

# A Practical Encrypted Microprocessor

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**Abstract:** This paper explores a new approach to encrypted microprocessing, potentiating new trade-offs in security versus performance engineering. The *coprocessor* prototype described runs standard machine code (32-bit OpenRISC v1.1) with encrypted data in registers, on buses, and in memory. The architecture is ‘superscalar’, executing multiple instructions simultaneously, and is sophisticated enough that it achieves speeds approaching that of contemporary off-the-shelf processor cores.

The aim of the design is to protect user data against the operator or owner of the processor, and so-called ‘Iago’ attacks in general, for those paradigms that require trust in data-heavy computations in remote locations and/or overseen by untrusted operators. A single idea underlies the architecture, its performance and security properties: it is that *a modified arithmetic* is enough to cause all program execution to be encrypted. The privileged operator, running unencrypted with the standard arithmetic, can see and try their luck at modifying encrypted data, but has no special access to the information in it, as proven here. We test the issues, reporting performance in particular for 64-bit Rijndael and 72-bit Paillier encryptions, the latter running keylessly.

## 1 INTRODUCTION

If the arithmetic in a conventional processor is modified appropriately, then, given three provisos (summarised in Section 3), the processor operates correctly, but all the states obtained in registers and memory and on buses are one-to-many encryptions of the states obtained in an unmodified processor running the same program (Breuer and Bowen, 2013). That opens a path to a new kind of processor that, operating encrypted, is a priori more secure from prying and interference than current processors are, yet it should in principle be as fast, because only one piece of stateless internal logic – the arithmetic unit – has changed.

This paper reports on prototyping that tests the idea to a pre-production level, just before the point of gate synthesis and layout. The object is

- (a) to protect user data (not code) from the operating system and operator;
- (b) to run fast enough for users wanting offline work

to be performed remotely and securely.

A typical use case would be image-processing.

The prototype is sophisticated enough to bear comparison with off-the-shelf processors: it is superscalar (it executes multiple instructions at a time), with a pipeline in which full ‘forwarding’ has been embedded (pipeline stalls in which an instruction behind waits for data from an instruction ahead have been eliminated as far as is logically possible), along with branch prediction, instruction and data caching, speculative execution, etc.

The prototype in its present form is intended to run as a coprocessor, executing ‘somewhat’ encrypted machine code (data fields are encrypted, not opcodes). That is set up in practice with interrupt handlers and a few system calls in memory, never a full multiuser multitasking operating system, and libraries and other support would be compiled-in to encrypted code.

An encrypted processor provides the lowest level kind of security possible and we recognise that not many security engineers are familiar with this level of working. To answer some basic questions immediately: while encrypted and unencrypted code run in the same core, they remain apart because they do not

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run at the same time. The problem is they might see remnants of the other's data, but from both points of view the other's data is encrypted. Yes, a user's program code is visible to the system operator, and that is as designed. The program's control flow would in any case become visible to an operator single-stepping the machine or running a debugger, but the operator cannot tell if that is an encrypted image of a mountain or a lake being processed.

Note that if a user is determined to hide control flow, at the expense of slower running they may supply a virtual machine to run encrypted on the platform. Then both code and control flow constitute a block of encrypted data that is repeatedly transformed in the same way every cycle by a virtual machine's state transition function.

But between theory and an encrypted processor that people might want to use lies much practical work. Here are three questions that a sceptical technologist could ask:

1. Can an architecture based on a changed arithmetic really approach the performance of modern processors? Demonstrate it!

That means 'superscalar' (multiple instructions executed piecewise simultaneously) and multicore technologies – we are way past the days when the Intel 8088 would first execute one instruction, then the next. Modern processors break instructions up into small operations and execute the parts simultaneously along one or more *pipelines*. Some of the execution is *speculative* – liable to be discarded and/or reversed – and instructions and their component parts may be accelerated or delayed according to a complex system of dependencies and constraints. A processor is not purely numerical – it is supposed to react to arithmetic overflows and a host of exception conditions and flags that might not be compatible with a modified arithmetic and encrypted execution. It is not a priori clear that any of that will be sustainable.

The prototype is a platform on which to test these issues. Broadly speaking, we do have the performance required, reaching 70% of the speed of unencrypted running as of the date of this paper submission<sup>2</sup> (Section 6), and we do have the correct instruction semantics in all aspects with respect to a recognised standard, as discussed.

2. Will the production machine be compatible with existing soft- and hardware technologies?

After all, in terms of software, nobody today is generating encrypted machine code and nobody has an operating system for it, and it is not clear if we know

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<sup>2</sup>80% has been reached at camera-ready copy date.

how to make user code run under an operating system that effectively runs blind to it. How would the two communicate? Should they? Do they? There is no future in a hardware technology, no matter how good it is in security terms, that requires us to discard our software and start again. Hopefully that will not be the case, but perhaps the machine will require too much memory, or too wide buses, or impossibly fast logic. A technologist needs convincing that these are not issues. Against that, we can say that we do have an assembler and compiler and a minimal operating system, and we are able to run standard test codes.

3. Will a working product adapted to the realities be as secure as the idea promises?

Here the answers are harder to specify and we will supply data in this paper. Both encrypted and unencrypted bits pass through common elements in the processor in close proximity in time and space, which is inherently dangerous. Perhaps side-channels and attack vectors will side-step the encrypted/unencrypted security barrier: the system operator can measure power drain and see when memory areas are used repeatedly via cache statistics, for example. Perhaps the operator can set the machine's control registers to break the barrier.

One answer that does not need a paper to discuss it is that a manufacturer may apply existing protection technology on top of this design. Technologies make no issue about whether  $1 \bmod 0 = 1$  or not, merely on there being details to be masked. Masking power drain is known 'moat' electronic technology (e.g., (Kissell, 2006)). Randomising memory addressing has a long history too ('oblivious RAM' (Ostrovsky, 1990) and its recent developments (Maas et al., 2013; Liu et al., 2015)). Moreover, a natural masking is already present, because many different encrypted numbers will be passed to the memory bus for what was meant by the programmer to be the same address under the (one-to-many) encryption (Section 3 describes how software may be compiled to deal with this). At any rate, the situation is not worse than for conventional processors, and the protections developed for them are admissible.

