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2 Modeled hydraulic redistribution by sunflower (*Helianthus annuus* L.) matches observed data
3 only after including nighttime transpiration
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1 **Abstract**

2 The movement of water from moist to dry soil layers through the root systems of plants, referred
3 to as hydraulic redistribution (HR), occurs throughout the world and is thought to influence
4 carbon and water budgets and ecosystem functioning. The realized hydrologic, biogeochemical,
5 and ecological consequences of HR depend on the amount of redistributed water, while the
6 ability to assess these impacts requires models that correctly capture HR magnitude and timing.
7 Using several soil types and two eco-types of sunflower (*Helianthus annuus* L.) in split-pot
8 experiments, we examined how well the widely used HR modeling formulation developed by
9 Ryel et al. (2002) matched experimental determination of HR across a range of water potential
10 driving gradients. *H. annuus* carries out extensive nighttime transpiration, and though over the
11 last decade it has become more widely recognized that nighttime transpiration occurs in multiple
12 species and many ecosystems, the original Ryel et al. (2002) formulation does not include the
13 effect of nighttime transpiration on HR. We developed and added a representation of nighttime
14 transpiration into the formulation, and only then was the model able to capture the dynamics and
15 magnitude of HR we observed as soils dried and nighttime stomatal behavior changed, both
16 influencing HR.

17

18 **Keyword index**

19 hydraulic redistribution, hydraulic lift, *Helianthus annuus*, sunflower, nighttime transpiration,
20 soil texture

21

22 **Summary Statement**

23 We coupled split-pot hydraulic redistribution (HR) experiments with mathematical
24 modeling to explore the effects of nighttime transpiration on the initiation and maximum

1 magnitude of HR as soils dry, and the ability of the widely-used Ryel et al. (2002, *Oecologia*
2 130: 173-184) model of HR to capture those effects. Using the Ryel formulation, we were
3 unable to match the measured magnitude and pattern of redistribution across a range of
4 water potential driving gradients until we added an empirical representation of nighttime
5 transpiration to the model. The work demonstrates how nighttime transpiration, a process
6 recognized to occur in many species and ecosystems, can diminish the magnitude and alter
7 the pattern of hydraulic redistribution.

10 **Introduction**

11 Hydraulic redistribution, the movement of water from moist to dry soil through the root
12 systems of, primarily, non-transpiring plants, is known to occur in over 60 tree and grass species
13 that grow in xeric, semiarid, temperate and tropical biomes (Caldwell, Dawson & Richards 1998;
14 Horton & Hart 1998; Jackson, Sperry & Dawson 2000; Neumann & Cardon 2012). The process
15 can move water upward, downward and sideways within the soil column, driven by the soil
16 water potential gradient spanning the root system. Both empirical and modeling studies suggest
17 that hydraulic redistribution (HR) can alter carbon and water budgets and ecosystem functioning.
18 The upward movement of water from deep moist soil layers into dry nutrient-rich shallow soil
19 layers where a majority of the root biomass resides can increase dry-season transpiration and
20 photosynthetic rates, maintain or stimulate microbial and/or mycorrhizal activity and increase
21 plant nutrient uptake, maintain soil–root contact, prolong the life span of fine roots, and provide
22 water for seedlings or other shallow-rooted plants. The downward movement of water can
23 facilitate storage of precipitation in deeper soil layers where it does not evaporate (Neumann &
24 Cardon 2012, and references there in).

25 The manner and extent to which HR impacts hydrologic, biogeochemical and ecological
26 processes depends on the amount of water moved by the root system. For example, a noticeable
27 enhancement of transpiration and photosynthetic rates requires redistribution of a large amount
28 of water (i.e., a significant fraction of the daily transpiration demand and more water moved into

1 dry soil layers than that which can be compensated for by deep roots in moist soil layers)
2 (Domec et al., 2010), while maintenance of soil–root contact and fine root life span requires only
3 a small amount of water (Domec et al. 2004; Bauerle et al. 2008). A recent review of the HR
4 literature (Neumann & Cardon 2012) demonstrates that across 16 different ecosystems, the
5 magnitude of redistribution spans more than two orders of magnitude, from 0.04 to 1.3 mm of
6 water per day in empirical studies and from 0.1 and 3.23 mm of water per day in modeling
7 studies. Notably, modeling studies produce HR estimates that are on the upper end of those
8 derived from empirical studies. The large variation in the magnitude of HR is likely due to
9 variations in site and plant characteristics, as well as to empirical and modeling methodological
10 issues (Neumann & Cardon 2012).

11 One of the most commonly used models of HR, developed by Ryel et al. (2002),
12 quantifies the magnitude of HR as a function of conductivity along the water flow path and the
13 driving soil water potential gradient between soil layers. The formulation requires few
14 parameters (root biomass distribution, maximum root–soil conductance, the soil water potential
15 where conductance is reduced by 50%, and an empirical constant), and works within the existing
16 framework of large-scale ecosystem models (e.g., Community Land Model (CLM) (Zheng &
17 Wang 2007; Wang 2011), Integrated Biosphere Simulator (IBIS) (Zheng & Wang 2007), Simple
18 Biosphere model (SiB) (Baker et al. 2008), and Australian community land surface model
19 (CABLE) (Li et al. 2012)). Past implementations of the formulation have assumed that during
20 the day, stomata are fully open and thus the soil-to-atmosphere pathway successfully
21 outcompetes the soil-to-soil pathway for available water, and during the night, stomata are fully
22 closed and thus the soil-to-atmosphere pathway does not compete with soil-to-soil pathway for
23 available water (Ryel et al. 2002; Zheng & Wang 2007; Baker et al. 2008; Scholz et al. 2010;

1 Wang 2011; Li et al. 2012). These assumptions are represented in the formulation with a
2 multiplier (*Dtran*) that is assigned a value of 0 during the day and a value of 1 at night.

3 Over the last decade, however, it has become widely recognized that nighttime
4 transpiration through stomata occurs in multiple species and many ecosystems (Caird, Richards
5 & Donovan 2007; Dawson et al. 2007), and that nighttime transpiration can reduce redistribution
6 (Howard et al. 2009; Scholz et al. 2008; Domec et al. 2012). The current binary *Dtran* term in
7 the Rye1 formulation does not account for this competition between nighttime transpiration (soil-
8 to-atmosphere pathway) and redistribution (soil-to-soil pathway); but competition between the
9 two has important water, carbon and ecosystem implications. For example, water transpired at
10 night rather than redistributed into the soil is not available to enhance next day transpiration and
11 photosynthetic rates, or to stimulate soil biogeochemistry. Further, nighttime transpiration has
12 been shown to reduce water use efficiency since the transpired water is not accompanied by a
13 carbon gain (Caird et al. 2007; Domec et al. 2012). More complex redistribution models
14 developed by Mendel, Hergarten & Neugebauer (2002), Amenu and Kumar (2008), and Siqueira,
15 Katual & Porporato (2008) capture the competition between transpiration and HR, particularly in
16 the context of the diel rhythms of HR and transpiration, but these more complex modeling
17 approaches have not been incorporated into larger-scale models such as CLM, IBIS, SiB, and
18 CABLE. (See Neumann and Cardon (2012) for a review of distinctions among the models).

