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# The Complexity of Counting Models of Linear-time Temporal Logic

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**Abstract** We determine the complexity of counting models of bounded size of specifications expressed in Linear-time Temporal Logic.

Counting word-models is  $\#P$ -complete, if the bound is given in unary, and as hard as counting accepting runs of nondeterministic polynomial space Turing machines, if the bound is given in binary.

Counting tree-models is as hard as counting accepting runs of nondeterministic exponential time Turing machines, if the bound is given in unary. For a binary encoding of the bound, the problem is at least as hard as counting accepting runs of nondeterministic exponential space Turing machines, and not harder than counting accepting runs of nondeterministic doubly-exponential time Turing machines.

Finally, counting arbitrary transition systems satisfying a formula is  $\#P$ -hard and not harder than counting accepting runs of nondeterministic polynomial time Turing machines with a PSPACE oracle, if the bound is given in unary. If the bound is given in binary, then counting arbitrary models is as hard as counting accepting runs of nondeterministic exponential time Turing machines.

**Keywords** Model Counting · Temporal Logic · Model Checking · Counting Complexity

## 1 Introduction

*Model counting*, the problem of computing the *number of models* of a logical formula, generalizes the satisfiability problem and has diverse applications:

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many probabilistic inference problems, such as Bayesian net reasoning [14], and planning problems, such as computing the robustness of plans in incomplete domains [16], can be formulated as model counting problems of propositional logic. Model counting for Linear-time Temporal Logic (LTL) has been recently introduced in [9]. LTL is the most commonly used specification logic for reactive systems [17] and the standard input language for model checking [3, 6] and synthesis tools [4, 5, 7]. LTL model counting asks for computing the number of transition systems that satisfy a given LTL formula. As such a formula has either zero or infinitely many models one considers models of *bounded* size: for a formula  $\varphi$  and a bound  $k$ , the problem is to count the number of models of  $\varphi$  of size  $k$ . This is motivated by applications like bounded model checking [3] and bounded synthesis [8], where one looks for short error paths and small implementations, respectively, by iteratively increasing a bound on the size of the model. Just like propositional model counting generalizes satisfiability, by considering two types of bounded models, namely, *word-models* (of length  $k$ ) and *tree-models* (of height  $k$ ), the authors of [9] introduced quantitative extensions of model checking and synthesis.

Word-models are ultimately periodic words of the form  $u.v^\omega$  of length  $k = |u.v|$ , which are used to model computations of a system. Counting word-models can be used in *model checking* to determine not only the existence of computations that violate the specification, but also the *number* of such *violations*. To this end, one turns the model checking problem into an LTL satisfiability problem by encoding the transition system and the negation of the specification into a single LTL formula. Its models represent erroneous computations of the system, i.e., counting them gives a quantitative notion of satisfaction.

Tree-models are finite trees (of fixed out-degree) of height  $k$  with back-edges at the leaves, i.e., tree-models can be exponentially-sized in the bound. They are used to describe implementations of the input-output behavior of reactive systems (see, e.g., [8]), namely the edges of a tree-model represent the input behavior of the environment and the nodes represent the corresponding output behavior of the system. In *synthesis*, counting tree-models can be used to determine not only the existence of an implementation that satisfies the specification, but also the *number* of such *implementations*. This number is a helpful metric to understand how much room for implementation choices is left by a given specification, and to estimate the impact of new requirements on the remaining design space.

For *safety* LTL specifications [19], algorithms solving the word- and the tree-model counting problem were presented in [9]. The running time of the algorithms is linear in the bound and doubly-exponential respectively triply-exponential in the length of the formula. The high complexity in the length of formula is, however, not a major concern in practice, since specifications are typically small while models are large (cf. the state-space explosion problem).

Here, we complement these algorithms by analyzing the computational complexity of the model counting problems for *full* LTL by placing the problems into counting complexity classes. These classes are based on counting ac-

cepting runs of nondeterministic Turing machines. In his seminal paper on the complexity of computing the permanent [21], Valiant introduced the class  $\#P$  of counting problems associated with counting accepting runs of nondeterministic polynomial time Turing machines: a function  $f: \Sigma^* \rightarrow \mathbb{N}$  is in  $\#P$  if there is a nondeterministic polynomial time Turing machine  $\mathcal{M}$  such that  $f(w)$  is equal to the number of accepting runs of  $\mathcal{M}$  on  $w$ . Furthermore, for a class  $\mathcal{C}$  of decision problems, he defined  $\#_o\mathcal{C}$  to be the class of counting problems induced by counting accepting runs of a nondeterministic polynomial time Turing machine with an oracle from  $\mathcal{C}$ .<sup>1</sup>

A nondeterministic polynomial time Turing machine  $\mathcal{M}$  (with or without oracle) has at most  $\mathcal{O}(2^{p(n)})$  different runs on inputs of length  $n$  for some polynomial  $p$ . This means that there is an exponential upper bound on functions in  $\#P$  and in  $\#_o\mathcal{C}$  for every  $\mathcal{C}$ . However, an LTL tautology has exponentially many word-models of length  $k$  and more than doubly-exponentially many tree-models of height  $k$ . This means, that no function in any of the counting classes defined above can capture all the counting problems for LTL, in particular if the bound  $k$  is encoded in binary.

To overcome this, we consider counting classes obtained by lifting the restriction on considering only nondeterministic polynomial time (oracle) machines: a function  $f: \Sigma^* \rightarrow \mathbb{N}$  is in  $\#PSPACE$ , if there is a nondeterministic polynomial *space* Turing machine  $\mathcal{M}$  such that  $f(w)$  is equal to the number of accepting runs of  $\mathcal{M}$  on  $w$ .<sup>2</sup> The classes  $\#EXPTIME$ ,  $\#EXPSPACE$ , and  $\#2EXPTIME$  are defined analogously.<sup>3</sup> Some of these classes appeared in the literature, e.g.,  $\#PSPACE$  was shown to be equal to  $FPSPACE$  [12] (if the output is encoded in binary). Also, computing a specific entry of a matrix power  $A^n$  is in  $\#PSPACE$ , if  $A$  is represented succinctly and  $n$  in binary [15]. Another problem in  $\#PSPACE$  is counting the number of Skolem functions satisfying a QBF formula [2]. Finally, counting self-avoiding walks in succinctly represented hypercubes is complete for  $\#EXPTIME$  [13] under right-bit-shift reductions.

We place the LTL model counting problems in these classes. Unsurprisingly, the encoding of the bound  $k$  is crucial: for unary bounds, we show counting word-models to be  $\#P$ -complete and show counting tree-models to be  $\#EXPTIME$ -complete. For binary bounds, the word-model counting problem is  $\#PSPACE$ -complete and counting tree-models is  $\#EXPSPACE$ -hard and in  $\#2EXPTIME$ . Our proofs of these results also have implications for the general model counting problem for LTL, where one is interested in computing the number of transition systems of a given size that satisfy a given formula. We show this problem to be  $\#P$ -hard and in  $\#_oPSPACE$  for unary bounds and  $\#EXPTIME$ -complete for binary bounds.

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<sup>1</sup> Valiant originally used the notation  $\#\mathcal{C}$ , but we added the subscript to distinguish the oracle-based classes from the classes introduced below.

<sup>2</sup> In an unpublished note [22], Williams has another definition of  $\#PSPACE$  which he shows to be equal to  $\#P$ .

<sup>3</sup> Following the “satanic” [10] tradition of naming counting classes, we drop the N (standing for nondeterministic) in the names of the classes, just as it is done for  $\#P$ .

Our upper bounds hold for full LTL while the formulas for the lower bounds define safety properties (using only the temporal operators next and release). Thus, the lower bounds already hold for the fragment considered in [9].

The algorithms we present to prove the upper bounds are not practical since they are based on guessing a word (tree) and then model checking it. Hence, a deterministic variant of these algorithms would enumerate all words (trees) of length (height)  $k$  and then run a model checking algorithm on them. In particular, the running time of the algorithms is exponential (or worse) in the bound  $k$ , which is in stark contrast to the practical algorithms [9]. Our lower bounds are reductions from the problem of counting accepting runs of a Turing machine. For the word counting problem, the reductions are slight strengthenings of the reduction proving PSPACE-hardness of the LTL model checking problem [18]. However, the reductions in the tree case are more involved (and to the best of our knowledge new), since we have to deal with exponential time respectively exponential space Turing machines. The main technical difficulties are to encode runs of exponential length and with configurations of exponential size into tree-models of “small” LTL formulas and to ensure that there is a one-to-one correspondence between accepting runs and models of the constructed formula.

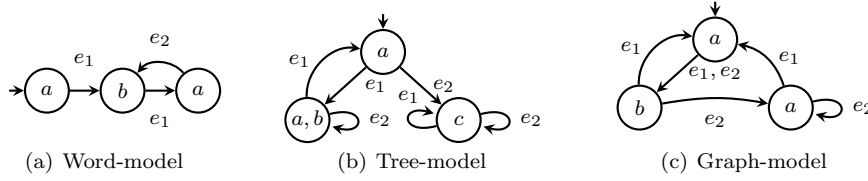
This paper is an extended version of the conference publication [20], and contains all proofs omitted there due to space restrictions and a new section about the general model counting problem.

