# A Nonparametric Solution for Finding the Optimum Useful Life of Equipment 

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A NONPARAMETRIC SOLUTION FOR FINDING THE OPTIMUM USEFUL LIFE OF ERUIPMENT by

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A report submitted in partial fulfillment of the requirements for the degree
of
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## CHAPTER I

## INTRODUCTION

It is often the case that equipment used by industry must be replaced with new equipment from time to time either because frequent malfunctions make it too costly to repair, or because the equipment has simply worn out. The new equipment often has the nature of either malfunctioning soon after installation due to manufacturing defects, or functioning for an extended period of time because it is free of these defects. For this reason, equipment is often given a preliminary running called the burn-in which gives no useful output but merely tests for manufacturing defects. Also, after a given amount of time, equipment is often replaced so as to avoid the added cost of a breakdown while under use. The term useful life is here used to denote the time period starting after burn-in time is reached and ending when replacement time is reached (Shooman, 1968).

The amount of burn-in and/or replacement times can be controlled to minimize cost per unit of operating time or to maximize reliability for some specified operating time. Whether to minimize cost or to maximize reliability is dependent upon the ultimate goal of the equipment user. An example of a minimum cost goal would be that of a company manufacturing a commodity whose production line
machinery must be replaced. This company would want to minimize their costs of production rather than maximize the reliability, because they are primarily interested in making a profit rather than insuring against production stops. On the other hand when the United States sends a man to the moon, they are not so much interested in minimizing costs as they are in maximizing the reliability of their equipment.

Given the various operating costs and previous operating data, this study proposes to develop equations and computer programs which could be used to determine the burn-in and/or replacement times for minimizing cost or maximizing reliability of equipment. The equations will be developed to include either burn-in time, replacement time or both.

## CHAPTER II

FEASIBILITY OF BURN-IN AND/OR REPLACEMENT TIMES

## Minimizing Cost

The total cost of operation of equipment can be considered to be composed of several different and contributing costs. There may be any number of these different costs but for practical purposes this study will consider six costs which will be either fixed or linear over time. Later, these six costs could easily be expanded to any number with small changes in the main computer programs. The costs will be as follows:

Cost number 1 - Fixed cost of purchase
Cost number 2 - Fixed cost of installation
Cost number 3 - Cost of operation per unit time
Cost number 4 - Fixed cost of burn-in installation
Cost number 5 - Cost of burn-in per unit time
Cost number 6 - Fixed cost of breakdown
The hazard function can be defined as the conditional probability
that an equipment will fail in a unit time interval after $t$, given that it was working at time $t$ (Sandler, 1963). The hazard function can therefore be given by the following equation:

$$
\text { Hazard }=f(t) /(1-F(t))
$$

When considering the performance of large numbers of equipment it is often the case that when the hazard function is graphed, one of three general patterns emerges. These general forms occur because there is either large amounts of early failures or large amounts of late failures or both large amounts of early and late failures. Illustrations of these situations follow:


Figure 1. Hazard function - early failure.

Hazard


Figure 2. Hazard function - late failure.


Figure 3. Combined hazard function

If a burn-in time was imposed on a set of data which had a hazard function similar to Figure 1, it would eliminate many of the costs incurred by having to spend time and effort installing equipment which would run for only a short time. These costs would have to be paid if a burn-in time was not imposed.

If a replacement time was imposed on a set of data which had a hazard function similar to Figure 2 it would eliminate many of the breakdown costs incurred by having to suspend operations during the replacement, whereas, a replacement could have been made at a more opportune time.

A burn-in and replacement time could be imposed on a set of data which had a hazard function similar to Figure 3, to avoid many installation and breakdown costs.

By choosing an appropriate burn-in and/or replacement time the total costs can ther efore be minimized.

## Maximizing Reliability

Reliability can be defined as the probability of performing successfully for a specified time. Thus, as the probability of performing successfully increases, the reliability increases. By imposing a burn-in time to data with a hazard function similar to Figure 1, the probability of performing successfully increases as the burn-in time increases until the last data point is reached, since the hazard function is asymptotic to the time axis. This leads to a meaningless burn-in time solution for maximizing the reliability with data similar to Figure 1 . However, by imposing a burn-in time to data with a hazard function similar to Figure 3, the probability of performing successfully increases as the burn-in time increases up to a point and then begins to decrease, since the hazard function is not asymptotic to the time axis. This leads to a meaningful burn-in time solution for maximizing the reliability with data similar to Figure 3. By choosing an appropriate burn-in time for a given time interval the reliability can be maximized.

