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A Simple Server Selection Algorithm to Reduce Electric Power for Storage and Computation Processes

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出版者	法政大学大学院理工学研究科	
journal or	法政大学大学院紀要.理工学・工学研究科編	
publication title		
volume	59	
page range	1-8	
year	2018-03-31	
URL	http://doi.org/10.15002/00021610	

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#### Abstract

In application processes like Web and databases, files and databases are manipulated on servers. Thus, both CPU and storage resources are used to perform application processes. In this paper, we propose a computation model to give the expected termination time of each application process. Then, we propose an SGEAG (Simple Globally-Energy-Aware for General processes) algorithm to select a server to perform a new process issued by a client, which is expected to consume the minimum electric energy to perform not only the new process but also every current process. In the evaluation, we show the electric energy consumed by servers and the average execution time of processes can be more reduced in the SGEAG algorithm than the other algorithms.

**Key Word**: Power consumption model; Computation model; improved MLCMG model; SGEAG algorithm; General processes; Storage operations;

#### **1** Introduction

In order to realize eco society, we have to reduce the electric energy consumed in information systems [10], [30], especially scalable systems like cloud computing systems [22] and IoT [11]. In hardware-oriented approaches to reducing the electric energy consumption of servers, energy-efficient devices like CPUs [14] [23] and storages [13] are developed. On the other hand, in our macro-level approach [6] [7] [8], we aim at reducing the total amount of electric energy [J] consumed by a whole server to perform application processes without considering the power consumption of each hardware device. In this paper, a *process* means an application process to be performed on a server.

In this paper, we propose an improved computation model of a server to perform general processes which use both CPU resources and storage drives. The MLCMG model [26] is improved so that computation and storage operations performed by each application process are uniformly handled. Here, computation steps and storage manipulation steps of each process are virtualized into virtual computation steps. Then, virtual computation rate and storage manipulation rate are defined in terms of virtual computation steps to show how much computation and storage manipulation are performed on a server for one time unit. Based on the improved MLCMG model, we newly propose an SGEAG (Simple Globally-Energy-Aware for General processes) algorithm to select a host server to perform general processes. Here, the total electric energy to be consumed by not only the host server but also the other servers is minimized as discussed in the GEAG algorithm. We evaluate the SGEAG algorithm compared with the random and round-robin algorithms in the simulation studies. We show the total electric energy consumption and total active time of servers in a cluster and the average execution time of processes can be more reduced in the SGEAG algorithm than the other algorithms in the evaluation.

In section 2, we present the power consumption model and improved computation model of a server to perform general processes. In section 3, we propose the SGEAG algorithm to select a host server. In section 4, we evaluate the SGEAG algorithm.

# 2 Multi-level Power Consumption and Computation Models

#### 2.1 MLPCM model

A cluster S is composed of  $m (\geq 1)$  servers  $s_1, \ldots, s_m$ . Each server  $s_t$  is composed of  $np_t (\geq 1)$  homogeneous CPUs [14]. Each CPU is composed of  $cc_t (\geq 1)$  homogeneous cores. Each core supports  $ct_t (\leq 2)$  threads. Let  $ncp_t$  and  $nt_t$  be the total numbers of cores and threads of a server  $s_t$ , i.e.  $ncp_t = np_t \cdot cc_t$  and  $nt_t = ncp_t \cdot ct_t$ . An active thread is one where at least one process is performed. An active server is a server where at least one thread is active, Let  $CP_t(\tau)$  be a set of processes performed on a server  $s_t$  at time  $\tau$ .

The electric power consumption  $E_t(\tau)$  [W] of a server  $s_t$  to perform computation processes is  $minE_t + ap_t(\tau) \cdot bE_t + ac_t(\tau) \cdot cE_t + at_t(\tau) \cdot tE_t$  where  $ap_t(\tau)(\leq np_t)$ ,  $ac_t(\tau)(\leq ncp_t)$ , and  $at_t(\tau)(\leq nt_t)$  are numbers of active CPUs, cores, and threads, respectively, at time  $\tau$  in the MLPCM model [18] [19].

Next, suppose n processes are performed on a server  $s_t$ . It is more convenient and practical to give the electric power consumption of a server  $s_t$  in terms of number n of current processes performed. Here, let  $nap_t(n), nac_t(n)$ ,

and  $nat_t(n)$  be numbers of active CPUs, cores, and threads of a server  $s_t$  where n computation processes are performed. Processes are fairly allocated with CPUs, cores, and threads in a scheduling algorithm like round-robin algorithm [20]. Hence, we can assume  $nap_t(n) = n$  if  $n \leq np_t$ , else  $np_t$ .  $nac_t(n) = n$  if  $n \leq ncp_t$ , else  $ncp_t$ .  $nat_t(n) = n$  if  $n \leq nt_t$ , else  $nt_t$ . The electric energy consumption  $CE_t(n)$  of a server  $s_t$  to perform n processes is given as follows:

$$CE_t(n) = minE_t + nap_t(n) \cdot bE_t + nac_t(n) \cdot cE_t + nat_t(n) \cdot tE_t.$$
(1)

The maximum electric power consumption  $CE_t(n)$  is  $maxCE_t$  [W] =  $minE_t + np_t \cdot bE_t + ncp_t \cdot cE_t + nt_t \cdot tE_t$  where  $n \ge nt_t$ .

