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| 1 | <u>Feasibility study of smartphone-based Near Infrared Spectroscopy (NIRS)</u> |
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| 2 | for salted minced meat composition diagnostics at different temperatures |
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| 7 | Abstract |
| 8 | This research work evaluates the feasibility of a smartphone-based spectrometer |

9 (740-1070 nm) for salted minced meat composition diagnostics at industrial scale. 10 A commercially available smartphone-based spectrometer and a benchtop NIR 11 spectrometer (940-1700 nm) were used for acquiring 1312 spectra from minced 12 meat samples stored at four different temperatures ranging from -14 °C to 25 °C. 13 Thereafter, for each spectrometer, PLS and Random Forest regression models 14 specific for each temperature and global models were created to predict the fat, 15 moisture and protein contents. Fat and moisture can be estimated with the global 16 model in a wide range of temperatures by using the smartphone-based 17 spectrometer, which has an acceptable accuracy for quality control purposes 18 (RPD>7) and comparable to the accuracy of a benchtop spectrometer.

19

20 Highlights:

| 21 | • | Smartphone-based NIR was used to estimate salted meat composition |
|----|---|---|
| 22 | • | Accuracy of fat and moisture estimates are acceptable for quality control |
| 23 | | purposes |

Predictive ability of smartphone-based NIR is similar to a benchtop
 spectrometer

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Random Forest predictive models are robust at temperatures from -14 °C
 to 25 °C

28

29 **1. Introduction**

30 Smartphone-based food diagnostic technologies have the potential to 31 revolutionize the food sector by allowing rapid, on-site and inexpensive analysis 32 of food and food products (Rateni, Dario, & Cavallo, 2017). This potential has been 33 recognized by the European Union (EU) and a Horizon Prize competition called 34 "Food Scanner" took place in 2016 for developing affordable and non-invasive 35 mobile solutions that will enable users to measure and analyze their food intake. 36 The winners were three European startups: Spectral Engines (winner), SCIO 37 (runner-up) and TellSpec (runner-up) (Horizon, 2016). These three companies have developed novel smartphone-based food diagnostic applications by utilizing 38 39 the analytical power of Near Infrared Spectroscopy (NIRS). NIRS utilize the 40 spectral range from 800nm to 2500nm in order to provide chemical information 41 through the different response of molecular bonds and structural information of 42 the scanned sample (Burns & Ciurczak, 2007).

43 Several research studies have been published in the last years in the agrifood 44 sector that are taking advantage of the combined use of the rear smartphone camera with augmented sensors. For example, bio-receptors (e.g. fluorescent 45 46 dyes) and colorimetric assays have been used for the on-site detection of 47 contaminants (Coskun, et al., 2017); (Chen, et al., 2014), pesticide residues (Levin, 48 Krishnan, Rajkumar, Halery, & Balkunde, 2016), (Wang, et al., 2016) and 49 foodborne pathogens (Zhu, Sikora, & Ozcan, 2012), (Seo, et al., 2016). As for 50 commercial applications, a great number of startups worldwide are offering 51 smartphone-based NIRS by exploding the technological advancements in the high-52 volume fabrication of microelectromechanical systems (MEMS) and micro-mirror 53 arrays. These advancements have made possible the construction of miniaturized 54 and inexpensive NIR spectrometers while keeping the performance at similar 55 levels with the benchtop equipment (Ozcan, 2016). Device schematics and details on how to design a low-cost smartphone-based spectrometers from off-the-shelf
components can be found in the literature (Das, Wahi, Kothari, & Raskar, 2016).

58 Spectral Engines solution uses a variety of Bluetooth-connected NIR sensors 59 together with advanced analytics, cloud-connectivity and spectral libraries to 60 reveal the fat, protein, sugar, and calories of food items (Antila, Kantojärvi, & Mäkynen, 2016). TellSpec is using a pocket-sized NIR spectrometer based on the 61 62 Texas Instruments DLP module for scanning food through a mobile application in 63 order to identify calories, allergens, contaminants and food frauds (Beam Your 64 Health Up–TellSpec, 2018). Consumer Physics has the in-house-developed SCIO, a 65 pocket-sized NIR spectrometer for molecular analysis of different samples, 66 including food (Goldring & Sharon, 2011). In addition to the advancements in 67 miniaturizing spectrometers, a mobile phone-compatible hyperspectral imager based on a tunable MEMS Fabry-Perot interferometer has been demonstrated for 68 69 food sensing applications among other applications (Rissanen, et al., 2016).

