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Darboux dressing and undressing for the ultradiscrete KdV equation

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Abstract

We solve the direct scattering problem for the ultradiscrete Korteweg de Vries (udKdV) equation, over \mathbb{R} for any potential with compact (finite) support, by explicitly constructing bound state and nonbound state eigenfunctions. We then show how to reconstruct the potential in the scattering problem at any time, using an ultradiscrete analogue of a Darboux transformation. This is achieved in two steps. First we use so-called 'undressing' transformations (i.e. Darboux transformations that use bound state eigenfunctions) on the potential in the scattering problem to obtain data that uniquely characterises both its soliton content and the remaining 'background', and thereby the entire potential. Then we use so-called 'dressing' transformations (i.e. Darboux transformations that use bound state eigenfunctions) to put back the solitonic content in the background at general time t, whereby obtaining an explicit expression for the solution to the udKdV equation associated to the original potential at t = 0.

1 Introduction

The ultradiscrete KdV equation was first introduced by Takahashi and Satsuma in 1990 under the name soliton cellular automaton [1]. A state in this system at time step t is a sequence $(U_i^t)_{i \in \mathbb{Z}}$, with all but a finite number of terms non-zero. The state at time t + 1 is determined by the update rule (19). In Takahashi and Satsuma's original formulation, U_i^t takes binary values only, that is, cell values are restricted to $\{0, 1\}$. The update rule then always gives another binary sequence and the system has an interpretation, which is now more commonly used, as a so-called box and ball system (BBS) in which the value 0 corresponds to an empty box and a 1 to a box occupied by a ball [2]. Over the past decade it has become clear that the BBS and the mathematical tools used to describe its properties, are intimately related to many topics in mathematical physics such as Yang-Baxter maps, crystal base theory in quantum groups and tropical geometry, to name but a few (cf. [3] for an exhaustive review).

At a more fundamental level, it has been known from the earliest papers that, in the BBS, all states evolve as $t \to \pm \infty$ into a finite number of blocks of consecutive 1s separated by blocks of 0s, where a block of k consecutive 1s translating at speed k is interpreted as a soliton of mass k. The two asymptotic states have the same block structure, with phase-shifts, and the evolution can be thought to represent interacting solitons. The initial value problem for the BBS was solved relatively recently, by introducing combinatorial quantities that play the role of action-angle variables and that are related to the Kerov-Kirillov-Reshetikhin bijection [4], [3] (or [5] for an alternative, elementary, construction), as well as through a direct and explicit construction of the general N-soliton state that results from arbitrary initial conditions [6].

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[†] Sadly Jon Nimmo passed away on 20th June 2017

By the mid-1990's [7] it had been realized the BBS can be seen to arise from the discrete KdV equation (1) via a limiting procedure called *ultradiscretization* (also known in tropical mathematics as Maslov dequantisation, see [8] for example). Hence the system is also referred to as the ultradiscrete KdV equation.

In the last few years there has also been some interest in more general versions of the ultradiscrete KdV equation. These have the same update rule as the BBS but U_i^t takes arbitrary integer [9, 10, 11] or arbitrary real values [12, 13]. In this non-binary case, the most general solution describes the interaction of pair-wise interacting solitons of arbitrary positive mass, similar to the BBS solitons, overlayed on a simply evolving background. We will give more details of these solutions later. In particular, in [10, 12], a procedure for solving the initial value problem for the ultradiscrete KdV equation by an inverse scattering method was described. This method bears a striking resemblance to the classical IST scheme for the (continuous) KdV equation [14] and the action-angle variables that appear in it play exactly the same role as those in the continuous case. A key part of this procedure, and the most difficult part, is the use of Darboux transformations to "undress" all of the solitons at time t = 0 one by one, and to determine their defining parameters, mass and phase. This parameter data, and the background that remains, evolve very simply, in fact linearly, in time and the solution at time t can be reconstructed by means of a sequence of Bäcklund transformations [15].

The main results of this paper are a general and explicit expression for the special undressing eigenfunction that removes the heaviest soliton in a given state. It is also shown that the Bäcklund transformation used to reconstruct the solution comes from exactly the same Darboux transformation but with a different type of eigenfunction, one that does not correspond to a bound state. This eigenfunction is constructed explicitly as well. The paper is organised as follows: in Section 2 we state some standard results on the discrete and ultradiscrete KdV equation including the ultradiscrete linear system (Lax pair) for the ultradiscrete KdV equation. Section 3 gives some details of the general solution of ultradiscrete KdV in the case that the solution $U_i^t \in \mathbb{R}$ and we give criteria which characterise solutions with and without soliton content. An alternative version of the update rule for udKdV is described in Section 4. This alternative method enables us to deduce some simple properties of the system, including the conservation of total mass, and might have more general interest. In Section 5 we establish another two (as far as we know) new conserved quantities which will play a vital role in finding the dressing and undressing transformations. In Section 6 we review some properties of Darboux transformations for the discrete KdV and introduce an ultradiscrete analogue. In Section 7 we obtain a two parameter family of solutions of the ultradiscrete linear system expressed as the maximum of two basis functions and we use such solutions to construct dressing Darboux transformations. In Section 8 we find the special choices of parameters for which the *minimum* of the basis solutions is also a solution and we show how this solution defines an undressing Darboux transformation. Finally in Section 9 we apply the dressing and undressing Darboux transformations to the Cauchy problem for the udKdV equation on \mathbb{R} and we give a detailed example of the calculations involved.

2 Discrete and ultradiscrete KdV equations

We first give a summary of some known results concerning the discrete and ultradiscrete KdV equations.

2.1 Discrete KdV

The discrete KdV equation (dKdV) [16] is the integrable partial difference equation

$$\frac{1}{u_{i+1}^{t+1}} + \delta u_i^{t+1} = \frac{1}{u_i^t} + \delta u_{i+1}^t,\tag{1}$$

where $i, t \in \mathbb{Z}$ and $u_i^t \in (0, \infty)$ and where δ is a real constant not equal to 0 or 1 (values for which there is no continuum limit to the KdV equation). This equation arises directly from the system

$$u_i^{t+1} = \frac{v_i^t}{1 + \delta u_i^t v_i^t}, \quad v_{i+1}^t = u_i^t (1 + \delta u_i^t v_i^t), \tag{2}$$

(a reduction of the Hirota-Miwa equation [17]) when v_i^t is eliminated. Alternatively, assuming boundary conditions $u_i^t \to 1$ and $v_i^t \to 1/(1-\delta)$ as $i \to \pm \infty$ for any t, one may express v_i^t as an infinite product in two ways

$$v_i^t = \frac{1}{1-\delta} \prod_{j < i} \frac{u_j^t}{u_j^{t+1}} \quad \text{or} \quad v_i^t = \frac{1}{1-\delta} \prod_{j \ge i} \frac{u_j^{t+1}}{u_j^t}.$$
 (3)

From this, assuming convergence, it follows that

$$\prod_{i \in \mathbb{Z}} u_i^t \tag{4}$$

is independent of t.

Eliminating v_i^t from (2) using (3) gives an alternative form of the dKdV equation

$$\frac{1}{u_i^{t+1}} = \delta u_i^t + (1-\delta) \prod_{j < i} \frac{u_j^{t+1}}{u_j^t},\tag{5}$$

which now defines an evolution in the positive *i* direction, in which the values $\{u_j^t | j \leq i\}$ define u_i^{t+1} . Notice that equation (1) is invariant under the changes $(u, \delta; i, t) \rightarrow (u, -\delta; t, i)$ and $(u, \delta; i, t) \rightarrow (1/u, 1/\delta; i, -t)$ and that δ can therefore be restricted to $\delta \in (0, 1)$ without loss of generality. From the alternative form (5) it follows that for such δ , positive initial values $\{u_i^0\}$ always result in positive values for u_i^t , for all t and i.

The dKdV equation has bilinear form [16]

$$\tau_{i+1}^{t+1}\tau_i^{t-1} = (1-\delta)\tau_{i+1}^t\tau_i^t + \delta\tau_i^{t+1}\tau_{i+1}^{t-1},\tag{6}$$

where

$$u_{i}^{t} = \frac{\tau_{i}^{t+1}\tau_{i+1}^{t}}{\tau_{i+1}^{t+1}\tau_{i}^{t}},\tag{7}$$

and Lax pair

$$\phi_{i-1}^t - \frac{2}{1+\delta} \left(\frac{1}{u_i^t} + \delta u_{i-1}^t \right) \phi_i^t + (1-\lambda^2) \phi_{i+1}^t = 0$$
(8)

$$\beta \phi_i^{t+1} = \phi_{i-1}^t + (\beta - 1)u_{i-1}^t \phi_i^t, \tag{9}$$

where $\delta \in (0, 1)$ and $\beta := (1 - \delta)/(1 + \delta)$ also lies in the interval (0, 1).

This linear problem is not self-adjoint. Its adjoint is

$$\psi_{i+1}^t - \frac{2}{1+\delta} \left(\frac{1}{u_{i-1}^{t-1}} + \delta u_i^{t-1} \right) \psi_i^t + (1-\lambda^2) \psi_{i-1}^t = 0$$
(10)

$$\beta \psi_i^{t-1} = \psi_{i+1}^t + (\beta - 1)u_i^{t-1} \psi_i^t.$$
(11)

However, this adjoint is gauge equivalent to (8), (9) since any solution ϕ_i^t of the linear problem (8) and (9) gives a solution

$$\psi_i^t := (1 - \lambda^2)^i (1 - \lambda^2 / \beta^2)^{-t} \phi_i^t, \tag{12}$$

of (10) and (11).

The squared eigenfunction potential $\Omega_i^t(\phi,\psi) = \Omega(\phi_i^t,\psi_i^t)$ is defined by the compatible difference equations

$$\Omega_{i}^{t} - \Omega_{i-1}^{t} = \phi_{i}^{t} \psi_{i-1}^{t}, \quad \Omega_{i}^{t+1} - \Omega_{i}^{t} = -\frac{1}{\beta} \phi_{i}^{t} \psi_{i}^{t+1}.$$
(13)

In general, under the assumption that $u_i^t \to 1$ as $i \to \pm \infty$,

$$\phi_i^t \sim a(1+\lambda)^{-i}(1+\lambda/\beta)^t + b(1-\lambda)^{-i}(1-\lambda/\beta)^t, \tag{14}$$

as $i \to -\infty$ and

$$\phi_i^t \sim c(1+\lambda)^{-i}(1+\lambda/\beta)^t + d(1-\lambda)^{-i}(1-\lambda/\beta)^t,$$
(15)

as $i \to +\infty$, for some constants a, b, c and d.

From here on we shall always assume that $0 < \lambda < \beta < 1$ (which is known to correspond to right-going solitons for the dKdV equation with $u_i^t \ge 1$). In this case,

$$(1+\lambda)^{-i} \to \begin{cases} \infty & \text{as } i \to -\infty \\ 0 & \text{as } i \to +\infty \end{cases}, \quad (1-\lambda)^{-i} \to \begin{cases} 0 & \text{as } i \to -\infty \\ \infty & \text{as } i \to +\infty \end{cases}$$

and so if the constants a and d are both zero, $\phi_i^t \to 0$ as $i \to \pm \infty$. Then $\phi_i^t \psi_{i-1}^t \sim b^2 \frac{(1+\lambda)^i (1-\lambda/\beta)^t}{(1-\lambda)^i (1+\lambda/\beta)^t} \to 0$ as $i \to -\infty$ and $\phi_i^t \psi_{i-1}^t \sim c^2 \frac{(1-\lambda)^i (1+\lambda/\beta)^t}{(1-\lambda/\beta)^t} \to 0$ as $i \to +\infty$. In such cases we can express Ω_t^i as a semi-infinite sum $\Omega_i^t = \sum_{j \leqslant i} \phi_j^t \psi_{j-1}^t$, and then define the norm,

$$\|\phi^t\| := \left|\lim_{i \to +\infty} \Omega_i^t\right| = \left|\sum_{i \in \mathbb{Z}} \phi_i^t \psi_{i-1}^t\right|,\tag{16}$$

which, given the asymptotics of $\phi_i^t \psi_{i-1}^t$, is finite, and ϕ_i^t is said to correspond to a *bound state*. We have seen, in fact, that $\phi_i^t \to 0$ as $i \to \pm \infty$ is sufficient for ϕ_i^t to be a bound state.

Notice also that for $i \to \pm \infty$, $\phi_i^t \psi_i^{t+1} \sim \phi_i^t \psi_{i-1}^t \to 0$. Taking the limit as $i \to \pm \infty$ in the second equation in (13) we see that $\|\phi^{t+1}\| = \|\phi^t\| = \|\phi\|$, and so the norm of an eigenfunction for a bound state is *t*-independent.

2.2 Ultradiscrete KdV

When taking the ultradiscrete limit, one assumes that $u_i^t = O(\delta^{-U_i^t})$, for positive $\delta \approx 0$, and keeping only the lowest order terms in (1) one obtains the naive ultradiscrete form of dKdV,

$$\max(U_i^{t+1} - 1, -U_{i+1}^{t+1}) = \max(U_{i+1}^t - 1, -U_i^t),$$
(17)

for all $i, t \in \mathbb{Z}$. From now on, we shall only consider solutions with finite support, that is we assume that $U_i^t = 0$ for |i| sufficiently large. By the same limiting process, (4) gives

$$\sum_{i \in \mathbb{Z}} U_i^t \text{ is independent of } t.$$
(18)

The naive form (17) cannot be used to determine the time evolution uniquely and instead one considers the ultradiscrete limit of (5) to obtain the *update rule*

$$U_i^{t+1} = \min\left(1 - U_i^t, \sum_{j < i} (U_j^t - U_j^{t+1})\right).$$
(19)

Changing t to t-1 and rewriting (19) using the conserved quantity (18) gives

$$U_i^t + U_i^{t-1} = \min\left(1, \sum_{j \leqslant i} U_j^{t-1} - \sum_{j < i} U_j^t\right) = \min\left(1, \sum_{j \geqslant i} U_j^t - \sum_{j > i} U_j^{t-1}\right),$$

which gives the *downdate rule*

$$U_i^{t-1} = \min\left(1 - U_i^t, \sum_{j>i} (U_j^t - U_j^{t-1})\right).$$
(20)

Note that if U_i^t satisfies (19) then (17) is also satisfied using the associativity and commutativity of min.

