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COMPUTER SCIENCE MEETS AUTOMATION

VOLUME II

- Session 6 Environmental Systems: Management and Optimisation
- Session 7 New Methods and Technologies for Medicine and Biology
- Session 8 Embedded System Design and Application
- Session 9 Image Processing, Image Analysis and Computer Vision
- **Session 10 Mobile Communications**
- Session 11 Education in Computer Science and Automation



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Preface

Dear Participants,

Confronted with the ever-increasing complexity of technical processes and the growing demands on their efficiency, security and flexibility, the scientific world needs to establish new methods of engineering design and new methods of systems operation. The factors likely to affect the design of the smart systems of the future will doubtless include the following:

- As computational costs decrease, it will be possible to apply more complex algorithms, even in real time. These algorithms will take into account system nonlinearities or provide online optimisation of the system's performance.
- New fields of application will be addressed. Interest is now being expressed, beyond that in "classical" technical systems and processes, in environmental systems or medical and bioengineering applications.
- The boundaries between software and hardware design are being eroded. New design methods will include co-design of software and hardware and even of sensor and actuator components.
- Automation will not only replace human operators but will assist, support and supervise humans so that their work is safe and even more effective.
- Networked systems or swarms will be crucial, requiring improvement of the communication within them and study of how their behaviour can be made globally consistent.
- The issues of security and safety, not only during the operation of systems but also in the course of their design, will continue to increase in importance.

The title "Computer Science meets Automation", borne by the 52nd International Scientific Colloquium (IWK) at the Technische Universität Ilmenau, Germany, expresses the desire of scientists and engineers to rise to these challenges, cooperating closely on innovative methods in the two disciplines of computer science and automation.

The IWK has a long tradition going back as far as 1953. In the years before 1989, a major function of the colloquium was to bring together scientists from both sides of the Iron Curtain. Naturally, bonds were also deepened between the countries from the East. Today, the objective of the colloquium is still to bring researchers together. They come from the eastern and western member states of the European Union, and, indeed, from all over the world. All who wish to share their ideas on the points where "Computer Science meets Automation" are addressed by this colloquium at the Technische Universität Ilmenau.

All the University's Faculties have joined forces to ensure that nothing is left out. Control engineering, information science, cybernetics, communication technology and systems engineering – for all of these and their applications (ranging from biological systems to heavy engineering), the issues are being covered.

Together with all the organizers I should like to thank you for your contributions to the conference, ensuring, as they do, a most interesting colloquium programme of an interdisciplinary nature.

I am looking forward to an inspiring colloquium. It promises to be a fine platform for you to present your research, to address new concepts and to meet colleagues in Ilmenau.

In Sherte

Professor Peter Scharff Rector, TU Ilmenau

"L. Ummt

Professor Christoph Ament Head of Organisation

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I. Aksit, K. Bünger, A. Fassbender, D. Frekers, C. Götze, J. Kemenas,

An ultra-fast on-line microscopic optical quality assurance concept for small structures in an environment of mass production

Today's Printed Circuit Boards (PCB) for sensors meet structure sizes in the µm or even nm range at high circuit complexity. These structures are usually printed in thin layer technology and coated in thin film technology. Those PCBs are being used in a large variety of applications ranging from cars to space stations, from private security devices to power plant control facilities, from toys and domestic appliances to consumer electronics, from robots to information devices. With increasing complexity, the demands on quality assurance and quality evaluation are quickly increasing. PCBs usually have to be investigated for surface and coating defects by optical techniques. So far, it has been impossible or prohibitively expensive to implement automated quality assurance procedures for each individual PCB by optical measures and at high throughput. Quality assessment is therefore mostly limited to statistical sampling techniques employing specially trained personnel performing the evaluations. This means that performance is frequently subjective and non-reproducible, let aside the often stress-prone conditions facing the personnel. Past attempts to automate optical inspections for each individual PCB and allowing on-line keep-or-reject decisions have largely been unsuccessful because the structures to be inspected are microscopically small, therefore requiring high magnifications and advanced image resolutions, which usually prevents large area inspections in one working step. Clearly, a novel approach is needed in the area of hardware and software, both of them being capable of acquiring and accurately analysing these structures at high resolution and within a time slot that allows on-line implementation in a mass production.

In the present pilot project, the authors have demonstrated a successful implemention of a system providing these features. Each partner company contributed special core competencies and integrated those into a single product. In a first step, the Eclipse optical microscope of the **MedXP GmbH** equipped with the patented AMBISTM

technique acquires a series of images from the entire area of test samples, each of them being about 10mm in diameter. Typical sustained acquisition speeds are about 25 - 30 frames/s at full image resolution in continuous scanning mode. The resulting image sizes depend on the optical system used, and in the present application perfect results were achieved with images of about 18.000x14.000 pixels per sample. In this case, the overall image of a single sample is separated into 14x14 partial images, each of 1280x1024 pixels in size and joined together without the need of a seaming algorithm for any of the edges. The samples can optionally be supplied to the microscope in a magazine of about 100 pieces by an automatic robot system. For acquiring the image of a single sample of the typical size of 10mm in diameter, the microscope needs about 10s, which includes the overhead for the focusing to the object surface. As there are no start-stop sequences involved during image acquisition, the microscope system operates without generating any extra noise and without creating any inertial forces due to acceleration or decelaration or any other frictional forces.

Together with position information for each single image the acquired images are then handed over to the *arivis ImageCore* software developed and distributed by **arivis** – **Multiple Image Tools GmbH**. This software package is capable of handling extremely large, multi-dimensional image data even on common, budget-priced hardware and manages these image areas for visual inspection at any zoom level or for an automated analysis. The software combines all individual image parts to a single large image for each sample and stores the image for subsequent ultra-fast access into a single file using proprietary formatting software.

Next, the image data are transferred to the *alfaVis* analysis software developed and distributed by **alfa vision systems GmbH**. This software package is developed for the detection of various types of structural defects on the original sample, like missing circuit structures, short circuits or any other surface defects or surface pollution. The analysis provides a quality certificate for every single sample in the line of the production.

The integrated pilot system needs about 20 minutes for the inspection of a magazine containing about 100 samples. Every sample is treated in an identical way making the evaluation independent of time, human subjectivity or human error. The

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system is flexible and can be adopted quickly and easily to a change of sample layout requiring only minutes for the adjustment to the new layout and to the optimization process.

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