

Feb 26th, 11:00 AM

Human-in-the-Loop Landing Flare Flight Test Simulation of the SpaceLiner Orbiter

Frank Morlang

DLR German Aerospace Center, Frank.Morlang@dlr.de

Follow this and additional works at: <https://commons.erau.edu/stm>



Part of the [Space Vehicles Commons](#)

Morlang, Frank, "Human-in-the-Loop Landing Flare Flight Test Simulation of the SpaceLiner Orbiter" (2019). *Space Traffic Management Conference*. 14.

<https://commons.erau.edu/stm/2019/presentations/14>

This Event is brought to you for free and open access by the Conferences at Scholarly Commons. It has been accepted for inclusion in Space Traffic Management Conference by an authorized administrator of Scholarly Commons. For more information, please contact commons@erau.edu.

Human-in-the-Loop Landing Flare Flight Test Simulation of the SpaceLiner Orbiter

Frank Morlang



Knowledge for Tomorrow



Overview

- Motivation
- Methodology
- Results
- Discussion & Outlook

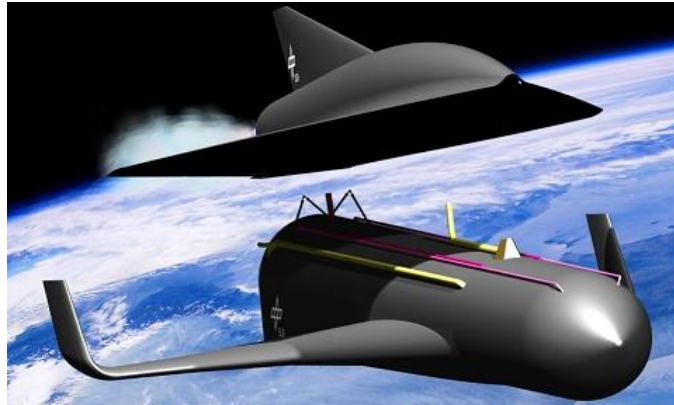


Motivation

- **Now**



- **Future (Who knows when ?)**



Methodology

Human-in-the-Loop Simulation for Space Traffic integration test purposes !

→ Use Case: DLR SpaceLiner concept



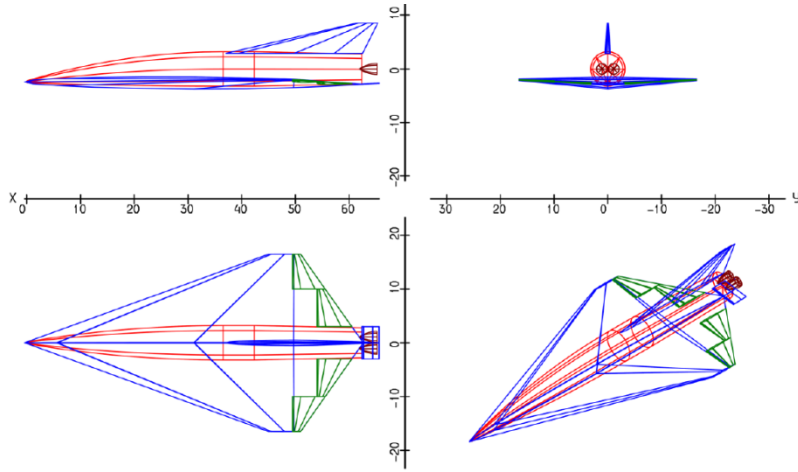
Methodology

Design drawings + CFD results

→ X-Plane flight simulation model



Methodology



+ (CAC)¹ & PAN AIR² model experiments' results

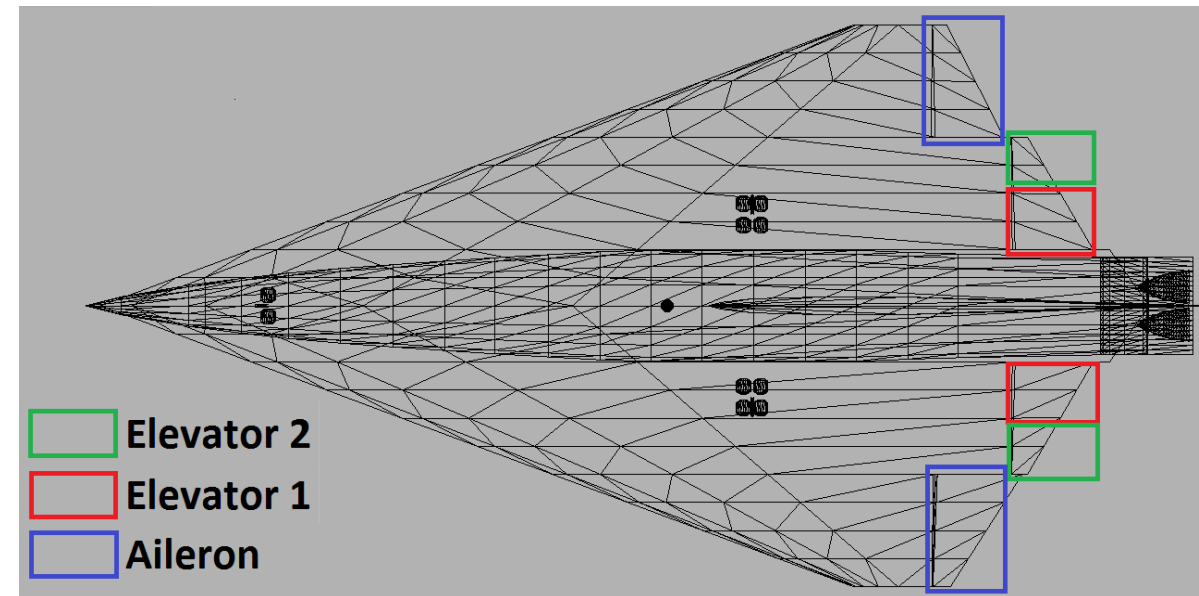
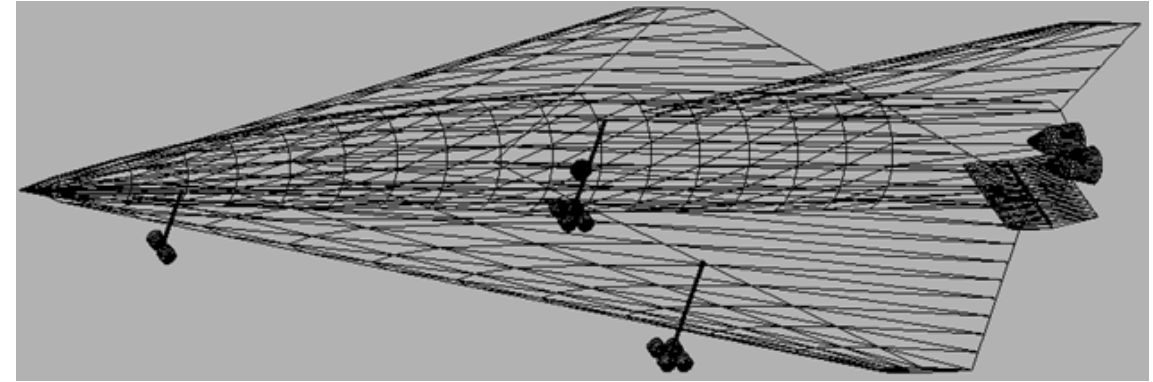
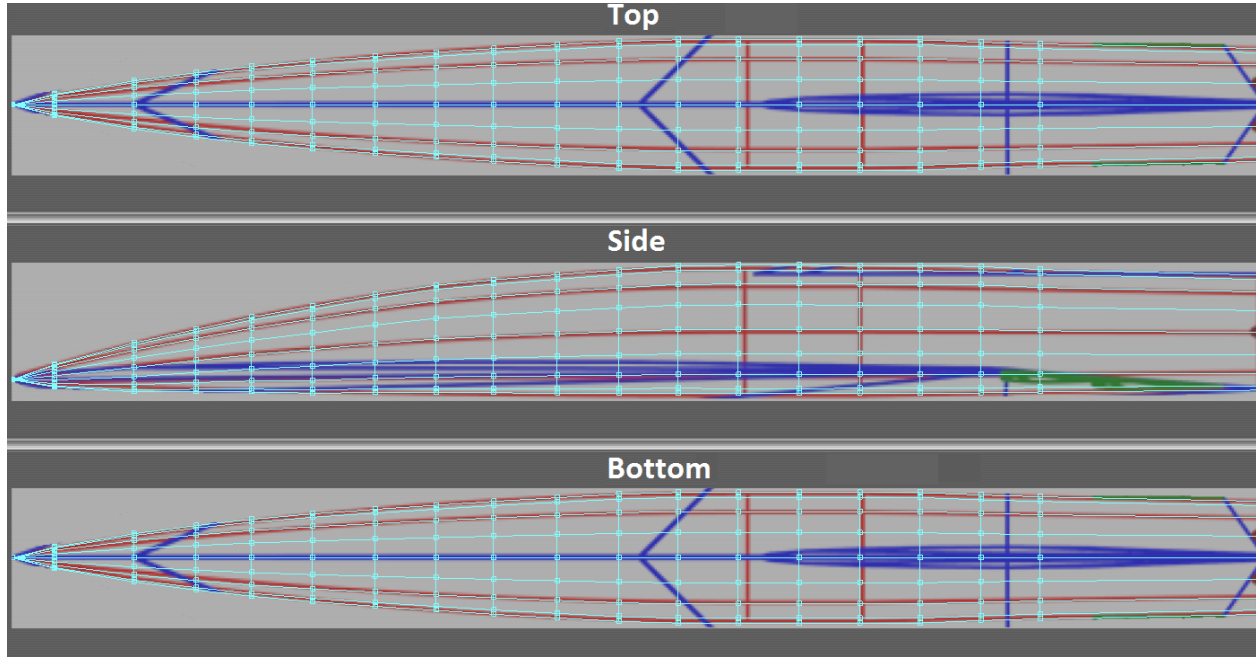
→ X-Plane flight simulation model