The bilinear form (6) has ultradiscrete limit $(\tau_i^t = O(\delta^{-T_i^t}))$

$$T_{i+1}^{t+1} + T_i^{t-1} = \max(T_{i+1}^t + T_i^t, T_i^{t+1} + T_{i+1}^{t-1} - 1),$$
(21)

where

$$U_i^t = T_{i+1}^t + T_i^{t+1} - T_i^t - T_{i+1}^{t+1}.$$
(22)

We assume that there is a solution ϕ_i^t of (8),(9) that is positive for all i, t. Then, taking the ultradiscrete limit $(\phi_i^t = O(\delta^{-\Phi_i^t}), 1 - \lambda^2 = O(\delta^{\kappa}), 1 - \lambda^2/\beta^2 = O(\delta^{\omega}))$ on the dKdV Lax pair leads to

$$\max(\Phi_{i+1}^t - \kappa, \Phi_{i-1}^t) = \Phi_i^t + \max(U_{i-1}^t - 1, -U_i^t),$$
(23)

$$\max(\Phi_{i+1}^{t+1} - \kappa, \Phi_{i-1}^{t+1}) = \Phi_i^{t+1} + \max(U_i^t - 1, -U_{i-1}^t),$$
(24)

$$\max(\Phi_{i+1}^{t+1}, \Phi_{i+1}^t + U_i^t - 1) = \Phi_i^t,$$
(25)

$$\max(\Phi_i^t + \kappa - \omega, \Phi_i^{t+1} + U_i^t + \kappa - 1) = \Phi_{i+1}^{t+1},$$
(26)

where ω is a nonnegative free parameter (spectral parameter) and $\kappa = \min(1, \omega)$. We call this system the ultradiscrete linear system for udKdV [10], where 'linearity' has to be understood as over the (max, +) semi-field: if Φ_i^t and $\widehat{\Phi}_i^t$ satisfy the system then so do $\max(\Phi_i^t, \widehat{\Phi}_i^t)$ and $\Phi_i^t + \phi$, for arbitrary constant ϕ . The rationale for imposing four linear equations in the ultradiscrete case instead of the customary two (as in the discrete or continuous case) is explained in [10].

3 Description of the general solution of udKdV

It is well known that the general solution of the box and ball system (udKdV with $U_i^t \in \{0, 1\}$ and finite support) consists of interacting solitons made up of strings of k consecutive 1s, propagating at speed k. The most general solution in the case $U_i^t \in \mathbb{R}$ is more complicated but can still be described completely: it consists of interacting solitons parametrised by positive parameters ω , plus a "background" that moves with speed 1, which is the minimal speed in the system [12, 13] (see also Remark 9.1).

Any pair of a positive real number ω and a real phase constant ϕ fully describes a soliton solution to udKdV. Its *T*-function can be obtained as the ultradiscrete limit of a dKdV soliton but can also be verified directly by substitution in (21). It is given by $T_i^t = \max(0, \kappa(i - \phi) - \omega t) = \max(0, \kappa(i - \phi^t))$, where $\kappa = \min(1, \omega)$ (the wave number) and $\varphi^t = \phi + ct$ (a time-dependent phase) in which the wave speed $c = \max(1, \omega)$ is always at least 1 (note that $\kappa c = \omega$). For $\omega \leq 1$, $\kappa = \omega$ and c = 1 whereas for $\omega \geq 1$, $\kappa = 1$ and $c = \omega$. From (22) the solution U_i^t is expressed in terms of four copies of the *T*-function: $U_i^t = T_{i+1}^t + T_i^{t+1} - T_i^t - T_{i+1}^{t+1}$.

It is beneficial here to study this solution $U^t(x) = U_i^t$ with the discrete space variable *i* replaced by a real-valued variable x [12]. The expression for $U^t(x)$ is written explicitly as

$$U^{t}(x) = \begin{cases} \kappa(x+1-\varphi^{t}) & \varphi^{t}-1 \leqslant x < \varphi^{t} \\ \kappa & \varphi^{t} \leqslant x < \varphi^{t+1}-1 \\ -\kappa(x-\varphi^{t+1}) & \varphi^{t+1}-1 \leqslant x < \varphi^{t+1} \\ 0 & \text{otherwise.} \end{cases}$$

In Figure 1 (a) $\omega = 17/3 > 1$ and so $\kappa = 1$ and c = 17/3. The solution at integer points is $U_i^0 = \ldots, 0, 0, 1/2, 1, 1, 1, 1, 1, 1/6, 0, \ldots$ When considered in terms of the real variable x, the soliton simply translates at speed c but when c is non-integer, due to a stroboscopic effect, the soliton is not of fixed form on the integer lattice. In (b) $\omega = 2/3 \leq 1$ and so $\kappa = 2/3$ and c = 1. Hence $U_i^t = \ldots, 0, 0, 1/2, 1/6, 0, \ldots$ which propagates without change at speed 1.

In all cases, the area under the (real) curve $U^t(x)$ is $\kappa c = \omega$ and so we call ω the soliton mass. If we restrict back to integer *i*, each soliton has formula



Figure 1: Solitons plotted on \mathbb{R} for t = 0. In each plot the solid line is the graph of $U^t(x)$ and the points show the values of U_i^t $(i \in \mathbb{Z})$. In (a) $\omega = 17/3$, $\phi = 5/2$ and in (b) $\omega = 2/3$, $\phi = 9/4$.

$$U_i^t = \begin{cases} \kappa (1 - \{\varphi^t\}) & i = \lfloor \varphi^t \rfloor \\ \kappa & \lfloor \varphi^t \rfloor + 1 \leqslant i < \lceil \varphi^{t+1} \rceil - 1 \\ \kappa (1 - \{-\varphi^{t+1}\}) & i = \lceil \varphi^{t+1} \rceil - 1 \\ 0 & \text{otherwise,} \end{cases}$$
(27)

where $\lfloor x \rfloor$ and $\lceil x \rceil$ denote, respectively, the floor and ceiling of a real number x and $\{x\} := x - \lfloor x \rfloor$ denotes the fractional part of x. Notice that the sum over all U_i^t always equals the soliton mass:

$$\begin{split} \sum_{i} U_{i}^{t} &= \kappa (1 - \{\varphi^{t}\}) + (\lceil \varphi^{t+1} \rceil - 1 - (\lfloor \varphi^{t} \rfloor + 1))\kappa + \kappa (1 - \{-\varphi^{t+1}\}) \\ &= \kappa (-\varphi^{t} + \lfloor \varphi^{t} \rfloor + \lceil \varphi^{t+1} \rceil - \lfloor \varphi^{t} \rfloor - (-\varphi^{t+1}) + \lfloor -\varphi^{t+1} \rfloor) \\ &= \kappa (\varphi^{t+1} - \varphi^{t}) = \kappa c = \omega, \end{split}$$

since for any x, $\lfloor x \rfloor + \lceil -x \rceil = 0$.

Define the maximal local sum

$$V^{t} := \max(U_{i}^{t} + U_{i+1}^{t}), \tag{28}$$

which is non-negative since $U_i^t = 0$ for large enough |i|. The state $U_i^t = 0$ for all i, t is called *trivial*. If U_i^t is nontrivial but $V^t = 0$ then we call U_i^t background. A background state translates with speed 1 in the direction of increasing i. Indeed, any state with $V^t \leq 1$ can be shown to translate at speed 1 (see Corollary 4.1). This makes it impossible, by superficial examination of the asymptotic state U_i^t at $t \to \infty$ alone, to distinguish background from solitons of mass $\omega \leq 1$.

In [9], Hirota has shown how to construct the *T*-function for a background solution to the ultradiscrete KdV equation. As will be proved in Corollary 4.1, a background B_i^t translates at speed 1 and so $B_i^t = B_{i-t}^0$. Now observe that the Kronecker δ -function satisfies $\delta_{i,j} = \frac{1}{2} (|i+1-j|+|i-1-j|-2|i-j|)$ and so $B_i^t = \sum_{j \in \mathbb{Z}} \delta_{i-t,j} B_j^0 = T_{i+1}^t + T_i^{t+1} - T_i^t - T_{i+1}^{t+1}$, where

$$T_{i}^{t} = \frac{1}{2} \sum_{j \in \mathbb{Z}} |i - t - j| B_{j}^{0},$$
(29)

is the background T-function [9].

When $V^t > 1$, in general, not much can be said about the *T*-functions at the level of the bilinear equation (21), besides their asymptotic behaviour in *i*. Let us define $Z_i^t = T_i^t - T_i^{t+1}$, which is a discrete potential for U_i^t : $U_i^t = \Delta Z_i^t = Z_{i+1}^t - Z_i^t$. Since U_i^t has finite support it is clear that asymptotically, for $|i| \gg 1$, Z_i^t will take values Z_+^t or Z_-^t depending on the sign of *i* but otherwise independent of |i|. In fact, these two values do not depend on *t* either. Replacing T_i^{t+1} by $T_i^t - Z_i^t$ and T_i^{t-1} by $T_i^t + Z_i^{t-1}$ in the ultradiscrete bilinear equation (21), we find in the asymptotic regime where $U_i^t = 0 \forall |i| \gg 1$ that $Z_{\pm}^{t-1} - Z_{\pm}^t = \max(0, Z_{\pm}^{t-1} - Z_{\pm}^t - 1)$ and that $Z_{\pm}^t = Z_{\pm}^{t-1}$ for all *t*. The asymptotic values Z_+ and Z_- are obviously related by $Z_+ - Z_- = \sum_{i \in \mathbb{Z}} U_i^t$. Note that since U_i^t has finite support, this last sum is actually a finite sum.

For example, the asymptotics for the background T-function (29) is

$$Z_{\pm} = \lim_{i \to \pm \infty} \frac{1}{2} \sum_{j \in \mathbb{Z}} \left(|i - t - j| - |i - t - 1 - j| \right) B_j^0 = \pm \frac{1}{2} \sum_{j \in \mathbb{Z}} B_j^0,$$

i.e. +1 or -1 times half the mass of the background.

Notice also that, by using the natural gauge freedom $T_i^t \mapsto T_i^t + \alpha i + \beta t + \gamma \ (\alpha, \beta, \gamma \in \mathbb{R})$ we have in defining a *T*-function by (21) or (22) (both relations are invariant under such a transformation, but $Z_i^t \mapsto Z_i^t - \beta$), we can assign any value we choose to either Z_+ or Z_- .

It was already mentioned in passing that the general solution of udKdV (with finite support) consists of a finite number of solitons of masses $0 < \omega_1 \leq \cdots \leq \omega_n$ plus a background. In the next few sections we shall develop a set of tools that will allow us to prove this statement and that yield an algorithm for obtaining analytic expressions for the *T*-functions for such general solutions to the udKdV equation.

4 Alternative version of the update and downdate rules

In this section, we give alternative descriptions of the update and downdate rules. These allow us to prove some basic results on the udKdV evolution in an elementary way. They also have some computational advantage over the more usual formulae.

Let $a = (a_i)_{i \in \mathbb{Z}}$ denote a real sequence. It is assumed that a is summable, that is, $\sum a := \sum_{i \in \mathbb{Z}} a_i$ is finite and so necessarily $a_i \to 0$ as $i \to \pm \infty$.

Definition 4.1. Define $R_j : \mathbb{R} \to \mathbb{R}$, for $j \in \mathbb{Z}$, by

$$R_j(a_j) = \min(1, a_j), \ R_j(a_{j+1}) = a_{j+1} + a_j - \min(1, a_j), \ R_j(a_i) = a_i \ (i \neq j, j+1)$$

This definition is extended to real sequences in the natural way: $R_j(a) = (R_j(a_1), R_j(a_2), \dots)$.

Remark 4.1. One may visualise (a_i) as the contents of an array of cells labelled *i* whose preferred capacities are each 1. Then the action of operator R_j is to transfer the excess content of an overfull cell *j* to the right neighbouring cell j + 1 (even though it might already be overfull or become overfull). If cell *j* is not overfull, $a_j \leq 1$, then R_j acts as the identity. Note also that for any j, $R_j(a_j) + R_j(a_{j+1}) = a_j + a_{j+1}$ and so acting by any R_j leaves the sum of the sequence invariant.

Definition 4.2. Define $R : \mathbb{R} \to \mathbb{R}$ by $R = \cdots \circ R_3 \circ R_2 \circ R_1 \circ \cdots$.

- *Remarks* 4.1. (i) For any sequence a, the resulting sequence R(a) has terms which do not exceed 1 and so R is idempotent: $R^2(a) = R(a)$.
- (ii) Although R is the composition of infinitely many functions, all but finitely many of them act as the identity. Since for any given $a, a_i \to 0$ as $i \to -\infty$ then certainly $a_i \leq 1$ for i < m (say). Also, since the sum of the sequence is finite, it follows that for some $n \geq m$,

$$R(a) = R_n \circ \cdots \circ R_{m+1} \circ R_m(a).$$

Lemma 4.1. For any summable sequence a,

$$R(a)_i = \min\left(1, \sum_{j \le i} a_j - \sum_{j < i} R(a)_j\right).$$
(30)

Proof. Let m be the smallest index such that $a_m > 1$ and for each j, where $j \ge m$, define $a^{(j)} = R_j \circ R_{j-1} \circ R_{j-2} \circ \cdots \circ R_m(a)$.

We first observe that for any i, $a_k^{(i)} = a_k$ for all k > i + 1 and $a_k^{(i)} = a_k^{(k)}$ for all k < i. It follows that for any i, $R(a)_j = a_j^{(j)}$. Also we have

$$a_i^{(i)} = \min(1, a_i^{(i-1)}) \text{ and } a_{i+1}^{(i)} = a_{i+1} + a_i^{(i-1)} - a_i^{(i)}.$$
 (31)

It follows by a straightforward inductive argument starting at i = m that $a_i^{(i-1)} = \sum_{j \leq i} a_j - \sum_{j < i} a_j^{(j)}$ and then (30) follows from (31).

Theorem 4.1. A real summable sequence (U_i^t) has udKdV time update (U_i^{t+1}) where

$$U_i^{t+1} + U_i^t = R(U_{i-1}^t + U_i^t).$$

Proof. Let a be the sequence with $a_i = U_{i-1}^t + U_i^t$. Then, by Lemma 4.1,

$$R(a)_{i} - U_{i}^{t} = \min\left(1, \sum_{j < i} U_{j}^{t} + \sum_{j \leq i} U_{j}^{t} - \sum_{j < i} R(a)_{j}\right) - U_{i}^{t}$$
$$= \min\left(1 - U_{i}^{t}, \sum_{j < i} U_{j}^{t} - \sum_{j < i} (R(a)_{j} - U_{j}^{t})\right),$$

which is the time update rule (19) with $R(a)_i - U_i^t = U_i^{t+1}$.

Remark 4.2. There is an entirely analogous alternative version of the downdate rule in which excess cell capacity is moved left rather than right:

$$U_i^{t-1} + U_i^t = L(U_i^t + U_{i+1}^t),$$

where $L = \cdots \circ L_1 \circ L_2 \circ L_3 \circ \cdots$ and

$$L_j(a_j) = \min(1, a_j), \ L_j(a_{j-1}) = a_{j-1} + a_j - \min(1, a_j), \ L_j(a_i) = a_i \ (i \neq j, j-1)$$

Examples 4.1. This example will illustrate how to use this version of the downdate rule. We use an over bar to indicate negative numbers and values of U_i^t outside the interval shown are 0.

