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National Seismic Stations Transducers and Filters

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January 13, 1981

 Lawrence
Livermore
National
Laboratory

 **Test Ban Treaty Verification Program**

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National Seismic Stations Transducers and Filters

ABSTRACT

The National Seismic Stations (NSS) instruments are being developed for seismic monitoring of regional and teleseismic events. They consist of two 3-component, broad-band, borehole seismometers: the KS-36000 and the S-700, which is the backup for the KS-36000. Output is divided into frequency bands to reduce data loss due to saturation.

Complete block diagrams of the KS-36000 and S-700 NSS seismometers and filters are presented. Both open-loop and closed-loop steady-state amplitude and phase curves are given. Without band-pass filters (but with shaping filters) the KS-36000 has a flat (i.e., between the -3 dB points) velocity sensitivity from 0.03 to 23 Hz. With its shaping filters, the S-700 is flat from 0.2 to 40 Hz. The structure of the three band-pass filters (LP, MP, and SP) is superimposed on these velocity sensitivities. Passbands of the resulting overall velocity sensitivity for the KS-36000 are as follows: LP band = 0.01-0.05 Hz, MP band = 0.02-1.3 Hz, and SP band = 1-10 Hz. Step-function responses and phase and group delays are given for each of the bands. The MP-band step response is oscillatory due to its sharp, high-frequency cutoff. An MP-band filter with a less abrupt cutoff eliminates the oscillation.

To generate typical NSS output seismograms, velocity inputs from 1000 representative seismic events were used: an underground nuclear test ($\Delta \approx 3.6$), a regional earthquake ($\Delta \approx 20$), a local earthquake ($\Delta \approx 45$), and a teleseismic earthquake ($\Delta \approx 23$). The velocity inputs for these events were obtained from the LINDA digital seismic network (DSS) around the Nevada Test Site (NTS). The seismograms resulting from each of the bands were satisfactory, although the low-frequency portion of the MP-band seismogram increased in frequency to 0.08 Hz.

The S-700 with an open-loop resonant frequency of 2.5 Hz, will not meet the 1 Hz specification at 1 Hz. We therefore recommend that the S-700 be replaced by a conventional short period seismometer, such as the Mark Products S-14.

CHAPTER 1: INTRODUCTION

National Seismic Stations (NSS) instruments are being developed for seismic monitoring of regional and teleseismic events. They consist of two 3-component, broad-band, borehole seismometers: the KS-36000 and the S-700, which is the backup for the KS-36000. Output is divided into frequency bands to reduce data loss due to saturation. Complete block diagrams of the KS-36000 and S-700 NSS seismometers and filters are presented. Both open-loop and closed-loop steady-state amplitude and phase curves are given. Without band-pass filters (but with shaping filters) the KS-36000 has a flat (i.e., between the -3 dB points) velocity sensitivity from 0.03 to 23 Hz. With its shaping filters, the S-700 is flat from 0.2 to 40 Hz. The structure of the three band-pass filters (LP, MP, and SP) is superimposed on these velocity sensitivities. Passbands of the resulting overall velocity sensitivity for the KS-36000 are as follows: LP band = 0.01-0.05 Hz, MP band = 0.02-1.3 Hz, and SP band = 1-10 Hz. Step-function responses and phase and group delays are given for each of the bands. The MP-band step response is oscillatory due to its sharp, high-frequency cutoff. An MP-band filter with a less abrupt cutoff eliminates the oscillation.

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in boreholes to reduce seismic noise. Three components are used because they greatly increase the ability to identify particular wave types.

This report presents the steady-state sinusoidal and dynamic responses of both NSS seismometers. The block diagram of each instrument and filter is given, and corresponding analytic transfer functions are contained in the Appendices.

Both open- and closed-loop frequency responses are plotted for the two transducers. Overall (including filters) velocity sensitivity* (VS) curves together with phase and group delays are also presented.

The dynamic response of each seismometer and filter combination is shown both by its response to a

step function in velocity and its response to seismic inputs. Representative seismic inputs are velocitygrams of local, regional, and teleseismic events as recorded by the LLNL digital seismic network.

Data for these computations were taken from the August 11, 1979 and February 27, 1980 informal reports of H. B. Durham (Sandia): "NSS-Model II, Seismic Data System Response Functions." Transfer functions for the S-700 were taken from the latter report and those for the KS-36000 from the former; therefore the responses for the KS-36000 are slightly, but not significantly, different from the current version.

CHAPTER 2: THE KS-36000

OVERALL BLOCK DIAGRAM

The overall block diagram for the KS-36000 is shown in Fig. 1. The transducer itself is block H_1 , which is further broken down into its internal feed

*The velocity sensitivity of a seismometer is the magnitude of its output velocity signal divided by the input ground velocity.

back loop. Transfer functions for H_1 , H_3 , H_B , and K_1 are given in Appendix A. H_1 is followed by the Long Period (LP) and Mid Period (MP) shaping filter, H_{S1} , and the Short Period (SP) shaping filter H_{S2} . Transfer functions for H_{S1} and H_{S2} are also given in Appendix A. The two shaping filters feed into the

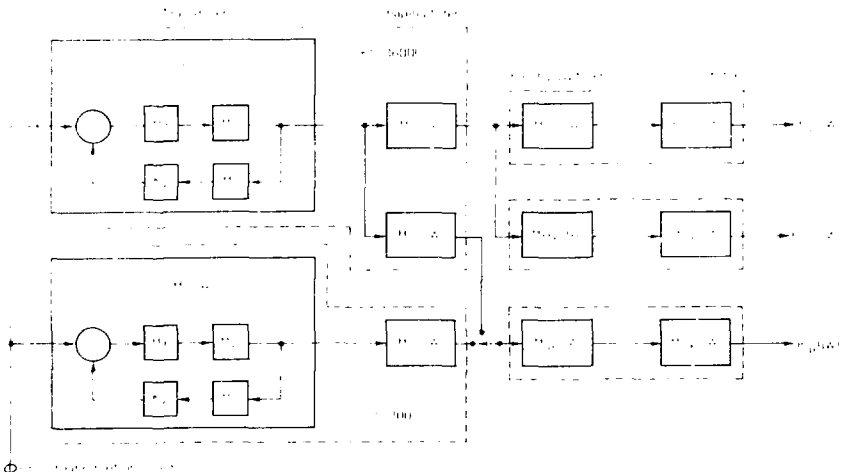


FIG. 1. Overall block diagram for NSS seismographs showing feedback loops for the transducers, shaping filters, band-pass filters, and common filters.

three major band-pass filters H_{LP} , H_{MP} , and H_{SP} which, in turn, are followed by the three common filters, H_{CF} . Transfer functions for the band-pass and common filters are listed in Appendix B.