## CHAPTER III

## OPTIMIZING USEFUL LIFE

## Nonparametric Solution

A statistic is a term used to describe a measure computed from the observations in a sample. In computing a statistic, it is not necessary to have a knowledge of any unknown population. The observations in a sample determine the statistic and therefore the statistic can be thought of as a function of the observations in a sample. The random variable defined by this functional relationship can be defined to be a statistic. If $\left(x_{1}, \ldots x_{n}\right)$ is a possible sample point, then the functional relationship

$$
y=t\left(x_{1}, \ldots x_{n}\right)
$$

transforms from the space that contains all the values of the sample points to the space that contains the values of the function. A probability distribution is induced in the space that contains the values of the function by this transformation and thus defines a random variable:

$$
Y=t\left(X_{1}, \ldots X_{n}\right)=t(X)
$$

It is often the case that creating order out of a mass of data requires that the observations be put in numerical order. The result is a vector of ordered observations, from the smallest to largest and is sometimes referred to as the order statistic.

For a given sample, there can be defined a sample distribution function. A "mass" of amount $1 / \mathrm{n}$ can be placed at each observed value. This mass distribution then has a distribution function of

$$
F_{n}(x)=1 / n \cdot(\text { number of observation } \leq x)
$$

This is the sample distribution function. It can be computed from the order statistic. It is known that the sample distribution function converges to the population distribution function with probability one, uniformly in x . Therefore, it is a natural estimate of the population distribution function.

The sample distribution function is mathematically the same as a probability distribution function for a discrete distribution as it has the same mathematical properties as this type of function.

Since the sample central moments can be shown to be expressible as polynomial functions of sample moments about zero, it can be shown that the sample central moments tend in probability to the corresponding population moments (Lindgren, 1968).

If the population distribution function is not known but a sample distribution function is, it can be assumed that the sample distribution
function will converge to the population distribution function as the sample size gets large. Therefore, for large sample sizes the population distribution function can be considered to be the sample distribution function and vise versa. This makes a nonparametric technique, for determining the minimum cost, possible. Since the sample distribution function is discrete this makes the burn-in and/or replacement times discrete because the time between data points need not be considered in finding the minimum cost. They need not be considered because, as can be seen in Figure 4, the discrete sample data gives a step function which, as previously stated, closely approximates the continuous population data's smooth curve function because of the large sample size. It can also be seen from Figure 4 that time values between data points of the step function give the same value for the number of breakdowns as the data point preceding the between data value. This of course, is what might be expected with a step function. Therefore, a burn-in or replacement time value between the discrete data points serves only to increase the burn-in or replacement time and their accompanying costs while not increasing the number of installation or replacement costs saved because the number of breakdowns have not increased. Since the number of data points is large but finite it is possible to compute the total cost of operation by using all the data points as burn-in and/or replacement times and choosing the times which minimize the cost.


Figure 4. Step function.

Calculating the cost for each appropriate burn-in and/or replacement time rather than finding the burn-in and/or replacement time which minimizes the cost by more direct means has the advantage of showing the relative size of the costs before it reaches its minimum value. In some cases it might be more advantageous to use a cost which is not quite minimal but has a burn-in and/or replacement time which is more compatable to the equipment users time schedule. For example, it may be more desirable to burn-in for eight hours rather than for eight and one half hours, even though the cost might not quite be minimal because the burn-in could be done in one eight hour shift rather than be carried over into another shift of workers and possibly forgotten about.

## Minimizing Cost

In a situation such as depicted by Figure 1, 2, or 3, where some burn-in and/or replacement time is going to be imposed, it is often not immediately evident what burn-in and/or replacement time will minimize the cost. One way of deciding the time or times to choose is to calculate the cost for each appropriate burn-in and/or replacement time in a large but finite sample which converges to the population and choose that particular time or times for which the cost is minimized.

Burn-in only
When it seems appropriate to impose only a burn-in time, costs one through five (as stated in Chapter II) may be considered. First, there is the cost of purchase. Assuming 100 pieces of equipment, this component of the total cost is 100 times the cost of purchase. Second, there is the cost of installation. There are 100 pieces of equipment but these will not all be installed due to malfunctions during the burn-in period. Therefore, there will be the number of equipment installed times the cost of installation for this component of total cost. The third cost consists of the cost of operation per unit time. This component of the total cost will be the total operation time, times the cost of operation per unit time. Fourth is the fixed cost of burn-in. This will apply to all the equipment, therefore, this component of the cost will be the
number of equipment times the fixed cost of burn-in. Fifth is the cost per unit time of burn-in. This cost may be thought of as including within it, the cost per unit time of not making the profit which would be made if the equipment was being used instead of being burned-in.

This component of the cost will be the total of the individual burn-in times, times the cost of burn-in per unit time. By imposing a burn-in time, some installation and breakdown costs can be saved. Where an installation cost is saved there will always be a cost of breakdown saved and vise versa, since, if equipment is not installed it can not breakdown. Therefore, in this part of the study breakdown cost as such is not considered seperately but is assumed to be includible in the installation cost.

