathrm{OS} \quad$ Job Card
$/ / \% \quad \operatorname{LIMITS}=(\mathrm{R}=130)$
//S1 EXEC XPLG
//G.PGM DD DSN=USER.SO150.TRACEY.ACDL.BEDNAR,
// VOL=SER=USERVL,DISP=OLD,UNIT=DISK
//G.DATA DD *
.

ACDL Program
$1 *$
If a recompilation of the translator/interpreter program is required, the job setup for this is:
//OS Job Card
$/ / * \operatorname{LIMITS}=(\mathrm{R}=(250), \mathrm{T}=5, \mathrm{P}=100)$
//SI EXEC XPLC
//C.FILE1 DD DSN=USER.S0150.TRACEY.ACDL.BEDNAR,
// VOL=SER=USERVL,DISP=OLD,UNIT=DISK
//C.SOURCE DD *
-

Source deck of XPL program
$1 *$
The job setup for running an $A C D L$ program with the translator/
interpreter program in source deck form is:

```
    //OS Job Card
    //% LIMITS = ( }\textrm{R}=(250),\textrm{T}=5,\textrm{P}=200
    //S1 EXEC XPLCG
    //C.SOURCE DD *
        Source Deck of XPL Program
        .
    1*
    //G.DATA DD *
        •
        ACDL Program
            .
    1*
The job setup for a BNF ANALYZER run is:
    //OS Job Card
    //* LIMITS = (R=150, P=40,T=5,C=100)
    //S1 EXEC XANALYZE
    //XPL.SYNTAX DD *
        \bullet
        BNF Description of ACDL
    $PUNCH
    /*
```

APPENDIX D<br>BNF Description of ACDL<br>for the Translator Writing System

In order to conserve computer storage and execution time the parsing algorithm of the ANALYZER program has the restriction of being context bounded. Specifically, it will parse only those grammars for which it can compute the stacking decision function by using no more than the top 2 symbols in the stack and the next symbol in the input text, and the production selection function, by using no more than 1 symbol below the production in the stack and the next symbol in the input text [17].

In order to make the BNF grammar of ACDL compatible to the context restrictions of ANALYZER, some changes to the description of Chapter III are required. The modified version of the grammar which was used as input to ANALYZER is shown below. In some cases, commas and parentheses required special definitions since these symbols were inadequate contexts for decision making.

To incorporate changes or extensions to the current structure of ACDL into the translator program, deletions, additions or modifications are made as necessary to the productions shown in the BNF description below. The job setup for an ANALYZER run is given in APPENDIX C.

