

8-28-2019

## Digital Signal Processing for Laser Printer Noise Source Detection and Identification

Yutong Xue  
*Purdue University, xue46@purdue.edu*

Nicholas Kim  
*Purdue University*

Xihui Wang  
*Purdue University*

Jan Allebach  
*Purdue University*

J Stuart Bolton  
*Purdue University, bolton@purdue.edu*

*See next page for additional authors*

Follow this and additional works at: <https://docs.lib.purdue.edu/herrick>

---

Xue, Yutong; Kim, Nicholas; Wang, Xihui; Allebach, Jan; Bolton, J Stuart; Chiu, George; Davies, Patricia; Ferguson, Katy; Kaisle, David; and Shaw, Mark, "Digital Signal Processing for Laser Printer Noise Source Detection and Identification" (2019). *Publications of the Ray W. Herrick Laboratories*. Paper 207.  
<https://docs.lib.purdue.edu/herrick/207>

This document has been made available through Purdue e-Pubs, a service of the Purdue University Libraries.  
Please contact [epubs@purdue.edu](mailto:epubs@purdue.edu) for additional information.

---

**Authors**

Yutong Xue, Nicholas Kim, Xihui Wang, Jan Allebach, J Stuart Bolton, George Chiu, Patricia Davies, Katy Ferguson, David Kaisle, and Mark Shaw



**NOISE-CON 2019**

August 26-28, 2019  
San Diego, CA

# **DIGITAL SIGNAL PROCESSING FOR LASER PRINTER NOISE SOURCE DETECTION AND IDENTIFICATION**

**Yutong Xue, Nicholas Kim, Xihui Wang, Jan Allebach, J. Stuart Bolton,  
George Chiu, Patricia Davies**

Ray W. Herrick Labs, Purdue University, West Lafayette, IN 47907

**Katy Ferguson, David Klaisle, Mark Shaw**

HP Inc., Boise, ID 83714

This presentation will be posted at Herrick E-Pubs: <http://docs.lib.purdue.edu/herrick/>



# Background

- **Noise problem**



- **Our goal**

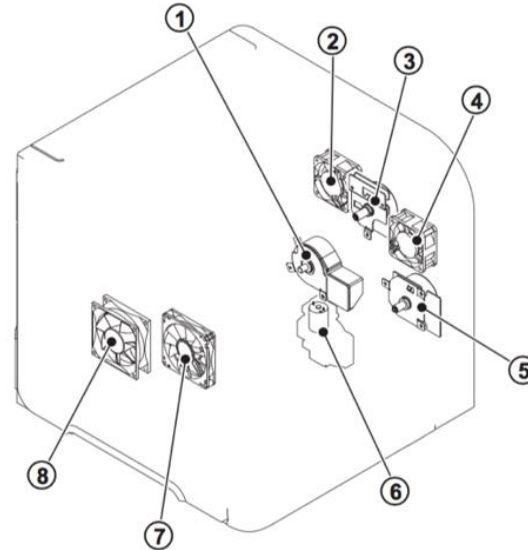


Self-detect before noise appears

- **Advantage**
  1. Reducing the cost for service department.
  2. High quality, quiet printer

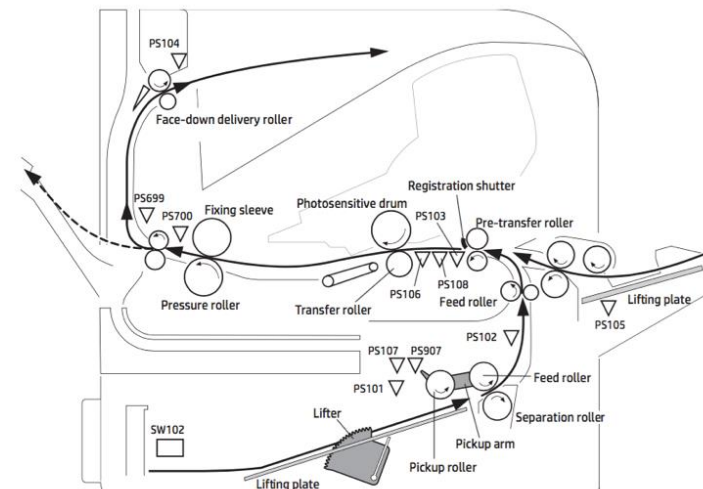
# Target Printer

- **Motors and fans of HP LaserJet M603**



- 1: Fuser motor (M299)
- 2: Fan (FN104)
- 3: Drum motor (M102)
- 4: Fan (FN102)
- 5: Feed motor (M101)
- 6: Lifter motor (M103)
- 7: Fan (FN103)
- 8: Fan (FN101)