Next, we consider general processes which read data in a file while doing the computation for simplicity.  $CP_t(\tau)$ is a set of processes which use CPU at time  $\tau$ .  $RP_t(\tau)$  is a set of processes which read data in storages on a server  $s_t$ at time  $\tau$ . If a process  $p_i$  uses both CPU and storage at time  $\tau$ ,  $p_i \in CP_t(\tau)$  and  $p_i \in RP_t(\tau)$ .  $PP_t(\tau)$  is a set of all processes performed on a server  $s_t$  at time  $\tau$ , i.e.  $PP_t(\tau) =$  $CP_t(\tau) \cup RP_t(\tau)$ . The electric power computation  $E_t(\tau)$ [W] of a server  $s_t$  to perform general processes at time  $\tau$ is given in the MLPCMG (MLPCM for General processes) model [27] as follows;

$$E_t(\tau) = CE_t(|CP_t(\tau)|) + \delta_t(\tau) \cdot RE_t$$
  
where  $\delta_t(\tau) = 1$  if  $|RP_t(\tau)| > 0$ , else 0. (2)

The maximum electric power consumption  $maxE_t$  of a server  $s_t$  is  $maxCE_t + RE_t$  where  $|CP_t(\tau)| (\geq nt_t)$ processes use CPU and at least one process accesses to storages.

We measure the electric power consumed by a pair of servers, DSLab (Two Intel Xeon CPUs, 128GB memory, 4.8TB storage)  $s_D$  and Atria (Intel Core i7 CPU, 16GB memory, 2.0TB storage)  $s_A$  in our laboratory. The DSLab server  $s_D$  supports thirty two threads and the Atria server  $s_A$  supports eight threads. Figure 1 shows the electric power consumption of the servers  $s_D$  and  $s_A$  to perform ngeneral processes and computation processes. Each general process uses both CPU and reads data of 1 [GB] in a file. C + R shows that n general processes are performed and C means only n computation processes are performed. As shown in Figure 1,  $minE_D = 126.1$ ,  $bE_D = 30$ ,  $cE_D$  $= 5.6, tE_D = 0.8, and maxCE_D = 301.1$  [W] for the DSLab server  $s_D$  and  $minE_A = 41.3$ ,  $bE_A = 15$ ,  $cE_A =$ 4.7,  $tE_A = 1.1$ , and  $maxCE_A = 89.5$  [W] for the Atria server  $s_A$ .  $RE_D = 21$  and  $maxE_D = 322.1$  [W] for the DSLab server  $s_D$  and  $RE_A = 2$  and  $maxE_A = 91.5$  [W] for the Atria server  $s_A$ .

#### 2.2 MLCMG model

Each general processes  $p_i$  is composed of read operations as storage operations in addition to computation operations. Let  $cp_i$  and  $sp_i$  denote subsequences of computation and storage operations of a process  $p_i$ , respectively.

A process  $p_i$  is at a time performed on a thread of a server  $s_t$  in a cluster S of  $m (\geq 1)$  servers  $s_1, \ldots, s_m$ .

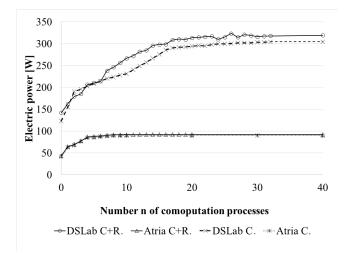


Figure1: Electric power consumption.

 $minCT_{ti}$  shows the minimum execution time of computation operations, i.e.  $cp_i$  of a process  $p_i$  on a thread of a server  $s_t$ , where only the process  $p_i$  is performed on a thread without any other process.  $minCT_i$  indicates the minimum one of the minimum execution time  $minCT_{1i}$ ,  $\cdots$ ,  $minCT_{mi}$  on the servers  $s_1, \ldots, s_m$ , respectively. A thread of a server  $s_f$  is fastest in a cluster S if  $minCT_i$  $= minCT_{fi}$  for every process  $p_i$ . Here, the server  $s_f$  is referred to as fastest in a cluster S. We assume one virtual computation step is performed on a thread of a fastest server  $s_f$  for one time unit [time unit (tu)]. That is, the thread computation rate  $CRT_f$  of a fastest server  $s_f$  is one [vs/tu]. The thread computation rate CRT of a cluster S is  $CRT_f$  of the fastest server  $s_f$  ( $CRT = CRT_f$  = 1). A server  $s_t$  supports the thread computation rate  $CRT_t$  $= (minCT_i / minCT_{ti}) \cdot CRT = minCT_i / minCT_{ti}$ [vs/tu] ( $\leq CRT = 1$ ). If the computation operations  $cp_i$ of a process  $p_i$  are performed on a fastest server  $s_f$  without any other process, it takes  $minCT_{fi} = minCT_i$  [tu]. Hence, the amount  $VC_i$  of computation of a process  $p_i$  is defined to be  $minCT_i$  [tu]  $\cdot CRT_f$  [vs / tu] =  $minCT_i$ [vs]. Thus,  $minCT_i$  shows the total number  $VC_i$  of virtual computation steps.

