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PROJECTIVE CHANGE BETWEEN RANDERS METRIC AND EXPONENTIAL (α, β) -METRIC

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Abstract. In this paper, we find conditions to characterize the projective change between two (α, β) -metrics, such as exponential (α, β) -metric, $L = \alpha e^{\frac{\beta}{\alpha}}$ and Randers metric $\overline{L} = \overline{\alpha} + \overline{\beta}$ on a manifold with dim n > 2, where α and $\overline{\alpha}$ are two Riemannian metrics, β and $\overline{\beta}$ are two non-zero 1-forms. We also discuss special curvature properties of two classes of (α, β) -metrics.

Keywords: Finsler space, (α, β) -metric, projective change, Randers metric, Berwlad, Riemannian metric.

1. Introduction

M. Matsumoto [10] introduced the concept of (α, β) -metric on a differentiable manifold with local coordinates x^i , where $\alpha^2 = a_{ij}(x)y^iy^j$ is a Riemannian metric and $\beta = b_i(x)y^i$ is a 1-form on M^n . M. Hashiguchi and Y. Ichijyo [6] studied some special (α, β) -metrics and obtained interesting results. In the projective Finsler geometry, there is a remarkable theorem called Rapcsak [14] theorem, which plays an important role in the projective geometry of Finsler spaces. In fact, this theorem gives the necessary and sufficient condition for a Finsler space to be projective to another Finsler space.

The projective change between two Finsler spaces has been studied by many authors ([2], [5], [8], [11], [12], [16]). In 1994, S. Bacso and M. Matsumoto [2] studied the projective change between Finsler spaces with (α, β) -metric. In 2008, H. S. Park and Y. Lee [11] studied the projective changes between a Finsler space with (α, β) -metric and the associated Riemannian metric. The authors Z. Shen and Civi Yildirim [16] studied a class of projectively flat metrics with a constant flag curvature. In 2009, Ningwei Cui and Yi-Bing Shen [5] studied projective change between two classes of (α, β) -metrics. Also the author N. Cui [4] studied the *S*curvature of some (α, β) -metrics. In this paper, we find conditions to characterize

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the projective change between two (α, β) -metrics, such as the exponential (α, β) metric, $L = \alpha e^{\frac{\beta}{\alpha}}$ and Randers metric $\overline{L} = \overline{\alpha} + \overline{\beta}$ on a manifold with dim n > 2, where α and $\overline{\alpha}$ are two Riemannian metrics, β and $\overline{\beta}$ are two non-zero 1-forms. In addition, we discuss special curvature properties of two classes of (α, β) -metrics.

2. Preliminaries

The terminology and notation are referred to ([15], [9], [1]). Let M^n be a real smooth manifold of dimension n and let $F^n = (M^n, L)$ be a Finsler space on the differentiable manifold M^n endowed with the fundamental function L(x, y). We use the following notation:

$$(2.1) \begin{cases} g_{ij} = \frac{1}{2} \dot{\partial}_i \dot{\partial}_j L^2, \\ C_{ijk} = \frac{1}{2} \dot{\partial}_k g_{ij}, \\ h_{ij} = g_{ij} - l_i l_j, \\ \gamma^i_{jk} = \frac{1}{2} g^{ir} (\partial_j g_{rk} + \partial_k g_{rj} - \partial_r g_{jk}), \\ G^i = \frac{1}{2} \gamma^i_{jk} y^j y^k, \ G^i_j = \dot{\partial}_j G^i, \\ G^i_{jk} = \dot{\partial}_k G^i_j, \ G^i_{jkl} = \dot{\partial}_l G^i_{jk}, \end{cases}$$

where $\dot{\partial}_i \equiv \frac{\partial}{\partial y^i}$.

Definition 2.1. A change $L \to \overline{L}$ of a Finsler metric on the same underlying manifold M is called projective change if any geodesic in (M, L) remains to be geodesic in (M, \overline{L}) and vice versa.

