1 **Title:** Slow lorises (*Nycticebus* spp.) display evidence of handedness in the wild and in 2 captivity

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5 Keywords: Nocturnal Primate, Handedness, Hand Use, Indonesia, Feeding

6 **Abstract:**

7 It has been suggested that strepsirrhines (lemurs, lorises, and galagos) retain the more 8 primitive left hand preference, whilst monkeys and apes more regularly display a right hand 9 preference at the individual-level. We looked to address questions of laterality in the slow 10 loris (*Nycticebus* spp.) using spontaneous observations of seven wild individuals, unimanual 11 tests in six captive individuals, and photos of 44 individuals in a bilateral posture assessing 12 handedness at the individual- and group-level. During the unimanual reach task, we found 13 at the individual-level, only four slow lorises showed a hand use bias (R: 3, L:1), Handedness 14 index (HI) ranged from -0.57-1.00. In the wild unimanual grasp task we found at the 15 individual-level two individual showed a right-hand bias, the HI ranged from -0.19-0.70. The 16 bilateral venom pose showed a trend toward a right hand dominant grip in those 17 photographed in captivity, but an ambiguous difference in wild individuals. There are many 18 environmental constraints in captivity that wild animals do not face, thus data collected in 19 wild settings are more representative of their natural state. The presence of right-20 handedness in these species suggest that there is a need to re-evaluate the evolution of 21 handedness in primates.

22

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48 Introduction

49 Humans show a bias for right-handedness across all populations, regardless of culture and 50 geographic location (Faurie & Raymond, 2004; Faurie, Schiefenhvel, le Bomin, Billiard, & 51 Raymond, 2005; McGrew & Marchant, 1994; Raymond & Pontier, 2004). No other species 52 shows this level of consistency in hand preference (Cashmore, Uomini, & Chapelain, 2008; 53 Cochet & Byrne, 2013). The roots of motor asymmetries can be traced back to early 54 vertebrates (Vallortigara, Rogers, & Bisazza, 1999). To uncover the root of this asymmetry, 55 researchers investigated handedness and laterality in invertebrates and vertebrates 56 including non-human primates (MacNeilage, Rogers, & Vallortigara, 2009; Neufuss et al., 57 2015; Regaiolli, Spiezio, & Hopkins, 2016a; Regaiolli, Spiezio, & Vallortigara 2016b; Wiper, 58 2017). Hopkins (2013) suggested that the lack of universal handedness in primates 59 compared to humans was related to a qualitative difference in the way behavioural and 60 brain asymmetries are expressed. Others noted that there is a more prominent 61 disconnection between the species-wide handedness seen in humans versus non-human 62 hand preference (Cashmore et al., 2008; Marchant & McGrew, 2013). Despite these 63 debates, nearly 70% of non-human vertebrates that have been tested display hand 64 preference (Ströckens, Güntürkün, & Ocklenburg, 2013).

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Some researchers report the presence of an individual-level bias, but not a group-level bias
in hand preference among various non-human primates (McGrew & Marchant, 1997;
Papademetriou, Sheu, & Michel, 2005), as evidenced by studies of lemurs (Schnoell,
Huebner, Kappeler, & Fichtel, 2014), Old World monkeys (Chapelain et al., 2012; Regaiolli,
Spezio, & Hopkins, 2016b), and New World monkeys (Cameron & Rogers, 1999; Hook-

Costigan & Rogers, 1996; Hook & Rogers, 2008). Extensive research on chimpanzees, gorillas, baboons, and capuchins not only found an individual- and group-level bias, but they reported a preferential use of the right hand, similar to humans (Hopkins, 2006; Meguerditchian, Calcutt, Lonsdorf, Ross, & Hopkins, 2010; Vauclair, Meguerditchian, & Hopkins, 2005). At the individual-level, far more primate species display hand preferences in both unimanual and bimanual tasks, suggesting that individual-level handedness is not uniquely human (McGrew & Marchant 1997; Papademetriou et al., 2005; Hopkins, 2007).

