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Magnetic Reconnection Propulsion

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Magnetic Reconnection Propulsion

D. Valletta

Magnetic Reconnection Propulsion

N. B. Orange

Magnetic Reconnection Propulsion

H. M. Oluseyi

Magnetic Reconnection Propulsion

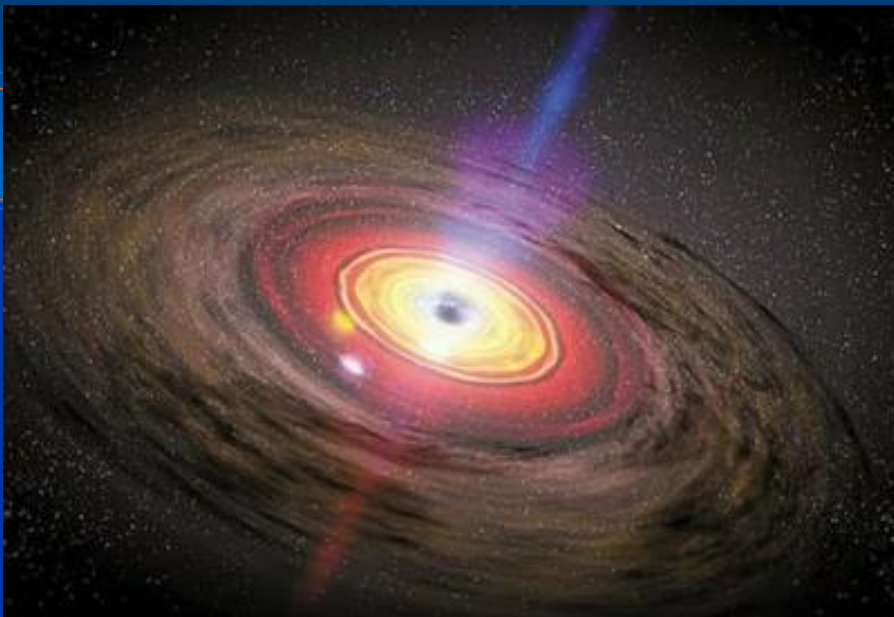
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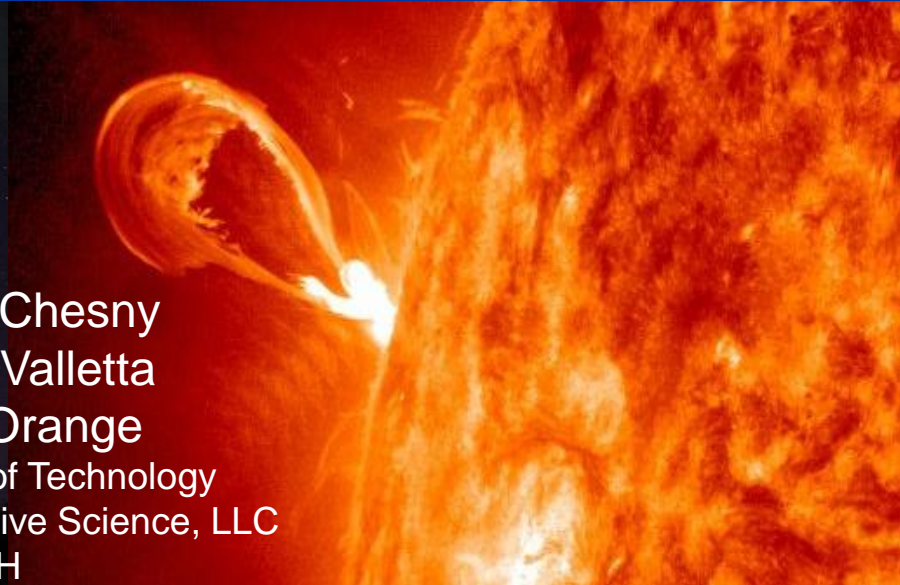
Chesny, D. L.; Valletta, D.; Orange, N. B.; and Oluseyi, H. M., "Magnetic Reconnection Propulsion" (2016).
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Magnetic Reconnection Propulsion



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Space Congress 2016



**“The Journey:
Further Exploration
for
Universal Opportunities”**

**“...showcase the evolution of our
industry... to meet the challenges of
the future.”**

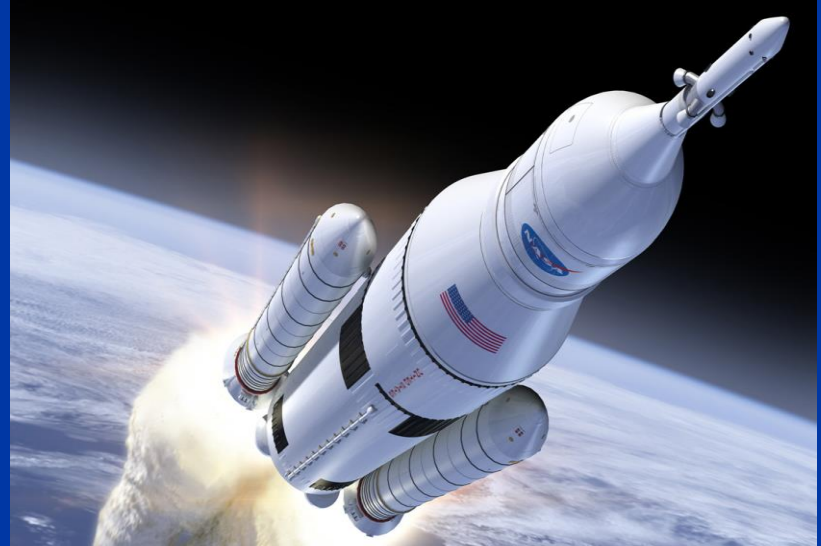
***Better, Faster,
Cheaper***



Faster?



Chemical
Propulsion

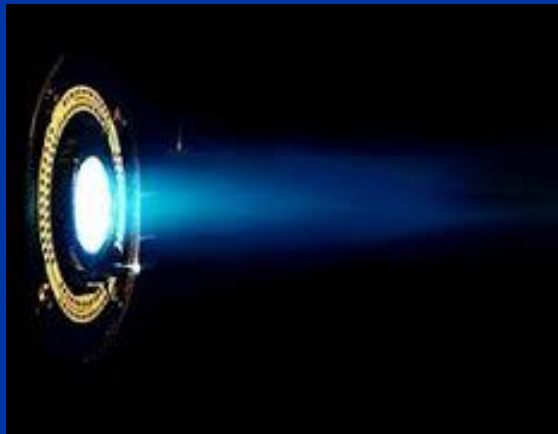


Faster? How?

Increase
Thrust

$$T = u_{ex} \dot{m}$$

Alternative \longrightarrow Plasma Propulsion



Chemical vs. Plasma Propulsion

Specific
c
Impulse

$$I_{sp} = \frac{u_{ex}}{g_0}$$

Thrust

$$T = u_{ex} \dot{m}$$

Chemical (hypergolic)

- $I_{sp} = 250-450$ s
- $u_{ex} = 5-10$ km s⁻¹
- Thrusts of ~1 N per unit input mass

Plasma (Hall thrusters, ion, SEP)

- $I_{sp} = 2000-5000$ s
- $u_{ex} = \sim 30$ km s⁻¹
- Thrusts of ~0.01 N per unit input mass

Maximize u_{ex} !



Sources of High-speed Particles

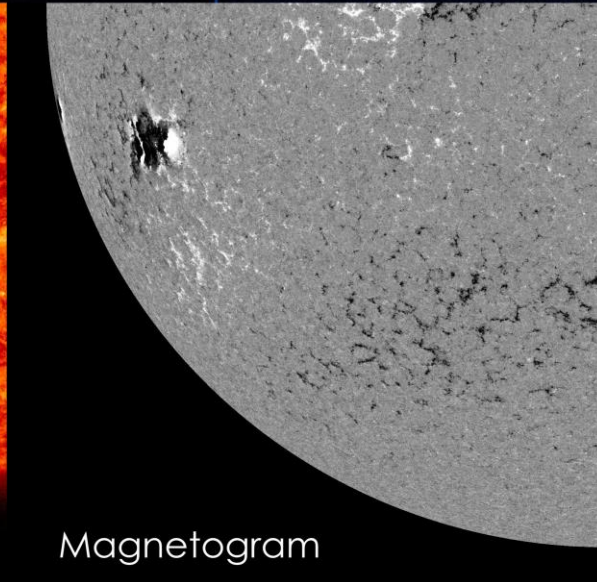
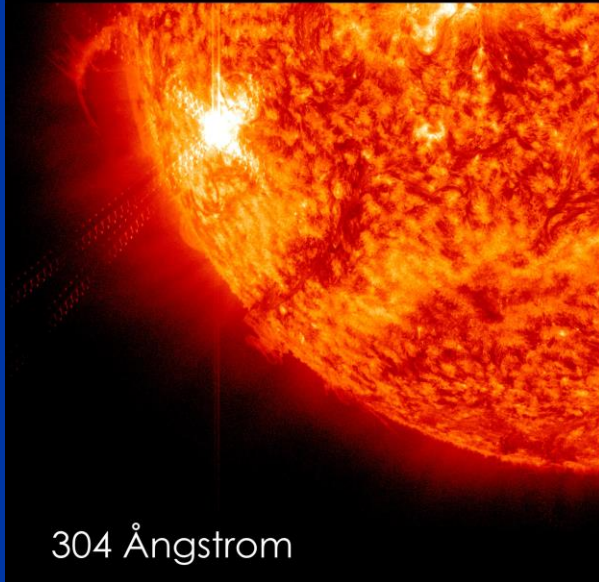
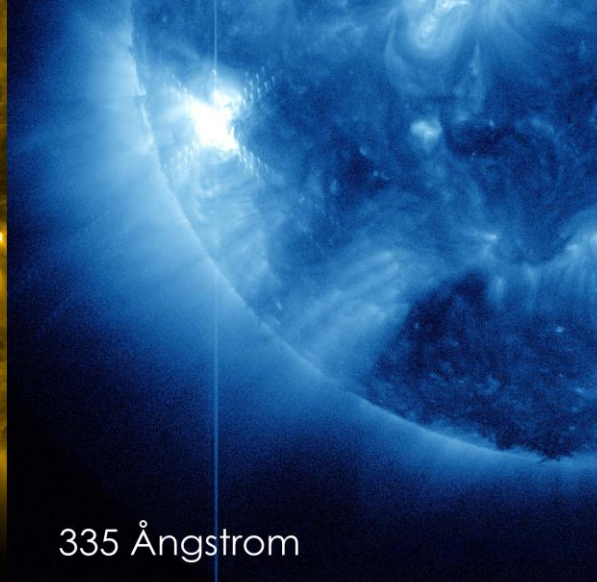
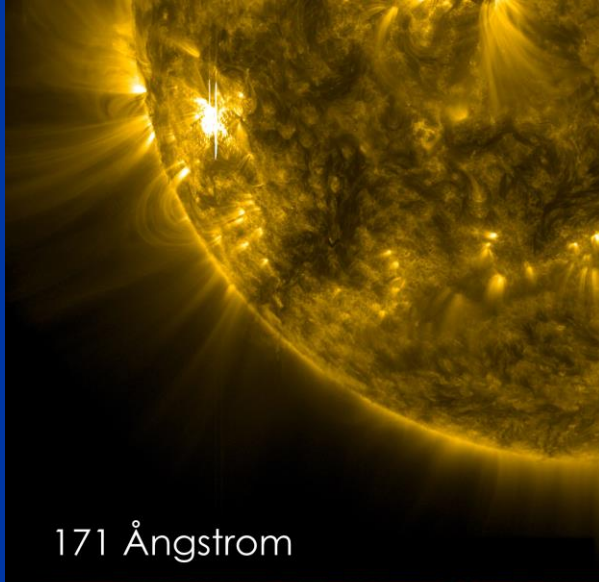
Solar
Wind
~400 km/s