A second example illustrates the update rule with real values.

$$\begin{array}{rcrcrcrcrcrcrc} U_i^t & : & 0 \ \pi \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \\ \\ U_{i-1}^t + U_i^t & : & 0 \ \pi \ \pi \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \\ \\ R(U_{i-1}^t + U_i^t) & : & 0 \ 1 \ 1 \ 1 \ 1 \ 1 \ \alpha \ 0 \\ \\ R(U_{i-1}^t + U_i^t) - U_i^t = U_i^{t+1} \ : & 0 \ \beta \ 1 \ 1 \ 1 \ 1 \ 1 \ \alpha \ 0 \end{array}$$

where $\alpha = 2\pi - 6 \in (0, 1)$ and $\beta = 1 - \pi < 0$. Note that the total masses in the two examples, $\frac{7}{2}$ and $\pi = 5 + \alpha + \beta$ respectively, are preserved under the evolution.

Using the alternative formulation of the update/downdate rule the following properties are apparent:

Corollary 4.1.

- (i) Total mass $\sum_{i \in \mathbb{Z}} U_i^t$ is conserved (cf. (4)).
- (ii) For any t, V^t defined in equation (28) satisfies: $V^t \leq 1 \iff U_i^{t+1} = U_{i-1}^t$ for all i. If $V^t \leq 1$ then it is t-invariant.

Proof. (i) This follows since the action of R preserves the sum of any sequence.

(ii) A sequence a is invariant under the action of R if and only if $a_i \leq 1$ for all i and $U^{t+1} = R(U_{i-1}^t + U_i^t) - U_i^t = U_{i-1}^t \iff R$ acts as the identity.

5 Two more conserved quantities

We have already seen that when U_i^t satisfies udKdV then the sum $\sum_i U_i^t$ is conserved. In this section we establish two more constants of the motion. These conserved quantities have essential applications to the study of the solution of the ultradiscrete linear problem (23)–(26). Some proofs given in this section make use of the following general result.

Lemma 5.1. Let (a_n) , (b_n) , $(n \in \mathbb{Z})$ be bounded real sequences. If there exists (at least one) m such that $a_m > a_{m-1}$, and for every such m, $b_m \ge a_m$ then $\sup_i b_i \ge \sup_i a_i$.

By reversing the order of these sequences this criterion is equivalently restated: if there exists (at least one) m such that $a_m > a_{m+1}$, and for every such m, $b_m \ge a_m$ then $\sup_i b_i \ge \sup_i a_i$.

Proof. Let I be the (necessarily non-empty) subset of \mathbb{Z} at which the sequence (a_n) increases, that is $I = \{m \in \mathbb{Z} : a_m > a_{m-1}\}$. It is obvious that $\sup_{i \in \mathbb{Z}} a_i = \sup_{i \in I} a_i$ and if $b_m \ge a_m$ for all $m \in I$ then $\sup_{i \in I} b_i \ge \sup_{i \in I} a_i$. Hence $\sup_{i \in I} b_i \ge \sup_{i \in \mathbb{Z}} a_i$.

Now consider two particular sequences defined by

$$X_i^t := \sum_{j \ge i} (U_j^{t+1} - U_j^{t-1}) = \sum_{j < i} (U_j^{t-1} - U_j^{t+1}),$$
(32)

and

$$Y_i^t := \sum_{j>i} U_j^t - \sum_{j\geqslant i} U_j^{t-1} = \sum_{j(33)$$

where the alternative expressions are obtained using the conservation of total mass (18). Since all time updates and downdates of U_j^t equal zero for |j| large enough, both X_i^t and Y_i^t are zero for |i| sufficiently large. These sequences therefore attain maximum values. Further, they will be seen to be the ultradiscrete conserved densities of two more conserved quantities: $\max_i X_i^t$ is the maximum soliton mass and $1+\max_i Y_i^t$ is the maximum soliton speed. A discrete conserved density is a sequence the sum of which is time independent; an ultradiscrete conserved density is a sequence the maximum of which is time independent.

We will now show some properties that will allow us to apply Lemma 5.1 to establish the connection between the maximum values of these two sequences. First we record a few basic formulae. The notation Δ for the forward difference operator $\Delta A_i = A_{i+1} - A_i$ is used:

$$\Delta X_i^t = U_i^{t-1} - U_i^{t+1} \tag{34}$$

$$\Delta Y_i^t = U_i^{t-1} - U_{i+1}^t \tag{35}$$

$$X_i^t = U_i^t + U_i^{t+1} + Y_i^t + Y_i^{t+1} = U_{i-1}^{t-1} + U_{i-1}^t + Y_{i-1}^t + Y_{i-1}^{t+1}.$$
(36)

The downdate rule (20) may be written in terms of Y_i^t as $\min(1 - U_i^t - U_i^{t-1}, Y_i^t) = 0$ and so it is clear that for all i, t

$$Y_i^t \ge 0 \quad \text{and} \quad U_i^t + U_i^{t-1} \le 1, \tag{37}$$

and

$$Y_i^t > 0 \implies U_i^t + U_i^{t-1} = 1, \quad U_i^t + U_i^{t-1} < 1 \implies Y_i^t = 0.$$
 (38)

Lemma 5.2. The following three statements are equivalent for any t:

- (i) $V^t \leq 1$,
- (ii) for all *i*, $U_i^{t+1} = U_{i-1}^t$,
- (iii) for all $i, Y_i^t = 0$.

Moreover, these three conditions are t-invariant.

Proof. The equivalence and t-invariance of the first two statements were established in Corollary 4.1 (ii). Suppose that $Y_i^t = 0$ for all i, at some t. Then relation (35) gives $U_i^{t-1} = U_{i+1}^t$, which is equivalent to (ii) since this condition is t-invariant by Corollary 4.1. Conversely, if condition (ii) holds then for all i and t we have $U_i^{t-1} = U_{i+1}^t$ and $Y_i^t = 0$, by (35), for all i at every instant t.

This Lemma implies:

Corollary 5.1.

- (i) If the conditions in Lemma 5.2 are met then: for all $i, X_i^t \leq V^t$, with equality for some i.
- (ii) If $V^t > 1$ then there exists some *i* for which $X_i^t > 1$.

Proof. (i) Suppose that $U_i^{t+1} = U_{i-1}^t$ for all *i*. Then (32) gives $X_i^t = U_i^t + U_{i-1}^t$ which is of course less than or equal to $\max_i(U_i^t + U_{i+1}^t)$. Hence, $X_i^t \leq V^t$ (28), and the equality must be attained for some *i*. Notice that these relations are *t*-invariant.

(ii) By Lemma 5.2, if $V^t > 1$ then $Y_i^t > 0$ for some *i*. Then by (38), $U_i^t + U_i^{t-1} = 1$ and by (36), $X_{i+1}^t = 1 + Y_i^t + Y_i^{t+1}$. Since $Y_i^t > 0$ and $Y_i^{t+1} \ge 0$, $X_{i+1}^t > 1$.

The second inequality in (37) can be slightly sharpened. In the case $V^t = \max_i (U_i^t + U_{i+1}^t) \leq 1$ we have $U_i^{t-1} = U_{i+1}^t$ and hence for any U_i^t ,

$$U_i^t + U_i^{t-1} \leqslant \min(1, V^t). \tag{39}$$

While investigating the relationship between the maxima of X_i^t and Y_i^t we will consider two cases, $V^t \leq 1$ and $V^t > 1$. In the case $V^t \leq 1$, it is clear from Lemma 5.2 and Corollary 5.1 that

$$\max_{i} Y_i^t = 0 \text{ and } \max_{i} X_i^t = V^t \text{ for all } t.$$
(40)

We will see below that this is a special case of a result that holds in all cases: $\max_i X_i^t$ and $1 + \max_i Y_i^t$ are independent of t and give the mass and speed of the heaviest soliton in U_i^t .

In the next two propositions we consider the case in which $V^t > 1$. Notice that this implies that $V^t > 1$ for all t (since any value $V^t \leq 1$ is t-invariant). So, by Corollary 5.1 and Lemma 5.2, for any t there exists i, such that $X_i^t > 1$ and $Y_i^t > 0$.

Proposition 5.1. Let $V^t > 1$.

(i) For any t, there exists m such that $Y_m^t > Y_{m-1}^t$ and for any such m, $X_{m+1}^t \ge 1 + Y_m^t$ and so

$$\max X_i^t \ge 1 + \max Y_i^t.$$

(ii) For any t, there exists m such that $X_{m+1}^t > X_m^t$ and for any such m, $1 + Y_m^t \ge X_{m+1}^t$ and so

$$1 + \max Y_i^t \ge \max X_i^t.$$

Hence

$$\max_{i} X_i^t = 1 + \max_{i} Y_i^t.$$

Proof. In both cases, the existence of m is clear (since $V^t > 1$ and $X_i^t, Y_i^t = 0$ for |i| sufficiently large) and the conclusions are obtained using the principle established in Lemma 5.1. In (i) we take $a_n = 1 + Y_n^t$ and $b_n = X_{n+1}^t$, and in (ii) $a_n = X_{n+1}^t$ and $b_n = 1 + Y_n^t$. We now establish the required inequalities.

(i) Let $Y_m^t > Y_{m-1}^t$ (i.e. $a_m > a_{m-1}$). From (37), all $Y_i^t \ge 0$ and it follows that $Y_m^t > 0$. Using (36) and (38)

$$X_{m+1}^{t} = U_{m}^{t-1} + U_{m}^{t} + Y_{m}^{t} + Y_{m}^{t+1} = 1 + Y_{m}^{t} + Y_{m}^{t+1} \ge 1 + Y_{m}^{t},$$

(i.e. $b_m \ge a_m$) and the result follows.

(ii) Similarly, let $X_{m+1}^t > X_m^t$. Then from (34), $U_m^{t+1} < U_m^{t-1}$ and since from (37) $U_m^t + U_m^{t-1} \leq 1$, we obtain $U_m^{t+1} + U_m^t < 1$ and so from (38) $Y_m^{t+1} = 0$. Therefore, using (36),

$$X_{m+1}^{t} = U_m^{t-1} + U_m^{t} + Y_m^{t} + Y_m^{t+1} \leqslant 1 + Y_m^{t}.$$

Proposition 5.2. Let $V^t > 1$.

(i) For any t, there exists m such that $Y_m^{t+1} > Y_{m+1}^{t+1}$ and for any such m, $X_m^t \ge 1 + Y_m^{t+1}$ and so

$$\max_{i} X_{i}^{t} \ge 1 + \max_{i} Y_{i}^{t+1}$$

(ii) For any t, there exists m such that $X_m^t > X_{m+1}^t$ and for any such m, $1 + Y_m^{t+1} \ge X_m^t$ and so

$$1 + \max_{i} Y_i^{t+1} \ge \max_{i} X_i^t.$$

Hence

$$\max_{i} X_i^t = 1 + \max_{i} Y_i^{t+1}.$$

Proof. Again the existence of m is clear and as in the proof of Proposition 5.1, we apply Lemma 5.1. In proving (i) we take $a_n = 1 + Y_n^{t+1}$ and $b_n = X_n^t$, and in (ii), $a_n = X_n^t$ and $b_n = 1 + Y_n^{t+1}$.

(i) Let $Y_m^{t+1} > Y_{m+1}^{t+1}$. Hence $Y_m^{t+1} > 0$ and so using (36) and (38)

$$X_m^t = U_m^{t+1} + U_m^t + Y_m^t + Y_m^{t+1} = 1 + Y_m^t + Y_m^{t+1} \ge 1 + Y_m^{t+1}.$$

(ii) Let $X_m^t > X_{m+1}^t$. Then from (34), $U_m^{t-1} < U_m^{t+1}$ and since $U_m^t + U_m^{t+1} \le 1$, we obtain $U_m^{t-1} + U_m^t < 1$ and so from (38) $Y_m^t = 0$. Therefore, using (36),

$$X_m^t = U_m^{t+1} + U_m^t + Y_m^t + Y_m^{t+1} \leqslant 1 + Y_m^{t+1}.$$

The results of this section so far are summarised in a theorem.

Theorem 5.1. Let U_i^t satisfy the udKdV equation (19). Then $\max_i X_i^t$ and $\max_i Y_i^t$, with X_i^t and Y_i^t as defined in (32) and (33), are conserved under time evolution.

Moreover, if $V^t > 0$,

$$\omega_{max} = \max_{i} X_i^t \quad and \quad 1 + \max_{i} Y_i^t = c_{max} = \max(1, \omega_{max}),$$

are the mass and speed of the solitons of maximal mass contained in the state U_i^t .

Remark 5.1. We define $\kappa_{\max} := \min(1, \omega_{\max})$. Then, in the case $0 < V^t \leq 1$, from (40), $\omega_{\max} = \kappa_{\max} = V^t \leq 1$ and $c_{\max} = \omega_{\max}/\kappa_{\max} = 1$. Such a state U_i^t consists of solitons that move in tandem with the background, at speed 1. The maximal mass ω_{\max} of the solitons in such a state can therefore not be ascertained by mere (visual) inspection of U_i^t if the solitons are engulfed in the background.

For $V^t > 1$ however (from Corollary 5.1) we have $\omega_{\max} > 1$ and $\kappa_{\max} = 1$ and ω_{\max} (being independent of t) may be calculated asymptotically as $t \to \pm \infty$. As discussed in Section 3, arbitrary initial conditions U_i^0 evolve into a finite train of solitons each characterised by a mass $\omega > 0$ and phase ϕ . For $V^t > 1$, the solitons of mass $\omega > 1$ move at speed $c = \omega$ and hence become well separated as $t \to \pm \infty$ whereas solitons of mass $\omega \leq 1$ move at speed 1 along with the background. As we shall see, the ultradiscrete spectrum is not simple and an arbitrary number of solitons may have the same mass ω and speed. However such sets of solitons have a minimum separation, also equal to ω . For large enough t all solitons are therefore well separated and it is straightforward to use (27) to show that any local maximum of X_i^t is equal to the mass of the soliton which includes site i, and is sub-maximal otherwise. The interpretation of ω_{\max} as maximal soliton mass follows.

Remark 5.2. Using the quantity $\kappa_{\text{max}} = \min(1, \omega_{\text{max}})$ inequality (39) can be reformulated, for general U_i^t , as

$$U_i^t + U_i^{t-1} \leqslant \kappa_{\max},\tag{41}$$

for any i, t.

Remark 5.3. If U_i^t is nontrivial but $V^t = 0$ at some instant t, it is 0 for all t and we have just background propagating unchanged at speed 1. There are no solitons: since $V^t = 0$, from Lemma 5.2 and Corollary 5.1 we have $\omega_{\max} = 0$. Moreover, $\kappa_{\max} = \min(1, \omega_{\max}) = 0$. Note that the converse is also true. If $\omega_{\max} = 0$, then from Theorem 5.1 we have $Y_i^t = 0$ for all i and thus, by Corollary 5.1, $U_{i+1}^{t+1} = U_i^t$, for all i and t. From remark 5.2 we then have $V^t = 0$ since $U_i^t + U_{i+1}^t = U_i^t + U_i^{t-1} \leq 0$ for all i.