The server computation rate  $NSR_t(\tau)$  [vs/tu] of a server  $s_t$  at time  $\tau$  is  $at_t(\tau) \cdot CRT_t$  where  $at_t(\tau) (\leq nt_t)$ is the number of active threads and  $nt_t$  is the total number of threads. As discussed in papers [16]-[19], the maximum computation rate  $maxCR_t$  of a server  $s_t$  is  $nt_t \cdot$  $CRT_t$ . maxCR shows the maximum one of maximum computation rates  $maxCR_1, \ldots, maxCR_m$  of the servers  $s_1, \ldots, s_m$ . Computation resources are assumed to be uniformly allocated to each process on a server  $s_t$  in the round-robin (RR) algorithm [20]. The server computation rate  $NSR_t(n)$  of a server  $s_t$  where  $n (= |CP_t(\tau)|)$  processes are performed is given as follows:

$$NSR_t(n) = \begin{cases} n \cdot CRT_t \text{ if } n \le nt_t.\\ nt_t \cdot CRT_t(=maxCR_t) \text{ if } n > 0. \end{cases}$$
(3)

We assume each process  $p_i$  is fairly allocated with computation resources. The process computation rate  $NPR_{ti}(n)$  of a process  $p_i$  performed concurrently with (n - 1) processes on a server  $s_t$  is  $NPR_{ti}(n) = NSR_t(n) / n$ .

For simplicity, we assume each process  $p_i$  only reads data in a file  $f_i$  different from every other process  $p_j$  ( $f_i \neq f_j$ ). Here,  $b_i$  shows the size [B] of a file  $f_i$ . Let  $maxRR_t$ indicate the maximum read rate [B/tu] of a server  $s_t$ . Suppose only storage operations  $sp_i$  of a process  $p_i$  are performed to just read data in a file  $f_i$  of the server  $s_t$ . It takes  $RT_{ti}$  time units [tu] for the process  $p_i$  to read every data in a file  $f_i$ . The minimum read time  $minRT_{ti}$  of a process  $p_i$  to read every data in a file  $f_i$  is  $b_i / maxRR_t$  [tu] where only the process  $p_i$  is performed without any other process on a server  $s_t$ . The read rate  $NRR_t(n)$  [B/tu] of a server  $s_f$  where n processes reading data in storages are performed is given as follows:

$$NRR_t(n) = maxRR_t.$$
 (4)

Each process  $p_i$  reads data in a file  $f_i$  at the rate  $NRR_{ti}(n)$  where n processes read data in the storages:

$$NRR_{ti}(n) = NRR_t(n)/n.$$
 (5)

The more number of processes read data, the smaller read rate of each of the processes.

In this paper, we take a fastest server  $s_f$  as a *canonical* server in a cluster S. The canonical read time  $cRT_i$  [tu] of a process  $p_i$  is defined to be  $minRT_{fi}$  on the fastest server  $s_f$ . We assume one virtual computation step is performed on the canonical server  $s_f$  to read data of size  $maxRR_f$  [B] for one time unit [tu]. That is, the canonical virtual read rate cRR is defined to be one [vs/tu]. Hence, cRR [vs/tu]  $\cdot cRT_i$  [tu] (=  $cRT_i$ ) virtual computation steps [vs] are performed to read every data in a file  $f_i$  on the fastest server  $s_f$ . The number  $VR_i$  of virtual computation steps of a process  $p_i$  to read every data in a file  $f_i$  is cRR [vs/tu]  $\cdot cRT_i$  [tu] =  $cRT_i = minRT_{fi}$  [vs]. The virtual read rate  $VRR_t$  [vs/tu] of a server  $s_t$  is defined as follows;

$$VRR_t = cRR \cdot maxRR_t/maxRR_f$$
$$= maxRR_t/maxRR_f.$$
 (6)

The virtual read rate  $VRR_f$  is assumed to be cRR (= 1) for the fastest server  $s_f$ . Even if a server  $s_t$  is slower than the fastest server  $s_f$ , i.e.  $CRT_t < CRT_f$ , the virtual read rate  $VRR_t$  may be larger than  $VRR_f$  depending on the read rates  $maxRR_t$  and  $maxRR_f$  of the storage drives. The virtual read rate  $VRR_{ti}(n)$  of a process  $p_i$  on a server  $s_t$  where  $n (\leq 1)$  read processes are performed is  $VRR_t / n$ .

