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14:NF-970302-12

STUDIES OF ANOMALOUS DISPERSION IN THE SLC SECOND ORDER ACHROMAT

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SLAC-PUB--4096

DE87 008871

Summary

Certain causes of anomalous dispersion in the second order achromats of the SLC arcs are investigated. For matched dispersion, transverse displacements of combined function magnets do not introduce anomalous dispersion. This is shown by deriving a non-dispersive condition connecting the average of the matched dispersion function with the quadrupole and ascuupole components of the field. In the SLC Arcs, however, the achromats are rolled producing a dispersion mismatch. In this case, the horizontal (vertical) dispersion is affected linearly by vertical (horizontal) displacement of magnets. The integral condition connecting the dipole and quadrupole fields and the matched dispersion is also derived. Combining this with the non-dispersive condition and the analytic expression of the matched dispersion gives two simple relationships for the fields of second order achromats constructed of combined function magnets.

The effects of the dispersion mismatch in the SLC Arcs is investigated using computer simulations. The results show that this mismatch will increase the sensitivity to transverse errors. We report the effects of certain systematic errors.

Introduction

The FODO cells of the SLC Arcs are put together to form second-order achromats.¹ Each cell is composed of two combined function magnets each having superimposed dipole, quadrupole and sextupole fields. The strength of the dipole field is the same for both magnets. The field gradients in both magnets are nearly the same but the signs are opposite. The sextupole components are different both in the signs and in the strengths.

In this lattice the matched dispersion function η , defining the deviation of the trajectory for an off-momentum particle, and its derivative η' with respect to the path length s are both periodic with a period equal to the cell length.

During the course of designing the SLC orbit correction sysism for the SLC Arcs one of us (JJM) observed² that transverse translations of the combined function magnets were effective in generating a non-dispersive orbit correction. By this is meant that the beam direction can be made to change and that this change is independent of momentum in the linear approximation. It is shown below that this effect is the result of a simple relationship between the average value of the matched dispersion function $\overline{\eta}$ and the strength of the quadrupole and sextupole components in each combined function magnet.

It has been shown³ that the integral relationship in this simple form consists of the most dominant terms contained in a more general integral expression which car. be used to define the properties of a second order achromat. In most situations, where the radius of corvature is large, the simpler form can be used to calculate sectupole strengths which agree with those obtained from TRANSPORT to within a few percent.

The demonstration of this non-dispersive effect was a key part of the decision to adopt transverse displacements of combined function magnets as the method^{4,5} of correcting the beam trajectory in the SLC Ares.

Even though the matched dispersion function is unperturbed in the linear approximation by either random or coherent displacment of magnets, it was later found⁶ that in the SLC Arcs

Work supported by the Department of Energy, contract DE-AC03-76SF00315. certain coherent displacements did indeed linearly perturb the dispersion. This observation led to several studies of systematic⁷ and random⁸ errors with the conclusion that this effect stems from the fact that the dispersion in the Arcs is not always matched (especially in the vertical plane) due to the necessity of rolling the achromats about the beam agis to follow the site terrain. We will now review these findings in simple form.

Non-Dispersive Conditic

Consider a differential slice of an Arc magnet with length do. The transverse field components can be expressed as follows,

$$B_{y} \approx B_{o} + B_{o}' x + \frac{1}{2} B_{o}'' (x^{2} - y^{2}), \qquad (1)$$

$$B_x = B'_o y + B''_o x y, \qquad (2)$$

where the coefficients B_0, B'_0 and B''_0 represent the dipole, quadrupole and sextupole strengths of the combined function magnet, respectively. Here the prime indicates differentiation with respect to transverse displacement.