## 2 Preliminaries

We represent models as *labeled transition systems*. For a given finite set  $\mathcal{Y}$  of directions and a finite set  $\Sigma$  of labels, a  $\Sigma$ -labeled  $\mathcal{Y}$ -transition system is a tuple  $\mathcal{S} = (S, s_0, \tau, o)$ , consisting of a finite set of states  $S$ , an initial state  $s_0 \in S$ , a transition function  $\tau: S \times \mathcal{Y} \rightarrow S$ , and a labeling function  $o: S \rightarrow \Sigma$ . A *path* in  $\mathcal{S}$  is a sequence  $\pi: \mathbb{N} \rightarrow S \times \mathcal{Y}$  of states and directions that follows the transition function, i.e., for all  $i \in \mathbb{N}$  if  $\pi(i) = (s_i, e_i)$  and  $\pi(i+1) = (s_{i+1}, e_{i+1})$ , then  $s_{i+1} = \tau(s_i, e_i)$ . We call the path initial if it starts with the initial state:  $\pi(0) = (s_0, e)$  for some  $e \in \mathcal{Y}$ .

We use Linear-time Temporal Logic (LTL) [17], with the usual temporal operators Next  $\circ$ , Until  $\mathcal{U}$ , Release  $\mathcal{V}$ , and the derived operators Eventually  $\diamond$  and Globally  $\square$ . We use  $\circ^i$  to refer to  $i$  nested next operators. LTL formulas are defined over a set of atomic propositions  $AP = I \cup O$ , which is partitioned into a set  $I$  of input propositions and a set  $O$  of output propositions. We denote the satisfaction of an LTL formula  $\varphi$  by an infinite sequence  $\sigma: \mathbb{N} \rightarrow 2^{AP}$  of valuations of the atomic propositions by  $\sigma \models \varphi$ . A  $2^O$ -labeled  $2^I$ -transition system  $\mathcal{S} = (S, s_0, \tau, o)$  satisfies  $\varphi$ , if for every initial path  $\pi$  the sequence  $\sigma_\pi: i \mapsto o(\pi(i))$ , where  $o(s, e) = (o(s) \cup e)$ , satisfies  $\varphi$ . Then  $\mathcal{S}$  is a model of  $\varphi$ .

A *k-word-model* of an LTL formula  $\varphi$  over  $AP$  is a pair  $(u, v)$  of finite words over  $2^{AP}$  such that  $|u.v| = k$  and  $u.v^\omega \models \varphi$ . We call  $u$  the prefix and  $v$



**Fig. 1** A word-model of length three, a tree-model of height one and a graph-model of size three for the formula  $\Box(b \rightarrow \bigcirc a)$ .

the period of  $(u, v)$ . Note that an ultimately periodic word might be induced by more than one  $k$ -word-model, i.e.,  $\{a\}^\omega$  is induced by the 2-word-models  $(\{a\}, \{a\})$  and  $(\varepsilon, \{a\}\{a\})$ .

A  $k$ -tree-model of an LTL formula  $\varphi$  over  $AP = I \cup O$  is a  $2^O$ -labeled  $2^I$ -transition system that forms a tree (whose root is the initial state) of height  $k$  with added back-edges from the leaves (for each leaf and direction, there is an edge to a state on the branch leading to the leaf) that satisfies  $\varphi$ . For the sake of simplicity, we refer to trees with back-edges as trees. As for word-models, two different tree-models might induce the same infinite unrolled tree.

Finally, a  $k$ -graph-model of an LTL formula  $\varphi$  over  $AP = I \cup O$  is a  $2^O$ -labeled  $2^I$ -transition system with  $k$  states that satisfies  $\varphi$ , where every state is reachable from the initial one (this avoids counting graph-models with unreachable states, which are already accounted for for some smaller  $k'$ ).

Figure 1 shows a word-model of length three, a tree-model of height one and a graph-model of size three for the formula  $\Box(b \rightarrow \bigcirc a)$ .

Fix  $AP = I \cup O$ . For a formula  $\varphi$  and  $k \in \mathbb{N}$ , the  $k$ -word counting problem asks to compute the number of  $k$ -word-models of  $\varphi$  over  $AP$ . The  $k$ -tree counting problem and the  $k$ -graph counting problem are defined analogously, but only count  $k$ -tree-models and  $k$ -graph-models, respectively, up to isomorphism.

### 3 Counting Complexity Classes

We use nondeterministic Turing machines with or without oracle access to define counting complexity classes, which we assume (without loss of generality) to terminate on every input. For background on (oracle) Turing machines and counting complexity we refer to [1].

A function  $f: \Sigma^* \rightarrow \mathbb{N}$  is in the class  $\#\text{P}$  [21] if there is a nondeterministic polynomial time Turing machine  $\mathcal{M}$  such that  $f(w)$  is equal to the number of accepting runs of  $\mathcal{M}$  on  $w$ . Similarly, for a given complexity class  $\mathcal{C}$  of decision problems, a function  $f$  is in  $\#\text{o}\mathcal{C}$  [21, 10] if there is a nondeterministic polynomial time oracle Turing machine  $\mathcal{M}$  with oracle in  $\mathcal{C}$  such that  $f(w)$  is equal to the number of accepting runs of  $\mathcal{M}$  on  $w$ . As a nondeterministic polynomial time Turing machine  $\mathcal{M}$  (with or without oracle) has at most

$\mathcal{O}(2^{p(n)})$  runs on inputs of length  $n$  for some polynomial  $p$  (that only depends on  $\mathcal{M}$ ), we obtain an exponential upper bound on functions in  $\#P$  and  $\#_o\mathcal{C}$  for every  $\mathcal{C}$ , which explains the need for larger counting classes to characterize the model counting problems for LTL.

A function  $f: \Sigma^* \rightarrow \mathbb{N}$  is in  $\#PSPACE$ , if there is a nondeterministic polynomial *space* Turing machine  $\mathcal{M}$  such that  $f(w)$  is equal to the number of accepting runs of  $\mathcal{M}$  on  $w$ . The classes  $\#EXPTIME$ ,  $\#EXPSPACE$ , and  $\#2EXPTIME$  are defined by counting accepting runs of nondeterministic exponential time, exponential space, and doubly-exponential time machines.

**Proposition 1**

1.  $\#P \subseteq \#_oPSPACE \subseteq \#_oEXPTIME \subseteq \#_oNEXPTIME \subseteq \#_oEXPSPACE \subseteq \#_o2EXPTIME$ .
2.  $\#PSPACE \subseteq \#EXPTIME \subsetneq \#EXPSPACE \subseteq \#2EXPTIME$ .
3.  $f \in \#EXPTIME$  implies  $f(w) \in \mathcal{O}(2^{2^{p(|w|)}})$  for a polynomial  $p$ .
4.  $f \in \#2EXPTIME$  implies  $f(w) \in \mathcal{O}(2^{2^{2^{p(|w|)}}})$  for a polynomial  $p$ .
5.  $w \mapsto 2^{2^{|w|}}$  is in  $\#PSPACE$
6.  $w \mapsto 2^{2^{2^{|w|}}}$  is in  $\#EXPSPACE$ .

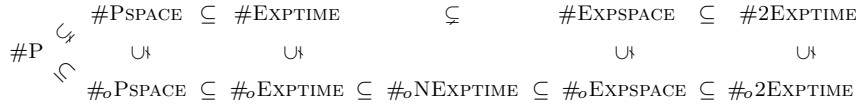
We continue by relating the oracle-based and the generalized classes introduced above, e.g., we show that  $\#_oPSPACE$  is a strict subset of  $\#PSPACE$ . Recall that  $\#_oPSPACE$  is based on nondeterministic polynomial time Turing machines with access to a  $PSPACE$  oracle. Such an oracle can be decided by a *deterministic* polynomial space Turing machine. The determinism is crucial for obtaining our result. On the other hand, the class  $\#PSPACE$  is based on nondeterministic polynomial space Turing machines, which are able to simulate the machine deciding the oracle.

**Lemma 1**  $\#_oC \subsetneq \#C$  for  $C \in \{PSPACE, EXPTIME, EXPSPACE, 2EXPTIME\}$ .

*Proof* We show  $\#_oPSPACE \subsetneq \#PSPACE$ , the other claims are proven analogously. Let  $f \in \#_oPSPACE$ , i.e., there is a nondeterministic polynomial time Turing machine  $\mathcal{M}$  with oracle  $A \in PSPACE$  such that  $f(w)$  is equal to the number of accepting runs of  $\mathcal{M}$  on  $w$ . Note that all oracle queries are polynomially-sized in the length  $|w|$  of the input to  $\mathcal{M}$ , since  $\mathcal{M}$  is polynomially time-bounded. Hence, in nondeterministic polynomial space one can simulate  $\mathcal{M}$  and evaluate the oracle calls explicitly by running a deterministic machine deciding  $A$  in polynomial space. Since the oracle queries are evaluated deterministically, the simulation has as many accepting runs as  $\mathcal{M}$  has. Thus,  $f \in \#PSPACE$ .

Now, consider the function  $|w| \mapsto 2^{2^{|w|}}$ , which is in  $\#PSPACE$ , but not in  $\#_oPSPACE$ .  $\square$

The inclusions between the complexity classes stated in Proposition 1 and Lemma 1 are visualized in Figure 2.