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79 MacNeilage, Studdert-Kennedy, & Lindblom (1987) suggested that strepsirrhines (e.g., 80 lemurs, lorises, pottos and galagos) are characterized by a left hand preference, whilst in all 81 other primates the right hand is used preferentially. Despite this assertion, most formal 82 studies examining handedness in strepsirrhines have reported various results. At the group-83 level, Papademetriou et al. (2005) found that strepsirrhines, New World monkeys, and Old 84 World monkeys often showed a left-hand bias, whereas most apes show a right-hand bias 85 (e.g. Lonsdorf & Hopkins, 2005). Studies on strepsirrhines have covered lemur species (e.g. 86 Nelson, O'Karma, Ruperti, & Novak, 2009; Regaiolli et al., 2016a; Schnoell et al., 2014), 87 galagos (e.g. Dodson, Stafford, Forsythe, Seltzer, & Ward, 1992; Sanford, Guin, & Ward, 88 1984) and pottos (Karberger, 1980), using both spontaneous and experimental conditions in 89 both unimanual and bimanual tasks though primarily were tested in captive settings (e.g. 90 Fagot & Vauclair, 1991)

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92 Reports of a right hand preference and a left hand preference at the individual- and group-93 level further contribute to the confusion and debate as to the primitive state of laterality in 94 primates and ultimately humans. Rogers (2009) noted that hand preferences at the 95 individual-level are linked to general aspects of behaviour. The task used to measure hand 96 preference and laterality can have a strong effect on individual- and group-level 97 preferences. Complex bimanual tasks are consistently associated with a stronger 98 asymmetric response in primates at the individual- and group-level contrary to unimanual 99 tasks (Cantalupo, Vauclair, & Meunier, 2013; Hopkins et al., 2011; Meguerditchian, Vauclair, 100 & Hopkins, 2013). Thus it is vital to diversify the types of tasks examined in relation to 101 laterality and to examine both the individual- and the group-level.

103 Slow lorises were once classified as solitary primates, but following more in-depth studies 104 across species, we now know that they exhibit levels of social interaction comparable to 105 many diurnal primates (Wiens & Zitzmann, 2003; Nekaris, 2014). Slow lorises display unique 106 morphological and physiological features related to a hind-limb dominated non-leaping 107 locomotion. They are characterised by a vice-like grip, as they hold on to branches for long 108 durations throughout the day as they sleep, and when they cling to trunks for exudate 109 feeding at night. In addition to this strong grip, they use precision while quickly grabbing 110 insects, and reeling in flowers on fine branches to drink nectar, without damaging the flower 111 (Nekaris, 2014). Physiologically, slow lorises are the only venomous primates. When 112 preparing to bite, slow loris species regularly clasp their arms in a bilateral position called 113 the venom pose (Nekaris, Moore, Rode, & Fry, 2013). This unique posture is similar to hand-114 clasping in humans and the hand clasp grooming of chimpanzees. In the venom pose, slow 115 lorises use one hand to grasp the wrist of the other arm above their head in threatening 116 situations; this position enables them to mix the oils secreted from a brachial gland with 117 their saliva (Nekaris, Moore, Rode, & Fry, 2013). The venom pose is seen in most species of 118 slow loris, during instances of handling both in captivity and in the wild, providing a unique 119 opportunity to incorporate another behaviour to examine lateralization.

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Most studies on strepsirrhine manual laterality focused on the influence of posture on hand preference and simple hand reach preferences, where 'primitive' primates used their right hand for holding on to branches, and their left hand for reaching and grasping items. (Sanford & Ward, 1986; Forsythe, Milliken, Stafford, & Ward, 1988; Forsythe & Ward, 1988; Sanford & Ward, 1986). Many studies on laterality in primates have been conducted in captivity, although it has been suggested that the surrounding environment can influence the development of a hand preference.