¹Software developed by DLR Institute of Space Systems, Dep. Space Launcher System Analysis

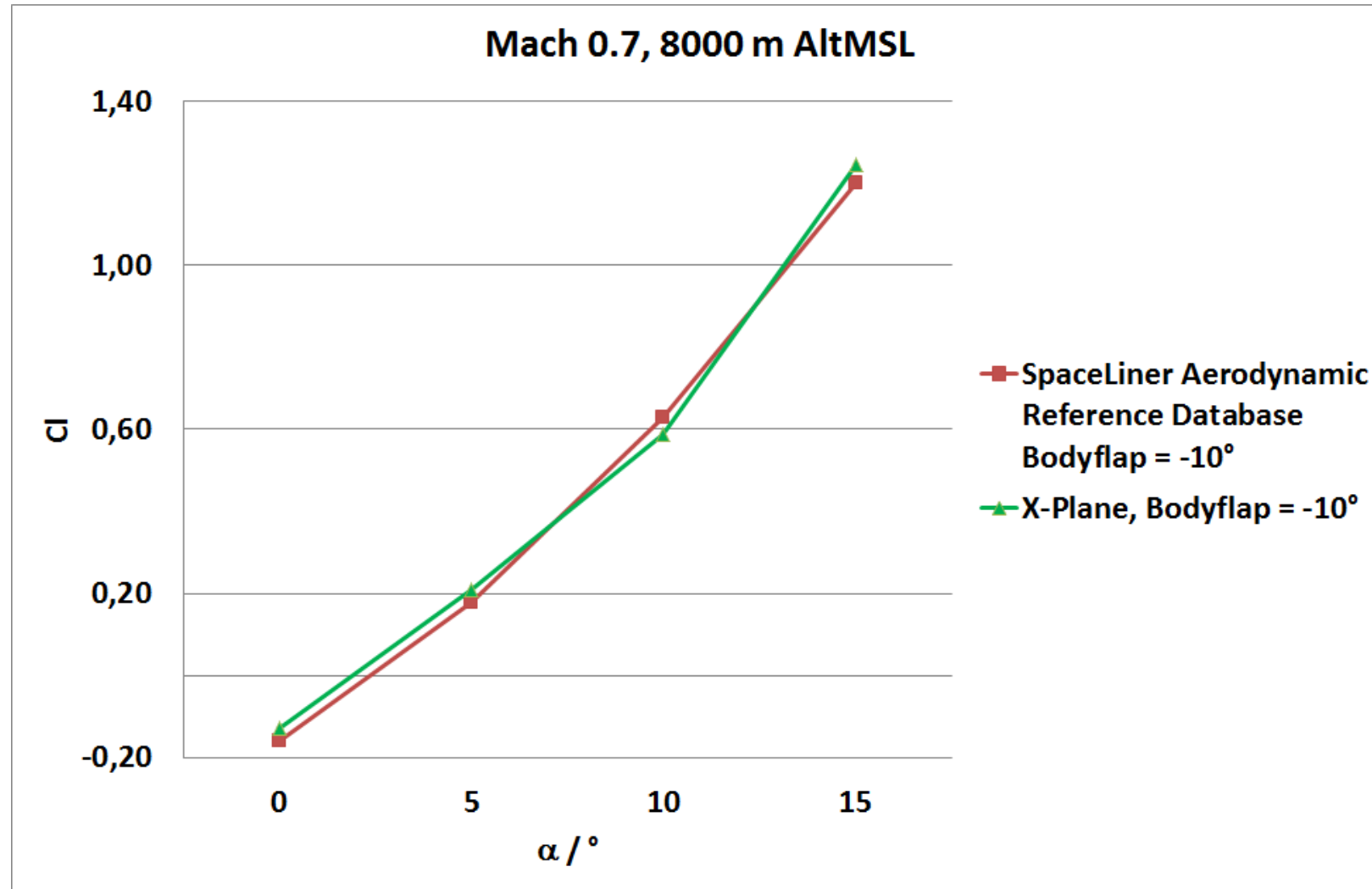