A criterion for success is that an operator, despite their privileges, cannot access *unencrypted* user data, or interfere meaningfully with it. What can a hostile operator do then? Still everything, but not undetected, if some simple finesses are built in: a computation trace hash under the encryption flags up interference; encrypted data in memory containing a hash of its address makes copying for replay use difficult, etc.

In this paper, we report on what the pre-production prototype tells us, running in simulation, explaining the design's solutions for the questions raised above.

After discussing related work and other context in Section 2, we lay out in Section 3 hardware and software provisos, as mentioned in the first paragraph of this section, required for the design to work. A definitive account of the processor architecture is given in Section 4. Section 5 gives answers to security questions, and Section 6 discusses performance, setting out the numerical evidence.

## 2 OVERVIEW & RELATED WORK

Firstly, here are some statements to set the ground for the reader and summarise the situation before entering into technical details:

**Standards.** Our processor covers the OpenRISC version 1.1 rev. 0 instruction set and register-level specification ([opencores.org/or1k/Architecture\\\_Specification](http://opencores.org/or1k/Architecture\_Specification)). There is an answer in that to the sceptical technologist's point #2, because the expertise of existing manufacturers may be leveraged for production and there is no doubt as to the suitability as a platform for general purpose computing. We are not starting from nothing. The OpenRISC specification details hundreds of conditions for the 220 machine code instructions, and our prototype passes the Or1ksim test suite ([opencores.org/or1k/Or1ksim](http://opencores.org/or1k/Or1ksim)) in encrypted and unencrypted running.

**Sizes.** Data words are 32 bits long under the encryption, but they physically occupy an encryption block, 64 or 128 bits, etc., depending on the encryption. The register size and memory word size is the encryption block size, not 32 bits. Buses are also correspondingly wider.

**Instructions.** Instructions are 32 bits in length, conforming to OpenRISC. Data embedded as part of an instruction is encrypted (see Section 4), but the rest of the instruction is 'in the clear' and can be read or rewritten by anyone. The kind of instruction is not secret – data, not code, is protected here.

**Memory.** Storage in RAM is not different from normal, and ordinary RAM sticks are to be used with this processor. Memory access occurs at the same points and slightly greater spacings (because of extra instructions needed to carry encrypted immediate data) in an encrypted program, but the access is always 64 bits, or 128 bits, matching the encrypted word size, not 32 bits. A program's memory footprint is  $\times 2$  or  $\times 4$  the unencrypted size, depending on the encryption, which has no real impact nowadays. Cache similarly needs to be double or quadruple size and caching is less effective than usual, overall, but the focus of memory and cache stress lies elsewhere, in remapping at the fine granularity required for en-

rypted addressing (see Section 4).

There is no particular stress on the widened memory bus otherwise. Fast load/store cycling stresses the bus as much as it does in a standard processor, for example, no more and no less. There is no extra encryption/decryption on the way to memory from the encrypted processor in our design, so no extra delays occur there.

**Software.** An existing OpenRISC toolchain port has been modified for use, the GNU 'gcc' version 4.9.1 compiler and 'gas' version 2.24.51 assembler (the modified source is at [sf.net/p/or1k64kpu-gcc](http://sf.net/p/or1k64kpu-gcc) and [sf.net/p/or1k64kpu-binutils](http://sf.net/p/or1k64kpu-binutils) respectively). Encryption is confined to the instruction assembler, which moves machine code around to make room for embedded encrypted data, while compilation focuses on higher level strategies. A standard executable file ('ELF' format) encapsulates the encrypted machine code in its '.text' section and read-only encrypted constants are put in subsections containing an encrypted word each, specifying the (encrypted) address.

**Encryptions.** We have run the same experiments with two different encryptions in the processor. The first is a symmetric 64-bit encryption, Rijndael-64 (Daemen and Rijmen, 2002). Registers and words are physically 64 bits wide (note that 64, 72, 128, etc., are in no way design limits).

We have also tried a Paillier encryption (Paillier, 1999). That is an additively homomorphic encryption, in which addition under the encryption corresponds to multiplication (modulo some  $m$ ) on the encrypted data. The experiment embedded only 72-bit Paillier where 512–1024 bits would be comparable to 64-bit Rijndael, but it is sufficient to draw conclusions. The encrypted word takes the left 72 bits of 128, encrypting 32-bit data, and registers and words are 128 bits wide.

**Independence.** It is to be emphasised that the approach here is not dependent on Rijndael or Paillier, or 64 or 72 bits etc. Any symmetric encryption works, Rijndael or not, provided it fits in the registers and on buses (and their size may be designed to match the requirement), but a key is always needed. More bits (e.g. 128) is reasonable today, but there is a penalty in that machine code instructions that contain embedded data become correspondingly larger, such that it is hard to contemplate from the point of view of performance. Programs would have to be compiled to avoid embedded data, choosing memory load and store instead, or the memory and cache pathway would have to be made wider (e.g., 8 consecutive instructions read at a time, instead of 4). Further architectural prototyping than that reported here is needed to map the trade-offs comprehensively.

Any additively homomorphic encryption works, Paillier or not, provided it fits, etc., and no key is required. But Paillier needs a ‘table of signs’, discussed below, that effectively limits its applicability to 32-bit computing at present, no matter what block or key size is used. An additive homomorphic encryption in which the sign were also obtained homomorphically would remove that limit, and we hope for one in the near future. However, known homomorphic encryptions are very ‘wide’ for the same level of security as symmetric encryptions and that will always give a performance hit in comparison.