For convenience the following notation will be used.

$$
\mathrm{bt}=\text { the burn-in time }
$$

$n_{1}(b t)=$ the number of data points less than or equal to the burn-in time
$n_{2}=$ the number of data points
$I_{1}=$ the set of data points $X_{(i)}$ such that $i=\left[1,2, \ldots n_{1}(b t)\right]$ so that for $\mathrm{i} \in \mathrm{I}_{1} \mathrm{X}_{(\mathrm{i})} \leq \mathrm{bt}$
$I_{2}=$ the set of data points $X_{(i)}$ such that $i=\left[n_{1}(b t)+1, \ldots n_{2}\right]$
so that for $\mathrm{i} \in \mathrm{I}_{2} \mathrm{X}_{(\mathrm{i})}>$ bt
$E=$ total cost per unit time

The total of the contributing costs can be found by totaling the purchase cost times the number of data points, the installation cost times the total of the number of data points minus the number that failed during burn-in, the operation cost times the sum of the time of the data greater than the burn-in time, the fixed cost of burn-in times the number of data points, and the cost per unit time of burn-in times the total of all the burn-in time of those that failed and those that did not.

The total cost per unit time will be the total of the contributing costs divided by the total operating time and is given in the following equation:
$E=C_{1}\left(n_{2}\right)+C_{2}\left(n_{2}-n_{i}(b t)+C_{3}\left(\Sigma X_{(i)}\right)+C_{4}\left(n_{2}\right)+C_{5}\left(\Sigma X_{(i)}+b t\left(n_{2}-n_{1}(b t)\right)\right.\right.$ $\mathrm{i} \in \mathrm{I}_{2}$ $\mathrm{i} \in \mathrm{I}_{1}$

$$
\begin{gathered}
\Sigma X_{(i)} \\
i \in I_{2}
\end{gathered}
$$

Without a burn-in time cost number four and cost number five would be equal to zero and the total operation time would increase but the number of equipment installed would also be increased, presumably offsetting any gains acquired by not using a burn-in time.

## Replacement time only

When it seems appropriate to use only a replacement time, costs one, two, three and six (as stated in Chapter II) may be considered
to apply. The first three components of the total costs, namely, costs one, two and three can be computed as in the case of burn-in time only. By imposing a replacement time some of the breakdown costs can be avoided because equipment that reach the replacement time successfully do not induce breakdown costs. The breakdown component of the total cost will be computed by multiplying the number of replacements needed times the cost of breakdown.

For convenience the following notation will be used.
$n_{1}(r t)=$ the number of data points less than or equal to the replacement time.
$n_{2}=$ the number of data points
$I_{1}=$ the set of data points $X_{(i)}$ such that $i=\left[1,2, \ldots n_{1}(r t)\right]$
so that for $\mathrm{i} \in \mathrm{I}_{1} \mathrm{X}_{(\mathrm{i})} \leq r t$
$I_{2}=$ the set of data points $X_{(i)}$ such that $i=\left[n_{1}(r t)+1, \ldots n_{2}\right]$
so that for $i \in I_{2} X_{(i)}>r t$
$E=$ total cost per unit time
The total of the contributing costs can be found by totaling the purchase cost times the number of data points, the installation cost times the number of data points, the operation costs times the total of the operating time, and the breakdown cost times the number of data less than the replacement time.

The total cost per unit time will be the total of the contributing
costs divided by the total operating time and is given in the following equation:

$$
\frac{E=C_{1}\left(n_{2}\right)+C_{2}\left(n_{2}\right)+C_{3}\left(\Sigma X_{(i)}\right)+C_{6}\left(n_{1}(r t)\right)}{\sum X_{(i)}}
$$

Without a replacement time the total operating time would be increased but the increased number of breakdown costs would presumably offset any gains acquired by not using a replacement time.

## Burn-in and replacement time

When it seems appropriate to use burn-in and replacement times, costs one through six may be considered.

For convenience the following notation will be used.

$$
\begin{aligned}
& \mathrm{bt}=\text { burn }- \text { in time } \\
& \mathrm{rt}=\text { replacement time }
\end{aligned}
$$

$n_{1}(b t)=$ the number of data points less than or equal to burn-in time

$$
\begin{aligned}
{ }^{n}{ }_{2}(r t)= & \text { the number of data points less than or equal to the } \\
& \text { replacement time }
\end{aligned}
$$

$$
n_{3}=\text { the number of data points }
$$

$$
I_{1}=\text { the set of data points } X_{(i)} \text { such that } i=\left[1,2, \ldots n_{1}(b t)\right]
$$

so that for $\mathrm{i} \in \mathrm{I}_{1} \mathrm{X}_{(\mathrm{i})}<\mathrm{bt}$

$$
\begin{aligned}
I_{2}= & \text { the set of data points } X_{(i)} \text { such that } i=\left[n_{1}(b t)+1, \ldots n_{2}(r t)\right] \\
& \text { so that for } i \in I_{2} \quad X_{(i)} \leq r t \\
I_{3}= & \text { the set of data points } X_{(i)} \text { such that } i=\left[n_{2}(r t)+1, \ldots n_{3}\right] \\
& \text { so that for } i \in I_{3} X_{(i)}>r t \\
E= & \text { total cost per unit time }
\end{aligned}
$$

The total of the contributing costs can be found by totaling the cost of purchase times the number of points greater than the burn-in time, the cost of installation times the number of data points greater than the burn-in time, the operation cost times the sum of the time between burn-in and replacement times, the fixed cost of burn-in times the number of data points, the cost per unit time of burn-in times the total of the times of those that failed before burn-in time and those that did not, and the breakdown cost times the number of data points that fall between the burn-in time and the replacement times.