TRANSDUCER CHARACTERISTICS

The open-loop frequency-response curve, $H_T H_A H_V K_F$, is given in Fig. 2. The peak at approximately 0.2 Hz is due to the resonance of the lightly damped ($\xi = 0.01417$) spring-mass system of the seismometer itself. The closed-loop acceleration response which is flat out to 23 Hz (-3dB) with a corner frequency at approximately 30 Hz is shown in Fig. 3.

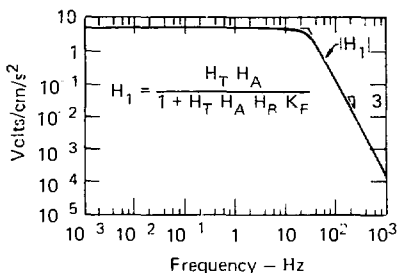


FIG. 3. KS-36000 closed loop acceleration response is flat to 23 Hz.

SHAPING FILTERS

Figures 4 and 5 show the frequency response of the two shaping filters, H_{S1} and H_{S2} . The purpose of H_{S1} is to cause the VS curve of H_1 to fall off as $\sim f^3$ at frequencies below 0.01 Hz. (Without H_{S1} , it would fall off as f .) The resulting overall VS curve for the transducer ($H_1 H_{S1}$) is shown in Fig. 6. It rises with a +3 slope (corresponding to f^3) below its low-frequency corner at 0.0105 Hz ($= 1.95$ sec). It is then flat out to approximately 20 Hz where it falls off with a -4 slope. The frequency response of LP and MP hands will be superimposed on this curve to obtain the overall VS curves for the KS-36000.

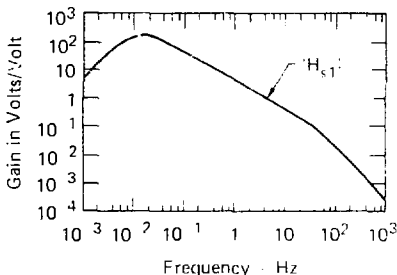


FIG. 4. Shaping filter, H_{S1} , frequency response.

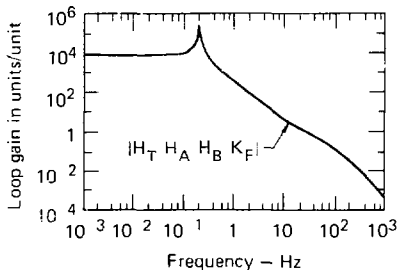


FIG. 2. KS-36000 open-loop frequency-response curve peaks at approximately 0.2 Hz due to mechanical resonance of the pendulum.

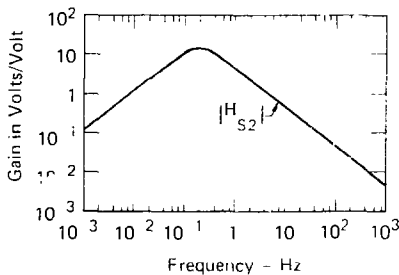


FIG. 5. Shaping filter, H_{S2} , frequency response.

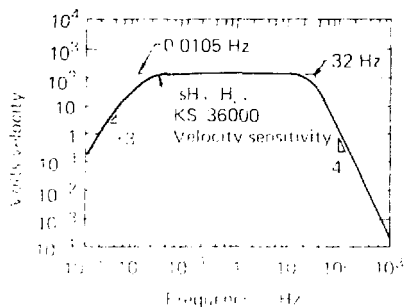


FIG. 6. KS-36000 velocity sensitivity without band filters for LP and MP bands.

Figure 6 shows that the 10^3 V/Hz sensitivity of the KS-36000 is maintained by the AS for the SP band. The HC is plotted in Figure 7, which shows a slope of only -20 dB/decade for frequencies above the upper LP pass frequency of 30 Hz. SP pass

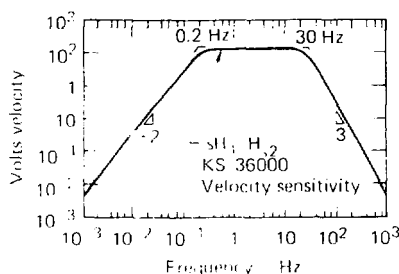


FIG. 7. KS-36000 velocity sensitivity without band filters for SP band.

band sensitivity will be imposed on this response to obtain the overall SPAS.

To summarize, the two important curves are those of Figs. 6 and 7 which characterize the AS of the KS-36000.

CHAPTER 3: THE S-700

The overall characteristics of the S-700 seismometer are shown in Figure 8. The transfer function $H_s(f)$ is $H_s(f) = H_p(f)H_c(f)H_{sp}(f)H_k(f)$, which is the same form as that for the KS-36000. The components for H_p , H_c , H_{sp} , and H_k for the S-700 are shown in Appendix A. The response of the S-700 to the seismic response is the product of the S-700 transfer function and the seismic response. The difference between the S-700 and the KS-36000, besides the different HC and HC_{sp} (a high-pass section), is the integration of outputs, resulting in an approximate

30 Hz. The peak shape of the velocity response of Fig. 9 is corrected by the addition of the shunting filter H_c shown in Fig. 10. The resulting overall AS for the S-700 is plotted in Figure 11, which is only 0.2 to 30 Hz. When compared to the S-700 response will generally extend to about 100 Hz, which is very much dependent on the magnitude of the seismic noise in that region. The characteristics of the SP filter will be combined with this response to develop the overall AS for the S-700 as seen through the SP filter. The overall LP or MP will be for the S-700.