19 Using several soil types and two eco-types of *Helianthus annuus* (a species that exhibits
20 nighttime transpiration, Howard & Donovan 2007), we examined how well the original Rye1 et
21 al. (2002) formulation matched our experimental determination of HR across a range of water
22 potential driving gradients. The fit of the original model structure was poor, but by developing
23 and adding a representation of nighttime transpiration into the model, it was then able to capture

1 the dynamics and magnitude of HR we observed as soils dried and nighttime stomatal behavior
2 changed.

3

4 **Material and Methods**

5 We used side-by-side balances to determine the magnitude of water redistributed by wild
6 *Helianthus annuus* L. grown in a split-pot configuration (Fig. 1). Below we detail our
7 experimental approach.

8 *Plants, Soils and Growth Conditions*

9 We grew wild *Helianthus annuus* L. from seeds (PI 649859 from California and PI
10 653547 from New Mexico) obtained from the USDA seed bank (<http://www.ars-grin.gov/npgs/>),
11 which were sterilized for 15 minutes in 10% bleach solution containing a drop of Tween, and
12 rinsed thoroughly before germination. We sowed seeds in germination trays containing well-
13 watered vermiculite and covered the trays with a plastic lid and tin foil. We placed the trays in a
14 cold room for a period of 15 to 20 days. The tin foil was then removed, and the trays were moved
15 into a growth chamber with 14-hour days (630 to 730 $\mu\text{moles m}^{-2} \text{s}^{-1}$ of light) and 10-hour nights.
16 The temperature and relative humidity remained constant in the growth chamber at 26 °C and
17 65%, respectively, resulting in a constant vapor pressure demand (VPD) of 1.17 kPa, day and
18 night. The constant day and night conditions were chosen not to mimic what occurs in the
19 environment but to minimize experimental complications caused by oscillations in temperature
20 and humidity, such as condensation of water vapor on the balance plates. The established vapor
21 pressure demand is representative of the nighttime summer VPD at the locations from which the
22 *H. annuus* seeds were collected.

23 After seedlings emerged, we gently rinsed their root systems with water to remove

1 attached vermiculite, and transplanted them into specially designed pots constructed out of 3-
2 inch PVC pipe. The pots consisted of two soil-filled sections, each ~ 15 cm tall, connected by a
3 removable section (~2.5 cm long) filled with sandbox sand. We attached a fine mesh cloth to the
4 bottom of the upper soil-filled section and to both the top and bottom of the lower soil-filled
5 section to contain the soil. We used a mesh that was flexible enough for roots to grow through,
6 allowing both the upper and lower soil volumes to become fully populated with roots. Once the
7 plants were fully developed, we gently rinsed out the sand in the removable middle section of the
8 pot, creating two soil-filled pots connected only by roots (Fig. 1).

9 We used two different types of soil in our experiments: Garden and Arboretum soil.
10 Samples of each were sent to North Carolina State University's (NCSU) Environmental and
11 Agricultural Testing Service Center, where they were analyzed for soil texture (i.e., % sand, %
12 silt, % clay as reported above) and water retention. The Garden soil, obtained from the Harvard
13 University garden, was a sandy soil (91.4% sand, 6.6% silt, 2% clay), with a dark brown/black
14 color and an organic matter content of 7.8% (determined from loss on ignition). The Arboretum
15 soil, obtained from the Harvard University Arboretum, was a sandy loam soil (52.7% sand,
16 40.5% silt, 6.8% clay) with a light red-brown color and an organic matter content of 7.6%
17 (determined from loss on ignition). We also mixed the Arboretum soil half and half with sandbox
18 sand resulting in a loamy sand (80.1% sand, 15.4% silt, 4.5% clay). Both field soils were sieved
19 through a coarse mesh to remove rocks and other large objects. We packed the soil-filled
20 portions of the pots to achieve a bulk density of approximately 1 g/cm³ for all soils.

21 To quantify the relationship between soil water potential and soil water content, we used
22 the SWRC fit web interface (Seki 2007) to fit the NCSU water retention data with Brooks &

23 Corey parameters: $\left(\frac{\theta - \theta_r}{\theta_s - \theta_r}\right) = \left(\frac{\Psi}{\Psi_e}\right)^\lambda$, where θ is water content, θ_r is residual water content, θ_s is

1 saturated water content, Ψ is soil water potential, Ψ_e is air entry water potential, and λ is a non-
2 dimensional parameter (Brooks & Corey 1964) (Fig. 2). Fitted parameter values are in Table 1.

3 We used isopiestic psychrometers (Isopiestic Co., Lewes DE) to determine the water
4 potential of the two soils at field capacity. We packed an experimental pot with field soil,
5 thoroughly watered it, and allowed it to drain. Once water was no longer dripping out of the
6 bottom of the pot, we took a sample of the soil and placed it in the psychrometer chamber. We
7 allowed the soil to sequentially equilibrate with a psychrometer holding a drop of 18 M Ω water
8 (0 MPa), a drop of -0.5 MPa sucrose, and no solution (dry) on its junction. The known solutions
9 were used to establish a calibration curve (current versus water potential), and the dry reading
10 was used to determine the sample's soil water potential (Boyer 1995). The relationship between
11 current and water potential is linear, so only two calibration solutions are required (Boyer and
12 Knippling 1965). The Arboretum and Garden soils had a field-capacity water potential of -0.08
13 MPa and -0.07 MPa, respectively

14 We conducted hydraulic redistribution experiments using five plants, two grown in
15 Garden soil (PI 653547 from New Mexico), two grown in Arboretum soil (PI 649859 from
16 California), and one grown in the 1/2 Arboretum: 1/2 sand mix (PI 649859 from California). For
17 three of these plants, after roots appeared at the bottom of the pot, we laid the pots horizontally in
18 the growth chamber to promote the growth of the plant vertically upwards (Fig. 1a). However,
19 Plant #1 in the Arboretum Soil and the plant in the 1/2 Arboretum: 1/2 sand mix were grown
20 vertically, not horizontally. We transitioned to using horizontally grown plants because the
21 resulting leaf and stem configuration for these plants resulted in a smaller spatial footprint for the
22 experimental setup (Fig. 1a and 1b) (see *HR Experiment: Setup*). All plants were watered daily
23 and fertilized with Peters Professional 20-20-20 general-purpose fertilizer (concentration of 250

1 ppm), as needed. For the horizontal plants, we drilled two access holes into the pots – one in
2 each soil-containing section – to enable watering through 50-ml plastic pipettes.

