A review of the state of art in applying Biot theory to acoustic propagation through the bone

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Abstract:

Understanding the propagation of acoustic waves through a liquid-perfused porous solid framework such as cancellous bone is an important pre-requisite to improving the diagnosis of osteoporosis by ultrasound. In order to elucidate the propagation dependence upon the material and structural properties of cancellous bone, several theoretical models have been considered to date, with Biot-based models demonstrating greatest potential. This paper describes the fundamental basis of these models and reviews their performance.

I. Introduction

Understanding the propagation of acoustic waves through cancellous bone is an important prerequisite to improving the diagnosis of osteoporosis by ultrasound. Bone essentially has two types of structure, both having the same mineralised collagen composition. Cortical bone has porosity less than 30% and may generally be considered to be solid; cancellous bone has porosity greater than 30% and consists of a complex open-celled porous network of rod- and plate-shaped elements termed trabeculae. The porosity of human cancellous bone ranges between 70% and 95%, the remaining volume being perfused with bone marrow. In the adult human vertebral body for example, both horizontal and vertical trabeculae range from 50–120 μ m in thickness, and spaced at intervals of between 1200 – 5000 μ m and 700 and 2000 μ m respectively (Thomsen *et al* 2002).

Osteoporosis leads to nearly 9 million fractures annually worldwide (Johnell and Kanis 2006), and over 300,000 patients present with fragility fractures to hospitals in the UK each year (British Orthopaedic Association 2007). Direct medical costs from fragility fractures to the UK healthcare

economy were estimated at £1.8 billion in 2000, with the potential to increase to £2.2 billion by 2025, and with most of these costs relating to hip fracture care (Burge et al, 2001).

Two mechanisms give rise to the structure of bone, modelling and remodelling. 'Modelling' is the process primarily responsible for maintaining bones in their correct shape as they grow and respond to its biomechanical environment; it also controls the cortical thickness and marrow cavity diameter of bones as they age. 'Remodelling' is mainly concerned with the continual replacing of old cancellous bone and occurs at discrete foci on the surface of the trabeculae. During remodelling, osteoclast cells create a resorption cavity that is subsequently filled with new collagen by osteoblast cells. In osteoporosis, there is an asymptomatic negative imbalance in remodelling, thereby creating a bone loss, particularly at sites of predominantly cancellous bone such as the spine, hip, wrist, and heel; this ultimately leads to skeletal fragility and increased risk of fracture (Rosen 2004).

The conventional method of assessing osteoporosis in the clinical environment is bone mineral density (BMD, g cm⁻²), an areal parameter describing the bone mineral content (BMC) within a projected area. BMD is generally measured at sites most at risk of osteoporotic fracture, the spine, hip and wrist. BMD is generally measured using the technique of dual energy X-ray absorptiometry (DXA) (Njeh and Shepherd 2004). The body may be considered to consist of three tissue components: bone, lean and fat. By assuming a certain proportion of lean/fat tissue overlying a bone, the BMC may be derived by solving simultaneous attenuation equations for two X-ray energies. True volumetric bone density may be derived using quantitative computed tomography (QCT) utilising a conventional CT scanner, a calibration phantom being scanned with the subject to convert Hounsfield numbers into g cm⁻³ (Lang 2004). QCT is increasingly being used, particularly at the lumbar spine although there is a higher radiation dose compared to DXA. Although generally utilised as a research tool for the measurement of excised tissue samples obtained from the pelvis, microCT provides a typical spatial resolution of 0.01 mm and hence replicates the true trabecular structure, compared to resolutions of approximately 1 mm for both DXA and QCT. A technique that is gaining increasing interest is magnetic resonance imaging (MRI) which essentially measures the water content of tissues. Bone does not therefore give an MR signal, although its presence may be inferred from a 'negative' image (Pothuaud and Mujandar 2004).

Quantitative Ultrasound (QUS) generally involves measurements of the transmission of ultrasonic signals, either along a cortical bone surface or through a bone such as the heel and

phalanx (Njeh *et al* 1997). There are two fundamental measurement parameters, velocity (ms⁻¹) and attenuation (dB). Velocity is obtained by dividing the propagation distance by the corresponding transit time, with through-transmission measurements recorded at the calcaneus (heel) and phalanx, and surface-transmission recorded primarily at the tibia. Attenuation is generally expressed as Broadband Ultrasound Attenuation (BUA, dB MHz⁻¹) at the calcaneus, describing the linear increase in attenuation with frequency between 200 kHz and 600 kHz. It has been clinically demonstrated that velocity provides higher precision, expressed as CV% whereas BUA exhibits higher dynamic range. It is generally accepted that of the QUS options, BUA measurement at the calcaneus provides the most accurate indication of osteoporotic fracture risk, particularly for hip fracture. Due to technical limitations, ultrasound measurements cannot be performed routinely at the common anatomical sites affected by osteoporosis (spine, hip and wrist).