Coronal Mass
Ejections
~3,000 km/s

Magnetic Reconnection



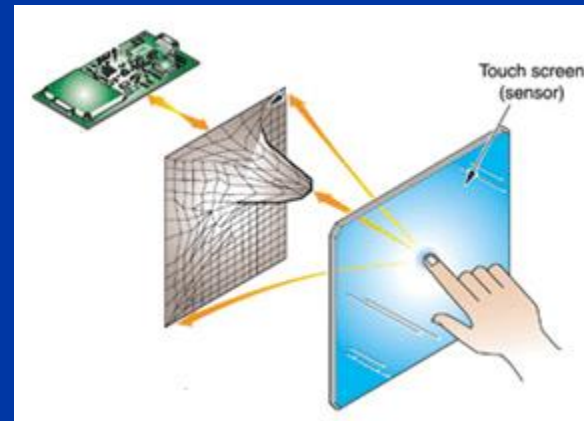
Sources of High Speed Particles



Translate **Theory** to **Engineering**

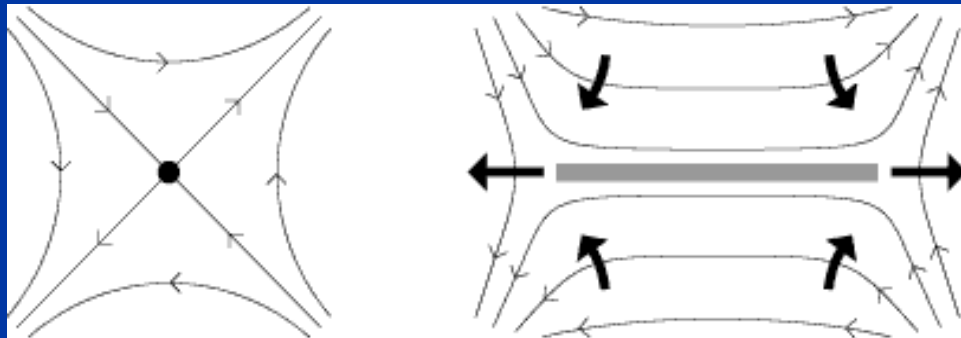
**Example: Smartphone
touchscreens!**

$$C = \epsilon_r \frac{A}{4\pi d} \quad \Delta V = \frac{Q}{C}$$



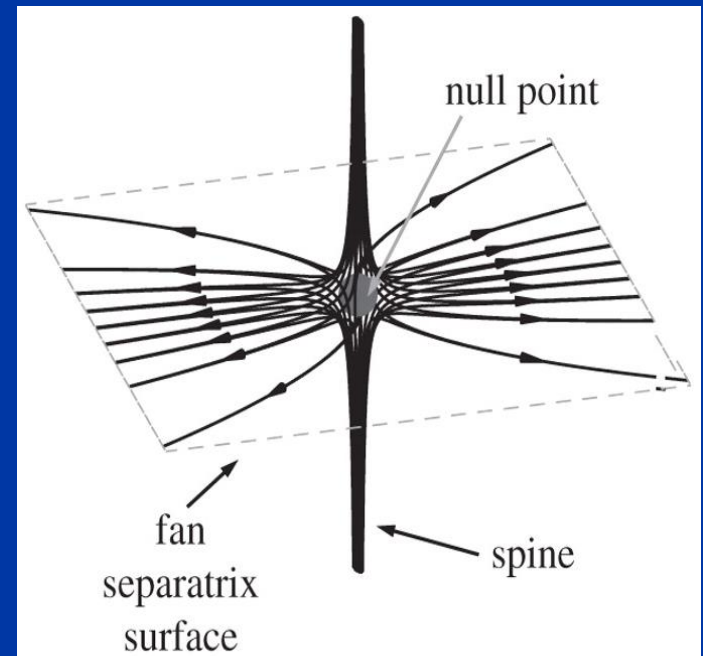
Magnetic Reconnection

2D

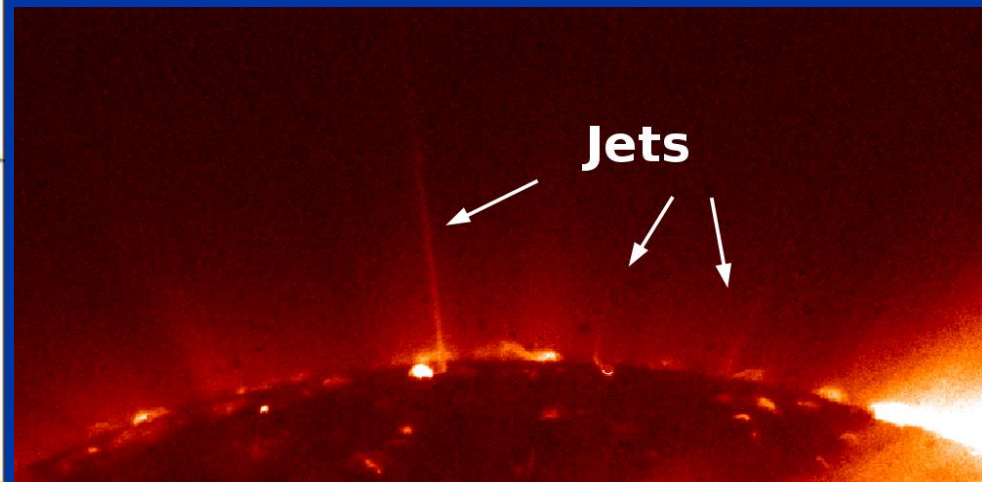
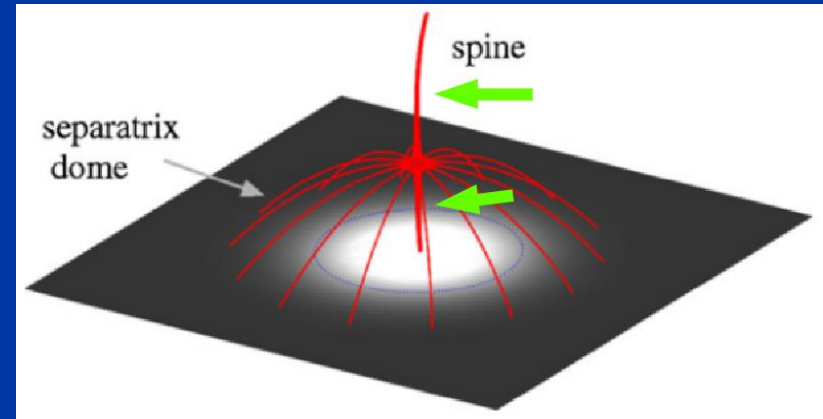
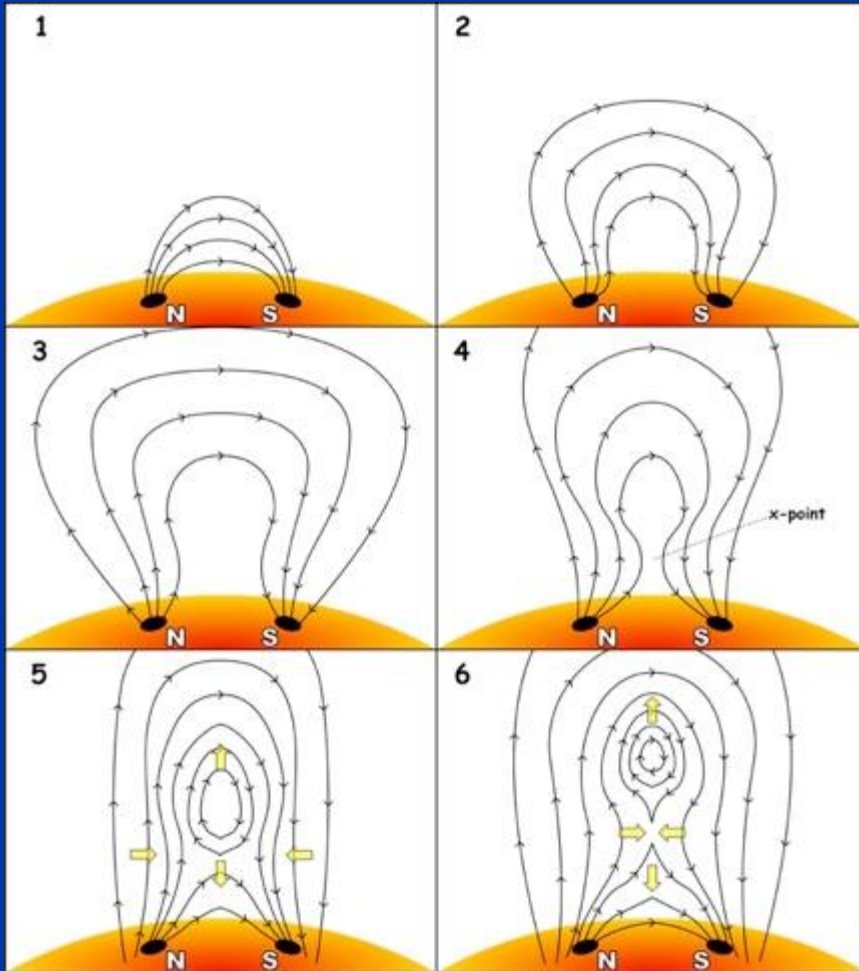


