

Proofs for "Discretization of Homogeneous Systems Using Euler Method with a State-Dependent Step"

Denis Efimov, Andrey Polyakov, Alexander Aleksandrov

▶ To cite this version:

Denis Efimov, Andrey Polyakov, Alexander Aleksandrov. Proofs for "Discretization of Homogeneous Systems Using Euler Method with a State-Dependent Step". 2019. hal-02164050

HAL Id: hal-02164050 https://hal.inria.fr/hal-02164050

Preprint submitted on 24 Jun 2019

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers. L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

Proofs for "Discretization of Homogeneous Systems Using Euler Method with a State-Dependent Step"

Denis Efimov^{a,b}, Andrey Polyakov^{a,b}, Alexander Aleksandrov^c

^aInria, Univ. Lille, CNRS, UMR 9189 - CRIStAL, F-59000 Lille, France

^bITMO University, 49 av. Kronverkskiy, 197101 Saint Petersburg, Russia

^cSaint Petersburg State University, 7-9 Universitetskaya nab., 199034 Saint Petersburg, Russia

Abstract

This note contains some proofs for the paper "Discretization of Homogeneous Systems Using Euler Method with a State-Dependent Step" of the same authors.

Key words: Homogeneous systems; Discretization; Euler method.

1 Proof of Theorem 9

Let us take a discretization step h > 0 and consider the behavior of a **r**-homogeneous Lyapunov function V(satisfying (7)) on the sequence generated by (2). For this purpose define $x_i = \Lambda_r(||x_i||_r)y_i$ for some $y_i \in S_r(1)$:

$$V(x_{i+1}) - V(x_i) = V(x_i + ||x_i||_r^{-\nu} hf(x_i)) - V(x_i)$$

= $||x_i||_r^{\mu} [V(y_i + hf(y_i)) - V(y_i)].$

Since V is twice continuously differentiable, then by the Taylor expansion theorem with Lagrange remainder [1] there is $\theta \in (0, 1)$ such that

$$\begin{split} V(y_i + hf(y_i)) &= V(y_i) + \left. \frac{\partial V(\xi)}{\partial \xi} \right|_{\xi = y_i} hf(y_i) \\ &+ \frac{h^2}{2} f^\top(y_i) \left. \frac{\partial^2 V(\xi)}{\partial \xi^2} \right|_{\xi = y_i + \theta hf(y_i)} f(y_i), \end{split}$$

then

$$V(x_{i+1}) - V(x_i) = \|x_i\|_r^{\mu} \left. \frac{\partial V(\xi)}{\partial \xi} \right|_{\xi=y_i} hf(y_i) \\ + \|x_i\|_r^{\mu} \frac{h^2}{2} f^{\top}(y_i) \left. \frac{\partial^2 V(\xi)}{\partial \xi^2} \right|_{\xi=y_i+\theta hf(y_i)} f(y_i).$$

Note that from (7),

$$\left. \frac{\partial V(\xi)}{\partial \xi} \right|_{\xi = y_i} hf(y_i) \le -ha.$$

and there is $v \in (0, +\infty)$ such that

$$\sup_{y \in S_r(1)} \sup_{\theta \in (0,1)} f^\top(y) \left. \frac{\partial^2 V(\xi)}{\partial \xi^2} \right|_{\xi = y + \theta f(y)} f(y) \le v.$$

Therefore,

$$V(x_{i+1}) - V(x_i) \le h \|x_i\|_r^{\mu} \left(\frac{h}{2}v - a\right)$$

and for all $h \in (0, h_0]$ with $h_0 = \min\{1, \frac{a}{v}\}$ we obtain:

$$V(x_{i+1}) - V(x_i) \le -\frac{a}{2}h \|x_i\|_r^{\mu} \le -\alpha h V(x_i),$$

where $\alpha = \frac{a}{2c_2}$ and the property given in (7) was used on the last step. Assume that actually $h_0 = \min\{1, \frac{a}{v}, 2\frac{c_2}{a}\},\$

Preprint submitted to Automatica

^{*} This work was partially supported by ANR 18 CE40-0008 (Project DIGITSLID), the Government of Russian Federation (Grant 08-08) and Saint Petersburg State University (Project Id 37569826).