A fundamental relationship exists linking the velocity (v) of a sound wave to the elasticity (E) and density (ρ) of a material, namely $v = \sqrt{(E/\rho)}$ although the elasticity modulus used in the relationship is dependent upon the sound propagation mode; for example Bulk modulus + 4/3 of the Rigidity modulus for the longitudinal wave (), the rigidity modulus for the shear wave and the Young's modulus for the bar wave. Young's modulus is derived from mechanical testing and longitudinal velocity from ultrasound measurements (Njeh *et al* 1996). A similar fundamental relationship does not exist for BUA. It has been shown however that BUA follows a parabolic-type dependence on porosity having a minimum values corresponding to both solid bone (0% porosity) and marrow (100% porosity) (Hodgskinson *et al* 1996). Hence, similar BUA values may be obtained for a few marrow pores within a largely solid bone and a few bony trabeculae within a largely marrow sample. A parameter that follows a similar pattern is the surface area of the bone-marrow interface; associated with this, a linear relationship between BUA and fractal dimension has been demonstrated (Langton *et al* 1998).

Even though more than twenty years have passed since BUA was first described (Langton *et al* 1984), there remains a lack of a fundamental understanding of the dependence of ultrasound propagation, and BUA, in particular, upon the material and structural properties of cancellous bone. In order to elucidate these relationships, a number of theoretical approaches have been considered including scattering, simple mixtures, idealized microstructures, and Biot. Scattering is caused by sudden spatial changes in elastic properties, the magnitude being dependent on relative size of in-homogeneities and the ultrasound wavelength. Multiple Scattering may also be

considered, being a combination of the original and previously scattered waves. Boutin (2007) has combined rigid-porous theory and scattering to investigate the low frequency scattering of acoustic wave propagation in heterogeneous media made of air and motionless inclusions. It should be noted however that scattering theories are only valid for low concentrations of isolated inhomogeneity and are not generally applicable to the study of cancellous bone. The simple mixture theory expresses velocity in terms of bone volume fraction, density, and bulk modulus. Chernov's theory (1960) combines scattering and simple mixture theory via velocity fluctuations and scatterer size. Simple mixture theories have also had limited success for porous media such as cancellous bone. Two theories that are inherently applicable to the solid framework perfused with a visco-elastic fluid are the Schoenberg and Biot theories. Schoenberg's theory (1983, 1984, 1986) considers periodically alternating parallel solid-fluid layers but does not consider the viscous absorption. The theory predicts two compressional waves, often referred to as 'fast' and 'slow' respectively, when the waves propagating through the solid frame of bone and marrow are in-phase and out-of-phase respectively. The angular dependences of phase velocities for the fast and the slow waves in cancellous bone have been predicted (Hughes et al 1999), along with the anisotropic behaviour of acoustic wave propagation (Hughes et al 2007). Biot theory was specifically developed to describe acoustic wave propagation in fluid-saturated porous elastic media (Biot 1956a, 1956b); although originating for geophysical testing of porous rocks, it has been used extensively to describe the wave motion in cancellous bone. The Biot theory allows for an arbitrary microstructure, with separate motions considered for the solid elastic framework (bone) and the interspersed fluid (marrow), induced by the ultrasonic wave, and also includes energy loss due to viscous friction between solid (bone) and fluid (marrow). In addition to the two compressional waves predicted by Schoenberg's theory, the Biot theory also predicts a shear wave. McKelvie and Palmer (1991) were first to apply Biot theory to ultrasonic wave propagation in cancellous bone. Hosokawa and Otani (1997) first observed experimentally the two theoretically predicted compressional waves in cancellous bone at ultrasonic frequencies. The Biot model has since been used extensively to describe the wave motion in trabecular (cancellous) bone (Haire and Langton 1999, Fellah et al 2004, Sebaa et al 2006, Pulau et al 2008). Attenborough et al. (2005) presented tortuosities deduced from audio-frequency measurements in air-filled cancellous bone replicas and showed that there was strong anisotropy. The Biot theory has been further developed including semi-analytical approach that allows for transverse anisotropy in the frame elastic moduli, tortuosity and permeability for geophysical applications (Carcione 1996). A modified Biot-Attenborough (MBA) model has also been proposed for acoustic wave propagation in a non-rigid porous medium with circular cylindrical pores starting from a formulation for a rigid-framed porous material (Roh *et al* 2003, Attenborough 1982, Attenborough 1983). The MBA has been used to predict the dependences of velocity and attenuation on frequency and porosity in bovine cancellous bone (Lee *et al* 2003, Lee and Yoon 2006). The Biot model has also been modified to include the acoustic anisotropy of cancellous bone by introducing empirical angle-dependent parameters, and used to predict both the fast and slow wave velocities as a function of propagation angle with respect to the trabecular alignment of cancellous bone (Lee *et al* 2007).