²Software developed by BOEING



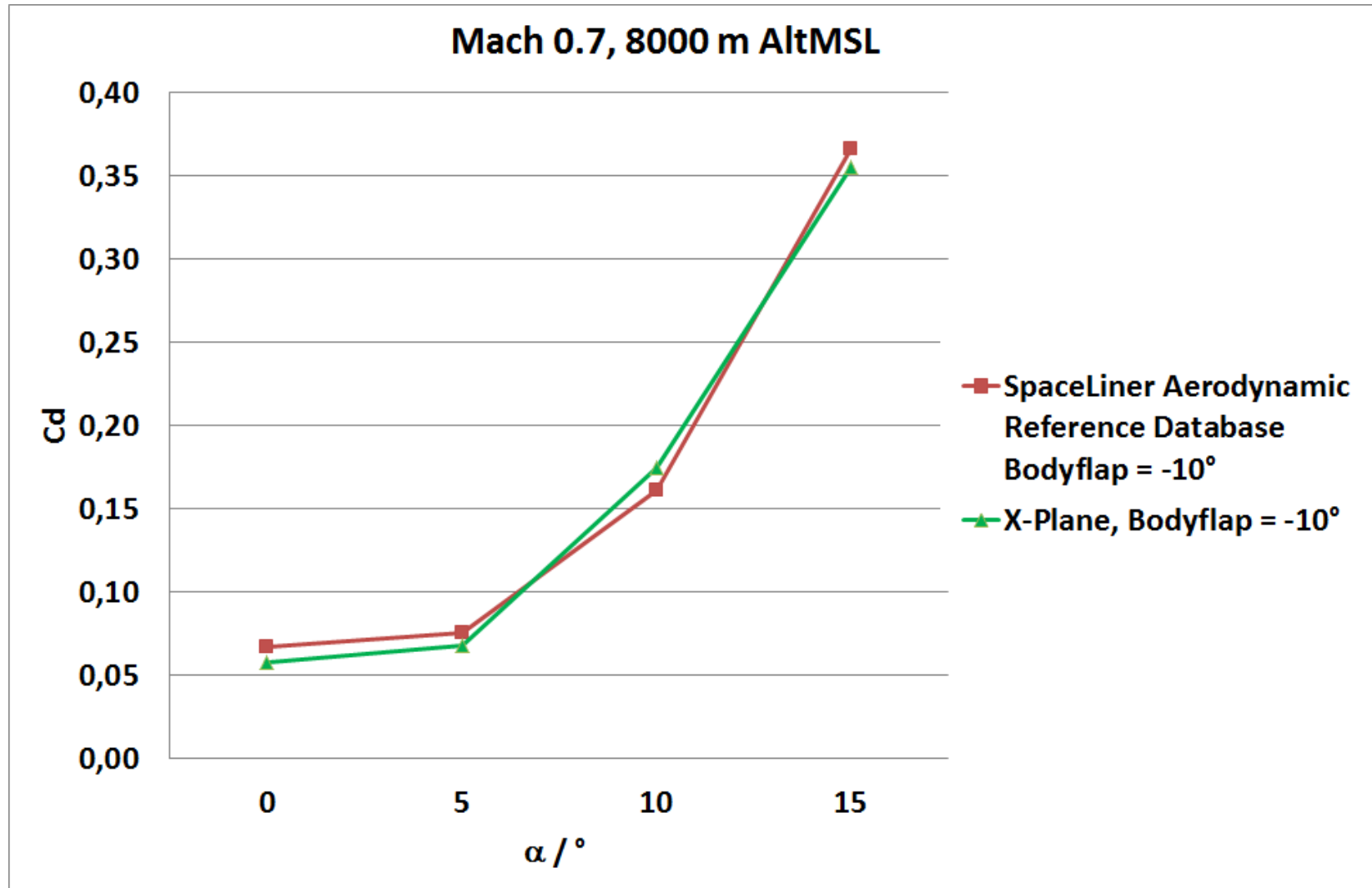
Methodology



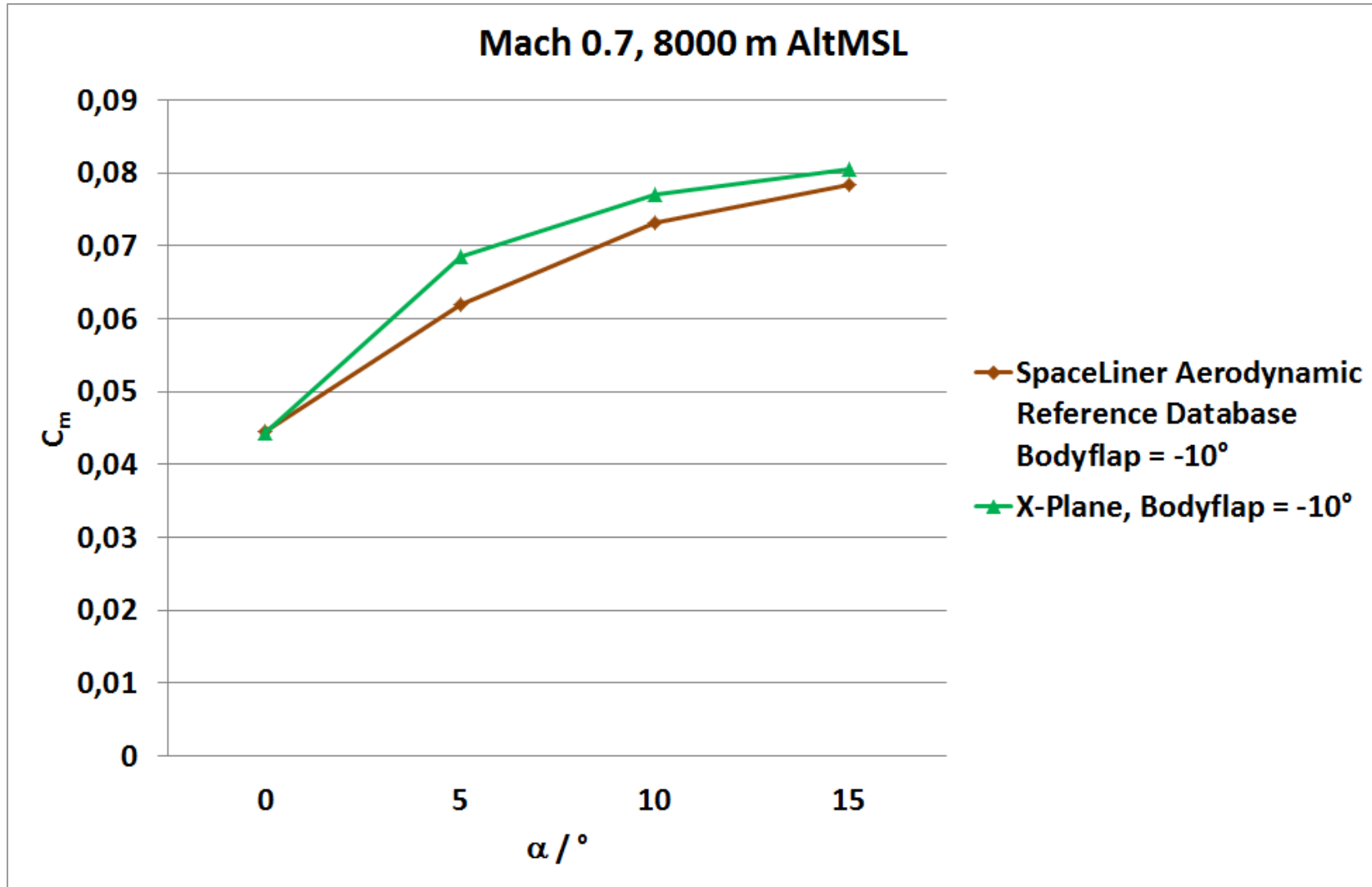
Results (flight model)