- **A side view of the inner structure to show the complexity of the paper path**

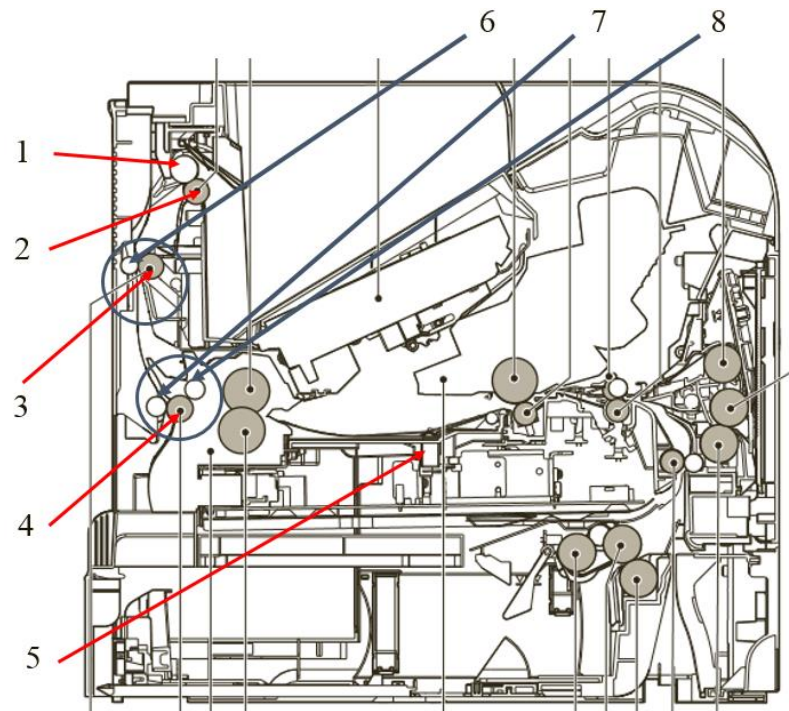






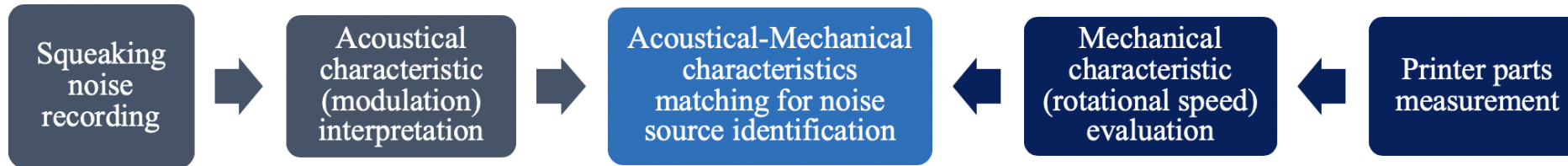
# Preliminary Analysis

- **Main noise issue with a faulty printer:** squeaking noise with strong and high frequency tonal content, caused by rollers' stick-slip motion
- **Rollers on the paper path**



- 1: Face-down delivery roller 1
- 2: Face-down delivery roller 2
- 3: Intermediate delivery roller
- 4: Fuser delivery roller
- 5: Inner delivery roller
- 6: Idler roller 1 (not driven)
- 7: Idler roller 2 (not driven)
- 8: Idler roller 3 (not driven)