**Fig. 2** Inclusions between the complexity classes.

We use parsimonious reductions to define hardness and completeness, i.e., the most restrictive notion of reduction for counting problems. A counting problem  $f$  is  $\#P$ -hard, if for every  $f' \in \#P$  there is a polynomial time computable function  $r$  such that  $f'(x) = f(r(x))$  for all inputs  $x$ . In particular, if  $f'$  is induced by counting the accepting runs of  $\mathcal{M}$ , then  $r$  depends on  $\mathcal{M}$  (and possibly on its time-bound  $p(n)$ ). Furthermore,  $f$  is  $\#P$ -complete, if  $f$  is  $\#P$ -hard and  $f \in \#P$ . Hardness and completeness for the other classes are defined analogously.

## 4 Counting Word-Models

In this section, we provide matching lower and upper bounds for the complexity of counting  $k$ -word-models of an LTL specification.

Our hardness proofs are based on constructing an LTL formula  $\varphi_{\mathcal{M}}^w$  for a given Turing machine  $\mathcal{M}$  and an input  $w$  that encodes the accepting runs of  $\mathcal{M}$  on  $w$ . Constructing such an LTL formula is straightforward and can be done in polynomial time for Turing machines with polynomially-sized configurations [18]. However, the challenge is to construct  $\varphi_{\mathcal{M}}^w$  such that the number of accepting runs on  $w$  is equal to the number of  $k$ -word-models of  $\varphi_{\mathcal{M}}^w$  for a fixed bound  $k$ . To this end, we have to enforce that each accepting run is represented by a unique  $k$ -word-model, i.e., by a unique prefix and period of total length  $k$ . We choose  $k$  such that a run on  $w$  of maximal length can be encoded in  $k - 1$  symbols and define  $\varphi_{\mathcal{M}}^w$  such that it has only  $k$ -word-models whose period has length one. If a run of  $\mathcal{M}$  is shorter than the maximal-length run we repeat the final configuration until reaching the maximal length, which is achieved by accompanying the configurations in the encoding with consecutive id's.

For the upper bounds we show that there are appropriate nondeterministic Turing machines that guess an ultimately-periodic word and model check it against  $\varphi$ , i.e., the number of accepting runs on  $k$  and  $\varphi$  is equal to the number of  $k$ -word-models of  $\varphi$ .

### 4.1 The Case of Unary Encodings.

First, we consider the word-model counting problem for unary bounds: the problem is  $\#P$ -complete. We start by proving the upper bound.

**Lemma 2** *The following problem is in  $\#P$ : Given an LTL formula  $\varphi$  and a bound  $k$  (in unary), how many  $k$ -word-models does  $\varphi$  have?*

*Proof* To show that the problem is in #P we define a nondeterministic polynomial time Turing machine  $\mathcal{M}$  as follows. The machine  $\mathcal{M}$  guesses a prefix  $u$  and a period  $v$  of an ultimately periodic word  $u.v^\omega$  with  $|u.v| = k$ , and checks deterministically in polynomial time [11], whether  $u.v^\omega$  satisfies  $\varphi$ . Hence, for each  $k$ -word-model  $(u, v)$  of  $\varphi$  there is exactly one accepting run of  $\mathcal{M}$ . Thus, counting the  $k$ -word-models of  $\varphi$  can be done by counting the accepting runs of  $\mathcal{M}$  on the input  $(k, \varphi)$ .  $\square$

The matching #P lower bound follows trivially from the #P-hardness of the model counting problem for propositional formulas [21] by interpreting variables as atomic propositions and considering models of length one. Altogether, we obtain the following result.

**Theorem 1** *The following problem is #P-complete: Given an LTL formula  $\varphi$  and a bound  $k$  (in unary), how many  $k$ -word-models does  $\varphi$  have?*

#### 4.2 The Case of Binary Encodings.

Now, we consider the word counting problem for binary bounds. As the input is more compact, we have to deal with a larger complexity class, i.e., we show the problem to be complete for #PSPACE. We begin with the upper bound.

**Lemma 3** *The following problem is in #PSPACE: Given an LTL formula  $\varphi$  and a bound  $k$  (in binary), how many  $k$ -word-models does  $\varphi$  have?*

*Proof* For the proof of the upper bound we cannot just guess a  $k$ -model in polynomial space as in Lemma 2, since the bound  $k$  is encoded in binary. Instead, we guess and verify the model on-the-fly relying on standard techniques for LTL model checking.

Formally, we construct a nondeterministic polynomial space Turing machine  $\mathcal{M}$  which guesses a  $k$ -word-model  $(u, v)$  by guessing  $u\$v = w(0) \cdots w(i-1)\$ w(i) \cdots w(k-1)$  symbol by symbol in a backwards fashion. Here,  $\$$  is a fresh symbol to denote the beginning of the period. To meet the space requirement,  $\mathcal{M}$  only stores the currently guessed symbol  $w(j)$ , discards previously guessed symbols, and uses a binary counter to guess exactly  $k$  symbols.

To verify whether  $u.v^\omega$  satisfies  $\varphi$ ,  $\mathcal{M}$  also creates for every  $j$  in the range  $0 \leq j < k$  a set  $C_j$  of subformulas of  $\varphi$  with the intention of  $C_j$  containing exactly the subformulas which are satisfied in position  $j$  of  $u.v^\omega$ . Due to space requirements,  $\mathcal{M}$  only stores the set  $C_{k-1}$  as well as the sets  $C_j$  and  $C_{j+1}$ , if  $w(j)$  is the currently guessed symbol. The set  $C_{k-1}$  is guessed by  $\mathcal{M}$  and the sets  $C_j$  for  $j < k-1$  are uniquely determined by the following rules:

- The membership of atomic propositions in  $C_j$  is determined by  $w(j)$ , i.e.,  $C_j \cap AP = w(j)$ .
- Conjunctions, disjunctions, and negations can be checked locally for consistency, e.g.,  $\neg\psi \in C_j$  if and only if  $\psi \notin C_j$ .



- $\bigcirc$ -formulas are propagated backwards using the following equivalence:  
 $\bigcirc\psi \in C_j$  if and only if  $\psi \in C_{j+1}$  (recall that  $\mathcal{M}$  stores  $C_j$  and  $C_{j+1}$ ).
- $\mathcal{U}$ -formulas are propagated backwards using the following equivalence:  
 $\psi_0\mathcal{U}\psi_1 \in C_j$  if and only if  $\psi_1 \in C_j$  or  $\psi_0 \in C_j$  and  $\psi_0\mathcal{U}\psi_1 \in C_{j+1}$ .
- $\mathcal{V}$ -formulas can be rewritten into  $\mathcal{U}$ -formulas.

Once  $\mathcal{M}$  has guessed the complete period  $v = w(i) \cdots w(k-1)$  it also checks that the guess of  $C_{k-1}$  is correct (recall that  $C_{k-1}$  is not discarded), which is the case if the following two requirements are met:

- For every subformula  $\bigcirc\psi$  we have  $\bigcirc\psi \in C_{k-1}$  if and only if  $\psi \in C_i$ .
- For every subformula  $\psi_0\mathcal{U}\psi_1$  we have  $\psi_0\mathcal{U}\psi_1 \in C_{k-1}$  if and only if  $\psi_1 \in C_{k-1}$  or  $\psi_0 \in C_{k-1}$  and  $\psi_0\mathcal{U}\psi_1 \in C_i$ . Furthermore, we have to require that  $\psi_0\mathcal{U}\psi_1 \in C_j$  for some  $j$  in the range  $i \leq j < k$  implies  $\psi_1 \in C_{j'}$  for some  $j'$  in the range  $i \leq j' < k$ . The latter condition can be checked on-the-fly while computing the  $C_j$ 's.

A straightforward structural induction over the construction of  $\varphi$  shows that we have  $\psi \in C_j$  if and only if  $w(j)w(j+1) \cdots w(k-1)v^\omega \models \psi$  for every subformula  $\psi$  of  $\varphi$ . Hence,  $u.v^\omega$  is a model of  $\varphi$  if and only if  $\varphi \in C_0$ . Thus,  $\mathcal{M}$  accepts if this is the case.  $\square$

Next, we complement the #PSPACE upper bound with a matching lower bound.

**Lemma 4** *The following problem is #PSPACE-hard: Given an LTL formula  $\varphi$  and a bound  $k$  (in binary), how many  $k$ -word-models does  $\varphi$  have?*

*Proof* Let  $\mathcal{M} = (Q, q_l, Q_F, \Sigma, \delta)$  be a one-tape nondeterministic polynomial space Turing machine, where  $Q$  is the set of states,  $q_l$  is the initial state,  $Q_F$  is the set of accepting states,  $\Sigma$  is the alphabet, and  $\delta: (Q \setminus Q_F) \times \Sigma \rightarrow 2^{Q \times \Sigma \times \{-1,1\}}$  is the transition function, where -1 and 1 encode the directions of the head. Note that the accepting states are terminal and that  $\mathcal{M}$  rejects by terminating in a nonaccepting state. Let  $\mathcal{M}$  be  $p(n)$ -space bounded for some polynomial  $p$ , and let  $w = w_0 \cdots w_{n-1}$  be an input to  $\mathcal{M}$ . Let  $p'(n)$  be a polynomial (which only depends on  $\mathcal{M}$ ) such that  $\mathcal{M}$  terminates in at most  $2^{p'(n)}$  steps on inputs of length  $n$ . We construct an LTL formula  $\varphi_{\mathcal{M}}^w$  and define a bound  $k$ , which are polynomial and exponential (using polynomially many bits) in  $|w|$  and  $|\mathcal{M}|$ , respectively, such that the number of accepting runs of  $\mathcal{M}$  on  $w$  is equal to the number of  $k$ -word-models of  $\varphi_{\mathcal{M}}^w$ .