The total cost per unit time will be the total of the contributing costs divided by the total operating time and is given by the following equation:

$$
\frac{E=C_{1}\left(n_{3}\right)+C_{2}\left(n_{3}-n_{1}(b t)+C_{3}\left(\sum X_{(i)}\right)+C_{4}\left(n_{3}\right)+C_{5}\left(\Sigma X_{(i)}\right)+b t\left(n_{3}-n(b t)\right)+C_{6}\left(n_{2}(n t)_{-n_{1}}(b t)\right)\right.}{\sum X_{(i)}}
$$

## Maximizing Reliability

In a situation such as depicted by Figure 3 where some burnin time is going to be imposed it is often not immediately evident what burn-in time to use to maximize the reliability. One way of deciding the time to use is to calculate the reliability for each appropriate burn-in time noting that particular time for which the reliability is maximized.

Since the reliability can be considered to be the probability of performing successfully for a specified time, then it can be calculated by the following formula:

$$
\mathrm{R}=\frac{\mathrm{G}(\mathrm{bt})}{\mathrm{H}(\mathrm{bt})}
$$

Where $G(b t)=$ number of successes as a function of the burn-in time
$H(b t)=$ number of events as a function of the burn-in time
When the situation is such as depicted by Figure 3, imposing an appropriate burn-in time reduces the total number of events without reducing the number of successes, thus, increasing reliability. The total number of events (H) can be computed by counting the number of times until failure greater than the burn-in time. The number of successes (G) can be computed by counting the number of times until failure greater than the burn-in and the specified (mission) times combined.

## CHAPTER IV

DISCUSSION AND RESULTS

This study used the Weibull distribution to generate data. The Weibull distribution function is given by the following:

$$
\begin{equation*}
F(t)=1-\exp \left((-t / \theta)^{V}\right) \tag{1}
\end{equation*}
$$

where $t$ is a time to failure and $\theta$ and $V$ are parameters of the distribution. A $t$ with a Weibull distribution can be found from the following equation:

$$
\begin{equation*}
t=\theta(-\ln x)^{1 / V} \tag{2}
\end{equation*}
$$

when x has a uniform distribution. The mean of the Weibull distribution is given by the following equation:

$$
\begin{equation*}
\text { Mean }=\frac{\theta}{\mathrm{V}}\left\lceil\left(\frac{1}{\mathrm{~V}}\right)\right. \tag{3}
\end{equation*}
$$

The hazard function is given by the following:

$$
H(t)=-\frac{R^{\prime}(t)}{R(t)}=\frac{V t}{V^{V}}
$$

where $R(t)=(1-F(t))$. When $V<1$ a curve similar to Figure 5 occurs.


Figure 5. Hazard function $V<1$

When $V>1$ a curve similar to Figure 6 occurs.


Figure 6. Hazard function $V>1$

The curves of Figures 5 and 6 can be combined with an additional chance failure source for which the hazard function is constant, to form
a combined hazard function by use of the following equation:

$$
\begin{equation*}
H(t)=\frac{V_{1} t^{V_{1}^{-1}}}{\theta_{1}}+\frac{1}{\theta_{1}}+\frac{V_{2}{ }^{V_{2}^{-1}}}{\theta_{2}} \tag{5}
\end{equation*}
$$

The $\frac{1}{\theta_{3}}$ pertains to the chance failure. The central part of the curve represents a constant hazard function where chance failures are predominant. This represents the exponential distribution of failures which is a special case of the Weibull with $\mathrm{V}=1$. This is illustrated in Figure 7 (Shooman, 1968).


Figure 7. Combined hazard function.

To get time until failure data with a hazard function similar to Figure 5, a mean of 25 and $V$ equal to 0.5 was selected. This makes $\theta$ approximately equal to 12 from equation 3. The t's can then be found by letting x be uniform random numbers between zero and one and solving equation two. To get time until failure data with a hazard
function similar to Figure 6, again a mean of 25 , but now a $V$ equal to 5. was selected. This makes $\theta$ approximately equal to 125 from equation three. Again the t's can be found by letting $x$ be uniform random numbers between zero and one and solving equation two. To get time until failure data with a hazard function similar to Figure 7, $\theta_{1}, \theta_{2}, \theta_{3}$, $V_{1}, V_{2}$, and $V_{3}$ were assigned the values of $12,5,100,0.5,5$ and 1 , respectively. Now, however, the minimum value of $t$ was choosen from equation two for each $\theta, V$ set because a failure would occur at the shorter time.