Email addresses: denis.efimov@inria.fr (Denis Efimov), andrey.polyakov@inria.fr (Andrey Polyakov), a.u.aleksandrov@spbu.ru (Alexander Aleksandrov).

then

$$V(x_{i+1}) \le (1 - \alpha h)V(x_i)$$

for all i = 0, 1, ... and the values of $V(x_i)$ are monotonously decreasing, hence the sequence $\{x_i\}_{i=0}^{\infty}$ is converging (the property (b) is substantiated). Global boundedness of $\{x_i\}_{i=0}^{\infty}$ (*i.e.* the property (a)) follows from the properties of the function V for $\gamma = (c_1^{-1}c_2)^{1/\mu}$.

Let us evaluate the rate of convergence for different signs of the degree of homogeneity ν of (1) stated in the property (c). Let $\nu = 0$, then trivially $t_{i+1} = t_i + h$ and an exponential rate of convergence is recovered. From (2) we have:

$$t_{i+1} - t_i = \frac{h}{\|x_i\|_r^{\nu}} \le \frac{h}{V^{\frac{\nu}{\mu}}(x_i)} \begin{cases} c_1^{\nu/\mu} & \nu < 0\\ c_2^{\nu/\mu} & \nu > 0 \end{cases}.$$

As it has been proven above

$$V(x_i) \le (1 - \alpha h)^i V(x_0)$$

for all i = 0, 1, ..., then for $\nu < 0$ and for any $k \ge 0$ an estimate can be derived:

$$t_{k+1} \le \sum_{i=0}^{k} \frac{c_1^{\nu/\mu} h}{V^{\frac{\nu}{\mu}}(x_i)} \le \frac{c_1^{\nu/\mu} h}{V^{\frac{\nu}{\mu}}(x_0)} \sum_{i=0}^{k} (1 - \alpha h)^{-i\frac{\nu}{\mu}}$$

Since $|1 - \alpha h| < 1$ for the selected h_0 , we get

$$t_{+\infty} \le \frac{c_1^{\nu/\mu}h}{V^{\frac{\nu}{\mu}}(x_0)} \sum_{i=0}^{+\infty} (1-\alpha h)^{-i\frac{\nu}{\mu}} \le \frac{c_1^{\nu/\mu}hV^{-\frac{\nu}{\mu}}(x_0)}{1-(1-\alpha h)^{-\frac{\nu}{\mu}}} < +\infty$$

for all $x_0 \neq 0$, which implies a finite-time convergence to the origin of any sequence $\{x_i\}_{i=0}^{\infty}$ in (2) but for $i \to +\infty$. For $\nu > 0$ we are interesting in the time of convergence from an infinite initial condition to $B_r(1)$, then it is necessary to repeat all above arguments in the inverse time, which leads to exactly the same estimate of such a time.

2 Proof of Proposition 11

Let $x_i \in S_r(1)$ be an arbitrary fixed vector, then the equation (3) can be rewritten as

$$\Delta = hz(x_i + \Delta)$$

for $\Delta = x_{i+1} - x_i$, where $z : \mathbb{R}^n \to \mathbb{R}^n$ is a continuous function defined as $z(x) = \frac{1}{\|x\|_r^\nu} f(x)$ with z(0) = 0. Indeed, $z(\Lambda_r(\lambda)x) = \Lambda_r(\lambda)z(x)$ for any $\lambda > 0$ and $x \in \mathbb{R}^n$, *i.e.* z is **r**-homogeneous vector field of degree 0 that is also continuous on $S_r(1)$. Denote $B(1) = \{x \in \mathbb{R}^n :$ $\|x\| \le 1\}$ as the unit ball in \mathbb{R}^n , if