Previous work on the influence of anisotropic pore structure and elasticity in cancellous bone has been extended by developing an anisotropic Biot–Allard model allowing for angle dependent tortuosity and elasticity by Aygün *et al.* 2009. The extreme angle dependence of tortuosity corresponding to the parallel plate microstructure used by Hughes *et al.* 2007 has been replaced by angle dependent tortuosity values based on data for slow wave transmission through air-filled bone replicas. Audio-frequency data obtained at audio-frequencies in air-filled bone replicas are used to derive an empirical expression for the angle-and porosity-dependence of tortuosity.

Most recently, Aygün *et al.* (2010 and 2011) have transmitted ultrasonic signals through water saturated stereolithograpical bone replicas. Predictions of a modified anisotropic Biot-Allard model, which neglects scattering have been compared to measurements made at normal and oblique incidence in a water filled tank at 100 kHz and 1 MHz. Remarkably, it is found that the expected occurrence of scattering does not cause significant discrepancies between predictions and data at 100 kHz (which would be equivalent to 1.3 MHz in real bone), perhaps as a consequence of the fact that the samples behave as low pass filters. Scattering should be even more important at 1 MHz (equivalent to 13 MHz in real bone) where the fast and slow wavelengths are 3 mm and 1.5 mm respectively. Nevertheless the modified Biot-Allard theory is found to predict the observed simple relationship between incident and transmitted waveforms at 1 MHz. Another effect of the structural anisotropy will be variation of permeability with direction.

II. The Biot Model

The Biot theory predicts the complex velocities of two compressional waves and a single shear wave, given by;

$$V_{fast, slow}^{2} = \frac{\Delta \pm \left[\Delta^{2} - 4(PR - Q^{2})(\rho_{11}\rho_{22} - \rho_{12}^{2})\right]^{2}}{2(\rho_{11}\rho_{22} - \rho_{12}^{2})}$$
(1)

$$V_{shear}^{2} = \frac{N}{(1 - \phi)\rho_{s} + (1 - 1/\alpha)\rho_{f}}$$
 (2)

where $\Delta = P\rho_{22} + R\rho_{11} - 2Q\rho_{12}$, PQR are generalized elastic constants, ρ_{11} , ρ_{22} , and ρ_{12} are mass coefficients which take into account the fact that the relative fluid flow through the pores is not uniform, ρ_s is the mass density of the solid, ρ_f is the mass density of the fluid, and α is the tortuosity of the medium. The elastic constants are given by;

$$P = \frac{(1 - \phi)\left(1 - \phi - \frac{K_b}{K_s}\right)K_s + \phi \frac{K_s}{K_f}K_b}{1 - \phi + \phi \frac{K_s}{K_f} - \frac{K_b}{K_s}} + \frac{4N}{3}$$
(3)

$$Q = \frac{\left(1 - \phi - \frac{K_b}{K_s}\right) \phi K_s}{1 - \phi + \phi \frac{K_s}{K_f} - \frac{K_b}{K_s}}$$

$$\tag{4}$$

$$R = \frac{\phi^2 K_s}{1 - \phi + \phi \frac{K_s}{K_f} - \frac{K_b}{K_s}}$$
 (5)

where K_b , K_f , and K_s are the bulk module of skeletal frame, fluid, and solid, respectively; N is the shear modulus and ϕ is the porosity.

The bulk modulus of the skeletal frame (K_b) and the bulk modulus of the solid (K_s) are given by;

$$K_b = \frac{E_b}{3(1 - 2\nu_b)}$$
 $K_s = \frac{E_s}{3(1 - 2\nu_s)}$ (6)

where v_b and v_s are the Poisson's ratio of the skeletal frame and the solid, respectively, E_b is the Young's modulus of the skeletal frame given by $E_b = E_s (1-\phi)^n$, where E_s is the Young's modulus of the solid, and n depends on the alignment of the structure (Gibson 1985).

