# 1 Fine-scale depth structure of pelagic communities throughout the global ocean based on

- 2 acoustic sound scattering layers
- 3 Running page header: Sound scattering layer depth structure
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## 9 Abstract

Most biomass in the mesopelagic zone (200 – 1000 m) comprises zooplankton and fish 10 11 aggregated in layers known as sound scattering layers (SSLs; they scatter sound and are detectable using echosounders). Some of these animals migrate vertically to and from the 12 13 near surface on a daily cycle (diel vertical migration; DVM), transporting carbon between 14 the surface and the deep ocean (biological carbon pump; BCP). To gain insight to potential global variability in the contribution of SSLs to the BCP, and to pelagic ecology generally 15 (SSLs are likely prey fields for numerous predators), we report here regional-scale (90000 16 km2) community depth structure based on the fine-scale (10s of m) vertical distribution of 17 18 SSLs. We extracted SSLs from a near-global dataset of 38 kHz echosounder observations and constructed local (300 km by 300 km) SSL depth and echo intensity (a proxy for biomass) 19 probability distributions. The probability distributions fell into six spatially coherent 20 21 regional-scale SSL probability distributions (RSPDs). All but one RSPD exhibited clear DVM, 22 and all RSPDs included stable night-time resident deep scattering layers (DSLs; SSLs deeper

23	than 200 m). Analysis of DSL number and stability (probability of observation at depth)
24	revealed 2 distinct DSL types: 1.) Single-Shallow DSL (single DSL at c. 500 m), and 2.) Double-
25	Deep DSL (two DSLs at c. 600 and 850 m). By including consideration of this fine-scale depth
26	structure in biogeographic partitions and ecosystem models, we will better understand the
27	role of mesopelagic communities in pelagic food-webs and consequences for them of
28	climate change.

- 29
- 30 Keywords: Biogeography, DVM, Acoustics, Water column, DSL, Mesopelagic

## 32 Introduction

33 The biological carbon pump (BCP), mediated by the regular vertical migrations of 34 mesopelagic organisms, transfers large quantities of carbon from the atmosphere in to the deep ocean (Anderson et al. 2018). It is estimated that the atmospheric concentration of 35 carbon dioxide is presently about 200 ppm lower than it would otherwise be in the absence 36 37 of the BCP (Parekh et al. 2006). The diel vertical migration (DVM) that is integral to the operation of the BCP can be detected, using scientific echosounders, as the upward and 38 downward migrations at dusk and dawn of the open-ocean communities that comprise 39 40 acoustic deep scattering layers (DSLs; sound scattering layers deeper than 200 m). The finescale (10s of m) depth structure of these communities will likely impact the efficiency of the 41 BCP (see Klevjer et al. 2016) and the foraging behaviour of air-breathing deep-diving 42 predators including Mirounga sp. (Northern and Southern Elephant Seals) and Aptenodytes 43 patagonicus (King penguins) (Scheffer et al. 2010, Boersch-Supan et al. 2012). It is therefore 44

important to consider regional variability in open-ocean community depth structure in
studies of open-ocean ecology and in the design of open-ocean ecosystem/biogeochemical
models such as SEAPODYM, Atlantis and MIZER (Lehodey et al. 2008, Fulton et al. 2011,
Trebilco et al. 2013, Scott et al. 2014), which are in turn important components of climate
models (Giering et al. 2014). Variability in depth structure should also be considered when
partitioning the ocean into ecological regions (Proud et al. 2017, Sutton et al. 2017).

#### 51 Vertical structure of water-column communities

52 From the sea-surface to 1000 m deep, the pelagic zone (i.e. the water-column away from 53 the seabed) can be divided into two zones, the epipelagic (0 to 200 m) and the mesopelagic 54 (200 to 1000 m). The epipelagic contains an illuminated mixed-layer that is isothermal and usually bounded by a steep seasonal thermocline, which is variable in depth. The epipelagic 55 is the site of oceanic primary production (PP), the magnitude of which is a function of light 56 intensity, temperature and nutrient availability (via mixing). PP varies widely both 57 58 geographically and over time (Boyce et al. 2010, 2012), and PP variability has been one 59 prominent basis for partitioning the global ocean into ecological regions, such as the 'provinces' derived by Longhurst (Longhurst 2007). The mesopelagic is typically colder than 60 61 the epipelagic, and seawater there is denser. Key inhabitants of the mesopelagic are the 62 zooplankton, squid and small bony fish that aggregate in layers and which generally migrate 63 daily (i.e. undertake DVM) upwards towards the surface at dusk to feed before returning to 64 depth at dawn (Bianchi et al. 2013, Bianchi & Mislan 2016). However, not all organisms 65 migrate daily, and 'resident' night-time mesopelagic communities have often been observed (Koslow et al. 1997, Flynn & Kloser 2012). Generally, the migrating community follows low-66 light intensity isolumes, such that they ascend to feed whilst minimising the risk of being 67

detected by visual predators (Hays, 2003). Daily movements and rest periods at depth
facilitates transport of carbon, nutrients and energy (via respiration and excretion) from the
surface to deep water (Schnetzer & Steinberg 2002). Seasonal community movements
including overwintering at depth by copepods also contribute to nutrient and energy flux
(Jónasdóttir et al. 2015).