The following is the present ANALYZER version of the BNF grammar for $A C D L$ as it appears in the program listing.

```
<PROGRAM> ::= <PROGRAM HEAD> <STATEMENT LIST> <ENDING>
<STATEMENT LIST> ::= <STATEMENT>
    | <STATEMENT LIST> <STATEMENT>
<PROGRAM HEAD> ::= <DESIGN STMT> ; <DECLARE STMT> ; <START STMT>
<STATEMENT> ::= <BASIC STMT>
    | <STMT BLOCK> ;
<BASIC STMT> ::= <TRANSITION STMT> ;
    | <INK STMT> ;
    | <LIST STMT> ;
    | <LABEL> <BASIC SIMT>
<ENDING> ::= END
    | <LABEL> END
<BEGINNING> ::= BEGIN ;
    | <LABEL> BEGIN ;
<LABEL> ::= <SINGLE LABEL> :
    | <LETTER Z> <(2> <OUTPUT STATE SET> ) :
<SINGLE LABEL> ::= <IDENTIFIER>
    | <IDENTIFIER> / <NUMBER>
<LETTER Z> ::= <IDENTIFIER>
<OUTPUT STATE SET> ::= <OUTPUT CODE>
    | <OUTPUT STATE SET> , <OUTPUT CODE>
<OUTPUT CODE> ::= <NUMBER>
    | <NUMBER> / <NUMBER>
```

```
\DESIGN STMT> ::= DESIGN
    DESIGN <ACCOUNTING INFO>
<ACCOUNTING INFO> ::= <DESIGN NUMBER>
    <DESIGN NUMBER> <,3> <DESIGNERS NAME>
    <DESIGN NUMBER> <,3> <DESIGNERS NAME> <,3> <DATE>
<,3> ::= ,
<DESIGN NUMBER> ::= <NUMBER>
<DESIGNERS NAME> ::= <IDENTIFIER>
    | <DESIGNERS NAME> <IDENTIFIER>
<DATE> ::= <IDENTIFIER> <NUMBER> , <NUMBER>
<DECLARE STMT> ::= DECLARE <DECLARATION TYPE>
    <ECCLARE STMT> <DECLARATION TYPE>
<DECLARATION TYPE> ::= <INPUT DCL>
            | <CONSTRAINTS DCL>
            <OUTPUT DCL>
            <GLOBAL DCL>
<INPUT DCL> ::= INPUTS : <VARIABLE DEFN>
    <INPUT DCL> <,2> <VARIABLE DEFN>
<VARIABLE DEFN> ::= <IDENTIFIER>
    | <IDENTIFIER 1> <INITIAL CONDITION>
<IDENTIFIER 1> ::= <IDENTIFIER>
<INITIAL CONDITION> ::= <(l> <IEVEL> )
```

```
<(l> ::= (
<CONSTRAINTS DCL> ::= CONSIR : <CONSTRAINTS>
<CONSTRAINTS> ::= NONE
                                AUS
    SIC
    <TRANSITION TERM>
    | <LEVEL FACTOR>
    |CONSTRAINTS> <,2> <TRANSITION TERM>
    <CONSTRAINTS> <,2> <IEVEL FACTOR>
<TRANSITION EXPRESSION> ::= <TRANSITION TERM>
            | <TRANSITION EXPRESSION> + <TRANSITION TERM>
            | <DUMMY TERM>
<DUMMY TERM> ::= LINKTEST
    | LK'T
<COMPOUND REIATION> ::= <TRANSITION PART> WHILE <IEVEL PART>
<TRANSITION PART> ::= <TRANSITION FACTOR>
    l <(2> <TRANSITION FACTOR> )
<LEVEL PART> ::= <IEVEL FACTOR>
    | <(2> <IEVEL FACTOR> )
<TRANSITION TERM> ::= <TRANSITION PART>
    | <COMPOUND REIATION>
    | <(2> <COMPOUND RELATION> )
<2> ::= (
```

```
<TRANSITION FACTOR> ::= <TRANSITION REIATION>
    | <TRANSITION FACTOR> & <TRANSITION REIATION>
<LEVEL FACTOR> ::= <LEVEL RELATION>
    | <LEVEL FACTOR> & <LEVEL RELATION>
<TRANSITION RELATION> ::= <IDENTIFIER> = <TRANSITION>
    <IDENTIFIER> <SHORT TRAN>
<LEVEL RELATION> ::= <IDENTIFIER> = <LEVEL>
<LEVEL> ::= <NUMBER>
<TRANSITION> ::= <NUMBER> - > <NUMBER>
<SHORT TRAN> : := - > <NUMBER>
OUTPUT DCL\ ::= OUTPUTS : <VARIABLE DEFN>
    | OUTPUT DCL> <,2 < VARIABLE DEFN
<,2> ::= ,
GLOBAL DCL: :}:= GLOBAL : <LIST>
START STMT> : := START ;
STMT BLOCK` ::= <BEGINNING> <STATEMENT ITST> &NDING:
TRANSITION STMT: ::= <BASIC TRAN STMT`
    | <AUTO LINK TRAN STMT.
<BASIC TRAN STMT: : := <TRANSITION EXPRESSION
    | <IRANSITION EXPRESSION> = \ OUTPUT CHANGE
```

```
<AUTO LINK TRAN STMT> ::= <BASIC TRAN STMT> <AUTO LINK>
<AUTO LINK> ::= /
    | / <NUMBER>
<OUTPUT CHANGE> ::= <IDENTIFIER> <REPLACEMENT OP> <OUTPUT EXPRESSION>
    | <OUTPUT CHANGE> <,I> <IDENTIFIER> <REPIACEMENT OP> <OUTPUT EXPRESSION>
<REPIACEMENT OP> ::= < -
<OUTPUT EXPRESSION> ::= <IEVEL>
        | <BOOL EXPR>
<BOOL EXPR> ::= <LOG FACTOR>
        <BOOL EXPR> + <LOG FACTOR>
<LOG FACTOR> ::= <LOG TERM>
    | <LOG FACTOR> & <LOG TERM>
<LOG TERM> ::= <LOG PRIMARY>
    | \ <LOG PRIMARY>
<LOG PRIMARY> ::= <IDENTIFIER>
    | < 2> <BOOL EXPR> )
<LINK STMT> ::= LINK <PARANETER LIST>
<PARAMETER LIST> ::= <NO TESTS>
            |<1 TEST> <1 LABEL>
            | <2 TESTS> <2 LABELS:
            | <3 TESTS> <3 IABELS>
            | <4 TESTS> <4 LABELS
            | <5 TESTS> <5 LABELS>
            <6 TESTS>><6 LABELS
```



```
    131 <LIST STMT> ::= LIST <LIST>
    132 <LIST> ::= <AUTO LINK TRAN STMT>
133 | <LIST> <,1> <AUTO LINK TRAN STMT>
$PUNCH
```