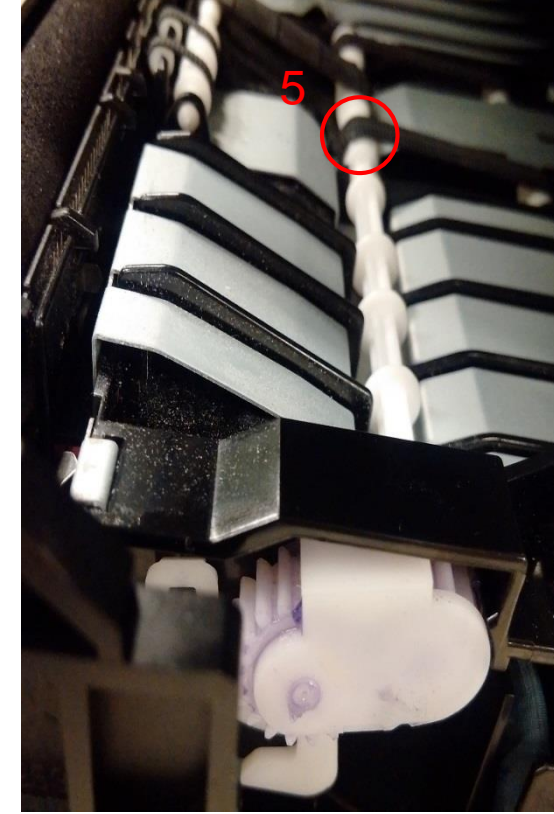
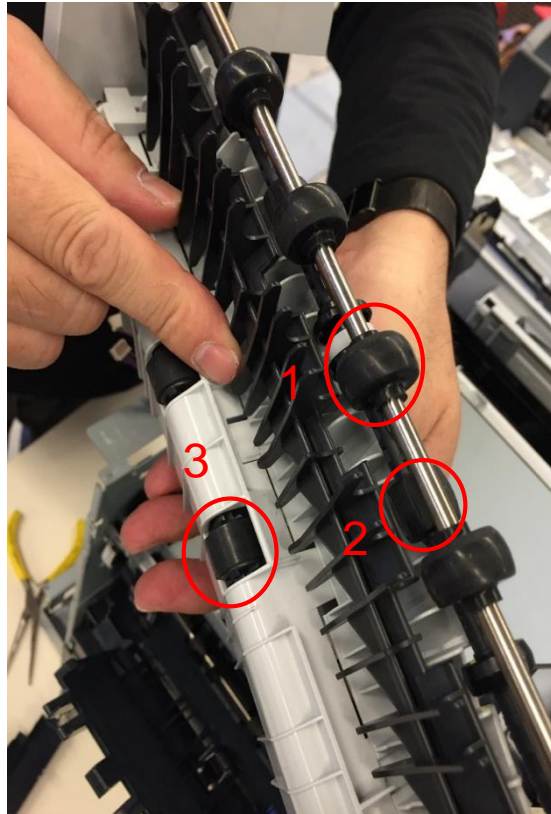
# General Approach



- **Mechanical characteristics (rotational speed) evaluation:**  $U = \frac{RL}{\pi D}$ 
  - Based on output rate,  $R$  (1.28 page/min), paper length,  $L$  (279.4 mm), and roller size,  $D$  (measured)
- **Acoustical characteristics (modulation frequency) evaluation:**
  - Based on digital signal processing methods such as
    - Discrete Fourier transform (DFT) for power spectrum density (PSD) analysis
    - Butterworth IIR filter to isolate the narrowband noise signal
    - Hilbert transform FIR filter to generate the analytic signal