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Researchers noted that strepsirrhines represent a valuable model for hemispheric lateralization because of their simple neural system and basal phylogenetic placement (Ward, 1991). Our goal in this study was to investigate hand preference in spontaneous unimanual tasks, including bilateral hand-clasp position in slow lorises, to determine if there is an individual or group- level lateralization. For the unimanual task, handedness was assessed by observing simple reaching for presented food items in captivity and spontaneous grabbing in the wild. For the bilateral position, we observed which hand subjects used to clasp their wrist during physical examinations.

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138 <u>Methods</u>

139 Bilateral hand clasp position (Venom pose):

140 We analyzed photos taken during physical examinations in both wild and captive 141 populations of slow lorises. These photos were taken between 2006 and 2014, and included 142 three species of slow lorises (Javan slow loris Nycticebus javanicus, greater slow loris N. 143 coucang, and Sumatran slow loris N. hilleri) as they employed the venom pose in which arms 144 are crossed above the animal's head as a defensive position (Figure 1). Forty-two individuals 145 made up the analysis of the slow loris bilateral clasp, which were photographed either at 146 wild field sites or rescue centres (Table 1). The species was determined based on the 147 geographic location and pelage coloration. We included only one photo of each of 42 148 observed individuals in the analysis, because any subsequent photos were from the same 149 session and lacked independence. We defined left hand preference as the left hand 150 clasping the right wrist and the digits are forward facing, and right hand preference was the 151 right hand grasping the left wrist and the digits are forward facing (Figure 1). The 152 experienced handling team followed a protocol approved by the Animal Ethics 153 Subcommittee at Oxford Brookes University and did not restrict arm movement in a way 154 that would influence which hand clasp their wrist during the venom pose.

155

156 Unimanual reach in captive slow lorises

157 We observed six individually-housed adult Sumatran slow lorises (M: 3| F: 3) at Cikananga 158 Wildlife Center (CWC) in Sukabumi, West Java, Indonesia, as they reached for presented 159 food items, which we classified as a unimanual reach tasks. We recorded which hand was 160 used each time a study subject reached for a presented food item. Individuals were sitting 161 symmetrically in front of three dishes presented to them outside of their cage. They had 162 equal access to each dish and were presented with either a thin slice of fruit or a small 163 mealworm in one of the dishes. All participants employed a single handed reach, which was 164 the only way they could successfully access the dishes through the mesh of their enclosures.

Here each single handed reach was defined as a unimanual reach task event, where we coded right, as the animal's right hand reaching for the dish and left represented the animal's left hand reaching for the dish.

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169 Unimanual grasping in wild slow lorises

170 From June 2015 - December 2017 we recorded the feeding techniques used in a population 171 of wild Javan slow lorises as a part of ongoing research at the Little Fireface Project field 172 station (LFP), Cipaganti, West Java, Indonesia (S7°6'6" 7°7' and E107°46' 107°46'5"). We 173 collected direct observational data using five-minute instantaneous sample points and all 174 occurrences of grasping behaviours (Altman, 1974). The main study area encompasses a 60 175 ha area of patches of cultivated lands, bamboo, shrubs, and trees used as lines of 176 demarcation (Nekaris et al., 2017). Nightly observations took place between 18:00 and 177 05:00, which constitute the slow lorises' active hours. Here we defined instances where 178 seven adult Javan slow lorises (M: 3 | F: 4) used their right or left hand to bring a food item 179 towards their mouth, as a unimanual grasp task (Figure 2).

180

181 Data analysis

182 To analyse the bilateral hand clasp we used descriptive statistic due to the lack of repeated 183 occurrence per individual. Results are reported as the mean count of either right- or left-184 handed clasping across all photos. To determine the preference at each site we used a one-185 sample binomial test. To determine individual preference in the two unimanual tasks, we 186 calculated the Handedness index (HI), or manual preference index for each slow loris across 187 all recorded hand grasping and reaching occurrences (Schmitt, Melchisedech, 188 Hammerschmidt, & Fischer, 2008). An HI of -1 represents a totally left-handed individual 189 and an HI of +1 represents a totally right-handed individual. A one-sample binomial test for 190 each slow loris in the unimanual reach and grasp task determined the significant bias in the 191 use of the right or left hand (Brand, Marchant, Boose, White, Rood, & Meinelt, 2017). To 192 analyse the unimanual task and spontaneous unimanual grasping at the group-level, we 193 performed a one-Sample T-test on the distribution of the Absolute Handedness index (ABS-194 HI) with significance set to p < 0.05.