## APPENDIX E

Program Structure

The ACDL translation and flow table construction program consists of 44 procedures. Figure 6 indicates the overall structure of the program with respect to these procedures.


Figure 6. Structure of the ACDL Translator/Interpreter Program





APPENDIX F

Procedure Descriptions

This appendix presents a description of the procedures composing the translator and flow table synthesis algorithm. A brief description of the procedures' main functions is given. Functional flow charts accompany those procedure descriptions which require a more detailed explanation; however, their emphasis is directed toward the synthesis procedures rather than the analysis (parsing) procedures, since it is these procedures that are ACDL dependent.

1. MAIN_PROCEDURE Procedure*

This procedure is the main entry point of the program. It is the master control for the translation process and collects timing information for the different phases of the translation.
2. INITIALIZATION Procedure*

This procedure prints the headings for the compilation listing. It initializes the character classes for the scanner and various other global variables. No initializations of 0 have to be made since all variables are automatically initialized to 0 (or null in the case of character string variables) by the XPL compiler, XCOM, unless otherwise indicated.
3. PRINT_DATE AND_TIME Procedure*

This procedure decodes the date into year, month and day, and then calls PRINT_TIME to print it.

[^0]4. PRINT TIME Procedure*

This procedure decodes time from hundreds of seconds into hours, minutes and seconds, and prints it together with its message parameter.
5. SCAN Procedure*

An ACDL program consists of a sequence of symbols interspersed with blanks and comments. A call to SCAN either produces the next symbol, removes the blanks and comments, or is responsible for the setting and resetting of control toggles.
6. GET_CARD Procedure*

This procedure reads a source card and stores it in the global character variable TEXT. It also prints the card image unless control toggle $\$ \mathrm{~L}$ has been specified, which inhibits the source program 1isting.
7. CHAR Procedure*

This procedure is used to advance the scan pointer by one character and to get a new card if necessary.
8. I FORMAT Procedure*

This procedure right justifies an integer in the field width specified.
9. ERROR Procedure*

This procedure prints error messages, counts total errors and severe errors and terminates compilation in case of excessive errors.
10. COMP ILATION_LOOP Procedure*

This procedure coordinates the stacking of symbols and their

[^1]reduction according to the $B N F$ constructs. A flow chart for this procedure is shown in Figure 7 .
11. STACKING Procedure*

This procedure is the basic decision function of the parsing algorithm. When the function is true, a symbol is stacked; when it is false, a reduction is made. If an error is detected, a recovery is initiated and a new value is computed.
12. RECOVER Procedure*

This procedure removes enough of the parse stack and input text to ensure that translation can proceed at least one more step without further errors. In many cases this procedure prevents single errors from causing multiple messages.
13. RIGHT_CONFLICT Procedure*

The most recently scanned symbol is stored in the global variable TOKEN. This procedure decides if a string in the parse stack is reducible on the basis that the result of the reduction must yield an allowed pair between the top of the stack and TOKEN. Similarly, when an error is encountered, parsing is not resumed until an allowed pair is in TOKEN and on top of the parse stack.
14. STACK_DUMP Procedure*

When syntactic errors are discovered by the analysis algorithm, the state of the parse stack is printed by this procedure as a diagnostic aid.
15. REDUCE Procedure*

This procedure looks up the proper reduction, calls SYNTHESIZE

[^2]to produce the associated semantic action and then makes the reduction.
16. PR_OK Procedure*

When there is more than one reducible string on the parse stack, this procedure uses the syntactic analysis tables to choose the proper reduction.