A Finsler metric is projectively related to another metric if they have the same geodesic as point sets. In Riemannian geometry, two Riemannian metrics α and $\overline{\alpha}$ are projectively related if and only if their spray coefficients have the relation [5]

(2.2)
$$G^i_{\alpha} = G^i_{\overline{\alpha}} + \lambda_{x^k} y^k y^i,$$

where $\lambda = \lambda(x)$ is a scalar function on the based manifold.

Two Finsler metric F and \overline{F} are projectively related if and only if their spray coefficients have the relation [5]

(2.3)
$$G^i = \overline{G}^i + P(y)y^i$$

where P(y) is a scalar function and homogeneous of degree one in y^i .

Definition 2.2. A Finsler metric is called a projectively flat metric if it is projectively related to a locally Minkowskian metric.

For a given Finsler metric L = L(x, y), the geodesic of L is given by

(2.4)
$$\frac{d^2x^i}{dt^2} + 2G^i(x, \frac{dx}{dt}) = 0,$$

where $G^{i} = G^{i}(x, y)$ are called geodesic coefficients, which are given by

(2.5)
$$G^{i} = \frac{g^{il}}{4} \bigg\{ [L^{2}]_{x^{m}y^{l}} y^{m} - [L^{2}]_{x^{l}} \bigg\}.$$

Let $\phi = \phi(s)$, $|s| < b_0$, be a positive C^{∞} satisfying the following

(2.6)
$$\phi(s) - s\phi'(s) + (b^2 - s^2)\phi''(s) > 0, \ (|s| \le b < b_0).$$

Let $\alpha = \sqrt{a_{ij}(x)y^iy^j}$ be a Riemannian metric, $\beta = b_iy^i$ is a 1-form satisfying $\|\beta_x\|_{\alpha} < b_0$ for all $x \in M$, then $L = \alpha \phi(s)$, $s = \frac{\beta}{\alpha}$, is called an (regular) (α, β) -metric. In this case, the fundamental form of the metric tensor induced by L is positive definite. Let $\nabla \beta = b_{i|j} dx^i \otimes dx^j$ be the covariant derivative of β with respect to α .

Denote

$$r_{ij} = \frac{1}{2}(b_{i|j} + b_{j|i}) \ s_{ij} = \frac{1}{2}(b_{i|j} - b_{j|i})$$

 β is closed if and only if $s_{ij} = 0$ [17]. Let $s_j = b^i s_{ij}$, $s_j^i = a^{il} s_{lj}$, $s_0 = s_i y^i$, $s_0^i = s_j^i y^j$ and $r_{00} = r_{ij} y^i y^j$.

The relation between the geodesic coefficient G^i of L and the geodesic coefficient G^i_{α} of α is given by

(2.7)
$$G^{i} = G^{i}_{\alpha} + \alpha Q s^{i}_{0} + \{r_{00} - 2Q\alpha s_{0}\}\{\psi b^{i} + \Theta \alpha^{-1} y^{i}\},$$

where

$$\begin{split} \Theta &= \frac{\phi \phi' - s(\phi \phi'' + \phi' \phi')}{2\phi((\phi - s\phi') + (b^2 - s^2)\phi'')}, \\ Q &= \frac{\phi'}{\phi - s\phi'}, \\ \psi &= \frac{1}{2} \frac{\phi''}{(\phi - s\phi') + (b^2 - s^2)\phi''}. \end{split}$$

Definition 2.3. [5] Let

(2.8)
$$D^{i}_{jkl} = \frac{\partial^{3}}{\partial y^{j} \partial y^{k} \partial y^{l}} \left(G^{i} - \frac{1}{n+1} \frac{\partial G^{m}}{\partial y^{m}} y^{i} \right),$$

where G^i is the spray coefficient of L. The tensor $D = D^i_{jkl}\partial_i \otimes dx^j \otimes dx^k \otimes dx^l$ is called the Douglas tensor. A Finsler metric is called a Douglas metric if the Douglas tensor vanishes.

