Complete 5-years time series of combined monthly gravity field models derived from Swarm GPS data

EGU2019-13412 - Session G4.1 - 11 April 2019

Pieter Visser⁽¹⁾, João de Teixeira da Encarnação^(2,1), Eelco Doornbos⁽¹⁾, Jose van den IJssel⁽¹⁾, Xinyuan Mao⁽¹⁾, Elisabetta Iorfida⁽¹⁾, Daniel Arnold⁽³⁾, Adrian Jäggi⁽³⁾, **Ulrich Meyer**⁽³⁾, Aleš Bezděk⁽⁴⁾, Josef Sebera⁽⁴⁾, Jaroslav Klokočník⁽⁴⁾, Matthias Ellmer⁽⁵⁾, Torsten Mayer-Gürr⁽⁵⁾, Sandro Krauss⁽⁵⁾, Junyi Guo⁽⁶⁾, Chaoyang Zhang⁽⁶⁾, C.K. Shum⁽⁶⁾, and Yu Zhang⁽⁶⁾

(1) Faculty of Aerospace Engineering of the Delft University of Technology, Delft, The Netherlands, (2) Center for Space Research, University of Texas at Austin, Austin, United States, (3) Astronomical Institute of the University of Bern, Bern, Switzerland, (4) Astronomical Institute of the Czech Academy of Sciences, Ondrejov, Czech Republic, (5) Institute of Geodesy of the Graz University of Technology, Graz, Austria, (6) School of Earth Sciences, The Ohio State University, Columbus, Ohio, USA

















Multi-approach gravity field models from Swarm GPS data

- ESA/DISC funded project (since 9/2017)
- Provide highest-quality monthly-independent Swarm gravity field models
- Combine individual gravity solutions, computed with:
 - different kinematic orbit solutions
 - different inversion approaches
- Monthly combined Swarm gravity field models:
 - from Dec. 2013 to Sept. 2018
 - available from:
 - ICGEM (http://icgem.gfz-potsdam.de/series)
 - ESA (https://earth.esa.int/web/guest/swarm/data-access,















Kinematic orbit solutions

- TU Delft: **GPS High precision Orbit determination Software Tool** (GHOST) Helleputte (2004); Wermuth et al. 2010
- AIUB: Bernese v5.3 Dach et al., (2015); Jäggi et al. (2007)
- IfG: Gravity Recovery Object Oriented Programming System (GROOPS) Zehentner et al. (2016)

















Gravity field estimation approaches

- AIUB: Celestial Mechanics Approach (CMA), Beutler et al. (2010)
- ASU: **Decorrelated Acceleration Approach** (DAA), Bezdek et al. (2014); Bezdek et al. (2016)
- IfG: Short-Arc Approach (SAA), Mayer-Gürr (2006)
- OSU: Improved Energy Balance Approach (IEBA), Shang et al. (2015)

















Combination of individual gravity field solutions

- Combination at the level of solutions, up do degree 40
- Weights derived from Variance Component Estimation (VCE)
- Degrees 2-20 considered in VCE
- Combination at the level of Normal Equations was tested but has slightly larger discrepancies w.r.t. GRACE (not shown)

















Gravity field model pre-processing

- Truncation to degree 40
- C₂₀ replaced with value from GRACE Technical Note 11
- Temporal variations relative to static GGM05G (GRACE and GOCE)
- Gaussian smoothing with 750-km radius (unless noted)
- GRACE CSR RL06 considered (with same pre-processing)
- GRACE and Swarm solutions interpolated to the union of both time domains (identical for all scenarios)