## 17. SYNTHESIZE Procedure

This procedure and the procedures it calls compose the semantic routines that are inserted into the skeleton deck. Corresponding to each production recognized by REDUCE, this procedure takes appropriate action to produce code and data images of the program being translated. Flow charts describing the action to be taken at the important productions are given in Figure 8. The case number corresponds to the position of the production in the BNF description of Appendix D. No action is taken in the cases not shown.
18. SPEC_LOOKUP Procedure

This procedure is a function procedure with two arguments, the output state symbol being searched for and the corresponding automatic link digit of the output state. The procedure searches the special symbol table in a sequential manner for the output symbol and automatic link digit passed to it. If the output symbol and correct automatic link digit are not found, the procedure will add them to the table. The row number of the symbol table in which the arguments were found (or added) is returned as the value of the function.

[^3]19. STD LOOKUP Procedure

This procedure is a function procedure with the symbol being searched for as its argument. The procedure sequentially searches the standard symbol table for the symbol passed to it. If the symbol is not found, the procedure will add the symbol to the table. The row number of the table in which the symbol was found (or added) is returned as the value of the function.

## 20. ENDING Procedure

This procedure is used to handle the ends of statement blocks and the end of the design (see Figure 9).
21. BEGINNING Procedure

This procedure is a special procedure used to handle the beginning of statement blocks. A flow chart for this procedure is shown in Figure 10.
22. PAD_ZEROS Procedure

This procedure adds zeros on the left of an integer until the specified field width is reached.
23. VARSTORE Procedure

This procedure stores input and output variables and their corresponding attributes in the standard symbol table via the function procedure STD_LOOKUP.
24. CONSTR_TRAN Procedure

This procedure controls the construction of the constraint transition table. A flow chart describing this procedure is illustrated in Figure 11.
25. DEC XFM Procedure

This procedure transforms a binary representation of an input transition or level to a decimal representation as indicated in Figure 13.
26. DC_TRAN Procedure

This procedure is used to handle the don't-care shorthand transition. The flow chart describing this procedure is illustrated in Figure 13.
27. MULTI_TRAN Procedure

This procedure stores the additional input transitions resulting from don't-cares and multiple transition expressions in secondary table 1. Figure 14 illustrates the flow chart for this procedure. 28. OVAR_CHK Procedure

This procedure checks the standard symbol table to see if output variables in transition statements have been properly defined. If not, an error message is printed.
29. IVAR_CHK Procedure

This procedure checks the standard symbol table to see if input variables in transition statements have been properly defined. If not, an error message is printed.
30. POLISHX Procedure

This procedure translates a Boolean infix expression to Reverse Polish format. A flow chart describing this procedure is given in Figure 15.
31. CTRAN_STORE Procedure

This procedure stores the input constraints in the constraint transition table. The flow chart for this procedure is illustrated in Figure 16.

## 32. EXPN Procedure

This is a function procedure which performs the exponentiation operation. The result is returned as the value of the function.
33. PRINT_SUMMARY Procedure*

This procedure prints the statistics of the translation which includes error statistics and translation times and rates. It also calls DUMPIT procedure to dump the internal tables if $\$ \mathrm{D}$ was given in an ACDL comment.
34. DUMPIT Procedure

This procedure dumps the internal form tables whenever the control toggle $\$ \mathrm{D}$ is specified in an $A C D L$ comment.
35. FLOW_TABLE Procedure

This procedure controls the construction of the primitive flow table. Its flow chart is shown in Figure 17.
36. LINKAGE Procedure

This is a function procedure which is a housekeeping routine for the state linkage table. The state linkage table records the internal states (i.e. flow table row numbers) that have been defined. Therefore, this procedure determines whether or not a correct next-state entry has been previously defined. If not, it defines a new state and records it in the state linkage table. The procedure has 3 arguments; the current input column state, the sequence 非 attribute of the next state, and the output attribute of the next state. The procedure returns the proper next-state entry as the value of its function. The flow chart for this procedure is given in Figure 18.

