

INFLUENCE OF EDGE CRACK ON FREQUENCIES OF THIN PLATE IN BENDING

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Abstract. This paper investigates the influence of crack location and crack length on changes in natural frequencies of bending thin plate. To perform this analysis, a computing program called CRACK-PLATE, using the finite element method based on the Rössner-Mindlin' theory of plate is developed. In order to achieve a high accuracy, an isoparametric element of Barsoum is combined with an 8-node quadrilateral isoparametric element. The numerical results show that the natural frequencies are very sensitive to the crack presence in the bending thin plate. This study is a basis for crack identification based on natural frequencies of plates.

Key words. Bending cracked plate, frequency, finite element method, Rössner-Mindlin' theory of plate, element of Barsoum.

1. INTRODUCTION

Crack has great influence on load carrying capacity and lifetime of structures. The problem of exact determining the crack position and depth is very important, from there; one can predict the real capacity of structures and propose a timely solution to prevent damages.

In recent years, several authors have carried out natural frequency analysis of cracked beams [1-2] to detect the presence of a crack in beams, and determine its location and size, based on experimental dynamic analysis results... Meanwhile, crack detection in plates has been little mentioned. Cawley and Adams [3] introduced an effective method of non-destructively assessing the integrity of structures using measurements of the structural natural frequencies obtained from tests on an aluminum plate. Recently, Wu and Law [4] proposed a damage localization method for two-dimensional plate structures, based on changes in uniform load surface (ULS) curvature. However, these studies are mainly experimental. Thus, a study for influence of crack on frequency of plate is necessary and has real meaning. It provides a basis to perform the inverse problem for crack detection in plate using changes in frequencies.

This paper aims to study the influence of crack location and crack length on changes in frequencies of cantilever thin plate, by the computing program CRACK-PLATE written by Matlab 6.0 language, using the finite element method with an 8-node quadrilateral isoparametric element based on the Rössner-Mindlin' theory of plate. An isoparametric element of Barsoum, in which, the mid-side nodes are moved to quarter-point position, is combined to achieve the singularity near crack tip in linear elastic fracture mechanics. To verify the reliability of the CRACK-PLATE program, the numerical results are compared with ANSYS program.

2. GENERAL FORMULATION

2.1. Free vibration problem

The equation of motion of a undamped free vibration structure are determined in the form [5]:

$$[M] \{\ddot{q}\} + [K] \{q\} = \{0\}, \tag{2.1}$$

where $[M]$ is the mass matrix, $[K]$ is the stiffness matrix, $\{q\}$ is the displacement vector and $\{\ddot{q}\}$ is the acceleration vector.

It will be assumed that the free vibration of structure is harmonic with natural circular frequency ω and amplitude $\{\bar{q}\}$ so equation (2.1) can be rewritten:

$$([K] - \omega^2 [M]) \cdot \{\bar{q}\} = \{0\}, \tag{2.2}$$

where $\omega = 2\pi f$, f is natural vibration frequency. Hence, a nontrivial solution is possible only when

$$\det ([K] - \omega^2 [M]) = 0 \tag{2.3}$$

Expanding the determinant of equation (2.3) will give an algebraic equation of the n^{th} degree in the frequency parametric ω^2 for a structure having n degree of freedom. The n roots of this equation represent the frequencies of the n modes of vibration that are possible in the structure.

2.2. Basic fracture mechanics

Fracture mechanics admits the existence of an initial fissure in the structure under consideration that defines a local and irreversible separation of a continuous milieu at two borders, calls crack surfaces. The external sollicitation tends to extend the fissures to different modes. There are three independent kinematical movements of the upper and lower crack surfaces with respect to each other and these are categorized as [6]:

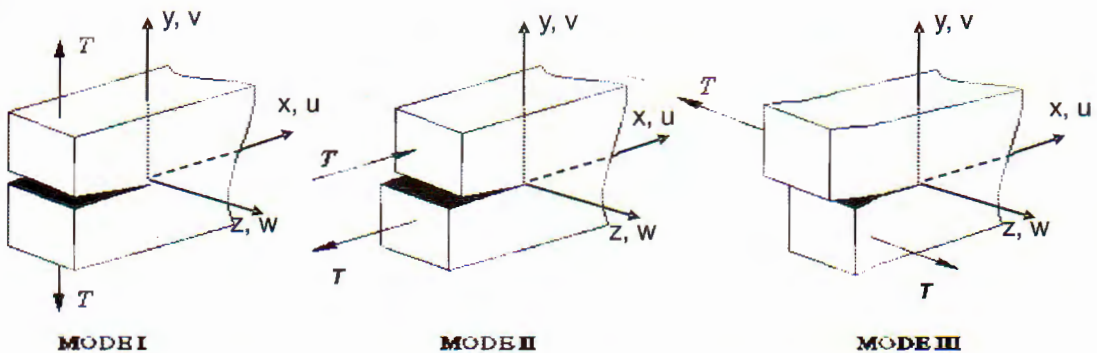


Fig. 1. The three modes of crack opening deformation

Opening mode (mode I): in which the two crack surfaces are pulled apart in their direction, but where the deformations are symmetric about the $x - z$ and $x - y$ planes.

Sliding mode (mode II): in which the two crack surfaces slide over each other in the x -direction, where the deformations are symmetric about the $x-y$ plane and skew symmetric about $x-z$ plane.

Tearing mode (mode III): in which the two crack surfaces slide over each other in the z -direction, where the deformations are skew symmetric about the $x-y$ and $x-z$ planes.

The appropriate superposition of these three modes describes the general case of cracking.

2.3. Quadratic isoparametric element

The shape functions for 8-node quadrilateral isoparametric element are given below [7]:

$$N_i(\xi, \eta) = \frac{\xi_i^2 \eta_i^2}{4} [(1 + \xi \xi_i)(1 + \eta \eta_i) - (1 - \xi^2)(1 + \eta \eta_i) - (1 - \eta^2)(1 + \xi \xi_i)] \\ + \frac{\xi_i^2}{2} (1 - \eta^2)(1 + \xi \xi_i)(1 - \eta_i^2) + \frac{\eta_i^2}{2} (1 - \xi^2)(1 + \eta \eta_i)(1 - \xi_i^2), \quad (2.4)$$

where $\xi_i, \eta_i = \pm 1$ at corner nodes and zero at mid-side nodes.

Stiffness matrix of element

The Reissner-Mindlin' theory of plate includes the effect of transverse shear deformation. Hence, the internal energy expression for the shear deformable plate should include the transverse shear energy as well as the bending energy and expressed as [7]:

$$U = \frac{1}{2} \int_V \{\varepsilon_b\}^T [D_b] \{\varepsilon_b\} dV + \frac{\kappa}{2} \int_V \{\varepsilon_s\}^T [D_s] \{\varepsilon_s\} dV, \quad (2.5)$$

where $\{\varepsilon_b\}, \{\varepsilon_s\}$ are the bending and shear strains; κ is the shear energy correction factor and equal to $\frac{5}{6}$; $[D_b], [D_s]$ are the bending and shear elasticity coefficient matrices, which are defined as follows:

$$[D_b] = \frac{E}{1 - \nu^2} \begin{bmatrix} 1 & \nu & 0 \\ \nu & 1 & 0 \\ 0 & 0 & \frac{1-\nu}{2} \end{bmatrix}. \quad (2.6)$$

$$[D_s] = \frac{E}{2(1 + \nu)} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \quad (2.7)$$

in which E is the module of Young, ν is the Poisson's coefficient.

The element stiffness matrix for plate bending is expressed as:

$$[K_e] = \frac{h^3}{12} \int_{-1}^1 \int_{-1}^1 [B_b]^T [D_b] [B_b] |J| d\xi d\eta + \kappa h \int_{-1}^1 \int_{-1}^1 [B_s]^T [D_s] [B_s] |J| d\xi d\eta, \quad (2.8)$$

where h is the plate thickness. The matrices B_b, B_s are defined as

$$[B_b] = \begin{bmatrix} \frac{\partial N_i}{\partial x} & 0 & 0 \\ 0 & \frac{\partial N_i}{\partial y} & 0 \\ \frac{\partial N_i}{\partial y} & \frac{\partial N_i}{\partial x} & 0 \end{bmatrix}, \quad [B_s] = \begin{bmatrix} -N_i & 0 & \frac{\partial N_i}{\partial x} \\ 0 & -N_i & \frac{\partial N_i}{\partial y} \end{bmatrix} \quad (2.9)$$

and

$$[J] = \begin{bmatrix} \frac{\partial x}{\partial \xi} & \frac{\partial y}{\partial \xi} \\ \frac{\partial x}{\partial \eta} & \frac{\partial y}{\partial \eta} \end{bmatrix} = \begin{bmatrix} \cdot & \cdot & \cdot & \frac{\partial N_i}{\partial \xi} & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \frac{\partial N_i}{\partial \eta} & \cdot & \cdot & \cdot \end{bmatrix} \begin{bmatrix} \vdots & \vdots \\ x_i & y_i \\ \vdots & \vdots \end{bmatrix} \quad (2.10)$$