3

4 *HR Experiment: Setup*

5 We used the *H. annuus* plants in our hydraulic redistribution experiments after they had
6 grown in the chamber for a period of 1.5 to 3.5 months (see Table 2 for exact ages and other
7 developmentally relevant plant characteristics). In preparations for the HR experiment, the top
8 and bottom of the pots were sealed with multiple layers of Parafilm to limit soil evaporation and
9 water drainage out the ends of the pots. We removed the middle section of the pot and gently
10 rinsed out the sand sandwiched between the two soil-filled pot sections. The two pots, now
11 connected only by roots, were attached with zip-ties to two side-by-side balances (Sartorius
12 model GW6202, 0.01g resolution) using braces Velcroed to the balance plates (Fig. 1a for
13 horizontally grown plants and Fig. 1b for vertically grown plants). To limit evaporation, we
14 wrapped the gap spanned by the roots with plastic that we taped to the two pots. We cut a hole in
15 the bottom of the bag to allow for water drainage, which was caught by a trough laid between the
16 balances. The balances were connected to a computer running Labview (National Instruments)
17 that recorded data from the balances every minute. After attaching the plants to the balances, we
18 checked the weight transfer between pots by systematically placing 200g, 100g and 50g weights
19 on the top and bottom portion of each soil-filled pot section and noting the weight change
20 detected by the adjacent balance. We found the weight transfer between pots ranged from only
21 0.3% to 1.4% of the applied weight (see SI Table 1).

22 A few days after placing the plants on the balances, the roots spanning the two pots
23 visually changed. The root surface dried out and turned from a white to brown color, suggesting

1 formation of a suberized layer. Past studies have demonstrated that roots exposed to air develop
2 exodermal suberin lamellae that restrict radial water loss (Clarkson et al. 1987; Enstone &
3 Peterson 1998). The roots remained capable of transporting water, as demonstrated by daily
4 weight changes in the bottom pot (e.g., weight loss during the day).

5
6 *HR Experiment: Standard Protocol*

7 Our hydraulic redistribution experiments involved drying out the soil in both pots by
8 allowing the plants to transpire for multiple days and nights, watering the top pot to create a
9 water potential difference between the two pots, and monitoring the nighttime weight change in
10 the bottom pot. This approach mimics the process of downward HR in the field, with shallow
11 soil layers receiving water during rain events. We chose to water the top pot because if we had
12 watered the bottom pot, water could have moved through the roots from the bottom pot into the
13 roots of the top pot and then continued up into the aboveground portion of the plant (i.e., leaves
14 and stems). In such a situation, re-hydration of aboveground biomass would have likely
15 dominated any resulting weight change in the top pot. By watering the top pot and watching
16 redistribution in the bottom pot, we minimized the weight contribution of water remaining in the
17 plant biomass (i.e., roots only).

18 We initiated our experiment by watering both pots to field capacity and zeroing the
19 balances. We withheld water and allowed the plants to transpire until the soil had reached a
20 desired level of dryness. We then bagged both a single leaf and the entire plant top after the
21 lights in the chamber turned off. Five hours after bagging, we cut the bagged leaf and
22 immediately measured its water potential using a pressure chamber (Soil Moisture Equipment
23 Corp., Santa Barbara, CA). We assumed the measured leaf water potential reflected the soil

1 water potential in both pots, since in all of our plants, both pots lost approximately the same
2 amount of water. We then watered the top pot to field capacity, which brought the soil water
3 potential in this pot to -0.07 MPa for the Garden soil and -0.08 MPa for the Arboretum soil —
4 the potentials measured using isopiestic psychrometers for the soils at field capacity. Thus, we
5 created a soil water potential difference between the two pots equal to -0.07 MPa (Garden)
6 or -0.08 MPa (Arboretum) minus the measured leaf water potential. We determined the
7 redistribution rate from the slope of a linear fit to the weight change in the bottom pot over the
8 remainder of the night (see SI Fig. 1 for one example). We left the plant to transpire the
9 following day, and re-watered both pots to field capacity the following night, repeating the
10 experimental sequence after achieving a different level of soil dryness by allowing the plants to
11 transpire for a longer period of time. For our last data point, we cut with scissors and completely
12 removed the roots between the two pots before watering the top pot. We left the plastic bag
13 spanning the gap between the pots in place, and thus, nighttime weight changes measured in the
14 bottom pot for this time point could account for any potential transfer of water vapor across the
15 air gap between the pots (a positive weight change in the bottom pot) and for soil evaporation (a
16 negative weight change in the bottom pot). We found that with the roots cut, the bottom pot lost
17 water (from 0.05 to 0.1 g/hr). We adjusted our calculated HR rates by this measured amount.

18 Upon completing the experiment, we dissected the pots to determine dry root biomass.
19 We emptied the contents of each pot into a plastic tub, which we filled with water. The soil sank
20 to the bottom of the tub, while the roots floated. We agitated the soil to release the roots, and
21 then captured the floating roots by decanting the water through a fine mesh screen. We refilled
22 the tub multiple times, repeating the process until we had captured a majority of the roots. After
23 removing other floating material from captured roots, we allowed the roots to air dry. Once fully

1 dry, we measured root weight on a balance (Sartorius, 0.0001g resolution).

2

3 *HR Experiment: Variations to the Standard Protocol*

4 Not all plants experienced exactly the standard protocol, both because the protocol
5 evolved slightly during experiments and because particular pieces of data essential for modeling
6 could not be gathered using the standard protocol. We did not bag the tops of Plant 1 in the
7 Arboretum soil and the plant in the ½ Arboretum: ½ sand mix before collecting leaves for
8 nighttime leaf water potentials (i.e., the leaves used to determine soil water potential of the dry
9 soil). We did, however, bag the leaves used to measure leaf water potential. To account for the
10 difference between leaf water potentials measured with and without bagged tops, we conducted a
11 separate experiment with *H. annuus* plants grown in the same PVC pots packed with the same
12 soils. While drying out the soil in these pots, we first measured leaf water potentials without a
13 bagged top, and then bagged the plant top, and measured leaf water potentials five hours later.
14 We used the resulting linear relationship ($r^2 = 0.91$) between the two leaf water potentials (see SI
15 Fig. 2) to adjust the measured leaf water potentials for these two plants. In addition, we did not
16 cut the roots of these two plants at the end of the HR experiment. Thus, we used the average
17 evaporation rate from the other plants (-0.07 ± 0.03 g/hr) to adjust the calculated HR rates for
18 these two plants.