The total mass of the fluid-solid aggregate per unit volume is given by $\rho = \rho_{11} + 2\rho_{12} + \rho_{22}$. The coefficient ρ_{12} represents a mass coupling parameter between fluid and solid, ρ_{11} represents the

total effective mass of the solid moving in the fluid, and ρ_{22} depends on the geometry of the frame not on the viscosity of the fluid [Biot 1956]. The mass coefficients may be written

$$\rho_{11} = \rho_1 + \rho_a \tag{7}$$

$$\rho_{22} = \rho_2 + \rho_a \tag{8}$$

$$\rho_{12} = -\rho_f \phi(\alpha - 1) \tag{9}$$

where ρ_a is the inertial coupling term given by $\rho_a = -\rho_{12}$, ρ_1 is the mass of solid per unit volume of aggregate given by $\rho_1 = (1-\phi)\rho_s$, and ρ_2 is the mass of fluid per unit volume of aggregate given by $\rho_2 = \phi \rho_f$.

Johnson et al. (1987) have presented the dynamic tortuosity as;

$$\alpha(\omega) = \alpha_{\infty} \left(1 + \frac{\eta \phi}{j \omega \alpha_{\infty} \rho_f k_0} \sqrt{1 + j \frac{4\alpha_{\infty}^2 k_0^2 \rho_f \omega}{\eta \Lambda^2 \phi^2}} \right)$$
 (10)

where α_{∞} is the tortuosity, Λ is the viscous characteristic length, η is the viscosity, and k_0 is the permeability.

Biot theory considers the material to be isotropic, although tortuosities deduced from audio-frequency measurements in air-filled bone replicas, assuming rigid-porous behaviour, have shown a strong anisotropy Hughes *et al.* (1999) have stated that there has been a consistent discrepancy between measured and predicted attenuation. It should be noted also that Biot theory does not include thermal effects. When the saturating fluid is air rather than a liquid, thermal effects become important and a further modification of the Biot theory is necessary.

III. The Biot-Attenborough Model

The Modified Biot-Attenborough (MBA) model was developed to consider acoustic wave propagation in a non-rigid porous medium with circular cylindrical pores (Roh *et al* 2003). The formulation starts from Attenborough's model (1982) which is concerned with rigid-framed media and, therefore, does not include the fast wave of the Biot theory, and treats the viscous and thermal effects in a separate manner. A non-rigid structure is then allowed for by introducing an additional parameter and boundary condition. A similar formulation to the MBA model has been employed (Lee *et al* 2006) with three new phenomenological parameters, namely: the boundary condition, phase velocity, and impedance parameters. An idealised microstructure was assumed consisting of circular cylindrical pores and considered one-dimensional sound propagation along with the axes of the cylinders.

The continuity equation of one-dimensional acoustic wave propagation through a single circular cylindrical pore filled with fluid is given by;

$$-\rho_f \frac{\partial \langle v \rangle}{\partial x} = \frac{\partial \rho}{\partial t},\tag{11}$$

where $\langle \upsilon \rangle$ is the averaged particle velocity over the pore cross section for propagation in the x direction, which is taken to be the direction normal to the surface of the model porous medium. The equation of motion is given by;

$$\frac{\partial p}{\partial x} \rho_c(\omega) \frac{\partial \langle v \rangle}{\partial t} \tag{12}$$

where p is the acoustic pressure, ω is the angular frequency, and $\rho_c(\omega)$ is the frequency-dependent density given by

$$\rho_c(\omega) = \rho_f \left[1 - 2(\lambda \sqrt{i})^{-1} T(\lambda \sqrt{i}) \right]^{-1}$$
(13)

where

$$T(\lambda\sqrt{i}) = \frac{J_1(\lambda\sqrt{i})}{J_0(\lambda\sqrt{i})} \tag{14}$$

 $i = \sqrt{-1}$, J_0 and J_1 are the cylindrical Bessel functions of the zeroth and the first order, respectively, and λ is the dimensionless parameter related to the thickness of the viscous boundary layer at a pore wall and given by $\lambda = am_1(\omega/\nu)^{1/2}$ where a is the radius of the circular cylindrical pore, m_1 is a boundary condition parameter allowing for non-rigidity of the pore frame, and ν is the kinematic viscosity of the fluid.