We know that the Douglas tensor is a projective invariant [13]. Note that the spray coefficients of a Riemannian metric are quadratic forms and one can see that the Douglas tensor vanishes (2.8). This shows that the Douglas tensor is a non-Riemannian quantity. In what follows, we use quantities with a bar to denote the

corresponding quantities of metric \overline{L} . We compute the Douglas tensor of a general (α, β) -metric. Let

(2.9)
$$\widehat{G}^i = G^i_\alpha + \alpha Q s^i_0 + \psi \{ r_{00} - 2Q\alpha s_0 \} b^i.$$

Using (2.9) in (2.7), we have

(2.10)
$$G^{i} = \widehat{G}^{i} + \Theta\{r_{00} - 2Q\alpha s_{0}\}\alpha^{-1}y^{i}.$$

Clearly, G^i and \hat{G}^i are projective equivalents according to (2.3). They have the same Douglas tensor. Let

(2.11)
$$T^{i} = \alpha Q s_{0}^{i} + \psi \{ r_{00} - 2Q\alpha s_{0} \} b^{i}.$$

Then $\widehat{G}^i = G^i_{\alpha} + T^i$, thus

$$D^{i}_{jkl} = D^{i}_{jkl}$$

$$= \frac{\partial^{3}}{\partial y^{j} \partial y^{k} \partial y^{l}} \left(G^{i}_{\alpha} - \frac{1}{n+1} \frac{\partial G^{m}_{\alpha}}{\partial y^{m}} y^{i} + T^{i} - \frac{1}{n+1} \frac{\partial T^{m}}{\partial y^{m}} y^{i} \right)$$

$$(2.12) \qquad = \frac{\partial^{3}}{\partial y^{j} \partial y^{k} \partial y^{l}} \left(T^{i} - \frac{1}{n+1} \frac{\partial T^{m}}{\partial y^{m}} y^{i} \right).$$

To simplify (2.12), we use the following identities

$$\alpha_{y^k} = \alpha^{-1} y_k, \ s_{y^k} = \alpha^{-2} (b_k \alpha - s y_k),$$

where $y_i = a_{il} y^l$, $\alpha_{y^k} = \frac{\partial \alpha}{\partial y^k}$. Then

$$[\alpha Q s_0^m]_{y^m} = \alpha^{-1} y_m Q s_0^m + \alpha^{-2} Q' [b_m \alpha^2 - \beta y_m] s_0^m$$

= Q's_0

and

$$\psi(r_{00} - 2Q\alpha s_0)b^m]_{y^m} = \psi'\alpha^{-1}(b^2 - s^2)[r_{00} - 2Q\alpha s_0] + 2\psi[r_0 - Q'(b^2 - s^2)s_0 - Qss_0],$$

where $r_j = b^i r_{ij}$ and $r_0 = r_i y^i$. Thus from (2.11), we get

(2.13)
$$T_{y^m}^m = Q's_0 + \psi'\alpha^{-1}(b^2 - s^2)[r_{00} - 2Q\alpha s_0] + 2\psi[r_0 - Q'(b^2 - s^2)s_0 - Qss_0].$$

We assume that the (α, β) -metrics L and \overline{L} have the same Douglas tensor, i.e., $D^i_{jkl} = \widehat{D}^i_{jkl}$. Thus from (2.8) and (2.12), we get

$$\frac{\partial^3}{\partial y^j \partial y^k \partial y^l} \left(T^i - \overline{T}^i - \frac{1}{n+1} (T^m_{y^m} - \overline{T}^m_{y^m}) y^i \right) = 0.$$

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Then there exists a class of scalar functions $H^i_{jk} = H^i_{jk}(x)$, such that

(2.14)
$$H_{00}^{i} = T^{i} - \overline{T}^{i} - \frac{1}{n+1} (T_{y^{m}}^{m} - \overline{T}_{y^{m}}^{m}) y^{i},$$

where $H_{00}^{i} = H_{jk}^{i} y^{j} y^{k}$.