19 For Plant 1 in the Arboretum soil, we also did not measure dry root biomass. Instead,
20 after the HR experiment we de-topped this plant to measure well-watered soil–root conductance.
21 We brought the soil up to field capacity, de-topped the plant under water, and sealed it in a
22 Passioura-style root pressure chamber (Passioura and Munns 1984) that we placed on a high-
23 capacity balance (Sartorius, resolution 0.1 g). We measured the flow rate of water out of the

1 plant versus chamber pressure four times over the course of three days. We set the well-watered
2 conductance equal to the slope of the line fitted through the average flow rate (n=4) versus
3 chamber pressure (see SI Fig 3). For the other four plants, we estimated conductance by scaling
4 the measured value for Plant 1 in Arboretum soil by the maximum transpiration rate of each
5 plant (see Table 2). This approach assumes that the maximum transpiration rate of the plants is
6 directly proportional to soil–root conductivity (Becker, Tyree & Tsuda 1999, Lee et al. 2005).

7

8 *Root-Scale Soil Physics Model*

9 To examine the effect of soil texture alone on the magnitude of HR-associated water flow
10 from a hypothetical single root into our experimental soils, we solved the one-dimensional radial
11 form of Richard’s equation $\left(\frac{\partial \theta}{\partial t}\right) = \frac{1}{r} \frac{\partial}{\partial r} \left(rK \frac{\partial \Psi}{\partial r} \right)$, where t is time, and r is radial distance from the
12 center of the root (Richards 1931) using a Kirchoff transform $\left(\Phi = \int_{-\infty}^{\Psi} K d\Psi\right)$, where Φ is the
13 Kirchoff transform variable) (Ross & Bristow 1990) and the pdepe function in MATLAB
14 (<http://www.mathworks.com/help/techdoc/>). We used our fitted Brooks & Corey parameters for
15 the soil water retention curves (Fig. 2) and default conductivity functions (Rawls, Brakensiek &
16 Saxton 1982) for a sandy loam (Arboretum soil) and sand (Garden soil). All model parameter
17 values are in Table 1. Our boundary conditions included a constant water potential of -0.07 MPa
18 at the soil–root interface, which was set at a radius of 0.05 cm, and constant water potential
19 (equal to the initial water potential) at the outer edge of the soil domain, which was set at a radius
20 of 50 cm to ensure the boundary was sufficiently far from the area of interest. We specified a
21 uniform initial soil water potential for the soil domain, the value of which we varied across
22 simulation runs.

23

1 *Plant-Scale HR Model*

2 We fit our experimental data to the widely-used Ryel HR formulation (Ryel et al. 2002),
3 which models HR at the whole-plant scale, using the fit function in MATLAB
4 (<http://www.mathworks.com/help/techdoc/>). The Ryel formulation, as modified by Scholz et al.
5 (2010) is represented as:

$$6 \quad HR_i = C_{RT} \sum_j (\Psi_j - \Psi_i) \min(c_i, c_j) \frac{R_i R_j}{1 - R_i} D_{tran} \quad (1)$$

7 where HR_i is net water movement into soil layer i from other layers (j), C_{RT} is the maximum
8 radial soil–root conductance of the root system, c_i is a factor ranging from 0 to 1 reducing soil–
9 root conductance based on Ψ_i , R_i is the fraction of active roots in layer i , and D_{tran} is a factor
10 ranging from 0 to 1 reducing redistribution due to transpiration. In previous studies, D_{tran} was
11 operationally set to zero during the day and one during the night (Ryel et al. 2002; Zheng &
12 Wang 2007; Baker et al. 2008; Scholz et al. 2010; Wang 2011; Li e al. 2012). However, Ryel et
13 al. (2002) note that the term could be modified to allow HR to occur when transpiration rates are
14 limited by stomatal conductance. The c_i term is empirically modeled with the relationship:

$$15 \quad c_i = \frac{1}{1 + \left(\frac{\Psi_i}{\Psi_{50}}\right)^b} \quad (2)$$

16 where Ψ_{50} is the soil water potential where soil–root conductance is reduced by 50% and b is an
17 empirical constant.

18

19 **Results**

20 *Hydraulic Redistribution Experiments*

21 Figure 3a shows the magnitude of HR as a function of water potential differences
22 between top and bottom pots; data are normalized in Fig. 3b to the measured maximum

1 transpiration rate. In both panels, vertical error bars represent propagated error resulting from
2 adjustments and normalizations made to the data. The error values used in the propagation
3 calculations include two times the standard error of the fitted slope to the nighttime weight data
4 and pot evaporation data (panel A), and two times the standard error of the fitted slope to the
5 nighttime weight data and transpiration data (panel B). Horizontal error bars are estimates of
6 experimental error associated with measuring leaf water potentials (i.e., the difference in
7 pressure at which water was visually seen at stele surface as leaf was pressurized, slightly de-
8 pressurized and then re-pressurized multiple times, and stopping when pressures began to
9 decrease due to water loss from the system). The horizontal error bars for Plant 1 in the
10 Arboretum soil and the ½ Arboretum: ½ sand mix are larger than for the other plants because the
11 tops of these two plants were not bagged before leaves were collected for leaf water potential
12 measurements. Resulting values were adjusted with data comparing leaf water potentials from
13 bagged and unbagged plants (see SI Fig. 2), and the error (standard error on the slope and
14 intercept of the fit) was propagated through this adjustment process. Where noted by symbols in
15 the figure, weight changes for three HR events were not linear (star symbol).

16 While the magnitude of hydraulic redistribution varied in our experiment, the general
17 pattern of redistribution across water potential driving gradients did not (Fig. 3a). In all five
18 plants, we did not detect HR when water potential differences between the top and bottom pots
19 were small (i.e. when soil in the bottom pot was relatively moist). Instead, even when corrected
20 for evaporation (see Methods), we detected a water loss from the bottom pot, indicating the
21 occurrence of nighttime transpiration. Redistribution, or a weight gain in the bottom pot, did not
22 occur until the soil water potential difference between the two pots increased to 0.7 MPa (i.e.,
23 water potential in the bottom pot decreased below -0.7 MPa). In our experiment, after this

1 “initiation” threshold was surpassed, HR increased and reached a peak at a soil water potential
2 difference of 1.5 to 2 MPa. HR then decreased as soil water potential differences continued to
3 increase due to drier soil conditions in the bottom pot.

4 The maximum amount of HR measured for the five individual plants in our HR
5 experiment ranged from 0.2 to 2 g/hr (Fig. 3a), representing 1 to 14% of the maximum measured
6 whole-plant transpiration rate (Fig. 3b). However, most of the redistributed water was not fully
7 utilized the next day. When the water potential difference between pots was large, the bottom pot
8 continued to gain water during the day though transpiration was active; in the cases when the
9 bottom pot received water during the night and lost water during the day, the amount lost to
10 transpiration was 1.5 to 7 times less than the amount of water redistributed into the pot the
11 previous night. These results suggest that the plant was able to meet its transpiration demand
12 with water from the moist upper pot, and that in our experimental setup, HR did not enhance
13 next day transpiration rates. Further, the results illustrate the competition for water that exists
14 between the soil and atmosphere, with dry soil conditions (i.e., low soil water potentials) in the
15 bottom pot pulling water out of the moist top pot during daytime transpiration. In subsequent
16 sections, we focus on the competition for water between the atmosphere and soil from the
17 perspective of nighttime redistribution. Mainly, the role that nighttime transpiration plays in
18 limiting HR. Both situations highlight that a binary depiction of the impact of transpiration on
19 HR (i.e., setting the D_{tran} term in the Ryel formulation, Eqn. 1, to 0 or 1) does not correctly
20 capture the occurrence of either daytime or nighttime redistribution.