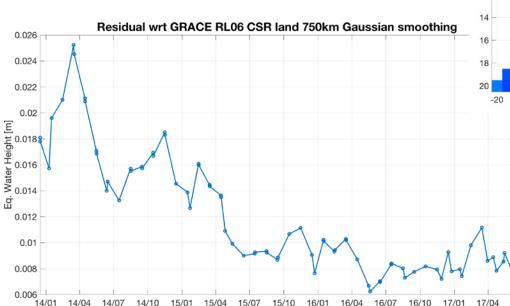


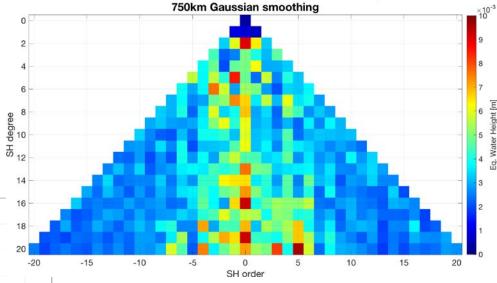






Agreement with **GRACE** over Land areas





swarm rl01 temporal RMS land (2013-12 to 2018-09)











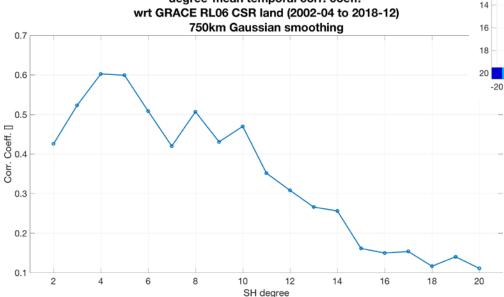






Agreement with **GRACE** over Land areas

degree-mean temporal corr. coeff. wrt GRACE RL06 CSR land (2002-04 to 2018-12)







-10



10

15

20

swarm rl01 temporal corr. coeff. land (2013-12 to 2018-09) 750km Gaussian smoothing

