Late Breaking Results: A Fast Simulation Method Using SPH and Wavelet for Turbulent Flow

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ABSTRACT

We present a fast simulation method for turbulent flow using a particle method and a wavelet analysis. Our method uses Smoothed Particle Hydrodynamics to simulate fluid flow which discretized the fluid as a collection of many particles and detects the region where the turbulent flow will take place by using the wavelet analysis without a spacial grid. The turbulent flow is calculated as a divergence-free velocity field based on a wavelet noise. In addition, we achieve real-time computation using GPU.

Index Terms: I.3.7 [Computer Graphics]: Three-Dimensional Graphics and Realism—Animation;

1 INTRODUCTION

Fluid simulation is widely being used to make very complex fluid phenomena for CG animation. However, most method developed previously targeted a laminar flow which the fluid moves in a regular way. On the other hand, a turbulent flow is unsteady, irregular, and chaotic flow. We can observe the turbulent flow in our everyday surroundings, for example, smokes from a chimney, water in a river, waterfall and big ocean wave.

For computer graphics, there are some method to incorporate the turbulence into the existing simulations because the turbulent flow is very important to enhance the visual quality of fluid animations. In these method, the average flow that has low-frequency characteristics is calculated by solving the Navie-Stokes equations on a grid, and the small detail of turbulence is generated by predicting the energy of vortex[3] or by advecting the vortices[4] that was manualy added. The most simulation method for a turbulent flow tend to be time consuming task, while the chaotic aspect of turbulence make the simulation difficult.

We propose a fast simulation method for the turbulent flow using Smoothed Particle Hydrodynamics(SPH) and a wavelet analysis based on particles. The method just uses the particles to calculate the energy spectrum of the vortex and then we generate the turbulent velocity field based on a wavelet noise. We also make use of graphics hardware to perform the simulation on real-time.

2 RELATED WORKS

Stam[5] developed a stable solver that uses semi-Lagrangian advection method and it is widely used in computer graphics leterature. Although the method allows us to use the large timestep width, it has a problem of numerical diffusion. The numerical diffusion induces a dissipation of turbulence energy. Selle et al.[4] proposed a vortex particle method. The vortex particle moves based on the vorticity form of Navier-Stokes equations and it transports turbulent energy which is resolved on the grid. By using the wavelet analysis, Kim et al.[2] determined the region we want to disturb the flow. They simulated the velocity field with the low resolution grid based

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on the Navier-Stokes equations and synthesize the high resolution turbulence field using the wavelet noise. They made the realistic animation, but the method is restricted for gas that doesn't have explicit surface and the computational cost is too large to perform on real-time. We extended their method to the particle based simulation for turbulent liquid animation and achieved real-time computation using GPU.

3 SIMULATION METHOD

In this section, we present our method for simulating turbulence flow.

3.1 Fluid Simulation

We adopt the SPH method for fluid simulation. The govering equations for incompressible viscous fluid are given by :

$$\frac{\partial u}{\partial t} + (u \cdot \nabla)u = \nu \nabla^2 u - \frac{1}{\rho}\nabla p + f \tag{1}$$

where u, ρ, p is the velocity, density and pressure of the fluid respectively, ν is the kinematic viscosity, f is the resultant force of gravity and the external forces. The above equations are called Navier-Stokes equations. The particle method, which is a technique of representing liquid by many particles, is used to descretize the Navier-Stokes equations and the SPH method is used to solve the equations.

A scalar quantity ϕ is desided by a weighted sum of neighbor partilces.

$$\phi(x) = \sum_{j \in N} m_j \frac{\phi_j}{\rho_j} W(x_j - x, h) \tag{2}$$

where, N is the number of neighbor particles, m is the mass of particle, ρ is the density and the function W is the smoothing kernel with effective radius h. We use a grid cells with the width h to reduce the computational complexity of neighborhood particles detection. The paritcles are stored in the grid and we only search in the own cell and the neighborhood cells. All the procedure of neighborhood search and the computation of the term of Eq.1 are implemented on Graphics Hardware using NVIDIA CUDA for fast and parallel computation.

3.2 Wavelet Analysis based on Particle

We generate the turbulent velocity field that consist of a collection of small-scale vortices based on Kolgomorov's law while the small vortices are being lost by numerical diffusion or Nyquist limit. Forward scattering, which is a phenomenon that the large vortex split into two small vortex according to the enegy distribution of Kolmogorov's five-third spectrum, has to be reproduced to make the small-scale vortices. The vortex energy $\hat{e}$ is evaluated by the spectral comporment of velocity field $\hat{u}$ in spectral band k:

$$\hat{e}(k) = \frac{1}{2}|\hat{u}(k)|^2. \tag{3}$$

In order to detect the place where the turbulent will take place, we need to consider both spatial and frequency distribution of the energy (i.e. $\hat{e}(k, x)$). Therefore, we use a wavelet transform similar to

[2] but we extend it for the particle method. In the particle method, there is no grid that can explicitly define the neighborhood value. It is possible to define a background grid which has the projected particle velocity field and use it to calculate the wavelet transform. However, to use the another grid with almost some resolution to the particle density will increase the memory usage and computational time and it also would cause the numerical diffusion during the projection. Instead, we directly determine the wavelet transform of the velocity field $\hat{u} = (\hat{u}, \hat{v}, \hat{w})$ and the energy spectrum $\hat{e}(1/s, x)$ at a scale s by a weighted sum of neighborhood particles as well as SPH method.