21 Soil texture and plant characteristics varied in our HR experiments. Our goal was to
22 create combinations of plant and soil that generated a range of magnitudes and patterns in HR,
23 but we were not explicitly testing the effects of soil texture and plant ecotype on HR in, for

1 example, a full factorial design. The California ecotype was grown in the Arboretum and ½
2 Arboretum: ½ sand mix soils and the New Mexico ecotype was grown in the Garden soil. The
3 impact of soil and plant variation on HR becomes clear when the HR data are normalized by the
4 maximum transpiration rate (Fig. 3b). After the normalization, the points gathered from the two
5 plants in Arboretum soil fall more closely together across the range of water potential
6 differences, and are distinct from points gathered from the two plants in Garden soil and the
7 plant in the ½ Arboretum: ½ sand mix. Based on these normalized data, the New Mexico ecotype
8 in the Garden soil appears to promote proportionally more HR per unit maximum transpiration
9 than the California ecotype in the Arboretum soil, which, in turn, promotes more HR per unit
10 maximum transpiration than the California ecotype in the ½ Arboretum: ½ sand mix.

11

12 *Root-Scale Soil-Physics Modeling Results*

13 We used a soil physics model to explore how much redistributed water the Arboretum
14 and Garden soils can theoretically accommodate flowing from an individual root as a function of
15 soil water potential. Over a 10-hour period, the model simulated the movement of three orders
16 of magnitude more water into the Arboretum soil than into the Garden soil (Fig. 4a,b). The
17 Garden soil's steeper water retention curve (Fig. 2) limits the movement of water through the soil
18 (i.e., a small change in water content results in a large decrease in soil water potential) while its
19 lower saturated water content and higher residual water content (Table 1) reduces the amount of
20 water the soil can accommodate. However, in the split-pot experiments (Fig. 3a), where soil
21 physics was coupled with variable plant characteristics, the magnitude of water redistributed into
22 the different soil types did not follow that predicted by the soil-physics model. The plants in the
23 Garden soil redistributed more water than the plants in the Arboretum soil.

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Plant-Scale HR Modeling Results

The Ryel HR formulation (Ryel et al. 2002), used in many large-scale modeling studies (Ryel et al. 2002; Zheng & Wang 2007; Baker et al. 2008; Scholz et al. 2010; Wang 2011; Li et al. 2012), includes a term that decreases redistribution with soil drying (c_i , which is a function of Ψ_{50} and b , see Eqn. 2). We detected a decrease in HR with soil drying in our experiments (Fig. 3a). However, we were unable to fit our experiment data with the published formulation. Figure 5 shows fits to experimental data given variations in Ψ_{50} and b for Plant 1 in the Arboretum soil, the plant for which we had a measured value of soil-root conductance (i.e., C_{RT} , see Eqn. 1). Regardless of the values of Ψ_{50} and b , the only unknown parameters, the formulation was unable to simultaneously match the magnitude of HR and the water potential difference between pots at which that maximum occurred. For example, Ψ_{50} set at -0.25 MPa approximately captured the appropriate magnitude of maximum HR when b was equal to 1 (Fig. 5a), but when the formulation captured the water potential difference at which the maximum amount of redistribution occurred (x axis ~1.75 MPa, Fig. 5c), it dramatically overestimated the magnitude of maximum HR. The inability of the Ryel formulation to fit our data was not limited to plant 1 in the Arboretum soil. Figure 6 shows the published formulation's best fit to our normalized experimental data sets in the Arboretum and Garden soils (i.e., data normalized by soil-root conductance (C_{RT} , Eqn. 1) see Table 2 for values). The r^2 values for the fits are low (0.35 and 0.23 for the Arboretum and Garden soils, respectively, Table 3).

The poor fit suggests that the Ryel formulation is not accounting for some process or behavior in our experiment that was influencing the magnitude and pattern of redistribution across water potential driving gradients. Our experimental data suggest nighttime transpiration

1 was an important factor. Figure 7 shows that redistribution of water into the bottom pot did not
2 occur when the plants had high rates of nighttime transpiration. Thus, we decided that to
3 correctly represent both the magnitude and pattern of hydraulic redistribution in our experiments,
4 the Ryel et al. (2002) model needed a more complex D_{tran} term that accounted for nighttime
5 transpiration.

6 We chose to represent nighttime transpiration with an empirical logistical function
7 originally created by Tuzet et al. (2003) to describe the sensitivity of stomata to leaf water
8 potentials during the day. The Tuzet function varies between zero and one, and assumes that
9 stomata remain open when bulk leaf water potentials are near zero and close as leaf water
10 potentials drop. To capture the sensitivity of nighttime stomatal behavior to soil drying observed
11 in the field (e.g. reviewed by Dawson 2007), we slightly modified the function to describe the
12 sensitivity of stomata to the average soil water potential during the night:

$$13 \quad D_{tran} = 1 - \frac{1 + \exp(s_f \psi_f)}{1 + \exp(s_f (\psi_f - \psi_s))} \quad (3)$$

14 where ψ_s is the average soil water potential experienced by the plant (i.e., soil water potential in
15 a soil layer scaled by root biomass fraction), ψ_f is a reference potential, and s_f is a sensitivity
16 parameter. The parameters (ψ_f and s_f) account for the sensitivity of stomata in different species to
17 soil water potential, with larger s_f and ψ_f values signifying greater sensitivity at higher soil water
18 potentials, respectively. The function works well for describing the response of stomata during
19 the night to drying soil conditions, with stomata remaining open enough at moist soil water
20 potentials to allow for nighttime transpiration and closing at drier soil water potentials to limit
21 nighttime transpiration. Simpler D_{tran} formulations, such as a linear response of stomata to soil
22 moisture, did not provide a satisfactory fit to our experimental data. Further, the species-specific
23 flexibility of the Eqn. 3 is important because nighttime stomata conductance can vary

1 substantially among species (Caird et al. 2007). The one minus portion of the right-hand side of
2 Eqn. 3 accounts for the fact that nighttime transpiration limits HR.