A run of  $\mathcal{M}$  on  $w$  is encoded by a finite alternating sequence of id's  $id_i$  and configurations  $c_i$  that is followed by an infinite repetition of a dummy symbol:

$$\$ id_0 \# c_0 \$ id_1 \# c_1 \$ id_2 \# c_2 \$ \cdots \$ id_{2^{l_c}} \# c_{2^{l_c}} (\perp)^\omega \quad (1)$$

for some suitable  $l_c$  to be defined later. Note that the period of the word-model is of the form  $\perp^\ell$  for some  $\ell > 0$ . We define  $k$  such that maximal-length runs of  $\mathcal{M}$  on  $w$  can be encoded in the prefix, and such that the only possible period has length one by ensuring that exactly  $2^{l_c}$  configurations are encoded (by

repeating the final configuration if necessary). This ensures that an accepting run is encoded by exactly one  $k$ -word-model.

Let  $l_r = p(n)$  be the maximal size of a configuration of  $\mathcal{M}$  on  $w$ . For the id's we use an encoding of a binary counter with  $l_c = p'(n)$  many bits. Let  $AP = (Q \cup \Sigma) \cup \{b_1, \dots, b_{l_c}, \$, \#, \perp\}$  be the set of atomic propositions. The atomic propositions in  $Q \cup \Sigma$  are used to encode the configurations of  $\mathcal{M}$  by encoding the tape contents, the state of the machine, and the head position. The atomic propositions  $b_1, \dots, b_{l_c}$  represent the bit values of an id. The symbols  $\$$  and  $\#$  are used as separators between id's and configurations, and  $\perp$  is a dummy symbol for the model's period. The distance between two  $\$$  symbols and also between two  $\#$  symbols in the encoding is given by  $d = l_r + 3$  (see (1)). Then,  $\varphi_{\mathcal{M}}^w$  is the conjunction of the following formulas:

- *Id* encodes the id's of the configurations. It uses a formula  $Inc(b_1, \dots, b_{l_c}, d)$  that asserts that the number encoded by the bits  $b_j$  after  $d$  steps is obtained by incrementing the number encoded at the current position. This formula is reused in the tree case.
- *Init* asserts that the run of  $\mathcal{M}$  starts with the initial configuration.
- *Accept* asserts that the run must reach an accepting configuration.
- *Config* declares the consistency of two successive configurations with the transition relation of  $\mathcal{M}$ . Here, we use  $d$  many next operators to relate the encoding of the two configurations.
- *Repeat* asserts that the encoding of an accepting configuration is repeated until the maximal id is reached
- *Loop* defines the period of the word-model, which may only contain  $\perp$ .

We show that all these properties can be expressed with polynomially-sized formulas. Furthermore, we need a formula to specify technical details: atomic propositions encoding the id's are not allowed to appear in the configurations and vice versa, symbols such as  $\$$  and  $\#$  only appear as separators, each separator appears  $2^{p'(n)}$  times every  $d$  positions, configuration encodings are represented by singleton sets of letters in  $\Sigma$  with the exception of one set that contains a symbol from  $Q$  to determine the head position and the state of  $\mathcal{M}$ , etc.

We start with the formula *Id*, which uses the formula *Inc* that enforces an increment of a binary counter. For later reuse, *Inc* is parameterized by the propositions  $b_1, \dots, b_\ell$  encoding the bits ( $b_1$  being the most significant one) and the distance  $d$  between the two positions to be compared. Intuitively, the different subformulas distinguish whether the increment ripples through to the current bit  $b_i$  or not. Note that the increment property only has to hold if there is no overflow of the counter.

$$Inc(b_1, \dots, b_\ell, d) = \left( \bigvee_{0 < i \leq \ell} \neg b_i \right) \rightarrow \bigwedge_{0 < i \leq \ell} \left[ \left( (\neg b_i \wedge \bigwedge_{i < j \leq \ell} b_j) \rightarrow \bigcirc^d b_i \right) \wedge \left( (\neg b_i \wedge \neg \bigwedge_{i < j \leq \ell} b_j) \rightarrow \bigcirc^d \neg b_i \right) \right]$$

$$\begin{aligned} & \wedge((b_i \wedge \bigwedge_{i < j \leq \ell} b_j) \rightarrow \bigcirc^d \neg b_i) \\ & \wedge((b_i \wedge \neg \bigwedge_{i < j \leq \ell} b_j) \rightarrow \bigcirc^d b_i) \end{aligned}$$

Now, the formula  $Id$  is defined by initializing the counter to zero and always requiring an increment after a  $\$$ -separator:

$$Id = \$ \wedge \bigcirc(\bigwedge_{0 < j \leq l_c} \neg b_j) \wedge \square(\$ \rightarrow \bigcirc Inc(b_1, \dots, b_{l_c}, d))$$

We continue with the formula  $Init$ . In the initial configuration the tape of  $\mathcal{M}$  contains the input word  $w$ , the head is on the first cell, and  $\mathcal{M}$  is in its initial state:

$$Init = \bigcirc^2(\# \wedge \bigcirc q_l \wedge (\bigwedge_{0 \leq j < n} \bigcirc^j w_j) \wedge (\bigwedge_{n \leq j \leq l_r} \bigcirc^j \sqcup))$$

The symbol  $\sqcup$  refers to the blank cells of the tape.

The formula  $Accept$  considers the maximal id and checks whether it is followed by an accepting configuration:

$$Accept = \square(\$ \wedge \bigcirc(\bigwedge_{0 < j \leq l_c} b_j) \rightarrow \bigvee_{q \in Q_F} \bigvee_{0 < j \leq l_r} \bigcirc^{j+2} q)$$

For atomic propositions  $q \in Q \setminus Q_F$  and  $\alpha \in \Sigma$  a formula  $config_{q,\alpha}$  asserts the relation between the states, the head positions, and the content of the cell where the head is pointing to in two successive configurations:

$$config_{q,\alpha} = \square(q \wedge \alpha \rightarrow \bigvee_{(q', \beta, \text{dir}) \in \delta(q, \alpha)} \bigcirc^d \beta \wedge \bigcirc^{d+\text{dir}} q')$$

Another formula  $config_\alpha$  asserts the relation of the other tape cells of successive configurations; the content of these cells is copied, unless the id is maximal:<sup>4</sup>

$$config_\alpha = \square(\$ \wedge \bigcirc(\bigvee_{0 < j \leq l_c} \neg b_j) \rightarrow \bigwedge_{0 < j \leq l_r} \bigcirc^{j+2} ((\bigwedge_{q \in Q \setminus Q_F} \neg q) \wedge \alpha \rightarrow \bigcirc^d \alpha))$$

$Config$  is the conjunction of all formulas  $config_\alpha$  and  $config_{q,\alpha}$ .

The formula  $Repeat$  requires an accepting configuration to be repeated if the id is not yet maximal. The repetition of the letters is taken care of by the formulas  $config_\alpha$ . Hence,  $Repeat$  only requires to copy the state and the head position.

$$Repeat = \square(\$ \wedge (\bigcirc \bigvee_{0 < j \leq l_c} \neg b_j) \rightarrow \bigwedge_{q_f \in Q_F} \bigwedge_{0 < j \leq l_r} \bigcirc^{j+2} (q_f \rightarrow \bigcirc^d q_f))$$

<sup>4</sup> Note that this is not necessary for  $config_{q,\alpha}$  since the machine terminates in at most  $p(n)$  steps

Finally, the period of the model is fixed by the formula *Loop* which requires the symbol  $\perp$  to be repeated after reaching the configuration with the maximal id:

$$\text{Loop} = \square(\$ \wedge \bigcirc(\bigwedge_{0 < j \leq l_c} b_j) \rightarrow \bigcirc^{l_r+3} \square \perp)$$

Now, let us prove that the formula has the desired properties: For  $k = 2^{l_c} \cdot (l_r + 3) + 1$ , each accepting run of  $\mathcal{M}$  on  $w$  corresponds to exactly one  $k$ -word-model of  $\varphi_{\mathcal{M}}^w$  that encodes the run in its prefix. Thus, the number of  $k$ -word-models is equal to the number of accepting runs of  $\mathcal{M}$  on  $w$ . The formula  $\varphi_{\mathcal{M}}^w$  can be obtained in polynomial time in  $|w| + |\mathcal{M}|$ , and  $k$  is exponential in  $|w|$  so it can be encoded in binary with polynomially many bits.  $\square$

Lemma 4 and Lemma 5 show that the word-model counting problem for binary bounds is indeed  $\#\text{PSPACE}$ -complete.

**Theorem 2** *The following problem is  $\#\text{PSPACE}$ -complete: Given an LTL formula  $\varphi$  and a bound  $k$  (in binary), how many  $k$ -word-models does  $\varphi$  have?*

## 5 Counting Tree-Models

In this section, we consider the tree counting problem for unary and binary bounds. There are at least doubly-exponentially many trees of height  $k$ . Hence, if  $k$  is encoded in binary, there are at least triply-exponentially many (in the size of the encoding of  $k$ )  $k$ -tree-models of a tautology. In order to capture these cardinalities using counting classes, we have to consider machines with that many runs, i.e., exponential time and exponential space machines.