Diffusion-dominated process

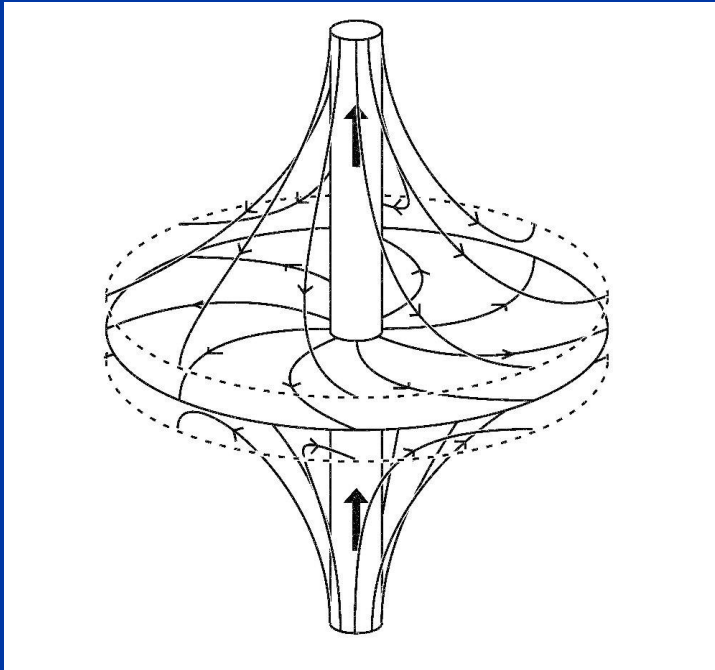
3D



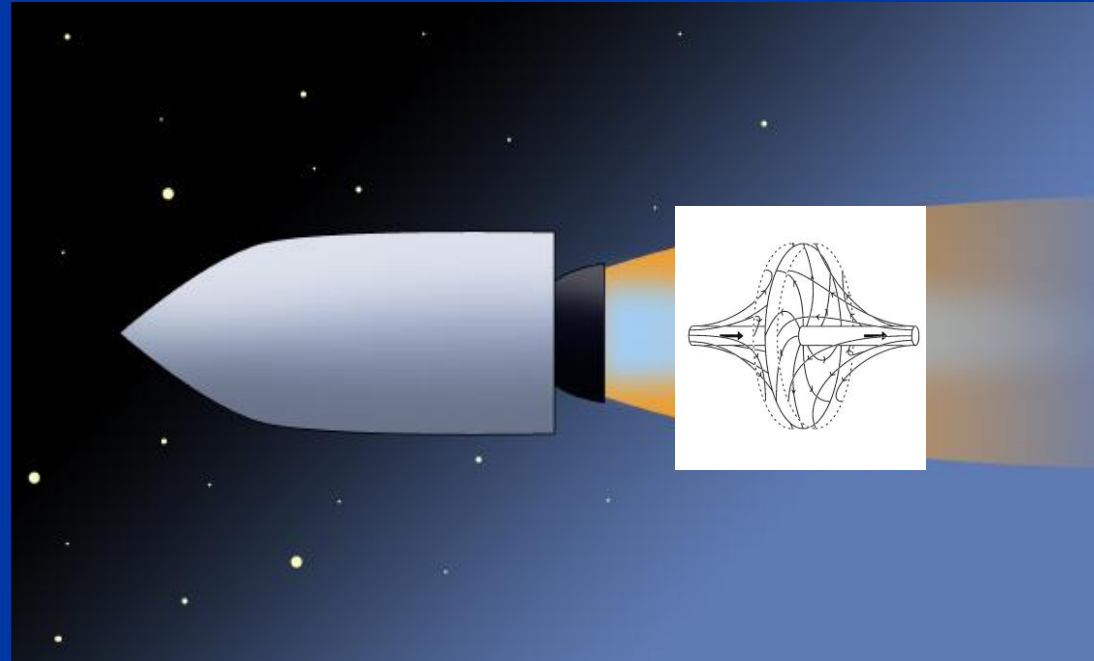
Reconnection in the Solar Atmosphere



Application to Propulsion?



Intense spine current

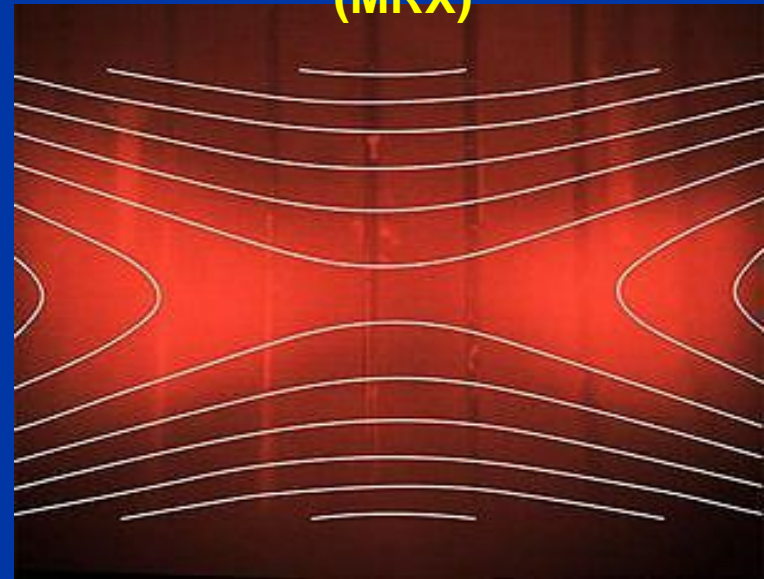


Reconnection on Earth

MIT
Versatile Toroidal
Facility



PPPL
Magnetic Reconnection Experiment
(MRX)



2D manifestations only

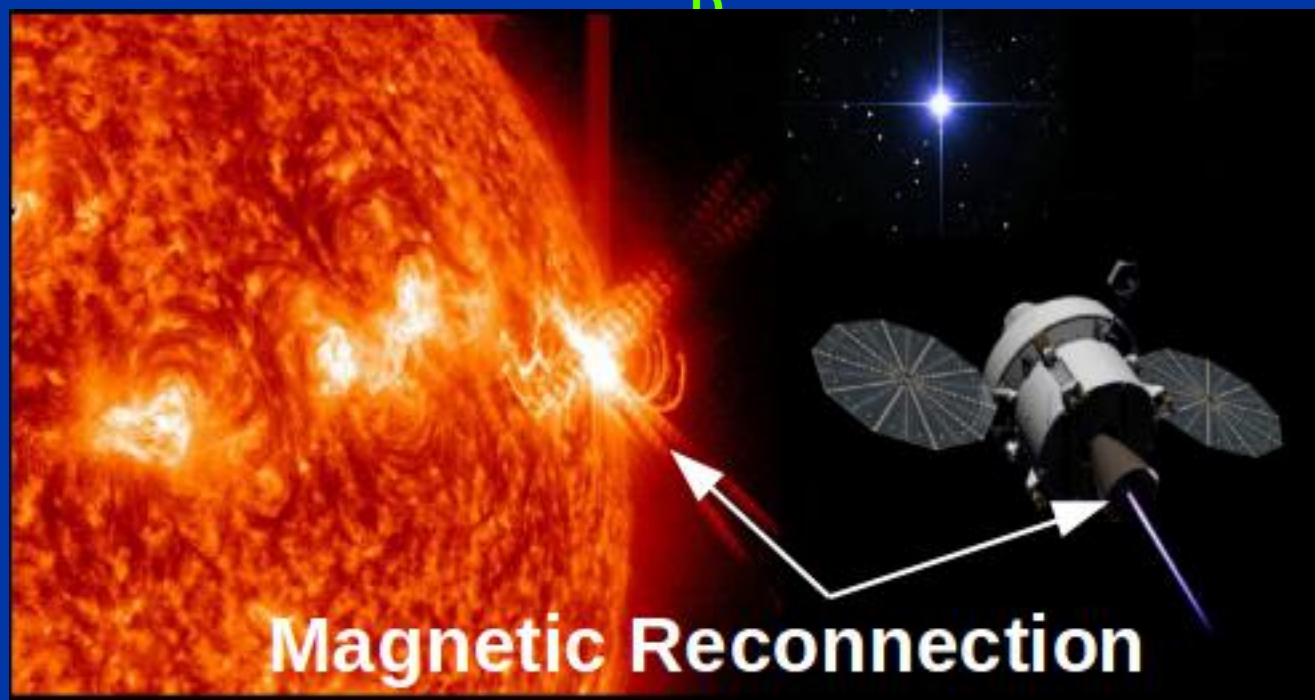


Innovate?