Theorem 2.1. [4] For the special form of (α, β) -metric, $L = \alpha + \epsilon\beta + k\left(\frac{\beta^2}{\alpha}\right)$, where ϵ , k are non-zero constant, the following are equivalent:

- L has an isotropic S-curvature, i.e., S = (n+1)c(x)L for some scalar function c(x) on M.
- L has an isotropic mean Berwald curvature.
- β is a killing one form of constant length with respect to α . This is equivalent to $r_{00} = s_0 = 0$.
- L has a vanished S-curvature, i.e., S = 0.
- L is a weak Berwald metric, i.e., E = 0.

3. Projective Change between Randers Metric and Exponential (α, β) -metric

In this section, we find the projective relation between two (α, β) -metrics on the same underlying manifold M of dimension n > 2. For (α, β) -metric $L = \alpha e^{\frac{\beta}{\alpha}}$, one can prove by (2.6) that L is a regular Finsler metric if and only if 1-form β satisfies the condition $\|\beta_x\|_{\alpha} < 1$ for any $x \in M$. The geodesic coefficient are given by (2.7) with

(3.1)
$$\begin{cases} \Theta = \frac{1-2s}{2(1+b^2-s-s^2)}, \\ Q = \frac{1}{1-s}, \\ \psi = \frac{1}{2(1+b^2-s-s^2)}. \end{cases}$$

Using (3.1) in (2.7), we get

$$G^{i} = G^{i}_{\alpha} + \frac{\alpha^{2}}{\alpha - \beta} s^{i}_{0} + \frac{1}{2(\alpha^{2} - \beta^{2} + \alpha^{2}b^{2} - \alpha\beta)} \left[r_{00} - \frac{2\alpha^{2}}{\alpha - \beta} s_{0} \right]$$

(3.2) × $[\alpha^{2}b^{i} + (\alpha - 2\beta)y^{i}].$

For the Randers metric $\overline{L} = \overline{\alpha} + \overline{\beta}$, one can also prove by (2.6) that \overline{L} is a regular Finsler metric if and only if $\|\beta_x\|_{\alpha} < 1$ for any $x \in M$. The geodesic coefficients are given by (2.7) with

(3.3)
$$\overline{\Theta} = \frac{1}{2(1+s)}, \ \overline{Q} = 1, \ \overline{\psi} = 0.$$

First, we prove the following lemma:

Lemma 3.1. Let $L = \alpha e^{\frac{\beta}{\alpha}}$ and $\overline{L} = \overline{\alpha} + \overline{\beta}$ be two (α, β) -metrics on a manifold M with dimension n > 2. Then they have the same Douglas tensor if and only if both metrics are Douglas metrics.

Proof. First, we prove the sufficient condition. Let L and \overline{L} be Douglas metrics and the corresponding Douglas tensor D^i_{jkl} and \hat{D}^i_{jkl} . Then by the definition of Douglas metric, we have $D^i_{jkl} = 0$ and $\hat{D}^i_{jkl} = 0$, that is, both metrics have the same Douglas tensor. Next, we prove the necessary condition. If L and \overline{L} have the same Douglas tensor, then (2.14) holds.