In our hardness proofs, we again construct formulas  $\varphi_{\mathcal{M}}^w$  that encode accepting runs of  $\mathcal{M}$  on  $w$  in trees. We choose binary trees, i.e., we consider a singleton set  $I$  of input propositions. Recall that the power set of  $I$  is used to (deterministically) label the edges in the tree. In the following, we identify the two elements of  $2^I$  with the directions **left** and **right**. Note that we have to formalize the structure of our models and have to encode the runs of the machines using LTL. The semantics require a formula to be satisfied on all paths, which requires us to write conditional formulas of the form “if the path has a certain form, then some property is satisfied”. We use two types of formulas: the first type describes the structure of the tree (e.g., it is complete and the targets of the back-edges) while the ones of the second type encode the actual run relying on this structure. The formulas of type one often assign addresses to nodes (sequences of bits that uniquely identify a node).

In the word case, we encoded runs of Turing machines with configurations of polynomial length. Hence, the distance between encodings of a tape cell in two successive configurations could be covered by a polynomial number of next-operators. Here, configurations are of exponential size. Thus, the challenge is to encode a run in a tree such that properties of two successive configurations

can still be encoded by an LTL formula of polynomial size. We present two such encodings, one for unary and one for binary bounds.

For the upper bounds we show that there are appropriate nondeterministic machines that guess a finite tree with back-edges and model check it deterministically against  $\varphi$ , i.e., the number of accepting runs on  $k$  and  $\varphi$  is equal to the number of  $k$ -tree-models of  $\varphi$ .

### 5.1 The Case of Unary Encodings

First, we consider tree-model counting for unary bounds, which we show to be  $\#EXPTIME$ -complete. The upper bound is a straightforward application of LTL model checking: the Turing machine guesses a tree and then model checks it. To count up to isomorphism, we identify a node of the tree with the unique sequence of directions in  $2^I$  leading from the root to it.

**Lemma 5** *The following problem is in  $\#EXPTIME$ : Given an LTL formula  $\varphi$  and a bound  $k$  (in unary), how many  $k$ -tree-models does  $\varphi$  have?*

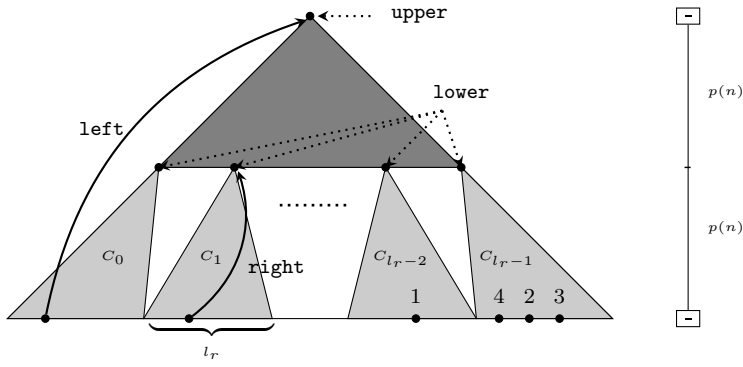
*Proof* To show that the problem is in  $\#EXPTIME$  we define a nondeterministic exponential time Turing machine  $\mathcal{M}$  as follows.  $\mathcal{M}$  guesses a tree of height  $k$  (which is of exponential size) and checks whether it satisfies  $\varphi$  using the classical model checking algorithm: the machine  $\mathcal{M}$  constructs the Büchi automaton recognizing the language of  $\neg\varphi$  and checks whether the product of the tree and the automaton has an empty language. The automaton and the product are of exponential size and the emptiness check can be performed in deterministic polynomial time (in the size of the product). Hence,  $\mathcal{M}$  runs in exponential time in  $k$  and the size of  $\varphi$ . For each  $k$ -tree-model of  $\varphi$ , there is exactly one accepting run in  $\mathcal{M}$ . Thus, counting the  $k$ -tree-models of  $\varphi$  can be done by counting the accepting runs of  $\mathcal{M}$  on the input  $(k, \varphi)$ .  $\square$

The next lemma shows  $\#EXPTIME$ -hardness of the tree-model counting problem for unary bounds.

**Lemma 6** *The following problem is  $\#EXPTIME$ -hard: Given an LTL formula  $\varphi$  and a bound  $k$  (in unary), how many  $k$ -tree-models does  $\varphi$  have?*

*Proof* Let  $\mathcal{M} = (Q, q_L, Q_F, \Sigma, \delta)$  be a one-tape nondeterministic exponential time Turing machine. Let  $\mathcal{M}$  be  $2^{p(n)}$ -time bounded for a polynomial  $p$  and let  $w = w_0 \cdots w_{n-1}$  be an input to  $\mathcal{M}$ . We construct an LTL formula  $\varphi_{\mathcal{M}}^w$  and define a bound  $k$ , both polynomial in  $|w|$  and  $|\mathcal{M}|$ , such that the number of accepting runs of  $\mathcal{M}$  on  $w$  is equal to the number of  $k$ -tree-models of  $\varphi_{\mathcal{M}}^w$ .

A run of  $\mathcal{M}$  is encoded in the leaves of a binary tree. Let  $l_r = 2^{p(n)}$  be the maximal length of a run of  $\mathcal{M}$  on  $w$ , which also bounds the size of a configuration. We choose  $k = 2p(n)$  to be the height of our tree-models. By using a formula labeling each of the first  $k$  levels of the tree by a unique proposition we enforce that every model of height  $k$  is complete. Thus, it has



**Fig. 3** Encoding an exponentially long run in a tree-model of polynomial height. The configurations are encoded in the lower-trees (light gray subtrees).

$l_r^2$  many leaves, enough to encode a run of maximal length. Figure 3 shows the structure of our tree-model.

Each configuration in the run is encoded in the leaves of a subtree of height  $p(n)$ , referred to as a *lower-tree* (depicted by the light gray trees). The lower-trees are uniquely determined by a leaf of the *upper-tree* (depicted in dark gray), which is the root of the lower-tree. By giving the leaves of the upper-tree id's, we also obtain unique id's for each of the lower-trees. These id's are used to enumerate the configurations of the run, i.e., two neighboring lower-trees encode two successive configurations of the run. The id's can be determined by a binary counter with polynomially many bits. We also provide each leaf in a lower-tree with a unique id within this lower-tree. This is used to compare the contents of a tape cell in two successive configurations by comparing the labels of leaves with the same leaf id in two successive lower-trees. Thus, every leaf stores the id encoding of the configuration it is part of and the number of the cell it encodes.

Recall that in a tree each leaf has a back-edge for every direction. For the direction **left** we require a transition to the root of the upper-tree, and for **right** a transition to the root of the own lower-tree. This enables us to compare two leaves in a lower-tree, or two leaves with the same id in two different lower-trees, with polynomially large formulas.

The following formulas define the structure of our tree-models as explained above and also provide the nodes of the tree with correct id's. We begin with  $Addr(\text{root}, a_1, \dots, a_d)$  which specifies a unique id for each leaf of a complete binary tree of height  $d$  using bits  $a_1, \dots, a_d$ , and provides the root of the tree with a label **root**. The id of a node depends on the sequence of **left** and **right** edges on the path from the root to this node, which is encoded in the bits  $a_1, \dots, a_d$ :

$$Addr(\text{root}, a_1, \dots, a_d) = \text{root} \wedge \bigwedge_{i=0}^{d-1} (\bigcirc^i(\text{left} \rightarrow \bigcirc^{d-i} \neg a_{i+1}) \wedge$$

$$\bigcirc^i(\mathbf{right} \rightarrow \bigcirc^{d-i} a_{i+1})$$

We use the formula  $Addr(\mathbf{upper}, u_1, \dots, u_{p(n)})$  to address the upper-tree. This gives each lower-tree a unique id via the id of its root. We also supply each node in a lower-tree with the id of its root in the upper-tree:

$$\bigwedge_{p(n) \leq i < k} \bigcirc^i \left( \bigwedge_{j=1}^{p(n)} (u_j \leftrightarrow \bigcirc u_j) \right)$$

Furthermore, we use the formula  $\bigcirc^{p(n)} Addr(\mathbf{lower}, l_1, \dots, l_{p(n)})$  to assign every leaf in a lower-tree a unique id within its lower-tree which essentially encodes the number of the tape cell it encodes. The next two formulas define the back-edges of the lower-trees. From each leaf, the  $\mathbf{left}$  transition leads back to the root of the upper-tree (recall that back-edges lead from a leaf to an ancestor), i.e.,  $\bigcirc^k(\mathbf{left} \rightarrow \bigcirc \mathbf{upper})$ , and the  $\mathbf{right}$  transition to the root of the lower-tree, i.e.,  $\bigcirc^k(\mathbf{right} \rightarrow \bigcirc \mathbf{lower})$ .