CHAPTER 4: BAND-PASS FILTER CHARACTERISTICS

As we show in the NSS block diagram, outputs of the KS-36000 and the S-700 are shaped by passbands. Then, through the three band-pass filters LP, MP, and SP. Before describing these filters in detail it is worthwhile to review some general characteristics of filter types used in the NSS.

PROPERTIES OF BAND-PASS FILTERS

Filters discussed in this section are all of the four-pass type. They are described in terms of some

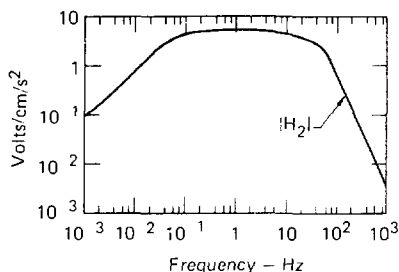


FIG. 8. S-700 closed-loop acceleration response.

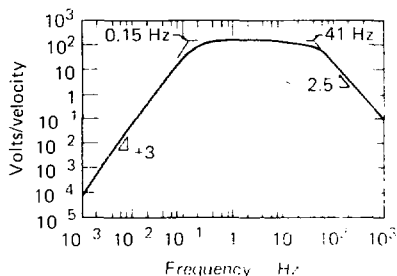


FIG. 11. Overall velocity sensitivity for S-700.

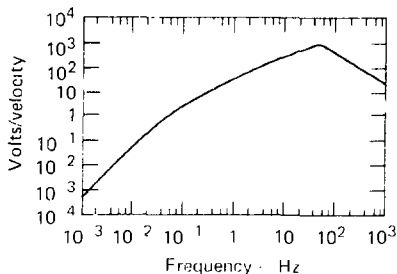


FIG. 9. S-700 closed-loop velocity response.

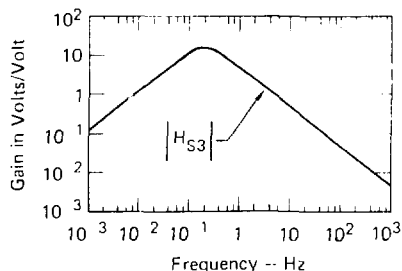


FIG. 10. Shaping filter, H_{S3} for S-700.

combination of their transfer function, frequency and phase response, and step-tangent response.

Some general properties of narrow-pass filters are as follows:

1. The sharper the filter corner, the greater the tendency for ringing in its step-tangent response.

2. In general, for broad band-pass filters the rise time of the step-tangent response is determined by the high-frequency corner and the decay time by the low-frequency corner.

3. The more the phase response of a filter as the frequency departs from a linear relationship, the greater the phase distortion or dispersion results.

4. In general, the narrower the pass-band, the higher the Q factor, greater the selectivity of the filter to noise.

TYPES OF CLASSICAL ANALOG FILTERS

Three types of analog filters most often used as seismic filters are as follows:

1. Simple filters. All poles and zeroes are on the negative real axis of the s plane, where $s = \sigma + j\omega$. A critically damped or overdamped second order filter could be considered to be a second order simple filter.

2. Butterworth filters. All poles are on a constant semicircle in the left half of the s plane. The amplitude spectrum is very flat and has a relatively sharp corner.

*The order of the filter is the number of poles and zeroes describing the filter.

TABLE 1. Summary of simple, Butterworth, and Bessel filter characteristics.

	Simple filter	Butterworth filter	Bessel filter
Shape of spectral amplitude response	Moderately flat, moderately rounded corner	Very flat, sharp corner	Very sloping, very rounded corner
Overshoot in step response	None	Moderate	Very little
Phase distortion	Moderate	Quite a bit	Least

3. Bessel filters. These filters tend to approximate a linear phase response and thus exhibit minimum phase distortion or dispersion. The amplitude spectrum is quite sloped with a very rounded corner.

Based on the above descriptions, the simple filter can be regarded as midway between the Butterworth and the Bessel filter.

A fourth type of filter, the Chebyshev, is not used as frequently in seismic instruments because its amplitude spectrum is not smooth and its step response has a large overshoot.

Table 1 shows that one of the filters exhibits all three desirable qualities of a near-rectangular passband, no overshoot in step response, and near linear phase. From the viewpoint of selectively rejecting noise in a stop band and passing signal in another, a near-rectangular passband (Butterworth filter) is desirable. But with regard to deconvolving seismic data, freedom from overshoot and dispersion is important. It is also desirable to minimize the number of poles to reduce the phase distortion. These tradeoffs will be referred to again when discussing the details of the NSS technology.

CHAPTER 5: NSS BAND-PASS FILTERS

BAND FILTERS

To lessen the chances of saturation of the electronics during large seismic events, it is desirable to split up the KS-30000 and S-700 output into bands. For example, if there were only one band (a so-called broadband system), the large amplitude surface waves generated by a major, remote earthquake could cause saturation of the electronics and loss of all signals during the period of the saturation. By breaking the output into bands, presumably only the LP band would experience electronic saturation, although mechanical or electrical saturation of the transducer would spoil the data in all three bands.

SANDIA FILTERS

Amplitude spectra of LP, MP, and SP filters proposed by Durham of Sandia (top of) are shown

in Fig. 12 and their transfer functions are given in Appendix B.

The LP band (label: LP) is essentially the same as that of the SRC. It consists of a 2nd-order,

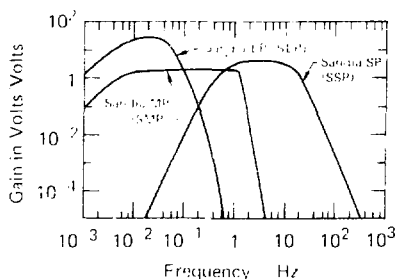


FIG. 12. Sandia LP, MP, and SP band filter amplitude spectra.

simple high-pass section at 0.005 Hz followed by a series of low-pass sections which result in a 12th-order rolloff (slope of -12). The result is the narrow LP band shown in Fig. 12, which is centered on 0.02 Hz ($\tau = 1/50$ sec).