The canonical execution time  $cT_i$  [tu] of a process  $p_i$  in terms of minimum computation time  $minCT_i$  and canonical read time  $CRT_i$  is defined as follows;

$$cT_i = minCT_i + cRT_i (= minRT_{fi}).$$
(7)

It takes  $cT_i$  [tu] to perform the process  $p_i$  on the fastest server  $s_f$ . The amount  $VP_i$  of virtual computation steps of a process  $p_i$  is defined to be  $VC_i + VR_i$  (=  $minCT_i + cRT_i$ ) [vs]. The computation ratio  $cr_i$  and the read ratio  $rr_i$  of a process  $p_i$  are  $VC_i / VP_i$  and  $VR_i / VP_i$ , respectively. Here,  $cr_i + rr_i = 1$ . In this paper, we assume the ratios of the numbers of virtual computation steps and virtual read steps of a process  $p_i$  performed for each time unit are invariant  $cr_i$  and  $rr_i$ , respectively. Let  $ncp_t$  be the number  $|CP_t(\tau)|$  of processes which do the computation and  $nrp_t$  be the number  $|RP_t(\tau)|$  processes which read data in storages. We assume virtual computation operations and virtual storage operations are uniformly distributed in a sequence of operations of each process. We define the virtual computation rate  $VCR_{ti}(\tau)$  [vs/tu] and virtual read rate  $VRR_{ti}(\tau)$  [vs/tu] of a process  $p_i$  as follows:

#### [Virtual computation (VC) and read (VR) rates]

$$VCR_{ti}(ncp_t) = \begin{cases} cr_i \cdot CRT_t \text{ if } ncp_t \leq nt_t. \\ cr_i \cdot maxCR_t/ncp_t \text{ if } ncp_t > nt_t. \end{cases}$$

$$VRR_{ti}(nrp_t) = rr_i \cdot VRR_t/nrp_t.$$
(9)

The variables  $vc_i$  and  $vr_i$  show the virtual computation laxity and virtual read laxity of a process  $p_i$ , respectively. That is,  $vc_i$  and  $vr_i$  virtual computation steps of a process  $p_i$  have to be still performed now. At time  $\tau$  a process  $p_i$  starts on a server  $s_t$ ,  $vc_i = VC_i$  ( $= minCT_i$ ) and  $vr_i$  $= VR_i$  ( $= cRT_i$ ) [vs]. At each time  $\tau$ ,  $vc_i$  and  $vr_i$  are decremented by the virtual computation rate  $VCR_{ti}(ncp_t)$ and virtual read rate  $VRR_{ti}(nrp_t)$  [vs/tu], respectively. If both the laxities  $vc_i$  and  $vr_i$  are equal to or smaller than zero, the process  $p_i$  terminates at time  $\tau$ .

Initially, a variable  $PP_t = \phi$  for each server  $s_t$ .  $PP_t$  shows a set of processes performed on a server  $s_t$ .

#### [Virtual computation (VC) model]

at each time  $\tau$ ,

for each server 
$$s_t$$
 in a cluster  $S$ , {  
/\*  $PP_t$  show  $PP_t(\tau)$  \*/  
for every new process  $p_i$  to be started on  $s_t$ , {  
 $PP_t = PP_t \cup \{p_i\};$   
 $vc_i = VC_i;$   
 $vr_i = VR_i;$   
}; /\* for process  $p_i$  end \*/  
for each process  $p_i$  in  $PP_t$ , { /\* decrement laxity \*/  
 $vc_i = vc_i - VCR_{ti}(\tau);$   
 $vr_i = vr_i - VRR_{ti}(\tau);$   
if  $vc_i \le 0$  and  $vr_i \le 0$ , /\*  $p_i$  terminates \*/  
 $PP_t = PP_t - \{p_i\};$   
}; /\* for process  $p_i$  end \*/  
}; /\* for server  $s_t$  end \*/

2.3 Estimation model

We discuss how to estimate at time  $\tau$  the electric energy consumption of a server  $s_t$  to perform all the current processes and the termination time of each current process. In the estimation models discussed by previous studies [26] - [24], it takes time to calculate the expected termination time of each process and the laxity of each process has to be collected on a server. In this paper, we consider a model to simply estimate the termination time of each process on a server. We assume each current process  $p_i$  on a server  $s_t$  finishes the half  $VC_i/2$  of the virtual computation steps and  $VR_i/2$  of virtual read steps at time  $\tau$ .