State-of-the-art ———> Better, Faster, Cheaper

Reconnection ———> Better, Smaller, Cheaper
Devices

3
D



From Theory to Practice

Magnetohydrodynamics

(MHD)

- Apply field parameters
- Predict timescales
- Predict particle velocities (u_{ex})

Kinetic Reconnection

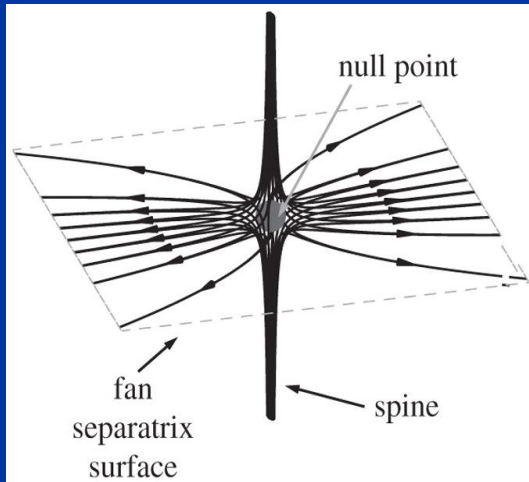
- Perturbations
- Time-dependent field evolution

Engineering

- Enabling components



MHD Modeling



$$\vec{B} = \vec{M} \cdot \vec{r}$$

$$\vec{M} = \begin{vmatrix} 1 & \frac{1}{2}(q - j_{\parallel}) & 0 \\ \frac{1}{2}(q + j_{\parallel}) & p & 0 \\ 0 & j_{\perp} & -(p + 1) \end{vmatrix}$$

Parnell et al. (1996)

Parnell et al. (2007): Perturb field so that current is induced along spine

$$\mathbf{B} = B_0 \left(x - \epsilon e^{\omega t} \frac{p}{p-1} j_{\parallel} y, -\epsilon e^{\omega t} \frac{1}{p-1} j_{\parallel} x + p y, -(p+1) z \right) / l$$

$$\mathbf{v} = \epsilon v_A e^{\omega t} \left(-\frac{p}{|p-1|} j_{\parallel} y, \frac{1}{|p-1|} j_{\parallel} x, 0 \right) / l$$

$$\mathbf{J} = B_0 \epsilon e^{\omega t} (0, 0, j_{\parallel}) / l$$

$$\omega = |p-1| v_A / l$$



MHD Modeling

Solve with physical parameters:

$$m = 2 m_H$$

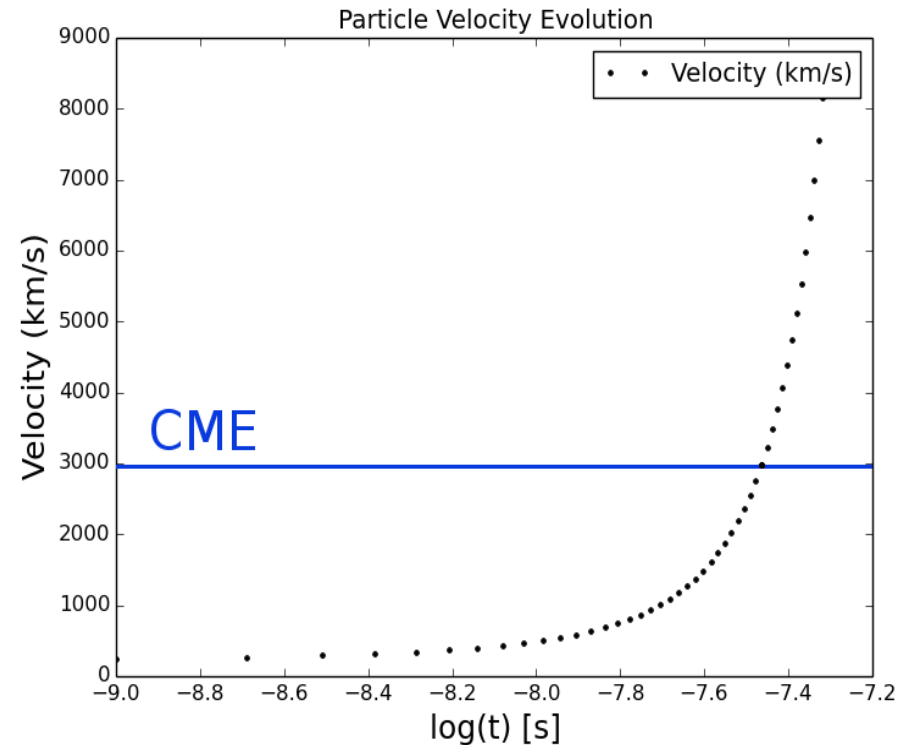
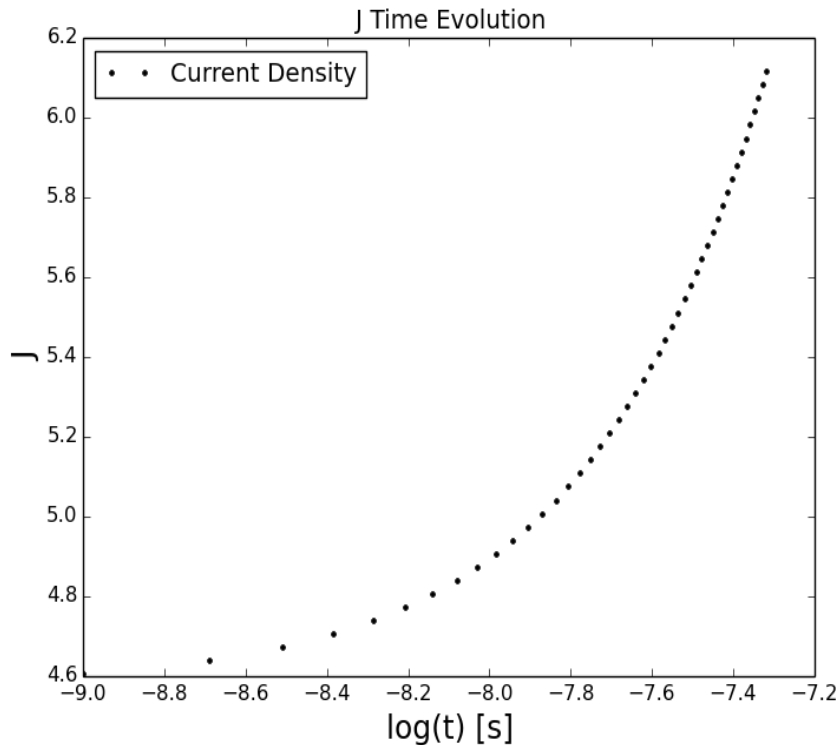
$$B_0 = 1 \text{ T}$$

$$l = 1 \text{ m}$$

$$n = 10^{18} \text{ m}^{-3}$$

$$v_A = 10^7 \text{ m/s}$$

$$\omega_A = 10^7 \text{ s}^{-1}$$



limits: $\epsilon j_z e^{\omega t} < 1$; $S \sim 10^2$

Reconnection will occur on very short timescales



Kinetic Modeling

How do charged particles respond
to externally imposed boundary
conditions?

Plasma flow along spine must be
driven by driven perturbation



Produce Initial Magnetic Field

Parnell et al. (1996)

$$\vec{B} = \vec{M} \cdot \vec{r}$$



Along
spine



Pontin et al. (2011)

$$\vec{B} = \left[\frac{2}{p+1}x, \frac{2p}{p+1}y, -2z \right]$$



Along
spine



Helical
twist



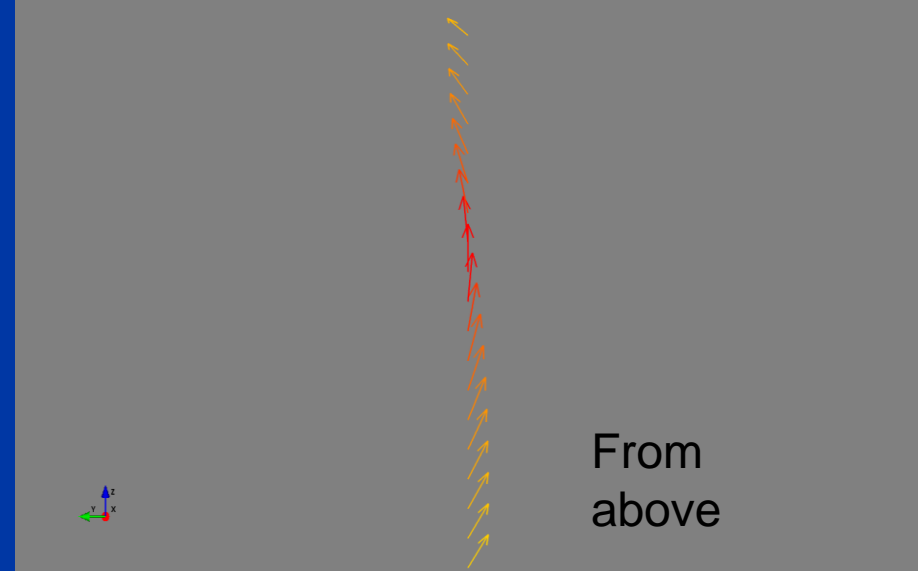
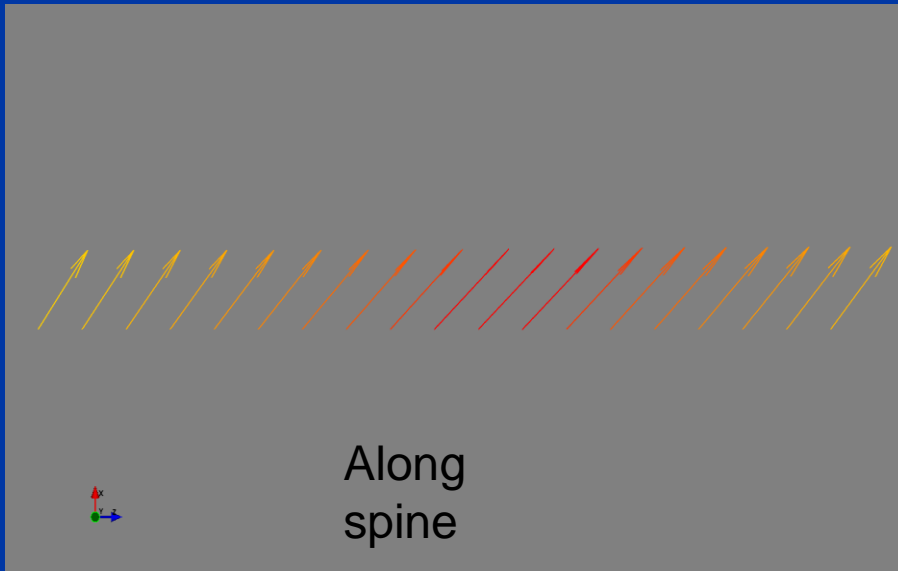
Around
spine