70 The abovementioned innovations have developed reliable food scanning mobile 71 applications but are mostly targeting the customer. There is a need to develop 72 more robust smartphone-based food diagnostic applications especially for the 73 meat industry in order to ensure food quality and safety. NIRS is a widely used 74 analytical technique in the food industry for the determination of the chemical 75 composition because of its non-destructive, fast and sensitive abilities, and 76 requires little or no sample preparation (Prieto, Roehe, Lavin, Batten, & Andres, 77 2009) (Van den Berg, Lyndgaard, Sørensen, & Engelsen, 2013). Furthermore, NIRS 78 coupled with multivariate analysis can determine the water and salt content at the 79 surface of fermented sausages during the drying process (Collell C., Gou, Arnau, 80 Muñoz, & Comaposada, 2012), water and salt content at the surface of dry-cured 81 ham during the resting and drying processes (Collell C., Gou, Arnau, & 82 Comaposada, 2011) and the authentication of meat products (Chiesa, et al., 2016).

A limitation for the adoption of NIRS-based innovations is the sample temperature because it can cause significant variation to the acquired spectra. When the light of wavelengths longer than 450 nm is absorbed by liquid water, the energy is transferred to one or more of the vibrational modes of the O–H bond. 87 Spectroscopic studies of liquid water have shown that the shift in frequency is 88 attributed to the weakness of intermolecular H-bonds due to the rise of 89 temperature, which strengthens the covalent O-H bonds and consequently causes 90 the water molecule to vibrate at higher frequencies (Segtnan, Sasic, Isaksson, & 91 Ozaki, 2001). Furthermore, the absorption of light from liquid water at the visible 92 and NIR region is getting stronger due to the rise of temperature above the 93 freezing point of water (Pegau, Deric, & Zaneveld, 1997). Unfortunately, the 94 temperature influence is usually ignored in NIRS predictive modeling because the 95 temperature control, especially in industrial conditions, is quite difficult. However, 96 recent studies have used compensation methods to mitigate the temperature 97 influence and to improve the accuracy of the prediction by employing 98 temperature-compensated PLSR global models (Yao, Chen, Xie, & Rao, 2013) 99 (Campos, Antolin, Deban, & Pardo, 2018).

100 The aim of this paper is to study the feasibility of smartphone-controlled near-101 infrared spectrometers for salted minced meat composition prediction at different 102 temperatures in comparison to a benchtop spectrometer. Additionally, linear and 103 nonlinear regression methods have been used for constructing global models with 104 the smartphone-based spectrometer that are robust for a great range of 105 temperatures, from -14°C to 25°C. Furthermore, the effect of different data 106 partitioning methods on how they affect the construction of predictive models is 107 also investigated.

108 **2. Material and Methods**

109 **2.1 Experimental Design**

Green hams (n= 328) from different origins were purchased: 171 Serrano-type
hams from Jamonificio Subirats, S.L. (Els Hostalets de Balenyà, Barcelona, Spain),
72 Serrano-type hams from Càrniques de Juià, S.A. (Juià, Girona, Spain), 30 Duroc
Serrano-type hams from Cárnica Batallé, S.A. (Riudarenes, Girona, Spain) and 55
Iberian hams from Corporación Alimentaria Guissona, S.A., (Guissona, Lleida,
Spain).

Green hams were salted by covering them with a layer of salt of at least 10 cm fordifferent periods of time (7 days to 16 days) in order to obtain a high variability in

118 salt uptake, and therefore, in composition. Each green ham was carefully dissected 119 and the subcutaneous fat, lean and intermuscular fat were minced together in a 120 bowl chopper until a homogeneous meat paste was obtained. Four samples from 121 each ham were vacuum packed and stored at different temperatures (-14 °C, +5 °C, +12 °C and +25 °C) until data acquisition. The whole procedure resulted in 122 123 samples with fat content varying from 5% to 43%, protein content varying from 124 12% to 23% and moisture content varying from 35% to 69%.2.2 125 Instrumentation