195

196 <u>Results</u>

197 Bilateral hand clasp position (venom pose):

We found no significant difference between the two bilateral venom poses across all sites and species (binomial test, N=42, p=0.090). A total of 64% of lorises favoured the right position; 36% favoured the left position. The photos taken at the CWC centre (binomial test, N=16, p=0.804), IAR centre (binomial test, N=15, p=0.118), and SPC centre (binomial test, N=5, p=0.750) showed no significant difference. The mean right hand use was 56%, 73%, and 67%, respectively. The mean hand use for the photos taken of wild slow lorises was 50% right and 50% left, statistically there was no difference (binomial test, N=6, p=1.000).

205

206 Unimanual reach in captive slow lorises

At the group-level, we found a significant difference in the distribution of the HI (Onesample Test, N=6, t=4.92, p=0.004). When considered as one sample, the slow lorises used their right hand 57% of the observations and their left hand 43% of the observations. The mean absolute HI for this task was 0.45 ± 0.16 (Figure 3). At the individual-level only four slow lorises showed a hand use bias (R: 3, L:1), HI ranged from -0.57-1, two individuals (FO & MD) displayed a negative HI value, the other four had positive HI values (Table 2).

213

214 Unimanual grasping in wild slow lorises

At the group-level, we found a significant difference in the distribution of HI (One-sample Test, N=7, t=3.29, p=0.016). When considered as one sample, slow lorises used their right hand 64% of the observations and their left hand 37% of the observations. The mean absolute Handedness Index (HI) for this task was 0.56±0.34 (Figure 4). At the individuallevel two individual showed a right-hand bias (AL & FE), the HI ranged from -0.19-0.70, two individuals (MA & SH) displayed negative values, TE had a value of zero, and the others displayed positive values (Table 2).

222

223 Discussion

Despite the small sample size, the results of this study suggest that there is variation between hand preference in wild and captive individuals during unimanual reaching and grasping tasks, but not during bilateral positions. In the bilateral position, there was no difference in the preferred clasping hand during venom poses. In the unimanual task in captive slow lorises, there was a difference at the group-level. At the individual-level one individual showed a left hand preference. The unimanual grasping in the wild slow lorises also displayed significant right-hand preferences as a group. In addition to a lack of continuity regarding strepsirrhine laterality, each tested task has a varying effect on the manifestation of hemispheric biases (Fagot & Vauclair, 1991). The results in this study offer a counterpoint to the idea that strepsirrhines have retained a left hand bias, as an assumed ancestral state for primates including humans (Papademetriou et al., 2005).

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236 MacNeilage et al. (1987) observed that the hands of strepsirrhines showed some 237 specialization such as grasping for supports with the right hand (left hemisphere) and 238 striking prey with the left hand (right hemisphere), revealing that task demands elicited the 239 obligate use of a particular hemisphere. It has been suggested that the left hemisphere 240 develops before the right hemisphere (Fagard, 2013; MacNeilage, Rogers, & Vallortigara, 241 2009) and based on studies of a wide range of vertebrates without forelimbs/hands it is became 242 known that the brain lateralized well before handedness. 243 Studies show that there may be subtle functional differences between the left and right 244 hand (Sainburg, 2014; Schabowsky, Hidler, & Lum, 2007). These authors provide a structure 245 for understanding the motor control process that lead to handedness. In this dynamic 246 dominance model, the left hemisphere in right-handed animals is most proficient at 247 processes that predict the effects of body and environmental dynamics, whereas left-248 handed animals relying on the right hemisphere are most proficient at object manipulation. 249 Futhermore, zoo-housed gorillas (Gorilla gorilla gorilla) and chimpanzees (Pan troglodytes) 250 display varied hand use bias when engaging with animate and inanimate objects suggesting 251 that object characteristics effect how the right and left hemisphere process manual actions 252 (Foster, Quaresmini, Leavens, Spiezip & Vallortigara, 2012; Forrester, Quaresmini, Leavens & 253 Vallortigara, 2011).