Suppose a set  $NP_t(\tau)$  of  $nn_t (\geq 0)$  processes are newly issued to a server  $s_t$  where a set  $PP_t(\tau)$  of current processes are performed by using CPU resources at time  $\tau$ . Let  $n_t$ ,  $ncp_t$ , and  $nrp_t$  be the numbers  $|PP_t(\tau)|$ ,  $|CP_t(\tau)|$ , and  $|RP_t(\tau)|$  of processes, respectively. Here,  $ncp_t \leq$  $n_t$ ,  $nrp_t \leq n_t$  and  $n_t \leq ncp_t + nrp_t \leq 2 \cdot n_t$ . The total number  $VSC_t$  [vs] of virtual computation steps to be performed by all the current processes and new processes is  $\sum_{p_j \in CP_t(\tau)} VC_j/2 + \sum_{p_j \in NP_t(\tau)} VC_j$  on a server  $s_t$ . The computation rate of a server  $s_t$  to perform  $ncp_t$  current processes and  $nn_t$  new processes is  $NSC_t(ncp_t + nn_t)$  [vs/tu]. The expected execution time  $ECT_t$  of a server  $s_t$  to perform every computation operation is  $VSC_t / NS_t(ncp_t + nn_t)$  [tu]. The total number  $VSR_t$  of virtual manipulation steps to be performed by all the current and new processes is on a server  $s_t$  $\sum_{p_j \in RP_t(\tau)} VR_j/2 + \sum_{p_j \in NP_t(\tau)} VR_j \text{ [vs] which are performed at rate } NRR_t(nt_t + nn_t) (= maxRR_t) \text{ [vs/tu]}.$ Here, the expected execution time  $ERT_t$  to perform all the storage operations is  $VSR_t / NRR_t(nrp_t + nn_t)$  [tu]. Thus, the expected termination time  $ECT_t$  and  $ERT_t$ of computation operations and storage operations of every current process in  $PP_t(\tau)$  and every new process in  $NP_t(\tau)$  are given as follows:

$$ECT_t = \left(\sum_{p_j \in CP_t(\tau)} VC_j / 2 + \sum_{p_j \in NP_t(\tau)} VC_j\right) / NSR_t(ncp_t + nn_t).$$
(10)

$$ERT_{t} = \left(\sum_{p_{j} \in RP_{t}(\tau)} VR_{j}/2 + \sum_{p_{j} \in NP_{t}(\tau)} VR_{j}\right) / NRR_{t}(nrp_{t} + nn_{t}).$$
(11)

The expected electric energy consumption  $EE_t$  [W · tu] of a server  $s_t$  is given as follows:

$$EE_t = ECT_t \cdot CE_t(ncp_t + nn_t) + ERT_t \cdot RE_t.$$
(12)

In order to make the estimation easier, we assume  $cr_i$  is a constant  $cr = \alpha (\leq 1)$ ,  $rr_i = rr = 1 - \alpha$  for each process  $p_i$ . We also assume  $VC_i = VC = \alpha$ , and  $VR_i = VR = 1$ -  $\alpha$  for every process  $p_i$ . The expected termination time of computation and read operations of a server  $s_t$  where n $(= |PP_t(\tau)|)$  processes are concurrently performed and k $(= |NP_t(\tau)|)$  new processes are issued to the server  $s_t$  are given as follows:

$$MECT_t(n_t, k) = \alpha \cdot (n_t/2 + k) / NCR_t(n_t + k).$$
 (13)

$$MERT_t(n_t, k) = (1 - \alpha) \cdot (n_t/2 + k) / NRR_t(n_t + k).$$
(14)

The expected electric energy consumption  $MEE_t(n_t, k)$  [W  $\cdot$  tu] of a server  $s_t$  is summation

of electric energy  $MECT_t(n_t, k)$  to be consumed by performing computation operations and electric energy  $MERT_t(n_t, k)$  to be consumed by performing storage operations is given as follows:

$$MEE_t(n_t, k) = MECT_t(n_t, k) + MERT_t(n_t, k).$$
(15)

A server  $s_t$  gets idle if every computation operation and manipulation operation of every processes finishes. Hence, the expected termination time  $MET_t(n_t, k)$  [tu] of a server  $s_t$  is given as follows:

$$MET_t(n_t, k) = max(MECT_t(n_t, k), MERT_t(n_t, k)).$$
(16)

#### **3** Server Selection Algorithms

A client issues a process  $p_i$  to a cluster S of servers  $s_1$ , ...,  $s_m$  ( $m \ge 1$ ). Then, one host server  $s_t$  is selected for performing the process  $p_i$ . The expected electric energy consumption  $EE_t$  and expected termination time  $ET_t$  of the server  $s_t$  are calculated by the simple estimation procedures  $MEE_t(|PP_t(\tau)|, 1)$  and  $MET_t(|PP_t(\tau)|, 1)$ , respectively.