**Vulnerabilities.** If an attacker has a scanning electron microscope or similar advanced physical probes, then a Rijndael encryption is vulnerable to it because there is a *codec* (encryption/decryption device) forming part of the processor pipeline, as described in Section 4. However, vulnerable areas will normally be buried deep inside the chip in a production model, as in the ubiquitous modern smartcard technology (Kömmerling and Kuhn, 1999). The arrangement here is not less secure. Keys for the codec may be built in at manufacture, as in a smartcard, or managed via an established key management technology. But key management for symmetric encryptions is emphatically not relevant for this paper’s aims. That is partly an issue for a business model and partly for future research directions and we do not want to gainsay the eventual answer here. The CIA (US Central Intelligence Agency) is not going to want to share their computers, for example, so one key per processor is fine for them. If a key is to be lodged in the codec just before use, then that may be handled by a Diffie-Hellman circuit such as (Buer, 2006), that can secretly transfer the key, never exposing it in registers or memory or on buses. It does not matter in principle if the wrong user runs with that key, as the user, lacking the key, cannot read the results or enter data that makes sense, nor compile a nontrivial program that will run. Whether a user can somehow devise programmed experiments that reveal an unknown key is the same question as whether the operator can, so key management is in that sense an orthogonal issue.

Notably, there are no codecs or keys involved with the Paillier encryption in the processor. In principle our simulations might be run in full public view. The parts of the processor taken up by the codec for Rijndael are occupied instead by the Paillier ‘addition’ on encrypted data. That is 72-bit multiplication modulo  $m$ , with no encryption or decryption. That can be done in hardware in one or two stages, but we envisage a production machine using 512- to 1024-bit Paillier, which would require many more stages, so our simulation pretends 10 of 15 pipeline stages are

required even for lowly 72-bit Paillier addition.

**Exceptional Stresses with Paillier.** In using the Paillier encryption we follow (Tsoutsos and Maniatakos, 2013; Tsoutsos and Maniatakos, 2015), where a ‘one instruction’ stack machine architecture (‘HEROIC’) for encrypted computing embedding a 16-bit Paillier encryption is prototyped. In conjunction with a lookup table for the signs (positive/negative) of encrypted data, the Paillier addition is computationally complete (any computable function can be implemented using addition, the table, an encrypted 1, and recursion), and addition, subtraction, and comparison machine code instructions suffice to write software routines for the rest. The 72 bits is the most that is convenient without alterations to our compile strategy to place encrypted constants in memory rather than inline in the machine code, and is not a hard limit. The problem is that 72 bits does not fit in 32-bit instructions, and the sequence is already ‘prefix; prefix; instruction’ for each inline constant used, so increasing the number of bits would further reduce the proportion of ‘real’ instructions in code, affecting performance.

However, we believe the table of signs is a vulnerability in practice (see Section 5). It is also very large, consisting of  $2^{31} \times x$  rows of 72 bits, where  $x$  is the number of different encryptions of each (negative) number. That is hundreds of GBytes, perhaps TBytes, and it is a concern with present technology. Still, motherboards are available with several TBytes of RAM (see for example the Supermicro Xeon 7000 range at [supermicro.com/products/motherboard/Xeon7000/](http://supermicro.com/products/motherboard/Xeon7000/)), so we expect that concern to diminish in the future. We have ‘cheated’ in our simulation by computing rows of the table externally on demand and caching them locally to the processor.

**Software Engineering.** OpenRISC’s ‘or1ksim’ simulator project has been modified to run the processor prototype. It is now a cycle-accurate simulator, 800,000 lines of finished C code having been added through a sequence of seven successive models. The code archive and history is available at [sf.net/p/or1ksim64kpu](http://sf.net/p/or1ksim64kpu).

**Historical use of Encryption in Computing.** Attempts at creating a processor that works with greater security against observation and tampering have regularly been made in the past. One of the earliest landmarks is a US Patent “Tamper Resistant Microprocessor” (Hashimoto et al., 2001) which states “it should be apparent to those skilled in the art that it is possible to add [a] data encryption function to the microprocessor . . .”, meaning that codecs could be placed between processor and encrypted content in memory.

However, a codec on the memory path, adding latency, forms no part of our design. Data is already encrypted by the time it leaves the processor pipeline, so there is nothing more to do. Extra overhead is incurred instead by remapping for encrypted addresses, as discussed in Section 4, which entails an extra cache retrieval (for the mapping) for each load/store and a minor fault handler call on a cache miss.

**Keyed Access to Memory.** Hashimoto et al. also aimed to segregate memory via access keys, and that aspect of their proposal has echoes in recent approaches such as Schuster et al.’s implementation of *MapReduce* for cloud-based query processing (Schuster et al., 2015) on Intel® SGX™ machines, which employs the machine’s built-in hardware (Anati et al., 2013) to isolate the memory regions involved to well-defined ‘enclaves’, and encryption may also feature.

**Encrypted Memory.** In Hashimoto et al. and others’ proposals the basis is that encrypted content is kept in memory and decrypted en route. That means that in case of a process crash and a dump of the memory region, the file will record encrypted memory content. Thus a malicious user cannot obtain the decryption of an encrypted CD by inducing through some ingenious means the reading process to crash and dump. Nor can ‘cold boot’ techniques (Halderman et al., 2009) recover information, as memory contents are encrypted. But memory is only one peripheral device of many (disk, keyboard, USB, etc).

Intel SGX is competition here, but we cannot compete with Intel’s design and implementation teams. All we can show is that our approach is an alternative, and if Intel were to apply their resources to it they may do better yet. In principle, our approach of embedding a codec in the processor pipeline is far faster than encryption on the way to/from memory can ever be, even in burst mode, because pipelining achieves an average throughput of one encryption per cycle though each encryption takes  $20\times$  that time.

**Security Basics.** The working of the encrypted processor described in this paper is intended to be simple enough that its security is analysable by security not hardware experts:

- (I) in user mode, data circulates encrypted in the processor, and
- (II) in supervisor mode it circulates unencrypted.