One thing to be noted in equation (2.8) that the shear energy becomes dominant compared to the bending energy as the plate thickness becomes very small compared to its side length. This is called a shear locking. To resolve this problem, the selective or reduced integration technique was proposed. For 8-node isoparametric element is used, the 3×3 Gauss-Legendre quadrature is used for the bending term and the 2×2 point integrations is used for the shear term.

Consistent mass matrix of element

In the normalized square space (ξ, η) , $(-1 \leq \xi \leq 1, -1 \leq \eta \leq 1)$, the consistent mass matrix of element can be obtained [9]:

$$[M_e] = \rho h \int_{-1}^1 \int_{-1}^1 [N_1]^T [N_1] |J| d\xi d\eta + \frac{\rho h^3}{12} \int_{-1}^1 \int_{-1}^1 [N_2]^T [N_2] |J| d\xi d\eta, \quad (2.11)$$

in which

$$[N_1] = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & N_i \end{bmatrix} \quad , \quad [N_2] = \begin{bmatrix} -N_i & 0 & 0 \\ 0 & -N_i & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

where N_i is the shape functions and are given by equation (2.4). Equation (2.11) is computed with 3×3 point integrations Gauss-Legendre.

2.4. Isoparametric element of Barsoum

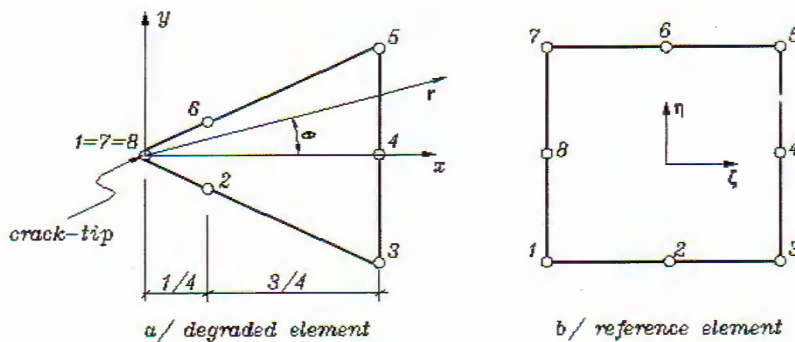


Fig. 2. Triangular element of Barsoum

Utilizing triangular element of Barsoum [8], we obtain the singularity $1/\sqrt{r}$ of strain at the crack tip of that element by degrading an edge of the quadrilateral element and moving the mid-side nodes to the quarter point adjacent to the crack-tip (Fig.2).

For this element, Barsoum has shown that:

$$\begin{aligned} \frac{\partial u}{\partial x} &= \frac{A_0}{\sqrt{r}} + A_1, \\ \frac{\partial u}{\partial y} &= \frac{B_0}{\sqrt{r}} + B_1, \\ \frac{\partial v}{\partial x} &= \frac{C_0}{\sqrt{r}} + C_1, \\ \frac{\partial v}{\partial y} &= \frac{D_0}{\sqrt{r}} + D_1, \end{aligned} \tag{2.12}$$

where $A_0, A_1, B_0, B_1, C_0, D_0, D_1$ are constants. Thus, the use of the Barsou's s element can describe the singularity of strain and stress fields around crack-tip in the plate.