Using (2.13), (3.1) and (3.3) in (2.14), we have

(3.4)
$$H_{00}^{i} = \frac{A^{i}\alpha^{7} + B^{i}\alpha^{6} + C^{i}\alpha^{5} + D^{i}\alpha^{4} + E^{i}\alpha^{3} + F^{i}\alpha^{2}}{K\alpha^{6} + U\alpha^{5} + M\alpha^{4} + N\alpha^{3} + V\alpha^{2} + R} - \overline{\alpha}\,\overline{s}_{0}^{i}$$

where

$$\begin{array}{rcl} A^{i} &=& (1+b^{2})[2s^{i}_{0}(1+b^{2})-2s_{0}],\\ B^{i} &=& (1+b^{2})[r_{00}b^{i}-2\beta(3+b^{2})s^{i}_{0}+2\beta s_{0}b^{i}\\ &-& 2\lambda ss_{0}(1+s)y^{i}-2\lambda r_{0}y^{i}]-2\lambda \beta ss_{0}(2+b^{2})y^{i}\\ &+& 4\lambda\beta s_{0}(1+b^{2})y^{i}+2\beta^{2}(1-2b^{2})s^{i}_{0}-\lambda b^{2}r_{00}y^{i},\\ D^{i} &=& 2\beta^{3}(3+2b^{2})s^{i}_{0}+r_{00}\beta^{2}(2+b^{2})b^{i}\\ &+& 2\lambda\beta(\beta s_{0}+2\beta s^{2}s_{0}-\beta b^{2}r_{0}-2\beta r_{0}-s^{2}r_{00})y^{i},\\ E^{i} &=& \beta^{2}r_{00}[\beta b^{i}+\lambda(3b^{2}-4s^{2}-2\beta b^{2})y^{i}]\\ &+& 2\lambda\beta^{3}(ss_{0}-r_{0}-2s_{0})y^{i}-2\beta^{4}s^{i}_{0},\\ F^{i} &=& 2\lambda\beta^{3}(\beta r_{0}-\beta s_{0}+s^{2}r_{00})y^{i}\\ &-& 2\beta^{5}s^{i}_{0}-\beta^{4}r_{00}b^{i},\\ \lambda &=& \frac{1}{n+1} \end{array}$$

and

$$\begin{split} K &= 2(1+b^2)^2, \ U = 4\beta(b^4 - 3b^2 - 2), \ M = 2\beta^2(b^2 + 2)^2, \\ N &= 4\beta^3(1+b^2), \ V = -4\beta^4(2+b^2), \ R = 2\beta^6. \end{split}$$

Then (3.4) is equivalent to

$$(3.5) A^i \alpha^7 + B^i \alpha^6 + C^i \alpha^5 + D^i \alpha^4 + E^i \alpha^3 + F^i \alpha^2 = (K\alpha^6 + U\alpha^5 + M\alpha^4 + N\alpha^3 + V\alpha^2 + R)(H^i_{00} + \overline{\alpha}\,\overline{s}^i_0).$$

Replacing y^i in (3.5) by $-y^i$, we have

$$(3.6) \qquad - A^{i}\alpha^{7} + B^{i}\alpha^{6} - C^{i}\alpha^{5} + D^{i}\alpha^{4} - E^{i}\alpha^{3} + F^{i}\alpha^{2} \\ = (K\alpha^{6} - U\alpha^{5} + M\alpha^{4} - N\alpha^{3} + V\alpha^{2} + R)(H^{i}_{00} - \overline{\alpha}\,\overline{s}^{i}_{0}).$$

Subtracting (3.6) from (3.5), we get

From (3.7), we have

(3.8)
$$\begin{aligned} \alpha^2 [A^i \alpha^5 + C^i \alpha^3 + E^i \alpha - (U\alpha^3 + N\alpha) H^i_{00} \\ -\overline{\alpha} \ \overline{s}^i_0 (K\alpha^4 + M\alpha^2 + V)] &= R\overline{\alpha} \ \overline{s}^i_0. \end{aligned}$$

From (3.8), $R \overline{\alpha} \ \overline{s}_0^i$ has the factor α^2 , i.e., the term $R \overline{\alpha} \ \overline{s}_0^i = 2\beta^6 \overline{\alpha} \ \overline{s}_0^i$ has the factor α^2 . We can study two cases for Riemannian metric.