$$h < \inf_{x_i \in S_r(1), \Delta \in B(1)} ||z(x_i + \Delta)||^{-1}$$

then the function $hz(x_i + \cdot) : B(1) \to B(1)$ is continuous on the convex compact set B(1). Hence, using the Brouwer fixed-point theorem [2] we conclude that the last equation has a solution with respect to $\Delta \in B(1)$ for any $x_i \in S_r(1)$. The conclusion for any $x_i \in \mathbb{R}^n$ follows from Corollary 6 or Proposition 5.

3 Proof of Theorem 12

Defining $x_{i+1} = \Lambda_r(||x_{i+1}||_r)y_{i+1}$ with $y_{i+1} \in S_r(1)$, we obtain:

$$V(x_{i+1}) - V(x_i) = V(x_{i+1}) - V(x_{i+1} - ||x_{i+1}||_r^{-\nu} hf(x_{i+1}))$$

= $||x_{i+1}||_r^{\mu} [V(y_{i+1}) - V(y_{i+1} - hf(y_{i+1}))]$
= $||x_{i+1}||_r^{\mu} \frac{\partial V(\xi)}{\partial \xi} \Big|_{\xi = y_{i+1}} hf(y_{i+1})$
- $||x_{i+1}||_r^{\mu} \frac{h^2}{2} f^{\top}(y_{i+1}) \frac{\partial^2 V(\xi)}{\partial \xi^2} \Big|_{\xi = y_{i+1} - \theta hf(y_{i+1})} f(y_{i+1})$

with application of the Taylor expansion theorem with Lagrange remainder [1] on the last step. Next, similarly

$$\left. \frac{\partial V(\xi)}{\partial \xi} \right|_{\xi = y_{i+1}} hf(y_{i+1}) \le -ha$$

from (7), and if the matrix $\frac{\partial^2 V(\xi)}{\partial \xi^2}$ is nonnegative definite for all $\xi \in \mathbb{R}^n$, then

$$V(x_{i+1}) - V(x_i) \le -ah \|x_{i+1}\|_r^{\mu}$$

for any h > 0. If this is not the case, then there is $w \in (0, +\infty)$ such that

$$\sup_{y \in S_r(1)} \sup_{\theta \in (0,1)} f^\top(y) \left. \frac{\partial^2 V(\xi)}{\partial \xi^2} \right|_{\xi = y - \theta f(y)} f(y) \le w,$$

which results in

$$V(x_{i+1}) - V(x_i) \le h \|x_{i+1}\|_r^{\mu} \left(\frac{h}{2}w - a\right)$$

and for all $h \in (0, h_0]$ with $h_0 = \min\{1, \frac{a}{w}\}$ we obtain:

$$V(x_{i+1}) - V(x_i) \le -\frac{a}{2}h \|x_{i+1}\|_r^{\mu} \le -\alpha h V(x_{i+1}),$$

where again $\alpha = \frac{a}{2c_2}$ and the property given in (7) was used on the last step. Finally,

$$V(x_{i+1}) \le (1 + \alpha h)^{-1} V(x_i)$$

for all i = 0, 1, ... and the values of $V(x_i)$ are monotonously decreasing, hence the sequence $\{x_i\}_{i=0}^{\infty}$ is converging (the property (b) is substantiated). Global boundedness of $\{x_i\}_{i=0}^{\infty}$ (*i.e.* the property (a)) follows from the properties of the function V for $\gamma = (c_1^{-1}c_2)^{1/\mu}$. The property (c) can be proven applying the same arguments as in the proof of Theorem 9.

References

- M. Abramowitz and I. A. Stegun, editors. Handbook of Mathematical Functions with Formulas, Graphs, and Mathematical Tables. Dover, New York, 9th edition, 1972.
- [2] D. Leborgne. Calcul différentiel et géométrie. Puf, Paris, 1982.