Proposition 5.3. For any U_i^t we have

$$\Delta X_i^t > 0 \implies U_i^t + U_i^{t+1} < \kappa_{max}, \quad \Delta X_i^t < 0 \implies U_i^t + U_i^{t-1} < \kappa_{max}.$$

Proof. From (34), $\Delta X_m^t = U_i^{t-1} - U_i^{t+1}$. Then, from (41),

$$\Delta X_m^t \leqslant \kappa_{\max} - U_i^t - U_i^{t+1} \quad \text{or} \quad \Delta X_m^t \geqslant U_i^t + U_i^{t-1} - \kappa_{\max}.$$

The results follow immediately.

Examples 5.1. Consider a state U_i^t . The first value shown has index i = 1 and the state is 0 outside of the interval shown. We use an over bar to indicate a negative number: for x > 0, \overline{x} denotes -x).

Hence $\omega_{\text{max}} = 3$, which is attained throughout two different regions (in *i*). This indicates the presence of at least two solitons of mass 3. In principle, there may be several maximal mass solitons within each maximal

	. 1	
	. 1	
	. 1	

region, as another example illustrates:

giving $\omega_{\max} = 2$, attained throughout a single region although U_i^t contains two mass 2 solitons.

Finally we state a technical lemma that is needed later. A proof can be found in Appendix A of [18].

Lemma 5.3. (i) If $X_m^t > 1$ is locally maximal at m, at time t, then

$$(U_{m-1}^t + U_m^t \ge 1 \text{ or } U_m^{t-1} + U_m^t = 1) \text{ and } (U_{m-1}^t + U_m^t \ge 1 \text{ or } U_{m-1}^t + U_{m-1}^{t+1} = 1).$$

(ii) If X_m^t is a global maximum, i.e. if $X_m^t = \omega_{max}$, then

$$U_{m-1}^{t} + U_{m-1}^{t-1} = \kappa_{max}$$

6 On Darboux transformations for dKdV and udKdV

Let u_i^t be a solution of the dKdV equation (1) and let θ_i^t be a non-zero solution of linear system (8), (9) for any choice of parameter λ . Then [19]

$$\widetilde{\phi}_i^t = \frac{\phi_{i-1}^t \theta_i^t - \phi_i^t \theta_{i-1}^t}{\theta_i^t},\tag{42}$$

satisfies (8), (9) with

$$\widetilde{\tau}_i^t = \tau_i^t \theta_i^t \tag{43}$$

and thus, using (7),

$$\widetilde{u}_i^t = u_i^t \frac{\theta_i^{t+1} \theta_{i+1}^t}{\theta_i^t \theta_{i+1}^{t+1}},\tag{44}$$

is a solution of the dKdV equation (1).

Because of the presence of a negative sign, there is no obvious ultradiscrete counterpart of (42). However, the transformation of the tau function (43) and potential (44) have ultradiscrete limits

$$\widetilde{T}_i^t = T_i^t + \Theta_i^t \quad \text{and} \quad \widetilde{U}_i^t = U_i^t + \Theta_{i+1}^t + \Theta_i^{t+1} - \Theta_i^t - \Theta_{i+1}^{t+1}.$$
(45)

In Sections 7 and 8 we will construct solutions to the linear problem (23)–(26) for which (45) indeed acts as an ultradiscrete Darboux transformation, i.e.: it maps a solution U_i^t of udKdV (19) with finite support to another solution of udKdV, also with finite support (and similarly for the associated *T*-functions).

We now derive some properties of the discrete Darboux transformation and the corresponding properties they imply for the ultradiscrete Darboux transformation.

Lemma 6.1. Let θ_i^t , any non-zero solution of (8), (9), determine the Darboux transformation (44) from u_i^t to \tilde{u}_i^t . Then

$$\frac{1}{\widetilde{u}_i^t} + \delta \widetilde{u}_{i-1}^t = \frac{\theta_i^{t^2}}{\theta_{i+1}^t \theta_{i-1}^t} \left(\frac{1}{u_i^t} + \delta u_{i-1}^t \right).$$

$$\tag{46}$$

The transformed linear problem has particular solution

$$\widetilde{\theta}_i^t := \frac{1}{\rho_i^t} = \frac{(1-\lambda^2)^{-i}(1-\lambda^2/\beta^2)^t}{\theta_i^t},\tag{47}$$

where ρ_i^t is the adjoint eigenfunction related to θ_i^t (cf. (12)). The Darboux transformation defined by $\tilde{\theta}_i^t$ maps \tilde{u}_i^t back to u_i^t .

Proof. From (8) and (9) the θ_i^t satisfy

$$\theta_{i-1}^{t} - \frac{2}{1+\delta} \left(\frac{1}{u_{i}^{t}} + \delta u_{i-1}^{t} \right) \theta_{i}^{t} + (1-\lambda^{2}) \theta_{i+1}^{t} = 0$$

$$\beta \theta_{i}^{t+1} = \theta_{i-1}^{t} + (\beta - 1) u_{i-1}^{t} \theta_{i}^{t} = -(1-\lambda^{2}) \theta_{i+1}^{t} - \frac{(\beta - 1)}{\delta u_{i}^{t}} \theta_{i}^{t},$$
(48)

for some parameter λ , with $\beta = \frac{1-\delta}{1+\delta}$. Using (48), we get

$$\begin{split} \frac{1}{\widetilde{u}_i^t} + \delta \widetilde{u}_{i-1}^t &= \frac{\theta_i^t}{\theta_{i+1}^t \theta_{i-1}^{t+1} \theta_i^{t+1}} \left(\frac{1}{u_i^t} \theta_{i+1}^{t+1} \theta_{i-1}^t + \delta u_{i-1}^t \theta_{i+1}^{t+1} \theta_{i-1}^{t+1} \right) \\ &= \frac{\theta_i^{t^2}}{\beta \theta_{i+1}^t \theta_{i-1}^t \theta_i^{t+1}} \left(\frac{1}{u_i^t} \theta_{i-1}^t - \delta u_{i-1}^t \theta_{i+1}^t (1-\lambda^2) \right) \\ &= \frac{\theta_i^{t^2}}{\theta_{i+1}^t \theta_{i-1}^t} \left(\frac{1}{u_i^t} + \delta u_{i-1}^t \right). \end{split}$$

This proves (46).

That θ_i^t is a solution of the transformed linear system follows by similar straightforward calculations. Let \hat{u}_i^t be the result of applying the Darboux transformation defined by $\tilde{\theta}_i^t$ to \tilde{u}_i^t . Then from (43),

$$\widehat{\tau}_i^t = \widetilde{\theta}_i^t \widetilde{\tau}_i^t = \widetilde{\theta}_i^t \theta_i^t \tau_i^t = (1 - \lambda^2)^{-i} (1 - \lambda^2 / \beta^2)^t \tau_i^t,$$

and so, using (7), $\hat{u}_i^t = u_i^t$, as required.

Remark 6.1. A generic solution θ_i^t of (8), (9) has asymptotic form as $i \to \pm \infty$ given by (14) and (15). Consequently, for $\tilde{\theta}_i^t$ given by (47),

$$\widetilde{\theta}_i^t \sim \frac{1}{a(1-\lambda)^i(1-\lambda/\beta)^{-t} + b(1+\lambda)^i(1+\lambda/\beta)^{-t}}$$

as $i \to -\infty$ and

$$\widetilde{\theta}_i^t \sim \frac{1}{c(1-\lambda)^i(1-\lambda/\beta)^{-t} + d(1+\lambda)^i(1+\lambda/\beta)^{-t}},$$

as $i \to +\infty$. When $0 < \lambda < \beta < 1$, the terms $(1 - \lambda)^i$ and $(1 + \lambda)^i$ tend to ∞ as $i \to -\infty$ and as $i \to +\infty$, respectively. Hence $\tilde{\theta}_i^t \to 0$ as $i \to \pm\infty$, showing it has finite norm (16) and therefore corresponds to a bound state.

As in the continuous case [14], a Darboux transformation determined by a generic eigenfunction θ_i^t can be used to add a bound state to u_i^t . That is, compared to u_i^t , the transformed potential \tilde{u}_i^t will have an extra eigenvalue added to its discrete spectrum, where we think of these solutions to the dKdV equation as potentials in spectral equation (8). Such a transformation is often referred to as a *dressing* transformation. Conversely, the Darboux transformation determined by the eigenfunction $\tilde{\theta}_i^t$ removes this bound state from \tilde{u}_i^t . A transformation based on a bound state eigenfunction is therefore referred to as an *undressing* transformation. **Lemma 6.2.** Let Θ_i^t be a solution of linear problem (23)–(26), and let the Darboux transformation (45) determined by Θ_i^t map U_i^t to \widetilde{U}_i^t . Then

$$\max(\widetilde{U}_{i-1}^t - 1, -\widetilde{U}_i^t) = 2\Theta_i^t - \Theta_{i+1}^t - \Theta_{i-1}^t + \max(U_{i-1}^t - 1, -U_i^t).$$
(49)

The transformed linear problem, (23)–(26) with potential \widetilde{U}_i^t , has particular solution

$$\widetilde{\Theta}_i^t := \kappa i - \omega t - \Theta_i^t, \tag{50}$$

and the Darboux transformation defined by $\widetilde{\Theta}_i^t$ maps \widetilde{U}_i^t back to U_i^t .

Proof. Formula (49) is the ultradiscrete limit of (46) and (50) is the ultradiscrete limit of (47). A direct proof of (49) seems to be very difficult, but given that result, it is an entirely routine procedure to verify that $\widetilde{\Theta}_i^t$ satisfies the transformed versions of (23)–(26).

The asymptotic behaviour, when $|i| \gg 1$, of a solution to the ultradiscrete linear problem can easily be deduced from the system (23)–(26) with $U_{i-1}^t = U_i^t = 0$. As explained in Section 6 of [18], when $\omega > 0$, there is what we shall call a *generic* solution to (23)–(26) which has asymptotic behaviour of the form

$$\Phi_i^t \sim \begin{cases} 0 & (i \to -\infty) \\ \kappa & (i - \phi - ct) & (i \to +\infty) \end{cases},$$
(51)

for some constant ϕ and where $c = \max(1, \omega)$.

In the next section (Section 7) we will show how to explicitly describe such generic solutions to (23)–(26) and how such solutions can be seen to give rise to dressing transformations for the potential in the ultradiscrete linear problem.

Remark 6.2. By analogy with the discrete case, if Θ_i^t of Lemma 6.2 is a generic solution to the ultradiscrete linear problem (23)–(26), $\widetilde{\Theta}_i^t$ can be regarded as the ultradiscrete counterpart of a bound state $\widetilde{\theta}_i^t$ and will be referred to as a *bound state* eigenfunction as well, even though it does not tend to zero asymptotically. In fact, in Section 8 we will show that such $\widetilde{\Theta}_i^t$ indeed have many properties in common with their discrete counterparts. In particular they can be shown to define undressing transformations for potentials in the ultradiscrete linear problem (23)–(26).

7 Ultradiscrete eigenfunctions and dressing transformations

We will show in this section that for any U_i^t the ultradiscrete linear system (23)–(26) has two solutions which may be combined (using max) to give a two parameter family of solutions. One of these parameters is the free parameter $\omega \ge 0$ of the linear system. As part of the verification of these solutions we will see that each solution exists if and only if $\omega \ge \omega_{\max}$ where ω_{\max} is the mass of the heaviest soliton in U_i^t . As in the previous section, it is sometimes useful to distinguish two cases, $V^t \le 1$ and $V^t > 1$, for V^t as in (28). Recall that in the former case, V^t is independent of t and $\omega_{\max} = V^t$ and in the latter case, $\omega_{\max} > 1$.

7.1 Solution
$$\Phi_i^t = \sum_{j < i} U_j^{t-1}$$

Note that, using (17), (24) can be seen to be the time update of (23), consequently we only need to check (23), (25) and (26). For any t, substituting $\Phi_i^t = \sum_{j < i} U_j^{t-1}$ in (23) gives

$$\max\left(\sum_{j$$

and so, using (17) to rewrite the RHS,

$$\max(U_i^{t-1} + U_{i-1}^{t-1} - \kappa, 0) = \max(U_i^{t-1} + U_{i-1}^{t-1} - 1, 0).$$
(52)

We consider two cases: if $V^t \leq 1$, $V^{t-1} = V^t = \omega_{\max} \leq 1$ (cf. Remark 5.1) and so (52) is equivalent to $\max(U_i^{t-1} + U_{i-1}^{t-1} - \kappa, 0) = 0$, that is $U_i^{t-1} + U_{i-1}^{t-1} \leq \kappa$. Since $\kappa = \min(1, \omega)$, in this case (23) is satisfied if and only if $\omega \geq \kappa \geq \omega_{\max}$. In the case $V^t > 1$, we have $V^{t-1} > 1$ and $\omega_{\max} > 1$. For some j, $\max(U_j^{t-1} + U_{j-1}^{t-1} - \kappa, 0) = U_j^{t-1} + U_{j-1}^{t-1} - 1 > 0$, giving $\kappa = 1$. In this case (23) is satisfied if and only if $\omega \geq 1$. In both cases, the solution of (23) is verified (at least) when $\omega \geq \omega_{\max}$. Next, substituting $\Phi_i^t = \sum_{j < i} U_j^{t-1}$ in (25) gives

$$\max\left(\sum_{j$$

which is equivalent to

$$\min\left(\sum_{ji} (U_j^t - U_j^{t-1}), 1 - U_i^t\right) = U_i^{t-1},$$

using conservation of mass (18). This is simply the downdate rule (20) and hence (25) is satisfied without restriction on ω . Finally, (26) gives

$$\max\left(\sum_{j$$

and so

$$\max\left(1+\sum_{j\leq i}U_j^{t-1}-\sum_{j\leqslant i}U_j^t-\omega,0\right)=1-\kappa$$

which may be written as

$$\max(1 + Y_i^t - \omega, 0) = \max(1 - \omega, 0), \tag{53}$$

where $Y_i^t = \sum_{j>i} U_j^t - \sum_{j \ge i} U_j^{t-1}$ is the conserved density defined in (33). If $V^t \le 1$, then $Y_i^t = 0$ for all i(Lemma 5.2) and so the condition (53) holds without restriction. Else $V^t > 1$ and for all $i, 1 + Y_i^t \leq \omega_{\max}$ (Theorem 5.1) since $\omega_{\text{max}} > 1$ (Corollary 5.1). If $\omega \ge \omega_{\text{max}} > 1$ then (53) is trivially satisfied for all *i*. On the other hand, if $\omega < \omega_{\max}$, for some j, $1 + Y_j^t = 1 + \max Y_i^t = \omega_{\max}$ and (53) gives $\omega_{\max} = \max(1, \omega)$, which means that ω_{\max} either takes the value 1 or ω , both values leading to a contradiction. Hence (52) is satisfied for all *i* if and only if $\omega \ge \omega_{\max}$.