73 Deep Scattering Layers

DSLs, which form in the mesopelagic zone, take their name from the fact that they scatter 74 75 sound. A consequence of this is that they can be detected using active acoustic sampling 76 (scientific echosounding). The depth at which DSLs are located varies geographically and 77 seasonally (Anderson et al. 2005, Kloser et al. 2009, Irigoien et al. 2014, Knutsen et al. 2017, Proud et al. 2017). This variability is thought to be predictable, since observed depths of 78 DSLs have been linked to environmental drivers such as seawater density (Godø et al. 2012), 79 light intensity (Hays 2003, Aksnes et al. 2017, Proud et al. 2017), oxygen concentration 80 81 (Bianchi et al. 2013; Klevjer et al. 2016) and wind-driven mixing (Proud et al. 2017). 82 Furthermore, regional variability in the intensity of echoes from DSLs, a rough proxy for biomass, has been linked to PP in the waters above and to temperature (Irigoien et al. 2014, 83 Fennell & Rose 2015, Proud et al. 2017). There is often more than one DSL in a given 84 location (Andreeva et al. 2000), and DSLs at different depths likely comprise different 85 86 communities (the stacked DSLs can be considered as rungs in Vinogradov's (1968) 'ladders 87 of migration'). The vertical distributions of these multiple DSLs can shift at twilight, with 88 some migrating in unison, some remaining stationary, some merging, and some splitting, such that there are distinct day and night patterns (e.g. Klevjer et al. 2012). These complex 89 and variable depth structures vary globally and may well be intimately linked to 90

concomitant environmental variability. By characterising the form and variability of these
depth structures, we inadvertently characterise complex and distinct environments, which
may enable improved partitioning of the ocean into biogeographic regions.

94 Biogeography

95 Historically, biogeographic partitioning of the ocean was generally performed using just biological data (Brinton 1962, Alvarino 1965, Briggs 1974, Semina 1997), but more recent 96 97 classifications have been able to capitalize on the availability of open-access data and to 98 incorporate numerous data sources (including biological, chemical and physical) into their 99 partitioning algorithms (Longhurst 2007, Proud et al. 2017, Sayre et al. 2017, Sutton et al. 100 2017). Distributions and abundances of species and 'environmental' parameters vary with depth, so it is not necessary to expect that the same spatial grid of classification at the 101 surface, say, would pertain in the mesopelagic. Further, the number of separate classes, 102 103 units, or provinces that can be identified/discriminated depends on many factors including 104 chosen scale and number of variables considered. In most cases the number of separations 105 can be considered to be an arbitrary, artificial construct, and is usually selected for a specific purpose e.g. management (e.g. Sayre et al. 2017) or research applications. Biogeographies 106 107 vary by depth strata, from surface and epipelagic classification (Longhurst 2007, Oliver & 108 Irwin 2008, Spalding et al. 2012), mesopelagic and water-column (Flynn & Marshall 2013, 109 Proud et al. 2017, Sayre et al. 2017, Sutton et al. 2017) to seabed (UNESCO 2009, Watling et 110 al. 2013). However, none have included detailed (10s of m) water-column community depth 111 structure because data have not been readily available.

112

114 Hypothesis and objectives

The biophysical drivers of DSL depth and echo intensity (a proxy for biomass; Proud et al. 115 116 2018) have been used to demark global biogeographies (Proud et al. 2017). We therefore hypothesise that distinct communities, with distinct depth preferences, exist and that these 117 118 preferences lead to spatially coherent vertical structuring at regional-scales. To test this 119 hypothesis, our approach was as follows: 1.) extract sound scattering layer (SSL; non-depthspecific scattering layer) depth, thickness and echo intensity (between 0 to 1200 m) from 120 121 globally collated 38 kHz echosounder data using the SSL extraction method (SSLEM, Proud 122 et al. 2015); 2.) produce local (300 km by 300 km) SSL probability distributions (SPD), which provide, for a given area, the probability of observing an SSL at a specific depth and echo 123 intensity value; 3.) cluster the SPDs by likeness and derive regional-scale SSL probability 124 125 distributions (RSPDs), and 4.) categorize RSPDs by DSL depth structure and vertical stability, defined as the probability of DSL observation at its principal, or most common, depth (e.g. 126 127 where a DSL is always observed at a certain depth for a specific RSPD, DSL vertical stability would equal 1). 128

129

#### 130 Method

131 SSLs were extracted from an extensive acoustic dataset (3196 38 kHz echograms; equal to

132 380 days of observations), spatially binned into 300 km by 300 km cells (90000 km<sup>2</sup>),

133 grouped by day and night, and summarised by depth and mean volume backscattering

strength (MVBS, dB re 1m<sup>-1</sup>, Maclennan et al. 2002) SSL probability distributions (SPDs). SSLs

that had a mean depth > 200 m were defined as deep scattering layers (DSLs). Cluster

analysis was used to group similar SPDs in space, and regional-scale SPDs were defined,

137 enabling inferences on the underlying biological communities to be made.