If that claim is true, then a system operator may give up on snooping an unencrypted form of user data, and can only meaningfully move encrypted data from place to place. Altering it is possible, but not meaningful unless the operator already knows something about the encryption.

That puts the focus on whether a system opera-

tor can determine information from the patterns of encrypted data observed, or achieved by experiment (submitting a known ciphertext for encrypted processing, for example), essentially the position of an unprivileged adversary who may obtain the same ends by social engineering, e.g., by tricking debug syscalls into submitted code.

### 3 THREE CONDITIONS

To make a conventional processor architecture work encrypted by virtue of a modified arithmetic, certain conditions must be met.

- (A) *The arithmetic must be ‘homomorphic’ with respect to ordinary computer arithmetic.*

That does not imply merely a one-to-one rearrangement of the conventional (2s complement) encoding of numbers in 32-bit binary. The constraint is  $\mathcal{E}(x+y)=f(\mathcal{E}(x),\mathcal{E}(y))$ , specifying what the encrypted output  $f(a,b)$  from the modified ALU in the processor must be when encrypted inputs  $a=\mathcal{E}(x)$  and  $b=\mathcal{E}(y)$  are presented, so a designer chooses an encryption  $\mathcal{E}$  that achieves a trade-off between security and the feasibility of an appropriate function  $f$  in hardware. The encryption  $\mathcal{E}$  is one-to-many, when random padding or blinding is taken into account.

The requirement is formally weaker than classical homomorphism in encryption, which has  $\mathcal{E}(x+y)=\mathcal{E}(x)+\mathcal{E}(y)$ . That is not a question of ‘what is in a name’ as to whether the function is called ‘ $f$ ’ or ‘ $+$ ’; the designer is not obliged to co-opt the familiar ‘ $+$ ’ for  $f$ . For the Paillier encryption, the ALU operation  $f(a,b)$  is multiplication  $ab \bmod m$ , where  $m$  is the Paillier modulus ( $m=n^2$ ,  $n=pq$ ,  $p, q$  36-bit primes such that  $\text{lcm}\{p-1, q-1\}$  has at least one small factor, in order to allow a blinding factor of low multiplicative order to exist). For the Rijndael encryption  $f(a,b)$  is  $\mathcal{E}(\mathcal{D}(a)+\mathcal{D}(b))$ , invoking a codec three times, where  $\mathcal{D}$  is the decryption function. Clever hardware improves that ‘dumb’ solution to work fast and securely in the prototype (Section 4).

The detailed conditions on the changed ALU functionality  $\text{ALU}'$  for every operation may be derived from the rendering in Fig. 1 (Breuer and Bowen, 2013). There are three equations, corresponding to the three kinds of arithmetic operations in the ALU: unary operations  $u$  such as bit-flipping  $x \rightarrow \hat{x}$ ; binary operations  $b$  such as addition  $(x,y) \rightarrow x+y$ ; comparisons  $r$  such as less than,  $(x,y) \rightarrow (x<y)$ . In terms of the relation between encrypted data  $e$  and decrypted

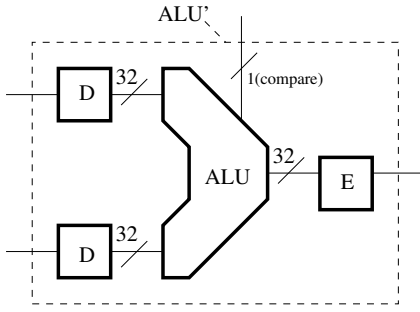


Figure 1: Idealised modified arithmetic logic unit (ALU) for encrypted operation ( $ALU'$ ), with decryption units (D) and encryption unit (E).

data  $d$ , such that  $d = \mathcal{D}(e)$ , the equations are

$$ALU_u(d) = \mathcal{D}(ALU'_u(e)) \quad (1)$$

$$ALU_b(d_1, d_2) = \mathcal{D}(ALU'_b(e_1, e_2)) \quad (2)$$

$$ALU_r(d_1, d_2) = ALU'_r(e_1, e_2) \quad (3)$$

The first two constrain the encrypted data output of the modified ALU, and the third constrains the 1-bit comparator output. For the addition operator, the assertion (2) is

$$d_1 + d_2 \pmod{2^{32}} = \mathcal{D}(f(e_1, e_2))$$

where  $f$  is the modified ALU's operation. If  $f$  is multiplication on the encrypted values, as in the Paillier encryption, then (2) is

$$d_1 + d_2 \pmod{2^{32}} = \mathcal{D}(e_1 e_2 \pmod{m})$$

but more solutions are possible in general.

Because they look no different and are produced dynamically in the course of a program, for example by adding an offset to a base address, *data addresses must be encrypted* just like other data. However, *program addresses* (the addresses of machine code instructions in memory) *are not encrypted*, the rationale being that the program counter is usually advanced by a constant at each tick of the clock, and that potentiates an attack against the encryption. The solution adopted is not to encrypt program addresses at all. So:

- (B) *Encrypted programs must never arithmetically mix program addresses and ordinary data.*

A conforming program may not jump to an address given by the square root of Elvis's birthdate.

That is easy to arrange via compilation from source, and can be checked automatically at the machine code level (Breuer and Bowen, 2012). Dynamic loaders and linkers are not restricted by this condition because they run in supervisor mode, although late linking is *not* recommended for a program intended to run securely.

The third condition on correct running on the encrypted platform is due to the fact that many differ-

Table 1: OpenRISC instruction set coverage in the prototype, per User and Supervisor mode.

kind\mode	32-bit		64-bit	
	Encrypted	Unencrypted	Encrypted	Unencrypted
Integer	U	S	-	S
Float	U	S	-	S
Vector	-	-	-	-

ent runtime encodings may be generated for what the programmer intended to be the same memory address, as a consequence of the one-to-many nature of good encryption. That gives rise to *hardware aliasing*, in that the same address (as seen by a program running under the encryption) sporadically accesses different data. To avoid it:

- (C) *Programs must be compiled to save data addresses for reuse, or recalculate them exactly the same way the next time.*

Stepping up then down a string is affected, for example. In truth, (C) only need hold over the reads following a write, which is an opportunity to change the address mapping at each write, achieving what classical 'oblivious RAM' does. The second option depends on the processor being deterministic at bottom, including generation of padding under the encryption.