It follows that the system of ultradiscrete linear equations (23)–(26) is satisfied by $\Phi_i^t = \sum_{j < i} U_j^{t-1}$ for all *i* if and only if $\omega \ge \omega_{\max}$.

Solution $\Phi_i^t = \kappa i - \omega t + \sum_{i \ge i} U_i^t$ 7.2

The verification of this second solution is very similar to that of the first. For any t, substituting $\Phi_i^t =$ $\kappa i - \omega t + \sum_{j \ge i} U_j^t$ in (23) gives

$$\max\left(\kappa i - \omega t + \sum_{j \ge i+1} U_j^t, \kappa(i-1) - \omega t + \sum_{j \ge i-1} U_j^t\right) = \kappa i - \omega t + \sum_{j \ge i} U_j^t + \max(U_{i-1}^t - 1, -U_i^t)$$

and therefore $\max(U_{i-1}^t + U_i^t - \kappa, 0) = \max(U_{i-1}^t + U_i^t - 1, 0)$, and so by the argument used following (52), it is sufficient that $\omega \ge \omega_{\max}$. Next, substituting $\Phi_i^t = \kappa i - \omega t + \sum_{j \ge i} U_j^t$ in (25) gives

$$\max\left(\kappa - \omega + \sum_{j \ge i+1} U_j^{t+1}, \kappa + \sum_{j \ge i} U_j^t - 1\right) = \sum_{j \ge i} U_j^t$$

which by similar algebra as in the case of the first solution can be seen to be equivalent to

$$\max(1 + Y_i^{t+1} - \omega, 0) = \max(1 - \omega, 0).$$

Since, in case $V^t \leq 1$ we have that $V^{t+1} = V^t \leq 1$ and therefore $Y_j^{t+1} = 0$, and since $V^t > 1$ implies that $V^{t+1} > 1$ as well, exactly the same reasoning as for (53) leads to the conclusion that equation (25) is satisfied if and only if $\omega \geq \omega_{\max}$. Substituting $\Phi_i^t = \kappa i - \omega t + \sum_{j \geq i} U_j^t$ in (26) gives

$$\max\left(\sum_{j \ge i} U_j^t, \sum_{j \ge i} U_j^{t+1} + U_i^t - 1\right) = \sum_{j \ge i+1} U_j^{t+1},$$

which is equivalent to

$$U_i^{t+1} = \min\left(\sum_{j \ge i} (U_j^{t+1} - U_j^t), 1 - U_i^t\right) = \min\left(1 - U_i^t, \sum_{j < i} (U_j^t - U_j^{t+1})\right),$$

which is just the update rule (19) and hence equation (26) is automatically satisfied.

In summary, we find that the requirement for $\Phi_i^t = \kappa i - \omega t + \sum_{j \ge i} U_j^t$ to satisfy the system (23)–(26) is again that $\omega \ge \omega_{\max}$.

Theorem 7.1. For any U_i^t , the linear system (23)–(26) has solutions

$$\Phi_i^t = \sum_{j < i} U_j^{t-1} \text{ and } \Phi_i^t = \kappa i - \omega t + \sum_{j \ge i} U_j^t,$$

where $\omega \ge \omega_{max}$. The max-linear combination of these gives a two parameter (ω, ϕ) family of solutions

$$\Theta_i^t = \max\left(\sum_{j < i} U_j^{t-1}, \kappa(i - \varphi^t) + \sum_{j \ge i} U_j^t\right),\tag{54}$$

where $\kappa = \min(1, \omega)$, $\varphi^t = \phi + ct$ and $c = \max(1, \omega)$. Moreover, there exist some $m^t \in \mathbb{Z}$, dependent on t, such that

$$\Theta_i^t = \begin{cases} \sum_{j < i} U_j^{t-1} & i < m^t \\ \kappa(i - \varphi^t) + \sum_{j \ge i} U_j^t & i \ge m^t. \end{cases}$$
(55)

Proof. The basic solutions were verified in the preceding paragraphs and the fact that their maximum is also a solution follows from the general properties of max. Define the difference of the two basic solutions

$$F_i^t = \kappa(i - \varphi^t) + \sum_{j \ge i} U_j^t - \sum_{j < i} U_j^{t-1}.$$
(56)

Since $\omega \ge \omega_{\max}$ and so $\kappa \ge \kappa_{\max}$, (41) gives

$$F_{i+1}^{t} - F_{i}^{t} = \kappa - U_{i}^{t} - U_{i}^{t-1} \ge \kappa_{\max} - U_{i}^{t} - U_{i}^{t-1} \ge 0,$$
(57)

and so the sequence F_i^t is weakly increasing in *i*. Notice that $F_i \to -\infty$ as $i \to -\infty$. The alternative form of the solution (55) then follows immediately. The *split point* m^t is any of the (consecutive) integers for which $F_{m^t}^t$ attains its smallest nonnegative value.

Notice that the solution (55) has exactly the asymptotic behaviour (51),

$$\Theta_i^t \sim \left\{ \begin{array}{ll} 0 & (i \to -\infty) \\ \kappa \ (i - \varphi^t) & (i \to +\infty) \end{array} \right.$$

and we conclude that with equations (55) (or equivalently (54)) we have found an explicit expression for a generic solution to the ultradiscrete linear problem. Besides the spectral parameter ω this solution has one more free parameter: a phase constant ϕ which fixes the asymptotic behaviour.

Example 7.1. This example illustrates the construction of a such an ultradiscrete eigenfunction. Consider the ultradiscrete state $U_i^0 = \ldots, 0, 0, 0, 0, 0, 1, \frac{1}{2}, 0, 1, 0, 0, 0, 0, 0, 0, \ldots$ where the index of the first zero is 1. We observe that $\omega_{\max} = \frac{3}{2}$ and we choose $\omega = 2 \ge \omega_{\max}$, giving $\kappa = 1$, and choose $\phi = 7$. We obtain

The split point m^0 may be chosen to be any of the indices 5, 6, or 7 (giving the smallest nonnegative values of F_i^0) and then the ultradiscrete eigenfunction at t = 0 is

$$\Theta_i^0 = \max\left(i - 7 + \sum_{j \ge i} U_j^0, \sum_{j < i} U_j^{-1}\right) = \dots, 0, 0, 0, 0, \frac{1}{2}, \frac{3}{2}, \frac{3}{2}, 2, 3, 3, 4, 5, 6, 7, 8, \dots$$

Now consider t = 1:

At this time, the split point m^1 may only be chosen to be index 12 (as this gives the smallest nonnegative value of F_i^1) and the ultradiscrete eigenfunction at t = 1 is

$$\Theta_i^1 = \max\left(i - 9 + \sum_{j \ge i} U_j^1, \sum_{j < i} U_j^0\right) = \dots, 0, 0, 0, 0, 0, 0, 1, \frac{3}{2}, \frac{3}{2}, \frac{5}{2}, \frac{5}{2}, 3, 4, 5, 6, \dots$$

7.3 Generic eigenfunctions and dressing transformations

We can now explain the connection between Darboux transformations, defined in terms of generic ultradiscrete eigenfunctions Θ_i^t as given by (54) or (55), and the work of Nakata [15] who first introduced a Bäcklund transformation for the udKdV equation that acts as a dressing transformation.

The effect of a Darboux transformation on an ultradiscrete tau function T_i^t and its corresponding U_i^t is stated in (45). With Θ_i^t given by (54) we have

$$\widetilde{T}_i^t = T_i^t + \max\left(\sum_{j < i} U_j^{t-1}, \kappa(i - \varphi^t) + \sum_{j \ge i} U_j^t\right),\tag{58}$$

for $\omega \ge \omega_{\max}$ and $\kappa = \min(1, \omega) > 0$. Now we use the discrete potential $Z_i^t := T_i^t - T_i^{t+1}$ for U_i^t we introduced in Section 3, such that $U_i^t = \Delta Z_i^t$ (cf. (22)), and we impose the boundary condition $Z_- = -\frac{1}{2} \sum_{j \in \mathbb{Z}} U_j^t$ for sufficiently large -i, for all t. This allows us to rewrite the (in practice, finite) sum $\sum_{j < i} U_j^t$ in terms of T-functions: $\sum_{j < i} U_j^t = -Z_- + Z_i^t = \frac{1}{2} \sum_{j \in \mathbb{Z}} U_j^t + T_i^t - T_i^{t+1}$. Using this expression at t and t - 1 in (58), we find

$$\begin{split} \widetilde{T}_i^t &= T_i^t + \max\Big(\sum_{j < i} U_j^{t-1}, \kappa(i - \varphi^t) + \sum_{j \in \mathbb{Z}} U_j^t - \sum_{j < i} U_j^t \Big) \\ &= \frac{1}{2} \sum_{j \in \mathbb{Z}} U_j^t + \frac{1}{2} \kappa(i - \varphi^t) + \max\Big(\frac{1}{2} \kappa(i - \varphi^t) + T_i^{t+1}, -\frac{1}{2} \kappa(i - \varphi^t) + T_i^{t-1}\Big), \end{split}$$

and using the gauge freedom for the T-functions $(\tilde{T}_i^t \sim \tilde{T}_i^t + \alpha i + \beta t + \gamma \text{ for appropriate constants } \alpha, \beta, \gamma)$ we obtain an equivalent formula for the transformed T-function

$$\widetilde{T}_i^t \sim \max\left(\frac{1}{2}\kappa(i-\varphi^t) + T_i^{t+1}, -\frac{1}{2}\kappa(i-\varphi^t) + T_i^{t-1}\right),\tag{59}$$

which is precisely the formula for the vertex operator form of the Bäcklund transformation for udKdV given in the BBS case [15] (or real-valued case [10]). In [15], (59) was shown to transform *T*-functions that satisfy the ultradiscrete bilinear KdV equation (21) to functions \tilde{T} that again satisfy the same equation, provided that ω is not less than the maximum soliton mass contained in U_i^t .

Let us calculate the asymptotic value of \widetilde{Z}_i^t for the *T*-function given by (59). As explained in Section 3, for i (or -i) sufficiently large, the asymptotic values of Z_i^t no longer depend on t and we can set $T_i^t - T_i^{t+1} = Z_{\pm}$ in $\widetilde{Z}_i^t = \widetilde{T}_i^t - \widetilde{T}_i^{t+1}$ for (59), in both asymptotic regimes:

$$|i| \gg 1: \qquad \widetilde{Z}_{i}^{t} = \max\left(\frac{1}{2}\kappa(i-\varphi^{t}) - Z_{\pm}, -\frac{1}{2}\kappa(i-\varphi^{t}) + Z_{\pm}\right) - \max\left(\frac{1}{2}\kappa(i-\varphi^{t+1}) - 2Z_{\pm}, -\frac{1}{2}\kappa(i-\varphi^{t+1})\right),$$

from which we find that $\widetilde{Z}_{+} = Z_{+} + \frac{\omega}{2}$ and $\widetilde{Z}_{-} = Z_{-} - \frac{\omega}{2}$. Moreover, since $Z_{+} - Z_{-} = \sum_{i \in \mathbb{Z}} U_{i}^{t}$ (cf. Section 3), we find that the dressing transformation has increased the mass of U_{i}^{t} by ω : $\sum_{i \in \mathbb{Z}} \widetilde{U}_{i}^{t} = \widetilde{Z}_{+} - \widetilde{Z}_{-} = Z_{+} - Z_{-} + \omega = \sum_{i \in \mathbb{Z}} U_{i}^{t} + \omega$. This also shows that the transformed *T*-function given by (59) preserves the boundary condition we chose in the above construction: $\widetilde{Z}_{-} = -\frac{1}{2} \sum_{i \in \mathbb{Z}} \widetilde{U}_{i}^{t}$.

Using expression (55) for Θ_i^t , (58) becomes

$$\widetilde{T}_{i}^{t} = \frac{1}{2} \sum_{j \in \mathbb{Z}} U_{j}^{t} + \begin{cases} T_{i}^{t-1} & i < m^{t} \\ \kappa(i - \varphi^{t}) + T_{i}^{t+1} & i \ge m^{t}. \end{cases}$$
(60)

As discussed in connection to Theorem 7.1, the split point m^t is defined to be any of the integers for which the difference $F_{m^t}^t$ (56) of the two basic solutions of Sections 7.1 and 7.2 attains its smallest nonnegative value. The split point is thus not only *t*-dependent, but also depends on the phase parameter ϕ . This is a complicated implicit definition, since the limits in the summations in the formula for F_i^t depend on *i*. We are unable to solve in general for m^t , in terms of ϕ , although it is not difficult to compute m^t in any given example. For large |i|, however, all *T*-functions in (22) are given by the same clause in (60) and we find:

$$\widetilde{U}_{i}^{t} = \begin{cases} U_{i}^{t-1} & i < \min(m^{t-1}, m^{t}, m^{t+1}) - 1\\ U_{i}^{t+1} & i \geqslant \max(m^{t-1}, m^{t}, m^{t+1}). \end{cases}$$
(61)

Roughly speaking, this means that the effect of a dressing Darboux transformation is to downdate U_i^t in the left part and update it in the right part, creating a space where the new soliton, with mass ω , is inserted.

Remark 7.1. This shows that a dressing transformation of a state with finite support again yields a state with finite support. Combined with the fact that the dressing (59) maps udKdV tau functions to tau functions, this proves that a dressing Darboux transformation, using a generic solution to (23)-(26), indeed maps solutions to the udKdV equation to solutions.

Example 7.2. Let us calculate the dressing of the state $U_i^0 = \ldots, 0, 0, 0, 0, 0, 1, \frac{1}{2}, 0, 1, 0, 0, 0, 0, 0, 0, \ldots$ (for which $\omega_{\max} = 3/2$) with the generic eigenfunction Θ_i^t we calculated for it in Example 7.1, in the case of $\omega = 2$ and phase constant $\phi = 7$. Recall that the dressed state is given by $\widetilde{U}_i^0 = U_i^0 + \Theta_{i+1}^0 + \Theta_i^1 - \Theta_i^0 - \Theta_{i+1}^1$. We have,

That \widetilde{U}_i^0 , compared to U_i^0 , has indeed gained a 2-soliton can be seen immediately on the time evolved states,

$$\begin{split} \widetilde{U}_i^0 &: \ 0 \ 0 \ 0 \ \frac{1}{2} \ 1 \ 0 \ \frac{1}{2} \ 1 \ 0 \ 1 \ \frac{1}{2} \ 0 \ 0 \ 0 \ 0 \\ \widetilde{U}_i^1 &: \ 0 \ 0 \ 0 \ 0 \ 0 \ 1 \ \frac{1}{2} \ 0 \ 1 \ 0 \ \frac{1}{2} \ 1 \ \frac{1}{2} \ 0 \ 0 \ 0 \ 0 \\ \widetilde{U}_i^{-1} &: \ 0 \ \frac{1}{2} \ 1 \ \frac{1}{2} \ 0 \ 1 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \\ \end{split}$$

while further analysis shows that, at t = 0, the inserted 2-soliton is in full interaction with the other solitons:

$$\begin{split} \widetilde{U}_i^{-1} &- \widetilde{U}_i^1 \ : \ 0 \ \frac{1}{2} \ 1 \ \frac{1}{2} \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ \frac{1}{2} \ \overline{1} \ \overline{1} \ \overline{2} \ 0 \ 0 \\ \widetilde{X}_i^0 \ : \ 0 \ 0 \ \frac{1}{2} \ \frac{3}{2} \ 2 \ 2 \ 2 \ 2 \ 2 \ 2 \ 2 \ \frac{3}{2} \ \frac{1}{2} \ 0 \ 0, \end{split}$$

where $\widetilde{X}^0_i = \sum_{j < i} (\widetilde{U}^{-1}_j - \widetilde{U}^1_j).$

In fact, the evolved states \widetilde{U}_i^{-1} and \widetilde{U}_i^1 in the above example also show that the solitons that were already present in the original state U_i^0 are unaltered in the dressing transformation: asymptotically they are shifted in phase, but they are all still present, with their original masses intact. In order to explain why this is true in general, we first need to construct a transformation that actually reverses a dressing: a so-called undressing transformation.