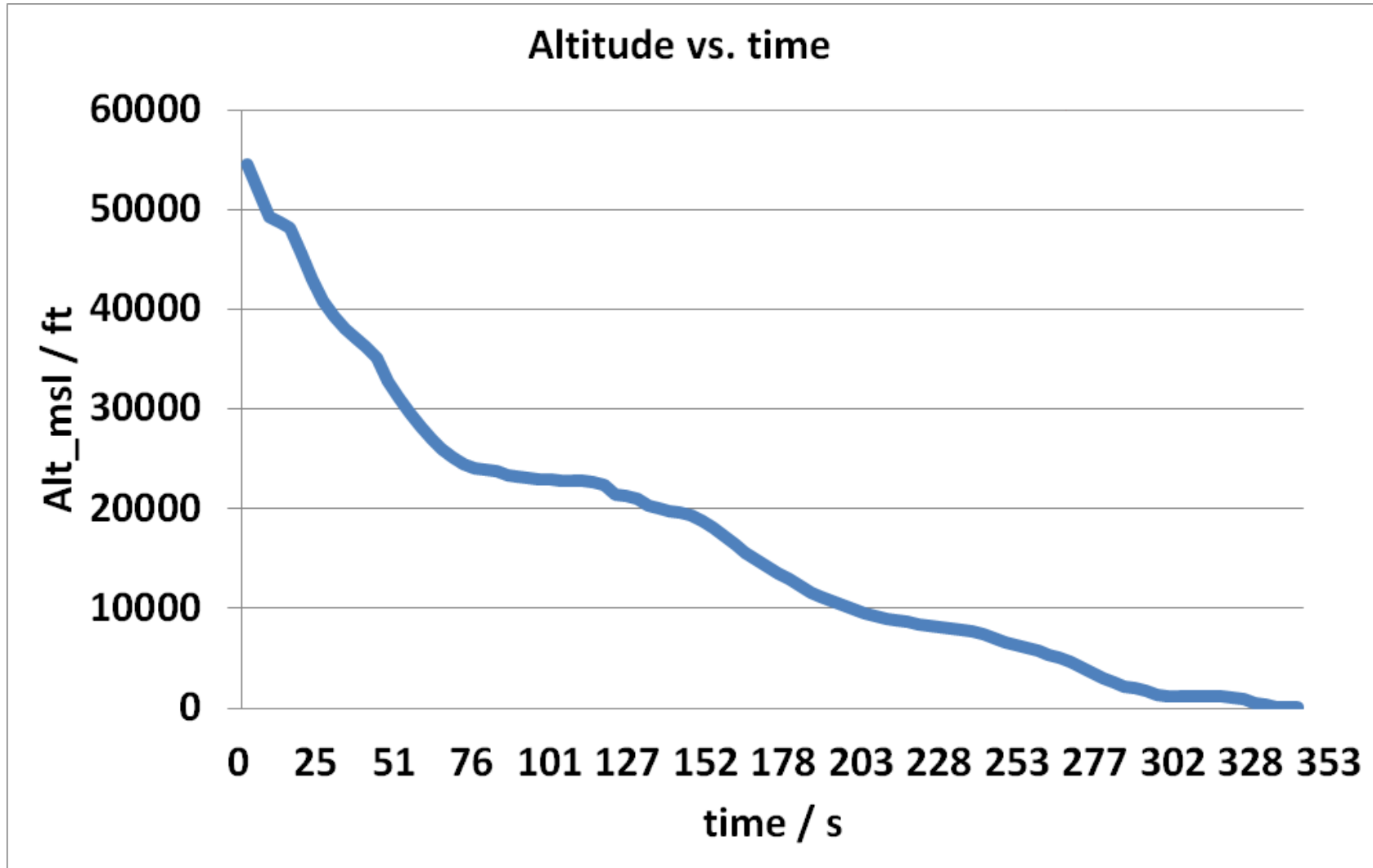
Results (flight model)



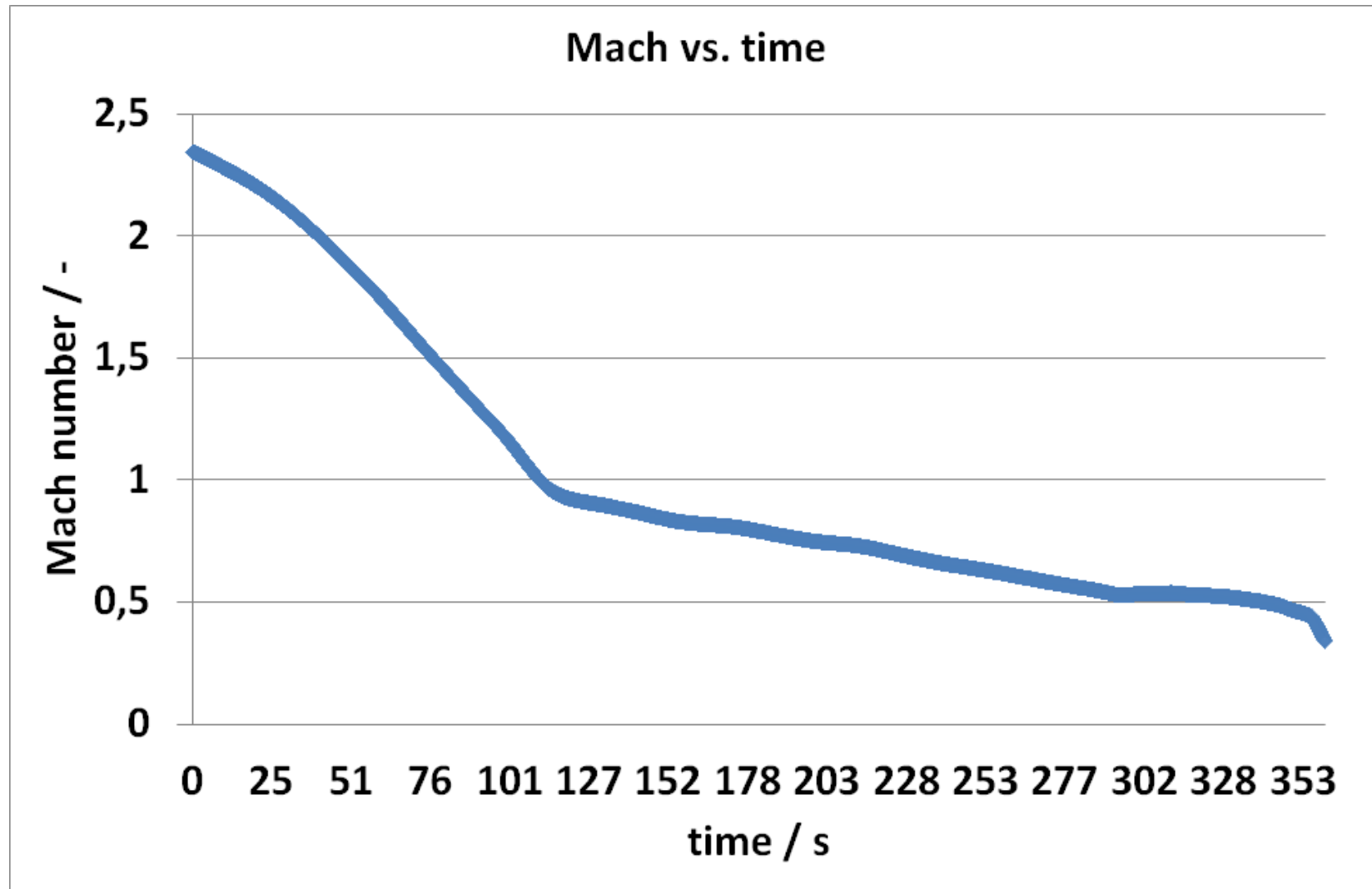
Results (flight model)