Suppose at this location that there is no dispersion in the y plane and that the horizontal dispersion is equal to τ impose further that the elemental magnet is displaced from the difference axis by Δx and Δy . Then, for a momentum $p = p_a(1 + \delta)$,

$$x = \eta \delta + \Delta x, \tag{3}$$

$$y = \Delta y.$$
 (4)

With these equations inserted in Eqs. (1) and (2), the angular "kicks" $d\theta$ in horizontal and $d\phi$ in vertical planes of a ray passing through the elemental magnet may be written as follows,

$$d\theta = \frac{-ds}{p_o(1+\delta)} \left\{ \left(B_o + B'_o \eta \delta + \frac{1}{2} B''_o \eta^2 \delta^2 \right) + \left(B'_o + B'_o \eta \delta \right) \Delta z + \frac{1}{2} B''_o \left(\Delta x^2 - \Delta y^2 \right) \right\},$$
(5)

$$d\phi = \frac{ds}{p_o(1+\delta)} \left\{ (B'_o + B'_o \eta \delta) \Delta y + B'_o \Delta x \Delta y \right\}.$$
 (6)

Consider only the terms up to the linear approximation in Δx and Δy and neglect all others, then

$$d\theta \approx \frac{-ds}{p_o(1+\delta)} \left\{ B_o(1+\frac{B'_o\eta}{B_o}\delta) + B'_o(1+\frac{B''_o\eta}{B'_o}\delta) \Delta x \right\}, \quad (7)$$

$$d\phi \approx \frac{ds}{p_o(1+\delta)} B'_o(1+\frac{B'_o\eta}{B'_o}\delta) \Delta y \qquad (8)$$

Clearly, the momentum dependence in both equations will factor out if the following conditions are satisfied everywhere,

$$\frac{B_o^*\eta}{B_o} = 1$$
 and $\frac{B_o^*\eta}{B_o^*} = 1$. MASTER

Presented at the Particle Accelerator Conference, Washington, D.C., March 16-19, 1987

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Eqs. (9) cannot be satisfied at all points since within a magnet η varies while B_{σ} B'_{σ} and B''_{σ} do not. However, if η is averaged over a single Arc magnet the second equation in Eqs. (9) is satisfied, i.e.,

$$\frac{B_{o}^{n}\overline{\eta}}{B_{o}^{\prime}} \Big|_{single \ magnet} = 1 \quad . \tag{10}$$

Eq. (10) is the non-dispersive condition given in Ref. 2. This equation is satisfied by the fields of combined function magnets in second order achromats.

Eqs. (7),(8), and (10) can be used to conclude that in the linear approximation the matched dispersion function η is immune to effects due to random or purposely induced transverse displacements of single magnets in an achromat composed of combined function magnets. For the SLC Arcs a transverse displacement of 100 microns for Δz (Δy) steers a beam horizontally (vertically) with a strength equivalent to 1.2% of the dipole bending field B, making such displacements an effective method of steering. Furthermore, since this non-dispersive property applies to a single magnet such a magnet can be used to provide a non-dispersive "kick" anywhere in any lattice provided that the average value of the dispersion is not zero.

Relationship of Field Components

The first equation in Eqs. (9) is also satisfied when η is averaged over each magnet of an entire cell, i.e.,

$$\frac{B'_o \overline{\eta}}{B_o} \Big|_{\text{enture cell}} = 1 . \tag{11}$$

This is shown to follow from the definition of the η function and a general integral equation derived in Ref. 9 and which apply to a cell of an arbitrary lattice. Eqs. (10) and (11) can be used to derive relationships for the field components correct to a few percent for achromats composed of combined function magnets. These relationships are useful because for such achromats η can be integrated analytically as in Ref. 9. Using the SLC Arc cell for an example, Eqs. (10) and (11) become

$$\frac{B_{ef}^{''}\bar{\eta}_{f}}{B_{e}^{'}} = 1 \quad , \qquad \frac{B_{ef}^{''}\bar{\eta}_{f}}{B_{e}^{'}} = 1 \quad , \qquad (12)$$

and

$$\frac{|B'_{o}|}{2B_{o}}(\overline{\eta}_{F}-\overline{\eta}_{D})=1 \quad , \tag{13}$$

where the subscripts F and D refer to the focusing and defocusing magnets, respectively. Similar relationships can be written for combined function lattices of second order achromats composed of magnets with differing lengths and field components.