SH order



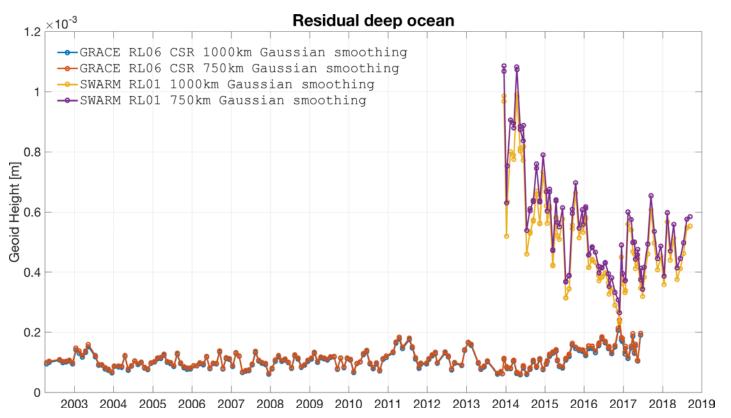








Swarm and Grace un-modeled ocean RMS









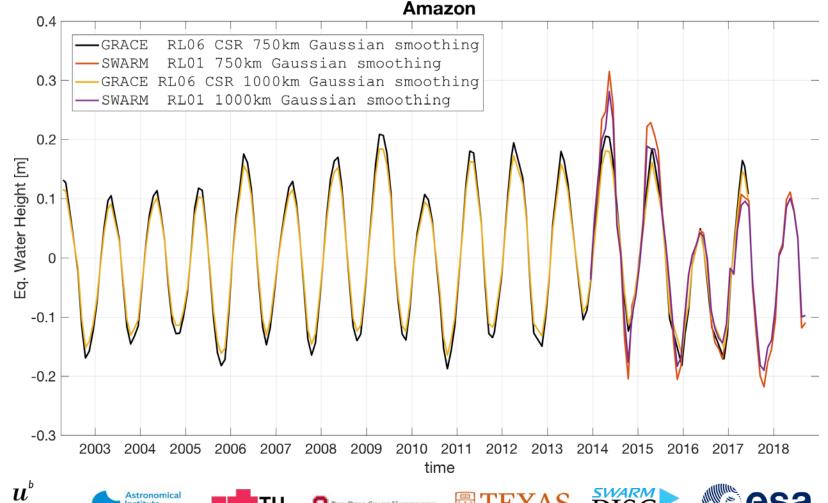
















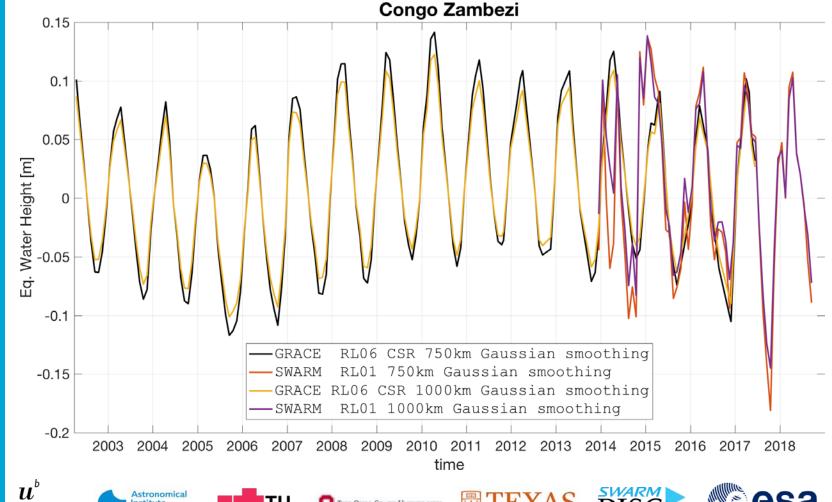
















UNIVERSITÄT BERN

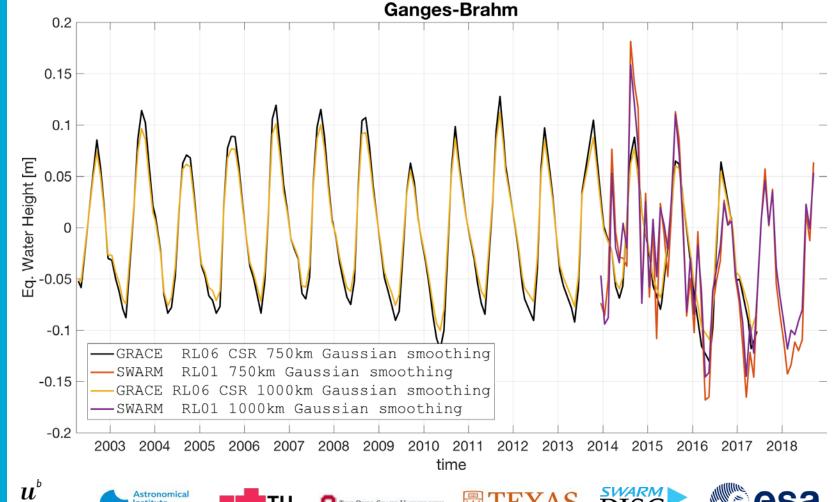
















UNIVERSITÄT BERN

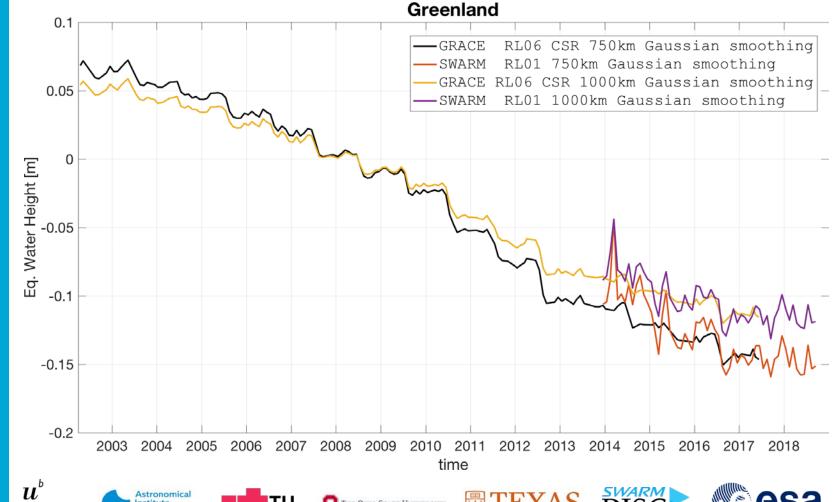
















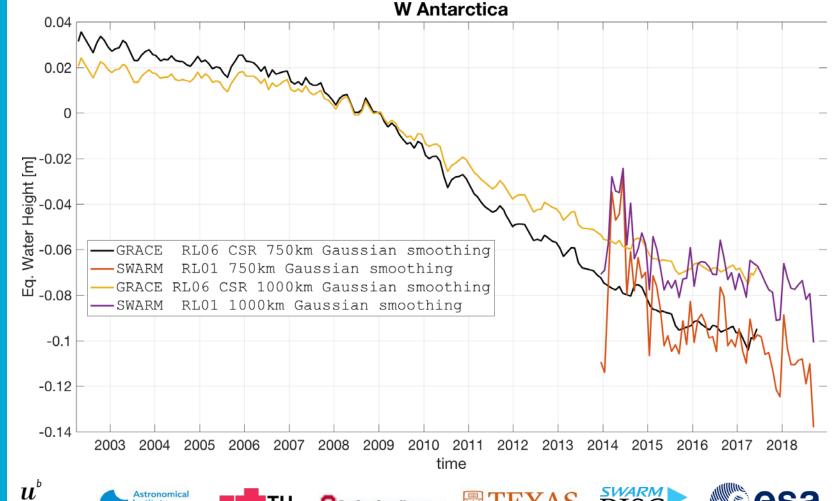
















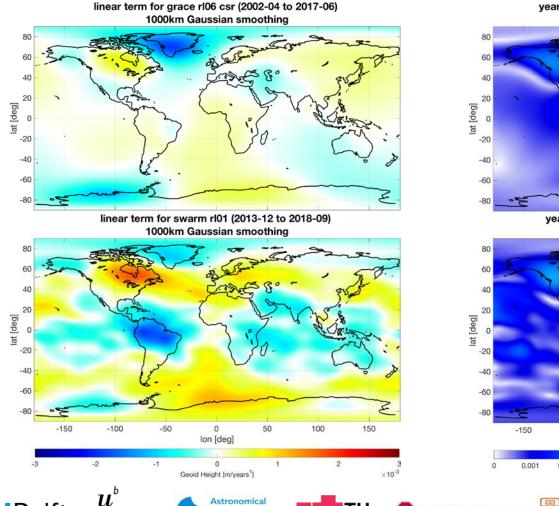


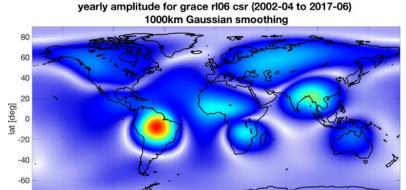


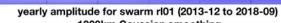


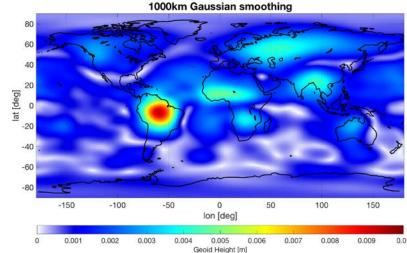




























Summary and conclusions

- Swarm signal useful below degree 15
- Temporal correlations decrease sharply over degree
 10
- Swarm basin averages noisier than GRACE, except for largest basins
- Global spatial agreement with GRACE at 1 cm RMS Eq. W. H.
 - over periods of low solar activity
 - Gaussian smoothing radius of 750 km
- Seasonal signal clearly resolvable by Swarm