138

139 Acoustic data

140 38 kHz echosounder observations, recorded between 2006 and 2015, were collated from 141 the British Oceanographic Data Centre (BODC, www.bodc.ac.uk, 2014), the British Antarctic Survey (BAS 2015, www.bas.ac.uk), the Pelagic Ecology Research Group (PERG), the 142 143 Integrated Marine Observing System (IMOS 2013, www.imos.org.au) and the Surface Mixed Layer Evolution at Sub-mesoscales Cruise (SMILES 2015). Seasonal coverage was variable, 144 145 ranging from near uniform sampling with full seasonal coverage in the South Indian Ocean, 146 to regions with lower sample coverage (1-2 seasons) in the polar and North Pacific regions 147 (polar regions are not typically sampled during winter due to sea ice cover). 148 Data were calibrated and noise was removed (see Proud et al. 2017 supplemental information for details of data processing). SSLs persisting for longer than 30 minutes were 149 extracted and characterised using the SSL extraction method (SSLEM, Proud et al. 2015). 150 151 Individual SSLs were described by their mean depth, thickness and MVBS, and binned by 152 geographic location onto a uniform global 300 km by 300 km grid (where seabed depth > 1000 m) as per the spatial scale applied by Proud et al. (2017). Gridded SSLs were grouped 153 by day and night periods (demarked using local sunrise and sunset times) and summarised 154 by depth and MVBS SSL probability distributions (SPDs). 155

156

## 158 Sound scattering layer probability distributions

Following Proud et al. (2017), we define the probability (P) of observing an SSL at a specific
depth (z) and MVBS value as

161 
$$P_{z,MVBS} = \frac{obs_{z,MVBS}}{se_z}, \quad (1)$$

where obs<sub>z,MVBS</sub> is the total time of SSL observation (s) by depth (0 to 1200 m by 5 m
intervals) and MVBS level (-50 dB re 1m<sup>-1</sup> to -100 dB re 1m<sup>-1</sup> by 2 dB re 1m<sup>-1</sup> intervals) and
se<sub>z</sub> is the sampling effort (s) by depth i.e. for each depth interval the probability of SSL
observation (including the probability of no observation) sums to one. Calculating P over the
entire depth and MVBS range yielded an SSL probability distribution (SPD) for each
geographic cell for both day and night.

# 168 Seasonal coverage index (SCI)

To quantify the temporal distribution of echosounder observations for each SPD, a seasonal
coverage index (SCI), given by,

171 
$$SCI = \sum_{i=1}^{4} se_i / max([se_1, se_2, se_3, se_4]) \quad (2)$$

was calculated, where se<sub>i</sub> is the sampling effort (s) for each season, represented by the
integer i, ranging from 1 (spring) to 4 (winter) and *max* is a function that returns the
maximum value of a given vector. For an SPD where all observations were made in a single
season, SCI would equal 1, whereas for an SPD where the sampling effort for all four
seasons was the same (uniform distribution), SCI would equal 4.

## 178 Epipelagic and mesopelagic nautical area scattering coefficient

179 The total amount of scattered energy produced per square nautical mile over a depth range

is known as the nautical area scattering coefficient (NASC, s<sub>A</sub>, m<sup>2</sup> nmi<sup>-2</sup>, Maclennan et al.,

181 2002). The NASC values over the epipelagic ( $s_{epi}$ , 0 – 200 m, m<sup>2</sup> nmi<sup>-2</sup>) and mesopelagic

182  $(s_{meso}, 200 - 1000 \text{ m}, \text{m}^2 \text{ nmi}^{-2})$  zones (in 5 m depth bins in both) are given by

183 
$$s_{\text{epi}} = \sum_{j=0}^{40} \left( \sum_{i=0}^{25} (P_{\mathbf{Z}[j],\mathbf{M}[i]} \times 10^{(\mathbf{M}[i]/10)}) \right) \times 4\pi \times 1852^2 \quad (3)$$

184 and

185 
$$s_{\text{meso}} = \sum_{j=40}^{200} \left( \sum_{i=0}^{25} (P_{\mathbf{Z}[j],\mathbf{M}[i]} \times 10^{(\mathbf{M}[i]/10)}) \right) \times 4\pi \times 1852^2 \quad (4)$$

respectively, where j is an index for the vector **Z**, which is consistent of 200 equally spaced SSL depth bins (0 – 1000 m by 5 m) and i, is an index for the vector **M**, which comprises 25 equally spaced SSL MVBS bins (-50 dB re  $1m^{-1}$  to -100 dB re  $1m^{-1}$  by 2 dB re  $1m^{-1}$ ).

189

# 190 Principal deep scattering layer depth, MVBS and stability

The probability of observing an SSL at a specific depth, P<sub>z[j]</sub>, defined as the vertical stability
of an SSL, is given by

193 
$$P_{\mathbf{Z}[j]} = \sum_{i=0}^{25} P_{\mathbf{Z}[j],\mathbf{M}[i]}.$$
 (5)

194 The principal or most common DSL depth, Z<sub>PDSL</sub> (see Proud et al. 2017), was determined by

195 finding the maximum value of  $P_{Z_{[j]}}$  between 200 and 1000 m (**Z**[40] to **Z**[200]):

196 
$$P_{\mathbf{Z}[40:200]} = \{P_{\mathbf{Z}[40]}, P_{\mathbf{Z}[41]}, P_{\mathbf{Z}[42]} \dots, P_{\mathbf{Z}[199]}\}, (6)$$

197 
$$P_{PDSL} = max(P_{Z[40:200]}), \quad (7)$$

198 
$$Z_{PDSL} = \mathbf{Z}[argmax(P_{\mathbf{Z}[40:200]})], (8)$$

199 where P<sub>PDSL</sub> is the probability of observing the principal DSL defined here as DSL vertical

stability and *argmax* is a function that returns the index of the maximum value. For

201 example, in the case where a DSL was always observed at a specific depth, P<sub>PDSL</sub> would equal

202 1, i.e. the DSL was always observed at Z<sub>PDSL</sub> and therefore had a high vertical stability.