126 Two NIR instruments were used. The first one is the smartphone-based SCiO 127 (Consumer Physics, Israel) that can acquire 331-points reflection spectra that are 128 ranging from 740 to 1070 nm. For controlling the SCiO spectrometer a Samsung 129 Galaxy Core Prime with an Android 5.1.1 operating system was used. The second 130 NIR instrument is a diode array Polychromix Spectral Probe (Polychromix Inc., 131 Wilmington, USA) with InGaAs detector type that is covering the spectral region 132 between 940 and 1700 nm with a resolution of 8 nm. Polychromix was used to 133 compare the results obtained with SCiO. Polychromix reflectance data were stored 134 as the logarithm of reciprocal of reflectance (1/R). For both instruments, three 135 spectra per sample were collected and the mean spectrum per sample was used 136 for further analysis. All the equipment was set in reflectance mode and operated 137 at room temperature (20 ± 3 °C).

The moisture, protein and fat contents of the meat samples were determined by
using a FoodScan[™] Lab (Foss Analytical, Hillerød, Denmark), which is an approved
method for the analysis of moisture, fat and protein in meat and meat products by
the Association of Analytical Communities, labeled as 2007.04 method (AOAC,
2007).

143 **2.3 NIRS Analysis**

144 **2.3.1 Data Acquisition**

Data acquisition was performed using the two different NIRS systems. Each sample was removed from the storage rooms and immediately three SCiO scans and three Polychromix scans were acquired at three different random spots and subsequently averaged. Great attention was given to keep the total acquisition time for both the instruments less than 2 minutes in order to ensure that the temperature did not change significantly the sample composition during the spectra acquisition.

152 **2.3.2 Data partitioning**

179

153 Dataset from each acquisition temperature was divided in two: a training dataset 154 with 80% of the initial data and a testing dataset with 20% of the initial data. The 155 general aim of performing the data partitioning is to prevent knowledge from the 156 training dataset to "leak" to the testing dataset, which will affect the predictive 157 power of the PLSR model (Wold, Sjöström, & Eriksson, 2001). Two different 158 methods for data partitioning have been selected, the first one is using only the 159 responses **Y** to construct the two datasets by separating the values of **Y** with 160 random stratification into groups. Each of the stratified groups contains 161 approximately the same percentage of each response as in the original **Y** dataset 162 (Molinaro, Simon, & Pfeiffer, 2005). For constructing the global model, the 163 datasets of each temperature were merged and the training and testing datasets 164 were obtained with the random stratification on the Y-dataset.

165 The second method is to use the properties of the NIR spectra from the predictors 166 **X** dataset. The Kennard-Stone (KS) algorithm was used for this partitioning, which 167 is a sequential method that covers the spectral space uniformly in order to build a 168 training dataset with flat distribution over the spectral space. It starts by 169 computing the geometric distances (e.g. Euclidean) between all the pairs of 170 spectra and the two spectra that are the farthest apart are assigned to the training 171 dataset. The selection procedure is repeated until to build the training dataset 172 according to the following maximin criterion, the next selected spectra must have 173 the least distance with respect to any other spectra already selected (Puzyn, 174 Mostrag-Szlichtyng, Gajewicz, Skrzyński, & Worth, 2011). Mahalanobis distance 175 can be used also for satisfying the maximin criterion by performing Principal 176 Component Analysis (PCA) on the spectra and computing the Euclidean distance 177 of the PCA scores according to the following definition of the Mahalanobis 178 distance:

$$H_{ij}^{2} = \sum_{n=1}^{N} (\hat{t}_{i,n} - \hat{t}_{j,n})^{2} / \hat{\lambda}_{n}$$
(1)

6

180 where $\hat{t}_{i,n}$ is the n-th principal component score of point *i*, $\hat{t}_{j,n}$ the corresponding 181 principal component score for point *j*, $\hat{\lambda}_n$ is the eigenvalue of principal component

182 *n* and *N* is the number of the selected principal components.

183 2.3.3 Data pretreatment

The scatter correction methods include Multiplicative Scatter Correction (MSC), Inverse MSC, Extended MSC, Extended Inverse MSC, detrending, Standard Normal Variate (SNV) and different kinds of normalization to unit-vector length (e.g. scaling). The most common spectral derivatives methods are the gap-segment (also known as Norris-Williams) derivatives and the Savitzky-Golay (SG) polynomial derivative filters (Rinnan, van den Berg and Engelsen 2009).