The frequency-dependent compressibility of the fluid within a pore of arbitrary (but constant) cross section is given by;

$$C_c(\omega) = \left(\frac{1}{\rho_f}\right) \left(\frac{d\rho_c}{dp}\right) = \left(\rho_f c_f^2\right)^{-1} \left[1 + 2(\gamma - 1)x \left(N_{\text{Pr}}^{1/2} \lambda \sqrt{i}\right)^{-1} T \left(N_{\text{Pr}}^{1/2} \lambda \sqrt{i}\right)\right]$$
(15)

where γ is the specific heat ratio of the fluid, N_{Pr} is the Prandtl number, and c_{f} is the equilibrium sound velocity of the fluid.

When the analysis, based on the sound propagation through a single circular cylindrical pore, is extended to a bulk non-rigid porous medium, the complex propagation constants of the fast and slow waves are given, respectively, by;

$$k_{fast} = \alpha_{\infty} k_{s} \sqrt{\frac{1}{(1 - \phi)^{m_{2}} + \phi^{m_{2}} (k_{s} / k_{c})^{2}}}$$
 (16)

$$k_{slow} = \alpha_{\infty} k_g \sqrt{\frac{1}{(1 - \phi)^{m_2} + \phi^{m_2} (k_g / k_c)^2}},$$
(17)

where k_s is the propagation constant of the pore frame given by $k_s = \omega/c_s$ where c_s is the pore frame velocity, k_c is the propagation constant of the fluid in the pore given by $k_c = \omega C_c(\omega) \rho_c(\omega)$, k_s is the wave number of a hypothetical fluid with an extremely low wave velocity, and m_2 is a phase velocity fitting parameter.

The phase velocities and attenuation coefficients of the fast and slow waves can be obtained from the real and imaginary part of the complex propagation constant of the fast and slow waves respectively.

IV. The Schoenberg Model

The Schoenberg model considers periodically alternating parallel solid-fluid layers, assuming that the viscous skin depth is much less than the fluid layer thickness when the fluid layer is ideal. Schoenberg has expressed acoustic wave propagation in terms of slowness vector given by $\mathbf{s} = (s_1, s_2, s_3)$. The components of the slowness vector parallel to the layers, s_1 , and normal to the layers, s_3 , are related by;

$$\frac{s_3^2}{\langle \rho \rangle} - \left[\frac{\phi(V_f^{-2} - s_1^2)}{\rho_f} + \frac{(1 - \phi)(V_s^{-2} - s_1^2)}{\rho_s (1 - V_{pl}^2 s_1^2)} \right] = 0$$
 (18)

where $V_{\rm f}$ is the sound speed of the fluid, $V_{\rm s}$ is the compressional speed of the solid, $<\rho>$ is given by $<\rho>=\phi\rho_{\rm f}+(1-\phi).\rho_{\rm s}$, $V_{\rm pl}$ is the plate velocity given by;

$$V_{pl}^2 = 4V_{sh}^2 \left(1 - \frac{V_{sh}^2}{s^2} \right) \tag{19}$$

where $V_{\rm sh}$ is the shear speed of the solid.

The phase velocity can be found from the inverse of the magnitude of the vector, $(|s|^{-1} = 1/(s_1^2 + s_3^2)^{1/2})$ and the propagation angle with respect to the layering $(\theta = \tan^{-1}(s_3/s_1))$. Schoenberg's theory predicts two compressional waves equivalent to the acoustic waves propagating through

the solid frame and fluid being in-phase and out-of-phase respectively. Inertial coupling varies with propagation angle relative to the stratification. For propagation parallel to the layers, inertial coupling is zero, and waves may propagate in the fluid and solid independently (Hughes *et al* 1999).

V. The Anisotropic Biot – Hughes Model

The Anisotropic Biot model incorporates viscous effects and anisotropic effects into the Biot model in a simple and straightforward manner (Hughes *et al* 2007), assuming that the degree of inertial coupling within Schoenberg's layers are equivalent to that occurring in an arbitrary anisotropic porous medium as described by the Biot's theory. An angle dependent tortuosity was introduced to describe a layered structure in the Biot's theory, from which the angle dependant tortuosity may be obtained by equating the compressional phase velocity in terms of α from the Biot's theory [Eqs. (1)], with that from Schoenberg's model in terms of propagation angle, θ , [Eqs. (18) and (19)]. Shear in the solid is neglected.

