



A Fast Björck-Pereyra-type algorithm for solving Complex-Vandermonde Systems



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INTRODUCTION

Modeling phenomenon of the interpolation problems can be seen in propagation of waves, weather conditions, real-time traffic patterns, etc. There are different interpolation techniques like polynomial interpolation, spline interpolation, rational interpolation, exponential interpolation, trigonometric interpolation, etc. One can see a polynomial interpolation problem as a system of equations problem. In here, we derive a fast $O(n^2)$ Björck-Pereyra-type algorithm to solve the system of equations.

Polynomials	Paper
Monomials	Björck-Pereyra (1970)
Real Orthogonal	Higham (1988)
Chebyshev	Rachel-Opfer (1991)
Szego	Bella et al. (2007)
Quasiseparable	Bella et al. (2009)
Complex	????

METHODOLOGY

We present the most general trigonometric interpolation problems to solve complex-Vandermonde system. We derive a fast $O(n^2)$ algorithm for solving a system of equations $W\vec{a} = \vec{f}$ where the coefficient-matrix is a complex Vandermonde matrix $W = [\omega_j^k]_{j,k=0}^{n-1}$ having $\omega = e^{-ix}$ and $i^2 = -1$. This method is much more favorable than Gaussian elimination which requires $O(n^3)$ complexity. This result generalizes the classical Björck-Pereyra algorithm from monomials to complex system $\{1, \omega, \omega^2, \dots, \omega^{n-1}\}$, where nodes are taken along the unit circle. The new algorithm applies to a fairly general class to solve trigonometric interpolation problems. We present numerical experiments together with the better forward error bound than the Gaussian elimination.

Our Problem is to construct a complex polynomial

$$P(\omega) = \beta_0 + \beta_1\omega + \beta_2\omega^2 + \dots + \beta_{n-1}\omega^{n-1}$$

where, $\omega^k = e^{-ix_k}$, $x_k = \frac{2\pi k}{n}$, and $i^2 = -1$, using the given data points (ω_k, f_k) for $k = 0, 1, 2, \dots, n-1$.

One can convert the corresponding system of equations into the matrix-vector form as follows;

$$\begin{bmatrix} 1 & e^{-ix_0} & e^{-2ix_0} & \dots & e^{-(n-1)ix_0} \\ 1 & e^{-ix_1} & e^{-2ix_1} & \dots & e^{-(n-1)ix_1} \\ 1 & e^{-ix_2} & e^{-2ix_2} & \dots & e^{-(n-1)ix_2} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & e^{-ix_{n-1}} & e^{-2ix_{n-1}} & \dots & e^{-(n-1)ix_{n-1}} \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \\ \vdots \\ \beta_{n-1} \end{bmatrix} = \begin{bmatrix} f_0 \\ f_1 \\ f_2 \\ \vdots \\ f_{n-1} \end{bmatrix}$$

RESULTS

To solve the system of equations, two factorizations were found; Type 1 & Type 2. Type 1 solves the system iteratively. This is a generalization of the original 1970 Björck-Pereyra algorithm to the complex plane. Type 2 solves the system recursively. The factorization of Type 2 holds the subtraction to a single value for the calculation of lower triangular matrices. This reduces the point floating point error in the sequent calculations and even leads to more accurate algorithm.

Sparse Factorization: Type 1

$$V(\omega_{1:n})^{-1} = U_1 \cdot \begin{bmatrix} 1 & & & & \\ & V(\omega_{2:n})^{-1} & & & \\ & & \ddots & & \\ & & & \ddots & \\ & & & & 1 \end{bmatrix} \cdot \bar{L}_1$$

$$U_k = \begin{bmatrix} I_{k-1} & & & & \\ & 1 & -\omega_i & & \\ & & 1 & \ddots & \\ & & & \ddots & -\omega_i \\ & & & & 1 \end{bmatrix}$$

$$\bar{L}_k = \begin{bmatrix} I_k & & & & \\ & \frac{1}{\omega_{k+1} - \omega_1} & & & \\ & & \ddots & & \\ & & & \frac{1}{\omega_n - \omega_{n-k}} & \\ & & & & I_{k-1} \end{bmatrix} \cdot \begin{bmatrix} I_{k-1} & & & & \\ & -1 & & & \\ & & 1 & & \\ & & & \ddots & \\ & & & & -1 & 1 \end{bmatrix}$$