[^4]37. PRIMARY_TABLE Procedure

This procedure checks the primary sequence table to see if the current input transition was specified in the design. A flow chart describing this procedure is shown in Figure 19.
38. GLOBAL TABLE Procedure

This is a function procedure which checks the global transition table to see if the current input transition is a global transition. If so, the procedure returns a value of true as the value of its function. A flow chart describing this procedure is given in Figure 20.
39. CONSTR_TABLE Procedure

This is a function procedure which checks the constraint transition table to see if the current input transition is a constraint transition. If so, the procedure returns a value of 1 , otherwise 0. The flow chart for this procedure is given in Figure 21.
40. TABLEI_SEARCH Procedure

This is a function procedure which searches secondary table lor additional input test conditions resulting from don't cares or multiple transition expressions. The value returned by the procedure indicates the point where the calling procedure is to continue. Figure 22 illustrates the flow chart for this procedure. 41. TABLE2_SEARCH Procedure

This procedure searches secondary table 2 for additional output changes whenever more than one output variable changes concurrently in a transition statement. The flow chart for the procedure is shown in Figure 23.
42. POLISH_EXEC Procedure
This procedure interpretively executes a Reverse Polish Boolean
expression. A flow chart of the procedure is given in Figure 24.
43. OUTPUT_FLOW_TABLE Procedure
This procedure is used to print the resul, ing primitive flow
table in its standard format. Stable states are indicated by attach-
ing a minus sign to the next-state entry.
44. PAD Procedure*
This is a function procedure with two arguments; a character
string variable and a format field width. The procedure adds blanks
to the right of the character string variable to give it the field
width specified. The padded string is then returned by the procedure.

[^5]

Figure 7. Flow Chart of COMPILATION_LOOP Procedure


Figure 8. Flow Chart of SYNTHESIZE Procedure

Case 1. <PROGRAM> : : \llPROGRAM HEAD> <STATEMENT IIST><ENDING>.


Figure 8. (Continued)

Case 5. <STATEMENT> ::=<BASIC STMT>


Case 7. <BASIC STMT> ::= <TRANSITION STMT>


Figure 8. (Continued)

```
Case 11. <ENDING> ::= END
Case 12. | <LABEL> END
```



Case 13. <BEGINNING> : : = BEGIN;
Case 14. | <LABEI> BEGIN;


Figure 8. (Continued)

```
Case 17. <SINGIE LABEL> ::= <IDENTIFIER>
```



Figure 8. (Continued)


Figure 8. (Continued)

## Case 19. <LETTER Z> ::= <IDENTIFIER>



Figure 8. (Continued)

Case 22. <OUTPUT CODE> : : = <NUMBER>


Figure 8. (Continued)

Case 23. <OUTPUT CODE> : := <NUMBER> / <NUMBER>


Figure 8. (Continued)

Case 30. <DESIGN NUMBER> : : = <NUMBER >


Case 31. <DESIGNERS NAME> : := <IDENTIFIER>
Case 32. $\mid<$ DESIGNERS NAME $><$ IDENTIFIER>


Figure 8. (Continued)


Case 36. <DECLARATION TYPE> : := <INPUT DECIARATION>


Case 42. <VARIABLE DEFN> : : = <IDENTIFIER>


Call VARSTORE
to store input (or output) variable.

End

```
Figure 8. (Continued)
```

Case 48. <CONSTRAINTS> : : = NONE


Case 49. <CONSTRAINTS> : := AUS


Case 50. <CONSTRAINTS> : := SIC


Figure 8. (Continued)

```
Case 51. <CONSTRAINTS> ::= <TRANSITION TERM>
Case 53. 1 <CONSTRAINTS><<,2>
                                    <TRANSITION TERM>
```



Case 52. <CONSTRAINTS> : := <LEVEL FACTOR>
Case 54. | <CONSTRAINTS $><, 2\rangle$ <LEVEL FACTOR>


Figure 8. (Continued)

Case 55. <TRANSITION EXPRESSION> : : = <TRANSITION TERM>


Figure 8. (Continued)