Computer programs for generating the data as well as arranging it in assending ordex can be found in Appendix A.

Appendix B contains four computer programs which can be used for minimizing costs using only a burn-in time, only a replacement time, both a burn-in and replacement time or for maximizing reliability using a burn-in time, in that order. The first two programs compute all the total costs per unit of time as outlined in Chapter III using each data point for a burn-in or replacement time. The third program does not use all possible combinations of burn-in and replacement time but rather uses combinations of every $n^{\text {th }}$ burn-in time with every $n^{\text {th }}$ replacement time where n is determined by the user, to get an initial idea of where the best combination is. The user then looks at the costs as displayed in Figure 8, for the combinations chosen and decides in what general area the minimum lies. Then, after running the program again
in this smaller area and with smaller jumps, he can narrow down the search area even more. This itervative procedure can be continued, using smaller and smaller search areas and jumps until the minimum is reached. This program has the advantage of showing the general trend of how much the cost is influenced by prescribed changes in burn-in and replacement times and may aid in choosing a time which may be better suited to a particular situation even though it does not quite minimize the cost. Other more sophisticated programing techniques such as the search methods which keep to rising paths or steepest gradients depend on the assumption that the function is unimodal as described by Wilde (1964). The cost function as seen in Figure 8 can be bimodal (doubly peaked). When the assumption of unimodel is not met, success can not be sure with such methods because the peak that is reached is dependent upon where the search starts (Wilde, 1964).

Figure 8 shows the calculated costs for combinations of every tenth burn-in time with every tenth replacement time where the burn-in time is less than the replacement time. The component costs one through six were $10,600,4,1,0.25,250$.

For example, the cell marked with "A" represents the total cost per unit time for the 20 th ordered data point as the burn-in time and the 80 th ordered data point as the replacement time.

The cost at point B is surrounded by combinations of times which give greater values for the cost. A similar situation exists at
point A, thus showing that the cost function can be bimodal as described by Wilde (1964).

Data Point Used for Burn-in Time


Figure 8. Costs for 100 data in jumps of ten

It seems that the program used in this study and any other program which does not compute the cost for all the possible combinations of burn-in and replacement times, runs the risk of missing the optimum combination because the cost may have several local minimums before reaching the true minimum. Checking all possible combinations may be the only sure solution for finding the optimum combination, but this may prove too costly to the user. With the program given here, the user can
come as close to checking all possible combinations as his resources allow by choosing the size of the "jumps".

The fourth program computes the reliability by using each data point as a burn-in time, as outlined in Chapter III, for any specified time interval. The program prints out all the reliabilities so that a burn-in time which does not quite maximize the reliability may be chosen if desired.

When using the first program, the user must read in the values for the component costs one, two, three, four and five, in addition to the number of data points, all on one card. The data must be read in one per card. Formats for reading in can be found from the comment card in the program and can be changed as needed. The program will then compute all the costs per unit time using each of the data points as a burn-in time and note the particular time for which the cost was minimized and the minimum cost. If the user wants to delete any of the component costs he can put a zero in its place when reading it in. If he wants to add a cost, then following the comment cards in the program should point the way.

When using the second program, the user must read in the values for the component costs one, two, three and six, in addition to the number of data points, all on one card. The data must be read in one per card. Formats for reading in can be found from the comment cards in the program and can be changed as needed. The program
will then compute all the costs per unit time using each of the data points as a replacement time and note the particular time for which the cost was minimized and the minimum cost. If the user wants to delete any of the component costs he can put a zero in its place when reading it in. If he wants to add a cost, then following the comment cards in the program should point the way.

When using the third program, the user must read in the values for the component costs one, two, three, four, five and six, in addition to the number of data points, the size of the jumps and the starting and ending points in the data for the search, all on one card. The data must be read in one per card. Formats for reading in can be found from the comment cards in the program and can be changed as needed. If the user wants to delete any of the component costs he can put a zero in its place when reading it in. If he wants to add a cost, then following the comment cards in the program should point the way.

When using the fourth program the user must specify on one card the mission time and the total number of data points. The data itself is read in one per card. Formats for reading in can be found from the comment cards in the program and can be changed as needed. The program will then compute all the reliabilities using each of the data points as a burn-in time and note the particular time for which the reliability was maximized and the maximum reliability.

In testing the programs, component costs had to be chosen
which would give practical results. These costs have the property that if one or more of them is too large or too small it may not be advantageous to use either a burn-in or a replacement time. The values of the costs as, illustrated in Table 1 were chosen to give proctical results. Because other costs may produce the situation where a burn-in and/or replacement time was not advantageous, the programs first compute the total cost using no burn-in or replacement time.