Case (i): If $\overline{\alpha} \neq \mu(x)\alpha$, then $R\overline{s}_0^i = 2\beta^6\overline{s}_0^i$ has the factor α^2 . Note that β^2 has no factor α^2 . Then the only possibility is that $\beta\overline{s}_0^i$ has the factor α^2 . Then for each i there exists a scalar function $\eta^i = \eta^i(x)$ such that $\beta\overline{s}_0^i = \eta^i\alpha^2$ which is equivalent to $b_j\overline{s}_k^i + b_k\overline{s}_j^i = 2\eta^i\alpha_{jk}$. When n > 2 and we assume that $\eta^i \neq 0$, then

$$2 \geq rank(b_j \overline{s}_k^i) + rank(b_k \overline{s}_j^i)$$

> rank(b_j \overline{s}_k^i + b_k \overline{s}_j^i)
= rank(2\eta^i \alpha_{jk}) > 2,

which is impossible unless $\eta^i = 0$. Then $\beta \overline{s}_0^i = 0$. Since $\beta \neq 0$, we have $\overline{s}_0^i = 0$, which says that $\overline{\beta}$ is closed.

Case (ii): If $\overline{\alpha} = \mu(x)\alpha$, then (3.7), becomes

(3.9)
$$\begin{aligned} R\mu(x)\overline{s}_{0}^{i} &= \alpha^{2}[A^{i}\alpha^{4}+C^{i}\alpha^{2}+E^{i}-(U\alpha^{2}+N)H_{00}^{i}\\ &- \mu(x)\overline{s}_{0}^{i}(K\alpha^{4}+M\alpha^{2}+V)]. \end{aligned}$$

From (3.9), we can see that $\mu(x)R\overline{s}_0^i$ has the factor α^2 . i.e., $\mu(x)R\overline{s}_0^i = 2\mu(x)\overline{s}_0^i\beta^6$ has the factor α^2 . Note that $\mu(x) \neq 0$ for all $x \in M$ and β^2 has no factor α^2 . The only possibility is that $\beta\overline{s}_0^i$ has the factor α^2 . As the similar reason in case (*i*), we have $\overline{s}_0^i = 0$, when n > 2, which says that $\overline{\beta}$ is closed.

M. Hashiguchi [7] proved that the Randers metric $\overline{L} = \overline{\alpha} + \overline{\beta}$ is a Douglas metric if and only if $\overline{\beta}$ is closed. Thus \overline{L} is a Douglas metric. Since L is projectively related to \overline{L} , then both L and \overline{L} are Douglas metrics. \Box

Theorem 3.1. The Finsler metric $L = \alpha e^{\frac{\beta}{\alpha}}$ is projectively related to $\overline{L} = \overline{\alpha} + \overline{\beta}$ if and only if the following conditions are satisfied

(3.10)
$$\begin{cases} G_{\alpha}^{i} = G_{\overline{\alpha}}^{i} + \theta y^{i} - \tau \xi \alpha^{2} b^{i}, \\ b_{i|j} = \tau [(1+2b^{2})a_{ij} - 3b_{i}b_{j}], \\ d\overline{\beta} = 0, \end{cases}$$

where $b^i = a^{ij}b_j$, $b = ||\beta||_{\alpha}$, $b_{i|j}$ denotes the coefficient of the covariant derivatives of β with respect to α , $\tau = \tau(x)$ is a scalar function and $\theta = \theta_i y^i$ is a 1-form on a manifold M with dimension n > 2. *Proof.* First, we prove the necessary condition. Since the Douglas tensor is invariant under projective changes between two Finsler metrics, if L is projectively related to \overline{L} , then they have the same Douglas tensor. According to Lemma 3.1, we obtain that both L and \overline{L} are Douglas metrics.

We know that the Randers metric $\overline{L} = \overline{\alpha} + \overline{\beta}$ is a Douglas metric if and only if $\overline{\beta}$ is closed, i.e., $d\overline{\beta} = 0$.