 $(K_b = N = 0 \text{ and } PR - Q^2 = 0)$. The tortuosity was found from

$$\alpha(\theta) = 1 + \left[\frac{(1 - \phi)\rho_s}{\langle \rho \rangle} \right] \cot^2 \theta \tag{20}$$

The angle-dependent tortuosity given by Eq. (20) should be substituted for α_{∞} to predict wave properties that change with orientation. Hughes *et al.* have observed a significant discrepancy, for predictions of the dependence of the fast wave speed on angle, between the Stratified Biot model and Schoenberg's theory, disagreeing by almost 50% at 0° . They have also stated that the Stratified Biot model gives poorer agreement with slow wave data than the Schoenberg model, both quantitatively and in the curvature of its angular variation.

VI. The Anisotropic Biot – Attenborough Model

Aygün *et al.* (2009) have combined the heuristic form of angle-dependent elasticity suggested by Lee *et al.* (2007) in Biot-Allard theory with a heuristic angle and porosity dependent tortuosity function based on data obtained at audio frequencies with air-filled (human) bone replicas by Attenborough *et al.* (2005). The heuristic form for porosity and angle dependent tortuosity may be written:

$$\alpha_{\infty} = 1 - r \left(1 - \frac{1}{\phi} \right) + k \cos^2(\theta) \tag{21}$$

where r and k can be considered adjustable.

The assumed angle dependence function is chosen arbitrarily but is simple and consistent with the expected variation in fast wave speed with angle. A range of possible values of r and k have been found by comparing predictions of equation (21) for $\theta = 0^{\circ}$ and 90° respectively with values deduced from air-filled replica bones (Attenborough *et al.* (2005)) of known porosity. Values of r and k are found by solving the resulting simultaneous equations. The value of r is predicted to have important influence on the fast wave speed variation with porosity perpendicular to the dominant structural orientation and on the slow wave speed variation with porosity parallel to the dominant structural orientation.

Aygün et al. [2010] have reported measurements of ultrasonic transmission made through watersaturated bone replicas at 100 kHz and 1 MHz. The resulting data are compared with predictions of a modified Biot-Allard model with anisotropic angle-and-porosity dependent tortuosity, and angle-dependent elasticity. Transmitted signals for water saturated stereolithograpical bone replicas have been predicted by modified anisotropic Biot-Allard model, which neglects scattering, and the results have been compared to measurements made in a water filled tank at 100 kHz and 1 MHz. The wavelengths of the slow and fast wave in water-saturated STL bone replicas at 100 kHz are 15 mm and 30 mm, respectively. These wavelengths are comparable with the dimensions of microstructural elements of STL bone replicas. According to Williams (1992), the pore sizes in cancellous bone vary between 0.5 and 1 mm, so typical trabeculae widths in the replicas vary between 6.5 and 13 mm. Remarkably, scattering seems not to cause significant discrepancies between predictions and data at 100 kHz (which would be equivalent to 1.3 MHz in real bone), perhaps as a consequence of the fact that the samples behave as low pass filters. Scattering should be more important at 1 MHz (equivalent to 13 MHz in real bone) where the fast and slow wavelengths are 3 mm and 1.5 mm respectively. So the agreement between predictions and data is rather surprising. These data and predictions support further use of Biot-based theories and of STL replicas for studying ultrasonic transmission through bone.

Aygün *et al.* (2011) have investigated further ultrasonic wave transmission in water-saturated bone replicas at 1 MHz as a function of angle. The predictions of the anisotropic Biot-Allard model allowing for angle-dependent elasticity and angle-and-porosity dependent tortuosity have been compared with measurements of pulses centered on 1 MHz transmitted through water saturated stereo-lithographical (STL) bone replicas which are thirteen times larger than the

original bone samples at normal and oblique angles. The predictions and data are in reasonable agreement despite the expected role of scattering.

VII. Discussion

Although Schoenberg's theory predicts two compressional waves equivalent to the wave of the first kind and the wave of the second kind of Biot's theory, it does not predict the shear wave of the Biot's theory. Schoenberg's theory does not consider the fluid viscosity, and thermal effects, and consequently, it is not possible to use Schoenberg's theory to predict wave attenuation or to make comparisons with the absorption predicted by Biot theory. The anisotropic behaviour of acoustic wave propagation in cancellous bone using the Schoenberg theory has been investigated, Hughes *et al* (1999) stating that the inclusion of viscosity in the Biot's theory gives no significant advantage in respect of agreement with experimental findings, and that the omission of the viscosity in Schoenberg's model prevents it from accounting for viscous absorption and confines its application to Biot's "high" frequency region (Hughes *et al* (2007).