## 4 ARCHITECTURE

The processor runs in two modes, user mode (32-bit data encrypted in 64 or more bits, OpenRISC 32-bit instructions) and supervisor mode (64-bit unencrypted data, 32/64-bit instructions). User mode instructions access 32 general purpose registers (GPRs) and a few permitted special purpose registers (SPRs,  $2^{16}$  available in supervisor mode). Attempts to write 'out of bounds' SPRs are silently ignored in user mode and a random value is read. The instruction set coverage across modes is summarised in Table 1.

In accord with the OpenRISC specification, there is no grand separation of memory into 'supervisor' and 'user' parts except that user mode is restricted to 32-bit addresses in a fundamentally 64-bit architecture. A supervisor mode process can always read user data in memory, but the data will be in encrypted form. The other way round, (user) access is guided by the memory mapping, which can only be programmed in supervisor mode, via the memory management unit (MMU). That is all quite conventional.

Unconventionally, however, in user mode, a special 'translation lookaside buffer' (TLB) in the MMU is active. It remaps encrypted addresses, which are scattered all over the cipherspace, to a contiguous linear sequence of unencrypted addresses in a designated

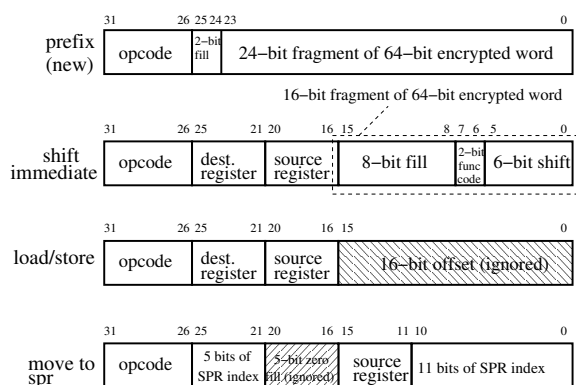


Figure 2: Modifications to OpenRISC instructions. An extra ‘prefix’ instruction carries part of an encrypted immediate, and the shift immediate instruction has been respecified to contain 16 bits of a 64-bit encrypted (6-bit) shift value, including the subfunction specifier. The displacement field in a load/store instruction is ignored, as is the alternative designator register in a move to/from SPR instruction.

region on a first-come, first-served basis. The mapping database is stored in memory and cached and the TLB hardware does the lookup and assignment. The upshot is that every encrypted memory address is blindly remapped to a contiguous region in user mode. Temporal locality of mappings gives rise to spatial locality in the cache, which is effective. Every word in memory is addressed via this TLB mapping database but the mapping is cached so the effect is usually not two memory accesses but one and one TLB cache access. On the other hand, a TLB cache miss is costly, invoking the minor TLB fault handler. Every encrypted word in memory (64 or 128 bits) also costs one new TLB entry (128 bits) in memory. Memory access is slower on average on that account, and more is used. There are already separate paths for data and program memory (‘Harvard’ layout), and we are considering introducing a path for TLB too.

Looking beyond the relatively mundane address engineering discussed above, the major modifications in the processor are associated with the Rijndael implementation of changed arithmetic, as illustrated in Fig. 1. In order to reduce the frequency with which a codec is brought into action for user mode instructions, ALU operation is *extended in the time dimension*, so it covers consecutive (encrypted) arithmetic operations in user mode. Only the beginning of the series is associated with a decryption event, when encrypted data from memory or registers is converted, and only the end of the series is associated with an encryption event. In between, arithmetic is carried out unencrypted in user mode, in a set of ‘shadow registers’, unavailable in supervisor mode. An instruction

in user mode sees the shadow registers and an instruction in supervisor mode sees the ‘real’ registers. The aliases are flipped per instruction mode per stage of the processor pipeline, so there is no possibility of an instruction seeing the wrong set (see Section 5).

The Rijndael codec is embedded across multiple stages of the processor instruction pipeline. Having it there is hugely effective, because it lets encryption/decryption benefit from the ‘pipeline speed-up’ effect largely responsible for modern processor speeds. A 15-stage pipeline can work on 15 instructions at a time in parallel, completing up to 15 times as many instructions per cycle as it would otherwise, making the processor 15 times as fast as a non-pipelined processor. One encryption/decryption can complete per cycle, even if each takes 10 cycles. The upshot should be that encryption/decryption is largely inconsequential, slowing nothing down during processing of linear code, and contributing significantly only on pipeline refills at jumps and branches.

That is the theory, but putting it into practice requires some minor adjustments to the instruction set. The instruction pipeline in (unencrypted) supervisor mode is the standard short 5-stage fetch, decode, read, execute, write pipeline of a RISC processor (Patterson, 1985), and it is embedded in the codec-extended pipeline traversed by the (encrypted) user mode instructions. To keep the pipeline short, there should be only one codec, yet Fig. 1 shows three around the ALU. To solve that we slightly modify OpenRISC instructions so they need at most *one* use of the codec in user mode (see Fig. 2). That creates two kinds of instruction: type ‘A’ need codec use after ALU use, and type ‘B’ need the codec before. The pipeline is configured differently for the two as shown in Fig. 4 (hardware for those stages that adopt two different configurations is duplicated).

The ‘A’ configuration triggers when a store instruction encrypts a register for memory, or a load instruction decrypts data from memory for registers. The ‘B’ configuration is used when encrypted immediate data in an ‘add immediate’ instruction is read in and decrypted prior to use. Instructions that do not use the codec go through as type ‘A’, because the earlier execution stage makes results available earlier for ‘forwarding’ to instructions behind.