203 Similarly, given that a DSL has been observed, the most likely MVBS value of the principal

204 DSL, MVBS<sub>PDSL</sub>, is given by

205 
$$P_{\mathbf{M}[i]} = \sum_{j=40}^{200} P_{\mathbf{Z}[j],\mathbf{M}[i]} / \sum_{j=40}^{200} \left( \sum_{i=0}^{25} (P_{\mathbf{Z}[j],\mathbf{M}[i]}) \right), \quad (9)$$

206 
$$P_{\mathbf{M}[0:25]} = \{ P_{\mathbf{M}[0]}, P_{\mathbf{M}[1]}, P_{\mathbf{M}[2]} \dots, P_{\mathbf{M}[24]} \}, (10)$$

207 
$$P_{PMVBS} = max(P_{M[0:25]}),$$
 (11)

208 
$$MVBS_{PDSL} = \mathbf{M}[argmax(P_{\mathbf{M}[0:25]})], \quad (12)$$

209 where P<sub>MVBS</sub> is the probability of the principal DSL having a MVBS value of MVBS<sub>PDSL</sub>.

# 210 Clustering sound scattering layer probability distributions (SPDs)

# A distance measure was derived to determine the similarity between each SPD. Since the SPDs were all constructed from a set of discrete probabilities, with values between 0 and 1 and with just one value per depth/MVBS bin, a simple matrix subtraction was used to

214 calculate a relative distance measure,

dist<sub>AB</sub> = 
$$\sum abs(\mathbf{A} - \mathbf{B})$$
, (13)

where **A** and **B** are 2-dimensional arrays (SPDs) and dist<sub>AB</sub> is a relative distance measure between **A** and **B**. The maximum value of dist<sub>AB</sub> is equal to the size of the SPD arrays (240 depth bins  $\times$  25 MVBS bins = 6000 cells) i.e. where the probability of SSL observation at a specific depth and MVBS combination in **A** = 0, the probability for the same depth and MVBS values in **B** would equal 1. By the same logic, where two SPDs are identical (i.e. where the probability of observing SSLs across all depth and MVBS combinations is the same) dist<sub>AB</sub> = 0.

Using Eq. 13, a dissimilarity matrix **D** that contained the pairwise distances between all 223 224 daytime SPDs (total number of SPDs = X) was constructed. Classical multi-dimensional 225 scaling (MDS, Hout et al. 2013) was applied to reduce the data to a smaller number of 226 dimensions, improving computational efficiency. From the resulting configuration matrix, an 227 appropriate number of dimensions, D, was assigned by evaluating values of stress (the 228 degree of correspondence between the distances of the original data and MDS map, where a value of 0 is perfect correspondence). A k-means clustering algorithm (Hartigan & Wong 229 230 1979) was applied to the resultant reduced dataset (size = X by D) to determine the natural number of groupings or clusters that were evident within the data. The optimum number of 231 232 clusters was selected by identifying interruptions, or elbow-like features, in the Log-233 Likelihood (LL) trend (e.g. Sugar 1998). The algorithm was run for a range of k clusters (2 – 20), where at each step the LL value was determined (Eq. 14 and 15) to enable model 234 235 assessment:

236 
$$P(x|u) = \frac{e^{-\sum_{d \in D} (u_d - x_d)^2}}{\sum_{u} e^{-\sum_{d \in D} (u_d - x_d)^2}}, \quad (14)$$

237 
$$LL = \sum_{x \in X} \log \max (P(x|u)), (15)$$

where P(x|u) is the probability of sample x (i.e. a single SPD) belonging to model u (k-means model).

240

## 241 Regional-scale sound scattering layer probability distributions (RSPDs)

The resultant k-clusters, consisting of n cluster members (SPDs formed from observations 242 made within a single 300 km by 300 km cell) were merged to form new 'regional-scale' SPDs 243 244 with larger spatial coverage (equal to  $n \times 90000 \text{ km}^2$ ) by matrix addition. This operation was carried out by adding the underlying data (obs<sub>z,MVBS</sub>, see Eq. 1) for all the SPDs in each 245 cluster together, and then determining a new set of probabilities by applying new values of 246 se<sub>z</sub> to Eq. 1; this accounted for differences in sampling effort between cluster members. The 247 248 merged clusters of SPDs were termed 'regional-scale SSL probability distributions' (RSPDs) 249 and are associated spatially with individual cluster members. Finally, a local neighbourhood dilation filter (3 x 3 cells) was passed over the spatial grid of cells labelled by cluster number 250 (k), and the centre value of the filter (either a cluster number or an unlabelled cell) was 251 replaced with the maximum value calculated over the local neighbourhood. This filtering 252 253 process removed anomalies and smoothed spatial transitions between RSPDs.

254

#### 255 Results

In total, 39455 SSLs were extracted from the acoustic survey data via the SSLEM (Proud et
al. 2015), including 26474 DSLs, and summarised by a set of metrics (depth, thickness and

MVBS). The SSL metrics were split by day and night and assigned to 297 unique 300 km by 300 km cells (these equate to c. 9% of the surface of the global open-ocean where seabed depth > 1000 m). SSL probability distributions (SPDs) were determined for each cell, and a distance measure was computed resulting in a dissimilarity matrix, **D**, with 297 rows and columns. The MDS analysis of **D** indicated that for a stress value of 0.1 (Kruskal 1964), **D** could be reduced from 297 dimensions to 37. The lower dimensional representation of the data, **D**', accounted for 72% of the variance.