After setting up the structure of the trees, it remains to show how we encode a run in the leaves. We proceed with the same scheme as in the word case, and use the formula  $\Delta_h(a_1, \dots, a_m)$  which is satisfied, if and only if the bits  $a_1, \dots, a_m$  encode the number  $h < 2^m$ . The formula  $Init$  encodes the initial configuration in the lower-tree with id 0.

$$\begin{aligned} \bigcirc^k [ & \Delta_0(u_1, \dots, u_{p(n)}) \rightarrow ((\Delta_0(l_1, \dots, l_{p(n)}) \rightarrow q_l) \\ & \wedge \bigwedge_{0 \leq j < n} (\Delta_j(l_1, \dots, l_{p(n)}) \rightarrow w_j) \\ & \wedge ((\bigwedge_{0 \leq j < n} \neg \Delta_j(l_1, \dots, l_{p(n)})) \rightarrow \heartsuit) ) ] \end{aligned}$$

The formula  $Accept$  checks whether the rightmost lower-tree encodes an accepting configuration:

$$\bigcirc^k ((\Delta_{l_r}(u_1, \dots, u_{p(n)}) \wedge \bigvee_{q \in Q} q) \rightarrow \bigvee_{q \in Q_F} q)$$

The formulas  $config_{q,\alpha}$  and  $config_\alpha$  for states  $q$  and symbols  $\alpha$  encode the transition relation. For a leaf with labels  $q$  and  $\alpha$  (leaf 1 in Figure 3) and a transition  $(q, \alpha, q', \beta, \mathbf{dir})$ , we have to check three leaves in the next lower-tree, namely, the leaf with the same id (leaf 2) has to be labeled with  $\beta$ , and depending on  $\mathbf{dir}$  either the successor leaf (leaf 3) or the predecessor leaf (leaf 4) has to be labeled with  $q'$ . The premise of the following formula only holds for paths that visit these leaves in the order given above, i.e., paths that lead to a leaf in a lower-tree, loop back to the root of the full tree and then lead to the same leaf id in the successor lower-tree (this takes  $k + 1$  edges), loop back to the root of this lower-tree and visit the leaf to the right (this takes another  $p(n) + 1$  edges), back to the root of this lower-tree again and then to the leaf to the left (this takes  $p(n) + 1$  edges more). To specify such a path, we use the formula  $Inc$  from the proof of Lemma 5 to reach the successor leaf and a dual formula called  $Dec$  to reach the predecessor leaf. This formula

implements a decrement of a nonzero counter. Note that we have to require the paths to visit the successor and predecessor leaf in the next lower-tree, i.e., we have to check the bits  $u_j$  to reach the next lower-tree and the bits  $l_j$  to reach the leaves. Thus,  $config_{q,\alpha}$  for  $q \in Q \setminus Q_F$  is given by:

$$\begin{aligned} & \mathcal{O}^k \left[ q \wedge \alpha \wedge Inc(u_1, \dots, u_{p(n)}, k+1) \wedge \bigwedge_{i=1}^{p(n)} l_i \leftrightarrow \mathcal{O}^{k+1} l_i \right. \\ & \quad \wedge Inc(u_1, \dots, u_{p(n)}, k+p(n)+2) \wedge Inc(l_1, \dots, l_{p(n)}, k+p(n)+2) \\ & \quad \left. \wedge Inc(u_1, \dots, u_{p(n)}, k+2p(n)+3) \wedge Dec(l_1, \dots, l_{p(n)}, k+2p(n)+3) \right. \\ & \quad \left. \rightarrow \bigvee_{(q',\beta, \text{dir}) \in \delta(q,\alpha)} (\mathcal{O}^{k+1} \beta \wedge \mathcal{O}^{(k+1)+c_{\text{dir}}(p(n)+1)} q') \right] \end{aligned}$$

Here, we have  $c_{\text{dir}} = 1$ , if  $\text{dir} = 1$ , and  $c_{\text{dir}} = 2$ , if  $\text{dir} = -1$ .

The formula  $config_\alpha$  determines the relation between the other tape cells' contents, namely where the head is not pointing to:

$$\begin{aligned} & \mathcal{O}^k \left( \bigvee_{i=1}^{p(n)} \neg u_i \wedge \left( \bigwedge_{q \in Q \setminus Q_F} \neg q \right) \wedge \alpha \wedge Inc(u_1, \dots, u_{p(n)}, k+1) \right. \\ & \quad \left. \wedge \left( \bigwedge_{i=1}^{p(n)} l_i \leftrightarrow \mathcal{O}^{k+1} l_i \right) \rightarrow \mathcal{O}^{k+1} \alpha \right) \end{aligned}$$

The formula *Repeat* repeats accepting states in the next lower-tree, if the id of the current lower-tree is not maximal. The repetition of the letters is being taken care of by  $config_\alpha$ .

$$\begin{aligned} & \mathcal{O}^k \left[ \left( \bigvee_{i=1}^{p(n)} \neg u_i \wedge Inc(u_1, \dots, u_{p(n)}, k+1) \wedge \bigwedge_{i=1}^{p(n)} (l_i \leftrightarrow \mathcal{O}^{k+1} l_i) \right) \rightarrow \right. \\ & \quad \left. \left( \bigwedge_{q_f \in Q_F} q_f \rightarrow \mathcal{O}^{k+1} q_f \right) \right] \end{aligned}$$

Similar to the word case we need some additional formulas to prevent atomic propositions of configurations to appear elsewhere in the tree to guarantee the one-to-one relation between runs and tree-models. For example to prevent a state label from appearing twice in a configuration we use a formula that asserts that from a leaf in which a state is encoded, no other leaf with a state label is reachable within  $p(n)+1$  steps, i.e., in the same lower-tree. This ensures that every configuration has exactly one state.  $\square$

Combining Lemma 6 and Lemma 7 yields the desired #EXPTIME-completeness result.

**Theorem 3** *The following problem is #EXPTIME-complete: Given an LTL formula  $\varphi$  and a bound  $k$  (in unary), how many  $k$ -tree-models does  $\varphi$  have?*



## 5.2 The Case of Binary Encodings.

In this section, we consider tree-model counting for binary bounds. Since the bound is encoded compactly, the trees we work with have exponential height and therefore doubly-exponential size. Unfortunately, our upper and lower bounds do not match (see the discussion in the conclusion). We start by proving the upper bound for the problem.

**Theorem 4** *The following problem is in #2EXPTIME: Given an LTL formula  $\varphi$  and a bound  $k$  (in binary), how many  $k$ -tree-models does  $\varphi$  have?*

*Proof* The upper bound is proved using the same algorithm as in the proof of Lemma 6. With a doubly-exponentially time bounded Turing machine we can guess a tree with back-edges that is exponential large in the bound  $k$  and model check it against  $\varphi$ .  $\square$

We continue with the proof of the #EXPSpace lower bound.

**Theorem 5** *The following problem is #EXPSpace-hard: Given an LTL formula  $\varphi$  and a bound  $k$  (in binary), how many  $k$ -tree-models does  $\varphi$  have?*

*Proof* Let  $\mathcal{M} = (Q, q_L, Q_F, \Sigma, \delta)$  be a one-tape nondeterministic exponential space Turing machine and let  $w = w_0 \cdots w_{n-1}$  be an input to  $\mathcal{M}$ . Furthermore, let  $l_c = 2^{p(n)} - 2$  be the maximal configuration length (for some polynomial  $p$ ) and let  $l_r = 2^{p'(n)}$  be the maximal length of a run of  $\mathcal{M}$  on  $w$  ( $p'$  is a polynomial which only depends on  $\mathcal{M}$ ).

We choose  $k = m \cdot 2^{p'(n)}$  to be the height of our tree-models, where  $m$  is the smallest power of two greater than  $p(n)$ . Figure 4 shows the main structure of our tree-models. We use nonbalanced binary trees that are composed of trees of height  $m$ . We refer to the latter trees as the *inner-trees*. The outermost leaves of an inner-tree are inner nodes and the others are leaves in the tree-model. Hence, each inner-tree has two children, which are again inner-trees rooted at the leftmost respectively the rightmost leaf.

In each inner-tree, we encode a configuration in a similar way as in the unary case (Theorem 3), namely in the leaves (except the two leaves serving as roots for other inner trees, which explains the  $-2$  in the definition of  $l_c$ ). We encode the configurations of a run in the tree-model such that we traverse the inner-trees in a depth-first search manner (DFS). In Figure 4, we can see how a run of 15 configurations can be encoded in a tree-model with four layers of inner-trees. To encode the DFS structure, we label each root of an inner-tree with its *level* (the number of inner-tree ancestors) and with its so-called *right-child-depth*: the number of right-child-inner-trees visited since the last left child to reach this tree (e.g., this value is 0 for the root  $C_1$  and all left children, for example for  $C_2, C_3, C_7$ ; it is 1 for  $C_5$  and 3 for  $C_{15}$ ). This allows to determine the next inner-tree in line in the DFS structure. We need a polynomial number of bits to encode these addresses. With the **right** transition we allow the leaves of an inner-tree to reach its root and we use **left** in the inner-tree of maximal

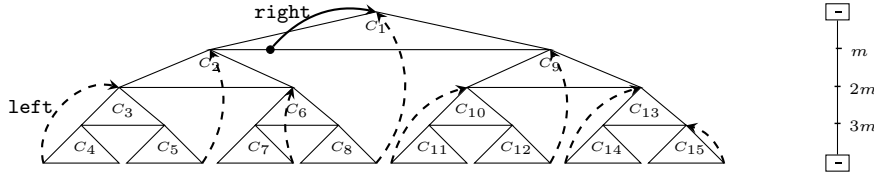


Fig. 4 Tree-model with DFS structure.

level to reach the parent of the next inner-tree in DFS order. In this way, the distance between the encoding of a tape cell in two successive configurations is polynomial.

As the distance between an inner-tree and its successor is polynomial, the formulas for encoding the run in the tree-model adapt the ideas of the formulas in the unary case with slight modifications that deal with the DFS order of inner-trees. In the following, we formalize this sketch.