Produce Initial NP Field

Field we want $\vec{B} = \vec{M} \cdot \vec{r}$ \longrightarrow Ampère's Law $\nabla \times \vec{B} = \mu_0 \vec{J}$ \longrightarrow Source currents $\vec{J} = \frac{1}{\mu_0} (j_{\perp}, 0, j_{\parallel})$

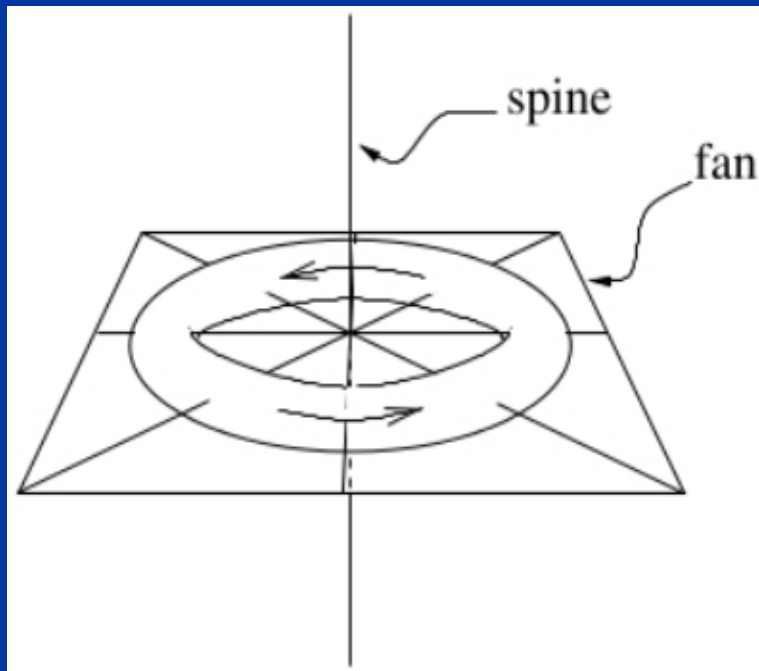
perpendicular



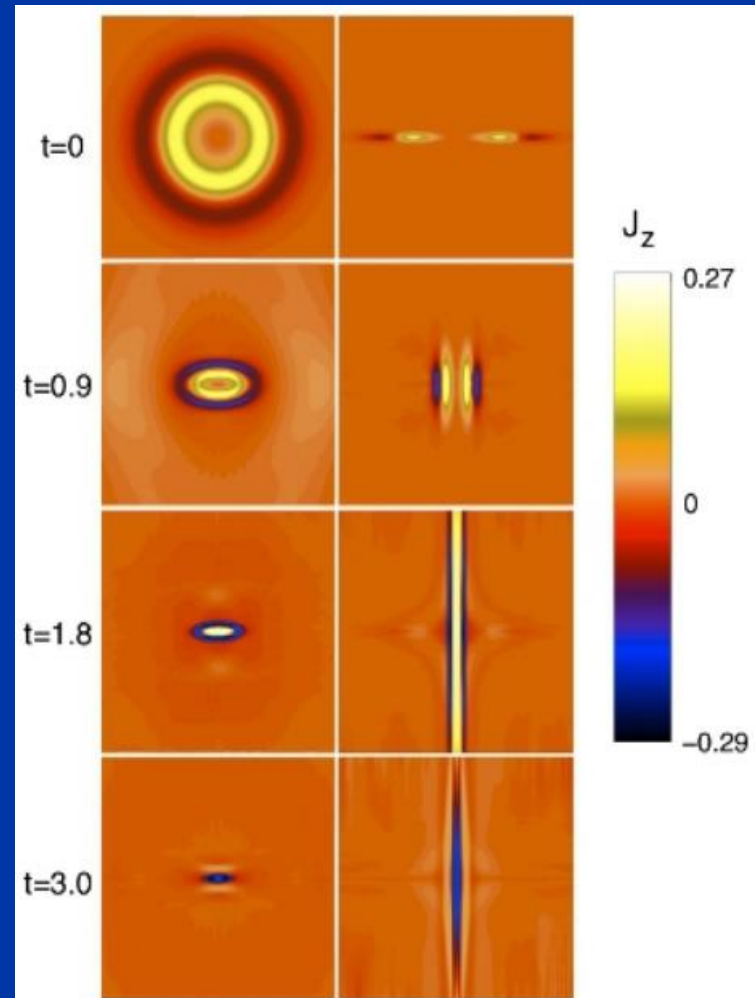
Is there an existing technology that can produce such fields?



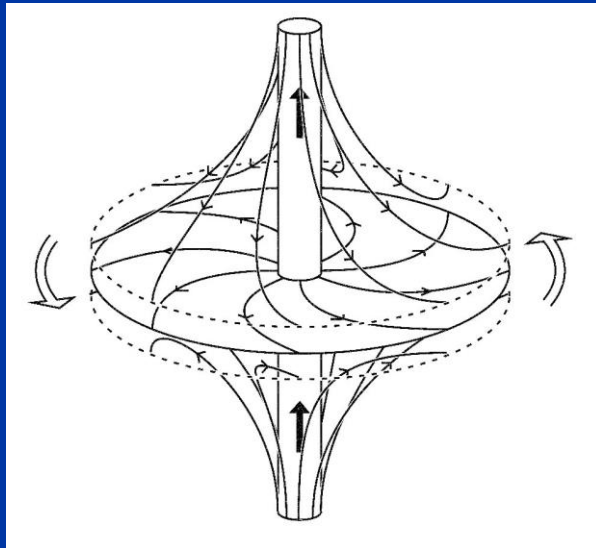
Perturbation Driving Plasma Flow



Pontin et al. (2011) applied circular magnetic field perturbation to existing neutral point potential field



Enabling Technology



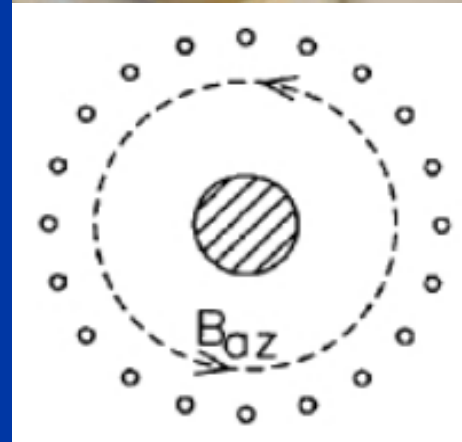
Theory

Engineering



outer electrodes (cathode)

inner electrode (anode)



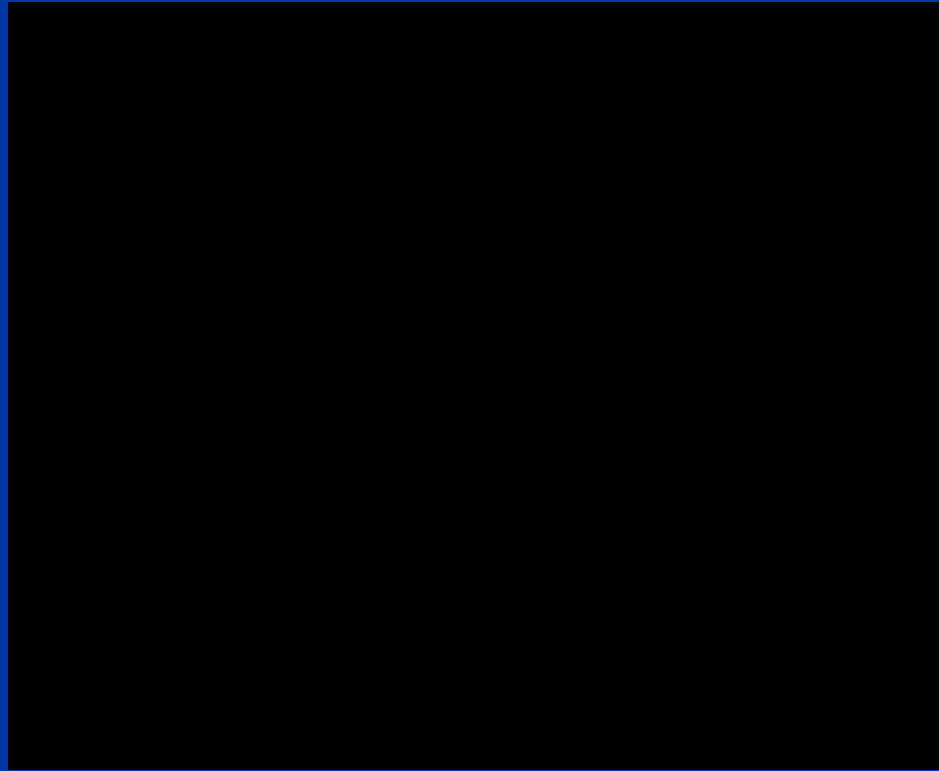
Dense Plasma Focus

Creates plasma sheath with circular magnetic field!