190 The SG method is fitting polynomials to windows around each point in the 191 spectrum and these polynomials are then used to smooth the obtained data and 192 subsequently differentiate them. Finite difference method can be used instead of 193 the polynomial fitting for the computation of the first and second derivative by 194 considering two different points of the spectrum:

195
$$x'_i = x_i - x_{i-1}$$
 (2)

196
$$x_i'' = x_{i-1} - 2x_i + x_{i+1}$$
(3)

197 This numerical subtraction deemphasizes lower frequencies and emphasizes 198 higher frequencies (e.g. noise). Data smoothing methods are needed in order to 199 improve the signal-to-noise ratio of the obtained data. The gap-segment method 200 first performs a smoothing under a given segment size, followed by a gap 201 derivative:

202
$$x'_i = x_{i+k} - x_{i-k}$$
 (4)

203
$$x_i'' = x_{i-k} - 2x_i + x_{i+k}$$
(5)

where *k* is the gap size between the points.

205 2.3.4 Predictive modelling

206 Partial Least Squares (PLS) Regression (also known as Projection of Latent207 Structures) is one of the most popular tools for multivariate analysis (Wold H.,

208 1966). PLSR derives its popularity from the ability to analyze data with multiple, 209 noisy, collinear (e.g. NIR spectra), and even incomplete variables. Its goal is to 210 predict a set of dependent variables (denoted as Y) from a set of predictors 211 (denoted as **X**). The prediction is achieved by extracting from the predictors a new 212 set of orthogonal factors called Latent Variables (LVs) that have the best predictive 213 power on unseen data. More specifically, PLSR tries to find two sets of weights w 214 and **c** in order to extract two vectors from **X** and **Y**, **t=Xw** and **u=Yc** such that 215 maximize the covariation between **X** and **Y**. It can be achieved with the following 216 cost function:

217 maximize cov(Xw, Y) subject to $w^Tw=1$ (6)

The number of LVs defines the complexity of the predictive model and selecting the optimal number is one the most important steps because the amount of variance explained by a LV indicates its importance in the prediction of **Y**. For example, selecting too many LVs will result in an over-fitted model that takes into consideration not only the variance of the data but also noise. While selecting too few LVs implies an under-fitted model, which incorporates insufficient information of the data.

225 In the current study, the target **Y** variables describe the concentration of certain 226 components and **X** are the spectral data. The PLSR analysis was applied to the 227 training dataset for each acquisition temperature. We also constructed a global 228 model for investigating further the temperature dependency on the predictive 229 ability of the PLSR model. For each instrument, the four training datasets acquired 230 at the four different temperatures were merged to create a global model for each 231 instrument. The Root Mean Squared Error of Prediction (RMSEP), the coefficient 232 of the determination (R²) and the residual predictive deviation (RPD) were used 233 to decide the number of LVs.

234 The RMSE of calibration was calculated:

$$RMSEC = \sqrt{\frac{\sum_{i=1}^{N} (Y_i - \hat{Y}_i)^2}{N - LVs - 1}}$$
(7)

236 **2.3.5 Validation of predictive models**

235

8

Predictive models obtained after PLSR analysis of training dataset were applied to
the testing data set. The RMSEP, R² and RPD were calculated:

239
$$RMSEP = \sqrt{\frac{\sum_{i=1}^{N} (Y_i - \hat{Y}_i)^2}{N}}$$
(8)

240
$$R^{2} = 1 - \frac{\sum_{i=1}^{N} (Y_{i} - \hat{Y}_{i})^{2}}{\sum_{i=1}^{N} (Y_{i} - \bar{Y})^{2}}$$
(9)

where N is the size of the dataset, Y_i is the experimentally measured reference value for sample *i*, \hat{Y}_i is the predicted reference value for sample *i* and \overline{Y} is the arithmetic mean of the corresponding dataset.

RPD is the ratio between the standard deviation of the reference values and the
error of prediction of the testing. It has been suggested that RPD values >3 are
considered good for screening purpose; RPD values >5 are good for quality control,
whereas RPD values >8 are considered excellent for all analytical tasks (Conzen,
2006).

249 2.4 Software and Algorithms

The open-source programming language R (version 3.4.0, codename: "You Stupid
Darkness") (The R Core Team, 2018) was used to develop in-house codes based
on the PLS and randomForest packages (Mevik & Wehrens, 2007) (Liaw & Wiener,
2002).