8 Undressing transformations and ultradiscrete bound states

We have already seen in Lemma 6.2 that to every dressing Darboux transformation from U_i^t to \widetilde{U}_i^t , defined by a generic eigenfunction Θ_i^t through (45), there corresponds an undressing transformation from \widetilde{U}_i^t to U_i^t , defined by $\widetilde{\Theta}_i^t$, given in (50). If the parameter $\omega > 0$, then the dressing transformation adds a soliton of that mass and the undressing transformation will therefore again remove that soliton.

In the previous section we obtained the expression $\Theta_i^t = \max\left(\kappa(i-\varphi^t) + \sum_{j\geq i} U_j^t, \sum_{j<i} U_j^{t-1}\right)$, and, through (50), we obtain

$$\widetilde{\Theta}_{i}^{t} = \kappa \phi + \min\left(\kappa(i - \varphi^{t}) - \sum_{j < i} U_{j}^{t-1}, -\sum_{j \ge i} U_{j}^{t}\right),$$
(62)

which, according to Lemma 6.2 and Remark 6.2, is a bound state eigenfunction for the linear system (23)–(26) for the dressed solution \tilde{U}_i^t . However, for the purpose of obtaining an explicit undressed state U_i^t from a given state \tilde{U}_i^t , the expression (62) is of no use: it is not defined in terms of the known \tilde{U}_i^t values, rather it is defined in terms of the unknown target values U_i^t . In this section we will obtain an alternative formula for this eigenfunction $\tilde{\Theta}_i^t$ expressed in terms of the known initial potential. From now on however we shall dispense with the notation $\tilde{}$ for the initial state to which we wish to apply the undressing transformation, to stress that our construction is fully general and does not rely on any prior dressing that might or might not have taken place.

As explained in Remark 5.3, when $V^t = 0$ there are no solitons and, as was done in Section 3, we can write an explicit solution to the ultradiscrete KdV equation (explicit in *i* and *t*) for any such given state. In this section we shall therefore always assume that the state U_i^t we want to apply the undressing transformation to is such that $V^t > 0$ (or, equivalently, that $\omega_{\max} > 0$) and, as before, that it has finite support.

8.1 Ultradiscrete bound state eigenfunctions

Consider the following min-linear combination of the basic solutions to (23)–(26) that we discussed in sections 7.1 and 7.2, for a given potential U_i^t :

$$\bar{\Theta}_i^t := \min\left(\kappa(i - \varphi^t) + \sum_{j \ge i} U_j^t, \sum_{j < i} U_j^{t-1}\right).$$
(63)

Note that the asymptotic form of the function $\overline{\Theta}_{i}^{t}$,

$$\bar{\Theta}_i^t \sim \sum_{j \in \mathbb{Z}} U_j^t + \begin{cases} \kappa(i - \varphi^t) & \text{as } i \to -\infty \\ 0 & \text{as } i \to \infty, \end{cases}$$

is essentially the same as that for the bound state (62), up to an inconsequential renormalisation of the latter by $\sum_{j \in \mathbb{Z}} U_j^t - \kappa \phi$. It will turn out that up to this renormalisation, both functions are actually identical for all *i* and *t*.

Let us first prove that $\overline{\Theta}_i^t$ also satisfies the linear system (23)–(26) for U_i^t . It has already been shown in (57) that when $\omega \ge \omega_{\max}$ the difference F_i^t of the two basic solutions, given by (56), is weakly increasing in *i* and so we may express (63) as

$$\bar{\boldsymbol{\Theta}}_{i}^{t} = \begin{cases} \kappa(i - \varphi^{t}) + \sum_{j \ge i} U_{j}^{t} & i < m^{t} \\ \sum_{j < i} U_{j}^{t-1} & i \ge m^{t} \end{cases}$$

for some $m^t \in \mathbb{Z}$. Also, we compute the difference in t, $F_i^{t+1} - F_i^t = \sum_{j \ge i} (U_j^{t+1} - U_j^{t-1}) - \omega = X_i^t - \omega$, with X_i^t as in (32) and where we have used the conservation of the total mass (18).

From Theorem 5.1 we have seen that $\omega_{\max} = \max_i X_i^t$. Now we choose $\omega = \omega_{\max}$ and m^t to be any index at which this maximum is attained. In other words, m^t is chosen such that $X_{m^t}^t = \omega_{\max}$. Then we have

$$F_{m^t}^{t+1} = F_{m^t}^t. ag{64}$$

Notice that this definition of the split point m^t differs from that in (55), in Theorem 7.1. We shall see however that there exists a special choice for the phase constant ϕ such that $\bar{\Theta}_i^t$ indeed becomes a solution to the linear system (23)–(26).

The set

$$M^t = \{i \in \mathbb{Z} : X_i^t = \omega_{\max}\}$$
(65)

may be written as the union $M^t = M_1^t \cup M_2^t \cup \cdots \cup M_k^t$ of one or more sets of consecutive integers, corresponding to disconnected peaks or plateaux of maximal height in the graph of X_i^t , plotted as a function of i at fixed t. As discussed in Remark 5.1, these indicate the location of one or more solitons of maximal mass. For example, in the first example in Examples 5.1 in Section 5, we find $\omega_{\max} = 3$ with $M^t = \{5, 6, 7, 8, 9, 10\} \cup \{14, 15, 16, 17\}$, which indicates the presence of (at least) two solitons with mass 3 and in the second example we find $\omega_{\max} = 2$ with $M^t = \{5, 6, 7, 8, 9, 10, 11\}$ indicating the existence of at least one soliton with mass 2. In fact, in this example there are two mass-2 solitons.

Next, since $V^t > 0$ (and hence $\omega_{\max} > 0$) we have $\kappa_{\max} > 0$ and we can choose the phase constant $\phi = \phi_{\max}$ to be such that $F_{m^t}^t = 0$, giving

$$\varphi_{\max}^{t} = m^{t} + \frac{1}{\kappa_{\max}} \Big(\sum_{j \ge m^{t}} U_{j}^{t} - \sum_{j < m^{t}} U_{j}^{t-1} \Big) = m^{t} + \frac{1}{\kappa_{\max}} \Big(\sum_{j \ge m^{t}} U_{j}^{t-1} - \sum_{j < m^{t}} U_{j}^{t} \Big), \tag{66}$$

and so the phase constant is

$$\phi_{\max} = m^t - c_{\max}t + \frac{1}{\kappa_{\max}} \Big(\sum_{j \ge m^t} U_j^{t-1} - \sum_{j < m^t} U_j^t \Big).$$
(67)

Using (64) it is easily confirmed that this expression—despite its appearance—is indeed independent of t.

Note that because we chose ϕ_{\max} such as to have $F_{m^t}^t = 0$, the split point m^t now plays exactly the same role as for the generic solution in Theorem 7.1. Furthermore, as $F_{m^t}^t = F_{m^t}^{t+1} = 0$, we may choose the split point m^{t+1} in the definition of $\overline{\Theta}_i^{t+1}$ to be m^t , as for $\overline{\Theta}_i^t$. This does not however imply, in general, that $m^t \in M^{t+1}$. Thus, in summary, we have shown that

$$\bar{\Theta}_{i}^{t} = \begin{cases} \kappa_{\max}(i - \varphi_{\max}^{t}) + \sum_{j \ge i} U_{j}^{t} & i < m^{t} \\ \sum_{j < i} U_{j}^{t-1} & i \ge m^{t}, \end{cases}$$

$$\tag{68}$$

and

$$\bar{\Theta}_i^{t+1} = \begin{cases} \kappa_{\max}(i - \varphi_{\max}^t) - \omega_{\max} + \sum_{j \ge i} U_j^{t+1} & i < m^t \\ \sum_{j < i} U_j^t & i \ge m^t, \end{cases}$$
(69)

where $m^t \in M^t$, as defined in (65), and $\varphi_{\max}^t = \phi_{\max} + c_{\max} t$ can be calculated directly from (66).

Theorem 8.1. If $V^t > 0$, the pair $\bar{\Theta}_i^t$ and $\bar{\Theta}_i^{t+1}$ given by (68) and (69) respectively, satisfy the ultradiscrete linear equations (23)–(26).

Proof. For linear equations (23) and (24) we may use Theorem 7.1 to prove that they are satisfied by $\overline{\Theta}_i^t$ and $\overline{\Theta}_i^{t+1}$ whenever all of the indices i-1, i and i+1 lie in the same interval $(-\infty, m^t]$ or $[m^t, \infty)$. It remains to prove (23) and (24) when $i = m^t$. This is done below. Equations (25) and (26) only involve indices i and i+1 which both lie in either $(-\infty, m^t]$ or $[m^t, \infty)$ and so Theorem 7.1 deals with all cases.

Because of the choice $X_{m^t}^t = \omega_{\max}$, satisfying (23) and (24) at $i = m^t$ requires that

$$\max(U_{m^t}^{t-1} + U_{m^t}^t, U_{m^t-1}^t + U_{m^t}^t) = \max(U_{m^t}^t + U_{m^t-1}^t, U_{m^t-1}^{t+1} + U_{m^t-1}^t)$$
$$= \max(U_{m^t}^t + U_{m^t-1}^t - 1, 0) + \kappa_{\max}.$$
(70)

First consider the case in which $V^t \leq 1$. Then certainly $U_{m^t-1}^t + U_{m^t}^t \leq 1$ and for all $i, t, U_i^{t-1} = U_{i+1}^t$ (cf. Corollary 4.1) and the maximum $\kappa_{\max} = \omega_{\max}$ is attained at m^t (Corollary 5.1). Hence the requirement (70) becomes

$$\max(U_{m^{t}+1}^{t} + U_{m^{t}}^{t}, U_{m^{t}-1}^{t} + U_{m^{t}}^{t}) = \max(U_{m^{t}}^{t} + U_{m^{t}-1}^{t}, U_{m^{t}-2}^{t} + U_{m^{t}-1}^{t}) = \kappa_{\max}$$

which is satisfied since $U_{m^t}^t + U_{m^t-1}^t = \omega_{\max} = \kappa_{\max}$ is maximal.

Finally we deal with the case $\tilde{V}^t > 1$ in which $\omega_{\max} > 1$ and $\kappa_{\max} = 1$. We proved in Lemma 5.3 (i) that if $V^t > 1$ and X_m^t is maximal then either

$$U_{m^t-1}^t + U_{m^t}^t \ge 1 \tag{71}$$

or

$$U_{m^{t}-1}^{t} + U_{m^{t}}^{t} < 1 \text{ and } U_{m}^{t-1} + U_{m^{t}}^{t} = U_{m^{t}-1}^{t} + U_{m^{t}-1}^{t+1} = 1.$$
 (72)

If (71) holds then (70) becomes $\max(U_{m^t}^{t-1}, U_{m^t-1}^t) = U_{m^t-1}^t$ and $\max(U_{m^t}^t, U_{m^t-1}^{t+1}) = U_{m^t}^t$, and so $U_{m^t}^{t-1} \leqslant U_{m^t-1}^t$ and $U_{m^t}^t \geqslant U_{m^t-1}^{t+1}$. These are simple consequences of (17) when (71) holds. On the other hand, if (72) holds then (70) becomes $\max(1, U_{m^t-1}^t + U_{m^t}^t) = \max(U_{m^t}^t + U_{m^t-1}^t, 1) = 1$, which is identically satisfied.

Finally, using the explicit dependence of φ_{\max}^t on the split point m^t given by (66), we obtain an alternative expression for the eigenfunction (68):

$$\bar{\Theta}_{i}^{t} = \begin{cases} \kappa_{\max}(i - m^{t}) + \sum_{j=i}^{m^{t}-1} U_{j}^{t} + \sum_{j < m^{t}} U_{j}^{t-1} & i \leq m^{t} \\ \sum_{j < i} U_{j}^{t-1} & i \geq m^{t}, \end{cases}$$
(73)

noting that the two cases in the formula agree at $i = m^t$.

Proposition 8.1. Let $\bar{\Theta}_i^t(m_1)$ and $\bar{\Theta}_i^t(m_2)$ be given by (73) for $m^t = m_1, m_2$ where $m_1 < m_2 \in M^t$. Then for all i,

 $\bar{\Theta}_i^t(m_1) \geqslant \bar{\Theta}_i^t(m_2).$

In particular,

$$\bar{\Theta}_i^t(m_1) = \bar{\Theta}_i^t(m_2),$$

if and only if m_1 and m_2 are in the same block $M_i^t \subset M^t$.

Proof. From (73),

$$\bar{\Theta}_{i}^{t}(m_{2}) - \bar{\Theta}_{i}^{t}(m_{1}) = \begin{cases} \sum_{j=m_{1}}^{m_{2}-1} (U_{j}^{t} + U_{j}^{t-1} - \kappa_{\max}) & i \leq m_{1} \\ \sum_{m_{2}-1}^{m_{2}-1} (U_{j}^{t} + U_{j}^{t-1} - \kappa_{\max}) & m_{1} < i < m_{2} \\ 0 & i \geq m_{2}. \end{cases}$$

Then, using (41), $U_j^t + U_j^{t-1} \leq \kappa_{\max}$ for all j and it follows immediately that $\bar{\Theta}_i^t(m_1) \geq \bar{\Theta}_i^t(m_2)$.

If m_1, m_2 belong to the same block then, by Lemma 5.3 (ii), $U_j^t + U_j^{t-1} = \kappa_{\max}$ for all $m_1 - 1 \leq j \leq m_2 - 1$, and hence $m_1 \leq j \leq m_2 - 1$, and so it follows that $\bar{\Theta}_i^t(m_1) = \bar{\Theta}_i^t(m_2)$.

If m_1, m_2 do not belong to the same block then, since $X_{m_1}^t$ and $X_{m_2}^t$ are separated maxima, there is some $m_1 \leq k < m_2$ for which $\Delta X_k < 0$. Then by Proposition 5.3, $U_k^t + U_k^{t-1} < \kappa_{\max}$ and so $\bar{\Theta}_i^t(m_1) > \bar{\Theta}_i^t(m_2)$ for some *i*.