The MP band is a broad, flat band running from approximately 0.02 to 1.3 Hz bracketing the microseism band. It begins at low frequencies with the same 2nd-order simple high-pass section at 0.005 Hz as the LP filter. This is followed by a sharply breaking 19th-order Butterworth low-pass filter at 1.3 Hz. These features are followed by simple low-pass filters at 10 and 100 Hz. Since the high-pass section is 2nd order and the low-pass section is 19th order (total 19 Hz), the result is the broad, flat band curve labeled SMP in Fig. 12.

The SP band is also approximately 1 to 10 Hz. It consists of a 2nd-order simple high-pass section at 0.4 Hz followed by a 2nd-order Butterworth low-pass filter at 10 Hz and a high-frequency section. The high-frequency section is a symmetrical SP band centered at 4 Hz and is classed as SSP in Fig. 12.

As shown in the NSS Section, the bandpass transfer functions for the LP, MP, and SP are all based on the KS-36000 AS and the common filter. The frequency response curves shown in Fig. 2 include the effects of the Butterworth low-pass high-frequency filter with corner frequencies of 100 and 200 Hz. The effects of the high-pass corner frequencies are negligible at the frequencies of interest. Appendix B of Fig. 12 shows the transfer functions for the result

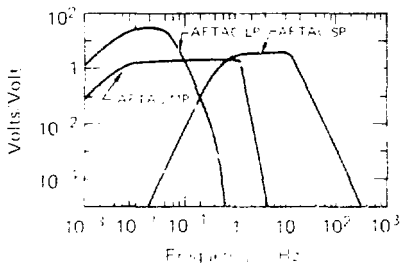


FIG. 13 AFTAC LP, MP, and SP band filter amplitude spectra.

disposing of the SP filter at 4 Hz. The transfer functions for the sandia filters are given in Appendix C of the manual of the system.

AFTAC FILTERS

AFTAC consists of three band-pass filters which are shown in Fig. 13. The filters are referred to as AFTAC LP, MP, and SP. The Sandia filter is a simple Butterworth SP bandpass (4 Hz) and Butterworth LP filter section at upper and lower frequencies. The SP filter is a Butterworth bandpass filter with a center frequency of 4 Hz. Appendix C of the manual of the system gives the transfer functions for the AFTAC filters and the transfer functions for the sandia filters.

CHAPTER 6: NSS OVERALL RESPONSES INCLUDING TRANSDUCERS AND BAND-PASS FILTERS

It is necessary to consider the details of the measurement of the series of responses of the transducer and the transfer functions of the transducer. For example, the KS-36000 AS and the LP and MP bands given in Fig. 5. SHE, H₁, is a composite of the LP and MP band transfer functions shown in Fig. 12 (SHE₁) and is to be read as over an AS. The SPAS, SHE, H₂, of Fig. 7 is multiplied by the SP transfer function also shown in Fig. 12. The overall AS relates to the acceleration into the transducer to volts out of the common filter, H₁, which is the first filter in each of the band-pass filters.

Although each of the band filters has an absolute gain associated with it, this discussion is not

concerned with the absolute gain of the NSS system. However, the relative gain of the NSS system is of interest.

PROPERTIES OF THE KS-36000 WITH SANDIA FILTERS

Velocity Sensitivity

The magnitude spectra of the resulting overall KS-36000 and sandia filter transfer functions for VS is shown in Fig. 4. In the proposed Sandia filters, the resulting curves are similar to those of

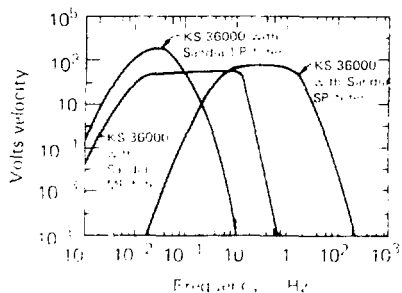


FIG. 14 Velocity sensitivity with filters: Sandia LP, Sandia MP, and Sandia SP.

Fig. 12 are the filters, except for the regions of very low and high frequencies where the KS-36000 VS drops to the noise floor. In those regions, the curves are not straight, as the KS-36000 response falls.

Table 1 lists the 3-dB points for this overall system.

- LP Band 0.006-0.95 Hz
- MP Band 0.02-3 Hz
- SP Band 1-10 Hz

Phase Response (6F)

The phase response accompanying the VS shown in Fig. 18 for the three Sandia filters. The phase response of the SSP was begun arbitrarily at zero degrees for low frequencies, and the other two phase responses were plotted accordingly. It should be noted that there is a jump in the MP curve near 1 Hz. This is due to the sharp, high-frequency corner of the MP filter. Although it is difficult to envision on semi-log plots, the closer the phase response is to 180 degrees at a frequency, the less distortion of signals is produced.

Group Delays

Group Delay (t_g) is the delay which would be experienced by a wave packet. It is calculated from the phase delay, $\phi(f)$, by the relation:

$$t_g = \frac{d\phi(f)}{d\omega} = \frac{1}{2\pi} \frac{d\phi(f)}{df} \quad (1)$$

It is useful to examine group delay since minima would result in large amplitude waves known as Ray phases, which distort the seismogram. Of course, onset times are also retarded by the group delay associated with the particular period of arrival.

Group delays of the KS-36000 with Sandia filters are shown in Fig. 16. The delays are large at low frequencies and approach zero at very high frequencies. Since the slopes of phase delay curves increase in proceeding through the SP, MP, and LP bands, group delays proceed in the same order, with the largest delay associated with the LP filter. Since

it is relatively clear that the minimum slope of the phase-delay curve occurs near the corner frequency of a filter, minima seen in Fig. 16 can be associated with a particular corner frequency, and the size of the group delay is proportional to the magnitude of the phase.