The assembler emits, in place of what might have been a single ‘load at offset 8’ instruction in standard OpenRISC, the sequence shown in Fig. 3. The modified machine code does not allow nonzero load offset, and that sequence is the result. Register 31 is treated specially as target: no arithmetic overflow is set or exception raised. The problem is that OpenRISC does not contain an unsigned addition and one is needed

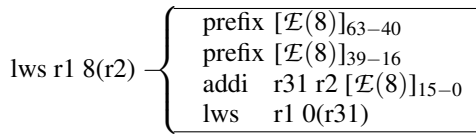


Figure 3: Assembling a load signed word instruction for encrypted execution.

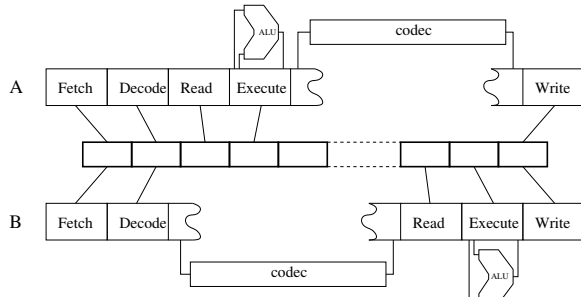


Figure 4: The Rijndael pipeline is configured in two different ways, ‘A’ and ‘B’, for two different kinds of user mode instructions during encrypted working.

there, else overflow might accidentally be signalled.

The codec covers 10 stages in the Rijndael implementation, corresponding to 10 clock cycles per encryption/decryption, but that may be varied to suit the encryption, and the effect is detailed in Section 6.

To further reduce codec use, a small user-mode-only instruction cache retains instructions with their immediate data replaced by the decrypted value ((Hampson, 1989) works the same trick). The cached copy of the prefix instructions carrying the encrypted constant is converted to a no-op to ensure this is done once only. Replacement is not done if the sequence spans cache-lines, to avoid later only half-flushing the altered copy.

The caches lie within the security boundary of the processor package. Fig. 5 shows the arrangement of functional units.

It has turned out to be possible with Rijndael to pass the unencrypted data address to the memory unit during the processing of load and store instructions. We do not suggest that! But the address could be hashed or encrypted in a different way. The hardware aliasing effect discussed in Section 3 then does not occur (it still occurs for Paillier, as there the address is never decrypted).

The implementation for Paillier has the same architecture (Fig. 5) but all the instructions are of ‘A’ type and the codec stages are devoted to the Paillier addition/subtraction operation on encrypted data. All the data passes through in encrypted form in what are the ‘shadow’ registers in user mode (‘real’ registers to supervisor mode). Instructions other than addi-

tion/subtraction and comparison are implemented as software routines.

Context switches (such as when an interrupt handler is triggered) are in principle an opportunity for system code to see unencrypted data being worked on by the user in shadow registers in the Rijndael implementation, but the swap of ‘shadow’ for ‘real’ registers on change of mode foils that. Instructions that copy from one register to another copy both real and shadow values, which means that handler code can save the user’s GPR data in the shadow registers, unseen, by copying GPRs to SPRs on entry and copying them back on exit. The protocol is explained further in Section 5, where its security is proved.

The Rijndael implementation of the processor is not suitable for multiuser operation in its current form, as shadow registers hold previous data in the clear through context switches. Paillier has no such problem as its data is never in the clear.

## 5 SECURITY

As discussed in Section 1, our aim is to protect user information (keys, cookies, passwords, lists of weapon parts, etc.) being processed in encrypted mode on our processor against the privileged operator or operating system as adversary.

**The Paillier Implementation:** appears suitable, because no decryption ever takes place, so unencrypted information ought never to be revealed. But the ‘table of signs’ required for general computation may give away too much. It shows the 31st bit (the most significant) of a 32-bit 2s complement number under the additively homomorphic encryption. Read  $\text{sign}(x)$  for the 31st bit, then  $\text{sign}(x+x)$  for the 30th, and so on, giving the decryption in 32 steps.

Concretely, the operator can embed a ‘sub r1 r1 r1’ (subtract in place in register r1) instruction in the user’s program to generate an encrypted zero in general register r1, from any encrypted datum originally there. For any encrypted value in register r2, the operator can run ‘sflt r2 r1’ (set flag if the value in r2 is less than the zero in r1) to get the sign bit (#31) flagged. The operator can run ‘add r2 r2 r2’ to double the content of r2 in place, and work the same trick again to get its next bit. That decodes r2.

(Tsoutsos and Maniatakos, 2015) avoids the problem by providing only the  $x+k$  operation, for constants  $k$ , not  $x+y$  (hence not  $x+x$  or  $x-x$ ), so we might declare all two-operand OpenRISC instructions *off-limits*, leaving only the one-operand ones:  $x+k$  and  $x<k$  are formally safe because  $x \rightarrow x+K$  is an automorphism that turns  $y=x+k$  into  $y+K=(x+K)+k$ , and



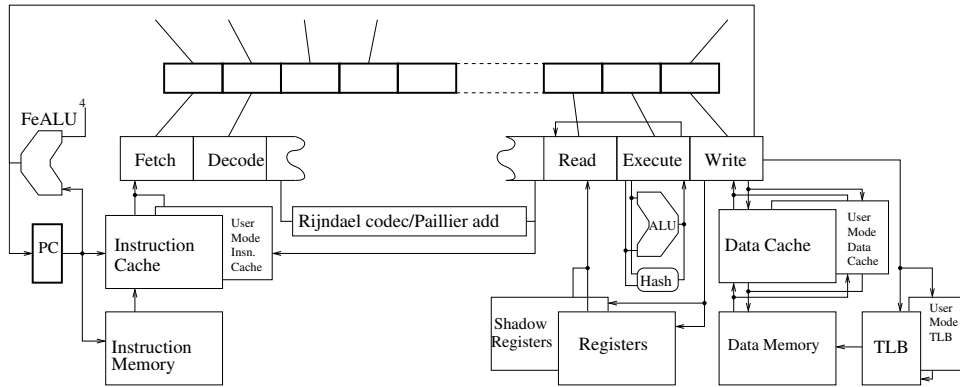


Figure 5: Pipeline integration with other functional units.