Effect of Mismatched Dispersion

Equations (3) and (4) are now rewritten to allow the position in the differential slice to include deviations from the matched dispersion. Let

$$\boldsymbol{x} = \Delta \boldsymbol{x} + \eta_{\boldsymbol{x}} \boldsymbol{\delta} \equiv \Delta \boldsymbol{x} + (\eta_{\boldsymbol{\theta}} + \Delta \eta_{\boldsymbol{x}}) \boldsymbol{\delta} \quad , \tag{14}$$

and

v

$$= \Delta y + \eta_v \delta \equiv \Delta y + \Delta \eta_v \delta , \qquad (15)$$

where Δx , Δy are transverse displacements, η_x , η_y are the actual dispersion functions, η_o is the matched η -function and $\Delta \eta_x$ and $\Delta \eta_y$ are the differences between the actual and matched functions.

Again, Eqs. (14) and (15) are inserted in Eqs. (1) and (2). Then retaining only terms linear in Δx and Δy , averaging the dispersion over the kligth of the moved magnet, *l*, and separating the remaining terms in dispersive and non-dispersive groups, one finds

$$\Delta \theta \approx \frac{-i}{p_{e}(1+\delta)} \left\{ \left(B_{e}^{i} + B_{\rho}^{i} \bar{\eta}_{e} \delta \right) \Delta x - B_{\phi}^{*} \delta \left(\bar{\Delta} \bar{\eta}_{x} \Delta x - \bar{\Delta} \bar{\eta}_{y} \Delta y \right) \right\}$$
(16)
$$\Delta \phi \approx \frac{i}{p_{e}(1+\delta)} \left\{ \left(B_{o}^{i} + B_{o}^{*} \bar{\eta}_{o} \delta \right) \Delta y + B_{o}^{*} \delta \left(\bar{\Delta} \bar{\eta}_{x} \Delta y + \bar{\Delta} \bar{\eta}_{y} \Delta x \right) \right\}$$
(17)

Inserting Eq. (10) and taking the derivative with respect to δ at the point $\delta = 0$, the anomalous $\Delta \eta'$, for z and y planes, respectively, become

$$\Delta \eta'_{z} = \frac{-B_{e}^{h}l}{p_{e}} \left(\overline{\Delta \eta}_{z} \Delta x - \overline{\Delta \eta}_{y} \Delta y \right)$$
(18)

$$\Delta \eta'_{y} = \frac{B''_{pl}}{p_{p}} \left(\overline{\Delta \eta}_{x} \Delta y + \overline{\Delta \eta}_{y} \Delta x \right)$$
(19)

These equations show that in the presence of a magnet misalignment a deviation of the dispersion from that of the matched dispersion will generate an anomalous $\eta'_{x,y}$. This is important to the SLC Arcs in that the dispersion is not always matched due to the required rolls. The consequence is that the Arcs are more sensitive to misalignment than if they had been constructed flat. For a typical 10° roll as in the Arcs, $\overline{\Delta \eta}_x$ is small compared to $\overline{\Delta \eta}_y$ so the main contribution to both $\Delta \eta'_{x,y}$ comes from the terms proportional to $\overline{\Delta \eta}_y$. That means that $\Delta \eta'_x$ is produced by a vertical displacement Δy and vice versa. On the other hand, for the whole Arc the accumulated error in $\overline{\Delta \eta}_y$ becomes large and both terms in Eqs. (18) and (19) are significant.