265 K-means clustering was applied to **D'** and using calculated values of the Log-Likelihood (Eq. 15), a six-cluster model was selected. An elbow-like feature was apparent when fitting six 266 267 clusters (Fig. 1), increasing the value of the Log-Likelihood away from the decreasing trend; 268 this feature indicated that there was a better than expected fit at this scale. As the number 269 of clusters increased, particularly towards 15, more of these features appeared. Since in this study we were interested in regional-scale trends, taking the first natural grouping was 270 271 appropriate. For the six-cluster model, 89% of the SPDs were assigned to a cluster with a 272 probability (Eq. 14) that was at least twice the value of the next best selection, indicating a 273 good fit.

274

275 [Figure1]

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277

278

## 280 DSL vertical stability and sampling effort of SPD cluster members

- Sampling effort per SPD ranged between c. 1 hour and 175 hours, and DSL vertical stability
   (P<sub>PDSL</sub>) ranged between c. 0.32 and 1 (Fig. 2). DSLs were typically less stable during the night-
- time than the day and the lowest values of DSL vertical stability occurred in summer (Fig. 2).
- DSLs in clusters 1, 2, 4 and 5 were the most vertically stable, whereas in cluster 6 DSLs were
- highly unstable across the full range of sampling effort values.
- 286 [Figure 2]

287

- 288
- 289 Geographical distribution of SPD clusters
- 290 The SPD cluster members were plotted in space, revealing the underlying spatial affiliation
- of the echosounder observations (Fig. 3). The clusters formed large-scale spatially
- aggregated regions (Fig. 3). Cluster 6 was located mostly at higher latitudes, typically lying
- 293 poleward of 40° latitude in both hemispheres. Cluster 3 formed a single region within the
- south Indian Ocean. The other clusters occurred at mid to low latitudes forming sub-regions
- both north and south of the equator (Fig. 3).
- 296

297 [Figure 3]

298

299

## 301 Regional-scale SSL probability distributions

302	SPDs were merged by cluster to form six distinct RSPDs (Fig. 4). RSPDs 1 to 5 exhibited
303	strong compact trunk-like features in depth-MVBS space (Fig. 4). MVBS values of these
304	RSPDs varied by a factor of 10 from RSPD1 (MVBS <sub>PDSL</sub> = -67 dB re $1m^{-1}$ ) to RSPD5 (MVBS <sub>PDSL</sub> =
305	-77 dB re 1m <sup>-1</sup> ). There was also an increase in backscattering intensity from day to night at
306	the surface and a decrease in the mesopelagic depth zone, indicating DVM (Table 1).

307

308 [Figure 4]

309

All RSPDs had relatively stable depth structures during both day and night (Fig. 4) i.e. in all 310 311 regions there was a component of the DSL assemblage that did not migrate, suggesting that 312 'resident' night-time DSLs are a ubiquitous feature of open-ocean pelagic ecosystems. This phenomenon could be explained by a component of the DSL consisting of either a 313 temporary (e.g. through ontogenetic migration) or permanent (e.g. non-migrating fish 314 315 species) resident mesopelagic community, or by asynchronous vertical migration (e.g. Dupont et al. 2009) where individuals of a given species behave as individuals, each 316 317 selectively undertaking migration (intermittently or opportunistically) at a time cued by 318 some individual trigger (e.g. predation pressure/food availability). 319 RSPD6, by contrast, was characterised by a broad, shallow probability distribution (Fig. 4), i.e. SSLs varied substantially in both depth and MVBS and there was no common structure. 320 This RSPD arises from seasonally-limited sampling, so is not an artefact caused by blurring of 321 temporal variability (Table 1, SCI = 1.8). It is formed from cells with low DSL vertical stability 322

323 (Fig. 2) and cells that contain relatively low MVBS SSLs (< -85 dB re 1m<sup>-1</sup>, see Fig. 4). RSPD6

324 MVBS increased from day to night in the mesopelagic (Table 1).

325

326 [Table 1]

327

- 328 Depth structure and DSL stability of RSPDs
- 329 RSPDs were ranked by s<sub>meso</sub>, which is reflected by the decreasing value of MVBS<sub>PDSL</sub> (Table 1
- and Fig. 5) from RSPD1 to 6. Analysis of the mesopelagic depth structure (number and depth
- of DSLs) and DSL vertical stability (P<sub>z[40-200]</sub>, see Eq. 5), enabled categorisation of the RSPDs
- into 3 DSL types: 1.) Single-Shallow DSL (SS-DSL: RSPD1, 3 and 5), a single DSL at c. 500 m, 2.)
- 333 Double-Deep DSL (DD-DSL: RSPD2 and 4), two DSLs at c. 600 m and 850 m and 3.)
- 334 Unclassified DSL (U-DSL: RSPD6), highly variable depth structure and/or low (< -85 dB re 1m<sup>-</sup>
- <sup>1</sup>) MVBS values (Table 1, Fig. 2, 4 and 5).