Operate at 100 Hz



Enabling Technology

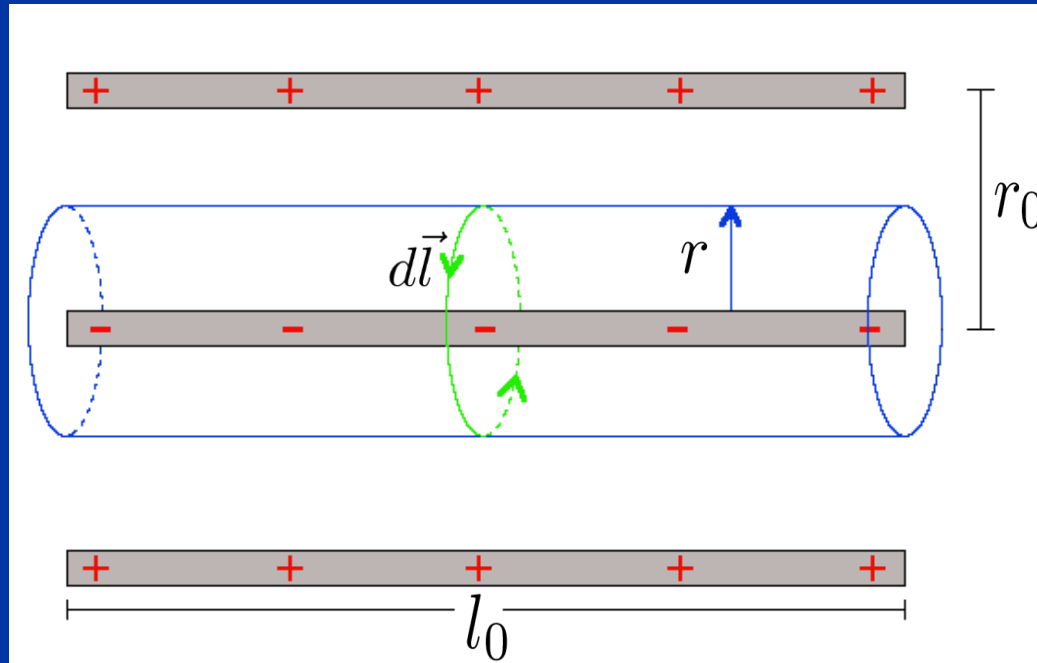


Dense Plasma Focus
Plasma Sheath
(Toroid)



DPF Fields

$$\oint_C \vec{B} \cdot d\vec{l} = \mu_0 \epsilon_0 \frac{d}{dt} \int_S \vec{E} \cdot \hat{n} da$$



$$Q(t) = C \Delta V e^{-\frac{t}{RC}}$$

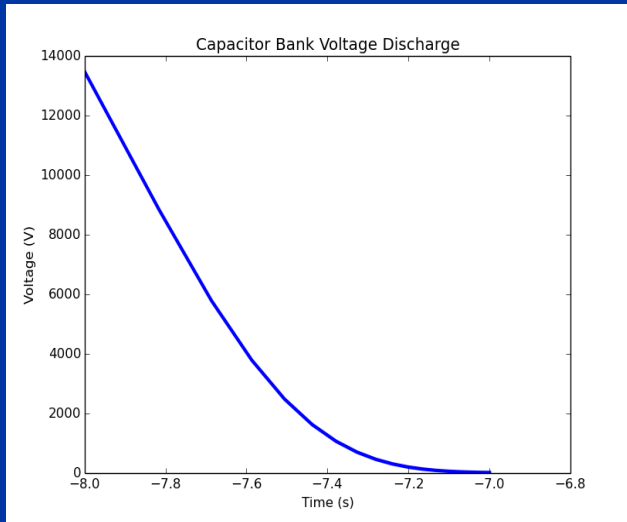
$$\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$B(r) = -\frac{\mu_0 \Delta V}{2\pi R} \frac{l}{rl_0} e^{-\frac{t}{RC}}$$

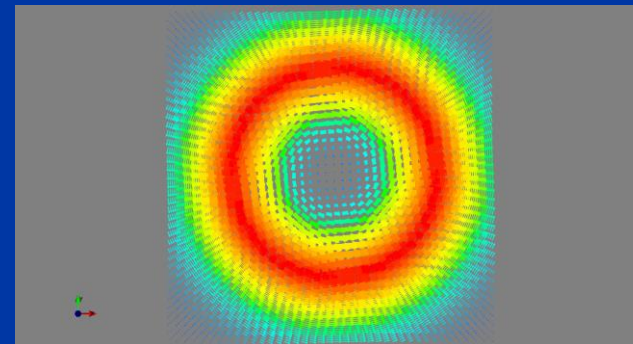
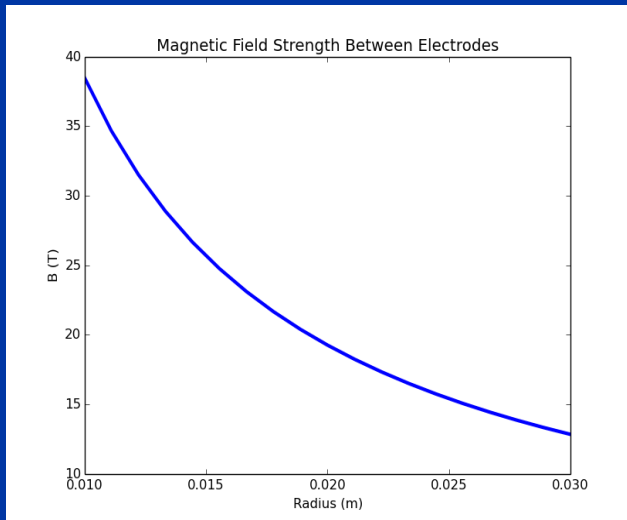
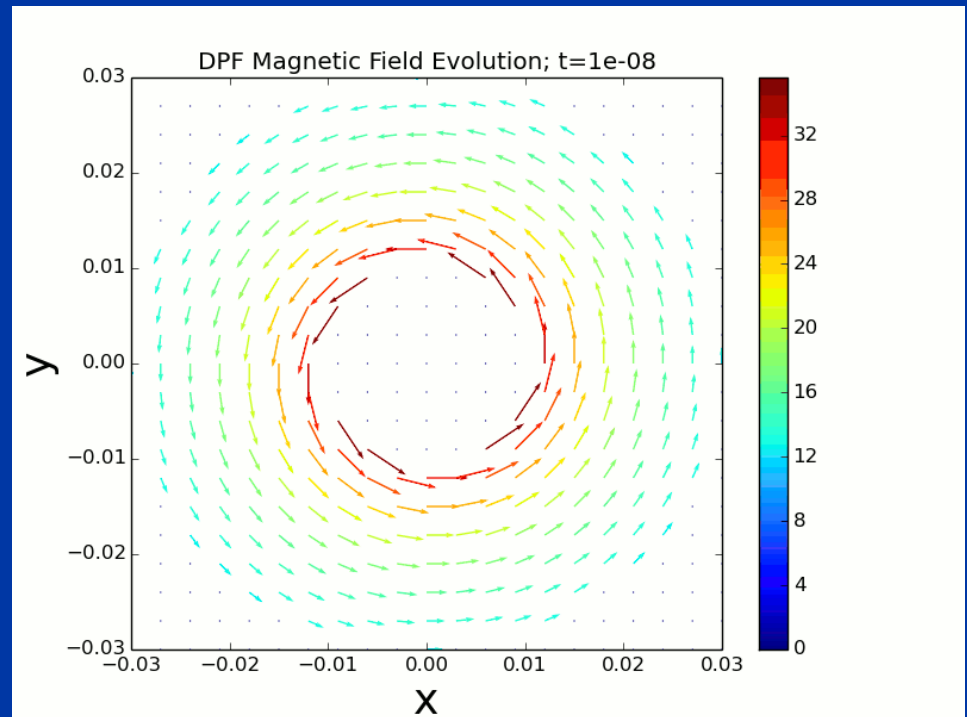
$$E(r) = \frac{\mu_0 \Delta V}{2\pi R^2 C} \frac{l}{l_0} \ln(r) e^{-\frac{t}{RC}}$$