$x < k$  into  $x + K < k'$  where  $k' = k + K$ , so there will be  $2^{32}$  self-consistent readings  $x + K$ ,  $y + K$ , etc. for any choice of  $K$ , for any guess by the operator at a consistent assignment of decrypted values  $x$ ,  $y$ , etc. to encrypted values  $x'$ ,  $y'$ , etc. that makes sense of the user's (or operator's) program.

However, it is easy to identify the encrypted constant 1 in the software routines for division and multiplication. With it, an adversary can calculate  $2 = 1 + 1$ , etc., producing any message. Addition and subtraction give 0 when both inputs are 0, so any combination of them has that property. That is a limited set of functions ( $1 - x$  is not among them). So a Paillier-based implementation for general computation must secrete some encrypted nonzero constant for use, 1 or some other (the same reasoning holds of fully homomorphic encryptions such as (Gentry, 2009)). That is as vulnerable as a key for Rijndael is.

A remedy for both  $1 + 1 = 2$  and  $\text{sign}(x)$  vulnerabilities is suggested in Section 7, but we have not yet trialled it in prototyping. That 'ABC' solution (Breuer and Bowen, 2014) does not restrict instructions, but relies on a further arrangement of the arithmetic of the processor's arithmetic logic unit according to a typing system, so that it produces nonsense from  $x + x$ , but compiled code can easily produce intended results.

**The Rijndael Implementation:** does decryption internally, but only in user mode, and security relies on never revealing the decrypted information to supervisor mode code. That can be expressed formally. There are five data types:

- Ⓜ 32-bit unencrypted data that originated as encrypted user data;
- Ⓢ encrypted user data occupying 64+ bits;
- ⓐ 32-bit data in the clear that originated in supervisor mode;
- Ⓝ notionally 'decrypted' data that originated in supervisor mode as 32-bit data and has been marked

by a  $0x7fff$  in the top 16 bits of 64;

- \* a 'placeholder', used to indicate a pending decryption (Ⓜ) or encryption (Ⓢ) that looks like the 'decrypted' zero datum (Ⓝ).

In supervisor mode, *real/shadow registers will contain types Ⓢ/Ⓜ or Ⓢ/\* or \*/Ⓜ or ⓐ/Ⓝ*. None of those expose type Ⓜ unencrypted user data.

In user mode, *real/shadow registers will contain types Ⓜ/Ⓢ, or \*/Ⓢ or Ⓜ/\* or Ⓝ/ⓐ*. Swapping real/shadow registers on mode change maintains the invariant. *Memory contains Ⓢ or ⓐ or \**.

To maintain those invariants, every instruction must preserve them and they must hold at start-up. The prototype does that. User mode addition, for example, does  $\text{Ⓜ/?} + \text{Ⓜ/?} = \text{Ⓜ/*}$ , requiring type Ⓜ in both addend registers, otherwise it raises a 'range' exception (if enabled) and leaves registers as they are (we may allow user mode arithmetic on Ⓝ/ⓐ in future).

Load from memory in user mode produces either Ⓜ/Ⓢ, decrypting encrypted data of type Ⓢ in memory via the codec, or Ⓝ/ⓐ, reading plain unencrypted supervisor mode data of type ⓐ from memory and marking it to type Ⓝ, or it produces Ⓝ/ⓐ reading the \* value in memory as a 'decrypted' zero and storing it as the \*/0 pair.

Store to memory in user mode takes type Ⓜ/Ⓢ or Ⓜ/\* or \*/Ⓢ and either stores the Ⓢ value or encrypts the Ⓜ value for memory via the codec. Type Ⓝ/ⓐ if seen causes the ⓐ value to be stored in memory.

Store in supervisor mode cannot use the codec, and the register types Ⓢ/Ⓜ, Ⓢ/\*, \*/Ⓜ, ⓐ/Ⓝ result in types Ⓢ, \* and ⓐ in memory respectively. Load from memory in supervisor mode also cannot use the codec and Ⓢ, ⓐ in memory produce register content Ⓢ/\*, ⓐ/Ⓝ respectively. The \* value in memory is read as zero and stored as the 0/\* pair, of type ⓐ/Ⓝ.

That establishes that the operator can never see the unencrypted value, so the question of whether the Ri-

Table 2: Rijndael performance data, or1ksim test suite instruction set add test.

@exit : cycles 315640, instructions 222006		
mode	user	super
register instructions	0.2%	0.2%
immediate instructions	7.3%	9.2%
load instructions (cached)	0.9% (0.9%)	2.8%
store instructions (cached)	0.9% (0.9%)	0.0%
branch instructions	1.0%	4.9%
jump instructions	1.1%	4.8%
no-op instructions	6.4%	15.8%
prefix instructions	11.5%	0.0%
move from/to SPR instructions	0.1%	2.7%
sys/trap instructions	0.5%	0.0%
wait states (stalls) (refills)	24.7% (22.1%) (2.7%)	4.9% (3.8%) (1.1%)
total	54.8%	45.2%

Branch Prediction Buffer			
hits	10328 ( 55%)	misses	8219 ( 44%)
right	8335 ( 44%)	right	6495 ( 35%)
wrong	1993 ( 10%)	wrong	1724 ( 9%)

User Data Cache			
read hits	2942 (99%)	misses	0 ( 0%)
write hits	2933 (99%)	misses	9 ( 0%)

Pipeline Hazards (22.1%+3.8%)			
to \ from	lwz	lws	lbz
andi	3.3%	-	-
sfeqi	-	-	16.9%
sw	-	-	-

jndael implementation is secure reduces to the question for Paillier, and the same arguments apply.

Overall, given the size of the Paillier ‘table of signs’, as well as performance considerations (Section 6), the Rijndael or similar symmetric encryptions seem the better option.