Table 1. Costs used for each of the three minimum costs programs

|  | Program | Program | Program |
| :--- | :---: | :---: | :---: |
| Cost 1--cost of purchase | 200 | 2 | 3 |
| Cost 2--cost of installation | 150 | 150 | 10 |
| Cost 3--cost of operation | 400 | 400 | 600 |
| Cost 4--cost of burn-in |  |  |  |
| (fixed) | 1 | -- | 400 |
| Cost 5--cost of burn-in |  |  |  |
| (per unit time) | 0.25 | -- | 1 |
| Cost 6--cost of breakdown | -- | 50 | 0.25 |

The mission time for testing the reliability program was 4.1872667 . Each of the programs were run using 100 and 200 data points. The burn-in and/or replacement time can perhaps be illustrated best by showing their relative position in the data which was arranged from the smallest to the largest. This is illustrated in Table 2.

Table 2. Results using 100 and 200 data points

|  | Relative position <br> in 100 data points | Relative position in <br> 200 data points |
| :--- | :---: | :---: |
| Minimum cost <br> Burn-in only program | 28 th | 73 th |
| Minimum cost <br> Replacement only <br> program |  |  |
| Minimum cost <br> Burn-in \& replacement <br> program | 22nd, 83 rd |  |
| Maximum reliability <br> Burn-in program | 8 th | 179 th |

The relative size of each of the component costs taken together determine the optimum burn-in and/or replacement time. When the size of one of the component costs changes and the others remain constant, the burn-in and/or replacement time may or may not change. If they change, they change as illustrated in Table 3.

Each of the four programs were tested for errors by using ten data points except the third program which was tested by using thirty data points. Hand calculations were found to produce the same results.

In conclusion it was found that the size of the component costs relative to each other, determine what the optimum burn-in and/or replacement times should be when minimizing costs and that no burnin and/or replacement time should be used when some of the component

Table 3. Results found when the component costs were changed

| Component cost increased | Burn-in time | Replacement time |
| :---: | :---: | :---: |
| C\#1 cost of purchase | decreased | increased |
| C\#2 cost of installation | increased | increased |
| C\#3 cost of operation | no effect | no effect |
| C\#4 cost of burn-in <br> (fixed) | decreased | increased |
| C\#5 cost of burn-in (per unit time) | decreased | increased |
| C\#6 cost of breakdown | increased | decreased |
| Component cost decreased | Burn-in time | Replacement time |
| C \#1 | increased | decreased |
| C \# 2 | decreased | decreased |
| C \#3 | no effect | no effect |
| C \# 4 | increased | decreased |
| C \# 5 | increased | decreased |
| C \#6 | decreased | increased |

costs have a relative size that is much greater or smaller than the others.

As can be seen in Table 3, the operation cost need not be considered in finding the optimum useful life.

With the maximum reliability program it was found that as the mission time decreased the optimum burn-in time decreased, and that a burn-in time only produced practical results when the hazard function took the form of Figure 3.

Shooman, Martin L. 1968. Probabilistic Reliability an Engineering Approach. McGraw-Hill, In., New York.

Sandler, Gerald H. 1963. System Reliability Engineering. PrenticeHall, Inc., Englewood Cliffs, New Jersey.

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Appendix A

DIMENSION D（100）ST（100）
S（G）TH＊X）sTH＊（（ABS（＊ALOG（X）））由由（1／G））
C18．5
THI 12.
4ARGES139921
DO 101 【 1.100
XeRANDOM（LARG）
DI SG6IOTMIOX）