3. NUMERICAL RESULTS AND DISCUSSION

3.1. Investigative procedure

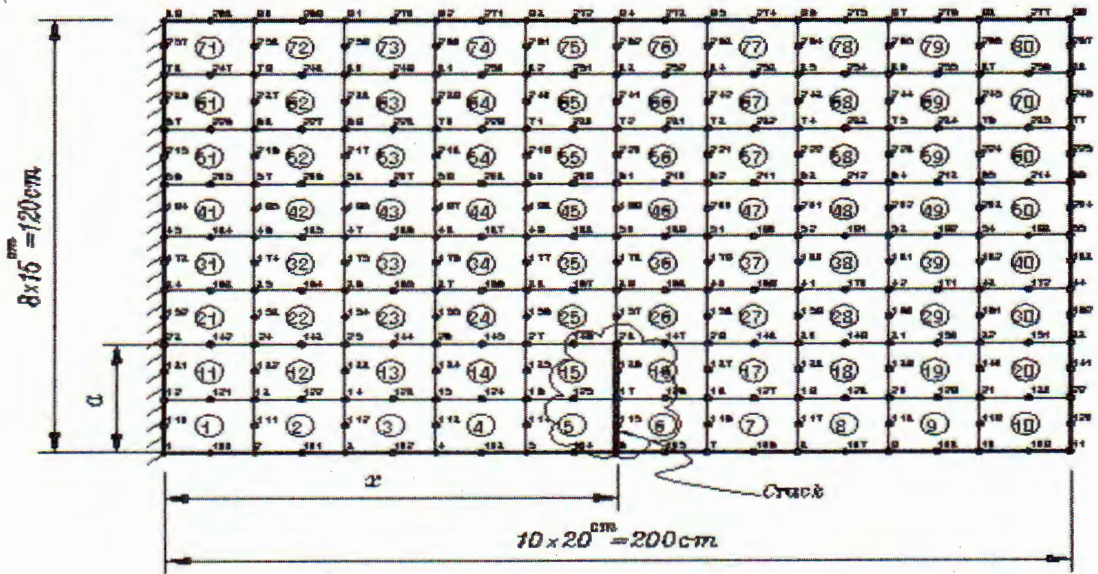


Fig. 3. Bending plate with an edge crack

Problem: Investigate the influence of crack location and crack length on changes in frequencies of bending thin plate with an edge crack (Fig.3). The computing program CRACK-PLATE, developed by Matlab 6.0 language, performs this problem.

Modeling of the problem: cantilever plate is meshed into 80 elements with an edge crack. Three d.o.f., which are translational along the Z-axis (w) and rotational along the X- and Y-axis (θ_x, θ_y), are used at each node. It is assumed that the crack location and the lines of mesh are coincident. The mesh around crack tip must have the shape as in the Fig.4.

Data input: - The module of Young: $E = 2.65 \times 10^8 \text{ N/m}^2$

- The Poisson's coefficient: $\nu = 0.2$
- Density: $\rho = 2500 \text{ kg/m}^3$
- Length of plate: $L = 2 \text{ m}$
- Width of plate: $W = 1.2 \text{ m}$
- Thickness of plate: $h = 0.1 \text{ m}$

The first four natural vibration frequencies of the uncracked plate are calculated. In this problem, the crack location ratio (x/L) (the ratio of the location of a crack to the length of plate) varied from 0.1 to 0.9 with an increment of 0.1, starting from a location near to the fixed end to a location near to the free end. Simultaneously, the crack length ratio (a/W) (the ratio of the length of a crack to the width of plate) also varied from 0.125 to 0.5 with an increment of 0.125. The results are compared with ANSYS program to verify the reliability of problem.