## 6 PERFORMANCE

The Or1ksim OpenRISC test suite codes have been modified to run encrypted in the prototype. For the measurements, cache latency is 3 cycles and memory latency 15 cycles, realistic for a nominal 1GHz clock.

Table 2 shows the performance summary from the

suite’s instruction set add test (‘is-add-test’). The statically compiled executable contains 185628 machine code instructions, occupying 742512 bytes. Table 2 shows that when the test was run (successfully) to completion in the Rijndael implementation, 222006 instructions were executed, so there are few loops and subroutines (the code is largely built using assembler macros) in 315640 cycles. If one reckons with a 1GHz clock, then the speed was just over 700Kips (instructions per second) overall.

In supervisor mode, pipeline occupation is just under 90%, at 892Kips for a 1GHz clock (wait states, cycles in which the pipeline fails to complete an instruction, comprise 4.9% of the 45.2% total), which one may take as a baseline for a single pipeline superscalar design. In user mode, pipeline occupation is only 54.9%, as measured by numbers of non-wait states, for 549Kips with a 1GHz clock. Measured against supervisor mode, that is 61.6% of the unencrypted speed.

The wait states are caused by real pipeline data hazards, as enumerated at bottom in Table 2. Most are due to a load from memory instruction (lwz, lws, lbz) feeding directly to an arithmetic instruction (andi, sfeqi). The matrix is  $64 \times 64$ , only entries over 0.1% being shown.

Over the whole test suite, the Rijndael implementation’s performance in encrypted mode varies between 61.4% and 67.2% of unencrypted running speed<sup>2</sup>, over many different tests running for between 12329 and 811871 cycles (respectively, 9495 and 562200 instructions) each.

The majority (13425; 82.0%) of codec uses in the add test were decryptions of immediate data in instructions. Load from memory always encountered the data already decrypted in the user-mode only data cache, rather than having to decrypt it from memory. Memory was not stressed at all, cache being perfectly effective in the test.

Running the same addition test in the Paillier implementation shows worse performance:

add test	cycles	instructions
Rijndael	315640	222006
Paillier	445099	222489

The difference is because Paillier arithmetic needs the full length of the pipeline to complete in, stalling following instructions that need the result in read stage, as far as 11 stages behind. The Rijndael implementation’s arithmetic is performed on unencrypted values in shadow registers and completes in just one stage, resulting in no stalls.

The disparity is more marked on other tests as the Paillier implementation does arithmetic other than

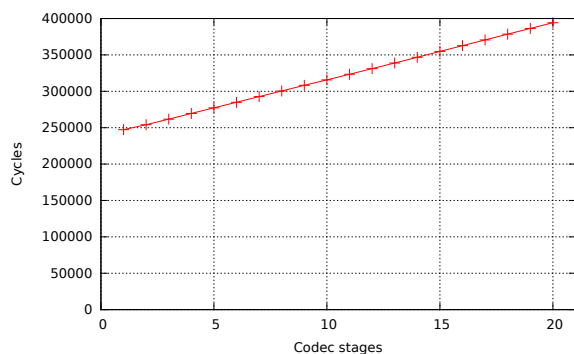


Figure 6: Number of cycles taken to execute the 222006 instructions of the test program of Table 2 against number of stages (cycles) taken up by the codec. Table 2 is constructed with a 10-stage codec.

add, subtract and compare in software:

mul. test	cycles	instructions
Rijndael	235037	141854
Paillier	457825	193887

To improve Paillier, several threads would have to run in the same pipeline. The lack of dependencies between instructions from different threads would allow them to pass each other when the other was blocked waiting for an instruction ahead to pass back data.

Results may be extrapolated for encryptions that take a different number of cycles/pipeline stages than the prototype’s default (10, for the Rijndael). Fig. 6 shows how long the test of Table 2 takes when the Rijndael implementation does encryption in from 1 to 20 cycles/stages. It is 2.5% slower per extra stage.

## 7 FUTURE WORK

We plan to model memory bus interactions more closely in order to optimise cache positioning. An ‘administrator’ mode will be added between supervisor and user mode to run encrypted with privileges for an encrypted operating system.

We are concerned by the weaknesses of homomorphic encryption in this setting and will investigate a scheme described in (Breuer and Bowen, 2014) in which the  $x$ ,  $y$ ,  $z$  in  $x+y=z$  (i.e., in two operand instructions) are required to be in slightly different encryptions, respectively A, B and C. The  $A+B=C$  arrangement is allowed, as is  $B+C=A$  and  $C+A=B$ , but anything else silently produces nonsense from the arithmetic unit in the processor. Thus the operator commanding  $x+x$  or  $x-x$  or  $x/x$  using an encrypted  $x$  observed in a user process as argument for one of the

two-operand machine code instructions (which contain no encrypted fields and hence can be assembled without knowing any secret), receives a nonsense result. But the legitimate user’s compiler can perfectly well generate code that satisfies the ABC constraints. For Paillier, powers of different blinding multipliers might be used for A, B, C.

## 8 CONCLUSION

The organisation of a sophisticated standards-compliant *superscalar* processor that ‘works encrypted’ for remote use has been described. It is based on the principle that a modified arithmetic automatically produces encrypted states and I/O. Data in memory, data in registers, and data and addresses on buses always exist in encrypted form, protecting against the privileges of the local administrator and operating system, who run unencrypted. The advance reported here is in how to turn the principle into a full-speed machine. Rijndael encryption (one codec embedded in the processor pipeline, not on the memory pathway) and Paillier partially homomorphic encryption (no codecs, no keys) have been tested. The Rijndael implementation is 60–70% as fast as unencrypted running<sup>2</sup> and is secured by guarantees in the hardware protocols that the administrator cannot see unencrypted user data, which renders it exactly as safe (or unsafe) as Paillier.

Conventional protections such as moat electronics, oblivious RAM, encrypting the memory address together with data, hashed program trace under the encryption, etc., may be added.

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