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The right or left hand dominance in the slow loris venom pose at the included rescue centres and in the wild varied from one slow loris to the next, showing no group-level preference. Despite our insignificant findings, we did observe right-hand dominated clasping in 64% of the slow lorises compared to 36% of the slow loris using a left hand dominated clasp. We suggest that this variation may be linked to the strong I-V grasp known to slow loris species (Gebo, 1987). The I-V grasp relies heavily on the thumb, which Morino, 261 Uchikoshi, Bercovitch, Hopkins, & Matsuzawa (2017) suggested may motivate a shift in 262 hemispheric involvement. Grips using the thumb in other primates including humans are 263 typically associated with right hand use (Christel, 1994; Hopkins, Cantalupo, Wesley, 264 Hostetter, & Pilcher, 2002; Hopkins & Russell 2004; Meguerditchian et al., 2015). In human 265 studies of arm folding and hand clasping, there was no evidence of consistent lateral 266 preferences that could be associated with handedness (Reiss & Reiss, 1998), noting that 267 bilateral preference has a weak connection to hemispheric lateralization. There is another 268 plausible factor, which may influence the left or right hand dominated grasp during the slow 269 loris venom pose. This posture serves the function of delivering brachial oil to the mouth, to 270 enable a venomous bite (Nekaris et al., 2013). Using either the right or left hand to grasp the 271 other wrist could be linked to the amount of brachial oil present on the right or left brachial 272 gland. To further discuss this theory, we would need to incorporate data on brachial oil 273 production at each instance of observing the venom pose.

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275 Hand clasping in non-human primates is very rarely reported in publications, outside of a 276 posture used by chimpanzees. McGrew and Tutin (1978) described this pattern of behaviour 277 as the grooming hand-clasp in the chimpanzees of K-group in the Mahale Mountains of 278 western Tanzania. This behaviour was absent in other chimpanzee populations, nearby and 279 in other countries (McGrew, Marchant, Nakamura, & Nishida, 2001). The presence or 280 absence of hand-clasp grooming in chimpanzee groups is related to cultural differences 281 between various populations (McGrew, Marchant, Nakamura, & Nishida, 2001). In humans 282 hand-clasping shows a lateral preference but there appears to be an east to west variation. 283 Indeed, left hand clasping (the thumb of the left hand resting on top of the thumb of the 284 right hand) is more dominant in populations near the Greenwich Meridian, and decreases 285 east of the Meridian, with the lowest level of left hand clasping in India and Australasia 286 (McManus & Mascie-Taylor, 1979; Reiss, 1999). This cultural influence suggests that 287 although hand-clasping shows lateral preference similar to manual tasks it has a weaker 288 connection to brain hemispheric lateralization (Critchley, 1972; Reiss, 1999; Reiss M., Reiss 289 G., & Freye, 1998). In this study we included three slow loris species in varying conditions. 290 The lack of an identifiable preference supports what is seen in humans, that unlike other 291 manual tasks this bilateral position displays less of a universal hand preference.