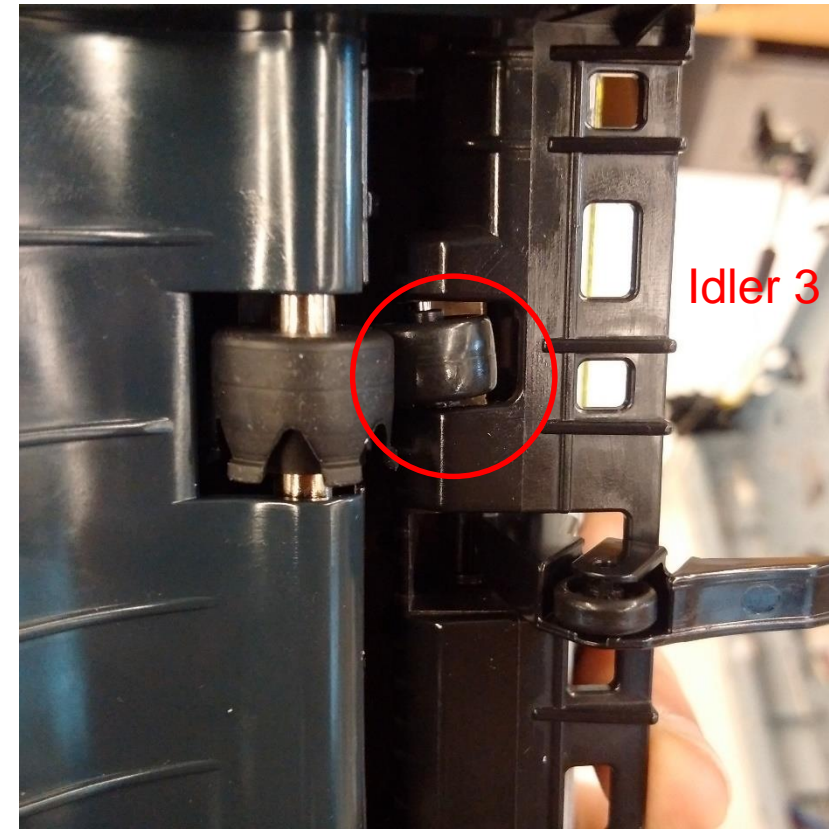
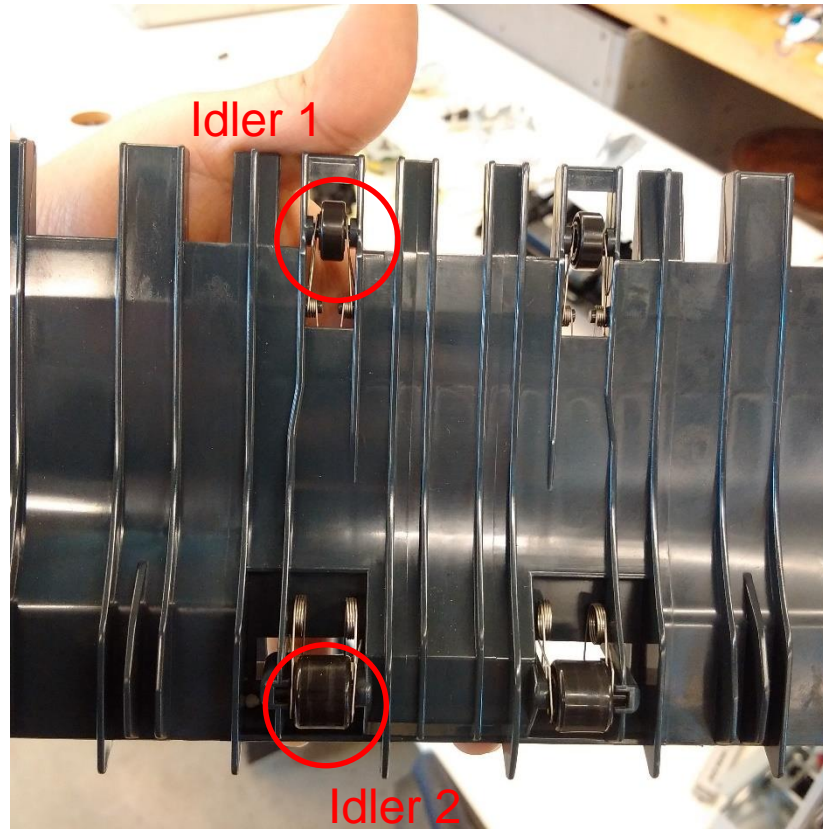
# Rollers on Paper Path



- **Diameter measurement**

- 1: Face-down delivery roller (up): **18.5 mm**
- 2: Face-down delivery roller (down): **15 mm**
- 3: Intermediate delivery roller: **15.85 mm**
- 4: Fuser delivery roller: **16.6 mm**
- 5: Inner delivery roller: **10 mm**

# Rollers on Paper Path



- **Diameter measurement**

Idler roller 1: 12.00 mm  
Idler roller 2: 13.84 mm  
Idler roller 3: 13.99 mm

# Rollers on Paper Path



- **Mechanical characteristics (rotational speed) evaluation:**  $U = \frac{RL}{\pi D}$ 
  - Based on output rate,  $R$  (1.28 page/min), paper length,  $L$  (279.4 mm), and roller size,  $D$  (measured)

**Table 1:** Rotational speeds of rollers on the paper path.

Parts name	$D$ [mm]	$U$ [rpm]	$U$ [rps]
Face-down delivery roller 1	18.50	370.00	6.17
Face-down delivery roller 2	15.00	457.00	7.60
Intermediate delivery roller	15.85	432.00	7.20
Fuser delivery roller	16.60	413.00	6.80
Inner delivery roller	10.00	654.00	10.90
Idler roller 1	12.00	571.00	9.52
Idler roller 2	13.84	495.00	8.25