Step Responses

Step responses of the KS-36000 with the Sandia LP, MP, and SP filters are shown in Fig. 17. Here, the curves are plotted on a log scale. Note that the step response of the LP filter shows that SP filter "leakage" into the LP shows. The step response of the MP response shows that the delay is only a fraction of the step delay of the MP filter, which was 0.25 Hz. This delay is the Butterworth filter frequency, or the 3dB point of the filter. The delay of the sandia filter is the delay of the Butterworth filter, or the 3dB point of the filter, which was 0.25 Hz. This delay is the delay of the filter, or the delay of the Butterworth

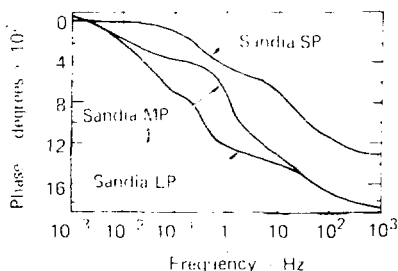


FIG. 15. Phase response of KS-36000 with Sandia filters.

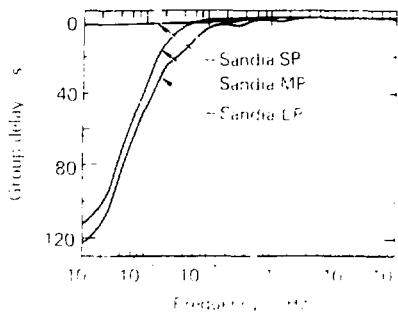


FIG. 16. Group delay of KS-36000 with Sandia filters.

the filter. The filter transfer function is given by

$$H(f) = \frac{1}{1 + j2\pi fRC} \quad (1)$$

where R is the resistance and C is the capacitance of the filter. The filter transfer function is given by

$$H(f) = \frac{1}{1 + j2\pi fRC} \quad (2)$$

PROPERTIES OF THE KS-36000 WITH AETAC FILTERS

Velocity Sensitivity Curves

The velocity sensitivity curves of the KS-36000 with the AETAC filters are shown in Figure 17. The curves show that the KS-36000 with the AETAC filters has a higher velocity sensitivity than the KS-36000 with the Sandia filters. The curves also show that the KS-36000 with the AETAC filters has a higher resonance frequency than the KS-36000 with the Sandia filters. The curves also show that the KS-36000 with the AETAC filters has a higher bandwidth than the KS-36000 with the Sandia filters. The curves also show that the KS-36000 with the AETAC filters has a higher peak velocity sensitivity than the KS-36000 with the Sandia filters.

Step-Function Response

The step function responses of the KS-36000 with the AETAC filters are shown in Figure 18. The curves show that the KS-36000 with the AETAC filters has a higher step function response than the KS-36000 with the Sandia filters.

Phase and Group Delay

The resulting SP phase delay is given by the transfer function with the Sandia filter. The resulting MP transfer function is given by the transfer function with the Sandia filter. The resulting LP transfer function is given by the transfer function with the Sandia filter. The phase and group delay curves for the KS-36000 with AETAC filters are given in Appendixes C, E, 2, C, and C2.

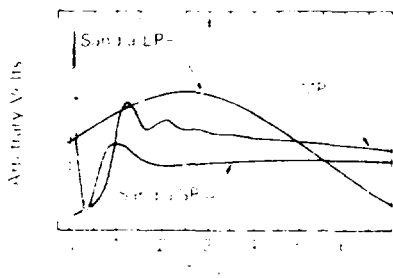


FIG. 17. Step responses of KS-36000 with Sandia filters.

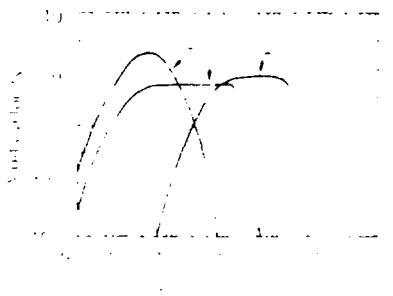


FIG. 18. Velocity sensitivity with filters: AETAC LP, AETAC MP, and AETAC SP.

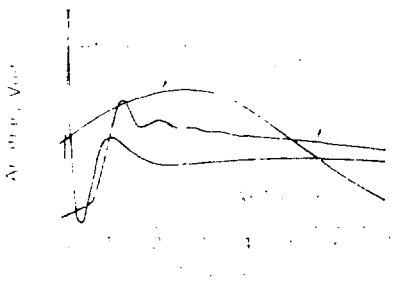


FIG. 19. Step responses of KS-36000 with AETAC filters.

CHAPTER 7: THE MP-BAND FILTER

As was stated previously, the upper corner of the standard MP-band filter is abrupt. It consists of a 10th-order Butterworth filter at 1.3 Hz. This results in the oscillatory step response for the MP band shown in Figs 17 and 18. Because this is undesirable, it is worthwhile considering two other low-pass filters for the high frequency corner of the MP band. One is a 4th-order Butterworth also centered at 1.3 Hz. The other is a 4th-order Bessel with the same corner frequency. The corresponding AS curves for the three filters are shown in Fig. 20. Note that the Bessel is the more rounded curve. Corresponding phase and group delays appear in Figs 21 and 22 where group delay is shown with

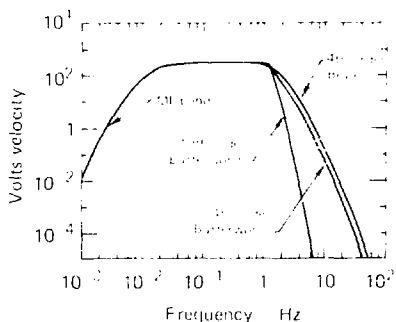


FIG. 20. Frequency response comparison of three MP band low pass filters.

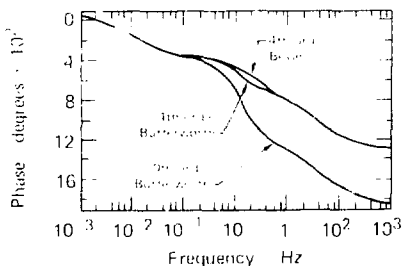


FIG. 21. Phase delay comparison of three MP band low pass filters.

an expanded scale. The minima in group delay for the 10th-order Butterworth is considerably greater than that for the 4th-order Butterworth. There is almost no minimum associated with the Bessel filter because of its nearly linear phase response (which is difficult to see in Fig. 21 because the horizontal axis is logarithmic).

Figure 23 compares the step-function responses of the three filters. The three different degrees of oscillation are in the order expected for each of the filter types. From this figure it is clear that the Bessel filter outperforms the Butterworth because of its improved transient behavior.