293 Our results in the unimanual task in captive lorises suggest a group-level bias. At the 294 individual-level one of six individuals had a negative HI, representing a left hand bias, the 295 other three that displayed a significant preference were right handed. These results refer 296 back to Sanford and Ward's (1986) suggestion that posture has a significant influence in 297 manual lateralization. As captive slow loris species generally maintain a sitting posture and 298 did so throughout testing, our findings are congruent with findings in strepsirrhines (Sanford 299 et al., 1984; Ward, Milliken, & Stafford, 1993), monkeys (Fagot & Vanclair, 1991; King & 300 Landau, 1993; Roney & King, 1993), and apes (Hopkins, 1996). Similar to the bilateral 301 posture, the simple unimanual hand reach recorded in the captive slow lorises is a poor 302 indicator of hemispheric specialization, as seen in other quadrupeds (Vauclair et al., 2005). 303 Merguerditchian and colleagues (2015) concluded that any hand preferences seen in this 304 task are likely due to situational and postural conditions. Our observations support this 305 assertion as individual slow lorises did not consistently rotate their bodies to use a specific 306 hand, but instead often used the hand closest to the presented food dish, which varied 307 based on where the individual was at the start of the testing session.

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309 In the Javan slow loris we found a group-level right-hand bias in the unimanual grasping in 310 wild individuals. This right-hand preference acts as a counter point to studies that report a 311 higher right-hand bias for nongrasping actions (Cochet & Vauclair, 2010; Esseily, Nadel, & 312 Fagard, 2010; Hopkins et al., 2005). If as suggested by Molesti et al. (2016) that precise and 313 complex manipulative activities may be selective pressures for the evolution of handedness 314 in the primate lineage, it is increasingly important for researchers exploring questions of 315 laterality to consider strepsirrhines, who like most haplorhines, engage in precise and 316 manipulative activities. In particular, Javan slow lorises observed in the wild used a precision 317 grip to grasp and reel in thin braches to access the flowers located on the end, or to grab 318 insects quickly (Moore, 2012). Given that precision and the visual demand of a motor action 319 are hallmark traits of task complexity (Fagot & Vauclair, 1991; Meunier & Vauclair, 2007), 320 the spontaneous unimanual grasping observed in free-ranging slow lorises could explain the 321 lateralization seen at the individual- and group-level.

322

We found a right-hand bias, whereas prior studies of lemurs and galagos show a left-handed bias (Leliveld, Scheumann, & Zimmermann, 2008; Lhota, Junek, & Bartoš, 2009; Milliken, 325 Forsythe, & Ward, 1989; Rigamonti, Spiezio, Poli, & Fazio, 2005; Schnoell et al., 2014; Ward, 326 Milliken, Dodson, Stafford, & Wallace, 1990). Hopkins et al. (2006) noted the impact of 327 sample size especially in comparative studies, thus the reported findings may change when 328 we analyse a larger dataset. Furthermore, it has been reported that right-handedness is 329 more common among terrestrial compared to arboreal non-human primate species, given 330 that they do not need their hands to support their posture (Hopkins et al., 2011; MacNeilage 331 et al., 1987; Meguerditchian et al., 2013). Following this justification, the slow loris may 332 deviate from other arboreal animals, due to their strong reliance on their hindlimbs to 333 maintain their posture. They regularly use both hands to grasp insects as they stretch 334 between discontinuous substrates using only their core and hindlimbs to support their 335 position (Poindexter & Nekaris, 2017).

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337 In this study we included both a bilateral posture and unimanual tasks, but to create a truly 338 comprehensive picture of *Nycticebus* laterality, we should complete further research 339 including a more complex bimanual task. Bimanual tasks require a higher level of fine motor 340 skill and manipulation, thus they are believed to have a higher likelihood to induce hand 341 preferences at the group-level (Colell, Segarra, & Sabater-Pi, 1995). In conclusion, results of 342 this study revealed a group-level right hand preference in the Javan slow loris during 343 observed unimanual grasping in the wild, but not in the bilateral venom pose or the 344 unimanual reach observed in captivity. These findings suggest that lateralization can be 345 elicited in unimanual tasks depending on the level of complexity needed to complete the 346 task. Lastly, our findings support the need to further consider strepsirrhines in the wild and 347 during more complex tasks as these results follow those in another strepsirrhine, the ring-348 tailed lemur (Lemur catta) (Ragaiolli, Spiezio, & Vallortigara, 2016a). The presence of right-349 handedness in this species and in these conditions highlights the importance of re-350 evaluating the evolution of hand preference in strepsirrhines.