First, in the SLEAG (Simple Locally-Energy-Aware for General processes) selection algorithm [5], a host server  $s_t$ is selected in the cluster S, whose expected electric energy consumption  $EE_t$  to perform not only the new process  $p_i$ but also every current process in the set  $PP_t(\tau)$  is minimum as follows:

# [SLEAG algorithm]

for each server  $s_u$  in a cluster S,

 $EE_u = MEE_u(|PP_u(\tau)|, 1);$ 

select a host server  $s_t$  where  $EE_t$  is minimum in S; perform a process  $p_i$  on  $s_t$ ;

As discussed in papers [18], [19], another server  $s_u \ (\neq s_t)$  where a new process  $p_i$  is not performed also consumes the electric energy while the process  $p_i$  is performed on the host server  $s_t$ . Even if the server  $s_u$  is idle, i.e. no process is performed, the server  $s_u$  just consumes the minimum electric power  $minE_t$ . We propose an SGEAG (Simple Globally-Energy-Aware for General processes) algorithm to select a host server  $s_t$  to perform a new process  $p_i$ . Here, we take into account the total electric energy consumption of not only a host server  $s_t$  of a new process  $p_i$  but also the other servers in a cluster S. For a process  $p_i$ , a host server  $s_t$  is selected in the SGEAG algorithm as follows:

#### [SGEAG algorithm]

for each server  $s_t$  in a cluster S, {

/\* not only every current process but also a new process  $p_i$  to be performed on  $s_t$  \*/

 $NT_t = MET_t(|PP_t(\tau)|, 1); /* \text{ execution time }*/$  $NE_t = MEE_t(|PP_t(\tau)|, 1); /* \text{ energy }*/$ 

/\* only every current process to be performed on  $s_t$ \*/  $ET_t = MET_t(|PP_t(\tau)|, 0)$ ; /\* execution time \*/  $EE_t = MEE_t(|PP_t(\tau)|, 0)$ ; /\* energy \*/ }; /\* for  $s_t$  end \*/

for each server  $s_t$  in S, {

for each server  $s_u \ (\neq s_t)$  in S, { if  $ET_u < NT_t$ , /\*  $s_u$  terminates before  $NT_t$  \*/  $NEE_u = EE_u + minE_u \cdot (NT_t - ET_u)$ else  $NEE_u = EE_u \cdot NT_t / ET_u$ ; }; /\* for  $s_u$  end \*/  $GE_t = NE_t + \sum_{s_v \in S - \{s_t\}} NEE_v$ ; } /\* for  $s_t$  end \*/

select a server  $s_t$  where  $GE_t$  is minimum in S; perform a process  $p_i$  on  $s_t$ ;

First, we obtain the expected electric energy  $NE_t$  to be consumed by each server  $s_t$  to perform not only every current process but also a new process  $p_i$  by the procedures  $NT_t = MET_t(|PP_t(\tau)|, 1)$  and  $NE_t = MEE_t(|PP_t(\tau)|, 1)$ 1). In addition, we obtain the expected electric energy consumption  $EE_t$  of each server  $s_t$  to perform only every current process by the procedures  $ET_t = MET_t(|PP_t(\tau)|, 0)$ and  $EE_t = MEE_t(|PP_t(\tau)|, 0)$ . For each host server  $s_t$ , we obtain the expected electric energy  $NEE_u$  to be consumed by each other server  $s_u$  until time  $NT_t$  when every process terminates on the server  $s_t$ . An idle server  $s_u$ , i.e.  $ET_u = 0$  consumes the electric energy  $NEE_u = minE_u$  $\cdot NT_t$ . If every current process terminates on a server  $s_t$ before time  $NT_t$ , i.e.  $ET_u < NT_t$ , the server  $s_t$  consumes the electric energy  $minE_t \cdot (NT_t - ET_u)$  after every current process terminates. Hence, the server  $s_u$  consumes the electric energy  $NEE_u = EE_u + minE_u \cdot (NT_t - ET_u)$ . If  $ET_u \leq NT_t$ ,  $NEE_u = EE_u \cdot NT_t / ET_u$ . If a process  $p_i$  is to be performed on a server  $s_t$ , all the servers in the cluster S are expected to totally consume the electric energy  $GE_t = NE_t + \sum_{s_u (\neq s_t) \in S} NEE_u$ . A server  $s_t$ where the expected total electric energy consumption  $GE_t$ is minimum is selected as a host server of a process  $p_i$ .

# **4** Evaluation

# 4.1 Environments

A cluster S is composed of  $m (\geq 1)$  real servers  $s_1$ , ...,  $s_m$  where  $n \geq 1$  processes  $p_1, \ldots, p_n$  are performed. In the evaluation, we consider four real servers  $s_1, \ldots, s_4$  in our laboratory. A pair of the servers  $s_1$  and  $s_4$  are equipped with two and one Intel Xeon E5-2667 v2 CPU, respectively. A pair of the equipped with one Intel Corei7-6700K and Intel Xeon E5-2620 CPU, respectively. The performance parameters like thread computation rate  $CRT_t$  and electric energy parameters like the minimum electric power  $minE_t$  of each server  $s_t$  are shown in Table 1. The threads of the servers  $s_1$  and  $s_4$  are the fastest,  $CRT_1 = CRT_2 = 1$  [vs/tu]. The maximum computation rate  $maxCR_4$  of the server  $s_4$  is  $32 \cdot 1 = 32$  [vs/tu] since thirty two threads are supported. On the other hands,  $maxCR_1 = 16$  since the server  $s_1$  supports sixteen threads. The server  $s_2$  supports the thread computation rate  $CRT_2$ = 0.7 and the maximum computation rate  $maxCR_2 = 5.6$ since eight threads are equipped. The server  $s_3$  is the slowest where  $CRT_3 = 0.5$  and  $maxCR_3 = 0.5 \cdot 12 = 6.0$  since twelve threads are supported. The server  $s_4$  is taken as a canonical server where virtual read rate  $VRR_1 = 1$  since the server  $s_4$  is the fastest.