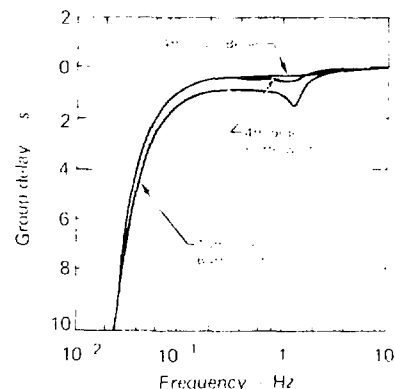


FIG. 22. Group delay comparison of three MP band low pass filters.

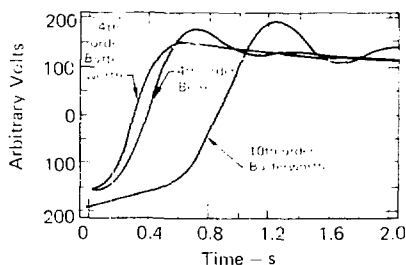


FIG. 23. Step response comparison of three MP band low pass filters.

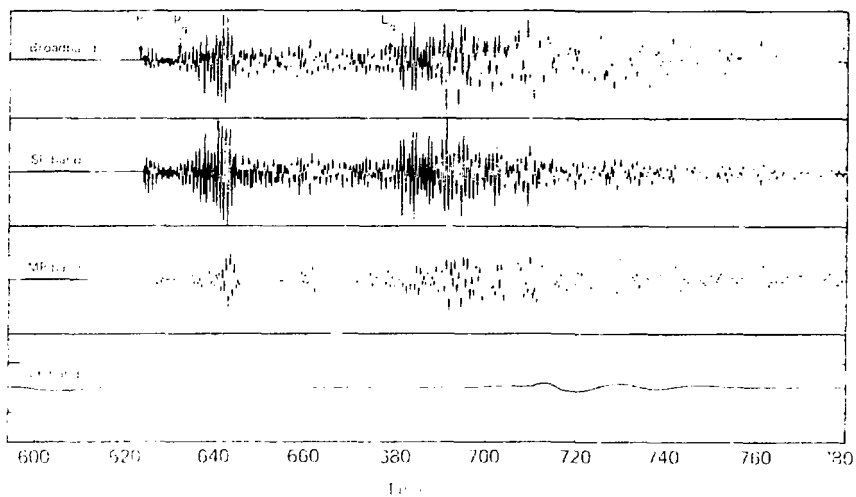


FIG. 25. Event (i): underground nuclear shot ($\Delta \approx 6^\circ$).

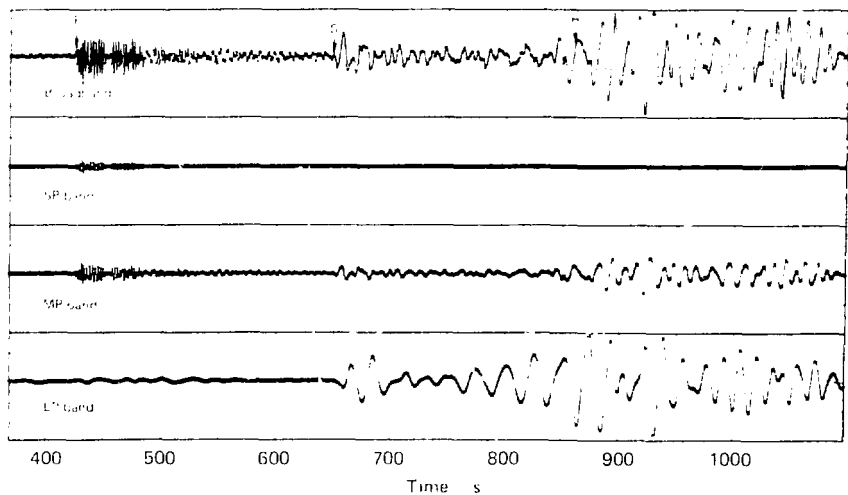


FIG. 26. Event (ii): regional earthquake ($\Delta \approx 20^\circ$).

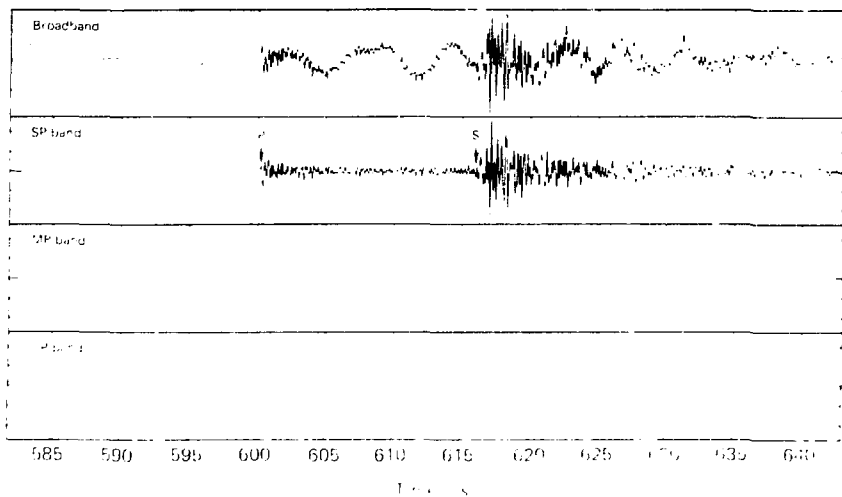


FIG. 27. Event (iii): local earthquake ($M_L = 1.5$).