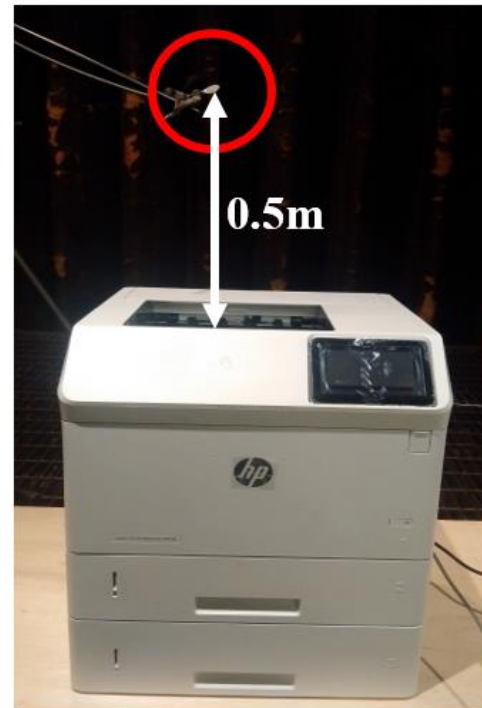


# Squeaking Signal Recording

- Noise data acquisition ( $f_s = 44100$  Hz): 6 samples were acquired



(a)



(b)



(c)

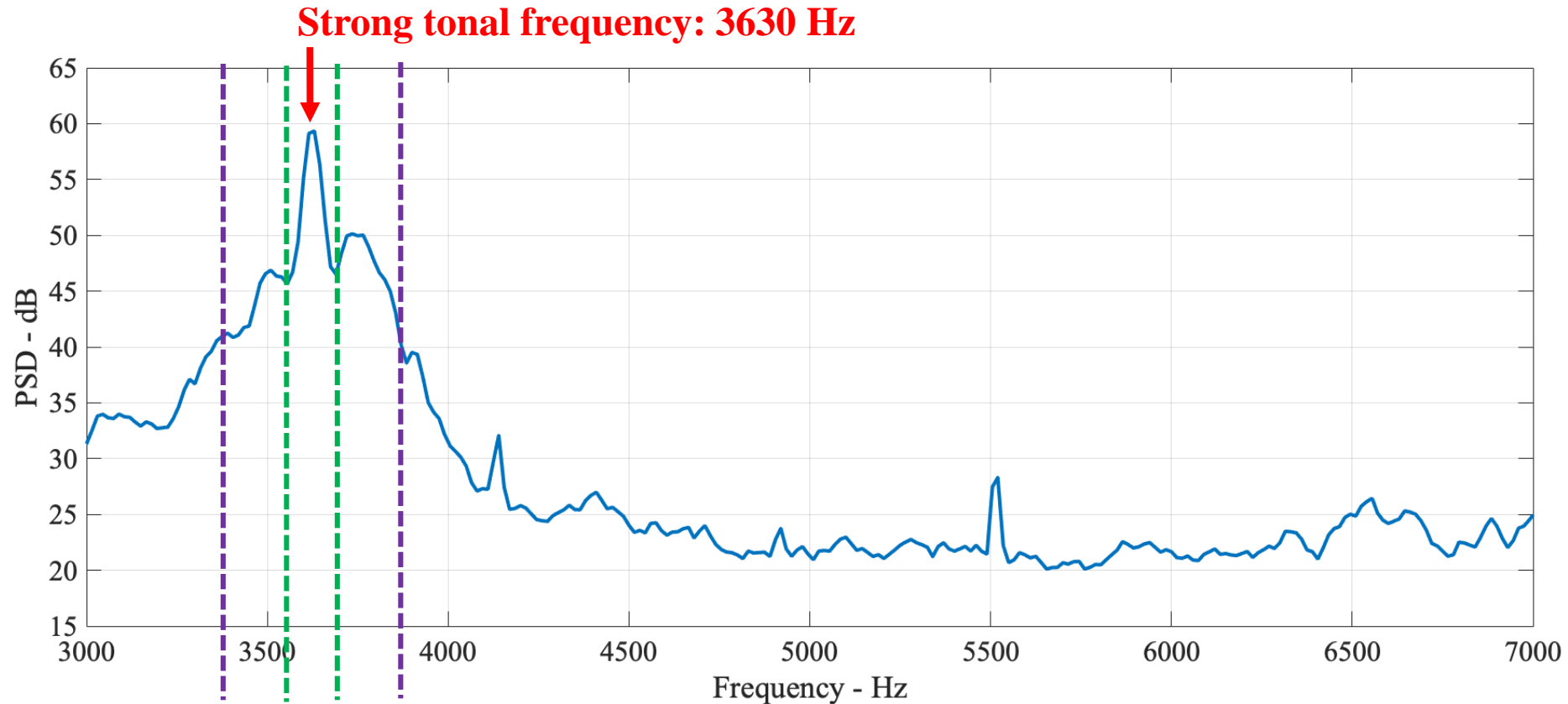


(d)