The number n (> 1) of processes  $p_1, \ldots, p_n$  are performed on the servers  $s_1, \ldots, s_4$ . The parameters of the processes are shown in Table 2. The starting time  $stime_i$ 

of each process  $p_i$  is randomly taken from 0 to xtime - 1 [tu]. In the evaluation, *xtime* is 1,000 [tu], i.e. 100 [sec]. The minimum computation time  $minCT_i$  of each process  $p_i$  is randomly taken from mT (= 5) to xT (= 20) [tu]. The total number  $VC_i$  [vs] of virtual computation steps of each process  $p_i$  is  $minCT_i$ . The canonical read time  $cRT_i$  [tu] is  $\alpha \cdot minCT_i$ . In the evaluation,  $\alpha = 0.025$ . The minimum execution time  $minT_i$  of a process  $p_i$  is  $minCT_i$  +  $cRT_i = (1 + \alpha) \cdot minCT_i = 1.025 \cdot minCT_i$  [tu]. The total amount  $VR_i$  of virtual read steps of a process  $p_i$  is  $cRT_i$  $\cdot cRR = cRT_i$ . At time  $\tau$  a process  $p_i$  starts, the virtual computation laxity  $vc_i$  is  $VC_i$  (=  $minCT_i$ ) and the virtual read laxity  $vr_i$  is  $VR_i$  (=  $cRT_i$ ) [vs]. At each time  $\tau$ , the laxity  $vc_i$  and  $vr_i$  are decremented by the rates  $VCR_{ti}(\tau)$ and  $VRR_{ti}(\tau)$ , respectively. In the simulation, the electric energy consumption  $EE_t$  [W · tu] and active time  $AT_t$ [tu] of each server  $s_t$  are obtained. The active time  $AT_t$  is time when the server  $s_t$  is active, i.e. at least one process is performed. The total electric energy consumption TEEof servers is  $EE_1 + \cdots + EE_4$  and the total active time TAT is  $AT_1 + \cdots + AT_4$ . In the simulation, the termination time  $etime_i$  of each process  $p_i$  is obtained. Here, the execution time  $et_i$  of the process  $p_i$  is  $etime_i - stime_i +$ 1. The average execution time AET of n processes is  $(et_1$  $+\cdots + et_n / n.$ 

The random (RD), round-robin (RR), and SGEAG algorithms are performed on the same pair of a server configuration and a process configuration. In the RD algorithm, a server  $s_t$  is randomly selected for each new process  $p_i$ . In the RR algorithm, after a server  $s_t$  is selected for a previous process, a server  $s_{t+1}$  is selected for a next process. In the SGEAG algorithm, one host server  $s_t$  is selected where the total electric energy  $GE_t$  of all the servers  $s_1, \ldots, s_m$ is minimum. Then, the electric energy consumption  $EE_t$ and active time  $AT_t$  of each server  $s_t$  and the execution time  $et_i$  of each process  $p_i$  are obtained for each server  $s_t$ in each process configuration in the simulation for each algorithm. etime is time when the simulation ends, i.e. a maximum one of  $etime_1, \dots, etime_n$ .

#### 4.2 Evaluation results

Figure 2 shows the total electric energy consumption TEE [W · tu] of the four servers  $s_1, \ldots, s_4$  for number n of processes in each algorithm. The total electric energy consumption TEE of the servers  $s_1, \ldots, s_4$  is  $EE_1 + \cdots + EE_4$  where  $EE_t$  is the electric energy consumption of each server  $s_t$ . The total electric energy consumption TEE of the SGEAG algorithm is minimum in the algorithms. For example, the total electric energy consumption TEE of the SGEAG algorithm is 8% and 11% smaller than the RD and RR algorithms for n = 1,000 and n = 2,000, respectively. As shown here, the total electric energy consumption TEE of the SGEAG algorithm compared with the RD and RR algorithms.

Figure 3 shows the total active time TAT of the servers  $s_1, \ldots, s_4$  for number n of processes. The total active time TAT is  $AT_1 + \cdots + AT_n$  where  $AT_t$  is the active time of each server  $s_t$ . The total active time TAT of the SGEAG algorithm is shorter than the RD and RR algorithms. For example, the total active time TAT of the SGEAG algorithm is about 50 % of the total active time TAT of the RR

and RD algorithms for n = 1,500. This meas, the servers are less loaded in the SGEAG algorithm than the RD and RR algorithms.