254 **3. Results and Discussion**

255 **3.1 Spectral description of the samples**

256 Figure 1 shows the raw mean spectrum of all the collected spectra at each one of 257 the acquisition temperatures. As expected, there are differences between the 258 different temperatures even with a shift in frequency (frozen sample at -14 °C) 259 due to perturbations caused by the increase in temperature (Fig. 1B). The primary 260 vibrational modes of liquid water are in the mid-infrared region at 3049 nm (v_1 , 261 symmetric stretch), 6079 nm (v_2 , bend), and 2865 nm (v_3 , asymmetric stretch). 262 Several higher overtones of the vibrational modes can be found at the detection 263 area of our equipment between 750-1800nm and therefore the whole spectrum

264 from each sample will be used for the construction of the predictive model in order

265 not to exclude any informative part of the spectrum.





Figure 1: The mean spectrum for each temperature for SCiO (A) and Polychromix (B).

267 **3.2 Pretreatment of raw spectra**

268 Figure 2 shows the effect of the pretreating methods upon 5 different SCiO spectra collected from samples stored at 25 °C. As expected the SNV and MSC are returning 269 270 almost identical spectra with the only difference to be the offset of the intensity. The spectra obtained from the two spectral derivatives methods shows distinct 271 272 differences between them, because of the different methods used for the 273 computation of the derivatives. The spectral derivatives need thoroughly tuning 274 because they have a number of parameters that are critical for building a 275 predictive model, such as the order and length of the polynomial for the SG, and 276 the size of the gap and the segment size of the smoothing filter for the gap-segment.



Figure 2: SCiO spectra without any pretreatment (A), with MSC pretreatment (B), with SNV pretreatment (C),
with SG-1Der pretreatment (D), and with gap-segment derivative pretreatment (E).

Several pretreatments have been used in order to build a PLSR model with thebest overall predictive ability for the two different spectrometers. For scatter

281 correction, we have selected to use only SNV for practical reasons. The signal-282 correction concept behind the SNV and MSC is similar except that a reference 283 spectrum is needed for the MSC correction. Usually, the reference spectrum is the 284 mean spectrum of all the measurements and that can lead to the so-called *data* 285 *leakage.* Data leakage is when unexpected information is being added to the 286 training dataset that can allow the model to learn something that it otherwise 287 would not know. This will hinder the performance of the predictive model under 288 construction (Nisbert, Elder, & Miner, 2009). Therefore, the selection of the MSC 289 reference spectrum is a great challenge and that gives to SNV a practical advantage 290 (Rinnan, van den Berg, & Engelsen, 2009). As for spectral derivatives, the gap-291 segment method performs better with the SCiO data compared to the SG method 292 that performs better with the Polychromix data.

3.3 Predictive ability of NIR devices with two different data partitioning methods

Table 1 and Table 2 show, for both NIR devices the predictive ability of the
different PLSR models created by using the random stratification method and the
KS method respectively for partitioning the data into training and testing datasets.

298 The predictive models were constructed on the SNV+gap-seg and SNV+SG 299 pretreated datasets. Fat, protein and moisture content of the samples were 300 accurately predicted with the lowest value of the coefficient of the determination 301 to be R²=0.92 and with 4 LVs for protein estimation at 25 °C. The RPD values for 302 all the predictions are above 3 and in some cases above 8, which means that our 303 PSLR modelling could be accurate enough for quality control of fat and moisture 304 contents and for screening purposes of protein content. It should be noted that RMSEP, R² and RPD for fat and moisture prediction are worst in frozen samples, 305 306 especially with SCiO device. RMSEP values for fat and moisture prediction are 307 similar to the results reported in previous studies where benchtop spectrometers 308 have been used in minced mass of pork sausages, for example SEP: 0.94-1.41% for 309 fat and 0.76–1.01% for moisture (Ortiz-Somovilla, Espana-Espana, Gaitan-Jurado, 310 Perez-Aparicio, & De Pedro-Sanz, 2007), RMSEP= 0.622-0-675% for moisture 311 (Collell C., Gou, Picouet, Arnau, & Comaposada, 2010), and in minced Biceps 312 femoris muscle of dry-cured ham RMSEP: 0.31-0.43% for fat and 0.44-0.51% for 313 moisture (Prevolnik, et al., 2011).