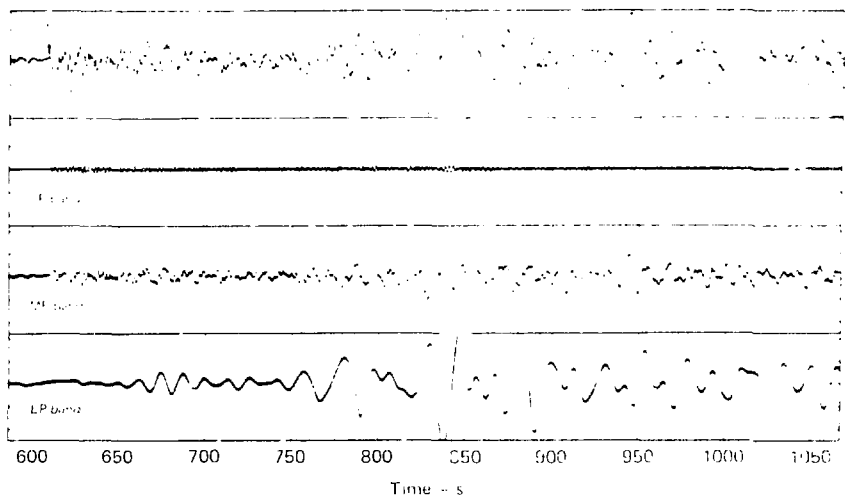


FIG. 28. Event (iv): large teleseism ($M_S = 12.3^{\circ}$).

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APPENDIX A: SEISMOMETER TRANSFER FUNCTIONS

TRANSFER FUNCTIONS FOR THE KS-36000 SEISMOMETER

$$H_{\text{KS}}(s) = \frac{H_{\text{KS}}(s) + H_{\text{KS}}(s)}{1 + H_{\text{KS}}(s) + H_{\text{KS}}(s) + H_{\text{KS}}(s)} \cdot K_s \cdot \begin{pmatrix} 1 \text{ m/s} \\ 1 \text{ s} \cdot 2 \text{ s} \end{pmatrix}$$

$$H_{\text{KS}}(s) = \frac{1}{s^2 + 2\zeta\omega_n s + \omega_n^2} \cdot \begin{pmatrix} 1 \text{ m/s} \\ 1 \text{ s} \end{pmatrix}$$

where

$$\omega_n = 2\pi \cdot 10 \text{ Hz}$$

$$H_{\text{KS}}(s) = \frac{1}{s^2 + 2\zeta\omega_n s + \omega_n^2} \cdot \begin{pmatrix} 1 \text{ m/s} \\ 1 \text{ s} \end{pmatrix}$$

$$H_{\text{KS}}(s) = \frac{1}{s^2 + 2\zeta\omega_n s + \omega_n^2} \cdot \begin{bmatrix} 1 \text{ m/s} & 1 \text{ s} \\ 1 \text{ s} & 1 \text{ s} \end{bmatrix} \cdot \begin{pmatrix} 1 \text{ m/s} \\ 1 \text{ s} \end{pmatrix}$$

$$K_s = \frac{1}{1} \cdot \begin{pmatrix} 1 \text{ m/s} \\ 1 \text{ s} \end{pmatrix}$$

TRANSFER FUNCTIONS FOR THE KS-36000 LP AND MP SHAPING FILTERS

$$H_{\text{LP}}(s) = H_{\text{LP}}(s) + H_{\text{LP}}(s) \cdot \begin{pmatrix} 1 \text{ s} \\ 1 \text{ s} \end{pmatrix}$$

$$H_{\text{LP}}(s) = \frac{G_{\text{LP}}(s) + 398.4 \text{ s}}{1 + G_{\text{LP}}(s) + 398.4 \text{ s}} \cdot \begin{pmatrix} 1 \text{ s} \\ 1 \text{ s} \end{pmatrix}$$

where

$$G_{\text{LP}}(s) = \frac{1}{s^2 + 2\zeta\omega_n s + \omega_n^2} \cdot \begin{pmatrix} 1 \text{ s} \\ 1 \text{ s} \end{pmatrix}$$

$$H_{\text{MP}}(s) = \frac{1 + 324 \text{ s}^2}{1 + 391.8 \text{ s} + 112 \text{ s}^2} \cdot \begin{pmatrix} 1 \text{ s} \\ 1 \text{ s} \end{pmatrix}$$

TRANSFER FUNCTIONS FOR THE KS-36000 AND S-700 SP SHAPING FILTERS

$$c) H_{K1}(s) = \frac{+18.61s}{s^2 + 268s + 0.633 \times 10^6} \quad \left(\frac{\text{cm/s}}{\text{cm/s}^2} \right)$$

$$d) H_{K2}(s) = \frac{+36.74s}{s^2 + 268s + 0.633 \times 10^6} \quad \left(\frac{\text{cm/s}}{\text{cm/s}^2} \right)$$

TRANSFER FUNCTIONS FOR THE S-700 SEISMOMETER

$$H_{S1}(s) = \frac{H_{S1}(0)H_{K1}(s)}{s + H_{S1}(0)(H_{K1}(0) + K_1)} \quad \left(\frac{\text{cm/sec}}{\text{cm/sec}^2} \right)$$

$$H_{S2}(s) = \frac{+1.01 \times 10^6}{s^2 + 268s + 0.633 \times 10^6} \quad \left(\frac{\text{cm}}{\text{cm/sec}^2} \right)$$

where:

$$H_{S1}(0) = 100 \times 10^{-6} \quad \text{cm/sec} \quad K_1 = 20 \times 10^3$$

$$e) H_{S3}(s) = \frac{+20s}{s^2 + 268s}$$

$$\left[\frac{+20s}{s^2 + 268s + 0.633 \times 10^6} \right] \quad \left(\frac{\text{cm/s}}{\text{cm/s}^2} \right)$$

$$H_{S4}(s) = \frac{0.0101s}{s^2 + 268s + 0.633 \times 10^6} \quad \left(\frac{\text{cm/sec}}{\text{cm/s}^2} \right)$$

$$f) K_2 = 27 \times 10^3 \quad \left(\frac{\text{cm/sec}}{\text{cm/s}^2} \right)$$

APPENDIX B: FILTER TRANSFER FUNCTIONS

SHORT PERIOD FILTER TRANSFER FUNCTIONS

$$H_{\text{SP}}(s) = G_{\text{SP}} \cdot H_{\text{IP}}(s) = H_{\text{IP}}(s) \cdot H_{\text{IP}}^2(s) \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

a) $G_{\text{SP}} = 1$

b) $H_{\text{IP}}(s) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$

c) $H_{\text{IP}}(s) = \frac{1}{s^2 + 0.2418s + 0.0499}$

d) $H_{\text{IP}}(s) = \frac{1}{s^2 + 0.2182s + 0.0499}$

COMMON FILTER TRANSFER FUNCTION

$$H_{\text{C}}(s) = \frac{1}{s^2 + 0.2418s + 0.0499} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