Computer Simulations

The predictions for the behavior of anomalous dispersion given in Eqs. (18) and (19) have been compared with computer simulations of both rolled and not rolled achromats. For the displacement of a single magnet, the results are in good agreement. That is, for an unrolled achromat (matched dispersion) there is no effect, whereas for a rolled achromat, the induced anomalous dispersion, as calculated using Eqs. (18) and (19), agree quantitatively with the simulation results. This agreement was confirmed for several magnets located at arbitrary points where the mismatched dispersion was either large or small in magnitude.

Systematic Translations of Magnets

With agreement established for simple cases, computer simulations were now used to investigate the effects of systematic errors in whole achromats and finally for the entire north arc.

Systematic translations of magnets in the arcs can have many causes; here we will examine two particular ones. In the arcs there is a one-to-one correspondence between magnet movers (steering correctors) and beam position monitors (BPM's). In this scheme each focusing magnet is moved horizontally (vertically) to steer the beam through the BPM₂ (BPM₂) attached to the next focusing (defocusing) magnet. This scheme utilizes 10 correctors and 10 monitors in the horizontal plane and 10 correctors and 10 monitors in the vertical plane per achromat. The position monitors are placed in the drifts between magnets. Thus the matched dispersion has the same magnitude ($\eta_{BPM} \sim 35$ mm) at all BPM's. Therefore, either a) a systematic error in BPM_x alignment or signal processing or b) steering a beam which has the wrong energy with respect to the arc excitation will cause a systematic offset of all horizontally focusing magnets. A systematic BPM_y error will do the same in the vertical plane. Fortunately, these systematics will show up in the harmonic analysis of the magnet mover positions and, in principle, is correctable for magnitudes greater than ~ 30 microns. Steering an off-momentum beam with $\frac{\Delta P}{P} = 10^{-3}$ will induce a systematic error in the magnet positions of 28 microns which is just detertable.

In Figures 1 and 2 $\Delta \eta_z$ is shown versus a systematic misalignment of BPM_x's or relative momentum error. Here, $\Delta \eta_z \approx \eta_z - \eta_z$ where $\eta_c \simeq 47$ mm at the end of the north arc.



Fig. 1. Error in η_2 when beam is steered with a Horizontal displacement at entrance of each focusing magnet in north Arc.

In Figure 1, each BPM_z is offset by the same amount and the art steering algorithm applied. Because of the one-to-one correspondence between each BPM_z and the upstream magnet mover a systematic translation is introduced at every horizontally focusing magnet. A systematic offset of 100 microns at the BPM_z's will cause an equivalent offset of \sim 80 microns at each horizontally focusing magnet. This same relationship holds for the vertical plane. It can be seen in Figure 1 that a systematic displacement of this magnitude will cause a 50 - 80% change in the horizontal dispersion function η_z at the end of the north arc.

Next, it can be seen that the results shown in Figure 2 are similar to those shown in Figure 1. Here a beam of the wrong momentum with respect to the arc excitation was steered through the system. In this case, prior to the application of the steering algorithm, the centroid of the beam would have the same offset at each BPM₂. The action of forcing this centroid offset to become zero at each BPM₂ again introduces a systematic offset of the horizontally focusing magnets. Thus steering a beam with a relative momentum error of 3×10^{-3} is equivalent to a systematic zeror of ~ 100 microns at the BPM₂'s. The vertical dispersion η_p is affected nonlinearly in both of the above cases, changing by ~ 12mm (compared to its nominal value of zero) for a BPM₄ offset of 100 microns.

A systematic error in the position of the vertical BPM_y's will also cause dispersion changes but at a level reduced by an order of magnitude.

Conclusion

In the linear approximation the matched dispersion function is not affected by random or coherent displacements of magnets in a second order achromat made up of combined function magnets. For the SLC Ares the necessity of rolling the achromats has caused a dispersion mismatch which has increased the sensitivity to transverse errors. In particular, the increased sensitivity to systematic errors will require close attention to these errors in component alignment and signal processing electronics for both the beam position monitors and the orbit correcting magnet movers.



Fig. 2. Error in η_x when off momentum beam is steered through the north Arc.

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