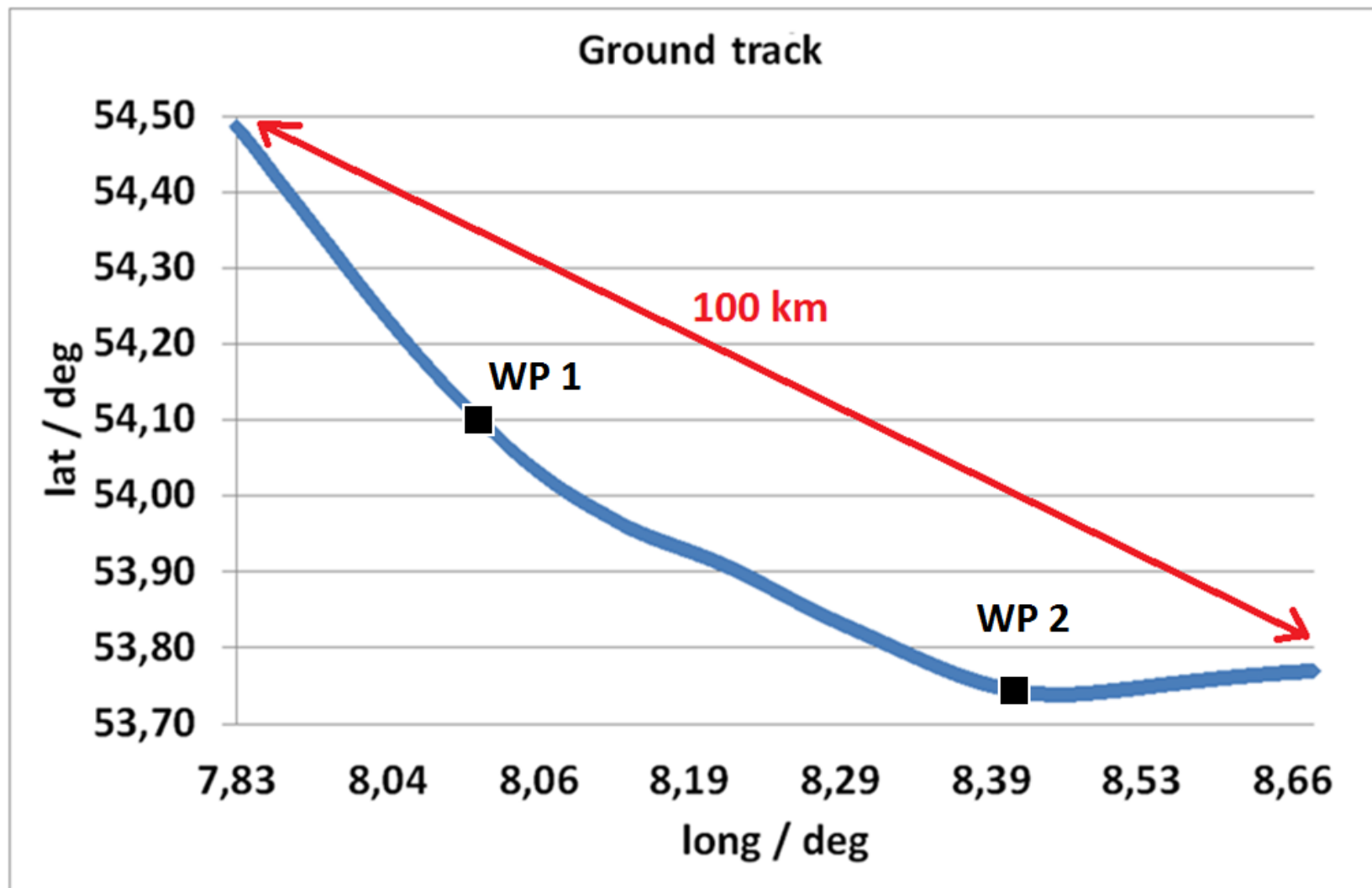
Results (simulated whole descent)