101 CONTINUE

DIMENSION D（100）T T 1100 ）

Q205．
IM2 125
6 A RG： 5139921
$001015 \pm 1.100$
$X$ ARANDOM（LARG）
D2 \＆（G2，iH2，X）
D（I）$=D 2$
LOI CQNTINUE

DIMENSION D（100）T $(100)$

61＝5
Q2㤟5。
G3：1．
TMI＝120
TH2 s 5＊
TH3E 200 。
LARG＝5139921
DO 101 I电 1 100
$X=R A N D O M(L A R G)$
DIES（GIEIHIEX）
X＊RANDOM（LARO）
D2笽（G2：TH2，X）
X＝AANDOM（LARG）
D3es（G3，fM3x）
IF（D1．GT．D2）GOTO 5
D（I）© D ！
$60 \quad 10100$
5 D（I）＝D2
100 CONTINUE
IF（D3．GT．D（I））GOTO 101
D（1）＝D3
101 CONTINUE

```
    00 500 J.2.100
    M&D(J)
    H*-5
    DO 600 l=1.J
    IF(R.GT.1:) GO TO 600
    If(X.LT,D(I)) GO 10 700
    GO TO 600
700 kejol
    R=2.
    OO 4 IIaI%K
    4 D(J+I-Id)=0(J=!る)
        D(b)ex
800 CONTINUE
500 CONTINUE
```

```
    DIMENSION T(1000)
    THIS PROGRAM COMPUTES THE BURNOIN TIME WHICH MINIMIZES COST
    THE NEXT GARD READS IN TME GOSTS AND NUMRER OF DATAOND
    COLUMNS & S ARE GOST NUMBER I
    COLUMNS 6-10 ARE COST NUMBER 2
    COLUMNS 11*15 ARE COST NUMBEA 3
    COLUMNS 16*20 ARE COST NUMBER 
    COLUMNS 21-25 ARE COST NUMEER 5
    CILUMNS 26*29 ARE THE NUMEER OF DATA
        READ(5,10)C1,C2,C3,C4,C5,ND
    10 FORMAT(5F5.2.14)
        TME NEXT FOUR CARDS READ IN THE DATA
        OO 15 I= IOND
        READ(5114) T(1)
    14 FORMAT(E15.8)
    15 CONTINUE
        CSUM IS TME TOTAL OF AGK THE DATA ISMES
        CO IS THE COST WITMOUT A GURN=IN TIME
        CSUMmO.
        00 97 I#IAND
        CSUMMCSUM*T&I)
    97 CDNTINUE
        XDEND
        WRITE60*98)
        C9*(N0*CI&NO*C2&CSUm甶C 3)/CSUM
        WRITE(6,90)C9
    98 FORMAT(' ', WITH NO BURN IN PIME')
    99 FGRMAT(IXOFI5.4)
        NNDEND-1
    3O ORMATS' 'GOURN=IN TIME COST')
        WRITE (0,30)
        SMIN溉1000000.
        00 25 Im 1 NNO
        AT IS THE BURN*IN TIME
        XSUM IS THE NUMBER OF DATA POINTS GREATER THAN THE BURN IN TIME
        XOSUM IS TME SUM OF IHE TIME GREATER THAN THE BURNGIN TIME
        SUM IS THE NUMEER OF DATA POINTS LESS THAN THE BURN=IN TIME
        XESUM IS THE SUM OF IHE TIME GESS THAN THE BURN\triangleIN IIME
        XD IS THE NUMEER OF DATA POINTS
        SUM=0.
        XSUM権O.
        MOSUMam0.
        0T**(I)
        00 }35\mathrm{ Jx&NNO
        IF(T(d).GT,BT)GO TO 45
        xSUMEXSUM*1.
        KOSUMaXOSUM+(TGJ)=BT)
        *0 T0 35
    45 SUM亚SUM*I(I)
    35 CONPINUE
```

XQSUMaSUM* (BT*XSUM)
KO = ND
C CG IS THE COST WITM A GURN IN TIME


W年ITE $(6,40)$ BT, 66
IF (CG.GT,SMIN) GO TO 1
$C$ SMIN IS THE MINIMUM COST OF ALL THE COMPUTED GOSTS SMINECG
SSMIN=T(I)
G SSMIN IS THE BURN IN TIME THAT CORRESPONDS TO THE MINIMUM GOST
1 CONTINUE
25 GONTINUE
WRITE (6,6)
6 FORMAT( ${ }^{\circ}$, 'OPTIMUM TIME MINIMUM COST')
WRITE 6,7 )SSMIN, SMIN