# DSP on the Sample “Squeaking 6”

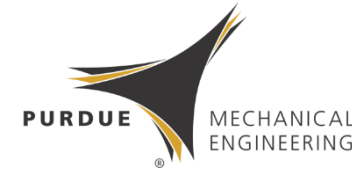


- DFT (using FFT algorithm) for PSD analysis & narrowband filtering

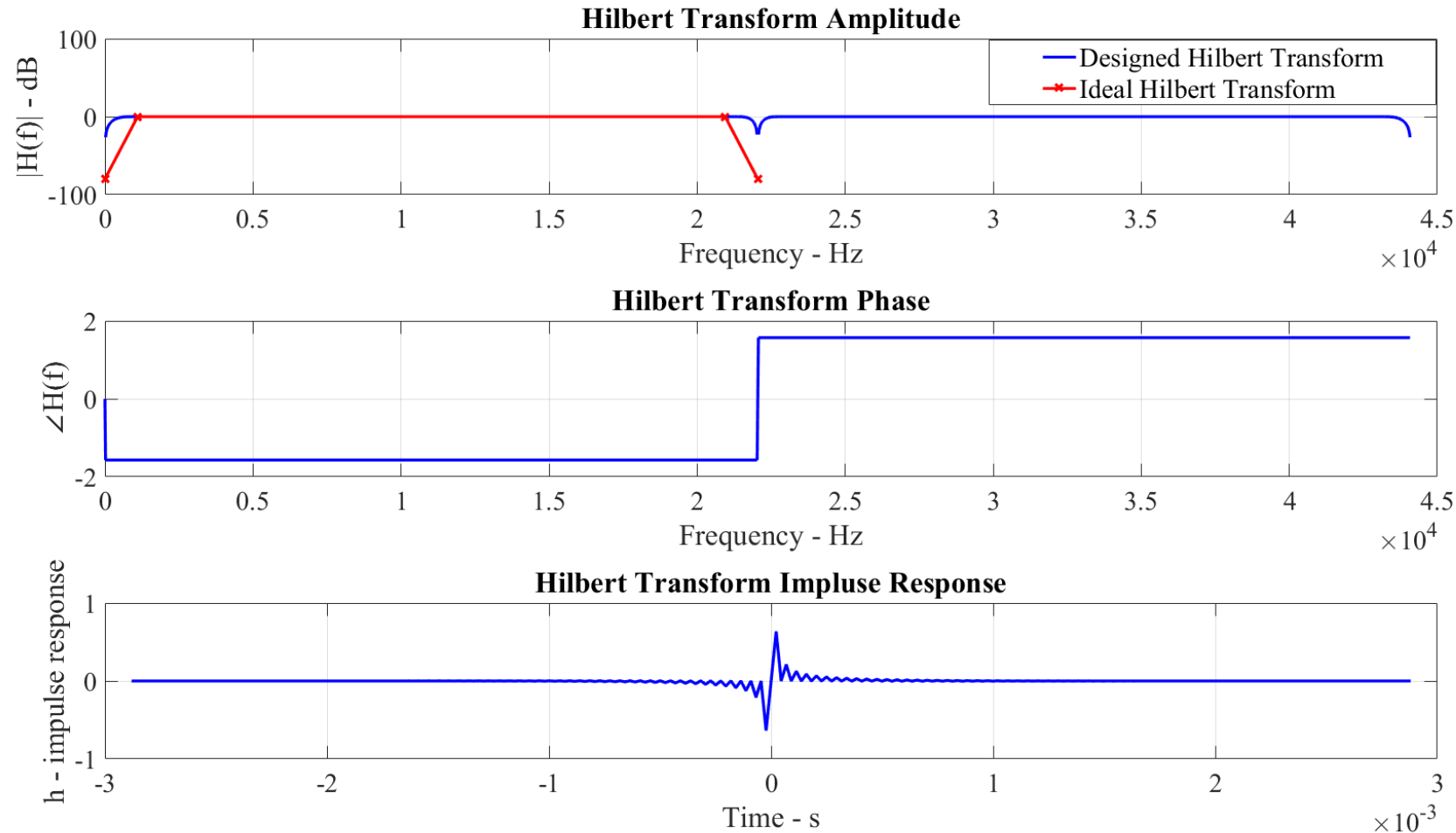


**Passband [3580 Hz, 3680 Hz] and stopband [3380 Hz, 3880 Hz]  
of the Butterworth IIR filter**