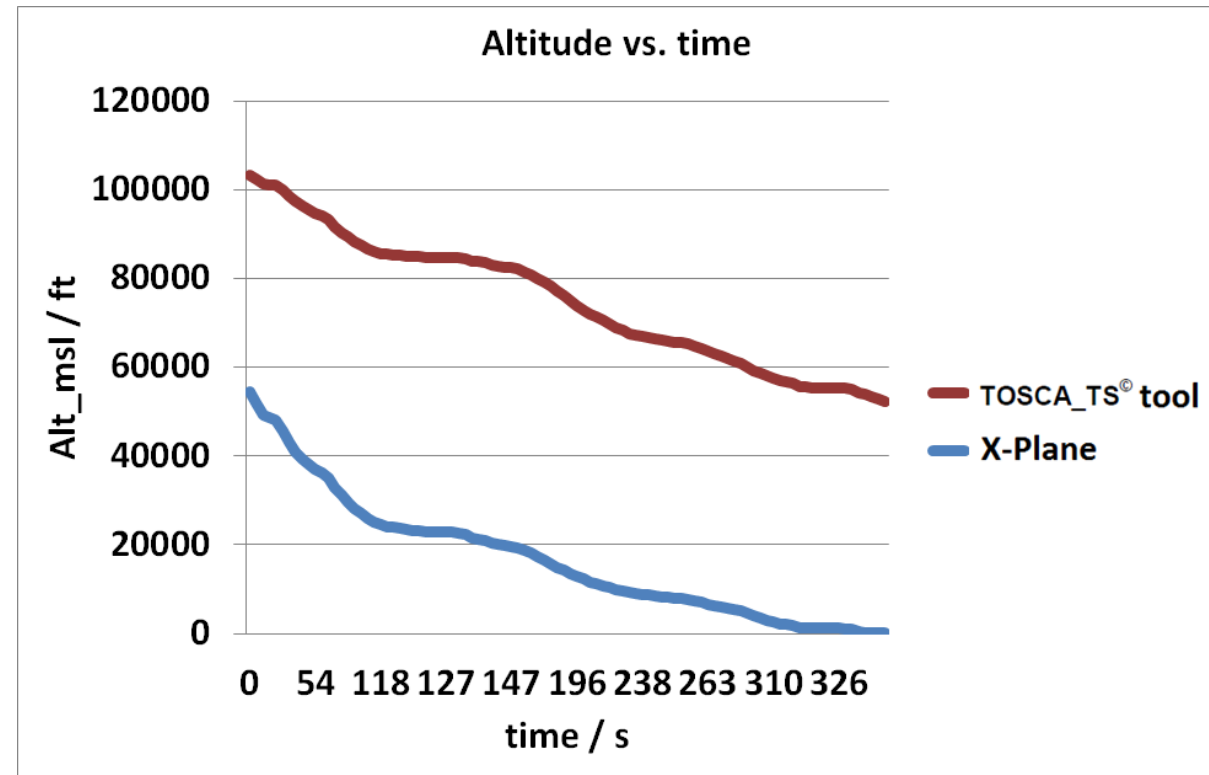
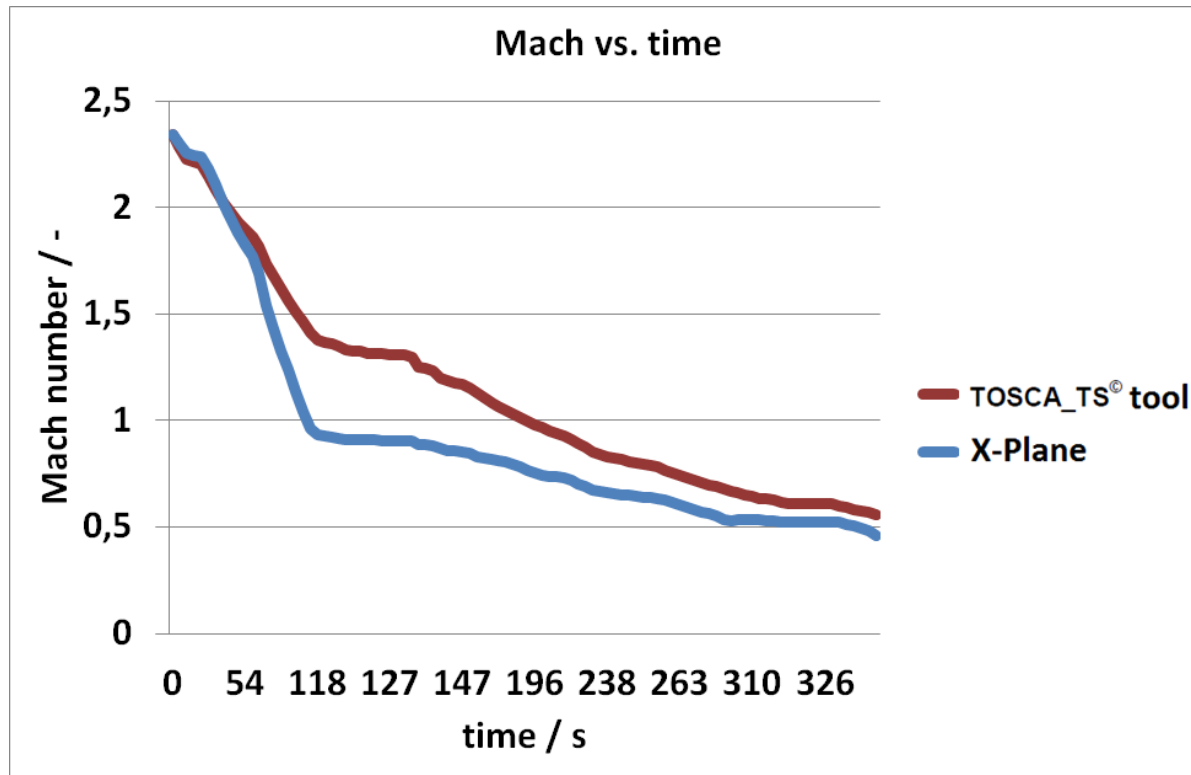
Results (simulated whole descent)



Results (simulated whole descent)



Results (simulated whole descent)

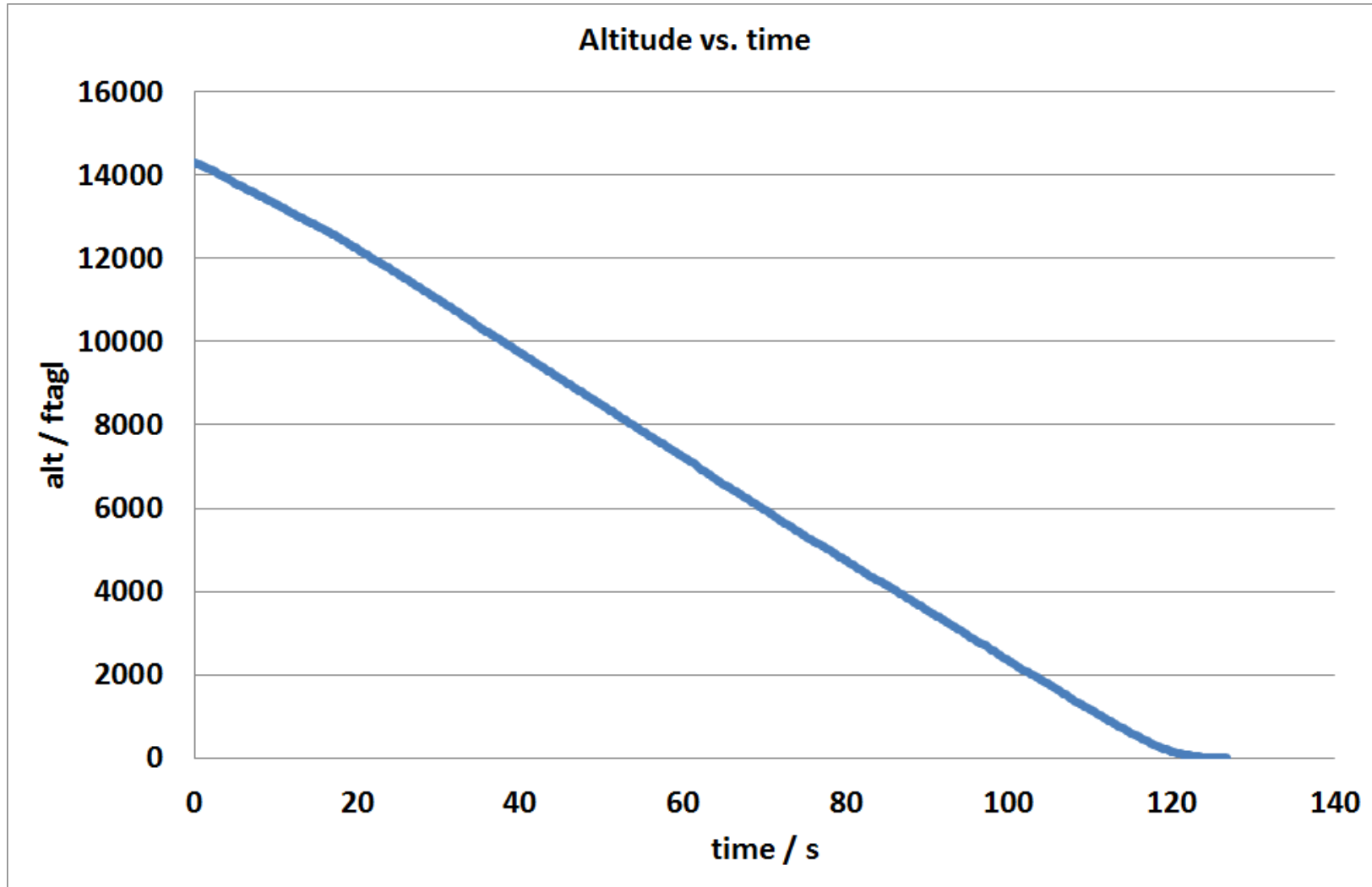


Results (simulated landing flare test)