The following formulas define the structure of our tree-models and also provide them with the correct level and right-child-depth. We use propositions  $\iota_1, \dots, \iota_m$  to give *ids* to the leaves of an inner-tree. For the  $2^{p'(n)}$  different levels of inner-trees in our tree-models we use propositions  $l_1, \dots, l_h$ , where  $h = p'(n)$ , to encode for each inner-tree its *level*. We also give internally for each node in an inner-tree its *depth* in this tree via  $d_1, \dots, d_{\log(m)}$  (remember that  $m$  is a power of 2). Propositions  $r_1, \dots, r_h$  are used to determine the inner-tree's *right-child-depth*. The maximum right-child-depth that can be reached is  $2^{p'(n)}$ , namely for the rightmost inner-tree at the maximal level.

We start by labeling each root of an inner-tree (and no other vertices) with the label **root**:

**root** $\wedge$

$$\square \left[ (\mathbf{root} \wedge \neg \left( \bigwedge_{0 < i \leq h} l_i \right) \wedge \left( \left( \bigwedge_{0 \leq j < m} \mathcal{O}^j \mathbf{left} \right) \vee \left( \bigwedge_{0 \leq j < m} \mathcal{O}^j \mathbf{right} \right) \right) \right] \leftrightarrow \mathcal{O}^m \mathbf{root} \right]$$

The negation of the conjunction over propositions  $l_i$  is used to exclude inner-trees of the last level. How the levels are defined in the tree is shown in more detail in the formula *depth*.

We encode a configuration in the leaves of an inner-tree in the same way as in the unary case (Lemma 3). Therefore, we provide the leaves with unique id's, which enable us to compare the contents of tape cells in two successive configurations by comparing leaves with the same id in two successive inner-trees. To this end, we use the formula *Addr*, as defined in the unary case, to equip the leaves with unique id's within their inner-tree:

$$\square (\mathbf{root} \rightarrow \mathit{Addr}(\mathbf{root}, \iota_1, \dots, \iota_m))$$

The next formula uses the propositions  $l_1, \dots, l_h$  to supply each inner-tree with its level, which is equal to the number of **root** labels visited from the root to this inner-tree. Line (1) assigns the root of the tree-model with level 0.

Line (2) assigns each node in an inner-tree, with the exception of the leaves labeled with **root** (the outermost leaves in all levels but the last), with the level of its inner-tree root. Line (3) gives, inductively, each root of an inner-tree its inner-tree level.

$$depth = \bigwedge_{0 < j \leq h} \neg l_j \quad (1)$$

$$\wedge \square(\mathbf{root} \rightarrow \bigwedge_{0 \leq j < m} \bigcirc^j (\bigcirc \neg \mathbf{root} \rightarrow \bigwedge_{0 < j \leq h} (l_j \leftrightarrow \bigcirc l_j))) \quad (2)$$

$$\wedge \square(\mathbf{root} \wedge (\bigvee_{0 < j \leq h} \neg l_j) \wedge \bigcirc^m \mathbf{root} \rightarrow Inc(l_1, \dots, l_h, m)) \quad (3)$$

If *depth* is satisfied then the tree contains a doubly-exponential number of inner-trees, enough to encode a run of  $\mathcal{M}$  on  $w$ .

The following formula gives each inner-tree its right-child-depth in the tree-model. If we are at a root of an inner-tree we reach the root of its left and right child in  $m$  steps via the outermost leaves. The formula counts the number of right-children visited along the way including the visited tree (Line (3)). Every time we visit a left-child the counter is reset (Line (4)). We again supply each node in an inner-tree, with the exception of the outermost leaves (Line (5)), with the right-child-depth of this tree. However the outermost leaves of all maximal-level inner-trees are labeled with the right-child-depth of the inner-tree.

$$rLevel = \bigwedge_{0 < j \leq h} \neg r_j \quad (1)$$

$$\wedge \square(\mathbf{root} \wedge \bigvee_{0 < j \leq h} \neg l_j \rightarrow \quad (2)$$

$$((\bigwedge_{0 < j \leq m} \bigcirc^j \mathbf{right}) \rightarrow Inc(r_1, \dots, r_h, m)) \quad (3)$$

$$\wedge ((\bigwedge_{0 < j \leq m} \bigcirc^j \mathbf{left}) \rightarrow \bigwedge_{0 < j \leq h} \neg r_j)) \quad (4)$$

$$\wedge \square(\mathbf{root} \rightarrow \bigwedge_{0 \leq j < m} \bigcirc^j (\bigcirc \neg \mathbf{root} \rightarrow \bigwedge_{0 < j \leq h} r_j \leftrightarrow \bigcirc r_j))) \quad (5)$$

Now that we have defined all the id's we need we show how to route the transitions at the leaves to the DFS positions as described earlier. To compute the correct node we only need to compute its level, because in the definition of our tree-models we force a back-edge to go to an ancestor node. This level can be computed as follows. If we are at a leaf of an inner-tree in the maximal level, reached by  $j$  many right children since the last left child the back-edge goes to the root with level  $2^{p'(n)} - (j + 1)$  (cf. Figure 4). This can be formulated by incrementing the right-child-depth described with bits  $r_1, \dots, r_h$  and inverting the bits of the result. The propositions  $d_1, \dots, d_{\log(m)}$  are used to talk about

the leaves of an inner-tree. If we are at a leaf in an inner-tree of maximal level we move with direction **left** to the next DFS position, namely the root of the next inner-tree in the DFS Line (computed by *addNflip*):

*DFS* =

$$\square \left( \bigwedge_{0 < j \leq \log(m)} d_j \wedge \bigwedge_{0 < j \leq h} l_j \wedge \mathbf{left} \rightarrow \bigcirc \mathbf{root} \wedge \mathit{addNflip}(l_1, \dots, l_h, r_1, \dots, r_h) \right)$$

where:

$$\begin{aligned} \mathit{addNflip}(l_1, \dots, l_c, r_1, \dots, r_c) = & \bigwedge_{0 < i \leq c} [((\neg r_i \wedge \bigwedge_{i < j \leq c} r_j) \rightarrow \bigcirc \neg l_i) \\ & \wedge ((\neg r_i \wedge \neg \bigwedge_{i < j \leq c} r_j) \rightarrow \bigcirc l_i) \\ & \wedge ((r_i \wedge \bigwedge_{i < j \leq c} r_j) \rightarrow \bigcirc l_i) \\ & \wedge ((r_i \wedge \neg \bigwedge_{i < j \leq c} r_j) \rightarrow \bigcirc \neg l_i)] \end{aligned}$$

Notice that *addNflip* is similar to *Inc* with the difference of flipping the bits.

Finally, a formula that asserts that from leaves of maximal level inner-trees a **right** transition goes to the root of these trees (Line (1)). For leaves of inner-trees of nonmaximal level (the outermost leaves are not considered leaves of the tree-model as their **right** and **left** transitions lead to subtrees), we move with both **left** and **right** to the root of their inner-trees (Line (2)):

$$\square \left( \bigwedge_{0 < j \leq \log(m)} d_j \wedge \bigwedge_{0 < j \leq h} l_j \wedge \mathbf{right} \rightarrow \bigcirc (\mathbf{root} \wedge \bigwedge_{0 < j \leq h} l_j) \right) \quad (1)$$

$$\wedge \square \left( \bigwedge_{0 < j \leq \log(m)} d_j \wedge \left( \bigvee_{0 < j \leq h} \neg l_j \right) \wedge \neg \mathbf{root} \rightarrow \bigcirc \mathbf{root} \wedge \left( \bigwedge_{0 < j \leq h} l_j \leftrightarrow \bigcirc l_j \right) \right) \quad (2)$$

Now, we present the formulas that encode the run of the Turing machine. Here, we again use the formula  $\Delta_h(a_1, \dots, a_m)$  which is satisfied, if and only if the bits  $a_1, \dots, a_m$  encode the number  $h < 2^m$ .

The formula *Init*:

$$\begin{aligned} \mathit{Init} = & \bigcirc^m ((\Delta_1(t_1, \dots, t_m) \rightarrow q_t) \\ & \wedge \left( \bigwedge_{0 \leq j < n} (\Delta_{j+1}(t_1, \dots, t_m) \rightarrow w_j) \right) \\ & \wedge \left( \left( \bigwedge_{0 < j \leq n} (\neg \Delta_j(t_1, \dots, t_m)) \rightarrow \lrcorner \right) \right)) \end{aligned}$$

Note that we encode the input word  $w = w_0 \cdots w_{n-1}$  in the leaves with id's 1 to  $n$ . In our encoding the outermost leaves of the inner-trees do not encode

any tape content of the Turing machine. This is due to the fact that in some inner-trees these leaves have no back-edges from which we can directly reach the leaves of the next inner-tree in DFS order. Thus, the content in the next configuration is not accessible.