314 The results obtained with datasets built with the KS method for partitioning the 315 data (Table 2) are comparable to those obtained with datasets built with the 316 stratified random partitioning based on Y values (Table 1). KS method is 317 concentrating most of the diversity of the data at the training set that in some cases can lead to overoptimistic results (Wested & Marini, 2015), which is not the case 318 319 for our study since the two data partitioning methods are returning similar results. 320 Similar methods to KS, such as the Duplex algorithm (Daszykowski, Walczak, & Massart, 2002), have great potential for building new predictive models with 321 322 smartphones because they require less computational effort compared to the 323 random stratification.

324 Table 1: Results of PLSR analysis after dataset partitioning based on random stratification sampling applied to

| Parameter | Pretreatment | LVs | RMSEC | RMSEP | R ² | RPD |
|-----------------------|--------------|-----|-------|-------|----------------|-------|
| SCiO, Temp=-14 | C | 1 | | 4 | 1 | |
| Fat | | 6 | 1.26% | 1.47% | 0.97 | 6.89 |
| Moisture | SNV+gap-seg | 6 | 1.23% | 1.36% | 0.96 | 5.48 |
| Protein | | 6 | 0.43% | 0.54% | 0.93 | 3.89 |
| Polychromix, Te | mp=-14°C | | | | | |
| Fat | | 4 | 0.99% | 0.92% | 0.99 | 10.34 |
| Moisture | SNV+SG (1D) | 5 | 0.78% | 0.76% | 0.99 | 7.46 |
| Protein | | 5 | 0.49% | 0.48% | 0.94 | 3.91 |
| SCiO, Temp=5°C | | L | | | | |
| Fat | | 5 | 0.97% | 1.00% | 0.99 | 6.99 |
| Moisture | SNV+gap-seg | 5 | 0.89% | 1.06% | 0.98 | 6.86 |
| Protein | | 5 | 0.49% | 0.43% | 0.95 | 3.87 |
| Polychromix, Temp=5°C | | | | | | |
| Fat | | 6 | 0.85% | 0.74% | 0.99 | 14.11 |
| Moisture | SNV+SG (1D) | 6 | 0.82% | 0.88% | 0.98 | 7.99 |
| Protein | | 5 | 0.42% | 0.49% | 0.93 | 4.76 |

325 response values (Y) for each temperature of spectra acquisition.

| SCiO, Temp=12oC | | | | | | |
|------------------------|-------------|---|-------|-------|------|-------|
| Fat | | 4 | 1.05% | 0.94% | 0.99 | 12.05 |
| Moisture | SNV+gap-seg | 5 | 0.96% | 0.83% | 0.98 | 8.55 |
| Protein | | 5 | 0.41% | 0.45% | 0.96 | 4.18 |
| Polychromix, Tei | mp=12°C | | | | | |
| Fat | | 6 | 0.86% | 0.92% | 0.99 | 10.79 |
| Moisture | SNV+SG (1D) | 4 | 0.79% | 0.88% | 0.98 | 9.76 |
| Protein | | 4 | 0.46% | 0.45% | 0.95 | 5.04 |
| SCiO, Temp=25° | C | | | | | |
| Fat | | 6 | 0.97% | 0.74% | 0.99 | 12.65 |
| Moisture | SNV+gap-seg | 4 | 0.85% | 0.71% | 0.98 | 9.05 |
| Protein | | 5 | 0.45% | 0.47% | 0.95 | 3.99 |
| Polychromix, Temp=25°C | | | | | | |
| Fat | | 5 | 0.92% | 0.86% | 0.99 | 10.65 |
| Moisture | SNV+SG (1D) | 5 | 0.76% | 1.01% | 0.98 | 9.56 |
| Protein | | 6 | 0.38% | 0.36% | 0.96 | 4.09 |

326 Table 2: Results of PLSR after dataset partitioning based on the KS method applied to X descriptors (NIR
327 spectra).