STOP
END
DIMENSION T（1000）
50 FORMAT（4F5．2．14）

```THE NEXT FOUR CARDS READ IN THE DATA
    00 55 I=1*ND
    READ(5,14) T(1)
    14 FIRMAT(E15.0.O)
    5S CONTINUE
    CSUM IS THE TOTAL OF ALG THE DATA TIMES
    CE IS THE COST WITHOUT M GURN*IN OR REPLAGEMENT TIME
    CSUM*O.
    DO 97 Im&NND
    CSUM*CSUM*T(I)
    OT CONTINUE
    XD=ND
    W\ITE(6*98)
    C94-6ND*CI&ND*G2+CSUM*C3+ND*C6)/CSUM
    W\mp@code{ITE(6.99)C9}
    Q8 FORMAT(' ',WIYM NO REPLACEMENT IIME')
    99 FORMAT(1X,F1S,4)
    70 FORMATG' REPLAGEMENT TIME COST'J
    WRITE(6,70)
    $NN湮1000000.
    NND*ND*1
    DO 65 I`1.NND
    RT IS TME REPLACEMENT TIME
    YXOSUM IS THE SUM DF THE TIME LESS THAN THE REPLACEMENT TIME OF
    OF THOSE DATA POINTS THAT AGE GREATER THAN THE REPLAGEMENT TIME
    YXSUM IS THE SUM OF THE TIME LESS THAN THE REPLACEMENT TIME OF
    TMOSE DATA POINTS THAT ARE LESS THAN THE REPLAGEMENT TIME
    YSUM IS IHE NUMBER OF DATA POINTS LESS THAN THE REPLACEMENT TIME
    YD IS THE NUMBER OF DATA POINTS
    RT潧(I)
    YKOSUM#O:
    YXSUM#O.
    VSUMm0.
    DO }75\mathrm{ JEIAND
    IF(T(N) LT,RT)GO TO &S
    YXOSU網YXOSUM&TGJJ由RT
    60 10 75
85 YXSUM=YXSUM&T(J)
    YSUM*YSUM*1*
75 CONTINUE
    YO#ND
```

```
C CT IS THE COST WITH A REPLAGEMENT TIME
            C7* (YD*C1*YD*C2*YSUM*C6*((RT)*(YD*YSUM)&YXSUM)* (3)/((RT)
        1-(YD=YSUM)&YXSUM)
    8O FORMAT(2X,E15,8,6X,F15,4)
        WRITE(6,8O)RT,C7
        IF(C7.GT.SMIN) GO TO I
C SMIN IS THE MINIMUM COST OF ALL THE COMPUTED COSTS
C
    SSMIN IS THE REPLACEMENT TYME TMAT CORRESPONDS TO
    SSMIN IS THE REPLAGEMENT TIME THAT GORRESPONDS TO THE MINIMUM COST
    SMINMC?
    SSMIN=T(I)
    1 CONTINUE
    6 5 \text { CONTINUE}
    WRITE(0,6)
    * FORMAT(" "OPTIMUM TIME MINImUM COST'%
    W⿵冂TE(O,T)SSMIN,SMIN
    7 FORMAT(1X,E15.8.F15.4)
        STOP
    END
```



```
00 125 LaloND
IF(T(L)OLT.BT)GO TO }13
MSUMEXSUM&&.
XOSUM=XOSUM*(T(L)*BT)
GO 10 }12
    135 SUMESUM+T(L)
    125 CONTINUE
    XBSUM=SUM*(BT由XSUM)
    DQ 145 MEIOND
    IF(T(M):LTORT)GO YO 155
    YXOSUM#YXOSUM&T(M)*RT
    G0 10 145
    155 YXSUMEYXSUM&T(M)
        YSUMBYSUM+1.
    145 GONTINUE
        XD=ND
C CY IS THE COST WITH A BURNOIN AND REPLACEMENT TIME
        C7&(6XD*C1)&(XSUM*C2)*(XD*C4)*6XBSUM*G5)&((YSUM*(XD=XSUM))*C6)*
```



```
        WRITE(6,120)BT,RT,C7
    120 FORMAT(3X,E15,8,E15,8,F15.4)
    IFSC7.LT.G8JGO TO 165
    GO PO 115
C GE IS THE FIRST APPROXIMATION OF THE MINIMUM GOST
C II IS THE FIRST APPROXIMATION OF THE GURN=IN TIME
    KK IS THE FIRST APPROXIMATION OF THE REPLACEMENT TIME
    1.5 68ac7
        |I|.|
        KK#に
    115 CONTINUE
    105 GONYINUE
        IIK=II-10
        IIKKEII+10
        WRITE(0,18)
    1B PGRMAT(' ', 'FIRST APPROX'J
        WRITE(6.1502T(11)OT(KK)OC8
    150 FORMAT(3X,E15.8.E15.8,F15.4)
    STQP
    -MD
```


## DIMENSIQN T(1000)

C THIS PROGRAM COMPUTES THE GURNOIN TIME WHICH MAXIMIZES THE C RELIABILITY
c
c
THE NEXT GARD READS IN THE MISSION TIME AND THE NUMEER OF DATA
COLUMNS I 15 ARE THE MISSION TIME
COLUMNS 16019 ARE PHE NUMBER OF DATA
READ(5.160)XMTAND
160 FORMATGE15.8. \% 4
THE NEXI FOUR CAROS REAO IN THE DATA

T(I) $\quad$ (1)
245 CONTINUE
RMIN $\begin{gathered} \\ \text { RO. }\end{gathered}$
WRITE(*) 180 )
1 BO FORMATG' 'MISSION TIME BURNEIN TIME RELIABILITY'J
NND』NDC1
DO 255 I 1 I. NND
C XSUM IS THE NUMBER OF DATA POINTS GREATER THAN THE BURNOIN AND
C MISSION TIMES COMBINED
XBSUM IS TME NUMBER OF DATA POINTS GREATER THAN TME BURN IN TIME
XTO IS THE BURN-IN TIME
XMT IS THE MISSION TIME
XT IS A OATA POINT
XSUM-O.
- $B S$ SUM 0.
XTO \# T (1)
XATEXTO\&XMT
DO $265 \mathrm{~J} \quad 1$ ND
$x T$ Tic)
If (XT,GT•XAT)GO TO 275
60 TO 285
275 XSUM \#xSUM\&i.
285 1F 6 XT.GTOXTOJGO 10295
0010265
205 XBSUM*XBSUM ${ }^{2}$ ©
265 CONTINUE
R=XSUM/XESUM
WRITE $(6.190) X M T, X T O, R$

IF (R.LT,RMIN) GO TO 255
C RMIN IS THE MAXIMUM RELIABILITY
C $X M I N$ IS THE CORRESPONDING BURN=IN TIME
RMIN:R
XMIN: XTO
255 CONTINUE
WRITE 6.16 I
WRITE(6,17) XMTAXMINORMIN
16 FORMATG OMISSION TIME BURN IN TIME BEST RELIABILITYIJ
17 FORMAT(3X, E15, B, E15, 8, F8.5)
STOP
E.ND