Figure 4 shows the average execution time AET [tu] of n processes  $p_1, \ldots, p_n$  on the four servers  $s_1, \ldots, s_4$ . The average execution time AET of the SGEAG algorithm is shorter than the RD and RR algorithms. For example, the average execution time AET of the n processes in SGEAG algorithms is about 35% shorter than the RD and RR algorithms for n = 2,000. The average execution time AET of the RD and RR algorithms exponentially increases as the number n of processes increases. In the SGEAG algorithm, the average execution time AET almost linearly increases.

As shown in Figures 2, 3, and 4, the total electric energy consumption TET and total active time TAT of the servers and the average execution time AET of the processes can be more reduced in the SGEAG algorithm than the RD and RR algorithms.

parameters	DSLab1 $(s_1)$	Atria $(s_2)$	Sunny $(s_3)$	$DSLab2(s_4)$
$np_t$	1	1	1	2
$ncp_t$	8	4	6	8
$nt_t$	16	8	12	32
$CRT_t$ [vs/tu]	1.0	0.7	0.5	1.0
$maxCR_t$ [vs/tu]	16	5.6	6.0	32
$VRR_t$ [vs/tu]	1.0	0.56	0.8	1.0
$minE_t$ [W]	126.1	41.3	87.2	126.1
$maxE_t$ [W]	222.7	91.5	136.2	322.1
$bE_t$ [W]	30	15	16	30
$cE_t$ [W]	5.6	4.7	3.6	5.6
$tE_t$ [W]	0.8	1.1	0.9	0.8
$RE_t$ [W]	21	2	5	21

Table. 2: Parameters of processes.

parameters	values	
n	number of processes $p_1, \ldots, p_n$ .	
α	computation - read ratio factor ( $\alpha = 0.025$ ).	
$minCT_i$ [tu]	minimum computation time (5 $\sim$ 20).	
$cRT_i$ [tu]	canonical read time $(\alpha \cdot minCT_i)$ .	
$minT_i$	$minCT_i + cRT_i = (1 + \alpha) \cdot minCT_i.$	
$VC_i$ [vs]	$minCT_i$ [vs].	
$VR_i$ [vs]	$\alpha \cdot minCT_i$ [vs].	
$stime_i[tu]$	starting time of $p_i$ ( $0 \le st_i < xtime - 1$ ) [tu].	
xtime[tu]	simulation time (= 1000) [tu].	

# 5 Concluding Remarks

In this paper, we newly proposed the improved computation MLCMG model of a server to perform general processes which use both CPU and storages. In the improved MLCMG model, the expected termination time of each process is simply estimated by using only the number of processes performed on each server. Then, we proposed the SGEAG algorithm to select a host server to perform a process issued by a client. Here, a host server  $s_t$  is se-

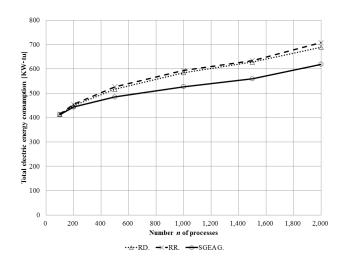


Figure 2: Total electric energy (*TEE*) ( $\alpha = 0.025, m = 4$ ).

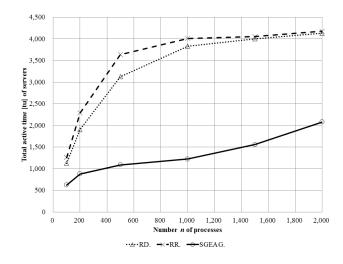


Figure 3: Total active time (TAT) ( $\alpha = 0.025, m = 4$ ).

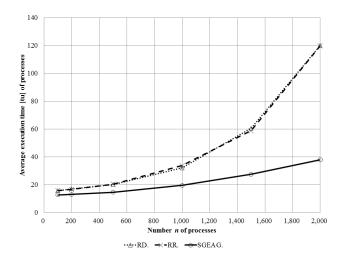


Figure4: Average execution time (AET) ( $\alpha = 0.025$ , m = 4).

lected to perform a new process issued by a client so that the total electric energy to be consumed by the host server  $s_t$  and the other servers is minimized. We evaluated the SGEAG algorithm compared with the RD and RR algorithms in the simulation. We showed the total electric energy consumption and total active time of servers and the average execution time of processes can be reduced in the SGEAG algorithm compared with the RD and RR algorithms. The SGEAG algorithm implies the smallest electric energy consumption of the servers. The average execution time of the processes is also shorter in the SGEAG algorithm than the RD and RR algorithms. The SGEAG algorithm is the best since the electric energy consumption of the servers and the shortest average execution time of the processes are smaller than the RD and RR algorithms.

# Acknowledgment

The author would like to express endless appreciation to my supervisor, Professor Makoto Takizawa, for his kindness, support, and instruction. He always gave the best support and help to the author.

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