3 After including the modified D_{tran} term to the Ryel formulation, we were better able to fit
4 our experimental data (Fig. 6). The r^2 value for the fit to the Arboretum- and Garden-soil data
5 sets were 0.79 and 0.99, respectively (Table 3). The 95% confidence range for the D_{tran}
6 parameters (i.e., Y_f , s_f) from the fit to the Garden-soil data set was narrow, while that from the fit
7 to the Arboretum-soil data set was wide. In fact, the 95% confidence range for the parameters
8 from the Arboretum-soil data set encompassed the parameter values from the Garden-soil data
9 set. Given this overlap and that fact that *Helianthus* species have similar nighttime stomatal
10 conductance (Caird et al., 2007; Howard & Donovan 2007), we chose to further simplify the new
11 model formulation by using the D_{tran} parameters values obtained from the Garden-soil data set to
12 re-fit the Arboretum-soil data set. The result is the dotted line in Fig. 6a — a similar fit to that
13 obtained initially, but with smaller confidence ranges for the fitted parameters (Table 3). Figure
14 8a shows the fitted D_{tran} and c_i functions for the experimental data sets.

15

16 **Discussion**

17 *Nighttime Transpiration*

18 Data from our redistribution experiments along with our efforts to fit these data with the
19 Ryel HR formulation highlighted the significant influence that nighttime transpiration can have
20 on the magnitude of HR across a range of water potential driving gradients. Past studies focused
21 on the phenomenon of nighttime transpiration have demonstrated both that it can restrict
22 redistribution in *H. annuus* and other species (Howard et al. 2009), and that it is strongly
23 connected to soil moisture and vapor pressure demand (VPD), with more transpiration occurring

1 at moist soil water potentials and high VPD (Dawson et al. 2007; Howard & Donovan 2007). In
2 our experiment, *H. annuus* consistently transpired during the nighttime redistribution events that
3 we stimulated (Fig. 7). The higher nighttime transpiration rates coincided with moist soil
4 conditions in the bottom pot (or with small differences in water potential between the two pots
5 with the top pot always at field capacity during the HR events), aligning with expectations. At
6 these small water potential differences (or moist soil conditions), nighttime transpiration
7 overwhelmed redistribution. Net redistribution did not occur until nighttime transpiration
8 dropped below 1 g/hr (Fig. 7), which coincided with the bottom pot drying out to approximately
9 -0.7 MPa (i.e., a water potential difference of 0.7 MPa, Fig. 3). This type of HR “initiation”
10 threshold has been detected in multiple field studies where HR did not begin until water
11 potentials in the dry soil layer dropped below -0.4 to -0.8 MPa (Ishikawa & Bledsoe 2000;
12 Domec et al. 2004; Meinzer et al. 2004). In our experiment, the threshold appears related to
13 competition for water between soil and nighttime transpiration.

14 The modified and fitted D_{tran} term (Fig. 8a) accounts for this competition between soil
15 and nighttime transpiration. For small water potential differences (i.e., moist soil conditions in
16 the bottom pot) the fitted D_{tran} term is zero, completely stopping redistribution. As the water
17 potential difference between pots increases (i.e., soil in the bottom pot dries), the term continues
18 to restrict redistribution, though with decreasing impact. The logistical function we used for the
19 D_{tran} term (Eqn. 3) is dependent on soil moisture, and thus, only captures the sensitivity of
20 nighttime transpiration to soil moisture. However, vapor pressure demand also exerts an
21 influence on nighttime transpiration rates (Dawson et al. 2007; Howard et al. 2009; Howard &
22 Donovan 2007). Our experiment did not explicitly test variations of VPD on the rate of HR, as
23 our growth chambers maintained a constant VPD day and night. Inclusion of a VPD response in

1 the D_{tran} term is warranted given the clear impact it can have on nighttime transpiration rates.

2

3 *Magnitude of HR*

4 The amount of water redistributed by our five experimental plants varied over an order of
5 magnitude, though the same species was grown in identically sized pots under the same climatic
6 conditions. These results highlight the significant impact that natural variations among soils and
7 individual plants can have on the amount of redistributed water— making it difficult to
8 accurately predict and model the amount of redistribution occurring in the environment. A key
9 plant characteristic responsible for some of this variation is soil–root conductance, or the
10 capacity of the plant and soil system to move water. Soil–root conductance estimated from
11 maximum transpiration rates for the five plants varied by a factor of three (Table 1). When the
12 redistribution data were normalized by maximum transpiration, the data sets became more
13 congruent within soil types (Fig. 3b), but an order of magnitude variation still existed in the
14 relative proportion of water redistributed by the plants.

15 These normalized data highlight the role that soil texture and plant characteristics exert
16 on the magnitude of redistribution. For the same ecotype, an increase in the percent of sand in
17 soil resulted in a decrease in normalized redistribution (Fig. 3b, California ecotype in Arboretum
18 vs. ½ Arboretum: ½ sand soil). This behavior is expected based on published empirical and
19 modeling studies that found sandy soils promote less HR than loamy soils (Schippers, Schroth &
20 Hildebrand 1967; Yoder & Nowak 1999; Siqueira et al. 2008; Wang et al. 2009; Prieto et al.
21 2010a). However, the New Mexico ecotype, growing in sandier Garden soil, redistributed
22 proportionately more water than the California ecotype growing in loamier Arboretum soil (Fig.
23 3b), even though our soil physics modeling suggested that the loamier Arboretum soil can

1 accommodate more redistribution than the sandier Garden soil (Fig. 4). These results
2 demonstrate the significant role that plant characteristics play in controlling the magnitude of
3 redistribution. Possible characteristics contributing to the different capacities of the ecotypes to
4 redistribute water include, among others, root biomass (the New Mexico ecotype has more dry
5 root biomass than the California ecotype, Table 2), root diameter and root size distribution,
6 vulnerability of root xylem to embolism, and ability of roots to maintain a connection with to the
7 soil. Only the first characteristic (root biomass) was assessed in our experiment.

8

9 *Pattern of HR Across Water Potential Driving Gradients*

10 The most striking aspect of our data set was the consistent pattern of redistribution among
11 the five plants, with no redistribution followed by an increase and then decrease in redistribution
12 as the water potential different between pots increased (i.e., the bottom pot dried out) (Fig. 3).
13 Empirical field studies have similarly seen HR increase as soil layers dry, reach a maximum, and
14 then decrease or plateau with continued soil drying (Meinzer et al. 2004; Warren et al. 2005;
15 Scholz et al. 2008; Prieto, Kikvidze & Pugnaire 2010b).

16 The Ryel et al. (2000) HR formulation, as published, captures the increasing and then
17 decreasing behavior in HR. In the formulation, HR increases as the water potential difference
18 driving flow increases, but as the contributing and/or receiving soil layers dry, the c_i term
19 decreases, reducing the modeled amount of HR (e.g., Fig. 5 and Fig. 8). However, the published
20 formulation does not capture the initial lack of redistribution, nor the magnitude and location of
21 maximum redistribution seen in our experiments. The inclusion of a more complex D_{tran} term
22 that represents the nighttime response of stomata to soil conditions allowed the modeled amount
23 of HR to capture these characteristics. Notably, the inclusion of nighttime transpiration in the

1 formulation reduced the amount of modeled HR and shifted the location of peak HR into drier
2 soil conditions (i.e., larger water potential differences between pots) (Fig. 8b and c).