Sparse Factorization: Type 2

$$U_k = \begin{bmatrix} I_{k-1} & & & & \\ & 1 & -\omega_i & & \\ & & 1 & \ddots & \\ & & & \ddots & -\omega_i \\ & & & & 1 \end{bmatrix}$$

$$D_k = \begin{bmatrix} I_k & & & & \\ & \frac{1}{\omega_{k+1} - \omega_k} & & & \\ & & \ddots & & \\ & & & \frac{1}{\omega_n - \omega_k} & \\ & & & & I_{k-1} \end{bmatrix}, L_k = \begin{bmatrix} I_{k-1} & & & & \\ & 1 & & & \\ & & \ddots & & \\ & & & -1 & \\ & & & & 1 \end{bmatrix}$$

Algorithms for Type 1 and Type 2

Input: $n, f_k, x_k = \frac{-2\pi(k-1)}{n}$, for $k = 1, 2, \dots, n$ **Input:** $n, f_k, x_k = \frac{-2\pi(k-1)}{n}$, for $k = 1, 2, \dots, n$

Recursion:

for $k = 1, 2, \dots, n$

$$\beta_k = f_k$$

end

for $k = 1, 2, \dots, n-1$

for $j = n, n-1, \dots, 1$

$$\beta_j = \frac{\beta_j - \beta_{j-1}}{e^{ix_j} - e^{ix_{j-k}}}$$

end

end

for $k = n-1, n-2, \dots, 1$

for $j = k, k+1, \dots, n-1$

$$\beta_j = \beta_j - \beta_j e^{ix_k}$$

end

end

Output: β_k , for $k = 1, 2, \dots, n$

Recursion:

for $t = 1, 2, \dots, n-1$

$$u = I_n$$

for $j = t, t+1, \dots, n-1$

$$u_{(n+1)j} = -e^{ix_t}$$

end

$$U_t = u$$

$$d = I_n$$

for $j = t+1, t+2, \dots, n$

$$d_{n(j-1)+j} = \frac{1}{e^{ix_j} - e^{ix_t}}$$

end

$$D_t = d$$

$$l = I_n$$

$$l_{t+1: \text{end}, t} = -1^l$$

$$L_t = l$$

end

$$\underline{\beta} = U_1 U_2 \dots U_{n-1} D_{n-1} L_{n-1} D_{n-2} L_{n-2} \dots D_1 L_1 \underline{f}$$

Output: $\underline{\beta} = \beta_k$, for $k = 1, 2, \dots, n$

RESULTS

Forward Error Bound for Both Algorithms

$$n \geq 4, \quad u := \text{unit roundoff}$$

$$\text{For } \underline{\beta} = V^{-1} \underline{f}$$

$$\frac{\|\beta - \hat{\beta}\|_2}{\|\beta\|_2} \leq (1 - 5u)^{1-n} \|U_1\|_2 \dots \|U_{n-1}\|_2 \|D_{n-1}\|_2 \|L_{n-1}\|_2 \dots \|D_1\|_2 \|L_1\|_2$$

Numerical Results

Size	BP-Type 1	BP-Type 2	Gaussian Elimination	BP-Type 1 Ordered Leja	BP-Type 2 Ordered Leja
10×10	1.491E-06	1.843E-08	2.645E-08	1.648E-07	1.894E-08
20×20	3.876E-04	1.619E-08	2.391E-08	4.228E-07	2.445E-08
30×30	8.302E-02	7.940E-09	2.517E-08	5.560E-07	1.955E-08
35×35	3.425E+00	2.266E-08	1.733E-08	5.657E-07	2.933E-08
40×40	2.443E+02	1.338E-07	3.334E-08	1.098E-06	1.262E-08
50×50	7.089E+06	3.193E-05	1.123E-05	1.316E-06	4.034E-08
60×60	1.657E+12	1.389E-02	3.916E-04	1.708E-06	1.433E-08
70×70	9.646E+16	3.948E+00	6.277E-03	1.863E-06	2.476E-08
80×80	1.898E+21	3.533E+04	3.991E-02	3.741E-06	2.226E-08
90×90	6.079E+26	6.264E+09	1.168E-01	3.155E-06	4.361E-08
100×100	7.919E+31	9.359E+14	2.844E-01	2.604E-06	1.474E-08
105×105	6.272E+34	1.781E+17	2.624E+00	3.422E-06	1.467E-08
150×150			8.979E+00	6.321E-06	1.558E-08
200×200			3.171E+01	9.046E-06	1.840E-08
250×250			1.953E+02	1.138E-05	4.871E-08
300×300			1.087E+02	1.841E-05	2.596E-08

CONCLUSION

Results on polynomial interpolation from real to complex plane leads to:

- Fast $O(n^2)$ Algorithms
- Sparse Factorizations
- Iterative Algorithms
- Stable Algorithms with Leja Ordering
- Accurate Algorithms beyond Gaussian Elimination for $n > 100$

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