Case 56. <TRANSITION EXPRESSION> ::= <TRANSITION EXPRESSION> + <TRANSITION TERM>


Case 58. <DUMMY TERM> ::= LINKTEST
Case 59. | LKK'T


Figure 8. (Continued)

```
Case 76. <LEVEL>>::= <NUMBER>
```



Figure 8. (Continued)


Figure 8. (Continued)

Case 77. <TRANSITION> : : = <NUMBER> - > <NUMBER>


Figure 8. (Continued)

Case 78. <SHORT TRAN $>:=-><$ NUMBER $\rangle$


Figure 8. (Continued)

Case 79. <SHORT TRAN> : : $=->$ ?


Figure 8. (Continued)

Case 83. <GLOBAL DCL> : := GLOBAL : <LIST>


Case 84. <START STMT> : : = START ;


Figure 8. (Continued)


Figure 8. (Continued)

```
Case 86. <TRANSITION STMT> ::= <BASIC TRAN STMT>
```



Case 91. <AUTO LINK> : : = /


Figure 8. (Continued)

```
Case 92. <AUTO LINK> ::= / <NUMBER>
```



Case 93. <OUTPUT CHANGE> : : = <IDENTIFIER> <REPLACEMENT OP> <OUTPUT EXPRESSION>


Figure 8. (Continued)


Figure 8. (Continued)

Case 94. <OUTPUT CHANGE> : := <OUTPUT CHANGE><, $>\ll$ IDENTTFIER> $<$ REPLACEMENT OP> <OUTPUT EXPRESSION>


Figure 8. (Continued)

Case 94. (Continued)


Figure 8. (Continued)

Case 97. <OUTPUT EXPRESSION> : := <BOOL EXPR>


Figure 8. (Continued)

Case 105. <LOG PRIMARY $>:=<(2><$ BOOL EXPR $>)$


Case 106. <LINK STMT> : := LINK <PARAMETER LIST>


Case 107. <PARAMETER LIST> : : = <NO TESTS>


Figure 8. (Continued)

```
Case 115. <1 TEST \(>:=\ll 1\rangle<\) TEST CONDITION:
```



Case 128. <TEST CONDITION> : := <TRANSITION EXPRESSION>


Figure 8. (Continued)


Figure 8. (Continued)


Case 131. <LIST STMT> : : = LIST <LIST>


Figure 8. (Continued)


Figure 8. (Continued)

Case 133. <LIST> : : = <LIST $\rangle\langle, I\rangle\langle$ AUTO LINK TRAN STMT>


Figure 8. (Continued)



Figure 10. Flow Chart of BEGINNING Procedure


Figure 11. Flow Chart of CONSTR_TRAN Procedure


Figure 12. Flow Chart of DEC_XFM Procedure


Figure 13. Flow Chart of DC_TRAN Procedure


Figure 14. Flow Chart of MULTI_TRAN Procedure


Figure 15. Flow Chart of POLISHX Procedure


Figure 16. Flow Chart of CTRAN_STORE Procedure


Figure 17. Flow Chart of FLOW_TABLE Procedure


Figure 17. (Continued)


Figure 18. Flow Chart of LINKAGE Procedure


Figure 19. Flow Chart of PRIMARY_TABLE Procedure


Figure 19. (Continued)


Figure 20. Flow Chart of GLOBAL_TABLE Procedure


Figure 20. (Continued)


Figure 21. Flow Chart of CONSTR_TABLE Procedure


Figure 22. Flow Chart of TABLE1_SEARCH Procedure


Figure 22. (Continued)


Figure 23. Flow Chart of TABLE2_SEARCH Procedure


Figure 24. Flow Chart of POLISH_EXEC Procedure


[^0]:    ${ }^{*}$ This procedure is part of the original proto-compiler SKELETON of TWS [17].

[^1]:    This procedure is part of the original proto-compiler SKELETON of TWS [17].

[^2]:    *This procedure is part of the original proto-compiler SKELETON of TWS [17].

[^3]:    *This procedure is part of the original proto-compiler SKELETON of TWS [17].

[^4]:    *This procedure is part of the original proto-compiler SKELETON of TWS [17].

[^5]:    * This procedure is part of the original proto-compiler SKELETON of TWS [17].