336

337 [Figure 5]

# 338 Discussion

The RSPDs defined here give new insight to fine-scale (10s of m) depth structure of openocean communities and their day-to-night vertical stability (i.e. probability of observation at depth) and MVBS variability. They provide evidence that regional-scale spatially coherent community depth structures exist between 0 and 1200 m (Fig. 3 and 4). Since DSL metrics (e.g. Z<sub>PDSL</sub> and MVBS<sub>PDSL</sub>, see Table 1) are characteristics of the underlying mesopelagic

biological communities and that similar partitions arise from environmentally-based 344 regionalisations (e.g. Longhurst provinces), then the observed cohesion here is likely to be 345 due to environmental control. The between-region differences in DSL vertical stability and 346 MVBS variability (Fig. 2, 4 and 5) are not artefacts of uneven sampling effort (see SCI in 347 348 Table 1 and Fig. 2). The most vertically stable region was RSPD4 (defined by highest PPDSL values, see Table 1) which occurred in the Southern Indian Ocean (Fig. 3), the area for which 349 we have full seasonal sampling coverage (Table 1, SCI = 3.1). Conversely, the high vertical 350 351 instability in the polar regions was evident in our seasonally-restricted data (we do not have data for the logistically-challenging winter period, see Table 1, RSPD6, SCI = 1.8). All RSPDs 352 include resident night time DSLs which adhere to their daytime depth (Fig. 4). Spatial 353 354 variability in DSL number and fine-scale depth structure will impact predator-prey interactions in pelagic food-webs and carbon transfer in the water-column via the biological 355 356 carbon pump (Klevjer et al. 2016). Such variability should be considered in ocean 357 partitioning schemes and in the design of mesopelagic components of ecosystem and biogeochemical models. 358

359

# 360 Implications for predator-prey interactions

DSL inhabitants (e.g. micronektonic organisms such as mesopelagic fish) represent a
 potentially rich food resource for both epipelagic predators (e.g. southern bluefin tuna
 (*Thunnus maccoyii*) and Pacific bluefin tuna (*Thunnus orientalis*); Bestley et al. 2008) at night
 and deep-sea consumers during the day (Hazen & Johnston 2010). Variability in daytime and
 night-time depth of DSLs, spatially characterised by RSPDs (Fig. 4), will likely impact the
 energy budgets of their inhabitants and deep-diving air-breathing predators (e.g. Southern

367 Elephant seals *Mirounga leonin*) for which DSLs constitute a dynamic prey-landscape
368 (Boersch-Supan et al. 2012). For active vertical migrators, the opportunity to feed (and
369 digest) in shallow, warm and productive waters may bring metabolic advantages that
370 outweigh the cost of migration. For predators, however, the fact that potential prey
371 biomass is deep during the day may effectively take it out of their reach: prey may exist but
372 be inaccessible.

373 Predators adjust the time allocated to foraging according to the prey patch quality 374 (Schoener 1979, Mori & Boyd 2004). Deep-diving air-breathing predators that are constrained by their oxygen requirements have been observed to rely on spatially 375 376 predictable foraging grounds (Brown 1980, Charrassin & Bost 2001). Variation in prey 377 availability leads predators to adjust their foraging behaviour and/or location, affecting their 378 foraging success, which in turn has an impact on survival, breeding success, and eventually population abundance (New et al. 2014). Mesopelagic fish are a key component of the DSL 379 380 as well as an important prey item for King penguins and Southern Elephant seals (Olsson & 381 North 1997, Vacquié-Garcia et al. 2015). Both Southern Elephant seals and King penguins 382 routinely dive to depths coincident with the DSL although direct evidence for foraging on DSLs by these species remains lacking. King penguins can dive down to depths of c. 400 m 383 384 (Charrassin et al. 2002) and Southern Elephant seals have dive ranges beyond the mesopelagic zone (down to 2000 m; McIntyre et al. 2010). If they do feed upon DSLs, 385 386 variation in DSL depth will impact the energy expenditure of their dives. 387 The daytime vertical range of DSLs in RSPD1, 3 and 5 extends to c. 400 m at their shallowest 388 extent, whereas in RSPD2 and 4, DSLs reside slightly deeper at their shallowest extent (c.

500 m, see Fig. 4). Geographically, the only RSPDs within the latitudinal feeding range of

390 King penguins (i.e. south of the polar front) are the shallower DSLs (e.g. RSPD5 see Fig. 3). It 391 is perhaps no coincidence that at the far extent of the King penguin's diving range, prey 392 biomass starts to increase because predation pressure upon DSL occupants is reduced. 393 Vertical zonation is a common phenomenon in the marine realm. The most readily apparent 394 examples come from the intertidal, where the lower depth distributions of many species are 395 set by predation (e.g. Luckens 1975). On land, a vivid evidence of the impact of consumption 396 on vertical distribution is seen by the browsing of giraffes on trees (Woolnough & Du Toit 397 2001). However, although the probability of DSL observation at shallower depths is low in 398 RSPD1, 3 and 5 (Fig. 4), they have been observed on occasion (< 10% probability), and we 399 have sampled from an incomplete dataset both temporally (e.g. missing winter period in the 400 Southern Ocean) and spatially (e.g. missing large sections of the Atlantic and eastern 401 boundary upwelling systems).

402 The energy consumption by mesopelagic organisms that actively migrate can be divided into 403 four different energy-consuming activities: i) foraging at the surface during the night (e.g. 404 Dypvik & Kaartvedt 2013); ii) buoyancy control, via a gas bladder, lipid investment or by swimming (Proud et al. 2018); iii) predator evasion (Hays 2003), and iv) actively swimming 405 406 during vertical migration (Brierley 2014). Variability in DSL depth directly impacts activities 407 ii-iv to different degrees. For example, a gas-bladdered fish that re-inflates its gas bladder at depth to maintain neutral buoyancy, moving from a daytime position of 500 m down to 600 408 409 m (e.g. from RSPD1 to RSPD2), needs to produce more gas (due to higher pressure) to 410 remain neutrally buoyant. The fish may also experience reduced predation from above by becoming inaccessible to some predators (e.g. King penguins), and more energy is required 411 412 to vertically migrate. Foraging will also be impacted indirectly, as the energy remaining after 413 other activities (ii-iv) may limit energy availability for foraging.