Both the velocity and attenuation of sound as predicted by the Biot theory are dependent on frequency, the elastic properties of the constituent materials, porosity, permeability, tortuosity, and effective stress. The original Biot formulation introduced a frequency-independent pore shape parameter. In a subsequent refinement, the frequency-dependent viscous effects due to relative motion of fluid and solid in the porous medium are predicted to depend on a viscous characteristic length (Johnson et al 1987). This is dominated by the smallest pore cross sections and is difficult to measure. When the saturating fluid is air rather than a liquid, thermal effects become important and a further modification of the Biot theory is necessary since the original formulation does not include them. Such a modification, which has been used mainly when modelling the acoustical properties of air-filled porous materials, used in building acoustics and engineering acoustics, introduces a thermal characteristic length (Allard 1993). Twice the inverse of thermal characteristic length represents the pore surface area per unit volume. In materials that are not affected by water saturation, this can be measured by a water suction method (Leclaire et al 1998). For many materials the thermal characteristic length is approximately twice the viscous characteristic length. The inclusion of the thermal characteristic length is relevant to comparison of predictions with high frequency data obtained from air-saturated bone replicas. During acoustic excitation (e.g. from a loudspeaker) of an air-filled porous solid most of the acoustic energy travels in the pores and the acoustical properties are described well by assuming that the solid frame is rigid. On the other hand intimate mechanical contact between a transducer and a porous elastic medium excites waves predominantly in the solid frame. Fellah *et al.* (2004) have presented an analytical model of the reflection and transmission coefficient of a slab of cancellous bone with an elastic frame based on the Biot theory modified by Johnson *et al.* (1987) to describe the viscous interaction between fluid and structure. By comparing predictions with laboratory data on ultrasonic pulse transmission through water-filled samples of human cancellous bone, Fellah *et al.* (2004) have concluded that the modified Biot theory using Johnson *et al.* model is suitable for describing the propagation of ultrasonic wave in cancellous bone. A significant attraction of the Biot theory is that it includes structurally dependent parameters including permeability and tortuosity as well as the elastic constants of the porous frame and frame material (Allard 1993). An important limitation of the Biot theory is that it requires that the acoustic wavelengths to be large compared with the microstructural features (such pores and trabeculae in cancellous bone). Another difficulty with the Biot theory is that it requires knowledge of many parameters, some of which are hard to determine.

The inherent anisotropy of cancellous bone means that the acoustical properties vary with transmission direction. Tortuosities deduced from audio-frequency measurements in air-filled bone replicas, assuming rigid-porous behaviour, have shown a strong anisotropy (Haire and Langton 1999). To predict fast wave transmission it is necessary to allow for elastic anisotropy also. The trabeculae in cancellous bone suggest transverse anisotropy: an idealized version of which, for example, is parallel plates (Hughes *et al* 1999). A method of including the effects of anisotropy in the Biot theory (Hughes *et al* 2007) introduces an angle dependent tortuosity, based on the parallel plate idealization of the microstructure, and a heuristic angle dependent Young's modulus. However the approach of Hughes *et al*. (2007) did not yield particularly good predictions of the angle dependence of fast wave speeds.

Lee *et al* (2007) have stated that the MBA model predicts a slightly negative dispersion of phase velocity linearly with frequency and the nonlinear relationships of attenuation and BUA with porosity. The experimental results presented by Lee *et al.* are in good agreement with the theoretical results estimated with the MBA model.

The anisotropic pore structure and elasticity of cancellous bone cause wave speeds and attenuation in cancellous bone to vary with angle. Aygün *et al.* (2009) have extended previous work on the influence of anisotropic pore structure and elasticity in cancellous bone by developing an anisotropic Biot-Allard model allowing for angle-dependent elasticity, and angle-and-porosity dependent tortuosity. The extreme angle dependence of tortuosity corresponding to

the parallel plate microstructure used by Hughes *et al.* (2007) has been replaced by angle-and-porosity dependent tortuosity values based on data for slow wave transmission through air-filled stereolithography (STL) bone replicas Aygün *et al.* (2010). It has been suggested that the anisotropic Biot-Allard model could be used to give further insight into the factors that have the most important influence on the angle dependency of wave speeds and attenuation in cancellous bone. Nevertheless the applicability of Biot-based theories to ultrasonic propagation in bone remains in question given the expected role of scattering which is neglected in the these theories.