# DSP on the Sample “Squeaking 6”



- Hilbert transform to generate the complex analytic signal

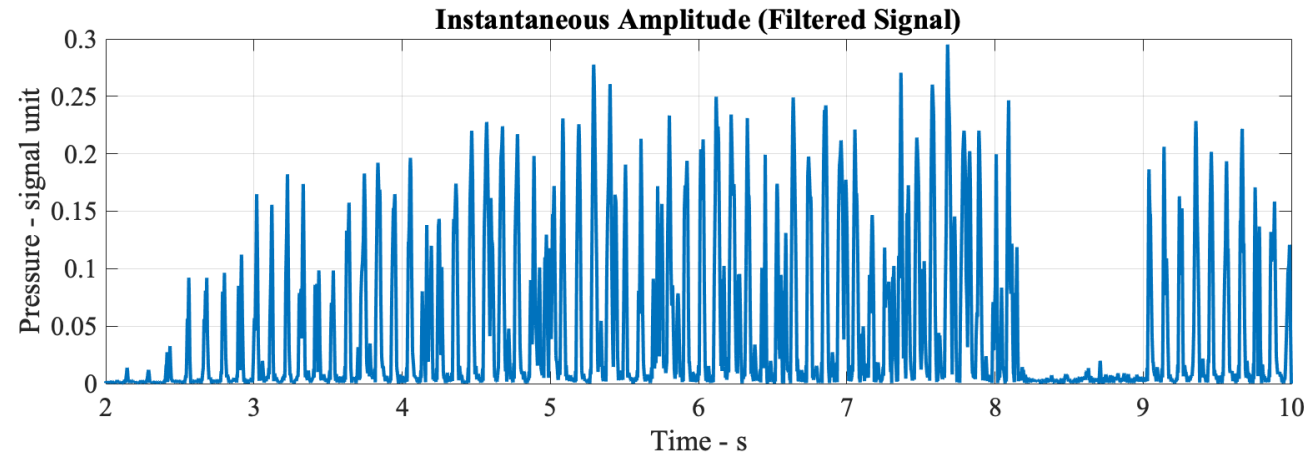




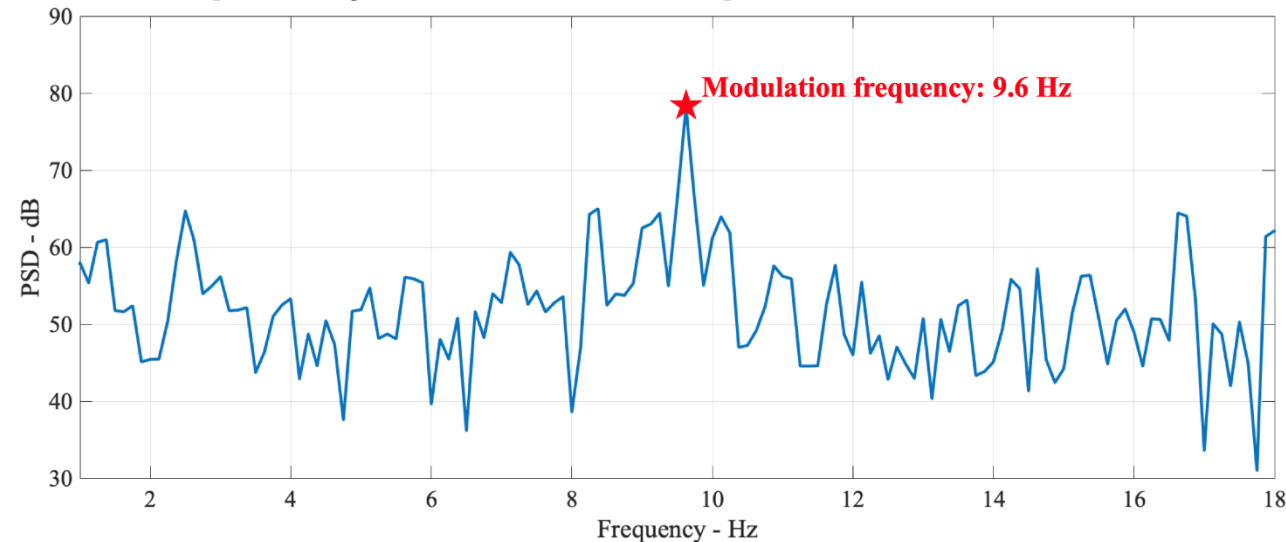
# DSP on the Sample “Squeaking 6”