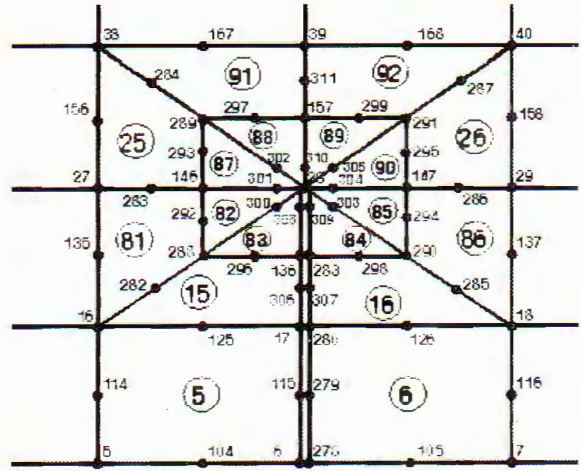


Fig. 4. Mesh around crack tip with Barsoum element $x/L = 0.5$

3.2. Results

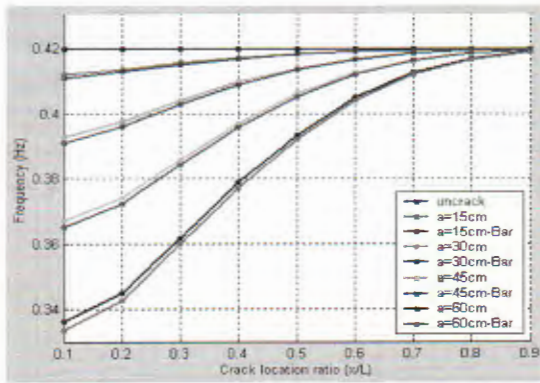


Fig. 5. Variation of the first natural frequency

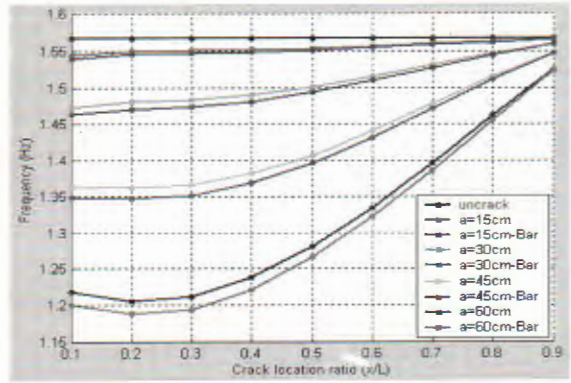


Fig. 6. Variation of the second natural frequency

The obtained numerical results from the CRACK-PLATE program are tabulated and plotted in the form of frequency versus the crack location ratio (x/L) for various crack length ratio (a/W). Figures 5-8 illustrate the variation of the first four natural frequencies in two cases: without and with element of Barsoum. For each crack length ratio (a/W), the upper and lower lines correspond to the cases without and with Barsoum element, respectively. In the latter case, tables 1-4 show the variation of the first four natural frequencies as a function of the crack location and crack length for cantilever plate. The corresponding mode shapes are described by CRACK-PLATE program with crack location ratio of $x/L = 0.5$ in Fig. 9.

Table 1. Variation of the first natural frequency depending on crack location and length

Crack length ratio (a/W)	Crack location ratio (x/L)								
	0.1	0.2	0.3	0.4	0.5	0.6	0.7	0.8	0.9
0.000	0.4197								
0.125 Relative diff. (%)	0.4108 -2.1206	0.4128 -1.6440	0.4150 -1.1198	0.4168 -0.6909	0.4181 -0.3812	0.4189 -0.1906	0.4194 -0.0715	0.4196 -0.0238	0.4197 0
0.250 Relative diff. (%)	0.3914 -6.7429	0.3962 -5.5992	0.4030 -3.9790	0.4089 -2.5733	0.4135 -1.4772	0.4165 -0.7624	0.4184 -0.3097	0.4193 -0.0953	0.4196 -0.0238
0.375 Relative diff. (%)	0.3652 -12.9855	0.3724 -11.2699	0.3845 -8.3869	0.3960 -5.6469	0.4053 -3.4310	0.4120 -1.8346	0.4162 -0.8339	0.4184 -0.309	0.4194 -0.0715
0.500 Relative diff. (%)	0.3336 -20.5146	0.3428 -18.3226	0.3599 -14.2483	0.3773 -10.1024	0.3925 -6.4808	0.4042 -3.6931	0.4120 -1.8346	0.4165 -0.7624	0.4188 -0.2144

Table 2. Variation of the second natural frequency depending on crack location and length

Crack length ratio (a/W)	Crack location ratio (x/L)								
	0.1	0.2	0.3	0.4	0.5	0.6	0.7	0.8	0.9
0.000	1.5668								
0.125 Relative diff. (%)	1.5393 -1.7552	1.5455 -1.3594	1.5469 -1.2701	1.5485 -1.1680	1.5511 -1.0020	1.5544 -0.7914	1.5581 -0.5553	1.5617 -0.3255	1.5651 -0.1085
0.250 Relative diff. (%)	1.4639 -6.5675	1.4708 -6.1271	1.4739 -5.9293	1.4812 -5.4634	1.4938 -4.6592	1.5099 -3.6316	1.5274 -2.5147	1.5444 -1.4296	1.5588 -0.5106
0.375 Relative diff. (%)	1.3497 -13.8563	1.3480 -13.9647	1.3519 -13.7158	1.3685 -12.6564	1.3965 -10.8693	1.4322 -8.5907	1.4720 -6.0505	1.5118 -3.5103	1.5462 -1.3148
0.500 Relative diff. (%)	1.2007 -23.3661	1.1882 -24.1639	1.1947 -23.7490	1.2223 -21.9875	1.2666 -19.1601	1.3224 -15.5987	1.3861 -11.5331	1.4553 -7.1164	1.5224 -2.8338