To investigate further, fine-scale predator-prey studies between access-restricted diving
predators and DSLs should be conducted.

416

## 417 Low deep scattering layer vertical stability in Polar Regions

418 We have revealed two different DSL depth structures, Single-Shallow DSL (SS-DSL) and 419 Double-Deep DSL (DD-DSL). The remaining cluster, RSPD6, found mainly in polar regions 420 (Fig. 3), consisted of SPDs with low DSL vertical stability (Fig. 2) and relatively low intensity 421 scattering layers (Fig. 4). Polar regions are cold, metabolic rates are reduced and life cycle stages are longer, reducing survival probability of larvae and hence lowering trophic 422 423 efficiency (Rogers et al. 2011). There are relatively few mesopelagic fish species in the polar 424 regions (3 spp. of *Myctophidae* in the Arctic and 19 in the Antarctic compared with > 100 spp. in the Indian Ocean, www.fishbase.org), which may lead to reduced productivity and 425 ecosystem stability (Johnson et al. 1996). As the climate warms, fish diversity in polar 426 regions may increase (e.g. Kaartvedt & Titelman 2018) and, with it, ecosystem stability and 427 428 biomass may increase. In the Southern Ocean, a proportion of the fish population is 429 believed to be migratory, spending their early life-cycle stages equatorward of the polar 430 front (Saunders et al. 2017) and progressing towards the Antarctic shelf as adults, following Bergmann's Rule (Saunders & Tarling 2017). Since fish are relatively strong scatterers 431 compared with zooplankton (Lavery et al. 2007), high spatial and temporal variability in 432 433 community composition (proportion of zooplankton to fish) and biomass, along with patchy 434 immigrations, could lead to the observed low vertical stability in DSL depth (see Table 1 and Fig. 2) and high variability in MVBS (Fig. 4, RSPD6). 435

436

## 437 Partitioning the ocean

438 The spatial coherence of the clusters (see Fig. 3) provides evidence that pelagic communities 439 as described using SSL characteristics (z, MVBS etc.) are distinct at the regional-scale. This is particularly apparent in the south Indian Ocean region, where even though the underlying 440 441 data had the most extensive seasonal coverage (Table 1, RSPD4, SCI = 3.1), spatially 442 coherent regions formed. The spatial extent of the RSPDs varied geographically. Across the North Atlantic, for example, the SSL structure varied substantially, shifting between 4 443 444 different RSPDs over a relatively small distance (Fig. 3). Anderson et al. (2005) reported similar findings, observing high spatial and seasonal variability in DSL depth and echo 445 intensity, inferring that changes in oceanographic regimes were responsible. Conversely, in 446 447 the North Pacific, the SSL structure was more spatially stable, formed in the majority of a 448 single RSPD (Fig. 3).

449 Flynn and Marshall (2013) describe four zoogeographic regions off eastern Australia based 450 on lanternfish species occurrence data and related environmental variables (nitrate, 451 phosphate, oxygen, salinity and temperature). The four regions, Coral Sea, Subtropical Lower water, Subantarctic, and Subtropical Convergence zone (South Tasman region) 452 correspond spatially to our RSPD5, 3, 6 and 1 respectively (Fig. 3 here and Flynn & Marshall's 453 454 (2013) Fig. 7). There is a stark difference between the Subantarctic region (RSPD6), also 455 defined by Longhurst (2007) as the Subantarctic water ring (SANT, Fig. 3), and the other 456 three RSPDs/zoogeographic regions, which all fall into the SS-DSL depth structure type and 457 are not as well-defined (Flynn & Marshall 2013, Fig. 7). In Flynn and Marshall's 458 bioregionalization model (2013), latitude is a significant covariate and they suggest that this is a proxy for some unknown parameter, speculating that it could be related to food source 459

distribution, breeding, competitive exclusion or a consequence of larval transport barriers or
aggregating eddies. Here, the RSPDs are distinguished by their DSL echo intensity, which
increases from RSPD1 to RSPD6 (Table 1). This increase could be related to an increase in
biomass (Irigoien et al. 2014), and therefore related to food source distribution, or may just
be a consequence of differences in fish population scattering properties (Davison et al.
2015).

Recently, Proud et al. (2017), described a mesopelagic biogeography based on the daytime 466 467 depth of the principal DSL and 38 kHz backscattering intensity of observed daytime DSLs. They predicted global mesopelagic backscatter using a simple linear model in which the 468 product of PP and temperature at the depth of the principle DSL was used as a predictor 469 470 variable. In this study, we have defined RSPDs based on the full water-column SSL structure 471 (not just the depth of the principle DSL), and quantified vertical stability of these structures. By including consideration of the full water-column structure, ecological partitions could be 472 473 constructed that are more suitable for studies where fine-scale distribution of DSLs is 474 required e.g. foraging behaviour of deep-diving predators such as Elephant Seals and King penguins in the Southern Ocean (Boersch-Supan et al. 2012). 475

476

## 477 Mesopelagic components in Ecosystem models

Recognition of the importance of the role of diel vertical migration in the carbon cycle has
increased over the last decade (Van De Waal et al. 2010, Doney et al. 2012, Passow &
Carlson 2012, Giering et al. 2014, Mitra et al. 2014), but modelling of these processes at
fine-scales has not developed as quickly. Traditional ecological models such as Ecopath
(Christensen & Walters 2004) do not explicitly define depth structure. Newer, more complex

models such as Atlantis (Fulton et al. 2011) have both diel variability and integrated depth
levels. Modelers are now beginning to adapt their models. For example, SEAPOYDM
(Lehodey et al. 2008) has recently been updated to included DVM behaviour and
consideration of DSL depth structure related to euphotic depth (Lehodey et al. 2014).
Accurate representation of the BCP in these models is important because output from these
models feed into climate/Earth-system models.