Hence $\bar{\Theta}_i^t(m_1) = \bar{\Theta}_i^t(m_2)$ if and only if m_1 and m_2 belong to the same block M_j^t .

Note that this also implies that, within the same block M_j^t , the value of ϕ_{max} calculated from (67) is the same regardless the value of m^t one chooses. This follows immediately from the asymptotic behaviour of the eigenfunction $\bar{\Theta}_i^t$:

$$\bar{\Theta}_i^t \sim \sum_{j \in \mathbb{Z}} U_j^t + \begin{cases} \kappa_{\max}(i - \phi_{\max} - c_{\max}t) & \text{if } i < \ell^t \\ 0 & \text{if } i > r^t, \end{cases}$$

where ℓ^t is the left-most and r^t the right-most boundary of the support of U_i^{t-1} .

In summary, proposition 8.1 tells us that in the ultradiscrete case the spectrum for the linear system is not simple as we can have different eigenfunctions for the same value of ω_{max} . In fact, there are exactly as many different bound state eigenfunctions as there are different blocks M_i^t in M^t .

8.2 The undressing transformation

In this section we consider the effect of a Darboux transformation defined in terms of $\overline{\Theta}_i^t$. We will see that it gives an undressing transformation $U_i^t \to \widehat{U}_i^t$, removing one of the fastest solitons from U_i^t . We shall also describe the action of this Darboux transformation on the *T*-functions for the state U_i^t we wish to undress. As we saw in Section 7.3, the effect of a dressing transformation on a given solution of udKdV is very complicated and it seems impossible to give a simple, explicit, expression for the dressed state. The best we could do was the asymptotic formula (61). The effect of an undressing Darboux transformation that removes a soliton can be described much more precisely.

The undressing eigenfunction $\overline{\Theta}_i^t$ given by (73) has a split point which is the same for t and t + 1 and which is completely determined by the state U_i^t to which the transformation will be applied. The target state for the transformation (or 'undressed' state) will be denoted by \widehat{U}_i^t . Then, from (73) we have

$$\bar{\Theta}_{i+1}^t - \bar{\Theta}_i^t = \begin{cases} \kappa_{\max} - U_i^t & i < m^t \\ U_i^{t-1} & i \ge m^t \end{cases}$$

Since the split point for $\bar{\Theta}_i^{t+1}$ can be taken to be the same as for $\bar{\Theta}_i^t$, the result of the undressing Darboux transformation is remarkably simple:

$$\widehat{U}_{i}^{t} = U_{i}^{t} + (\bar{\Theta}_{i+1}^{t} - \bar{\Theta}_{i}^{t}) - (\bar{\Theta}_{i+1}^{t+1} - \bar{\Theta}_{i}^{t+1}) = \begin{cases} U_{i}^{t+1} & i < m^{t} \\ U_{i}^{t-1} & i \ge m^{t}, \end{cases}$$
(74)

(to be compared with (61) for the dressing transformation). This formula tells us, roughly speaking, that the undressed solution is obtained by removing the soliton near to m^t and filling the gap by joining the update of the left part and the downdate of the right part. The target state in the undressing is therefore again of finite support. Moreover, it is easily verified that the total mass of the initial state U_i^t is indeed reduced by ω_{\max} in the undressing:

$$\sum_{i\in\mathbb{Z}}\widehat{U}_i^t = \sum_{i< m^t} U_i^{t+1} + \sum_{i\geqslant m^t} U_i^{t-1} = \sum_{i\in\mathbb{Z}} U_i^{t-1} - X_{m^t}^t = \sum_{i\in\mathbb{Z}} U_i^t - \omega_{\max},$$

with X_i^t as defined in (32). It is worth emphasizing that since $\overline{\Theta}_i^t$ can only be constructed for $\omega = \omega_{\max}$, the undressing transformation we just obtained can only remove a soliton that has maximal mass in U_i^t .

Example 8.1. As an example, let us calculate the eigenfunction $\overline{\Theta}_i^t$ and target state \widehat{U}_i^t for the undressing transformation that reverses the dressing of Example 7.2, in which a soliton with mass $\omega = 2$ was added to the initial state ..., $0, 0, 0, 0, 0, 1, \frac{1}{2}, 0, 1, 0, 0, 0, 0, 0, 0, \dots$ at t = 0, for a phase constant $\phi = 7$. We therefore start from the state U_i^0 :..., $0, 0, 0, 0, \frac{1}{2}, 1, 0, \frac{1}{2}, 1, 0, 1, \frac{1}{2}, 0, 0, 0, 0, \dots$ (the \widetilde{U}_i^t state of Example 7.2) and first analyse its soliton content. This will tell us which solitons can be removed and what the appropriate split points are.

$$\begin{array}{rcl} U_i^0 &:& 0 \; 0 \; 0 \; \frac{1}{2} \; 1 \; 0 \; \frac{1}{2} \; 1 \; 0 \; 1 \; \frac{1}{2} \; 0 \; 0 \; 0 \; 0 \\ X_i^0 &:& 0 \; 0 \; \frac{1}{2} \; \frac{3}{2} \; 2 \; 2 \; 2 \; 2 \; 2 \; 2 \; 2 \; \frac{3}{2} \; \frac{1}{2} \; 0 \; 0 \end{array}$$

We find that an $\omega_{\text{max}} = 2$ soliton can be removed at split points $m^t = 5, \dots, 11$. As all these split points belong to the same block in X_i^0 the appropriate value for ϕ_{max} is unique and can, for example, be obtained from (67) at $m^t = 5$ and t = 0:

$$\phi_{\max} = 5 + \sum_{j \ge 5} U_j^{-1} - \sum_{j < 5} U_j^0 = 5 + \frac{5}{2} - \frac{1}{2} = 7.$$

We will see shortly that it is not a coincidence that this value exactly matches the value of the phase constant that was used in the dressing. The downdate U_i^{-1} , together with the update U_i^1 of the initial state, can also be used to obtain the undressed state \hat{U}_i^0 by means of (74):

 $\begin{array}{rrrr} U_i^1 &:& 0 \; 0 \; 0 \; 0 \; [01 \; \frac{1}{2} \; 0 \; 1 \; 0 \; \frac{1}{2} \; 1 \; \frac{1}{2} \; 0 \; 0] \\ U_i^{-1} &:& [0 \frac{1}{2} \; 1 \; \frac{1}{2}] \; 0 \; 1 \; \frac{1}{2} \; 0 \; 1 \; 0 \; 0 \; 0 \; 0 \; 0 \; 0 \\ \widehat{U}_i^0 &:& 0 \; 0 \; 0 \; 0 \; 0 \; 1 \; \frac{1}{2} \; 0 \; 1 \; 0 \; 0 \; 0 \; 0 \; 0 \; 0 \; 0, \end{array}$

for $m^t = 5$, where the bracketed values indicate the parts of U_i^1 and U_i^{-1} that are not used in the construction of \hat{U}_i^0 . We see that the target state \hat{U}_i^0 indeed matches the initial state of Example 7.2.

It is also interesting to calculate the bound state eigenfunction $\overline{\Theta}_i^0$ used in the undressing and to compare it with the eigenfunction $\Theta_i^0 = \ldots, 0, 0, 0, 0, \frac{1}{2}, \frac{3}{2}, \frac{3}{2}, 2, 3, 3, 4, 5, 6, 7, 8, \ldots$ that was used in Example 7.2 to dress the state \widehat{U}_i^0 .

$$\begin{split} (i-7) + \sum_{j \geqslant i} U_j^0 &: \quad \overline{\frac{3}{2}} \, \overline{\frac{1}{2}} \, \frac{1}{2} \, \frac{3}{2} \, 2 \, 2 \, 3 \, \frac{7}{2} \, \frac{7}{2} \, \frac{9}{2} \, \frac{9}{2} \, 5 \, 6 \, 7 \, 8 \\ & \sum_{j < i} U_j^{-1} \, : \quad 0 \, 0 \, \frac{1}{2} \, \frac{3}{2} \, 2 \, 2 \, 3 \, \frac{7}{2} \, \frac{7}{2} \, \frac{9}{2} \, \frac{$$

for $\sum_{j\in\mathbb{Z}} U_j^0 = \frac{9}{2}$ and where a bar designates negative values. We see that $\overline{\Theta}_i^0 + \Theta_i^0 = \sum_{j\in\mathbb{Z}} U_j^0 + (i-7)$ which suggests that the (generic) eigenfunction used in the dressing of Example 7.2 is in fact adjoint to $\overline{\Theta}_i^0$, in the sense of (50) (up to a renormalisation by $\sum_{j\in\mathbb{Z}} U_j^0 - \phi_{\max}$). We will see in the next section that this is indeed the case and that, in general, there always exists a generic eigenfunction that reverses the effect of an undressing Darboux transformation.

Finally, let us describe the effect of the undressing transformation on the *T*-function for U_i^t . Starting from the form (63) for $\bar{\Theta}_i^t$ and introducing a discrete potential $Z_i^t = T_i^t - T_i^{t+1}$ for U_i^t with boundary condition $Z_- = -\frac{1}{2} \sum_{j \in \mathbb{Z}} U_j^t$ as $i \to -\infty$ (just as we did in Section 7.3), we find $\sum_{j < i} U_j^t = \frac{1}{2} \sum_{j \in \mathbb{Z}} U_j^t + T_i^t - T_i^{t+1}$, for all t and we can write the undressed *T*-function, $\hat{T}_i^t = T_i^t + \bar{\Theta}_i^t$, as

$$\widehat{T}_{i}^{t} = \frac{1}{2} \sum_{j \in \mathbb{Z}} U_{j}^{t} + \frac{1}{2} \kappa_{\max}(i - \varphi_{\max}^{t}) + \min\left(\frac{1}{2} \kappa_{\max}(i - \varphi_{\max}^{t}) + T_{i}^{t+1}, -\frac{1}{2} \kappa_{\max}(i - \varphi_{\max}^{t}) + T_{i}^{t-1}\right).$$

Using gauge freedom, as before, this suggests that the transformation $T_i^t \mapsto \widehat{T}_i^t$,

$$\widehat{T}_i^t \sim \min\left(\frac{1}{2}\kappa_{\max}(i-\varphi_{\max}^t) + T_i^{t+1}, -\frac{1}{2}\kappa_{\max}(i-\varphi_{\max}^t) + T_i^{t-1}\right),\tag{75}$$

and the dressing given by (59) are inverse to each other. In fact, it was brought to our attention [20] that this can be proven, directly on the *T*-functions, but only in the case where (75) is used to remove a soliton that was first added by means of (59). There is however also a different way to prove the desired result.

8.3 Reversing an undressing transformation by dressing

Consider the undressing/dressing chain $U_i^t \xrightarrow{\bar{\Theta}_i^t} \widehat{U}_i^t \xrightarrow{\bar{\Theta}_i^t} \widetilde{U}_i^t$ composed of an undressing Darboux transformation using a bound state $\bar{\Theta}_i^t$ with $(\omega_{\max}, \phi_{\max})$ for the initial potential U_i^t , followed by a dressing Darboux transformation in terms of a generic eigenfunction $\widehat{\Theta}_i^t$ for the undressed potential \widehat{U}_i^t , with $\omega = \omega_{\max}$ and $\phi = \phi_{\max}$.

As shown in (74), the effect of undressing U_i^t by a Darboux transformation (45) in terms of a $\bar{\Theta}_i^t$ given by (68), is simply

$$U_i^t \mapsto \ \widehat{U}_i^t = \begin{cases} U_i^{t+1} & i < m^t \\ U_i^{t-1} & i \ge m^t, \end{cases}$$
(76)

for a split point $m^t \in M^t$ (65) determined on U_i^t . As this undressing has taken out a soliton with mass ω_{\max} , the remaining solitons in U_i^t necessarily have masses less than or equal to ω_{\max} and we can therefore always consider a dressing Darboux transformation on \hat{U}_i^t using a generic eigenfunction $\hat{\Theta}_i^t$ for \hat{U}_i^t with $\omega = \omega_{\max}$. Since the phase constant ϕ in this generic eigenfunction is completely free, we can always choose it to coincide with ϕ_{\max} of $\overline{\Theta}_i^t$, given by (67). Moreover, as will see in Lemma 8.1, there is always an index $m \in \mathbb{Z}$ that conforms to both the definition of a split point for the bound state eigenfunction $\overline{\Theta}_i^t$ (for U_i^t) as well as to that for a split point for the generic eigenfunction $\widehat{\Theta}_i^t$ (for \widehat{U}_i^t) we are considering here. Taking this index as the common split point m^t for both functions, we write $\widehat{\Theta}_i^t$ as

$$\widehat{\Theta}_{i}^{t} = \begin{cases} \sum_{j < i} \widehat{U}_{j}^{t-1} & i < m^{t} \\ \kappa_{\max}(i - \varphi_{\max}^{t}) + \sum_{j \ge i} \widehat{U}_{j}^{t} & i \ge m^{t} \end{cases}$$
(77)

(cf. (55)) where the split point m^t is now exactly the same as that in (76). Taken together then, these two relations tell us that

$$\widehat{\Theta}_{i}^{t} = \begin{cases} \sum_{j < i} U_{j}^{t} & i < m^{t} \\ \kappa_{\max}(i - \varphi_{\max}^{t}) + \sum_{j \ge i} U_{j}^{t-1} & i \ge m^{t}, \end{cases}$$

or, because of (68), that we have

$$\bar{\Theta}_i^t + \widehat{\Theta}_i^t = \kappa_{\max}(i - \varphi_{\max}^t) + \sum_{j \in \mathbb{Z}} U_j^t, \quad \text{for all } i, t \in \mathbb{Z}.$$
(78)

Since both $\overline{\Theta}_i^t$ and $\widehat{\Theta}_i^t$ solve the linear system (23)–(26), for the respective potentials U_i^t and \widehat{U}_i^t which are related by Darboux transformation, we conclude from (78) that $\overline{\Theta}_i^t$ and $\widehat{\Theta}_i^t$ are in fact related as in (50), up

to a trivial renormalisation by $\sum_{j \in \mathbb{Z}} U_j^t - \kappa_{\max} \phi_{\max}$. Hence, $U_i^t \xrightarrow{\bar{\Theta}_i^t} \widehat{U}_i^t \xrightarrow{\bar{\Theta}_i^t} \widetilde{U}_i^t \equiv U_i^t$ and we find that:

Theorem 8.2. For any undressing Darboux transformation, defined by a bound state eigenfunction $\overline{\Theta}_i^t$ (68), there exists a dressing Darboux transformation that reinserts the soliton that was taken out in the undressing, thereby reconstructing the original solution to udKdV one had before undressing.