Magnetic Field Evolution



$t = 1 \times 10^{-8} \rightarrow 1 \times 10^{-7} \text{ s}$

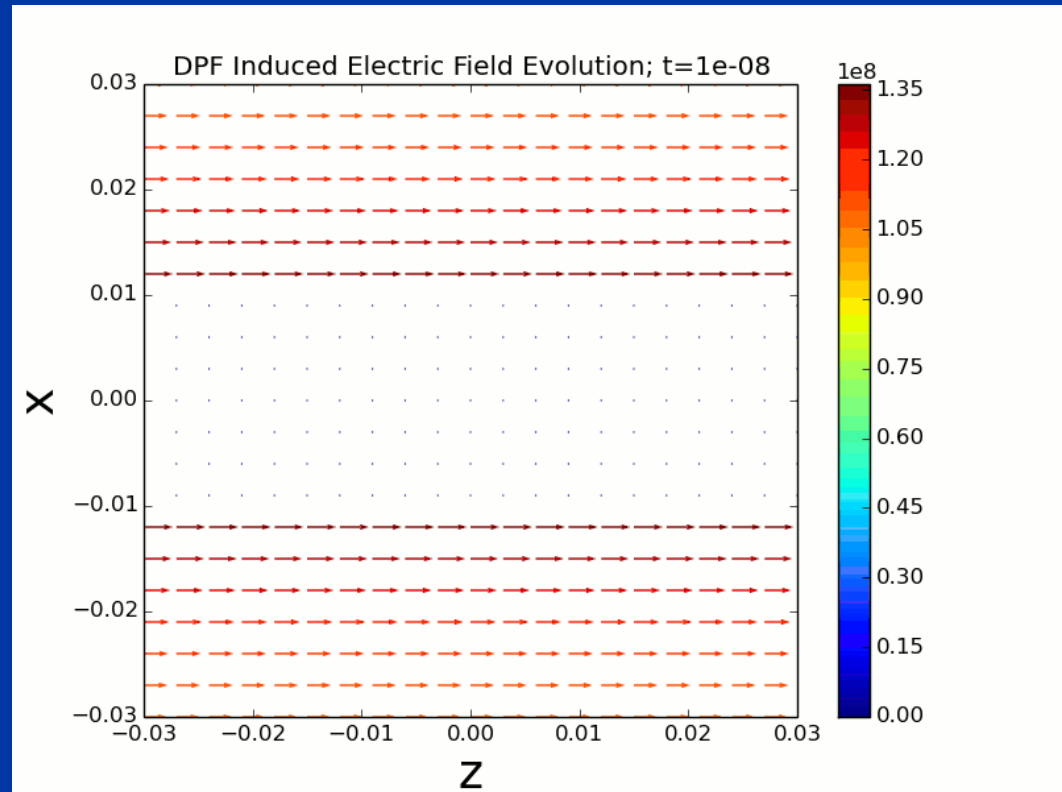


Theoretical
Perturbation



Induced Electric Field Evolution

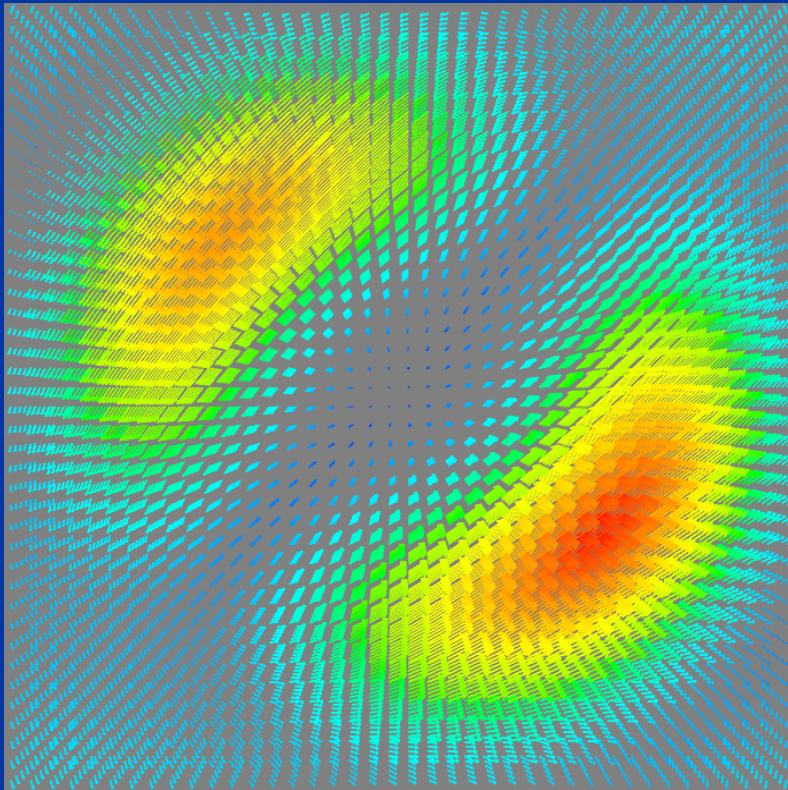
$$\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$



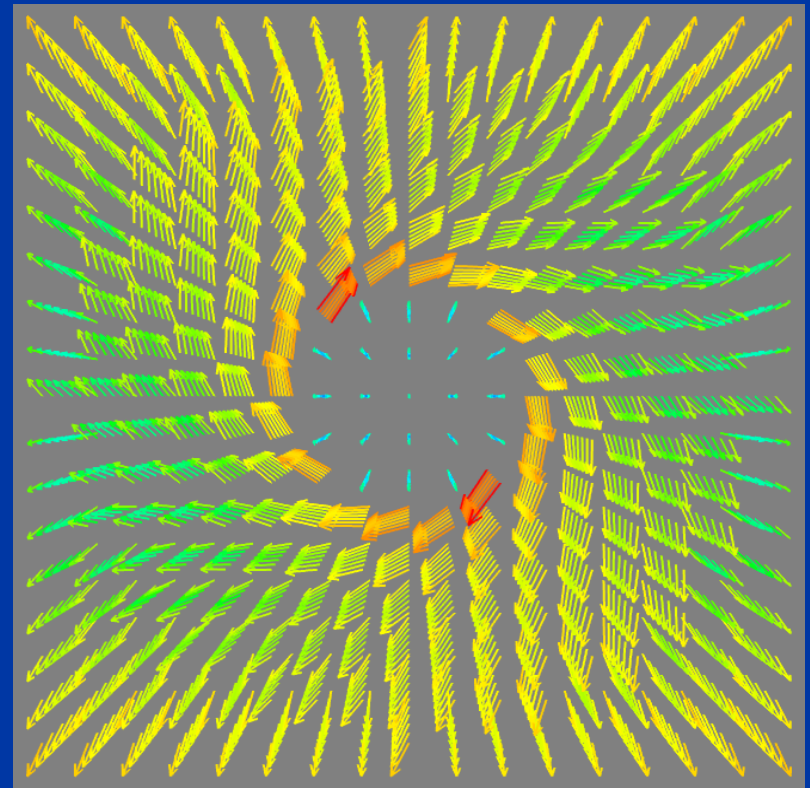
Acts to initialize plasma motions



Kinetic Modeling



Theoretical
Potential field PLUS
Perturbation



Experimental
Potential field PLUS **DPF**
Perturbation



Kinetic Modeling

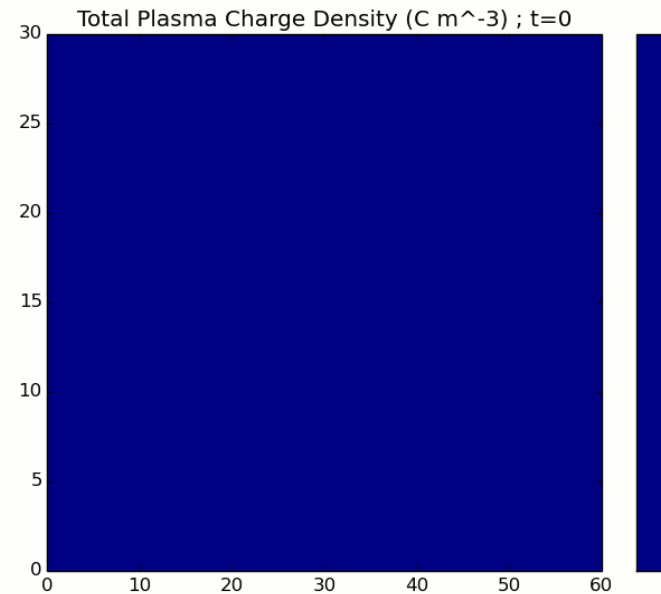
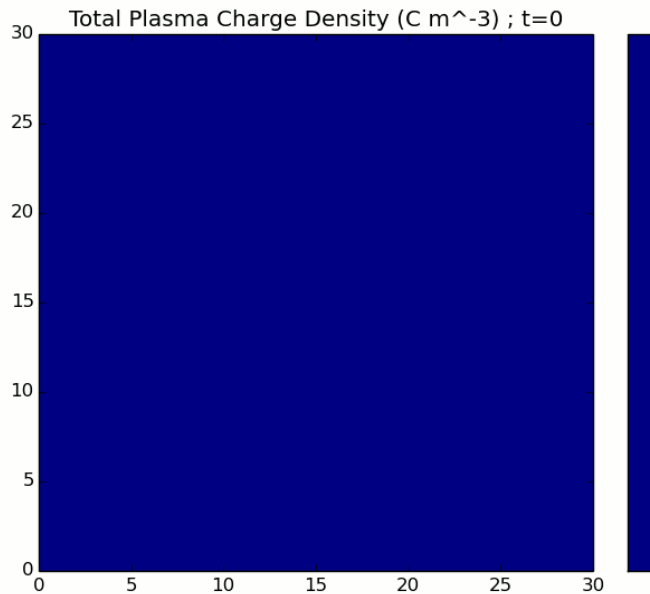
Particle-in-cell (PIC) simulations

Solves plasma motion in charge density space

$$\vec{F} = q(\vec{E} + \vec{v} \times \vec{B})$$

y=0 Plane ; spine up/down

z=0 Plane ; spine in/out



Engineering Considerations

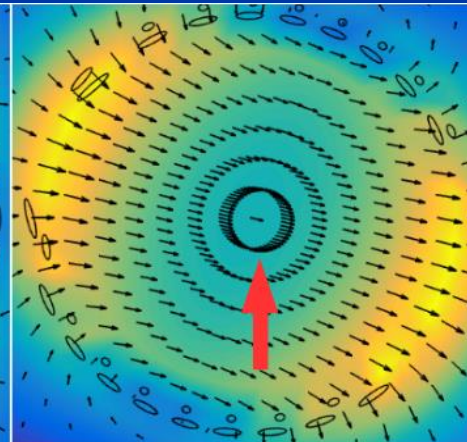
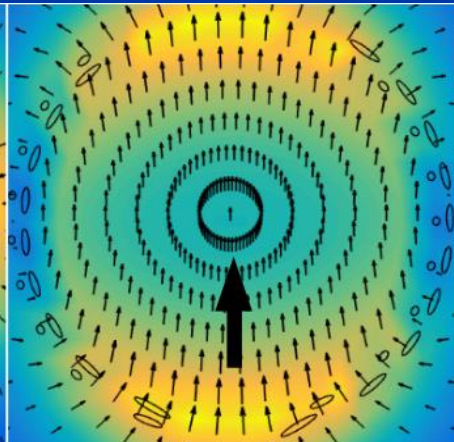
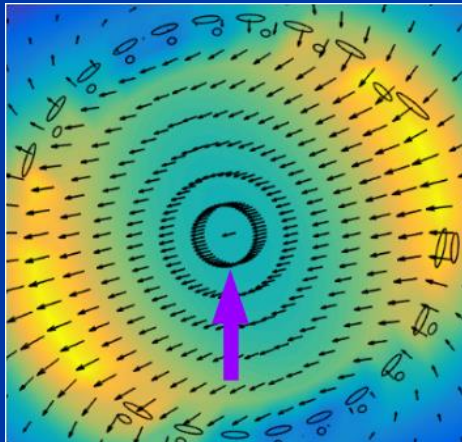
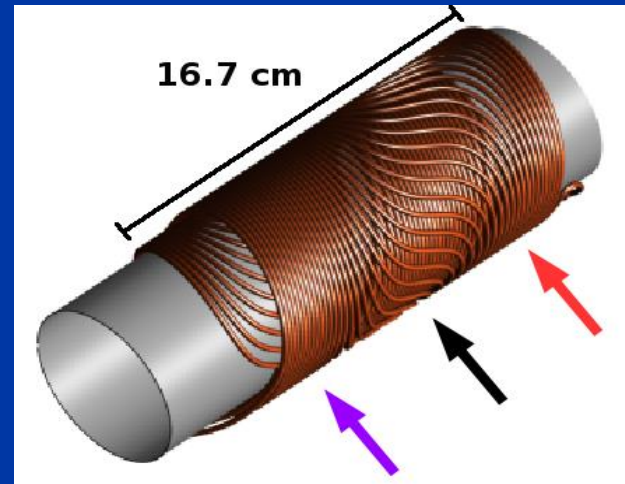