The formula *Accept* checks the last inner-tree in DFS order for an accepting configuration. The first release formula selects the outermost right path and stops at the root of the last inner-tree. If we arrive at this root we assert that the state in the configuration of this inner-tree must be accepting:

$$(\mathbf{right} \wedge \neg \Delta_{2^h-1}(l_1, \dots, l_h)) \mathcal{V}(\Delta_{2^h-1}(l_1, \dots, l_h)) \quad (1)$$

$$\rightarrow (\mathbf{right} \wedge \neg \Delta_{2^h-1}(l_1, \dots, l_h)) \mathcal{V} \quad (2)$$

$$(\Delta_{2^h-1}(l_1, \dots, l_h) \wedge \mathcal{O}^m(\bigvee_{q \in Q} q \rightarrow \bigvee_{q \in Q_F} q)) \quad (3)$$

We define the formula *Next* to determine the successor inner-tree of an inner-tree, i.e., the formula holds at a vertex on a path if after  $m$  steps on this path the root of the next inner-tree in DFS order is reached:

$$Next = [(\bigvee_{0 < j \leq m} \neg l_j) \quad (1)$$

$$\rightarrow \mathbf{right} \wedge (\bigwedge_{0 < j \leq m} \mathcal{O}^j \mathbf{left})] \quad (2)$$

$$\wedge [(\bigwedge_{0 < j \leq m} l_j) \quad (3)$$

$$\rightarrow \mathbf{left} \wedge (\bigwedge_{0 < j \leq m} \mathcal{O}^j \mathbf{right})] \quad (4)$$

We distinguish two cases asserted by Lines (1) and (3), namely the case of an inner-tree in the maximal level and one in a nonmaximal level. In the second case, the successor tree is the left child of the current inner-tree. Here, we go up to the root of the inner-tree and traverse down the left side to the root of the left child (Line (2)). If we are in the maximal level the successor tree is reached via the DFS order, which means, going to the inner-tree in DFS order and traversing down the right side to the right child (Line (4)).

If we are at a leaf with symbol  $\alpha \in \Sigma$  and state  $q \in Q \setminus Q_F$  we move to the root of the next inner-tree in DFS order (this is determined by the formula *Next*). In this tree we have to check whether  $\alpha$  is rewritten to the correct symbol and whether the head moved to the correct position. This is checked in the same way as in the proof of the unary case, namely, in three phases: we consider a path that leads to a leaf in successor inner-tree with the same leaf id, loops back up to the root of the inner-tree, and leads down to the same tree and visits the leaf to the right, loops back up and down the same tree and visits the leaf on the left (Lines (2),(3)). In Line (4), the distance  $2m + 1$  results from going one step in the inner-tree and then going  $2m$  steps down to

the leaves of the successor tree. The distance  $3m + 2$  results from looping in the same tree a second time, and  $4m + 3$  from looping a third time.

Here, we again use the formulas *Inc* and *Dec* introduced above.

$$\text{config}_{q,\alpha} = \Box(q \wedge \alpha \wedge \text{Next} \wedge (\bigwedge_{j=1}^m \iota_j \leftrightarrow \bigcirc^{4m+1} \iota_j)) \quad (1)$$

$$\wedge \text{Inc}(\iota_1, \dots, \iota_m, 3m + 2) \wedge \bigcirc^{2m+1}(\mathbf{right} \wedge \bigcirc \mathbf{root}) \quad (2)$$

$$\wedge \text{Dec}(\iota_1, \dots, \iota_m, 4m + 3) \wedge \bigcirc^{3m+2}(\mathbf{right} \wedge \bigcirc \mathbf{root}) \quad (3)$$

$$\rightarrow (\bigvee_{(q', \beta, \mathbf{dir}) \in \delta(q, \alpha)} \bigcirc^{2m+1} \beta \wedge \bigcirc^{c_{\mathbf{dir}}(m+1)-1} q') \quad (4)$$

where  $c_{\mathbf{dir}} = 3$  for  $\mathbf{dir} = 1$  and  $c_{\mathbf{dir}} = 4$  for  $\mathbf{dir} = -1$ .

The formula  $\text{config}_\alpha$  is similar:

$$\text{config}_\alpha = \Box((\bigwedge_{q \in Q \setminus Q_F} \neg q) \wedge \alpha \wedge \text{Next} \wedge (\bigwedge_{j=1}^m \iota_j \leftrightarrow \bigcirc^{2m+1} \iota_j) \rightarrow \bigcirc^{2m+1} \alpha)$$

Note that due to the DFS structure, we do not need to check for the configuration having a nonmaximal id as in the unary case.

Finally the formula *Repeat* propagates all final states  $q$  to the successor tree:

$$\begin{aligned} \text{Repeat} &= \Box((\bigvee_{j=1}^h \neg r_j) \wedge \text{Next} \wedge (\bigwedge_{j=1}^m \iota_j \leftrightarrow \bigcirc^{2m+1} \iota_j)) \\ &\rightarrow (\bigvee_{q \in Q_F} (q \rightarrow \bigcirc^{2m+1} q)) \end{aligned}$$

Again we need an additional formula that for example forces the atomic propositions to appear only in the designated node or to have only one state label in each inner-tree, and additional ones for other technical properties.  $\square$

## 6 Counting Graph-Models

In this section, we consider the graph-model counting problem and show how the results shown in the previous sections can be transferred to this problem. Recall that the graph-model counting problem asks to determine the number of transitions systems (up to isomorphism) with  $k$  states that satisfy a given LTL formula.

### 6.1 The Case of Unary Encodings

The following theorem shows the lower and upper bounds for the problem of counting graph-models for unary bounds. The lower bound is shown by

enforcing the models to *look* like a word-model and then applying the #P-hardness proof for those. The upper bound we present here is #<sub>o</sub>PSPACE, the only occurrence of an oracle-based complexity class. We discuss this gap in the conclusion.

**Theorem 6** *The following problem is #P-hard and in #<sub>o</sub>PSPACE: Given an LTL formula  $\varphi$  and a bound  $k$  (in unary), how many  $k$ -graph-models does  $\varphi$  have?*

*Proof* Hardness can be shown by applying the same idea of the proof of Lemma 5 using a nondeterministic polynomial time Turing machine where both the size of the configuration and the length of the maximal run are polynomial. We add a polynomially-sized formula implementing a counter with  $\lceil \log k \rceil$  bits that is satisfied if and only if the transition system is a cycle of length  $k$  (in particular, all outgoing transitions lead to the same state). Then, one can encode a run of a nondeterministic polynomial time Turing machine on such a cycle as using the formula  $\varphi_{\mathcal{M}}^w$  from the proof of Lemma 5.

Membership in #<sub>o</sub>PSPACE is an immediate consequence of LTL model checking being in PSPACE, i.e., one can guess a transition system with  $k$  states and then use a PSPACE oracle for model-checking it. To only count models up to isomorphism, we identify a state by the minimal path of directions in  $2^I$  leading from the initial state to it and guess the transition system in a breadth-first manner starting at the initial state.  $\square$

## 6.2 The Case of Binary Encodings

Our last result shows matching lower and upper bounds for the problem of counting graph-models for binary bounds, which both follow from adapting previous proofs.

**Theorem 7** *The following problem is #EXPTIME-complete: Given an LTL formula  $\varphi$  and a bound  $k$  (in binary), how many  $k$ -graph-models does  $\varphi$  have?*

*Proof* For binary bounds, adapting the construction presented in Lemma 7 yields #EXPTIME-hardness: To this end, one uses a formula of polynomial size in  $\lceil \log k \rceil$  that is satisfied by a transition system if and only if it is a  $\lceil \log k \rceil$ -tree. Then, one can use the formula  $\varphi_{\mathcal{M}}^w$  constructed in the proof of Lemma 7 to encode an accepting run of an exponential time Turing machine.

Finally, the problem is in #EXPTIME, which can be shown by adapting the algorithm presented in the proof of Lemma 6, again making sure to count models up to isomorphism by naming states canonically.  $\square$

## 7 Discussion

We investigated the complexity of the model counting problem for specifications in linear-time temporal logic. The word-model counting problems are

$\#P$ -complete (for unary bounds) respectively  $\#PSPACE$ -complete (for binary bounds) while the tree-model counting problems are  $\#EXPTIME$ -complete respectively  $\#EXPSPACE$ -hard and in  $\#2EXPTIME$ , i.e., the exact complexity of the tree-model counting problem for binary bounds is open. Finally, the graph-model counting problem is  $\#P$ -hard and in  $\#_oPSPACE$  (for unary bounds) respectively  $\#EXPTIME$ -complete (for binary bounds), i.e., the exact complexity of the unary case is open, too.

First, let us discuss the gap in the tree-case: the problem we face trying to lower the upper bound is that we cannot guess the complete tree-model in non-deterministic exponential space. To meet the space requirements, we have to construct it step by step, as in the proof of the corresponding upper bound in the word case. However, the correctness of the on-the-fly model checking procedure described there relies on the fact that the model is an ultimately-periodic word. It is open whether the technique can be extended to tree-models. On the other hand, if we try to raise the lower bound, we have to encode nondeterministic doubly-exponential time Turing machines, which seems challenging using polynomially-sized LTL formulas. *Deterministic* doubly-exponential time Turing machines are routinely encoded by such formulas in the context of two-player games, where one player produces sequences of configurations and the other one checks that he respects the transition relation. It is an interesting open question whether the role of the second player can be replaced by the tree structure of the models, which are able to encode strategies.

Finally, let us discuss the second gap in our results, in the unary case of the graph-model counting problem: here, the  $\#P$ -membership is questionable, because of the  $PSPACE$ -hardness of the model-checking problem. However, a  $\#P$  algorithm does not violate standard complexity theoretic assumptions, as the size  $k$  is part of the input and encoded in unary. On the other hand, showing  $\#_oPSPACE$ -hardness requires to encode computations of a decider for the oracle in a small transition system, which seems challenging as well.

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