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1 **Table 1.** Values for Brooks & Corey Water-Retention Parameters

	θ_s	θ_r	λ	ψ_e (MPa)	K_s (cm/hr)*	$\eta=3+2/\lambda$
Arboretum Soil	0.4	0	0.230	-0.0016	30.5	11.7
Garden Soil	0.35	0.06	0.535	-0.0005	32.0	6.7

2 * default values from Rawls et al. (1982) for sandy loam (Arboretum soil) and sand (Garden soil)

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Table 2. Characterization of plants used in redistribution experiments

Plant	Maximum Well-Watered Transpiration Rate (g/hr)	Well-Watered Soil–Root Conductance, C_{RT} in Eqn. 1 (g/hr/MPa)	Age of Plant at Start of Exp. (weeks) ^a	Plant Height at Start of Exp. (cm)	Number of leaves at Start of Exp.	Dry Root Biomass at End of Exp. (g)
Arboretum Soil CA Ecotype Plant 1	14.1	12.2	18	n.m. ^c	n.m.	n.m.
Arboretum Soil CA Ecotype Plant 2	6.3	5.5 ^b	20	69	~100 small leaves	9.5
Top Pot						5.6
Bottom Pot						3.9
Garden Soil NM Ecotype Plant 1	11.6	10.1 ^b	10.5	29	12 big and 28 small leaves	26.3 ^d
Top Pot						17.3 ^d
Bottom Pot						9.0
Garden Soil NM Ecotype Plant 2	13.6	11.8 ^b	10.5	29	12 big and 26 small leaves	25.0 ^d
Top Pot						19.6 ^d
Bottom Pot						5.4
½ Arboretum: ½ sand CA Ecotype	19.5	16.9 ^b	14	45	~125 small leaves	7.8
Top Pot						4.7
Bottom Pot						3.1
^a Weeks since seeds placed in growth chamber.						
^b Estimated by scaling measured conductance for Plant 1 in Arboretum Soil by the maximum well-watered transpiration rates.						
^c Not measured.						
^d Includes stem below the soil surface.						

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1 **Table 3.** Parameter Values and Statistics for Fit to Ryel HR Formulation

	Soil	Ψ_{50} MPa	95% conf. bounds	b	95% conf. bound s	Ψ_f MPa	95% conf. bounds	s_f	95% conf. bounds	sse 10^{-3}	r^2
Night: As published	Arbor. Soil	-0.001	-0.03, 0.03	0.41	-0.79, 1.61					5.8	0.36
	Garden Soil	-0.60	-1.84, 0.64	1.95	-1.58, 5.48					2.7	0.23
Night: Model with nighttime transp.	Arbor. Soil	-1.76	-4.45, 0.92	6.61	-0.91, 14.12	-1.41	-6.17, 3.34	2.92	-16.85, 22.69	2.2	0.76
	Arbor. Soil w/ Garden Param.	-1.56	-1.74, -1.38	6.81	4.43, 9.18	-1.04	n/a	6.68	n/a	2.5	0.73
	Garden Soil	-1.89	-1.92, -1.86	15.28	13.54, 17.03	-1.04	-1.07, -1.00	6.68	5.81, 7.55	.007	0.99

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1 **Figure Captions**

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3 **Figure 1:** HR experimental setup for A) horizontally grown plants and B) vertically grown
4 plants.

5 **Figure 2:** Water retention curves (i.e., water content versus water potential) for the Garden and
6 Arboretum experimental soils. The closed symbols represent data collected by NCSU
7 Environmental and Agricultural Testing Service Center. The open symbol represents the
8 saturated water content determined from drainage tests. Data were fit with Brooks and Corey
9 parameters. The fit for the Garden soil had an r^2 of 0.99, and the fit for the Arboretum soil had an
10 r^2 of 0.98. Fitted parameter values are in Table 1.

11 **Figure 3:** Data from HR experiments. A) Nighttime weight change in the bottom pot versus
12 water potential difference between the two pots. The top pot remained at field capacity for all of
13 the experiments. B) Nighttime weight change in the bottom pot normalized by the maximum,
14 well-watered transpiration rate (see Table 2) versus water potential difference between pots. See
15 text for descriptions of error bars (which, in some cases, are small enough to be hidden
16 underneath symbols).

17

18 **Figure 4:** Results from root-scale soil-physics model. Simulated cumulative nighttime (10-hour)
19 radial flux of water through A) Arboretum and B) Garden soil. X-axis identifies initial water
20 potential for soils. Note the y-axis scale difference for the two panels. C) Soil conductivity
21 functions used in model.

22

23 **Figure 5:** Measured versus modeled HR using Ryel formulation (Eqn. 1) for Plant 1 in the
24 Arboretum soil.

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26 **Figure 6:** Measured versus modeled HR for experimental data sets normalized by estimated
27 soil–root conductance (Table 2), i.e., C_{RT} term in Ryel formulation (Eqn. 1) A) Plants in
28 arboretum soil. B) Plants in Garden soil. Grey line indicates best fit to data using unmodified
29 Ryel formulation. Black lines indicate best fit to data with nighttime transpiration modification
30 (Eqn. 3). Dotted black line indicates fit to data from plants in Arboretum-soil data using
31 parameters developed from plants in Garden soil.

32

33 **Figure 7:** Relationship between nighttime weight change in bottom pot and nighttime
34 transpiration for all five experimental plants.

35

36 **Figure 8:** Summary of experimental and modeling results. A) Fitted functions for c_i and D_{tran}
37 terms in the Ryel formulation (Eqns. 1, 2, and 3) based on experimental data. B & C) Modeled
38 redistribution normalized by soil–root conductance (i.e., C_{RT} in Eqn. 1) for plants in B) Garden
39 and C) Arboretum soil both with and without nighttime transpiration (i.e., inclusion of D_{tran}).