MID PERIOD FILTER TRANSFER FUNCTIONS

$$H_{\text{MP}}(s) = G_{\text{MP}} \cdot H_{\text{IP}}(s) = H_{\text{IP}}(s) \cdot H_{\text{IP}}(s) \cdot H_{\text{IP}}(s) \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

a) $H_{\text{IP}}(s) = \frac{1}{s^2 + 0.2418s + 0.0499}$

b) $H_{\text{IP}}(s) = \frac{1}{s^2 + 0.2182s + 0.0499}$

$$c) H_C(s) = \frac{1.0}{1.0 + 0.731s + 0.01499s^2}$$

$$d) H_D(s) = \frac{1.0}{1.0 + 0.1112s + 0.01499s^2}$$

$$e) H_E(s) = \frac{1.0}{1.0 + 0.33830s + 0.01499s^2}$$

$$f) H_f(s) = \left[\frac{31.83s}{1.0 + 31.83s} \right]$$

$$g) H_g(s) = \frac{1.0}{1.0 + 1.892s} + \frac{1.0}{1.0 + 1.892 \times 10^{-7}s}$$

f) G_{fp}

LONG PERIOD FILTER TRANSFER FUNCTIONS

$$H_{fp}(s) = G_{fp} \cdot H_C(s) \cdot H_D(s) \cdot H_E(s) \cdot H_f(s) \cdot H_g(s) \cdot H_h(s) \cdot H_i(s) \cdot \left(\frac{0.05s}{s+R} \right)$$

$$a) H_C(s) = \left[\frac{1.0}{1.0 + 4.886s + 11.7s^2} \right]$$

$$b) H_D(s) = \frac{1.0}{1.0 + 0.9460s + 0.2398s^2}$$

$$c) H_E(s) = \frac{1.0}{1.0 + 0.6926s + 0.2398s^2}$$

$$d) H_f(s) = \frac{1.0}{1.0 + 0.2838s + 0.7398s^2}$$

$$e) H_g(s) = \left[\frac{31.83s}{1.0 + 31.83s} \right]^2$$

$$f) H_h(s) = \frac{1.0}{1.0 + 0.1892s} + \frac{1.0}{1.0 + 1.892 \times 10^{-7}s}$$

g) $G_{fp} = 32.0$

APPENDIX C: PHASE AND GROUP DELAY WITH AFTAC FILTERS

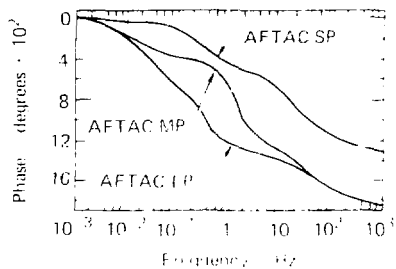


FIG. C1. Phase delay KS-36000 with AFTAC filters.

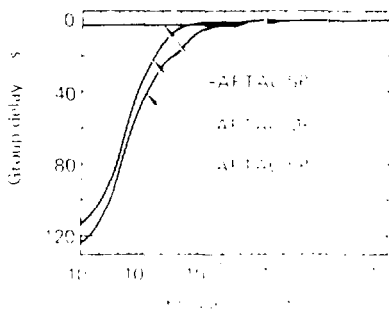


FIG. C2. Group delay KS-36000 with AFTAC filters.

APPENDIX D: EVENT AMPLITUDE SPECTRA

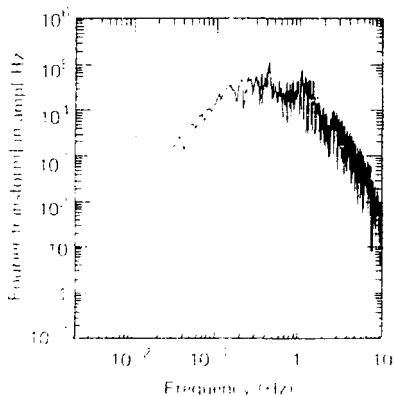


FIG. D1. Event (i): underground nuclear shot amplitude spectrum.

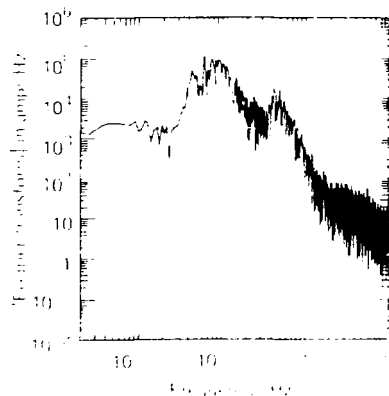


FIG. D2. Event (ii): regional earthquake amplitude spectrum.

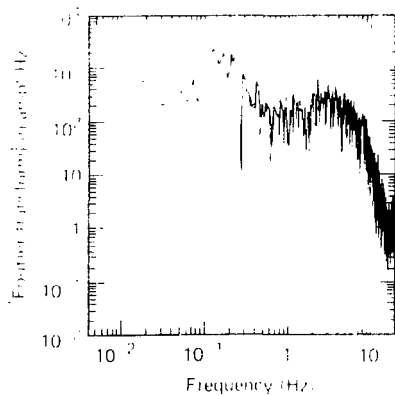


FIG. D3. Event (iii): local earthquake amplitude spectrum.

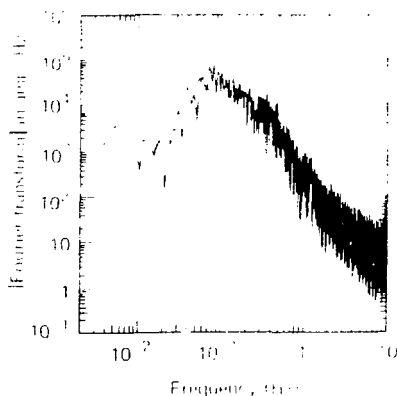


FIG. D4. Event (iv): large teleseism amplitude spectrum.