Table 3. Variation of the third natural frequency depending on crack location and length

Crack length ratio (a/W)	Crack location ratio (x/L)								
	0.1	0.2	0.3	0.4	0.5	0.6	0.7	0.8	0.9
0.000	2.5940								
0.125 Relative diff. (%)	2.5686 -0.9792	2.5871 -0.2660	2.5814 -0.4857	2.5645 -1.1372	2.5533 -1.5690	2.5563 -1.4533	2.5701 -0.9213	2.5847 -0.3585	2.5923 -0.0655
0.250 Relative diff. (%)	2.5078 -3.3230	2.5525 -1.5998	2.5372 -2.1896	2.4884 -4.0709	2.4550 -5.3585	2.4613 -5.1156	2.5018 -3.5543	2.5502 -1.6885	2.5820 -0.4626
0.375 Relative diff. (%)	2.4174 -6.8080	2.4756 -4.5644	2.4533 -5.4240	2.3767 -8.3770	2.3189 -10.6052	2.3202 -10.5551	2.3786 -8.3038	2.4634 -5.0347	2.5430 -1.9661
0.500 Relative diff. (%)	2.3012 -11.2876	2.3599 -9.0247	2.3366 -9.9229	2.2441 -13.4888	2.1629 -16.6191	2.1475 -17.2128	2.1972 -15.2968	2.2801 -12.1010	2.4081 -7.1665

Table 4. Variation of the fourth natural frequency depending on crack location and length

Crack length ratio (a/W)	Crack location ratio (x/L)								
	0.1	0.2	0.3	0.4	0.5	0.6	0.7	0.8	0.9
0.000	5.1174								
0.125	5.0418	5.0673	5.0710	5.0695	5.0630	5.0531	5.0481	5.0580	5.0891
Relative diff. (%)	-1.4773	-0.9790	-0.9067	-0.9360	-1.0630	-1.2565	-1.3542	-1.1607	-0.5530
0.250	4.7863	4.8640	4.9412	4.9807	4.9311	4.8255	4.7509	4.7756	4.9343
Relative diff. (%)	-6.4701	-4.9517	-3.4431	-2.6713	-3.6405	-5.7041	-7.1618	-6.6792	-3.5780
0.375	4.3587	4.5295	4.7610	4.9040	4.6988	4.3866	4.1998	4.1739	4.3984
Relative diff. (%)	-14.8259	-11.4882	-6.9645	-4.1701	-8.1799	-14.2807	-17.9310	-18.4371	-14.0501
0.500	3.9211	4.2147	4.5876	4.8506	4.2310	3.8088	3.6123	3.5494	3.5337
Relative diff. (%)	-23.3771	-17.6398	-10.3529	-5.2136	-17.3213	-25.5716	-29.4114	-30.6405	-30.9473

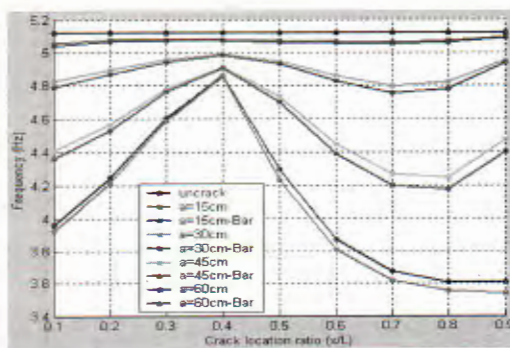
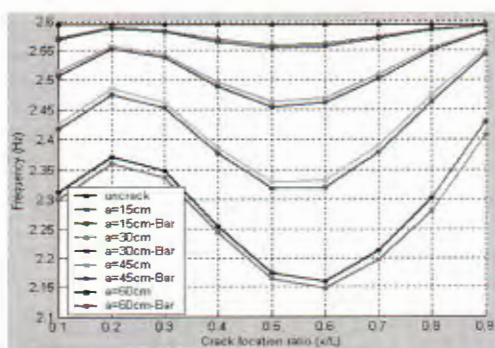