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Figure 1

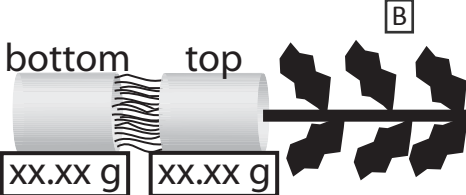
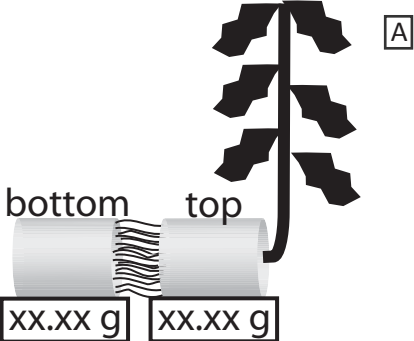


Figure 2

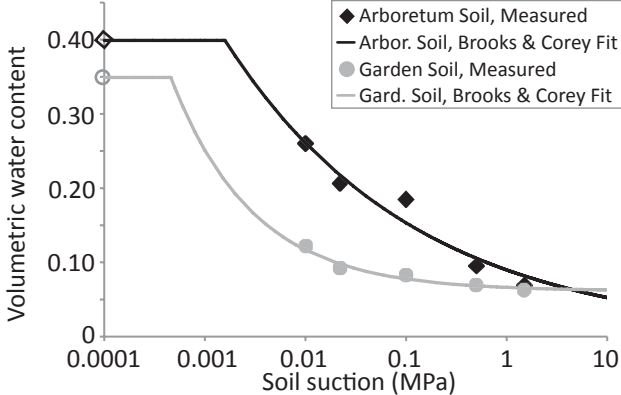


Figure 3

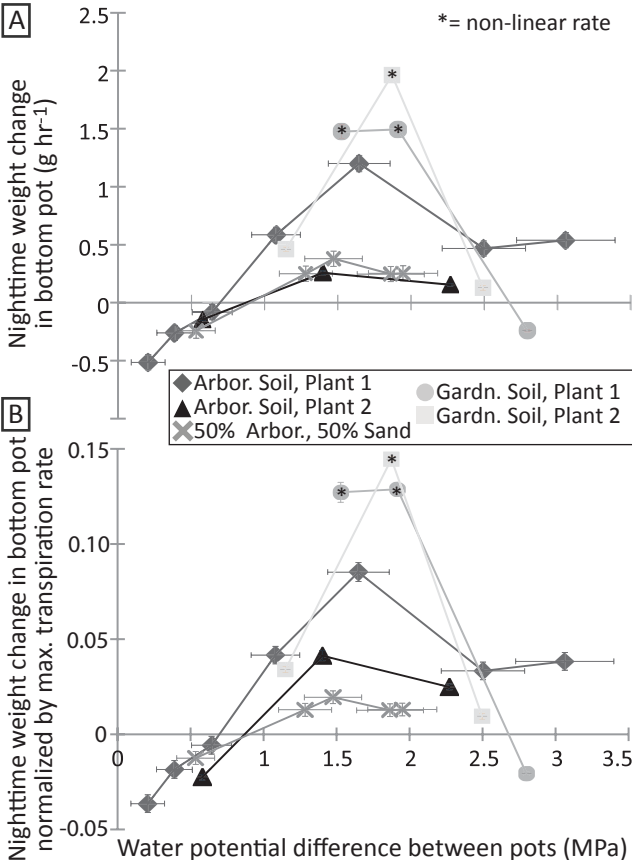


Figure 4

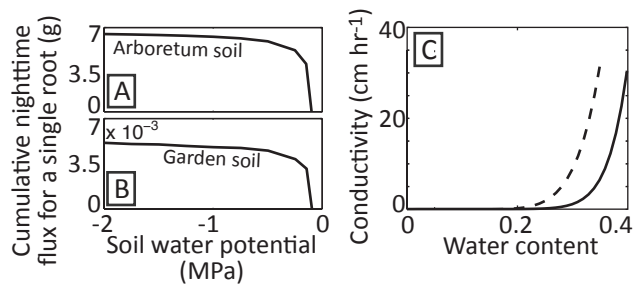


Figure 5

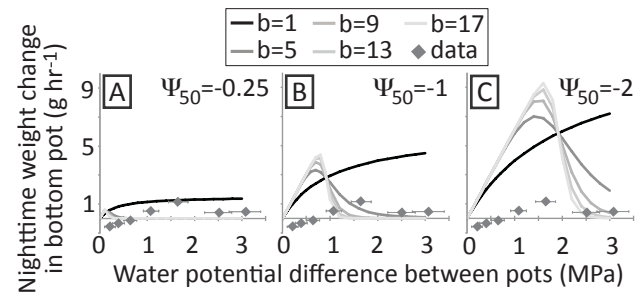


Figure 6

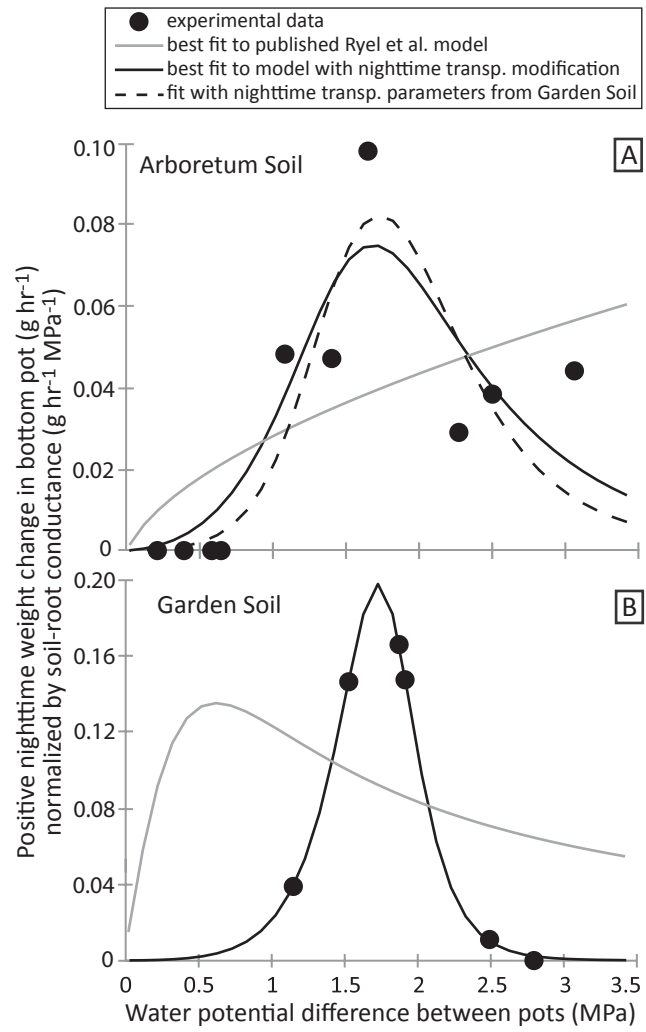


Figure 7

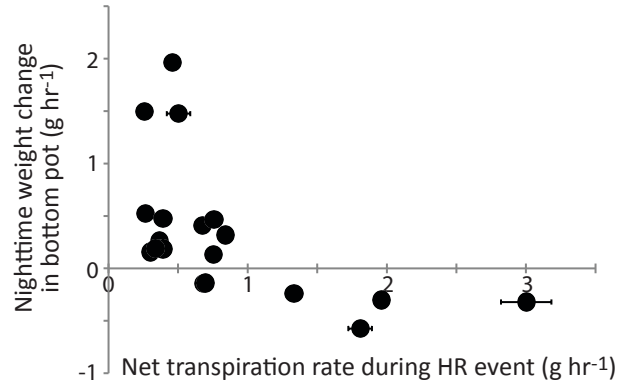


Figure 8