| Parameter | Pretreatment | LVs | RMSEC | RMSEP | R ² p | RPD |
|------------------|--------------|-----|-------|-------|------------------|-------|
| SCiO, Temp=-14 | °C | | · | | | |
| Fat | | 6 | 1.23% | 1.43% | 0.98 | 7.12 |
| Moisture | SNV+gap-seg | 6 | 1.29% | 1.02% | 0.97 | 6.34 |
| Protein | | 5 | 0.48% | 0.49% | 0.92 | 3.29 |
| Polychromix, Ter | mp=-14°C | | | | | |
| Fat | | 4 | 1.13% | 0.76% | 0.99 | 7.51 |
| Moisture | SNV+SG (1D) | 5 | 0.82% | 0.72% | 0.98 | 8.79 |
| Protein | | 4 | 0.50% | 0.45% | 0.94 | 2.64 |
| SCiO, Temp=5°C | | | | | | |
| Fat | | 4 | 1.11% | 0.83% | 0.99 | 11.64 |
| Moisture | SNV+gap-seg | 4 | 0.99% | 0.78% | 0.99 | 8.57 |
| Protein | | 6 | 0.46% | 0.43% | 0.94 | 3.87 |

| Polychromix, Temp=5°C | | | | | | |
|------------------------|-------------|---|-------|-------|------|-------|
| Fat | | 4 | 0.95% | 0.90% | 0.99 | 9.38 |
| Moisture | SNV+SG (1D) | 5 | 0.83% | 0.90% | 0.98 | 7.96 |
| Protein | | 6 | 0.42% | 0.47% | 0.93 | 4.11 |
| SCiO, Temp=12° | С | | | | | |
| Fat | | 5 | 1.00% | 1.19% | 0.98 | 10.15 |
| Moisture | SNV+gap-seg | 5 | 0.93% | 1.12% | 0.97 | 7.95 |
| Protein | | 6 | 0.46% | 0.52% | 0.93 | 3.21 |
| Polychromix, Ter | mp=12°C | | | | | |
| Fat | | 4 | 1.02% | 0.76% | 0.99 | 8.54 |
| Moisture | SNV+SG (1D) | 5 | 0.83% | 0.79% | 0.98 | 6.83 |
| Protein | | 4 | 0.48% | 0.43% | 0.93 | 3.35 |
| SCiO, Temp=25° | С | | | | | |
| Fat | | 6 | 1.01% | 0.80% | 0.99 | 10.50 |
| Moisture | SNV+gap-seg | 6 | 0.87% | 0.78% | 0.98 | 7.54 |
| Protein | | 5 | 0.49% | 0.37% | 0.95 | 3.37 |
| Polychromix, Temp=25°C | | | | | | |
| Fat | | 4 | 0.98% | 0.68% | 0.99 | 9.46 |
| Moisture | SNV+SG (1D) | 4 | 0.76% | 0.84% | 0.99 | 7.82 |
| Protein | | 4 | 0.44% | 0.47% | 0.92 | 3.41 |

328 3.4 Global Model

329 For constructing the global model, the datasets of different temperatures were 330 merged and the training and testing datasets were obtained with the random 331 stratification on the Y-dataset. Table 3 shows that when a global temperature 332 model is applied, in most of the cases the SCiO has results similar to those obtained 333 with local temperature models. The predictive ability for the fat content of the SCiO global model has slightly improved for the -14 °C 334 samples from 335 RMSEP=1.47% to RMSEP=1.18% and for the 5 °C samples from RMSEP=1.00% to 336 RMSEP=0.88%. Predictive errors do not show any specific pattern related to the 337 temperature (Figure 3a-c).

338 However, Figure 3b shows that the predicted values of moisture are always lower 339 than the measured values at the midrange (53-59%). Figure 3a for fat predictions 340 has a similar trend at the midrange but to a lesser extent. There is a non-linear 341 relationship between moisture or fat content and spectral response over large 342 ranges of fat or moisture. PLS, as a linear regression method, cannot handle this 343 non-linear relationship and some part of the explanatory information is going to 344 the residuals of the model. Therefore, for estimating correctly the predicted values 345 of moisture and fat, non-linear regression methods are needed such as Random 346 Forest (RF) regression that has the ability of fully utilizing the explanatory 347 information from various types of data (Hastie, Tibshirani, & Friedman, 2009).

RF is an ensemble learning algorithm that can be used for both classification and regression. It is using a large number of decision trees (ntree) to split the data into an equal number of bootstrap samples that will be randomly sampled by a number of predictors (mtry). This adds randomness to the model while growing the number of the decision trees, and the algorithm chooses the best split between the sampled variables leading to a wide diversity that generally results in a better model (Breiman, 2001).