Fig. 7. Variation of the third natural frequency

Fig. 8. Variation of the fourth natural frequency

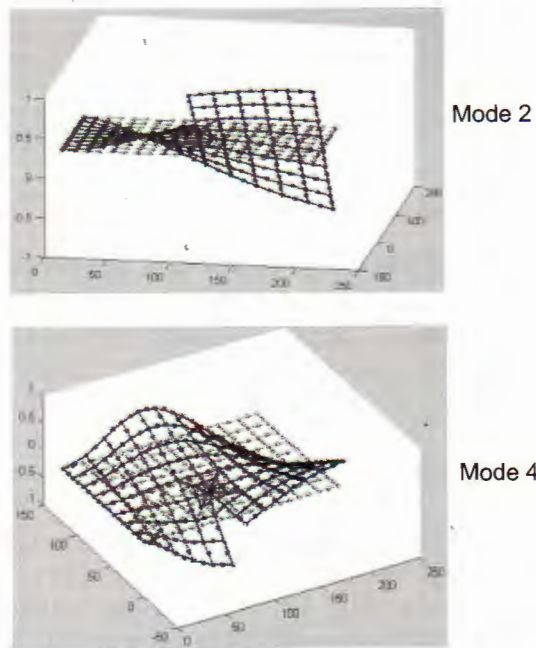
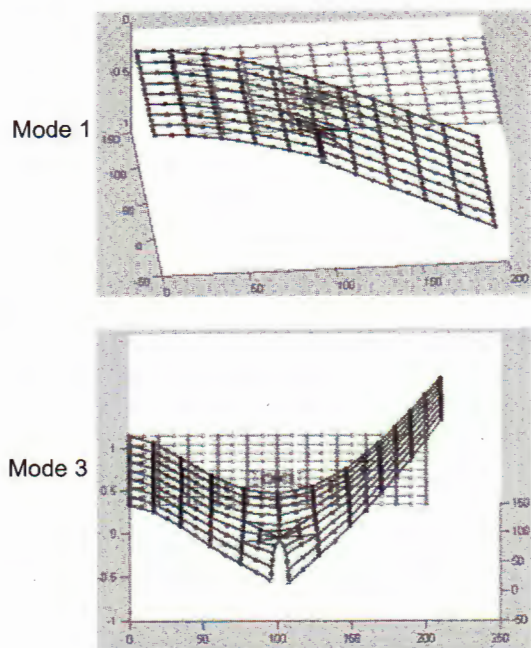


Fig. 9. Mode shapes description by Matlab ($x/L=0.5$)

3.3. Results in comparing with ANSYS program

To verify the reliability of the CRACK-PLATE program, the investigative results are compared with ANSYS program for the crack length $a = 60$ cm ($a/W = 0.5$). In the ANSYS program, the SHELL 93 element is used.

Table 5. Comparison of the first natural frequency by CRACK-PLATE and ANSYS

Mode 1	Crack location ratio (x/L)								
	0.1	0.2	0.3	0.4	0.5	0.6	0.7	0.8	0.9
CRACK-PLATE	0.3336	0.3428	0.3599	0.3773	0.3925	0.4042	0.4120	0.4165	0.4188
ANSYS	0.3318	0.3410	0.3582	0.3761	0.3917	0.4038	0.4121	0.4169	0.4196
Error (%)	0.5396	0.5251	0.4723	0.3180	0.2038	0.0989	0.0243	0.0959	0.1906

Table 6. Comparison of the second natural frequency by CRACK-PLATE and ANSYS

Mode 1	Crack location ratio (x/L)								
	0.1	0.2	0.3	0.4	0.5	0.6	0.7	0.8	0.9
CRACK-PLATE	1.2007	1.1882	1.1947	1.2223	1.2666	1.3224	1.3861	1.4553	1.5224
ANSYS	1.1968	1.1841	1.1904	1.2183	1.2640	1.3204	1.3853	1.4568	1.5254
Error (%)	0.3248	0.3450	0.3599	0.3272	0.2053	0.1512	0.0577	0.1029	0.1967

Table 7. Comparison of the third natural frequency by CRACK-PLATE and ANSYS

Mode 1	Crack location ratio (x/L)								
	0.1	0.2	0.3	0.4	0.5	0.6	0.7	0.8	0.9
CRACK-PLATE	2.3012	2.3599	2.3366	2.2441	2.1629	2.1475	2.1972	2.2801	2.4081
ANSYS	2.2973	2.3559	2.3320	2.2373	2.1541	2.1375	2.1884	2.2755	2.4099
Error (%)	0.1695	0.1695	0.1969	0.3030	0.4068	0.4656	0.4005	0.2017	0.0747