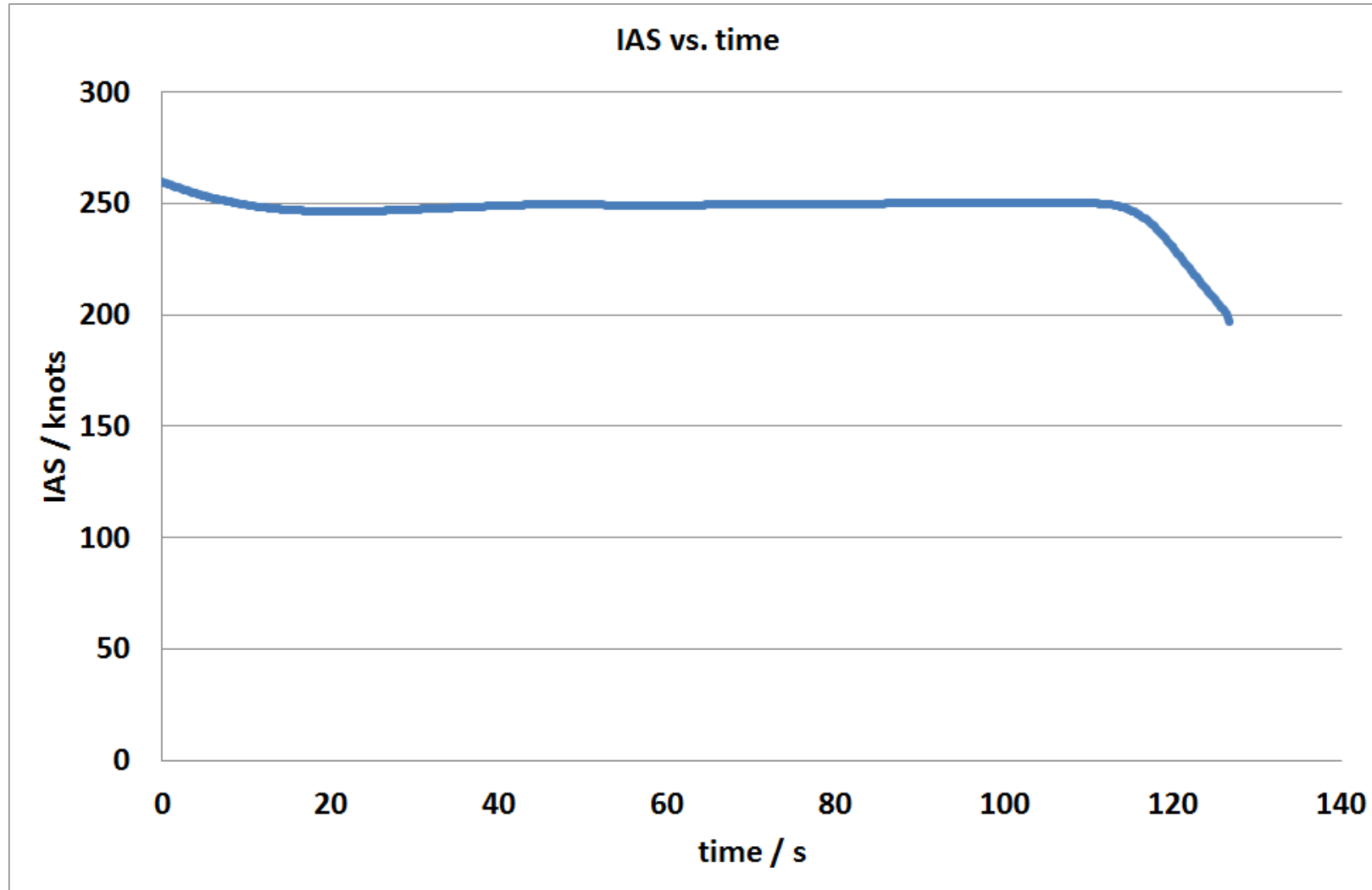
- **Initial altitude setting of 14000 ftagl**
- **Autopilot pitch mode speed with pitch setting of 250 kts**
- **Gear extraction at 10000 ftagl**
- **Flare out at 1200 ftagl with autopilot pitch mode vertical speed of 0 feet per minute**



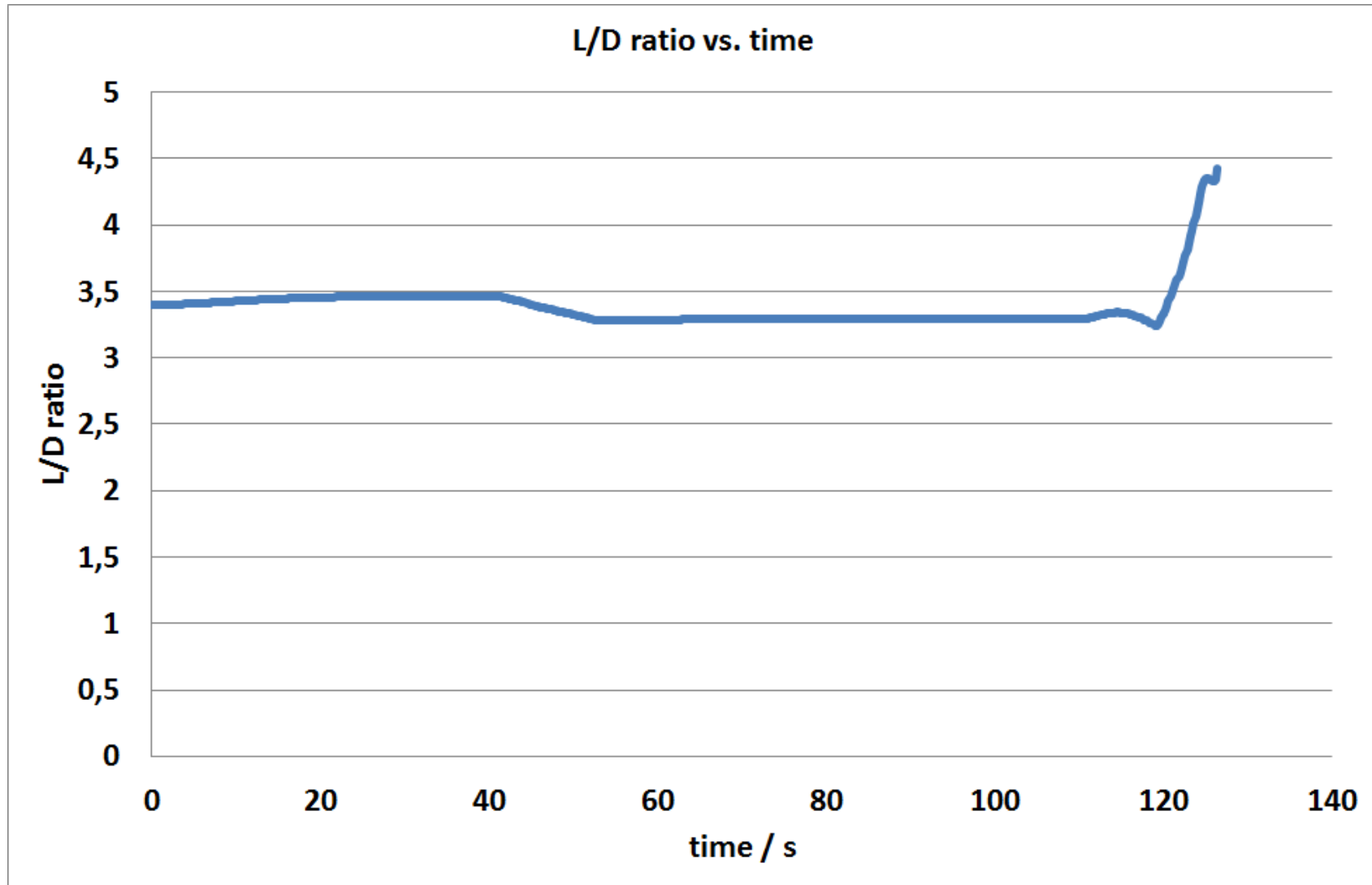
Results (simulated landing flare test)