The Finsler metric $L = \alpha e^{\frac{\beta}{\alpha}}$ is a Douglas metric if and only if

(3.11)
$$b_{i|j} = \tau[(1+2b^2) - 3b_i b_j],$$

for some scalar function $\tau = \tau(x)$ [3], where $b_{i|j}$ denotes the coefficient of the covariant derivatives of $\beta = b_i y^i$ with respect to α . In this case, β is closed. Since β is closed, $s_{ij} = 0 \Rightarrow b_{i|j} = b_{j|i}$. Thus $s_0^i = 0$ and $s_0 = 0$. By using (3.11), we have $r_{00} = \tau[(1+2b^2)\alpha^2 - 3\beta^2]$. Substituting all these in (3.2),

By using (3.11), we have $r_{00} = \tau [(1+2b^2)\alpha^2 - 3\beta^2]$. Substituting all these in (3.2), we get

(3.12)
$$G^{i} = G^{i}_{\alpha} + \tau \frac{\left[(1+2b^{2})(\alpha^{3}-2\alpha^{2}\beta)-3\alpha\beta^{2}+6\beta^{3}\right]}{2(\alpha^{2}-\beta^{2}+b^{2}\alpha^{2}-\alpha\beta)}y^{i} + \tau\xi\alpha^{2}b^{i},$$

where $\xi = \frac{\tau[(1+2b^2)\alpha^2 - 3\beta^2]b^i}{2(\alpha^2 - \beta^2 + b^2\alpha^2 - \alpha\beta)}$.

Since L is projectively related to \overline{L} , this is a Randers change between L and $\overline{\alpha}$. Noticing that $\overline{\beta}$ is closed, then L is projectively related to $\overline{\alpha}$. Thus, there is a scalar function P = P(y) on $TM - \{0\}$ such that

$$(3.13) G^i = G^i_{\overline{\alpha}} + Py^i.$$

From (3.12) and (3.13), we have

(3.14)
$$\left[P + \frac{3\alpha\beta^2 - 6\beta^3 - (1+2b^2)(\alpha^3 - 3\alpha^2\beta)}{2(\alpha^2 - \beta^2 + b^2\alpha^2 - \alpha\beta)} \right] y^i = G^i_\alpha - G^i_{\overline{\alpha}} + \tau \xi \alpha^2 b^i.$$

Note that the RHS of the above equation is a quadratic form. Then there must be one form $\theta = \theta_i y^i$ on M, such that

$$P + \frac{3\alpha\beta^2 - 6\beta^3 - (1+2b^2)()\alpha^3 - 3\alpha^2\beta}{2(\alpha^2 - \beta^2 + b^2\alpha^2 - \alpha\beta)} = \theta.$$

Thus (3.14) becomes

(3.15)
$$G^i_{\alpha} = G^i_{\overline{\alpha}} + \theta y^i - \tau \xi \alpha^2 b^i.$$

Equations (3.11) and (3.12) together with (3.15) complete the proof of the necessity. Since $\overline{\beta}$ is closed, it suffices to prove that L is projectively related to $\overline{\alpha}$. From (3.12) and (3.15), we have

$$G^{i} = G^{i}_{\overline{\alpha}} + \left[\theta + \frac{\tau[(1+2b^{2})(\alpha^{3}-3\alpha^{2}\beta)-3\alpha\beta^{2}+6\beta^{3}]}{2(\alpha^{2}-\beta^{2}+b^{2}\alpha^{2}-\alpha\beta)}\right]y^{i},$$

that is, L is projectively related to $\overline{\alpha}$ \Box

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From the above theorem, we get the following corollaries.

Corollary 3.1. The Finsler metric $L = \alpha e^{\frac{\beta}{\alpha}}$ is projectively related to $\overline{L} = \overline{\alpha} + \overline{\beta}$ if and only if they are Douglas metrics and the spray coefficients of α and $\overline{\alpha}$ have the following relation

$$G^i_{\alpha} = G^i_{\overline{\alpha}} + \theta y^i - \tau \xi \alpha^2 b^i,$$

where $b^i = a^{ij}b_j$, $\tau = \tau(x)$ is a scalar function and $\theta = \theta_i y^i$ is one form on a manifold M with dimension $n \ge 2$.