Engineering – Potential Field



“Twisted dipole”

- Copper
- Non-superconducting



Engineering - DPF

DPF Specifications

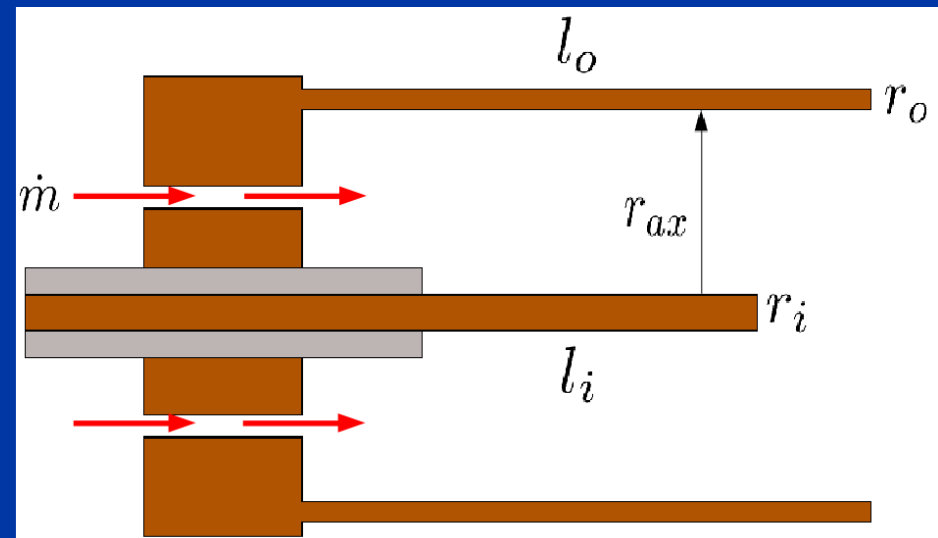
- Mather/Fillipov design
- Inner electrode (anode) radius
- Outer electrode (cathode) radius
- Axial radius

(anode-cathode offset distance)

- Anode length
- Cathode length
- Optimal conducting material
- Optimal insulating material
- Optimal plasma generation surface

Fuel input

- Number of feeds
- Radius of feeds
- Feed rate and pressure
- Determines thrust \dot{m}**



Engineering - Thermodynamics

Electrode **degradation** due to charged particle bombardment

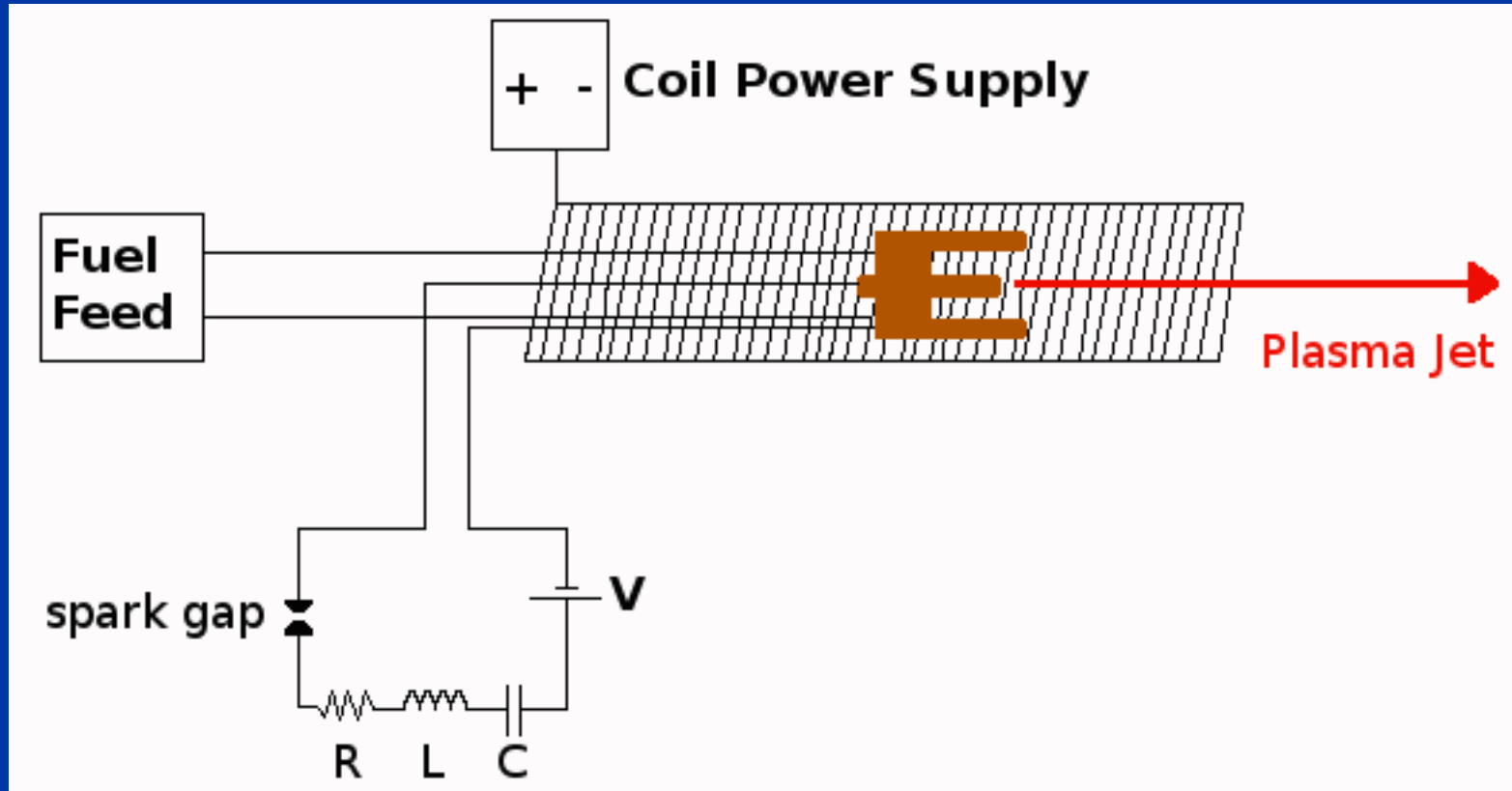
- DPF anode decay from fusion reactions
- After 10^3 shots

Thermal analysis

- Heat losses
- Inefficiencies



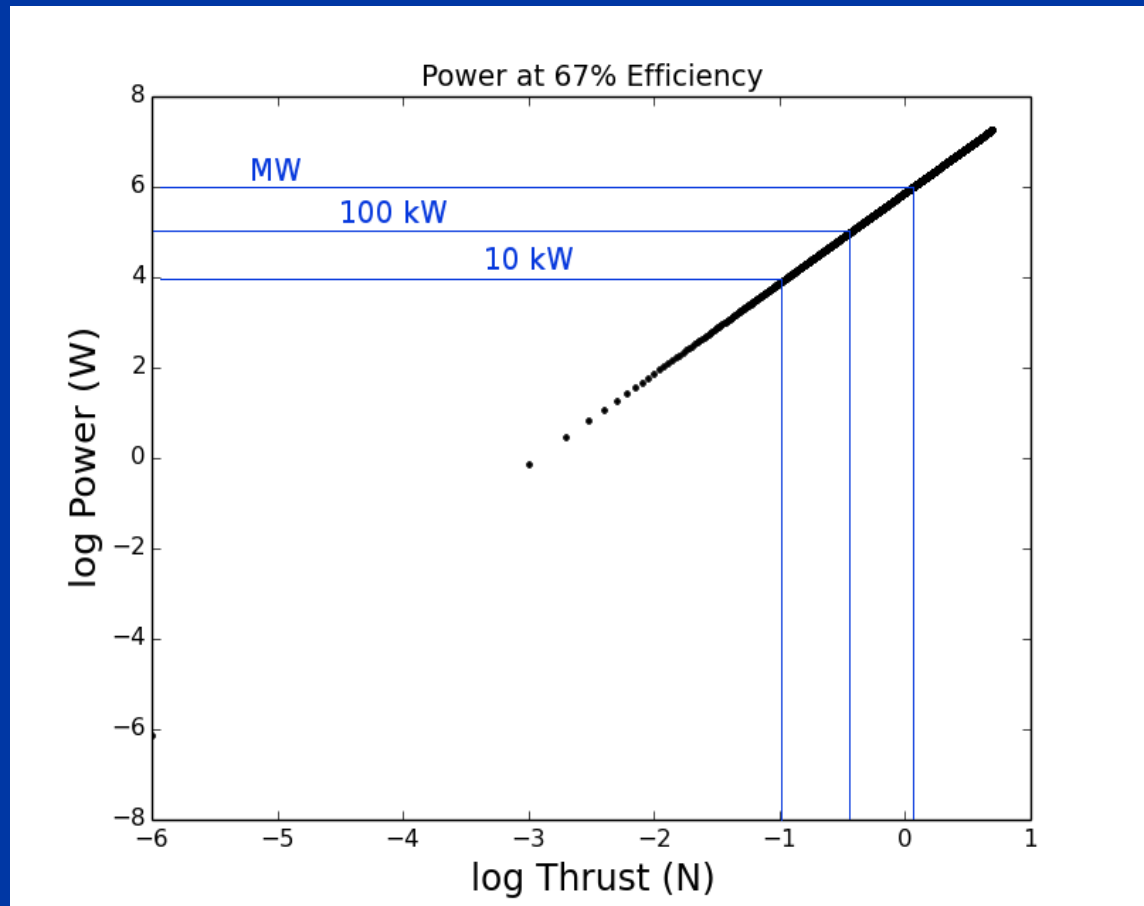
Engineering - System



Engineering – Power

$$P = \frac{1}{2} \dot{m} u_{ex}^2$$

10 MW – nuclear
200 kW – SAFE-2 fission
100 kW – ISS module



Summary

- Show feasibility
- Demonstrate proof-of-concept
- Working towards first publication
 - MHD, kinetic models, engineering
- Grant writing
 - FSGC, Space Technology Research, NIAC



Thank You