Proof. As is clear from the above arguments, such a dressing transformation is obtained from a (generic) eigenfunction $\widehat{\Theta}_i^t$ as in (77) for the undressed state \widehat{U}_i^t , if we can take the split point m^t for $\widehat{\Theta}_i^t$ such that it coincides with a valid split point for the bound state eigenfunction $\overline{\Theta}_i^t$, in the block M_j^t that corresponds to the soliton that was taken out from the original solution. This is always possible by Lemma 8.1.

The following Lemma is proven in Appendix B of [18].

Lemma 8.1. If we consider an undressing of a state U_i^t by a bound state eigenfunction $\bar{\Theta}_i^t$ (68) with $(\omega_{max}, \phi_{max})$, resulting in an undressed state \hat{U}_i^t , then the left-most index in the block M_j^t in X_i^t (32) that corresponds to the soliton that was taken out by the undressing, is also a valid split point for a generic eigenfunction $\hat{\Theta}_i^t$ with $(\omega_{max}, \phi_{max})$ (77) for \hat{U}_i^t .

Theorem 8.2, in fact, offers a practical method for solving the Cauchy problem for the udKdV equation.

9 Solution to the Cauchy problem for udKdV

We have seen that the dressing and undressing transformations, using the same parameters ω and ϕ , are inverse to one another. As described in [10], this leads to a method for solving the Cauchy problem for udKdV. This method can be summarized as:

Theorem 9.1. For the udKdV equation (19) any given initial state U_i^0 , with finite support, can be completely undressed until only a background state remains. The data (ω, ϕ) obtained at each step in the undressing, together with the background state, suffice to construct an exact solution U_i^t for (19) that coincides with U_i^0 at t = 0. *Proof.* That any initial state U_i^0 with finite support can be fully undressed, down to a pure background state (i.e. a state for which $V^t = 0$) follows immediately from the fact that an undressing transformation reduces the extent of the state (cf. (74)), which means that after repeated undressings one eventually ends up with the trivial state, or with a state for which $\omega_{\max} = 0$ and further undressing is impossible. In either case one has $V^t = 0$ (see Remark 5.3). We can then proceed as follows:

- (i) Given initial data U_i^0 , use an undressing transformation to remove one of the heaviest solitons and record $\omega = \omega_{\text{max}}$ and $\phi = \phi_{\text{max}}$ for this soliton.
- (ii) Repeat until all solitons are removed and only a background state B_i^0 remains, at which point we have obtained the full set of spectral data: a finite number of pairs (ω_j, ϕ_j) (j = 1, ..., N) for non-increasing soliton masses $(\omega_1 \ge \omega_2 \ge \cdots \ge \omega_N)$ and the background B_i^0 , or just a background if the initial state did not contain any solitons.
- (iii) Evolve the background—it simply translates at speed 1—to give $B_i^t = B_{i-t}^0$. This is straightforward if calculated in terms of the *T*-function (29) for the background, which we shall denote by $T_i^{[0],t}$.
- (iv) Add back all the solitons in reverse order using the sets of parameters (ω, ϕ) obtained at each undressing, to obtain the exact solution as a function of i and t.

This can be done by simple iteration of the dressing transformation (59) with parameters $(\omega_{N-j}, \phi_{N-j})$,

$$T_i^{[j],t} \xrightarrow{(\omega_{N-j},\phi_{N-j})} T_i^{[j+1],t}$$

for j running from 0 to N-1. Since dressing transformations for the same ω commute [15], we always obtain a unique "fully dressed" T-function, $T_i^{[N],t}$, which is guaranteed to solve the bilinear udKdV equation (21). From this T-function we can then calculate $U_i^t = T_{i+1}^{[N],t} + T_i^{[N],t+1} - T_i^{[N],t+1} - T_{i+1}^{[N],t+1}$, which solves the udKdV equation (19) and which, by construction, coincides with U_i^0 at t = 0.

Remark 9.1. Notice that the first statement in Theorem 9.1 tells us that any initial state for which $V^t > 1$ must, asymptotically, separate into a train of solitons with speeds greater than 1 (see also Remark 5.1) and a remaining part that travels, unchanged, with speed 1 and that consists of solitons with $\omega \leq 1$, possibly embedded into a background.

Corollary 9.1. The undressing transformation (74), in terms of a bound state eigenfunction (68), maps between (finite support) solutions of the udKdV equation and the corresponding undressing transformation for T-functions (75) maps between solutions of the bilinear udKdV equation (21).

Proof. Suppose that U_i^t is a solution to the udKdV equation (of finite support) that contains at least one soliton. For this solution, let $T_i^{[N-1],t}$ denote the *T*-function obtained after N-1 dressings in the algorithm in the proof of Theorem 9.1, for some particular choice of initial undressing (ω_1, ϕ_1) , and let T_i^t denote the result of the last dressing, i.e.: $U_i^t = T_{i+1}^t + T_i^{t+1} - T_i^t - T_{i+1}^{t+1}$ with $T_i^t = T_i^{[N-1],t} + \widehat{\Theta}_i^t$, where $\widehat{\Theta}_i^t$ is the generic eigenfunction (77) for $\widehat{U}_i^t = T_{i+1}^{[N-1],t} + T_i^{[N-1],t+1} - T_i^{[N-1],t} - T_{i+1}^{[N-1],t+1}$ with $\omega_{\max} = \omega_1$ and $\phi_{\max} = \phi_1$. Note that, by construction, $T_i^{[N-1],t}$ satisfies the bilinear udKdV equation (21). Then, because of (78), we have that the bound state eigenfunction $\overline{\Theta}_i^t$ for (ω_1, ϕ_1) that undresses T_i^t to $\widehat{T}_i^t = T_i^t + \overline{\Theta}_i^t$ (and therefore U_i^t to $\widehat{U}_i^t = \widehat{T}_{i+1}^{t+1} - \widehat{T}_i^{t-1} - \widehat{T}_{i+1}^{t+1}$) can be expressed as $\overline{\Theta}_i^t = \kappa(i - \varphi^t) + \sum_{j \in \mathbb{Z}} U_j^t - \widehat{\Theta}_i^t$, and that \widehat{T}_i^t and $T_i^{[N-1],t}$ are therefore gauge equivalent: $\widehat{T}_i^t = T_i^{[N-1],t} + \kappa(i - \varphi^t) + \sum_{j \in \mathbb{Z}} U_j^t$. Hence, the undressed T-function \widehat{T}_i^t solves the bilinear equation (21) and \widehat{U}_i^t , which has finite support, therefore solves the udKdV equation.

To finish we give a detailed worked example of the undressing and redressing procedure.

Example 9.1. Consider the initial state

 $U_i^0 = (\dots, 0, 0, 0, \frac{2}{3}, \frac{2}{3}, -\frac{1}{2}, 1, \frac{1}{2}, 1, 1, 0, 0, -\frac{1}{3}, 1, 1, 1, -1, 1, 1, 1, 0, 0, 0, 0, 0, 0, \dots).$

First we will show how to characterise the soliton content in terms of the spectral data, i.e.: pairs (ω, ϕ) and a background. Then we reconstruct the solution from this data at an arbitrary time. As above, we use a bar notation for negative numbers. First we determine the data for the maximal soliton(s) in U_i^0 ; the left-most 0 displayed has index i = 1. Recall that $X_i^0 = \sum_{j < i} (U_j^{-1} - U_j^1)$, as defined in (32).

from which it is clear that X_i^0 attains its maximum $\omega_{\max} = 3$ in two disjoint clusters, at $m^0 \in \{8, 9, 10, 11\}$ or $m^0 \in \{15, 16, 17, 18, 19, 20, 21\}$. We can remove a soliton from the state at t = 0 by using the undressing (74) with m^0 taking any one of these maximising values. The phase parameter for this soliton is given by the formula (67), at t = 0,

$$\phi = m^0 + \frac{1}{\kappa_{\max}} \Big(\sum_{j \ge m^0} U_j^{-1} - \sum_{j < m^0} U_j^0 \Big).$$

By Proposition 8.1, the result of the undressing only depends on which cluster m^0 belongs to and so, for example, the choices $m^0 = 8$, 9, 10,11 all give the same result. We first choose $m^0 = 11$, removing the left-most 3-soliton

In this case, $\kappa_{\max} = \min(1, \omega_{\max} = 3) = 1$ and so

$$\phi = 11 + \frac{14}{3} - \frac{13}{3} = \frac{34}{3}$$

The spatial extent of the undressed state (which we denote \tilde{U}_i^0) is clearly smaller than that of the initial state U_i^0 and its mass has been reduced by 3. Furthermore, analysing the solitonic content of \tilde{U}_i^0 ,

we see that the left-most 3-soliton has indeed disappeared.

Alternatively, we could choose $m^0 = 15, 16, 17, 18, 19, 20, 21$ (which all give the same result) to remove a 3-soliton on the right. We will take $m^0 = 17$

and obtain

$$\phi = 17 + 2 - 7 = 12,$$

as the phase constant for the 3-soliton we removed.

If we continue with the $m^0 = 17$ case and again calculate X_i^0 for the undressed state \widetilde{U}_i^0 we get:

Notice here that although a 3-soliton has been removed on the right, there are still two disjoint clusters where \tilde{X}_i^0 attains its maximum $\omega_{\max} = 3$. This tells us that the right-most cluster must, originally, have had a least two 3-solitons contained in it. Indeed it turns out that there are three 3-solitons in the system altogether, one in the left-most cluster of 3's and two in the right-most cluster of 3's in X_i^0 . The order in which they are removed does not matter: there are three different possibilities LRR (left then right then right), RLR or RRL but once all 3-solitons have been removed, the end result does not depend on the order of the undressings. Since the undressing transformation is valid for all times t, this is easily checked on the asymptotic state $t \to +\infty$, where all 3-solitons are well separated and for which the effect of the undressing (74) is explicit.

We can repeat the undressing procedure until all solitons have been removed. The intermediate states we obtain depend on the exact sequence of undressings we chose, but the final soliton-free state is independent of the order in which we perform the undressings. The complete process is summarised in the following table, in which we list besides the initial and final states, all intermediate states (for one particular order of the undressings), the split points m^0 at which a soliton is removed from each state as well as the value of ω and the phase constant for that soliton:

	U_i^0	m^0	$(\omega_{\max}, \phi_{\max})$
(a)	$0\ 0\ 0\ \frac{2}{3}\ \frac{2}{3}\ \frac{\overline{1}}{2}\ 1\ \frac{1}{2}\ 1\ 1\ 0\ 0\ \frac{\overline{1}}{3}\ 1\ 1\ 1\ 1\ \overline{1}\ 1\ 1\ 1\ 0\ 0\ 0\ 0\ 0\ 0$	17	(3, 12)
(b)	$0\ 0\ 0\ 0\ \frac{1}{3}\ 1\ \frac{1}{2}\ \frac{1}{2}\ 0\ 0\ 1\ 1\ 1\ \frac{1}{3}\ 0\ 0\ 2\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0$	11	$(3, \frac{34}{3})$
(c)	$0\ 0\ 0\ 0\ 0\ 0\ \frac{4}{3}\ \frac{\overline{1}}{2}\ \frac{1}{2}\ 0\ 0\ 0\ \frac{\overline{1}}{3}\ 1\ 1\ 1\ \overline{1}\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0$	15	(3, 12)
(d)	$0\ 0\ 0\ 0\ 0\ \frac{1}{3}\ \frac{3}{2}\ \frac{1}{3}\ \frac{1}{2}\ 0\ 0\ 0\ \frac{1}{3}\ 0\ \overline{1}\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0$	8	$(rac{4}{3},7)$
(e)	$0\ 0\ 0\ 0\ 0\ 0\ 0\ \frac{1}{2}\ \frac{1}{2}\ 0\ 0\ 0\ \frac{1}{3}\ 0\ \frac{1}{3}\ 0\ \overline{1}\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0\$	10	$\left(\frac{1}{2},\frac{22}{3}\right)$
(f)	$0\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0$	(r	no soliton).

The solution at a general time t may be reconstructed using the dressing transformation (59). To begin, we write the background state at time t, B_i^t , in terms of T-functions. As explained in Section 3, the



Figure 2: Simulation (dots) and exact solution (solid line) shown together. The solution is plotted at time steps $t = 0, 10, \ldots, 50$ in a frame moving to the right at speed 1 (the left-most dot in each plot is located at i = t + 1).

background T-function is given by $T_i^t = \frac{1}{2} \sum_{j \in \mathbb{Z}} |i - t - j| B_j^0$. For the current example,

 $B_i^0 = 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ \overline{\frac{1}{2}} \ 0 \ 0 \ \overline{\frac{1}{3}} \ 0 \ \overline{1} \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0$

where the index of the first zero is 1, and so the background T-function is

$$T_i^t = -\frac{1}{4}|i-t-9| - \frac{1}{6}|i-t-12| - \frac{1}{2}|i-t-14|$$

Next, the solitons are added back using the data (ω, ϕ) collected above, in weakly increasing order for the mass ω , by iterating transformation (59) $\tilde{T}_i^t = \max(\frac{1}{2}\kappa(i-\varphi^t) + T_i^{t+1}, -\frac{1}{2}\kappa(i-\varphi^t) + T_i^{t-1})$, where $\kappa = \min(1, \omega)$ and $\varphi^t = \max(1, \omega)t + \phi$. After this sequence of dressing transformations, using (22), the resulting *T*-function then yields an explicit expression for the solution U_i^t of udKdV, corresponding to the given initial data.

In Figure 2 we show this solution at every tenth time step in a moving frame of speed 1. Solitons of mass not exceeding 1 and background are stationary in this frame. The plots show both the time evolution of the initial state calculated using the update rule (19), plotted as dots, as well as the exact solution found by the sequence of dressing Darboux transformations described above, with i taken to be a real variable, plotted as a continuous line. We observe that, as they should, the two plots coincide at integer values of i.

10 Conclusions

We have given an explicit description of eigenfunctions for the max-linear system for the udKdV equation. Eigenfunctions that do not correspond to a bound state only exist if the associated eigenvalue (ω) is greater than or equal to the mass (ω_{max}) of the heaviest soliton in the potential in the linear system. The eigenvalue is otherwise free, as is the phase of the eigenfunction. On the other hand, eigenfunctions for bound states only exist for $\omega = \omega_{max}$ and the phase of such an eigenfunction can only take a finite number of values. This number can in fact be less than the number of solitons with mass ω_{max} that are contained in the potential in the linear system.

We have shown how the soliton adding (dressing) and soliton removing (undressing) procedures for the udKdV equation (over \mathbb{R} , for solutions with compact support) defined by these eigenfunctions, may be performed explicitly, and in complete generality. These processes were shown to be ultradiscete analogues of the Darboux transformation for the dKdV equation and, as such, of the continuous KdV equation: dressing is performed with a Darboux transformation that uses a non-bound state eigenfunction whereas undressing is the result of a Darboux transformation that uses a bound state eigenfunction.

As part of proving these results we discovered two new conserved densities, $\max X_i^t$ and $\max Y_i^t$, with X_i^t and Y_i^t defined by (32) and (33). These new conserved densities correspond to conservation of maximal soliton mass and speed respectively.

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