489

490 Conclusions

Regional-scale, spatially and vertically coherent, water-column community depth structures 491 492 can be derived from echosounder observations. In total, we describe six regional-scale 493 sound scattering layer probability distributions from a near-global acoustic dataset. Other 494 characteristic SSL depth structures may exist in regions for which we had no observations e.g. in the central and South Atlantic and the eastern boundary upwelling systems. 495 Variability in deep scattering layer (DSL) number, depth, mean volume backscattering 496 497 strength and vertical stability drive the characteristic forms of these day-night depth structures (Single-Shallow DSL and Double-Deep DSL) and these forms will likely impact the 498 efficiency of the biological carbon pump and predator-prey interactions. The results 499 500 presented here highlight the variability in fine-scale depth structure and vertical stability of the mesopelagic community throughout the global ocean. Both of these should be 501 considered when partitioning the ocean's water-column into bioregions, and in the future 502 503 development of ecological models.

504

505	Acknowledgements
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506	We thank the British Oceanographic Data Centre, the Australian Integrated Marine
507	Observing System, the British Antarctic Survey, and Dr. Phil Hosegood for providing
508	echosounder data. This study has received support from the European H2020 International
509	Cooperation project MESOPP (Mesopelagic Southern Ocean Prey and Predators,
510	http://www.mesopp.eu/).
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718 Figures





Fig. 1. Change in Log-Likelihoods by number of k-means clusters. Six clusters were selected

721 (indicated by a black dashed line) on the basis that an elbow-like feature with an increasing

722 Log-Likelihood at that scale diverged from the otherwise decreasing linear trend.



Fig. 2. Deep scattering layer (DSL) vertical stability, defined as the maximum probability of
DSL observation (P<sub>PDSL</sub>) and sampling effort (echosounder observations) by season, diel state
and cluster for each local-scale (300 by 300 km cell) sound scattering layer probability
distribution.





Fig. 3. Geographical distribution of echosounder data (coloured cells) and sound scattering

- 730 layer probability distribution cluster membership (C1 to C6). Longhurst's (2007) pelagic
- ocean provinces are shown for reference, labelled by their short-name.





Fig. 4. Regional-scale sound scattering layer probability distributions (RSPDs) plotted in
depth-MVBS space. Each RSPD has a day and night component. P<sub>z,MVBS</sub> is the probability of
observing a sound scattering layer of a given depth (z) and MVBS value. White regions

indicate a probability of 0 i.e. no sound scattering layers were observed in the region





Fig. 5. Stability of deep scattering layer (DSL; sound scattering layer > 200 m) depth and
mean volume backscattering strength (MVBS) for each regional-scale sound scattering layer
probability distribution (RSPD). P<sub>z</sub> (panels a and c), is the probability of DSL observation by
depth and, P<sub>MVBS</sub> (panels b and d), is the probability of an observed DSL having a specific
MVBS value.

## 746 Tables

		Day				Night			
RSPD	SCI (1-4)	Z <sub>PDSL</sub> (m)	MVBS <sub>PDSL</sub>	s <sub>meso</sub> (m <sup>2</sup>	s <sub>epi</sub> (m²	Z <sub>PDSL</sub>	<b>MVBS</b> <sub>PDSL</sub>	s <sub>meso</sub> (m <sup>2</sup>	s <sub>epi</sub> (m²
			(dB re 1m <sup>-1</sup> )	nmi⁻²)	nmi⁻²)	(m)	(dB re 1m <sup>-1</sup> )	nmi⁻²)	nmi⁻²)
1	2.1	510	-67 (0.23)	2692	139	525	-67 (0.27)	2173	479
		(0.87)				(0.91)			
2	2.9	590	-71 (0.25)	1103	143	585	-71 (0.33)	848	368
		(0.94)				(0.93)			
3	1.7	510	-73 (0.25)	679	121	510	-73 (0.2)	390	650
		(0.82)				(0.77)			
4	3.1	615	-75 (0.31)	517	232	605	-75 (0.31)	370	511
		(0.95)				(0.97)			
5	1.8	530	-77 (0.35)	287	44	545	-79 (0.26)	215	280
		(0.87)				(0.85)			
6	1.8	625	-83 (0.12)	95	19	615	-91 (0.09)	152	35
		(0.44)				(0.46)			

747

748 Table 1. Regional-scale sound scattering layer (SSL) probability distribution (RSPD) characteristics ranked in accordance to their daytime smeso values. SCI is the seasonal 749 750 coverage index, which ranges between 1 (single season) and 4 (all seasons uniformly represented). Z<sub>PDSL</sub>, is the principal (most common) deep scattering layer (DSL; SSL deeper 751 than 200 m) depth, MVBSPDSL, is the most likely MVBS value for the principal DSL, given that 752 a DSL is observed, and s<sub>meso</sub> and s<sub>epi</sub>, are the nautical area scattering coefficient (NASC) 753 754 values for SSLs found within the mesopelagic (200 – 1000 m) and epipelagic (0 – 200 m) 755 zones respectively. Bracketed values are stability of principal DSL depth (PPDSL) and principal DSL MVBS value (PPMVBS). Day-to-night increase in NASC in the epipelagic and decrease in the 756 mesopelagic implies DVM (shaded cells). 757