Predictions of a modified anisotropic Biot-Allard theory by Aygün *et al.* (2011) have been compared with measurements of pulses centered on 1 MHz transmitted through water saturated stereo-lithographical (STL) bone replicas which are thirteen times larger than the original bone samples at normal and oblique angles. The predictions and data are in reasonable agreement despite the expected role of scattering.

The likely ranges of validity for Biot modelling approaches can be discussed in terms of the ratio $(\varepsilon = l/L)$ of a characteristic inhomogeneity size (l) and the reduced sound wavelength $L = \lambda/2\pi$ (λ). Scattering is likely to be significant for values of ε greater than 1 whereas Biot theory was derived for values of ε that are significantly less than 1. At 1 MHz the fast and slow wavelengths are 3 mm and 1.5 mm respectively. For the fast waves the values of the ratios, ε , in FRA and CAB replicas are 0.1257 and 0.3142 respectively, and for the slow waves the values are 0.2513 and 0.6283. These indicate clearly that scattering should be significant so the agreement between Biot-based predictions and data at 1 MHz is rather surprising.

VIII. Conclusions and Further Work

Several models being used for acoustic wave propagation in cancellous bone have been presented and reviewed. Of these, the various forms of Biot theory have shown some promise. That by Fellah *et al.* (2004), has been found to give excellent agreement with data obtained from transmitting ultrasonic pulses through water-filled samples of human cancellous bone. Using another version of Biot theory, Lee *et al.* (2007) have observed that the phase velocity is approximately non-dispersive and the attenuation coefficient linearly increases with frequency. Lee *et al.* (2003) also stated that the experimental results are in good agreement with the theoretical results estimated with the MBA model which predicts a slightly negative linear dispersion of phase velocity with frequency and the nonlinear relationships of attenuation and BUA with porosity. On the other hand, Haiat *et al.* (2008) have stated that scattering effects are

responsible for the negative values of dispersion whereas the frequency dependence of the attenuation coefficient in bone marrow and/or in the trabecular is shown to induce an increase in the dispersion. The existence of the trabeculae in cancellous bone means that it has transverse anisotropy. The inherent anisotropy of cancellous bone means that the acoustical properties vary with transmission direction (Attenborough *et al* 2005). To predict fast wave transmission it is necessary to allow for elastic anisotropy also. Although Hughes *et al*. (2007) have presented a method of including the effects of anisotropy in Biot theory introducing an angle dependent tortuosity, based on the parallel plate idealization of the microstructure, and a heuristic angle dependent Young's modulus their approach did not yield particularly good predictions of the angle dependence of fast wave speeds and another effect of the structural anisotropy will be variation of permeability with direction.

Aygün *et al.* (2010) has stated that the use of stereolithograpical bone replicas made from resin has the potential to enable systematic investigations of the influences of perforation and thinning in cancellous bone on the acoustical and mechanical properties of the bone structure. Waves transmitted through STL bone replicas with higher porosity values have higher amplitudes. Osteoporotic bones will have higher porosity values due to bone loss, so greater energy will be transmitted through them in comparison with normal bone.

Another consequence of using replica bones which are 13 times the actual size of the bone microstructure is that scattering should become important at lower frequencies than in measurements with real bone samples.

The predictions of the anisotropic Biot-Allard model allowing for angle-dependent elasticity and angle-and-porosity dependent tortuosity have been compared with measurements made in a fluid (water) filled tank at 1 MHz by Aygün *et al.* (2011). It is found that predictions of the variation of transmitted waveforms with angle through two types of bone replica are in reasonable agreement with data despite the fact that scattering is not included in the theory.

A Finite Element Models (FEM), preferably an anisotropic Biot-based model modified by Aygün *et al*, (2010 and 2011), for cancellous bone should be developed. This would enable modelling of complete bone structures which would be more appropriate to the context of clinical monitoring. Such models of the acoustical properties of complex arrangements of anisotropic porous and elastic media are used increasingly in engineering studies, for example those related

to the acoustical design of vehicle interiors (Atalla *et al* (1997), Gorog *et al* (1997), Hörlin *et al* (2001), and Panneton *et al* (1998)).

Boutin (2007) has discussed a general multiple-scale approach that allows for scattering and visco-thermal effects in a rigid-porous medium and has considered a specific application to a parallel plate medium. However, the development of model capable of covering both viscous and scattering regimes and applicable to an anisotropic poroelastic medium remains a formidable challenge.

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