The discrete wavelet transform of the velocity u_i of the particle i is

$$\hat{u}_i = \frac{1}{\sqrt{s}\psi_{sum}} \sum_j u_j \psi \left(\frac{x_i - x_j}{s}, \frac{y_i - y_j}{s}, \frac{z_i - z_j}{s} \right). \quad (4)$$

where s is the scale of wavelet, ψ is the mother wavelet and ψ_{sum} is determined by

$$\psi_{sum} = \sum_j \psi. \quad (5)$$

The number of around cell is constant if we use a grid or pixel. In case of particle method, the number of neighborhood particles varys according to position and time. The absolute value of wavelet transform tends to be large near the surface of liquid because there are only small number of particles and the influence of a particle will be large. In order to prevent this, we introduce the ψ_{sum} to normalize the value. The energy of vortex $e_i(k)$ can be calculated by substituting $\hat{u}$ to Eq.3.

3.3 Wavelet Turbulence Synthesis

To synthesize small vortices from the energy spectrum, we use a divergence-free velocity field $w(x)$ calculated from a curl of the wavelet noise[1]. The calculation of the wavelet noise is fast enough to run it real-time, but the calculation of the turbulent noise that includes the noises with multiple band takes high computational cost. Therefore, we parallelize the noise generation using GPU. The wavelet turbulence function based on Kolgomorov's theory is

$$y(x) = \sum_{i=i_{min}}^{i_{max}} w(2^i x) 2^{-\frac{5}{6}(i - i_{min})}, \quad (6)$$

where $[i_{min}, i_{max}]$ is the band width of spectrum. i_{max} can be the resolution that the width is same to the particle diameter, because we want to generate the particle-scale turbulence. i_{min} is determined based on the wavelet scale s.

The turbulent force from the energy $\hat{e}_i(k)$ and the wavelet function is

$$f_i^{turb} = A \frac{\rho_i}{\Delta t} \hat{e}_i(k) y(x_i) \quad (7)$$

where A is the user control parameter to change the scale of turbulence. The method easily extended to another particle method, e.g. MPS method, because we simply add the turbulence field as a external force.

4 RESULTS

This section describes the results of our method. All results were made on a computer equipped with a 2.93GHz Intel Core i7 Duo CPU and a NVIDIA GeForce GTX480 GPU. The most of our algorithm was implemented on GPU by using NVIDIA CUDA and we used the Mexican hat as the mother wavelet.

Figure 1 show the result of river in the valley. The fluid flows along to the valley. Since our method can simulate the turbulence, the flow is disturbed. The total number of fluid particles in the scene is about 40,000. The computation time for the simulation was about 15 msec per frame. The calculation of the energy spectrum and the wavelet turbulence requires about 70% of the simulation. We used

marching cubes method to construct the liquid surface mesh and it only took about 15 msec per frame with at most 80k triangles, while we also implemented the marching cubes on GPU.

5 CONCLUSIONS

We have presented a method to simulate turbulent flow using SPH method and a wavelet analysis. Our method directly calculates the turbulent energy by taking a weighted sum of neighborhood particles and adds the turbulence field as a external force. This enables fast simulations that includes various turbulent flow. In addition, we synthesize small vortices, which are dissipated by numerical diffusion, from the energy spectrum using a wavelet turbulent noise based on Kolgomorov's theory. Moreover, we perform the simulation in real-time by using GPU.

There are many directions for future work. We would like to extend the method to handle more small scale turbulent flow by using sub-particles or modifying the surface mesh based on wave equation. For realistic rendering, a bubble, foam and splash are also very important. We will be able to generate these effects based on the turbulence energy.
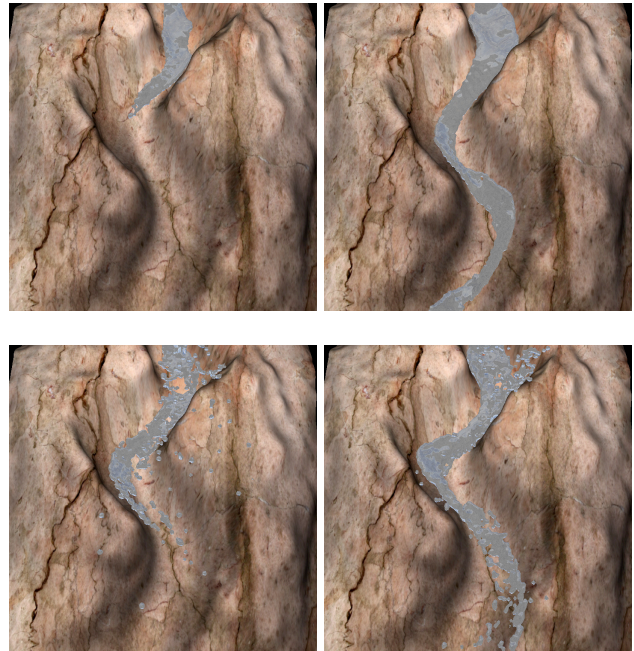

Figure 1: Water flows in the valley without turbulence (top), and with turbulence (bottom)

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