Figure 3e-f depicts the new prediction plots and it is obvious that the RF regression has corrected the non-linear relationship between moisture and fat content. The RMSEC values at Table 2 have significantly improved because the model captures all the explanatory information from the data, but the RMSEP values are at the same levels as PLS results.

Therefore, the RF regression global temperature model build with smartphonebased NIR spectrometers has the potential to predict fat and moisture contents at
different temperatures, even in frozen samples, with high accuracy and protein
content with good accuracy.

Table 3: Results of the global PLS and RF regression after datasets selection based on random stratification
 sampling applied to response values (Y) for all temperatures of spectra acquisition.

| Parameter | Pretreatment | Parameter | RMSEC | RMSEP | R ² p | RPD |
|-----------------|--------------|-----------|-------|-------|------------------|------|
| PLS SCiO Global | | | | | | |
| Fat | SNV+gap-seg | 8 LVs | 1.21% | 1.07% | 0.99 | 8.89 |

| Moisture | | 7 LVs | 1.01% | 1.03% | 0.98 | 7.16 | | | |
|--------------|----------------|-----------|--------|--------|------|------|--|--|--|
| Protein | | 7 LVs | 0.46% | 0.49% | 0.94 | 3.94 | | | |
| RF SCiO Glob | RF SCiO Global | | | | | | | | |
| Fat | | ntree=500 | 0 58% | 1.18% | 0.98 | 7 91 | | | |
| T ut | | mtry=104 | 0.0070 | | | 7.71 | | | |
| Moisture | | ntree=500 | 0.47% | 0.98% | 0.98 | 6.88 | | | |
| Monsture | | mtry=106 | | | | | | | |
| Protein | | ntree=500 | 0.21% | 0.48% | 0.94 | 4 21 | | | |
| liotem | | mtry=105 | 0.2190 | 0.4070 | 0.94 | 7.21 | | | |







368 3.5 Prediction error

369 The whole procedure of this study has resulted in a predictive model with high 370 RPD values. However, NIRS-based predictions were used for obtaining the 371 reference values of **Y** instead of using wet chemistry methods and this introduces 372 an additional error to our final predictive model. The Foss FoodScan has the 373 following Standard Errors of Prediction (SEP): for fat 1.01%, for moisture 0.72% 374 and for protein 0.62%. By following simple error propagation, our global RF 375 predictive model has the following SEPs: for fat 1.56%, for moisture 1.21% and for 376 protein 0.78%.

377 **4. Conclusion**

378 Robust, efficient and reliable methods for predicting minced meat composition at 379 four temperatures (-14°C, 5°C, 12°C and 25°C) have been demonstrated by using 380 a smartphone-based spectrometer. The predictive ability of the smartphone-381 based spectrometer is comparable with the one obtained from a benchtop 382 spectrometer with in-house developed predictive analytics. Two different data 383 partition techniques were applied to construct a PLSR predictive model, which 384 perform well for moisture and fat contents even for frozen meat samples (RPD>7). 385 Furthermore, a global model with all the temperatures was constructed for 386 further examining the abilities of the smartphone-based spectrometer. In this case, 387 the PLS modelling has shown problems to capture all the explanatory information 388 from the global model, which was leaked to the residuals of the model. Random 389 Forest regression was used instead of PLS, which improved the predictive 390 modelling.

391 It is expected that as the technological improvements will continue, the 392 smartphones will include greater computational power, high-end sensing 393 technologies and higher connectivity. This together with the massive volume of 394 smartphone users, which is over than 7 billion, will provide a paradigm shift in 395 how measurement science for food quality and safety will be practiced globally.

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405 **Conflicts of Interest Statement**

The authors whose names are listed on the first page of this manuscript certify
that they have NO affiliations with or involvement in any organization or entity
with any financial interest (such as honoraria; educational grants; participation in

- 409 speakers' bureaus; membership, employment, consultancies, stock ownership, or
- 410 other equity interest; and expert testimony or patent-licensing arrangements), or
- 411 non-financial interest (such as personal or professional relationships, affiliations,
- 412 knowledge or beliefs) in the subject matter or materials discussed in this
- 413 manuscript.

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