Table 8. Comparison of the fourth natural frequency by CRACK-PLATE and ANSYS

Mode 1	Crack location ratio (x/L)								
	0.1	0.2	0.3	0.4	0.5	0.6	0.7	0.8	0.9
CRACK-PLATE	3.9211	4.2147	4.5876	4.8506	4.2310	3.8088	3.6123	3.5494	3.5337
ANSYS	3.9255	4.2131	4.5865	4.8512	4.2360	3.8076	3.6057	3.5438	3.5359
Error (%)	0.1121	0.0379	0.0239	0.0124	0.1180	0.0315	0.1827	0.1578	0.0622

3.4. Discussion

From the above results and figures, the following observations are made:

- The first four natural frequencies are decreased depending on the crack location and crack length. The longer crack length causes the higher change in frequency.
- The first natural frequency is mostly affected as the crack is located near to the fixed end of plate ($x/L = 0.1$). When the crack moves towards the free end of plate, the first natural frequency is less affected. As indicated in the Table 1 and Fig. 5, the crack occurring near to the free end of plate ($x/L = 0.9$) does not almost change the first frequency.
- For the second natural frequency, the maximum changes of frequency takes place as the crack occurs near to the fixed end of plate ($x/L = 0.1; 0.2$). When the crack moves towards the free end of plate, the second natural frequency is less affected and almost unaffected for a crack located at $x/L = 0.9$. The most reduction is 24.16% with $a/W = 0.5$ (Table 2, Fig. 6).

- For the plate with a crack is located at the center of the plate ($x/L = 0.5; 0.6$), the third natural frequency is the highest decreased. When the crack is located near to the fixed end of plate ($x/L = 0.1$), the third natural frequency is more affected than at the other end of plate (Table 3, Fig. 7).

- As indicated in the Table 4 and Fig. 8, the reduction of the fourth natural frequency depends on the crack length. The most reduction is 30.95% when the crack is located at the free end of plate ($x/L = 0.9$) with $a/W = 0.5$.

From the above observations, it can be stated that the first four natural frequencies are very sensitive to the crack location and crack length for cracked plate. Among them, the second and fourth natural frequencies are most sensitive. This can be explained by the fact that the second and fourth modes are greatly influenced by the tearing mode (mode III) of crack opening deformation. Therefore, we can base on the sensitiveness of the first four natural frequencies to detect crack in bending thin cantilever plate.

The investigative results are reliable when compared with ANSYS program. The highest error between CRACK-PLATE and ANSYS program is 0.54% (table 5-8). Comparing CRACK-PLATE and ANSYS programs, we notice that the CRACK-PLATE program is more efficient. This program allows us to investigate the influence of crack location along the whole length of the plate with an iterative procedure, while the ANSYS program only treats the problem at each crack location with more times and efforts.

The procedure using degenerated element of Barsoum gives lower frequencies than the case without the Barsoum element (Figures 5-8), with the relative difference up to 1.92% for the fourth frequency when $a/W = 0.5, x/L = 0.9$.

4. CONCLUSION

Investigation of the influence of crack on the first four natural frequencies of vibrating bending thin plate has been presented in this paper. The dynamical behavior of the cracked plate is shown to be very sensitive to the crack location and crack length. It can be concluded that the CRACK-PLATE program by the finite element method, based on the Rössner-Mindlin' theory of plate with the singularity element of Barsoum, is efficient and reliable for the analysis of cracked bending thin plate problem. For further development, this forward study can be used to carry out the inverse problem for crack detection in bending thin plate using changes in frequencies.

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ẢNH HƯỞNG CỦA VẾT NỨT BIÊN ĐẾN TẦN SỐ CỦA TẤM MỎNG CHỊU UỐN

Bài báo nghiên cứu ảnh hưởng của vị trí và chiều dài vết nứt đến tần số dao động riêng của tấm mỏng chịu uốn. Một chương trình máy tính sử dụng phương pháp phần tử hữu hạn gọi là CRACK-PLATE, đã được thiết lập trên cơ sở lý thuyết tấm Reissner-Minlin để thực hiện việc phân tích trên. Để thu được kết quả với độ chính xác cao, phần tử Barsoum được kết hợp sử dụng với phần tử tấm 8 nút. Kết quả phân tích số cho thấy tần số dao động riêng của tấm rất nhạy cảm với vết nứt. Kết quả nghiên cứu này là cơ sở để giải quyết bài toán chẩn đoán vết nứt của tấm bằng các tần số riêng.