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Figure 1. Nycticebus venom pose.

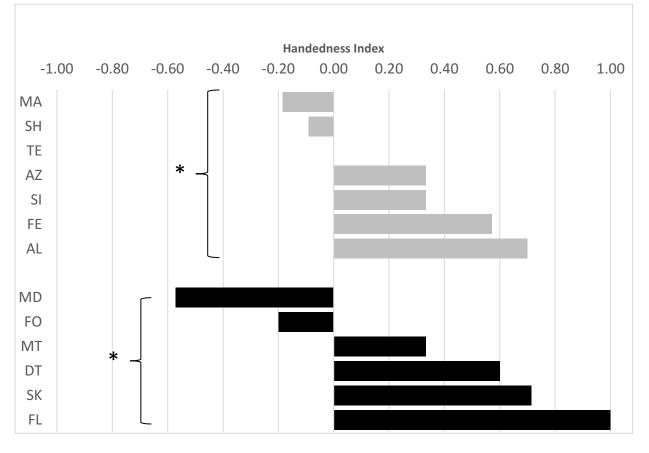
Figure 2. Wild Javan slow loris (*Nycticebus javanicus*) in the process of grasping a flower in terminal branches of a tree in Cipaganti, West Java, Indonesia.





637 Figure 3. The bilateral venom pose in two Javan slow lorises (*Nycticebus javanicus*), right-638 handed grasp (left) and the left-handed grasp (right).

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640 641

Figure 4. HI value for wild grasping (grey) and captive reach (black) observations in slow lorises. Positive values represent a right hand preference and a negative value represents a left hand preference. The (*) denotes a significant difference between the right and left hand use in the group.

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647

649 Table 1. Details about the sample size and location of the photographed slow lorises.

650

050										
	NYCTICEB	NYCTICEBUS SPECIES		LOO	CATION	IN INDO	NESIA			
	SUMATRA	SUMATRAN JAVAN			20 Cikananga Conservation Breeding Centre (CCBC), Sukabumi, Java					
	JAVAN				Little Fireface Project Field site (LFP), Garut, Java					
	JAVAN	9	Inte	International Animal Rescue (IAR), Bogor, Java						
	GREAT		7	Sch	Schmutzer Primate Center (SPC), Jakarta, Java					
51										
52										
53										
54	Table 2.	Handedne	ss of	Unim	anual	reach a	and grasp	oing in two	species of slow loris	
55	(Nycticebus javanicus and N. coucang).									
56										
57		651/	••							
		SEX	Ν	RH	LH	HI	ASB-HI	P-VALUE	HAND	
									PREFERENCE	
	AL	M	20	17	3	0.70	0.70	0.003	R	
	AZ	M	6	4	2	0.33	0.33	0.688	A	
	FE	M	28	22	6	0.57	0.57	0.005	R	
	MA	F	27	11	16	-0.19	0.18	0.556	А	
	SH	F	11	5	6	-0.09	0.09	1	А	
	SI	F	6	4	2	0.33	0.33	0.688	А	
	TE	F	16	8	8	0.00	0.00	1	A	
		•	10	Ũ	Ū	0.00	0.00	-		
	DT	F	15	12	3	0.60	0.60	0.035	R	
	FO	F	15	6	9		0.80	0.607		
						-0.20		0.007	A	
	FL	F	15	15	0	1.00	1.00	-	R	
	MD	F	28	6	22	-0.57	0.57	0.005	L	
	SK	M	21	18	3	0.71	0.71	-	R	

A, ambivalent hand preference index; HI, handedness index; ABS-HI, LH, left hand reach or

0.33

0.33

0.238

А

659 grasp; RH, right hand reach or grasp; L, left hand dominance during task; R, right hand660 dominance during task

6

661

MT

Μ

18