Further, we assume that the Randers metric $\overline{L} = \overline{\alpha} + \overline{\beta}$ is locally Minkowskian, where $\overline{\alpha}$ is a Euclidean metric and $\overline{\beta} = \overline{b}_i y^i$ is one form with \overline{b}_i =constant. Then (3.10) can be written as

(3.16)
$$\begin{cases} G_{\alpha}^{i} = \theta y^{i} - \tau \xi \alpha^{2} b^{i}, \\ b_{i|j} = \tau [(1+2b^{2})a_{ij} - 3b_{i}b_{j}]. \end{cases}$$

Thus, we state

Corollary 3.2. The Finsler metric $\alpha e^{\frac{\beta}{\alpha}}$ is projectively related to $\overline{L} = \overline{\alpha} + \overline{\beta}$ if and only if L is projectively flat, that is, L is projectively flat if and only if (3.16) holds.

4. Special Curvature Properties of two (α, β) -metrics

We know that the Berwald curvature tensor of a Finsler metric L is defined by [9]

(4.1)
$$G = G^i_{ikl} dx^j \otimes \partial_i \otimes dx^k \otimes dx^l,$$

where $G_{jkl}^i = [G^i]_{y^j y^k y^l}$ and G^i are the spray coefficients of L. The mean Berwald curvature tensor is defined by

(4.2)
$$E = E_{ij} dx^i \otimes dx^j,$$

where $E_{ij} = \frac{1}{2}G_{mij}^m$.

A Finsler space is said to be of the isotropic mean Berwald curvature if

(4.3)
$$E_{ij} = \frac{n+1}{2}c(x)L_{y^iy^j},$$

where c(x) is scalar function on M.

In this section, we assume that (α, β) -metric $L = \alpha e^{\frac{\beta}{\alpha}}$ has some special curvature properties.

Theorem 4.1. The Finsler metric $L = \alpha e^{\frac{\beta}{\alpha}}$ having an isotropic S-curvature or isotropic mean Berwald curvature is projectively related to $\overline{L} = \overline{\alpha} + \overline{\beta}$ if and only if the following conditions hold:

- α is projectively related to $\overline{\alpha}$,
- β is parallel with respect to α , i.e., $b_{i|j} = 0$,
- $\overline{\beta}$ is closed, i.e., $d\overline{\beta} = 0$,

where $b_{i|j}$ denotes the coefficient of the covariant derivative of β with respect to α .

Proof. The sufficiency is obvious from Theorem (3.2). For the necessary condition, from Theorem 3.1, if L is projectively related to \overline{L} , then

$$b_{i|j} = \tau [(1+2b^2)a_{ij} - 3b_i b_j],$$

where $\tau = \tau(x)$ is scalar function. Transvecting the above equation with y^i and y^j , we have

(4.4)
$$r_{00} = \tau [(1+2b^2)\alpha^2 - 3\beta^2].$$

From Theorem 2.4, if L has an isotropic S-curvature or an equivalently isotropic mean Berwald curvature, then $r_{00} = 0$. If $\tau \neq 0$, then (4.4) gives

(4.5)
$$(1+2b^2)\alpha^2 - 3\beta^2 = 0,$$

which is equivalent to

(4.6)
$$(1+2b^2)a_{ij} - 3b_ib_j = 0.$$

Transvecting (4.6) with a^{il} , we get

(4.7)
$$(1+2b^2)\delta_j^l - 3b^l b_j = 0.$$

Contracting l and j in (4.7), we have $n + (2n-3)b^2 = 0$, which is impossible. Thus $\tau = 0$. Substituting in Theorem 3.2, we complete the proof. \Box

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