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Quantifying the fine-scale behaviour of spawning run river lamprey (Lampetra fluviatilis) approaching a low-head weir retrofitted with studded tiles

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Quantifying the fine-scale behaviour of spawning run river lamprey (*Lampetra fluviatilis*) approaching a low-head weir

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Aims and objectives

Aim: Create a model to predict the upstream movement of river lamprey (*Lampetra fluviatilis*) as they approach a riverine barrier

Objectives:

- Quantify lamprey upstream movement parameters (e.g. speed/tortuosity)
- Link movement to environmental factors (e.g. depth/velocity)
- Develop behavioural rules
- Integrate behavioural rules into an ABM



Upstream migrating river lamprey movement model





- 2D Model includes:
 - Advection
 - Swimming
 - Reflection
 - Tortuosity/persistence
 - Aim to incorporate:
 - Behavioural preferences to certain hydrodynamic conditions
 - Rules learnt from telemetry study

Quantifying movement parameters:

Field work site:

- River Derwent, Yorkshire, UK
 - SAC
 - Multiple anthropogenic barriers
- Buttercrambe weir
 - Gauging weir (1973)
 - Ineffective fish passage options (2013)
 - Microhydropower (2017)





Monitoring equipment downstream of the weir







Bathymetry and hydraulics:



- ArcBoat
- GPS
- ADCP

Depth (m)



Depth averaged velocity (m s⁻¹)



Hydraulic model mesh:



Whiw-uk.localiprojects/live/MAS12403/Wode/JimKen/For Tom/mesh/butter05dp_02_osgb84.geom Whiw-uk.localiprojects/live/MAS12403/Mode/JimKen/For Tom/mesh/butter05dp_02_osgb84.mws

- 395 lamprey captured and released over 10 release events November/December 2017.
 - All lamprey PIT tagged
 - 34 lamprey double tagged with acoustic and PIT tags









Acoustic 2D tracking

- Multiple issues with acoustic telemetry at the site
 - Air entrainment
 - Depth
 - Bed structure
 - Solid surfaces
- Conventional tracking software wasn't effective:
 - Failed
 - Errors
 - No transparency



Acoustic 2D tracking

- 1) Select and clean the required data
- 2) Track fish position based on 'time difference of arrival' calculations
- 3) Calculate exact ping time of the tag
- 4) Track fish position based on 'time till arrival' calculations







Tracking accuracy

- Five ArcBoat transits through the array blind tracked.
- Median error:
 - 0.83 m
- Maximum error:
 - 2.20 m









Predicting lamprey movement

Track fish movements

Predict fish movements

Correlate fish movement with hydraulics and bathymetry ABM

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Impact of climate change/turbine management?

Develop behavioural rules

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Thank you. Any questions?

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