- Envelope of the narrowband filtered complex analytic signal

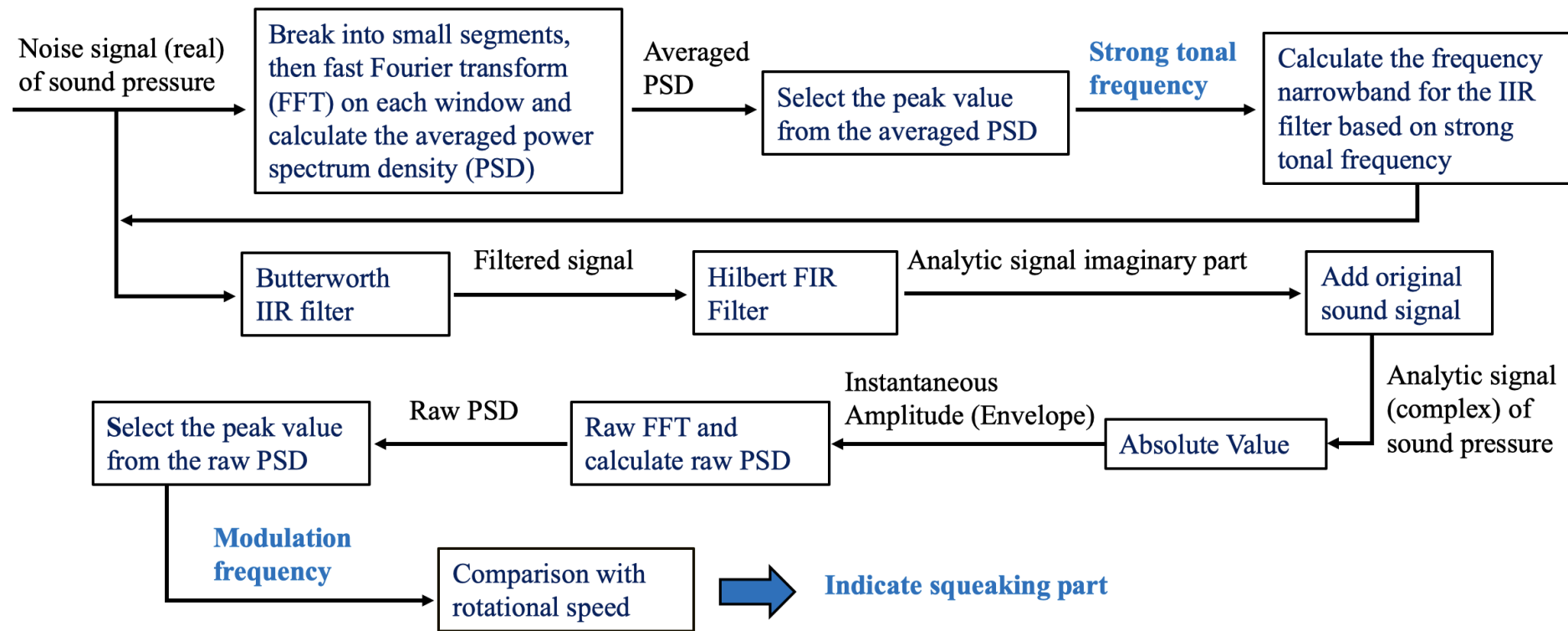


- Modulation frequency of the envelope

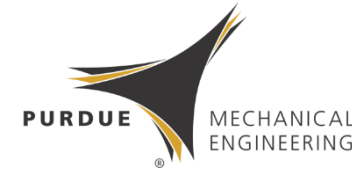


# Detector Design

- Design methodology of the to realize squeaking self-detection









# Detection Results



**Table 2: Diagnoses results from the squeaking signals.**

Noise samples	Strong tonal frequency [Hz]	Modulation frequency [Hz]	Corresponding rotational speed [rps]	Squeaking parts
Squeaking 1	3779	7.93	8.17	Idler roller 3
Squeaking 2	3473	5.80	6.17	Face-down delivery roller 1
Squeaking 3	8797	10.40	10.90	Inner delivery roller
Squeaking 4	3647	5.81	6.17	Face-down delivery roller 1
Squeaking 5	3727	10.40	10.90	Inner delivery roller
Squeaking 6	3617	9.60	9.52	Idler roller 1

Squeaking 1	Squeaking 2	Squeaking 3	Squeaking 4	Squeaking 5	Squeaking 6
					

# Conclusions



- A squeaking noise source self-diagnosis detector was developed using data from the HP LaserJet M603 printer, by returning the accurate acoustical characteristics (**e.g., strong tonal frequency, modulation frequency**) from each noise sample, and by matching those acoustical characteristics with the mechanical characteristics (**e.g., rotational speed**) of different parts, the detector was proven to be capable of providing precise source identification results (verified by HP). **Detection + machine learning is the next step.**