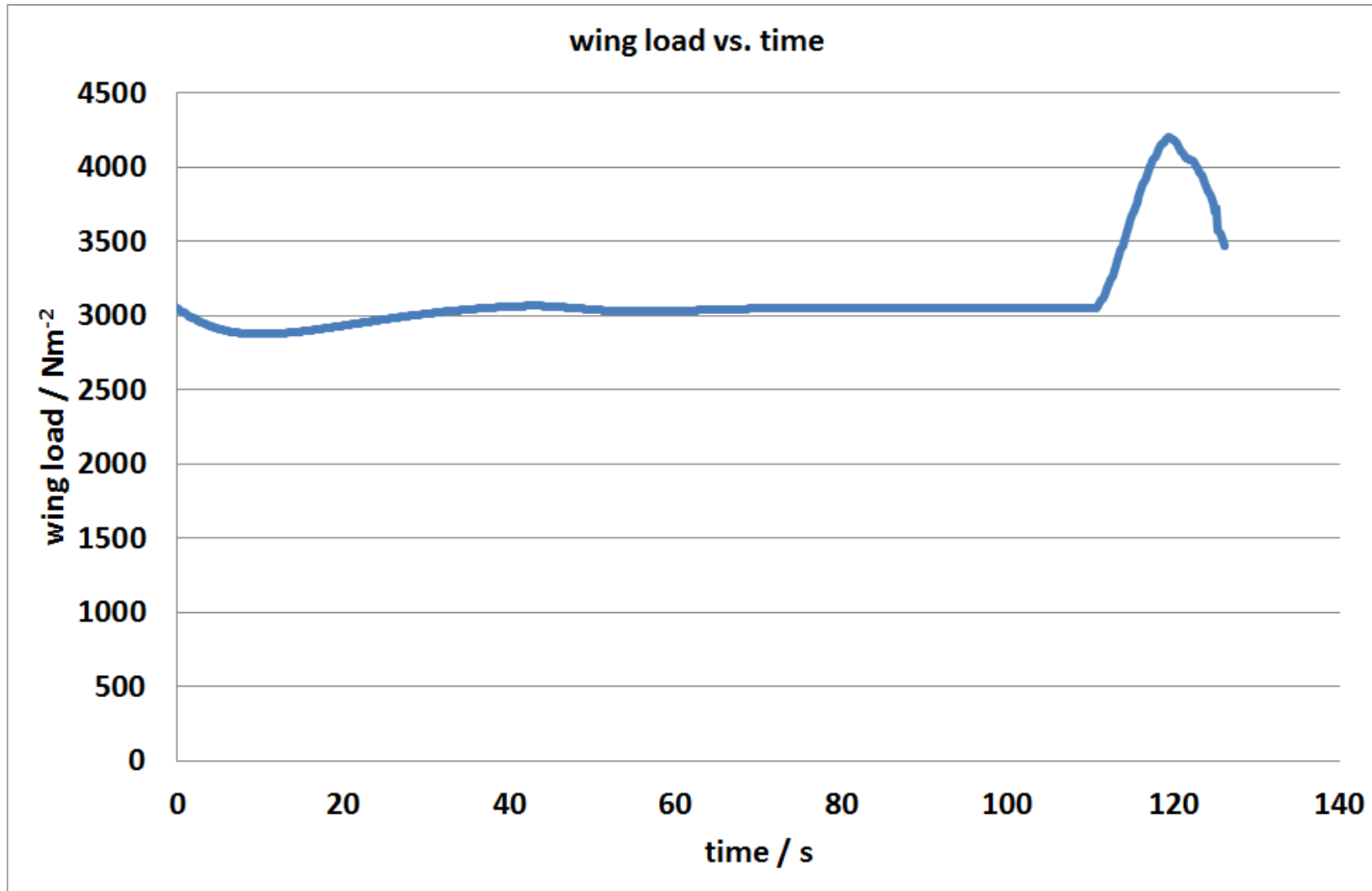
Results (simulated landing flare test)



Results (simulated landing flare test)



Results (simulated landing flare test)



Discussion & Outlook

- **Similar whole descent decline X-Plane / TOSCA with a steep, a nearly time constant and flat decrease phase**



Discussion & Outlook

- **Although compressible flow effects are considered using Prandtl-Glauert, the SpaceLiner X-Plane simulation model needs deeper investigation in its transonic and supersonic behavior, taking into account that transonic effects in X-Plane only refer to an empirical mach-divergent drag increase and the airfoil becomes an appropriate thickness ratio diamond shape under supersonic conditions.**



Discussion & Outlook

- **Smooth approach and landing with:**
 - **About 1200 ftagl flare out initiation**
 - **About 200 kts IAS**
 - **Final approach at about 250 kts**
 - **lift-to-drag ratio keeps above the acceptable value of 3.0¹**

¹P. M. Sforza, Manned Spacecraft Design Principles, 1st ed., Elsevier Aerospace Engineering Series, Elsevier, November 2015, pp. 175-176.



Discussion & Outlook

•BUT

- wing loading peak of 4200 N / m² exceeded the typical maximum values of the F-104 (mod), the X-15 and the Space Shuttle in the range of 3500 to 3800 N / m²¹

¹P. M. Sforza, Manned Spacecraft Design Principles, 1st ed., Elsevier Aerospace Engineering Series, Elsevier, November 2015, pp. 175-176.



Discussion & Outlook

- **Further simulated landing flare flight tests with smoother elevator actuator dynamics for target pitch mode vertical speed of 0 feet per minute and flare out initiation above 1200 ftagl are needed to find a setting not exceeding a wing loading peak 3800 N / m².**

